# EXISTENCE OF SOLUTIONS IN A CONE FOR NONLINEAR ALTERNATIVE PROBLEMS 

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#### Abstract

Using the alternative method we present sufficient conditions for the existence of positive solutions to nonlinear equations at resonance and extend a well-known result of Cesari and Kannan.


Introduction. Cesari and Kannan [2] proved an abstract result in terms of the alternative method. Their result and some of its ramifications (see [1]) have been applied to a large class of problems at resonance to prove the existence of solutions.

Let $E$ be a Banach space. We say that $C$ is a cone in $E$ if $C$ is a nonempty, convex subset of $E$ such that $\lambda C \subset C$ for every $\lambda \geqslant 0$.

Here we prove the existence of solutions in a cone for equations at resonance of the form $L u=N u$, where $L$ is a linear operator and $N$ is a (nonlinear) operator. In the case when the cone is $E$, we obtain the well-known result of Cesari and Kannan [2].

In applications, for instance, if $L$ is an elliptic operator on a bounded domain $\Omega$ of $\mathbf{R}^{n}$, one usually takes $E$ as a subspace of $L^{2}(\Omega)$ and the cone $C=\{u \in E: u \geqslant 0$ a.e. in $\Omega\}$.

Also, our result is related to that of Gaines and Santanilla [3] concerning the existence of solutions in a convex set.

Main result. Let $E$ and $F$ be Banach spaces with norms $\left\|\|_{E}\right.$ and $\| \|_{F}$, respectively. Let $L: D(L) \subset E \rightarrow F$ be a linear operator and $N: E \rightarrow F$ a continuous (nonlinear) operator such that $N$ maps bounded sets into bounded sets. Assume that $C$ is a cone in $E$ and
(1) there exists a continuous map $\gamma: E \rightarrow C$ such that $\gamma(c)=c$ for every $c \in C$, and $\gamma$ maps bounded sets in $E$ into bounded sets in $E$.

In addition, suppose that $L$ is a Fredholm map of index 0 and there exist projections $P: E \rightarrow E, Q: F \rightarrow F$, and a linear map $H:(I-Q) F \rightarrow(I-P) E$

[^0]satisfying
\[

$$
\begin{array}{ll}
H(I-Q) L u=(I-P) u & \text { for every } u \in D(L) \\
Q L u=L P u & \text { for every } u \in D(L)  \tag{2}\\
L H(I-Q) N u=(I-Q) N u & \text { for every } u \in E
\end{array}
$$
\]

Thus, it is well known that $L u=N u$ is equivalent to the coupled system of equations

$$
\begin{array}{ll}
Q N u=0 & \text { (bifurcation equation) } \\
u=P u+H(I-Q) N u & \text { (auxiliary equation) }
\end{array}
$$

We can write the spaces $E$ and $F$ as the direct sums $E=E_{0} \oplus E_{1}, F=F_{0} \oplus F_{1}$, where $E_{0}=P E, E_{1}=(I-P) E, F_{0}=Q F$, and $F_{1}=(I-Q) F$. Also, we assume
(3) $E_{0}=\operatorname{Ker} L, F_{1}=\operatorname{Im} L, D(H)=\operatorname{Im} L$ and $\operatorname{Im} H=E_{1} \cap D(L)$.
(4) $\operatorname{dim} E_{0}=\operatorname{dim} F_{0}<+\infty$.
(5) $H$ is completely continuous.
(6) There exist continuous maps $B: E \times F \rightarrow \mathbf{R}$ and $J: F_{0} \rightarrow E_{0}$ such that $B$ is bilinear, $J$ is one-to-one and onto, and
(i) for $v_{0} \in F_{0}, v_{0}=0$ iff $B\left(u_{0}, v_{0}\right)=0$ for all $u_{0} \in E_{0}$,
(ii) $B\left(J v_{0}, v_{0}\right) \geqslant 0$ for every $v_{0} \in F_{0}$ and $B\left(J v_{0}, v_{0}\right)=0$ iff $v_{0}=0$,
(iii) $J v_{0}=0$ iff $v_{0}=0$,
(iv) $B\left(u_{0}, J^{-1} u_{0}\right)=0$ iff $u_{0}=0$,
(v) $B\left(u_{0}, v_{0}\right)=B\left(J v_{0}, J^{-1} u_{0}\right)$ for every $u_{0} \in E_{0}, v_{0} \in F_{0}$.

Remark. If $E \subset F$ and $F$ is a Hilbert space with inner product $\langle u, v\rangle$, then one can define $B\left(u_{0}, v_{0}\right)=\left\langle u_{0}, v_{0}\right\rangle$. Thus, if $F=L^{2}(\Omega)$,

$$
B\left(u_{0}, v_{0}\right)=\int_{\Omega} u_{0}(x) \cdot v_{0}(x) d x
$$

For $u \in E$ we write $u=u_{0}+u_{1}$, with $u_{0} \in E_{0}, u_{1} \in E_{1}$. With this, the auxiliary and bifurcation equations become $Q N\left(u_{0}+u_{1}\right)=0$ and $u_{1}=H(I-Q) N\left(u_{0}+u_{1}\right)$, respectively. We are now in a position to prove our result.

Theorem. Let conditions (1)-(6) hold. In addition, assume there exists
(7) $J_{0}>0$ such that $\|N u\| \leqslant J_{0}$ for every $u \in C$,
(8) $R_{0}>0$ such that $B\left(u_{0}, Q N(u)\right) \leqslant 0$ for every $u=u_{0}+u_{1} \in C$, with $\left\|u_{0}\right\|=R_{0}$ and $u_{1}=H(I-Q) N\left(u_{0}+u_{1}\right)$, and
(9) $r_{0} \geqslant\|H(I-Q)\| \cdot J_{0}$ such that $(P+J Q N) \gamma u \in C$ and $H(I-Q) N \gamma(u) \in C$ for every $u \in S$, where

$$
S=\left\{u=u_{0}+u_{1} \in E:\left\|u_{0}\right\| \leqslant R_{0},\left\|u_{1}\right\| \leqslant r_{0}\right\}
$$

Then $L u=N u$ has at least one solution $u \in S \cap C$.
Proof. The set $S$ is closed, bounded, and convex. Define the homotopy $T$ : $[0,1] \times S \rightarrow E$ by $T(\lambda, u)=\lambda P \gamma(u)+H(I-Q) N \gamma(u)+\lambda J Q N \gamma(u)$. Note that $T(\lambda, \cdot)$ is compact for every $\lambda \in[0,1]$ since $P$ and $Q$ are projections with finitedimensional range and $H$ is compact. For $\lambda=0, T(0, u)=H(I-Q) N \gamma(u) \in E_{1}$.

Thus, by (9),

$$
\|T(0, u)\| \leqslant\|H(I-Q)\| \cdot\|N \gamma(u)\|<r_{0}
$$

which shows that $T(0, \partial S) \subset S$.
We shall now prove that $T(\lambda, u) \neq u$ for every $(\lambda, u) \in[0,1) \times \partial S$. Indeed, let $T(\lambda, u)=u$ and, consequently,

$$
\begin{gather*}
u_{0}=\lambda P \gamma(u)+\lambda J Q N \gamma(u),  \tag{10}\\
u_{1}=H(I-Q) N \gamma(u) \tag{11}
\end{gather*}
$$

If $u \in \partial S$, then either $\left\|u_{1}\right\|=r_{0}$ or $\left\|u_{0}\right\|=R_{0}$. In the first case, using (11), we get

$$
r_{0}=\left\|u_{1}\right\|=\|H(I-Q) N \gamma(u)\|<r_{0}
$$

which is a contradiction.
In the second case, $\left\|u_{0}\right\|=R_{0}$. Hence, by (9), $(P+J Q N) \gamma(u) \in C$ and $u_{0} \in C$ since $C$ is a cone. Also by (9), $u_{1}=H(I-Q) N \gamma(u) \in C$ and, consequently, $u=u_{0}+u_{1} \in C$. This implies, by the property of $\gamma$, that $\gamma(u)=u$ and $u_{0}=\lambda P u+$ $\lambda J Q N u$. This last inequality is equivalent to $(1-\lambda) u_{0}=\lambda J Q N u$. We assume that $\lambda>0$ since $\lambda=0$ implies $(1-\lambda) u_{0}=0$ and $u_{0}=0$. Thus, by (8) and (11), $B\left(u_{0}, Q N \gamma(u)\right) \leqslant 0$. On the other hand,

$$
\lambda B\left(u_{0}, Q N u\right)=\lambda B\left(J Q N u, J^{-1} u_{0}\right)=B\left((1-\lambda) u_{0}, J^{-1} u_{0}\right)>0
$$

which is again a contradiction. Therefore, $T(\lambda, u) \neq u$ for every $(\lambda, u) \in[0,1) \times \partial S$, and we can conclude [ 4 , Theorem 4.4.11] that $T(1, \cdot)$ has a fixed point. Hence, there exists $u \in S$ satisfying

$$
u=P \gamma(u)+H(I-Q) N \gamma(u)+J Q N \gamma(u) .
$$

Reasoning as before, $u \in C$ and satisfies the auxiliary and bifurcation equations, that is, $u$ is a solution of $L u=N u$ such that $u \in S \cap C$. This completes the proof of the Theorem.

If $C=E$ we obtain the result of [2].
Corollary. Let conditions (1)-(6) hold. In addition, assume there exists
(7)' $J_{0}>0$ such that $\|N u\| \leqslant J_{0}$ for every $u \in E$,
(8)' $R_{0}>0$ such that $B\left(u_{0}, Q N u\right) \leqslant 0$ for every $u=u_{0}+u_{1} \in E$, with $\left\|u_{0}\right\|=R_{0}$ and $u_{1}=H(I-Q) N\left(u_{0}+u_{1}\right)$.

Then $L u=N u$ has at least one solution.
For some particular cases of our result and applications to nonlinear boundary value problems, see [5].

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