

Error Resilient Compression and Transmission of Scalable Video

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Features Requirements

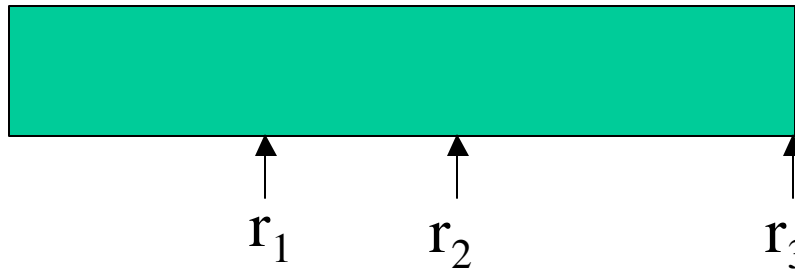
- High performance
 - low MSE (high PSNR) for given rate
- fast, simple encoding and decoding
- low memory usage
 - independent of image/video frame size
- random access



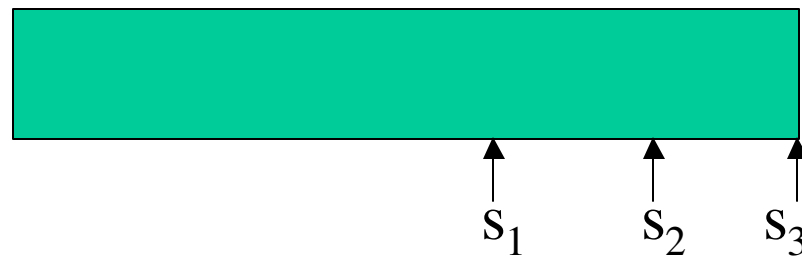
Features Requirements: Scalability

Rate or PSNR scalability: lower rate files embedded in full compressed file

S_2



Spatial (resolution) scalability: lower resolution files embedded in full compressed file

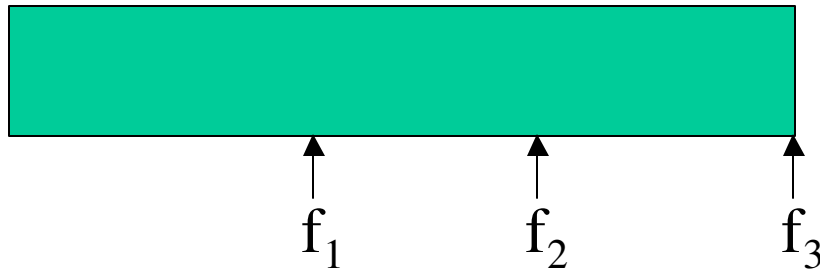


S_1



Scalability (cont.)

Video frame rate scalability: lower frame rates embedded in full compressed file



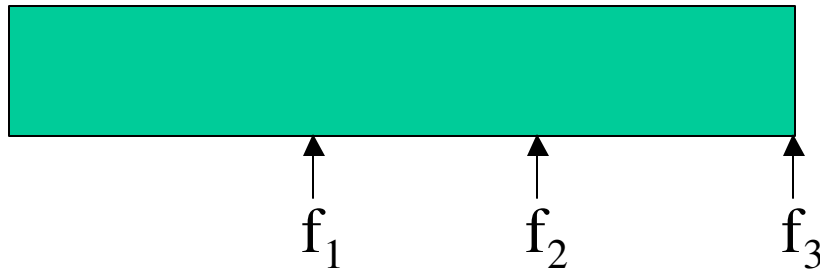
f_1 -> every 4th frame

f_2 -> every 2nd frame

f_3 -> every frame

Scalability (cont.)

Video frame rate scalability: lower frame rates embedded in full compressed file



f_1 -> every 4th frame

f_2 -> every 2nd frame

f_3 -> every frame

Transmission Features

- Robust to channel errors/packet loss
 - unprotected bit stream degrades gracefully
 - no overhead required for robustness
- Resilience to channel errors/packet loss
 - redundant bits added for error-correcting channel code
 - video reception of acceptable quality in severe environments

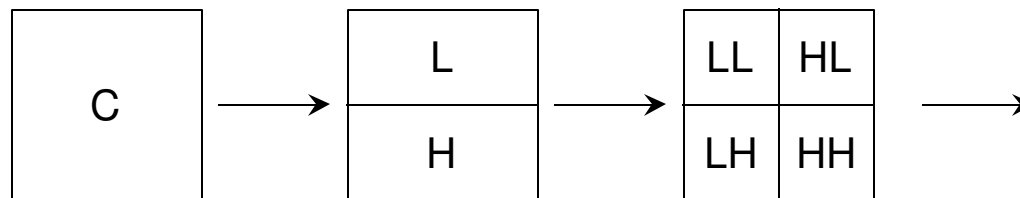
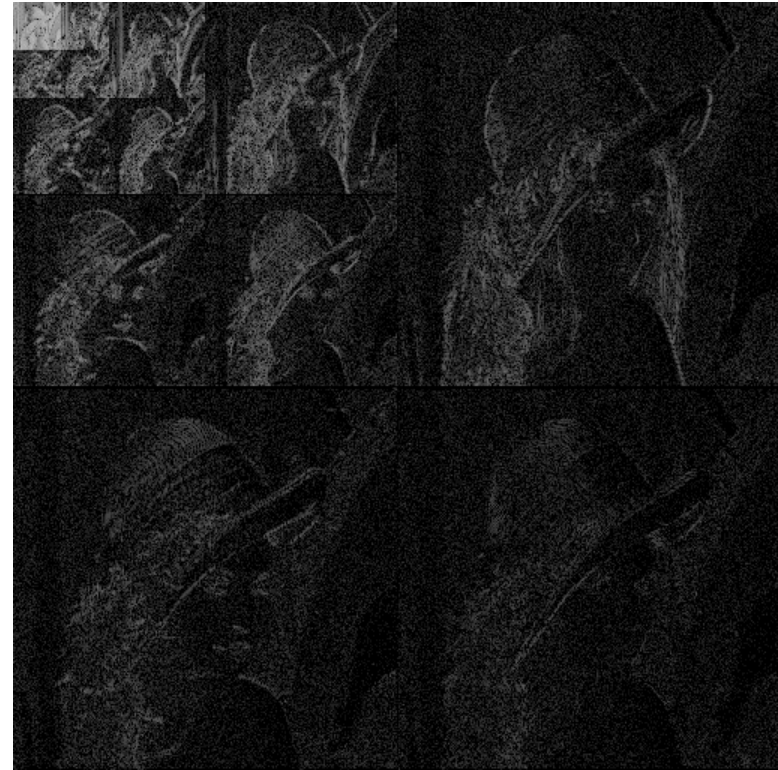
Basis: SPIHT

- State of the art performance
 - › SPIHT is the modern-day benchmark
- Low in complexity
 - › efficient and fast
- Fidelity embedded
 - › scalable in rate with precise rate control
- Coding of wavelet subbands
 - › capable of progressive resolution

SPIHT (cont.)

- Sensitive to channel errors
 - error in significance decision bit causes catastrophic degradation for rest of bit stream
 - error in refinement bit causes graceful degradation only

Image Wavelet/Subband Transform



SPIHT Algorithm

- Discovered by Said and Pearlman (IEEE CSVT 1996)
- Partitions spatial orientation tree sets
- The algorithm maintains three lists of sets
 - LIP: list of coordinates of insignificant pixels
 - initialized by highest level low-pass (DC) subband
 - LIS: list of coordinates of insignificant sets and their type (D or G)
 - initialized by coordinates in DC subband with descendants as D type
 - LSP: list of coordinates of significant pixels
 - initially empty

SPIHT Tree Structure

3 level dyadic subband transform shown

Arrows depict parent-child relationships in the SPIHT tree structure

Coefficients are grouped to exploit magnitude dependence

Each subband coefficient has four children

Some coefficients in the DC subband have no children

Each coefficient is denoted by its coordinates (i,j)

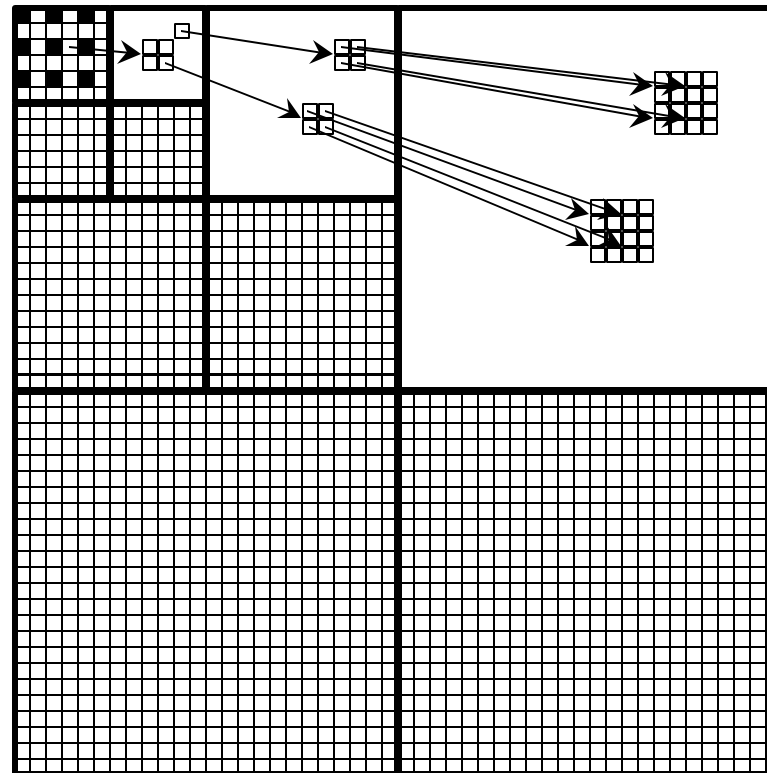
Set Types

(i,j) : Single coefficient

$C(i,j)$: Children of (i,j)

$D(i,j)$: Descendants of (i,j)

$G(i,j)$: $D(i,j) - C(i,j)$



Set Partitioning

Significance test for pixels $c_{i,j}$ in set B

$$S_n(B) = \begin{cases} 1, & \text{if } \left(\max_{(i,j) \in B} |c_{ij}| \right) \geq 2^n, \\ 0, & \text{otherwise.} \end{cases}$$

- SPIHT uses three lists to minimize the number of tests for a given bit-plane (n).
 - LIP (List of Insignificant Pixels) – visit pixels that are insignificant and do not belong to insignificant sets.
 - LIS (List of Insignificant Sets) – visit all the sets (with more than one pixel) that are insignificant but do not belong to a larger insignificant set.
 - LSP (List of Significant Pixels) – send n-th bit of all pixels found to be significant in previous passes.

Sorting by Magnitude and Bit-Plane Transmission

Transmission of magnitude-sorted coefficients

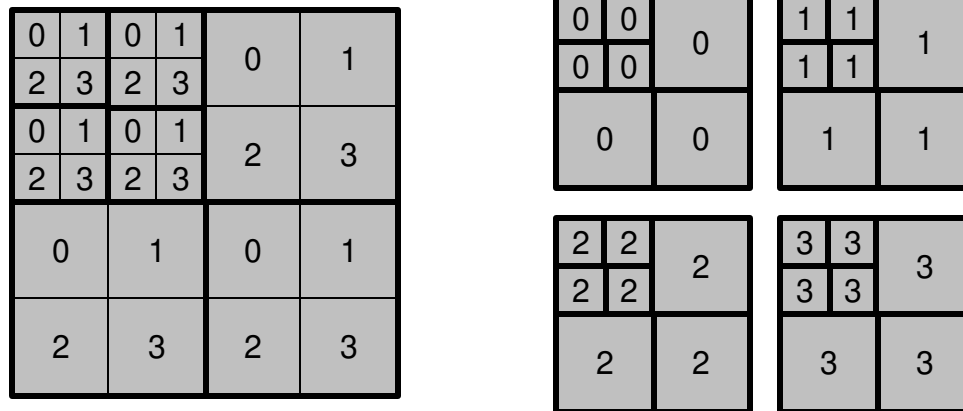
	sign	s	s	s	s	s	s	s	s	s	s	s	s	s
msb	5	1	1	0	0	0	0	0	0	0	0	0	0	0
	4	→	→	1	1	0	0	0	0	0	0	0	0	0
	3	→	→	→	→	1	1	1	1	0	0	0	0	0
	2	→	→	→	→	→	→	→	→	1	1	1	1	1
	1	→	→	→	→	→	→	→	→	→	→	→	→	→
lsb	0	→	→	→	→	→	→	→	→	→	→	→	→	→

Spatial (Tree) Blocks

- SPIHT coding applied to small transform tree-blocks independently
 - these *spatial blocks* in transform domain correspond to spatial regions plus overlap area in image domain
- Embedded bit streams from independent tree-block encoders are packetized and multiplexed to generate a progressive main bit stream

Tree-Block Partitioning

- Works with line- or block-based wavelet transform
- Transform will deliver subband partition corresponding to image block
- Subband partition is organized into tree-blocks, if necessary
- SPIHT encoder is applied to trees
- Example shows a 2 level subband partition organized into 4 trees forming a tree-block



In actual experiments a 5 level transform is used and partitioning generates 128 by 128 or 64 by 64 tree-blocks

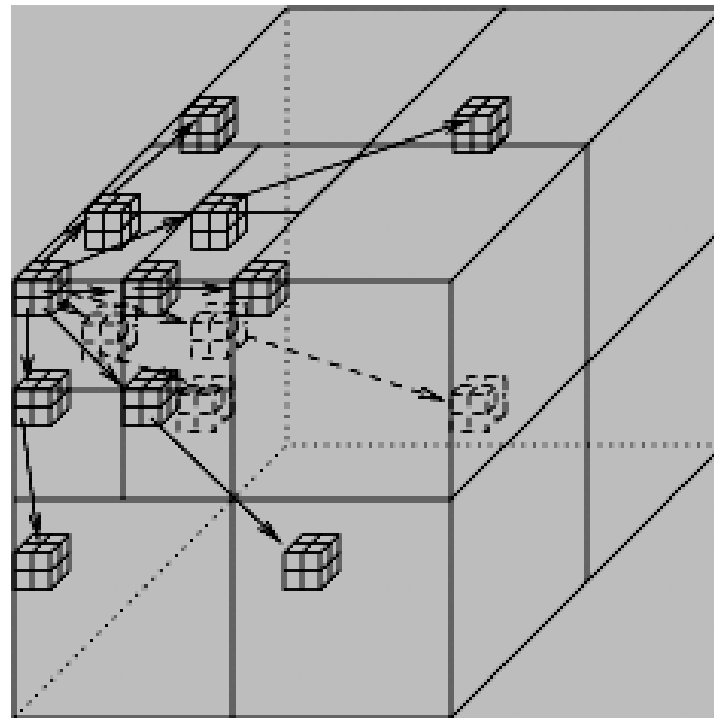
Image Sequence Coding

- 3D Wavelet Subbands of Groups of Frames
 - 4, 8, 16 frames
- Temporal (axial) subbanding decorrelates and compacts energy into low frequency bands
 - *no motion estimation/compensation*

Image Sequence Coding (cont.)

- SPIHT coding on 3D s-t orientation trees
- Independent coding of s-t blocks for robust bitstream transmission
- Packet interleaving for fidelity embedding
- Channel coding of packets for error resilient reception
- Selective decoding in received bit stream for desired rate, spatial resolution, and frame rate

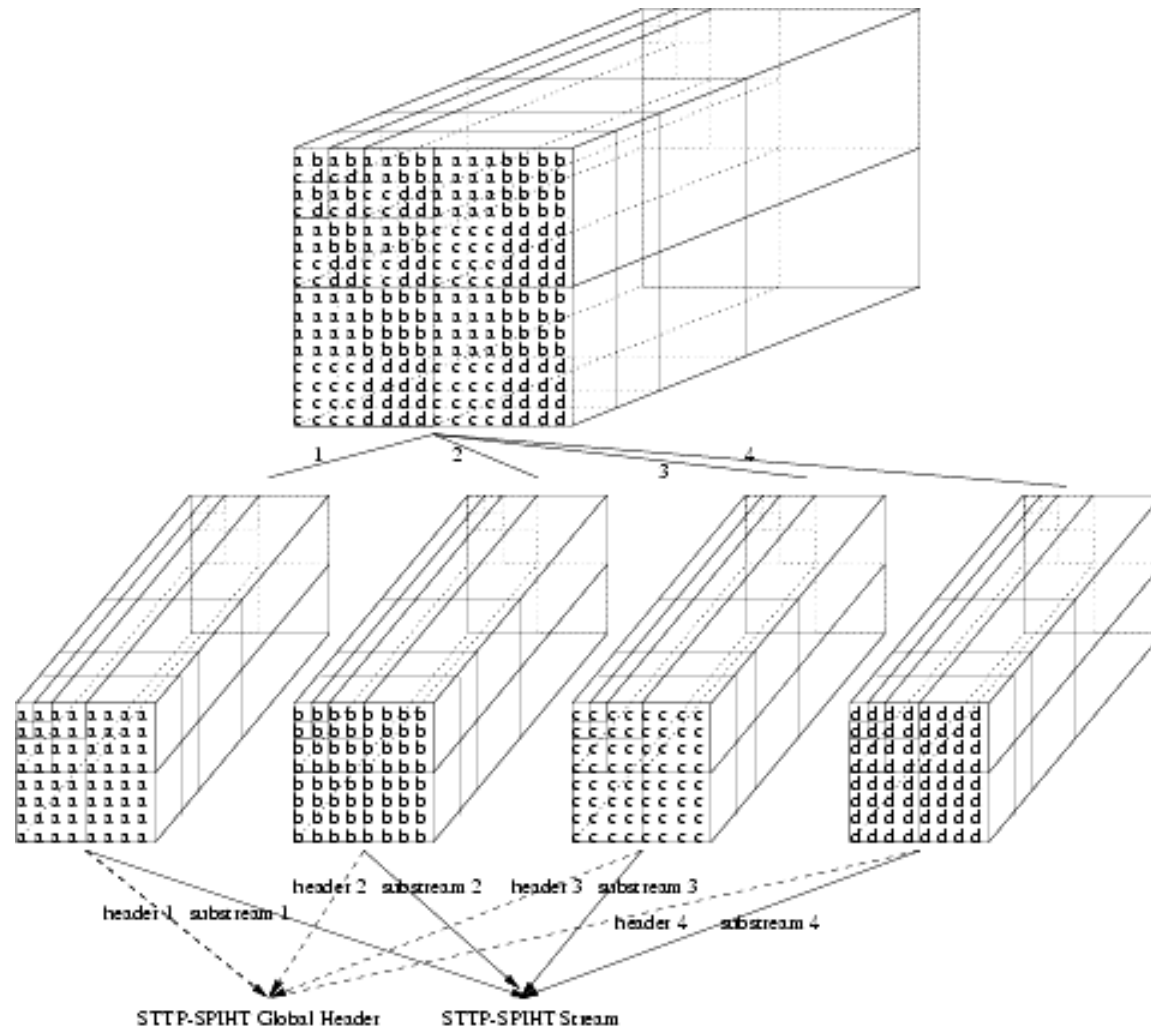
3-D S-T Orientation Tree



STTP-SPIHT

- Break transform into n groups of spatio-temporal trees, called spatio-temporal (s-t) blocks (corresponds to s-t region in sequence)
- Encode (decode) each s-t block independently
- Channel error or packet loss affects only one block and hence one s-t region

Spatio-Temporal Tree Preserving SPIHT



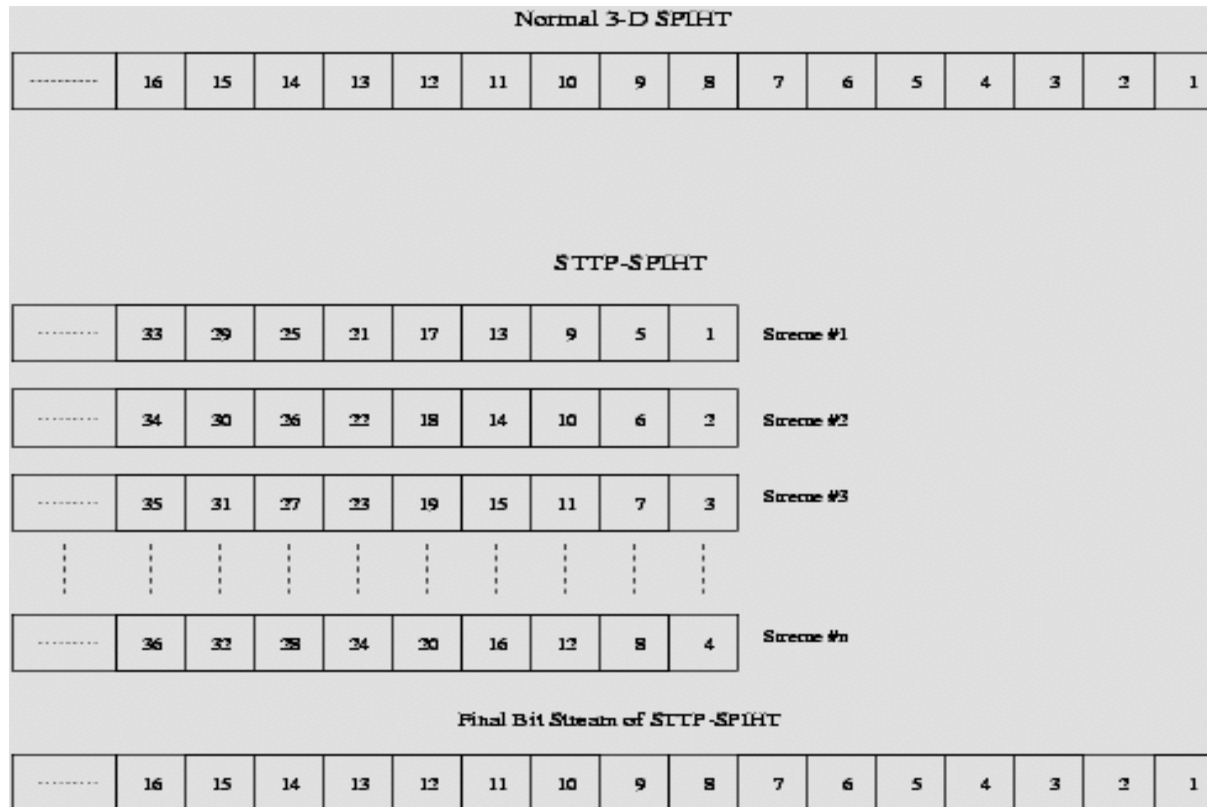
Progressive Bit Stream

- The SPIHT algorithm generates a progressive bit stream for each tree-block
- As the SPIHT algorithm progresses it periodically records the current bit plane and list (LIP, LIS or LSP) being processed
- Once a sub-bit stream has been generated for each sub-image they are packetized and multiplexed to generate the primary bit stream
- Priority is given to packets with data for more significant bit planes
- Within the same bit plane, priority is given to packets with data for the LIP, then LIS then LSP
- The packetized bit stream is progressive

Example main bit stream structure:

hdr	0	data for 0	1	data for 1	2	data for 2	3	data for 3	
2	data for 2	3	data for 3	3	data for 3	1	data for 1	2	data for 2

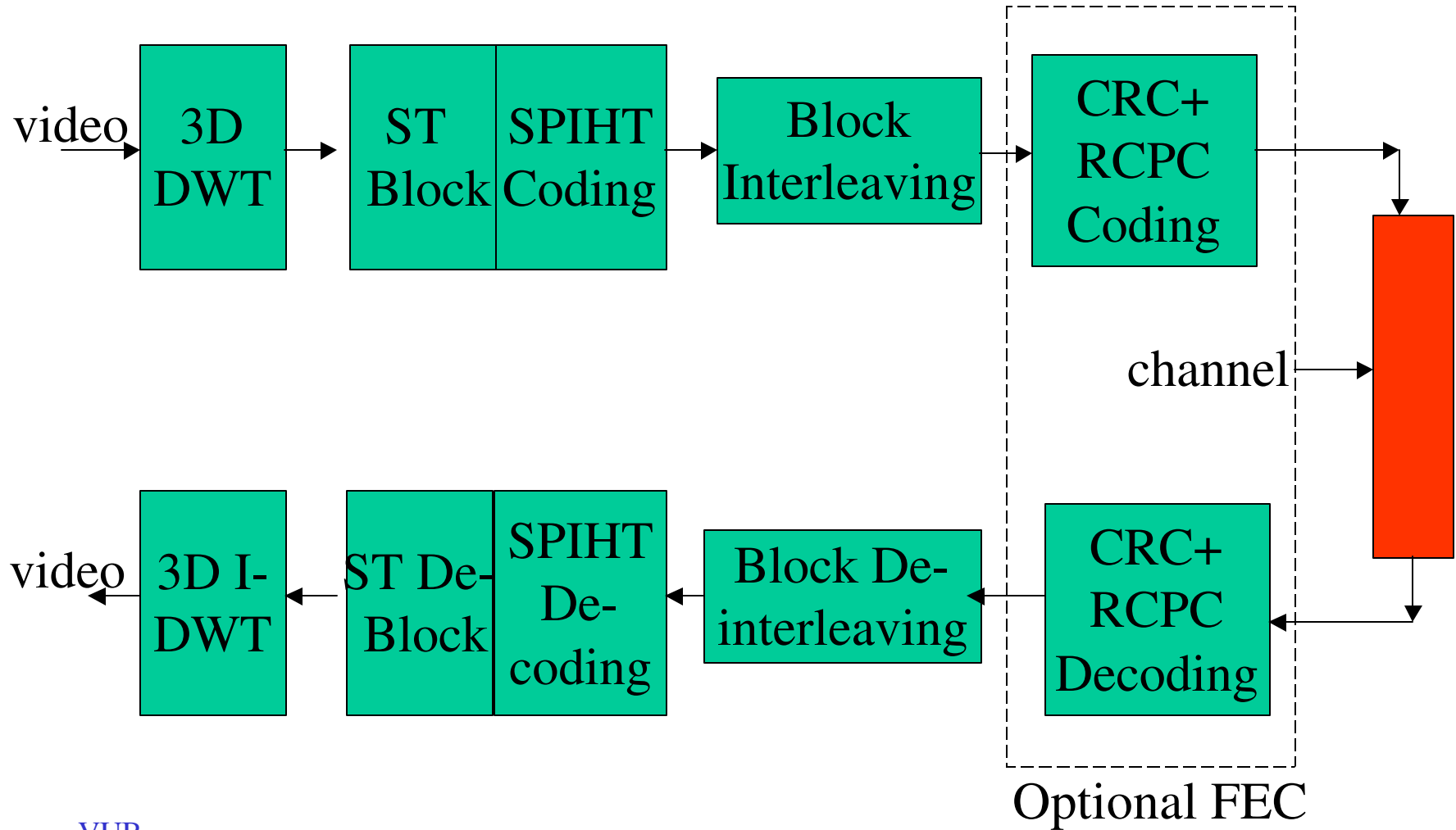
Packet Interleaving



STTP-SPIHT

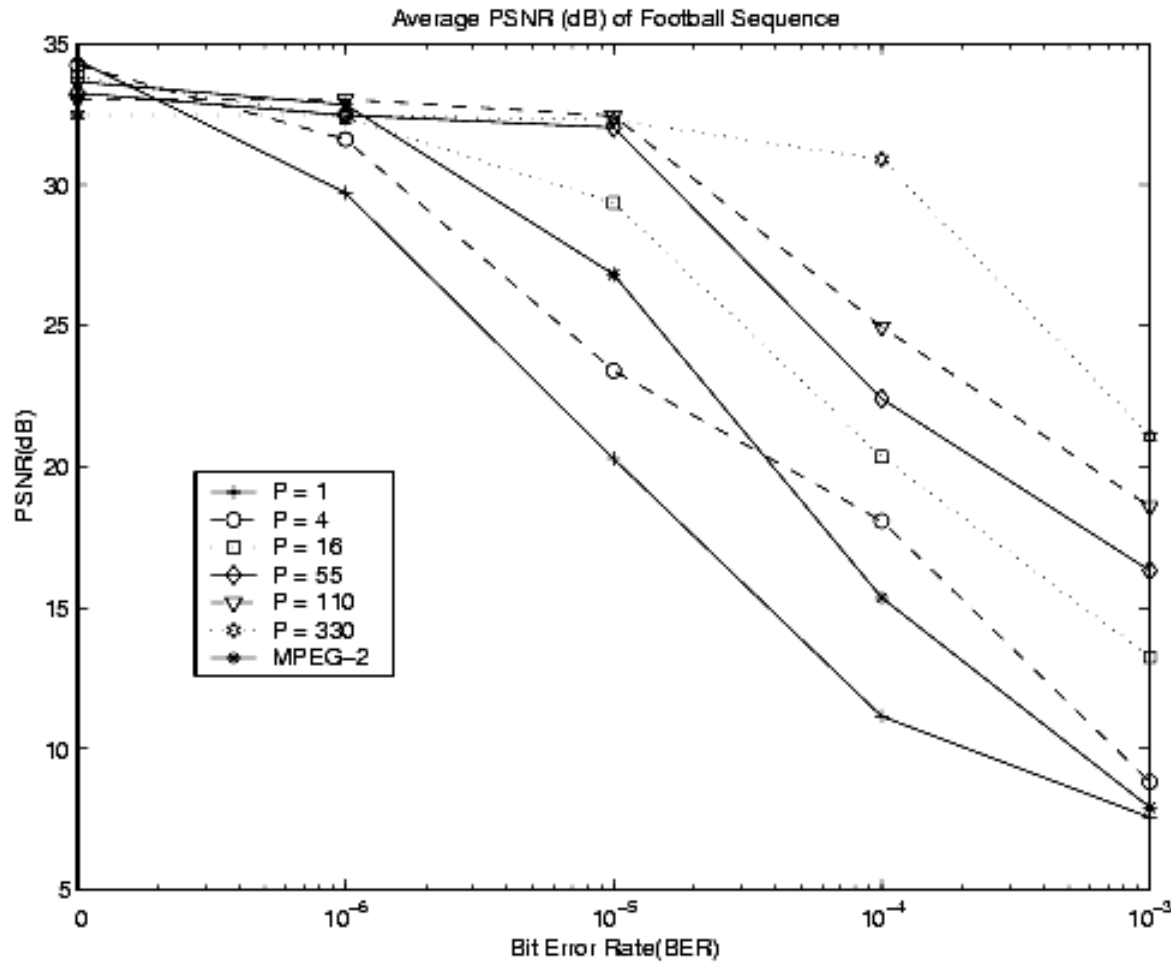
- Requires overhead of header for each s-t block
- Fidelity embedding retained
 - bit stream packetized and re-organized

Video Coding/Transmission System



PSNR vs. BER for Different P

No FEC



Rensselaer Error Sensitivity of Normal SPIHT

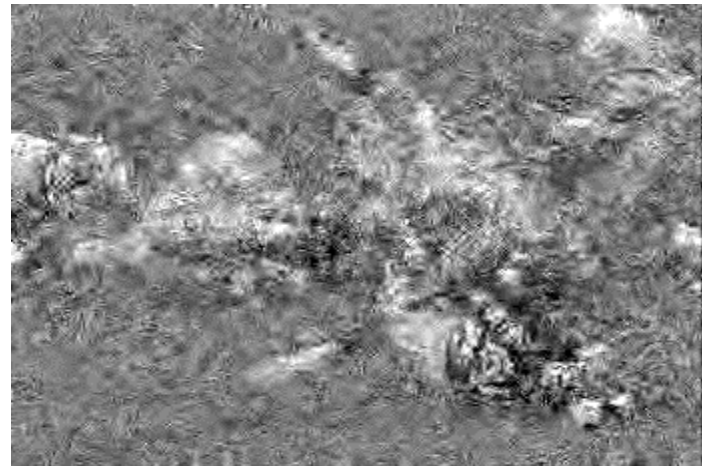
Original Frame 15



BER=0,
33.26 dB



BER= 10^{-5} , P=16, 27.00 dB



BER= 10^{-5} , PSNR=18.25 dB

STTP-SPIHT vs. MPEG: BER=10⁻⁴, No FEC

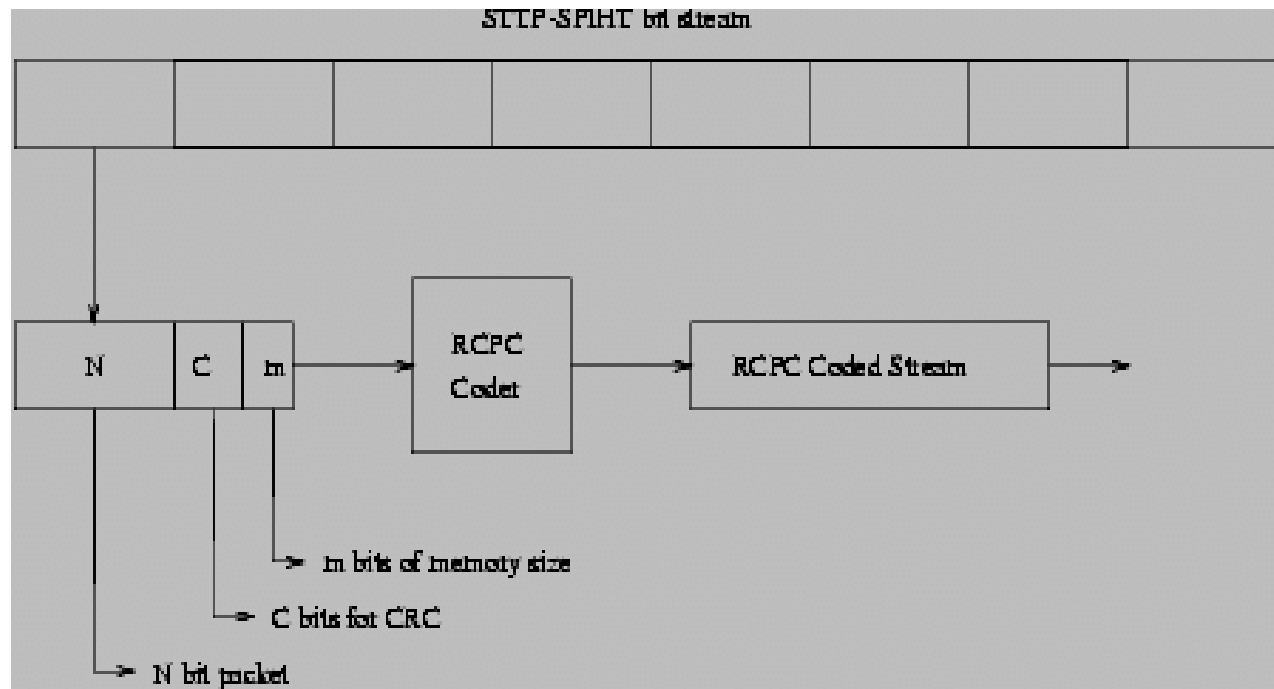


STTP-SPIHT, P=110, 25.80 dB



MPEG-2, PSNR=16.88 dB

Channel Coding Sub-system



FEC SPIHT Framework

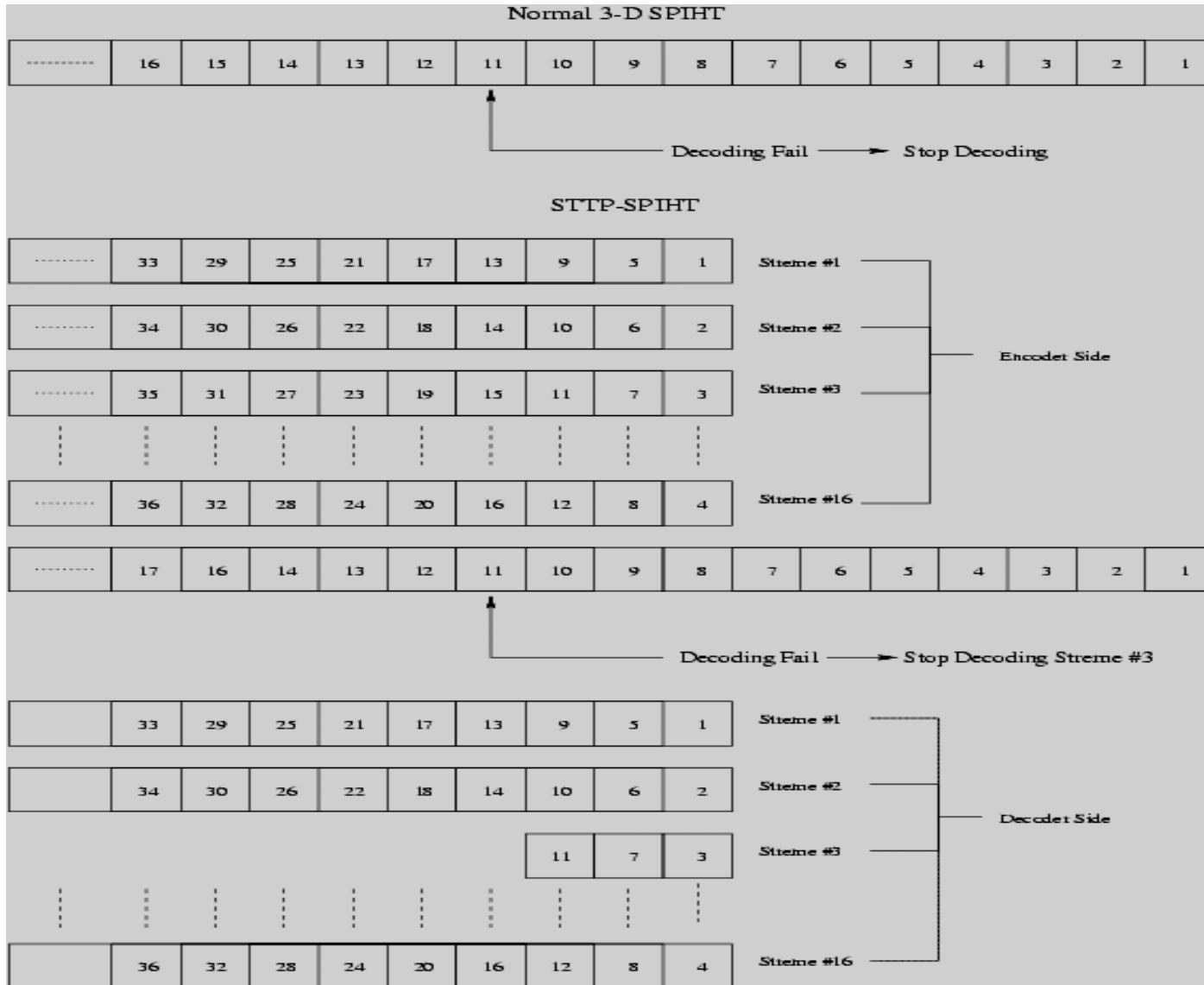
- Cascade 3D SPIHT with FEC scheme
 - $c = 16$ bit CRC parity check code + RCPC code: same decoder for different rates r
 - $m = 6$ bits to flush memory
- For length N source segment, effective rate

$$R_{eff} = [Nr/(N+c+m)] * R_{trans}$$

$$R_{trans} = 2.53 \text{ Mbps}$$

r	2/7	2/3	8/9
BER	0.1	0.01	0.001
$R_{eff} (bps)$	651,223	1,519,519	2,026,026

Bit Stream Organization



Rensselaer FEC, BER=10⁻² Comparisons



Original Frame 15



SPIHT, P=1, 24.41 dB



SPIHT, P=16, 29.35 dB



MPEG-2, 27.45 dB



STTP-SPIHT vs. MPEG-2: BER=10⁻², FEC

Frame 10



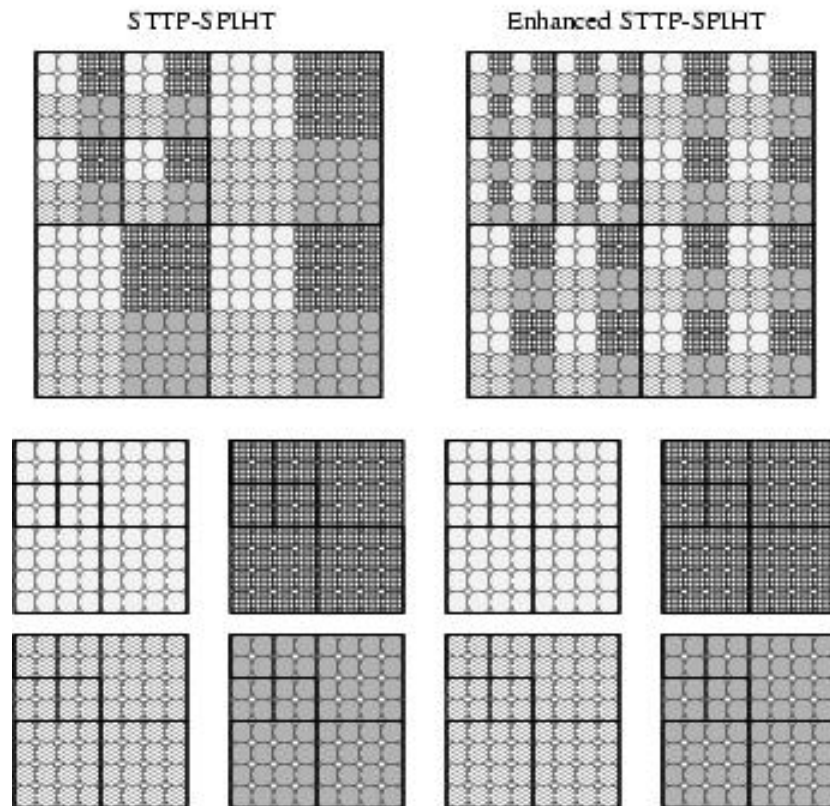
STTP-SPIHT, $P=16$, 30.49 dB



MPEG-2, 21.48 dB

New Tree Block Formation

Graphical Illustration of 2 Methods



Video Frames for Different Methods

Comparison in Noisy Channel

Original Image



Normal 3D-SPIHT



PSNR = 24.41 dB

ESTTP-SPIHT



PSNR = 31.47 dB

STTP-SPIHT



PSNR = 28.68 dB

SPIHT FEC Average Results*

BER	ENER-SPIHT	STTP-SPIHT	3D-SPIHT	3D SPIHT/ ARQ
0.01	30.23	29.75	24.5	32.1
0.001	31.75	31.75	28.2	32.8

*Football Sequence, PSNR numbers

Conclusions

- Even w/o MC, better than MPEG-2 in noiseless and noisy channels
- SPIHT video bit stream can be robust or resilient to channel errors and packet loss
- Acceptable video quality can be delivered over very noisy channels
- Improvement possible via unequal error protection
- Promising for real-time, hardware applications