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Experimental prediction of the vibration response of panels under a turbulent boundary layer excitation from sensitivity functions

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Abstract

This study aims at validating an experimental method for characterizing the vibration behavior of panels excited by a turbulent boundary layer excitation as a possible alternative to standard means like wind-tunnels or *in situ* tests. The approach takes advantage of an explicit separation of the excitation contribution from the dynamic behavior of the panel. Based on the measurement of deterministic transfer functions on the panel, called 'sensitivity functions', which are then combined with either measurements or a model of the wall-pressure fluctuations induced by the turbulent boundary layer excitation, the vibration response under such an excitation can be retrieved. For validation purposes, the wall-pressure fluctuations of the turbulent flow generated in an anechoic wind tunnel are measured with a flush-mounted microphone array. The decay rates and the convection velocity which mainly characterize the excitation are extracted from these measurements. The plate velocity response to this excitation is estimated following the proposed method using the measured sensitivity functions and the model of Mellen fed with experimentally estimated decay rates and convection velocity. A comparison between a directly measured vibration autospectrum under the actual flow and the one predicted following the suggested method shows satisfactory agreement.

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1 I. INTRODUCTION

The experimental characterization of panels vibration under a turbulent boundary layer 2 (TBL) excitation is of great interest for the transport industry and for researchers studying 3 flow-induced vibration topics. Panel-like structures are mainly tested in wind tunnels or via 4 in situ measurements. These experimental methods are hard to control, costly and subjected 5 to variability between different laboratories and/or measuring techniques. Over the past 6 decades, studies have been carried out to experimentally synthesize the pressure field induced 7 by a TBL on a panel surface using an array of acoustic sources [1-3] and ultimately providing 8 improved methods to characterize the vibration behavior of a panel under this excitation. 9 However, these synthesis methods require a large number of sources (approximately 4 per 10 smallest wavelength) to reproduce the small correlation lengths of the surface pressure field 11 induced by the TBL, especially for subsonic velocities of the convected TBL. As frequency 12 increases, the number of reproduction sources thus becomes very large and then prohibitive. 13 A synthesis of the TBL excitation focussed on a subdomain of the simulation surface [4] 14 helps reaching higher frequencies while ensuring correct reproduction of the TBL excitation, 15 but limits the observation area to a fraction of the actual panel. Also, some of the proposed 16 methods [5, 6] are not able to accurately reproduce the TBL-induced wall-pressure field 17 outside the acoustic wavenumber domain, where the most energetic components of a subsonic 18 TBL are yet located and should be taken into account. 19

In this context, this study investigates an alternative approach to experimentally predict 20 the vibration response of panels under a TBL excitation by separating the contributions of 21 the forcing wall-pressure excitation from the vibration behavior of the panel. Indeed, the 22 mathematical formulation in the wavenumber domain of a panel vibration response when 23 submitted to random excitations allows estimating the system response at any point on 24 the structure from wall-pressure cross-spectral density (CSD) functions (characterizing the 25 excitation) and from so-called 'sensitivity functions'. The latter are defined as the panel 26 vibration response to wall-pressure acoustic plane waves and characterize the intrinsic vi-27 bration behavior of the panel. Since the contributions of the excitation and those from the 28 structural behavior are separated, the method can be fed with numerical and/or experimen-29 tal data either for the excitation or for the sensitivity functions. This allows performing fast 30 parametric studies by changing the properties of the panel or those of the excitation. 31

A method [7] has recently been proposed for estimating the sensitivity functions exper-32 imentally without having to excite the panel by sets of surface plane waves which is hard 33 to realize in practice. This alternative approach is based on the reciprocity principle, which 34 states that the sensitivity functions at any point on the structure are equivalent to the panel 35 velocity response expressed in the wavenumber domain when the system is excited by a nor-36 mal effort at the point of interest. Following this, the experimental process for estimating the 37 sensitivity functions consists in exciting the panel with a transverse force at the point where 38 the panel vibration response is to be determined. The spatial vibratory response of the panel 39 to this force is measured with a scanning laser vibrometer. In a subsequent post-processing 40 phase, a discrete 2-D wavenumber transform of the measured vibratory field normalized 41 by the input force is performed to deduce the sensitivity functions. Finally, by combining 42 the wall-pressure CSD function of the considered random excitation and the previously es-43 timated sensitivity functions, the response of the panel excited by the random excitation 44 can be deduced at the point of interest. This approach has been successfully applied in the 45 case of a panel excited by a diffuse acoustic field (DAF) [7]. In this particular case, the 46 wall-pressure field (WPF) is described in the wavenumber domain by components restricted 47 to the acoustic domain and the sensitivity functions of the panel have to be evaluated only 48 for wavenumbers of magnitude smaller than the acoustic wavenumber. 49

In principle, the method proposed in [7] for the case of a diffuse acoustic field excitation 50 can be applied for a panel excited by a spatially homogeneous stationary turbulent boundary 51 layer. However, from the authors' knowledge, this has never been assessed experimentally. 52 The work presented in this paper consists in applying and experimentally validating this 53 approach for such an excitation by comparison with direct vibration measurements in an 54 anechoic wind tunnel. This constitutes the main novelty of the paper. Even if the study 55 is limited to the vibration response of a panel to a turbulent boundary layer excitation, 56 its acoustic response (radiated pressure, acoustic intensity) could be further obtained by 57 exciting the panel with a monopole and a dipole source, as pointed out in [7]. In contrast 58 with the DAF, the WPF of a subsonic TBL excitation exhibits components located outside 59 the acoustic domain. The results of the method would therefore be sensitive to the accuracy 60 of the measured sensitivity functions for wavenumbers larger than the acoustic wavenumber. 61 A particular attention is therefore paid to the estimation of these sensitivity functions for a 62 set of wavenumbers adapted for dealing with TBL excitations. Moreover, unlike the DAF 63

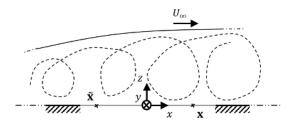
for which the theoretical CSD functions are well defined [8], various models of the TBL excitation [9, 10] exist but none of them is able to accurately describe the WPF induced by a TBL excitation on a large wavenumber range. These models are mostly semi-empirical and can thus be adjusted through parameters like decay rates and convective wavenumber. As there is no clear consensus in the literature regarding universal values for these parameters and/or the model to be used, the WPF of the excitation considered in this study has been measured and used to fit the model of Mellen [11].

The paper is organized as follows: the mathematical formulation of the vibration problem 71 is presented in Sec. II A, and the sensitivity functions involved in the problem are defined in 72 Sec. IIB based on the reciprocity principle. The proposed methodology for characterizing 73 the panel vibration response under a TBL is summarized in Sec. IIC. The characterization 74 of the WPF under the experimental TBL excitation is presented in Sec. III. In Sec. IV the 75 procedure is validated for an aluminum panel excited by a turbulent flow, based on measured 76 sensitivity functions and an adjusted model of the WPF. The measured sensitivity functions 77 are presented in Sec. IVB. Finally, the complete method is implemented to predict the 78 vibration response of the panel to the experimental TBL, which are compared to direct 79 measurements performed in an anechoic wind tunnel in Sec. IVC. 80

⁸¹ II. PROPOSED METHOD FOR ESTIMATING THE VIBRATION RESPONSE ⁸² OF PANELS UNDER A TURBULENT BOUNDARY LAYER EXCITATIONS

Let us consider a baffled panel of surface Σ_p with arbitrary boundary conditions. As illus-83 trated in Fig. 1, a fully developed TBL with a flow velocity U_{∞} outside the boundary layer 84 is supposed to excite the panel on one of its sides. This excitation is considered stationary 85 in time and spatially homogeneous. The plate and the boundary layer are supposed to be 86 weakly coupled; in other words, the vibration of the plate does not interfere with the WPF 87 and the forcing term is thus not modified by the panel vibration response. This assumption 88 is generally admitted when the panel displacements are much smaller than the characteristic 89 length scales of the flow [12]. The TBL excitation is then characterized by the WPF (*i.e.*, 90 lateral force) induced on a smooth rigid surface. We also define $\mathbf{x} = (x, y)$ an observation 91 point and $\tilde{\mathbf{x}} = (\tilde{x}, \tilde{y})$ an excitation point (where the surface pressure fluctuation induced by 92 the TBL is prescribed). Both points are defined in a Cartesian coordinate system (x, y, z)93

with the origin at the center of the panel, as shown in Fig. 1, and are located on the panel surface z = 0.



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FIG. 1. Illustration of a baffled panel (gray line) excited by a TBL and coordinate system.

To characterize the vibration response of the panel under this excitation, the one-sided normal vibration velocity spectrum $v(\mathbf{x}, f)$ at point \mathbf{x} is considered, where f is the frequency and is considered positive. As the excitation is random, this quantity is derived from the normal velocity auto-spectral density (ASD) function $G_{vv}(\mathbf{x}, f)$. An approach for evaluating this quantity based on deterministic transfer functions and making use of the reciprocity principle has been thoroughly presented in [7] and is briefly summarized in Secs. II A and II B.

104 A. Mathematical formulation of the vibration response

The one-sided frequency ASD function of the velocity $G_{vv}(\mathbf{x}, f)$ at point \mathbf{x} can be expressed as the following inverse space-wavenumber Fourier transform:

$$G_{vv}\left(\mathbf{x},f\right) = \frac{1}{4\pi^2} \iint_{-\infty}^{\infty} \left|H_v\left(\mathbf{x},\mathbf{k},f\right)\right|^2 G_{p_b p_b}\left(\mathbf{k},f\right) d\mathbf{k},\tag{1}$$

107 where

$$H_{v}(\mathbf{x}, \mathbf{k}, f) = \iint_{\Sigma_{p}} H_{v/F_{n}}(\mathbf{x}, \tilde{\mathbf{x}}, f) e^{-j\mathbf{k}\tilde{\mathbf{x}}} d\tilde{\mathbf{x}},$$
(2)

where $\mathbf{k} = (k_x, k_y)$ is the wavevector defined in the plane (x, y). The function $G_{p_b p_b}(\mathbf{k}, f)$ corresponds to the CSD function of the WPF on the excitation side (for instance a TBL excitation). The $H_v(\mathbf{x}, \mathbf{k}, f)$ function is called the sensitivity function [13] and characterize the vibration behavior of the panel. The term $H_{v/F_n}(\mathbf{x}, \mathbf{\tilde{x}}, f)$ corresponds to the transfer function between the panel velocity v at point \mathbf{x} and a normal point force F_n applied at point $\mathbf{\tilde{x}}$. According to Eq. (2), the sensitivity function can be interpreted as the vibration response of the panel at point \mathbf{x} due to a plane wave excitation with a wavevector $-\mathbf{k}$ (as illustrated in Fig. 2(a)).

Eq. (1) shows that the panel has a filtering effect on the excitation in the wavenumber space [12], which somehow limits the integration to a finite wavenumber domain $\Omega_{\mathbf{k}}$ while ensuring a correct estimation of the integral (see Sec. IV A). This filtering effect allows approximating the integral in Eq. (1) by performing a sum over an appropriately defined finite set of wavevectors $\mathbf{k} \in \Omega_{\mathbf{k}}$ (using the rectangular integration rule). The one-sided frequency ASD function of the velocity at point \mathbf{x} is thereby estimated with

$$G_{vv}\left(\mathbf{x},f\right) \approx \frac{1}{4\pi^2} \sum_{\mathbf{k}\in\Omega_{\mathbf{k}}} |H_v(\mathbf{x},\mathbf{k},f)|^2 G_{p_b p_b}\left(\mathbf{k},f\right) \delta \mathbf{k},\tag{3}$$

where $\delta \mathbf{k}$ represents the wavenumber resolution. To evaluate this quantity, the sensitivity functions H_v for wavenumbers belonging to $\Omega_{\mathbf{k}}$ have to be determined.

124 B. Sensitivity functions based on the reciprocity principle

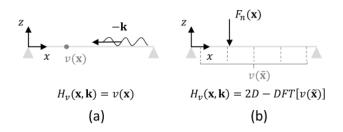
In its most general form, the reciprocity principle states that the response of a system is invariant with respect to the exchange of excitation and observation points [14]. For the particular case of a normal force applied at point $\tilde{\mathbf{x}}$ and normal velocity observed at point \mathbf{x} , the reciprocity relationship can be translated following the previous notations into [15]

$$H_{v/F_n}(\mathbf{x}, \tilde{\mathbf{x}}, f) = H_{v/F_n}(\tilde{\mathbf{x}}, \mathbf{x}, f),$$
(4)

Introducing Eq. (4) in Eq. (2) one obtains

$$H_{v}(\mathbf{x}, \mathbf{k}, f) = \iint_{\Sigma_{p}} H_{v/F_{n}}(\tilde{\mathbf{x}}, \mathbf{x}, f) e^{-j\mathbf{k}\tilde{\mathbf{x}}} d\tilde{\mathbf{x}}.$$
 (5)

The right hand side of Eq. (5) can be interpreted as the space-wavenumber transform of $H_{v/F_n}(\tilde{\mathbf{x}}, \mathbf{x}, f)$ with respect to the space variable $\tilde{\mathbf{x}}$. The points $\tilde{\mathbf{x}}$ become observation points on the panel surface Σ_p , which means that the space-wavenumber transform is performed over the vibration velocity field of the panel. To sum up, the sensitivity function $H_v(\mathbf{x}, \mathbf{k}, f)$ may be obtained by exciting the panel with a normal effort F_n at point \mathbf{x} and by calculating the space-wavenumber transform of the transfer function between the panel velocity at the ¹³⁶ observation points and the applied effort (as illustrated in Fig. 2(b)).



137

FIG. 2. Determination of the sensitivity functions H_v : (a) based on the direct interpretation, (b) using the reciprocity principle.

In practice, the vibration field has to be measured on a regular grid of points denoted 140 $\Gamma_{\tilde{\mathbf{x}}}$, using a scanning laser vibrometer for example. The space-wavenumber transform is 141 therefore approximated by a 2D discrete Fourier transform (2D-DFT). In order to avoid 142 aliasing effects, the spatial resolution $\delta \tilde{\mathbf{x}}$ over $\Gamma_{\tilde{\mathbf{x}}}$ should be determined so that the spatial 143 variations of the vibration field can be correctly represented by the grid of points. For a 144 homogeneous isotropic thin panel, $\delta \tilde{\mathbf{x}}$ should be less than or equal to a quarter of the natural 145 flexural wavelength of the panel λ_f at the highest frequency of interest (as considered in 146 [7]). According to [16], having four points per smallest flexural wavelength allows a non-147 biased estimation of the vibration field up to a frequency corresponding to two times this 148 flexural wavenumber. It ensures correct estimation of the sensitivity functions close the 149 flexural wavenumber (where vibratory levels are the largest) and avoids potential aliasing 150 effects. For a more complex panel, a preliminary study should be carried out to define this 151 parameter (for instance, by using a numerical model of the panel or by using a trial and 152 error procedure). 153

¹⁵⁴ C. Description of the proposed methodology

A methodology for experimentally estimating the vibration response of a panel excited by a TBL is derived from Eq. (3) and the sensitivity functions determined using the previously described reciprocity principle. The methodology for evaluating the velocity ASD function G_{vv} at a given point **x** of the panel (z = 0) can be summarized as follows:

- Excite the panel with a normal mechanical force at point \mathbf{x} and measure the normal velocity response of the panel at points $\mathbf{\tilde{x}} \in \Gamma_{\mathbf{\tilde{x}}}$ to determine $H_{v/F_n}(\mathbf{\tilde{x}}, \mathbf{x}, f)$, - Perform a 2D-DFT of the panel velocity response $H_{v/F_n}(\tilde{\mathbf{x}}, \mathbf{x}, f)$ (with respect to $\tilde{\mathbf{x}}$) to obtain the sensitivity functions $H_v(\mathbf{x}, \mathbf{k}, f)$ at point \mathbf{x} for $\mathbf{k} \in \Omega_{\mathbf{k}}$,

- Use Eq. (3) and an estimation of the CSD functions of the wall-pressure fluctuations $G_{p_bp_b}(\mathbf{k}, f)$ to estimate the velocity ASD function G_{vv} at point \mathbf{x} under the considered TBL excitation.

In the following, the vibration behavior of a thin isotropic homogeneous plate will be investigated. The proposed method is however valid for any panel having a linear mechanical behavior and, isotropic and homogeneous conditions are thus not mandatory.

169 III. CHARACTERIZATION OF THE EXCITATION

In addition to the knowledge of the vibration behavior of the panel through the sensitivity 170 functions, solving Eq. (3) requires that CSD functions of the blocked wall-pressure of the 171 excitation are known. Over the past few years, numerous studies have shown that the 172 coherent power of the wall-pressure fluctuations induced by a TBL decays exponentially 173 with the increasing separation distances along flow and transverse directions [17]. It has 174 also been shown that the phase of the cross-spectrum is directly related to the convection 175 wavenumber $k_c = \omega/U_c$, where ω is the angular frequency and U_c is the convection speed 176 (usually defined as a constant fraction of the free flow velocity U_{∞}). These dependencies are 177 included in most of the semi-empirical models [9, 10] aiming at predicting the CSD functions 178 of the wall-pressure fluctuations. 179

In order to validate the proposed methodology in comparison to actual measurements of the panel response in an anechoic wind tunnel, the wall-pressure fluctuations induced by a subsonic turbulent flow generated in a low-speed anechoic wind tunnel have been measured on the considered frequency range in this study ([170, 2000 Hz], see Sec. IV). These measurements will then be used to fit the model of Mellen in Sec. III B.

185 A. Spiral-shaped surface microphone array

The wall-pressure fluctuations have been measured at two flow velocities: $U_{\infty} = 20 \text{ m.s}^{-1}$ and $U_{\infty} = 40 \text{ m.s}^{-1}$ using the spiral-shaped rotating microphone array introduced by Robin *et al.* [18]. The array is composed of 61 microphones of three different types in order to reach the desired microphone density and to tackle congestion issues at the center of the array. A deported B&K 4182 probe and three flush-mounted Knowles FG-23629-P16 microphones are used at the center of the array (as shown in Fig. 3(b)). The remaining part of the array consists of 57 quarter inch pinhole-mounted B&K 4957 microphones (for further details refer to [18]).

The pattern over which the 61 microphones are positioned (red markers in Fig. 3(a)) 195 has been designed so that each microphone has a different radial position with a radial 196 separation of 2 mm. Measurements following 180 consecutive rotations allow reaching an 197 angular resolution of 2° and thereby reconstructing a high density microphone array at a 198 post-processing step (as illustrated in Fig. 3(a)). Under the assumption of a stationary 199 and homogeneous turbulent WPF, the translation or rotation of an array with at least one 200 reference sensor has proven to be a solution to obtain the needed compromise between a 201 small sensor diameter (to avoid spatial averaging) and small sensor spacing (to gain high 202 spatial resolution) [18] [19]. Since the central microphone position is the only invariant one, 203 it is used as a reference in the calculations of wall-pressure CSD functions. 204

An amplitude calibration of the microphone array was performed by placing a Larson 205 Davis CAL200 calibrator over each microphone separately and by exciting it with a sine wave 206 of 94 dB SPL at 1000 Hz. Since the B&K 4182 probe is deported from the microphone array 207 surface by approximately 4 cm, an additional phase calibration was necessary. To do so, the 208 calibrator was positioned over the three microphones at the center of the array (the B&K 209 4182 probe and the two closest Knowles microphones). A simultaneously triggered acoustic 210 pressure signal at 1000 Hz was extracted for each microphone. The time offset between the 211 signal measured by the deported probe and the signal measured by the two adjacent Knowles 212 microphones (both signals were identical) was compensated in all resulting measurements. 213 Once the signals are expressed in the frequency domain, as a time offset has been applied, 214 the phase calibration was effective regardless of the frequency. 215

B. Measurement of the wall-pressure fluctuations and adjusted model of Mellen

The considered TBL-like excitation is reproduced in a low-speed anechoic wind tunnel. The installation consists in a closed-loop wind tunnel powered by two rotating fans. The

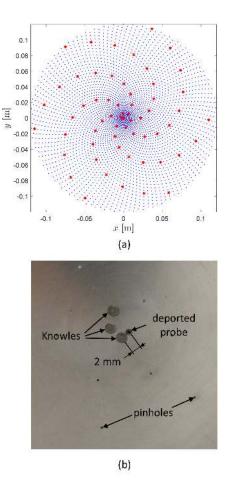
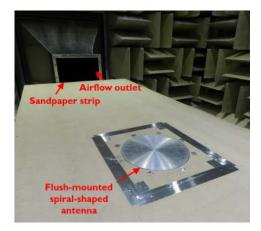


FIG. 3. (Color online) (a) Microphone positions (red markers) and illustration of a reconstructed grid (blue dots). (b) Close-up view of the mounted sensors and pinholes on measurement side.

air flow is directed to the anechoic chamber through a vent pipe containing a screen to 219 homogenize the flow. A convergent is mounted at the end of the vent pipe inside the 220 anechoic chamber which allows reaching higher flow velocities (up to Mach ≤ 0.12). An 221 $1.22 \times 2.44 \text{ m}^2$ plywood panel of 0.019 m thickness was mounted in the anechoic wind tunnel 222 at the end of the convergent and to help the TBL develop, a sandpaper strip was glued at 223 the end of the convergent (as shown in Fig. 4). The spiral-shaped array was flush-mounted 224 1.8 m away from the convergent and 30 seconds acquisitions were performed with a sampling 225 frequency of 8192 Hz. Time signals of the wall-pressure fluctuations were extracted for all 226 microphones and all 180 rotations. 227

The reconstructed microphone measurement grid theoretically allows reaching a maximum wavenumber of 1570 m⁻¹, which is sufficient to capture the convective contributions over the whole frequency range and for both considered flow velocities (at 2000 Hz and for $U_{\infty} = 20 \text{ m.s}^{-1}$, the convective wavenumber k_c equals 838 m⁻¹ with $U_c = 0.75 \times U_{\infty}$).



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FIG. 4. (Color online) Measurement of the wall-pressure fluctuations using the spiral-shaped surface microphone array flush-mounted in the wind tunnel.

The spatial CSD functions of the wall-pressure fluctuations $G_{p_b p_b}(\xi_x, \xi_y, f)$ were estimated 235 as a function of the spatial separations (ξ_x, ξ_y) in both x and y directions using the "cpsd" 236 MATLAB command with a fixed reference point at the center of the array (x = 0, y = 0). 237 For the remainder of this paper, the "cpsd" MATLAB command was defined with a Hanning 238 window applied to time signals and with a 50% overlap. Two approaches were investigated 239 to post-process the spatial CSD functions. The first consists in performing a 2D-DFT on 240 $G_{p_b p_b}(\xi_x, \xi_y, f)$ in order to directly estimate the blocked wall-pressure CSD functions in the 241 wavenumber domain [19]. However, the finite dimensions of the microphone array result 242 in unrealistic predictions in the low-wavenumber domain. As the low-wavenumber domain 243 mainly dictates the response of the panel to a TBL excitation (see Sec. IVA), it has to be 244 accurately estimated. Deconvolution methods can be used to compensate for this windowing 245 effect, but they require significant and prohibitive computation time [20]. 246

With this in mind and for computation time to be reasonable, the measurements were fitted to the model of Mellen [11] in the spatial domain

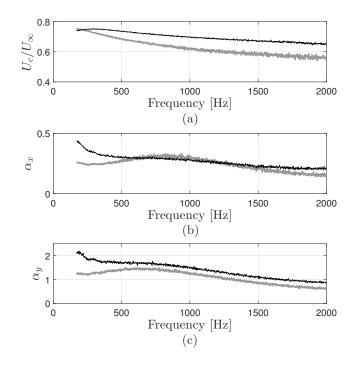
$$G_{p_b p_b}(\xi_x, \xi_y, f) = G_{p_b p_b}(f) e^{-\sqrt{(\alpha_x k_c \xi_x)^2 + (\alpha_y k_c \xi_y)^2}} e^{jk_c \xi_x},$$
(6)

where $G_{p_bp_b}(f)$ is the measured blocked wall-pressure ASD function, (α_x, α_y) are the exponential decay rates along x and y directions and k_c is the convective wavenumber. Performing a space-wavenumber transform of Eq. (6) yields an expression of blocked wall-pressure CSD functions in the wavenumber domain [11]

$$G_{p_b p_b}(\mathbf{k}, f) = G_{p_b p_b}(f) \frac{2\pi \left(\alpha_x \alpha_y k_c^2\right)^2}{\left[\left(\alpha_x \alpha_y k_c^2\right)^2 + \left(\alpha_x k_c k_y\right)^2 + \left(\alpha_y k_c\right)^2 \left(k_c - k_x\right)^2\right]^{3/2}}.$$
 (7)

The model of Mellen has been chosen because, like the Corcos model, it can easily be adjusted by estimating α_x , α_y and k_c which is directly related to the convection speed U_c . Also, the convective peak in the model of Mellen expressed in the wavenumber domain has an oval shape which is in better accordance with the measurements, as opposed to the model of Corcos which has a diamond-like shape [9].

In order to estimate the decay rates (α_x, α_y) and convective wavenumber k_c , the considered model has been fitted to measurements by solving Eq. (6) following the least squares method using the "lsqcurvefit" MATLAB command. First the decay rates have been estimated by solving Eq. (6) while considering the modulus of all the terms in this equation. In a second step, Eq. (6) has been solved by implementing the previously determined decay rates and while considering all terms as complex values to extract U_c . The extracted parameters are presented in Fig. 5 for the two considered flow velocities.



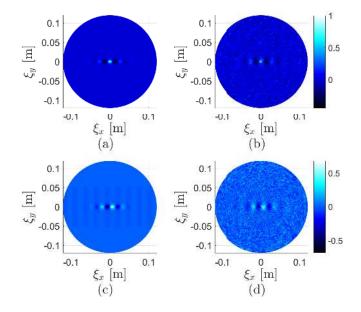
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FIG. 5. TBL parameters extracted from measurements at $U_{\infty} = 20 \text{ m.s}^{-1}$ (bold gray line) and at $U_{\infty} = 40 \text{ m.s}^{-1}$ (light black line) based on the model of Mellen. (a) Convection speed normalized by the flow velocity. (b) Streamwise exponential decay rate α_x . (c) Spanwise exponential decay rate α_y .

The convection speed normalized by the flow velocity is presented in Fig. 5(a). As already observed in the literature [19, 22, 23], the convection speed normalized by the flow velocity decreases with the increasing frequency and has values in the range [0.55 - 0.75].

The exponential decay rates estimated along x and y directions are shown in Figs. 5(b) and 5(c) respectively. For the two considered flow velocities, the values of decay rates are generally larger than those commonly found in the literature for both Corcos and Mellen models (*i.e.*, $\alpha_x = 0.116$ and $\alpha_y = 0.7$ [23]). Like for the convection speed, these estimated decay rates are implemented in the model of Mellen as functions of the frequency.

Finally, the real and imaginary parts of the spatial CSD functions of the blocked wallpressure obtained by fitting the model of Mellen are compared to those derived from measurements with the microphone array in Figs. 6 and 7 for flow velocities of $U_{\infty} = 20 \text{ m.s}^{-1}$ and $U_{\infty} = 40 \text{ m.s}^{-1}$, respectively and at a frequency of 500 Hz.



282

FIG. 6. (Color online) Spatial CSD function of the blocked wall-pressure normalized by the autospectrum at the center of the array $G_{p_bp_b}(\xi_x,\xi_y,f)/G_{p_bp_b}(f)$ at 500 Hz and at a flow velocity $U_{\infty} = 20 \text{ m.s}^{-1}$. (a) Mellen model, real part. (b) Direct measurement, real part. (c) Mellen model, imaginary part. (d) Direct measurement, imaginary part.

Numerically, it has been observed that to correctly estimate the CSD functions of the WPF beneath a TBL, a large number of realizations has to be considered [24]. From an experimental point of view, this can be directly related to the time of acquisition required to average the random process. Since the time required to measure the TBL fluctuations at successive rotated positions of the antenna was already significant (30 seconds per each

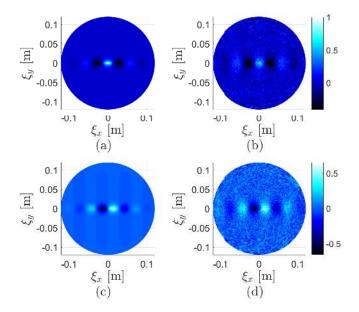


FIG. 7. (Color online) Spatial CSD function of the blocked wall-pressure normalized by the autospectrum at the center of the array $G_{p_bp_b}(\xi_x, \xi_y, f)/G_{p_bp_b}(f)$ at 500 Hz and at a flow velocity $U_{\infty} = 40 \text{ m.s}^{-1}$. (a) Mellen model, real part. (b) Direct measurement, real part. (c) Mellen model, imaginary part. (d) Direct measurement, imaginary part.

²⁹² consecutive 180 rotations), no attempt was made to increase the acquisition time. However,
²⁹³ using a fitted model tends to eliminate measurement noise while ensuring a satisfactory
²⁹⁴ estimation of the wall-pressure fluctuations.

The adjusted model of Mellen is in good agreement with the measurement at both considered flow velocities, which suggests that the proposed method to fit measurements to a model is accurate. It also shows that the extracted parameters can be implemented in the model of Mellen expressed in the wavenumber domain (see Eq. (7)) to apply the proposed methodology for predicting the vibration response of the plate. However, the model of Mellen also needs to define the wall-pressure ASD function $G_{p_bp_b}(f)$ which is the object of the next paragraph.

Under the assumption of a spatially homogeneous TBL, the auto-spectrum of the wallpressure should be invariant with the observation point. In reality, our measurement results indicate that the auto-spectrum varies (essentially in the streamwise direction). In the proposed approach the wall-pressure auto-spectrum should be estimated at the point of interest \mathbf{x} where the plate response is to be obtained. This information could not be retrieved from this experiment because response point \mathbf{x} considered in Sec. IV was slightly outside and downstream the area covered by the microphone array. The auto-spectra at each micro-

phones have been estimated using the "cpsd" MATLAB command and their mean value 309 was finally considered for $G_{p_b p_b}(f)$ in Eq. (3) in the remainder of this work. It is therefore 310 assumed that the spatially averaged ASD function of the blocked wall-pressure $\langle G_{p_b p_b}(f) \rangle$ 311 provides an acceptable estimation of the auto-spectrum at all points sufficiently close to the 312 spiral-shaped array. The spatially averaged ASD function of the blocked wall-pressure is 313 presented in Fig. 8 at both considered flow velocities. The trends of the two curves are quite 314 identical. The increase of flow speed results in a nearly constant shift of the auto-spectrum 315 level. The results presented in Figs. 5 and 8 fully describe the parameters used in the model 316 of Mellen which will be considered in Sec. IV C. 317

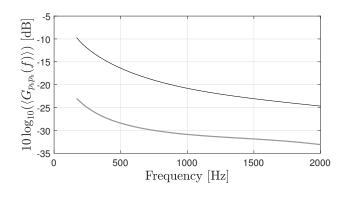


FIG. 8. Spatially averaged ASD function of the blocked wall-pressure $\langle G_{p_bp_b}(f) \rangle$ (dB, ref. 1 Pa².Hz⁻¹) at a flow velocity $U_{\infty} = 20 \text{ m.s}^{-1}$ (bold gray line) and $U_{\infty} = 40 \text{ m.s}^{-1}$ (light black line).

322 IV. VALIDATION OF THE PROPOSED METHODOLOGY

A. Test case description

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For experimental validation purposes an academic test case was considered, which consists in a baffled rectangular thin aluminum plate with simply supported boundary conditions on all edges. This baffled plate is submitted to a subsonic TBL air flow on one side. The plate's geometrical and mechanical properties are detailed in Table I. Simply-supported boundary conditions have been chosen because they lead to a simple analytical solution of the plate sensitivity functions. The experimental fabrication method proposed by Robin et al. [21] has been used to setup panels with representative simply supported boundary conditions. The considered frequency range is [170, 2000] Hz and the modal structural loss factors η_{mn} have been experimentally estimated using the -3 dB bandwidth method at all resonance peaks in the considered frequency range. They are taken into account in the numerical simulations and given in Table II with their corresponding resonance frequencies for the first eight resonance peaks.

In this work, the methodology described in Sec. II C was implemented at a given, arbitrary position \mathbf{x} of coordinates (x = 0.18 m, y = 0.09 m, z = 0 m) on the plate. Therefore, the quantities of interest are the sensitivity functions H_v at point \mathbf{x} and the ASD function of the vibration velocity $G_{vv}(\mathbf{x}, f)$ at point \mathbf{x} when the plate is excited by the TBL.

Like in the previous section, two flow velocities are considered: $U_{\infty} = 20 \text{ m.s}^{-1}$ and $U_{\infty} = 40 \text{ m.s}^{-1}$. The frequency range is well above the aerodynamic coincidence frequency f_c defined as the frequency at which the flexural wavenumber k_f equals the convective wavenumber k_c . These two wavenumbers are defined by:

$$k_f = \sqrt{\omega} \sqrt[4]{\frac{\rho h}{D}} \tag{8}$$

where $D = \frac{Eh^3}{12(1-\nu^2)}$ is the flexural rigidity and,

$$k_c = \frac{\omega}{U_c},\tag{9}$$

where U_c is the convection speed which has been extracted from measurements of the wallpressure fluctuations in Sec. IIIB. The aerodynamic coincidence frequency can thus be expressed as follows

$$f_c = \frac{U_c^2}{2\pi} \sqrt{\frac{\rho h}{D}}.$$
(10)

In the considered case, $f_c = 7.5 \text{ Hz at } U_{\infty} = 20 \text{ m.s}^{-1} \text{ and } f_c = 30 \text{ Hz at } U_{\infty} = 40 \text{ m.s}^{-1}$. It is 348 clear from Eq. (1) that the plate filters out the excitation and this filtering effect gets effective 349 above f_c , in which case $k_c > k_f$. To illustrate this effect, the theoretical squared absolute 350 value of the sensitivity functions have been plotted in Fig. 9(a) at point x, as a function of 351 k_x ($k_y = 0$) and as a function of the frequency (see [7] for details on the numerical model). 352 The strongly decreasing magnitude of $|H_v(\mathbf{x}, k_x, f)|^2$ above the flexural wavenumber can be 353 noticed. Similarly, the CSD function of the wall-pressure fluctuations according to the fitted 354 model of Mellen is plotted in Fig. 9(b) while considering the previously obtained decay rates 355

and convection speed at a flow velocity of $U_{\infty} = 40 \text{ m.s}^{-1}$. Strong contributions around 356 the convective wavenumber k_c can be noticed. Fig. 9(c) shows the product of the squared 357 absolute value of the sensitivity functions and the wall-pressure CSD functions (which is 358 directly involved in the ASD function of the plate velocity), normalized by the maximum 359 value at each frequency. Components are considered filtered out in the (k_x, k_y) space when 360 their magnitude is smaller than the maximum value at the corresponding frequency minus 361 10 dB. In this particular case, the convective wavenumber components centered on k_c are 362 entirely filtered out on the whole considered frequency range and the vibration response 363 of the plate to the experimental TBL is mainly driven by the region inside and close to 364 the circle of radius k_f , the flexural wavenumber. It should be noted that in this work the 365 excitation is a low-speed subsonic TBL. The higher the flow velocity, the lower the slope of 366 the curve $k_c(f)$ and therefore, the less the plate filtering effect is effective. 367

In order to fully characterize the filtering effect of the plate, this study has been performed 368 in both x and y directions and for both considered flow velocities. It allowed retrieving the 369 maximum wavenumbers that need to be considered in Eq. (3) while ensuring a correct 370 estimation of the response of the plate to the experimental TBL. Based on this numerical 371 study and for the considered test case, the wavenumber domain $\Omega_{\mathbf{k}}$ over which Eq. (3) is 372 calculated is limited to wavenumbers $|k_x| \leq 55 \text{ m}^{-1}$ and $|k_y| \leq 55 \text{ m}^{-1}$. These limits are 373 slightly above the flexural wavenumber at 2000 Hz ($k_f \approx 51 \text{ m}^{-1}$) which can be explained 374 by the fact that significant contributions remain slightly above the flexural wavenumber (see 375 Fig. 9(c)). 376

This study on the filtering effect of the plate shows that with an *a priori* knowledge on the 377 panel, the limits of the wavenumber domain involved in Eqs. (1) and (3) can be minimized 378 while ensuring a correct estimation of the response of the plate to a TBL excitation. From 379 a practical point of view, it allows optimizing the grid of points over which the vibration 380 response of the structure to a normal effort is to be estimated in order to determine the 381 sensitivity functions. For a more complex panel with unknown properties, it might be 382 necessary to extend the wavenumber domain as much as possible (define a refined mesh to 383 determine the sensitivity functions) to minimize errors linked to truncation effects in the 384 wavenumber domain. 385

To apply the methodology described in Sec. II C, the panel velocity field has to be measured on a grid of points $\Gamma_{\tilde{\mathbf{x}}}$. A uniform mesh of 37×27 points was considered in directions

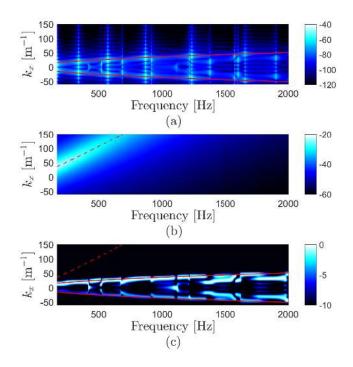


FIG. 9. (Color online) Illustration of the filtering effect of the plate. (a) Theoretical squared absolute value of the sensitivity functions $|H_v(\mathbf{x}, k_x, 0, f)|^2$ (dB, ref. 1 m.s⁻¹.Hz⁻¹). (b) Model of Mellen $G_{p_bp_b}(k_x, 0, f), U_{\infty} = 40 \text{ m.s}^{-1}$ (dB, ref. 1 Pa².Hz⁻¹). (c) Product $|H_v(\mathbf{x}, k_x, 0, f)|^2 \times G_{p_bp_b}(k_x, 0, f)$ (dB, ref. 1 Pa²m².s⁻².Hz⁻¹) normalized by the maximum value at each frequency. Continuous line: flexural wavenumber k_f according to Eq. (8). Dashed line: convective wavenumber k_c according to Eq. (9).

³⁸⁸ x and y respectively and a gap of 1 cm along the edges was left for practical reasons. This ³⁸⁹ leads to spatial separations of $\delta_x \simeq 1.3$ cm and $\delta_y \simeq 1.6$ cm. These separations are well ³⁹⁰ above the criterion of 4 points per flexural wavelength for all frequencies of interest. The ³⁹¹ density of points has voluntarily been set to reach wavenumbers higher than the flexural ³⁹² wavenumber in order to experimentally validate the filtering effect of the plate.

Based on this grid of points, the highest wavenumbers k_x^{max} and k_y^{max} that can be resolved in directions x and y, respectively, are given by

$$k_x^{max} = \frac{\pi}{\delta_x} \simeq 246 \text{ m}^{-1} ; \ k_y^{max} = \frac{\pi}{\delta_y} \simeq 204 \text{ m}^{-1}.$$
 (11)

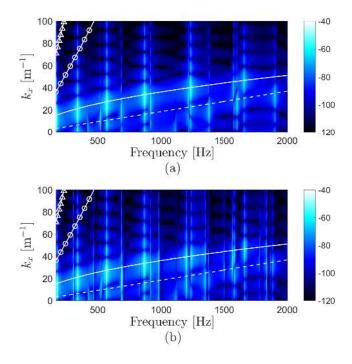
The chosen discretization prevents significant spatial aliasing and thereby ensures a correct estimation of the sensitivity functions on $\Omega_{\mathbf{k}}$. The wavenumber resolutions δk_x and δk_y in directions x and y respectively, are given by

$$\delta k_x = \frac{2\pi}{L_x} \simeq 13 \text{ m}^{-1} ; \ \delta k_y = \frac{2\pi}{L_y} \simeq 15 \text{ m}^{-1}.$$
 (12)

These wavenumber resolutions are relatively large because of the small dimensions of the panel. In order to improve the wavenumber resolution, zero-padding was used to obtain a wavenumber resolution of 1 m⁻¹ along k_x and k_y .

401 B. Experimental sensitivity functions

The accuracy of the reciprocity approach for evaluating the panel sensitivity functions has been assessed in [7] for wavenumbers restricted to the acoustic wavenumber circle (of radius defined by $k_0 = \omega/c_0$, with c_0 the speed of sound). In this work, the sensitivity functions have to be determined on a larger wavenumber domain (inside and close to the flexural wavenumber circle of radius k_f).



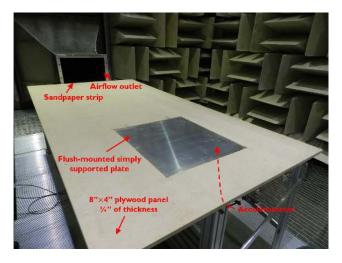
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FIG. 10. (Color online) Squared absolute value of the sensitivity functions $|H_v(\mathbf{x}, \mathbf{k}, f)|^2$ (dB, ref. 1 m².s⁻².Hz⁻¹) along $k_x \ge 0$ for $k_y = 0$: (a) numerical result, (b) experimental result. The superimposed lines represent: k_f according to Eq. (8) (continuous line); k_0 (dashed line); k_c according to Eq. (9) for $U_{\infty} = 20 \text{ m.s}^{-1}$ (line with triangle markers); k_c according to Eq. (9) for $U_{\infty} = 40 \text{ m.s}^{-1}$ (line with circle markers).

The sensitivity functions of the panel have been estimated from measurements based on 413 the methodology described in Sec. IIC. A normal effort was applied at point \mathbf{x} using a 414 TMS SmartShaker K2007E01 with integrated amplifier, which was fed with a swept sine 415 over the considered frequency range and the force was measured using an impedance head 416 PCB288D01. An adapter was used between the impedance head and the plate reducing 417 the area of mechanical coupling to approximately a 5 mm diameter circle. The vibratory 418 response of the panel was measured on the grid of 37×27 points with a single point scanning 419 laser vibrometer (PSV-300 Polytec) and a time Fourier transform was directly performed in 420 the post-processing software with ten linear averages. A frequency resolution of 0.625 Hz 421 was chosen and fixed for the remainder of this paper. The numerically obtained sensitivity 422 functions in Fig. 10(a) (see [7] for details on the numerical model) are compared to the 423 experimental sensitivity functions in Fig. 10(b). In both cases, the sensitivity functions are 424 presented along $k_x \ge 0$ and for $k_y = 0$ as a function of the frequency. The panel vibration 425 modes are noticeable below or close to the dispersion curve of the flexural motion, Eq. (8). 426 Since the plate is considered isotropic, its vibration behavior is similar in both direction 427 which explains why results are only presented in the flow-direction, where the excitation 428 has its most energetic components. A representation along k_y would have shown similar 429 results with differences linked to the dimensions of the plate resulting in different modal 430 wavenumbers in direction y. Results presented in Fig. 10 show that the experimentally 431 obtained sensitivity functions are in good agreement with numerical simulations on the 432 whole frequency range. Slight differences between experimental and numerical results can 433 be observed mainly for the upper part of the frequency range. They can be attributed to 434 the boundary conditions of the actual plate, which are close to simply supported boundary 435 conditions but not absolutely perfect. 436

437 C. Application of the proposed methodology and comparison with direct mea-438 surements in the wind tunnel

The vibration response of the plate estimated from the proposed approach (Eq. (3)) is finally compared to direct measurements in the wind tunnel. Measurements in the wind tunnel were performed with a plate identical to the one used for sensitivity functions measurement (Sec. IV B) and described in Table I (similar dimensions, material and boundary conditions). The plate was flush-mounted at the location of the previously mounted spiralshaped array (as shown in Fig. 11). Aside from replacing the spiral-shaped array with the
plate, the experimental conditions remained unchanged in order to keep the turbulent flow
excitation identical to the one characterized in Sec. III.



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FIG. 11. (Color online) Experimental setup used to measure the vibration response of the plate tothe TBL excitation generated in the wind tunnel.

On the one hand, the vibration velocity of the plate was measured at point **x** using a PCB 353B18 accelerometer, the acceleration signal over time was extracted from the postprocessing software with a sampling frequency of 8192 Hz and the vibration velocity ASD function G_{vv} was estimated using the "cpsd" MATLAB command. On the other hand, the vibration velocity ASD function was estimated by applying the proposed methodology using Eq. (3), the measured sensitivity functions $H_v(\mathbf{x}, \mathbf{k}, f)$ and the fitted Mellen model of the WPF CSD function $G_{p_bp_b}(\mathbf{k}, f)$.

The plate velocity ASD function measured in the anechoic wind tunnel room at point \mathbf{x} is compared to the result obtained with the proposed method in Figs. 12 and 13 for flow velocities of 20 m.s⁻¹ and 40 m.s⁻¹, respectively. One can notice that all modes are excited by the reproduced TBL. According to the formulation presented in Eq. (1), where both functions in the integral are positive or null, any type of mode (even or odd) can be excited by any random excitation.

For both considered flow velocities, slight shifts of the resonance peaks in the high frequency range are noticed. They can be explained by the fact that an adapter was used between the impedance head and the plate for the measurement of the sensitivity functions,

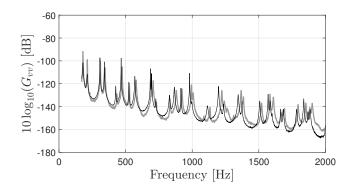


FIG. 12. Velocity ASD functions G_{vv} (dB, ref. 1 m².s⁻².Hz⁻¹) at flow velocity $U_{\infty} = 20$ m.s⁻¹: proposed approach (light black line) vs. wind tunnel measurements (bold gray line).

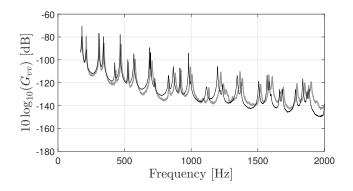


FIG. 13. Velocity ASD functions G_{vv} (dB, ref. 1 m².s⁻².Hz⁻¹) at flow velocity $U_{\infty} = 40$ m.s⁻¹: proposed approach (light black line) vs. wind tunnel measurements (bold gray line).

adding a mass to the system. It can also be explained by the fact that the sensitivity 466 functions were not measured on the same plate as the plate installed in the wind tunnel to 467 directly measure the response. Despite all efforts made to have two identical panels, slight 468 differences in dimensions, material properties and boundary conditions were unavoidable. 469 The structural damping is implicitly taken into account through the measurement of the 470 sensitivity functions in the proposed approach and through the direct measurement of the 471 vibration response in the wind tunnel. The differences in peak values, as well as off reso-472 nance values, can again be linked to the fact that the two plates had differences in structural 473 damping values. For instance, the damping loss factors estimated at the first two peaks for 474 the plate mounted in the wind tunnel ($\eta_{21} = 0.55$ % and $\eta_{12} = 0.56$ %) are lower than those 475 estimated on the plate used to measure the sensitivity functions (given in Table II). For 476 the following six peaks, an opposite trend has been observed which is in line with obtained 477

⁴⁷⁸ results and, thereby, explains the amplitude differences at the resonance peaks.

The differences can also be attributed to the fact that the auto-spectrum of the blocked 479 wall-pressure has not been estimated directly at point \mathbf{x} but by averaging the auto-spectra 480 over the area covered by the spiral-shaped array. This leads to slight errors in terms of 481 overall trend and thereby also contributes to the under-estimation by the proposed method, 482 particularly at high frequencies. Despite the differences at the first two peaks of resonance, 483 which again are linked to discrepancies in the structural loss factors of both plates, the 484 predicted and measured data are in good agreement, which shows that for the considered 485 test case, the velocity response of the plate can be fairly well estimated experimentally by 486 applying the proposed methodology. 487

488 V. CONCLUSION

In this paper, an alternative methodology for characterizing the vibration response of 489 panels to a turbulent boundary layer excitation was proposed. This approach is based on 490 the concept that the panel response at a point \mathbf{x} on the panel to a random pressure field 491 depends on two quantities in the wavenumber domain. First, the wall-pressure cross-spectral 492 density function, which characterizes the excitation. Second, so-called 'sensitivity functions' 493 determined at point \mathbf{x} and which characterize the dynamic behavior of the panel. Those sen-494 sitivity functions can be determined using the reciprocity principle, which states that they 495 are equivalent to the panel velocity frequency response function when the panel is excited 496 by a normal force at the point of interest \mathbf{x} , expressed in the wavenumber domain. The 497 sensitivity functions can be estimated easily by experiments based on this reciprocal inter-498 pretation. The method has been validated experimentally for a simply supported aluminum 499 plate. The confrontation to direct measurements in an anechoic wind tunnel has shown that 500 a fairly good estimate of the vibration response can be obtained by applying the proposed 501 methodology. This indicates that the excitation, as well as the panel behavior, have been 502 correctly characterized. 503

The main limitations of the proposed approach rely on the assumptions of the mathematical formulation of the problem: the system should be linear (*i.e.*, elastic material, small deformations) and time invariant. It is also assumed that the wall-pressure field exciting the panel corresponds to that of the turbulent flow in rigid conditions. Models provided in the literature can be used but should be adjusted to actual measurements in order to correctly
 represent the considered excitation (it is however not mandatory to apply the method).

From a practical point of view, the acquisition time for the reciprocal approach is significantly longer than for a direct measurement in the wind tunnel because a scanning laser vibrometer was used. However, it could be well reduced with the recently developed fullfield vibration measuring techniques (such as digital image correlation or deflectometry [25]). Once the excitation is characterized, the overall cost for a measurement in a given facility as well as variability between measurements in different ones can be greatly reduced using the proposed approach.

The strongest asset of the proposed methodology is that it allows performing an *ex situ* characterization of a panel under turbulent boundary layer excitation. The characterization of the excitation and/or the panel can be experimental, but might as well come from numerical models. This approach is therefore well suited for parametric studies. Once the excitation is defined, the response of panels with various mechanical properties under the considered excitation can easily be deduced.

523 ACKNOWLEDGMENTS

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Fig. 1. Illustration of a baffled panel (gray line) excited by a TBL and coordinate system.

Fig. 2. Determination of the sensitivity functions H_v : (a) based on the direct interpretation, (b) using the reciprocity principle.

Fig. 3. (a) Microphone positions (red markers) and illustration of a reconstructed grid (blue dots). (b) Close-up view of the mounted sensors and pinholes on measurement side.

Fig. 4. Measurement of the wall-pressure fluctuations using the spiral-shaped surface
 microphone array flush-mounted in the wind tunnel.

Fig. 5. TBL parameters extracted from measurements at $U_{\infty} = 20 \text{ m.s}^{-1}$ (bold gray line) and at $U_{\infty} = 40 \text{ m.s}^{-1}$ (light black line) based on the model of Mellen. (a) Convection speed normalized by the flow velocity. (b) Streamwise exponential decay rate α_x . (c) Spanwise exponential decay rate α_y .

- Fig. 6. Spatial CSD function of the blocked wall-pressure normalized by the autospectrum at the center of the array $G_{p_bp_b}(\xi_x, \xi_y, f)/G_{p_bp_b}(f)$ at 500 Hz and at a flow velocity $U_{\infty} = 20 \text{ m.s}^{-1}$. (a) Mellen model, real part. (b) Direct measurement, real part. (c) Mellen model, imaginary part. (d) Direct measurement, imaginary part.
- Fig. 7. Spatial CSD function of the blocked wall-pressure normalized by the autospectrum at the center of the array $G_{p_bp_b}(\xi_x, \xi_y, f)/G_{p_bp_b}(f)$ at 500 Hz and at a flow velocity $U_{\infty} = 40 \text{ m.s}^{-1}$. (a) Mellen model, real part. (b) Direct measurement, real part. (c) Mellen model, imaginary part. (d) Direct measurement, imaginary part.
- Fig. 8. Spatially averaged ASD function of the blocked wall-pressure $\langle G_{p_bp_b}(f) \rangle$ (dB, ref. $4 \times 10^{-10} \text{ Pa}^2.\text{Hz}^{-1}$) at a flow velocity $U_{\infty} = 20 \text{ m.s}^{-1}$ (bold gray line) and $U_{\infty} = 40 \text{ m.s}^{-1}$ (light black line).

Fig. 9. Illustration of the filtering effect of the plate. (a) Theoretical squared absolute value of the sensitivity functions $|H_v(\mathbf{x}, k_x, 0, f)|^2$ (dB, ref. 1 m.s⁻¹.Hz⁻¹). (b) Model of Mellen $G_{p_bp_b}(k_x, 0, f), U_{\infty} = 40 \text{ m.s}^{-1}$ (dB, ref. 1 Pa².Hz⁻¹). (c) Product ⁶²¹ $|H_v(\mathbf{x}, k_x, 0, f)|^2 \times G_{p_b p_b}(k_x, 0, f)$ (dB, ref. 1 Pa²m².s⁻².Hz⁻¹) normalized by the max-⁶²² inum value at each frequency. Continuous line: flexural wavenumber k_f according to ⁶²³ Eq. (8). Dashed line: convective wavenumber k_c according to Eq. (9).

Fig. 10. Squared absolute value of the sensitivity functions $|H_v(\mathbf{x}, \mathbf{k}, f)|^2$ (dB, ref. 1 m².s⁻².Hz⁻¹) along $k_x \ge 0$ for $k_y = 0$: (a) numerical result, (b) experimental result. The superimposed lines represent: k_f according to Eq. (8) (continuous line); k_0 (dashed line); k_c according to Eq. (9) for $U_{\infty} = 20 \text{ m.s}^{-1}$ (line with triangle markers); k_c according to Eq. (9) for $U_{\infty} = 40 \text{ m.s}^{-1}$ (line with circle markers).

- Fig. 11. Experimental setup used to measure the vibration response of the plate to the TBL excitation generated in the wind tunnel.
- Fig. 12. Velocity ASD functions G_{vv} (dB, ref. 1 m².s⁻².Hz⁻¹) at flow velocity $U_{\infty} =$ 20 m.s⁻¹: proposed approach (light black line) vs. wind tunnel measurements (bold gray line).

Fig. 13. Velocity ASD functions G_{vv} (dB, ref. 1 m².s⁻².Hz⁻¹) at flow velocity $U_{\infty} =$ 40 m.s⁻¹: proposed approach (light black line) vs. wind tunnel measurements (bold gray line).

TABLE I. Mechanical properties of the simply supported aluminum plate.

Parameter (Symbol), Unit	Value
Young's modulus (E) , GPa	68.9
Poisson's ratio (ν)	0.3
Mass density (ρ) , kg/m ³	2740
Length (L_x) , mm	480
Width (L_y) , mm	420
Thickness (h) , mm	3.17

TABLE II. Modal properties of the simply supported aluminum plate.

(m,n)	Resonance frequency, f_{mn} [Hz]	Modal structural loss factor, η_{mn} [%]
(2,1)	180	1.71
(1, 2)	213.1	2.05
(2, 2)	307.5	0.28
(3, 1)	340.6	0.3
(1, 3)	426.3	0.5
(3, 2)	466.9	0.11
(2, 3)	524.4	0.29
(4,1)	569.4	0.41