

Dynamic Bayesian Network and Nonparametric Regression Model for Inferring Gene Networks

SunYong Kim

sunk@ims.u-tokyo.ac.jp

Seiya Imoto

imoto@ims.u-tokyo.ac.jp

Satoru Miyano

miyano@ims.u-tokyo.ac.jp

Human Genome Center, Institute of Medical Science, University of Tokyo,
4-6-1 Shirokanedai, Minato-ku, Tokyo 108-8639, Japan

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1 Introduction

A Bayesian network is a powerful tool for modeling relations among a large number of random variables. Therefore the Bayesian network has received considerable attention from the studies of gene network estimation using microarray gene expression data. Imoto *et al.* [1, 2] proposed a Bayesian network and nonparametric regression model for capturing nonlinear relations between genes from the continuous gene expression data. However, a Bayesian network still has a problem that it cannot construct cyclic regulations, while real gene networks have cyclic regulations. For a solution of this problem, in this paper, we propose a dynamic Bayesian network and nonparametric regression model for estimating a gene network with cyclic regulations from time series microarray data. We also derive a criterion for selecting a network from Bayes approach. The effectiveness of our method is displayed through the analysis of the *Saccharomyces cerevisiae* gene expression data.

2 Method

Let X be an $n \times p$ time series microarray data matrix, where n and p are the number of microarrays and genes, respectively. Under the first order Markov relation between the time points, the joint probability can then be decomposed as $P(X_{11}, \dots, X_{np}) = P(\mathbf{X}_1)P(\mathbf{X}_2|\mathbf{X}_1) \times \dots \times P(\mathbf{X}_n|\mathbf{X}_{n-1})$, where $\mathbf{X}_i = (X_{i1}, \dots, X_{ip})^T$ is a random variable vector at time i . The conditional probability $P(\mathbf{X}_i|\mathbf{X}_{i-1})$ can be decomposed as $P(\mathbf{X}_i|\mathbf{X}_{i-1}) = P(X_{i1}|\mathbf{P}_{i-1,1}) \times \dots \times P(X_{ip}|\mathbf{P}_{i-1,p})$, where $\mathbf{P}_{i-1,j}$ denotes the parents of j th gene at time $i-1$.

Using the nonparametric regression in order to model the relationship between a gene and its parents, we define a dynamic Bayesian network and nonparametric regression model by the density,

$$f(x_{11}, \dots, x_{np}; \boldsymbol{\theta}_G) = f_1(\mathbf{x}_1) \prod_{j=1}^p \left[\prod_{i=2}^n \frac{1}{\sqrt{2\pi\sigma_j^2}} \exp \left\{ -\frac{(x_{ij} - \mu(\mathbf{p}_{i-1,j}))^2}{2\sigma_j^2} \right\} \right],$$

where $\mathbf{p}_{i-1,j} = (p_{i-1,1}^{(j)}, \dots, p_{i-1,q_j}^{(j)})$ is a parents vector of j th gene, observed at time $i-1$.

When the network structure is given, we can construct a gene network by using the proposed model. However, the true gene network is still unknown, and we should guess the optimal network structure from the data. We derive a criterion for evaluating the network structure from Bayes approach. By using the Laplace approximation for integrals, the criterion, named $\text{BNRC}_{\text{dynamic}}$ can be expressed as

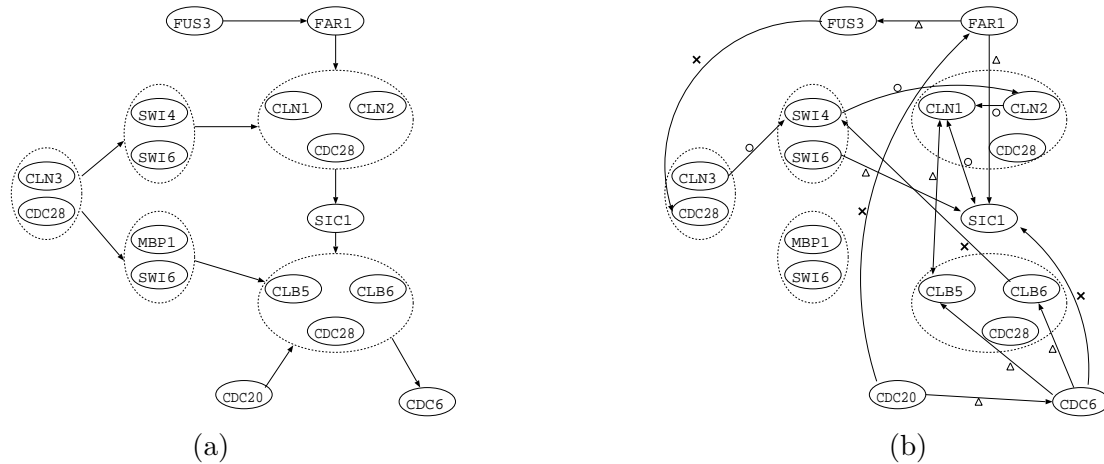


Figure 1: Yeast cell cycle pathway compiled by KEGG. (a) Target, (b) Estimate.

$$\begin{aligned} \text{BNRC}_{\text{dynamic}}(G) &= -2 \log \left\{ \pi_{\text{prior}}(G) \int f(x_{11}, \dots, x_{np}; \theta_G) \pi(\theta_G | \lambda) d\theta_G \right\} \\ &\approx -2 \log \pi_{\text{prior}}(G) - r \log(2\pi/n) + \log |J_{\lambda}(\hat{\theta}_G)| - 2n l_{\lambda}(\hat{\theta}_G | \mathbf{X}), \end{aligned}$$

where $\pi(\theta_G | \lambda)$ and $\pi_{\text{prior}}(G)$ are the prior distribution of the parameter θ_G and the prior probability of the network G , respectively, λ is the hyper parameter vector, r is the dimension of θ_G , $l_{\lambda}(\theta_G | \mathbf{X}) = \log f(x_{11}, \dots, x_{np}; \theta_G) / n + \log \pi(\theta_G | \lambda) / n$, $J_{\lambda}(\theta_G) = -\partial^2 \{l_{\lambda}(\theta_G | \mathbf{X})\} / \partial \theta_G \partial \theta_G^T$ and $\hat{\theta}_G$ is the mode of $l_{\lambda}(\theta_G | \mathbf{X})$. We can choose the optimal network such that the $\text{BNRC}_{\text{dynamic}}$ is minimal.

3 Result

We apply the proposed method to the *Saccharomyces cerevisiae* cell cycle data collected by Spellman *et al.* [3]. The target network is a part of cell cycle pathway compiled by KEGG [4] and shown in Figure 1 (a). Figure 1 (b) is the estimated network based on the proposed method. In Figure 1 (b), we evaluate the estimated edges by three kinds of marks: Round is the correct edge, crisscross is the wrong edge and triangle represents the misdirection or skip.

References

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