Fibonaed Search with Arbitrary First Evaluation

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by

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## ABSTRACT

The Fibonacci search technique for maximizing a unimodal function of one real variable is generalized to the case of a given first evaluation. This technique is then employed to determine the optimal sequential search technique for the maximization of a concave function.

## I. Introduction

A real function $f:[a, b] \rightarrow R$, where $a<b$, is called (1.1) unimodal,
if there are $\underline{x}, \bar{x} \varepsilon[a, b]$ such that $f$ is increasing for $x \leq \underline{x}$ and nonincreasing for $x \geq \underline{x}$, decreasing for $x \geq \bar{x}$ and nondecreasing for $x \leq \bar{x}$ (Fig. 1).
(1.2) If $f$ is unimodal, then the interval $[\underline{x}, \bar{x}]$ consists of all maxima of $f$.

Proof: $f$ is constant in $[x, \bar{x}]$, since it is by definition nonincreasing for $x \geq \underline{x}$ as well as nondecreasing for $x \leq \bar{x}$. If $x<\underline{x}$, then $f(x)<f(\bar{x})$ as $f$ increases in $[a, x]$. If $x>\bar{x}$, then $f(x)<f(\bar{x})$ as $f$ decreases in $[\bar{x}, b]$.-

The definition of unimodality is chosen so as to guarantee that
(1.3) Whenever a wimodal function $\mathbf{f}$ has been evaluaied for two argwents $\mathrm{x}_{1}$ and $\mathrm{x}_{2}$ with $\mathrm{a} \leq \mathrm{x}_{1}<\mathrm{x}_{2} \leq \mathrm{b}$, then some maximum of $f$ must lie in $\left[x_{1}, b\right]$ if $f\left(x_{1}\right) \leq f\left(x_{2}\right)$ and in $\left[a, x_{2}\right]$ if $f\left(x_{1}\right) \geq f\left(x_{2}\right)$.

Proof: If $f\left(x_{1}\right) \geq f\left(x_{2}\right)$, then $x_{1}$ and $x_{2}$ cannot be both in that portion of the interval $[a, b]$ in which the function decreases. In other words, $\bar{x}$ cannot lie to the left of $x_{1}$. Thus $\bar{x} \varepsilon\left[x_{1}, b\right]$,


Figure 1. Example of a unimodal function.
and $\bar{x}$ is a maximum of $f$ by (1.2). Similarly, if $f\left(x_{1}\right) \leq f\left(x_{2}\right)$, then $x \in\left[a, x_{2}\right]$.

A sequential search based on (1.3) will successively narrow down the interval in which a maximum of $f$ is known to lie. Such an Interval is called the
(1.4) interval of wicertainty.

Kiefer [3] has asked the question of optimally sonducting this search, and answered it by developing his well known Fibonacci search.

The Fibonacci search gives a choice of two arguments for which to make the first evaluation. But what happens if by mistake or for some other reason the first evaluation took place at some argument other than the two optimal ones? How does one optimally proceed from there?

In this paper, we shall therefore ask and answer the question for an optimal sequential search plan with given arbitrary first evaluation. The resulting technique is applied to improving on Fibonacci search for functions known to be concave. The technique may also be of interest in the context of stability of Fibonacci search in the presence of round-off errors as studied by Overholt [6] and Boothroydt [1] (see also Kovalik and Osborne [4]).

## 2. Length of Uncertainty

In what follows we assume that $a=0$ and $b=1$. Furthermore, we siall permit zero distances between two arguments of evaluation,
interpreting each such occurrence as evaluating the (not necessarily unique or finite) derivative of the function $f$. A more careful analysis would take into account the amallest justifiable distance c between arguments (Kiefer [3], Oliver and Wilde [5]).

By

$$
L_{k}(x), \quad 0 \leq x \leq 1,
$$

we denote the length to which the interval of uncertainty (1.4) can surely be reduced by $k$ evaluations in addition to a first one at x. Extending a recursive argument due to Johnson [2], we obtain

$$
\begin{equation*}
L_{k}(x)=\min \left\{M_{k}(x), \quad M_{k}(1-x)\right\}, \tag{2.1}
\end{equation*}
$$

where

$$
M_{k}(x):=\min _{x \leq y \leq 1} \max \left\{(1-x) L_{k-1}\left(\frac{1-y}{1-x}\right), y L_{k-1}\left(\frac{x}{y}\right)\right\}
$$

Prooj: Let $y$ denote the first function argument over which we have control. If $x \leq y \leq 1$, then the two possible intervals of uncertainty are $[0, y]$ and $[x, 1]$. The former contains the point of evaluation $x$. The best upper bound for the length of the interval of uncertainty after the remaining $k-1$ evaluations is given by

$$
\begin{equation*}
y L_{k-1}\left(\frac{x}{y}\right) \tag{2.2}
\end{equation*}
$$

Similarly, $y$ is the evaluation point in $[x, 1]$, leading to the best upper bound

## -5-

$$
\begin{equation*}
(1-x) l_{n_{k-1}}\left(\frac{1-y}{1-x}\right) . \tag{2,3}
\end{equation*}
$$

Whether $[0, y]$ or $[x, 1]$ is the first interval of uncertainty depends on the result of the evaluation at $y$ : if $f(y)>f(x)$, then $[0, y]$, if $f(y) \leqslant f(x)$, then $[x, 1]$. Hence the maximum $M_{k}(x)$ of the two expressions (2.2) and (2.3) is the best result achievable if $y$ is selected between $x$ and 1 . The expression

$$
N_{k}(x):-\min _{0 \leq y \leq x} \max \left\{x L_{k-1}\left(\frac{y}{x}\right),(1-y) L_{k-1}\left(\frac{1-x}{1-y}\right)\right\}
$$

analogously describes the best result achievable if $y$ is between 0 and $x$. Since we control the choice of $y$, we can choose the smaller one of these two expressions; and this gives

$$
L_{k}(x)=\min \left\{M_{k}(x), N_{k}(x)\right\}
$$

Introducing for $0 \leq x \leq y \leq 1$,

$$
S_{k}(x, y):=\max \left\{(1-x) L_{k-1}\left(\frac{1-y}{1-x}\right), y L_{k-1}\left(\frac{x}{y}\right)\right\},
$$

we have

$$
M_{k}(x)=\min _{x \leq y \leq 1} S_{k}(x, y), \quad N_{k}(x)=\min _{0 \leq y \leq x} S_{k}(y, x)
$$

Now for $U \leq \mathbf{x} \leq \mathbf{y} \leq 1$,

$$
\begin{equation*}
s_{k}(x, y)=s_{k}(1-y, 1-x) \tag{2,4}
\end{equation*}
$$

Therefore, $N_{k}(x)=M_{k}(1-x)$, and (2.1) is proved. -

At the beginning, the interval of uncertainty is the entire interval in which the function is to be examined. A single function
evaluation at any point $x$ does not change this situation. Hence

$$
L_{0}(x)=1
$$

We then have

$$
M_{1}(x)=\min _{x \leq y \leq 1} \max \{1-x, y\}=\max \{1-x, x\}=M_{1}(1-x)
$$

Hence

$$
L_{1}(x)=\max \{1-x, x\}= \begin{cases}1-x & \text { for } 0 \leq x \leq \frac{1}{2}  \tag{2.5}\\ x & \text { for } \frac{1}{2} \leq x \leq 1\end{cases}
$$

For $k \geq 2$, we claim (Fig. 2):

$$
L_{k}(x)=\left\{\begin{array}{lll}
\frac{1-x}{F_{x}} & \text { for } & 0 \leq x \leq \frac{F_{k-1}}{F_{k+1}}  \tag{2.6}\\
\frac{x}{F_{k-1}} & \text { for } & \frac{F_{k-1}}{F_{k+1}} \leq x \leq \frac{1}{2} \\
\frac{1-x}{F_{k-1}} & \text { for } & \frac{1}{2} \leq x \leq \frac{F_{k}}{F_{k+1}} \\
\frac{x}{F_{k}} & \text { for } & \frac{F_{k}}{F_{k+1}} \leq x \leq 1
\end{array}\right.
$$

where $F_{0}=1, F_{1}=1, F_{2}=2, F_{3}=3, \ldots, F_{k}=F_{k-2}+F_{k-1}$ are the Fibonacci numbers.

Proof: The case $k=2$ requires special treatment. From (2.5),

$$
y L_{1}\left(\frac{x}{y}\right)= \begin{cases}y-x & \text { for }(x, y) \in A_{1}:=\left\{0 \leq \frac{x}{y} \leq \frac{1 / 2}{2}\right\} \\ x & \text { for }(x, y) \in A_{2}:=\left\{\frac{1}{2} \leq \frac{x}{y} \leq 1\right\},\end{cases}
$$



Figure 2. $L_{k}(x)$ for $k=0, \ldots, 4$.

$$
(1-x) L_{1}\left(\frac{1-y}{1-x}\right)=\left\{\begin{array}{lll}
y-x & \text { for } & (x, y) \varepsilon B_{1}:=0 \leq \frac{1-y}{1-x}<\frac{1}{2} \\
1-y & \text { for } & (x, y) \varepsilon B_{2}:=\frac{1}{2} \leq \frac{1-y}{1-x}<1 .
\end{array}\right.
$$

We are now able to determine $S_{2}(x, y)$ in each of the four regions $A_{i} \cap B_{j}$ separately:
$A_{1} \cap B_{1}: \quad S_{2}(x, y)=\max \{y-x, y-x\}=y-x$.
$A_{1} \cap B_{2}: \quad S_{2}(x, y)=\max \{y-x, 1-y\}=1-y$.
$A_{2} \cap B_{1}: \quad S_{2}(x, y)=x$ by (2.4) and (1-y,1-x) \& $A_{1} \cap B_{2}$.
$A_{2} \cap B_{2}: \quad S_{2}(x, y)=\max \{x, 1-y\}= \begin{cases}x & \text { if } y \geq 1-x \\ 1-y & \text { if } y \leq 1-x .\end{cases}$

The sets $A_{i}$ and $B_{j}$ are represented in Fig. 3. They are triangles formed by the line segments marked $A_{i}$ and $B_{j}$, respectively, and the corresponding opposite corner of the triangles. The feathered lines are the minimum lines with respect to constant values of $x$, i.e. if proceeding vertically the intersection with the feathered lines marks a minimum. Tine function $M_{k}(x)$ is defined to be the value of this minimum. Hence

$$
M_{2}(x)= \begin{cases}\frac{1-x}{2} & \text { if } 0 \leq x \leq \frac{1}{3} \\ x & \text { if } \\ \frac{1}{3} \leq x \leq 1\end{cases}
$$

By (2.1) we then have finally

$$
L_{2}(x)=\left\{\begin{array}{ccc}
\frac{1-x}{2} & \text { if } & 0 \leq x \leq \frac{1}{3} \\
x & \text { if } & \frac{1}{3} \leq x \leq \frac{1}{2} \\
1-x & \text { if } & \frac{1}{2} \leq x \leq \frac{2}{3} \\
x & \text { if } & \frac{2}{3} \leq x \leq 1
\end{array}\right.
$$



Figure 3. $S_{2}(x, y)$.

In accordance with (2,6).

The case $k \geq 3$ is now proved by induction over $k$. We have
$y L_{k-1}\left(\frac{x}{y}\right)= \begin{cases}\frac{y-x}{F_{k-1}} & \text { for }(x, y) \in A_{1}:=0 \leq \frac{x}{y} \leq \frac{F_{k-2}}{F_{k}} \\ \frac{x}{F_{k-2}} & \text { for }(x, y) \varepsilon A_{2}:=\frac{F_{k-2}}{F_{k}} \leq \frac{x}{y} \leq \frac{1}{2} \\ \frac{y-x}{F_{k-2}} & \text { for }(x, y) \in A_{3}:=\frac{1}{2} \leq \frac{x}{y} \leq \frac{F_{k-1}}{F_{k}} \\ \frac{x}{F_{k-1}} & \text { for }(x, y) \in A_{4}:=\frac{F_{k-1}}{F_{k}} \leq \frac{x}{y} \leq 1\end{cases}$

$$
\begin{aligned}
& (1-x) L_{k-1}\left(\frac{1-y}{1-x}\right)=0 \frac{y-x}{F_{k-1}} \quad \text { for } \quad(x, y) \varepsilon B_{1}:=0 \leq \frac{1-y}{1-x} \leq \frac{F_{k-2}}{F_{k}} \\
& \frac{1-y}{F_{k-2}} \text { for } \quad(x, y) \varepsilon B_{2}:=\frac{F_{k-2}}{F_{k}} \leq \frac{1-y}{1-x} \leq \frac{1}{2} \\
& \frac{y-x}{F_{k-2}} \text { for }(x, y) \in B_{3}:=\frac{1}{2} \leq \frac{1-y}{1-x} \leq \frac{F_{k-1}}{F_{k}} \\
& \frac{1-y}{F_{k-1}} \quad \text { for } \quad(x, y) \varepsilon B_{4}:=\frac{F_{k-1}}{F_{k}} \leq \frac{1-y}{1-x} \leq 1
\end{aligned}
$$

we determine $S_{k}(x, y)$ in all regions $A_{1} \cap B_{j}$ with $1 \leq j$. For the remaining regions, we use (2.4).
$A_{1} \cap B_{1}: \quad S_{k}(x, y)=\max \left\{\frac{y-x}{F_{k-1}}, \frac{y-x}{F_{k-1}}\right\}=\frac{y-x}{F_{k-1}}$
$A_{1} \cap B_{2}: \quad S_{k}(x, y)=\max \left\{\frac{y-x}{F_{k-1}}, \frac{1-y}{F_{k-2}}\right\}=\frac{1-y}{F_{k-2}}$ since $\quad(x, y) \in B_{2}$
gives $(1-x) F_{k-2} \leq(1-y) F_{k}$, and therefore $(y-x) F_{k-2}=$
$(1-x) F_{k-2}-(1-y) F_{k-2} \leq(1-y) F_{k}-(1-y) F_{k-2}=(1-y) F_{k-1}$.
$A_{1} \cap B_{3}: \quad S_{k}(x, y)=\max \left\{\frac{y-x}{F_{k-1}}, \frac{y-x}{F_{k-2}}\right\}=\frac{y-x}{F_{k-2}}$.
$A_{1} \cap B_{4}: \quad S_{k}(x, y)=\max \left\{\frac{y-x}{F_{k-1}}, \frac{1-y}{F_{k-1}}\right\}=\frac{1-y}{F_{k-1}}$ since $\quad(x, y) \varepsilon E_{4}$
gives $1-x \leq 2(1-y)$ or $y-x \leq 1-y$.
$A_{2} \cap B_{2}: \quad S_{k}(x, y)=\max \left\{\frac{x}{F_{k-2}}, \frac{1-y}{F_{k-2}}\right\}=\frac{1}{F_{k-2}} \max \{x, 1-y\}$.
$A_{2} \cap B_{3}: \quad S_{k}(x, y)=\max \left\{\frac{x}{F_{k-2}}, \frac{y-x}{F_{k-2}}\right\}=\frac{y-x}{F_{k-2}}$ since $\quad(x, y) \in A_{2}$
gives $2 \mathrm{x} \leq \mathrm{y}$ or $\mathrm{x} \leq \mathrm{y}-\mathrm{x}$.
$A_{2} \cap B_{4}: \quad S_{k}(x, y)=\max \left\{\frac{x}{F_{k-2}}, \frac{1-y}{F_{k-1}}\right\}=\frac{1-y}{F_{k-1}}$ since $(x, y) \in A_{2}$
gives $2 x-y \leq 0$, and since $(x, y) \in B_{4}$ gives $-x F_{k-1}+y F_{k} \leq F_{k-2}$.
Indned, multiplying the former inequality by $\mathrm{F}_{\mathrm{k}-1}$ and adding it
to the latter gives $x F_{k-1}+y F_{k-2} \leq F_{k-2}{ }^{\circ}$
$A_{3} \cap B_{3}: \quad S_{k}(x, y)=\max \left\{\frac{y-x}{F_{k-2}}, \frac{y-x}{F_{k-2}}\right\}=\frac{y-x}{F_{k-2}}$.
$A_{3} \cap B_{4}: \quad S_{k}(x, y)=\max \left\{\frac{y-x}{F_{k-2}}, \frac{1-y}{F_{k-1}}\right\}=\frac{1-y}{F_{k-1}}$ since $(x, y) \varepsilon B_{4}$
gives $(1-x) F_{k-1} \leq(1-y) F_{k}$, and therefore $(y-x) F_{k-1}=$
$(1-x) F_{k-1}-(1-y) F_{k-1} \leq(1-y) F_{k}-(1-y) F_{k-1}=(1-y) F_{k-2}$.
$A_{4} \cap B_{4}: \quad S_{k}(x, y)=\max \left\{\frac{x}{F_{k-1}}, \frac{1-y}{F_{k-1}}\right\}=\frac{1}{F_{k-1}} \max \{x, 1-y\}$.
The schematic representation of $S_{k}(x, y)$ then is given by Fig. 4. There are breaks along the line $x=1-y$ in areas $A_{2} \cap B_{2}$ and $A_{4} \cap B_{4}$. The feathered lines are again those boundaries of linearity regions at which $S_{k}$ decreases for fixed $x$. The abscissae of intersection points of feathered lines are therefore critical. The first one of these critical arguments we denote by $v$. It is the abscissa of the intersection


Figure 4. $S_{k}(x, y)$ and critical arguments.
point of the line
(2.7) $\quad \frac{1-y}{1-x}=\frac{F_{k-2}}{F_{k}}$,
which separates $B_{1}$ from $B_{2}$, and the line
(2.8)

$$
\frac{x}{y}=\frac{F_{k-2}}{F_{k}}
$$

which separates $A_{1}$ from $A_{2}$. Elimination of $y$ yields

$$
v=\frac{F_{k-2}}{F_{k}+F_{k-2}}
$$

The next critical argument clearly has the value $\frac{1}{3}$. The third one, which we call $w$, is the intersection of the line

$$
\begin{equation*}
\frac{1-y}{1-x}=\frac{F_{k-1}}{F_{k}} \tag{2.9}
\end{equation*}
$$

which separates $B_{3}$ from $B_{4}$, and the line
(2.10) $\quad \frac{x}{y}=\frac{F_{k-1}}{F_{k}}$,
which separates $A_{3}$ and $A_{4}$. Elimination of $y$ yields

$$
w=\frac{F_{k-1}}{F_{k+1}}
$$

The last critical argument finally has the value $\frac{1}{2}$.

For $0 \leq x-v$ the values of $S_{k}(x, y)$ at the intersection of the vertical through $x$ with the two feathered lines (2.8) and (2.9) are potential minima. The equations of these lines can be rewritten as

$$
\frac{1-y}{F_{k-2}}=\frac{1-x}{F_{k}} \text { and } \frac{1-y}{F_{k-1}}=\frac{1-x}{F_{k}}
$$

As these terms also represent the value of $S_{k}(x, y)$, we have
$M_{k}(x)=\frac{1-x}{F_{k}}$ for $0 \leq x \leq v$.
For $v<x<\frac{1}{3}$ locally minimal points are to be found on line (2.9) and in the area where $S_{k}(x, y)$ assumes the value $\frac{x}{F_{k-2}}$. Now $x \geq v$ gives $x F_{k} \geq(1-x) F_{k-2}$ or $\frac{x}{F_{k-2}} \geq \frac{1-x}{F_{k}}$. Thus $M_{k}(x)=\frac{1-x}{F_{k}}$ for $v \leq x \leq \frac{1}{3}$.

For $\frac{1}{3} \leq x \leq w$ only the line (2.9) is interesting, and $M_{k}(x)$ still takes the value $\frac{1-x}{F_{k}}$.

For $w \leq x \leq \frac{1}{2}$ and beyond the minimum is assumed within the entire line segment which happens to meet the area in which $S_{k}(x, y)=\frac{x}{F_{k-1}}$. Thus finally

$$
M_{k}(x)=\left\{\begin{array}{lll}
\frac{1-x}{F_{k}} & \text { for } & 0 \leq x \leq \frac{F_{k-1}}{F_{k+1}}  \tag{2.11}\\
\frac{x}{F_{k-1}} & \text { for } & \frac{F_{k-1}}{F_{k+1}} \leq x \leq 1,
\end{array}\right.
$$

and (2.6) follows immediately from (2.1).-

Note also that (2.11) implies

$$
L_{k}(x)=\left\{\begin{array}{lll}
M_{k}(x) & \text { for } & 0 \leq x \leq \frac{1}{2}  \tag{2.12}\\
M_{k}(1-x) & \text { for } & \frac{1}{2} \leq x \leq 1
\end{array}\right.
$$

## 3. Search Strategy.

In the previous section, we have determined the optimal length of uncertainty $L_{k}(x)$, which can be achieved in $k$ evaluations in addition to one evaluation at $x \in[0,1]$. We have yet to describe a search strategy
which realizes $L_{k}(x)$. This amounts to specifying the argument $y$ of the first evaluation in addition to $x$. In view of (2.12), this reduces to determining $y$ such that $M_{k}(x)=S_{k}(x, y)$ for given $x$ between 0 and $\frac{1}{2}$, a task which has been performed already while calculating $M_{k}(x)$.

If $0 \leq x \leq v$, then there are two optimal solutions $y$, since $S_{k}(x, y)=\frac{1-x}{F_{k}}$ along both feathered lines in Fig. 4. This nonuniqueness is not surprising. Indeed, if $x=0$, then the evaluation at this argument does not contribute at all towards narrowing the interval of uncertainty, and the optimal continuation is just plain Fibonacci with one evaluation wasted. And in this case there are two optimal arguments, namely the first and second (k-1)-st order Fibonacci points

$$
\frac{F_{k-2}}{F_{k}}, \frac{F_{k-1}}{F_{k}}
$$

(3.1) If $0<x<\frac{F_{k-2}}{F_{k}+F_{k-2}}$, tinen any of the two ( $k-1$ )-st onder Fibonacci points in the interval $[x, 1]$ is an optimal evaluation point

$$
\begin{aligned}
& y_{1}=x+\frac{F_{k-2}}{F_{k}}(1-x)=\frac{x F_{k-1}+F_{k-2}}{F_{k}} \\
& y_{2}=x+\frac{F_{k-1}}{F_{k}}(1-x)=\frac{x F_{k-2}+F_{k-1}}{F_{k}}
\end{aligned}
$$

In both intervals $v \leq x \leq \frac{1}{3}$ and $\frac{1}{3} \leq x \leq w$, the optimal solution $y$ is unique.
-16-
(3.2) If $\frac{F_{k-2}}{F_{k}+F_{k-2}} \leq x \leq \frac{F_{k-1}}{F_{k-2}}$ then the cptimal evaluation point $y$ is the first $(k-1)-s t$ order Fibonacci point of the interval [ $x, 1$ ].
+.ally, if $w \leq x \leq \frac{1}{2}$, then the optimal solutions fill an entire interval.
(3.3) Let $\frac{F_{k-1}}{F_{k-2}} \leq x \leq \frac{1}{2}$. If $y_{0}$ is sucin that $x i_{s}$ the second (k-1)-st order Fibonasci point in $\left[0, y_{0}\right]$, then all points in [1-x, $y_{0}$ ] are optimal evaluation points.

The following rule will always yield an optimal solution:
(3.4) Theorem: An optimal search strategy after an arbitrary first evaluation at $x_{0} \in[a, b]$ is as follows. If $c \leq x \leq d$ are such that [c,d] constitutes the interval of uncertainty after $\ell$ additional evaluations, and if $\mathbf{x}$ is the argumint for which the function has been evaluated already, then:
(1) If $x$ lies betwee. $c$ and the first $(k-l)$-th order Fibonacci points in $[c, d]$, then choose $y$ as the first $(k-\ell)$-th order Fibonacoi point in [x,d].
(1i) If $x$ lies between the two $(k-l)$-th order Fibonacai points of $[c, d]$, tiben choose $y$ as the symmetric image of $x$ in [c,d], i.e. $y=c+d-x$.
(iii) If x lies between d and the second of the two $(k-l)$-th order Fibonacci points in [c,d], then choose $y$ as the second $(k-\ell)$-th order Fibonave point in $[c, x]$.

We shall refer to any sequential search strategy in keeping with
(3.1, 2,3 ), in particular the rule described in Theorem (3.4), as modified Fibonaoci searcin .

If the interior of the interval of uncertainty does not contain an argument at which the function has been evaluated already, then the select! $n$ of the next evaluation by modified Fibonacci search will be the same as in standard Fibonacel search.

## 4. Spies

Intervals of uncertainty with nonoptimal evaluation points may be the result of the following situation. Suppose in maximizing a function we avall ourselves of the services of a "spy". This spy operates as follows: every time an interval of uncertainty has been based on the results of prior evaluations, he is consulted, and as a result of this consultation, the interval of uncertainty may sometimes be further reduced (remaining an interval) without additional evaluations. One cannot expect, however, that the remaining evaluation point (if there is any) is in optimal position within the new interval of uncertainty.

In this case, there is a question whether the additional information should be accepted. It is indeed conceivable that reducing the interval of uncertainty and subsequently continuing from a nonoptimal evaluation point would in the final analysis lead to a larger interval of uncertainty than ignoring the additional information and doing a straightforward Fibonacci search. That this is not so, is essentially the content of the following
(4.1) Iheorem: The optimal policy in the presence of an unpredictable spy is to heed his advice coll! to procecd from the interval of uncertainty so achieved by modificd Fibonacci search with respect to the remaining evaluation point if there is any.

Proof: Let [ $c, d$ ] be the interval of uncertainty as determined by the previous step of the search, and let $[\bar{c}, \bar{d}], c \leq \bar{c} \leq \bar{d} \leq d$, be the interval of uncertainty after consulting the spy. As the spy is unpredictable, there may be no further information forthcoming. This is the worst case, since even if the spy is providing information, it need not be heeded. Thus all we have to show is that we do not worse by proceeding form $[\bar{c}, \bar{d}]$ than from any other interval [ $\left.c^{*}, d^{*}\right]$ with $[c, d] \supseteq\left[c^{*}, d^{*}\right] \supseteq[\bar{c}, \bar{d}]$.

Now let $x$ be the evaluation point in $[c, d]$. Then we distinguish two cases, depending on whether $x \varepsilon[\bar{c}, \bar{d}]$ or not. Suppose $x \in[\bar{c}, \bar{d}]$, then $x \in\left[c^{*}, d^{\star}\right]$. Working on the latter Interval, the best we can do in $\ell$ remaining steps is reducing the uncertainty to

$$
\left(d^{*}-c^{*}\right) L_{\ell}\left(\frac{x-c^{*}}{d^{*}-c^{*}}\right)=\left\{\begin{array}{cc}
\frac{d^{*}-x}{F_{\ell}} & \text { for } 0<\frac{x-c^{*}}{d^{*}-c^{*}}<\frac{F_{\ell-1}}{F_{\ell+1}} \\
\frac{x-c^{*}}{F_{\ell-1}} & \text { for } \frac{F_{\ell-1}}{F_{\ell+1}}<\frac{x-c^{*}}{d^{*}-c^{*}}<\frac{1}{2} \\
\left(=: I_{1}\right) \\
\frac{d^{*}-x}{F_{\ell-1}} & \text { for } \frac{1}{2}<\frac{x-c^{*}}{d^{*}-c^{*}}<\frac{F_{\ell}}{F_{\ell+1}} \\
\frac{x-c^{*}}{F_{\ell}} & \left(=: I_{3}\right) \\
& \text { for } \frac{F_{\ell}}{F_{\ell+1}}<\frac{x-c^{*}}{d^{*}-c^{*}}<1
\end{array} \quad\left(=: I_{4}\right) .\right.
$$

For all $x$ such that $\frac{x-c^{*}}{d^{*}-c^{*}}$ and $\frac{x-\bar{c}}{\bar{d}-\bar{c}}$ are both in one of the four intervals $I_{1}$ above,

$$
\begin{equation*}
\left(d^{*}-c^{*}\right) L_{\ell}\left(\frac{x-c^{*}}{d^{*}-c^{*}}\right) \geq(\bar{d}-\bar{c}) L_{\ell}\left(\frac{x-\bar{c}}{\bar{d}-\bar{c}}\right) \tag{4.2}
\end{equation*}
$$

is immediate. Of the remaining twelve cases, we need consider only six, as the others follow by symmetry. Let

$$
u^{*}:=d^{*}-c^{*} \text { and } \bar{u}:=\bar{d}-\bar{c} .
$$

$\frac{x-c^{*}}{u^{*}} \varepsilon I_{1}$ and $\frac{x-\bar{c}}{\bar{u}} \varepsilon I_{2}: \frac{x-c^{*}}{u^{*}} \leq \frac{F_{\ell-1}}{F_{\ell+1}}$ implies $\frac{d^{*}-x}{u^{*}} \geq \frac{F_{\ell-1}}{F_{\ell+1}}$ Thus $\frac{d^{*}-x}{F_{\ell}} \geq \frac{x-c^{*}}{F_{\ell-1}} \geq \frac{x-\bar{c}}{F_{\ell-1}}$.
$\frac{x-c^{*}}{u^{*}} \varepsilon I_{1}$ and $\frac{x-\bar{c}}{\bar{u}} \varepsilon I_{4}: \quad F_{\ell} \geq F_{\ell-1}$.
Thus $\frac{d^{*}-x}{F_{\ell}} \geq \frac{x-c^{*}}{F_{\ell-1}}>\frac{x-\bar{c}}{F_{\ell-1}} \geq \frac{x-\bar{c}}{F_{\ell}}$.
$\frac{x-c^{*}}{u^{*}} \in I_{2}$ and $\frac{x-\bar{c}}{\bar{u}} \in I_{3} ; \quad x-\bar{c} \geq \frac{\bar{u}}{2}$ gives $x-\bar{c} \geq \bar{d}-x$.
Thus $\frac{x-c^{*}}{F_{\ell-1}}>\frac{x-\bar{c}}{F_{\ell-1}}>\frac{\bar{d}-x}{F_{l-1}}$.
$\frac{x-c^{*}}{u^{*}} \varepsilon I_{2}$ and $\frac{x-\bar{c}}{\bar{u}} \varepsilon I_{4}: \quad F_{\ell} \geq F_{\ell-1}$.
Thus $\frac{x-c^{*}}{F_{\ell-1}} \geq \frac{x-\bar{c}}{F_{\ell-1}} \geq \frac{x-\bar{c}}{F_{\ell}}$.
$\frac{x-c^{*}}{u^{*}} \varepsilon I_{3}$ and $\frac{x-\bar{c}}{\bar{u}} \in I_{4}: \frac{x-c^{*}}{u^{*}} \leq \frac{F_{\ell}}{F_{\ell+1}}$ implies $\frac{d^{*}-x}{u^{*}} \leq \frac{F_{\ell-1}}{F_{\ell+1}}$.
Thus $\frac{d^{*}-x}{F_{\ell-1}} \geq \frac{x-c^{*}}{F_{\ell}} \geq \frac{x-\bar{c}}{F_{\ell}}$

The case in which $x \in[\bar{c}, \bar{d}]$ remains to br considered. Suppose $x<\bar{c}<\bar{d}$. Since we proceed by standard Fibonacci in any interval of uncertainty not containing $x$ in its interior, starting with [ $\bar{c}, \bar{d}]$ is certainly better than starting with $[x, \bar{d}] \subseteq[c . d]$, and we have already seen that $[x, \bar{d}]$ is better than any interval between $[c . d]$ and $[x, \bar{d}]$.

A spy is called
(4.3) almost unpredictable , if for each subinterval [ $\left.c^{*}, d^{*}\right]$ of the interval of uncertainty [c.d], which results from the evaluation pattern, the spy has the option of reducing it only to an interval $[\bar{c}, \bar{d}]$ which contains [ $c *, d *]$. Plainly, we still have
(4.4) Trieonem: Tile optimal policy in the presence of an almost unprodictaile spy is to ilecalins advice and to proceed from the interval of uncertaint: so aciieved by modified Fibonacai search with respect to til remaining evaluation point if there is any.

## 5. Concave Functions

We shall see that a "spy" is available if the unimodal function to be maximized is known to be concave.

A function $f:[a, b] \rightarrow R$ is
consave
in $[a, b]$ if

$$
f(\lambda x+\mu y)>\lambda f(x)+\mu f(y)
$$

holds for all $x, y \in[a, b], \lambda, \mu \geq 0$ and $\lambda+\mu=1$. The function is

## strietly concave

if

$$
f(\lambda x+\mu y)>\lambda f(x)+\mu f(y)
$$

holds for all $x, y, \lambda, \mu$ which are as above and satisfy in addition $x \neq y$ and $\lambda, i>0$. We state without proof that
overu upper semicontinuous concave fronction on $[a, b]$
is mimodal.

Without the additional hypothesis of upper semicontinuity. (5.3) does not hold as there are concave functions without maximum on $[a, b]$.

Now consider two points $P_{i}:=\left(x_{i}, f\left(x_{i}\right)\right) \quad P_{j}:=\left(x_{j}, f\left(x_{j}\right)\right)$, $x_{i}<x_{j}$, of the graph

$$
G(f):=|(x, f(x)): x \in[a, b]|,
$$

and let $L_{i j}$ be the straight line through $P_{i}, P_{j}$. Concavity implies that the graph of $f$ lies not below $L_{i j}$ in $\left[x_{i}, x_{j}\right]$ and not above $L_{i j}$ in the remainder of the interval $[a, b]$. Hence if five points of the graph $G(f)$,

$$
P_{0}:=\left(x_{0}, f\left(x_{0}\right)\right), \ldots, P_{4}:=\left(x_{4}, f\left(x_{4}\right)\right)
$$

with

$$
x_{0}<x_{1}<x_{2}<x_{3}<x_{4}
$$

and

$$
f\left(x_{2}\right) ; f\left(x_{1}\right), \quad 1=1,2,
$$

are known, then that part of the graph $G(f)$ that lies above $\left[x_{1}, x_{3}\right]$ is contained in the union of the two triangles $\Delta_{1}$ and $\Delta_{2}$ formed by $\mathrm{L}_{01}, \mathrm{~L}_{12}, \mathrm{~L}_{23}$ and $\mathrm{L}_{12}, \mathrm{~L}_{23}, \mathrm{~L}_{34}$, respectively. $\mathrm{f}\left(\mathrm{x}_{2}\right)$ is a lower bound for the maximum value of $f$. Therefore
a maximum of $f$ must lie in the intersection of $\Delta_{1} \cup \Delta_{2}$ with the horizontal through $\mathbf{p}_{2}$. (Fig. 5)

The information that the function $f$ is concave can thus be used in order to reduce the interval of uncertainty.

In order to complete the description of the proposed search method for concave functions, a few more conventions are necessary. At the ends of the interval $[a, b]$, we pretend that the function has value $-\infty$, and if it has been evaluated there, we pretend that there are two values for the same abscissa, one of the values being Infinite. Three evaluations will therefore reduce the interval of uncertainty as indicated in Fig. 6.

We proceed to show that
concality is an almost unpredictable spy (4.3)

Proof: Suppose we have five points

$$
a \leq x_{0} \leqslant x_{1}<x_{2}<x_{3} \leq x_{4} \leq b,
$$

where $x_{0}$ and $x_{1}$ may both coincide with the left end-point $a$, and similarly $x_{3}$ and $x_{4}$ may coincide with the right end-point $b$. For


Figure 5. Bounding a concave function by chords.


Figure 6. Three evaluations.
$x_{1}$ with $1 \notin 0,4$, we have finite function values $f\left(x_{1}\right)$, whereas $f\left(x_{0}\right)$ and $f\left(x_{4}\right)$ are possibly infinitc, provided $x_{0}=a$ or $x_{4}=b$, respectively. We suppose furthermore that

$$
f\left(x_{0}\right)<f\left(x_{1}\right)<f\left(x_{2}\right)<f\left(x_{3}\right)<f\left(x_{4}\right)
$$

Let $[c, d]$ be the interval of uncertainty that results in view of concavity. Observe that

$$
x_{2} \varepsilon[c, d]
$$

Now select any $x$ with $c \leq x \leq x_{2}, x_{1}<x$, and assume that $f(x)$ satisfies

$$
f(x)=f\left(x_{2}\right)+s\left(x-x_{2}\right)
$$

for some $S$ with

$$
0 \leq s \leq \frac{f\left(x_{1}\right)-f\left(x_{1}\right)}{x_{2}-x_{1}}
$$

Then the new interval of uncertainty taking concavity into account will be of the form $[\vec{c}, d]$, where

$$
\bar{c}=x+\frac{\hat{v}\left(x-x_{1}\right)\left(x_{2}-x\right)}{f\left(x_{2}\right)-f\left(x_{1}\right)-\delta\left(x_{2}-x\right)}>x
$$

The difference $\bar{c}-x$ measures the reduction of uncertainty due to concavity. Now by definition of $\delta$,

$$
\bar{c}-x \leq \frac{\delta\left(x-x_{1}\right)\left(x_{2}-x\right)}{f\left(x_{2}\right)-f\left(x_{1}\right)-\delta\left(x_{2}-x_{1}\right)} \leq \frac{\delta\left(x_{2}-x_{1}\right)^{2}}{f\left(x_{2}\right)-f\left(x_{1}\right)-\delta\left(x_{2}-x_{1}\right)}
$$

and the last term, independent of $x$, goes to zero as $\delta$ goes to zero. In other words, the contribution of concavity beyond unimodality becomes arbitrarily small as $f(x)$ approaches $f\left(x_{2}\right)$ from below, but not

## assuming it.

What happens if $f(x)$ approaches $f\left(x_{2}\right)$ from above? Assume $\delta>0$ and

$$
f(x)=f\left(x_{2}\right)-\delta\left(x-x_{2}\right)
$$

If $m>0$ denotes the, - possibly infinite - , slope of line $L_{01}$, then

$$
\begin{aligned}
& \bar{c}:= \begin{cases}c+\frac{f(x)-f\left(x_{2}\right)}{m} & \text { for } m=+\infty \\
c & \text { for } m=\infty\end{cases} \\
& \bar{d}:=x_{2}+\frac{f(x)-f\left(x_{2}\right)}{f\left(x_{3}\right)-f\left(x_{2}\right)}
\end{aligned}
$$

determine the new interval $[\bar{c}, \bar{d}]$ of uncertainty, taking into account concavity. The reduction beyond unimodality is the sum of $\bar{c}-c$ and $x_{2}-\bar{d}$. Now

$$
\begin{aligned}
& \bar{c}-c=\frac{-\delta\left(x-x_{2}\right)}{m} \leq \frac{\delta\left(x_{2}-x_{1}\right)}{m} \\
& x_{2}-\bar{d}=\frac{\delta\left(x-x_{2}\right)}{f\left(x_{3}\right)-f\left(x_{2}\right)} \leq \frac{\delta\left(x_{2}-x_{1}\right)}{f\left(x_{2}\right)-f\left(x_{3}\right)},
\end{aligned}
$$

and again the gain beyond unimodality becomes arbitrarily small as $f(x)$ approaches $f\left(x_{2}\right)$ from above without assuming it.

The symmetric argument can be carried out for $x_{2}<x \leq d$ and $x<x_{3}$. This then will establish concavity as an almost independent spy.-

## Combining (5.5) with Theorem (4.4) yields

(5.6) Theorem: Using concavity as a spy in a modified Fibonacci search is the optimal strategy for reducing the interval of uncertainty of concave functions.

## 6. Final Remarks

From the proof of Theorem (5.6) it is apparent that the proposed search strategy for concave function is "rin sup" rather than "min max". In other words, the problem is not well set. Indeed, it makes probably more sense for concave functions to decrease the uncertainty in the value of the minimum than in its location.

A similar argument as was used for proving (5.5) can be emploved to show that fure each $\varepsilon>0$ and each positive integer $k$ there is a concave function for which the reduction of uncertainty by optimal search is improved by less than $\varepsilon$ over unimodal search. In general, however, the improvement will be drastic, in part 1 cular if the function is well rounded, so to speak, and has a maximum in the interior.

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