GLOBAL EXISTENCE FOR A SYSTEM OF MULTIPLE-SPEED WAVE EQUATIONS VIOLATING THE NULL CONDITION

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ABSTRACT. We discuss the Cauchy problem for a system of semilinear wave equations in three space dimensions with multiple wave speeds. Though our system does not satisfy the standard null condition, we show that it admits a unique global solution for any small and smooth data. This generalizes a preceding result due to Pusateri and Shatah.

The proof is carried out by the energy method involving a collection of generalized derivatives. The multiple wave speeds disable the use of the Lorentz boost operators, and our proof therefore relies upon the version of Klainerman and Sideris. Due to the presence of nonlinear terms violating the standard null condition, some of components of the solution may have a weaker decay as $t \to \infty$, which makes it difficult even to establish a mildly growing (in time) bound for the high energy estimate. We overcome this difficulty by relying upon the ghost weight energy estimate of Alinhac and the Keel-Smith-Sogge type L^2 weighted space-time estimate for derivatives.

1. Introduction

This paper is concerned with the Cauchy problem for a system of semilinear wave equations in three space dimensions of the form

(1.1)
$$\begin{cases} \partial_t^2 u_1 - \Delta u_1 = F_1(\partial u_1, \partial u_2, \partial u_3), \ t > 0, \ x \in \mathbb{R}^3, \\ \partial_t^2 u_2 - \Delta u_2 = F_2(\partial u_1, \partial u_2, \partial u_3), \ t > 0, \ x \in \mathbb{R}^3, \\ \partial_t^2 u_3 - c_0^2 \Delta u_3 = F_3(\partial u_1, \partial u_2, \partial u_3), \ t > 0, \ x \in \mathbb{R}^3 \end{cases}$$

subject to the initial condition

$$(1.2) (u_i(0), \partial_t u_i(0)) = (f_i, g_i) \in C_0^{\infty}(\mathbb{R}^3) \times C_0^{\infty}(\mathbb{R}^3), i = 1, 2, 3,$$

where $(u_1, u_2, u_3) : (0, \infty) \times \mathbb{R}^3 \to \mathbb{R}^3$, $\partial = (\partial_0, \partial_1, \partial_2, \partial_3)$, $\partial_0 = \partial/\partial t$, $\partial_i = \partial/\partial x_i$, and $c_0 > 0$. Moreover, $F_1(y)$, $F_2(y)$, and $F_3(y)$ are polynomials in $y \in \mathbb{R}^{12}$ of degree ≥ 2 . That is, we suppose that the nonlinear term has the form

$$(1.3) F_i(\partial u_1, \partial u_2, \partial u_3) = F_i^{jk,\alpha\beta}(\partial_\alpha u_i)(\partial_\beta u_k) + C_i(\partial u_1, \partial u_2, \partial u_3), i = 1, 2, 3,$$

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where $C_i(y)$ is a polynomial in $y \in \mathbb{R}^{12}$ of degree ≥ 3 . In what follows, we suppose $F_i^{jk,\alpha\beta} = 0$ if j > k, without loss of generality. Here, and in the following discussion as well, we use the summation convention: if lowered and uppered, repeated Greek letters and Roman letters are summed for 0 to 3 and 1 to 3, respectively.

Though our main interest lies in global existence of small, smooth solutions in the case $c_0 \neq 1$, we first review some of the results for the case $c_0 = 1$. It follows from the fundamental result of John and Klainerman [13] that the equation (1.1) admits a unique "almost global" solution for small, smooth data with compact support. That is, the time interval on which the local solution exists becomes exponentially large as the size of initial data gets smaller and smaller. Almost global existence is the most that one can expect in general. Indeed, nonexistence of global solutions is known even for small data. See, e.g., John [11] and Sideris [27] for the scalar equations $\partial_t^2 u - \Delta u = (\partial_t u)^2$ and $\partial_t^2 u - \Delta u = |\nabla u|^2$, respectively. On the other hand, if the null condition is satisfied, that is, for any given i,j,k we have $F_i^{jk,\alpha\beta}X_\alpha X_\beta\equiv 0$ for all $(X_0,X_1,X_2,X_3)\in\mathbb{R}^4$ satisfying $X_0^2=X_1^2+X_2^2+X_3^2$, then it follows from the seminal result of Christodoulou [4] and Klainerman [17] (see also Alinhac [3, p. 94] for a new proof using L^2 space-time weighted estimates for some special derivatives) that the equation (1.1) admits a unique global solution for small, smooth data. Christodoulou employed the method of conformal mapping and Klainerman employed the energy method involving the generators of the translations, the Lorentz transformations, and the dilations.

Let us turn our attention to the case $c_0 \neq 1$, which does not seem amenable to the method in [4] or [17] because of the presence of multiple wave speeds. Alternative techniques based on a smaller collection of generators have been explored by a lot of authors, such as Kovalyov [20] and Yokoyama [33] using point-wise estimations of the fundamental solution, Klainerman and Sideris [19] and Sideris and Tu [30] without relying upon pointwise estimations of the fundamental solution, and Keel, Smith and Sogge [15] using L^2 space-time weighted estimates for derivatives. Obviously, the technique in [15] is applicable to the Cauchy problem (1.1)–(1.2) with $c_0 \neq 1$ and leads to almost global existence result. Moreover, if $c_0 \neq 1$ and the null condition in the sense of [33], [30], and [22] is satisfied, that is, we have for any i = 1, 2 and (j, k) = (1, 1), (1, 2), and (2, 2)

(1.4)
$$F_i^{jk,\alpha\beta} X_{\alpha} X_{\beta} \equiv 0, \ X \in \mathcal{N}^{(1)},$$

(1.5)
$$F_3^{33,\alpha\beta} X_{\alpha} X_{\beta} \equiv 0, \ X \in \mathcal{N}^{(c_0)},$$

then it follows from [33], [30, Remark following Theorem 3.1], and [22, Theorem 1.1] that the equation (1.1) admits a unique global solution for small, smooth data. (We note that as pointed out in [5], the argument of Sideris and Tu is general enough to handle the nonlinear terms satisfying (1.4)–(1.5), although they were not explicitly treated in [30].)

Here, and in the following as well, we use the notation

$$(1.6) \mathcal{N}^{(c)} := \{ X = (X_0, X_1, X_2, X_3) \in \mathbb{R}^4 : X_0^2 = c^2(X_1^2 + X_2^2 + X_3^2) \}, \ c > 0.$$

Recently, there have been a lot of activities in studying systems of wave equations with wider classes of quadratic nonlinear terms for which one still enjoys global solutions for any small, smooth data. See, e.g., [23], [2], [21], [14], [8], and [16] for systems in three space dimensions with equal propagation speeds. As for (1.1) with $c_0 \neq 1$, we easily see that the condition (1.4)–(1.5) is sufficient but not necessary for global existence. Indeed, setting $F_1 = (\partial_t u_2)^2$, $F_2 = F_3 = (\partial_t u_2)(\partial_t u_3)$, we see this term $(\partial_t u_2)^2$ violating the condition (1.4) but we obtain global solutions by first solving the system consisting of the second and the third equations in (1.1) on the basis of the results in [33], [30], and [22] and then regarding the first equation in (1.1) just as the inhomogeneous wave equation with the "source term" $(\partial_t u_2)^2$. Interestingly, using the space-time resonance method, Pusateri and Shatah [26] have proved that global existence of small solutions carries over to 3-component systems with a class of nonlinear terms, say, $F_1 = (\partial_t u_2)^2 + (\partial_t u_1)(\partial_t u_3)^2$, $F_2 = (\partial_t u_2)(\partial_t u_3) + ((\partial_t u_2)^2 - |\nabla u_2|^2), F_3 = (\partial_t u_2)(\partial_t u_3) + (\partial_t u_1)(\partial_t u_2)^2.$ They also mention that ∂u_1 has a weaker decay as $t \to \infty$. Inspired by their observation, we like to find 3-component and 2-speed systems with a wider class of nonlinear terms for which one still obtains global solutions for small, smooth data. In particular, we are interested in the case where u_1 , which may have a weaker decay, is involved in quadratic nonlinear terms. We suppose

$$(1.7) F_1^{11,\alpha\beta} X_{\alpha} X_{\beta} \equiv 0, \ X \in \mathcal{N}^{(1)},$$

(1.8)
$$F_2^{11,\alpha\beta} X_{\alpha} X_{\beta} = F_2^{12,\alpha\beta} X_{\alpha} X_{\beta} = F_2^{22,\alpha\beta} X_{\alpha} X_{\beta} \equiv 0, \ X \in \mathcal{N}^{(1)},$$

(1.9)
$$F_3^{33,\alpha\beta} X_{\alpha} X_{\beta} \equiv 0, \ X \in \mathcal{N}^{(c_0)},$$

(1.10)
$$F_2^{13,\alpha\beta} = 0 \text{ for any } \alpha, \beta,$$

(1.11)
$$F_3^{13,\alpha\beta} = 0 \text{ for any } \alpha, \beta,$$

(1.12)
$$F_3^{11,\alpha\beta} X_{\alpha} X_{\beta} = F_3^{12,\alpha\beta} X_{\alpha} X_{\beta} \equiv 0, \ X \in \mathcal{N}^{(1)},$$

which means that since the condition (1.7) is weaker than (1.4) with i = 1, the nonlinear term such as

$$(1.13) F_1 = (\partial_t u_2)^2 + (\partial_t u_1)(\partial_t u_2) + ((\partial_t u_1)^2 - |\nabla u_1|^2) + C_1(\partial_t u_1, \partial_t u_2, \partial_t u_3)$$

is admissible. Also, any cubic term is admissible. On the other hand, we need the restrictive conditions (1.10)–(1.12) in order to obtain a mildly growing bound for the high energy estimate of u_2 , u_3 , though readers might expect to benefit from difference of propagation speeds. Before stating the main theorem, we set the notation. We use the operators $\Omega_{jk} := x_j \partial_k - x_k \partial_j$, $1 \le j < k \le 3$ and $S := t \partial_t + x \cdot \nabla$. The operators ∂_1 , ∂_2 , ∂_3 , Ω_{12} , Ω_{23} , Ω_{13} and S are denoted by Z_1, Z_2, \ldots, Z_7 , respectively. For multi-indices

$$a = (a_1, a_2, \dots, a_7)$$
, we set $Z^a := Z_1^{a_1} Z_2^{a_2} \cdots Z_7^{a_7}$. Setting
$$E(v(t); c) := \frac{1}{2} \int_{\mathbb{T}^3} \left((\partial_t v(t, x))^2 + c^2 |\nabla v(t, x)|^2 \right) dx$$

for c > 0, we define

(1.14)
$$N_{\kappa}(v(t);c) := \left(\sum_{|a| < \kappa - 1} E(Z^a v(t);c)\right)^{1/2}, \ \kappa \in \mathbb{N}.$$

When there is no confusion, we abbreviate $N_{\kappa}(v(t);c)$ to $N_{\kappa}(v(t))$. To measure the size of data (f,g) with $f=(f_1,f_2,f_3)$ and $g=(g_1,g_2,g_3)$, we use

We are in a position to state the main theorem.

THEOREM 1.1. Suppose $c_0 \neq 1$ in (1.1) and suppose (1.7)–(1.12). There exists an $\varepsilon_0 > 0$ such that if the initial data $(f_i, g_i) \in C_0^{\infty}(\mathbb{R}^3) \times C_0^{\infty}(\mathbb{R}^3)$ (i = 1, 2, 3) satisfy $||(f, g)||_D < \varepsilon_0$, then the Cauchy problem (1.1)–(1.2) admits a unique global solution satisfying

$$(1.16) N_3(u_1(t)) \le C\varepsilon_0(1+t)^{\delta}, \ N_4(u_1(t)) \le C\varepsilon_0(1+t)^{2\delta},$$

$$(1.17) N_3(u_2(t)), N_3(u_3(t)) \le C\varepsilon_0, N_4(u_2(t)), N_4(u_3(t)) \le C\varepsilon_0(1+t)^{\delta}.$$

Here δ is a small constant such that $0 < \delta < 1/24$.

REMARK 1.2. Using (2.16), (6.7) with $\mu = 3$, and (2.18), we see that the solution (u_1, u_2, u_3) in Theorem 1.1 satisfies

(1.18)
$$\|\partial u_1(t)\|_{L^{\infty}(\mathbb{R}^3)} = O(t^{-1+\delta}), \|\partial u_i(t)\|_{L^{\infty}(\mathbb{R}^3)} = O(t^{-1}), i = 2, 3$$
 as $t \to \infty$.

REMARK 1.3. Suppose that the system (1.1) satisfies the assumptions (1.7)–(1.12) in Theorem 1.1. The referee has kindly pointed out that if we ignore the third line of (1.1) and remove u_3 from the first two lines, then the remaining 2-component system satisfies the weak null condition in Alinhac [2, see (AA)–($\overline{\text{AA}}$)]. Also, if we ignore the first line of (1.1) and remove u_1 from the last two lines, then the remaining 2-component system satisfies the null condition in Yokoyama [33] and Sideris-Tu [30]. The assumptions (1.7)–(1.12) are considerably weaker than those in [26] indeed, but they still seem restrictive. There arises a natural question to what extent we can weaken (1.7)–(1.12). In this regard, one might want to ask whether or not the 3-component system (1.1) admit a unique global solution for small, smooth data, if Alinhac's conditions (AA) and ($\overline{\text{AA}}$) are satisfied by the 2-component system derived by removal of u_3 from (1.1) and the null condition in [33] and [30] is satisfied by the 2-component system derived by removal of u_1 from (1.1). This seems to the authors an interesting open question.

Differently from the space-time resonance method of Pusateri and Shatah [26], the proof of our main theorem employs the method of Klainerman and Sideris [19] which is the energy method involving the generators of the translations, the spatial rotations, and the dilations. It does not involve the generators of the hyperbolic rotations, and has successfully led to results of global existence of small solutions under the null condition, for systems of multiple-speed wave equations [30], and for the equation of elasticity [28], [29]. Unlike the system considered in Sideris and Tu [30], the system (1.1) is permitted to involve the term $(\partial_t u_2)^2$ or $(\partial_t u_1)(\partial_t u_2)$ in the first equation (see (1.13) above), and the presence of terms violating the null condition causes a weaker decay of ∂u_1 as $t \to \infty$. Therefore, we must enhance the discussion in [30], although we basically follow their argument based on the two-energy method. We recall that the proof of global existence in [30] employed the "high energy" estimate and the "low energy" estimate, allowing the bound in the former estimate to grow mildly in time, and establishing the uniform (in time) bound in the latter estimate by virtue of the null condition and the difference of propagation speeds. We note that because of the problem of "loss of derivatives" caused by the use of the standard estimation lemma for the null forms (see [30, Lemma 5.1]), it is only for the estimate of the low energy that the null condition plays a role in [30]. In the present case, owing to the weaker decay of ∂u_1 , even a mildly growing bound in the high energy estimate is far from trivial. A similar difficulty already occurred in the proof of Alinhac [1] for global existence of small solutions to the null-form quasilinear (scalar) wave equations in two space dimensions. (Recall that the time decay rate of solutions in two space dimensions is worse than in three space dimensions.) Creating the ghost weight energy method, he succeeded in employing the null condition for the purpose of establishing a mildly growing bound in the high energy estimate. (See also [34] for this matter.) Alinhac set up his remarkable method by relying upon the generators of the hyperbolic rotations, and we note that his technique, combined with the method of Klainerman and Sideris, remains useful without such operators. See [34], [35], and [9]. In order to obtain such an estimate for the high energy, we can therefore rely upon the ghost weight technique and utilize a certain L^2 space-time weighted norm for the special derivatives $\partial_j u_1 + (x_j/|x|)\partial_t u_1$ along with the estimation lemma (see Lemma 2.2 below), when handling such a null-form nonlinear term as $((\partial_t u_1)^2 - |\nabla u_1|^2)$ (see (1.13) above) on the region "far from the origin", that is, $\{x \in \mathbb{R}^3 : |x| > (1+t)/2\}$.

Actually, this way of handling the null-form nonlinear term $((\partial_t u_1)^2 - |\nabla u_1|^2)$ is effective only on the region "far from the origin", because in the present paper, the L^2 space-time weighted norm for the special derivatives is employed in combination with the trace-type inequality with the weight $r^{1-\eta}\langle t-r\rangle^{(1/2)+\eta}$ (see (2.19) with $\theta=(1/2)-\eta$ below, here $\eta>0$ is small enough) and the factor $r^{1-\eta}$ no longer yields the decay factor $t^{-1+\eta}$ on the region "inside the cone" $\{x\in\mathbb{R}^3: |x|<(1+t)/2\}$. As in [30], inside the cone we therefore give up benefiting from the special structure that the null-form nonlinear terms

enjoy, and we regard them simply as products of the derivatives, when considering the high energy estimate of u_1 . Because of the growth of the bound even in the low energy estimate for u_1 , we then proceed differently from [30]. Namely, we make use of the Keel-Smith-Sogge type L^2 weighted norm for usual derivatives (see Lemma 2.7 below) together with the trace-type inequality with weight $r^{1/2}\langle t-r\rangle$ (see (2.19) with $\theta=0$ below). See, e.g., (4.18) below. In this way, such a null-form nonlinear term as $((\partial_t u_1)^2 - |\nabla u_1|^2)$ is no longer the hurdle to establishing a mildly growing bound in the high energy estimate of u_1 .

Because of the weaker decay of ∂u_1 and the mildly growing bound in the high energy estimate of u_2 (see (1.17) above), the presence of such a term as $(\partial_t u_1)(\partial_t u_2)$ also causes another difficulty in establishing a mildly growing bound in the energy estimate of u_1 . This is the reason why we use different growth rates for the high energy and the low energy of u_1 (see the factors $(1+t)^{2\delta}$ and $(1+t)^{\delta}$ in (1.16) above) for the purpose of closing the argument. See (4.24)–(4.26) below.

This paper is organized as follows. In the next section, we first recall some special properties that the null-form nonlinear terms enjoy, and then we recall several key inequalities that play an important role in our arguments. Section 3 is devoted to obtaining bounds for certain weighted $L^2(\mathbb{R}^3)$ -norms of the second or higher-order derivatives of solutions. We carry out the energy estimate and the L^2 weighted space-time estimate in Sections 4 and 5, using the ghost weight method of Alinhac and the Keel-Smith-Sogge type estimate, respectively. In the final section, we complete the proof of Theorem 1.1 by using the method of continuity.

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2. Preliminaries

We need the commutation relations. Let $[\cdot, \cdot]$ be the commutator: [A, B] := AB - BA. It is easy to verify that

(2.1)
$$[Z_i, \square_c] = 0 \text{ for } i = 1, \dots, 6, [S, \square_c] = -2\square_c,$$

(2.2)
$$[Z_j, Z_k] = \sum_{i=1}^7 C_i^{j,k} Z_i, \quad j, \ k = 1, \dots, 7,$$

(2.3)
$$[Z_j, \partial_k] = \sum_{i=1}^3 C_i^{j,k} \partial_i, \quad j = 1, \dots, 7, \quad k = 1, 2, 3,$$

(2.4)
$$[Z_j, \partial_t] = 0, j = 1, \dots, 6, [S, \partial_t] = -\partial_t.$$

Here $\square_c := \partial_t^2 - c^2 \Delta$, and $C_i^{j,k}$ denotes a constant depending on i, j, and k.

The next lemma states that the null form is preserved under the differentiation. Recall the definition of $\mathcal{N}^{(c)}$ (see (1.6)).

LEMMA 2.1. Let c > 0. Suppose that $\{H^{\alpha\beta}\}$ satisfies

(2.5)
$$H^{\alpha\beta}X_{\alpha}X_{\beta} = 0 \text{ for any } X \in \mathcal{N}^{(c)}.$$

For any Z_i (i = 1, ..., 7), the equality

(2.6)
$$Z_{i}(H^{\alpha\beta}(\partial_{\alpha}v)(\partial_{\beta}w))$$

$$= H^{\alpha\beta}(\partial_{\alpha}Z_{i}v)(\partial_{\beta}w) + H^{\alpha\beta}(\partial_{\alpha}v)(\partial_{\beta}Z_{i}w) + \tilde{H}_{i}^{\alpha\beta}(\partial_{\alpha}v)(\partial_{\beta}w)$$

holds with the new coefficients $\{\tilde{H}_i^{\alpha\beta}\}$ also satisfying (2.5).

See, e.g., [3, pp. 91–92] for the proof. It is possible to show the following lemma essentially in the same way as in [3, pp. 90–91].

LEMMA 2.2. Suppose that $\{H^{\alpha\beta}\}$ satisfies (2.5) for some c > 0. With the same c as in (2.5), we have for smooth functions v(t,x) and w(t,x)

$$(2.7) |H^{\alpha\beta}(\partial_{\alpha}v)(\partial_{\beta}w)| \le C(|T^{(c)}v||\partial w| + |\partial v||T^{(c)}w|).$$

Here, and in the following, we use the notation

(2.8)
$$|T^{(c)}v| := \left(\sum_{k=1}^{3} |T_k^{(c)}v|^2\right)^{1/2}, \quad T_k^{(c)} := c\partial_k + (x_k/|x|)\partial_t.$$

Together with (2.7), we will later exploit the fact that for local solutions u, the special derivatives $T_i^{(c)}u$ have better space-time L^2 integrability, in addition to improved time decay property of their $L^{\infty}(\mathbb{R}^3)$ norms as shown in the following lemma.

Lemma 2.3 (Lemma 2.2 of [35]). Let c > 0. The inequality

$$(2.9) |T^{(c)}v(t,x)| \le C\langle t\rangle^{-1} \left(|\partial_t v(t,x)| + \sum_{i=1}^7 |Z_i v(t,x)| + \langle ct - r\rangle |\partial_x v(t,x)| \right)$$

holds for smooth functions v(t, x).

Lemma 2.3 is a direct consequence of the identity such as

(2.10)
$$T_1^{(c)} = \frac{1}{t} \left(\frac{x_1}{|x|} S - \frac{x_2}{|x|} \Omega_{12} - \frac{x_3}{|x|} \Omega_{13} + (ct - r) \partial_1 \right).$$

The following lemma is concerned with Sobolev-type or trace-type inequalities. With c > 0, the auxiliary norms

(2.11)
$$M_2(v(t);c) = \sum_{\substack{0 \le \delta \le 3 \\ 1 \le i \le 2}} \|\langle ct - |x| \rangle \partial_{\delta j}^2 v(t) \|_{L^2(\mathbb{R}^3)},$$

(2.12)
$$M_{\mu}(v(t);c) = \sum_{|a| \le \mu - 2} M_2(Z^a v(t);c), \ \mu = 3, 4,$$

which appear in the following discussion, play an intermediate role. We remark that ∂_t^2 is absent in the right-hand side of (2.11) above. We also use the notation

(2.13)
$$||v||_{L_r^{\infty}L_{\omega}^p(\mathbb{R}^3)} := \sup_{r>0} ||v(r\cdot)||_{L^p(S^2)},$$

(2.14)
$$||v||_{L^{2}_{r}L^{p}_{\omega}(\mathbb{R}^{3})} := \left(\int_{0}^{\infty} ||v(r\cdot)||_{L^{p}(S^{2})}^{2} r^{2} dr \right)^{1/2}.$$

LEMMA 2.4. Let c > 0. Suppose that v decays sufficiently fast as $|x| \to \infty$. The following inequalities hold for $\alpha = 0, 1, 2, 3$

$$(2.16) \langle ct - r \rangle |\partial_{\alpha} v(t, x)| \le C \left(\sum_{|a| < 1} N_1(\partial_x^a v(t)) + \sum_{|a| < 1} M_2(\partial_x^a v(t); c) \right).$$

Moreover, we have

(2.17)
$$||r\partial_{\alpha}v(t)||_{L_{r}^{\infty}L_{\omega}^{4}(\mathbb{R}^{3})} \leq C \sum_{|a|+|b|<1} ||\partial\partial_{x}^{a}\Omega^{b}v(t)||_{L^{2}(\mathbb{R}^{3})},$$

(2.18)
$$\langle r \rangle |\partial_{\alpha} v(t,x)| \le C \sum_{|a|+|b| \le 2} ||\partial \partial_{x}^{a} \Omega^{b} v(t)||_{L^{2}(\mathbb{R}^{3})}.$$

Here, we have used the notation $\Omega^b := \Omega_{12}^{b_1} \Omega_{23}^{b_2} \Omega_{13}^{b_3}$ for multi-indices $b = (b_1, b_2, b_3)$. These inequalities have been already employed in the literature. For the proof of (2.15), see [6, (2.10)]. For the proof of (2.16), see [35, (37)], [6, (2.13)]. See [29, (3.19)] for the proof of (2.17). Finally, combining [29, (3.14b)] with the Sobolev embedding $H^2(\mathbb{R}^3) \hookrightarrow L^{\infty}(\mathbb{R}^3)$, we obtain (2.18).

We also need the following inequality.

LEMMA 2.5. Let c>0 and $\alpha=0,1,2,3$. Suppose that v decays sufficiently fast as $|x|\to\infty$. For any θ with $0\leq\theta\leq1/2$, there exists a constant C>0 such that the inequality

$$(2.19) r^{(1/2)+\theta} \langle ct - r \rangle^{1-\theta} \|\partial_{\alpha} v(t, r \cdot)\|_{L^{4}(S^{2})} \le C \left(\sum_{|a| \le 1} N_{1}(\Omega^{a} v(t)) + M_{2}(v(t); c) \right)$$

holds.

Following the proof of [29, (3.19)], we are able to obtain this inequality for $\theta = 1/2$. The next lemma with $v = \langle ct - r \rangle \partial_{\alpha} w$ immediately yields (2.19) for $\theta = 0$. We follow the idea in Section 2 of [24] and obtain (2.19) for $\theta \in (0, 1/2)$ by interpolation.

In our proof, the trace-type inequality also plays an important role. For the proof, see, e.g., [29, (3.16)].

LEMMA 2.6. There exists a positive constant C such that if v = v(x) decays sufficiently fast as $|x| \to \infty$, then the inequality

$$(2.20) r^{1/2} ||v(r\cdot)||_{L^4(S^2)} \le C ||\nabla v||_{L^2(\mathbb{R}^3)}$$

holds.

Differently from the analysis in Sideris and Tu [30], we need the space-time L^2 estimate because of the growth of the bound not only in the high energy estimate but also in the low energy estimate. The following one corresponds to the special case of [7, Theorem 2.1].

LEMMA 2.7. Let c > 0 and $0 < \mu < 1/2$. Then, there exists a positive constant C depending on c and μ such that the inequality

$$(2.21) (1+T)^{-2\mu} \left(\|r^{-(3/2)+\mu}w\|_{L^{2}((0,T)\times\mathbb{R}^{3})}^{2} + \|r^{-(1/2)+\mu}\partial w\|_{L^{2}((0,T)\times\mathbb{R}^{3})}^{2} \right)$$

$$\leq C\|\partial w(0,\cdot)\|_{L^{2}(\mathbb{R}^{3})}^{2} + C\int_{0}^{T} \int_{\mathbb{R}^{3}} \left(|\partial w||\Box_{c}w| + \frac{|w||\Box_{c}w|}{r^{1-2\mu}\langle r\rangle^{2\mu}} \right) dxdt$$

holds for smooth functions w(t,x) compactly supported in x for any fixed time.

See also Appendix of [32] and [25] for earlier and related estimates. At first sight, the above estimate may appear useless for the proof of global existence, because of the presence of the factor $(1+T)^{-2\mu}$. Owing to the useful idea of dyadic decomposition of the time interval [31, p. 363] (see also (6.13) below), the estimate (2.21) actually works effectively for the proof of global existence.

The following was proved by Klainerman and Sideris.

Lemma 2.8 (Klainerman-Sideris inequality [19]). Let c > 0. There exists a constant C > 0 such that the inequality

$$(2.22) M_2(v(t);c) \le C(N_2(v(t)) + t \|\Box_c v(t)\|_{L^2(\mathbb{R}^3)})$$

holds for smooth functions v = v(t, x) decaying sufficiently fast as $|x| \to \infty$.

3. Bound for
$$M_{\mu}(u_1; 1), M_{\mu}(u_2; 1), \text{ and } M_{\mu}(u_3; c_0)$$

We know that for any data $(f_i, g_i) \in C_0^{\infty}(\mathbb{R}^3) \times C_0^{\infty}(\mathbb{R}^3)$ (i = 1, 2, 3), the Cauchy problem (1.1)–(1.2) admits a unique local (in time) smooth solution which is compactly supported in x at any fixed time by virtue of finite speed of propagation. This section is devoted to the bound for $M_{\mu}(u_1; 1)$, $M_{\mu}(u_2; 1)$, and $M_{\mu}(u_3; c_0)$ $(\mu = 3, 4)$. Though much influenced by [30], our strategy for establishing their bounds is similar to the way adopted in [9, Section 3].

In the discussion below, we use the following quantity for the local solutions $u = (u_1, u_2, u_3)$:

$$(3.1)$$
 $\langle\langle u(t)\rangle\rangle$

$$\begin{split} &:= \langle t \rangle^{-\delta} \| r \langle t - r \rangle^{1/2} \partial u_1(t) \|_{L^{\infty}(\mathbb{R}^3)} + \sum_{|a| \leq 1} \langle t \rangle^{-2\delta} \| r \langle t - r \rangle^{1/2} \partial Z^a u_1(t) \|_{L^{\infty}(\mathbb{R}^3)} \\ &+ \| r \langle t - r \rangle^{1/2} \partial u_2(t) \|_{L^{\infty}(\mathbb{R}^3)} + \sum_{|a| \leq 1} \langle t \rangle^{-\delta} \| r \langle t - r \rangle^{1/2} \partial Z^a u_2(t) \|_{L^{\infty}(\mathbb{R}^3)} \\ &+ \| r \langle c_0 t - r \rangle^{1/2} \partial u_3(t) \|_{L^{\infty}(\mathbb{R}^3)} + \sum_{|a| \leq 1} \langle t \rangle^{-\delta} \| r \langle c_0 t - r \rangle^{1/2} \partial Z^a u_3(t) \|_{L^{\infty}(\mathbb{R}^3)} \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 1} \left(\| r^{1/2} \langle t - r \rangle \partial Z^a u_1(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_1(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-2\delta} \sum_{|a| \leq 2} \left(\| r^{1/2} \langle t - r \rangle \partial Z^a u_1(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_2(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \sum_{|a| \leq 1} \left(\| r^{1/2} \langle t - r \rangle \partial Z^a u_2(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_2(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 2} \left(\| r^{1/2} \langle t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \sum_{|a| \leq 1} \left(\| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 2} \left(\| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 1} \left(\| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 1} \left(\| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 1} \left(\| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \sum_{|a| \leq 1} \left(\| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{1/2} Z_i Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} \right) \\ &+ \langle t \rangle^{-\delta} \| r^{1/2} \langle c_0 t - r \rangle \partial Z^a u_3(t) \|_{L^{\infty}_{\tau} L^{4}_{\omega}} + \sum_{i=1}^{7} \| r^{$$

Using the constant δ appearing in Theorem 1.1, we also set

(3.2)
$$\mathcal{M}_{\kappa}(u(t)) := \langle t \rangle^{-\delta} M_{\kappa}(u_1(t); 1) + M_{\kappa}(u_2(t); 1) + M_{\kappa}(u_3(t); c_0),$$

(3.3)
$$\mathcal{N}_{\kappa}(u(t)) := \langle t \rangle^{-\delta} N_{\kappa}(u_1(t)) + N_{\kappa}(u_2(t)) + N_{\kappa}(u_3(t)).$$

The purpose of this section is to prove the following:

Proposition 3.1. Suppose

(3.4)
$$F_1^{11,\alpha\beta} X_{\alpha} X_{\beta} = 0, \ F_2^{11,\alpha\beta} X_{\alpha} X_{\beta} = F_2^{12,\alpha\beta} X_{\alpha} X_{\beta} = 0,$$
 and
$$F_3^{11,\alpha\beta} X_{\alpha} X_{\beta} = F_3^{12,\alpha\beta} X_{\alpha} X_{\beta} = 0$$

for any $X \in \mathcal{N}^{(1)}$. For $\mu = 3, 4$, the inequality

(3.5)
$$\mathcal{M}_{\mu}(u(t)) \leq C_{KS} \mathcal{N}_{\mu}(u(t)) + C_{31} \langle \langle u(t) \rangle \rangle \mathcal{N}_{\mu}(u(t)) + C_{32} \langle \langle u(t) \rangle \rangle^{2} \mathcal{N}_{3}(u(t)) + C_{33} \langle \langle u(t) \rangle \rangle \mathcal{M}_{\mu}(u(t))$$

holds. Here, C_{KS} , C_{31} , C_{32} , and C_{33} are positive constants.

The proof of this proposition is carried out in the following three subsections.

3.1. **Bound for** $M_{\mu}(u_1; 1)$. We have for $|a| \leq \mu - 2$, $\mu = 3, 4$

$$(3.6) \qquad \Box_1 Z^a u_1 = \sum_{j=1}^{n} \tilde{F}_1^{11,\alpha\beta} (\partial_\alpha Z^{a'} u_1) (\partial_\beta Z^{a''} u_1) + \sum_{j=1}^{n} \tilde{F}_1^{jk,\alpha\beta} (\partial_\alpha Z^{a'} u_j) (\partial_\beta Z^{a''} u_k) + Z^a C_1(\partial u_1, \partial u_2, \partial u_3),$$

where the new coefficients $\tilde{F}_1^{11,\alpha\beta}$ and $\tilde{F}_1^{jk,\alpha\beta}$ ($\tilde{F}_1^{jk,\alpha\beta}=0$ if j>k) actually depend also on a' and a''. By \sum' , we mean the summation over all a' and a'' such that $|a'|+|a''|\leq |a|$. By \sum'' , we mean the summation over all such a', a'' and all j and k such that $(j,k)\neq (1,1)$; for the second term on the right-hand side above, the summation convention only over the repeated Greek letters α and β has been used. By Lemma 2.1, we know

(3.7)
$$\tilde{F}_1^{11,\alpha\beta} X_{\alpha} X_{\beta} = 0, \ X \in \mathcal{N}^{(1)}.$$

We apply Lemma 2.8 to $v = Z^a u_1$, $|a| \le \kappa - 2$, $\kappa = 3, 4$. Taking (2.22) into account, we need to bound

(3.8)
$$t \sum_{j} \|\tilde{F}_{1}^{11,\alpha\beta}(\partial_{\alpha}Z^{a'}u_{1})(\partial_{\beta}Z^{a''}u_{1})\|_{L^{2}(\mathbb{R}^{3})} + t \sum_{j} \|(\partial Z^{a'}u_{j})(\partial Z^{a''}u_{k})\|_{L^{2}(\mathbb{R}^{3})}$$

and

(3.9)
$$t \sum_{i,j,k} \sum_{k} ||\partial u_i(t)||_{L^{\infty}(\mathbb{R}^3)} ||(\partial Z^{a'} u_j)(\partial Z^{a''} u_k)||_{L^2(\mathbb{R}^3)}.$$

In the following discussion, we utilize the characteristic function χ_1 of the set $\{x \in \mathbb{R}^3 : |x| < (c_*/2)t + 1\}$, where $c_* := \min\{c_0, 1\}$. We set $\chi_2 := 1 - \chi_1$. Just for simplicity, we omit dependence of χ_1, χ_2 on t. Owing to (3.1), we get

Here we have used the Hardy inequality, as in [5, (6.27)]. Also, we have assumed $|a'| \le |a''|$ because the other case can be handled similarly. Since $|a'| \le |a''| \le |a| \le \mu - 2$ ($\mu = 3, 4$), we have used the fact $|a'| \le 1$.

Since the property (3.7) has played no role above, we also obtain by assuming $|a'| \leq |a''|$ without loss of generality

Here, and in the following as well, by c_k we mean $c_1 = c_2 = 1$, $c_3 = c_0$ (see (1.1)).

Let us turn our attention to $|x| > (c_*/2)t + 1$. Using Lemmas 2.2–2.3 together with (3.7), we obtain

$$(3.12) \sum \|\chi_{2}\tilde{F}_{1}^{11,\alpha\beta}(\partial_{\alpha}Z^{a'}u_{1})(\partial_{\beta}Z^{a''}u_{1})\|_{L^{2}(\mathbb{R}^{3})}$$

$$\leq C \sum_{|a'|+|a''|\leq\mu-2} (\|\chi_{2}|T^{(1)}Z^{a'}u_{1}\|\partial_{z}Z^{a''}u_{1}\|\|_{L^{2}(\mathbb{R}^{3})})$$

$$+ \|\chi_{2}|\partial_{z}Z^{a'}u_{1}\|T^{(1)}Z^{a''}u_{1}\|\|_{L^{2}(\mathbb{R}^{3})})$$

$$\leq C \sum_{|a'|+|a''|\leq\mu-2} \langle t\rangle^{-3/2} (\|r^{1/2}\partial_{t}Z^{a'}u_{1}\|_{L^{\infty}_{r}L^{4}_{\omega}} + \sum_{i=1}^{7} \|r^{1/2}Z_{i}Z^{a'}u_{1}\|_{L^{\infty}_{r}L^{4}_{\omega}}$$

$$+ \|r^{1/2}\langle t-r\rangle\partial_{x}Z^{a'}u_{1}\|_{L^{\infty}_{r}L^{4}_{\omega}}) \|\partial_{z}Z^{a''}u_{1}\|_{L^{2}_{r}L^{4}_{\omega}}$$

$$\leq C\langle t\rangle^{-(3/2)+2\delta} \langle \langle u(t)\rangle\rangle N_{\mu}(u_{1}(t)).$$

When dealing with $\|\chi_2(\partial Z^{a'}u_j)(\partial Z^{a''}u_k)\|_{L^2}$ $(1 \leq j \leq k \leq 3, (j, k) \neq (1, 1))$, we obviously know k = 2 or k = 3. When $|a'| \leq 2$ and |a''| = 0, we get

When $|a'| \leq 1$ and $|a''| \leq 1$, we get

When |a'| = 0 and $|a''| \le 2$, we get

(3.15)
$$\|\chi_2(\partial u_j)(\partial Z^{a''}u_k)\|_{L^2(\mathbb{R}^3)}$$
$$\leq C\langle t\rangle^{-1}\|r\partial u_j\|_{L^\infty(\mathbb{R}^3)}\|\partial Z^{a''}u_k\|_{L^2(\mathbb{R}^3)}$$

$$\leq C\langle t\rangle^{-1+\delta}\langle\langle u(t)\rangle\rangle (N_3(u_2(t)) + N_3(u_3(t))).$$

As for (3.9), it easy to get for $|a| \le \mu - 2$, $\mu = 3, 4$

$$(3.16) t \sum_{i,j,k} \sum_{k} ||\partial u_i(t)||_{L^{\infty}(\mathbb{R}^3)} ||(\partial Z^{a'} u_j)(\partial Z^{a''} u_k)||_{L^2(\mathbb{R}^3)} \le C \langle \langle u(t) \rangle \rangle^2 \mathcal{N}_{\mu-1}(u(t)).$$

Summing up, we have obtained for $\mu = 3, 4$

$$(3.17) \qquad \langle t \rangle^{-\delta} M_{\mu}(u_{1}(t); 1)$$

$$\leq C \langle t \rangle^{-\delta} N_{\mu}(u_{1}(t))$$

$$+ C \langle t \rangle^{-(1/2)+\delta} \langle \langle u(t) \rangle \rangle \sum_{k=1}^{3} \left(N_{\mu-1}(u_{k}(t)) + M_{\mu}(u_{k}(t); c_{k}) \right)$$

$$+ C \langle t \rangle^{-(1/2)+\delta} \langle \langle u(t) \rangle \rangle N_{\mu}(u_{1}(t)) + C \left(\langle \langle u(t) \rangle \rangle + \langle \langle u(t) \rangle \rangle^{2} \right) \mathcal{N}_{3}(u(t)).$$

3.2. **Bound for** $M_{\mu}(u_2; 1)$ **.** As in (3.6), we have

$$\Box_1 Z^a u_2 = \sum_{\substack{1 \le j \le k \le 3 \\ (j,k) \ne (1,3)}} \sum_{j=1}^{\infty} \tilde{F}_2^{jk,\alpha\beta} (\partial_{\alpha} Z^{a'} u_j) (\partial_{\beta} Z^{a''} u_k) + Z^a C_2 (\partial u_1, \partial u_2, \partial u_3),$$

where the new coefficients $\tilde{F}_2^{jk,\alpha\beta}$ actually depend also on $a',\,a''$. By Lemma 2.1, we know

(3.19)
$$\tilde{F}_{2}^{11,\alpha\beta}X_{\alpha}X_{\beta} = \tilde{F}_{2}^{12,\alpha\beta}X_{\alpha}X_{\beta} = \tilde{F}_{2}^{22,\alpha\beta}X_{\alpha}X_{\beta} = 0, \ X \in \mathcal{N}^{(1)}.$$

(In fact, the condition on $\tilde{F}_2^{22,\alpha\beta}$ plays no role in the present section.) The same computation as in (3.10)–(3.11) yields

(3.20)
$$\|\chi_1 \tilde{F}_2^{11,\alpha\beta} (\partial_{\alpha} Z^{a'} u_1) (\partial_{\beta} Z^{a''} u_1) \|_{L^2(\mathbb{R}^3)}$$

$$\leq C \langle t \rangle^{-(3/2) + 2\delta} \langle \langle u(t) \rangle \rangle (N_{\mu-1}(u_1(t)) + M_{\mu}(u_1(t); 1)),$$

On the other hand, using the property (3.19) of the coefficients $\tilde{F}_2^{11,\alpha\beta}$ and $\tilde{F}_2^{12,\alpha\beta}$, we get

and

as in (3.12). Therefore, we focus on the terms with (j, k) = (2, 2), (2, 3), and (3, 3) on the right-hand side of (3.18). We have only to show how to estimate the term with

(j,k)=(2,3) because the others can be handled similarly. When |a'|=0 and $|a''|\leq 2$, we get

When $|a'| \leq 1$ and $|a''| \leq 1$, we get

$$(3.25) \|\chi_1(\partial Z^{a'}u_2)(\partial Z^{a''}u_3)\|_{L^2(\mathbb{R}^3)} \le C\langle t\rangle^{-1} \|\langle t-r\rangle \partial Z^{a'}u_2\|_{L^6(\mathbb{R}^3)} \|\partial Z^{a''}u_3\|_{L^3(\mathbb{R}^3)}$$

$$\le C\langle t\rangle^{-1} \langle \langle u(t)\rangle \rangle N_3(u_3(t)).$$

Furthermore, we obtain for $|a'| \leq 2$ and |a''| = 0

On the other hand, repeating the same discussion as in (3.13)–(3.15), we can obtain

(3.27)
$$\|\chi_2(\partial Z^{a'}u_2)(\partial Z^{a''}u_3)\|_{L^2(\mathbb{R}^3)} \le C\langle t \rangle^{-1} \langle \langle u(t) \rangle \rangle (N_3(u_2(t)) + N_3(u_3(t)))$$
 for $|a'| + |a''| \le 2$.

The cubic term $Z^aC_2(\partial u_1, \partial u_2, \partial u_3)$ can be handled in the same way as in (3.16). Summing up, we have obtained for $\mu = 3, 4$

$$(3.28) M_{\mu}(u_{2}(t); 1)$$

$$\leq CN_{\mu}(u_{2}(t)) + C\langle t \rangle^{-(1/2)+2\delta} \langle \langle u(t) \rangle \rangle \sum_{k=1}^{2} \left(N_{\mu}(u_{k}(t)) + M_{\mu}(u_{k}(t); 1) \right)$$

$$+ C(\langle \langle u(t) \rangle \rangle + \langle \langle u(t) \rangle \rangle^{2}) \mathcal{N}_{3}(u(t)).$$

3.3. **Bound for** $M_{\mu}(u_3; c_0)$ **.** As in (3.6), we have

$$(3.29) \qquad \square_{c_0} Z^a u_3 = \sum_{\substack{1 \le j \le k \le 3 \\ (j,k) \ne (1,3)}} \sum_{j} \tilde{F}_3^{jk,\alpha\beta} (\partial_\alpha Z^{a'} u_j) (\partial_\beta Z^{a''} u_k) + Z^a C_3 (\partial u_1, \partial u_2, \partial u_3),$$

where the new coefficients above actually depend on a', a''. By Lemma 2.1, we have

(3.30)
$$\tilde{F}_{3}^{11,\alpha\beta}X_{\alpha}X_{\beta} = \tilde{F}_{3}^{12,\alpha\beta}X_{\alpha}X_{\beta} = 0, \ X \in \mathcal{N}^{(1)},$$

(3.31)
$$\tilde{F}_{3}^{33,\alpha\beta} X_{\alpha} X_{\beta} = 0, \ X \in \mathcal{N}^{(c_0)}.$$

(In fact, this condition on $\tilde{F}_3^{33,\alpha\beta}$ plays no role in the present section.) The terms with (j,k)=(1,1) and (1,2) on the right-hand side of (3.29) can be handled in the same way as in (3.20), (3.22) and (3.21), (3.23), respectively. Moreover, we can bound the terms with (j,k)=(2,2), (2,3), and (3,3) on the right-hand side of (3.29) similarly to (3.24)–(3.27).

The cubic term can be handled in the same way as before. We have therefore obtained for $\mu = 3, 4$

(3.32)
$$M_{\mu}(u_{3}(t); c_{0})$$

$$\leq CN_{\mu}(u_{3}(t)) + C\langle t \rangle^{-(1/2)+2\delta} \langle \langle u(t) \rangle \rangle \sum_{k=1}^{2} \left(N_{\mu}(u_{k}(t)) + M_{\mu}(u_{k}(t); 1) \right)$$

$$+ C(\langle \langle u(t) \rangle \rangle + \langle \langle u(t) \rangle \rangle^{2}) \mathcal{N}_{3}(u(t)).$$

It is obvious that Proposition 3.1 is a direct consequence of (3.17), (3.28), and (3.32). We have finished the proof.

4. Energy estimate

We carry out the energy estimate by relying upon the ghost weight method of Alinhac [1], [3]. Just in order to make the proof self-contained, let us start our discussion with some preliminaries. Let c > 0, and define $m^{\alpha\beta} := \text{diag}(-1, c^2, c^2, c^2)$. We define the energy-momentum tensor as

(4.1)
$$T^{\alpha\beta} := m^{\alpha\mu} m^{\beta\nu} (\partial_{\mu} v)(\partial_{\nu} v) - \frac{1}{2} m^{\alpha\beta} m^{\mu\nu} (\partial_{\mu} v)(\partial_{\nu} v).$$

A straightforward computation yields

(4.2)
$$\partial_{\beta} T^{\alpha\beta} = (m^{\alpha\mu} \partial_{\mu} v)(-\Box_{c} v).$$

In particular, we have

$$\partial_{\beta} T^{0\beta} = (\partial_t v)(\Box_c v).$$

For any $g = g(\rho) \in C^1(\mathbb{R})$, we therefore get

(4.4)
$$\partial_{\beta}(e^{g(ct-r)}T^{0\beta}) = e^{g(ct-r)}g'(ct-r)(-\omega_{\beta})T^{0\beta} + e^{g(ct-r)}\partial_{\beta}T^{0\beta}$$
$$= e^{g(ct-r)}\left\{\frac{c}{2}g'(ct-r)\sum_{j=1}^{3}(T_{j}^{(c)}v)^{2} + (\partial_{t}v)(\Box_{c}v)\right\}.$$

Here, by $\omega = (\omega_0, \omega_1, \omega_2, \omega_3)$, we mean $\omega_0 = -c$, $\omega_j = x_j/|x|$. As for $T_j^{(c)}$, see (2.8). With $0 < \eta < 1/4$, we choose

(4.5)
$$g(\rho) = -\int_0^{\rho} \langle \tilde{\rho} \rangle^{-1-2\eta} d\tilde{\rho}, \ \rho \in \mathbb{R},$$

so that $g'(ct-r) = -\langle ct-r\rangle^{-1-2\eta}$. Since $g(\rho)$ is a bounded function and we have $T^{00} = \{(\partial_t v)^2 + c^2 |\nabla v|^2\}/2$, we get the key estimate

$$(4.6) E(v(t);c) + \sum_{j=1}^{3} \int_{0}^{t} \int_{\mathbb{R}^{3}} \langle c\tau - r \rangle^{-1-2\eta} \left(T_{j}^{(c)} v(\tau,x) \right)^{2} d\tau dx$$

$$\leq CE(v(0);c) + C \int_{0}^{t} \int_{\mathbb{R}^{3}} |\Box_{c} v(\tau,x)| |\partial_{t} v(\tau,x)| d\tau dx$$

for any smooth function v(t,x) decaying sufficiently fast as $|x| \to \infty$. In the following, we use the notation for c > 0

(4.7)
$$G(v(t);c) := \left(\sum_{|a| \le 3} \sum_{j=1}^{3} \int_{\mathbb{R}^{3}} \langle ct - r \rangle^{-1-2\eta} \left(T_{j}^{(c)} Z^{a} v(t,x)\right)^{2} dx\right)^{1/2}$$

associated with (4.6) and

(4.8)
$$L(v(t)) := \left(\sum_{|a| < 3} \left(\|r^{-5/4} Z^a v(t)\|_{L^2(\mathbb{R}^3)}^2 + \|r^{-1/4} \partial Z^a v(t)\|_{L^2(\mathbb{R}^3)}^2 \right) \right)^{1/2}$$

associated with (2.21). Recall that we use the notation $c_1 = c_2 = 1$, $c_3 = c_0$ (see (1.1)). The purpose of this section is to prove the following a priori estimate.

PROPOSITION 4.1. Suppose $c_0 \neq 1$ in (1.1) and suppose (1.7)–(1.11). The unique local (in time) solution to (1.1)–(1.2) defined in $(0,T) \times \mathbb{R}^3$ for some T > 0 satisfies

$$(4.9) \qquad (\langle t \rangle^{-\delta} N_3(u_1(t)))^2 + N_3(u_2(t))^2 + N_3(u_3(t))^2$$

$$\leq C \sum_{k=1}^3 N_3(u_k(0))^2$$

$$+ C \langle \langle u \rangle \rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{M}_4(u(t)) \right) \sup_{0 < t < T} \mathcal{N}_3(u(t))$$

$$+ C \langle \langle u \rangle \rangle_T^2 \left(\sup_{0 < t < T} \mathcal{N}_3(u(t)) \right)^2$$

and

$$(4.10) \qquad (\langle t \rangle^{-2\delta} N_4(u_1(t)))^2 + \sum_{k=2}^3 (\langle t \rangle^{-\delta} N_4(u_k(t)))^2$$

$$+ \langle t \rangle^{-4\delta} \int_0^t G(u_1(\tau); 1)^2 d\tau + \sum_{k=2}^3 \langle t \rangle^{-2\delta} \int_0^t G(u_k(\tau); c_k)^2 d\tau$$

$$\leq C \sum_{k=1}^3 N_4(u_k(0))^2$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \int_0^T \langle \tau \rangle^{-1+2\delta} \left(\sum_{k=1}^3 L(u_k(\tau)) \right)^2 d\tau$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) \right) \int_0^T \langle \tau \rangle^{-1+\eta+4\delta} \sum_{k=1}^3 G(u_k(\tau); c_k) d\tau$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) \right)^2$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t)) \right) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t))$$

for 0 < t < T. (See (4.30) for the definition of $\langle\langle u \rangle\rangle_T$.)

4.1. Energy estimate for u_1 . Note that (3.6) remains valid for $|a| \leq 3$. Using (4.6) and (3.6), we get for $|a| \leq 3$

$$(4.11) E(Z^{a}u_{1}(t); 1) + \sum_{j=1}^{3} \int_{0}^{t} \int_{\mathbb{R}^{3}} \langle \tau - r \rangle^{-1-2\eta} (T_{j}^{(1)} Z^{a}u_{1}(\tau, x))^{2} d\tau dx$$

$$\leq CE(Z^{a}u_{1}(0); 1) + C\sum_{j=1}^{3} \int_{0}^{t} J_{11} d\tau + C\sum_{j=1}^{3} \int_{0}^{t} J_{12} d\tau + C\int_{0}^{t} J_{13} d\tau,$$

where

$$J_{11} = \|\tilde{F}_1^{11,\alpha\beta}(\partial_{\alpha}Z^{a'}u_1)(\partial_{\beta}Z^{a''}u_1)(\partial_t Z^a u_1)\|_{L^1(\mathbb{R}^3)},$$

$$J_{12} = \|\tilde{F}_1^{jk,\alpha\beta}(\partial_{\alpha}Z^{a'}u_j)(\partial_{\beta}Z^{a''}u_k)(\partial_t Z^a u_1)\|_{L^1(\mathbb{R}^3)},$$

$$(4.14) J_{13} = \| (Z^a C_1(\partial u_1, \partial u_2, \partial u_3)) (\partial_t Z^a u_1) \|_{L^1(\mathbb{R}^3)}.$$

We refer to (3.6) for \sum' and \sum'' . As for $|a| \le 2$ we have only to repeat quite the same argument as before. Indeed, as in (3.10) and (3.12) with $\mu = 4$, we obtain for $|a| \le 2$

$$(4.15) J_{11} \leq C\langle \tau \rangle^{-(3/2)+3\delta} \langle \langle u(\tau) \rangle \rangle (N_4(u_1(\tau)) + M_4(u_1(\tau);1)) (\langle \tau \rangle^{-\delta} N_3(u_1(\tau))).$$

As in (3.11), (3.13)–(3.15), we get for $|a| \le 2$, using the notation $c_1 = c_2 = 1$, $c_3 = c_0$

$$(4.16) J_{12} \leq C\langle \tau \rangle^{-(3/2)+3\delta} \langle \langle u(\tau) \rangle \rangle \left(\sum_{k=1}^{3} \left(N_3(u_k(\tau)) + M_4(u_k(\tau); c_k) \right) \right)$$

$$\times \left(\langle \tau \rangle^{-\delta} N_3(u_1(\tau)) \right)$$

$$+ C\langle \tau \rangle^{-1+2\delta} \langle \langle u(\tau) \rangle \rangle \mathcal{N}_3(u(\tau)) \left(\langle \tau \rangle^{-\delta} N_3(u_1(\tau)) \right).$$

It is also possible to get for $|a| \leq 2$

$$(4.17) J_{13} \leq C \langle \tau \rangle^{-2+4\delta} \langle \langle u(\tau) \rangle \rangle^2 \mathcal{N}_3(u(\tau)) (\langle \tau \rangle^{-\delta} N_3(u_1(\tau))).$$

Therefore, we may focus on $|a| \leq 3$. Note that we can no longer rely upon the Hardy inequality as we have done in (3.10), (3.11). (Its use would cause the loss of derivatives, and we could not close the argument.) As mentioned in Introduction, this is one of the places where we need to proceed quite differently from [30], and we utilize the weighted norm (4.8) associated with (2.21). Assuming $|a'| \leq |a''|$ (and hence $|a'| \leq 1$) without loss of generality, we get

Here, the Sobolev embedding $W^{1,4}(S^2) \hookrightarrow L^{\infty}(S^2)$ has been used to bound $\langle \tau \rangle^{-2\delta} || r^{1/2} \langle \tau - r \rangle \partial Z^{a'} u_1 ||_{L^{\infty}(\mathbb{R}^3)}$ by a constant-multiple of $\langle u(\tau) \rangle$. Similarly, we get for $(j,k) \neq (1,1)$

(4.19)
$$\|\chi_1(\partial Z^{a'}u_j)(\partial Z^{a''}u_k)(\partial_t Z^a u_1)\|_{L^1(\mathbb{R}^3)}$$

$$\leq C\langle\tau\rangle^{-1+2\delta}\langle\langle u(\tau)\rangle\rangle\left(\sum_{k=0}^3 L(u_k(\tau))\right)L(u_1(\tau)).$$

On the other hand, as in (3.12), we employ (2.7) to get

To continue the estimate of (4.20), we may assume $|a'| \leq |a''|$ (hence $|a'| \leq 1$) by symmetry. Using simply the $L^{\infty}(\mathbb{R}^3)$ norm (together with $W^{1,4}(S^2) \hookrightarrow L^{\infty}(S^2)$) and the L^2 norm in place of the $L^{\infty}_r L^4_{\omega}$ and the $L^2_r L^4_{\omega}$ norms, we naturally modify the argument in (3.12) to get

Moreover, using (2.19) with $\theta = (1/2) - \eta$ and c = 1, we obtain

To handle

$$(4.23) \qquad \sum^{"} \|\chi_2 \tilde{F}_1^{jk,\alpha\beta} (\partial_{\alpha} Z^{a'} u_j) (\partial_{\beta} Z^{a''} u_k) (\partial_t Z^a u_1) \|_{L^1(\mathbb{R}^3)},$$

we focus on the estimate of

for $|a| \leq 3$, $|a'| + |a''| \leq 3$, and $(j,k) \neq (1,1)$, because of lack of the null condition on the coefficients $\{F_1^{jk,\alpha\beta}\}$ with $(j,k) \neq (1,1)$. Unlike (4.20), we fully utilize the different growth rates for the high energy and the low energy of u_1 . Without loss of generality, we may suppose $j \neq 1$ in (4.24). When |a'| = 0 (and hence $|a''| \leq 3$), we get

When |a'| = 1 (and hence $|a''| \le 2$), we employ the $L_r^{\infty} L_{\omega}^4$ norm and the $L_r^2 L_{\omega}^4$ norm (together with $W^{1,2}(S^2) \hookrightarrow L^4(S^2)$) in place of the $L^{\infty}(\mathbb{R}^3)$ norm and the $L^2(\mathbb{R}^3)$ norm, to get the same bound as in (4.25). When |a'| = 2 (and hence $|a''| \le 1$), we obtain

$$(4.26) \|\chi_2(\partial Z^{a'}u_i)(\partial Z^{a''}u_k)(\partial_t Z^a u_1)\|_{L^1(\mathbb{R}^3)}$$

$$\leq C\langle \tau \rangle^{-1+4\delta} \left(\langle \tau \rangle^{-\delta} \|\partial Z^{a'} u_j\|_{L^2_r L^4_\omega} \right) \left(\langle \tau \rangle^{-\delta} \|r \partial Z^{a''} u_k\|_{L^\infty_r L^4_\omega} \right) \left(\langle \tau \rangle^{-2\delta} N_4(u_1(\tau)) \right) \\ \leq C\langle \tau \rangle^{-1+4\delta} \left(\langle \tau \rangle^{-\delta} \mathcal{N}_4(u(\tau)) \right) \left\langle \langle u(\tau) \rangle \right\rangle \left(\langle \tau \rangle^{-2\delta} N_4(u_1(\tau)) \right).$$

For |a'|=3 (and hence |a''|=0), we employ the $L^2(\mathbb{R}^3)$ norm and the $L^\infty(\mathbb{R}^3)$ norm in place of the $L^2_r L^4_\omega$ norm and the $L^\infty_r L^4_\omega$ norm, to get the same bound as in (4.26).

It remains to bound (4.14) for $|a| \leq 3$. It is possible to get

$$(4.27) J_{13} \leq C \langle \tau \rangle^{-2+6\delta} \langle \langle u(\tau) \rangle \rangle^{2} (\langle \tau \rangle^{-\delta} \mathcal{N}_{4}(u(\tau)) + \mathcal{N}_{3}(u(\tau))) (\langle \tau \rangle^{-2\delta} N_{4}(u_{1}(\tau))).$$

It suffices to handle such a typical cubic term as $(\partial_t Z^{a'}u_1)(\partial_t Z^{a''}u_1)(\partial_t Z^{a'''}u_1)$ with |a'| + |a''| + |a'''| = 3, to show (4.27). We get

$$(4.28) \qquad \left(\sum_{|a'|=3} \|\chi_{1}(\partial_{t}Z^{a'}u_{1})(\partial_{t}u_{1})^{2}\|_{L^{2}(\mathbb{R}^{3})} \right. \\
+ \sum_{|a'|=|a''|=1} \|\chi_{1}(\partial_{t}Z^{a'}u_{1})(\partial_{t}Z^{a''}u_{1})(\partial_{t}u_{1})\|_{L^{2}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\chi_{1}(\partial_{t}Z^{a'}u_{1})(\partial_{t}Z^{a''}u_{1})(\partial_{t}Z^{a'''}u_{1})\|_{L^{2}(\mathbb{R}^{3})} \right) N_{4}(u_{1}) \\
\leq C \langle \tau \rangle^{-2} \left(\sum_{|a'|=3} \|\partial_{t}Z^{a'}u_{1}\|_{L^{2}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\partial_{t}Z^{a'}u_{1}\|_{L^{3}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \\
+ \sum_{|a'|=|a''|=1} \|\langle \tau - r \rangle \partial_{t}Z^{a'}u_{1}\|_{L^{\infty}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_{L^{6}(\mathbb{R}^{3})} \|\langle \tau - r \rangle \partial_{t}Z^{a''}u_{1}\|_$$

We also obtain

$$(4.29) \qquad \left(\sum_{|a'|=3} \|\chi_{2}(\partial_{t}Z^{a'}u_{1})(\partial_{t}u_{1})^{2}\|_{L^{2}(\mathbb{R}^{3})} + \sum_{\substack{|a'|=2\\|a''|=1}} \|\chi_{2}(\partial_{t}Z^{a'}u_{1})(\partial_{t}Z^{a''}u_{1})(\partial_{t}u_{1})\|_{L^{2}(\mathbb{R}^{3})} + \sum_{\substack{|a'|=|a''|\\=|a'''|=1}} \|\chi_{2}(\partial_{t}Z^{a'}u_{1})(\partial_{t}Z^{a''}u_{1})(\partial_{t}Z^{a'''}u_{1})\|_{L^{2}(\mathbb{R}^{3})}\right) N_{4}(u_{1})$$

$$\leq C\langle \tau \rangle^{-2} \left(\sum_{\substack{|a'|=3\\|a''|=1}} \|\partial_t Z^{a'} u_1\|_{L^2(\mathbb{R}^3)} \|r \partial_t u_1\|_{L^{\infty}(\mathbb{R}^3)}^2 \right) \\ + \sum_{\substack{|a'|=2\\|a'''|=1}} \|\partial_t Z^{a'} u_1\|_{L^2_r L^4_{\omega}} \|r \partial_t Z^{a''} u_1\|_{L^{\infty}_r L^4_{\omega}} \|r \partial_t u_1\|_{L^{\infty}(\mathbb{R}^3)} \\ + \sum_{\substack{|a'|=|a''|\\=|a'''|=1}} \|\partial_t Z^{a'} u_1\|_{L^2_r L^{\infty}_{\omega}} \|r \partial_t Z^{a''} u_1\|_{L^{\infty}_r L^4_{\omega}} \|r \partial_t Z^{a'''} u_1\|_{L^{\infty}_r L^4_{\omega}} \right) N_4(u_1) \\ \leq C\langle \tau \rangle^{-2+6\delta} \left(\langle \tau \rangle^{-2\delta} N_4(u_1)\right)^2 \langle \langle u(\tau) \rangle \rangle^2.$$

With the notation

(4.30)
$$\langle\!\langle u \rangle\!\rangle_T := \sup_{0 < t < T} \langle\!\langle u(t) \rangle\!\rangle,$$

summing yields for $|a| \leq 2$

$$(4.31) \qquad \langle t \rangle^{-2\delta} E(Z^{a}u_{1}(t); 1)$$

$$\leq CE(Z^{a}u_{1}(0); 1)$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) + \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{M}_{4}(u(t)) \right) \sup_{0 < t < T} \mathcal{N}_{3}(u(t))$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \mathcal{N}_{3}(u(t)) \right)^{2} + C\langle\langle u \rangle\rangle_{T}^{2} \left(\sup_{0 < t < T} \mathcal{N}_{3}(u(t)) \right)^{2},$$

and for $|a| \leq 3$

$$(4.32) \qquad \langle t \rangle^{-4\delta} E(Z^{a}u_{1}(t); 1) + \langle t \rangle^{-4\delta} \int_{0}^{t} G(u_{1}(\tau); 1)^{2} d\tau$$

$$\leq CE(Z^{a}u_{1}(0); 1)$$

$$+ C\langle\langle u \rangle\rangle_{T} \int_{0}^{t} \langle \tau \rangle^{-1+2\delta} \left(\sum_{k=1}^{3} L(u_{k}(\tau)) \right) L(u_{1}(\tau)) d\tau$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right) \int_{0}^{t} \langle \tau \rangle^{-1+\eta+4\delta} G(u_{1}(\tau); 1) d\tau$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right)^{2}$$

$$+ C\langle\langle u \rangle\rangle_{T}^{2} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) + \sup_{0 < t < T} \mathcal{N}_{3}(u(t)) \right) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)).$$

4.2. Energy estimate for u_2 . As in (4.11), we get for $|a| \leq 3$

(4.33)
$$E(Z^{a}u_{2}(t); 1) + \sum_{j=1}^{3} \int_{0}^{t} \int_{\mathbb{R}^{3}} \langle \tau - r \rangle^{-1-2\eta} \left(T_{j}^{(1)} Z^{a} u_{2}(\tau, x) \right)^{2} d\tau dx$$

$$\leq CE(Z^{a}u_{2}(0); 1)$$

$$+C\sum_{\substack{(j,k)=(1,1),\\(1,2),(2,2)}}\sum'\int_0^t J_{21}\,d\tau+C\sum_{\substack{(j,k)=(2,3),\\(3,3)}}\sum'\int_0^t J_{21}\,d\tau+C\int_0^t J_{22}\,d\tau,$$

here we have set

$$(4.34) J_{21} = J_{21}^{(j,k)} := \|\tilde{F}_2^{jk,\alpha\beta}(\partial_{\alpha}Z^{a'}u_j)(\partial_{\beta}Z^{a''}u_k)(\partial_t Z^a u_2)\|_{L^1(\mathbb{R}^3)}$$

(Note that the summation convention only for the Greek letters α and β has been used above, and the coefficients $\tilde{F}_2^{jk,\alpha\beta}$ actually depend also on a', a''.), and

$$(4.35) J_{22} := \| (Z^a C_2(\partial u_1, \partial u_2, \partial u_3)) (\partial_t Z^a u_2) \|_{L^1(\mathbb{R}^3)}.$$

Let us first consider the low energy $|a| \le 2$. As in (3.20)–(3.21), it is possible to obtain

$$(4.36) \|\chi_1(\partial Z^{a'}u_j)(\partial Z^{a''}u_k)(\partial_t Z^a u_2)\|_{L^1(\mathbb{R}^3)}$$

$$\leq C\langle \tau \rangle^{-(3/2)+4\delta} \langle \langle u(\tau) \rangle \rangle (\mathcal{N}_3(u(\tau)) + \langle \tau \rangle^{-\delta} \mathcal{M}_4(u(\tau))) \mathcal{N}_3(u_2(\tau)).$$

On the other hand, for (j, k) = (1, 1), (1, 2), and (2, 2), we benefit from the null condition and obtain

$$(4.37) \|\chi_2 \tilde{F}_2^{jk,\alpha\beta} (\partial_{\alpha} Z^{a'} u_j) (\partial_{\beta} Z^{a''} u_k) (\partial_t Z^a u_2) \|_{L^1(\mathbb{R}^3)}$$

$$\leq C \langle \tau \rangle^{-(3/2)+4\delta} \langle \langle u(\tau) \rangle \rangle (\langle \tau \rangle^{-2\delta} N_4(u_1(\tau)) + \langle \tau \rangle^{-\delta} N_4(u_2(\tau))) N_3(u_2(\tau))$$

as in (3.12). For (j,k) = (2,3), (3,3), we divide the set $\{x \in \mathbb{R}^3 : |x| > (c_*/2)t + 1\}$ $(c_* = \min\{c_0, 1\})$ into

$$\left\{ x \in \mathbb{R}^3 : \frac{c_*}{2}t + 1 < |x| < \frac{c_0 + 1}{2}t + 1 \right\} \text{ and } \left\{ x \in \mathbb{R}^3 : |x| > \frac{c_0 + 1}{2}t + 1 \right\},$$

and obtain for $j = 2, 3, |a'| + |a''| \le 2$, and $|a| \le 2$

by considering the two cases $c_0 < 1$ and $c_0 > 1$, separately. It is also possible to get for $|a| \le 2$

$$(4.39) J_{22} \leq C\langle \tau \rangle^{-2+3\delta} \langle \langle u(\tau) \rangle \rangle^2 \mathcal{N}_3(u(\tau)) N_3(u_2(\tau)).$$

Summing yields for $|a| \leq 2$

(4.40)
$$E(Z^a u_2(t); 1)$$

 $\leq CE(Z^a u_2(0); 1)$

$$+ C\langle\langle u\rangle\rangle_T \left(\sup_{0 < t < T} \langle t\rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \langle t\rangle^{-\delta} \mathcal{M}_4(u(t))\right) \sup_{0 < t < T} \mathcal{N}_3(u(t))$$
$$+ C\langle\langle u\rangle\rangle_T^2 \left(\sup_{0 < t < T} \mathcal{N}_3(u(t))\right)^2.$$

Let us turn our attention to the high energy $|a| \le 3$. Proceeding as in (4.18) and (4.19), we get for $|a'| + |a''| \le 3$

On the other hand, for (j,k) = (1,1), (1,2), (2,2), we rely upon the null condition to get

$$(4.42) \sum_{\substack{(j,k)=(1,1),\\(1,2),(2,2)}} \|\chi_2 \tilde{F}_2^{jk,\alpha\beta} (\partial Z^{a'} u_j) (\partial Z^{a''} u_k) (\partial_t Z^a u_2) \|_{L^1(\mathbb{R}^3)}$$

$$\leq C \langle \tau \rangle^{-(3/2)+4\delta} \langle \langle u(\tau) \rangle \rangle (\langle \tau \rangle^{-2\delta} N_4(u_1(\tau)) + \langle \tau \rangle^{-\delta} N_4(u_2(\tau))) N_4(u_2(\tau))$$

$$+ C \langle \tau \rangle^{-1+\eta+2\delta} \langle \langle u(\tau) \rangle \rangle \left(\sum_{i=1,2} G(u_i(\tau);1) \right) N_4(u_2(\tau))$$

in the same way as in (4.20), (4.21), and (4.22). For (j,k) = (2,3), (3,3), we can no longer rely upon the null condition. Instead, we rely upon the fact $\min\{|a'|, |a''|\} \le 1$ for $|a'| + |a''| \le 3$. Proceeding as in (4.25) and (4.26), we then obtain

(4.43)
$$\sum_{j=2,3} \|\chi_2(\partial Z^{a'}u_j)(\partial Z^{a''}u_3)(\partial_t Z^a u_2)\|_{L^1(\mathbb{R}^3)}$$

$$\leq C\langle \tau \rangle^{-1+2\delta} \langle \langle u(\tau) \rangle \rangle (\langle \tau \rangle^{-\delta} N_4(u_2(\tau)) + \langle \tau \rangle^{-\delta} N_4(u_3(\tau))) \langle \tau \rangle^{-\delta} N_4(u_2(\tau)).$$

Finally, we get for $|a| \leq 3$

$$(4.44) J_{22} \leq C\langle \tau \rangle^{-2+5\delta} \langle \langle u(\tau) \rangle \rangle^{2} (\langle \tau \rangle^{-\delta} \mathcal{N}_{4}(u(\tau)) + \mathcal{N}_{3}(u(\tau))) (\langle \tau \rangle^{-\delta} \mathcal{N}_{4}(u_{2}(\tau)))$$

in the same way as in (4.27). Summing yields for $|a| \leq 3$

$$(4.45) \qquad \langle t \rangle^{-2\delta} E(Z^{a}u_{2}(t); 1) + \langle t \rangle^{-2\delta} \int_{0}^{t} G(u_{2}(\tau); 1)^{2} d\tau$$

$$\leq CE(Z^{a}u_{2}(0); 1)$$

$$+ C\langle\langle u \rangle\rangle_{T} \int_{0}^{t} \langle \tau \rangle^{-1+2\delta} \left(\sum_{k=1}^{3} L(u_{k}(\tau)) \right) L(u_{2}(\tau)) d\tau$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right) \int_{0}^{t} \langle \tau \rangle^{-1+\eta+3\delta} \left(\sum_{i=1,2} G(u_{i}(\tau); 1) \right) d\tau$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right)^{2}$$

$$+ C\langle\langle u \rangle\rangle_T^2 \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t)) \right) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)).$$

4.3. Energy estimate for u_3 . As in (4.11), we get for $|a| \leq 3$

$$(4.46) E(Z^{a}u_{3}(t); c_{0}) + \sum_{j=1}^{3} \int_{0}^{t} \int_{\mathbb{R}^{3}} \langle c_{0}\tau - r \rangle^{-1-2\eta} \left(T_{j}^{(c_{0})} Z^{a}u_{3}(\tau, x) \right)^{2} d\tau dx$$

$$\leq CE(Z^{a}u_{3}(0); c_{0}) + C \sum_{\substack{(j,k)=(1,1),\\ (1,2)}} \sum_{j=1}^{3} \int_{0}^{t} J_{31} d\tau + C \sum_{j=1}^{3} \int_{0}^{t} J_{32} d\tau$$

$$+ C \sum_{k=2,3} \sum_{j=1}^{3} \int_{0}^{t} J_{33} d\tau + C \int_{0}^{t} J_{34} d\tau.$$

Here we have set

$$(4.47) J_{31} = J_{31}^{(j,k)} := \|\tilde{F}_{3}^{jk,\alpha\beta}(\partial_{\alpha}Z^{a'}u_{j})(\partial_{\beta}Z^{a''}u_{k})(\partial_{t}Z^{a}u_{3})\|_{L^{1}(\mathbb{R}^{3})},$$

(Note that the summation convention only for the Greek letters α and β has been used above.)

$$(4.48) J_{32} := \|\tilde{F}_3^{33,\alpha\beta}(\partial_{\alpha}Z^{a'}u_3)(\partial_{\beta}Z^{a''}u_3)(\partial_t Z^a u_3)\|_{L^1(\mathbb{R}^3)},$$

$$(4.49) J_{33} = J_{33}^{(k)} := \|\tilde{F}_{3}^{2k,\alpha\beta}(\partial_{\alpha}Z^{a'}u_{2})(\partial_{\beta}Z^{a''}u_{k})(\partial_{t}Z^{a}u_{3})\|_{L^{1}(\mathbb{R}^{3})},$$

(Note that the coefficients $\tilde{F}_3^{jk,\alpha\beta}$ actually depend also on $a',\,a''.$), and

$$(4.50) J_{34} := \| (Z^a C_3(\partial u_1, \partial u_2, \partial u_3)) (\partial_t Z^a u_3) \|_{L^1(\mathbb{R}^3)}.$$

Let us first consider the low energy $|a| \leq 2$. In the same way as in (4.36)–(4.37), we obtain

$$(4.51) J_{31} \leq C\langle \tau \rangle^{-(3/2)+4\delta} \langle \langle u(\tau) \rangle \rangle (\langle \tau \rangle^{-\delta} \mathcal{N}_4(u(\tau)) + \langle \tau \rangle^{-\delta} \mathcal{M}_4(u(\tau))) N_3(u_3(\tau)).$$

Since $\{\tilde{F}_3^{33,\alpha\beta}\}$ satisfies the null condition (1.9), we also get

$$(4.52) J_{32} \leq C\langle \tau \rangle^{-(3/2)+2\delta} \langle \langle u(\tau) \rangle \rangle (\langle \tau \rangle^{-\delta} \mathcal{N}_4(u(\tau)) + \langle \tau \rangle^{-\delta} \mathcal{M}_4(u(\tau))) N_3(u_3(\tau)).$$

For J_{33} , we proceed as in (4.36) and (4.38), to get

$$(4.53) J_{33} \leq C\langle \tau \rangle^{-(3/2)+2\delta} \langle \langle u(\tau) \rangle \rangle (\langle \tau \rangle^{-\delta} \mathcal{N}_4(u(\tau)) + \langle \tau \rangle^{-\delta} \mathcal{M}_4(u(\tau))) \mathcal{N}_3(u(\tau)).$$

It is possible to get for $|a| \le 2$

$$(4.54) J_{34} \leq C\langle \tau \rangle^{-2+3\delta} \langle \langle u(\tau) \rangle \rangle^2 \mathcal{N}_3(u(\tau)) N_3(u_3(\tau)).$$

Summing yields for $|a| \leq 2$

$$(4.55) E(Z^{a}u_{3}(t); c_{0})$$

$$\leq CE(Z^{a}u_{3}(0); c_{0})$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) + \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{M}_{4}(u(t))\right) \sup_{0 < t < T} \mathcal{N}_{3}(u(t))$$

$$+ C\langle\langle u\rangle\rangle_T^2 \left(\sup_{0 < t < T} \mathcal{N}_3(u(t))\right)^2.$$

As for the high energy $|a| \leq 3$, we obtain

$$(4.56) J_{31}, J_{32}$$

$$\leq C\langle \tau \rangle^{-1+2\delta} \langle \langle u(\tau) \rangle \rangle \left(\sum_{k=1}^{3} L(u_{k}(\tau)) \right) L(u_{3}(\tau))$$

$$+ C\langle \tau \rangle^{-(3/2)+4\delta} \langle \langle u(\tau) \rangle \rangle \left(\langle \tau \rangle^{-\delta} \mathcal{N}_{4}(u(\tau)) \right) N_{4}(u_{3}(\tau))$$

$$+ C\langle \tau \rangle^{-1+\eta+2\delta} \langle \langle u(\tau) \rangle \rangle \left(\sum_{i=1,2} G(u_{i}(\tau); 1) + G(u_{3}(\tau); c_{0}) \right) N_{4}(u_{3}(\tau))$$

in the same way as in (4.41) and (4.42). Moreover, as in (4.41) and (4.43), we obtain

$$(4.57) J_{33} \leq C\langle \tau \rangle^{-1+\delta} \langle \langle u(\tau) \rangle \rangle \left(\sum_{k=2}^{3} L(u_k(\tau)) \right) L(u_3(\tau))$$

$$+ \langle \tau \rangle^{-1+2\delta} \langle \langle u(\tau) \rangle \rangle \left(\langle \tau \rangle^{-\delta} N_4(u_2(\tau)) + \langle \tau \rangle^{-\delta} N_4(u_3(\tau)) \right) \langle \tau \rangle^{-\delta} N_4(u_3(\tau)).$$

For J_{34} , we easily obtain

$$(4.58) J_{34} \leq C\langle \tau \rangle^{-2+5\delta} \langle \langle u(\tau) \rangle \rangle^{2} (\langle \tau \rangle^{-\delta} \mathcal{N}_{4}(u(\tau)) + \mathcal{N}_{3}(u(\tau))) (\langle \tau \rangle^{-\delta} \mathcal{N}_{4}(u_{3}(\tau))).$$

Recall the notation $c_1 = c_2 = 1$, $c_3 = c_0$. Summing yields for $|a| \leq 3$

$$(4.59) \qquad \langle t \rangle^{-2\delta} E(Z^{a}u_{3}(t); c_{0}) + \langle t \rangle^{-2\delta} \int_{0}^{t} G(u_{3}(\tau); c_{0})^{2} d\tau$$

$$\leq CE(Z^{a}u_{3}(0); c_{0})$$

$$+ C\langle\langle u \rangle\rangle_{T} \int_{0}^{t} \langle \tau \rangle^{-1+2\delta} \left(\sum_{k=1}^{3} L(u_{k}(\tau)) \right) L(u_{3}(\tau)) d\tau$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right) \int_{0}^{t} \langle \tau \rangle^{-1+\eta+3\delta} \left(\sum_{i=1}^{3} G(u_{i}(\tau); c_{i}) \right) d\tau$$

$$+ C\langle\langle u \rangle\rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right)^{2}$$

$$+ C\langle\langle u \rangle\rangle_{T}^{2} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) + \sup_{0 < t < T} \mathcal{N}_{3}(u(t)) \right) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)).$$

Now we are in a position to complete the proof of Proposition 4.1. It is obvious that the estimate (4.9) follows from (4.31), (4.40), and (4.55). The high energy estimate (4.10) is a direct consequence of (4.32), (4.45), and (4.59). We have finished the proof.

5. L^2 WEIGHTED SPACE-TIME ESTIMATES

The purpose of this section is to prove the following a priori estimates:

PROPOSITION 5.1. The smooth local (in time) solution $u = (u_1, u_2, u_3)$ to (1.1)–(1.2) defined in $(0,T) \times \mathbb{R}^3$ for some T > 0 satisfies the following a priori estimates for all $t \in (0,T)$:

$$(5.1) \qquad \langle t \rangle^{-(1/2)-4\delta} \int_{0}^{t} L(u_{1}(\tau))^{2} d\tau$$

$$\leq C \sum_{|a| \leq 3} \|(\partial Z^{a} u_{1})(0)\|_{L^{2}(\mathbb{R}^{3})}^{2}$$

$$+ C \langle \langle u \rangle \rangle_{T} \int_{0}^{t} \langle \tau \rangle^{-1+2\delta} \left(\sum_{k=1}^{3} L(u_{k}(\tau)) \right) L(u_{1}(\tau)) d\tau$$

$$+ C \langle \langle u \rangle \rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right) \int_{0}^{t} \langle \tau \rangle^{-1+\eta+4\delta} G(u_{1}(\tau); 1) d\tau$$

$$+ C \langle \langle u \rangle \rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) \right)^{2}$$

$$+ C \langle \langle u \rangle \rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) + \sup_{0 < t < T} \mathcal{N}_{3}(u(t)) \right) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)),$$

$$(5.2) \qquad \langle t \rangle^{-(1/2)-2\delta} \int_0^t L(u_2(\tau))^2 d\tau$$

$$\leq C \sum_{|a| \leq 3} \|(\partial Z^a u_2)(0)\|_{L^2(\mathbb{R}^3)}^2$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \int_0^t \left(\sum_{k=1}^3 L(u_k(\tau)) \right) L(u_2(\tau)) d\tau$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) \right) \int_0^t \langle \tau \rangle^{-1+\eta+3\delta} \left(\sum_{i=1,2} G(u_i(\tau); 1) \right) d\tau$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) \right)^2$$

$$+ C \langle\!\langle u \rangle\!\rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t)) \right) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)),$$

(5.3)
$$\langle t \rangle^{-(1/2)-2\delta} \int_0^t L(u_3(\tau))^2 d\tau$$

$$\leq C \sum_{|a| \leq 3} \|(\partial Z^a u_3)(0)\|_{L^2(\mathbb{R}^3)}^2$$

$$\begin{split} &+ C\langle\!\langle u \rangle\!\rangle_T \int_0^t \biggl(\sum_{k=1}^3 L(u_k(\tau)) \biggr) L(u_3(\tau)) d\tau \\ &+ C\langle\!\langle u \rangle\!\rangle_T \biggl(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) \biggr) \int_0^t \langle \tau \rangle^{-1 + \eta + 3\delta} \biggl(\sum_{i=1}^3 G(u_i(\tau); c_i) \biggr) d\tau \\ &+ C\langle\!\langle u \rangle\!\rangle_T \biggl(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) \biggr)^2 \\ &+ C\langle\!\langle u \rangle\!\rangle_T^2 \biggl(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t)) \biggr) \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)). \end{split}$$

In (5.3), we have used the notation $c_1 = c_2 = 1$, $c_3 = c_0$. The proof of this proposition naturally uses Lemma 2.7 with $\mu = 1/4$. With the simple inequality $r^{2\mu} \langle r \rangle^{-2\mu} \leq 1$, the contributions from the term

$$\int_0^T \!\! \int_{\mathbb{R}^3} \frac{|w||\Box_c w|}{r^{1-2\mu} \langle r \rangle^{2\mu}} dx dt$$

(see the right-hand side of (2.21)) can be handled with use of the Hardy inequality or the norm (4.8), and therefore the proof is essentially the same as that of (4.32), (4.45), and (4.59). We may omit the details.

6. Proof of Theorem 1.1

Now we are ready to complete the proof of Theorem 1.1 by using the method of continuity. By the standard contraction-mapping argument, it is easy to show that for any smooth, compactly supported data (1.2), there exists $\hat{T} > 0$ depending on $||(f,g)||_D$ such that the equation (1.1) admits a unique local (in time) solution $u = (u_1, u_2, u_3)$ defined in the strip $(0,\hat{T}) \times \mathbb{R}^3$ satisfying $\partial_{\alpha} Z^a u_i \in C([0,\hat{T}); L^2(\mathbb{R}^3))$ ($\alpha = 0, 1, 2, 3, |a| \leq 3, i = 1, 2, 3$) and supp $u_i(t, \cdot) \subset \{x \in \mathbb{R}^3 : |x| < R + c^*t\}$ ($i = 1, 2, 3, 0 < t < \hat{T}$). Here we have set $c^* := \max\{1, c_0\}$ (see (1.1) for c_0) and chosen R > 0 so that supp $f_i \cup \text{supp } g_i \subset \{x \in \mathbb{R}^3 : |x| < R\}, i = 1, 2, 3$. Actually, this solution is smooth in the strip $(0, \hat{T}) \times \mathbb{R}^3$, and it has the important properties

(6.1)
$$N_{\mu}(u_1(t)), N_{\mu}(u_2(t)), N_{\mu}(u_3(t)) \in C([0,\hat{T})), \mu = 3, 4,$$

(6.2)
$$N_4(u_1(0)) + N_4(u_2(0)) + N_4(u_3(0)) \le C_d \|(f,g)\|_D$$

for a suitable constant $C_d > 0$. We employ the numerical constant C_{61} appearing in (6.13) and set

(6.3)
$$C^* := \max \left\{ 2C_d, \frac{2}{3} \sqrt{\frac{4}{3} C_{61}} \right\} \text{ so that } \sqrt{\frac{4}{3} C_{61}} \le \frac{3}{2} C^*.$$

On the basis of the properties (6.1)–(6.2), for the smooth data (1.2) with the support contained in the ball $\{x \in \mathbb{R}^3 : |x| < R\}$, we can define the non-empty set of all the

numbers T > 0 such that there exists a unique smooth solution u to (1.1)–(1.2) defined in $(0,T) \times \mathbb{R}^3$ satisfying

(6.4)
$$\langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \mathcal{N}_3(u(t)) \le 2C^* \| (f, g) \|_{D},$$

(6.5)
$$\bigcup_{i=1}^{3} \operatorname{supp} u_{i}(t, \cdot) \subset \{x \in \mathbb{R}^{3} : |x| < R + c^{*}t\}$$

for all $t \in (0, T)$. We define $T^* \in (0, \infty]$ as the supremum of this non-empty set. To proceed, we assume

(6.6)
$$||(f,g)||_{D} < \varepsilon_{0} := \min \left\{ 1, \frac{1}{8C^{*}C_{33}C_{60}}, \frac{1}{12C^{*}C_{60}(C_{31} + 2C^{*}C_{32}C_{60})}, \frac{1}{2C^{*}C_{60}C_{62}}, \frac{1}{C^{*}C_{60}C_{63}} \right\}.$$

For the constants appearing above, see (3.5), (6.10), and (6.13). We prove

PROPOSITION 6.1. Let u be the smooth solution to (1.1)-(1.2) satisfying (6.4) and (6.5) for all $t \in (0, T^*)$. The estimate

(6.7)
$$\mathcal{M}_{\mu}(u(t)) \le C \mathcal{N}_{\mu}(u(t)), \quad 0 < t < T^*$$

holds for $\mu = 3, 4$, provided that $||(f, g)||_D$ satisfies (6.6).

PROOF. We proceed closely following the proof of [9, Proposition 8.1]. When the initial data is identically zero and hence the corresponding solution identically vanishes, we obviously have (6.7). We may therefore suppose without loss of generality that the smooth initial data is not identically zero. We then have $\mathcal{N}_{\mu}(u(0)) > 0$. Moreover, we see $\mathcal{N}_{\mu}(u(t)) > 0$ for all $t \in (0, T^*)$ by repeating basically the same argument as in the proof of Proposition 8.1 in [9]. (While the uniqueness theorem of C^2 -solutions of John [11], [12] was employed in [9], the uniqueness of $H^3 \times H^2$ -solutions, which can be shown in the standard way for such systems of semilinear equations as (1.1), suffices in the present case.) Therefore, we may suppose without loss of generality that $\mathcal{N}_{\mu}(u(t)) > 0$ for all $t \in [0, T^*)$.

Next, we remark the important fact that $\mathcal{M}_{\mu}(u(t))$ is continuous on the interval $[0, T^*)$. This can be easily verified thanks to the fact that the smooth solution u satisfies (6.5) on the interval $[0, T^*)$ and hence the uniform continuity of $\partial_{\alpha}\partial_{x}Z^{a}u_{i}$ ($|a| \leq \mu-2, \alpha=0,\ldots,3$) in such a bounded and closed set as $\{(t,x): t \in [0,T+\delta], |x| \leq R+c^{*}t\}$ (δ is a suitable positive constant) can be utilized in order to show the continuity of $\mathcal{M}_{\mu}(u(t))$ at $t = T \in [0,T^*)$. This is the place where our proof of Theorem 1.1 relies upon the compactness of the support of data. Since all the constants appearing in our argument are independent of R, this condition on the support can be actually removed in the standard way.

Now we are ready to prove (6.7). We start with the inequality

$$\mathcal{M}_{\mu}(u(t))|_{t=0} \le C_{KS} \mathcal{N}_{\mu}(u(t))|_{t=0}$$

for the constant C_{KS} appearing (3.5), which is a direct consequence of (2.22). (See the second term on the right-hand side of (2.22), which vanishes at t = 0.) Since $(\mathcal{M}_{\mu}(u(t))/\mathcal{N}_{\mu}(u(t)))|_{t=0} \leq C_{KS}$ and $\mathcal{M}_{\mu}(u(t))/\mathcal{N}_{\mu}(u(t))$ is continuous on the interval $[0, T^*)$, we have $\mathcal{M}_{\mu}(u(t))/\mathcal{N}_{\mu}(u(t)) \leq 2C_{KS}$, that is

(6.8)
$$\mathcal{M}_{\mu}(u(t)) \le 2C_{KS}\mathcal{N}_{\mu}(u(t))$$

at least for a short time interval, say, $[0, \tilde{T}] \subset [0, T^*)$. It remains to show that (6.8) actually holds for all $t \in [0, T^*)$. Let

(6.9)
$$\bar{T} := \sup\{ T \in (0, T^*) : \mathcal{M}_{\mu}(u(t)) \le 2C_{KS} \mathcal{N}_{\mu}(u(t))$$

$$(\mu = 3, 4) \text{ for all } t \in [0, T) \}$$

By definition, we know $\bar{T} \leq T^*$. To show $\bar{T} = T^*$, we proceed as follows. By (3.1), Lemmas 2.4 –2.6, and (6.4), we get for $t \in (0, \bar{T})$

(6.10)
$$\langle \langle u(t) \rangle \rangle \leq C \langle t \rangle^{-\delta} \left(\mathcal{N}_4(u(t)) + \mathcal{M}_4(u(t)) \right) + C \left(\mathcal{N}_3(u(t)) + \mathcal{M}_3(u(t)) \right)$$
$$\leq C_{60} \left(\langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \mathcal{N}_3(u(t)) \right) \leq 2C^* C_{60} \| (f, g) \|_D.$$

Here, C_{60} is a suitable positive constant. Owing to the size condition (6.6), Proposition 3.1 combined with the last inequality (6.10) immediately yields for $\mu = 3, 4$

(6.11)
$$\mathcal{M}_{\mu}(u(t)) \leq \frac{3}{2} C_{KS} \mathcal{N}_{\mu}(u(t)), \quad 0 < t < \bar{T}.$$

Since $\mathcal{M}_{\mu}(u(t))/\mathcal{N}_{\mu}(u(t))$ is continuous on the interval $[0, T^*)$, we have finally arrived at the conclusion $\bar{T} = T^*$. Indeed, if we assume $\bar{T} < T^*$, then the estimate (6.11) contradicts the definition of \bar{T} . We have finished the proof of Proposition 6.1.

Now we are going to prove the crucial a priori estimate

(6.12)
$$\langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \mathcal{N}_3(u(t)) \le \frac{3}{2} C^* ||(f,g)||_D, \quad 0 < t < T^*.$$

This estimate combined with the standard local existence theorem will immediately implie $T^* = \infty$, i.e., global existence. Just for simplicity, we use the notation

$$\mathcal{G}(t) := \langle t \rangle^{-\delta} \|G(u_1(\cdot); 1)\|_{L^2((0,t))} + \|G(u_2(\cdot); 1)\|_{L^2((0,t))} + \|G(u_3(\cdot); c_0)\|_{L^2((0,t))},
\mathcal{L}(t) := \langle t \rangle^{-(1/4)} (\langle t \rangle^{-\delta} \|L(u_1(\cdot))\|_{L^2((0,t))} + \|L(u_2(\cdot))\|_{L^2((0,t))} + \|L(u_3(\cdot))\|_{L^2((0,t))}).$$

Without loss of generality, we may suppose $T^* > 1$ because we are considering solutions with small data. It then follows from (4.9), (4.10), (5.1), (5.2), and (5.3) that for any T with $1 < T < T^*$ we have

(6.13)
$$\left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t))\right)^2$$

$$+ \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{G}(t)\right)^{2} + \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{L}(t)\right)^{2}$$

$$\leq C_{61} \|(f,g)\|_{D}^{2} + C_{62} \langle \langle u \rangle \rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{L}(t)\right)^{2}$$

$$+ C_{63} \langle \langle u \rangle \rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t))\right) \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{G}(t)\right)$$

$$+ C_{64} \langle \langle u \rangle \rangle_{T} \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_{4}(u(t)) + \sup_{0 < t < T} \mathcal{N}_{3}(u(t))\right)^{2}.$$

Here the positive constants C_{6i} (i = 1, ..., 4) are independent of T. We note that δ and η are so small that the idea of decomposing the interval [1, T] dyadically has played an important role as in such previous papers as [31, p. 363], [9, (122)-(125)]. For any T with $T < T^*$, we easily see

$$\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{G}(t), \quad \sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{L}(t) < \infty$$

and it is therefore possible to move the second and the third terms on the right-hand side of (6.13) to its left-hand side. Using the estimate (6.10), which holds for all $t \in (0, T^*)$, and (6.6), we thereby obtain

(6.14)
$$\left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t))\right)^2$$

$$\leq C_{61} \|(f, g)\|_D^2$$

$$+ \left(\frac{1}{2} C_{63} + C_{64}\right) \langle \langle u \rangle \rangle_T \left(\sup_{0 < t < T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 < t < T} \mathcal{N}_3(u(t))\right)^2,$$

which immediately implies

(6.15)
$$\frac{3}{4} \left(\sup_{0 \le t \le T} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 \le t \le T} \mathcal{N}_3(u(t)) \right)^2 \le C_{61} \| (f, g) \|_D^2$$

thanks to (6.10) and (6.6). Since $T(< T^*)$ is arbitrary and the constant C_{61} is independent of T, we finally obtain

(6.16)
$$\sup_{0 \le t \le T^*} \langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \sup_{0 \le t \le T^*} \mathcal{N}_3(u(t)) \le \sqrt{\frac{4}{3}C_{61}} \|(f,g)\|_D \le \frac{3}{2}C^* \|(f,g)\|_D.$$

See (6.3). Now we are in a position to show $T^* = \infty$. Assume $T^* < \infty$. By solving (1.1) with data $(u_i(T^* - \delta, x), (\partial_t u_i)(T^* - \delta, x)) \in C_0^{\infty}(\mathbb{R}^3) \times C_0^{\infty}(\mathbb{R}^3)$ given at $t = T^* - \delta$ (δ is a sufficiently small positive constant), we can extend the local solution under consideration smoothly to a larger strip, say, $\{(t, x) : 0 < t < \tilde{T}, x \in \mathbb{R}^3\}$, where $T^* < \tilde{T}$. The local solution thereby extended satisfies

$$N_{\mu}(u_1(t)), N_{\mu}(u_2(t)), N_{\mu}(u_3(t)) \in C([0, \tilde{T})), \ \mu = 3, 4,$$

$$\bigcup_{i=1}^{3} \text{supp } u_i(t, \cdot) \subset \{x \in \mathbb{R}^3 : |x| < R + c^*t\}, \quad 0 < t < \tilde{T}.$$

Since $(\langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \mathcal{N}_3(u(t)))|_{t=T^*} \leq (3/2)C^* ||(f,g)||_D$ by (6.12) and $\langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \mathcal{N}_3(u(t)) \in C([0,\tilde{T}))$, we see that there exists $T' \in (T^*,\tilde{T}]$ such that $\langle t \rangle^{-\delta} \mathcal{N}_4(u(t)) + \mathcal{N}_3(u(t))) \leq 2C^* ||(f,g)||_D$ for all $t \in (0,T')$, which contradicts the definition of T^* . Hence we have $T^* = \infty$. We have finished the proof.

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