

Effect of Platooning on Fuel Consumption of Class 8 Vehicles Over a Range of Speeds, Following Distances, and Mass

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ABSTRACT

This research project evaluates fuel consumption results of two Class 8 tractor-trailer combinations platooned together compared to their standalone fuel consumption. A series of ten modified SAE Type II J1321 fuel consumption track tests were performed to document fuel consumption of two platooned vehicles and a control vehicle at varying steady-state speeds, following distances, and gross vehicle weights (GVWs). The steady-state speeds ranged from 55 mph to 70 mph, the following distances ranged from a 20-ft following distance to a 75-ft following distance, and the GVWs were 65K lbs and 80K lbs. All tractors involved had U.S. Environmental Protection Agency (EPA) SmartWay-compliant aerodynamics packages installed, and the trailers were equipped with side skirts. Effects of vehicle speed, following distance, and GVW on fuel consumption were observed and analyzed. The platooning demonstration system used in this study consisted of radar systems, Dedicated Short-Range Communication (DSRC) vehicle-to-vehicle (V2V) communications, vehicle braking and torque control interface, cameras and driver displays. The lead tractor consistently demonstrated an improvement in average fuel consumption reduction as following distance decreased, with results showing 2.7% to 5.3% fuel savings at a GVW of 65k. The trailing vehicle achieved fuel consumption savings ranging from 2.8% to 9.7%; tests during which the engine cooling fan did not operate achieved savings of 8.4% to 9.7%. "Team" fuel savings, considering the platooned vehicles as one, ranged from 3.7% to 6.4%, with the best combined result being for 55 mph, 30-ft following distance, and 65k GVW.

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INTRODUCTION

Vehicle automation is a promising petroleum reduction technology, and platooning systems for heavy-duty vehicles are likely to be a first step towards acceptance of vehicle automation. These systems may employ existing technologies such as radar or laser range finders, global positioning system (GPS), dedicated vehicle-to-vehicle communications (V2V), and braking and engine torque authority to enable vehicles to follow safely in close proximity with the goal of reducing fuel consumption, traffic congestion, and possibly collisions.

Early studies have consistently suggested significant fuel savings from the reduced aerodynamic drag; however, because platooning systems are still emerging technologies that are not yet commercially available, questions remain about how effective they will be at reducing fuel consumption in the real world and under what conditions they will perform best.

As part of the California Partners for Advanced Transportation Technology (PATH) program, Browand et al. found that platooning vehicles were able to achieve 8%-11% in fuel consumption savings from 3- to 10-meter following distance. Tests were conducted on an unused runway in two directions with a usable 220-350 meter overlap to collect data. Two

identical 2001 Freightliner Century Class trucks powered by Cummins N14 Celec engines were used in the testing with empty or lightly loaded trailers. The fuel rate was derived from on-board vehicle bus communication signals versus weighing tanks, and test speeds of 50-55 mph were employed. Spacing of 10 meters found 10% and 6% fuel consumption savings, respectively, for the trailing and lead truck. In the spacing range of 3-10 meters, fuel consumption was reduced in the range 10%-12% for the trailing truck and 5%-10% for the lead truck. Vehicle mass was not specified, but the test trailers were empty. [1]

Alam et al. found a maximum fuel reduction of 4.7%-7.7% depending on the following distance at a set speed of 70 km/h (44 mph) with two identical European cab-over trucks at 40,000 kg (88K lbs GVW) [2].

Tsugawa et al. showed through modeling and track testing that a three-truck platoon at 80 km/h (50 mph) and a 10-meter following distance could improve fuel consumption by an average of 14% with the lead truck experiencing a 7.5% reduction and the tail truck experiencing a 16% reduction. European style cab-over tractors were used, and vehicle mass was not specified. [3]

The New Energy and Industrial Technology Development Organization (NEDO) in Japan showed with track testing that a platoon of four cab-over straight trucks maintaining a 4-meter following distance and 80 km/h (50 mph) speeds attained a 15% average improvement. Vehicle mass was not specified. [4]

This research project, funded by the Department of Energy (DOE), evaluated the fuel consumption reduction of a pair of platooned Class 8 tractor-trailers on a track over a range of highway truck speeds, following distances, and weights that would represent driving on public road conditions under test track conditions. The project was managed by the National Renewable Energy Laboratory (NREL), and the tests were performed by Intertek Testing Services NA and LINK Engineering. Testing took place at the Continental Tire Proving Grounds [5] in Uvalde, Texas, which is an 8.5-mile (13.7-km)) asphalt oval with several small grade changes rather than a zero grade environment. As such, the constant-speed tests operated under cruise control had an average speed standard deviation of ± 0.6 mph and a maximum deviation of 1.0 mph as the heavy tractors responded to the small grade changes. The fuel consumption savings were recorded through methods prescribed in SAE J1321 Fuel Consumption Test Procedure [6]. Effects on engine cooling to the trailing vehicle from platooning were recorded with data logging devices through the use of J1939 controller area network (CAN) bus messages [7].

BACKGROUND AND METHODS

Test Track Selection

The Continental Tire Uvalde Proving Grounds track is a three-lane wide, 8.5-mile (13.7 km) oval with one-mile radius turns and a 1.1-mile straightaway between the turns. The oval track is shown in a satellite view in [Figure 1](#). The track is not perfectly level, but rather has several small elevation changes of approximately 15 ft, resulting in gentle grade changes throughout the lap.



Figure 1. 8.5-mile oval at Continental Tire Uvalde Proving Grounds (© Google Earth)

Vehicle Selection and Details

Several previous studies tested platooning on older tractors, which paid less attention to base aerodynamics than many tractors popular in the United States today or cab-over designs popular outside the United States, which may respond to platooning differently [1, 2, 3, 4]. In this study, modern "aero" model tractors with EPA's SmartWay-compliant [8] design packages and trailer side skirts were tested. The authors feel that this should be more representative of fleets that would adopt platooning technology in the United States if it becomes available, as many fleets are currently making aerodynamic packages standard across their fleet. EPA Phase 2 greenhouse gas emissions and fuel efficiency standards in preliminary rulemaking likely will make improved aerodynamics standard across the new Class 8 truck population. [Table 1](#) lists the test tractor and trailer specifications. [Figures 2, 3, and 4](#) show the lead, trailing, and control test tractor-trailer combinations, respectively.

Table 1. Test tractor and trailer specifications

Van Specification	Lead Tractor-Trailer	Trailing Tractor-Trailer	Control Tractor-Trailer
Manufacturer	Peterbilt	Peterbilt	Peterbilt
Model	386	386	579
Model year	2011	2011	2013
Vehicle Mileage at Test Start	325,367	360,334	43,618
Engine manufacturer	Cummins	Cummins	PACCAR
Engine model	ISX-15 450	ISX-15 450	MX-13 475
Engine model year	2010	2010	2010
Emissions equipment	DOC/DPF/SCR	DOC/DPF/SCR	DOC/DPF/SCR
Transmission	Eaton Fuller 10-speed	Eaton Fuller 10-speed	Eaton Fuller 10-speed
Retarder/regenerative braking	Engine Brake	Engine Brake	Engine Brake
Tires	Michelin XDA Energy	Michelin XDA Energy	Goodyear Fuel MAX
Cab Fairing to nose of trailer (visible space between tractor and trailer)	50"	50"	41"
Trailer Configuration	53-ft Van Trailer with angled side skirts	53-ft Van Trailer with angled side skirts	53-ft Van Trailer with angled side skirts
Trailer Manufacturer	Great Dane	Stoughton	Wabash
Trailer Model	74111 SSLAK	2GPVW-53ST-S-L-AR	TRA/ VAN
Trailer Height	13' 6"	13' 6"	13' 6"
Trailer Width	102"	102"	102"
King Pin Set Back	36"	36"	36"
Trailer Side Skirt	Freight Wing AeroFlex	Freight Wing AeroFlex	DuraPlate AeroSkirt
Distance from rear of trailer side skirt to front of trailer wheels	6.5"	8.5"	9.5"



Figure 2. Lead platoon tractor and trailer Photo by Alex Nicholson, Link Engineering Company



Figure 3. Trailing platoon tractor and trailer; Photo by Alex Nicholson, Link Engineering Company

The platooning demonstration system used is from Peloton Technology, Inc. [9], and includes radar systems, Dedicated Short-Range Communication (DSRC) [10] vehicle-to-vehicle communications, vehicle braking and torque control interface, cameras and driver displays. Table 2 lists the specifications of the platooning demonstration system tested. The system controls the throttle and braking on the rear truck using a combination of inputs including, but not limited to: radar-measured distance, GPS locations and speeds of both

vehicles, lead vehicle wheel-based speed, torque request and braking application. The system does not control lateral position so the trailing truck driver is still responsible for steering, which is a possible source of variation in the tests.



Figure 4. Control tractor and trailer; Photo by Alex Nicholson, Link Engineering Company

Table 2. Demonstration platooning system specifications

Category	Demonstration Platooning System Description
Manufacturer/integrator	Peloton Technology Inc.
Radar	Delphi Electronic Scanning Radar: Dual beams Short range +/- 45degree beam, 60m range Long range +/- 10 degree beam 175m range 20 Hz update rate Mounted in front bumper
Dedicated Short Range Communications	Denso DSRC Radio WSU 1.5 Dual antennas in diversity mode Omni-directional antennae mounted on mirrors Single 10 MHz channel Single-board computer and 5.9 GHz DSRC radio Supports IEEE 802.11p, P1609.3, P1609.4, P1609.2
Vehicle communication	CAN/J1939 interface through interface card in embedded PC Private Controller Area Network (CAN) for sensors J1939 for vehicle bus and actuation
ABS/Stability control	Meritor Wabco Brakes ESC with J1939 brake actuation capability

Variable Speed Track Testing

Because some of the nation's highway traffic flow may not enable constant-speed driving for extended durations, a variable speed test was desired. The system used for this testing disengages the platoon formation if a gear shift, transmission neutral, or brake pedal activation is detected. This necessitated a speed trace that the vehicles could accomplish while staying in top gear and using only engine braking to vary the speed. The "Cruise Mode" section of the California Air Resources Board (CARB) Heavy Heavy-Duty Diesel Truck (HHDDT) schedule [11] was used as a starting point, but the speed range was too low for top gear for a standard line haul tractor; therefore, 10 mph was added to all speed points of the HHDDT to bring the trace into the range of highway driving accomplished in top gear for these tractors. This modified HHDDT schedule was repeated roughly 2.5 times to approach 56 miles, intentionally short of the test distance of 59.5 miles. The variable-speed distance was set shorter than the normal test distance both to allow for error in meeting the trace and to allow the vehicles to enter and exit the test under 60 mph in the cruise control condition using normal test procedures. A heads-up driver's aid that displayed the desired speed for the next 30 seconds as well as current GPS speed, very similar to

driver's aids used in chassis dynamometer testing, was developed to enable the variable speed modified HHDDT testing program. Figure 5 shows a speed trace of the variable-speed program. Drivers were instructed to meet the trace as close as possible, but it was understood that the harder accelerations and decelerations would probably not be matched due to the limitations placed on each driver to remain in the same gear for the entire trace. Additionally, the grade changes of the track meant some accelerations/decelerations occurred on an up or down grade, which either mitigated or exacerbated the difficulty of meeting the trace. Because the trace was time based and started at the same point on the track, all vehicles experienced the same relative duty cycle at each location on the track.

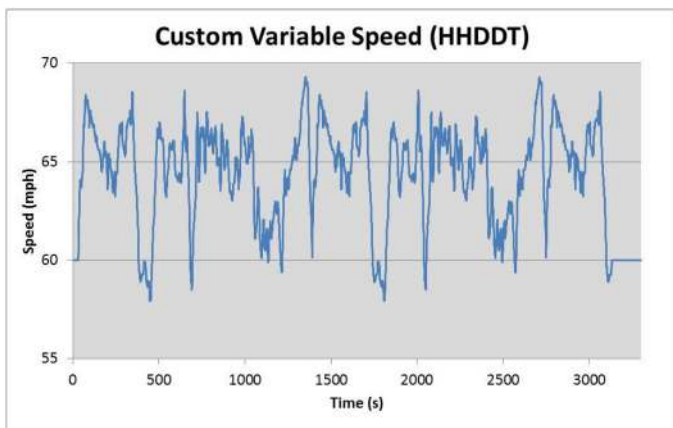


Figure 5. Custom variable-speed test trace based on the HHDDT

Track Testing Procedures

Track testing methods recommended in SAE J1321 Fuel Consumption Test Procedure - Type II (1986) [6] were used with some adaptations for platoon testing. The first modification to the procedure was to have two test vehicles compared independently to the control vehicle during baseline and test condition runs. Thus, two test-to-control (T/C) ratios were calculated for each test. The second modification was to utilize a solenoid valve to switch between vehicle fuel tanks for warm up and test tanks for test runs. As such, "run time" is the total elapsed time from energizing the fuel solenoid valve to de-energizing it (simultaneously triggering the J1939 data acquisition system). This was necessary to allow the test vehicles time to attain platoon formation prior to test start and to end platoon formation after test stop. Also, due to the nature of the dynamic interaction between the two test vehicles on test runs, additional variability outside the prescribed 2% was accepted on three tests. During the initial baseline test at 65 mph with 65,000 GVW and during the 70 ft. and 55 ft. following distance, the climate control and cab fan settings were kept constant with the air-conditioning clutch engaged and vent mode with a fan setting of "3" selected. For each baseline set and test set for the remainder of testing, the air-conditioning clutch was turned off while in vent mode and the fan speed remained at 3 to minimize variability between the control, lead, and trailing trucks. This adjustment was made to eliminate

possible variability from the air-conditioning compressor and was made possible by running tests outside the heat of the day. The test runs and respective baseline runs were always conducted using the same settings and as such all ratios were valid.

A full warm-up procedure was conducted at the start of each test day or after the vehicles had been parked for more than 30 minutes. The full warm-up procedure consisted of the following:

- The vehicles were driven for at least seven laps at the speed of the test segment that followed (55, 65, 70 mph, etc.).
- Fuel was drawn from the vehicle main tank (i.e., not the measured test tank) during the Full Warm-up Procedure.
- The vehicles were platooned together by the end of the warm-up period, allowing the test segment to start immediately upon reaching completion of the warm-up phase.
- Any set points such as cruise control, other speed locking settings, and/or platooning distance settings were set during the Full Warm-up Procedure.

A Partial Warm-up Procedure was conducted if the vehicles were parked for less than 30 minutes, which typically occurred at the end of a test segment. The Partial Warm-up Procedure consisted of the following:

- The vehicles were driven for 16.5 miles at the speed of the test segment to follow (55, 65, 70 mph, etc.).
- Fuel was drawn from the vehicle main tank (i.e., not the measured test tank) during the Partial Warm-up Procedure.
- The vehicles were platooned together by the end of the warm-up period, allowing the test segment to start immediately upon reaching completion of the Partial Warm-up procedure.
- Any set points such as cruise control, other speed locking settings, and/or platooning distance settings were set during the partial warm-up procedure.

A test run procedure was initiated without pause after the appropriate warm-up procedure was completed. The test run procedure consisted of:

- Three valid test runs are required for each series in the 65 mph, 65k GVW condition. Only two test runs per series for other conditions were performed due to budget considerations.
- By the end of the warm-up procedure/beginning of the test run procedure, all three vehicles were at the test speed and the spacing/distance with the cruise control and/or platooning system settings were engaged.

- As each vehicle crossed the 8.0-mile marker, the driver of each respective vehicle switched from drawing fuel from the vehicle main tank to the measured test tank. The tank switch solenoid also initiated logging by the data loggers. The data loggers were Isaac Instruments DRU-908 devices with 5 Hz GPS antennas and SAE J1939 CAN bus connections.
 - For the variable speed tests, the driver's aid trace was started as each vehicle crossed the 8.5-mile marker after having switched to the measured test tank. On platooning runs, only the lead platoon vehicle and control vehicle initiated the driver's aid.
- The test run consisted of seven laps (59.5 miles total). If conducting a baseline (non-platooning) run, each vehicle had significant spacing (3-5 min). If conducting a test (platooning) run, the control vehicle had significant spacing (3-5 min) behind the platooning pair.
- As each vehicle crossed the 8.0-mile marker after the seven test laps were completed, the driver of each respective vehicle switched from drawing fuel from the measured test tank to the vehicle main tank.
- Each vehicle then exited the track and parked in the staging area.
- The measured test tanks were quickly removed and replaced with a replacement measured test tank that had already been fueled and weighed.
- The vehicles were sent back out as quickly as possible to minimize cooling.
- Upon re-entering the track, the vehicles conducted the partial warm-up procedure (unless the transition time was longer than 30 minutes) and then initiated the next test run.

The measurement was defined as the T/C ratio, the ratio of the fuel used by test vehicle to that used by the control vehicle:

$T/C \text{ ratio} = \text{fuel used by test vehicle} / \text{fuel used by control vehicle}$

In this testing, there were two T/C ratios considered for validity checking: one for the lead platooning vehicle and one for the trailing platooning vehicle.

Lead Vehicle T/C ratio = T_L/C

Trailing Vehicle T/C ratio = T_T/C

If the desired number of consecutive runs did not comply with the 2.5% band, additional runs were completed until the desired number of consecutive runs fell within a 2.5% band.

Validity checks were completed for each of the test segments: the recorded fuel measurement ratios of three or two runs (per the test plan) were required to be within a 2.5% band of each other. Values above 2.5% were not considered valid. All baseline sets were within 1% variation. However, due to the nature of the platooning test and the need for air conditioning use due to ambient conditions during early testing, three test sets results were higher than the SAE J1321-prescribed 2%

band [5] but were still accepted; no results higher than 2.5% were accepted on steady-state test sets. The exception was the variable speed test set, where the previously discussed difficulty in meeting the trace led to a 3.8% variation on the test runs that were accepted.

An additional T/C ratio was calculated during post processing but was not considered during the validity check process. "Team" fuel savings were calculated in an effort to consider the total fuel savings of a pair of platooned vehicles, without introducing any bias via an averaging method. Team fuel savings were determined by summing both the leading and trailing vehicle fuel consumption and using that value to calculate a new T/C ratio measurement.

$$\text{Team T/C ratio} = (T_L + T_T) / C$$

Ambient Conditions Measurement

Ambient temperature, relative humidity, average wind speed, peak wind speed, wind direction, and barometric pressure measurements were provided by a weather station located at the test track, which recorded the information once a minute. Testing took place over 3 weeks and over much of the day and night; as such ambient conditions during testing ranged as well. Average wind speeds over the course of a test ranged from 2 mph to 11.7 mph. Average temperatures ranged from 13° to 32°C. Relative humidity ranged from 17% to 88%.

Fuel Consumption Measurement

The fuel consumption measurement in this project relied on a gravimetric approach. The engine fuel supply and return lines were connected to a fuel container placed on the frame rails behind the cab. The driver controlled a switch between the test tanks and main vehicle tanks. The difference between the beginning and the end of test mass measurement indicated the mass of fuel consumed during the test. Each day, the scale calibration was verified with a known calibration weight. A Sartorius ISI-10 scale with 0.002 kg readability and NIST traceable calibration on site at the Continental Tire Proving Grounds was used for this test. Engine fuel rate from the SAE J1939 CAN bus was also recorded as an investigative method, not to back up the gravimetric fuel measurement but rather to be evaluated alongside it. A sample of the fuel used for the testing was analyzed and the resulting specifications are presented in the appendix, [Table A1](#).

Engine and Vehicle Parameters Measurement

It was desired to understand the impact of close platooning of other engine and vehicle systems that could have negative unintended consequences such as engine cooling and selective catalytic reduction (SCR) exhaust aftertreatment performance. It was also of interest to evaluate whether the SAE J1939 fuel consumption rate reporting was accurate enough to replace gravimetric fuel measurement during investigative SAE Type II fuel consumption tests. The Isaac data loggers were recording the GPS location and SAE J1939

channels at a 5-Hz rate. A high resolution Race Technologies GPS Speedbox II with 0.02 m/s accuracy was used to measure the test speeds accurately. The J1939 CAN bus channel list is presented in the appendix, [Table A2](#).

RESULTS

SAE Type II Fuel Consumption Results from Platooned Tractors

Gravimetric Fuel Savings Analysis

All fuel consumption results for the 65 mph, 65k GVW conditions are averaged from three baseline/test runs each. The remaining test conditions are averaged from two baseline/test runs each due to budget considerations. Data analysis methods and the SAE spreadsheet recommended in SAE J1321 Fuel Consumption Test Procedure - Type II (2012) [12] were used during post processing to determine the 95% confidence interval (CI) and statistical significance for each test condition. The percent fuel saved and 95% CI for each test truck individually and as a “team” are shown in [Table 3](#). The variable speed test demonstrated no statistically significant difference from baseline for either truck or the combined team result. Three test runs may have allowed a difference to be determined given this test's higher inherent variability. The lead truck in the 80K lbs GVW condition and 65 mph, 65K lbs GVW, 75-ft condition also resulted in no statistically significant differences. Values with no statistically significant difference from their baseline are italicized in [Table 3](#) and are not discussed further.

Table 3. Percent fuel saved (gravimetric) of platooned tractors

Test Conditions	Percent Fuel Saved (Gravimetric)					
	Lead Truck		Trailing Truck		“Team”	
	Nominal	95% CI	Nominal	95% CI	Nominal	95% CI
55 mph, 65k, 30 ft	4.33%	0.70%	8.38%	1.03%	6.38%	0.28%
55 mph, 65k, 50 ft	2.22%	0.49%	9.72%	2.24%	6.01%	1.33%
65 mph, 65k, 20 ft	5.28%	0.34%	2.81%	0.71%	4.04%	0.52%
65 mph, 65k, 30 ft	4.06%	1.19%	7.53%	1.33%	5.80%	1.26%
65 mph, 65k, 40 ft	2.69%	0.99%	9.10%	0.71%	5.91%	0.84%
65 mph, 65k, 50 ft	3.14%	2.65%	9.17%	2.11%	6.15%	2.37%
65 mph, 65k, 75 ft	1.69%	2.35%	9.39%	1.93%	5.53%	2.12%
70 mph, 65k, 30 ft	4.42%	1.92%	4.62%	2.33%	4.52%	2.12%
70 mph, 65k, 50 ft	2.23%	0.35%	8.36%	1.44%	5.31%	0.90%
VAR, 65k, 50 ft	2.70%	8.32%	4.22%	6.82%	3.45%	7.56%
65 mph, 80k, 50 ft	0.55%	3.58%	6.67%	4.84%	3.68%	2.07%

Statistically significant percent fuel savings with 95% CI bars for the lead platooned tractor-trailer are shown in [Figure 6](#). The lead tractor consistently demonstrated an improvement in

average fuel consumption reduction as following distance decreased. The fuel savings ranged from 2.7% to 5.3% at 65k GVW, with a low point of 2.2% savings at both 55 mph 50' and 70 mph 50'. The possible anomaly at 40 ft/50 ft (shown in [Figure 6](#)) for the 65 mph, 65k condition could be caused by changes in ambient conditions, wake structure from the lead vehicle, or uncertainty in the data. It may be due to those tests being conducted during a change in the weather consisting of colder temperatures, higher humidity, and lower wind speed than any other tests of that series. The possible mechanism of that change to the aerodynamic benefit for the lead vehicle has not yet been identified. Atmospheric conditions for all tests are presented in the appendix, [Table A3](#). While the nominal test values at 40 ft/50 ft show a distinct discontinuity, there is not sufficient statistical confidence in the tests to definitively state a difference, and as such it may just be part of the uncertainty in the data.

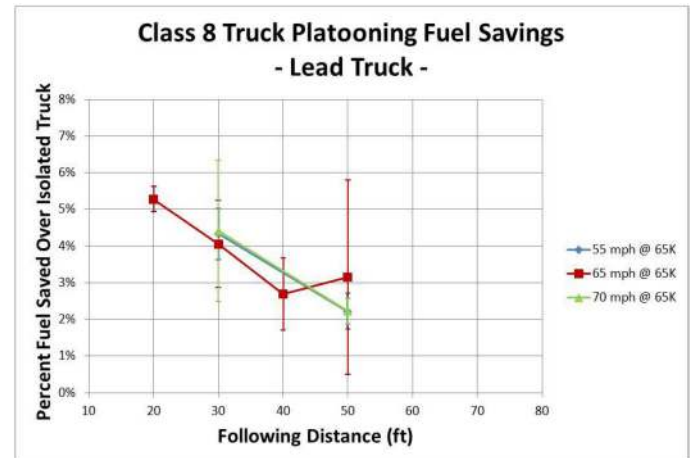


Figure 6. Lead platoon tractor percent fuel savings

Statistically significant percent fuel savings with 95% CI bars for the trailing platooned tractor-trailer are shown in [Figure 7](#). Engine coolant temperatures on the trailing truck generally increased as following distances decreased, resulting in engine fan-on time as high as 19% for some closer following conditions compared to 0%-1% for longer following distances. Baseline tests never resulted in fan-on events as unobstructed airflow over the radiator kept the engine coolant temperatures cool enough not to require the fan. Engine fan usage correlates to reduced fuel savings on the trailing truck, but the magnitude of impact is currently undefined as such an aerodynamic effect may also be contributing to the lower fuel savings. The trailing truck achieved savings from 2.8% to 9.7%; tests with no fan-on time had savings of 8.4% to 9.7%. Tests at 55 mph and 65 mph with no fan-on events still demonstrated a slight downward trend in nominal average savings with shorter following distances, which could be due to some aerodynamic effects or uncertainty in the data. The 80K lbs GVW condition lowered the fuel consumption reduction by 2.5% as compared to the 65k GVW 65 mph 50 ft following distance test set, resulting in a 6.7% reduction.

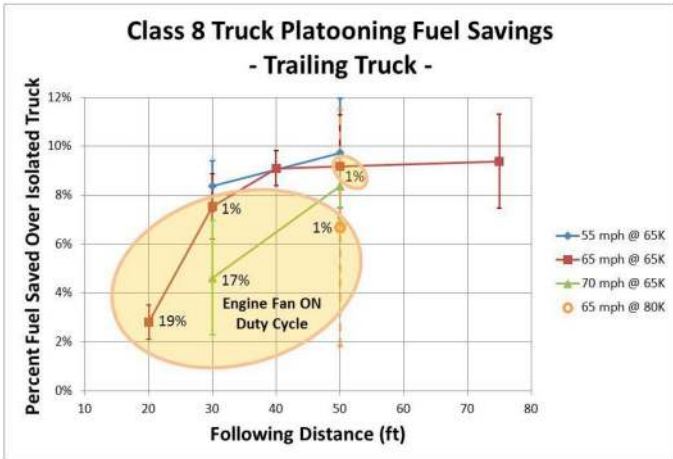


Figure 7. Trailing platoon tractor percent fuel savings

Statistically significant percent fuel savings with 95% CI bars for the team of two platooned tractor-trailers are shown in Figure 8. Team fuel savings were determined by summing both the leading and trailing vehicle fuel consumption to consider them as one vehicle. The resulting values ranged from 3.7% to 6.4% with the best combined result documented for 55 mph, 30 ft following distance, 65k GVW. The nominal percent savings at 70 mph were lower than at 55 mph and 65 mph, which does not agree with what would be predicted by the road load equation, but the differences are within the 95% CI of the 55 mph and 65 mph results so may be due to uncertainty in the data. The 80K lbs GVW condition negatively impacted fuel saved percent as well, resulting in the lowest combined nominal savings. Closer following distances caused the engine fan on the trailing truck to engage, which negatively impacted fuel savings. Test conditions that experienced no fan-on events had nominal results that ranged in team fuel saved from 5.3% to 6.4% for the combined pair of vehicles.

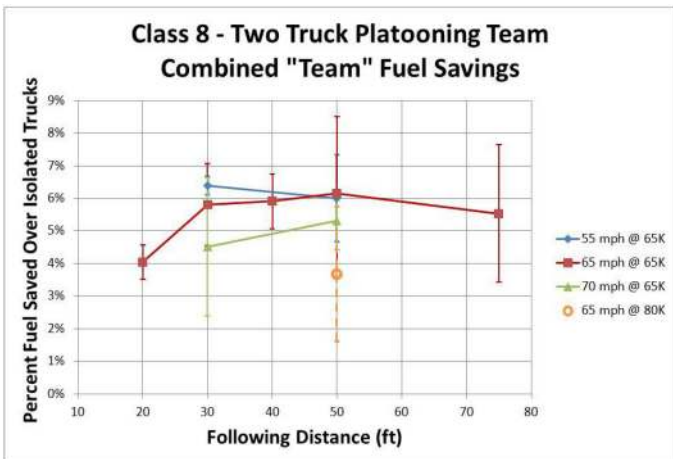


Figure 8. Platoon team percent fuel savings

Ambient Conditions Effects

Testing took place over a period of 3 weeks, with tests conducted throughout the day and night, resulting in a wide range of observed ambient conditions. For example, average wind speeds over the course of a test ranged from 2 mph to 11.7 mph. Average temperatures ranged from 13°C to 32°C. Relative humidity ranged from 17% to 88%. The test set at 65 mph, 65K lbs GVW and 40 ft following distance took place with the lowest wind and lowest temperatures of all baseline and test sets. The test set at 65 mph, 65K lbs GVW and 50 ft following distance took place with the highest wind. An anomaly in the fuel consumption savings results for the lead vehicle occurs at either 40 ft or 50 ft. Higher wind speeds could have increased the savings demonstrated by the lead vehicle at 50 ft or the colder temperatures and low winds could have reduced the savings at 40 ft (or a combination of both). To counter the changing ambient conditions, baseline sets preceded test sets for each vehicle speed / GVW condition and the 65 mph, 65K lbs GVW condition had two baseline sets to cover the five following distance tests. Atmospheric conditions for all tests are presented in the appendix, Table A3.

J1939 Analysis Results

Fuel Consumption

The J1939 reported fuel rate was recorded at a 5-Hz rate and then integrated to determine aggregate fuel consumption for each test. The results were compared to the gravimetric fuel consumption measurement for each test to evaluate whether J1939 CAN bus reported fueling information could be used in place of gravimetric analysis in future fuel consumption studies. Across the 41 baseline and test condition runs performed, analysis of the CAN-reported fuel consumption values compared to the gravimetric values resulted in a remarkably consistent error observed across each of the vehicles, with the average error value being unique. The fuel consumed by all three vehicles on all tests in this program was underestimated by the J1939 approach. Errors on the three vehicles ranged from -0.6% to -7.1% with vehicle-level standard deviation of error of less than 1.4%. Table 4 shows the range of error for each vehicle; run by run fuel consumption by each method is presented in the appendix, Table A4.

Table 4. SAE J1939 fuel consumption percent error

	Lead Truck Error	Trailing Truck Error	Control Truck Error
Max Error	-7.1%	-6.4%	-5.9%
Average Error	-6.1%	-4.6%	-3.6%
Minimum Error	-4.6%	-3.3%	-0.6%
Std Dev of Error	0.76%	0.62%	1.38%

Trailing Tractor Coolant and Intake Air Temperature

The J1939 CAN bus reported coolant and intake air temperatures were examined to evaluate the observed engine fan effects on the fuel savings on the trailing tractor. The temperatures were analyzed using the same SAE J1321 T/C ratio analysis prescribed for analyzing fuel consumption. While this is not a normal application for this analysis, this method was chosen as it accounted for the test-to-test weather variations well. Table 5 lists the percent changes in average and maximum temperatures seen over each test series as compared to the fuel savings demonstrated and engine fan duty cycle seen. Figure 9 shows the relationship between coolant temps, fan duty cycle, and fuel savings achieved. A rise of between 7% and 8% in average coolant temperature appears to be the point at which the fan may come on. Intake air temperatures were not the primary driver of the fan engagement and as such had poor correlation and so are not shown here.

Table 5. Average and maximum coolant and intake air temperature changes observed on the trailing tractor over each test series

Test Conditions	Fuel Savings	Coolant Temp Avg	Coolant Temp Max	Intake Air Temp Avg	Intake Air Temp Max	Engine Fan Duty Cycle
65 mph, 65k, 75 ft	9.4%	1.5%	2.6%	0.2%	-4.4%	0%
65 mph, 65k, 50 ft	9.2%	4.9%	7.0%	4.6%	9.0%	1%
65 mph, 65k, 40 ft	9.1%	0.4%	1.5%	6.7%	2.3%	0%
Test Conditions	Fuel Savings	Coolant Temp Avg	Coolant Temp Max	Intake Air Temp Avg	Intake Air Temp Max	Engine Fan Duty Cycle
65 mph, 65k, 30 ft	7.5%	7.0%	10.7%	0.8%	11.8%	1%
65 mph, 65k, 20 ft	2.8%	8.4%	12.4%	-2.4%	13.2%	19%
55 mph, 65k, 50 ft	9.7%	-0.3%	-0.6%	-22.0%	-14.0%	0%
55 mph, 65k, 30 ft	8.4%	0.2%	1.7%	-9.5%	0.4%	0%
70 mph, 65k, 50 ft	8.4%	1.0%	1.6%	5.8%	1.7%	0%
70 mph, 65k, 30 ft	4.6%	8.5%	9.3%	24.3%	22.4%	17%
VAR, 65k, 50 ft	4.2%	6.6%	9.4%	0.9%	9.6%	3%
65 mph, 80K, 50 ft	6.7%	1.3%	0.9%	-10.8%	-4.1%	1%

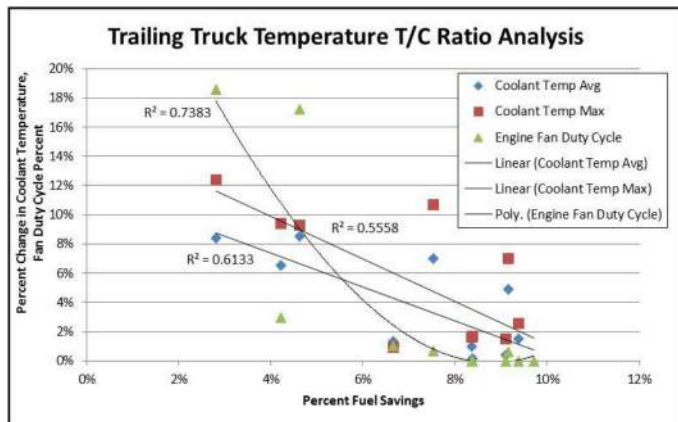


Figure 9. Trailing tractor coolant temperature analysis

DISCUSSION

While previous studies have set expectations for platooning tractor-trailers to achieve fuel savings above 10%, the findings of the current study are more modest, but still impressive. Maximum fuel savings observed as part of this experiment were 5.3% and 9.7% for the lead and trailing trucks, respectively. It should be noted that these maximums were not achieved at the same test configuration. However, the vehicle combinations of a previous study [1] relied on older tractors and trailers without side skirts, which would not have had coefficient of drag (Cd) values near the EPA SmartWay tractors and trailer side skirt designs that are becoming common on U.S. interstates today and that were studied in this test series. Some previous studies [2, 3, 4] utilized cab-over designs not currently common in the United States, which may respond differently to the complex aerodynamics of platooning. All of these studies [1, 2, 3, 4] also took place at road speeds of 45-55 mph, which are also not common for a line haul application in the United States and may simplify the aerodynamics associated with platooning. Another study [2] examined higher vehicle mass than studied in this paper. The results demonstrated lower maximum savings, supporting the trend seen with mass.

The road load equation that governs the force required to move a tractor-trailer combination at constant speed neglecting road grade and wind variables is:

$$F = \frac{1}{2} * C_d A * \rho * V^2 + CRR * m * g$$

Platooning, from a fuel consumption perspective, is not as straightforward as adjusting the Cd term in the same manner as the SmartWay aerodynamic aid systems are designed to address. The dynamic interaction between the two vehicles may also affect dynamic pressure, Reynolds number, flow direction, turbulence, and wake structure experienced by the platooned vehicle pair (or one of the pair). The tests demonstrated higher average percent fuel savings at lower speeds, which is opposite what would be predicted by the V² term if only Cd is being affected by platooning. More study is needed to fully understand the complex aerodynamic interaction between platooned tractor-trailer combinations at highway speeds. It is possible that testing these vehicles below 55 mph could have produced results similar to other studies, but they would not have been applicable to the current line haul environment in the United States today and what is expected in the future. It is also possible that testing at lower vehicle mass (or empty trailer) would have produced results similar to other studies, but it would not have conformed to the EPA SmartWay program test trailer and cargo weights for measuring fuel economy improvement [13].

The following distances tested equate to a 0.2 second to 0.8 second time gap between the vehicles at 65 mph (0.3 to 0.5 second at 70 mph), which could not be manually performed in a safe way on public roads on long duration trips. However, it is not known how closely trucks routinely follow each other on public roads today. Results failed to demonstrate at what

following distance the benefit to the trailing vehicle begins to diminish. Further study is needed to identify at what distance the benefit to the trailing vehicle approaches zero and whether trucks today are manually following at distances where platooning effects could be observed.

SUMMARY/CONCLUSIONS

The results of this study clearly indicate an opportunity for significant fuel savings through platooning technology in line haul applications. Some observations include:

- Platooning can result in significant fuel savings for both a leading (up to 5.3%) and a trailing (up to 9.7%) Class 8 vehicle.
- Engine coolant temperature needs to be monitored / addressed for the trailing vehicle to maximize the fuel savings for the vehicle pair by avoiding fan-on situations.
- Atmospheric conditions may play a strong role in the savings attainable due to the reduced air flow across the radiator induced by vehicle speed on the trailing vehicle. Hot days may require greater distance and possibly reduced savings without some specific platooning aerodynamic aid addressing the air flow across the radiator needs of the trailing vehicle while cooler ambient temperatures may allow for greater percent fuel savings by allowing closer following distances with less risk of fan-on.
- Heavy loads will affect the percent savings from platooning but still result in significant fuel savings, especially considering that heavily loaded vehicles consume fuel at a higher rate.
- Because the technology is expected to require a modest investment, the "team" savings of 6.4% on a pair of vehicles could end up with an attractive return on investment (ROI) for the fleet without reducing safety by attempting to follow closely under driver control.
- Additional study is necessary to reduce uncertainty about what combination of conditions offers the most advantageous platooning configuration.

FUTURE WORK

There are many questions still to be answered about the platooning of Class 8 tractor-trailer combinations. Some future research needs to be considered are:

- Collecting more data points/test sets to extrapolate the trends seen here and expand to greater following distances are desired to clarify the optimum configuration under differing atmospheric conditions. This work could also possibly be done with extensive computational fluid dynamics modeling.
- Testing platoons consisting of more than two tractor-trailer combinations or a combination of tractor-trailer and light-duty vehicles over a range of speeds, following distances, and loads.

- Identifying what percent of national line haul miles would be conducive to platooning. As observed here, while a pair of platooned tractor-trailers can save close to 6% on fuel consumption, the realistic in-use national savings will be less depending on the percent of time the system is able to be activated. This may depend on the logistics of routing vehicles from the same fleet together, opportunities to identify other, non-affiliated vehicles on the highway employing this technology as well as traffic and weather conditions that allow it to be employed.
- Designing aerodynamic aids specific to platooning that may be different than for an isolated truck or that may possibly address the loss of cooling airflow over the radiator for the trailing tractor to allow closer following without engine fan engagement.

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DEFINITIONS/ABBREVIATIONS

CAN - controller area network

CARB - California Air Resources Board

CFD - Computational fluid dynamics

Cd - coefficient of drag

CI - confidence interval

Crr - coefficient of rolling resistance

DOE - Department of Energy

DSRC - Dedicated Short-Range Communication

DPF - diesel particulate filter

EPA - U.S. Environmental Protection Agency

GPS - global positioning system

GVW - gross vehicle weight

HHDDT - Heavy Heavy-Duty Diesel Truck

NEDO - New Energy and Industrial Technology Development Organization

NREL - National Renewable Energy Laboratory

PATH - Partners for Advanced Transportation Technology

ROI - return on investment

SAE - Society of Automotive Engineers International

SCR - selective catalytic reduction

V2V - Vehicle-to-vehicle

APPENDIX

Table A1. Diesel fuel test results

Method	Unit	Result
D1319		
Aromatics	%	36.1
Olefins	%	1.2
Saturates	%	62.7
ASTM D445 @40C		
Viscosity		2.186
ASTM D482		
Ash Content	mass %	<0.001
ASTM D5453		
Sulfur	ppm	4.0
ASTM D86		
IBP	degF	345.8
Evap_5	degF	380.7
Evap_10	degF	391.4
Evap_15	degF	402.6
Evap_20	degF	413.0
Evap_30	degF	433.3
Evap_40	degF	454.1
Evap_50	degF	475.6
Evap_60	degF	499.2
Evap_70	degF	524.3
Evap_80	degF	553.8
Evap_90	degF	592.5
Evap_95	degF	624.8
FBP	degF	652.0
Recoverd	mL	98.0
Residue	mL	1.4
Loss	mL	0.6
PCorrIBP	degF	345.8
PCorrFBP	degF	652.0
PCorrD10	degF	392.5
PCorrD50	degF	477.0
PCorrD90	degF	596.0
PCorrD95	degF	631.2
UCorRcvd	mL	97.9
UCorLoss	mL	0.7
ASTM D93		
Flash Point	deg F	141
	deg C	61
DCN		55.8
Density	g/cm3	0.8158
Gross heat of Combustion D240	J/g	46,215
FAME by IR		0% biodiesel
CP	C	-12.7

Table A2. SAE J1939 data logging channel list

Data Channel Name	Data Channel Name	Acronym	PGN#	SPN#	Units
Transmission Output Shaft Speed	TransOutputShaftSpeed_1	ETC1	61442	191	RPM
Transmission Input Shaft Speed	TransInputShaftSpeed_1	ETC1	61442	161	RPM
Accelerator Pedal Position 1	AccelPedalPos1	EEC2	61443	91	%
Engine Percent Load At Current Speed	EngPercentLoadAtCurrentSpeed	EEC2	61443	92	%
Actual Maximum Available Engine - Percent Torque	ActMaxAvailEngPercentTorque	EEC2	61443	3357	%
Driver's Demand Engine - Percent Torque	DriversDemandEngPercentTorque	EEC1	61444	512	%
Actual Engine - Percent Torque	ActualEngPercentTorque	EEC1	61444	513	%
Engine Speed	EngSpeed	EEC1	61444	190	RPM
Transmission Selected Gear	TransSelectedGear_1	ETC2	61445	524	Gear
Transmission Current Gear	TransCurrentGear_1	ETC2	61445	523	Gear
Engine Exhaust Gas Recirculation 1 (EGR1) Mass Flow Rate	EngExhstGsRrcrltionMassFlowRate	EGF1	61450	2659	kg/hr
Engine Intake Air Mass Flow Rate	EngInletAirMassFlowRate	EGF1	61450	132	kg/hr
Diesel Particulate Filter Lamp Command	DieselParticulateFilterLampCmd	DPFC1	64892	3697	-
Diesel Particulate Filter Passive Regeneration Status	DslPrtclPssvRgnrtionStatus	DPFC1	64892	3699	-
Diesel Particulate Filter Active Regeneration Status	DslPrtclActvRgnrtionStatus	DPFC1	64892	3700	-
Diesel Particulate Filter Status	DieselParticulateFilterStatus	DPFC1	64892	3701	-
Exhaust System High Temperature Lamp Command	ExhaustSystemHighTempLampCmd	DPFC1	64892	3698	-
Diesel Particulate Filter Active Regeneration Forced Status	DslPrtclActvRgnrtionFrcdStatus	DPFC1	64892	4175	-
Aftertreatment 1 Diesel Particulate Filter Outlet Gas Temperature	Aftrtrtmnt1PrtclTrpOtlGstemp	AT1OG2	64947	3246	deg C
Aftertreatment Exhaust Gas Temp	Aftertreatment1ExhaustGasTemp1	AT1IG2	64948	3241	deg C
Referenced Torque	ReferenceEngineTorque	EC1	65251	544	Nm
Red Stop Lamp (engine)	EngRedStopLampData	DLCD1	64773	5095	-
Amber Warning Lamp (engine)	EngAmberWarningLampData	DLCD1	64773	5094	-
Protect Lamp (engine)	EngProtectLampData	DLCD1	64773	5093	-
Nominal Friction - Percent Torque	NominalFrictionPercentTorque	EEC3	65247	514	%
Engine Coolant Temperature	EngCoolantTemp	ET1	65262	110	deg C
Engine Fuel Temperature 1	EngFuelTemp	ET1	65262	174	deg C
Engine Oil Temperature 1	EngOilTemp1	ET1	65262	175	deg C
Engine Intercooler Temperature	EngIntercoolerTemp	ET1	65262	52	deg C
Engine Fuel Delivery Pressure	EngFuelDeliveryPress	EFL_P1	65263	94	kPa
Engine Oil Pressure	EngOilPress	EFL_P1	65263	100	kPa
Wheel-Based Vehicle Speed	WheelBasedVehicleSpeed	CCVS	65265	84	km/h
Brake Switch	BrakeSwitch	CCVS	65265	597	-
Engine Fuel Rate	EngFuelRate	LFE	65266	183	l/h
Barometric Pressure	BarometricPress	AMB	65269	108	kPa
Ambient Air Temperature	AmbientAirTemp	AMB	65269	171	deg C
Engine Air Intake Temperature	EngAirInletTemp	AMB	65269	172	deg C
Engine Intake Manifold 1 Pressure	EngTurboBoostPress	IC1	65270	102	kPa
Engine Intake Manifold 1 Temperature	EngIntakeManifold1Temp	IC1	65270	105	deg C
Engine Air Intake Pressure	EngAirInletPress	IC1	65270	106	kPa
Engine Exhaust Gas Temperature	EngExhaustGasTemp	IC1	65270	173	deg C
Engine Oil Temperature 2	EngOilTemp2	ET2	65188	1135	deg C
Engine Exhaust Gas Temperature - Left Manifold	EngExhaustGasTempLeftManifold	ET	65031	2434	deg C
Engine Exhaust Gas Temperature - Right Manifold	EngExhaustGasTempRightManifold	ET	65031	2433	deg C
Engine Exhaust Gas Average Temperature	EngExhaustGasTempAverage	EAI	64851	4151	deg C
Diesel Oxidation Catalyst Intake Gas Temperature 1	Aftrtrtmnt1DslOxdtnCtlystDffPrss	A1DOC	64800	4765	deg C
Diesel Oxidation Catalyst Exhaust Gas Temperature 1	Aftrtrtmnt1DslOxdtnCtlystIntkGsT	A1DOC	64800	4766	deg C
Diesel Oxidation Catalyst Differential Pressure 1	Aftrtrtmnt1DslOxdtnCtlystOutlGsT	A1DOC	64800	4767	kPa
Diesel Oxidation Catalyst Intake Gas Temperature 2	Aftrtrtmnt2DslOxdtnCtlystIntkGsT	A2DOC	64799	4771	deg C
Diesel Oxidation Catalyst Exhaust Gas Temperature 2	Aftrtrtmnt2DslOxdtnCtlystOutlGsT	A2DOC	64799	4772	deg C
Diesel Oxidation Catalyst Differential Pressure 2	Aftrtrtmnt2DslOxdtnCtlystDffPrss	A2DOC	64799	4773	kPa
SCR Catalyst Intake Gas Temperature 1	Aftrtrtmnt1SCRctlystIntkGasTemp	A1SCREGT	64830	4360	deg C
SCR Catalyst Exhaust Gas Temperature 1	Aftrtrtmnt1SCRctlystOutlGasTemp	A1SCREGT	64830	4363	deg C
SCR Exhaust Gas Differential Pressure 1	Aftrtrtmnt1SCRctlystExhstGsDffPr	A1DCREGP	64831	4358	kPa
SCR System State 1	Aftertreatment1SCRSystemState	A1SCRDS1	61475	4332	-
SCR Diesel Exhaust Fluid Dosing Requested Quantity 1	Aftrtrtmnt1SCRReqdDsngRgntQty	A1SCRDSR1	61476	4348	g/hr
SCR 1 Diesel Exhaust Fluid Average Consumption	Aftrtrtmnt1SCRAvrgCtlystRgntCnsm	SCR1	64878	3826	L/hr
SCR Conversion Efficiency	Aftrtrtmnt1SCRctlystCnvrnsnEffcnc	SCR1	64878	4364	%
Diesel Exhaust Fluid Actual Dosing Quantity 1	Aftrtrtmnt1SCRActlDsngRgntQty	A1SCRDSI1	61475	4331	g/hr
Diesel Particulate Filter Differential Pressure	Aftrtrtmnt1DsPrtclFltrDffPrss	AT1IMG	64946	3251	kPa
Diesel Particulate Filter Intermediate Gas Temperature	Aftrtrtmnt1DsPrtclFltrInt_0001	AT1IMG	64946	3252	deg C
Engine Exhaust Gas Recirculation Temperature 1	EngExhaustGasRecirculation1Temp	ET2	65188	4750	deg C
Aftertreatment 1 Outlet NH3	Aftertreatment1OutletNH3	A1SCRAI	61477	4377	ppm
Aftertreatment 1 Outlet NOx	Aftertreatment1OutletNOx	AT1OF1	61455	3226	ppm
Aftertreatment 1 Intake NOx	Aftertreatment1IntakeNOx	AT1IG1	61454	3216	ppm

Table A3. Weather data

Test Description	Baseline	Vehicle GCWV (lbs)	Vehicle Speed (mph)	Trailing Distance (ft)	Ave Wind Speed (mph)	Max Wind Speed (mph)	Min Wind Speed (mph)	Ave Peak Wind Speed (mph)	Max Peak Wind Speed (mph)	Min Peak Wind Speed (mph)	Ave Ambient Temp (°C)	Max Ambient Temp (°C)	Min Ambient Temp (°C)	Ave Relative Humidity (%)	Max Relative Humidity (%)	Min Relative Humidity (%)	Ave Barometric Pressure (in Hg)	Min Barometric Pressure (in Hg)	Max Barometric Pressure (in Hg)
65 mph, 20 ft Average	Baseline 2	65,000	65 MPH	20'	5.5	9.9	2.1	7.1	34.4	2.8	27.6	28.5	26.7	50.0	53.3	45.4	28.4	28.4	28.4
65 mph, 30 ft Average	Baseline 2	65,000	65 MPH	30'	6.1	8.2	4.3	7.0	10.2	4.9	21.7	22.3	21.1	70.6	74.0	67.0	28.5	28.5	28.5
65 mph, 40 ft Average	Baseline 2	65,000	65 MPH	40'	2.0	3.3	1.3	2.4	3.9	1.5	13.1	13.7	12.6	70.3	73.5	67.4	28.8	28.8	28.8
65 mph, 50 ft Average	Baseline 1	65,000	65 MPH	50'	11.7	15.0	7.4	14.0	18.5	9.8	25.3	25.9	24.5	52.3	56.0	49.9	28.6	28.6	28.6
65 mph, 75 ft Average	Baseline 1	65,000	65 MPH	75'	7.0	9.6	4.7	8.2	11.2	5.4	23.0	23.8	22.3	39.2	42.0	36.4	28.7	28.7	28.7
70 mph, 30 ft Average		65,000	70 MPH	30'	10.0	14.4	6.5	12.7	17.8	8.0	27.8	28.4	27.3	17.1	18.9	15.6	28.8	28.8	28.8
70 mph, 50 ft Average		65,000	70 MPH	50'	3.1	7.4	0.0	4.0	9.3	0.5	15.9	16.5	15.2	51.7	56.6	47.9	28.7	28.7	28.8
55 mph, 30 ft Average		65,000	55 MPH	30'	10.4	13.3	7.0	12.6	16.3	9.3	26.4	26.6	26.1	19.4	19.9	18.9	28.8	28.8	28.8
55 mph, 50 ft Average		65,000	55 MPH	50'	8.1	11.9	4.3	9.8	14.4	5.3	19.8	20.3	19.3	76.7	78.5	74.9	28.7	28.6	28.7
Variable Test Average		65,000	VAR MPH	50'	4.2	7.3	1.5	5.4	8.6	2.4	29.1	30.1	27.9	37.6	40.6	34.5	28.5	28.5	28.5
65 mph, 50 ft Average		80,000	65 MPH	50'	6.3	8.6	4.1	7.6	10.8	4.9	27.4	28.2	26.7	53.9	58.2	50.7	28.4	28.4	28.4
65 mph Baseline 1 Average		65,000	65 MPH	--	7.4	12.0	3.4	9.9	15.3	5.1	21.4	22.2	20.5	30.4	32.6	28.4	28.8	28.8	28.8
65 mph Baseline 2 Average		65,000	65 MPH	--	4.1	6.8	1.9	5.5	8.8	2.8	18.0	18.8	17.2	53.6	56.7	51.0	28.7	28.7	28.7
70 mph Baseline Average		65,000	70 MPH	--	4.8	6.7	2.8	6.0	8.8	3.6	19.3	19.7	18.6	88.2	89.9	87.1	28.5	28.5	28.5
55 mph Baseline Average		65,000	55 MPH	--	6.4	8.9	3.0	7.9	11.0	3.8	20.4	21.5	19.3	30.1	34.8	26.2	28.7	28.7	28.7
Variable Baseline Average		65,000	VAR MPH	--	2.7	4.6	0.0	4.0	5.8	0.0	26.1	26.4	24.8	54.5	56.2	50.1	28.6	28.6	28.6
65 mph Baseline Average		80,000	65 MPH	--	8.1	13.3	4.2	10.2	16.3	6.1	31.7	32.1	31.3	40.5	43.0	37.6	28.4	28.4	28.4

