

# Enhanced grinding performance by means of patterned grinding wheels

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## Abstract

In this paper a new and innovative method for the patterning of grinding wheels is presented. The patterns are machined with a patterning tool by using fly-cutting kinematics. By changing the patterning process parameters different pattern sizes and densities can be machined in a flexible way. Surface and cylindrical grinding experiments show that grinding with patterned grinding wheels can significantly reduce process forces, grinding burn and grinding power. The surface roughness increases because less active cutting edges remain when grinding with patterned wheels. But especially for roughing processes the results show great potential for increasing the overall grinding performance.

**Keywords** grinding, grinding performance, patterning, fly-cutting

## 1 Introduction

Grinding is an important manufacturing process, especially if high surface qualities have to be realized or if hard or brittle materials have to be machined [1]. Nevertheless the productivity of grinding processes is often limited due to work piece failure, caused by a high thermal load in the contact zone. When grinding with vitrified bonded aluminum oxide grinding wheels up to 75 % of the mechanical energy is converted into heat that diffuses directly into the work piece [2]. Therefore in recent years many research activities have focused on the reduction of the thermal load in the contact zone by applying new innovative grinding tools with a modified grinding wheel topography. The topographies of these tools are intermitted. This can be realized by using specially manufactured grinding wheels with a segmented abrasive coating or with a defined grain pattern [3, 4, 5, 6]. Other researchers have developed a special dressing method to generate a reduced effective contact area or have applied laser techniques for machining voids into the coating [7, 8]. In summary, most of the concepts require non-standard grinding tools or a cost-intensive manufacturing process, such as laser technology for creating a patterned grinding wheel topography. Given that today's manufacturing processes have to be highly flexible

in order to machine customized parts with a large geometrical variety, the introduced concepts do not meet these requirements [9]. Therefore an innovative method for machining patterns into the grinding wheel topography in a flexible and productive way was developed by Denkena et al. by using a fly-cutting kinematic and a standard dressing spindle [10].

Parallel the use of patterned grinding wheels has been investigated for the manufacturing of textured surfaces only and not under the view of productivity enhancement [11, 12]. Here, a flexible method for creating a patterned grinding wheel was designed by Oliveira et al. by employing a controlled shaker for dressing [13]. The aim of those investigations is the generation of tribological optimized surfaces for friction reduction by means of face or cylindrical grinding. Patterns or micro dimples are transferred from the grinding wheel topography to the work piece. Those patterns or dimples increase the fluid retention capacity of a sliding system and therefore reduce the overall friction [14]. Nevertheless only few research activities have focused on using those grinding wheels for enhancing the grinding performance [13].

In this paper the patterning of vitrified bonded grinding wheels by applying a fly-cutting kinematic for enhancing the overall grinding performance will be presented. In contrast to the results of other researchers comparatively small patterns will be machined into the grinding wheel surface. Face grinding and cylindrical grinding experiments will be conducted in order to analyze the overall potential of enhancing the grinding performance by means of patterning. Finally, possible future industrial applications for each process will be identified.

## 2 Patterning with fly-cutting kinematic

The developed patterning process for grinding wheels can be integrated into any conventional grinding machine by using a common dressing spindle equipped with a patterning tool. This tool is a specially manufactured disc with single diamonds placed along the circumference. The patterning process is graphically illustrated in Fig. 1. For the experiments presented in this paper two different patterning tools with one and four diamonds were used. The patterning tool is connected with a common dressing and placed be-

neath the grinding wheel such as a standard form roller. By adjusting the speed of grinding wheel and patterning tool ( $v_s$  and  $v_{tool}$ ), as well as the depth of patterning cut ( $a_{ed}$ ) and feed rate ( $v_f$ ), the patterning can be conducted. Due to the discontinuous machining of just a single cutting edge and the overlapping of two moving directions, single patterns appear on the grinding wheel topography.

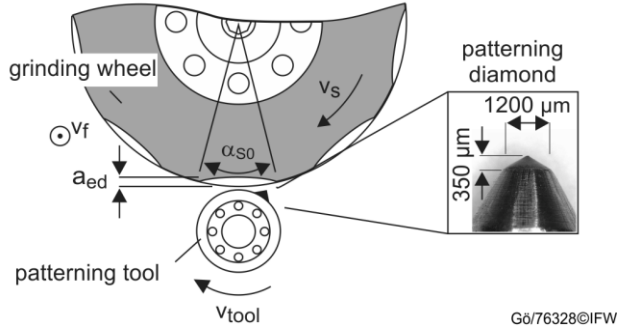


Fig. 1 Patterning process

The pattern length ( $l_{pat}$ ) (Fig. 2) is primarily influenced by the tool radii ( $r_s$  and  $r_{tool}$ ) as well as the relative speed between grinding wheel and cutting tool. According to Grün the pattern length is calculated as follows [15]:

$$l_{pat} = \sqrt{2 * r_s^2 * (1 - \cos(\alpha_s))} \quad (1)$$

with the resulting angle  $\alpha_s$ , which is the engagement angle  $\alpha_{s0}$  between patterning tool and grinding wheel multiplied with the relative speed. The positive and negative sign indicate the patterning tool speed direction regarding the grinding wheel speed (+: counterclockwise, -: clockwise):

$$\alpha_s = \left(1 \pm \frac{n_s}{n_{tool}} * \frac{r_s}{r_{tool}}\right) * \alpha_{s0} \quad (2)$$

The engagement angle  $\alpha_{s0}$  is derived from the contact conditions by using trigonometry:

$$\alpha_{s0} = 2 * \arccos \frac{(r_s + r_{tool} - a_e)^2 + (r_s)^2 - r_{tool}^2}{2 * (r_s + r_{tool} - a_e) * (r_s)} \quad (3)$$

Another process parameter influencing the pattern length ( $l_{pat}$ ) is the patterning depth ( $a_{pat}$ ), which is identical with the depth of cut ( $a_{ed}$ ). An increased depth leads to a larger pattern width ( $b_{pat}$ ), due to the conical tool profile as well as to a longer contact length between tool and grinding wheel. The patterns having a length of about  $l_{pat} = 3 - 7$  mm and a width of  $b_{pat} = 0.2 - 0.5$  mm are machined with a depth of  $a_{pat} = 20 - 100$   $\mu$ m. The spacing between the patterns in axial direction ( $s_{ax}$ ) is identical with the feed rate ( $f$ ) during patterning and can be adjusted by the numerical control. The pattern size and arrangement is a function of the process parameters described in Fig. 2. The number of patterns created by one single turn of the grinding wheel depends on the frequency ratio ( $\lambda$ ) between grinding wheel rotational

frequency ( $n_s$ ) and tool rotational frequency ( $n_{tool}$ ) as well as the number of diamonds ( $n_{diam}$ ). The spacing of the patterns along the grinding wheel circumference ( $s_{tan}$ ) can be derived from this ratio.

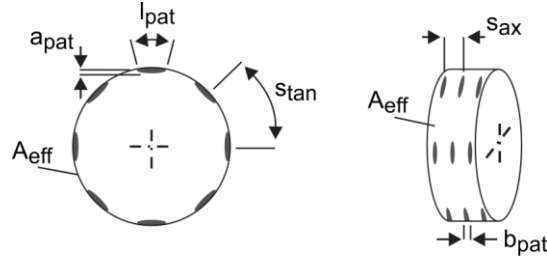


Fig. 2 Characteristics of the patterning process

The tool trajectories of a single grinding wheel revolution are schematically illustrated in Fig. 3 for up-patterning mode and a frequency ratio of 8 and 32, respectively. With an increasing frequency ratio ( $\lambda$ ) the patterns get shorter due to a decreased effective cutting time. The area of the grinding wheel between the patterns is called effective contact area ( $A_{eff}$ ), as this area will be in direct contact with the workpiece while grinding. With an increased frequency ratio ( $\lambda$ ) the effective contact area decreases. Similar behavior occurs if the tangential feed motion ( $v_f$ ) during the patterning process is minimized. More tool trajectories repeat itself with a defined offset between each other and therefore increase the pattern density.

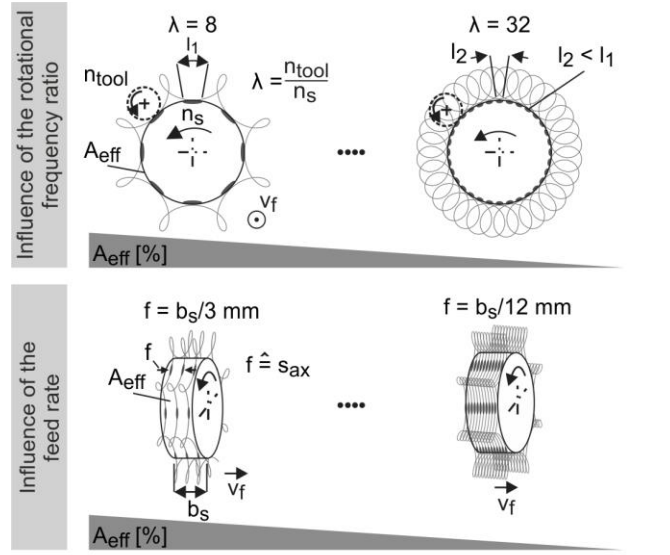
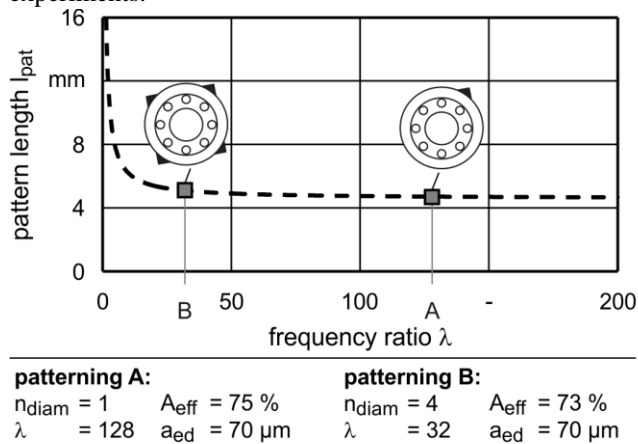


Fig. 3 Effective contact area

The grinding wheels used for this research have a diameter of  $d = 300$  mm for face grinding and  $d = 400$  mm for cylindrical grinding. In order to pattern the whole circumference of such grinding wheels with a patterning tool with only one cutting edge ( $n_{diam} = 1$ ), high patterning spindle frequencies or extremely low grinding wheel frequencies are required. The grinding machines used in this research rotate

with a minimum frequency of about  $165 \text{ min}^{-1}$ . In order to generate highly structured grinding wheel topographies, frequency ratios of  $\lambda > 100$  are necessary, which requires patterning spindle frequencies of up to  $20,000 \text{ min}^{-1}$ . Increasing the number of cutting diamonds enables the use of conventional dressing spindles with lower rotational speed, since the same amount of patterns can be machined with smaller frequency ratios ( $\lambda$ ). Nevertheless the pattern length ( $l_{\text{pat}}$ ) is a function of  $\lambda$  (see Fig. 4). When patterning with one cutting edge ( $n_{\text{diam}} = 1$ ), 128 patterns are machined with a length of about 4.7 mm ( $\lambda_A = 128$ ). The feed motion stays constant resulting into an effective contact area of  $A_{\text{eff}} = 75 \%$ . This effective contact area slightly changes to  $A_{\text{eff}} = 73 \%$ , when patterning with four diamonds since the pattern length increases to  $l_{\text{pat}} = 5 \text{ mm}$  ( $\lambda_B = 32$ ). In order to obtain a constant effective contact area, fewer patterns have to be machined by marginally decreasing the frequency ratio ( $\lambda$ ) or increasing the feed motion ( $v_f$ ). Within this research a patterning tool with one diamond ( $n_{\text{diam}} = 1$ ) has been used for the face grinding experiments and a tool equipped with four diamonds for the cylindrical grinding experiments.



**patterning A:**  
 $n_{\text{diam}} = 1$      $A_{\text{eff}} = 75 \%$   
 $\lambda = 128$      $a_{\text{ed}} = 70 \mu\text{m}$

**patterning B:**  
 $n_{\text{diam}} = 4$      $A_{\text{eff}} = 73 \%$   
 $\lambda = 32$      $a_{\text{ed}} = 70 \mu\text{m}$

Fig. 4 Pattern length as a function of the frequency ratio for the counter-clockwise patterning mode

### 3 Materials and methods

Acoustic mapping was used for process monitoring and control. The map represents the acoustic emission (AE) distribution around the grinding wheel along the time axis, according to the method proposed by Oliveira et al. [16] and Oliveira and Dornfeld [17]. The technique allows the monitoring of the contact between the wheel and the patterning tool during the patterning process in real-time. The pattern arrangement on the grinding wheel topography can be derived from the AE-signals and the proposed method by Oliveira.

In order to investigate the potential of patterned grinding wheels, two different grinding processes were used. The

surface grinding experiments were conducted at the Institute of Production Engineering and Machine Tools (IFW) in Germany on a Blohm Profimat 307 grinding machine. Following, the patterning equipment was transferred to the Laboratory of Advanced Processes and Sustainability (LAPRAS) in Brazil and installed in a Zema cylindrical grinding machine. For both tests, vitrified bonded aluminium oxide grinding wheels with a grain size of 80 mesh have been used. The work-piece material was a hardened tool steel X155CrVMo12 (1.2379) for the surface grinding and a steel 42CrMo4 (1.7225) for the cylindrical grinding. Effective contact areas of the grinding wheel of 90 % and 75 % have been realized by using a patterning tool with one diamond or rather four diamonds. Before each experiment all grinding wheels have been dressed in an identical way. For the surface grinding experiments a surface plate was used. The dressing parameters were set to  $a_{\text{ed}} = 5 \mu\text{m}$  and  $U_d = 8$ . The dressing process before the cylindrical grinding experiments was also conducted with a surface plate with  $a_{\text{ed}} = 10 \mu\text{m}$  and  $U_d = 8$ .

### 4 AE-mapping during patterning

In this chapter the acoustic mapping method will be applied to the patterning process. In Fig. 5 the AE-mappings of three different patterning processes with  $\lambda = 5, 11$  and  $22$  using a tool with four diamonds are displayed. The contact between tool tip and grinding wheel during patterning is visualized by a bright and yellow pixel. Each pattern consists of several pixels. The patterns are aligned very close to each other along the grinding wheel width  $b_c$ , therefore they appear as a curved yellow line. Minor changes of the grinding wheel or tool spindle rotational frequency directly affect the position of a single pattern on the grinding wheel and therefore create a sinuous and not a straight pattern arrangement. In contrast to the bright pixels, the dark area is the un-machined topography of the grinding wheel, which is the effective contact area ( $A_{\text{eff}}$ ) described in Fig. 3. The effective contact area (dark area) considerably decreases when  $\lambda$  rises, because more patterns are machined along the grinding wheel circumference.

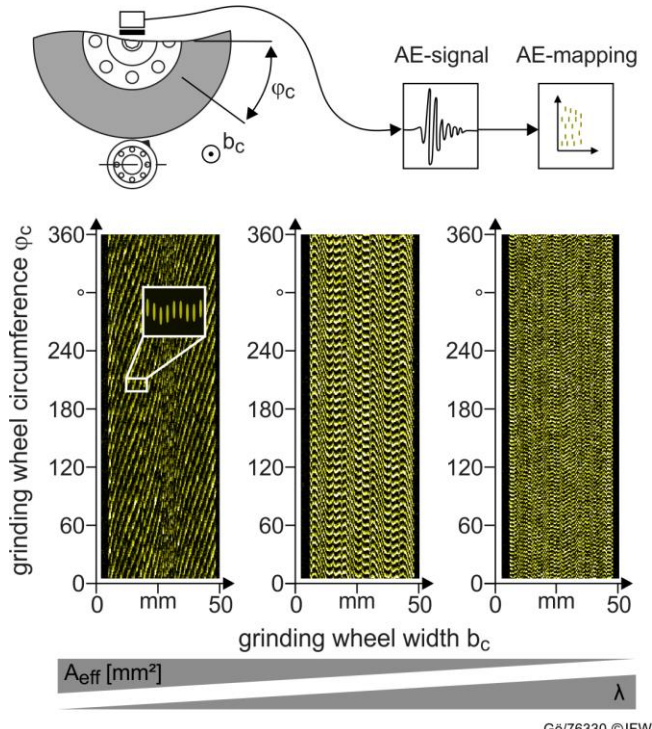


Fig. 5 AE-mapping for patterning process monitoring

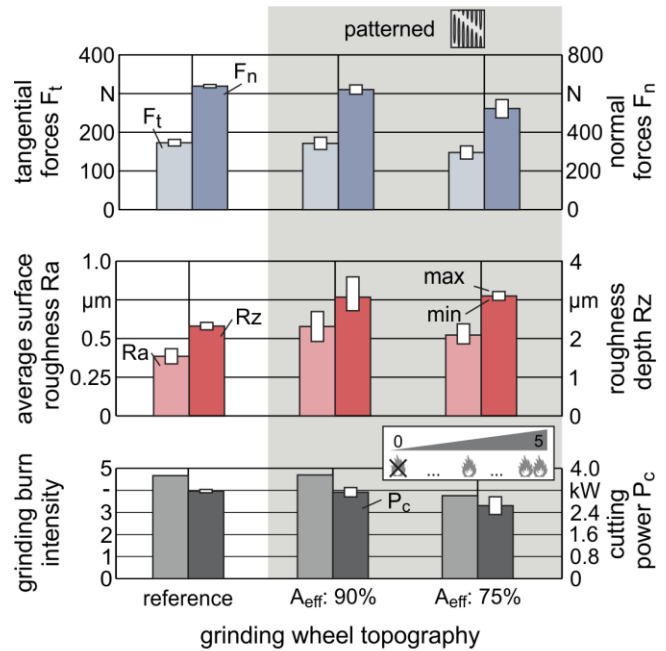
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## 5 Influence of patterned grinding wheels in grinding

In this chapter the results of face grinding experiments are presented. In order to proof if the results obtained by face grinding can be transferred to another grinding process kinematic, cylindrical grinding experiments are conducted. The grinding results of the patterned tools are compared to the results when grinding with a non-patterned grinding wheel (reference).

### 5.1 Face grinding results

The results of the face grinding experiments are illustrated in Fig. 6. The process parameters were kept constant at a cutting speed of  $v_s = 20$  m/s, a feed rate of  $v_w = 2.400$  mm/min and cutting depth of  $a_c = 50$   $\mu$ m. The results show the mean value of three experimental runs.



grinding:	patterning:	workpiece / tool:
face grinding	patterning tool	Al <sub>2</sub> O <sub>3</sub> , #80
$v_s = 20$ m/s	(1 diamond)	1.2379, 64 HRC
$a_c = 50$ $\mu$ m	$A_{eff} = \text{var.}$	
$v_w = 2.400$ mm/min	$a_{ed} = 70$ $\mu$ m	

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Fig. 6 Results of face grinding experiments

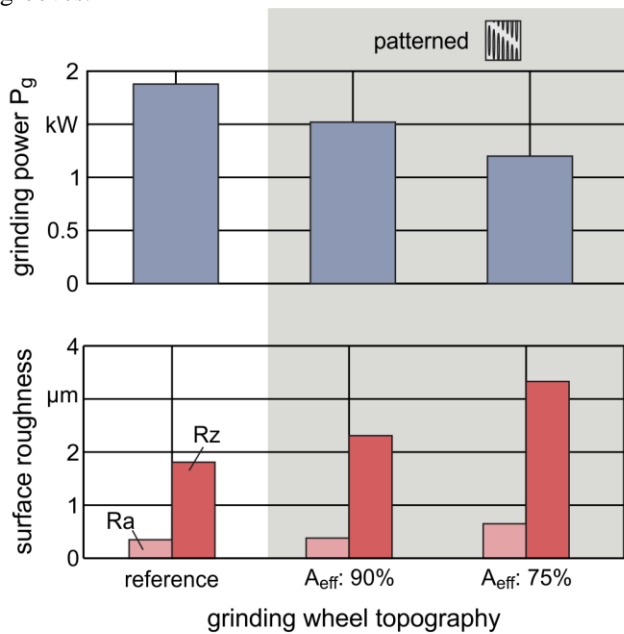
The process forces in normal and tangential direction decrease significantly if the number of pattern rises and the effective contact area decreases to  $A_{eff} = 75$  %. Less active grains are involved in the grinding process and therefore ploughing and rubbing processes are suppressed for the benefit of a more effective cutting process due to increased micro cutting in the contact zone. By reducing the number of cutting edges, the surface roughness after grinding with patterned grinding wheels is higher compared to the reference, since less kinematic overlappings of cutting paths that even the work piece surface occur. As a result of reduced tangential forces, also less cutting power ( $P_c$ ) was necessary when grinding with an effective contact area of  $A_{eff} = 75$  %. The cutting power was calculated according to:

$$P_c = F_t * v_c \quad (4)$$

After grinding the work piece surface was optically analyzed and grinding burn marks have been correlated with a grinding burn intensity on a scale from 0 to 5 (0 = no burning, 5 = severe burning). The patterns on the grinding wheel increase the coolant flow and chip transport capacity through the contact zone and therefore reduce the thermal load. Thus, less grinding burn was detected when grinding with patterned grinding wheels.

### 5.2 Cylindrical grinding results

The results of the cylindrical grinding experiments are shown in Fig. 7. The cutting velocity was  $v_s = 30$  m/s, the radial feed rate  $v_{fr} = 0.2$  mm/min, the grinding width of cut  $b = 50$  mm, and a material removal rate of  $Q'_w = 0,5$  mm<sup>3</sup>/mm\*s. The spark out time was set to 2 seconds. Different from the face grinding experiments, the grinding power was estimated based on the net power consumption of the wheel head motor during grinding. Similar to the face grinding force results, the grinding power decreases significantly when the number of pattern is increased (lower value of effective contact area), due to the reduced contact area and increased number of patterning grooves. The grinding power was reduced from 1,9 kW to 1,3 kW by more than 30 %. Less power is necessary for the material removal, since the rubbing component is reduced along with the lower wheel contact area. The surface roughness values were also influenced by the changes on the effective contact area due to patterning. For the baseline condition, regular dressed wheel, with no patterning, the obtained values were:  $R_a = 0,35$   $\mu$ m and  $R_z = 1,81$   $\mu$ m. When grinding with a highly patterned grinding wheel with  $A_{eff} = 75$  %, the roughness increased to  $R_a = 0,65$   $\mu$ m and  $R_z = 3,33$   $\mu$ m, due to the reduced contact area and also the additional wheel macro effect of patterning with shallow grooves.



grinding:	patterning:	workpiece / tool:
cylindrical grinding	patterning tool	$Al_2O_3$ , # 80
$v_s = 30$ m/s	(4 diamonds)	1.7225
$b = 50$ mm	$A_{eff} = \text{var.}$	
$v_r = 0.2$ mm/min	$a_{ed} = 70$ $\mu$ m	

Fig. 7 Results of cylindrical grinding experiments

### 6 Conclusion

In this paper a new and innovative method for the patterning of grinding wheels was presented. The patterns are machined with a patterning tool with one or four diamonds that is connected to a conventional dressing spindle. Therefore this compact setup can be transferred to almost any grinding machine. By changing the patterning process parameters different pattern sizes and densities resulting in different effective contact areas ( $A_{eff}$ ) can be machined in a flexible way.

In order to identify the potential of patterned grinding wheels, surface and cylindrical grinding experiments have been conducted. The results show that patterned grinding wheels decrease:

- process forces of up to 20 %
- thermal damage in terms of grinding burn significantly
- the grinding power by over 30 %

compared to non-patterned grinding wheels. Nevertheless this benefit goes along with an increase of the surface roughness due to less active kinematic cutting edges. Especially for roughing processes the results show great potential for increasing the overall grinding performance, since high surface qualities are generally achieved by subsequent finishing processes. Possible future industrial applications should focus on highly thermal stressed grinding processes, such as creep feed grinding of superalloys, profile grinding of gears or plunge grinding of crankshafts. An advantage of this patterning method is that only certain areas of the grinding wheel can be patterned to partially reduce the grinding burn for example.

### 7 Acknowledgements

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