

# Generation of Concurrency Control Code using Discrete-Event Systems Theory

Christopher Dragert, Juergen Dingel, Karen Rudie

Presented by David Gerhard

# Motivation

- Optimal usage of today's Multi-core systems requires parallel executable Software
- Efficient and correct concurrent source code is hard to write and debug

→ facilitate development of concurrent source code

# Introduction

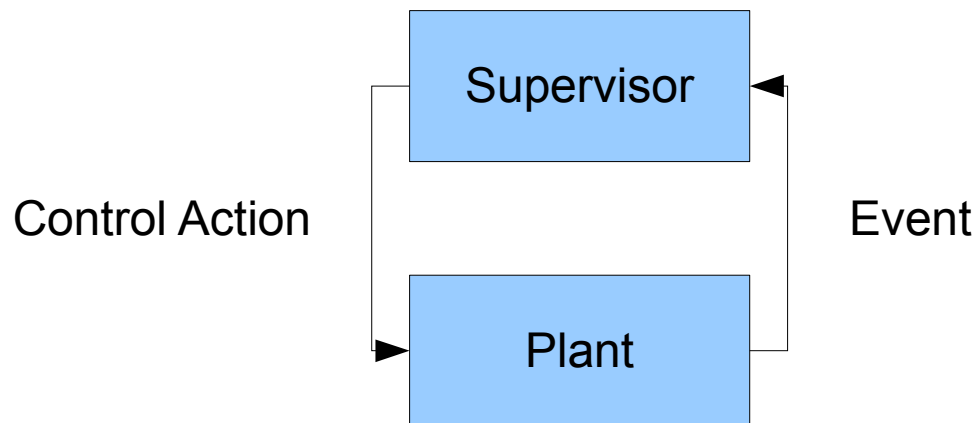
- Automatic generation of concurrency control code
  - Input
    - Source code without concurrency control
    - Informal specification of the desired concurrent behaviour
  - Output
    - Source code with concurrency controls

# Introduction

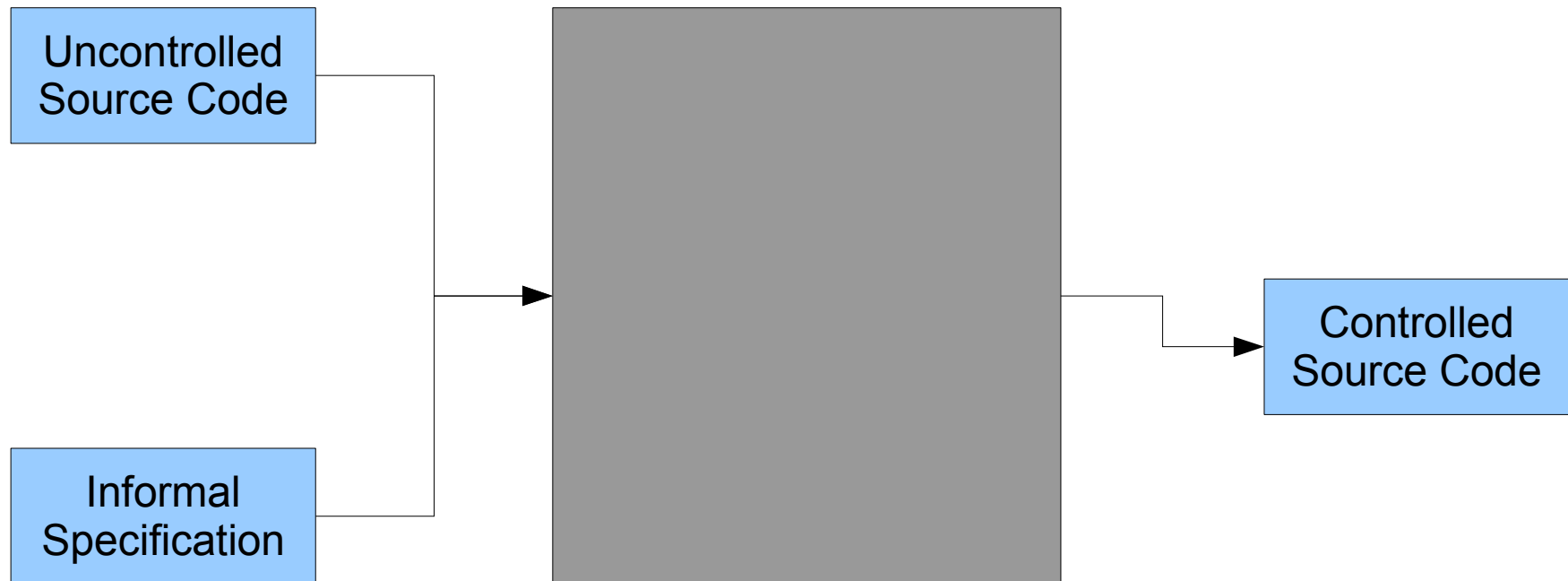
- Aims
    - No Deadlocks
    - No Starvation
    - Minimally restrictive
- using control theory (Discrete-event System)

# DES - Supervisor-Plant

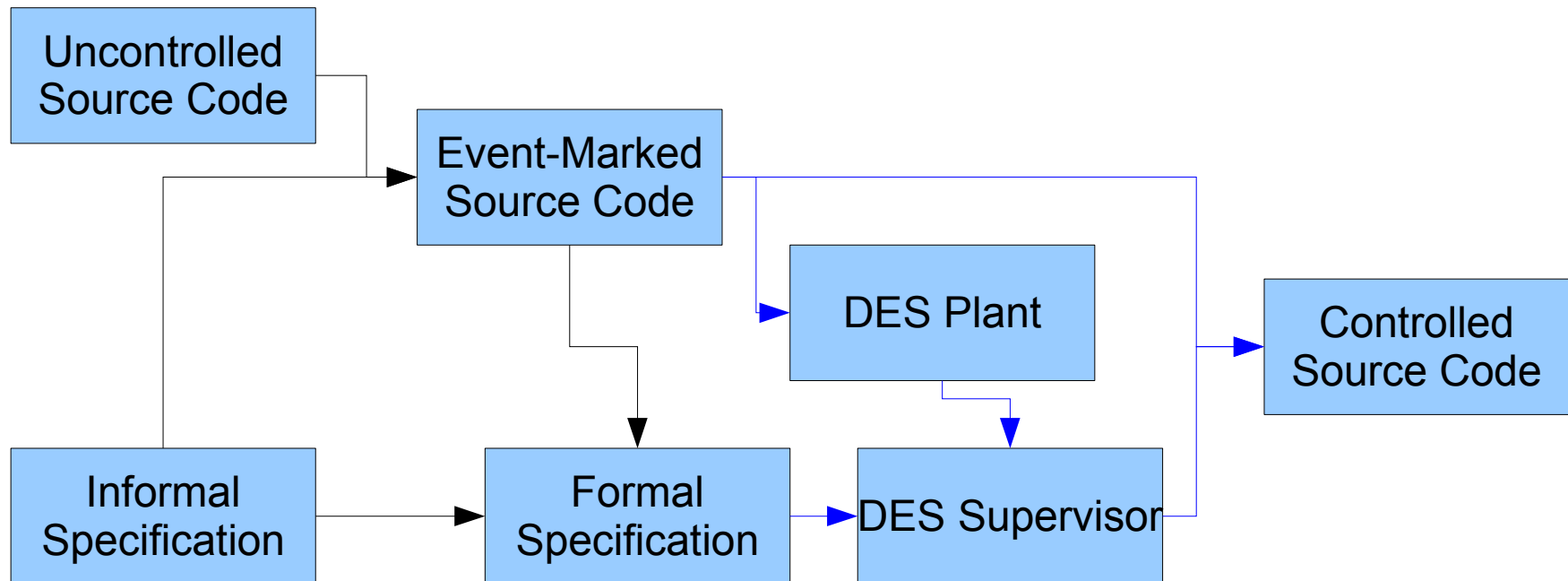
- System(Plant) modelled as a finite-state automaton (FSA)
  - Transitions in FSA are called events
    - Events can be controllable or uncontrollable
- Supervisor modelled as a FSA
  - Enables or disables controllable events



# Process Overview



# Process Overview



# Relevant Events

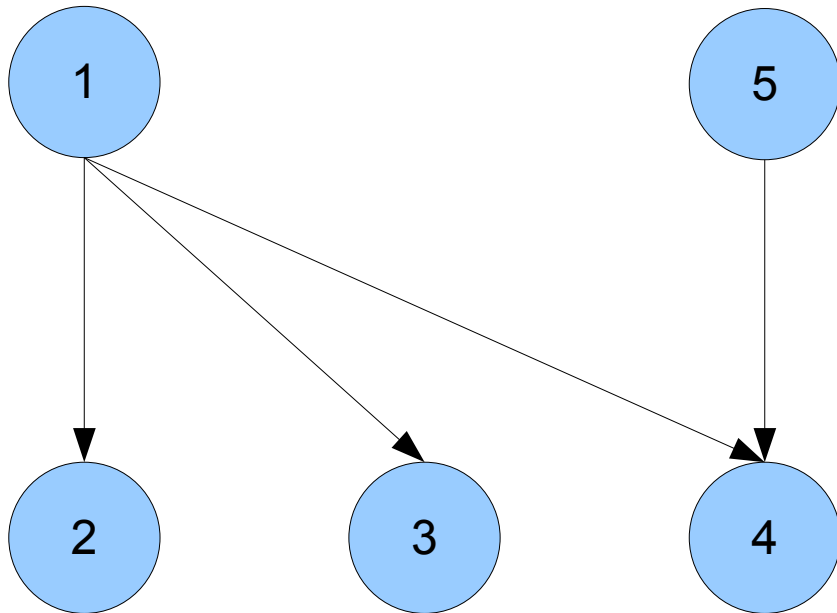
- Find relevant events for concurrency control
  - Example
    - Enter/Exit Critical Section → relevant
    - Accessing shared variable → non-relevant
- Mark events in the source code
- Differentiate controllable and uncontrollable events



# Example

- 5 Threads with dependencies

- $1 \rightarrow 2,3,4$
- $5 \rightarrow 4$



Code example for Thread 3:

```
public void run() {  
    // relevant event: T3-start  
    System.out.println(id);  
    doWork();  
}
```

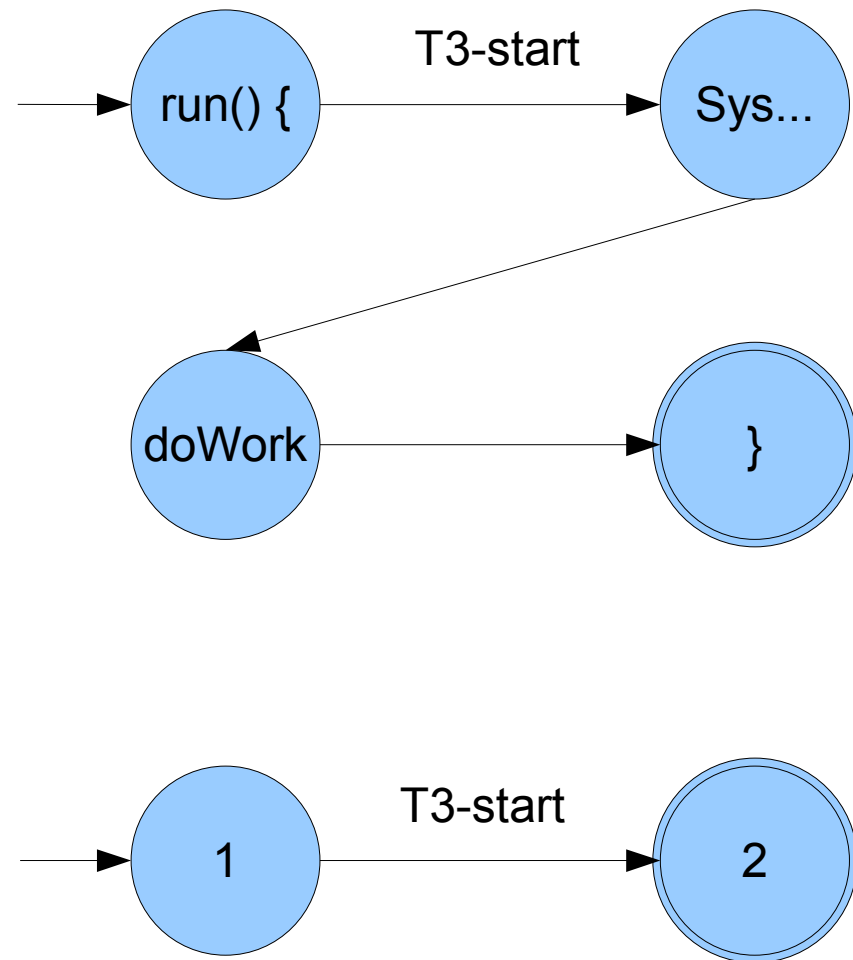
# DES Plant

- Build a Finite-state automaton (FSA) representing all possible event sequences for each Thread
  - Build control-flow graph(CFG) from source code
  - Reduce CFG
    - All relevant events remain
    - All non-relevant events important for CFG structure remain

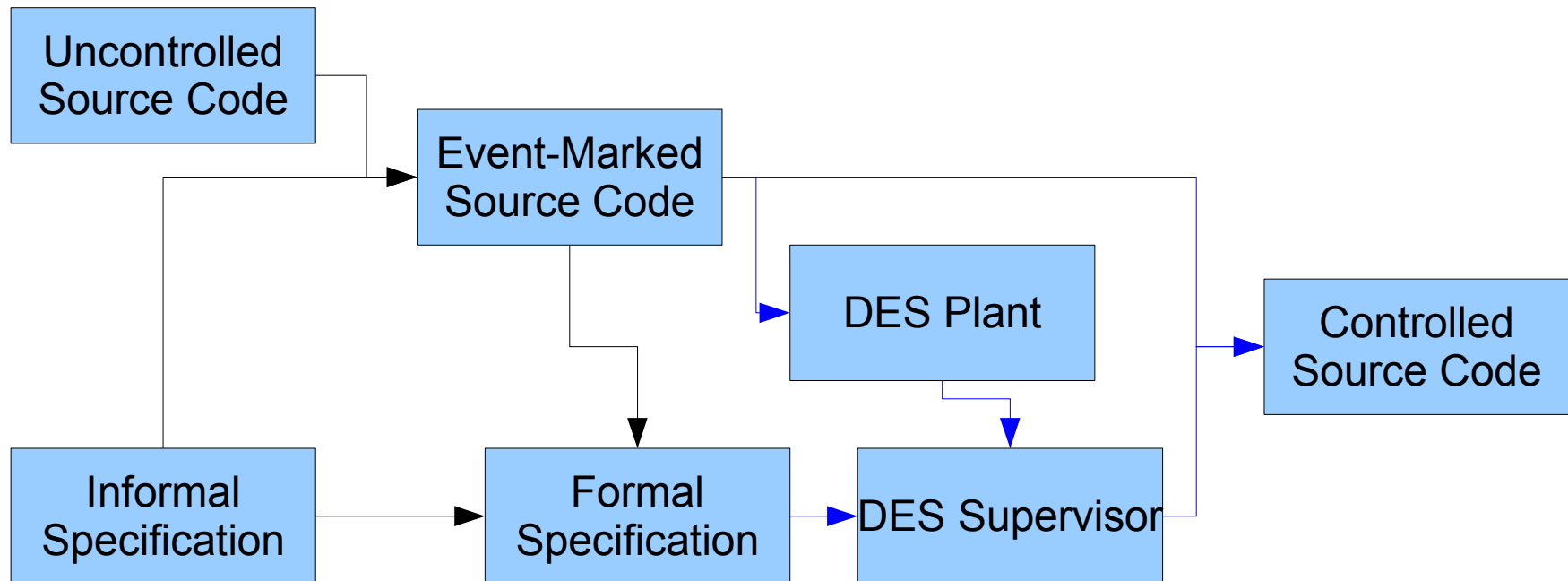
# Example

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public void run() {  
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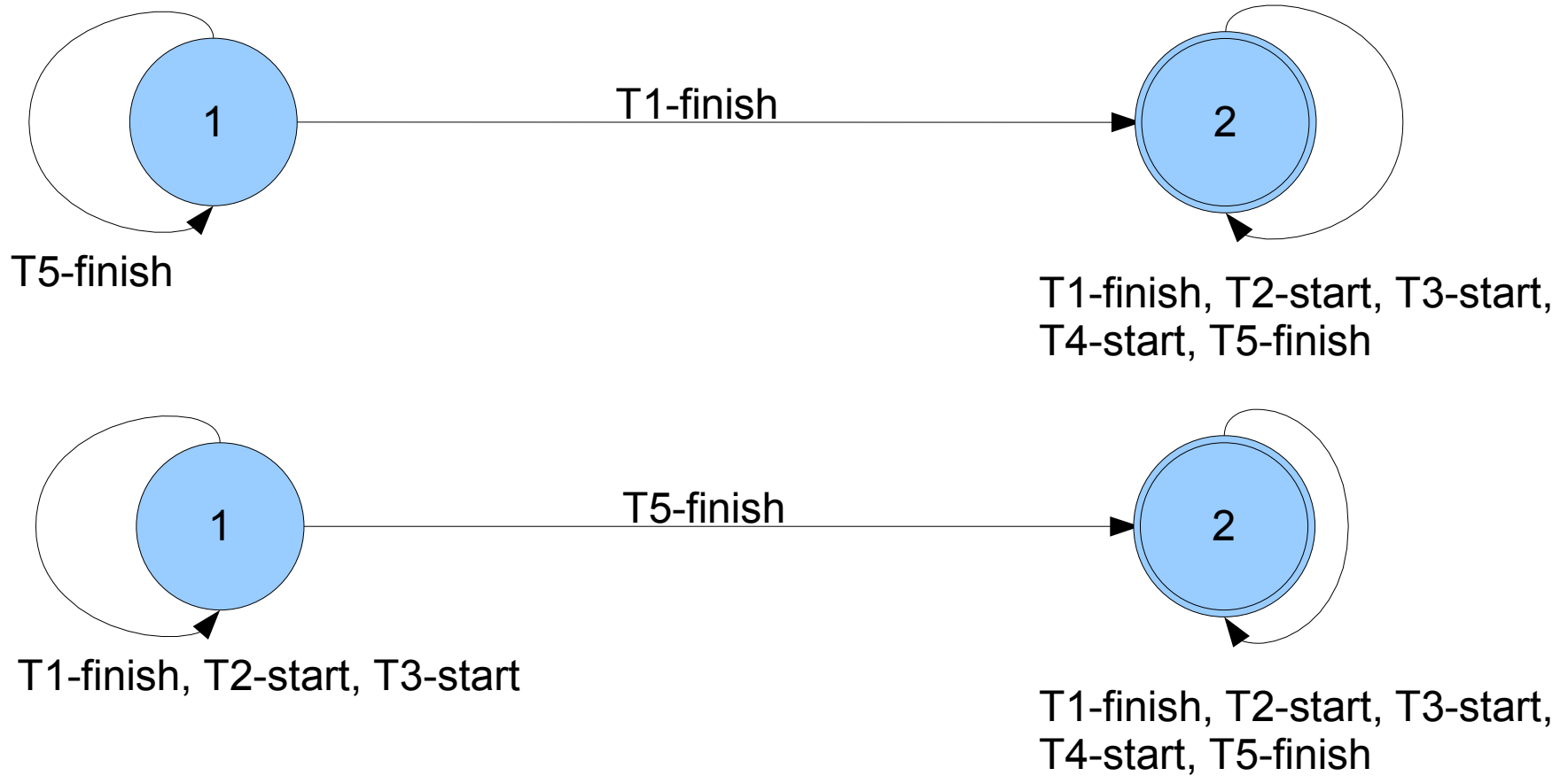
# Process Overview



# Formal Specification

- Specifies the allowed subset of event sequences
  - FSA for each restriction
  - Only restrictive

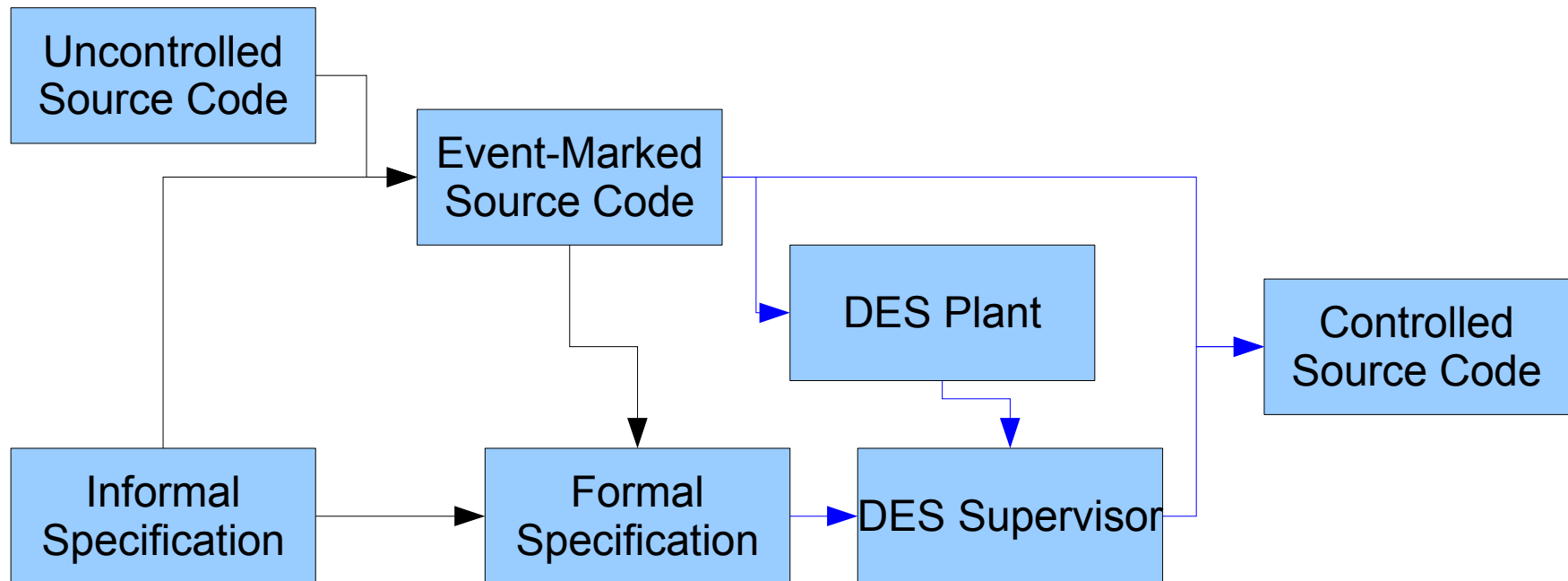
# Example



# DES Supervisor

- Only one supervisor (simplification)
- Different FSA's need to be combined into a monolithic specification
  - Scalability issue

# Process Overview





# Code Generation

- Supervisor needs to block non allowed controllable events
  - Generates a Semaphore for each controllable event set to the initial state
  - Supervisor state changing function enables/disables controllable events

# Example – Thread 3

//relevant event: T3start

while (true) {

    if(Synchronizer.stateChangeTest("T3start",  
    Synchronizer.T3start))

        break;

    Synchronizer.T3start.acquireUninterruptibly();

    Synchronizer.T3start.release();

}

# Example – Supervisor I

```
public static synchronized Boolean stateChangeTest(String event,
Semaphore eventBlocker) {
    if (!(eventBlocker == null)) {
        if (!eventBlocker.tryAcquire()) {
            return false;
        }
        eventBlocker.release();
    }
    changeSupervisorState(event);
    return true;
}
```

# Example – Supervisor II

```
private static void changeSupervisorState(String event) {  
    if (event.equals("T1finish")) {  
        switch(Synchronizer.stateTracker) {  
            case(0):  
                Synchronizer.T3start.release();  
                Synchronizer.T2start.release();  
                Synchronizer.stateTracker = 1;  
            break;  
            case(1):  
                ...  
            ...  
        }  
    }  
}
```

# Verification

- Discrete-event theory is proven correct and non blocking
- Formal proof for algorithm is still needed
- Modelchecker (Java Pathfinder)
- Input not reliable!

# Limitations

- No dynamic threads generation allowed
- Monolithic supervisor not very efficient
- Starvation not properly addressed

# Conclusion

- DES theory can be applied to concurrency
- Chosen FSA-based version of DES not expressive enough
- Further work needed

# Questions

?