Existence of conformal metrics with constant Q-curvature

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ABSTRACT. Given a compact four dimensional manifold, we prove existence of conformal metrics with constant Q-curvature under generic assumptions. The problem amounts to solving a fourth-order non-linear elliptic equation with variational structure. Since the corresponding Euler functional is in general unbounded from above and from below, we employ topological methods and minimax schemes, jointly with the compactness result of [32].

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1 Introduction

In recent years, much attention has been devoted to the study of partial differential equations on manifolds, in order to understand some relationship between analytic and geometric properties of these objects.

A basic example is the Laplace-Beltrami operator on a compact surface (Σ, g) . Under the conformal change of metric $\tilde{g} = e^{2w}g$, we have

(1)
$$\Delta_{\tilde{g}} = e^{-2w} \Delta_g; \qquad -\Delta_g w + K_g = K_{\tilde{g}} e^{2w},$$

where Δ_g and K_g (resp. $\Delta_{\tilde{g}}$ and $K_{\tilde{g}}$) are the Laplace-Beltrami operator and the Gauss curvature of (Σ, g) (resp. of (Σ, \tilde{g})). From the above equation one recovers in particular the conformal invariance of $\int_{\Sigma} K_g dV_g$, which is related to the topology of Σ through the Gauss-Bonnet formula

(2)
$$\int_{\Sigma} K_g dV_g = 2\pi \chi(\Sigma),$$

where $\chi(\Sigma)$ is the Euler characteristic of Σ . Of particular interest is the classical Uniformization Theorem, which asserts that every compact surface carries a (conformal) metric with constant curvature.

On four dimensional manifolds there exists a conformally covariant operator, the Paneitz operator, which enjoys analogous properties to the Laplace-Beltrami operator on surfaces, and to which is associated a natural concept of curvature. This operator, introduced by Paneitz, [34], [35], and the corresponding

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Q-curvature, introduced in [7], are defined in terms of Ricci tensor Ric_g and scalar curvature R_g of the manifold (M, g) as

(3)
$$P_g(\varphi) = \Delta_g^2 \varphi + div_g \left(\frac{2}{3}R_g g - 2Ric_g\right) d\varphi;$$

(4)
$$Q_g = -\frac{1}{12} \left(\Delta_g R_g - R_g^2 + 3 |Ric_g|^2 \right),$$

where φ is any smooth function on M. The behavior (and the mutual relation) of P_g and Q_g under a conformal change of metric $\tilde{g} = e^{2w}g$ is given by

(5)
$$P_{\tilde{g}} = e^{-4w} P_g; \qquad P_g w + 2Q_g = 2Q_{\tilde{g}} e^{4w}$$

Apart from the analogy with (1), we have an extension of the Gauss-Bonnet formula which is the following

(6)
$$\int_{M} \left(Q_g + \frac{|W_g|^2}{8} \right) dV_g = 4\pi^2 \chi(M),$$

where W_g denotes the Weyl tensor of (M, g). In particular, since $|W_g|^2 dV_g$ is a pointwise conformal invariant, it follows that the integral of Q_g over M is also a conformal invariant, which is usually denoted with the symbol

(7)
$$k_P = \int_M Q_g dV_g.$$

We refer for example to the survey [18] for more details.

To mention some first geometric properties of P_g and Q_g , we discuss some results of Gursky, [27] (see also [26]). If a manifold of non-negative Yamabe class (Y(g)) satisfies $k_P \ge 0$, then the kernel of P_g are only the constants, and $P_g \ge 0$. If in addition Y(g) > 0, then the first Betti number of M vanishes, unless (M,g) is conformally equivalent to a quotient of $S^3 \times \mathbb{R}$. On the other hand, if $Y(g) \ge 0$, then $k_P \le 8\pi^2$, with the equality holding if and only if (M,g) is conformally equivalent to the standard sphere.

As for the Uniformization Theorem, one can ask whether every four-manifold (M, g) carries a conformal metric \tilde{g} for which the corresponding *Q*-curvature $Q_{\tilde{g}}$ is a constant. Writing $\tilde{g} = e^{2w}g$, by (5) the problem amounts to finding a solution of the equation

(8)
$$P_g w + 2Q_g = 2\overline{Q}e^{4w},$$

where \overline{Q} is a real constant. By the regularity results in [39], critical points of the following functional

(9)
$$II(u) = \langle P_g u, u \rangle + 4 \int_M Q_g u dV_g - k_P \log \int_M e^{4u} dV_g; \qquad u \in H^2(M),$$

where

(10)
$$\langle P_g u, v \rangle = \int_M \left(\Delta_g u \Delta_g v + \frac{2}{3} R_g \nabla_g u \cdot \nabla_g v - 2(Ric_g \nabla_g u, \nabla_g v) \right) dV_g \quad \text{for } u, v \in H^2(M),$$

which are weak solutions of (8), are also strong solutions.

Problem (8) has been solved in [16] for the case in which P_g is a positive operator and $k_P < 8\pi^2$. By the above-mentioned result of Gursky, sufficient conditions for these assumptions to hold are that $Y(g) \ge 0$ and that $k_P \ge 0$ (and (M,g) is not conformal to the standard sphere). See also [28] for more sufficient conditions. Under the assumptions in [16], by the Adams inequality (see (23) with P_g^+ replaced by P_g) the functional II is bounded from below and coercive, hence solutions can be found as global minima. The result in [16] has also been extended in [10] to higher-dimensional manifolds (regarding higher-order operators and curvatures) using a geometric flow.

The solvability of (8), under the above hypotheses, has been useful in the study of some conformally invariant fully non-linear equations, as is shown in [13]. Some remarkable geometric consequences of this study, given in [12], [13], are the following. If a manifold of positive Yamabe class satisfies $\int_M Q_g dV_g > 0$, then there exists a conformal metric with positive Ricci tensor, and hence M has finite fundamental group. Furthermore, under the additional quantitative assumption $\int_M Q_g dV_g > \frac{1}{8} \int_M |W_g|^2 dV_g$, M must be diffeomorphic to the four-sphere or to the projective space. Finally, we also point out that the Paneitz operator and the Q-curvature (together with their higher-dimensional analogues, see [5], [6], [24], [25]) appear in the study of Moser-Trudinger type inequalities, log-determinant formulas and the compactification of locally conformally flat manifolds, [7], [8], [14], [15], [16].

We are interested here in extending the uniformization result in [16], namely to find solutions of (8) under more general assumptions. Our result is the following.

Theorem 1.1 Suppose ker $P_g = \{constants\}$, and assume that $k_P \neq 8k\pi^2$ for k = 1, 2, ... Then M admits a conformal metric with constant Q-curvature.

Remark 1.2 (a) Our assumptions are conformally invariant and generic, so the result applies to a large class of four manifolds, and in particular to some manifolds of negative curvature or negative Yamabe class, previously excluded by the results in [27].

(b) Under these assumptions, imposing the volume normalization $\int_M e^{4u} dV_g = 1$, the set of solutions (which is non-empty) is bounded in $C^m(M)$ for any integer m, by Theorem 1.3 in [32].

(c) Theorem 1.1 does NOT cover the case of locally conformally flat manifolds with positive Euler characteristic, by (6).

Our assumptions include those made in [16] and one (or both) of the following two possibilities

(11)
$$k_P \in (8k\pi^2, 8(k+1)\pi^2), \quad \text{for some } k \in \mathbb{N};$$

(12)
$$P_g$$
 possesses \overline{k} (counted with multiplicity) negative eigenvalues.

In these cases the functional II is unbounded from below, and hence it is necessary to find extrema which are possibly saddle points. This is done using a new minimax scheme, which we are going to describe below, depending on k_P and the spectrum of P_g (in particular on the number of negative eigenvalues \overline{k}). By classical arguments, the scheme yields a *Palais-Smale sequence*, namely a sequence $(u_l)_l \subseteq H^2(M)$ satisfying the following properties

(13)
$$II(u_l) \to c \in \mathbb{R}; \qquad II'(u_l) \to 0 \qquad \text{as } l \to +\infty.$$

We can also assume that such a sequence $(u_l)_l$ satisfy the volume normalization

(14)
$$\int_{M} e^{4u_l} dV_g = 1 \qquad \text{for all } l.$$

This is always possible since the functional II is invariant under the transformation $u \mapsto u + a$, where a is any real constant. Then, to recover existence, one should prove for example that $(u_l)_l$ is bounded, or to recover a similar compactness criterion.

In order to do this, we apply a procedure from [36], used in [22], [29], [38]. For ρ in a neighborhood of 1, we define the functional $II_{\rho}: H^2(M) \to \mathbb{R}$ by

$$II_{\rho}(u) = \langle P_g u, u \rangle + 4\rho \int_{M} Q_g dV_g - 4\rho k_P \log \int_{M} e^{4u} dV_g, \qquad u \in H^2(M),$$

whose critical points give rise to solutions of the equation

(15)
$$P_q u + 2\rho Q_q = 2\rho k_P e^{4u} \quad \text{in } M.$$

One can then define the minimax scheme for different values of ρ and prove boundedness of some Palais-Smale sequence for ρ belonging to a set Λ which is dense in some neighborhood of 1, see Section 5. This implies solvability of (15) for $\rho \in \Lambda$. We then apply the following result from [32], with $Q_l = \rho_l Q_g$, where $(\rho_l)_l \subseteq \Lambda$ and $\rho_l \to 1$.

Theorem 1.3 ([32]) Suppose ker $P_q = \{constants\}$ and that $(u_l)_l$ is a sequence of solutions of

(16)
$$P_{q}u_{l} + 2Q_{l} = 2k_{l}e^{4u_{l}} \qquad in \ M,$$

satisfying (14), where $k_l = \int_M Q_l dV_q$, and where $Q_l \to Q_0$ in $C^0(M)$. Assume also that

(17)
$$k_0 := \int_M Q_0 dV_g \neq 8k\pi^2 \qquad for \ k = 1, 2, \dots$$

Then $(u_l)_l$ is bounded in $C^{\alpha}(M)$ for any $\alpha \in (0,1)$.

We are going to give now a brief description of the scheme and an heuristic idea of its construction. We describe it for the functional II only, but the same considerations hold for II_{ρ} if |rho - 1| is sufficiently small. It is a standard method in critical point theory to find extrema by looking at the difference of topology between sub or superlevels of the functionals. In our specific case we investigate the structure of the sublevels $\{II \leq -L\}$, where L is a large positive number. Looking at the structure of the functional II, see (9), one can image two ways for attaining large negative values.

The first, assuming (11), is by bubbling. In fact, for a given point $x \in M$ and a large $\lambda > 0$, consider the following function

$$\varphi_{\lambda,x}(y) = \log\left(\frac{2\lambda}{1+\lambda^2 dist(y,x)^2}\right).$$

Then $e^{4\varphi_{\lambda,x}} \simeq \delta_x$ (the Dirac mass at x) represents the volume density of a four sphere attached to Mat the point x, and one can show that $II(\varphi_{\lambda,x}) \to -\infty$ as $\lambda \to +\infty$. Similarly, for k given in (11), $(x_i) \subseteq M, t_i \ge 0$, it is possible to construct an appropriate function φ of the above form (near each x_i) with $e^{4\varphi} \simeq \sum_{i=1}^k t_i \delta_{x_i}$, and on which II still attains large negative values. Precise estimates are given in Section 4 and in the Appendix. Since II stays invariant if $e^{4\varphi}$ is multiplied by a constant, we can assume that $\sum_{i=1}^k t_i = 1$. On the other hand, if $e^{4\varphi}$ is concentrated at k + 1 points, it is possible to prove, using an improved Moser-Trudinger inequality from Section 2, that $II(\varphi)$ cannot attain large negative values anymore, see Lemmas 2.2 and 2.4. From this argument we see that one is led naturally to consider the family M_k of elements $\sum_{i=1} t_i \delta_{x_i}$ with $(x_i)_i \subseteq M$, and $\sum_{i=1}^k t_i = 1$, known in literature as the formal set of barycenters of M, which we are going to discuss in more detail below.

The second way to attain large negative values, assuming (12), is by considering the negative-definite part of the quadratic form $\langle P_g u, u \rangle$. Letting $V \subseteq H^2(M)$ denote the corresponding subspace, the functional II will tend to $-\infty$ on the boundaries of large balls in V, namely boundaries sets homeomorphic to the unit \overline{k} -ball $B_1^{\overline{k}}$.

Having these considerations in mind, we will use for the minimax a set, denoted by $A_{k,\overline{k}}$, which is constructed using some contraction of the product $M_k \times B_1^{\overline{k}}$, see the end of Section 2 (when $k_P < 8\pi^2$, we just take the sphere $S^{\overline{k}-1}$ instead of $A_{k,\overline{k}}$). It is possible indeed to map this set into $H^2(M)$ in such a way that the functional II on the image is close to $-\infty$, see Section 4. On the other hand, it is also possible to do the opposite, namely to map appropriate sublevels of II into $A_{k,\overline{k}}$, see Section 3. The composition of these two maps turns out to be homotopic to the identity on $A_{k,\overline{k}}$ (which is non-contractible by Corollary 3.8) and therefore they are both topologically non-trivial. Some comments are in order. For the case k = 1 and $\overline{k} = 0$, which is presented in [23], the minimax scheme is similar to that used in [22], where the authors study a mean field equation depending on a real parameter λ (and prove existence for $\lambda \in (8\pi, 16\pi)$). We believe that our construction could extend to that problem as well when $\lambda \neq 8k\pi$. Solutions for large values of λ have been obtained recently by Chen and Lin, using blow-up analysis and degree theory. See also the papers [30], [31], [38] and references therein for related results.

The set of barycenters M_k (see Subsection 3.1 for more comments or references) has been used crucially in literature for the study of problems with lack of compactness, see [3], [4]. In particular, for Yamabe-type equations (including the Yamabe equation and several other applications), it has been used to understand the structure of the *critical points at infinity* (or asymptotes) of the Euler functional, namely the way compactness is lost through a pseudo-gradient flow. Our use of the set M_k , although the map Φ of Section 4 presents some analogies with the Yamabe case, is of different type since it is employed to reach low energy levels and not to study critical points at infinity. As mentioned above, we consider a projection onto M_k , but starting only from functions in $\{II \leq -L\}$, whose concentration behavior is not as clear as that of the asymptotes. Here a technical difficulty arises. The main point is that, while in the Yamabe case all the coefficients t_i are bounded away from zero, in our case they can be arbitrarily small, and hence it is not so clear what the choice of the points x_i and the numbers t_i should be. To construct a continuous projection takes us some work, and this is done in Section 3.

The cases which are not included in Theorem 1.1 should be more delicate, especially when k_P is an integer multiple of $8\pi^2$. In this case non-compactness is expected, and the problem should require an asymptotic analysis as in [3], or some fine blow-up analysis as in [30], [19], [20]. Some blow-up behavior on open flat domains of \mathbb{R}^4 is studied in [2].

A related question in this context arises for the standard sphere $(k_P = 8\pi^2)$, where one could ask for the analogue of the *Nirenberg's problem*. Precisely, since the *Q*-curvature is already constant, a natural problem is to deform the metric conformally in such a way that the curvature becomes a given function f on S^4 . Equation (8) on the sphere admits a non-compact family of solutions (classified in [17]), which all arise from conformal factors of Möbius transformations. In order to tackle this loss of compactness, usually finite-dimensional reductions of the problem are used, jointly with blow-up analysis and Morse theory. Some results in this direction are given in [11], [33] and [40] (see also references therein for results on the Nirenberg's problem on S^2).

The structure of the paper is the following. In Section 2 we collect some notation and preliminary results, based on an improved Moser-Trudinger type inequality. We also introduce the set $A_{k,\overline{k}}$ used to perform the minimax construction. In Section 3 then we show how to map the sublevels $\{II \leq -L\}$ into $A_{k,\overline{k}}$. We begin by analyzing some properties of M_k as a stratified set (union of open manifolds of different dimensions), in order to understand the M_k -component of the projection, which is the most involved. Then we turn to the construction of the global map. In Section 4 we show how to embed $A_{k,\overline{k}}$ into any sublevel $\{II \leq -L\}$ for L large. This requires some long and delicate estimates, some of which are carried out in the Appendix. Finally in Section 5 we prove Theorem 1.1, defining a minimax scheme based on the construction of $A_{k,\overline{k}}$, solving the modified problem (15), and applying Theorem 1.3.

An announcement of the present results is given in the preliminary note [23].

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2 Notation and preliminaries

In this section we fix our notation and we recall some useful known facts. We state in particular an inequality of Moser-Trudinger type for functions in $H^2(M)$, an improved version of it and some of its consequences.

The symbol $B_r(p)$ denotes the metric ball of radius r and center p, while dist(x, y) stands for the distance between two points $x, y \in M$. $H^2(M)$ is the Sobolev space of the functions on M which are in $L^2(M)$ together with their first and second derivatives. The symbol $\|\cdot\|$ will denote the norm of $H^2(M)$. If $u \in H^2(M)$, $\overline{u} = \frac{1}{|M|} \int_M u dV_g$ stands for the average of u. For l points $x_1, \ldots, x_l \in M$ which all lie in a small metric ball, and for l non-negative numbers $\alpha_1, \ldots, \alpha_l$, we will consider *convex combinations* of the form $\sum_{i=1}^l \alpha_i x_i, \alpha_i \geq 0$, $\sum_i \alpha_i = 1$. To do this, we can consider the embedding of M into some \mathbb{R}^n given by Whitney's theorem, take the convex combination of the images of the points $(x_i)_i$, and project it onto the image of M. If $dist(x_i, x_j) < \xi$ for ξ sufficiently small, then this operation is well-defined and moreover we have $dist\left(x_j, \sum_{i=1}^l \alpha_i x_i\right) < 2\xi$ for every $j = 1, \ldots, l$. Note that these elements are just points, not to be confused with the formal barycenters $\sum t_i \delta_{x_i}$.

Large positive constants are always denoted by C, and the value of C is allowed to vary from formula to formula and also within the same line. When we want to stress the dependence of the constants on some parameter (or parameters), we add subscripts to C, as C_{δ} . Also constants with subscripts are allowed to vary.

Since we allow P_g to have negative eigenvalues, we denote by $V \subseteq H^2(M)$ the direct sum of the eigenspaces corresponding to negative eigenvalues of P_g . The dimension of V, which is finite, is denoted by \overline{k} , and since P has no kernel we can find a basis of eigenfunctions $\hat{v}_1, \ldots, \hat{v}_{\overline{k}}$ of V (orthonormal in $L^2(M)$) with the properties

(18)
$$P_g \hat{v}_i = \lambda_i \hat{v}_i, \quad i = 1, \dots, \overline{k}; \qquad \lambda_1 \le \lambda_2 \le \dots \le \lambda_{\overline{k}} < 0 < \lambda_{\overline{k}+1} \le \dots,$$

where the λ_i 's are the eigenvalues of P_g counted with multiplicity. From (18), since P_g has a divergence structure, it follows immediately that $\int_M \hat{v}_i dV_g = 0$ for $i = 1, \ldots, \overline{k}$. We also introduce the following positive-definite pseudo-differential operator P_g^+

(19)
$$P_g^+ u = P_g u - 2\sum_{i=1}^{\overline{k}} \lambda_i \left(\int_M u \hat{v}_i dV_g \right) \hat{v}_i.$$

Basically, we are reversing the sign of the negative eigenvalues of P_q .

Now we define the set $A_{k,\overline{k}}$ to be used in the existence argument. We let M_k denote the family of formal sums

(20)
$$M_k = \sum_{i=1}^k t_i \delta_{x_i}; \qquad t_i \ge 0, \sum_{i=1}^k t_i = 1; \quad x_i \in M,$$

endowed with the weak topology of distributions. This is known in literature as the *formal set of* barycenters of M (of order k), see [3], [4], [9]. We stress that this set is NOT the family of convex combinations of points in M which is introduced at the beginning of the section. To carry out some explicit computations, we will use on M_k the metric given by $C^1(M)^*$, which induces the same topology, and which will be denoted by $dist(\cdot, \cdot)$.

Then, recalling that \overline{k} is the number of negative eigenvalues of P_g , we consider the unit ball $B_1^{\overline{k}}$ in $\mathbb{R}^{\overline{k}}$, and we define the set

where the notation $\tilde{}$ means that $M_k \times \partial B_1^{\overline{k}}$ is identified with $\partial B_1^{\overline{k}}$, namely $M_k \times \{y\}$, for every $y \in \partial B_1^{\overline{k}}$, is collapsed to a single point. When $k_P < 8\pi^2$ and $\overline{k} \ge 1$, we will perform the minimax argument just by using the sphere $S^{\overline{k}-1}$.

2.1 Some improved Adams inequalities

In this subsection we give some improvements of the Adams inequality and in particular we consider the possibility of dealing with negative eigenvalues. The following Lemma is proved in [32] using a modification of the arguments in [16], which in turn extend to the Paneitz operator some previous embeddings due to Adams, see [1], involving the operator Δ^m in flat domains.

Lemma 2.1 Suppose $kerP_g = \{constants\}$, let V be the direct sum of the eigenspaces corresponding to negative eigenvalues of P_g , and let P_g^+ be defined in (19). Then there exists a constant C such that

(22)
$$\int_{M} e^{\frac{32\pi^{2}(u-\overline{u})^{2}}{\langle P_{g}^{+}u,u\rangle}} dV_{g} \leq C$$

As a consequence one has

(23)
$$\log \int_{M} e^{4(u-\overline{u})} dV_g \le C + \frac{1}{8\pi^2} \langle P_g^+ u, u \rangle.$$

From this result we derive an improved inequality for functions which are concentrated at more than one single point, related to a result in [21]. A consequence of this inequality is that it allows to give an upper bound (depending on $\int_M Q_g dV_g$) for the number of concentration points of e^{4u} , where u is any function in $H^2(M)$ on which II attains large negative values, see Lemma 2.4.

Lemma 2.2 Let $S_1, \ldots, S_{\ell+1}$ be subsets of M satisfying $dist(S_i, S_j) \ge \delta_0$ for $i \ne j$, and let $\gamma_0 \in \left(0, \frac{1}{\ell+1}\right)$. Then, for any $\tilde{\varepsilon} > 0$ and any S > 0 there exists a constant $C = C(\tilde{\varepsilon}, S, \delta_0, \gamma_0)$ such that

$$\log \int_{M} e^{4(u-\overline{u})} dV_g \le C + \frac{1}{8(\ell+1)\pi^2 - \tilde{\varepsilon}} \langle P_g u, u \rangle$$

for all the functions $u \in H^2(M)$ satisfying

(24)
$$\frac{\int_{S_i} e^{4u} dV_g}{\int_M e^{4u} dV_g} \ge \gamma_0, \quad i \in \{1, \dots, \ell+1\}; \qquad \sum_{i=1}^{\overline{k}} \alpha_i^2 \le S.$$

Here $\hat{u} = \sum_{i=1}^{\overline{k}} \alpha_i \hat{v}_i$ denotes the component of u in V.

PROOF. We modify the argument in [21] avoiding the use of truncations, which is not allowed in the H^2 setting. Assuming without loss of generality that $\overline{u} = 0$, we can find $\ell + 1$ functions $g_1, \ldots, g_{\ell+1}$ satisfying the following properties

(25)
$$\begin{cases} g_i(x) \in [0,1] & \text{for every } x \in M; \\ g_i(x) = 1, & \text{for every } x \in S_i, i = 1, \dots, \ell+1; \\ g_i(x)g_j(x) = 0, & \text{for every } x \in M, i \neq j; \\ \|g_i\|_{C^4(M)} \le C_{\delta_0}, \end{cases}$$

where C_{δ_0} is a positive constant depending only on δ_0 . By interpolation, for any $\varepsilon > 0$ there exists C_{ε,δ_0} (depending only on ε and δ_0) such that, for any $v \in H^2(M)$ and for any $i \in \{1, \ldots, \ell+1\}$ there holds

(26)
$$\langle P_g^+ g_i v, g_i v \rangle \le \int_M g_i^2 (P_g^+ v, v) dV_g + \varepsilon \langle P_g^+ v, v \rangle + C_{\varepsilon, \delta_0} \int_M v^2 dV_g$$

If we can write $u = u_1 + u_2$ with $u_1 \in L^{\infty}(M)$, then from our assumptions we deduce

(27)
$$\int_{S_i} e^{4u_2} dV_g \ge e^{-4\|u_1\|_{L^{\infty}(M)}} \int_{S_i} e^{4u} dV_g \ge e^{-4\|u_1\|_{L^{\infty}(M)}} \gamma_0 \int_M e^{4u} dV_g; \qquad i = 1, \dots, \ell + 1.$$

Using (25), (27) and then (23) we obtain

$$\log \int_{M} e^{4u} dV_{g} \leq \log \frac{1}{\gamma_{0}} + 4 \|u_{1}\|_{L^{\infty}(M)} + \log \int_{M} e^{4g_{i}u_{2}} dV_{g}$$

$$\leq \log \frac{1}{\gamma_{0}} + 4 \|u_{1}\|_{L^{\infty}(M)} + C + \frac{1}{8\pi^{2}} \langle P_{g}^{+}g_{i}u_{2}, g_{i}u_{2} \rangle + 4\overline{g_{i}u_{2}}$$

We now choose *i* such that $\langle P_g^+ g_i u_2, g_i u_2 \rangle \leq \langle P_g^+ g_j u_2, g_j u_2 \rangle$ for every $j \in \{1, \ldots, \ell + 1\}$. Since the $g'_i s$ have disjoint supports, the last formula and (26) imply

$$\log \int_{M} e^{4u} dV_{g} \le \log \frac{1}{\gamma_{0}} + 4 \|u_{1}\|_{L^{\infty}(M)} + C + \left(\frac{1}{8(\ell+1)\pi^{2}} + \varepsilon\right) \langle P_{g}^{+}u_{2}, u_{2} \rangle + C_{\varepsilon,\delta_{0}} \int_{M} u_{2}^{2} dV_{g} + 4\overline{g_{i}u_{2}}.$$

Next we choose $\tilde{C}_{\varepsilon,\delta_0}$ to be an eigenvalue of P_g^+ such that $\frac{C_{\varepsilon,\delta_0}}{\tilde{C}_{\varepsilon,\delta_0}} < \varepsilon$, where C_{ε,δ_0} is given in the last formula, and we set

$$u_1 = P_{V_{\varepsilon,\delta_0}} u; \qquad \qquad u_2 = P_{V_{\varepsilon,\delta_0}^{\perp}} u,$$

where V_{ε,δ_0} is the direct sum of the eigenspaces of P_g^+ with eigenvalues less or equal to $\tilde{C}_{\varepsilon,\delta_0}$, and $P_{V_{\varepsilon,\delta_0}}$, $P_{V_{\varepsilon,\delta_0}^{\perp}}$ denote the projections onto V_{ε,δ_0} and $V_{\varepsilon,\delta_0}^{\perp}$ respectively. Since $\overline{u} = 0$, the L^2 -norm and the L^{∞} -norm on V_{ε,δ_0} are equivalent (with a proportionality factor which depends on ε and δ_0), and hence by our choice of u_1 and u_2 there holds

$$\|u_1\|_{L^{\infty}(M)}^2 \leq \hat{C}_{\varepsilon,\delta_0} \langle P_g^+ u_1, u_1 \rangle; \qquad C_{\varepsilon,\delta_0} \int_M u_2^2 dV_g \leq \frac{C_{\varepsilon,\delta_0}}{\tilde{C}_{\varepsilon,\delta_0}} \langle P_g^+ u_2, u_2 \rangle < \varepsilon \langle P_g^+ u_2, u_2 \rangle,$$

where $\hat{C}_{\varepsilon,\delta_0}$ depends on ε and δ_0 . Furthermore, by the positivity of P_g^+ and the Poincaré inequality (recall that $\overline{u} = 0$), we have

$$\overline{g_i u_2} \le C \|u_2\|_{L^2(M)} \le C \|u\|_{L^2(M)} \le C \langle P_g^+ u, u \rangle^{\frac{1}{2}}.$$

Hence the last formulas imply

$$\begin{split} \log \int_{M} e^{4u} dV_{g} &\leq \log \frac{1}{\gamma_{0}} + 4\hat{C}_{\varepsilon,\delta_{0}} \langle P_{g}^{+}u, u \rangle^{\frac{1}{2}} + C + \left(\frac{1}{8(\ell+1)\pi^{2}} + \varepsilon\right) \langle P_{g}^{+}u_{2}, u_{2} \rangle + \varepsilon \langle P_{g}^{+}u_{2}, u_{2} \rangle \\ &+ C \langle P_{g}^{+}u_{2}, u_{2} \rangle^{\frac{1}{2}} \leq \left(\frac{1}{8(\ell+1)\pi^{2}} + 3\varepsilon\right) \langle P_{g}^{+}u, u \rangle + \overline{C}_{\varepsilon,\delta_{0}} + C + \log \frac{1}{\gamma_{0}}, \end{split}$$

where $\overline{C}_{\varepsilon,\delta_0}$ depends only on ε and δ_0 . Now, since we have the bound on \hat{u} , we can replace $\langle P_g^+ u, u \rangle$ with $\langle P_g u, u \rangle$ plus a constant in the right-hand side. This concludes the proof.

In the next lemma we show a criterion which implies the situation described in the first condition in (24).

Lemma 2.3 Let $f \in L^1(M)$ be a non-negative function with $||f||_{L^1(M)} = 1$. Suppose that the following property holds true. There exist $\varepsilon > 0$ and r > 0 such that

$$\int_{\bigcup_{i=1}^{\ell} B_r(p_i)} f dV_g < 1 - \varepsilon \qquad \text{for all } p_1, \dots, p_{\ell} \in M.$$

Then there exist $\overline{\varepsilon} > 0$ and $\overline{r} > 0$, depending only on ε, r and M (and not on f), and $\ell + 1$ points $\overline{p}_1, \ldots, \overline{p}_{\ell+1} \in M$ (which depend on f) satisfying

$$\int_{B_{\overline{\tau}}(\overline{p}_1)} f dV_g > \overline{\varepsilon}, \ \dots, \ \int_{B_{\overline{\tau}}(\overline{p}_{\ell+1})} f dV_g > \overline{\varepsilon}; \qquad \qquad B_{2\overline{\tau}}(\overline{p}_i) \cap B_{2\overline{\tau}}(\overline{p}_j) = \emptyset \text{ for } i \neq j.$$

PROOF. Suppose by contradiction that for every $\overline{\varepsilon}, \overline{r} > 0$ and for any $\ell + 1$ points $p_1, \ldots, p_{\ell+1} \in M$ there holds

(28)
$$\int_{B_{\overline{r}}(p_1)} f dV_g \ge \overline{\varepsilon}, \dots, \int_{B_{\overline{r}}(p_{\ell+1})} f dV_g \ge \overline{\varepsilon} \qquad \Rightarrow \qquad B_{2\overline{r}}(p_i) \cap B_{2\overline{r}}(p_j) \neq \emptyset \text{ for some } i \ne j$$

We let $\overline{r} = \frac{r}{8}$, where r is given in the statement. We can find $l \in \mathbb{N}$ and l points $x_1, \ldots, x_l \in M$ such that M is covered by $\bigcup_{i=1}^{l} B_{\overline{r}}(x_i)$. If ε is as above, we also set $\overline{\varepsilon} = \frac{\varepsilon}{2l}$. We point out that the choice of \overline{r} and $\overline{\varepsilon}$ depends on r, ε and M only, as required.

Let $\{\tilde{x}_1, \ldots, \tilde{x}_j\} \subseteq \{x_1, \ldots, x_l\}$ be the points for which $\int_{B_{\overline{\tau}}(\tilde{x}_i)} f dV_g \geq \overline{\varepsilon}$. Fixing $\tilde{x}_{j_1} = \tilde{x}_1$, let A_1 denote the set

$$A_1 = \{ \cup_i B_{\overline{r}}(\tilde{x}_i) : B_{2\overline{r}}(\tilde{x}_i) \cap B_{2\overline{r}}(\tilde{x}_{j_1}) \neq \emptyset \} \subseteq B_{4\overline{r}}(\tilde{x}_{j_1}).$$

If there exists \tilde{x}_{j_2} such that $B_{2\overline{r}}(\tilde{x}_{j_2}) \cap B_{2\overline{r}}(\tilde{x}_{j_1}) \neq \emptyset$, we define

$$A_2 = \{ \cup_i B_{\overline{r}}(\tilde{x}_i) : B_{2\overline{r}}(\tilde{x}_i) \cap B_{2\overline{r}}(\tilde{x}_{j_2}) \neq \emptyset \} \subseteq B_{4\overline{r}}(\tilde{x}_{j_2}).$$

Proceeding in this way, we define recursively some points $\tilde{x}_{j_3}, \tilde{x}_{j_4}, \ldots, \tilde{x}_{j_h}$ satisfying

$$B_{2\overline{r}}(\tilde{x}_{j_h}) \cap B_{2\overline{r}}(\tilde{x}_{j_a}) = \emptyset \ \forall 1 \le a \le h; \qquad A_h = \{ \cup_i B_{\overline{r}}(\tilde{x}_i) : B_{2\overline{r}}(\tilde{x}_i) \cap B_{2\overline{r}}(\tilde{x}_{j_h}) \neq \emptyset \} \subseteq B_{4\overline{r}}(\tilde{x}_{j_h}).$$

By (28), the process cannot go further than \tilde{x}_{j_ℓ} , and hence using the definition of \bar{r} we obtain

(29)
$$\cup_{i=1}^{l} B_{\overline{r}(\tilde{x}_{i})} \subseteq \cup_{i=1}^{\ell} B_{4\overline{r}}(\tilde{x}_{j_{i}}) \subseteq \cup_{i=1}^{\ell} B_{\frac{r}{2}}(\tilde{x}_{j_{i}}).$$

Then by our choice of $l, \overline{\varepsilon}, \{\tilde{x}_1, \ldots, \tilde{x}_l\}$ and by (29) there holds

$$\int_{M \setminus \cup_{i=1}^{\ell} B_r(\tilde{x}_{j_i})} f dV_g \leq \int_{M \setminus \cup_{i=1}^{l} B_{\overline{r}(\tilde{x}_i)}} f dV_g \leq (l-\ell)\overline{\varepsilon} \leq \frac{\varepsilon}{2}.$$

Finally, if we chose $\overline{p}_i = \tilde{x}_{j_i}$, $i = 1, \ldots, \ell$, we get a contradiction to the assumptions.

Next we characterize some functions in $H^2(M)$ for which the value of II is large negative. Recall that the number k is given in formula (11).

Lemma 2.4 Under the assumptions of Theorem 1.1, and for $k \ge 1$, the following property holds. For any S > 0, $\varepsilon > 0$ and any r > 0 there exists a large positive $L = L(S, \varepsilon, r)$ such that for every $u \in H^2(M)$ with $II(u) \le -L$ and $\|\hat{u}\| \le S$ there exists k points $p_{1,u}, \ldots, p_{k,u} \in M$ such that

(30)
$$\int_{M \setminus \cup_{i=1}^k B_r(p_{i,u})} e^{4u} dV_g < \varepsilon.$$

PROOF. Suppose by contradiction that the statement is not true. Then we can apply Lemma 2.3 with $\ell = k, f = e^{4u_l}$, and in turn Lemma 2.2 with $\delta_0 = 2\overline{r}, S_1 = B_{\overline{r}}(\overline{p}_1), \ldots, S_{k+1} = B_{\overline{r}}(p_{k+1})$. This implies

$$II(u) \ge \langle P_g u, u \rangle + 4 \int_M Q_g u dV_g - Ck_P - \frac{k_P}{8(k+1)\pi^2 - \tilde{\varepsilon}} \langle P_g u, u \rangle - 4k_P \overline{u}.$$

Since $k_P < 8(k+2)\pi^2$, we can choose $\tilde{\varepsilon} > 0$ so small that $1 - \frac{k_P}{8(k+1)\pi^2 - \tilde{\varepsilon}} > \delta > 0$. Hence using also the Poincaré inequality we deduce

(31)

$$II(u) \geq \delta \langle P_g u, u \rangle + 4 \int_M Q_g(u - \overline{u}) dV_g - Ck_P$$

$$\geq \delta \langle P_g u, u \rangle - 4C \langle P_g u, u \rangle^{\frac{1}{2}} - Ck_P \geq -C.$$

This concludes the proof. \blacksquare

3 Mapping sublevels of *II* into $A_{k\bar{k}}$

In this section we show how to map non trivially some sublevels of the functional II into the set $A_{k,\overline{k}}$. Since adding a constant to the argument of II does not affect its value, we can always assume that the functions $u \in H^2(M)$ we are dealing with satisfy the normalization (14) (with u instead of u_l). Our goal is to prove the following result.

Proposition 3.1 For $k \ge 1$ (see (11)) there exists a large L > 0 and a continuous map Ψ from the sublevel $\{II < -L\}$ into $A_{k,\overline{k}}$ which is topologically non-trivial. For $k_P < 8\pi^2$ and $\overline{k} \ge 1$ the same is true with $A_{k,\overline{k}}$ replaced by $S^{\overline{k}-1}$

We divide the section into two parts. First we derive some properties about the set M_k for $k \ge 1$. Then we turn to the construction of the map Ψ . Its non-triviality will follow from Proposition 4.1 below, where we show that there is another map Φ from $A_{k,\overline{k}}$ into $H^2(M)$ such that $\Psi \circ \Phi$ is homotopic to the identity on $A_{k,\overline{k}}$, which is not contractible by Corollary 3.8.

3.1 Some properties of the set M_k

In this subsection we collect some useful properties of the set M_k , beginning with some local ones near the singularities. Although its topological structure is well-known, we need some quantitative (metric) estimates near the singularities, namely the subsets $M_j \subseteq M_k$ with j < k. The reason, as mentioned in the introduction, is that the amount of concentration of e^{4u} (where $u \in \{II \leq -l\}$, see Lemma 2.4) near a single point can be arbitrarily small. In this way we are forced to define a projection which depends on *all* the distances from the M_j 's, see Subsection 3.2, which requires some preliminary estimates.

For $\varepsilon > 0$ and $2 \le j \le k$, we define

$$M_{i}(\varepsilon) = \{ \sigma \in M_{i} : d_{i-1}(\sigma) > \varepsilon \}.$$

For convenience, we extend the definition also to the case j = 1, setting

$$M_1(\varepsilon) := M_1.$$

We give a first quantitative description of the set $M_j(\varepsilon)$, which leads immediately to (the known) Corollary 3.3.

Lemma 3.2 Let $j \in \{2, ..., k\}$. Then there exists ε sufficiently small with the following property. If $\sigma \in M_j(\varepsilon), \sigma = \sum_{i=1}^j t_i \delta_{x_i}$, then there holds

(32)
$$t_i \ge \frac{\varepsilon}{2}; \quad dist(x_i, x_l) \ge \frac{\varepsilon}{2}; \quad i, l = 1, \dots, j, i \ne l.$$

PROOF. Assuming by contradiction that the first inequality in (32) is not satisfied, there exists $i \in \{1, \ldots, j\}$ such that $t_{\overline{i}} \leq \frac{\varepsilon}{2}$. Then, for $\tilde{i} \in \{1, \ldots, j\}$, $\tilde{i} \neq \bar{i}$, we consider the following element

$$\hat{\sigma} = (t_{\overline{i}} + t_{\widetilde{i}})\delta_{x_{\overline{i}}} + \sum_{i \neq \overline{i}, \overline{i}} t_i \delta_{x_i} \in M_{j-1}.$$

For any function f on M with $||f||_{C^1(M)} \leq 1$ there holds clearly

$$|(\sigma, f) - (\hat{\sigma}, f)| \le t_{\overline{i}} \left(|f(x_{\overline{i}})| + |f(x_{\overline{i}})| \right) \le 2t_{\overline{i}}.$$

Taking the supremum with respect to such functions f we deduce

$$\varepsilon < dist(\sigma, M_{j-1}) \le dist(\sigma, \hat{\sigma}) = \sup_{f} |(\sigma, f) - (\hat{\sigma}, f)| \le 2t_{\overline{i}}.$$

This gives us a contradiction. Let us prove now the second inequality. Assuming that there are $x_i, x_l \in M$ with, $x_i \neq x_l$ and $dist(x_i, x_l) < \varepsilon$, let us define the element

$$\hat{\sigma} = (t_i + t_l)\delta_{\frac{1}{2}x_i + \frac{1}{2}x_l} + \sum_{s \neq i,l} t_s \delta_{x_s} \in M_{j-1},$$

see the notation introduced in Section 2. Similarly as before, for $||f||_{C^1(M)} \leq 1$ we obtain

$$\begin{aligned} |(\sigma, f) - (\hat{\sigma}, f)| &\leq t_i \left| f(x_i) - f\left(\frac{x_i + x_l}{2}\right) \right| + t_l \left| f(x_l) - f\left(\frac{x_i + x_l}{2}\right) \right| \\ &\leq \left| f(x_i) - f\left(\frac{x_i + x_l}{2}\right) \right| + \left| f(x_l) - f\left(\frac{x_i + x_l}{2}\right) \right|. \end{aligned}$$

Taking the supremum with respect to such functions f, since they all have Lipshitz constant less or equal than 1, we deduce

$$\varepsilon < dist(\sigma, M_j) \le dist(\sigma, \hat{\sigma}) = \sup_{f} |(\sigma, f) - (\hat{\sigma}, f)| \le 2dist(x_i, x_l).$$

This gives us a contradiction and concludes the proof. \blacksquare

Corollary 3.3 (well-known) The set M_1 is a smooth manifold. Furthermore, for any $\varepsilon > 0$ and for $j \ge 2$, the set $M_j(\varepsilon)$ is also a smooth (open) manifold of dimension 5j - 1.

PROOF. The first assertion is obvious. Regarding the second one, the previous lemma guarantees that all the numbers t_i are uniformly bounded away from zero and that the mutual distance between the points x_i 's is also uniformly bounded from below. Therefore, recalling that the t_i 's satisfy the constraint $\sum_i t_i = 1$, each element of $M_j(\varepsilon)$ can be smoothly parameterized by 4j coordinates locating the points x_i 's and by j - 1 coordinates identifying the numbers t_i 's.

We show next that it is possible to define a continuous homotopy which brings points in M_k , close to $M_i(\varepsilon)$, onto $M_i(\frac{\varepsilon}{2})$. We also provide some quantitative estimates on the deformation.

Lemma 3.4 Let $j \in \{1, ..., k-1\}$, and let $\varepsilon > 0$. Then there exist $\hat{\varepsilon} \ (\ll \varepsilon^2)$, depending only on ε and k, and a map T_i^t , $t \in [0, 1]$, from the set

$$\hat{M}_{k}^{\hat{\varepsilon},\varepsilon} := \{ \sigma \in M_{k} : dist(\sigma, M_{j}(\varepsilon)) < \hat{\varepsilon} \}$$

into M_k such that the following five properties hold true

(i) $T_i^0 = Id;$

(ii) $T_i^1(\sigma) \in M_j\left(\frac{\varepsilon}{2}\right)$ for every $\sigma \in \hat{M}_k^{\hat{\varepsilon},\varepsilon}$;

(iii) $dist(T_j^0(\sigma), T_j^t(\sigma)) \le C_k \sqrt{\hat{\varepsilon}} \text{ for every } \sigma \in \hat{M}_k^{\hat{\varepsilon}, \varepsilon};$

- (iv) if $\sigma \in \hat{M}_k^{\hat{\varepsilon},\varepsilon} \cap M_l$ for some $l \in \{j+1,\ldots,k-1\}$, then $T_j^t(\sigma) \in M_l$;
- (v) if $\sigma \in \hat{M}_{k}^{\hat{\varepsilon},\varepsilon} \cap M_{j}$, then $T_{i}^{t}(\sigma) = \sigma$ for every $t \in [0,1]$.

The constant C_k in (iii) depends only on k.

PROOF. By Corollary 3.3, we know that $M_j\left(\frac{\varepsilon}{4}\right)$ is a smooth manifold. Therefore, if $\hat{\varepsilon}$ is sufficiently small, there exists a well-defined and continuous projection P_j from M_k onto M_j , which maps σ to its closest point in M_j . To fix some notation, we use the following convention

$$\sigma = \sum_{i=1}^{k} t_i \delta_{x_i}; \qquad \qquad P_j(\sigma) = \sum_{i=1}^{j} s_i \delta_{y_i}.$$

By Lemma 3.2, since we are assuming that $P_i(\sigma)$ belongs to $M_i(\varepsilon)$, we have the following estimates

$$s_i \ge \frac{\varepsilon}{2},$$
 $dist(y_i, y_l) \ge \frac{\varepsilon}{2};$ $i, l = 1, \dots, s, i \ne l.$

Moreover the points y_i and the numbers s_i depend continuously on σ .

We define first an auxiliary map \tilde{T}_j^t , $\tilde{T}_j^t(\sigma) = \sum \tilde{t}_i \delta_{\tilde{x}_i}$, which misses the normalization condition $\sum_{i=1}^k \tilde{t}_i = 1$, but only up to a small error. This map will then be corrected to the real T_j^t . The idea to construct \tilde{T}_j^t is the following. If a point x_i is far from each y_l , we keep this point fixed and let its coefficient vanish to zero as t varies from 0 to 1. On the other hand, if x_i is close to some of the y_l 's, then we translate it to a weighted convex combination of the points x_i which are close to the same y_l .

To make this construction rigorous (and the map \tilde{T}_j^t continuous), we consider a small number $\eta \ll \varepsilon$ (this will be chosen later of order $\sqrt{\hat{\varepsilon}}$), and define a cutoff function ρ_η satisfying the following properties

(33)
$$\begin{cases} \rho_{\eta}(t) = 1, & \text{for } t \leq \frac{\eta}{16}; \\ \rho_{\eta}(t) = 0, & \text{for } t \geq \frac{\eta}{8}; \\ \rho_{\eta}(t) \in [0, 1], & \text{for every } t \geq 0. \end{cases}$$

Then we set

(34)
$$\rho_{i,\eta}(x) = \rho_{\eta}(dist(x, y_i)); \qquad \text{for } i = 1, \dots, j$$

We define also the following quantities

$$\mathcal{T}_{l}(\sigma) = \sum_{x_{i} \in B_{\frac{\eta}{8}(y_{l})}} \rho_{i,\eta}(x_{i})t_{i}; \qquad \mathcal{X}_{l}(\sigma) = \frac{1}{\mathcal{T}_{l}(\sigma)} \sum_{x_{i} \in B_{\frac{\eta}{8}(y_{l})}} \rho_{i,\eta}(x_{i})t_{i}x_{i}, \qquad l = 1, \dots, j.$$

We notice that, if η is chosen sufficiently small, the weighted convex combination $\mathcal{X}_l(\sigma)$ is well-defined, see the notation in Section 2. We also set

$$z_i(\sigma) = \frac{8}{\eta} dist(x_i, y_l) - 1, \qquad \text{for } x_i \in B_{\frac{\eta}{4}}(x_i).$$

Now we define the map $\tilde{T}_i^t(\sigma)$ as follows

$$\tilde{T}_j^t(\sigma) = \sum_{i=1}^k \tilde{t}_i(\sigma, t) \delta_{\tilde{x}_i(\sigma, t)}$$

where the numbers $\tilde{t}_i(\sigma, t)$ and the points $\tilde{x}_i(\sigma, t)$ are given by

$$\begin{split} \tilde{t}_i(\sigma,t) &= (1-t)t_i; \qquad \tilde{x}_i(\sigma,t) = x_i \quad \text{if} \quad x_i \in M \setminus \bigcup_l B_{\frac{\eta}{4}}(y_l);\\ \tilde{t}_i(\sigma,t) &= (1-t)t_i; \qquad \tilde{x}_i(\sigma,t) = (1-t)x_i + t[z_i(\sigma)x_i + (1-z_i(\sigma))\mathcal{X}_l(\sigma)] \quad \text{if} \quad x_i \in B_{\frac{\eta}{4}}(y_l) \setminus B_{\frac{\eta}{8}}(y_l);\\ \tilde{t}_i(\sigma,t) &= ((1-t) + t\rho_{i,\eta}(x_i))t_i; \qquad \tilde{x}_i(\sigma,t) = (1-t)x_i + t\mathcal{X}_l(\sigma) \quad \text{if} \quad x_i \in B_{\frac{\eta}{8}}(y_l). \end{split}$$

As already mentioned, the numbers $\tilde{t}_i(\sigma, t)$ will in general miss the normalization condition $\sum_i \tilde{t}_i(\sigma, t) = 1$. The next step consists in estimating this sum and correct the map $\tilde{T}_j^t(\sigma)$ in order to match this condition. For this purpose it is convenient to define

$$\tilde{\mathcal{T}}_{l}(\sigma,t) = \sum_{x_{i} \in B_{\frac{\eta}{8}}(y_{l})} \tilde{t}_{i}(\sigma,t); \qquad \qquad \tilde{\mathcal{T}}(\sigma,t) = 1 - \sum_{i} \tilde{\mathcal{T}}_{l}(\sigma,t).$$

Now we finally set

(35)
$$T_j^t(\sigma) = \frac{1}{(1-t)\tilde{T}(0) + \sum_l \tilde{T}_l(\sigma,t)} \sum_{i=1}^k \tilde{t}_i(\sigma,t) \delta_{\tilde{x}_i(\sigma,t)}.$$

We notice that the sum of all the coefficients is 1, and that the map is well defined and continuous in both t and σ . We also notice that the properties (i), (iv) and (v) are satisfied, while (ii) follows from (iii). Therefore it only remains to prove (iii). First of all we give an estimate on the terms $\tilde{T}_l(\sigma, t)$ and $\tilde{T}(\sigma, t)$.

We recall that we have taken $\sigma \in \hat{M}_k^{\hat{\varepsilon},\eta}$, and this means that for any function $f \in C^1(M)$ one has $|(\sigma - P_j(\sigma), f)| \leq \hat{\varepsilon}$. We now choose a function f satisfying the following properties

$$f(x) = \begin{cases} \frac{1}{2}, & \text{for } x \in \bigcup_l B_{\frac{\eta}{48}(y_l)};\\ \frac{1}{2} + \frac{\eta}{32}, & \text{for } x \in M \setminus \bigcup_l B_{\frac{\eta}{16}(y_l)};\\ \|f\|_{C^1(M)} \le 1. \end{cases}$$

For this function we have $(P_j(\sigma), f) = \sum_{i=1}^j s_i f(y_i) = \frac{1}{2}$ and moreover

$$(\sigma, f) = \sum_{x_i \in \bigcup_l B_{\frac{\eta}{16}}(y_l)} t_i f(x_i) + \sum_{x_i \in M \setminus \bigcup_l B_{\frac{\eta}{16}}(y_l)} t_i f(x_i)$$

$$\geq \frac{1}{2} \sum_{x_i \in \bigcup_l B_{\frac{\eta}{16}}(y_l)} t_i + \left(\frac{1}{2} + \frac{\eta}{32}\right) \sum_{x_i \in M \setminus \bigcup_l B_{\frac{\eta}{16}}(y_l)} t_i.$$

Therefore we deduce the following inequality

$$\frac{\eta}{32} \sum_{x_i \in M \setminus \cup_l B_{\frac{\eta}{16}}(y_l)} t_i \le (\sigma, f) - (P_j(\sigma), f) \le \hat{\varepsilon}.$$

This estimate implies

$$\tilde{\mathcal{T}}(\sigma,0) = \sum_{x_i \in M \setminus \cup_l B_{\frac{\eta}{16}}(y_l)} t_i \le 32 \frac{\hat{\varepsilon}}{\eta},$$

and that, (since $\rho_{l,\eta}\equiv 1$ in $B_{\frac{\eta}{16}}(y_l))$

$$\begin{split} \tilde{\mathcal{T}}_{l}(\sigma,t) &= \sum_{x_{i} \in B_{\frac{\eta}{8}}(y_{l}) \setminus B_{\frac{\eta}{16}}(y_{l})} \left((1-t) + t\rho_{l,\eta}(x_{i}) \right) t_{i} + \sum_{x_{i} \in B_{\frac{\eta}{16}}(y_{l})} \left((1-t) + t\rho_{l,\eta}(x_{i}) \right) t_{i} \\ &= \tilde{\mathcal{A}}_{l}(\sigma,t) + \sum_{x_{i} \in B_{\frac{\eta}{16}}(y_{l})} t_{i}, \qquad \text{where} \quad \sum_{l=1}^{j} |\tilde{\mathcal{A}}_{l}(\sigma,t)| \leq 32\frac{\hat{\varepsilon}}{\eta}. \end{split}$$

Therefore, since $\sum_{l} \tilde{\mathcal{T}}_{l}(\sigma, 0) + \tilde{\mathcal{T}}(\sigma, 0) = 1$, there holds

$$1 = \sum_{x_i \in \bigcup_l B_{\frac{\eta}{16}}(y_l)} t_i + \sum_l \tilde{\mathcal{A}}_l(\sigma, 0) + \sum_{x_i \in M \setminus \bigcup_l B_{\frac{\eta}{8}}(y_l)} t_i,$$

from which we deduce

$$\begin{aligned} \left| \sum_{l} \tilde{\mathcal{T}}_{l}(\sigma, t) + (1-t)\tilde{\mathcal{T}}(0) - 1 \right| &= \left| \left(\sum_{l} \tilde{\mathcal{A}}_{l}(\sigma, t) - \tilde{\mathcal{A}}_{l}(\sigma, 0) \right) + (1-t) \sum_{x_{i} \in M \setminus \cup_{l} B_{\frac{\eta}{g}}(y_{l})} t_{i} \right| \\ &\leq 64 \frac{\hat{\varepsilon}}{\eta} + 32 \frac{\hat{\varepsilon}}{\eta} = 96 \frac{\hat{\varepsilon}}{\eta}. \end{aligned}$$

Therefore, using a Taylor expansion, we find that the coefficient added in the definition of T_j^t can be estimated by

$$\left|\frac{1}{\sum_{l} \tilde{\mathcal{T}}_{l}(\sigma, t) + (1-t)\tilde{\mathcal{T}}(0)} - 1\right| \le 100\frac{\hat{\varepsilon}}{\eta}$$

To control the metric distance in (iii), we use the last formula to get, for an arbitrary function $f \in C^1(M)$ with $||f||_{C^1(M)} \leq 1$

$$\begin{aligned} \left| (\sigma, f) - (T_j^t(\sigma), f) \right| &\leq \left| (\sigma, f) - (\tilde{T}_j^t(\sigma), f) \right| + \left| (\tilde{T}_j^t(\sigma), f) - (T_j^t(\sigma), f) \right| \\ \leq \left| (\sigma, f) - (\tilde{T}_j^t(\sigma), f) \right| + 100 \frac{\hat{\varepsilon}}{\eta}. \end{aligned}$$
(36)

Hence it is sufficient to estimate the distance between σ and $\tilde{T}_{i}^{t}(\sigma)$. We can write

$$\begin{aligned} \left| (\sigma, f) - (\tilde{T}_j^t(\sigma), f) \right| &\leq \sum_{\substack{x_i \in M \setminus \bigcup_l B_{\frac{\eta}{4}}(y_l)}} t_i + \sum_{\substack{x_i \in \bigcup_l (B_{\frac{\eta}{4}}(y_l) \setminus B_{\frac{\eta}{16}}(y_l))}} \left| t_i f(x_i) - \tilde{t}_i(\sigma, t) f(\tilde{x}_i(\sigma, t)) \right| \\ &+ \sum_{\substack{x_i \in \bigcup_l B_{\frac{\eta}{16}}(y_l)}} t_i dist(x_i, \tilde{x}_i(\sigma, t)). \end{aligned}$$

Since $\left|t_i f(x_i) - \tilde{t}_i(\sigma, t) f(\tilde{x}_i(\sigma, t))\right| \le |t_i - \tilde{t}_i(\sigma, t)| + \tilde{t}_i(\sigma, t) dist(x_i, \tilde{x}_i(\sigma, t)) \le 2t_i$ (for η small), we obtain

$$\begin{aligned} \left| (\sigma, f) - (\tilde{T}_{j}^{t}(\sigma), f) \right| &\leq 2 \sum_{x_{i} \in M \setminus \cup_{l} B_{\frac{\eta}{16}}(y_{l})} t_{i} + \sum_{l} \sum_{x_{i} \in B_{\frac{\eta}{16}}(y_{l})} t_{i} dist(x_{i}, \mathcal{X}_{l}(\sigma)) \\ &\leq 64 \frac{\hat{\varepsilon}}{\eta} + \sum_{l} \sum_{x_{i} \in B_{\frac{\eta}{16}}(y_{l})} t_{i} dist(x_{i}, \mathcal{X}_{l}(\sigma)). \end{aligned}$$

In order to estimate the last term, we notice that each point x_i in the homotopy is shifted at most of $\frac{\eta}{2}$, see the comments at the beginning of Section 2. Therefore from (36) and the last expression we obtain the estimate

$$\left| (\sigma, f) - (T_j^t(\sigma), f) \right| \le 170 \frac{\hat{\varepsilon}}{\eta} + \frac{\eta}{2}.$$

Therefore, choosing $\eta = \sqrt{\hat{\varepsilon}}$, we obtain the desired conclusion.

Remark 3.5 We notice that, by the property (iv) in the statement of Lemma 3.4, the above homotopy is well defined also from each M_l into itself, for $l \in \{1, \ldots, k-1\}$, and extends continuously to a neighborhood of M_l in M_k . This fact will be used in the next subsection.

Corollary 3.6 Let T_j^t denote the map constructed in Lemma 3.4 above. Then for $\hat{\varepsilon}$ sufficiently small there exists an homotopy H_j^t , $t \in [0, 1]$ between $P_j(\sigma)$ and $T_j^1(\sigma)$ in $M_j\left(\frac{\varepsilon}{2}\right)$, namely a map satisfying the following properties

(37)
$$\begin{cases} H_j^t(\sigma) \in M_j\left(\frac{\varepsilon}{2}\right), & \text{for every } t \in [0,1] \text{ and every } \sigma \in \hat{M}_k^{\hat{\varepsilon},\varepsilon}; \\ H_j^0(\sigma) = T_j^1(\sigma), & \text{for every } \sigma \in \hat{M}_k^{\hat{\varepsilon},\varepsilon}; \\ H_j^1(\sigma) = P_j(\sigma), & \text{for every } \sigma \in \hat{M}_k^{\hat{\varepsilon},\varepsilon}. \end{cases}$$

PROOF. The corollary follows from the smoothness of $M_j\left(\frac{\varepsilon}{4}\right)$ (a neighborhood of $M_j\left(\frac{\varepsilon}{2}\right)$), see Corollary 3.3 and (iii) in Lemma 3.4.

In view of Corollary 3.6, we can modify the map T_j^t by composing it with the above homotopy H_j^t , namely we set

(38)
$$\hat{T}_{j}^{t}(\sigma) = \begin{cases} T_{j}^{2t}(\sigma), & \text{for } t \in [0, \frac{1}{2}]; \\ H_{j}^{2t-1} \circ T_{j}^{1}(\sigma), & \text{for } t \in [\frac{1}{2}, 1]. \end{cases}$$

In this way we obtain an homotopy between the identity map and P_j in a neighborhood of $M_j(\varepsilon)$.

Next we recall the following result, which is necessary in order to carry out the topological argument below. For completeness, we give a brief idea of the proof.

Lemma 3.7 (well-known) For any $k \ge 1$, the set M_k is non-contractible.

PROOF. For k = 1 the statement is obvious, so we consider the case $k \ge 2$. The set $M_k \setminus M_{k-1}$, see Corollary 3.3, is an open manifold of dimension 5k - 1. It is possible to prove that, even if M_{k-1} is not a smooth manifold (for $k \ge 3$), it is anyway a Euclidean Neighborhood Retract, namely it is a contraction of some of its neighborhoods which has smooth boundary (of dimension 5k - 2), see [4], [9]. Therefore M_k has an orientation (mod 2) with respect to M_{k-1} , namely the relative homology class $H_{5k-1}(M_k, M_{k-1}; \mathbb{Z}_2)$ is non-trivial. Consider now this part of the exact homology sequence of the pair (M_k, M_{k-1})

$$\cdots \to H_{5k-1}(M_{k-1};\mathbb{Z}_2) \to H_{5k-1}(M_k;\mathbb{Z}_2) \to H_{5k-1}(M_k,M_{k-1};\mathbb{Z}_2) \to H_{5k-2}(M_{k-1};\mathbb{Z}_2) \to \cdots$$

Since the dimension of (the stratified set) M_{k-1} is less or equal than 5(k-1) - 1 < 5k - 2, both the homology groups $H_{5k-1}(M_{k-1};\mathbb{Z}_2)$ and $H_{5k-2}(M_{k-1};\mathbb{Z}_2)$ vanish, and therefore $H_{5k-1}(M_k;\mathbb{Z}_2) \simeq$ $H_{5k-1}(M_k, M_{k-1};\mathbb{Z}_2) \neq 0$. The proof is concluded.

From the preceding Lemma is it easy to deduce the following result.

Corollary 3.8 For any (relative) integers $k \ge 1$ and $\overline{k} \ge 0$, the set $A_{k,\overline{k}}$ is non-contractible.

3.2 Construction of Ψ

In this subsection we finally construct the map Ψ , using the preceding results about the set M_k . First we show how to construct some partial projections on the sets $M_j(\varepsilon)$ for $\varepsilon > 0$. When referring to the distance of a function in $L^1(M)$ from a set M_j , we always adopt the metric induced by $C^1(M)^*$.

Lemma 3.9 Suppose that $f \in L^1(M)$, $f \ge 0$ and that $\int_M f dV_g = 1$. Then, given any $\varepsilon > 0$ and any $j \in \{1, \ldots, k\}$, there exists $\hat{\varepsilon} > 0$, depending on j and ε with the following property. If $dist(f, M_j(\varepsilon)) \le \hat{\varepsilon}$, then there is a well-defined continuous projection of f onto $M_j(\frac{\varepsilon}{2})$, mapping f to its closest point in M_j . We denote this projection by $P_j(f)$.

PROOF. The Lemma is an easy consequence of Corollary 3.3, since for any $\varepsilon > 0$ $M_j\left(\frac{\varepsilon}{2}\right)$ is a smooth (open) manifold. Therefore, for $\hat{\varepsilon}$ sufficiently small, f is close to this manifold and does not approach its boundary.

Next we define an auxiliary map $\hat{\Psi}$ from a suitable sublevel of II into M_k .

Lemma 3.10 For $k \ge 1$ there exists a large $\hat{L} > 0$ and a continuous map $\hat{\Psi}$ from $\{II \le -\hat{L}\} \cap \{\|\hat{u}\| \le 1\}$ into M_k . Here, as before, \hat{u} denotes the component of u belonging to V, the direct sum of the negative eigenspaces of P_g (if any).

PROOF. First we define some numbers

$$\varepsilon_k \ll \varepsilon_{k-1} \ll \cdots \ll \varepsilon_2 \ll \varepsilon_1 \ll 1$$

in the following way. We choose ε_1 so small that there is a projection from the non-negative $L^1(M)$ functions in an ε_1 -neighborhood of M_1 onto M_1 (to their closest point). This projection will be denoted by P_1 . We now apply Lemma 3.9 with j = 2, $\varepsilon = 4\varepsilon_1$ and, obtaining the corresponding $\hat{\varepsilon}$, we define $\varepsilon_2 = \frac{\hat{\varepsilon}}{4}$. Then we choose the numbers $\varepsilon_3, \ldots, \varepsilon_k$ iteratively in this way.

For any i = 1, ..., k, let f_i be a cutoff function which satisfies the following properties

(39)
$$\begin{cases} f_i(t) = 1, & \text{for } t \leq \varepsilon_i; \\ f_i(t) = 0, & \text{for } t \geq 2\varepsilon_i; \\ f_i(t) \in [0, 1] & \text{for every } t. \end{cases}$$

Next we choose suitably the large number \hat{L} . In order to do this, we apply Lemma 2.4 with S = 1 and some small ε . It is easy to see that if ε is chosen first sufficiently small, and then $\hat{L} = L$ is sufficiently large, then for any $u \in H^2(M)$ with $II(u) \leq -\hat{L}$ (and $\int_M e^{4u} dV_g = 1$) there holds $dist(e^{4u}, M_k) < \varepsilon_k$.

Now, given $u \in H^2(M)$ with $II(u) \leq -\hat{L}$, we let j (depending on u) denote the first integer such that $f_j(dist(e^{4u}, M_j)) = 1$. We notice that for j > 1, since $f_{j-1}(dist(e^{4u}, M_{j-1})) < 1$, there holds $dist(e^{4u}, M_{j-1}) > \varepsilon_{j-1}$ and $dist(e^{4u}, M_{j-1}) < \varepsilon_j$. Therefore, by Lemma 3.9 and our choice of the ε_i 's, the projection $P_j(e^{4u})$ is well-defined. Then we set

$$\hat{\Psi}(u) = \hat{T}_1^{f_1(dist(e^{4u}, M_1))} \circ \hat{T}_2^{f_2(dist(e^{4u}, M_2))} \circ \dots \circ \hat{T}_{j-1}^{f_{j-1}(dist(e^{4u}, M_{j-1})))} \circ P_j(e^{4u}).$$

Some comments are in order. This definition depends in principle on the index j, which is a function of u. Nevertheless, since all the distance functions from the M_l 's are continuous, and since $\hat{T}_l^1 = P_l$, see (38), the above map $\hat{\Psi}$ is indeed well defined and continuous in u, see Remark 3.5.

We are finally in position to introduce the global map Ψ . If $\hat{v}_1, \ldots, \hat{v}_{\overline{k}}$ are an orthonormal basis (in $L^2(M)$) of V of eigenvalues of P_g , see Section 2, we define the \overline{k} -vector

$$s(u) = \left((\hat{v}_1, u)_{L^2(M)}, \dots, (\hat{v}_{\overline{k}}, u)_{L^2(M)} \right) \in \mathbb{R}^k.$$

Then, if \hat{L} is as in Lemma 3.10 and if $\overline{\sigma}$ is any fixed element of M_k , for $k \ge 1$ we let

(40)
$$\Psi(u) = \begin{cases} (s(u), \Psi(u)) & \text{for } |s(u)| \le 1; \\ \begin{pmatrix} s(u) \\ |\overline{s(u)}|, \overline{\sigma} \end{pmatrix}, & \text{for } |s(u)| > 1. \end{cases}$$

Since for |s| tending to 1 the set M_k is collapsing to a single point in $A_{k,\overline{k}}$, the map Ψ is continuous.

On the other hand, if $k_P < 8\pi^2$ and if $\overline{k} \ge 1$ we just set

(41)
$$\Psi(u) = \frac{s(u)}{|s(u)|}.$$

PROOF OF PROPOSITION 3.1. It remains to prove the non-triviality of the map Ψ . This follows from Corollary 3.8 and from (b) in Proposition 4.1.

4 Mapping $A_{k,\overline{k}}$ into low sublevels

The next step consists in finding a map Φ from $A_{k,\overline{k}}$ (resp. from $S^{\overline{k}-1}$) into $H^2(M)$ on which image the functional II attains large negative values.

Proposition 4.1 Let Ψ be the map defined in the previous section. Then, assuming $k \geq 1$ (resp. $k_P < 8\pi^2$ and $\overline{k} > 0$), for any L > 0 sufficiently large (such that Proposition 3.1 applies) there exists a map $\Phi_{\overline{S},\overline{\lambda}}: A_{k,\overline{k}} \to H^2(M)$ (resp. $\Phi_{\overline{S}}: S^{\overline{k}-1} \to H^2(M)$) with the following properties

(a) $II(\Phi_{\overline{S},\overline{\lambda}}(z)) \leq -L$ for any $z \in A_{k,\overline{k}}$ (resp. $II(\Phi_{\overline{S}}(z)) \leq -L$ for any $z \in S^{\overline{k}-1}$);

(b) $\Psi \circ \Phi_{\overline{S},\overline{\lambda}}$ is homotopic to the identity on $A_{k,\overline{k}}$ (resp. $\Psi \circ \Phi_{\overline{S}}$ is homotopic to the identity on $S^{\overline{k}-1}$).

In order to prove this proposition we need some preliminary notations and lemmas. For $\delta > 0$ small, consider a smooth non-decreasing cut-off function $\chi_{\delta} : \mathbb{R}_+ \to \mathbb{R}$ satisfying the following properties

(42)
$$\begin{cases} \chi_{\delta}(t) = t, & \text{for } t \in [0, \delta]; \\ \chi_{\delta}(t) = 2\delta, & \text{for } t \ge 2\delta; \\ \chi_{\delta}(t) \in [\delta, 2\delta], & \text{for } t \in [\delta, 2\delta]. \end{cases}$$

Then, given $\sigma \in M_k$, $\sigma = \sum_{i=1}^k t_i \delta_{x_i}$ and $\lambda > 0$, we define the function $\varphi_{\lambda,\sigma} : M \to \mathbb{R}$ by

(43)
$$\varphi_{\lambda,\sigma}(y) = \frac{1}{4} \log \sum_{i=1}^{k} t_i \left(\frac{2\lambda}{1 + \lambda^2 \chi_{\delta}^2 \left(d_i(y) \right)} \right)^4,$$

where we have set

$$d_i(y) = dist(y, x_i), \qquad x_i, y \in M,$$

with $dist(\cdot, \cdot)$ denoting the distance function on M. We are now in position to define the function $\Phi_{\overline{S},\overline{\lambda}}: A_{k,\overline{k}} \to H^2(M)$. For large \overline{S} and $\overline{\lambda}$ we let

$$\Phi_{\overline{S},\overline{\lambda}}(s,\sigma) = \begin{cases} \varphi_s + \varphi_{\overline{\lambda},\sigma}, & \text{for } |s| \leq \frac{1}{4}; \\ \varphi_s + \varphi_{2\overline{\lambda}-1+4(1-\overline{\lambda})|s|,\sigma}, & \text{for } \frac{1}{4} \leq |s| \leq \frac{1}{2}; \\ \varphi_s + 2(1-\varphi_{1,\sigma})|s| + 2\varphi_{1,\sigma} - 1, & \text{for } |s| \geq \frac{1}{2}, \end{cases}$$

where

$$s = (s_1, \dots, s_{\overline{k}});$$
 $\varphi_s(y) = \overline{S} \sum_{i=1}^{\overline{k}} s_i \hat{v}_i(y).$

For $k_P < 8\pi^2$ and for $\overline{k} \ge 1$ we just set

$$\Phi_{\overline{S}}(s) = \varphi_s, \qquad |s| = 1.$$

Notice that the map is well defined on $A_{k,\overline{k}}$.

We have the following two preliminary Lemmas.

Lemma 4.2 Suppose $\varphi_{\lambda,\sigma}$ is as in (43). Then as $\lambda \to +\infty$ one has

$$\langle P_g \varphi_{\lambda,\sigma}, \varphi_{\lambda,\sigma} \rangle \leq (32k\pi^2 + o_\delta(1)) \log \lambda + C_\delta,$$

where $o_{\delta}(1) \to 0$ as $\delta \to 0$, and where C_{δ} is a constant independent of λ and $\{x_i\}$.

The proof of Lemma 4.2 is quite involved, and therefore it is given in the Appendix.

Lemma 4.3 For $k \ge 1$ (resp. for $k_P < 8\pi^2$ and for $\overline{k} \ge 1$), given any L > 0, there exist a small δ , some large \overline{S} and $\overline{\lambda}$ such that $II(\Phi_{\overline{S},\overline{\lambda}}(s,\sigma)) \le -L$ for every $(\sigma,s) \in A_{k,\overline{k}}$ (resp. $II(\Phi_{\overline{S}}(s)) \le -L$ for every $(s) \in S^{\overline{k}-1}$).

Proof. We begin with the case $k \ge 1$, and we prove first the following three estimates

(44)
$$\int_{M} Q_g(\varphi_s + \varphi_{\lambda,\sigma}) dV_g = -k_P \log \lambda + O(\delta^4 \log \lambda) + O(|\log \delta|) + \overline{S}O(|s|) + O(1);$$

(45)
$$\log \int_{M} \exp\left(4(\varphi_s + \varphi_{\lambda,\sigma})\right) dV_g = O(1) + O(\overline{S}|s|);$$

(46)
$$\langle P_g(\varphi_s + \varphi_{\lambda,\sigma}), (\varphi_s + \varphi_{\lambda,\sigma}) \rangle \leq -|\lambda_{\overline{k}}||s|^2 \overline{S}^2 + 32k\pi^2 (1 + o_\delta(1)) \log \lambda + C_\delta + O(\delta^4 |s|\overline{S}).$$

Proof of (44). We have

$$\varphi_{\lambda,\sigma}(y) = \log \frac{2\lambda}{1+4\lambda^2\delta^2}, \quad \text{for } y \in M \setminus \cup_i B_{2\delta}(x_i),$$

and

$$\log \frac{2\lambda}{1+4\lambda^2\delta^2} \le \varphi_{\lambda,\sigma}(y) \le \log 2\lambda, \quad \text{for } y \in \bigcup_i B_{2\delta}(x_i).$$

Writing

$$\begin{split} \int_{M} Q_{g}(y)\varphi_{\lambda,\sigma}(y)dV_{g}(y) &= \log \frac{2\lambda}{1+4\lambda^{2}\delta^{2}}\int_{M} Q_{g}(y)dV_{g}(y) \\ &+ \int_{M} Q_{g}(y)\left(\varphi_{\lambda,\sigma}(y) - \log \frac{2\lambda}{1+4\lambda^{2}\delta^{2}}\right)dV_{g}(y), \end{split}$$

from the last three formulas it follows that

(47)
$$\int_{M} Q_g(y)\varphi_{\lambda,\sigma}(y)dV_g(y) = k_P \log \frac{2\lambda}{1+4\lambda^2\delta^2} + O\left(\delta^4 \log(1+4\lambda^2\delta^2)\right).$$

Furthermore recalling that the average of φ_s is zero, see Section 2, we also deduce that

(48)
$$\int_{M} Q_g(y)\varphi_s(y)dV_g(y) = \overline{S}\sum_{i=1}^k s_i \int_{M} Q_g(y)\hat{v}_i(y)dV_g(y) = \overline{S}O(|s|).$$

Hence (47) and (48) yield

$$\int_{M} Q_g(y)(\varphi_s + \varphi_{\lambda,\sigma}(y)) dV_g(y) = k_P \log \frac{2\lambda}{1 + 4\lambda^2 \delta^2} + O\left(\delta^4 \log(1 + 4\lambda^2 \delta^2)\right) + \overline{S}O(|s|),$$

which implies immediately (44).

Proof of (45). We recall that in V the L^2 -norm and the L^{∞} norm are equivalent. Therefore, noticing that

(49)
$$\exp\left(4(\varphi_s(y))\right) \in \left[\exp(4\inf_M \varphi_s), \exp(4\sup_M \varphi_s)\right] \subseteq \left[\exp(-4C\overline{S}|s|), \exp(4C\overline{S}|s|)\right],$$

we obtain

(50)
$$\log \int_{M} \exp\left(4(\varphi_{s} + \varphi_{\lambda,\sigma})\right) dV_{g} = \log \int_{M} \exp\left(4\varphi_{s}\right) dV_{g} + \log \int_{M} \exp\left(4\varphi_{\lambda,\sigma}\right) dV_{g}$$
$$= \log \int_{M} \exp\left(4\varphi_{\lambda,\sigma}\right) dV_{g} + O(\overline{S}|s|).$$

By the definition of $\varphi_{\lambda,\sigma}$, there holds

$$\int_{M} \exp\left(4\varphi_{\lambda,\sigma}(y)\right) dV_g(y) = \sum_{i=1}^{k} t_i \int_{M} \left(\frac{2\lambda}{1+\lambda^2 \chi_{\delta}^2\left(dist(y,x_i)\right)}\right)^4 dV_g(y).$$

We divide each of the above integrals into the metric ball $B_{\delta}(x_i)$ and its complement. By construction of χ_{δ} , working in normal coordinates centered at x_i , we have (for δ sufficiently small)

$$\begin{split} &\int_{B_{\delta}(x_i)} \left(\frac{2\lambda}{1+\lambda^2\chi_{\delta}^2\left(dist(y,x_i)\right)}\right)^4 dV_g(y) = \int_{B_{\delta}^{\mathbb{R}^4}(0)} (1+O(\delta)) \left(\frac{2\lambda}{1+\lambda^2|y|^2}\right)^4 dy \\ &= \int_{B_{\lambda\delta}^{\mathbb{R}^4}(0)} (1+O(\delta)) \left(\frac{2}{1+|y|^2}\right)^4 dy = (1+O(\delta)) \left(\frac{8}{3}\pi^2 + O\left(\frac{1}{\lambda^4\delta^4}\right)\right). \end{split}$$

On the other hand, for $dist(y, x_i) \ge \delta$ there holds $\left(\frac{2\lambda}{1+\lambda^2\chi^2_{\delta}(dist(y, x_i))}\right)^4 \le \left(\frac{2\lambda}{1+\lambda^2\delta^2}\right)^4$. Hence, from these two formulas we deduce

(51)
$$\int_{M} \exp\left(4\varphi_{\lambda,x}(y)\right) dV_g(y) = \frac{8}{3}\pi^2 + O(\delta) + O\left(\frac{1}{\lambda^4\delta^4}\right) + O\left(\frac{2\lambda}{1+\lambda^2\delta^2}\right)^4.$$

It follows from (50) and (51) that

(52)
$$\int_{M} \exp\left(4\varphi_s + 4\varphi_{\lambda,\sigma}\right) dV_g = O(\overline{S}) \left(\frac{8}{3} + o(1)\right)$$

This concludes the proof of (45).

Proof of (46). We have trivially

$$\langle P_g(\varphi_s + \varphi_{\lambda,\sigma}), (\varphi_s + \varphi_{\lambda,\sigma}) \rangle = \int_M (P_g \varphi_{\lambda,\sigma}, \varphi_{\lambda,\sigma}) dV_g + 2 \int_M (P_g \varphi_s, \varphi_{\lambda,\sigma}) dV_g + \int_M (P_g \varphi_s, \varphi_s) dV_g + 2 \int_M (P_g \varphi_s) dV$$

By Lemma 4.2 it is sufficient to estimate the last two terms. Since P_g is negative-definite on V (and since the larger negative eigenvalue is $\lambda_{\overline{k}}$), we have clearly

(53)
$$\int_{M} (P_g \varphi_s, \varphi_s) dV_g \le -|\lambda_{\overline{k}}| |s|^2 \overline{S}^2.$$

To evaluate the second term we write $2 \int_M (P_g \varphi_s, \varphi_{\lambda,\sigma}) dV_g = 2\overline{S} \sum_{i=1}^{\overline{k}} s_i \lambda_i \int_M \hat{v}_i \varphi_{\lambda,\sigma} dV_g$. Hence it is sufficient to study each of the terms $\int_M \hat{v}_i \varphi_{\lambda,\sigma} dV_g$. We claim that for each i

(54)
$$\int_{M} \hat{v}_{i} \varphi_{\lambda,\sigma} dV_{g} = O(\delta^{4}).$$

In order to prove this claim, we notice first that the following inequality holds (recall that we have chosen χ_{δ} non-decreasing)

$$\log\left(\frac{2\lambda}{1+4\lambda^2\delta^2}\right) \le \varphi_{\lambda,\sigma} \le \log\left(\frac{2\lambda}{1+\lambda^2\chi_{\delta}^2\left(d_{\min}(y)\right)}\right)$$

where $d_{min}(y) = dist(y, \{x_1\} \cup \cdots \cup \{x_k\})$. Recalling also that $\int_M \hat{v}_i dV_g = 0$, we write

$$\int_{M} \hat{v}_{i}(y)\varphi_{\lambda,\sigma}(y)dV_{g}(y) = \int_{M} \hat{v}_{i}\left(\varphi_{\lambda,\sigma}(y) - \log\frac{2\lambda}{1+4\lambda^{2}\delta^{2}}\right)dV_{g}.$$

Therefore we deduce that

$$\begin{aligned} \left| \int_{M} \hat{v}_{i} \varphi_{\lambda,\sigma} dV_{g} \right| &\leq \| \hat{v}_{i} \|_{L^{\infty}(M)} \int_{M} \left(\varphi_{\lambda,\sigma}(y) - \log \frac{2\lambda}{1 + 4\lambda^{2}\delta^{2}} \right) dV_{g}(y) \\ &\leq \| \hat{v}_{i} \|_{L^{\infty}(M)} \sum_{j=1}^{k} \int_{B_{2\delta}(x_{j})} \left(\log \left(\frac{2\lambda}{1 + \lambda^{2}\chi_{\delta}^{2}(d_{j}(y))} \right) - \log \frac{2\lambda}{1 + 4\lambda^{2}\delta^{2}} \right) dV_{g}(y). \end{aligned}$$

Working in geodesic coordinates around the point x_i we find

$$\begin{split} \int_{B_{2\delta}(x_j)} \left(\varphi_{\lambda,\sigma}(y) - \log \frac{2\lambda}{1+4\lambda^2 \delta^2} \right) dV_g(y) &\leq C \int_0^\delta s^3 \left(\log \frac{2\lambda}{1+\lambda^2 s^2} - \log \frac{2\lambda}{1+4\lambda^2 \delta^2} \right) ds \\ &+ \int_\delta^{2\delta} s^3 \log \frac{1+4\lambda^2 \delta^2}{1+\lambda^2 \chi_\delta^2(s)} ds. \end{split}$$

Using elementary computations we then find

$$\left| \int_{M} \hat{v}_{i}(y) \varphi_{\lambda,\sigma}(y) dV_{g}(y) \right| \leq C \frac{1}{\lambda^{4}} \left[\lambda^{4} \delta^{4} \log \frac{1 + 4\lambda^{2} \delta^{2}}{1 + \lambda^{2} \delta^{2}} + \frac{1}{8} \lambda^{4} \delta^{4} \right] + C \delta^{4} \leq C \delta^{4},$$

which proves our claim (54). Notice that this expression is independent of λ (this will be used at the end of the section). Then, from the above formulas we obtain

$$\langle P_g(\varphi_s + \varphi_{\lambda,\sigma}), (\varphi_s + \varphi_{\lambda,\sigma}) \rangle \leq -|\lambda_{\overline{k}}| |s|^2 \overline{S}^2 + 32k\pi^2 (1 + o_{\delta}(1)) \log \lambda + C_{\delta} + O(\delta^4 |s|\overline{S}).$$

This concludes the proof of (46).

From the three estimates (44), (45) and (46) we deduce that

(55)
$$II(\varphi_{\lambda,x}) \le \left(32k\pi^2 - 4k_P + o_{\delta}(1)\right)\log\lambda - |\lambda_{\overline{k}}||s|^2\overline{S}^2 + O(|s|\overline{S}) + C_{\delta} + O(1).$$

Since $k_P > 8k\pi^2$, choosing δ sufficiently small, the coefficient of the log term is negative. In order to show the upper bound, we fix L > 0. It is easy to see that for \overline{S} sufficiently large one has

$$\left\{ \begin{array}{ll} II(\varphi_s + 2(1 - \varphi_{1,\sigma})|s| + 2\varphi_{1,\sigma} - 1) \leq -L, & \forall \sigma \in M_k, \forall |s| \geq \frac{1}{2}; \\ II(\varphi_s + \varphi_{\overline{\lambda},\sigma}) \leq -L & \forall \sigma \in M_k, \forall |s| \in \left[\frac{1}{4}, \frac{1}{2}\right], \forall \lambda \geq 1. \end{array} \right.$$

After this choice of \overline{S} , we can also take $\overline{\lambda}$ so large that

$$II(\varphi_s + \varphi_{\overline{\lambda},\sigma}) \le -L, \qquad \forall |s| \le \frac{1}{4}.$$

This concludes the proof of the lemma for $k \ge 1$. In the case $k_P < 8\pi^2$ and $\overline{k} \ge 1$, it is sufficient to use the estimates (48), (49) and (53) to obtain

$$II(\varphi_s) \le -|\lambda_{\overline{k}}|\overline{S}^2 + O(\overline{S}).$$

The proof is thereby complete. \blacksquare

PROOF OF PROPOSITION 4.1 The statement (a) follows from Lemma 4.3. Let us prove property (b), starting from the case $k \ge 1$. From the expression of $e^{4\varphi_{\lambda,\sigma}}$ it is easy to see that $\Psi \circ \Phi_{0,\overline{\lambda}}$ is homotopic to the identity on M_k . Furthermore, by continuity and by the estimate (54) one can check that for $|s| \le \frac{1}{8\overline{S}}$ (if $\overline{S} > 1$ and if δ is chosen sufficiently small), we have

(56)
$$\Psi(\varphi_s + \varphi_{\overline{\lambda},\sigma}) = \left(s\overline{S} + O(|s|\overline{S}\delta^4), \hat{\Psi}(\varphi_s + \varphi_{\overline{\lambda},\sigma})\right),$$

and therefore $\Psi \circ \Phi_{\overline{S},\overline{\lambda}}$ is homotopic (in $A_{k,\overline{k}}$) to the identity on $M_k \times B_{\frac{1}{8\overline{S}}}^{\overline{k}} \subseteq A_{k,\overline{k}}$.

On the other hand, by (56), for $|s| \geq \frac{1}{8\overline{S}}$, the \overline{k} -vector $s\overline{S} + O(|s|\overline{S}\delta^4)$ almost parallel to s (and non-zero), and therefore on this set $\Psi \circ \Phi_{\overline{S},\overline{\lambda}}$ can be easily contracted to the boundary of $B_{\overline{k}}^1$ (recall the definition of $A_{k,\overline{k}}$), as for the identity map. This concludes the proof in the case $k \geq 1$. The proof for $k_P < 8\pi^2$ and under the assumption (12) is analogous.

5 Proof of Theorem 1.1

In this section we prove Theorem 1.1 employing a minimax scheme based on the construction of the above set $A_{k,\overline{k}}$, see Lemma 5.1. As anticipated in the introduction, we then define a modified functional II_{ρ} for which we can prove existence of solutions in a dense set of the values of ρ . Following an idea of Struwe, this is done proving the a.e. differentiability of the map $\rho \mapsto \overline{\Pi}_{\rho}$, where $\overline{\Pi}_{\rho}$ is the minimax value for the functional II_{ρ} .

We now introduce the minimax scheme which provides existence of solutions for (8), beginning with the case $k \geq 1$. Let $\widehat{A_{k,\overline{k}}}$ denote the (contractible) cone over $A_{k,\overline{k}}$, which can be represented as $\widehat{A_{k,\overline{k}}} = (A_{k,\overline{k}} \times [0,1])$ with $A_{k,\overline{k}} \times \{0\}$ collapsed to a single point. Let first L be so large that Proposition 3.1 applies with $\frac{L}{4}$, and then let $\overline{S}, \overline{\lambda}$ be so large (and δ so small) that Proposition 4.1 applies for this value of L. Fixing these numbers \overline{S} and $\overline{\lambda}$, we define the following class

(57)
$$\Pi_{\overline{S},\overline{\lambda}} = \left\{ \pi : \widehat{A_{k,\overline{k}}} \to H^2(M) : \pi \text{ is continuous and } \pi(\cdot \times \{1\}) = \Phi_{\overline{S},\overline{\lambda}}(\cdot) \right\}.$$

In the case $k_P < 8\pi^2$ and $\overline{k} \ge 1$ we simply use the closed unit \overline{k} -dimensional ball $\overline{B}_1^{\overline{k}}$ and we set (still for large values of L)

$$\Pi_{\overline{S}} = \left\{ \pi: \overline{B}_1^{\overline{k}} \to H^2(M) \ : \ \pi \text{ is continuous and } \pi(\cdot) = \Phi_{\overline{S}}(\cdot) \right\}.$$

Then we have the following properties.

Lemma 5.1 The set $\Pi_{\overline{S},\overline{\lambda}}$ (resp. $\Pi_{\overline{S}}$) is non-empty and moreover, letting

$$\begin{split} \overline{\Pi}_{\overline{S},\overline{\lambda}} &= \inf_{\pi \in \Pi_{\overline{S},\overline{\lambda}}} \sup_{m \in \widetilde{A}_{k,\overline{k}}} II(\pi(m)), \qquad there \ holds \qquad \overline{\Pi}_{\overline{S},\overline{\lambda}} > -\frac{L}{2}, \\ \\ \begin{pmatrix} resp. \ \overline{\Pi}_{\overline{S}} &= \inf_{\pi \in \Pi_{\overline{S}}} \sup_{m \in \overline{B}_{1}^{\overline{k}}} II(\pi(m)), \qquad there \ holds \qquad \overline{\Pi}_{\overline{S}} > -\frac{L}{2} \end{pmatrix}. \end{split}$$

PROOF. To prove that $\prod_{\overline{S},\overline{\lambda}} \neq \emptyset$, we just notice that the following map

(58)
$$\overline{\pi}(\cdot,t) = t\Phi_{\overline{S}\,\overline{\lambda}}(\cdot)$$

belongs to $\Pi_{\overline{S},\overline{\lambda}}$. Assuming by contradiction that $\overline{\Pi}_{\overline{S},\overline{\lambda}} \leq -\frac{L}{2}$, there would exist a map $\pi \in \Pi_{\overline{S},\overline{\lambda}}$ with $\sup_{m \in \widehat{A_{k,\overline{k}}}} II(\pi(m)) \leq -\frac{3}{8}L$. Then, since Proposition 3.1 applies with $\frac{L}{4}$, writing m = (z,t), with $z \in A_{k,\overline{k}}$, the map

$$t \mapsto \Psi \circ \pi(\cdot, t)$$

would be an homotopy in $A_{k,\overline{k}}$ between $\Psi \circ \Phi_{\overline{S},\overline{\lambda}}$ and a constant map. But this is impossible since $A_{k,\overline{k}}$ is non-contractible (see Corollary 3.8) and since $\Psi \circ \Phi_{\overline{S},\overline{\lambda}}$ is homotopic to the identity, by Proposition 4.1. Therefore we deduce $\overline{\Pi}_{\overline{S},\overline{\lambda}} > -\frac{L}{2}$.

In the case $k_P < 8\pi^2$ and $\overline{k} \ge 1$ it is sufficient to take $\overline{\pi}(\cdot, t) = t\Phi_{\overline{S}}(\cdot)$ and to proceed in the same way.

Next we introduce a variant of the above minimax scheme, following [36] and [22]. When $k_P < 8\pi^2$, we define for convenience $A_{k,\overline{k}} = S^{\overline{k}}$, $\widehat{A_{k,\overline{k}}} = \overline{B}_1^{\overline{k}}$, $\Phi_{\overline{S},\overline{\lambda}} = \Phi_{\overline{S}}$, etc. For ρ in a small neighborhood of 1, $[1 - \rho_0, 1 + \rho_0]$, we define the modified functional $II_{\rho} : H^2(M) \to \mathbb{R}$

(59)
$$II_{\rho}(u) = \langle P_g u, u \rangle + 4\rho \int_{M} Q_g u - 4\rho k_P \log \int_{M} e^{4u} dV_g.$$

Following the estimates of the previous sections, one easily checks that the above minimax scheme applies uniformly for $\rho \in [1 - \rho_0, 1 + \rho_0]$ and for \overline{S} , $\overline{\lambda}$ sufficiently large. More precisely, given any large number L > 0, there exist \overline{S} and $\overline{\lambda}$ sufficiently large and ρ_0 sufficiently small such that

$$(60) \sup_{\pi \in \overline{\Pi}_{\overline{S},\overline{\lambda}}} \sup_{m \in \partial \widetilde{A_{k,\overline{k}}}} II_{\rho}(\pi(m)) < -2L; \quad \overline{\Pi}_{\rho} := \inf_{\pi \in \Pi_{\overline{S},\overline{\lambda}}} \sup_{m \in \widetilde{A_{k,\overline{k}}}} II(\pi(m)) > -\frac{L}{2}; \qquad \rho \in [1-\rho_0, 1+\rho_0],$$

where $\Pi_{\overline{S},\overline{\lambda}}$ is defined in (57). Moreover, using for example the test map (58), one shows that for ρ_0 sufficiently small there exists a large constant \overline{L} such that

(61)
$$\overline{\Pi}_{\rho} \leq \overline{L} \qquad \text{for every } \rho \in [1 - \rho_0, 1 + \rho_0].$$

We have the following result, regarding the dependence in ρ of the minimax value $\overline{\Pi}_{\rho}$. A similar statement has been proved in [22], but here we allow the presence of negative eigenvalues for the elliptic operator, so the proof is more involved.

Lemma 5.2 Let \overline{S} , $\overline{\lambda}$ and ρ_0 so small that (60) holds. Then, taking ρ_0 possibly smaller, there exists a fixed constant C (depending only on M and ρ_0) such that the function

$$\rho \mapsto \frac{\overline{\Pi}_{\rho}}{\rho} - C\rho$$
 is non-increasing in $[1 - \rho_0, 1 + \rho_0]$.

PROOF. If P_g is non-negative, for $8(k+1)\pi^2 > \rho' \ge \rho > 8k\pi^2$ (resp. for $8\pi^2 > \rho' \ge \rho$) we clearly have

$$\frac{II_{\rho}(u)}{\rho} - \frac{II_{\rho'}(u)}{\rho'} = \left(\frac{1}{\rho} - \frac{1}{\rho'}\right) \langle P_g u, u \rangle \le 0,$$

and the conclusion follow immediately taking C = 0. Therefore from now on we consider the case in which P_q possesses some negative eigenvalues. The last formula in this case yields

(62)
$$\frac{II_{\rho'}(u)}{\rho'} \le \frac{II_{\rho}(u)}{\rho} - \frac{(\rho' - \rho)}{\rho\rho'} \langle P_g \hat{u}, \hat{u} \rangle,$$

where \hat{u} is the V-part of u, see (18).

Fixing $\rho \in [1 - \rho_0, 1 + \rho_0]$ and $\varepsilon > 0$, we consider a map $\pi_{\rho, \varepsilon} \in \overline{\Pi}_{\overline{S}, \overline{\lambda}}$ such that

(63)
$$\sup_{m\in \widetilde{A_{k,\overline{k}}}} II_{\rho}(\pi_{\rho,\varepsilon}(m)) < \overline{\Pi}_{\rho} + \varepsilon.$$

We can also assume that each element of the form $u = \pi_{\rho,\varepsilon}(m)$ satisfies the normalization condition $\int_M e^{4u} dV_g = 1$. Now, considering the V-part \hat{u} of all these elements, we fix three numbers $\theta > 0$ (small, depeding on $\pi_{\rho,\varepsilon}$), and $C_0, C_1 > 0$ (depending on M and ρ_0 , with $C_1 \gg C_0 \gg 1$), and we define a new map $\tilde{\pi}_{\rho,\varepsilon}$ in the following way

(64)
$$\tilde{\pi}_{\rho,\varepsilon}(m) = \pi_{\rho,\varepsilon}(m) + \eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}(m)})\widehat{\pi_{\rho,\varepsilon}(m)}; \qquad m \in \widetilde{A_{k,\overline{k}}},$$

where the function $\eta_{\theta}(m)$, $m = (m_1, t) \in A_{k,\overline{k}} \times [0, 1]$, is defined as

$$\eta_{\theta}(m) = \begin{cases} 1, & \text{for } t \in [0, 1-\theta];\\ \frac{1}{\theta}(1-t), & \text{for } t \in [1-\theta, 1], \end{cases}$$

and where $\widehat{\eta}(\widehat{\pi_{\rho,\varepsilon}(m)})$ is given by

$$\widetilde{\eta}(\widehat{\pi_{\rho,\varepsilon}(m)}) = \begin{cases} 0, & \text{for } \|\widehat{\pi_{\rho,\varepsilon}(m)}\| \in [0, C_0], \\ \frac{1}{C_1 - C_0}(\|\widehat{\pi_{\rho,\varepsilon}(m)}\| - C_0), & \text{for } \|\widehat{\pi_{\rho,\varepsilon}(m)}\| \in [C_0, C_1], \\ 1, & \text{for } \|\widehat{\pi_{\rho,\varepsilon}(m)}\| \ge C_1. \end{cases}$$

When $\eta_{\theta}(m) = 1$, by the normalization of $\pi_{\rho,\varepsilon}$ we have the following upper bound on $II_{\rho}(\tilde{\pi}_{\rho,\varepsilon}(m))$

$$(65) \qquad II_{\rho}(\tilde{\pi}_{\rho,\varepsilon}) = \langle P_{g}\pi_{\rho,\varepsilon}, \pi_{\rho,\varepsilon} \rangle + \left(2\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) + (\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}))^{2}\right) \langle P_{g}\widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle \\ + 4\rho \int_{M} Q_{g}(\pi_{\rho,\varepsilon} + \tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}})\widehat{\pi_{\rho,\varepsilon}}) dV_{g} - 4\rho k_{P} \int_{M} e^{4\pi_{\rho,\varepsilon} + 4\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}})\widehat{\pi_{\rho,\varepsilon}}} dV_{g} \\ \leq II_{\rho}(\pi_{\rho,\varepsilon}) + \left(2\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) + (\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}))^{2}\right) \langle P_{g}\widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle + \tilde{C}_{0}\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \|\widehat{\pi_{\rho,\varepsilon}}\|,$$

where \tilde{C}_0 is a fixed constant depending only on M and on ρ_0 . If C_0 is sufficiently large (depending only \tilde{C}_0 which, in turn, depends only on M and ρ_0), then one has

(66)
$$\left(2\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) + (\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}))^2\right) \langle P_g \widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle + \tilde{C}_0 \tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \|\widehat{\pi_{\rho,\varepsilon}}\| \le 0 \quad \text{for } \|\widehat{\pi_{\rho,\varepsilon}}(m)\| \ge C_0.$$

Having fixed this value of C_0 , from (62) and the fact that $\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}(m)}) = 0$ for $\|\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}(m)})\| \leq C_0$ it follows that

(67)
$$\frac{II_{\rho'}(\tilde{\pi}_{\rho,\varepsilon})}{\rho'} \leq \frac{II_{\rho}(\pi_{\rho,\varepsilon})}{\rho} - \frac{\rho' - \rho}{\rho\rho'} \langle P_g \widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle \leq \frac{\overline{\Pi}_{\rho} + \varepsilon}{\rho} + \hat{C}_0(\rho' - \rho); \qquad \|\widehat{\pi_{\rho,\varepsilon}}(m)\| \leq C_0, \eta_{\theta}(m) = 1,$$

where \hat{C}_0 depends only on M and ρ_0 . Now we fix also the value of C_1 . We choose ρ_0 so small and $C_1 > 0$ (depending only on M and ρ_0) so large that

(68)
$$\frac{3}{\rho'} \left(1 - \frac{4}{3} \frac{\rho' - \rho}{\rho} \right) \langle P_g \hat{v}, \hat{v} \rangle + \frac{C_0}{\rho'} \| \hat{v} \| \le \langle P_g \hat{v}, \hat{v} \rangle \le -2\overline{L} - L \quad \text{for all } \hat{v} \in V \text{ with } \| \hat{v} \| \ge C_1,$$

where L and \overline{L} are the constants given in (60) and (61). From (62), (65) and (66) we immediately find (still for $\eta_{\theta}(m) = 1$)

(69)
$$\frac{II_{\rho'}(\pi_{\rho,\varepsilon})}{\rho'} \leq \frac{II_{\rho}(\pi_{\rho,\varepsilon})}{\rho} - \frac{\rho'-\rho}{\rho\rho'} \langle P_g \widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle \leq \frac{\overline{\Pi}_{\rho} + \varepsilon}{\rho} + \hat{C}_1(\rho'-\rho); \qquad C_0 \leq \|\widehat{\pi_{\rho,\varepsilon}(m)}\| \leq C_1,$$

where \hat{C}_1 depends only on M and ρ_0 . By (62) and (65), since $\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) = 1$ when $\|\widehat{\pi_{\rho,\varepsilon}}\| \ge C_1$, we obtain (70)

$$\frac{II_{\rho'}(\tilde{\pi}_{\rho,\varepsilon})}{\rho'} \leq \frac{II_{\rho}(\pi_{\rho,\varepsilon})}{\rho} + \frac{3}{\rho'} \left(1 - \frac{4}{3}\frac{\rho' - \rho}{\rho}\right) \langle P_g \widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle + \frac{\tilde{C}_0}{\rho'} \|\widehat{\pi_{\rho,\varepsilon}}\|; \qquad \|\widehat{\pi_{\rho,\varepsilon}(m)}\| \geq C_1, \eta_{\theta}(m) = 1.$$

Then (68) implies

(71)
$$\frac{II_{\rho'}(\tilde{\pi}_{\rho,\varepsilon})}{\rho'} \le \frac{\overline{\Pi}_{\rho}}{\rho}, \qquad \text{for } \|\hat{\pi}\| \ge C_1.$$

From (67), (69) and (71) we deduce

(72)
$$\frac{II_{\rho'}(\tilde{\pi}_{\rho,\varepsilon})}{\rho'} \le \frac{\overline{\Pi}_{\rho} + \varepsilon}{\rho} + (\hat{C}_0 + \hat{C}_1)(\rho' - \rho), \quad \text{for } \eta_{\theta}(m) = 1.$$

Therefore it remains to consider the case in which $\eta_{\theta}(m) \neq 1$, namely for $t > 1-\theta$ (recall that $m = (m_1, t)$ with $m_1 \in A_{k,\overline{k}}$). This is where the choice of θ enters. Reasoning as for (65) we find

$$II_{\rho'}(\tilde{\pi}_{\rho,\varepsilon}) \leq II_{\rho'}(\pi_{\rho,\varepsilon}) + 2\eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \langle P_{g}\widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle + \tilde{C}_{0}\eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \|\widehat{\pi_{\rho,\varepsilon}}\|.$$

Recall that the map $\pi_{\rho,\varepsilon}$ belongs to $\Pi_{\overline{S},\overline{\lambda}}$, and hence it satisfies $\pi_{\rho,\varepsilon}(t,\cdot) \to \Phi_{\overline{S},\overline{\lambda}}(\cdot)$ in $C^0(A_{k,\overline{k}})$. Since ρ is varying in the small interval $[1 - \rho_0, 1 + \rho_0]$, we have estimates of the form (55) (with ρk_P replacing k_P) uniformly for ρ in this interval. Thus from the last formula we deduce that, for $\eta_{\theta}(m) < 1$

$$\begin{split} II_{\rho'}(\tilde{\pi}_{\rho,\varepsilon}(m)) &\leq II_{\rho'}(\Phi_{\overline{S},\overline{\lambda}}(m_{1})) + o_{\theta}(1) + 2\eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \langle P_{g}\widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle + \hat{C}_{0}\eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \|\widehat{\pi_{\rho,\varepsilon}}\| \\ &\leq \left(32k\pi^{2} - 4\rho'k_{P} + o_{\delta}(1)\right)\log\lambda - |\lambda_{\overline{k}}||s|^{2}\overline{S}^{2} + O(|s|\overline{S}) + C_{\delta} + O(1) + o_{\theta}(1) \\ &+ 2\eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \langle P_{g}\widehat{\pi_{\rho,\varepsilon}}, \widehat{\pi_{\rho,\varepsilon}} \rangle + \tilde{C}_{0}\eta_{\theta}(m)\tilde{\eta}(\widehat{\pi_{\rho,\varepsilon}}) \|\widehat{\pi_{\rho,\varepsilon}}\| \\ &\leq \left(32k\pi^{2} - 4\rho'k_{P} + o_{\delta}(1)\right)\log\lambda - |\lambda_{\overline{k}}||s|^{2}\overline{S}^{2} + O(|s|\overline{S}) + C_{\delta} + O(1) < -\frac{3}{2}L, \end{split}$$

if L is chosen sufficiently large (see (60)) and θ is chosen sufficiently small. Now the conclusion follows from (72) and the last estimate.

From Lemma 5.2 it follows that the function $\rho \mapsto \frac{\overline{\Pi}_{\rho}}{\rho}$ is a.e. differentiable, and we obtain the following corollary.

Corollary 5.3 Let \overline{S} , $\overline{\lambda}$ and ρ_0 be as in Lemma 5.2, and let $\Lambda \subset [1 - \rho_0, 1 + \rho_0]$ be the (dense) set of ρ for which the function $\frac{\overline{\Pi}_{\rho}}{\rho}$ is differentiable. Then for $\rho \in \Lambda$ the functional II_{ρ} possesses a bounded Palais-Smale sequence $(u_l)_l$ at level $\overline{\Pi}_{\rho}$.

PROOF. The existence of a Palais-Smale sequence $(u_l)_l$ follows from Lemma 5.1, and the boundedness is proved exactly as in [22], Lemma 3.2.

Remark 5.4 When $k_P < 8\pi^2$ one can use a direct approach to prove boundedness of Palais-Smale sequences (satisfying (14)). We test the relation $II'(u_l) \to 0$ (in $H^{-2}(M)$) on \hat{u}_l and \tilde{u}_l , where \hat{u}_l is the component of u_l in V and \tilde{u}_l is the component perpendicular to V.

Testing the equation on \hat{u}_l we obtain

(73)
$$\langle P_g \hat{u}_l, \hat{u}_l \rangle + 4 \int_M Q_g \hat{u}_l dV_g - 4k_P \int_M e^{4u_l} \hat{u}_l dV_g = o_l(1) \|\hat{u}_l\|_{L^{\infty}(M)}$$

Since $\|e^{4u_l}\|_{L^1(M)} = 1$ by (14) and since on V the L^{∞} -norm is equivalent to the H^2 -norm, the last formula implies $-\langle P_g \hat{u}_l, \hat{u}_l \rangle = O(1) \|\hat{u}_l\|_{H^2(M)}$. Therefore, being P_g is negative-definite on V, we get uniform bounds on $\|\hat{u}_l\|$.

On the other hand, testing the equation on \tilde{u}_l we find

$$2\langle P_g \tilde{u}_l, \tilde{u}_l \rangle - 4k_P \int_M e^{4u_l} (\tilde{u}_l - \overline{u}_l) dV_g = O(\|\tilde{u}_l - \overline{u}_l\|_{H^2(M)}).$$

This implies, for any $\alpha > 1$ (using (23) and (73))

$$\begin{aligned} 2\langle P_{g}\tilde{u}_{l},\tilde{u}_{l}\rangle &\leq Ce^{4\overline{u}_{l}}\int_{M}e^{4(u_{l}-\overline{u}_{l})}(\tilde{u}_{l}-\overline{u}_{l})dV_{g}+O(\|\tilde{u}_{l}-\overline{u}_{l}\|_{H^{2}(M)})\\ &\leq C_{\alpha}e^{4\overline{u}_{l}}\int_{M}e^{4\alpha(u_{l}-\overline{u}_{l})}dV_{g}+O(\|\tilde{u}_{l}-\overline{u}_{l}\|_{H^{2}(M)})\\ &\leq C_{\alpha}e^{4\overline{u}_{l}}e^{\alpha^{2}\frac{\langle P_{g}\tilde{u}_{l},\tilde{u}_{l}\rangle}{8\pi^{2}}}+O(\|\tilde{u}_{l}-\overline{u}_{l}\|_{H^{2}(M)}).\end{aligned}$$

Moreover, since we are assuming $II(u_l) \to c \in \mathbb{R}$, for any small ε we get

$$C \ge II(\tilde{u}_l) = \langle P_g \tilde{u}_l, \tilde{u}_l \rangle + 4 \int_M Q_g u_l = (1 + O(\varepsilon)) \langle P_g \tilde{u}_l, \tilde{u}_l \rangle + 4k_P \overline{u}_l + C_{\varepsilon},$$

provided l is sufficiently large. Hence from the last two formulas we deduce

$$\langle P_g \tilde{u}_l, \tilde{u}_l \rangle \le C_{\alpha, \varepsilon} e^{\langle P_g \tilde{u}_l, \tilde{u}_l \rangle - \frac{\alpha^2}{8\pi^2} - \frac{1+O(\varepsilon)}{k_P}} + O(\|\tilde{u}_l - \overline{u}_l\|_{H^2(M)})$$

Now, choosing α and ε so small that the exponential factor has a negative coefficient (this is possible since $k_P < 8\pi^2$), we obtain an uniform bound for $\tilde{u}_l - \overline{u}_l$. The bound on \overline{u}_l now follows easily.

Now the proof of Theorem 1.1 is an easy consequence of the following Proposition and of Theorem 1.3.

Proposition 5.5 Suppose $(u_l)_l \subseteq H^2(M)$ is a sequence for which

$$II_{\rho}(u_l) \to c \in \mathbb{R}; \qquad \qquad II'_{\rho}[u_l] \to 0; \qquad \qquad \|u_l\|_{H^2(M)} \le C$$

Then $(u_l)_l$ has a weak limit u_0 which satisfies (15).

PROOF. The existence of a weak limit u_0 follows from Corollary 5.3. Let us show that u_0 satisfies $II'_{\rho}(u_0) = 0$. For any function $v \in H^2(M)$ there holds

$$II'_{\rho}(u_0)[v] = II'_{\rho}(u_l)[v] + 2\langle P_g v, (u_0 - u_l) \rangle + 4\rho k_P \left(\frac{\int_M e^{4u_l} v dV_g}{\int_M e^{4u_l} dV_g} - \frac{\int_M e^{4u_0} v dV_g}{\int_M e^{4u_0} dV_g} \right).$$

Since the first two terms tend to zero by our assumptions, it is sufficient to check that $\int_M e^{4u_l} v dV_g = \int_M e^{4u_0} v dV_g + o(1) ||v||_{H^2(M)}$ (to deal with the denominators just take $v \equiv 1$). In order to do this, consider p, p', p'' > 1 satisfying $\frac{1}{p} + \frac{1}{p'} + \frac{1}{p''} = 1$. Using Lagrange's formula we obtain, for some function θ_l with range in $[0, 1], e^{4u_l} - e^{4u_0} = e^{4\theta_l u_l + 4(1-\theta_l)u_0}(u_l - u_0)$ a.e. in x. Then from some elementary inequalities we find

$$\begin{split} \int_{M} \left(e^{4u_{l}} - e^{4u_{0}}v \right) dV_{g} &\leq C \int_{M} \left(e^{4u_{l}} + e^{4u_{0}} \right) |u_{l} - u_{0}| |v| dV_{g} \\ &\leq C \left[\|e^{4u_{l}}\|_{L^{p}(M)} + \|e^{4u_{0}}\|_{L^{p}(M)} \right] \|u_{l} - u_{0}\|_{L^{p'}(M)} \|v\|_{L^{p''}(M)} \\ &\leq o(1) \|v\|_{L^{p''}(M)} = o(1) \|v\|_{H^{2}(M)}, \end{split}$$

by (23), the boundedness of $(u_l)_l$ and the fact that $u_l \rightharpoonup u_0$.

6 Appendix

PROOF OF LEMMA 4.2 For simplicity, see Section 4, we adopt again the notation $d_i = d_i(y) = dist(y, x_i)$, and we consider these as functions of y, for $\{x_i\}$ fixed. With some straightforward computations we find

(74)
$$\nabla \varphi_{\lambda,\sigma} = -\lambda^2 (2\lambda)^4 \frac{\sum_{i=1}^k t_i \nabla(\chi_\delta^2(d_i)) (1+\lambda^2 \chi_\delta^2(d_i))^{-5}}{\sum_{s=1}^k t_s \left(\frac{2\lambda}{1+\lambda^2 \chi_\delta^2(d_s)}\right)^4},$$

and

$$\Delta \varphi_{\lambda,\sigma} = \lambda^{2} (2\lambda)^{4} \frac{\sum_{i=1}^{k} t_{i} (1+\lambda^{2} \chi_{\delta}^{2}(d_{i}))^{-6} \left[5\lambda^{2} |\nabla(\chi_{\delta}^{2}(d_{i}))|^{2} - \Delta(\chi_{\delta}^{2}(d_{i}))(1+\lambda^{2} \chi_{\delta}^{2}(d_{i})) \right]}{\sum_{s=1}^{k} t_{s} \left(\frac{2\lambda}{1+\lambda^{2} \chi_{\delta}^{2}(d_{s})} \right)^{4}} - 4\lambda^{4} (2\lambda)^{8} \frac{\sum_{i,s=1}^{k} t_{i} t_{s} (1+\lambda^{2} \chi_{\delta}^{2}(d_{i}))^{-5} (1+\lambda^{2} \chi_{\delta}^{2}(d_{s}))^{-5} \nabla(\chi_{\delta}^{2}(d_{i})) \cdot \nabla(\chi_{\delta}^{2}(d_{s}))}{\left[\sum_{r=1}^{k} t_{r} \left(\frac{2\lambda}{1+\lambda^{2} \chi_{\delta}^{2}(d_{r})} \right)^{4} \right]^{2}}.$$

We begin by estimating $\int_M (\Delta \varphi_{\lambda,\sigma})^2 dV_g$. This is the most involved part of the proof, and the result is given in formula (98) below. We notice first that the following pointwise estimate holds true, as one can easily check using (75)

$$|\Delta \varphi_{\lambda,\sigma}| \le \frac{C}{\lambda^2}.$$

For a large but fixed constant $\Theta > 0$ (and $\lambda \to +\infty$), the volume of a ball of radius $\frac{\Theta}{\lambda}$ is bounded by $C\frac{\Theta^4}{\lambda^4}$. From this we deduce that

(76)
$$\int_{\bigcup_i B_{\frac{\Theta}{\lambda}}(x_i)} (\Delta \varphi_{\lambda,\sigma})^2 dV_g \le C\Theta^4.$$

Therefore we just need to estimate the integral of the complement of the union of these balls, which we denote by

(77)
$$M_{\sigma,\Theta} = M \setminus \bigcup_{i=1}^{k} B_{\underline{\Theta}}(x_i).$$

In this set, since we are taking Θ large, the ratio between $1 + \lambda^2 d_i$ and $\lambda^2 d_i$ is very close to 1, and hence we obtain the following estimates

(78)
$$(1 + \lambda^2 \chi_{\delta}^2(d_i)) = (1 + o_{\delta,\Theta}(1))\lambda^2 \chi_{\delta}^2(d_i), \qquad \text{in } M_{\sigma,\Theta};$$

(79)
$$5\lambda^2 |\nabla(\chi_{\delta}^2(d_i))|^2 - \Delta(\chi_{\delta}^2(d_i))(1 + \lambda^2 \chi_{\delta}^2(d_i)) = 12(1 + o_{\delta,\Theta}(1))\lambda^2 \tilde{\chi}_{\delta}^2(d_i), \quad \text{in } M_{\sigma,\Theta},$$

where $o_{\delta,\Theta}(1)$ tends to zero as δ tends to zero and Θ tends to infinity, and where $\tilde{\chi}_{\delta}$ is a new cutoff function (which depends on χ_{δ}) satisfying

(80)
$$\begin{cases} \tilde{\chi}_{\delta}(t) = t, & \text{for } t \in [0, \delta]; \\ \tilde{\chi}_{\delta}(t) = 0, & \text{for } t \ge 2\delta; \\ \tilde{\chi}_{\delta}(t) \in [0, 2\delta], & \text{for } t \in [\delta, 2\delta]. \end{cases}$$

Using (75), (78) and (79) one finds that the following estimate holds

$$\Delta \varphi_{\lambda,\delta} = 12(1+o_{\delta,\Theta}(1)) \frac{\sum_{i} t_{i} \frac{\tilde{\chi}_{\delta}^{2}(d_{i})}{\chi_{\delta}^{12}(d_{i})}}{\sum_{s} \frac{t_{s}}{\chi_{\delta}^{8}(d_{s})}} - 4(1+o_{\delta,\Theta}(1)) \frac{\sum_{i,s=1}^{k} t_{i} t_{s} \frac{\nabla(\chi_{\delta}^{2}(d_{i})) \cdot \nabla(\chi_{\delta}^{2}(d_{s}))}{\chi_{\delta}(d_{i})^{10}\chi_{\delta}(d_{s})^{10}}}{\left[\sum_{r=1}^{k} t_{r} \frac{1}{\chi_{\delta}^{8}(d_{r})}\right]^{2}} + o_{\delta,\Theta}(1) \frac{\sum_{i,s=1}^{k} t_{i} t_{s} \frac{|\nabla(\chi_{\delta}^{2}(d_{i}))| |\nabla(\chi_{\delta}^{2}(d_{s}))|}{\chi_{\delta}(d_{i})^{10}\chi_{\delta}(d_{s})^{10}}}{\left[\sum_{r=1}^{k} t_{r} \frac{1}{\chi_{\delta}^{8}(d_{r})}\right]^{2}} \qquad \text{in } M_{\sigma,\Theta}.$$

To have a further simplification of the last expression, it is convenient to get rid of the cutoff functions χ_{δ} and $\tilde{\chi}_{\delta}$. In order to do this, we divide the set of points $\{x_1, \ldots, x_k\}$ in a suitable way. Since the number k is fixed, there exists $\hat{\delta}$ and sets $\mathcal{C}_1, \ldots, \mathcal{C}_j, j \leq k$ with the following properties

(82)
$$\begin{cases} C_k^{-1}\delta \leq \hat{\delta} \leq \frac{\delta}{16}; \\ \mathcal{C}_1 \cup \cdots \cup \mathcal{C}_j = \{x_1, \dots, x_k\}; \\ dist(x_i, x_s) \leq \hat{\delta} & \text{if } x_i, x_s \in \mathcal{C}_a; \\ dist(x_i, x_s) \geq 4\hat{\delta} & \text{if } x_i \in \mathcal{C}_a, x_s \in \mathcal{C}_b, a \neq b, \end{cases}$$

where C_k is a positive constant depending only on k. Now we define

$$\hat{\mathcal{C}}_a = \left\{ y \in M : dist(y, \mathcal{C}_a) \le 2\hat{\delta} \right\}; \qquad T_a = \sum_{x_i \in \mathcal{C}_a} t_i, \qquad a = 1, \dots, j.$$

By the definition of $\hat{\delta}$ it follows that

(83)
$$\chi_{\delta}(d_i(y)) = \tilde{\chi}_{\delta}(d_i(y)) = d_i(y), \quad \text{for } x_i \in \mathcal{C}_a \text{ and } y \in \hat{\mathcal{C}}_a,$$

and

(84)
$$\chi_{\delta}(d_i(y)) \ge 2\delta$$
, for $x_i \in \mathcal{C}_a$ and $y \notin \hat{\mathcal{C}}_a$.

Furthermore one has

$$\mathcal{C}_a \cap \mathcal{C}_b = \emptyset$$
 for $a \neq b$.

From (81) and (84) it follows that

(86)
$$|\Delta \varphi_{\lambda,\sigma}(y)| \le C_{\hat{\delta}} \qquad \text{for } y \in M \setminus \bigcup_{a=1}^{j} \tilde{\mathcal{C}}_{a}.$$

Therefore, by (85), it is sufficient to estimate $\Delta \varphi_{\lambda,\sigma}$ inside each set $\hat{\mathcal{C}}_a$, where (83) holds. We obtain immediately the following two estimates, regarding the first terms in (81)

$$(87) \quad \sum_{i} t_{i} \frac{\tilde{\chi}_{\delta}^{2}(d_{i})}{\chi_{\delta}^{12}(d_{i})} = \sum_{x_{i}\in\hat{\mathcal{C}}_{a}} \frac{t_{i}}{d_{i}^{10}} + O((1-T_{a})\hat{\delta}^{-10}); \qquad \sum_{s} \frac{t_{s}}{\chi_{\delta}^{8}(d_{s})} = \sum_{x_{s}\in\hat{\mathcal{C}}_{a}} \frac{t_{s}}{d_{s}^{8}} + \overline{O}((1-T_{a})\hat{\delta}^{-8}) \quad \text{in } \hat{\mathcal{C}}_{a}.$$

Here we have used the symbol \overline{O} to denote a quantity such that

$$\overline{O}(t) \ge C^{-1}t,$$

where C is large but fixed positive constant (independent of λ and $\{x_i\}_i$).

To estimate the last term in (81), we use geodesic coordinates centered at some point $y_a \in \hat{\mathcal{C}}_a$. With an abuse of notation, we identify the points in \mathcal{C}_a with their pre-image under the exponential map. Using these coordinates, we find

$$\nabla (d_i(y))^2 = 2(y - x_i) + o_{\delta}(1)|y - x_i|, \quad \text{for } y \in \hat{\mathcal{C}}_a, \text{ and for } x_i \in \mathcal{C}_a,$$

which implies

(88)

$$\frac{\nabla(\chi_{\delta}^{2}(d_{i})) \cdot \nabla(\chi_{\delta}^{2}(d_{s}))}{\chi_{\delta}(d_{i})^{10}\chi_{\delta}(d_{s})^{10}} = 4\frac{(y-x_{i}) \cdot (y-x_{s})}{d_{i}^{10}d_{s}^{10}} + o_{\delta}(1)\frac{1}{d_{i}^{9}d_{s}^{9}}; \quad \text{for } y \in \hat{\mathcal{C}}_{a} \text{ and for } x_{i}, x_{s} \in \mathcal{C}_{a}.$$

In particular, for $y \in \hat{\mathcal{C}}_a$, we get

$$\begin{split} \sum_{i,s=1}^{k} t_{i}t_{s} \frac{\nabla(\chi_{\delta}^{2}(d_{i})) \cdot \nabla(\chi_{\delta}^{2}(d_{s}))}{\chi_{\delta}(d_{i})^{10}\chi_{\delta}(d_{s})^{10}} &= 4 \sum_{x_{i},x_{s} \in \mathcal{C}_{a}} t_{i}t_{s} \frac{(y-x_{i}) \cdot (y-x_{s})}{d_{i}^{10}d_{s}^{10}} + o_{\delta}(1) \sum_{x_{i},x_{s} \in \mathcal{C}_{a}} \frac{t_{i}t_{s}}{d_{i}^{9}d_{s}^{9}} \\ &+ O((1-T_{a})\hat{\delta}^{-9}) \sum_{x_{i} \in \mathcal{C}_{a}} \frac{t_{i}}{d_{i}^{9}} + O((1-T_{a})^{2}\hat{\delta}^{-18}). \end{split}$$

We have also (still for $y \in \hat{\mathcal{C}}_a$)

$$(89) \quad \sum_{i,s=1}^{k} t_i t_s \frac{|\nabla(\chi_{\delta}^2(d_i))| |\nabla(\chi_{\delta}^2(d_s))|}{\chi_{\delta}(d_i)^{10} \chi_{\delta}(d_s)^{10}} \le 4 \sum_{x_i, x_s \in \mathcal{C}_a} t_i t_s \frac{(y-x_i) \cdot (y-x_s)}{d_i^{10} d_s^{10}} + o_{\delta}(1) \sum_{x_i, x_s \in \mathcal{C}_a} \frac{t_i t_s}{d_i^{9} d_s^{9}}.$$

Hence from (81), (87), (88) and (89) we deduce (we are still working in the above coordinates)

$$\begin{split} \Delta \varphi_{\lambda,\sigma}(y) &= 12(1+o_{\delta,\Theta}(1)) \frac{\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^{10}} + O((1-T_a)\hat{\delta}^{-10})}{\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^8} + \overline{O}((1-T_a)\hat{\delta}^{-8})} \\ &- 16(1+o_{\delta,\Theta}(1)) \frac{\left|\sum_{x_i \in \mathcal{C}_a} \frac{t_i(y-x_i)}{d_i^{10}}\right|^2 + o_{\delta}(1) \left|\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^9}\right|^2}{\left[\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^8} + \overline{O}((1-T_a)\hat{\delta}^{-8})\right]^2} \\ &+ \frac{O((1-T_a)\hat{\delta}^{-9}) \sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^9} + O((1-T_a)\hat{\delta}^{-18})}{\left[\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^8} + \overline{O}((1-T_a)\hat{\delta}^{-8})\right]^2}; \qquad y \in \hat{\mathcal{C}}_a \end{split}$$

Using the inequality $ab \leq \varepsilon a^2 + C_{\varepsilon}b^2$ we then find

$$\Delta \varphi_{\lambda,\sigma}(y) = (1+o_{\delta,\Theta}(1)) \left[12 \frac{\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^{10}}}{\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^{2}} + \overline{O}((1-T_a)\hat{\delta}^{-8})} - 16 \frac{\left|\sum_{x_i \in \mathcal{C}_a} \frac{t_i(y-x_i)}{d_i^{10}}\right|^2}{\left[\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^{8}} + \overline{O}((1-T_a)\hat{\delta}^{-8})\right]^2} \right]$$

$$(90) + \frac{(o_{\delta}(1) + O(\varepsilon)) \left|\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^{9}}\right|^2}{\left[\sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^{8}} + \overline{O}((1-T_a)\hat{\delta}^{-8})\right]^2} + O(\mathcal{C}_{\varepsilon} + 1)(1-T_a)^2\hat{\delta}^{-2}; \qquad y \in \hat{\mathcal{C}}_a.$$

Now, given a large and fixed constant \overline{C} , we define the set $\mathcal{B}_a^{\overline{C}}$ by

$$\mathcal{B}_{a}^{\overline{C}} = \left\{ y \in \hat{\mathcal{C}}_{a} \cap M_{\sigma,\Theta} : \text{ if } x_{i} \in \mathcal{C}_{a} \quad \Rightarrow \quad d_{i}(y) \leq \left(1 + \frac{1}{\overline{C}}\right) dist(y,\mathcal{C}_{a}) \text{ or } d_{i}(y) \geq \overline{C}dist(y,\mathcal{C}_{a}) \right\}.$$

We start by characterizing the points belonging to the complement of $\mathcal{B}_{a}^{\overline{C}}$ in $M_{\sigma,\Theta} \cap \hat{\mathcal{C}}_{a}$. By definition, we have

(91)
$$y \in \left(M_{\sigma,\Theta} \cap \hat{\mathcal{C}}_a\right) \setminus \mathcal{B}_a^{\overline{C}} \Rightarrow \text{ there exists } x_i \in \mathcal{C}_a \text{ such that } d_i(y) \in \left(1 + \frac{1}{\overline{C}}, \overline{C}\right) dist(y, \mathcal{C}_a).$$

Given $y \in M_{\sigma,\Theta} \cap \hat{\mathcal{C}}_a$, we let $x_{\overline{i}}$ denote one of its closest points in \mathcal{C}_a , and we let $x_{\overline{j}}$ denote one of the closest points in \mathcal{C}_a to y, among those which do not realize the infimum of the distance from y. Then, since $dist(y, x_{\overline{i}}) < dist(y, x_{\overline{i}})$ and since $dist(y, x_{\overline{i}}) < \overline{C}dist(y, x_{\overline{i}})$ (by (91)), we clearly have

$$\frac{1}{\overline{C}} dist(y, x_{\overline{j}}) < dist(y, x_{\overline{i}}) < dist(y, x_{\overline{j}}),$$

namely y lies in an annulus centered at $x_{\overline{i}}$ whose radii have a ratio equal to \overline{C} .

Now, fixing $x_{\overline{i}} \in \mathcal{C}_a$, we consider the following set

$$\mathcal{D}_{\overline{i}} = \left\{ y \in \left(M_{\sigma,\Theta} \cap \hat{\mathcal{C}}_a \right) \setminus \mathcal{B}_a^{\overline{C}} : d_i(y) = dist(y,\mathcal{C}_a) \right\},\$$

namely the points y in $(M_{\sigma,\Theta} \cap \hat{\mathcal{C}}_a) \setminus \mathcal{B}_a^{\overline{C}}$ for which $x_{\overline{i}}$ is the closest point to y in \mathcal{C}_a . Now, letting y vary, there might be different points $x_{\overline{j}}$, chosen as before, which do not realize the distance from y, but anyway their number never exceeds k. This implies that $\mathcal{D}_{\overline{i}}$ is contained in the union of at most k annuli with fixed relative ratios centered at $x_{\overline{i}}$, namely

(92)
$$\mathcal{D}_{\overline{i}} \subseteq \bigcup_{l=1}^{k} \left(B_{d_{l,\overline{i}}}(x_{\overline{i}}) \setminus B_{c_{l,\overline{i}}}(x_{\overline{i}}) \right), \quad \text{with } d_{l,\overline{i}} \leq 2\overline{C}c_{l,\overline{i}}.$$

Clearly we also have

(93)
$$\left(M_{\sigma,\Theta} \cap \hat{\mathcal{C}}_a\right) \setminus \mathcal{B}_a^{\overline{C}} = \cup_{x_{\overline{i}} \in \mathcal{C}_a} \mathcal{D}_{\overline{i}}$$

In $\mathcal{D}_{\overline{i}}$ there holds

$$\frac{t_i}{d_i^{10}} \le \frac{1}{d_{\bar{i}}^2} \frac{t_i}{d_i^8}; \qquad \qquad \left| \sum_{x_i \in \mathcal{C}_a} \frac{t_i(y - x_i)}{d_i^{10}} \right| \le \frac{1}{d_{\bar{i}}} \sum_{x_i \in \mathcal{C}_a} \frac{t_i}{d_i^8}.$$

Then from (90) it follows that

(94)
$$|\Delta \varphi_{\lambda,\sigma}| \le C_{\delta,\Theta,\varepsilon} \left(1 + \frac{1}{d_{\tilde{i}}^2} \right), \qquad \text{in } \mathcal{D}_{\tilde{i}}$$

Hence, from (92) and (93) we deduce that

$$(95) \qquad \int_{(M_{\sigma,\Theta}\cap\hat{\mathcal{C}}_{a})\setminus\mathcal{B}_{a}^{\overline{C}}} (\Delta\varphi_{\lambda,\sigma})^{2} dV_{g} \leq \cup_{x_{\overline{i}}\in\mathcal{C}_{a}} \cup_{l=1}^{k} \int_{B_{d_{l,\overline{i}}}(x_{\overline{i}})\setminus B_{c_{l,\overline{i}}}(x_{\overline{i}})} C_{\delta,\Theta,\varepsilon} \left(1+\frac{1}{d_{\overline{i}}^{2}}\right)^{2} dV_{g}$$
$$\leq C_{\delta,\Theta,\varepsilon} k \ card(\mathcal{C}_{a}) \left(\log\frac{d_{l,\overline{i}}}{c_{l,\overline{i}}}+1\right) \leq C_{\delta,\Theta,\varepsilon,\overline{C}}.$$

At this point, to estimate $\int_{M} (\Delta \varphi_{\lambda,\sigma})^2 dV_g$, it only remains to consider the contribution inside $\mathcal{B}_a^{\overline{C}}$. In this set, we call $d_{a,min}$ the distance of y from \mathcal{C}_a , and $d_{a,out}$ the minimal distance of y from the points x_i in \mathcal{C}_a satisfying $d_i(y) \geq \overline{C}dist(y, \mathcal{C}_a)$ (see the definition of $\mathcal{B}_a^{\overline{C}}$). Therefore, setting

$$T_{a,in} = \sum_{x_i \in \mathcal{C}_a \ : \ d_i(y) \leq \left(1 + \frac{1}{\overline{c}}, \overline{c}\right) dist(y, \mathcal{C}_a)} t_i$$

from (90) we obtain the estimate

$$\begin{split} \Delta\varphi_{\lambda,x}(y) &= 12(1+o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \frac{\frac{T_{a,in}}{d_{a,min}^{10}} + \frac{O(T_a - T_{a,in})}{d_{a,out}^{10}}}{\frac{T_{a,in}}{d_{a,min}^8} + \frac{\overline{O}(T_a - T_{a,in})}{d_{a,out}^8} + \overline{O}((1-T_a)\hat{\delta}^{-8})} \\ &- 16(1+o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \frac{\left|\frac{T_{a,in}}{d_{a,min}^9} + \frac{O(T_a - T_{a,in})}{d_{a,out}^9}\right|^2}{\left[\frac{T_{a,in}}{d_{a,min}^8} + \frac{\overline{O}(T_a - T_{a,in})}{d_{a,out}^8} + \overline{O}((1-T_a)\hat{\delta}^{-8})\right]^2} + C_{\delta,\Theta,\varepsilon,\overline{C}}. \end{split}$$

Now we notice that for $y \in \mathcal{B}_a^{\overline{C}}$ the following inequalities holds

$$\begin{aligned} \frac{T_{a,in}}{d_{a,min}^9} + \frac{O(T_a - T_{a,in})}{d_{a,out}^9} &\leq \left(C_{\delta,\Theta,\varepsilon,\overline{C}} + \frac{(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1))}{d_{a,min}}\right) \left(\frac{T_{a,in}}{d_{a,min}^8} + \frac{\overline{O}(T_a - T_{a,in})}{d_{a,out}^8}\right);\\ \frac{T_{a,in}}{d_{a,min}^{10}} + \frac{O(T_a - T_{a,in})}{d_{a,out}^1} &\leq \left(C_{\delta,\Theta,\varepsilon,\overline{C}} + \frac{(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1))}{d_{a,min}^2}\right) \left(\frac{T_{a,in}}{d_{a,min}^8} + \frac{\overline{O}(T_a - T_{a,in})}{d_{a,out}^8}\right);\\ \frac{T_{a,in}}{d_{a,min}^{10}} + \frac{O(T_a - T_{a,in})}{d_{a,out}^1} &\geq \left(-C_{\delta,\Theta,\varepsilon,\overline{C}} + \frac{(1 - o_{\delta,\Theta,\varepsilon,\overline{C}}(1))}{d_{a,min}^2}\right) \left(\frac{T_{a,in}}{d_{a,min}^8} + \frac{\overline{O}(T_a - T_{a,in})}{d_{a,out}^8}\right);\\ &= \log t \text{ four formulas and some elementary computations one can deduce that}.\end{aligned}$$

From the last four formulas and some elementary computations one can deduce that

(96)
$$|\Delta\varphi_{\lambda,\sigma}| \le C_{\delta,\Theta,\varepsilon,\overline{C}} + 4(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1))\frac{1}{d_{a,min}^2} \qquad \text{in } \mathcal{B}_a^{\overline{C}}$$

We notice that, trivially

$$\mathcal{B}_{a}^{\overline{C}} = \bigcup_{x_i \in \mathcal{C}_a} \left(\mathcal{B}_{a}^{\overline{C}} \cap \{ y : d_i(y) = d_{a,min} \} \right).$$

Therefore, recalling that $\frac{\Theta}{\lambda} \leq d_i(y) \leq \hat{\delta}$ for every $y \in \mathcal{B}_a^{\overline{C}}$, from the last two formulas it follows that (the volume of the three-sphere is $2\pi^2$)

$$\begin{aligned}
\int_{\mathcal{B}_{a}^{\overline{C}}} (\Delta \varphi_{\lambda,\sigma})^{2} dV_{g} &\leq \sum_{x_{i} \in \mathcal{C}_{a}} \int_{\mathcal{B}_{a}^{\overline{C}} \cap \{y : d_{i}(y) = d_{a,min}\}} \left(C_{\delta,\Theta,\varepsilon,\overline{C}} + 4(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \frac{1}{d_{a,min}^{2}} \right)^{2} dV_{g} \\
\end{aligned}$$

$$\begin{aligned}
(97) &\leq \sum_{x_{i} \in \mathcal{C}_{a}} \int_{B_{\delta}(x_{i}) \setminus B_{\frac{\Theta}{\lambda}}(x_{i})} \left(C_{\delta,\Theta,\varepsilon,\overline{C}} + 4(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \frac{1}{d_{a,min}^{2}} \right)^{2} dV_{g} \\
&\leq \operatorname{card}(\mathcal{C}_{a}) \left(32\pi^{2}(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \log \frac{\delta\lambda}{\Theta} + C_{\delta,\Theta,\varepsilon,\overline{C}} \right) \\
&\leq \operatorname{card}(\mathcal{C}_{a}) 32\pi^{2}(1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \log\lambda + C_{\delta,\Theta,\varepsilon,\overline{C}}.
\end{aligned}$$

From (76), (86), (95) and (97), considering all the sets $\hat{\mathcal{C}}_a$ and the complement of their union, we finally deduce

(98)
$$\int_{M} (\Delta \varphi_{\lambda,\sigma})^2 dV_g \leq 32\pi^2 k (1 + o_{\delta,\Theta,\varepsilon,\overline{C}}(1)) \log \lambda + C_{\hat{\delta},\varepsilon,\overline{C},\Theta},$$

which concludes the estimate of the term involving the squared laplacian.

Next, we estimate the term $\int_M |\nabla \varphi_{\lambda,\sigma}|^2 dV_g$. It could be possible to proceed using L^p estimates on $\varphi_{\lambda,\sigma} - \overline{\varphi_{\lambda,\sigma}}$ and interpolation, but having the computations for the laplacian at hand, it is convenient to work directly. From (74), one finds first the following pointwise estimate

$$|\nabla \varphi_{\lambda,\sigma}| \le \frac{C}{\lambda},$$

which implies, similarly as before

(99)
$$\int_{\bigcup_i B_{\frac{\Theta}{\lambda}}(x_i)} |\nabla \varphi_{\lambda,\sigma}|^2 dV_g \le C \frac{\Theta^4}{\lambda^2}$$

On the other hand, in the set $M_{\sigma,\Theta}$, using (78) and reasoning as above we obtain

$$\nabla \varphi_{\lambda,\sigma} = -(1+o_{\delta,\Theta}(1)) \frac{\sum_{i} t_i \frac{\nabla(\chi_{\delta}^2(d_i))}{\chi_{\delta}^{10}(d_i)}}{\sum_s \frac{t_s}{\chi_{\delta}^8(d_s)}} + o_{\delta,\Theta}(1) \frac{\sum_{i} t_i \frac{|\nabla(\chi_{\delta}^2(d_i))|}{\chi_{\delta}^{10}(d_i)}}{\sum_s \frac{t_s}{\chi_{\delta}^8(d_s)}}.$$

Taking the square we get

$$(100) \qquad |\nabla\varphi_{\lambda,\sigma}|^2 \leq (1+o_{\delta,\Theta}(1)) \frac{\sum_{i,s} t_i t_s \frac{\nabla(\chi_{\delta}^2(d_i)) \cdot \nabla(\chi_{\delta}^2(d_s))}{\chi_{\delta}^{10}(d_i)\chi_{\delta}^{10}(d_s)}}{\left[\sum_s \frac{t_s}{\chi_{\delta}^{8}(d_s)}\right]^2} + o_{\delta,\Theta}(1) \left(\frac{\sum_i t_i \frac{|\nabla(\chi_{\delta}^2(d_i))|}{\chi_{\delta}^{10}(d_i)}}{\sum_s \frac{t_s}{\chi_{\delta}^{8}(d_s)}}\right)^2.$$

Using (88) and (89) we deduce (working as before in geodesic coordinates)

$$\begin{aligned} \nabla \varphi_{\lambda,\sigma}|^{2}(y) &= 4(1+o_{\delta,\Theta,\varepsilon}(1)) \frac{\left|\sum_{x_{i}\in\mathcal{C}_{a}}\frac{t_{i}(y-x_{i})}{d_{i}^{10}}\right|^{2}+o_{\delta,\Theta,\varepsilon}(1)\left|\sum_{x_{i}\in\mathcal{C}_{a}}\frac{t_{i}}{d_{i}^{9}}\right|^{2}}{\left[\sum_{x_{i}\in\mathcal{C}_{a}}\frac{t_{i}}{d_{i}^{8}}+\overline{O}((1-T_{a})\hat{\delta}^{-8})\right]^{2}} \\ &+ \frac{C_{\delta,\Theta,\varepsilon}O((1-T_{a})^{2}\hat{\delta}^{-18})}{\left[\sum_{x_{i}\in\mathcal{C}_{a}}\frac{t_{i}}{d_{i}^{8}}+\overline{O}((1-T_{a})\hat{\delta}^{-8})\right]^{2}}, \qquad y\in\hat{\mathcal{C}}_{a}.\end{aligned}$$

Reasoning as for (94) and (96), one then finds

$$|\nabla \varphi_{\lambda,\sigma}|^2 \le C_{\delta,\Theta,\varepsilon,\overline{C}} \left(1 + \frac{1}{d_{a,min}^2} \right), \qquad \text{in } \hat{\mathcal{C}}_a \cap M_{\sigma,\Theta}.$$

It follows that

$$\int_{\hat{\mathcal{C}}_a} |\nabla \varphi_{\lambda,\sigma}|^2 dV_g \le C_{\delta,\Theta,\varepsilon,\overline{C}}.$$

On the other hand, we have also

$$|\nabla \varphi_{\lambda,\sigma}(y)|^2 \le C_{\hat{\delta}} \qquad \text{for } y \in M \setminus \cup_{a=1}^j \hat{\mathcal{C}}_a.$$

Therefore from the last two formulas we deduce

(101)
$$\int_{M} |\nabla \varphi_{\lambda,\sigma}|^2 dV_g \le \hat{C}_{\delta,\Theta,\varepsilon,\overline{C}}.$$

From (10) it follows that

$$\langle P_g \varphi_{\lambda,\sigma}, \varphi_{\lambda,\sigma} \rangle \leq \int_M (\Delta \varphi_{\lambda,\sigma})^2 dV_g + C \int_M |\nabla \varphi_{\lambda,\sigma}|^2 dV_g$$

Hence, from (98) and (101) we finally obtaib, fixing the values of the constants Θ, ε and \overline{C}

$$\int_{M} (P_g \varphi_{\lambda,\sigma}, \varphi_{\lambda,\sigma}) dV_g \le 32k\pi^2 (1 + o_{\delta}(1)) \log \lambda + C_{\delta}.$$

This concludes the proof. \blacksquare

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