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§ 1. Introduction

In this paper we solve the subfield problem of a generic cubic polynomial g(t, Y)for the symmetric group \mathfrak{S}_3 of degree 3 by using a certain sextic polynomial $P(\mathfrak{t}, Z)$ which is generic for the direct product $(\mathfrak{S}_3)^2$ of the two groups \mathfrak{S}_3 . We also study the descent genericity of the polynomial $P(\mathfrak{t}, Z)$ explicitly. See § 2 for the notion about the genericity of a polynomial and the subfield problem of the polynomial.

Let k be a field with $char(k) \neq 2, 3$ and k(t) the rational function field over k in one variable t. Let g(t, Y) be a cubic polynomial over k(t) of the form

$$g(t, Y) = Y^{3} - tY - t = Y^{3} - t(Y+1).$$

Let $k(\mathfrak{t})$ be the rational function field over k with two variables t_1 and t_2 where $\mathfrak{t} = (t_1, t_2)$. We define a sextic polynomial $P(\mathfrak{t}, Z) \in k(\mathfrak{t})[Z]$ over $k(\mathfrak{t})$ by

$$P(\mathfrak{t}, Z) = Z^6 - r_1 Z^4 + r_1 Z^3 + r_0 Z^2 - 2r_0 Z + r_0$$

where r_1 and r_0 are rational functions in k(t) such that

$$r_1 = \frac{t_1 t_2 (2(t_1 + t_2) - 27)}{(t_1 - t_2)^2}, \quad r_0 = \frac{t_1^2 t_2^2}{(t_1 - t_2)^2}$$

Let b_1 and b_2 be two elements in an extension K of k such that $b_1b_2(4b_1-27)(4b_2-27)(4b_2-27)(4b_1b_2-27(b_1+b_2))(b_1-b_2) \neq 0$. Let M_i denote the minimal splitting fields of $g(b_i, Y)$ over K and put $n_i = [M_i : K]$, respectively. When a polynomial $F \in K[X]$ over K satisfies $F = \prod_{j=1}^r F_j$ for irreducible polynomials F_j over K of degree d_j with $1 \leq d_1 \leq d_2 \leq \cdots \leq d_r$, we say that the decomposition type $\mathcal{DT}_K F$ of F over K is $[d_1, d_2, \ldots, d_r]$.

Theorem 1.1 (Proposition 3.2). We assume $n_1 \leq n_2$.

(1) If $n_1 = 1$, then $M_1 \subseteq M_2$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [n_2, n_2, \dots, n_2]$.

(2) When $n_1 = n_2 = 2$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,1,2,2] & \text{if and only if } M_{1} = M_{2}, \\ [2,4] & \text{if and only if } M_{1} \neq M_{2}. \end{cases}$$

(3) If $n_1 = 2$ and $n_2 = 3$, then $M_1 \cap M_2 = K$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$.

(4) When $n_1 = 2$ and $n_2 = 6$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [3,3] & \text{if and only if } M_{1} \subset M_{2}, \\ [6] & \text{if and only if } M_{1} \not\subset M_{2}. \end{cases}$$

(5) When $n_1 = n_2 = 3$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,1,1,3] & \text{if and only if } M_{1} = M_{2}, \\ [3,3] & \text{if and only if } M_{1} \neq M_{2}. \end{cases}$$

- (6) If $n_1 = 3$ and $n_2 = 6$, then $M_1 \cap M_2 = K$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$.
- (7) When $n_1 = n_2 = 6$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,2,3] & \text{if and only if } M_{1} = M_{2}, \\ [3,3] & \text{if and only if } [M_{1} \cap M_{2} : K] = 2 \\ [6] & \text{if and only if } M_{1} \cap M_{2} = K. \end{cases}$$

Corollary 1.2. With the same notation as in Theorem 1.1, the equation $M_1 = M_2$ holds if and only if $P(\mathfrak{b}, Z)$ has a solution in K.

Proposition 1.3 (Corollary 2.7). The sextic polynomial $P(\mathfrak{t}, Z)$ is generic for $(\mathfrak{S}_3)^2$ over k.

The exceptional case that $b_1b_2(4b_1-27)(4b_2-27)(4b_1b_2-27(b_1+b_2))(b_1-b_2) = 0$ is as follows.

Lemma 1.4 (Lemma 3.8). We have $M_i = K$ if $b_i(4b_i - 27) = 0$. When $(4b_1b_2 - 27(b_1 + b_2))(b_1 - b_2) = 0$, it holds that $M_1 = M_2$.

REMARK 1.5. By using an other method with the representation of a cubic field embedding in the ring of 3×3 matrices over \mathbb{Q} , Miyake [6] gave a solution for the isomorphism problem of g(t, Y) over \mathbb{Q} , that is, a condition so that $\operatorname{Spl}_{\mathbb{Q}}g(b_1, Y) =$ $\operatorname{Spl}_{\mathbb{Q}}g(b_2, Y)$ for $b_1, b_2 \in \mathbb{Q}$. His result is one of the motivations of this paper. In § 2 we recall the notion on the genericity of a regular polynomial and introduce the subfield problem of the polynomial. We show the genericity of $P(\mathfrak{t}, Z)$ for $(\mathfrak{S}_3)^2$ over k (Proposition 1.3). In § 3 we study the specialization of $P(\mathfrak{t}, Z)$ and solve the subfield problem of g(t, Y) (Theorem 1.1). In § 4 we exhibit the discriminants of the polynomials described in § 2. In § 5 we study the descent genericity of $P(\mathfrak{t}, Z)$ and present explicit generic polynomials $P_H(\mathfrak{c}, Z)$ for all subgroups H of $(\mathfrak{S}_3)^2$ as degenerations of $P(\mathfrak{t}, Z)$.

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§ 2. Genericity of the sextic polynomial

We first recall the notion on the genericity of a regular polynomial (cf. Jensen-Ledet-Yui [3]) and introduce the subfield problem of the polynomial. Let k be a field and G a finite group. The rational function field $k(t_1, t_2, \ldots, t_m)$ over k with m variables t_1, t_2, \ldots, t_m is denoted by $k(\mathfrak{t})$ where $\mathfrak{t} = (t_1, t_2, \ldots, t_m)$. For a polynomial $F(X) \in K[X]$ over a field K let us denote by $\text{Spl}_K F(X)$ the minimal splitting field of F(X) over K. We say a polynomial $F(\mathfrak{t}, X) \in k(\mathfrak{t})[X]$ is a kregular G-polynomial or a regular polynomial over k for G if $L = \operatorname{Spl}_{k(\mathfrak{t})} F(\mathfrak{t}, X)$ is a Galois extension with $\operatorname{Gal}(L/k(\mathfrak{t})) \simeq G$ and $L \cap \overline{k} = k$ where \overline{k} is an algebraic closure of k. For example, if n is a positive integer greater than 2, then the Kummer polynomial $X^n - t \in \mathbb{Q}(t)[X]$ is a regular polynomial for the cyclic group \mathcal{C}_n of order n not over \mathbb{Q} but over $\mathbb{Q}(\zeta_n)$ where ζ_n is a primitive n-th root of unity in $\overline{\mathbb{Q}}$. A k-regular G-polynomial $F(\mathfrak{t}, X) \in k(\mathfrak{t})[X]$ is called to be generic over k if $F(\mathfrak{t}, X)$ yields all the Galois G-extensions containing k, that is, for every Galois extension L/K with $\operatorname{Gal}(L/K) \simeq G$ and $K \supseteq k$ there exists a K-specialization $\mathfrak{a} = (a_1, a_2, \dots, a_m), a_i \in K$ so that $L = \operatorname{Spl}_K F(\mathfrak{a}, X)$. The subfield problem for a regular polynomial $F(\mathfrak{t}, X)$ is to determine in terms of $\mathfrak{a} = (a_1, a_2, \ldots, a_m)$ and $\mathfrak{b} = (b_1, b_2, \dots, b_m)$ whether $\mathrm{Spl}_K F(\mathfrak{a}, X) \subseteq \mathrm{Spl}_K F(\mathfrak{b}, X)$ or not.

In the following we construct the sextic polynomial $P(\mathfrak{t}, Z)$ and show the genericity of $P(\mathfrak{t}, Z)$. Let k be a field with $\operatorname{char}(k) \neq 2, 3$ and k(s) the rational function field over k in one variable s. Let f(s, X) be a cubic polynomial over k(s) of the form

$$f(s,X) = X^3 - 3sX^2 - (3s+3)X - 1 = X^3 - 3X - 1 - 3s(X^2 + X),$$

which is called the simplest cubic polynomial of Shanks type [10]. It is known that f(s, X) is generic for C_3 over k (cf. [9]). Let $A_2(X)$ and $A_3(X)$ be linear fractionals over k such that $A_2(X) = -X - 1$ and $A_3(X) = -(X + 1)/X$. Then one has $A_2^2(X) = A_3^3(X) = X$. It is easy to check

Lemma 2.1. We have $f(A_2(s), X) = -f(s, A_2(X))$. Every solution $x \in \overline{k(s)}$ of f(s, X) = 0 satisfies that $f(s, X) = (X - x)(X - A_3(x))(X - A_3^2(x))$.

Let us recall a descent Kummer theory studied in a previous paper [5] (see also Morton [7], Chapman [1] and Ogawa [8]). Let $+_T$ be a composite law on $T = \mathbb{P}^1 - \{\zeta, \zeta^{-1}\}$ such that $a_1 +_T a_2 = (a_1 a_2 - 1)/(a_1 + a_2 + 1)$ for $a_1, a_2 \in T$ where ζ is a primitive third root of unity in \overline{k} . Then T is an abelian group with $+_T$. In fact, Tis an algebraic torus of dimension 1 with group isomorphism $\varphi: T \to \mathbb{G}_m, a \mapsto (a - \zeta)/(a - \zeta^{-1})$ over $k(\zeta)$. The composite law $+_T$ satisfies $a_1 +_T a_2 = \varphi^{-1}(\varphi(a_1)\varphi(a_2))$. The identity 0_T of T is $\infty = \varphi^{-1}(1)$. The inverse $-_T a$ of $a \in T$ is equal to -a - 1. The 3-torsion subgroup $T[3] = \text{Ker}([3]: T \to T)$ of T is generated by $-1 = \varphi^{-1}(\zeta)$ where [n] is the multiplication by n map on T. For an $x \in \overline{k(s)}$ the equation f(s, x) = 0 holds if and only if [3](x) = s. Thus the subfield problem of f(s, X) can be solved by the cohomological argument related to the group T(see [5]). One can consider the functions $A_2(X)$ and $A_3(X)$ as $A_2(X) = -_T X$ and $A_3(X) = X +_T(-1)$, respectively. Lemma 2.1 implies

Corollary 2.2. We have

$$f(s,X)f(-_T s,X) = (X^2 + X + 1)^3 - 9(s^2 + s + 1)(X^2 + X)^2,$$

whose zero set is equal to

$$\mathcal{A}(x) = \{x, A_3(x), A_3^2(x), A_2(x), A_3A_2(x), A_3^2A_2(x)\} \\ = \left\{x, -\frac{x+1}{x}, -\frac{1}{x+1}, -x-1, -\frac{x}{x+1}, \frac{1}{x}\right\}$$

for a solution $x \in \overline{k(s)}$ of f(s, X) = 0.

Let g(t, Y) be as in Introduction and $\delta \in \overline{k(t)}$ a square root of the discriminant of the polynomial g(t, Y), that is,

$$g(t, Y) = Y^3 - tY - t = Y^3 - t(Y+1)$$

and $\delta^2 = 4t^3 - 27t^2$. It is known that g(t, Y) is generic for \mathfrak{S}_3 over k (cf. [9]).

Lemma 2.3. If s and t have a relation $s = (9t - \delta)/(2\delta) \in k(t, \delta)$, then

$$\operatorname{Spl}_{k(t)}g(t,Y) = \operatorname{Spl}_{k(t,\delta)}f(s,X) = k(t,x)$$

for a solution $x \in \overline{k(t)}$ of f(s, X) = 0. The Galois group $\operatorname{Gal}(k(t, x)/k(t))$ is equal to $\langle \sigma, \tau \rangle \simeq \mathfrak{S}_3$ where σ and $\tau \in \operatorname{Gal}(k(t, x)/k(t))$ satisfy $\sigma(x) = x + \tau(-1)$ and $\tau(x) = -\tau x$, respectively.

Proof. For $s = (9t - \delta)/(2\delta)$ and $\gamma = 3t/\delta \in k(t, \delta)$, one can see that $f(s, \gamma Y + s) = \gamma^3 g(t, Y)$. This means that $\operatorname{Spl}_{k(t,\delta)} g(t, Y) = \operatorname{Spl}_{k(t,\delta)} f(s, X)$. Note that $\delta = \pm (y_1 - y_2)(y_2 - y_3)(y_3 - y_1) \in \operatorname{Spl}_{k(t)} g(t, Y)$ where $g(t, Y) = \prod_{i=1}^3 (Y - y_i)$ for $y_i \in \overline{k(t)}$. Thus we have $\operatorname{Spl}_{k(t)} g(t, Y) = \operatorname{Spl}_{k(t,\delta)} g(t, Y) = \operatorname{Spl}_{k(t,\delta)} f(s, X)$. Lemma 2.1 implies that $\operatorname{Spl}_{k(t,\delta)} f(s, X) = k(t, \delta, x)$. Since $s = [3]x \in k(x)$ and $\delta = 9t/(2s+1) \in k(t, x)$, we have $k(t, \delta, x) = k(t, x)$. Here g(t, Y) is a cubic Eisenstein polynomial at the prime divisor t and the discriminant δ^2 of g(t, Y) is not square in k(t). Thus it holds that $[k(t,x) : k(t)] = [\operatorname{Spl}_{k(t)} g(t, Y) : k(t)] = 6$. The element x is a zero of $f(s, X)f(-_Ts, X) = (X^2 + X + 1)^3 - 27t(X^2 + X)^2/(4t - 27)$ which is defined over k(t). This means that $f(s, X)f(-_Ts, X)$ is the minimal polynomial of x over k(t). Corollary 2.2 implies that there exist elements σ and τ in $\operatorname{Gal}(k(t,x)/k(t))$ such that $\sigma(x) = A_3(x)$ and $\tau(x) = A_2(x)$. Since the set $\{\sigma^i \tau^j(x)|i, j \in \mathbb{Z}\} = \mathcal{A}(x)$ has order 6, so does the subgroup $\langle \sigma, \tau \rangle$ of $\operatorname{Gal}(k(t,x)/k(t))$. Hence we have $\operatorname{Gal}(k(t,x)/k(t)) = \langle \sigma, \tau \rangle \simeq \mathfrak{S}_3$.

Let $P(\mathfrak{t}, Z) \in k(\mathfrak{t})[Z]$ be the sextic polynomial as in Introduction, i.e.,

$$P(\mathfrak{t}, Z) = Z^6 - r_1 Z^4 + r_1 Z^3 + r_0 Z^2 - 2r_0 Z + r_0$$

where $r_1 = t_1 t_2 (2(t_1 + t_2) - 27)/(t_1 - t_2)^2$ and $r_0 = t_1^2 t_2^2/(t_1 - t_2)^2$.

Proposition 2.4. We have $\operatorname{Spl}_{k(\mathfrak{t})} P(\mathfrak{t}, Z) = \operatorname{Spl}_{k(\mathfrak{t})} g(t_1, Y) \cdot \operatorname{Spl}_{k(\mathfrak{t})} g(t_2, Y).$

For i = 1 and 2 let δ_i be square roots of $4t_i^3 - 27t_i^2$ in $\overline{k(\mathbf{t})}$ and put $s_i = (9t_i - \delta_i)/(2\delta_i)$, respectively. Let us define $s_{\pm} = s_1 \pm_T s_2$ and $u_{\pm} = 9(s_{\pm}^2 + s_{\pm} + 1)$, respectively.

Lemma 2.5. We have

$$s_{\pm} = \frac{27t_1t_2 - 3(\delta_1t_2 \pm \delta_2t_1) \mp \delta_1\delta_2}{6(\delta_1t_2 \pm \delta_2t_1)},$$
$$u_{\pm} = \frac{t_1t_2(2(t_1 + t_2) - 27) \mp \delta_1\delta_2}{2(t_1 - t_2)^2},$$

 $u_+ + u_- = r_1$ and $u_+ u_- = r_0$.

Proof. It follows from the definition that

$$s_{+} = \frac{(\frac{9t_{1} - \delta_{1}}{2\delta_{1}})(\frac{9t_{2} - \delta_{2}}{2\delta_{2}}) - 1}{\frac{9t_{1} - \delta_{1}}{2\delta_{1}} + \frac{9t_{2} - \delta_{2}}{2\delta_{2}} + 1}$$
$$= \frac{(9t_{1} - \delta_{1})(9t_{2} - \delta_{2}) - 4\delta_{1}\delta_{2}}{18(\delta_{1}t_{2} + \delta_{2}t_{1})}$$
$$= \frac{27t_{1}t_{2} - 3(\delta_{1}t_{2} + \delta_{2}t_{1}) - \delta_{1}\delta_{2}}{6(\delta_{1}t_{2} + \delta_{2}t_{1})}$$

Then one has

$$\begin{split} u_{+} &= 9((s_{+}+1/2)^{2}+3/4) \\ &= (\frac{27t_{1}t_{2}-\delta_{1}\delta_{2}}{2(\delta_{1}t_{2}+\delta_{2}t_{1})})^{2} + \frac{27}{4} \\ &= \frac{(27t_{1}t_{2}-\delta_{1}\delta_{2})^{2}+27(\delta_{1}t_{2}+\delta_{2}t_{1})^{2}}{4(\delta_{1}t_{2}+\delta_{2}t_{1})^{2}} \\ &= \frac{(27t_{1}^{2}+\delta_{1}^{2})(27t_{2}^{2}+\delta_{2}^{2})}{4(\delta_{1}t_{2}+\delta_{2}t_{1})^{2}} \\ &= \frac{4t_{1}^{3}t_{2}^{3}}{(\delta_{1}t_{2}+\delta_{2}t_{1})^{2}} \\ &= \frac{4t_{1}^{3}t_{2}^{3}(\delta_{1}t_{2}-\delta_{2}t_{1})^{2}}{(\delta_{1}^{2}t_{2}^{2}-\delta_{2}^{2}t_{1}^{2})^{2}} \\ &= \frac{4t_{1}^{3}t_{2}^{3}(4t_{1}^{3}t_{2}^{2}+4t_{2}^{3}t_{1}^{2}-54t_{1}^{2}t_{2}^{2}-2\delta_{1}\delta_{2}t_{1}t_{2})}{16(t_{1}^{3}t_{2}^{2}-t_{2}^{3}t_{1}^{2})^{2}} \\ &= \frac{t_{1}t_{2}(2(t_{1}+t_{2})-27)-\delta_{1}\delta_{2}}{2(t_{1}-t_{2})^{2}}. \end{split}$$

Note that $-Ts_2 = -(9t_2 - \delta_2)/(2\delta_2) - 1 = (9t_2 - \delta'_2)/(2\delta'_2)$ where $\delta'_2 = -\delta_2$. This means that s_- and u_- are obtained from s_+ and u_+ with substituting $-\delta_2$ in δ_2 ,

respectively. Here it holds that $u_+ + u_- = r_1$. By the argument above we have

$$u_{+}u_{-} = \frac{4t_{1}^{3}t_{2}^{3}}{(\delta_{1}t_{2} + \delta_{2}t_{1})^{2}} \frac{4t_{1}^{3}t_{2}^{3}}{(\delta_{1}t_{2} - \delta_{2}t_{1})^{2}}$$
$$= \frac{16t_{1}^{6}t_{2}^{6}}{16(t_{1}^{3}t_{2}^{2} - t_{2}^{3}t_{1}^{2})^{2}}$$
$$= \frac{t_{1}^{2}t_{2}^{2}}{(t_{1} - t_{2})^{2}}. \Box$$

Let x_i be solutions of $f(s_i, X) = 0$ in $\overline{k(\mathfrak{t})}$, respectively. Let us denote the field $k(\mathfrak{t}, x_1, x_2)$ by L. We define an element $\xi(i_1, i_2, i) \in L$ by

$$\xi(i_1, i_2, i) = [i_1]x_1 + T[i_2]x_2 + T[i](-1)$$

for integers i_1, i_2 and $i \in \mathbb{Z}$. Here -1 is a non-trivial 3-torsion element in T. Let Λ be a finite set consisting of elements $\xi(i_1, i_2, i) \in L$ with $i_1, i_2 \in \{\pm 1\}$ and $i \in \{0, 1, 2\}$. We denote by $\beta(X)$ a rational function $(X^2 + X + 1)/(X^2 + X) \in k(X)$. For $j = 1, 2, \ldots, 6$ let $z_j \in \beta(\Lambda)$ be elements in L defined by

$$\begin{aligned} &z_1 = \beta(\xi(1,1,0)), \quad z_2 = \beta(\xi(1,1,1)), \quad z_3 = \beta(\xi(1,1,2)), \\ &z_4 = \beta(\xi(1,-1,0)), \quad z_5 = \beta(\xi(1,-1,1)), \quad z_6 = \beta(\xi(1,-1,2)). \end{aligned}$$

Lemma 2.6. We have $P(t, Z) = \prod_{j=1}^{6} (Z - z_j)$.

Proof. Let us assume that $\xi(i_1, i_2, i) = \xi(i'_1, i'_2, i')$ for integers i_1, i_2, i, i'_1, i'_2 and $i' \in \mathbb{Z}$. Then it holds that $[i_1]s_1+_T[i_2]s_2 = [i'_1]s_1+_T[i'_2]s_2$ for $[3]\xi(i_1, i_2, i) = [i_1]s_1+_T[i_2]s_2$. The elements s_1 and s_2 are linearly independent in the group $T(k(\mathfrak{t}, s_1, s_2))$, which means that $(i_1, i_2) = (i'_1, i'_2)$. Since -1 is a non-trivial 3-torsion, one has $i \equiv i'$ (mod 3). Thus the set Λ has 12 elements. The elements ξ_1 and $\xi_2 \in \Lambda$ satisfy $\beta(\xi_1) = \beta(\xi_2)$ if and only if ξ_1 is equal to ξ_2 or $-_T\xi_2$. This shows that z_j are distinct from each other. For $[3]\xi(i_1, i_2, i) = [i_1]s_1+_T[i_2]s_2$ the element $\xi(i_1, i_2, i)$ is a solution of $f([i_1]s_1+_T[i_2]s_2, X) = 0$. Thus one has

$$\begin{split} &\prod_{\xi \in \Lambda} (X - \xi) \\ &= f(s_1 + Ts_2, X) f(s_1 - Ts_2, X) f(-Ts_1 + Ts_2, X) f(-Ts_1 - Ts_2, X) \\ &= f(s_+, X) f(-Ts_+, X) f(s_-, X) f(-Ts_-, X) \\ &= ((X^2 + X + 1)^3 - u_+ (X^2 + X)^2) ((X^2 + X + 1)^3 - u_- (X^2 + X)^2) \\ &= (X^2 + X + 1)^6 - r_1 (X^2 + X + 1)^3 (X^2 + X)^2 + r_0 (X^2 + X)^4, \end{split}$$

which is equal to $P(\mathfrak{t}, \beta(X))(X^2 + X)^6$. This implies that z_j are solutions of $P(\mathfrak{t}, Z) = 0$. Since z_j are distinct, we have $P(\mathfrak{t}, Z) = \prod_{j=1}^6 (Z - z_j)$.

Proof of Proposition 2.4. Lemma 2.3 implies that $L = k(\mathfrak{t}, x_1, x_2)$ is equal to the composite field $\operatorname{Spl}_{k(\mathfrak{t})}g(t_1, Y)\operatorname{Spl}_{k(\mathfrak{t})}g(t_2, Y)$ of two extensions $\operatorname{Spl}_{k(\mathfrak{t})}g(t_1, Y)$ and $\operatorname{Spl}_{k(\mathfrak{t})}g(t_2, Y)$ over $k(\mathfrak{t})$. Let G be the Galois group $\operatorname{Gal}(L/k(\mathfrak{t}))$. Lemma 2.3 means that there exist elements $\sigma_1, \tau_1, \sigma_2$ and τ_2 in G such that

$$\begin{aligned} \sigma_1(x_1) &= x_1 + T(-1), \quad \tau_1(x_1) = -Tx_1, \quad \sigma_2(x_1) = x_1, \qquad \tau_2(x_1) = x_1, \\ \sigma_1(x_2) &= x_2, \qquad \tau_1(x_2) = x_2, \qquad \sigma_2(x_2) = x_2 + T(-1), \quad \tau_2(x_2) = -Tx_2. \end{aligned}$$

Then it holds that $G = \langle \sigma_1, \tau_1, \sigma_2, \tau_2 \rangle = \langle \sigma_1, \tau_1 \rangle \times \langle \sigma_2, \tau_2 \rangle \simeq (\mathfrak{S}_3)^2$. It follows from the definition that $z_j \in L$. One can calculate $\sigma_1(z_1) = \sigma_1(\beta(\xi(1,1,0))) = \beta(\sigma_1(\xi(1,1,0))) = \beta(\xi(1,1,1)) = z_2$. In the same way as above we see the actions on z_j of some elements in G as follows:

The elements $\rho(z_j)$ for $\rho \in G$ and $z_j \in L$ are denoted at the (ρ, z_j) -components in the table above, respectively. Note that for each z_j there exists an element $\rho \in G$ such that $z_j = \rho(z_1)$. Let G_j be the stabilizer of z_j in G, that is, $G_j =$ $\{\rho \in G | \rho(z_j) = z_j\}$. Then it holds that $G_1 = \langle \sigma_1 \sigma_2^2, \tau_1 \tau_2 \rangle \simeq \mathfrak{S}_3$. It is seen that $G_j = \rho G_1 \rho^{-1} \simeq G_1$ if $z_j = \rho(z_1)$ for $\rho \in G$. Here one has the sequence of the extension fields $L/L^{G_j}/k(\mathfrak{t}, z_j)/k(\mathfrak{t})$. By considering the orders of the Galois groups we have $[L : k(\mathfrak{t})] = 36$ and $[L : L^{G_j}] = 6$. Since z_j are conjugate to each other over $k(\mathfrak{t})$, the degrees $[k(\mathfrak{t}, z_j) : k(\mathfrak{t})]$ are equal to 6. This shows that $L^{G_j} = k(\mathfrak{t}, z_j)$ for every j. It satisfies that $G_1 \cap G_2 = \langle \sigma_1 \sigma_2^2 \rangle \simeq C_3$, $G_1 \cap G_4 = \langle \tau_1 \tau_2 \rangle \simeq C_2$ and $G_1 \cap G_2 \cap G_4 = \{1\}$. This implies that $L = L^{G_1 \cap G_2 \cap G_4} = k(\mathfrak{t}, z_1, z_2, z_4)$. Hence we conclude $L = \operatorname{Spl}_{k(\mathfrak{t})} P(\mathfrak{t}, Z)$.

Proposition 2.4 and the genericity of g(t, Y) imply

Corollary 2.7 (Proposition 1.3). The polynomial $P(\mathfrak{t}, Z)$ is generic for $(\mathfrak{S}_3)^2$ over k.

§ 3. Solution of the subfield problem on the generic cubic polynomial

In this section we solve the subfield problem of the cubic polynomial g(t, Y) by using the sextic polynomial $P(\mathfrak{t}, Z)$. Let $b \in K$ be an element in an extension K of k with $b(4b - 27) \neq 0$. Let δ be a square root of $4b^3 - 27b^2$ in \overline{K} and put $a = (9b - \delta)/(2\delta) \in K(\delta)$. Let $Q_b(K)$ be the set of solutions $w \in K$ of the quadratic equation $W^2 = 4b^3 - 27b^2$ and $C_b(K)$ that of the cubic one g(b, Y) = 0.

Lemma 3.1. For a solution $x \in \overline{K}$ of f(a, X) = 0, we have $\text{Spl}_K g(b, Y) = K(x)$ and

$$\operatorname{Gal}(K(x)/K) = \begin{cases} \langle \sigma, \tau \rangle &\simeq \mathfrak{S}_3 & \text{if } Q_b(K) = \emptyset \text{ and } C_b(K) = \emptyset, \\ \langle \sigma \rangle &\simeq \mathcal{C}_3 & \text{if } Q_b(K) \neq \emptyset \text{ and } C_b(K) = \emptyset, \\ \langle \iota \rangle &\simeq \mathcal{C}_2 & \text{if } Q_b(K) = \emptyset \text{ and } C_b(K) \neq \emptyset, \\ \{1\} & \text{otherwise}, \end{cases}$$

where $\sigma(x) = A_3(x) = x + \tau(-1), \ \tau(x) = A_2(x) = -\tau x$ and $\iota(x) = A_3^i A_2(x)$ for an integer $i \in \mathbb{Z}$.

Proof. In the same way as in the proof of Lemma 2.3 one sees $\text{Spl}_K g(b, Y) = K(x)$. Let G_0 be the Galois group $\operatorname{Gal}(K(x)/K)$. Since g(b, Y) is cubic, G_0 is isomorphic to a subgroup of \mathfrak{S}_3 . The sets $Q_b(K)$ (resp. $C_b(K)$) are empty if and only if G_0 contains subgroups which are isomorphic to the cyclic groups \mathcal{C}_2 (resp. \mathcal{C}_3). It determines the group structure of G_0 completely. Let $G_0(x)$ be the orbit of x by G_0 , that is, $G_0(x) = \{\rho(x) | \rho \in G_0\}$. Note that x is a solution of f(a, X) f(-Ta, X) = 0which is a equation over K. Thus $G_0(x)$ has elements as those of $\mathcal{A}(x)$ at Corollary 2.2. If $G_0 \simeq \mathfrak{S}_3$, then $G_0(x)$ is the same form as $\mathcal{A}(x)$, whose order is equal to 6. Thus one has $G_0 = \langle \sigma, \tau \rangle$. When $G_0 \simeq \mathcal{C}_3$, the set $G_0(x)$ has three elements. Note that $A_2(X)$, $A_3A_2(X)$ and $A_3^2A_2(X)$ are linear fractionals of period 2. Thus we have $G_0(x) = \{x, A_3(x), A_3^2(x)\}$, which means that $G_0 = \langle \sigma \rangle$. If $G_0 \simeq \mathcal{C}_2$, then $G_0 = \langle \iota \rangle$ where $\iota(x) = A_3^i A_2(x)$ for an integer $i \in \mathbb{Z}$. The integer *i* depends on the choice of the solution x. In fact, if x satisfies $\iota(x) = A_3^i A_2(x)$ for an integer $i \in \mathbb{Z}$, then $x' = A_3^i(x)$ is a solution of f(a, X) = 0 such that $\iota(x') = A_2(x')$. It is obvious for the case $G_0 = \{1\}$.

Let $F \in K[X]$ be a polynomial over K and $d_1 \leq d_2 \leq \cdots \leq d_r$ positive integers. If there exist irreducible polynomials F_j over K of degree d_j such that $F = \prod_{j=1}^r F_j$, then we say that the decomposition type of F over K is $[d_1, d_2, \ldots, d_r]$ and denote it by $\mathcal{DT}_K F$. Let b_1 and b_2 be two elements in K such that $b_1 b_2 (4b_1 - 27)(4b_2 -$ 27) $(4b_1b_2 - 27(b_1 + b_2))(b_1 - b_2) \neq 0$. Now put $M_i = \operatorname{Spl}_K g(b_i, Y)$ and $n_i = [M_i : K]$, respectively. One can calculate the integers n_i by using Lemma 3.1. We obtain a criterion whether $M_1 \subseteq M_2$ or not in terms of the decomposition type $\mathcal{DT}_K P(\mathfrak{b}, Z)$ of $P(\mathfrak{b}, Z)$ over K for $\mathfrak{b} = (b_1, b_2)$ as follows.

Proposition 3.2 (Theorem 1.1). We assume $n_1 \leq n_2$.

- (1) If $n_1 = 1$, then $M_1 \subseteq M_2$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [n_2, n_2, \dots, n_2]$.
- (2) When $n_1 = n_2 = 2$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,1,2,2] & \text{if } M_{1} = M_{2}, \\ [2,4] & \text{otherwise.} \end{cases}$$

- (3) If $n_1 = 2$ and $n_2 = 3$, then $M_1 \cap M_2 = K$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$.
- (4) When $n_1 = 2$ and $n_2 = 6$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [3,3] & \text{if } M_{1} \subset M_{2}, \\ [6] & \text{otherwise.} \end{cases}$$

(5) When $n_1 = n_2 = 3$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,1,1,3] & \text{if } M_{1} = M_{2}, \\ [3,3] & \text{otherwise.} \end{cases}$$

- (6) If $n_1 = 3$ and $n_2 = 6$, then $M_1 \cap M_2 = K$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$.
- (7) When $n_1 = n_2 = 6$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b}, Z) = \begin{cases} [1, 2, 3] & \text{if } M_{1} = M_{2}, \\ [3, 3] & \text{if } [M_{1} \cap M_{2} : K] = 2, \\ [6] & \text{otherwise.} \end{cases}$$

Let L be the composite field M_1M_2 and G the Galois group $\operatorname{Gal}(L/K)$. For i = 1and 2 let δ_i be square roots of $4b_i^3 - 27b_i^2$ in \overline{K} and put $a_i = (9b_i - \delta_i)/(2\delta_i)$, respectively. Let x_i be solutions of $f(a_i, X) = 0$ in \overline{K} . In the same way as for the case of the function field $k(\mathfrak{t})$ described at the previous section, we define $z_j \in L$ for integers $j = 1, 2, \ldots, 6$. Since $\operatorname{disc}_Z P(\mathfrak{b}, Z)$ is not equal to 0 due to Lemma 4.2 below, the elements z_j are distinct from each other.

Lemma 3.3. If
$$n_1 = 1$$
, then $M_1 \subseteq M_2$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [n_2, n_2, \dots, n_2]$.

Proof. When $n_1 = n_2 = 1$, we have $x_1, x_2 \in K$ and $z_j \in K$. This means that $\mathcal{DT}_K P(\mathfrak{b}, Z) = [1, 1, 1, 1, 1]$. When $(n_1, n_2) = (1, 2)$, we have $G = \langle \iota_2 \rangle$ where $\iota_2(x_1) = x_1$ and $\iota_2(x_2) = A_3^i A_2(x_2)$ for an $i \in \mathbb{Z}$. If $\iota_2(x_2) = A_2(x_2)$, then

$$\iota_2: z_1 \mapsto z_4 \mapsto z_1, \quad z_2 \mapsto z_5 \mapsto z_2, \quad z_3 \mapsto z_6 \mapsto z_3,$$

which means that $\mathcal{DT}_K P(\mathfrak{b}, Z) = [2, 2, 2]$. In the same way as above one sees $\mathcal{DT}_K P(\mathfrak{b}, Z) = [2, 2, 2]$ provided $\iota_2(x_2) = A_3^i A_2(x_2)$ for every $i \in \mathbb{Z}$. If $(n_1, n_2) = (1, 3)$, then $G = \langle \sigma_2 \rangle$ with $\sigma_2(x_1) = x_1$ and $\sigma_2(x_2) = A_3(x_2)$. Then one has

$$\sigma_2: z_1 \mapsto z_2 \mapsto z_3 \mapsto z_1, \quad z_4 \mapsto z_6 \mapsto z_5 \mapsto z_4,$$

which implies that $\mathcal{DT}_{K}P(\mathfrak{b},Z) = [3,3]$. When $(n_{1},n_{2}) = (1,6)$, we have $G = \langle \sigma_{2}, \tau_{2} \rangle$ with $\sigma_{2}(x_{1}) = x_{1}, \tau_{2}(x_{1}) = x_{1}, \sigma_{2}(x_{2}) = A_{3}(x_{2})$ and $\tau_{2}(x_{2}) = A_{2}(x_{2})$. Then σ_{2} and τ_{2} satisfy $\sigma_{2} : z_{1} \mapsto z_{2} \mapsto z_{3}, z_{4} \mapsto z_{6} \mapsto z_{5}$ and $\tau_{2}(z_{1}) = z_{4}$, respectively. Thus we have $\mathcal{DT}_{K}P(\mathfrak{b},Z) = [6]$.

Lemma 3.4. Now assume $n_1 = 2$. When $n_2 = 2$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,1,2,2] & \text{if } M_{1} = M_{2} \\ [2,4] & \text{otherwise.} \end{cases}$$

If $n_2 = 3$, then $M_1 \cap M_2 = K$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$. For the case of $n_2 = 6$ we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [3,3] & \text{if } M_{1} \subset M_{2}, \\ [6] & \text{otherwise.} \end{cases}$$

Proof. Let us first consider the case that $n_1 = n_2 = 2$ and $M_1 = M_2$. Then it satisfies that $G = \langle \iota \rangle$ where $\iota(x_1) = A_3^{i_1}A_2(x_1)$ and $\iota(x_2) = A_3^{i_2}A_2(x_2)$ for integers $i_1, i_2 \in \mathbb{Z}$. By replacing x_1 and x_2 by the solutions $x'_1 = A_3^{i_1}(x_1)$ and $x'_2 = A_3^{i_2}(x_1)$, one may have $\iota(x'_1) = A_2(x'_1)$ and $\iota(x'_2) = A_2(x'_2)$, respectively. The replacement of (x_1, x_2) by (x'_1, x'_2) permutes the elements z_j , however, it does not change the polynomial $P(\mathfrak{b}, Z)$ and the decomposition type $\mathcal{DT}_K P(\mathfrak{b}, Z)$. So we may check only the case $i_1 = i_2 = 0$. It holds that

$$\iota: z_1 \mapsto z_1, \quad z_2 \mapsto z_3 \mapsto z_2, \quad z_4 \mapsto z_4, \quad z_5 \mapsto z_6 \mapsto z_5,$$

which means $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [1, 1, 2, 2]$. If $n_{1} = n_{2} = 2$ and $M_{1} \neq M_{2}$, then $G = \langle \iota_{1}, \iota_{2} \rangle$ where $\iota_{1}(x_{1}) = A_{3}^{i_{1}}A_{2}(x_{1}), \iota_{1}(x_{2}) = x_{2}, \iota_{2}(x_{1}) = x_{1}$ and $\iota_{2}(x_{2}) = A_{3}^{i_{2}}A_{2}(x_{2})$ for integers $i_{1}, i_{2} \in \mathbb{Z}$. When $i_{1} = i_{2} = 0$, it satisfies

This shows that $\mathcal{DT}_K P(\mathfrak{b}, Z) = [2, 4]$. If $(n_1, n_2) = (2, 3)$, then $G = \langle \iota_1, \sigma_2 \rangle$ where $\iota_1(x_1) = A_3^{i_1} A_2(x_1), \ \iota_1(x_2) = x_2, \ \sigma_2(x_1) = x_1$ and $\sigma_2(x_2) = A_3(x_2)$ for an integer $i_1 \in \mathbb{Z}$. In the case $i_1 = 0$ one has that $\iota_1(z_1) = z_4$ and $\sigma_2 : z_1 \mapsto z_2 \mapsto z_3, z_4 \mapsto$

 $z_6 \mapsto z_5$. Thus we have $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$. Let us assume $(n_1, n_2) = (2, 6)$. If $M_1 \subset M_2$, then $G = \langle \sigma_2, \tau \rangle$ where $\sigma_2(x_1) = x_1, \sigma_2(x_2) = A_3(x_2), \tau(x_1) = A_3^{i_1}A_2(x_1)$ and $\tau(x_2) = A_2(x_2)$ for an integer $i_1 \in \mathbb{Z}$. Under the condition $i_1 = 0$ one has

$$\begin{aligned} \sigma_2: & z_1 \mapsto z_2 \mapsto z_3 \mapsto z_1, \quad z_4 \mapsto z_6 \mapsto z_5 \mapsto z_4, \\ \tau: & z_1 \mapsto z_1, \quad z_2 \mapsto z_3 \mapsto z_2, \quad z_4 \mapsto z_4, \quad z_5 \mapsto z_6 \mapsto z_5, \end{aligned}$$

which means that $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [3, 3]$. If $M_{1} \not\subset M_{2}$, then $G = \langle \iota_{1}, \sigma_{2}, \tau_{2} \rangle$ where $\iota_{1}(x_{1}) = A_{3}^{i_{1}}A_{2}(x_{1}), \ \iota_{1}(x_{2}) = x_{2}, \ \sigma_{2}(x_{1}) = x_{1}, \ \sigma_{2}(x_{2}) = A_{3}(x_{2}), \ \tau_{2}(x_{1}) = x_{1}$ and $\tau_{2}(x_{2}) = A_{2}(x_{2})$ for an integer $i_{1} \in \mathbb{Z}$. Then in the same way as in the case $(n_{1}, n_{2}) = (1, 6)$, one has $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [6]$.

Lemma 3.5. Assume $n_1 = 3$. When $n_2 = 3$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b},Z) = \begin{cases} [1,1,1,3] & \text{if } M_{1} = M_{2}, \\ [3,3] & \text{otherwise.} \end{cases}$$

If $n_2 = 6$, then $M_1 \cap M_2 = K$ and $\mathcal{DT}_K P(\mathfrak{b}, Z) = [6]$.

Proof. Let us assume that $n_1 = n_2 = 3$ and $M_1 = M_2$. Then it holds that $G = \langle \sigma \rangle$ where $\sigma(x_1) = A_3(x_1)$ and $\sigma(x_2) = A_3^i(x_2)$ for $i \in \{1, 2\}$. Here one sees

$$\sigma: \left\{ \begin{array}{ll} z_1 \mapsto z_3 \mapsto z_2 \mapsto z_1, & z_4 \mapsto z_4, & z_5 \mapsto z_5, & z_6 \mapsto z_6 & \text{if } i = 1, \\ z_1 \mapsto z_1, & z_2 \mapsto z_2, & z_3 \mapsto z_3, & z_4 \mapsto z_6 \mapsto z_5 \mapsto z_4 & \text{if } i = 2. \end{array} \right.$$

This means that $\mathcal{DT}_K P(\mathfrak{b}, Z) = [1, 1, 1, 3]$. When $n_1 = n_2 = 3$ and $M_1 \neq M_2$, we have $G = \langle \sigma_1, \sigma_2 \rangle$ where $\sigma_1(x_1) = A_3(x_1), \sigma_1(x_2) = x_2, \sigma_2(x_1) = x_1$ and $\sigma_2(x_2) = A_3(x_2)$. Then

$$\begin{aligned} \sigma_1 : & z_1 \mapsto z_2 \mapsto z_3 \mapsto z_1, \quad z_4 \mapsto z_5 \mapsto z_6 \mapsto z_4, \\ \sigma_2 : & z_1 \mapsto z_2 \mapsto z_3 \mapsto z_1, \quad z_4 \mapsto z_6 \mapsto z_5 \mapsto z_4, \end{aligned}$$

which implies that $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [3, 3]$. If $(n_{1}, n_{2}) = (3, 6)$, then $M_{1} \cap M_{2} = K$ and $G = \langle \sigma_{1}, \sigma_{2}, \tau_{2} \rangle$ where $\sigma_{1}(x_{1}) = A_{3}(x_{1}), \sigma_{1}(x_{2}) = x_{2}, \sigma_{2}(x_{1}) = x_{1}, \sigma_{2}(x_{2}) = A_{3}(x_{2}), \tau_{2}(x_{1}) = x_{1}$ and $\tau_{2}(x_{2}) = A_{2}(x_{2})$. In the same way as in the case $(n_{1}, n_{2}) = (1, 6),$ one has $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [6]$.

Lemma 3.6. When $n_1 = n_2 = 6$, we have

$$\mathcal{DT}_{K}P(\mathfrak{b}, Z) = \begin{cases} [1, 2, 3] & \text{if } M_{1} = M_{2}, \\ [3, 3] & \text{if } [M_{1} \cap M_{2} : K] = 2, \\ [6] & \text{otherwise.} \end{cases}$$

Proof. If $M_1 = M_2$, then $G = \langle \sigma, \tau \rangle$ where $\sigma(x_1) = A_3(x_1)$, $\sigma(x_2) = A_3^i(x_2)$ $\tau(x_1) = A_2(x_1)$ and $\tau(x_2) = A_3^{i_2}A_2(x_2)$ for integers $i \in \{1, 2\}$ and $i_2 \in \mathbb{Z}$. In the case $(i, i_2) = (1, 0)$ we have

This shows that $\mathcal{DT}_K P(\mathfrak{b}, Z) = [1, 2, 3]$. When $[M_1 \cap M_2 : K] = 2$, we have $G = \langle \sigma_1, \sigma_2, \tau \rangle$ where $\sigma_1(x_1) = A_3(x_1), \sigma_1(x_2) = x_2, \sigma_2(x_1) = x_1, \sigma_2(x_2) = A_3(x_2)$ $\tau(x_1) = A_2(x_1)$ and $\tau(x_2) = A_3^{i_2} A_2(x_2)$ for an integer $i_2 \in \mathbb{Z}$. For the case $i_2 = 0$ one has

Thus we have $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [3, 3]$. If $M_{1} \cap M_{2} = K$, then $G = \langle \sigma_{1}, \sigma_{2}, \tau_{1}, \tau_{2} \rangle$ where $\sigma_{1}(x_{1}) = A_{3}(x_{1}), \ \sigma_{1}(x_{2}) = x_{2}, \ \sigma_{2}(x_{1}) = x_{1}, \ \sigma_{2}(x_{2}) = A_{3}(x_{2}), \ \tau_{1}(x_{1}) = A_{2}(x_{1}),$ $\tau_{1}(x_{2}) = x_{2}, \ \tau_{2}(x_{1}) = x_{1} \text{ and } \tau_{2}(x_{2}) = A_{2}(x_{2}).$ In the same way as in the case $(n_{1}, n_{2}) = (1, 6)$, one has $\mathcal{DT}_{K}P(\mathfrak{b}, Z) = [6].$

REMARK 3.7. In the proofs of Lemmas 3.3 to 3.6 one may have $i_1 = i_2 = 0$ by replacing the solutions x_1 and x_2 by others solutions of $f(a_1, Y) = 0$ and $f(a_2, Y) =$ 0, respectively. We may have i = 1 by replacing the solutions x_2 of $f(a_2, Y) = 0$ by a solution $-_T x_2$ of $f(-_T a_2, Y) = 0$. Such replacements do not change the extensions M_1, M_2 , the polynomial $P(\mathfrak{b}, Z)$ and the decomposition type $\mathcal{DT}_K P(\mathfrak{b}, Z)$.

Lemmas 3.3 to 3.6 verify Proposition 3.2.

Proof of Theorem 1.1. For a fixed (n_1, n_2) , Proposition 3.2 means that the decomposition types $\mathcal{DT}_K P(\mathfrak{b}, Z)$ are distinct if the relations between M_1 and M_2 are different, which implies that the converses are also true. This shows Theorem 1.1 completely.

For the exceptional case that $b_1b_2(4b_1-27)(4b_2-27)(4b_1b_2-27(b_1+b_2))(b_1-b_2) = 0$ one sees

Lemma 3.8 (Lemma 1.4). We have $M_i = K$ provided $b_i(4b_i - 27) = 0$. When $(4b_1b_2 - 27(b_1 + b_2))(b_1 - b_2) = 0$, it holds that $M_1 = M_2$.

Proof. Since $g(0, Y) = Y^3$ and $g(27/4, Y) = (Y - 3)(Y + 3/2)^2$, one has $M_i = K$ if $b_i(4b_i - 27) = 0$. Now assume that $b_i(4b_i - 27) \neq 0$ and $4b_1b_2 - 27(b_1 + b_2) = 0$. Then one has that $\delta_1^2 \delta_2^2 = 27^2 b_1^2 b_2^2$ and $K(\delta_1, \delta_2) = K(\delta_1) = K(\delta_2)$. Lemma 2.5 shows that $a_1 + Ta_2 = -1/2$ or $a_1 - Ta_2 = -1/2$. Since $-1/2 = [3](-1/2) \in [3]T(K)$, it holds that $\text{Spl}_{K(\delta_1, \delta_2)} f(a_1, X) = \text{Spl}_{K(\delta_1, \delta_2)} f(a_2, X)$. Lemma 2.3 implies that $M_i = \text{Spl}_{K(\delta_i)} f(a_i, X)$, respectively. Hence we have $M_1 = M_2$. □

§ 4. Discriminants of the polynomials

Let us denote the discriminants of the polynomials f(s, X) and g(t, Y) by $\Delta_f(s)$ and by $\Delta_g(t)$, respectively.

Lemma 4.1. We have $\Delta_f(s) = 3^4(s^2 + s + 1)^2$ and $\Delta_g(t) = t^2(4t - 27)$. Under the relations $s = (9t - \delta)/(2\delta)$ and $\delta^2 = 4t^3 - 27t^2$ one has $\Delta_f(s) = 3^6t^2/(4t - 27)^2$ and $\Delta_g(t) = 3^{10}(s^2 + s + 1)^2/(2s + 1)^6$.

Proof. The equations $s = (9t - \delta)/(2\delta)$ and $\delta^2 = 4t^3 - 27t^2$ imply that $t = 3^3(s^2 + s + 1)/(2s + 1)^2$. This means that $s^2 + s + 1 = 3t/(4t - 27)$. \Box Let $\Delta_P(\mathfrak{t})$ be the discriminant of the polynomial $P(\mathfrak{t}, Z)$.

Lemma 4.2. We have

$$\Delta_P(\mathfrak{t}) = \frac{t_1^{10} t_2^{10} (4t_1 - 27)^3 (4t_2 - 27)^3 (4t_1 t_2 - 27(t_1 + t_2))^2}{(t_1 - t_2)^{18}}.$$

Proof. We first note that $P(\mathfrak{t}, -Z) = g(u_+, Z)g(u_-, Z)$ whose discriminant is equal to that of $P(\mathfrak{t}, Z)$. Here the resultant $\operatorname{Res}_Z(g_1(Z), g_2(Z))$ of two polynomials $g_1(Z)$ and $g_2(Z)$ satisfies an equation

$$\operatorname{disc}_{Z}(g_{1}(Z)g_{2}(Z)) = \operatorname{disc}_{Z}(g_{1}(Z))\operatorname{disc}_{Z}(g_{2}(Z))\operatorname{Res}_{Z}(g_{1}(Z),g_{2}(Z))^{2}$$

(cf. [2] § 3.3). Lemma 2.5 implies that

$$\begin{aligned} \operatorname{disc}_Z g(u_+, Z) \operatorname{disc}_Z g(u_-, Z) \\ &= (4u_+^3 - 27u_+^2)(4u_-^3 - 27u_-^2) \\ &= r_0^2 (16r_0 - 108r_1 + 729) \\ &= t_1^4 t_2^4 (4t_1 t_2 - 27(t_1 + t_2))^2 / (t_1 - t_2)^6 \end{aligned}$$

By the Sylvester's matrix method one can calculate that $\operatorname{Res}_Z(g(u_+, Z), g(u_-, Z))$ is equal to $(u_+ - u_-)^3$. It holds that $(u_+ - u_-)^2 = r_1^2 - 4r_0 = t_1^2 t_2^2 (4t_1 - 27)(4t_2 - 27)/(t_1 - t_2)^4$. Hence the equation of the assertion follows. \Box

§ 5. Descent genericity of the sextic polynomial

It is known due to Kemper [4] that a generic polynomial for a finite group G over a field k yields not only all the Galois G-extensions containing k but also all the Galois H-extensions containing k for any subgroups H of G. In this section we give explicit generic polynomials $P_H(\mathfrak{c}, Z)$ for all subgroups H of $(\mathfrak{S}_3)^2$ by the degenerations of the sextic polynomial $P(\mathfrak{t}, Z)$.

Let $\lambda(c)$, $\mu(c)$ and $\nu(c) \in k(c)$ be rational functions over k with one variable c such that

$$\lambda(c) = \frac{3^3(c^2 + c + 1)}{(2c + 1)^2}, \quad \mu(c) = \frac{c^3}{3^2(c - 9)^2},$$
$$\nu(s) = \lambda([3](c)) = \mu(\lambda(c)) = \frac{3^3(c^2 + c + 1)^3}{(c - 1)^2(2c + 1)^2(c + 2)^2}$$

where [3] is the multiplication by 3 map of the group T, that is, $[3](c) = (c^3 - 3c - 1)/(3c^2 + 3c)$. For subgroups $H = \{1\}$, C_2 , C_3 and \mathfrak{S}_3 of \mathfrak{S}_3 , we define polynomials $g_H(c, Y) \in k(c)[Y]$ by

$$g_{\{1\}}(c,Y) = g(\nu(c),Y), \quad g_{\mathcal{C}_2}(c,Y) = g(\mu(c),Y), \quad g_{\mathcal{C}_3}(c,Y) = g(\lambda(c),Y)$$

and $g_{\mathfrak{S}_3}(c, Y) = g(c, Y)$, respectively. By the direct calculation one sees

Lemma 5.1. We have

$$g_{\{1\}}(c,Y) = (Z - \frac{3(c^2 + c + 1)}{(c - 1)(c + 2)})(Z + \frac{3(c^2 + c + 1)}{(c + 2)(2c + 1)})(Z + \frac{3(c^2 + c + 1)}{(c - 1)(2c + 1)}),$$

$$g_{C_2}(c,Y) = (Z + \frac{c}{c - 9})(Z^2 - \frac{c}{c - 9}Z - \frac{c^2}{3^2(c - 9)}),$$

$$\operatorname{disc}_Z(g_{\{1\}}(c,Y) = \frac{3^{12}c^2(c + 1)^2(c^2 + c + 1)^6}{(c - 1)^6(2c + 1)^6(c + 2)^6},$$

$$\operatorname{disc}_Z(g_{C_2}(c,Y)) = \frac{c^6(c - 27)^2(4c - 27)}{3^6(c - 9)^6}, \quad \operatorname{disc}_Z(g_{C_3}(c,Y)) = \frac{3^{10}(c^2 + c + 1)^2}{(2c + 1)^6}.$$

Corollary 5.2. For each subgroup $H = \{1\}$, C_2 , C_3 and \mathfrak{S}_3 of \mathfrak{S}_3 , the polynomial $g_H(c, Y)$ is generic for H over k.

Proof. Lemma 5.1 means that $\operatorname{Spl}_{k(c)}(g_{\{1\}}(c,Y)) = k(c)$ and $\operatorname{Spl}_{k(c)}(g_{\mathcal{C}_2}(c,Y)) = k(c,\sqrt{4c-27})$. Thus $\operatorname{Spl}_{k(c)}(g_{\{1\}}(c,Y))$ and $\operatorname{Spl}_{k(c)}(g_{\mathcal{C}_2}(c,Y))$ are generic. Lemma 2.3 implies that $\operatorname{Spl}_{k(c)}(g_{\mathcal{C}_3}(c,Y)) = \operatorname{Spl}_{k(c)}f(c,X)$ for $\operatorname{disc}_Z(g_{\mathcal{C}_3}(c,Y)) \in k(c)^2$. Since f(c,X) is generic for \mathcal{C}_3 over k, so is $g_{\mathcal{C}_3}(c,Y)$. For subgroups H of $(\mathfrak{S}_3)^2$ we define polynomials $P_H(\mathfrak{c}, Z) \in k(\mathfrak{c})[Z], \mathfrak{c} = (c_1, c_2)$ by

$$\begin{split} P_{\{1\}}(\mathbf{c},Z) &= P(\nu(c_1),\nu(c_2),Z), & P_{\mathfrak{S}_3}(\mathbf{c},Z) = P(\nu(c_1),c_2,Z), \\ P_{C_2}(\mathbf{c},Z) &= P(\nu(c_1),\mu(c_2),Z), & P_{(C_3)^2}(\mathbf{c},Z) = P(\lambda(c_1),\lambda(c_2),Z), \\ P_{C_3}(\mathbf{c},Z) &= P(\nu(c_1),\lambda(c_2),Z), & P_{C_2\times\mathfrak{S}_3}(\mathbf{c},Z) = P(\mu(c_1),c_2,Z), \\ P_{(C_2)^2}(\mathbf{c},Z) &= P(\mu(c_1),\mu(c_2),Z), & P_{C_3\times\mathfrak{S}_3}(\mathbf{c},Z) = P(\lambda(c_1),c_2,Z), \\ P_{C_6}(\mathbf{c},Z) &= P(\mu(c_1),\lambda(c_2),Z), & P_{(\mathfrak{S}_3)^2}(\mathbf{c},Z) = P(c_1,c_2,Z). \end{split}$$

Proposition 2.4 and Corollary 5.2 imply

Corollary 5.3. For every subgroup H of $(\mathfrak{S}_3)^2$ the polynomial $P_H(\mathfrak{c}, Z)$ is generic for H over k.

REMARK 5.4. We omit the description of the discriminants $\operatorname{disc}_Z P_H(\mathfrak{c}, Z)$ of the polynomials $P_H(\mathfrak{c}, Z) = P(\varepsilon_1(c_1), \varepsilon_2(c_2), Z)$ since $\operatorname{disc}_Z P_H(\mathfrak{c}, Z)$ are equal to $\Delta_P(\varepsilon_1(c_1), \varepsilon_2(c_2))$, respectively.

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