DYNAMIC SUSCEPTIBILITY OF A MODEL POLYMER IN SEVERAL LIMITS -THEORY AND CALCULATIONS.

M. J. Mandell

Laboratory of Atomic and Solid State Physics Cornell University Ithaca, New York 14850



April 1972

This report was prepared as an account of work sponsored by the United States Government. Neither the United States Government. Neither the United States Alomic Energy Commission, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, complateness or unefulness of any information, apparalus, product or process disclosed, or represents that its use would not infringe privately owned rights.

DISCLAIMER

This report was prepared as an account of work sponsored by an agency of the United States Government. Neither the United States Government nor any agency Thereof, nor any of their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.

DISCLAIMER

Portions of this document may be illegible in electronic image products. Images are produced from the best available original document.

Dynamic Susceptibility of a Model Polymer in Several Limits -
*
Theory and Calculations

M. J. Mandell

Laboratory of Atomic and Solid State Physics
Cornell University
Ithaca, New York 14850

Abstract

We study the susceptibility of a model polymer having rotating dipolar sidechains with nearest neighbor interactions and diagonal viscosity. The susceptibility can be found exactly (1) at zero frequency for arbitrary interaction strength, and (2) at zero interaction strength for arbitrary frequency and viscosity. In addition, a high-temperature expansion exists for arbitrary frequency both in the viscous limit and for finite viscosity. We also study the time-dependent correlation function $<\cos\phi_1(t)\cos\phi_{1+1}(0)>$ for arbitrary viscosity and we ak interaction, and the possibility of a more complex diagonal friction law. In no case are we able to produce a Cole-Cole plot which approaches the origin with finite slope at high frequencies, as does much experimental data.

I. Introduction

There has been some interest in recent years in the dynamical (nonequilibrium) properties of many-particle systems under the influence of stochastic forces. Examples include the work of Glauber on the Ising model⁽¹⁾, and a series of papers on harmonic oscillator systems by Oppenheim, Shuler and Weiss.⁽²⁾

Various properties of polymers have been considered candidates for explanation by such models. (3,4,5) In this paper we study a model similar to that proposed by Work and Fujita (6) to explain dielectric relaxation in certain polymers. The frequency dependent susceptibility of such polymers, as represented on a Cole-Cole plot, takes either the semicircular Debye form (1-i\omega_7)^{-1}, or a distorted form which approaches the origin with finite slope (Fig. 1.). (7)

Our model is a polymer consisting of a backbone with polar sidechains free to rotate in the plane normal to the backbone. Each such side element has a dipole moment μ (which we henceforth set to unity) and is subject to a random torque. We furthermore suppose an interaction between nearest neighbors of the form $v\cos(\phi_i-\phi_{i-1}),$ so as to create a tendency toward antiferroelectric alignment for v>0. (This would be an excellent approximation if the interaction is electrostatic in origin, taking $v\sim \mu^2/a^3,$ with a the nearest neighbor distance. However, it is rather naive to suppose this to be the case.)

We then attempt to calculate the linear susceptibility for arbitrary frequency.

In section II we present the solution of the model for zero frequency. Section III reviews the theory of motion in the field of a random force. In section IV we derive a high-temperature expansion for the susceptibility in the viscous limit.

In section V we derive the susceptibility for the noninteracting system in the case of finite viscosity, and we demonstrate the existence of a high-temperature expansion. Section VI deals with the dynamic, linear nearest-neighbor correlation function for the case of finite viscosity. Section VII discusses the case of a more complex random force, and we summarize our conclusions in section VIII.

In all the cases we consider we are unable to convincingly produce a Cole-Cole plot which approaches the origin with finite slope as in Figure 1. This suggests that our model, as well as all similar models, lacks the essential ingredient needed to produce such behavior.

II. Exact Equilibrium Results

At equilibrium it is possible to find many properties exactly by the techniques used by Fisher (8) on the classical Heisenberg model. We give these calculations in some detail both for completeness and because we will use some of the results later.

The Hamiltonian is given by

$$H = H_{k} + H_{v} + H_{E}(t)$$
 (1)

where

$$H_{k} = \frac{1}{2I} \sum_{j} p_{j}^{2}$$

$$H_{E} = -E \sum_{j} \cos (\phi_{j} - \omega t)$$

$$H_{v} = v \sum_{j} \cos (\phi_{j} - \phi_{j+1})$$

$$j$$
(2)

we use I to denote the moment of inertia per sidechain, and p_j is the momentum conjugate to the angular position ϕ_j . The partition function (for $\omega=0$) is then

$$Z = \begin{bmatrix} \pi & \int dp_j & \exp(-\frac{\beta}{2I} p_j^2) \end{bmatrix} \begin{bmatrix} \int d^N \varphi_j & \exp(-\beta \Sigma_j (v \cos u_j - E \cos \varphi_j)) \end{bmatrix}$$
(3)

where we have written $u_j = \phi_j - \phi_{j-1}$. At zero applied field, and neglecting end effects, the partition function may be evaluated to give

$$z = (2\pi I T)^{-N/2} (2\pi I_o(v/T))^N$$
 (4)

where I is the Bessel function for imaginary argument, and we have set Boltzmann's constant to unity. This result enables the calculation of such thermal properties as the specific heat by the usual methods. (See Fig. 2).

Next we calculate the correlation function

$$< \exp[i(\varphi_o - \varphi_k)] > = 2 < \cos \varphi_o \cos \varphi_k >$$

$$= 2 < \sin \varphi_o \sin \varphi_k > .$$
(5)

For concreteness we take k > 0. We note that

$$\cos \varphi_k = \cos(u_k + \varphi_{k-1}) = \cos u_k \cos \varphi_{k-1} - \sin u_k \sin \varphi_{k-1}$$
 (6)

Thus

where we use the fact that there are N variables ϕ , but only N-1 variables u. Since the u_k s are all independent, and since $<\sin\,u_k>$ = 0, we get a recursion formula

< cos
$$\phi_0$$
 cos ϕ_k > = < cos u_k >< cos ϕ_0 cos ϕ_{k-1} > . (8) Now,

$$< \cos u_{j} > = -\frac{\partial}{\partial (\beta v)} \ln \int du_{j} \exp(-\beta v \cos u_{j})$$

$$= -I_{o}^{\dagger} (\beta v)/I_{o}(\beta v)$$
(9)

and $< \cos^2 \varphi_0 > = \frac{1}{2}$, so that

$$< \exp[i(\varphi_{o} - \varphi_{k})] > = [-i_{o}(\beta v)/i_{o}(\beta v)]^{k}$$
 (10)

The function $< -e^{i(\phi_0 - \phi_1)} > = I_0/I_0$ is shown on Figure 2.

Furthermore, we may calculate

<
$$\exp[2i(\varphi_0 - \varphi_1)] > = < \cos 2u_1 >$$

$$= < 2\cos^2 u_1 - 1 >$$

$$= [2I_0''(\beta v) - I_0'(\beta v)]/I_0'(\beta v) \qquad (11)$$

and this technique may be extended to < $e^{in(\phi}o^{-\phi}1)$ >.

Finally, using once again the independence of the coordinates \mathbf{u}_{i} , we may calculate such a term as

$$<\exp\left[i\sum_{j=0}^{k}n_{j}\phi_{j}\right]> = <\exp\left[in_{k}u_{k}\right]> <\exp\left[i(n_{k-1}-n_{k})\phi_{k-1}\right]$$

$$+i\sum_{j=0}^{k-2}\phi_{j}>$$
(12)

Since all coordinates u, are independent.

The static susceptibility is given by

$$\chi = \beta \sum_{ij} < \cos \varphi_i \cos \varphi_j > \tag{13}$$

which can be derived by differentiating the partition function twice with respect to E before taking the zero-field limit.

This is easily evaluated to give

$$\chi = \frac{N\beta}{2} \left(1 + 2 \sum_{k=1}^{\infty} \left[-\frac{I_o(\beta v)}{I_o(\beta v)} \right]^k \right)$$

$$= \left(\frac{N}{2T} \right) \left(\frac{I_o(\beta v) - I_o(\beta v)}{I_o(\beta v) + I_o(\beta v)} \right)$$
(14)

$$\chi \xrightarrow{\text{BV} \to \infty} \left(\frac{N}{2T}\right) \frac{T}{4V} = \frac{N}{8V}. \tag{15}$$

III. Review of the Theory of a Particle Subject to a Random Force

In this section we outline the theory of a system subject to a random force in order to derive the equations basic to subsequent sections. We follow the development of Kramers. (9)

An ensemble of model polymers may be characterized by a distribution function $(\underline{w}, \underline{p}, t)$, where \underline{w} and \underline{p} are N-dimensional vectors describing the angular positions and momenta of the side-chains of a given polymer. We wish to calculate

$$\frac{\partial^{\rho}}{\partial t} \approx \frac{1}{\tau} \left\{ \rho(\underline{\omega}, \underline{p}, t + \tau) - \rho(\underline{\omega}, \underline{p}, t) \right\}$$
 (16)

where a is a macroscopically small time interval. We proceed using

$$\underline{\dot{\mathbf{p}}} = \frac{1}{\bar{\mathbf{I}}} \mathbf{p} \tag{17a}$$

and

$$\dot{\underline{p}} = -\nabla_{\underline{\phi}} U(\underline{\phi}) + \frac{1}{\tau} \underline{B}_{\underline{\tau}}$$
 (17b)

where

$$\underline{B} = \int_{t}^{t+\tau} \underline{X}(t) dt$$
 (18)

 $X_1(t)$ being the random torque on the 1th sidechain, and $\underline{B}_{\underline{\tau}}$ is described by a distribution $Y_{\underline{\tau}}(\underline{B}, \underline{\varphi}, \underline{p})$. Then

$$P(\underline{\varphi}, \underline{p}, t + \tau) = \int d^{N}B P(\underline{\varphi} - \frac{\tau}{\underline{I}}\underline{p}, \underline{p} + \tau \underline{\nabla}_{\underline{\varphi}}\underline{U}(\underline{\varphi}) - \underline{B}, t) \tilde{\Phi}_{\underline{\tau}}(\underline{B}, \underline{\varphi}, \underline{p})$$
(19)

which leads to

$$\frac{\partial^{\rho}}{\partial t} \approx -\frac{1}{I} \underline{p} \cdot \underline{\nabla}_{p} \rho + \underline{\nabla}_{\underline{\varphi}} U(\underline{\varphi}) \cdot \underline{\nabla}_{\underline{\rho}} \rho + \frac{1}{\tau} \Delta \rho \tag{20}$$

where

$$\Delta \rho = \int d^{N}B[\rho(\underline{\varphi},\underline{p} - \underline{B},t) - \rho(\underline{\varphi},\underline{p},t)] \phi_{\gamma}(\underline{B},\underline{\varphi},\underline{p})$$

$$= \sum_{\mathbf{i}} \int_{-\infty}^{\infty} dB_{\mathbf{i}} \left\{ \sum_{\mathbf{m}=1}^{\infty} \frac{(-B_{\mathbf{i}})^{\mathbf{m}}}{m!} \left(\frac{\partial}{\partial P_{\mathbf{i}}} \right)^{\mathbf{m}} (P_{\mathbf{i}}) \right\} . \tag{21}$$

Note that we have assumed the random forces on different sidechains to be uncorrelated, and also that Φ_{τ} is independent of Φ_{τ} . Defining

$$\mu_n = \int_{-\infty}^{\infty} B^n_{\frac{1}{2}}(B, p) dB$$
 (22)

yields the Fokker-Planck equation

$$\frac{\partial P}{\partial t} = \underline{\nabla}_{\underline{\omega}} U(\varphi) \cdot \underline{\nabla}_{\underline{p}} P - \underline{P} \cdot \underline{\nabla}_{\underline{\omega}} P + \sum_{i} \sum_{n=1}^{\infty} \frac{1}{n!} \left(-\frac{\partial}{\partial P_{i}} \right)^{n} \left(\frac{\mu_{n}}{\tau} P \right)$$
 (23)

It is usual to choose (Einstein damping) $\mu_1 = -\eta p_T$, $\mu_2 = 2\eta I T_T$, and all higher moments zero. This choice is not unique, however. The moments μ_1 are restricted only by the conditions that the Maxwell-Boltzmann distribution be stationary and stable. We shall return to this point in section VII. Under the usual choice of μ_1 , (23) becomes

$$\frac{\partial P}{\partial t} = \underline{\nabla}_{\underline{w}} U(\underline{\varphi}) \cdot \underline{\nabla}_{\underline{p}} P - \underline{p} \cdot \underline{\nabla}_{\underline{w}} P + \underline{\eta} \underline{\nabla}_{\underline{p}} \cdot (\underline{p} P + \underline{I} \underline{T} \underline{\nabla}_{\underline{p}} P) \quad . \tag{24}$$

In the case of large viscosity, it is customary to assume that

$$\rho(\underline{\omega}, \underline{p}, t) = \sigma(\underline{\omega}, t) \exp[-\underline{p} \cdot \underline{p}/2IT]$$
 (25)

The equation for σ is derived by integrating (24) over the path $\underline{\omega} + \underline{p}/\eta I = \underline{\phi}$ from $\underline{p}_i = -\infty$ to $+\infty$, and assuming that the force and the distribution $P(\underline{\omega},\underline{p})$ have nearly the same values as at φ_0 over the region making the main contribution to the

integral. This leads to the diffusion equation

$$I\eta \frac{\partial \sigma}{\partial t} = \underline{\nabla} \cdot [(\underline{\nabla}_{\underline{\omega}} U(\underline{\omega}))_{\sigma} + \underline{T} \underline{\nabla}_{\underline{\omega}} \sigma]. \tag{26}$$

IV. Susceptibility in the Viscous Limit

Single Particle Susceptibility

In this subsection we calculate the susceptibility of an ensemble of noninteracting side-chains whose dynamics are governed by equation (26), with $U = -E \cos \theta$, $\theta = \phi - \omega t$. The quantity we will calculate is a reduced susceptibility given by

$$X = 2T \frac{\delta}{\delta E} < e^{-i\theta} >$$
 (27)

We will write (26) in the form

$$\frac{\mathrm{I}\eta}{\mathrm{T}}\frac{\partial\sigma}{\partial\mathrm{t}} = \frac{\mathrm{E}}{\mathrm{T}}\frac{\partial}{\partial\varphi}(\sigma\sin(\varphi - \omega\mathrm{t})) + \frac{\partial^2\sigma}{\partial\varphi^2} \tag{28}$$

Denoting In/T by τ_1 and writing

$$\sigma(\varphi, t) = \frac{1}{2\pi} \sum_{n=-\infty}^{\infty} A_n e^{in\theta}$$
 (29)

gives

$$\sum_{n} (n^{2} - inz) A_{n} = iy \frac{\partial}{\partial \theta} [(e^{i\theta} - e^{-i\theta}) \sum_{n} A_{n} e^{in\theta}]$$
 (30)

where $z = \omega_{\tau_1}$ and y = E/2T. Equating powers of $e^{i\theta}$ gives

$$(n - iz) A_n = y(A_{n-1} - A_{n+1}).$$
 (31)

Now we observe that, using $A_0 = 1$,

$$< e^{-i\theta} > = A_1 = \frac{y}{1-iz} + O(y^3).$$
 (32)

This yields, then, the expected result

$$\chi = (1 - iz)^{-1}. \tag{33}$$

Many Particle Susceptibility

For our model we need consider a distribution function

$$\sigma = \sigma(\varphi_1, \dots, \varphi_N, t) \tag{34}$$

with a potential given by $H_E + H_V$. The generalization of equation (29) is

$$\sigma = \left(\frac{1}{2\pi}\right)^{N} \sum_{\left\{n_{j}\right\}} A_{\left\{n_{j}\right\}} \exp\left(i\sum_{j} n_{j} \theta_{j}\right); \qquad A_{\left\{0\right\}} = 1.$$
 (35)

We assume that (a) $A_{\{n_j\}}$ is invariant under $j \rightarrow j + m$ or $j \rightarrow m - j$; (b) we may neglect $A_{\{n_j\}}$ if more than a few nearby n_j 's are nonzero, provided v/T is not too large; and (c) end effects are negligible. Under these assumptions, we may write the generalization of equation (31) as

$$\sum_{j} n_{j}^{2} - iz \sum_{j} n_{j} A_{n_{j}} = y \sum_{j} n_{j} A_{n_{j-1}, n_{j-1}, n_{j-1}, n_{j+1}, \dots} - A_{n_{j-1}, n_{j+1}, n_{j+1}, \dots}$$

$$- A_{n_{j-1}, n_{j+1}, n_{j+1}, \dots} A_{n_{j-1}, n_{j+1}$$

where x = v/2T.

For simplicity, in what follows we subscript the coefficients A only with indices from the region in which they
may be nonzero, such a procedure being justified by the assumptions
(a, b, c) above. Once again, our object is to find the coefficient A₁ to linear order in y, but as a power series in x. The
equation for A₁ is now

$$(1 - iz)A_1 = y(A_0 - A_2) - 2x(A_1 - A_{2,-1}).$$
 (37)

Since $A_2 \sim y^2$ and $A_{2,-1} \sim xy$, we have, to linear order in x, $A_1 = \frac{y}{1 + 2x - iz}.$ (38)

To go to higher order in x we must write the equation for $A_{2,-1}$, which is

$$(5 - iz)A_{2,-1} = y(2A_{1,-1} - 2A_{3,-1} - S_{2,-2} + A_{2})$$

$$-x(3A_{1} - 3A_{3,-2} + 2A_{1,1,-1} - 2A_{-1,3,-1}$$

$$-A_{2,-2,1} + A_{2,0,-1}).$$
(39)

Four types of quantities appear on the right handside: (1) A_1 appears in a previous equation, and may be handled algebraically or expanded to low order; (2) A_2 and $A_{3,-1}$ are proportional to y^2 and may be ignored; (3) $A_{1,-1}$ and $A_{2,-2}$ are known from the exact results of section II, or, alternatively, may be expanded as a power series using (36); (4) The remaining terms satisfy equations similar to (39), and contribute to the susceptibility terms cubic or higher in x. We may thus proceed to include terms to arbitrarily high powers of x = v/2T. Including terms through x^5 leads to the Cole-Cole plots shown in Figure 3.

For the highest values we have plotted (x = 0.6 and x = 1.0) the Cole-Cole plot is definitely distorted from a semi-circular shape, showing some tendency toward the plot of Figure 1. (See Figure 4.)

The numerical results suggest that, for very high frequencies $z \gg (1 + 8x)$, the susceptibility may be well fit by

$$\chi''(z) = z^{-1}$$

 $\chi''(z) = (1 + 5.2x^{4/3})z^{-2}$ (40)

for 0 < x < 3. The slope of the resulting Cole-Cole plot, $\chi''/\chi' \sim z x^{-4/3} \text{ is less than that of the semicircle } (\alpha x - iz)^{-1},$ for which $\chi''/\chi' \sim z x^{-1}$.

V. Susceptibility in the Finite Viscosity Case

1. Single Particle

To find the susceptibility when the approximations leading to (26) do not apply, it is necessary to deal with the Fokker-Planck equation (24), 10 which for our case becomes

$$\frac{\partial \rho}{\partial t} = E \sin(\varphi - \omega t) \frac{\partial \rho}{\partial p} - p \frac{\partial \rho}{\partial \omega} + \eta \frac{\partial}{\partial p} \left(p\rho + IT \frac{\partial \rho}{\partial p} \right)$$
 (41)

We define $g(\theta, p) = (\varphi, p, \frac{\varphi - \theta}{\omega}) \exp(p^2/2IT)$, and its fourier transform g(n, p) by

$$g(\theta,p) = (2\pi)^{-1} \sum_{n} e^{in\theta} g(n,p). \tag{42}$$

The susceptibility is now given by

$$\chi = 2T \frac{\partial}{\partial E} < e^{-i\theta} > = (2\pi IT)^{-\frac{1}{2}} \int dp \exp(-p^2/2IT) f_0(p^2/IT)^{\frac{1}{2}}$$
 (43)

where $f_0(p^2/IT)^{\frac{1}{2}} = g(1,p)$ evaluated at E/2T = 1 (keeping only terms linear in E), and satisfies the equation

$$[L(x) + i(\omega_{\tau_2} - x(\tau_2/\tau_1)^{\frac{1}{2}})]f_o(x) = -ix(\tau_2/\tau_1)^{\frac{1}{2}}.$$
 (44)
Here we have defined $\tau_2 = \eta^{-1}$ and

$$L(x) = \frac{\delta^2}{\delta x^2} - x \frac{\delta}{\delta x}. \tag{45}$$

Equation (44) is derived from equation (41) in a straightforward manner using the definitions above and the fact that $g(0,p) = 1 + O(E^2)$. Some further details will be given in the
next subsection when we deal with the many-particle case.

Equation (44) seems to have no reasonably simple analytic solution, but it is a well-behaved linear differential equation

and is susceptible to numerical methods. (See Appendix A.) We plot in Figure 5 the function $f_0(x) \exp(-x^2/2)$. For small frequencies (a) the real part is gaussian and the imaginary part is a gaussian which grows with increasing frequency. At intermediate frequencies (b) the imaginary part peaks at a momentum which corresponds roughly to the angular velocity of the field. This represents a sort of "surf-riding" effect. For high frequencies (c) we have $f_0 \sim x/\varpi(\tau_1\tau_2)^{\frac{1}{2}}$.

The resulting Cole-Cole plots for various values of τ_2/τ_1 are shown in Figure 6. The negative susceptibility at high frequencies is characteristic of a harmonically oscillating particle which accelerates in phase with the field. In addition, Figure 7 shows the absorption χ'' as a function of frequency for various values of τ_2/τ_1 .

2. Many Particles

The susceptibility in this case is given by

$$\frac{\chi}{N} = \langle e^{-i\theta}o \rangle = \int e^{-i(\phi_0 + \omega t)} \rho(\underline{\phi}, \underline{p}, t) d^N_{\phi} d^N_{\phi}$$

$$= (2\pi I T)^{N/2} \int d^N p f(\underline{p}) \exp(-\underline{p} \cdot \underline{p}/2I T) \qquad (45)$$

where we understand all quantities to be taken to linear order in E/2T, which we then equate to unity. We shall write the equation for f and show that

$$f = f_0(x_0) + 2(v/2T) f_1(x_0, x_1) + 0(v/2T)^2,$$
 (46)

where $x_i = p_i/IT$. We shall then consider the function f_1 and neglect the higher order terms.

The Fokker-Planck equation for this case is

$$\frac{\partial \rho}{\partial t} = \sum_{i} \left\{ E \sin(\varphi_{i} - \omega t) - v(\sin(\varphi_{i} - \varphi_{i-1}) + \sin(\varphi_{i} - \varphi_{i+1})) \right\} \frac{\partial \rho}{\partial P_{i}}$$

$$-\sum_{i} \frac{P_{i}}{I} \frac{\partial \rho}{\partial \varphi_{i}} + \eta \sum_{i} \frac{\partial}{\partial P_{i}} \left(P_{i} P + IT \frac{\partial \rho}{\partial P_{i}} \right)$$
(47)

Define $\phi = \rho \exp(\frac{\Sigma}{k} p_k^2/2IT)$. The viscous term now becomes

$$\eta \sum_{\mathbf{i}} \frac{\partial}{\partial \mathbf{p_i}} \left[\left(\mathbf{p_i} + \mathbf{p_i} + \mathbf{IT} \frac{\partial \Phi}{\partial \mathbf{p_i}} \right) \exp\left[-\frac{\Sigma}{k} \mathbf{p_k^2/2IT} \right] \right] \\
= \eta \sum_{\mathbf{i}} \left(\mathbf{IT} \frac{\partial^2 \Phi}{\partial \mathbf{p_i^2}} - \mathbf{p_i} \frac{\partial \Phi}{\partial \mathbf{p_i}} \right) \exp\left[-\frac{\Sigma}{k} \mathbf{p_k^2/2IT} \right] \\
= \tau_2^{-1} \sum_{\mathbf{i}} \left(\mathbf{L}(\mathbf{x_i}) \Phi \right) \exp\left(-\frac{\Sigma}{k} \mathbf{x_k^2/2} \right) \tag{48}$$

As before, we set

$$= \sum_{\{\mathbf{n_j}\}} \exp(\mathbf{i} \, \mathbf{j} \, \mathbf{n_j} \, \mathbf{\theta_j}) \, \mathbf{i} \, \{\mathbf{n_j}\} \, (\mathbf{p})$$

$$= \sum_{\{\mathbf{n_j}\}} \exp(\mathbf{i} \, \mathbf{j} \, \mathbf{n_j} \, \mathbf{\theta_j}) \, \mathbf{i} \, \{\mathbf{n_j}\} \, (\mathbf{p})$$

$$= \sum_{\{\mathbf{n_j}\}} \exp(\mathbf{i} \, \mathbf{j} \, \mathbf{n_j} \, \mathbf{\theta_j}) \, \mathbf{i} \, \{\mathbf{n_j}\} \, (\mathbf{p})$$

and keep those terms proportional to $\exp(i\theta_0)$. This gives

$$-i\omega f(p) = \frac{iE}{2} \left(\frac{P_{o}}{1T} + \frac{P_{-1}}{1T} \cdot \frac{1}{2} - 1, 1, 0 + \frac{P_{1}}{1T} \cdot \frac{1}{2} 0, 1, -1 \right)$$

$$+ \frac{v}{2i} \left\{ \left(\frac{P_{o}}{1T} - \frac{\partial}{\partial P_{o}} \right) \left(\frac{1}{2} 0 + \frac{1}{2} \frac{1}{2} 0 - \frac{1}{2} 0, 2, -1 - \frac{1}{2} - 1, 2, 0 \right) \right\}$$

$$- \left(\frac{P_{-1}}{1T} - \frac{\partial}{\partial P_{-1}} \right) \left(\frac{1}{2} 1 0 - \frac{1}{2} - 1, 2, 0 \right) - \left(\frac{P_{1}}{1T} - \frac{\partial}{\partial P_{1}} \right) \left(\frac{1}{2} 0 0 - \frac{1}{2} 0, 2, -1 \right)$$

$$- i \frac{P_{o}}{1} f(\underline{p}) + \tau_{2}^{-1} \sum_{i} L(x_{i}) f.$$

$$(50)$$

Here the central subscript refers to the zeroth sidechain, and

we have used the fact that $\{n_j\}$ differs from a pure gaussian by $O(E^2)$ if $\sum_{j=1}^{\infty} n_j = 0$. Rewriting the above in dimensionless variables and using translational invariance gives

$$\begin{split} & \left[\sum_{i} L(x_{i}) + i \left(\omega \tau_{2} - x_{o} \left(\frac{\tau_{2}}{\tau_{1}} \right)^{\frac{1}{2}} \right) \right] f(\underline{x}) \\ &= -i \left(\frac{\tau_{2}}{\tau_{1}} \right)^{\frac{1}{2}} \frac{E}{2T} (x_{o} + x_{-1} - 10 + x_{1} - 01 - 1) \\ &+ i \left(\frac{\tau_{2}}{\tau_{1}} \right)^{\frac{1}{2}} \frac{V}{2T} \left\{ \left(x_{o} - \frac{\partial}{\partial x_{o}} \right) \left(f(\underline{x}^{+}) + f(x^{-}) - \frac{\delta}{2} - 02 - 1 - \frac{\delta}{2} - 120 \right) \right. \\ & \left. - \left(x - 1 - \frac{\partial}{\partial x_{-1}} \right) \left(f(\underline{x}^{-}) - \frac{\delta}{2} - 1, 2, 0 \right) - \left(x_{1} - \frac{\partial}{\partial x_{1}} \right) \left(f(\underline{x}^{+}) - \frac{\delta}{2} - 0, 2, -1 \right) \right\} \end{split}$$

$$(51)$$

where, if
$$f(\underline{x}) = f(...x_{-1}, x_0, x_1, ...)$$

then $f(\underline{x}^+) = f(...x_0, x_1, x_2, ...)$
and $f(\underline{x}^-) = f(...x_{-2}, x_{-1}, x_0, ...)$. (52)

All the terms on the right hand side of (51) are linear in E/2T (which we now set to unity) and it is now clear that we can write equation (46), where f_{O} satisfies (44) and

$$\left[L(x_{o}) + L(x_{1}) + i\left(\omega\tau_{2} - x_{o}\left(\frac{\tau_{2}}{\tau_{1}}\right)^{\frac{1}{2}}\right)\right]f_{1}(x_{o}, x_{1}) \\
= i\left(\frac{\tau_{2}}{\tau_{1}}\right)^{\frac{1}{2}}(x_{1} + (x_{o} - x_{1})f_{o}(x_{1}) + \frac{\partial}{\partial x_{1}}f_{o}(x_{1})).$$
(53)

We have used a modified relaxation method to solve this equation. (See Appendix B.) The solution enables us to calculate the first order correction to the susceptibility, according to

$$\chi = \chi_{o} + 2\left(\frac{v}{2T}\right)\chi_{1} + \theta\left(\frac{v}{2T}\right)^{2}$$

$$\chi_{1} = \frac{1}{2\pi} \int dx_{o} e^{-x_{o}^{2}/2} \int dx_{1} e^{-x_{1}^{2}/2} f_{1}(x_{o}, x_{1}) . \tag{54}$$

Typical results are shown in Figures 8, 9, and 10.

VI. Dynamic Correlation Functions

The susceptibility is related to a time-dependent correlation function according to 11

$$(\mathbf{x_i} \mathbf{x_k})_{\omega} = \frac{\mathbf{T}}{\pi \omega} \quad \chi_{ik}^{\prime\prime}(\omega) \tag{55}$$

or, for our case,

$$\frac{1}{\pi} \int_{0}^{\infty} \langle \cos \varphi_{0}(t) \cos \varphi_{1}(0) \rangle e^{i\omega t} dt = \frac{1}{2\pi\omega} \left(\frac{v}{2T}\right) \chi_{1}^{"}(\omega) \quad (56)$$

and

For the viscous case we had

$$X = (1 + 2x - iz)^{-1} + 0(x^{2})$$

$$= (1 - iz)^{-1} + 2x/(1-iz)^{2} + 0(x^{2})$$
(58)

so that

$$\chi_1^{\text{(viscous)}} = -(1 - iz)^{-2}$$

$$\chi_1^{\text{(viscous)}} = -2z/(1 + z^2)^2$$
(59)

Here we define $z = \omega_{T_1} = \omega$ if we take $\tau_1 = 1$. We then have

<
$$\cos \varphi_0(t)\cos \varphi_1(0)$$
 > = $-\frac{v}{2T} \int_{-\infty}^{\infty} \frac{1}{2\pi} e^{izt} \frac{2dz}{(1+z^2)^2}$
= $-\frac{1}{2} \left(\frac{v}{2T}\right) \left(1+t\right) e^{-t}$. (60)

We have numerically evaluated these correlation functions for three non-viscous cases, and these are shown in Figures 11 and 12. The errors on the curve $\tau_2 = 0.3$ are particularly large, so that this curve should not be taken too seriously.

One should observe, however, that (1) for large τ_2 the time scale of the correlations appears to vary like $\tau_2^{\frac{1}{2}}$, and (2) the correlation reaches a broad maximum before decaying. The first may be understood by noting that the characteristic angular velocity in the problem is $\frac{1}{1} < p^2 >^{\frac{1}{2}} = (\tau_1 \tau_2)^{-\frac{1}{2}}$. The second follows from noting that a measurement of $\cos \varphi_0(0)$ corresponds to a measurement of the force field on a neighboring particle at time zero, and this will be reflected in the position of the particle at some later time.

VII. Non-Einstein Damping

We have begun to examine the effect on the single-particle susceptibility of a random force more complex than the Einstein case we have used thus far. Such a force, which we describe by its moments $\mu_{\bf i}$, must satisfy the conditions that the Maxwell-Boltzmann distribution be both stationary and stable.

In the absence of applied field we may write

$$P(p,t) = (1 + g(p,t)) \exp(-p^2/2IT)$$
 (61)

and

$$\frac{\partial \rho}{\partial t} = \sum_{n=1}^{\infty} (-1)^n \frac{1}{n!} \frac{\partial^n}{\partial p^n} (u_n \rho). \tag{62}$$

The stationarity condition may be satisfied by choosing, for any n,

$$\mu_{2n} = (2n)! \xi_n IT$$

$$\mu_{2n-1} = -(2n-1)! \xi_n P$$
(63)

This gives

$$\frac{\partial P}{\partial t} = \sum_{n=1}^{\infty} \frac{\partial^{2n-1}}{\partial p^{2n-1}} \left\{ \xi_n p P + \xi_n I T \frac{\partial P}{\partial p} \right\}$$

$$= \sum_{n=1}^{\infty} \frac{\partial^{2n-1}}{\partial p^{2n-1}} \left\{ \xi_n I T \frac{\partial R}{\partial p} \exp(-p^2/IT) \right\} \tag{64}$$

which clearly vanishes for g = constant. For a collection of N such pairs of moments (63), g(x, t) will satisfy an equation of the form

$$\frac{\partial g}{\partial t} = \xi_{N} \frac{\partial^{2N} g}{\partial x^{2N}} - (2N - 1)\xi_{N} \times \frac{\partial^{2N-1} g}{\partial g^{2N-1}} + \dots + h_{2}(x^{2}) \frac{\partial^{2} g}{\partial x^{2}} + xh_{1}(x^{2}) \frac{\partial g}{\partial x}$$
(65)

where h_1 and h_2 are polynomials of degree N - 1. (The right hand side of (65) corresponds to the linear operator L of section V.) We may now consider the question of the stability of the Maxwell-Boltzmann distribution. For concreteness, we consider a distortion of the form $g \sim \cos \alpha x$. For α sufficiently small, such a distortion will decay in time as long as $h_2(x^2) > 0$. However, for large α the (2N)th derivative will be the dominant term, and, since the μ_n 's are all positive-definite, this says that N must be odd to insure stability against a distortion which varies rapidly as a function of momentum.

We have done a few calculations using the method of Appendix A for the case N = 3, for which L takes the form

$$L(x) = \xi_{3} \left(\frac{\delta^{6}}{\delta x^{6}} - 5x \frac{\delta^{5}}{\delta x^{5}} \right) + \left(\xi_{2} + 10\xi_{3}(x^{2} - 1) \right) \frac{\delta^{4}}{\delta x^{4}}$$

$$+ x(10\xi_{3}(3 - x^{2}) - 3\xi_{2}) \frac{\delta^{3}}{\delta x^{3}}$$

$$+ \left[1 + 5\xi_{3}(x^{4} - 6x^{2} + 3) + 3\xi_{2}(x^{2} - 1) \right] \frac{\delta^{2}}{\delta x^{2}}$$

$$+ x[\xi_{2}(3 - x^{2}) - \xi_{3}(x^{4} - 10x^{2} + 15) - 1] \frac{\delta}{\delta x}$$
(66)

Some results are shown in Figure 13.

The susceptibility is determined by the function $f_0(x) = 1 + g(x)$, where g satisfies

$$L(x) g(x) + \frac{1}{2}(\omega_{\tau_2} - (\tau_2/\tau_1)^{\frac{1}{2}})g(x) = -i\omega_{\tau_2}.$$
 (67)

One should note that the behavior of g(x) for $|x| \to \infty$ is very different in the N > 1 case from the Einstein (N = 1) case. For N = 1, the dominant term on the left is $-i(\tau_2/\tau_1)^{\frac{1}{2}}xg(x)$, so that

$$g(x) \xrightarrow{} \omega(\tau_1 \tau_2)^{\frac{1}{2}}/x . \tag{68}$$

For N > 1, the dominant term is $-\xi_N \propto^{2N-1} \frac{\partial}{\partial x} g(x)$, so that

$$\mathbf{g}(\mathbf{x}) \xrightarrow{\mathbf{i}\omega_{\uparrow_{2}}} -\mathbf{i}\omega_{\uparrow_{2}}/(\xi_{\mathbf{N}} \mathbf{x}^{2\mathbf{N}-2}) . \tag{69}$$

This results in decreased absorption at high frequencies.

VIII. Conclusions

We have produced a model polymer whose dielectric relaxation can be solved under a variety of conditions:

At low frequencies,

$$\chi(\omega) = \frac{2T}{N\mu^2} (\varepsilon(\omega) - \varepsilon_{\infty}) \xrightarrow{\omega \to 0} \frac{I_o(2x) - I_o(2x)}{I_o(2x) + I_o^{\dagger}(2x)}$$
(70)

where x = v/2T. For x >> 1, $\chi(0) \rightarrow 1/8x$.

- (2) In the viscous limit χ(ω) may be expanded as a power series in x (high temperature expansion). The high frequency end of the Cole-Cole plot is shifted to the right by the interaction, but we find no indication of the slope's becoming finite near the origin. The shape of the curve depends only on the parameter x = v/2T.
- (3) For the finite viscosity the problem is characterized by two times: a kinematic time $\tau_2 = \eta^{-1}$, and a relaxation time τ_1 = $\eta I/T$, the viscous limit applying for $\tau_2 << \tau_1$. The non-interacting problem can be solved exactly (i.e., reduced to the solution of a differential equation), and a high temperature expansion exists in the more general In particular, dynamic correlation functions can be calculated for small x.
- (4) Our method can be generalized to include a more complex random force. It is possible to construct a force for which the high frequency susceptibility moves to the

right of the Debye semicircle, even in the finite viscosity non-interacting case.

None of the above cases convincingly reproduces a ColeCole plot such as that of Figure 1, unless one is willing to
believe that the method of section VII, with a judicious choice
of moments (possibly an infinite number), can give such
behavior. A more likely cause of this effect is off-diagonal
viscosity, i.e., the random torque on a given sidechain
depends on the angular momentum of its neighbors. We have
neglected this possibility in deriving equation (21), but
it should be possible to generalize our methods to this case.

We believe this model to be interesting in its own right, as well as shedding some light on the question of polymer relaxation.

Acknowledgments

The author wishes to thank J. A. Krumhansl for initiating his interest in this problem and for several fruitful conversations. He would also like to thank M. Nelkin and R. N. Work for useful conversations and references, the latter also for some unpublished data, and N. Singer for a useful discussion on numerical analysis.

Appendix A. Method for Numerical Solution of (44)

This is a special case of a linear differential equation on the domain $-\infty < x < \infty$. The first step is to transform the real line into a finite interval by a change of variables such as

$$x = \alpha \tan \beta \emptyset . (A1)$$

Next we discretize the problem by dividing the interval $-\pi/2\beta < \emptyset < \pi/2\beta$ into N subintervals of length $\Delta = \pi/N\beta$, and replacing the derivatives by the corresponding symmetric finite differences, e.g.,

$$\frac{dy}{dx} \rightarrow \frac{y_{n+1} - y_{n-1}}{2\Delta} \tag{A2}$$

$$\frac{d^2y}{dx^2} \to \frac{y_{n+1} - 2y_n + y_{n-1}}{\Delta^2}$$
 (A3)

etc.

This procedure will give, for a differential equation of order 2π , (N+1-2m) equations for N+1 unknowns y_n . The remaining 2m equations are supplied by the boundary conditions. (The boundary conditions for (44) are $f_0=1$ for $x=\pm\infty$.) It is known that under fairly general conditions the solution of the discrete problem will converge to that of the continuous problem as $N\to\infty$.

We have now reduced the problem to solving a set of complex linear equations

 $AY = B \tag{A4}$

where A is an (N + 1) by (N + 1) matrix. In general, the computer time required to solve such a problem is at least $O(N^2)$, but by taking advantage of the fact that A is band-diagonal we may reduce the time to O(N).

We have solved equation (44) using the SSP subroutine GELB¹², modified for complex numbers, and taking α = 3, β = $\frac{1}{2}$, and N = 40. The time required to solve the equation for one set of parameters is less than one second on the Cornell University IBM 360/65.

Appendix B. Method of Solution of Equation (53)

This equation is of the form $L(x_1,x_2)f = R(x_1,x_2)$ where R is a known function and L is a linear operator. This may be converted into a discrete problem with $(N+1)^2$ mesh points, but the matrix will not be band diagonal.

The usual relaxation method is as follows: We make an initial guess, satisfying the appropriate boundary conditions, for the solution f. The interior equations are of the form

$$L^{D}(x_{i},x_{j},f(x_{i},x_{j}),\underline{x}^{p},f(\underline{x}^{p})) = R(x_{i},x_{j})$$
 (B1)
where \underline{x}^{p} denotes the set of points immediately surrounding (x_{i},x_{j}) . A measure of the distance of our guess from the exact solution is

$$s - \sum_{i,j} s_{ij}$$

where

$$S_{ij} = L^{D} - R.$$
 (B2)

We then choose a point (x_i, x_j) and solve (B1) for $f(x_i, x_j)$. This sets S_{ij} to zero, but may increase the S_{k1} 's on the set \underline{x}^p , in which case the method may diverge.

The modification is to solve (B1) simultaneously on an nxn square of points (x_i, x_j) . This reduces the number of points \underline{x}^p relative to the number of points for which $S_{ij} = 0$, and should improve the chance of convergence.

We solved (53) using N=20 and n=3. The method always converged, while the usual relaxation method often diverged. However, convergence in some cases was rather slow.

References

- * This work has been supported by the U.S. Atomic Energy Commission under Contract No. AT(11-1)3161, Technical Report No. COO-3161-2.
- R. J. Glauber, J. Math. Phys. 4, 294 (1963).
- I. Oppenheim, K. E. Shuler, and G. H. Weiss, J. Chem.
 Phys. <u>46</u>, 4100 (1967) and J. Chem. Phys. <u>50</u>, 3662 (1969).
- 3. E. Simon, J. Chem. Phys. 52, 3879 (1970).
- 4. K. Iwata and M. Kuruta, J. Chem. Phys. 50, 4008 (1969).
- 5. J. E. Anderson, J. Chem. Phys. <u>52</u>, 2821 (1970).
- 6. R. N. Work and S. Fujita, J. Chem. Phys. <u>45</u>, 3779 (1966). The results of this paper must be questioned because their "correlation" term $\gamma_{jk}(\phi^j \phi^k; t t')$ is double-valued if written as $\gamma(s s'; t t')$ with $s = \phi^j + 2j\pi$.
- A collection of such data may be found in S. Havriliak and S. Negami, Polymer 8, 161 (1967).
- 8. M. E. Fisher, Amer. J. Phys. 32, 343 (1964).
- 9. H. A. Kramers, Physica VII, 284 (1940).
- 10. The number of problems for which this equation can be solved is usually considered small. We are not aware of any previous solution of this case.

- 11. L. D. Landau and E. M. Lifshitz, <u>Statistical Physics</u>
 (Addison-Wesley, Reading, Massachusetts, 1969).
- 12. System/360 Scientific Subroutine Package (360A-CM-03X)

 Version III Programmer's Manual (International Business

 Machines Corp., 1968).

Figure Captions

- Figure 1: Typical Cole-Cole plot of dielectric relaxation for a sidechain polymer. The dotted line is a semicircle.
- Figure 2: Specific heat and correlation function <-exp $i(\phi_0^- \phi_1^-)$ > for a sidechain polymer. A discontinuity appears at (v/2T) = 1.7 for computational reasons.
- Figure 3: Cole-Cole plots in the viscous limit for x = 0,

 0.1, 0.2, 0.4, 0.6, 1.0. The crosses indicate the

 exact zero frequency results for x = 0.6 and x = 1.0.

 The dashed lines are lines of constant frequency.
- Figure 4: Enlargement of the x = 1.0 plot of Figure 3. The dashed line is a semicircle.
- Figure 5: The function $f_0(x) e^{-x^2/2}$ for $\tau_1 = \tau_2 = 1$ and (a) $\omega = .125$, (b) $\omega = 1.0$, and (c) $\omega = 4.0$.
- Figure 6: Cole-Cole plots for $\tau_2/\tau_1 = 0.1$ (smallest curve), $\tau_2/\tau_1 = 0.316$, $\tau_2/\tau_1 = 1.0$, $\tau_2/\tau_1 = 3.16$, and $\tau_2/\tau_1 = 10.0$ (largest curve). The dashed line is a semicircle.
- Figure 7: Absorption X" for the same five cases as in Figure 6.

 Curve A is $\tau_2/\tau_1 = 0.1$; curve E is $\tau_2/\tau_1 = 10$.

 The dashed line is $z/(1+z^2)$.
- Figure 8: The change in absorption $(-\chi_1^n)$ for (A) $\tau_2/\tau_1 = 0$, (B) $\tau_2/\tau_1 = .316$, (C) $\tau_2/\tau_1 = 1.0$, (D) $\tau_2/\tau_1 = 3.16$.
- Figure 9: χ_1 (solid line) and χ_1 (dashed line) for $\tau_2/\tau_1 = 1.0$.

- Figure 10: Cole-Cole plots for $\tau_2/\tau_1 = 1.0$ and v = 0 (upper curve) and (v/2T) = 0.15 (lower curve).
- Figure 11: The correlation function $\chi_1^{''}/\omega$ for (A) $\tau_2/\tau_1 = 0$, (B) $\tau_2/\tau_1 = .316$, (c) $\tau_2/\tau_1 = 1.0$, (d) $\tau_2/\tau_1 = 3.16$.
- Figure 12: The correlation function $< \cos \theta_0(t) \cos \theta_1(0) >$ for the same cases as Figure 11.
- Figure 13: Cole-Cole plots for non-Einstein damping: $\xi_2 = 2/3$, $\xi_3 = 1/15$, and $\tau_2^2/\tau_1 = 0.1$ (upper curve), $\tau_2/\tau_1 = 1.0$ (lower curve). The dashed line is a semicircle.

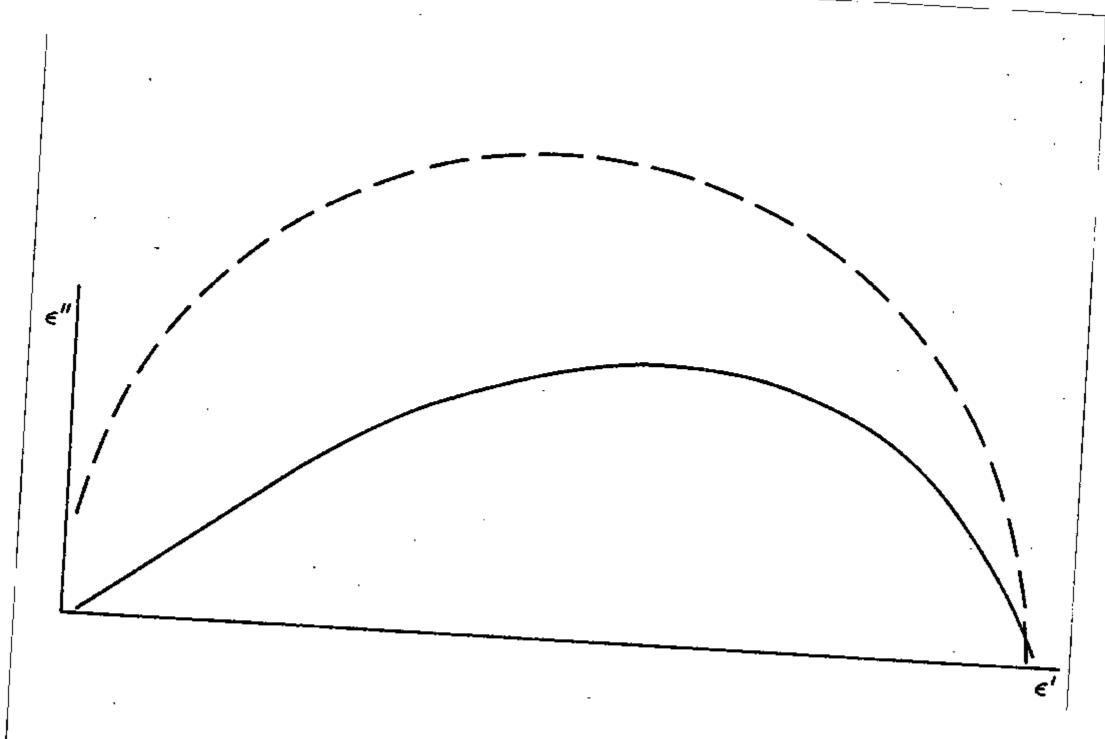


Figure I

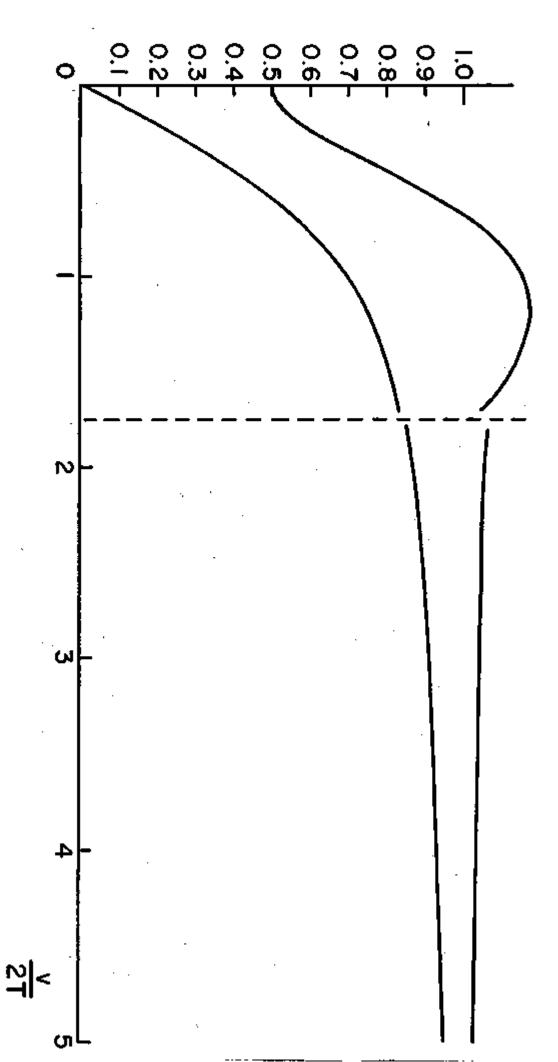
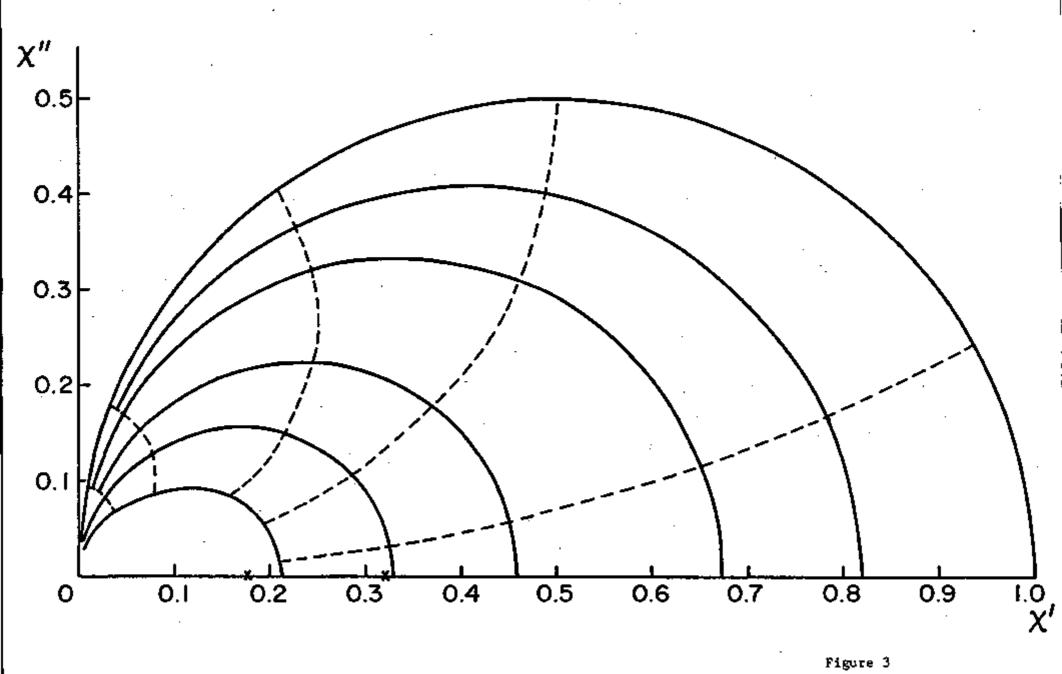


Figure 2



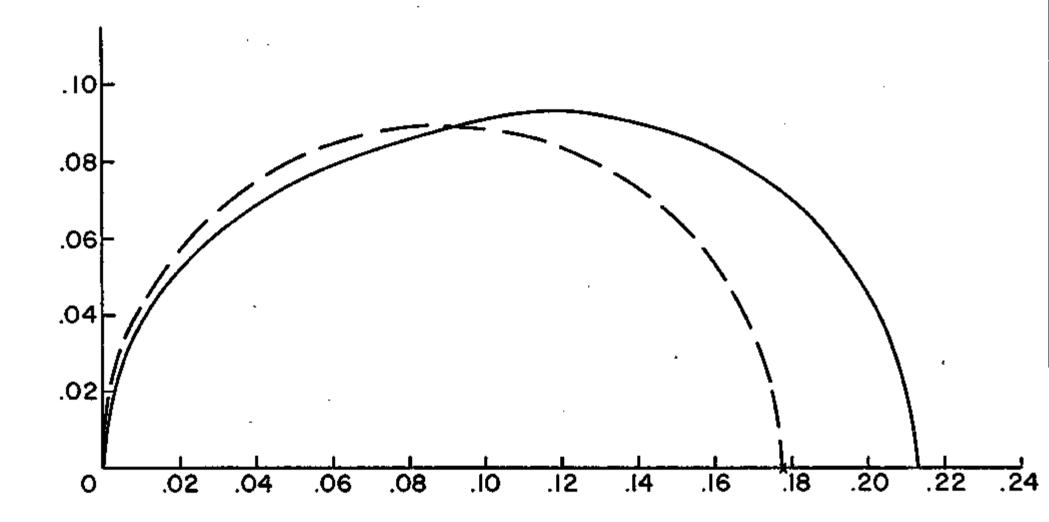
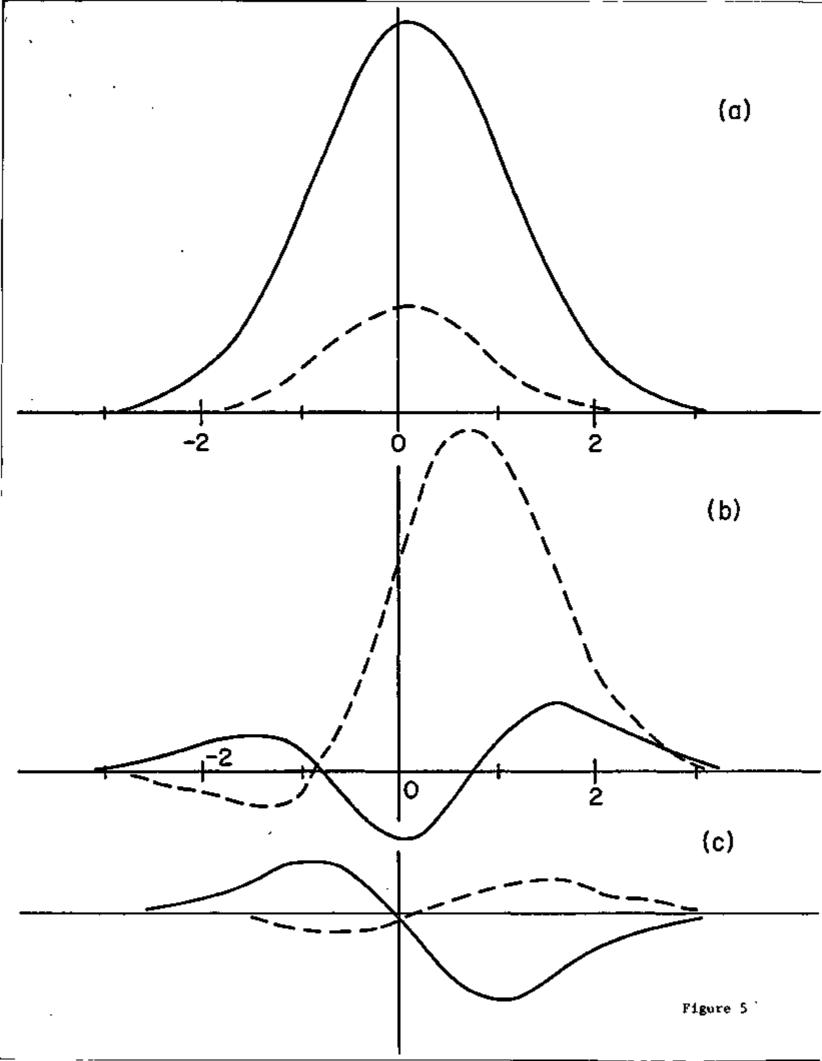
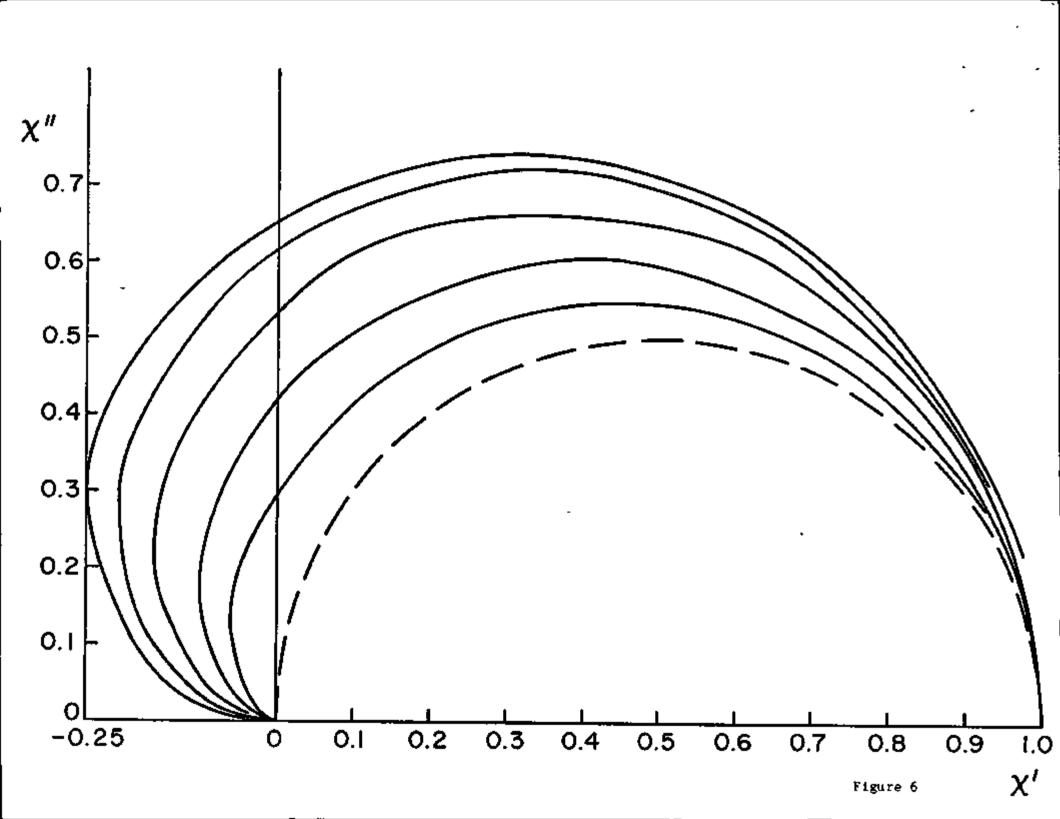
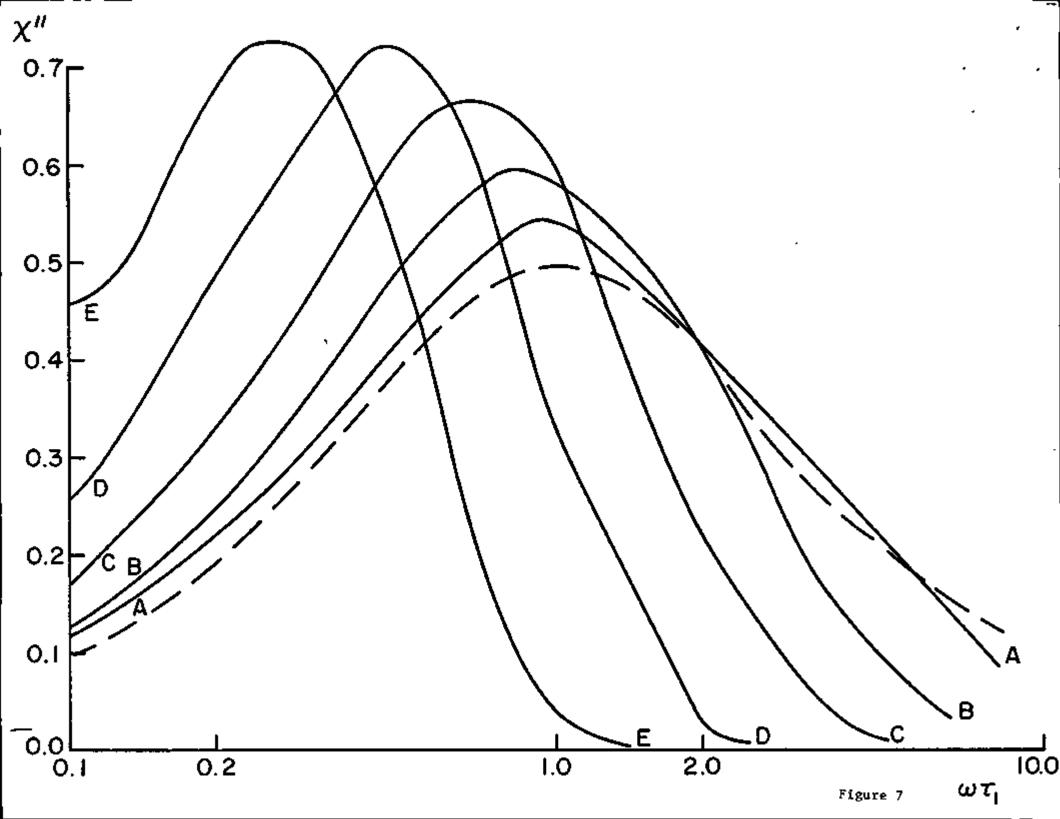
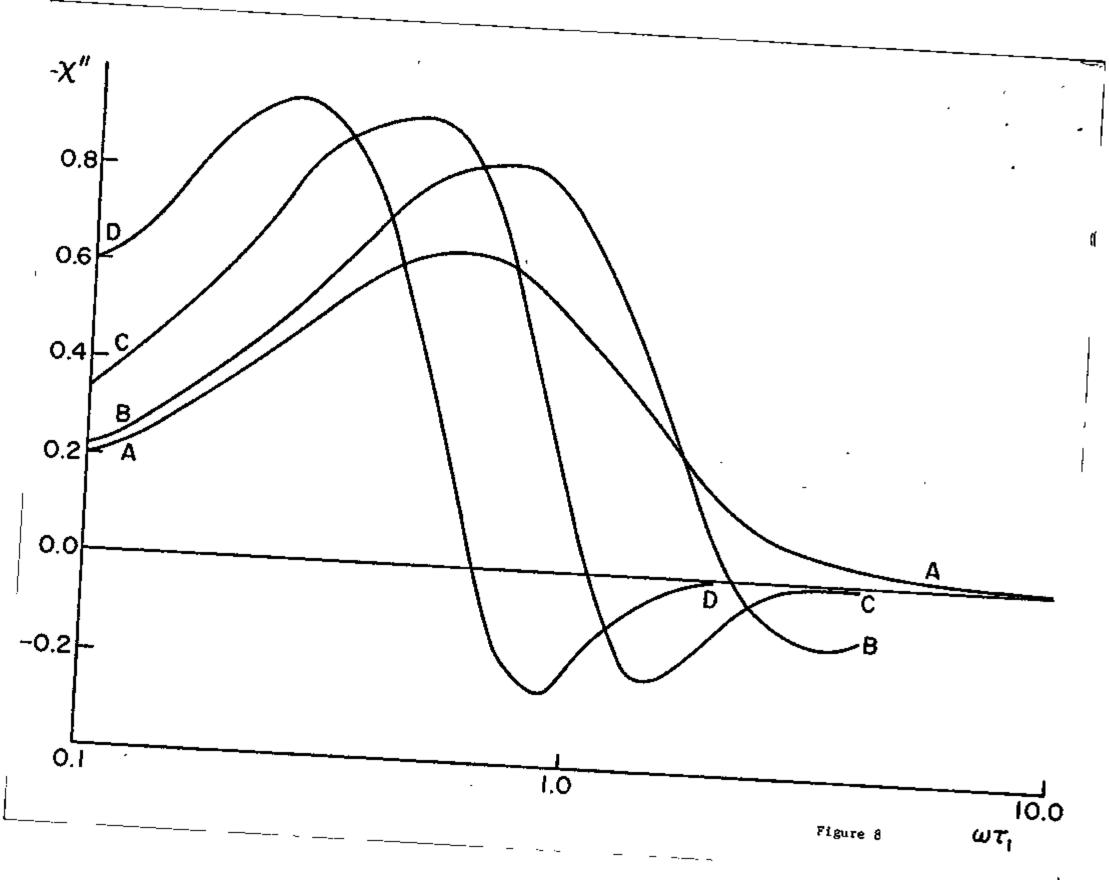


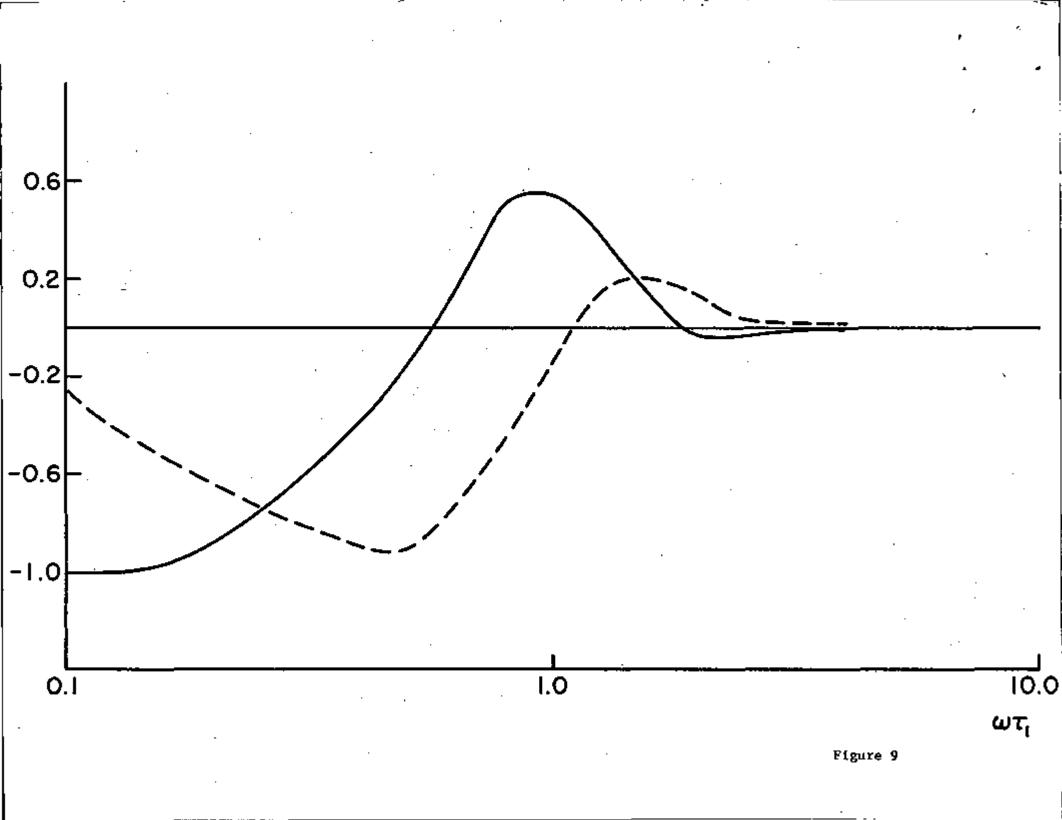
Figure 4











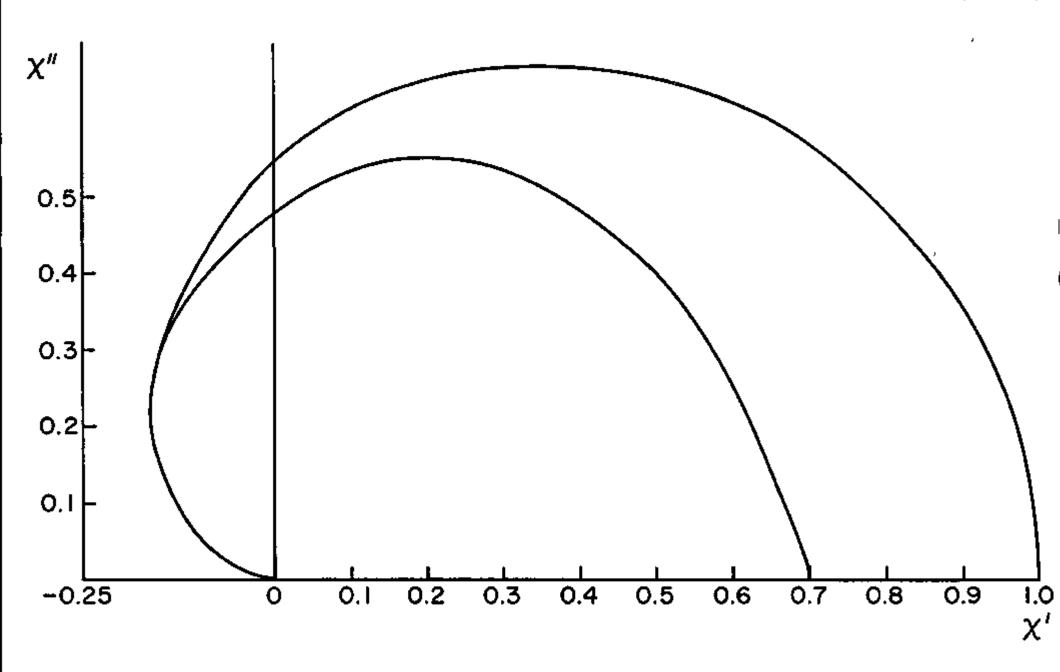
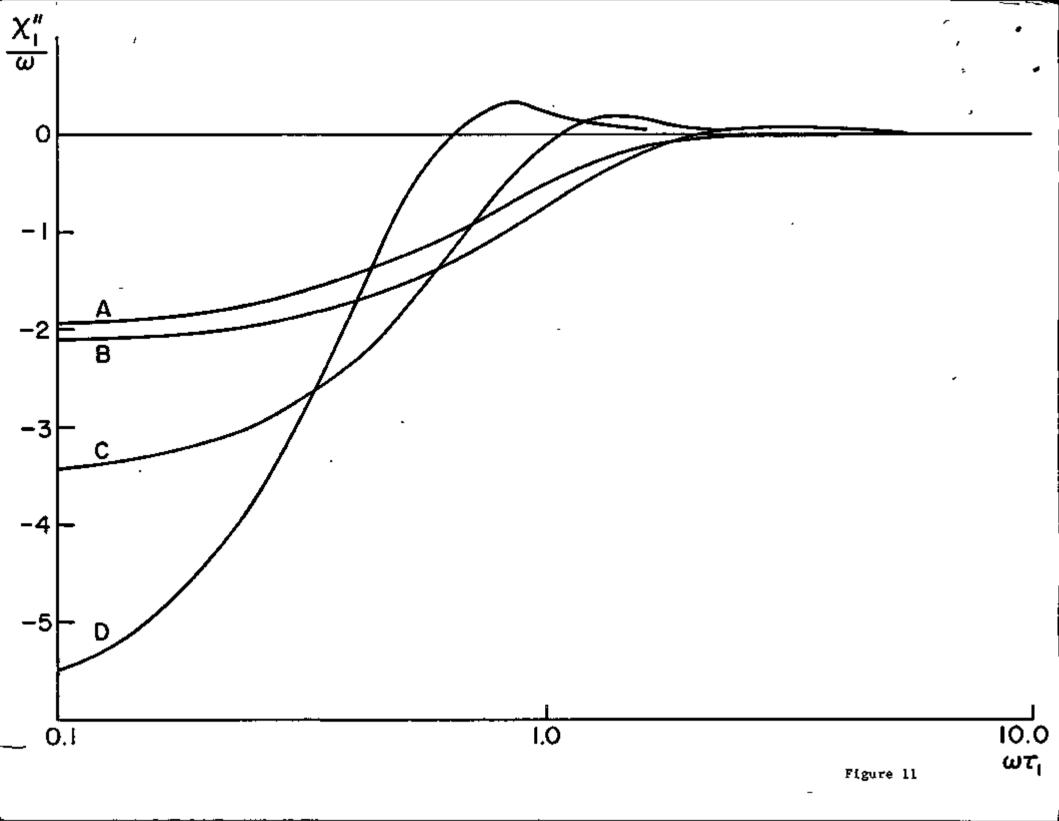


Figure 10



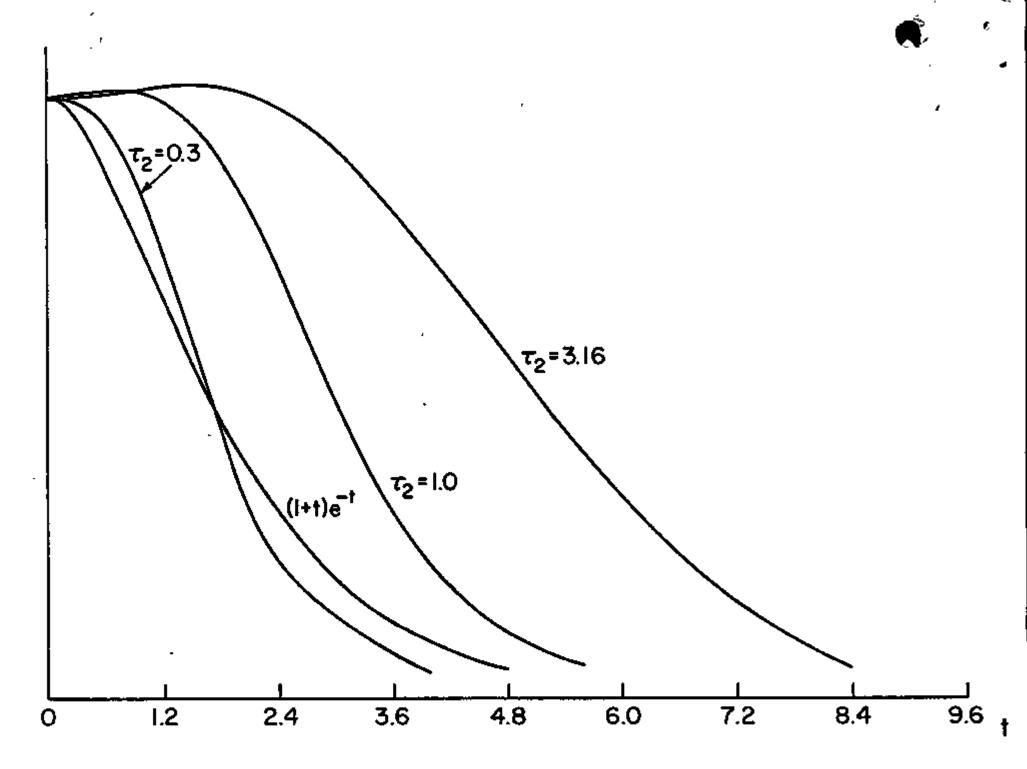


Figure 12

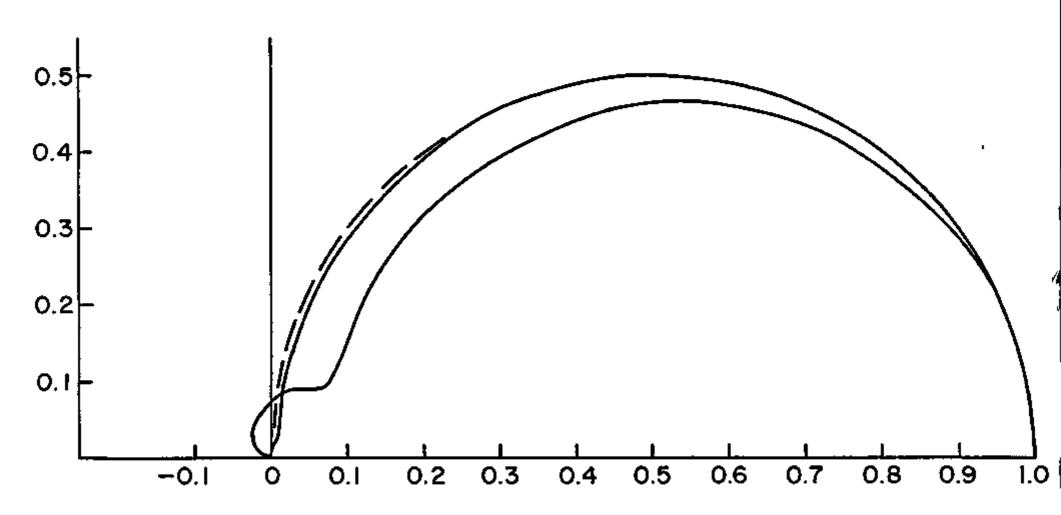


Figure 13