

EXTENDING THE RANK LIKELIHOOD FOR SEMIPARAMETRIC COPULA ESTIMATION

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Quantitative studies in many fields involve the analysis of multivariate data of diverse types, including measurements that we may consider binary, ordinal and continuous. One approach to the analysis of such mixed data is to use a copula model, in which the associations among the variables are parameterized separately from their univariate marginal distributions. The purpose of this article is to provide a simple, general method of semiparametric inference for copula models via a type of rank likelihood function for the association parameters. The proposed method of inference can be viewed as a generalization of marginal likelihood estimation, in which inference for a parameter of interest is based on a summary statistic whose sampling distribution is not a function of any nuisance parameters. In the context of copula estimation, the extended rank likelihood is a function of the association parameters only and its applicability does not depend on any assumptions about the marginal distributions of the data, thus making it appropriate for the analysis of mixed continuous and discrete data with arbitrary marginal distributions. Estimation and inference for parameters of the Gaussian copula are available via a straightforward Markov chain Monte Carlo algorithm based on Gibbs sampling. Specification of prior distributions or a parametric form for the univariate marginal distributions of the data is not necessary.

1. Introduction. Studies involving multivariate data often include measurements of diverse types. For example, a survey or observational study may record the sex, education level and income of its participants, thus including measurements that we may consider binary, ordinal and continuous. Such studies are generally concerned with statistical associations among the variables, but not necessarily the scale on which the variables are measured. One approach to data analysis in these situations is to obtain rank-based measures of bivariate association, such as the rank correlation or “Spearman’s rho.” Such procedures are scale-free, but involve ad-hoc methods for dealing with ties and provide inference that is generally limited to hypothesis tests of bivariate association. These issues make such procedures problematic for the analysis of much of social science survey data, in which the variables are often discrete and the hypotheses of interest generally concern multivariate and conditional associations. For example, Figure 1 shows histograms

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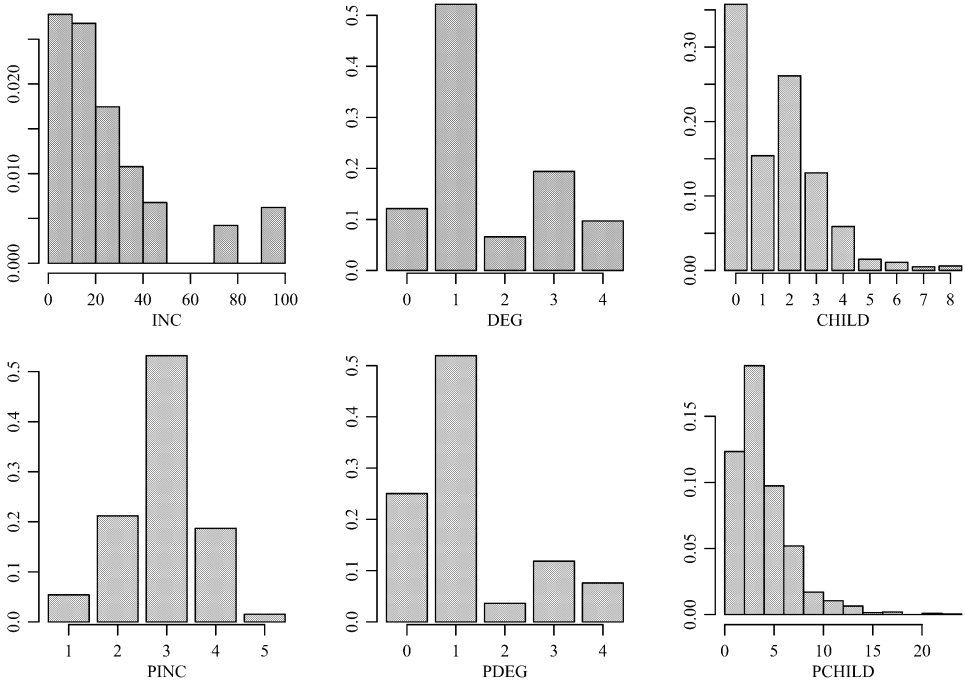


FIG. 1. Univariate histograms of the GSS data.

of six demographic variables of male respondents to the 1994 General Social Survey. The variables INC, DEG and CHILD refer to the income, highest degree and number of children of a survey respondent, and PINC, PDEG and PCHILD refer to similar variables of the respondent's parents (further details on the variables are given in Section 4). All of these variables are ordered categorical variables, even though some of them have many levels. Additionally, our interests in these variables involve measures of conditional association: An assessment of the relationship between income and number of children would generally be considered incomplete if it failed to account for heterogeneity of the survey respondents in terms of their age, parental income and other variables.

The standard approach to making statistical assessments of conditional association is the use of regression models. For example, to describe the conditional association between income and number of children, we could estimate the parameters in a regression model of the following form:

$$\begin{aligned}
 (1) \quad \text{INC}_i &= \beta_0 + \beta_1 \text{CHILD}_i + \beta_2 \text{DEG}_i + \beta_3 \text{AGE}_i \\
 &+ \beta_4 \text{PCHILD}_i + \beta_5 \text{PINC}_i + \beta_6 \text{PDEG}_i + \epsilon_i.
 \end{aligned}$$

Least-squares parameter estimates for this model, along with normal-theory p -values appear in the first row of Table 1. Standard practice is to interpret the

TABLE 1

Estimation linear and Poisson regression coefficients in the conditional models for INC and CHILD, with p -values in parentheses

Response	Predictor						
	INC	CHILD	DEG	AGE	PCHILD	PINC	PDEG
INC	NA	1.10 (0.11)	7.03 (<0.01)	0.34 (<0.01)	4.07 (<0.01)	0.28 (0.41)	1.40 (0.12)
CHILD	0.01 (0.01)	NA	-0.07 (0.06)	0.04 (<0.01)	-0.06 (0.20)	0.02 (0.08)	-0.05 (0.20)

p -value of 0.11 for CHILD as suggesting that there is not substantial evidence against $\beta_1 = 0$, in which case the model implies that INC and CHILD are conditionally independent given the other variables. Alternatively, we could have evaluated the same conditional independence hypothesis with a regression model for CHILD. As this is a count variable, we might use a Poisson regression model:

$$(2) \quad \text{CHILD}_i \sim \text{Pois}(\exp\{\beta_0 + \beta_1 \text{INC}_i + \beta_2 \text{DEG}_i + \beta_3 \text{AGE}_i + \beta_4 \text{PCHILD}_i + \beta_5 \text{PINC}_i + \beta_6 \text{PDEG}_i\}).$$

Maximum likelihood estimates and p -values for this model appear in the second row of Table 1. In contrast to the results of model (1), these results indicate reasonably strong evidence ($p = 0.01$) that CHILD and INC are *not* conditionally independent, given the other variables.

The contradiction between the above two analyses is partly due to the inadequacies of the simple univariate parametric Gaussian and Poisson models. However, in general, there is no reason to expect that two separately estimated conditional models will give compatible results: Given two conditional models $f_1(y_1|y_2, \mathbf{x})$ and $f_2(y_2|y_1, \mathbf{x})$, only under very specific conditions does there exist a joint probability distribution $p(y_1, y_2|\mathbf{x})$ having f_1 and f_2 as its full conditional distributions [Arnold and Press (1989)]. This presents a problem for the analysis of multivariate data of diverse types: in the absence of an appropriate multivariate model, common practice is to analyze the data via one or more univariate regression models, choosing the “response” from the variables which might best fit an ordinary or generalized linear regression model. However, as the above example shows, different choices about which variables to treat as the response can lead to incompatible models with different conclusions.

Part of the above problem can be resolved by jointly modeling the variables of interest. A number of latent-variable methods have been recently developed to accommodate non-Gaussian multivariate data. These methods generally proceed by modeling each component of a vector of observations with a parametric exponential family model, in which the parameters for each component involve an unobserved latent variable. For example, Chib and Winkelmann (2001) present a model for a vector of correlated count data in which each component is a Poisson

random variable with a mean depending on a component-specific latent variable. Dependence among the count variables is induced by modeling the vector of latent variables with a multivariate normal distribution. Similar approaches are proposed by [Dunson \(2000\)](#) and described in Chapter 8 of [Congdon \(2003\)](#). The model of Chib and Winkelmann can be viewed as a copula model, in which the association parameters are modeled separately from the marginal distributions of the observed data. Such a modeling approach can be applied to a wide variety of multivariate analysis problems: An old mathematical result known as Sklar's theorem says that every multivariate probability distribution can be represented by its univariate marginal distributions and a copula, which is a type of joint distribution with fixed marginals.

[Pitt, Chan and Kohn \(2006\)](#) develop an estimation procedure for multivariate normal copula models in which the marginal distributions belong to specified parametric families. Unfortunately, the marginal distributions of survey data such as age, number of children, income and education level generally do not belong to standard families. For such data, a semiparametric estimation strategy may be appropriate, in which the associations among the variables are represented with a simple parametric model but the marginal distributions are estimated nonparametrically. In the case where all the variables are continuous, [Genest, Ghoudi and Rivest \(1995\)](#) suggest a "pseudo-likelihood" approach to estimation, in which the observed data is transformed via the empirical marginal distributions to obtain pseudo-data that can be used to estimate the association parameters. [Klaassen and Wellner \(1997\)](#) study a similar type of estimation in the case of the Gaussian copula. Such estimators are well-behaved for continuous data but can fail for discrete data, making them somewhat inappropriate for the analysis of mixed continuous and discrete data. For ordinal discrete data with a known number of categories, the dependence induced by the Gaussian copula model is called polychoric correlation. [Olsson \(1979\)](#) describes a two-stage estimation procedure for the parameters in the copula, and this and other estimation strategies appear in a number of software packages including SAS PROC FREQ and the LISREL module PRELIS. [Kottas, Müller and Quintana \(2005\)](#) describe a nonparametric estimation procedure in which the copula is based on a mixture of normal distributions. However, such procedures do not accommodate continuous data, and may even be problematic for discrete data with a large number of categories, as inference in this case requires the simultaneous estimation of the large number of parameters specifying the marginal distributions.

As an alternative to these procedures, this article presents an approach to copula estimation in which the marginal distributions are arbitrary and of unspecified types, thus accommodating both discrete and continuous data. This is achieved by the use of a likelihood function that depends on the association parameters only, and does not make assumptions about the form of the univariate marginal distributions. Inference based on such a likelihood is therefore appropriate for the joint

analysis of continuous and ordinal discrete data. For continuous data, the likelihood function we propose is derived from the marginal probability of the ranks, and can be seen as a multivariate version of a “rank likelihood” [Pettitt (1982), Heller and Qin (2001)] which does not depend on the univariate marginal distributions. Unfortunately, for discrete data the probability of the observed ranks is not free of these nuisance parameters. To solve this problem, we derive a likelihood that is equivalent to the distribution of the ranks for continuous data but is also free of the nuisance parameters for discrete data. This likelihood function is derived from the probability that the latent variables of the copula model satisfy the partial ordering induced by the observed data. We call this function an extended rank likelihood, as it generalizes the concept of rank likelihood. This likelihood can also be seen as a generalization of a marginal likelihood, which is based on a statistic whose sampling distribution depends only on the parameter of interest and not on any nuisance parameters.

In what follows we work with the Gaussian copula model, although the basic ideas can be extended to other parametric families of copulas. In the next section we review the general Gaussian copula model, and discuss how inference for discrete data using existing semiparametric methods is problematic. Section 3 derives the extended rank likelihood as a general approach to semiparametric copula estimation and discusses parameter estimation in the context of Bayesian inference using a relatively simple Gibbs sampling scheme.

The primary goal of this paper is to provide a simple method of inference for the multivariate relationships between variables, such as INC, CHILD, DEG described above, whose univariate marginal distributions cannot be well approximated with simple parametric models. In Section 4 we present an analysis of these and other demographic characteristics of males in the 1994 U.S. workforce and their parents. In particular, we are interested in the statistical associations among income, education and number of children of the survey respondents, and how they relate to similar characteristics of the parents of the survey respondents. The data come from the 1994 General Social Survey, and include a number of discrete and non-Gaussian random variables. In addition to estimating a Gaussian copula model for these data, we estimate and describe the conditional dependencies among the variables on the Gaussian scale, as well as provide predictive and conditional distributions on the original scale of the data.

Section 5 considers notions of statistical sufficiency relevant to the rank likelihood, and a discussion follows in Section 6.

2. Semiparametric copula estimation. Let y_1 and y_2 be two random variables with continuous CDFs F_1 and F_2 . The transformed variables $u_1 = F_1(y_1)$ and $u_2 = F_2(y_2)$ both have uniform marginal distributions. The term “copula modeling” generally refers to a model that parametrizes the joint distribution of u_1 and u_2 separately from the marginal distributions F_1 and F_2 . A semiparametric copula

model includes a parametric model for the joint distribution of u_1 and u_2 , but lacks any parametric restrictions on F_1 or F_2 .

Any continuous multivariate distribution can be used to form a copula model via an inverse-CDF transformation. For example, the bivariate normal distribution can be used to generate dependent data with arbitrary marginals F_1 and F_2 as follows:

1. sample $\begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \sim \text{bivariate normal} \left[\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right]$;
2. set $y_1 = F_1^{-1}[\Phi(z_1)]$, $y_2 = F_2^{-1}[\Phi(z_2)]$,

where $F^{-1}(u) = \inf\{y : F(y) \geq u\}$ denotes the pseudo-inverse of a CDF F . The correspondence to the usual copula formulation can be seen by noting that $\Phi(z) = u$ is uniformly distributed.

Suppose $(y_{1,1}, y_{1,2}), \dots, (y_{n,1}, y_{n,2})$ are samples from a population that we wish to model with a Gaussian copula. If the marginal distributions F_1 and F_2 were continuous and known, then the values $z_{i,j} = \Phi^{-1}[F_j(y_{i,j})]$ could be treated as observed data and ρ could be estimated directly from the z 's, perhaps using the unbiased estimator $\hat{\rho} = \frac{1}{n} \sum_{i=1}^n z_{i,1} z_{i,2}$. Of course, the marginal CDFs are not typically known. One semiparametric estimation strategy is to plug-in the empirical CDFs \hat{F}_1 and \hat{F}_2 to obtain pseudo-data $\tilde{z}_{i,j} = \Phi^{-1}[\frac{n}{n+1} \hat{F}_j(y_{i,j})] \equiv \Phi^{-1}[\tilde{F}_j(y_{i,j})]$, where the rescaling is to avoid infinities. For continuous data, the estimator $\tilde{\rho} = \frac{1}{n} \sum_{i=1}^n \tilde{z}_{i,1} \tilde{z}_{i,2}$ is asymptotically equivalent to the asymptotically efficient Van der Waerden normal-scores rank correlation coefficient [Hájek and Šidák (1967), Klaassen and Wellner (1997)]. This estimator is similar to one obtained from a more general pseudo-likelihood estimation procedure described and studied by Genest, Ghoudi and Rivest (1995). In the context of the Gaussian copula model, the maximum pseudo-likelihood procedure is the following:

1. set $\tilde{z}_{i,j} = \Phi^{-1}[\tilde{F}_j(y_{i,j})]$;
2. maximize in ρ the pseudo-log-likelihood $\sum_{i=1}^n \log \text{bvn}(\tilde{z}_{i,1}, \tilde{z}_{i,2} | \rho)$,

where $\text{bvn}(\cdot | \rho)$ denotes the bivariate normal density with standard normal marginals. Genest, Ghoudi and Rivest show that the resulting pseudo-likelihood estimator is consistent and asymptotically normal under the condition that F_1 and F_2 are continuous. However, this condition calls into question the appropriateness of the pseudo-likelihood approach for noncontinuous data such as sex, education level, age or any other type of data where there are likely to be ties.

What could go wrong with such an estimator in situations involving discrete data? In general, these pseudo-data estimators of copula parameters will be problematic for discrete data because transformations of such data do not really change the data distribution, they just change the sample space. Consider the simple case of a continuous variable y_1 and a binary variable y_2 such that $\Pr(y_2 = 0) = \Pr(y_2 = 1) = 1/2$. Letting $\tilde{z}_{i,j} = \Phi^{-1}[\tilde{F}_j(y_{i,j})]$, the distribution of $\tilde{z}_{1,1}, \dots, \tilde{z}_{n,1}$ will have an approximately standard normal distribution, but $\tilde{z}_{i,2}$ will

be approximately equal to either $\Phi^{-1}(\frac{1}{2}\frac{n}{n+1})$ or $\Phi^{-1}(\frac{n}{n+1})$ with probability one-half each. If the Gaussian copula model is correct, then one can show that the expectation of $\tilde{\rho}$ is roughly $\frac{\rho}{\sqrt{2\pi}}\Phi^{-1}(\frac{n}{n+1})$. As n increases, so does the expectation of $\tilde{\rho}$, and it is not a consistent estimator. One problem here is that all of the $\tilde{z}_{i,2}$'s such that $y_{i,2} = 1$ are being pushed to the extreme standard normal quantile $\Phi^{-1}(\frac{n}{n+1})$, which in the case of continuous data would happen just to a single datapoint. The situation is only partly improved by using the sample correlation of the pseudo-data as an estimator: The variance of \tilde{z}_1 is approximately 1 and the variance of \tilde{z}_2 is approximately $[\frac{1}{2}\Phi^{-1}(\frac{n}{n+1})]^2$, giving an approximate sample correlation of $\text{Cor}(\tilde{z}_{i,1}, \tilde{z}_{i,2}) \approx \rho\sqrt{2/\pi}$.

3. Estimation using the extended rank likelihood. In this section we derive a likelihood function that depends on the association parameters and not on the unknown marginal distributions. For continuous data, this function is equivalent to the distribution of the multivariate ranks. This is not the case of discrete data, for which the distribution of the ranks depends on the univariate marginal distributions. In this case the derived likelihood function contains less total information than one based on the ranks, but it is free of any parameters describing the marginal distributions.

3.1. *Extended rank likelihood.* Generalizing from the previous section, the Gaussian copula sampling model can be expressed as follows:

$$(3) \quad \mathbf{z}_1, \dots, \mathbf{z}_n | \mathbf{C} \sim \text{i.i.d. multivariate normal}(\mathbf{0}, \mathbf{C}),$$

$$y_{i,j} = F_j^{-1}[\Phi(z_{i,j})],$$

where \mathbf{C} is a $p \times p$ correlation matrix and each F_j^{-1} denotes the (pseudo) inverse of an unknown univariate CDF, not necessarily continuous.

Our goal is to make inference on \mathbf{C} , and not on the potentially high-dimensional parameters F_1, \dots, F_p . If the \mathbf{z} 's were observed, we could use them to directly estimate \mathbf{C} . The \mathbf{z} 's are not observed of course, but the \mathbf{y} 's do provide a limited amount of information about them, even absent any knowledge of the F 's: Since the F 's are nondecreasing, observing $y_{i_1,j} < y_{i_2,j}$ implies that $z_{i_1,j} < z_{i_2,j}$. More generally, observing $\mathbf{Y} = (\mathbf{y}_1, \dots, \mathbf{y}_n)^T$ tells us that $\mathbf{Z} = (\mathbf{z}_1, \dots, \mathbf{z}_n)^T$ must lie in the set

$$\{\mathbf{Z} \in \mathbb{R}^{n \times p} : \max\{z_{k,j} : y_{k,j} < y_{i,j}\} < z_{i,j} < \min\{z_{k,j} : y_{i,j} < y_{k,j}\}\}.$$

We can take the occurrence of this event as our data. Letting D be the fixed subset of $\mathbb{R}^{n \times p}$ generated by the observed value of \mathbf{Y} , we can calculate the following "likelihood":

$$(4) \quad \text{Pr}(\mathbf{Z} \in D | \mathbf{C}, F_1, \dots, F_p) = \int_D p(\mathbf{Z} | \mathbf{C}) d\mathbf{Z} = \text{Pr}(\mathbf{Z} \in D | \mathbf{C}).$$

As a function of the parameters, this likelihood depends only on the parameter of interest \mathbf{C} and not the nuisance parameters F_1, \dots, F_p . Estimation of \mathbf{C} can proceed by maximizing $\Pr(\mathbf{Z} \in D|\mathbf{C})$ as a function of \mathbf{C} , or by obtaining a posterior distribution $\Pr(\mathbf{C}|\mathbf{Z} \in D) \propto p(\mathbf{C}) \times \Pr(\mathbf{Z} \in D|\mathbf{C})$.

The likelihood function (4) can be seen as a type of marginal likelihood function for estimation in the presence of a nuisance parameter: Consider a generic statistical problem in which the density for data y depends on a parameter of interest θ and a nuisance parameter ψ . If there exists a statistic $t(y)$ whose distribution depends on θ only, then the density of y may be decomposed as

$$\begin{aligned} p(y|\theta, \psi) &= p(t(y), y|\theta, \psi) \\ &= p(t(y)|\theta) \times p(y|t(y), \theta, \psi). \end{aligned}$$

In this situation, estimation of θ can be based on the marginal likelihood $p(t(y)|\theta)$, eliminating the need to estimate the nuisance parameter ψ [see, e.g., Section 8.3 of Severini (2000)]. The likelihood function $\Pr(\mathbf{Z} \in D|\mathbf{C})$ in our copula estimation problem can be derived analogously, by decomposing the probability of the observed data as

$$\begin{aligned} (5) \quad p(\mathbf{Y}|\mathbf{C}, F_1, \dots, F_p) &= p(\mathbf{Z} \in D, \mathbf{Y}|\mathbf{C}, F_1, \dots, F_p) \\ (6) \quad &= \Pr(\mathbf{Z} \in D|\mathbf{C}) \times p(\mathbf{Y}|\mathbf{Z} \in D, \mathbf{C}, F_1, \dots, F_p). \end{aligned}$$

Equation (5) holds because the event $\mathbf{Z} \in D$ occurs whenever \mathbf{Y} is observed. This derivation can be made rigorous by deriving the density $p(\mathbf{Y}|\mathbf{C}, F_1, \dots, F_p)$ from the limit of $\Pr(\bigcap_{i,j} (y_{i,j} - \epsilon, y_{i,j}]|\mathbf{C}, F_1, \dots, F_p)$ as $\epsilon \rightarrow 0$. As in the case of marginal likelihood, our approach is to estimate \mathbf{C} using only $\Pr(\mathbf{Z} \in D|\mathbf{C})$, the part of the observed data likelihood (6) that depends on the parameter of interest \mathbf{C} and not on the nuisance parameters F_1, \dots, F_p . Since our likelihood function is based on the marginal probability of an event that is a superset of observing the ranks, we refer to it as an extended rank likelihood.

3.2. *Estimation of the copula parameters.* Bayesian inference for \mathbf{C} can be achieved via construction of a Markov chain having a stationary distribution equal to $p(\mathbf{C}|\mathbf{Z} \in D) \propto p(\mathbf{C}) \times p(\mathbf{Z} \in D|\mathbf{C})$. In the case of the Gaussian copula with a semi-conjugate prior distribution, the Markov chain can be constructed quite easily using Gibbs sampling. This prior distribution for \mathbf{C} is defined as follows: Let \mathbf{V} have an inverse-Wishart($\nu_0, \nu_0 \mathbf{V}_0$) prior distribution, parameterized so that $E[\mathbf{V}^{-1}] = \mathbf{V}_0^{-1}$, and let \mathbf{C} be equal in distribution to the correlation matrix with entries $\mathbf{V}_{[i,j]} / \sqrt{\mathbf{V}_{[i,i]} \mathbf{V}_{[j,j]}}$. Using this prior distribution, approximate samples from $p(\mathbf{C}|\mathbf{Z} \in D)$ can be obtained by iterating the following Gibbs sampling scheme:

Resample \mathbf{Z} . Iteratively over (i, j) , sample $z_{i,j}$ from $p(z_{i,j}|\mathbf{V}, \mathbf{Z}_{[-i,-j]}, \mathbf{Z} \in D)$ as follows:

For each $j \in \{1, \dots, p\}$:

For each $y \in \text{unique}\{y_{1,j}, \dots, y_{n,j}\}$:

1. Compute $z_l = \max\{z_{i,j} : y_{i,j} < y\}$ and $z_u = \min\{z_{i,j} : y < y_{i,j}\}$.
2. For each i such that $y_{i,j} = y$,
 - (a) compute $\sigma_j^2 = \mathbf{V}_{[j,j]} - \mathbf{V}_{[j,-j]}\mathbf{V}_{[-j,-j]}^{-1}\mathbf{V}_{[-j,j]}$;
 - (b) compute $\mu_{i,j} = \mathbf{Z}_{[i,-j]}(\mathbf{V}_{[j,-j]}\mathbf{V}_{[-j,-j]}^{-1})^T$;
 - (c) sample $u_{i,j}$ uniformly from $(\Phi[\frac{z_l - \mu_{i,j}}{\sigma_j}], \Phi[\frac{z_u - \mu_{i,j}}{\sigma_j}])$;
 - (d) Set $z_{i,j} = \mu_{i,j} + \sigma_j \times \Phi^{-1}(u_{i,j})$.

Resample V. Sample \mathbf{V} from an inverse-Wishart($\nu_0 + n, \nu_0 \mathbf{V}_0 + \mathbf{Z}^T \mathbf{Z}$) distribution.

Compute C. Let $\mathbf{C}_{[i,j]} = \mathbf{V}_{[i,j]} / \sqrt{\mathbf{V}_{[i,i]}\mathbf{V}_{[j,j]}}$.

Iteration of this algorithm generates a Markov chain in \mathbf{C} whose stationary distribution is $p(\mathbf{C}|\mathbf{Z} \in D)$. This algorithm is easily modified to accommodate data that are missing-at-random: If $y_{i,j}$ is missing, the full conditional distribution of $z_{i,j}$ is the unconstrained normal distribution with mean $\mu_{i,j}$ and variance σ_j^2 given above.

The reader may have noticed that the samples of \mathbf{Z} are based on the covariance matrix \mathbf{V} and not the correlation matrix \mathbf{C} . To see why this does not matter for estimation of \mathbf{C} , compare our original model,

$$\begin{aligned} \mathbf{V} &\sim \text{inverse-Wishart}(\nu_0, \nu_0 \mathbf{V}_0), \\ \{\mathbf{C}_{[i,j]}\} &= \{\mathbf{V}_{[i,j]} / \sqrt{\mathbf{V}_{[i,i]}\mathbf{V}_{[j,j]}}\}, \\ \mathbf{z}_1, \dots, \mathbf{z}_n &\sim \text{i.i.d. multivariate normal}(\mathbf{0}, \mathbf{C}), \\ y_{i,j} &= G_j(z_{i,j}), \end{aligned}$$

to the equivalent model

$$\begin{aligned} \mathbf{V} &\sim \text{inverse-Wishart}(\nu_0, \nu_0 \mathbf{V}_0), \\ \mathbf{z}_1, \dots, \mathbf{z}_n &\sim \text{i.i.d. multivariate normal}(\mathbf{0}, \mathbf{V}), \\ \tilde{z}_{i,j} &= z_{i,j} / \sqrt{\mathbf{V}_{[j,j]}} \quad \text{and let } \mathbf{C} = \text{Cov}(\tilde{\mathbf{z}}), \\ y_{i,j} &= G_j(\tilde{z}_{i,j}). \end{aligned}$$

The \mathbf{z} 's in the first formulation are equal in distribution to the $\tilde{\mathbf{z}}$'s in the second, and so posterior inference for \mathbf{C} is equivalent under either model. The Gibbs sampling scheme outlined above is based on a Markov chain in \mathbf{V} and $\mathbf{z}_1, \dots, \mathbf{z}_n$ based on the second formulation. Note that in this formulation the observed data implies the same ordering D on both the $\tilde{\mathbf{z}}$'s and the \mathbf{z} 's. Additionally, posterior estimation of \mathbf{C} is invariant to changes in the prior distribution on \mathbf{V} that do not alter the induced prior on \mathbf{C} . For example, if \mathbf{V}_0 and \mathbf{V}'_0 are two different covariance matrices with the same correlations, then the posterior distribution of \mathbf{C} under $\mathbf{V} \sim \text{inverse-Wishart}(\nu_0, \nu_0 \mathbf{V}_0)$ will be equal to that under $\mathbf{V} \sim \text{inverse-Wishart}(\nu_0, \nu_0 \mathbf{V}'_0)$.

4. Income, education and intergenerational mobility. The U.S. census reports a strong positive relationship between income and educational attainment [Day and Newburger (2002)]. However, in many studies both of these variables have been shown to be associated with a number of family background variables such as parental income, parental educational attainment and number of siblings [Ermisch and Francesconi (2001), Blake (1985)]. Additionally, some researchers have suggested that having children reduces opportunities for educational attainment [Moore and Waite (1977)], while others have found evidence that economic status of males is positively associated with their fertility [Hopcroft (2006)]. Results such as these are generally based on univariate regression models in which one variable from a sample survey is selected as a “response” or “dependent” variable and the others as “control” or “independent” variables. However, all of the variables in these studies are randomly sampled and all are potentially dependent on one another.

In this section we describe the multivariate dependencies among income, education and number of children using the Gaussian copula model and the semi-parametric estimation procedure described in Section 3. Specifically, we analyze survey data on 1002 males in the U.S. labor force (meaning not retired, in school or in an institution), obtained from the 1994 General Social Survey. Data and details for the survey are available at <http://webapp.icpsr.umich.edu/GSS/>.

The relevant variables for this analysis include the income, education and number of children of the survey respondent, as well as similar variables for the respondent’s parents. Age of the survey respondent is additionally included, as it is typically strongly related to income and number of children. The measurement scales for these variables are as follows:

- INC: income of the respondent in 1000s of dollars, binned into 21 ordered categories.
- DEG: highest degree ever obtained (None, HS, Associates, Bachelors, Graduate).
- CHILD: number of children ever had.
- PINC: financial status of respondent’s parents when respondent was 16 (on a 5-point scale).
- PDEG: maximum of mother’s and father’s highest degree.
- PCHILD: number of siblings of the respondent plus one.
- AGE: age of the respondent in years.

Missing data rates among each of the nonincome variables was less than 4%. The missing data rates for INC and PINC were 10% and 48% respectively. However, the question PINC was asked on only half of the surveys, and so missing values for this variable can reasonably be considered as missing at random.

4.1. Estimation of \mathbf{C} . Using an inverse-Wishart $(p + 2, (p + 2) \times \mathbf{I})$ prior distribution for \mathbf{V} , the Gibbs sampling scheme outlined in Section 3 was iterated

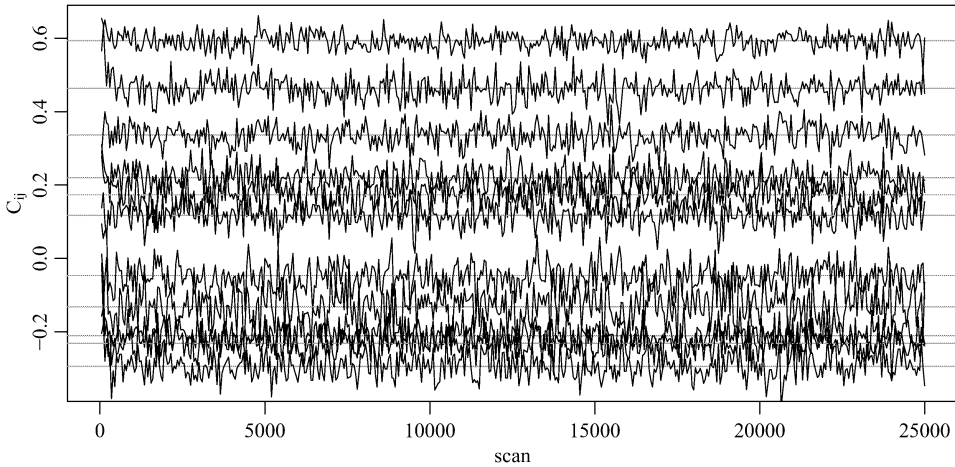


FIG. 2. MCMC samples of 11 of the correlation coefficients, plotted every 50th scan.

25,000 times with parameter values saved every 10 scans, resulting in 2500 samples of \mathbf{C} for posterior analysis. Mixing of the Markov chain was quite good: Figure 2 shows MCMC samples of 11 elements of \mathbf{C} , corresponding to the odd order statistics of $E[\mathbf{C}|\mathbf{Z} \in D]$. Convergence to stationarity appears to occur quickly, almost certainly within the first 5000 scans. Dropping these scans to allow for burn-in, we are left with 2000 saved scans for posterior analysis. The autocorrelation across these saved scans was low, with the lag-10 autocorrelation less than 0.05 in absolute value for all elements of \mathbf{C} , and much closer to zero for most. Based on the autocorrelation in the Markov chain, the effective sample sizes for estimating the posterior means of the elements of \mathbf{C} were at least 1500.

4.2. Posterior inference. Posterior distributions of the correlation parameters are summarized in the first and second rows of Figure 3. The first row gives 2.5%, 50% and 97.5% posterior quantiles of the correlation coefficients, representing scale-invariant bivariate associations among the six variables of interest. The fact that most of these 95% credible intervals do not contain zero indicates that most variables are associated with most of the other variables. For example, the results suggest that INC has nonzero positive correlations with DEG, CHILD, PINC, PDEG and AGE, and a weak negative correlation with PCHILD. DEG shows positive correlations with INC, PINC, PDEG, and negative correlation with PCHILD [in accordance with the conclusion of Blake (1985)].

Perhaps of more interest are conditional associations. The second column of Figure 3 gives the 2.5%, 50% and 97.5% quantiles for the “regression coefficients” $\mathbf{C}_{[j,-j]}\mathbf{C}_{[-j,-j]}^{-1}$ for each variable. These coefficients represent conditional dependencies among the underlying processes that give rise to the observed data. On this scale, the full conditional distribution of INC depends most strongly on DEG, and

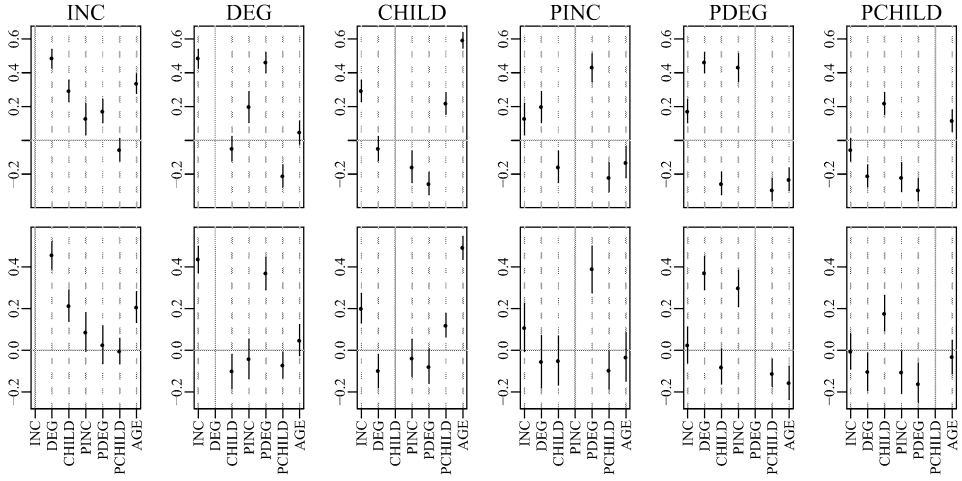


FIG. 3. Dependence parameters for the GSS data. The first row gives 2.5%, 50%, 97.5% posterior quantiles of the correlation coefficients $E[z_j z_k]$. The second row gives the regression coefficients $\nabla E[z_j | z_{-j}]$.

to a lesser extent on CHILD and AGE. Interestingly, the conditional relationship between INC and PINC has a nonnegligible ($> 5\%$) probability of being less than or equal to zero. Figure 4 summarizes these results with a graph indicating the conditional dependencies among the \mathbf{z} -variables corresponding to the six variables of interest (implicitly conditioning on AGE). An edge is present between two nodes if the 95% credible interval for the associated regression parameter does not contain zero. This graph suggests that although INC and PINC are positively associated, this association is mediated by the intergenerational relationships of DEG, PDEG, CHILD and PCHILD.

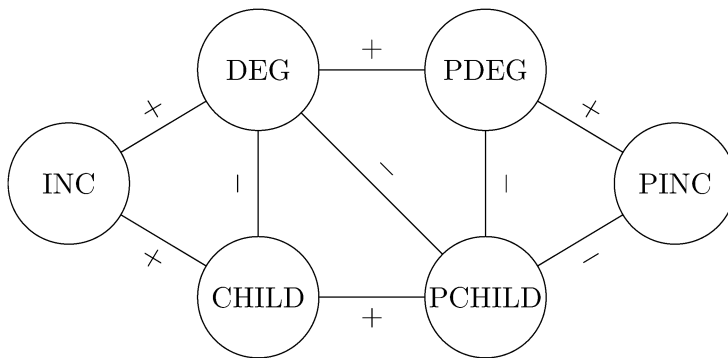


FIG. 4. Reduced conditional dependence graph for the GSS data.

4.3. *Conditional distributions for the INC, DEG, PINC relationship.* The results in Figure 3 suggest that, although INC and PINC are positively correlated, PINC is a relatively weak predictor of INC compared to DEG. However, PINC is a strong predictor of PDEG, and PDEG is a strong predictor of DEG, suggesting an indirect effect of PINC on INC.

These conclusions about INC, DEG and PINC are made in terms of associations among the \mathbf{z} -variables, although it is often desirable to report results on the scale of the original data. With this in mind, we now describe the relationship between INC, DEG and PINC on the original data scale, using an estimated predictive distribution $\Pr(\text{INC}, \text{DEG}, \text{PINC})$, which we decompose as $\Pr(\text{INC}|\text{DEG}, \text{PINC}) \times \Pr(\text{DEG}|\text{PINC}) \times \Pr(\text{PINC})$.

A predictive distribution for \mathbf{y} can be obtained in a few different ways. Perhaps the simplest method is to combine the posterior distribution of \mathbf{C} with the empirical univariate marginal distributions $\hat{F}_1, \dots, \hat{F}_p$ of the observed data (an alternative method is presented in the Discussion). Using this method, a predictive sample of \mathbf{y} can be obtained as follows:

1. sample $\mathbf{C} \sim p(\mathbf{C}|\mathbf{Z} \in D)$;
2. sample $\mathbf{z} \sim \text{multivariate normal}(\mathbf{0}, \mathbf{C})$;
3. set $y_j = \hat{F}_j^{-1}(z_j)$.

Although this somewhat ad-hoc approach disregards uncertainty in the estimation of F_1, \dots, F_p (for prediction of \mathbf{y} , not for estimation of \mathbf{C}), it provides a predictive joint distribution that matches the observed data in terms of the univariate marginal distributions but has a simple, smooth Gaussian copula representing multivariate dependence. From these predictive samples we can obtain Monte Carlo estimates of various quantities of interest, including a consistent set of conditional distributions on the original scale of the data.

The first column of Figure 5 plots the predictive distribution of DEG conditional on $\text{PINC} = x$ for $x \in \{1, 2, 3, 4, 5\}$. As on the \mathbf{z} -scale, large values of PINC correspond to large values of DEG. The estimated conditional probability of someone not finishing high-school given $\text{PINC} = 5$ is 5%, whereas for $\text{PINC} = 1$ it is 22%, giving an odds ratio of $\text{odds}(\text{DEG} = \text{None}|\text{PINC} = 1)/\text{odds}(\text{DEG} = \text{None}|\text{PINC} = 5) = 5.35$. Similarly, the corresponding odds ratio for having a graduate degree is $\text{odds}(\text{DEG} = \text{Grad}|\text{PINC} = 5)/\text{odds}(\text{DEG} = \text{Grad}|\text{PINC} = 1) = 6.5$. For comparison, the empirical conditional distributions are provided on the same plot. In general the fit is good, with most of the discrepancies occurring in categories of PINC with small sample sizes ($n = 28$ for $\text{PINC} = 1$ and $n = 8$ for $\text{PINC} = 5$). Note that if we were to estimate the above odds ratios using the empirical conditional distributions, we would obtain ratios equal to infinity. In situations such as these, where the sample size is low, we may prefer to estimate conditional distributions with a model that can share information across the categories of a variable, rather than use an empirical estimator having a high sampling variability.

The second column of Figure 5 displays estimated quantiles of $\Pr(\text{INC}|\text{DEG}, \text{PINC})$ for each combination of DEG and PINC. Specifically, each row corresponds to a single value of DEG, and each boxplot within a row corresponds to a single value of PINC. The boxplot provides 5, 25, 50, 75 and 95% quantiles of $\Pr(\text{INC}|\text{DEG}, \text{PINC})$. Note that the boxplots within a row indicate very small increases in INCOME with increasing values of PINC, while differences across rows indicate much larger increases with DEG (changes in the quantiles do not happen continuously due to the binned nature of the raw data). For high-school graduates ($\text{DEG} = 1$), the estimated conditional mean incomes across levels of PINC are {23, 25, 26, 28, 29} in thousands of dollars. For college graduates ($\text{DEG} = 2$), the estimated means are {41, 41, 43, 44, 47}. For these mean calculations, the income in a binned income category was taken as the average of the endpoints of the bin.

For comparison, the actual values of INC for each combination of DEG and PINC are plotted on the corresponding boxplots (data are jittered to allow ties to be distinguished). As before, the main discrepancies occur for combinations of DEG and PINC for which there are few data. Also, the predictive distributions based on the copula model are much smoother than the empirical versions: The empirical conditional means of INC for $\text{DEG} = 1$ and $\text{DEG} = 3$ are {23, 27, 24, 27, 8} and {41, 44, 35, 58, 75} respectively, across increasing levels of PINC. However, several of these empirical means are calculated from as few as 3 or 4 samples.

5. Notions of sufficiency. The extended rank likelihood described above can be viewed as a generalization of marginal likelihood, a standard technique for dealing with nuisance parameters [see Section 8.3 of Severini (2000) for a review]. One benefit of using such a likelihood is a gain in robustness, as inference no longer depends on assumptions about the relationship of the data to the nuisance parameters. Another benefit is a general simplification of the estimation problem, as the need to estimate a potentially high-dimensional set of parameters is eliminated. These benefits come at the cost of potentially losing information about the parameters of interest by only using part of the available data. Ideally, the statistic that generates the marginal likelihood is “partially sufficient” in the sense that it contains all relevant information in the data about the parameter of interest. Various definitions of partial sufficiency have been developed: Fraser (1956) defined S -sufficiency via properties of the marginal and conditional distributions of the statistic and the data. The concept of G -sufficiency was introduced in Barnard (1963) as a general principle for making inference about a parameter of interest when the inference problem remains invariant under a group of transformations. Rémon (1984) developed a generalization of these notions based on profile likelihoods called L -sufficiency, which has been refined and studied by Barndorff-Nielsen (1988, 1999). The general recommendation of these authors is to base inference for a parameter of interest on the sampling distribution of a statistic that is sufficient in some sense.

If F_1, \dots, F_p are all continuous, then there are no ties among the data, and knowledge of $\mathbf{Z} \in D$ provides a complete ordering of $\{y_{1,j}, \dots, y_{n,j}\}$ for each j .

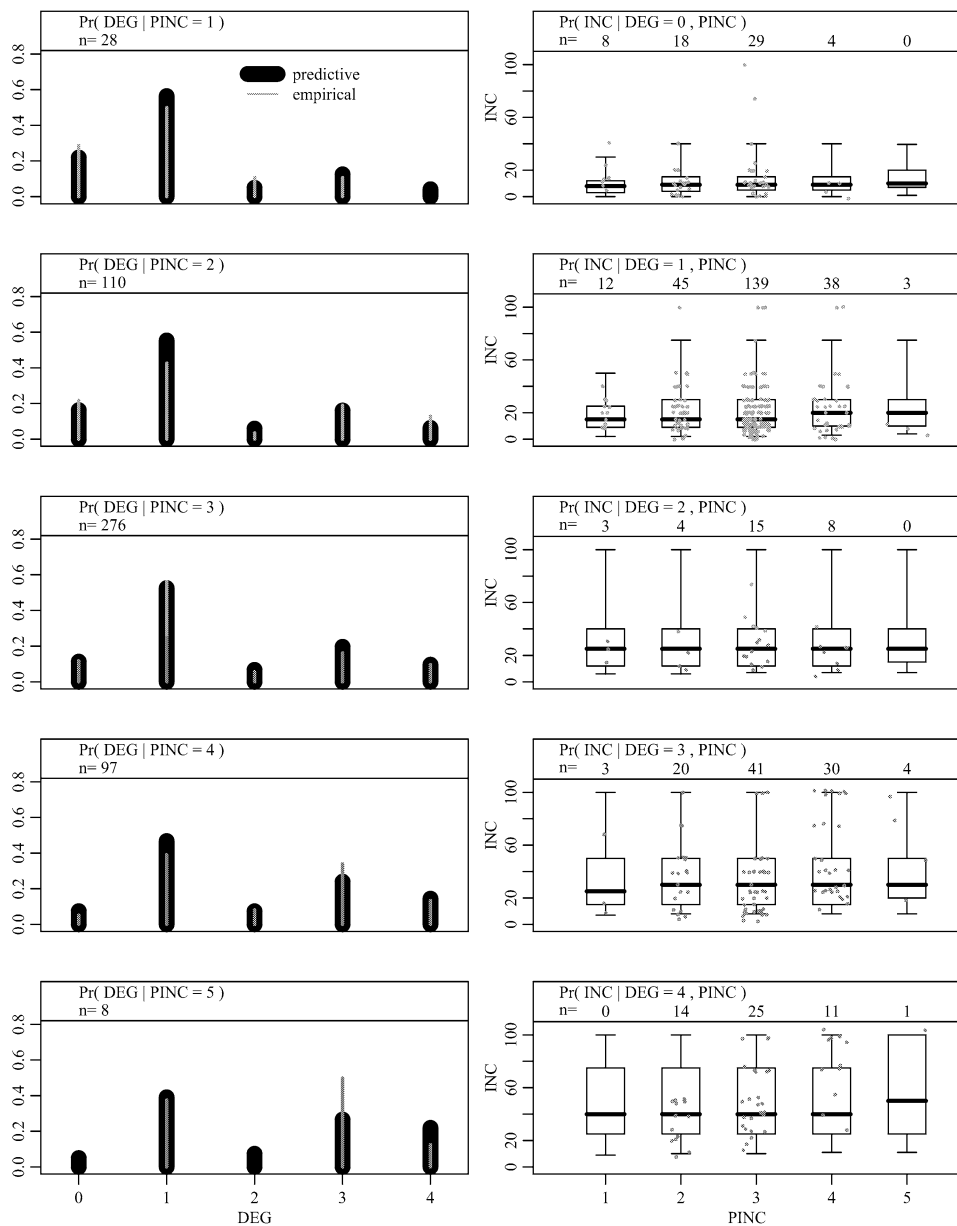


FIG. 5. Empirical and predictive conditional distributions for INC, DEG and PINC.

This information is equivalent to the information contained in the ranks, and so $\Pr(\mathbf{Z} \in D | \mathbf{C})$ is equivalent to the sampling distribution of the multivariate ranks. Following the notation of Rémon (1984), we now show that the ranks $r(\mathbf{Y})$ are a G -sufficient statistic in the sense of Barnard (1963): Let $\mathbf{C} \in \mathcal{C}$ describe the

copula and $\mathbf{F} = \{F_1, \dots, F_p\} \in \mathcal{F}$ the marginal distributions, and so the parameter space is $\Omega = \mathcal{C} \times \mathcal{F}$ and the model space is $\mathcal{P} = \{\Pr(\cdot|\omega) : \omega \in \Omega\}$, where $\Pr(\cdot|\omega)$ is a probability measure on \mathbb{R}^p for each $\omega \in \Omega$. Furthermore, let \mathcal{G} be the group of collections of p continuous strictly increasing functions, so that $\mathcal{G} = \{\mathbf{G} = (G_1, \dots, G_p) : G_j \text{ is a continuous and strictly increasing function on } \mathbb{R}\}$. To each $\mathbf{G} \in \mathcal{G}$ there corresponds a one-to-one function on \mathcal{P} mapping $P(\cdot|\omega)$ to $P(\mathbf{G}^{-1}(\cdot)|\omega)$ and the model space is closed under the action of \mathcal{G} . As a result, \mathcal{G} induces a group $\bar{\mathcal{G}} = \{f_{\mathbf{G}} : \mathbf{G} \in \mathcal{G}\}$ on Ω defined by $P(\cdot|f_{\mathbf{G}}\omega) = P(\mathbf{G}^{-1}(\cdot)|\omega)$.

If the marginals are continuous, the orbits of Ω under $\bar{\mathcal{G}}$ can be put into 1-1 correspondence with \mathbf{C} , and \mathbf{C} is therefore a maximal invariant parameter. Barnard defined a statistic $t(\mathbf{Y})$ to be G -sufficient if it can be put into 1-1 correspondence with the orbits of \mathbb{R}^p under \mathcal{G} . This is the case for the ranks $r(\mathbf{Y})$ of \mathbf{Y} , and so $r(\mathbf{Y})$ is said to be G -sufficient for estimation of \mathbf{C} . For continuous data, the marginal distribution of the ranks is equal to the extended rank likelihood, and so basing inference on this likelihood function can be seen as using all available, relevant information in the G -sufficient sense.

A notion of sufficiency that is more directly related to maximum likelihood estimation is L -sufficiency: In the context of copula modeling, a statistic $t(\mathbf{Y})$ is said to be L -sufficient for \mathbf{C} if

- A1. $t(\mathbf{Y}_0) = t(\mathbf{Y}_1) \Rightarrow \sup_{\{F_1, \dots, F_p\} \in \mathcal{F}} p(\mathbf{Y}_0|\mathbf{C}, F_1, \dots, F_p) = \sup_{\{F_1, \dots, F_p\} \in \mathcal{F}} p(\mathbf{Y}_1|\mathbf{C}, F_1, \dots, F_p)$;
- A2. $p(t(\mathbf{Y})|\mathbf{C}, F_1, \dots, F_p) = p(t(\mathbf{Y})|\mathbf{C})$.

Note that the maximum likelihood estimate of \mathbf{C} and its distribution will be a function only of an L -sufficient statistic, if one exists. If \mathcal{F} contains only continuous marginals, then one can show directly that the ranks $r(\mathbf{Y})$ satisfy A1 and A2 [alternatively, Rémon (1984) shows that a G -sufficient statistic is also L -sufficient]. Thus, in the continuous case, the ranks are G - and L -sufficient, the MLE of \mathbf{C} is a function of the ranks alone, and inference for \mathbf{C} can be based on the distribution of the multivariate ranks, or equivalently, the extended rank likelihood.

If the marginals are allowed to be discontinuous, then the orbits of Ω under $\bar{\mathcal{G}}$ cannot be put into 1-1 correspondence with \mathbf{C} and so \mathbf{C} is not a maximal invariant. The problem is basically that if $F_j(\cdot)$ is a discrete CDF, then $F_j[G_j^{-1}(\cdot)]$ does not range over the space of all CDFs as \mathbf{G} ranges over \mathcal{G} . The ranks are no longer L -sufficient either: Condition A1 holds but A2 is violated because in the discrete case the distribution of the ranks depends on the marginal distributions. This means that estimation based on $\Pr(r(\mathbf{Y})|\mathbf{C}, F_1, \dots, F_p)$ requires estimation of the nuisance parameters F_1, \dots, F_p . This may not be much of an issue if the number of levels of each variable is low, but for moderate numbers of levels we may wonder about the variability of the estimates due to the large number of parameters, or the need to specify a prior distribution for the marginals F_1, \dots, F_p in the context of Bayesian estimation. In contrast, the extended rank likelihood

based on $\Pr(\mathbf{Z} \in D|\mathbf{C})$ does not depend on F_1, \dots, F_p , thereby reducing the number of parameters to estimate and eliminating any need for a prior distribution on F_1, \dots, F_p . Furthermore, the extended rank likelihood is “sufficient” for continuous data but can be used with mixed continuous and discrete data. However, the concern remains that this likelihood may not be making full use of the information in discrete data about the copula parameters of interest. It would be desirable to describe precisely any potential information loss that results from using the rank likelihood as opposed to a full likelihood approach. Such a description could be obtained by comparing the curvatures of the extended rank likelihood and full likelihood surfaces, although the complicated parameter space and likelihood functions make description difficult except for the simplest of cases. A general description of the information properties of the rank likelihood in the context of copula estimation is a current research interest of the author.

6. Discussion. This article has presented an inferential procedure for copula parameters that can be applied to mixed continuous and discrete data. The procedure is based on a type of marginal likelihood, called an extended rank likelihood, which does not depend on the univariate marginal distributions of the data. The procedure therefore allows for the estimation of dependence parameters without the burden of having to estimate the marginal distributions.

The data analyzed in this paper are categorical, although some of the variables have very large numbers of categories. An alternative approach to the analysis of categorical data is log-linear modeling. For categorical data, a log-linear model can potentially provide a more detailed representation of complex dependencies and interactions than can a Gaussian copula model. However, if the number of categories is large and the data are ordinal, a copula model might be more appropriate. The variables AGE, INC and PCHILD in this article have 60, 21 and 19 categories respectively. Stable log-linear analysis of these data would require a coarsening of these and perhaps some of the other variables into many fewer categories, resulting in information loss. In contrast, the semiparametric Gaussian copula approach taken here provides a simple dependence model for data having arbitrary marginal distributions, discrete or continuous.

The Gibbs sampling algorithm described in Section 3.2 is quite simple and performs well for the data analysis in Section 4. However, the fact that each $z_{i,j}$ is being sampled one at a time, and from a distribution that is constrained by the values of $\{z_{k,j} : k \neq i\}$, might raise concerns that the simple Gibbs sampler might mix poorly in some situations. If poor mixing occurs, one remedy is to add Metropolis–Hastings updates that propose simultaneous changes to multiple $z_{i,j}$ ’s. One such procedure that I have implemented is to propose changes to the set $\{z_{i,j} : i = 1, \dots, n\}$ by shuffling the distances between the order statistics. In the examples I have tried, this type of procedure has given reasonable acceptance rates and has reduced autocorrelation.

Inference on the scale of the original data can be obtained with a posterior predictive distribution based on plugging in the empirical univariate marginal distributions as described in Section 3. Alternatively, a predictive distribution which accounts for uncertainty in the univariate marginal distributions can be derived as follows: The Gibbs sampling scheme of Section 3 can be used to generate a joint posterior distribution for $\mathbf{z}_1, \dots, \mathbf{z}_n$ in addition to a new sample \mathbf{z}_{n+1} , for which we do not observe \mathbf{y} -values. However, if $z_{n+1,j}$ is between two other z_j 's having the same y_j value, then $y_{n+1,j}$ must equal y_j as well since the g_j 's are nondecreasing. Technically, this produces a type of interval probability distribution for \mathbf{y} [Weichselberger (1995)], and for continuous data gives univariate marginal predictive probabilities equivalent to the A_n procedure of Hill (1968). For large n , however, this procedure is essentially equivalent to using the the empirical marginal distributions.

Although this article has focused on semiparametric estimation of a Gaussian copula, the notion of rank likelihood is equally applicable to other copula models: Letting $\{p(\mathbf{u}|\theta) : \theta \in \Theta\}$ denote a parametric family of copula densities and $\{y_{i,j} = G_j(u_{i,j}), i = 1, \dots, n, j = 1, \dots, p\}$ be the observed data, the extended rank likelihood for θ is given by $\Pr(\max\{u_{k,j} : y_{k,j} < y_{i,j}\} < u_{i,j} < \min\{u_{k,j} : y_{i,j} < y_{k,j}\}, i = 1, \dots, n, j = 1, \dots, p | \theta)$. Given a prior distribution on θ , posterior inference can be obtained via a Markov chain Monte Carlo algorithm which iteratively resamples values of θ and the $u_{i,j}$'s. However, full conditional distributions for these unknown quantities are generally hard to come by, and an MCMC sampler based on the Metropolis–Hastings algorithm is required for most models.

Code to implement the estimation strategy outlined in Section 3, written in the R statistical computing environment, is provided on-line as supplemental material to this article. A more detailed open-source software package is downloadable from R-archive at the following website: <http://cran.r-project.org/src/contrib/Descriptions/sbgcop.html>

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