# GLOBAL-IN-TIME WEAK MEASURE SOLUTIONS, FINITE-TIME AGGREGATION AND CONFINEMENT FOR NONLOCAL INTERACTION EQUATIONS 

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#### Abstract

In this paper we provide a well-posedness theory for weak measure solutions of the Cauchy problem for a family of nonlocal interaction equations. These equations are continuum models for interacting particle systems with attractive/repulsive pairwise interaction potentials. The main phenomenon of interest is that, even with smooth initial data, the solutions can concentrate mass in finite time. We develop an existence theory that enables one to go beyond the blow-up time in classical norms and allows for solutions to form atomic parts of the measure in finite time. The weak measure solutions are shown to be unique and exist globally in time. Moreover, in the case of sufficiently attractive potentials, we show the finite time total collapse of the solution onto a single point for compactly supported initial measures. Finally, we give conditions on compensation between the attraction at large distances and local repulsion of the potentials to have global-in-time confined systems for compactly supported initial data. Our approach is based on the theory of gradient flows in the space of probability measures endowed with the Wasserstein metric. In addition to classical tools, we exploit the stability of the flow with respect to the transportation distance to greatly simplify many problems by reducing them to questions about particle approximations.


Keywords: well-posedness for measure solutions, gradient flows, optimal transport, nonlocal interactions, finite time blow-up, particle approximation, confinement.

AMS Classification: 35B40, 45K05, 49K20, 92DXX.

## 1. Introduction

We consider a mass distribution of particles, $\mu \geq 0$, interacting under a continuous interaction potential, $W$. The associated interaction energy is defined as

$$
\begin{equation*}
\mathcal{W}[\mu]:=\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} W(x-y) d \mu(x) d \mu(y) . \tag{1.1}
\end{equation*}
$$

Our paper is devoted to the class of continuity equations of the form

$$
\begin{equation*}
\frac{\partial \mu}{\partial t}=\operatorname{div}\left[\left(\nabla \frac{\delta \mathcal{W}}{\delta \mu}\right) \mu\right]=\operatorname{div}[(\nabla W * \mu) \mu] \quad x \in \mathbb{R}^{d}, t>0 \tag{1.2}
\end{equation*}
$$

The equation is typically coupled with an initial datum

$$
\begin{equation*}
\mu(0)=\mu_{0} \tag{1.3}
\end{equation*}
$$

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The velocity field in the continuity equation, $-(\nabla W * \mu)(t, x)$, represents the combined contributions, at the point $x$, of the interaction through the potential $W$ with particles at all other points.

The choice of $W$ depends on the phenomenon studied. For instance in population dynamics, one is interested in the description of the evolution of a density of individuals. Very often the interaction between two individuals only depends on the distance between them. This suggests a choice of $W$ as a radial function, i.e. $W(x)=w(|x|)$. Moreover, a choice of $w$ such that $w^{\prime}(r)>0$ corresponds to an attractive force among the particles (or individuals), whereas $w^{\prime}(r)<0$ models a repulsive force.

Equation (1.2) arises in several applications in physics and biology. Simplified inelastic interaction models for granular media were considered in [4, [18] with $W=|x|^{3} / 3$ and [44, 28] with $W=|x|^{\alpha}, \alpha>1$. Such models usually lead to convex attractive potentials.

Mathematical modeling of the collective behavior of individuals, such as swarming, has also been treated by continuum models steaming from discrete particle models 33, [14, 42, 34, 43, 15, 36, 13, 21, 23, 16, 17. Typical examples of interaction potentials appearing in these works are the attractive Morse potential $W(x)=-e^{-|x|}$, attractiverepulsive Morse potentials $W(x)=-C_{a} e^{-|x| / \ell_{a}}+C_{r} e^{-|x| / \ell_{r}}, W(x)=-e^{-|x|^{2}}, W(x)=$ $-C_{a} e^{-|x|^{2} / \ell_{a}}+C_{r} e^{-|x|^{2} / \ell_{r}}$, or $W$ being the characteristic function of a set in $\mathbb{R}^{d}$. A major issue is the possibility of a finite time blow-up of initially regular solutions, which occurs when $w$ is attractive enough near $r=0$. In particular, the solution can aggregate (collapse) part (or all) of its mass to a point in finite time. Blow-up producing potentials feature a suitable singularity in their second derivative at $r=0$. Typically, the potential is of the form $W(x) \approx|x|^{1+\alpha}$ with $0 \leq \alpha<1$, see [27, 7, 6], 5] in case of the Lipschitz singularity. Related questions with diffusion added to the system have been tackled in [9, 29, 30, 31].

Finally, another source of models with interaction potential appear in the modeling of cell movement by chemotaxis. In fact, the classical Patlak-Keller-Segel [38, 26] system, see [12, 10, 11, corresponds to the choice of the Newtonian potential in $\mathbb{R}^{2}$ as interaction, $W=\frac{1}{2 \pi} \log |x|$, with linear diffusion. In the case without diffusion, a notion of weak measure solutions was introduced in [39] for which the author proved global-in-time existence, although uniqueness is lacking.

Given a continuous potential $W$, thanks to the structure of (1.2), we can assume without loss of generality that the following basic assumption holds:
(NL0) $W$ is continuous, $W(x)=W(-x)$, and $W(0)=0$.
Moreover, the potentials considered in this paper will also satisfy the following assumptions:
(NL1) $W$ is $\lambda$-convex for some $\lambda \leq 0$, i.e. $W(x)-\frac{\lambda}{2}|x|^{2}$ is convex.
(NL2) There exists a constant $C>0$ such that

$$
W(z) \leq C\left(1+|z|^{2}\right), \quad \text { for all } z \in \mathbb{R}^{d} .
$$

(NL3) $W \in C^{1}\left(\mathbb{R}^{d} \backslash\{0\}\right)$.
We will say that the potential is a pointy potential if it satisfies (NL0)-(NL3) and it has a Lipschitz singularity at the origin. If in addition, the potential is continuously differentiable at the origin, we will speak about a $C^{1}$-potential. If 0 is a local minimum of the potential $W$, we will say that the potential is locally attractive. Note that any
potential which is $\lambda$-convex for a positive $\lambda$ is also $\lambda$-convex for $\lambda=0$ and thus satisfies assumption (NL1).

Remark 1.1. Assumptions (NL0)-(NL1) imply that

$$
\begin{equation*}
W(x) \geq \frac{\lambda}{2}|x|^{2} \tag{1.4}
\end{equation*}
$$

since $0 \in \partial W(0)$ and $W(0)=0$. Hypotheses (NL1)-(NL3) imply a growth control on the gradient of $W$. More precisely, using the convexity of $x \mapsto \tilde{W}(x):=W(x)-\frac{\lambda}{2}|x|^{2}$ and the quadratic growth of $W(x)$, there exists $K>0$ such that

$$
\nabla \tilde{W}(x) \cdot p \leq \tilde{W}(x+p)-\tilde{W}(x) \leq K\left(1+|x|^{2}+|p|^{2}\right)
$$

for any $x \neq 0$. Now, taking the supremum among all vectors $p$ such that $|p|=\max \{|x|, 1\}$, we get $|\nabla \tilde{W}(x)| \leq K(2+2|x|)$ from which

$$
\begin{equation*}
|\nabla W(x)| \leq 2 K+(2 K+|\lambda|)|x| . \tag{1.5}
\end{equation*}
$$

Let us also remark that (NL1) together with (NL3) imply that if the potential is not differentiable at the origin, then it has at most a Lipschitz singularity at the origin. Examples of locally attractive potentials neither pointy nor smooth are the ones with a local behavior at the origin like $|x|^{1+\alpha}$, with $0<\alpha<1$.

The first problem we treat in this paper is to give a well-posedness theory of weak measure solutions in the case of pointy potentials. Due to the possible concentration of solutions in a finite time, one has to allow for a concept of weak solution in a (nonnegative) measure sense. Our work fills in an important gap in the present studies of the equation. Simplistically speaking: on the one hand, [2, 3, provide a good theory for weak measure solutions for potentials which are either smooth or do not produce blow-up in finite time. Indeed, when solutions concentrate and the potential is not everywhere differentiable, this is the first paper where one is able to characterize the subdifferential of $\mathcal{W}$, see Proposition 2.2. On the other hand, in the works that study potentials that do produce blow-up [27, 7, 6, 5] the notion of the solution breaks down at the blow-up time.

Before discussing the main results of this work, we introduce the concept of weak measure solution to (1.2). A natural way to introduce a concept of weak measure solution is to work in the space $\mathcal{P}\left(\mathbb{R}^{d}\right)$ of probability measures on $\mathbb{R}^{d}$. Since the class of equations described here does not feature mass-threshold phenomena, we normalize the mass to 1 without loss of generality, see Remark 5.5. Following the approach developed in [2, 3], we shall consider weak measure solutions which additionally belong to the metric space

$$
\mathcal{P}_{2}\left(\mathbb{R}^{d}\right):=\left\{\mu \in \mathcal{P}\left(\mathbb{R}^{d}\right): \int_{\mathbb{R}^{d}}|x|^{2} d \mu(x)<+\infty\right\}
$$

of probability measures with finite second moment, endowed with the 2 -Wasserstein distance $d_{W}$; see the next section.

Definition 1.2. A locally absolutely continuous curve $\mu:[0,+\infty) \ni t \mapsto \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ is said to be a weak measure solution to (1.2) with initial datum $\mu_{0} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ if $\partial^{0} W * \mu$ belongs
to $L_{l o c}^{1}\left([0,+\infty) ; L^{2}(\mu(t))\right)$ and

$$
\begin{align*}
& \int_{0}^{+\infty} \int_{\mathbb{R}^{d}} \frac{\partial \varphi}{\partial t}(x, t) d \mu(t)(x) d t+\int_{\mathbb{R}^{d}} \varphi(x, 0) d \mu_{0}(x)= \\
& \int_{0}^{+\infty} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \nabla \varphi(x, t) \cdot \partial^{0} W(x-y) d \mu(t)(x) d \mu(t)(y) d t \tag{1.6}
\end{align*}
$$

for all test functions $\varphi \in C_{c}^{\infty}\left([0,+\infty) \times \mathbb{R}^{d}\right)$.
In this definition, $\partial^{0} W(x)$ denotes the element of minimal norm in the subdifferential of $W$ at $x$. In particular, thanks to our assumptions on $W$ we will show the formula

$$
\left(\partial^{0} W * \mu\right)(x)=\int_{y \neq x} \nabla W(x-y) d \mu(y)
$$

see Proposition 2.2. Here, the absolute continuity of the curve of measures means that its metric derivative is integrable, see next section. Let us point out that, as a consequence of 1.5., $\partial^{0} W * \mu \in L^{2}(\mu)$ for any $\mu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$.

The main idea to construct weak measure solutions to $\sqrt{1.2}$ ) is to use the interpretation of these equations as gradient flows in the space $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ of the interaction potential functional (1.1) with respect to the transport distance $d_{W}$. Such an interpretation turns out to be extremely well-adapted to proving uniqueness and stability results for gradient flow solutions compared to other strategies. This basic intuitive idea, introduced in 37] for the porous medium equation and generalized to a wide class of equations in [19], was made completely rigorous for a large class of equations in [2, 3] including some particular instances of (1.2). For gradient flow solutions we are able to obtain the existence, uniqueness and $d_{W}$-stability. Let us point out that gradient flow solutions are eventually shown to be equivalent to weak measure solutions.

Let us remark that the well-posedness theory of gradient flow solutions in the space of probability measures is developed in [2, 3] for $\lambda$-convex potentials. However, a characterization of the subdifferential of the interaction functional $\mathcal{W}$ is provided only when the potential $W$ is $C^{1}$. Here, we mainly focus on generalizing this theory to allow Lipschitz singularities at the origin. In the case of not $C^{1}$-potentials satisfying (NL0)-(NL3), the technical point to deal with is the characterization of the subdifferential and its element of minimal norm. Moreover, we generalize this gradient flow theory allowing a negative quadratic behaviour at infinity. This fact introduces certain technical difficulties at the level of coercivity and lower semicontinuity of the functional defining the variational scheme. The well-posedness theory of gradient flow solutions is the goal of Section 2.

One of the key properties of the constructed solutions is the stability with respect to $d_{W}$ : given two gradient flow solutions $\mu^{1}(t)$ and $\mu^{2}(t)$,

$$
d_{W}\left(\mu^{1}(t), \mu^{2}(t)\right) \leq e^{-\lambda t} d_{W}\left(\mu_{0}^{1}, \mu_{0}^{2}\right)
$$

for all $t \geq 0$. If $\lambda>0$ the above estimate still holds provided that the initial measures have the same center of mass, see Remark 2.14. The above stability estimate is not only useful for showing uniqueness but it is mainly a tool for approximating general solutions by particle ones. In fact, the previous estimate can be considered as a proof of the convergence of the continuous particle method for this equation on bounded time
intervals. This is very much in the spirit of early works in the convergence of particle approximations to Vlasov-type equations in kinetic theory [22, 35, 40 .

Let us finally mention that it is not difficult to check that weak- $L^{p}$ solutions with initial data in $L_{+}^{1} \cap L^{p}\left(\mathbb{R}^{d}\right)$ with finite second moment constructed in [5, 20, 8] are also weak measure solutions in the sense of Definition 1.2 up to their maximal existence time, see Remark 2.15

Section 3 is devoted to show qualitative properties of the approximate solutions obtained by the variational scheme as in [25. More precisely, we prove that particles remain particles at the level of a discrete variational scheme, provided the time step is small enough. In particular, this shows that the gradient flow solution starting from a finite number of particles remains at any time a finite number of particles, whose positions are determined by an ODE system. Although the fact that this construction give the solutions for finite number of particles can be directly checked on the solution concept, it is quite interesting to prove it directly at the variational scheme level, as it shows its suitability as a numerical scheme.

Section 4 is devoted to the question of finite-time blow-up of solutions. For a radially symmetric attractive potential, i.e. $W(x)=w(|x|), w^{\prime}(r)>0$ for $r>0$, the number

$$
\begin{equation*}
T\left(\varepsilon_{1}\right):=\int_{0}^{\varepsilon_{1}} \frac{d r}{w^{\prime}(r)}, \quad \varepsilon_{1}>0 \tag{1.7}
\end{equation*}
$$

can be thought as the time it takes for a particle obeying the ODE $\dot{X}=-\nabla W(X)$ to reach the origin if it starts at a distance $\varepsilon_{1}$ from the origin. This number quantifies the attractive strength of the potential: the smaller $T\left(\varepsilon_{1}\right)$ is, the more attractive the potential is. It was shown in [6, 7, 8] that if $T\left(\varepsilon_{1}\right)=+\infty$ for some (or equivalently for all) $\varepsilon_{1}>0$, then solutions of (1.2) starting with initial data in $L^{p}$ will stay in $L^{p}$ for all time, whereas if $T\left(\varepsilon_{1}\right)<+\infty$ for some $\varepsilon_{1}>0$, then compactly supported solutions will leave $L^{p}$ in finite time (this result holds in the class of potentials which does not oscillate pathologically around the origin). In Section 4, thanks to our developed existence theory, we are able to obtain further understanding of the large time behavior of the solutions: loosely speaking, we prove that if the potential is attractive enough (i.e. $T\left(\varepsilon_{1}\right)<+\infty$ for some $\varepsilon_{1}>0$ ) then solutions of (1.2) starting with measure initial data will concentrate to a single Delta Dirac in finite time. We refer to this phenomena as finite time total collapse.

We will say that $W$ is an attractive non-Osgood potential if in addition to (NL0)(NL3), it satisfies the finite time blow-up condition:
(NL-FTBU) $W$ is radial, i.e. $W(x)=w(|x|), W \in C^{2}\left(\mathbb{R}^{d} \backslash\{0\}\right)$ with $w^{\prime}(r)>0$ for $r>0$ and satisfying the following monotonicity condition: either (a) $w^{\prime}\left(0^{+}\right)>$ 0 , or (b) $w^{\prime}\left(0^{+}\right)=0$ with $w^{\prime \prime}(r)$ monotone decreasing on an interval $\left(0, \varepsilon_{0}\right)$. Moreover, the potential satisfies the integrability condition

$$
\begin{equation*}
\int_{0}^{\varepsilon_{1}} \frac{1}{w^{\prime}(r)} d r<+\infty, \quad \text { for some } \varepsilon_{1}>0 \tag{1.8}
\end{equation*}
$$

Let us point out that the condition of monotonicity of $w^{\prime \prime}(r)$ is not too restrictive. It is actually automatically satisfied by any potential who satisfies 1.8 ) and whose second derivative does not oscillate badly at the origin, as in [6, 7] (more comments on this
assumption are done in Section 4). Examples of this type of potentials are the ones having a local behavior at the origin like $w^{\prime}(r) \simeq r^{\alpha}$ with $0 \leq \alpha<1$ or $w^{\prime}(r) \simeq r \log ^{2} r$.

The proof of finite-time total collapse of solutions for attractive non-Osgood potentials is based on showing a finite-time total collapse result for the particles approximation independent of the number of particles, but possibly depending on the initial support.
This fact, together with the convergence of the particle approximation, leads to the finitetime aggregation onto a single particle with the total mass of the system. This is the main technical novelty of our approach to blow-up.

It is worthwhile to remark on how our finite time total collapse result relates to previous works on finite time blow-up of weak- $L^{p}$ solutions [7, 5, 8]. It was shown in [8] that a weak- $L^{p}$ solution will exist as long as its $L^{p}$-norm is bounded. Since weak- $L^{p}$ solutions agree with the weak measure solutions for as long as weak- $L^{p}$ solutions exist, if the finite time collapse occurs then there exists a time $T^{*}$ such that $L^{p}$-norm of the density of the measure $\mu(t)$ goes to infinity as $t \rightarrow T^{*}$. That is, the finite time collapse of weak measure solutions implies finite time blow-up in the $L^{p}$-norm for weak- $L^{p}$ solutions. In this way, we recover the results of finite time blow-up for more restrictive potentials $W$ obtained in [6] under the condition (NL-FTBU). We emphasize that the condition (NL-FTBU) implies both the finite time blow-up in $L^{p}$ and the finite time collapse. Let us also point out that, even if we extend the notion of solution in a unique way passed any $L^{p}$ blow-up time, we are not able with this strategy to characterize the typical profile of $L^{\infty}$ or $L^{p}$ blow-up. We refer the reader to [24] for a numerical study of this question. Let us remark that the blow-up of the solution in $L^{p}$-norms will in general happen before the total aggregation/collapse onto a single point. The transition from the first $L^{\infty}$ blow-up to the total collapse can be very complicated. For instance one could have multiple points of aggregation onto Dirac deltas interacting between them and with smooth parts of the measure in a challenging evolution before the total aggregation onto a single point. As explained in Section 4, as a consequence of the strategy of proof for the finite time total collapse, we can exhibit the appearance of multiple collapses into different Dirac deltas which eventually will collapse all together, see Proposition 4.6. This also shows that generically any $L^{p}$ blow-up will happen before the total collapse time except for very particular initial symmetric distributions. This complex behavior was already encountered in [39] in the case of the chemotaxis model without diffusion, but his notion of solution lacks of uniqueness and stability. Many problems on the details of the blow-up in 1.2 and the interaction of delta masses with surrounding absolutely-continuous-measure part remain open.

The last section is devoted to proving confinement of solutions for attractive/repulsive potentials which are radial and increasing outside a ball, that is for ones that satisfy
(NL-RAD) There exists $R_{a} \geq 0$ such that $W(x)=w(|x|)$ for $|x| \geq R_{a}$, and $w^{\prime}(r) \geq 0$ for $r>R_{a}$.
We say that a potential is strongly-attractive-at-infinity if in addition to (NL0)-(NL3) and (NL-RAD) it satisfies the strong confinement condition:
(NL-CONF-strong)

$$
\liminf _{r \rightarrow+\infty} w^{\prime}(r)>8 \sqrt{2} C_{W}
$$

where

$$
C_{W}:=\left\{\begin{array}{cc}
0 & \text { if } R_{a}=0  \tag{1.9}\\
\sup _{x \in B\left(0, R_{a}\right) \backslash\{0\}}|\nabla W(x)| & \text { if } R_{a}>0
\end{array}\right.
$$

¿From 1.5 follows that $C_{W}$ is finite.
We say that a potential is weakly-attractive-at-infinity if in addition to (NL0)-(NL3) and (NL-RAD) it satisfies the weak confinement condition:
(NL-CONF-weak)

$$
\lim _{r \rightarrow+\infty} w^{\prime}(r) \sqrt{r}=+\infty
$$

We prove estimates on the evolution of the radius of the support of solutions. For potentials satisfying (NL-CONF-strong) these estimates guarantee that if the radius of the support is large then it must be decreasing. We then refine the argument to show that even if only (NL-CONF-weak) is satisfied, the radius must remain uniformly bounded in time. To showcase the robustness of the notion of the solution we use two different techniques: for the first result we use the JKO approximation scheme, while for the second one we use the particle approximations.

## 2. The Jordan-Kinderlehrer-Otto (JKO) scheme

In this section we develop the existence theory for measure-valued solutions in the sense of Definition 1.2 by following the set up developed in [2]. A natural choice of a space of measures where to develop such a theory is the space $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ endowed with the Wasserstein distance

$$
\begin{equation*}
d_{W}(\mu, \nu):=\left[\min \left\{\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \gamma(x, y): \gamma \in \Gamma(\mu, \nu)\right\}\right]^{1 / 2} \tag{2.1}
\end{equation*}
$$

where the set $\Gamma(\mu, \nu)$ of transport plans between $\mu$ and $\nu$ is defined by

$$
\Gamma(\mu, \nu):=\left\{\gamma \in \mathcal{P}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}\right):\left(\pi_{1}\right)_{\# \gamma}=\mu \text { and }\left(\pi_{2}\right)_{\# \gamma}=\nu\right\}
$$

with $\pi_{1}(x, y)=x$ and $\pi_{2}(x, y)=y$, that is,

$$
\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \phi(x) d \gamma=\int_{\mathbb{R}^{d}} \phi(x) d \mu, \quad \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \phi(y) d \gamma=\int_{\mathbb{R}^{d}} \phi(y) d \nu, \quad \text { for all } \phi \in C_{b}\left(\mathbb{R}^{d}\right)
$$

The space $\left(\mathcal{P}_{2}\left(\mathbb{R}^{d}\right), d_{W}\right)$ is a complete metric space [45, 2]. The standard theory of optimal transportation [2, 45] provides the existence of an optimal transport plan for variational problem (2.1), i.e. there exists $\gamma_{o} \in \Gamma(\mu, \nu)$ such that

$$
\begin{equation*}
d_{W}^{2}(\mu, \nu)=\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \gamma_{o}(x, y) \tag{2.2}
\end{equation*}
$$

The set of all the optimal plans $\gamma_{o}$ satisfying 2.2 is denoted by $\Gamma_{o}(\mu, \nu)$.
We recall that the interaction energy $\mathcal{W}: \mathcal{P}_{2}\left(\mathbb{R}^{d}\right) \rightarrow \mathbb{R}$ is defined as follows:

$$
\begin{equation*}
\mathcal{W}[\mu]:=\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} W(x-y) d \mu(x) d \mu(y) \tag{2.3}
\end{equation*}
$$

Note that $\mathcal{W}$ is well-defined on $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ due to assumptions (NL1)-(NL2), which provide suitable control of the integral at infinity. Also, the continuity of $W$ ensures the well-posedness of $\mathcal{W}$ on singular measures.

Following [2], we shall first address the problem of the existence of a curve of maximal slope for the functional $\mathcal{W}$. For this purpose, let us introduce some definitions. The slope of $\mathcal{W}$ is defined as:

$$
\begin{equation*}
|\partial \mathcal{W}|[\mu]:=\underset{\nu \rightarrow \mu}{\limsup } \frac{(\mathcal{W}[\mu]-\mathcal{W}[\nu])^{+}}{d_{W}(\mu, \nu)} \tag{2.4}
\end{equation*}
$$

where $u^{+}:=\max \{u, 0\}$. Given an absolutely continuous curve $[0, T] \ni t \mapsto \mu(t) \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, its metric derivative is:

$$
\begin{equation*}
\left|\mu^{\prime}\right|(t):=\limsup _{s \rightarrow t} \frac{d_{W}(\mu(s), \mu(t))}{|s-t|} \tag{2.5}
\end{equation*}
$$

Finally, we recall the definition of a curve of maximal slope for the functional $\mathcal{W}$. With the notation in [2], such a notion is referred to as a "curve of maximal slope with respect to $|\partial \mathcal{W}|$ ".

Definition 2.1. A locally absolutely continuous curve $[0, T] \ni t \mapsto \mu(t) \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ is a curve of maximal slope for the functional $\mathcal{W}$ if $t \mapsto \mathcal{W}[\mu(t)]$ is an absolutely continuous function, and the following inequality holds for every $0 \leq s \leq t \leq T$ :

$$
\begin{equation*}
\frac{1}{2} \int_{s}^{t}\left|\mu^{\prime}\right|^{2}(r) d r+\frac{1}{2} \int_{s}^{t}|\partial \mathcal{W}|^{2}[\mu(r)] d r \leq \mathcal{W}[\mu(s)]-\mathcal{W}[\mu(t)] \tag{2.6}
\end{equation*}
$$

The notion of solutions provided in Definition 2.1 is purely metric (see [2, Part I]). We shall improve this notion of solution (in the spirit of [2, Part II]) to a solution in the "gradient flow" sense in Subsection 2.3.

The inequality (2.6), which defines the notion of a curve of maximal slope, is better understood after providing a representation formula for the slope $|\partial \mathcal{W}|$ in terms of an integral norm of a vector field involving the "gradient" of $W$, or rather its minimal subdifferential $\partial^{0} W$. Moreover, the metric derivative $\left|\mu^{\prime}\right|$ should be interpreted in a "length space" sense, which accounts for the metric space $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ being endowed with a kind of Riemannian structure, first introduced in [37] and then proven rigorously in [2]. For the sake of clarity, let us briefly recall this framework (see [2, Chapter 8] for further details).

Given a measure $\mu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, the tangent space $\operatorname{Tan}_{\mu} \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ to $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ in $\mu$ is the closed vector subspace of $L^{2}(\mu)$ given by

$$
\operatorname{Tan}_{\mu} \mathcal{P}_{2}\left(\mathbb{R}^{d}\right):=\overline{\left\{\nabla \phi: \phi \in C_{c}^{\infty}\left(\mathbb{R}^{d}\right)\right\}}{ }^{L^{2}(\mu)}
$$

Moreover, given an absolutely continuous curve $t \mapsto \mu(t) \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, the "tangent vectors" to $\mu(t)$ can be identified as elements of the set of vector fields $v(t)$ solving the continuity equation

$$
\begin{equation*}
\partial_{t} \mu(t)+\nabla \cdot(v(t) \mu(t))=0 \tag{2.7}
\end{equation*}
$$

in the sense of distributions. Among all the possible velocity fields $v(t)$ solving (2.7), as a consequence of [2, Theorem 8.3.1], there is one with minimal $L^{2}(\mu(t))$-norm, equal to the metric derivative of $\mu(t)$. Therefore, we have the following representation formula for $\left|\mu^{\prime}\right|(t)$ : for a.e. $t \in(0, T)$,

$$
\left|\mu^{\prime}\right|(t)=\min \left\{\|v(t)\|_{L^{2}(\mu(t))}: v(t) \text { solves 2.7) in the sense of distributions }\right\} .
$$

More precisely, for every solution $v(t)$ of 2.7 ) the inequality $\left|\mu^{\prime}\right|(t) \leq\|v(t)\|_{L^{2}(\mu(t))}$ holds at a.e. $t \in(0, T)$, and there exists a "unique" solution of 2.7) for which equality holds
a.e. on $(0, T)$, see [2, Theorem 8.3.1 and Proposition 8.4.5]. We recall here the upper bound

$$
\begin{equation*}
\limsup _{\varepsilon \searrow 0} \frac{d_{W}\left((i d+\varepsilon \xi)_{\#} \mu, \mu\right)}{\varepsilon} \leq\|\xi\|_{L^{2}(d \mu)} \tag{2.8}
\end{equation*}
$$

which follows immediately from the the trivial inequality

$$
W_{2}\left(S_{\#} \mu, T_{\#} \mu\right) \leq\|S-T\|_{L^{2}(d \mu)} .
$$

As for the slope $|\partial \mathcal{W}|$ of the functional $\mathcal{W}$ (similarly to the classical subdifferential calculus in Hilbert spaces), it can be written as

$$
|\partial \mathcal{W}|(\mu)=\min \left\{\|w\|_{L^{2}(\mu)}: w \in \partial \mathcal{W}(\mu)\right\}
$$

where $\partial \mathcal{W}(\mu)$ is the (possibly multivalued) subdifferential of $\mathcal{W}$ at the measure $\mu$. The definition of subdifferential of a functional $\mathcal{W}$ on $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ in the general case is pretty involved (see [2, Definition 10.3.1]) and we shall not need to recall it here. In the next subsection, we follow the approach of 22 to characterize the (unique) element of the minimal subdifferential of $\mathcal{W}$ denoted by $\partial^{0} \mathcal{W}(\mu)$.
2.1. Subdifferential of $\mathcal{W}$. Given $W$ a potential satisfying (NL0)-(NL3), let $\partial W(x)$ be the (possibly multivalued) subdifferential of $W$ at the point $x$, namely the convex set

$$
\partial W(x):=\left\{\kappa \in \mathbb{R}^{d}: W(y)-W(x) \geq \kappa \cdot(y-x)+o(|x-y|), \text { for all } y \in \mathbb{R}^{d}\right\} .
$$

Denoting by $\partial^{0} W(x)$ the (unique) element of $\partial W(x)$ with minimal norm, due to the assumptions (NL0)-(NL1) and (NL3) we have $\partial^{0} W(x)=\nabla W(x)$ for $x \neq 0$ and $\partial^{0} W(0)=0$.

A vector field $\mathbf{w} \in L^{2}(\mu)$ is said to be an element of the subdifferential of $\mathcal{W}$ at $\mu$, and we write $\mathbf{w} \in \partial \mathcal{W}[\mu]$, if

$$
\begin{equation*}
\mathcal{W}[\nu]-\mathcal{W}[\mu] \geq \inf _{\gamma_{o} \in \Gamma_{o}(\mu, \nu)} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \mathbf{w}(x) \cdot(y-x) d \gamma_{o}(x, y)+o\left(d_{W}(\nu, \mu)\right) \tag{2.9}
\end{equation*}
$$

In principle, according to [2, Definition 10.3.1], the elements of $\partial W(x)$ are plans $\gamma$ in the set $\mathcal{P}_{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}\right)$ such that $\left(\pi_{1}\right)_{\#} \gamma=\mu$. If a plan $\gamma \in \partial \mathcal{W}[\mu]$ is concentrated on the graph of a vector field $\mathbf{w} \in L^{2}(\mu)$, then [2, Definition 10.3.1] reduces to (2.9). By following the approach of [2, Sections 10.3 and 10.4], it is easy to see that the (unique) element with minimal norm of $\partial \mathcal{W}[\mu]$ is concentrated on the graph of a vector field. Following [2], we call this element the minimal subdifferential of $\mathcal{W}$ at $\mu$, and we denote it by $\partial^{0} \mathcal{W}[\mu]$. The following characterization of the subdifferential is obtained in [2, Theorem 10.4.11] for smooth $C^{1}$-potentials, and here we generalize it to potentials satisfying (NL0)-(NL3):

Proposition 2.2. Given a potential satisfying (NL0)-(NL3), the vector field

$$
\kappa(x):=\left(\partial^{0} W * \mu\right)(x)=\int_{y \neq x} \nabla W(x-y) d \mu(y)
$$

is the unique element of minimal $L^{2}(\mu)$-norm in the subdifferential of $\mathcal{W}$, i.e. $\partial^{0} W * \mu=$ $\partial^{0} \mathcal{W}[\mu]$.

Proof. We divide the proof into two steps.
Step 1: $\kappa(x) \in \partial \mathcal{W}[\mu]$. We have to show that

$$
\mathcal{W}[\nu]-\mathcal{W}[\mu] \geq \inf _{\gamma \in \Gamma_{o}(\mu, \nu)} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \kappa(x) \cdot(y-x) d \gamma(x, y)+o\left(d_{W}(\nu, \mu)\right) .
$$

Thanks to the $\lambda$-convexity of $W$, it suffices to prove that, for any fixed $\gamma \in \Gamma_{o}(\mu, \nu)$, we have

$$
\begin{equation*}
\liminf _{t \rightarrow 0} \frac{\left.\mathcal{W}\left[(1-t) \pi_{1}+t \pi_{2}\right)_{\#} \gamma\right]-\mathcal{W}[\mu]}{t} \geq \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \kappa(x) \cdot(y-x) d \gamma(x, y) . \tag{2.10}
\end{equation*}
$$

To see this, we observe that the $\lambda$-convexity of $W$ implies that the function

$$
\begin{equation*}
t \mapsto f(t):=\frac{W(t y+(1-t) x)-W(x)}{t}-\frac{\lambda}{2} t|x-y|^{2} \tag{2.11}
\end{equation*}
$$

is nondecreasing in $t$. Therefore, by writing $f(1) \geq \liminf _{t \searrow 0} f(t)$, integrating with respecto to $\gamma$, and using the monotone convergence theorem, we easily recover

$$
\mathcal{W}[\nu]-\mathcal{W}[\mu] \geq \liminf _{t \rightarrow 0} \frac{\left.\mathcal{W}\left[(1-t) \pi_{1}+t \pi_{2}\right)_{\#} \gamma\right]-\mathcal{W}[\mu]}{t}+\frac{\lambda}{2} d_{W}^{2}(\nu, \mu)
$$

We now prove 2.10. Let us write $W=\tilde{W}+\frac{\lambda}{2}|x|^{2}$, so that $\tilde{W}:=W-\frac{\lambda}{2}|x|^{2}$ is convex and $0 \in \partial \tilde{W}(0)$. Moreover we define

$$
\tilde{\mathcal{W}}[\mu]:=\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \tilde{W}(x-y) d \mu(x) d \mu(y), \quad \mathcal{Q}[\mu]:=\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \mu(x) d \mu(y) .
$$

Observe that $\mathcal{W}=\tilde{\mathcal{W}}+\mathcal{Q}$. We first estimate $\left.\frac{1}{t}\left(\tilde{\mathcal{W}}\left[(1-t) \pi_{1}+t \pi_{2}\right)_{\# \gamma}\right]-\tilde{\mathcal{W}}[\mu]\right)$ : since $\tilde{W}$ is nonnegative, we have

$$
\begin{aligned}
& \frac{\left.\tilde{\mathcal{W}}\left[(1-t) \pi_{1}+t \pi_{2}\right)_{\# \gamma}\right]-\tilde{\mathcal{W}}[\mu]}{t} \\
& =\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left[\frac{\tilde{W}\left(t\left(y_{2}-y_{1}\right)+(1-t)\left(x_{2}-x_{1}\right)\right)-\tilde{W}\left(x_{2}-x_{1}\right)}{t}\right] d \gamma\left(x_{1}, y_{1}\right) d \gamma\left(x_{2}, y_{2}\right) \\
& \geq \frac{1}{2} \int_{x_{1} \neq x_{2}}\left[\frac{\tilde{W}\left(t\left(y_{2}-y_{1}\right)+(1-t)\left(x_{2}-x_{1}\right)\right)-\tilde{W}\left(x_{2}-x_{1}\right)}{t}\right] d \gamma\left(x_{1}, y_{1}\right) d \gamma\left(x_{2}, y_{2}\right) .
\end{aligned}
$$

Thanks to the convexity of $\tilde{W}$ and its (at most) quadratic growth at infinity, and using the fact that $\nabla \tilde{W}$ is odd, it is easily seem that the last term in the above equation converges to

$$
\int_{x_{1} \neq x_{2}} \nabla \tilde{W}\left(x_{2}-x_{1}\right) \cdot\left(y_{2}-x_{2}\right) d \gamma\left(x_{1}, y_{1}\right) d \gamma\left(x_{2}, y_{2}\right) .
$$

On the other hand, it is an easy computation to check that

$$
\begin{aligned}
\frac{\left.\mathcal{Q}\left[(1-t) \pi_{1}+t \pi_{2}\right)_{\# \gamma}\right]-\mathcal{Q}[\mu]}{t} & \rightarrow \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(x_{2}-x_{1}\right) \cdot\left(y_{2}-x_{2}\right) d \gamma\left(x_{1}, y_{1}\right) d \gamma\left(x_{2}, y_{2}\right) \\
& =\int_{x_{1} \neq x_{2}}\left(x_{2}-x_{1}\right) \cdot\left(y_{2}-x_{2}\right) d \gamma\left(x_{1}, y_{1}\right) d \gamma\left(x_{2}, y_{2}\right)
\end{aligned}
$$

Combining all these estimates together, we get the desired result.
Step 2: $w$ is the element of minimal norm of $\partial \mathcal{W}[\mu]$. We closely follows the
argument in [2, Theorem 10.4.11]. Fix a vector field $\xi \in C_{c}^{\infty}\left(\mathbb{R}^{d}, \mathbb{R}^{d}\right)$. Observing that $W(x-z+t(\xi(x)-\xi(z)))=W(x-z)=0$ when $x=z$, we get
$\lim _{t \rightarrow 0} \frac{\mathcal{W}\left[(i d+t \xi)_{\#} \mu\right]-\mathcal{W}[\mu]}{t}$
$=\lim _{t \rightarrow 0} \frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \frac{W((x-z)+t(\xi(x)-\xi(z)))-W(x-z)}{t} d \mu(x) d \mu(z)$
$=\lim _{t \rightarrow 0} \frac{1}{2} \int_{x \neq z} \frac{W((x-z)+t(\xi(x)-\xi(z)))-W(x-z)}{t} d \mu(x) d \mu(z)$
$=\frac{1}{2} \int_{x \neq z} \nabla W(x-z) \cdot(\xi(x)-\xi(z)) d \mu(x) d \mu(z)$
$=\int_{\mathbb{R}^{d}} \kappa(x) \cdot \xi(x) d \mu(x)$.
Hence, since the definition of slope (2.4) easily implies

$$
\liminf _{t \searrow 0} \frac{\mathcal{W}\left[(i d+t \xi)_{\#} \mu\right]-\mathcal{W}[\mu]}{d_{W}\left((i d+t \xi)_{\#} \mu, \mu\right)} \geq-|\partial \mathcal{W}|(\mu),
$$

we can use (2.8) and $(2.12)$ to get

$$
\int_{\mathbb{R}^{d}} \kappa(x) \cdot \xi(x) d \mu(x) \geq-|\partial \mathcal{W}|(\mu) \liminf _{t \rightarrow 0} \frac{d_{W}\left((i d+t \xi)_{\#} \mu, \mu\right)}{t} \geq-|\partial \mathcal{W}|(\mu)\|\xi\|_{L^{2}(\mu)} .
$$

Changing $\xi$ with $-\xi$ gives

$$
\left|\int_{\mathbb{R}^{d}} \kappa(x) \cdot \xi(x) d \mu(x)\right| \leq|\partial \mathcal{W}|(\mu)\|\xi\|_{L^{2}(\mu)},
$$

so that by the arbitrariness of $\xi$ we get $\|\kappa\|_{L^{2}(\mu)} \leq|\partial \mathcal{W}|(\mu)$, and therefore $\kappa$ is the (unique) element of minimal norm.
2.2. Well-posedness and convergence of the scheme. The approach of [2] in proving the existence of a curve of maximal slope for a functional on $\mathcal{P}_{2}$ is based on a variational version of the implicit Euler scheme, sometimes referred to as the Jordan-KinderlehrerOtto (JKO) scheme or minimizing movement scheme [25, 1, 2]. Given an initial measure $\mu_{0} \in \mathcal{P}_{2}$ and time-step $\tau>0$, we consider a sequence $\mu_{k}^{\tau}$ recursively defined by $\mu_{0}^{\tau}=\mu_{0}$ and

$$
\begin{equation*}
\mu_{k+1}^{\tau} \in \arg \min _{\mu \in \mathcal{P}_{2}}\left\{\mathcal{W}[\mu]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{k}^{\tau}, \mu\right)\right\}, \tag{2.13}
\end{equation*}
$$

for all $k \in \mathbb{N}$.
We shall address here the well-posedness of the definition (2.13) and the convergence of $\mu_{k}^{\tau}$ as $\tau \rightarrow 0$ (after a suitable interpolation) to a limit which satisfies Definition 2.1. Such a problem has been widely studied for smooth convex potentials in [2], where convergence of the discrete scheme to a suitable limit is shown. However, allowing for $W(x)$ behaving like $-C|x|^{2}$ as $|x| \rightarrow+\infty$ and for a pointy singularity at $x=0$ would require in general some improvements of the arguments in [2, Part I], as we shall see below. Indeed let us point out that, for $W(x)$ behaving like $-C|x|^{2}$, the functional $\mathcal{W}[\mu]$ is upper (and not lower!) semicontinuous with respect to the narrow convergence. Let us observe that in our case one could exploit the fact the functional $\mathcal{W}$ is $\lambda$-convex along generalized geodesic to directly apply the theory developed in [2], see Remark 2.9. On the other
hand our proofs are more flexible, and so we believe that our strategy can be of interest also in other situations.

For the sake of clarity, we shall recall all the main steps of the JKO scheme developed in [2] in the particular case of a functional given by a pure nonlocal interaction energy. We shall perform this task also for another reason, namely to relax the set of assumptions (NL0)-(NL3) in order to admit $|\nabla W|$ to be possibly unbounded at the origin (see Remark 2.11).

We start by showing that the minimization problem (2.13) admits at least one solution, which in our situation is not a trivial issue. To this aim, we prove a technical lemma which will be also useful in the sequel.

Lemma 2.3 (Weak lower semi-continuity of the penalized interaction energy). Suppose $W$ satisfies (NL0)-(NL3). Then, for a fixed $\bar{\mu} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, the penalized interaction energy functional

$$
\mathcal{P}_{2}\left(\mathbb{R}^{d}\right) \ni \mu \mapsto \mathcal{W}[\mu]+\frac{1}{2 \tau} d_{W}^{2}(\mu, \bar{\mu})
$$

is lower semi-continuous with respect to the narrow topology of $\mathcal{P}\left(\mathbb{R}^{d}\right)$ for all $\tau>0$ such that $8 \tau \lambda^{-} \leq 1$, where $\lambda^{-}:=\max \{0,-\lambda\}$.

Proof. Let $\left\{\mu_{n}\right\}_{n} \subset \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ such that $\lim _{n \rightarrow+\infty} \mu_{n}=\mu_{\infty}$ narrowly. We have to prove that

$$
\begin{equation*}
\liminf _{n \rightarrow+\infty}\left[\mathcal{W}\left[\mu_{n}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)\right] \geq \mathcal{W}\left[\mu_{\infty}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{\infty}, \bar{\mu}\right) \tag{2.14}
\end{equation*}
$$

From the estimate in Remark 1.1 and the fact that $\lambda \leq 0$, we have

$$
W(x-y) \geq \frac{\lambda}{2}|x-y|^{2} \geq \lambda\left(|x|^{2}+|y|^{2}\right)
$$

which implies that

$$
h(x, y):=W(x-y)-\lambda\left(|x|^{2}+|y|^{2}\right)
$$

is a nonnegative continuous function. Therefore,

$$
\begin{align*}
\mathcal{W}\left[\mu_{n}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)= & \lambda \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(|x|^{2}+|y|^{2}\right) d \mu_{n}(x) d \mu_{n}(y) \\
& +\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} h(x, y) d \mu_{n}(x) d \mu_{n}(y)+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right) \\
= & \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} h(x, y) d \mu_{n}(x) d \mu_{n}(y) \\
& +\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)+2 \lambda \int_{\mathbb{R}^{d}}|x|^{2} d \mu_{n}(x) . \tag{2.15}
\end{align*}
$$

Since $h \geq 0$, we easily get

$$
\begin{equation*}
\liminf _{n \rightarrow+\infty} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} h(x, y) d \mu_{n}(x) d \mu_{n}(y) \geq \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} h(x, y) d \mu_{\infty}(x) d \mu_{\infty}(y) \tag{2.16}
\end{equation*}
$$

Therefore, to get the desired assertion it suffices to prove that

$$
\begin{equation*}
\liminf _{n \rightarrow+\infty} \frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)+2 \lambda \int_{\mathbb{R}^{d}}|x|^{2} d \mu_{n}(x) \geq \frac{1}{2 \tau} d_{W}^{2}\left(\mu_{\infty}, \bar{\mu}\right)+2 \lambda \int_{\mathbb{R}^{d}}|x|^{2} d \mu_{\infty}(x) . \tag{2.17}
\end{equation*}
$$

Now, let $\gamma_{n} \in \Gamma_{o}\left(\bar{\mu}, \mu_{n}\right)$. Then,

$$
\begin{equation*}
\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)+2 \lambda \int_{\mathbb{R}^{d}}|x|^{2} d \mu_{n}(x)=\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(\frac{1}{2 \tau}|x-y|^{2}+2 \lambda|y|^{2}\right) d \gamma_{n}(x, y) \tag{2.18}
\end{equation*}
$$

Stability of optimal transportation plans (see [46, Theorem 5.20]) implies that there exists a subsequence, that we may assume to be the whole sequence, such that $\gamma_{n}$ converges narrowly to an optimal plan $\gamma_{\infty} \in \Gamma_{o}\left(\bar{\mu}, \mu_{\infty}\right)$. As a consequence of

$$
\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x|^{2} d \gamma_{n}(x, y)=\int_{\mathbb{R}^{d}}|x|^{2} d \bar{\mu}(x)=\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x|^{2} d \gamma_{\infty}(x, y)
$$

and of the elementary inequality $|y|^{2} \leq 2|x-y|^{2}+2|x|^{2}$ which implies

$$
\begin{equation*}
\frac{1}{2 \tau}|x-y|^{2}+2 \lambda|y|^{2}+\frac{1}{2 \tau}|x|^{2} \geq\left(\frac{1}{4 \tau}+2 \lambda\right)|y|^{2} \geq 0 \quad \text { if } \tau \leq \frac{1}{8 \lambda^{-}}, \tag{2.19}
\end{equation*}
$$

we easily obtain

$$
\begin{aligned}
& \liminf _{n \rightarrow+\infty} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(\frac{1}{2 \tau}|x-y|^{2}+2 \lambda|y|^{2}\right) d \gamma_{n}(x, y) \\
& =-\frac{1}{2 \tau} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x|^{2} d \gamma_{\infty}(x, y)+\liminf _{n \rightarrow+\infty} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(\frac{1}{2 \tau}|x-y|^{2}+2 \lambda|y|^{2}+\frac{1}{2 \tau}|x|^{2}\right) d \gamma_{n}(x, y) \\
& \geq-\frac{1}{2 \tau} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x|^{2} d \gamma_{\infty}(x, y)+\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(\frac{1}{2 \tau}|x-y|^{2}+2 \lambda|y|^{2}+\frac{1}{2 \tau}|x|^{2}\right) d \gamma_{\infty}(x, y) \\
& =\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left(\frac{1}{2 \tau}|x-y|^{2}+2 \lambda|y|^{2}\right) d \gamma_{\infty}(x, y) .
\end{aligned}
$$

This proves (2.17).
Remark 2.4. We observe that the optimality of the plans $\gamma_{n}$ and $\gamma_{\infty}$ is never actually needed in the previous proof. More precisely, the weak lower semi-continuity property stated in the above lemma still holds for the functional

$$
\mathcal{P}_{2}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}\right) \ni \gamma \mapsto \mathcal{W}\left[\left(\pi_{1}\right)_{\#} \gamma\right]+\frac{1}{2 \tau} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \gamma(x, y),
$$

where $\left(\pi_{2}\right)_{\# \gamma}=\bar{\mu}$ is fixed.
Next, we prove the solvability of the minimization problem (2.13).
Proposition 2.5 (Existence of minimizers). Suppose $W$ satisfies (NL0)-(NL3). Then, there exists $\tau_{0}>0$ depending only on $W$ such that, for all $0<\tau<\tau_{0}$ and for a given $\bar{\mu} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, there is $\mu_{\infty} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ such that

$$
\mathcal{W}\left[\mu_{\infty}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\bar{\mu}, \mu_{\infty}\right)=\min _{\mu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)}\left\{\mathcal{W}[\mu]+\frac{1}{2 \tau} d_{W}^{2}(\bar{\mu}, \mu)\right\} .
$$

Proof. Step 1: Compactness. Let us fix a measure $\bar{\mu} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ and a time step $\tau>0$, and consider a minimizing sequence $\mu_{n} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, i.e.

$$
\inf _{\mu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)}\left\{\mathcal{W}[\mu]+\frac{1}{2 \tau} d_{W}^{2}(\mu, \bar{\mu})\right\}=\lim _{n \rightarrow+\infty}\left\{\mathcal{W}\left[\mu_{n}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)\right\} .
$$

Since $\mu_{n}$ is a minimizing sequence, we have

$$
\begin{equation*}
\mathcal{W}\left[\mu_{n}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right) \leq C_{1} \tag{2.20}
\end{equation*}
$$

for some constant $C_{1}$. Then, the lower estimate of $W$ in Remark 1.1 and the inequality (2.19) imply, after very similar computations as in Lemma 2.3 , that $d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)$ is uniformly bounded with respect to $n$ if $\tau$ is small enough. Prokhorov's compactness theorem then implies that the sequence $\left\{\mu_{n}\right\}_{n}$ is tight.

Step 2: Coercivity. We need to prove that

$$
\liminf _{n \rightarrow+\infty}\left[\mathcal{W}\left[\mu_{n}\right]+\frac{1}{2 \tau} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)\right] \geq C_{0} d_{W}^{2}\left(\mu_{n}, \bar{\mu}\right)-C_{1}
$$

for some positive constant $C_{0}, C_{1}$ independent on $n$. This follows similarly to Step 1 for $\tau$ small enough.

Step 3: Passing to the limit by lower semi-continuity. This is a consequence of Lemma 2.3.

Next we have to establish that the family $\left\{\mu_{k}^{\tau}\right\}_{\tau \in\left(0, \tau_{0}\right)}$ (up to a suitable interpolation) converges narrowly to a certain limit. This task can be performed exactly as described in [2, Chapters 2, 3]. For the sake of clarity, we recall here the result in [2] stating the convergence of the JKO scheme. The proof can be found in [2, Proposition 2.2.3]. First, we introduce the piecewise constant interpolation

$$
\begin{aligned}
& \mu^{\tau}(0):=\mu_{0} \\
& \mu^{\tau}(t):=\mu_{k}^{\tau} \quad \text { if } \quad t \in((k-1) \tau, k \tau], \quad k \geq 1 .
\end{aligned}
$$

Proposition 2.6 (Compactness in the JKO scheme [2]). Suppose $W$ satisfies (NL0)(NL3). There exist a sequence $\tau_{n} \searrow 0$, and a limit curve $\mu \in A C_{l o c}\left([0,+\infty) ; \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)\right)$, such that

$$
\mu^{n}(t):=\mu^{\tau_{n}}(t) \rightarrow \mu(t), \quad \text { narrowly as } \quad n \rightarrow+\infty
$$

for all $t \in[0,+\infty)$.
According to the notation recalled in [2, Definition 2.0.6], the above proposition states that the set of minimizing movements for $\mathcal{W}$ starting from $\mu_{0}$ is not empty. The last step of the procedure proposed in [2] is to check that the limit curve provided by Proposition 2.6 is a curve of maximal slope for $W$ according to definition 2.1.

Let $\tilde{\mu}^{n}(t)$ denote the De Giorgi variational interpolation (see [2, Section 3.2]). Then, from [2, Equation (3.1.12)] and the argument in the proof of [2, Lemma 3.2.2] we have the energy inequality

$$
\begin{equation*}
\mathcal{W}\left[\mu_{0}\right] \geq \frac{1}{2} \int_{0}^{T}\left\|v^{n}(t)\right\|_{L^{2}\left(\mu^{n}(t)\right)}^{2} d t+\frac{1}{2} \int_{0}^{T}|\partial \mathcal{W}|\left(\tilde{\mu}^{n}(t)\right)^{2} d t+\mathcal{W}\left[\mu^{n}(T)\right] \tag{2.21}
\end{equation*}
$$

for all $T>0$, where on any interval $\left[(k-1) \tau_{n}, k \tau_{n}\right]$ the curve $\mu^{n}(t)$ is a Wasserstein geodesic connecting $\mu_{k-1}^{\tau_{n}}$ to $\mu_{k}^{\tau_{n}}$, and $v^{n}(t)$ is its velocity field. Let us recall that the continuity equation $\partial_{t} \mu^{n}(t)+\operatorname{div}\left(v^{n}(t) \mu^{n}(t)\right)=0$ holds, and that up to a subsequence both $\mu^{n}(t)$ and $\tilde{\mu}^{n}(t)$ narrowly converge to the same limit curve $\mu(t)$ on $[0,+\infty)$ provided by Proposition 2.6. The following lemma is needed to suitably pass to the limit the slope term in (2.21).

Lemma 2.7 (Lower semicontinuity of the slope).

$$
\liminf _{n \rightarrow+\infty} \int_{0}^{T}|\partial \mathcal{W}|^{2}\left(\tilde{\mu}^{n}(t)\right) d t \geq \int_{0}^{T}|\partial \mathcal{W}|^{2}(\mu(t)) d t
$$

Proof. By using the representation formula proven in Proposition 2.2, we have to prove that

$$
\liminf _{n \rightarrow+\infty} \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|\kappa^{n}(x, t)\right|^{2} d \mu^{n}(t)(x) d t \geq \int_{0}^{T} \int_{\mathbb{R}^{d}}|\kappa(x, t)|^{2} d \mu(t)(x) d t
$$

where

$$
\kappa^{n}(x, t):=\partial^{0} W * \mu^{n}(x, t), \quad \kappa(x, t):=\partial^{0} W * \mu(x, t) .
$$

Without loss of generality, up to passing to a subsequence we can assume that

$$
\sup _{n} \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|\kappa^{n}(x, t)\right|^{2} d \mu^{n}(t)(x) d t<+\infty .
$$

Hence, as a byproduct of [2, Theorem 5.4.4] on the measure space $X:=\mathbb{R}^{d} \times[0, T]$ with the family of measures $\mu^{n} \otimes d t$, we get the desired assertion once we prove that $\kappa^{n}$ converges weakly to $\kappa$, i.e. that for any vector field $\phi \in C_{c}^{\infty}\left(\mathbb{R}^{d} \times[0, T] ; \mathbb{R}^{d}\right)$

$$
\begin{equation*}
\int_{0}^{T} \int_{\mathbb{R}^{d}} \phi(x, t) \cdot \kappa^{n}(x, t) d \mu^{n}(t)(x) \rightarrow \int_{0}^{T} \int_{\mathbb{R}^{d}} \phi(x, t) \cdot \kappa(x, t) d \mu(t)(x) \tag{2.22}
\end{equation*}
$$

as $n \rightarrow+\infty$. To show this, we observe that term on the left-hand side is given by

$$
\begin{gathered}
\int_{0}^{T} \int_{\mathbb{R}^{d}} \phi(x, t) \cdot \kappa^{n}(x, t) d \mu^{n}(t)(x)=\int_{0}^{T} \int_{x \neq y} \phi(x, t) \cdot \nabla W(x-y) d \mu^{n}(t)(y) d \mu^{n}(t)(x) d t \\
=\frac{1}{2} \int_{0}^{T} \int_{x \neq y}(\phi(x, t)-\phi(y, t)) \cdot \nabla W(x-y) d \mu^{n}(t)(y) d \mu^{n}(t)(x) d t
\end{gathered}
$$

where for the second equality we used the (crucial) fact that $\nabla W$ is odd, so we could symmetrize the expression inside the integral.

By [2, Lemma 3.2.2], the sequence $\mu_{n}$ has uniformly bounded second moments. Therefore, thanks to the linear growth control on the gradient of $W$ in 1.5), the function $(\phi(x, t)-\phi(y, t)) \cdot \nabla W(x-y)$ is uniformly integrable with respect to $\mu^{n}(t) \otimes \mu^{n}(t) \otimes d t$, and we easily recover 2.22 by weak convergence arguments.

We are now ready to complete the proof of the existence of a solution to $\sqrt{1.2}-(1.3)$ in the sense of Definition 2.1.

Theorem 2.8 (Existence of curves of maximal slope). Let $W$ satisfy the assumptions (NL0)-(NL3). Then, there exists at least one curve of maximal slope for the functional $\mathcal{W}$, i.e. there exists at least one curve $\mu \in A C_{l o c}\left([0,+\infty) ; \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)\right)$ such that the energy inequality

$$
\begin{align*}
\mathcal{W}\left[\mu_{0}\right] \geq \frac{1}{2} \int_{0}^{T} & \|v(t)\|_{L^{2}(\mu(t))}^{2} d t \\
& +\frac{1}{2} \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|\int_{x \neq y} \nabla W(x-y) d \mu(t)(y)\right|^{2} d \mu(t)(x) d t+\mathcal{W}[\mu(T)], \tag{2.23}
\end{align*}
$$

is satisfied, where $v(t) \in L^{2}(\mu(t))$ is the minimal velocity field associated to $\mu$.

Proof. We want to prove that the curve $\mu(t)$ provided by Proposition 2.6 satisfies the desired condition. As a consequence of (2.21) and of Lemma 2.7, if we show that

$$
\begin{equation*}
\liminf _{n \rightarrow \infty} \frac{1}{2} \int_{0}^{T}\left\|v^{n}(t)\right\|_{L^{2}\left(\mu^{n}(t)\right)}^{2} d t+\mathcal{W}\left[\mu^{n}(T)\right] \geq \frac{1}{2} \int_{0}^{T}\|v(t)\|_{L^{2}\left(\mu^{n}(t)\right)}^{2} d t+\mathcal{W}[\mu(T)] \tag{2.24}
\end{equation*}
$$

all the remaining parts of the proof of the convergence of the scheme to a solution goes through like in the case when $\mathcal{W}$ is lower semicontinuous with respect to the narrow topology, see [2, Chapter 3].

To prove the inequality (2.24), having in mind the constitutive relation (2.7) linking $\mu^{n}$ and $v^{n}$, we regularize the solutions of $\partial_{t} \mu^{n}(t)+\operatorname{div}\left(v^{n}(t) \mu^{n}(t)\right)=0$ and $\partial_{t} \mu(t)+$ $\operatorname{div}(v(t) \mu(t))=0$ as follows:

$$
\begin{array}{ll}
v^{n, \varepsilon}(t):=\frac{\left(v^{n}(t) \mu^{n}(t)\right) * \eta_{\varepsilon}}{\mu^{n}(t) * \eta_{\varepsilon}}, & \mu^{n, \varepsilon}(t):=\mu^{n}(t) * \eta_{\varepsilon} \\
v^{\varepsilon}(t):=\frac{(v(t) \mu(t)) * \eta_{\varepsilon}}{\mu(t) * \eta_{\varepsilon}}, & \mu^{\varepsilon}(t):=\mu(t) * \eta_{\varepsilon}
\end{array}
$$

where $\eta_{\varepsilon}=\frac{1}{\varepsilon^{d}} \eta(\dot{\bar{\varepsilon}}) \in C^{\infty}\left(\mathbb{R}^{d}\right)$ is a smooth convolution kernel with support the whole $\mathbb{R}^{d}$, say a gaussian. Applying [2, Proposition 8.1.8] we deduce that the measures $\mu^{n, \varepsilon}(t), \mu^{\varepsilon}(t)$ are given by the formula $\mu^{n, \varepsilon}(t)=\left(X^{n, \varepsilon}(t)\right)_{\#} \mu_{0}$ and $\mu^{\varepsilon}(t)=\left(X^{\varepsilon}(t)\right)_{\#} \mu_{0}$, where $X^{n, \varepsilon}(t)$ and $X^{\varepsilon}(t)$ denote the flows of $v^{n, \varepsilon}(t)$ and $v^{\varepsilon}(t)$ respectively, more precisely

$$
\begin{aligned}
& \frac{d}{d t} X^{n, \varepsilon}(t, x)=v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right), \quad X^{n, \varepsilon}(0, x)=x \\
& \frac{d}{d t} X^{\varepsilon}(t, x)=v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right), \quad X^{\varepsilon}(0, x)=x
\end{aligned}
$$

We now define the transport map from $\mu^{\varepsilon}(T)$ to $\mu^{n, \varepsilon}(T)$ as $T_{n}^{\varepsilon}:=X^{n, \varepsilon}(T) \circ\left(X^{\varepsilon}(T)\right)^{-1}$. We have

$$
\begin{aligned}
& d_{W}^{2}\left(\mu^{\varepsilon}(T), \mu^{n, \varepsilon}(T)\right) \leq \int_{\mathbb{R}^{d}}\left|T_{n}^{\varepsilon}(x)-x\right|^{2} d \mu^{\varepsilon}(T)(x) \\
& =\int_{\mathbb{R}^{d}}\left|X^{n, \varepsilon}(T) \circ\left(X^{\varepsilon}(T)\right)^{-1}(x)-\left(X^{\varepsilon}(T)\right)^{-1}(x)+\left(X^{\varepsilon}(T)\right)^{-1}(x)-x\right|^{2} d \mu(T)(x) \\
& =\int_{\mathbb{R}^{d}}\left|\int_{0}^{T}\left[v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t) \circ\left(X^{\varepsilon}(T)\right)^{-1}(x)\right)-v^{\varepsilon}\left(t, X^{\varepsilon}(t) \circ\left(X^{\varepsilon}(T)\right)^{-1}(x)\right)\right] d t\right|^{2} d \mu^{\varepsilon}(T)(x) \\
& =\int_{\mathbb{R}^{d}}\left|\int_{0}^{T}\left[v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right)-v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right)\right] d t\right|^{2} d \mu_{0}^{\varepsilon}(x)
\end{aligned}
$$

By Hölder's inequality and expanding the squares, we get

$$
\begin{align*}
& d_{W}^{2}\left(\mu^{\varepsilon}(T), \mu^{n, \varepsilon}(T)\right) \leq T \int_{\mathbb{R}^{d}} \int_{0}^{T}\left|v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right)-v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right)\right|^{2} d t d \mu_{0}^{\varepsilon}(x) \\
& \quad \leq T \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{n, \varepsilon}(t, x)\right|^{2} d \mu^{n, \varepsilon}(t)(x) d t+T \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{\varepsilon}(t, x)\right|^{2} d \mu^{\varepsilon}(t)(x) d t \\
& -2 T \int_{0}^{T} \int_{\mathbb{R}^{d}} v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right) \cdot v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right) d \mu_{0}(x) d t \tag{2.25}
\end{align*}
$$

Thanks to [2, Lemma 8.1.10] we have

$$
\begin{equation*}
\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{n, \varepsilon}(t, x)\right|^{2} d \mu^{n, \varepsilon}(t)(x) d t \leq \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{n}(t, x)\right|^{2} d \mu^{n}(t)(x) d t \quad \forall \varepsilon>0 \tag{2.26}
\end{equation*}
$$

Moreover, thanks to the weak convergence of $\left(\mu^{n}(t), v^{n}(t) \mu^{n}(t)\right)$ to $(\mu(t), v(t) \mu(t))$, which is a consequence of the linear growth control of the gradient of $W$ in (1.5) and the fact that $\mu^{n, \varepsilon}(t)$ and $\mu^{\varepsilon}(t)$ are uniformly (in $n \in \mathbb{N}$ ) bounded away from zero on compact sets of $\mathbb{R}^{d}$, we deduce that

$$
\begin{equation*}
v^{n, \varepsilon}(t) \rightarrow v^{\varepsilon}(t) \text { in } L^{1}\left([0, T], C_{l o c}^{\infty}\left(\mathbb{R}^{d}\right)\right) . \tag{2.27}
\end{equation*}
$$

Indeed,

$$
\begin{aligned}
& D^{\alpha}\left[v^{n, \varepsilon}-v^{\varepsilon}\right]=\frac{D^{\alpha} \eta^{\varepsilon} *\left(v^{n} \mu^{n}\right)}{\mu^{n, \varepsilon}}-\frac{D^{\alpha} \eta^{\varepsilon} *(v \mu)}{\mu^{\varepsilon}} \\
& \quad=D^{\alpha} \eta^{\varepsilon} *\left(v^{n} \mu^{n}\right)\left(\frac{\mu^{\varepsilon}-\mu^{n, \varepsilon}}{\mu^{\varepsilon} \mu^{n, \varepsilon}}\right)+\frac{1}{\mu^{\varepsilon}} D^{\alpha} \eta^{\varepsilon} *\left(v \mu-v^{n} \mu^{n}\right)
\end{aligned}
$$

and $v^{n}$ is uniformly bounded in $L^{2}\left(\mu^{n}\right)$ with respect to $n$. Since the flows $X^{n, \varepsilon}(t)$ and $X^{\varepsilon}(t)$ are globally defined (see for instance [2, Proposition 8.1.8]), 2.27) easily implies that for any $t \in[0, T]$

$$
\begin{equation*}
X^{n, \varepsilon}(t) \rightarrow X^{\varepsilon}(t) \quad \text { locally uniformly on compact subsets of } \mathbb{R}^{d} . \tag{2.28}
\end{equation*}
$$

This fact, together with the fact that $v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t)\right)$ are uniformly bounded in $L^{2}\left(\mu_{0} \otimes d t\right)$ thanks to (2.26), implies that

$$
\begin{align*}
& \lim _{n \rightarrow \infty} \int_{\mathbb{R}^{d}} \int_{0}^{T} v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right) \cdot v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right) d t d \mu_{0}(x) \\
& \quad=\int_{\mathbb{R}^{d}} \int_{0}^{T}\left|v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right)\right|^{2} d t d \mu_{0}(x)=\int_{\mathbb{R}^{d}} \int_{0}^{T}\left|v^{\varepsilon}(t, x)\right|^{2} d \mu_{0}(x) d t . \tag{2.29}
\end{align*}
$$

To prove (2.29), split the integral on the left-hand side as follows

$$
\begin{aligned}
& \int_{\mathbb{R}^{d}} \int_{0}^{T} v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right) \cdot v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right) d t d \mu_{0}(x) \\
&=\int_{|x|>R} \int_{0}^{T} v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right) \cdot v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right) d t d \mu_{0}(x) \\
&+\int_{|x| \leq R} \int_{0}^{T} v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right) \cdot v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right) d t d \mu_{0}(x)=: I_{1}+I_{2} .
\end{aligned}
$$

Now, thanks to 2.26) and the fact that $v^{n}$ is uniformly bounded in $L^{2}\left(\mu^{n}\right)$ with respect to $n$, we can estimate

$$
\begin{aligned}
I_{1}^{2} & \leq \int_{\mathbb{R}^{d}} \int_{0}^{T}\left|v^{n, \varepsilon}\left(t, X^{n, \varepsilon}(t, x)\right)\right|^{2} d t d \mu_{0}(x) \int_{|x|>R} \int_{0}^{T}\left|v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right)\right|^{2} d t d \mu_{0}(x) \\
& \leq C \int_{|x|>R} \int_{0}^{T}\left|v^{\varepsilon}\left(t, X^{\varepsilon}(t, x)\right)\right|^{2} d t d \mu_{0}(x)
\end{aligned}
$$

for some constant $C$ independent on $n$. Hence, one can choose $R$ large enough such that $\left|I_{1}\right|<\eta$ for an arbitrarily small $\eta>0$. On the other hand, (2.27) and (2.28) imply

$$
I_{2} \rightarrow \int_{|x| \leq R} \int_{0}^{T}\left|v^{\varepsilon}(t, x)\right|^{2} d \mu_{0}(x) d t
$$

as $n \rightarrow+\infty$, and 2.29 follows by letting $R \rightarrow+\infty$.
Therefore, by combining (2.29) with 2.25) and 2.26 we obtain

$$
\begin{align*}
& \liminf _{n \rightarrow \infty} d_{W}^{2}\left(\mu^{\varepsilon}(T), \mu^{n, \varepsilon}(T)\right)+2 T \mathcal{W}\left[\mu^{n}(T)\right]  \tag{2.30}\\
& \leq \liminf _{n \rightarrow \infty} T\left[\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{n}(t, x)\right|^{2} d \mu^{n}(t)(x) d t-\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{\varepsilon}(t, x)\right|^{2} d \mu^{\varepsilon}(t)(x) d t+2 \mathcal{W}\left[\mu^{n}(T)\right]\right] .
\end{align*}
$$

We now claim that there exists a constant $C_{0}>0$, depending only on the convolution kernel $\eta$, such that for any $\mu \in \mathcal{P}\left(\mathbb{R}^{d}\right)$

$$
\begin{equation*}
d_{W}^{2}\left(\mu, \mu * \eta_{\varepsilon}\right) \leq C_{0} \varepsilon^{2} \tag{2.31}
\end{equation*}
$$

Indeed is suffices to consider the transport plan $\gamma^{\varepsilon} \in \Gamma\left(\mu, \mu * \eta_{\varepsilon}\right)$ defined has

$$
\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} f(x, y) d \gamma^{\varepsilon}(x, y):=\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} f(x, y) \eta_{\varepsilon}(y-x) d y d \mu(x) \quad \forall f \in C_{b}\left(\mathbb{R}^{d} \times \mathbb{R}^{d}\right)
$$

to get that

$$
\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|y-x|^{2} d \gamma^{\varepsilon}(x, y)=\int_{\mathbb{R}^{d}}|z|^{2} \eta_{\varepsilon}(z) d z=\varepsilon^{2} \int_{\mathbb{R}^{d}}|z|^{2} \eta(z) d z
$$

which proves 2.31. We finally observe that

$$
\begin{equation*}
\liminf _{\varepsilon \rightarrow 0} \int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{\varepsilon}(t, x)\right|^{2} d \mu^{\varepsilon}(t)(x) d t \geq \int_{0}^{T} \int_{\mathbb{R}^{d}}|v(t, x)|^{2} d \mu(t)(x) d t \tag{2.32}
\end{equation*}
$$

(actually using (2.26) one could prove that the above liminf is a limit, and equality holds). Combining (2.30) with (2.31) we obtain

$$
\begin{aligned}
& \liminf _{n \rightarrow \infty} d_{W}^{2}\left(\mu(T), \mu^{n}(T)\right)+2 T \mathcal{W}\left[\mu^{n}(T)\right] \leq \liminf _{n \rightarrow \infty} T\left[\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{n}(t, x)\right|^{2} d \mu^{n}(t) d t\right. \\
& \left.-\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{\varepsilon}(t, x)\right|^{2} d \mu^{\varepsilon}(t)(x) d t+2 \mathcal{W}\left[\mu^{n}(T)\right]\right]+O(\varepsilon)
\end{aligned}
$$

so, that letting $\varepsilon \rightarrow 0$, thanks to 2.32 we finally get

$$
\begin{align*}
& \liminf _{n \rightarrow \infty} d_{W}^{2}\left(\mu(T), \mu^{n}(T)\right)+2 T \mathcal{W}\left[\mu^{n}(T)\right]  \tag{2.33}\\
& \leq \liminf _{n \rightarrow \infty} T\left[2 \mathcal{W}\left[\mu^{n}(T)\right]+\int_{0}^{T} \int_{\mathbb{R}^{d}}\left|v^{n}(t, x)\right|^{2} d \mu^{n}(t)(x) d t-\int_{0}^{T} \int_{\mathbb{R}^{d}}|v(t, x)|^{2} d \mu(t)(x) d t\right]
\end{align*}
$$

Moreover, in view of Lemma 2.3 we deduce

$$
\begin{equation*}
\liminf _{n \rightarrow \infty} d_{W}^{2}\left(\mu(T), \mu^{n}(T)\right)+2 T \mathcal{W}\left[\mu^{n}(T)\right] \geq 2 T \mathcal{W}[\mu(T)] \tag{2.34}
\end{equation*}
$$

for $T$ small enough. Combining (2.34) with (2.33), we obtain that 2.24 holds provided $T$ is sufficiently small (but independent on the initial datum $\mu_{0}$ ), and this allows to prove the existence of a curve of maximal slope on a small time interval $[0, T]$. Iterating now the construction via minimizing movements on $[T, 2 T],[2 T, 3 T]$ and so on, and adding the energy inequalities (2.23) on each time interval, we get the desired result.

Remark 2.9 ( $\lambda$-Generalised convexity). Let us emphasize that, since $\lambda \leq 0$, our functional is not only $\lambda$-convex with respect to Wasserstein geodesics, but also with respect to generalized geodesics, see [2, Definition 9.2.4]. It follows directly from [2, Proposition 9.3.5], decomposing $\mathcal{W}=\tilde{\mathcal{W}}+\mathcal{Q}$ as in Proposition 2.2. Exploiting this fact, the existence of solutions for the discrete scheme and the convergence of the scheme follow from the theory developed in [2]. On the other hand, we believe that our strategy to show the convergence of the discrete scheme is of interest in itself, being much more flexible and since it may be applied to more general situations where $\lambda$-convexity fails. This is why we chose to prove existence of curves of maximal slope in this way.
Remark 2.10 (The ODE system). Let $x_{i}(t), i=1, \ldots, N$, be $C^{1}$-solutions of the ODE system (for the time intervals that such exist)

$$
\begin{equation*}
\dot{x}_{i}=-\sum_{j \neq i} m_{j} \nabla W\left(x_{i}-x_{j}\right), \quad i=1, \ldots, N \tag{2.35}
\end{equation*}
$$

with $m_{i}>0$ and $\sum_{i} m_{i}=1$. Then it is straightforward to check that $\mu(t):=\sum_{i=1}^{N} m_{i} \delta_{x_{i}(t)}$ is a solution of 1.2 in the sense of Definition 1.2. Conversely, if $\mu(t)$ of the form above solves the PDE and $x_{i}(t)$ are $C^{1}$ curves for $i=1, \ldots, N$, then $x_{i}(t)$ solve the ODE system.

The question is what happens if the particles collide: can the solutions of the PDE still be represented by an ODE? This question has a positive answer, see for instance [2, Theorems 8.2 .1 and 11.2.3 and Equation (11.2.22)] For completeness, we give a sketch a proof in our particular case.

We consider absolutely continuous solutions of

$$
\begin{align*}
\dot{x}_{i}= & -\sum_{j \in C(i)} m_{j} \nabla W\left(x_{i}-x_{j}\right), \quad i=1, \ldots, N,  \tag{2.36}\\
& \text { with } C(i):=\left\{j \in\{1, \ldots, N\}: j \neq i, x_{j}(t) \neq x_{i}(t)\right\} . \tag{2.37}
\end{align*}
$$

More precisely we consider the solutions of the associated integral equation. If $C(i)$ is empty, then all particles have collapsed to a single particle. We then define the right hand side to be zero, that is we define the sum over empty set of indexes to be zero. The right hand side of this ODE system is bounded and Lipschitz-continuous in space on short time intervals. Thus the ODE system has a unique Lipschitz-continuous solutions on short time intervals. The estimate (1.5) then implies that the solutions are global-in-time. Note that the solutions are Lipschitz (in time) on bounded time intervals. Also note that collisions of particles can occur, but that we do not relabel the particles when they collide. Since the number of particles is $N$ there exist $0 \leq k \leq N-1$ times $0=: T_{0}<T_{1}<T_{2}<\cdots<$ $T_{k}<\infty=: T_{k+1}$ at which collisions occur. Note that $\mu(t)=\sum_{i=1}^{N} m_{i} \delta_{x_{i}(t)}$ is a solution of the PDE on the time intervals $\left[T_{l}, T_{l+1}\right)$. Furthermore, the Lipschitz continuity of $x_{i}$ implies that $\mu$ is an absolutely continuous curve in $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$. It is then straightforward to verify that $\mu$ is a weak solution according to Definition 1.2. Since the solution to the PDE is unique the converse claim also holds.

Let us mention that while above we did not relabel the particles after collisions, at times it is useful to do so. That is on time intervals $\left[T_{l}, T_{l+1}\right)$ the ODE system (2.36) is equivalent to

$$
\begin{equation*}
\frac{d \tilde{x}_{i}}{d t}=-\sum_{j \neq i} \tilde{m}_{j} \nabla W\left(\tilde{x}_{l}-\tilde{x}_{j}\right), \quad i=1, \ldots, N_{l}, \tag{2.38}
\end{equation*}
$$

where $N_{l}$ is the number of distinct particles on the time interval $\left[T_{l}, T_{l+1}\right)$, and $\tilde{x}_{j}, \tilde{m}_{j}$ are their locations and masses, respectively.

Remark 2.11 (Existence of minimizing movements when $\nabla W$ is unbounded). We remark here that the construction of the JKO scheme, up to the proof of the Proposition 2.6, can be performed even in case $\nabla W$ has a singular behavior such as $W(x)=|x|^{\alpha}$ for $\alpha \in(0,1)$ (although in this case we are not able to characterize the subdifferential). Therefore, one can easily prove that there exist at least one minimizing movement for such a kind of functional. Note that the case $\alpha=0$ is critical, since one recovers the logarithmic kernel $W(x)=\log |x|$ as $\alpha \rightarrow 0$, for which it is an open problem how to define unique global-in-time weak measure solutions for all initial masses, see [39].
2.3. Gradient Flow Solutions. In this subsection, we will show the existence of global-in-time weak measure solutions for (1.2) for potentials satisfying (NL0)-(NL3) as a consequence of the general abstract theorems proved in [2]. In fact, using that the potential is $\lambda$-convex by (NL1), Lemma 2.3 and the existence of minimizers in Proposition 2.5 , we meet the hypotheses of [2, Theorem 11.1.3]. This abstract theorem shows that curves of maximal slope are equivalent under certain hypotheses to gradient flows. As a direct consequence of the existence of curves of maximal slope in Theorem [2.8, we can assert the following result. Let us remark that Proposition 2.2 has played a key role in the argument leading to Theorem 2.8 in two ways: allowing to show the lower semicontinuity of the slope to get the energy inequalities, and in order to identify the limiting velocity field.

Theorem 2.12 (Existence of the Gradient Flow). Let $W$ satisfy the assumptions (NL0)(NL3). Given any $\mu_{0} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, then there exists a gradient flow solution, i.e. a curve $\mu \in A C_{\text {loc }}\left([0, \infty) ; \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)\right)$ satisfying

$$
\begin{aligned}
& \frac{\partial \mu(t)}{\partial t}+\operatorname{div}(v(t) \mu(t))=0 \text { in } \mathcal{D}^{\prime}\left([0, \infty) \times \mathbb{R}^{d}\right), \\
& v(t)=-\partial^{0} \mathcal{W}[\mu(t)]=-\partial^{0} W * \mu(t), \\
& \|v(t)\|_{L^{2}(\mu(t))}=\left|\mu^{\prime}\right|(t) \quad \text { a.e. } t>0,
\end{aligned}
$$

with $\mu(0)=\mu_{0}$. Moreover, the energy identity

$$
\begin{equation*}
\int_{a}^{b} \int_{\mathbb{R}^{d}}|v(t, x)|^{2} d \mu(t)(x) d t+\mathcal{W}[\mu(b)]=\mathcal{W}[\mu(a)] \tag{2.39}
\end{equation*}
$$

holds for all $0 \leq a \leq b<\infty$.
To summarize, the notions of curves of maximal slope and gradient flow solutions are equivalent and they imply the notion of weak measure solutions in the sense of Definition 1.2. Furthermore, absolute continuity of the curve of weak measure solutions and the characterization of the subdifferential imply that weak measure solutions are gradient flow solutions, see [2, Sections 8.3 and 8.4]. Thus, the three notions of solution are equivalent.

The $\lambda$-geodesic convexity of the functional plays a crucial role for the uniqueness of gradient flow solutions. Since the interaction potential is $\lambda$-geodesically convex for $\lambda \leq 0$, the following result follows readily from [2, Theorem 11.1.4].

Theorem 2.13 ( $d_{W}$-Contraction). Let $W$ satisfy the assumptions (NL0)-(NL3). Given two gradient flow solutions $\mu^{1}(t)$ and $\mu^{2}(t)$ in the sense of the theorem above, we have

$$
d_{W}\left(\mu^{1}(t), \mu^{2}(t)\right) \leq e^{-\lambda t} d_{W}\left(\mu_{0}^{1}, \mu_{0}^{2}\right)
$$

for all $t \geq 0$. In particular, the gradient flow solution starting from any given $\mu_{0} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ is unique. Moreover, this solution is characterized by a system of evolution variational inequalities:

$$
\frac{1}{2} \frac{d}{d t} d_{W}^{2}(\mu(t), \sigma)+\frac{\lambda}{2} d_{W}^{2}(\mu(t), \sigma) \leq \mathcal{W}[\sigma]-\mathcal{W}[\mu(t)] \quad \text { a.e. } t>0
$$

for all $\sigma \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$.
With this we have completed the existence, uniqueness and stability for gradient flow solutions for potentials satisfying (NL0)-(NL3).
Remark 2.14 (Case $\lambda>0$ ). All the theory and results obtained in this section can be applied $\lambda$-convex potentials with $\lambda>0$, i.e. allowing for $\lambda>0$ in (NL1), provided we restrict ourselves to measures with equal initial center of mass. This relies on the fact that, when $\lambda>0$, the interaction potential is $\lambda$-geodesically convex on the space of probability measures with fixed center of mass, a set which is preserved by the evolution equation, see [32, 18, 45, 2].

Remark 2.15 (Weak- $L^{p}$ solutions). Since weak measure solutions are equivalent to gradient flow solutions, our main uniqueness-stability Theorem 2.13 concludes the uniqueness of weak measure solutions to 1.2. Therefore, we can easily check that the previous constructed solutions in the series of papers [27, 7, 5, 20] for a family of more restrictive potentials $W$ than the ones presented in this work, are indeed weak measure solutions up to their maximal time of existence. Let us make this statement more precise. It was shown in [8, Theorem 18] that weak- $L^{p}$ solutions with initial data in $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ remain in $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ as long as they exist. These weak- $L^{p}$ solutions satisfy equation $(1.2)$ in the distributional sense, and they lead to curves in the space $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right) \cap L^{p}\left(\mathbb{R}^{d}\right)$ which are continuous with respect to the strong topology in $L^{p}$, for suitable $p$, up to a maximal time of existence $T^{*}$. Hence, for potentials satisfying (NL0)-(NL3) and assuming the same additional conditions of growth at infinity in $\nabla W$ as in [27, 7, 5, 20, 8, one can show that the velocity field $\nabla W * \rho$ belongs to $L^{1}\left((0, T) ; L^{2}(\rho(t))\right)$ for all $0<T<T^{*}$, see for instance the proofs in [7, Section 3], [20, Section 2.2] or [8, Section 3]. Therefore, weak- $L^{p}$ solutions with initial data in $\mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ are weak measure solutions up to their maximal time of existence, and thus, they do coincide up to that time with the weak measure solution constructed in Theorems 2.12, 2.13. Let us also remark that in the works [27, 7, 5, 20, 8] the energy identity 2.39 was used as a tool for proving blow-up of the $L^{p}$-norm in finite time. To be more precise, for weak- $L^{p}$ solutions one can prove an energy inequality like (2.39), where the equality sign is replaced by a less or equal sign, but the exact energy identity was missing. Hence our result in Theorem 2.12) also implies the energy identity for weak- $L^{p}$ solutions.

Remark 2.16 (Comparison with classical PDE arguments). Let us observe that a more classical strategy to construct weak measure solutions is based on approximating the initial datum by atomic measures, i.e. showing the convergence of the particle method.

More precisely, one exploits the existence of solutions for the discrete particle system in Remark 2.10 and the stability result in Theorem 2.13 to show convergence of the discrete approximating solutions to a limit curve. In this way, everything reduces to prove that the limit curve is a weak measure solution to (1.2), which is however not completely trivial, and would require some work. Moreover, it is not clear how to show directly that the weak measure solutions constructed in this way are both gradient flow solutions and curves of maximal slope, and that they satisfy the energy identity. This kind of strategy is well-known in kinetic theory, see for instance [22, 35, 40].

## 3. Particle measures in the JKO scheme

In this section, we show that the JKO scheme preserves the atomic part of the initial datum for all times, provided the time step is small enough. In particular, if we start with $N$-particles measure, it remains so, possibly with less particles, for all times. As a consequence, this immediately identifies the limit solution of the JKO scheme in this particular case. Moreover, it shows the well-posedness of a particle numerical scheme for solving numerically (1.2). More comments on this will be given below. Throughout this section, we allow $\lambda$ to be positive, in which case our statements are stronger.

Given $\bar{\mu} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ let, for $\tau>0$,

$$
\begin{equation*}
F_{\tau}[\mu]:=\mathcal{W}[\mu]+\frac{1}{2 \tau} d_{W}^{2}(\bar{\mu}, \mu) . \tag{3.1}
\end{equation*}
$$

Let us denote $u^{-}:=\max \{0,-u\}$. We show that during a sufficiently small step of the JKO scheme, the mass contained in a particle remains concentrated, regardless of what the rest of the state looks like.
Definition 3.1 (Atomization). Given $\mu \in \mathcal{P}_{1}\left(\mathbb{R}^{d}\right)$, $\mu^{*}$ stands for the point mass located at the center of mass of $\mu$, i.e:

$$
\mu^{*}:=\delta_{z} \quad \text { where } \quad z=\int_{\mathbb{R}^{d}} x d \mu(x)
$$

We say that $\mu^{*}$ is the atomization of $\mu$.
Theorem 3.2. Assume $W$ satisfies (NL0)-(NL1). Let $\bar{\mu}=m \delta_{a}+\mu_{r} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ with $0<m \leq 1$ and $\delta_{a} \perp \mu_{r}$. Given any $\tau>0$ such that $\tau \lambda^{-}<1$, let

$$
\begin{equation*}
\mu \in \operatorname{argmin}_{\nu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)} F_{\tau}[\nu], \tag{3.2}
\end{equation*}
$$

and denote by $\pi$ an optimal transportation plan between $\bar{\mu}$ and $\mu$. Let us define

$$
\begin{equation*}
\mu_{1}(E):=\frac{1}{m} \pi(\{a\} \times E), \tag{3.3}
\end{equation*}
$$

for any Borel set E. Then $\mu_{1}=\mu_{1}^{*}$. In particular,

$$
\mu=m \delta_{z}+\mu_{s}
$$

for some $z \in \mathbb{R}^{d}$ and $\mu_{s}$ a nonnegative measure.
To rephrase the statement of the theorem in plain language: Any optimal transportation plan from the present state $\bar{\mu}$ to a minimizer of the JKO step $\mu$ carries all the mass from the particle at $a$ to another point $z$. Thus the updated state has a particle at $z$, whose mass is at least the same as the one of the particle which was in $a$.

In case the measure $\bar{\mu}$ is a sum of $N$ particles, by applying Theorem 3.2 to each particle, we easily conclude that $\mu$ is still a sum of particles, possibly less than $N$.

Corollary 3.3 (Particles remain particles). Assume $W$ satisfies (NL0)-(NL1). Let $\bar{\mu}=\sum_{i=1}^{N} m_{i} \delta_{x_{i}}$, where $x_{1}, \ldots, x_{N}$ are distinct points in $\mathbb{R}^{d}, \sum_{i=1}^{N} m_{i}=1$ and $m_{i} \in(0,1)$. Given any $\tau>0$ such that $\tau \lambda^{-}<1$, let

$$
\mu \in \operatorname{argmin}_{\nu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)} F_{\tau}[\nu] .
$$

Then there exist $y_{1}, \ldots, y_{N} \in \mathbb{R}^{d}$, not necessarily distinct, such that $\mu=\sum_{i=1}^{N} m_{i} \delta_{y_{i}}$.
To prove Theorem 3.2, given a minimizer $\mu$ of the JKO step, we show that

$$
\begin{equation*}
\mu_{\text {new }}:=m \mu_{1}^{*}+\left(\mu-m \mu_{1}\right) \tag{3.4}
\end{equation*}
$$

decreases the JKO functional:

$$
\begin{equation*}
F_{\tau}\left[\mu_{\text {new }}\right]<F_{\tau}[\mu], \quad \text { if } \mu_{1} \neq \mu_{1}^{*} . \tag{3.5}
\end{equation*}
$$

This implies $\mu=\mu_{\text {new }}$. To prove (3.5) we examine what effect does atomizing $\mu_{1}$ have on the two terms in the JKO functional: the energy and the Wasserstein distance. We show that, as expected, atomizing decreases the Wasserstein distance. On the other hand atomizing can increase the interaction energy, but only if $\lambda$ is negative. The key observation is that in each of the terms the change is controlled by the variance of $\mu_{1}$. Taking the time step small enough allows us to conclude.
Lemma 3.4. Assume $\mathcal{W}$ satisfies (NL0)-(NL1). Let $\nu_{1}, \nu_{2} \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$ and $\nu=m_{1} \nu_{1}+$ $m_{2} \nu_{2}$ with $0 \leq m_{1} \leq 1$ and $m_{2}=1-m_{1}$. Let $\nu_{\text {new }}:=m_{1} \nu_{1}^{*}+m_{2} \nu_{2}$. Then

$$
\mathcal{W}[\nu]-\mathcal{W}\left[\nu_{\text {new }}\right] \geq \frac{\lambda}{2} m_{1} \operatorname{Var}\left(\nu_{1}\right)
$$

Proof. Introduce the symmetric bilinear form

$$
B\left(\eta_{1}, \eta_{2}\right)=\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} W(x-y) d \eta_{1}(x) d \eta_{2}(y)
$$

so that

$$
\begin{aligned}
\mathcal{W}[\nu]-\mathcal{W}\left[\nu_{\text {new }}\right]= & B\left(m_{1} \nu_{1}+m_{2} \nu_{2}, m_{1} \nu_{1}+m_{2} \nu_{2}\right)-B\left(m_{1} \nu_{1}^{*}+m_{2} \nu_{2}, m_{1} \nu_{1}^{*}+m_{2} \nu_{2}\right) \\
= & 2 m_{1} m_{2} B\left(\nu_{1}, \nu_{2}\right)+m_{1}^{2} B\left(\nu_{1}, \nu_{1}\right)-2 m_{1} m_{2} B\left(\nu_{1}^{*}, \nu_{2}\right)-m_{1}^{2} B\left(\nu_{1}^{*}, \nu_{1}^{*}\right) \\
= & m_{1} m_{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left[W(x-y)-W\left(z_{1}-y\right)\right] d \nu_{1}(x) d \nu_{2}(y) \\
& +\frac{m_{1}^{2}}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left[W(x-y)-W\left(z_{1}-z_{1}\right)\right] d \nu_{1}(x) d \nu_{1}(y),
\end{aligned}
$$

where $z_{1}$ is the center of mass of $\nu_{1}$. By the $\lambda$-convexity assumption (NL1), for each $p \in \mathbb{R}^{d}$ and $r_{p} \in \partial W(p) \neq \emptyset$ the inequality

$$
W(q) \geq W(p)+r_{p} \cdot(q-p)+\frac{\lambda}{2}|q-p|^{2}
$$

holds for all $q \in \mathbb{R}^{d}$. Semiconvexity of $W$ also implies that for $y \in \mathbb{R}^{d}$ there exists $r_{z_{1}-y} \in \partial W\left(z_{1}-y\right)$. Using this along with the fact that $0 \in \partial W(0)$ we obtain

$$
\begin{aligned}
W(x-y)-W\left(z_{1}-y\right) & \geq r_{z_{1}-y} \cdot\left(x-z_{1}\right)+\frac{\lambda}{2}\left|x-z_{1}\right|^{2}, \\
W(x-y)-W(0) & \geq \frac{\lambda}{2}|x-y|^{2},
\end{aligned}
$$

for all $x, y \in \mathbb{R}^{d}$. Since $\int_{\mathbb{R}^{d}}\left(x-z_{1}\right) d \nu_{1}(x)=0$ we get

$$
\begin{aligned}
\mathcal{W}[\nu]-\mathcal{W}\left[\nu_{n e w}\right] & \geq m_{1} m_{2} \frac{\lambda}{2} \operatorname{Var}\left(\nu_{1}\right)+\frac{m_{1}^{2}}{2} \frac{\lambda}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left|\left(x-z_{1}\right)-\left(y-z_{1}\right)\right|^{2} d \nu_{1}(x) d \nu_{1}(y) \\
& =m_{1} m_{2} \frac{\lambda}{2} \operatorname{Var}\left(\nu_{1}\right)+m_{1}^{2} \frac{\lambda}{2} \operatorname{Var}\left(\nu_{1}\right) \\
& =\frac{m_{1} \lambda}{2} \operatorname{Var}\left(\nu_{1}\right),
\end{aligned}
$$

which concludes the proof.
Lemma 3.5. Let $\bar{\mu}$ given as in Theorem 3.2. Given any $\nu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)$, let $\pi$ be an optimal transportation plan between $\bar{\mu}$ and $\nu$ and let $\nu_{1}$ be defined by (3.3). Let $\nu_{\text {new }}:=m \nu_{1}^{*}+$ ( $\nu-m \nu_{1}$ ). Then

$$
d_{W}^{2}(\bar{\mu}, \nu)-d_{W}^{2}\left(\bar{\mu}, \nu_{\text {new }}\right) \geq m \operatorname{Var}\left(\nu_{1}\right) .
$$

Proof. Let $z$ be the center of mass of $\nu_{1}$ (so that $\nu_{1}^{*}=\delta_{z}$ ). Denote by $\pi_{1}$ the restriction of $\pi$ to $\{a\} \times \mathbb{R}^{d}$, and $\pi_{2}:=\pi-\pi_{1}$. Let $\pi_{\text {new }}:=m \delta_{(a, z)}+\pi_{2}$. Note that $\pi_{\text {new }}$ is a transportation plan between $\bar{\mu}$ and $\nu_{\text {new }}$. Therefore,

$$
\begin{aligned}
d_{W}^{2}(\bar{\mu}, \nu) & =\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d\left(\pi_{1}+\pi_{2}\right) \\
& =m \int_{\mathbb{R}^{d}}|y-a|^{2} d \nu_{1}(y)+\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \pi_{2} \\
& =m \int_{\mathbb{R}^{d}}\left[|y-z|^{2}+2(y-z) \cdot(z-a)+|z-a|^{2}\right] d \nu_{1}(y)+\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \pi_{2} \\
& =m \int_{\mathbb{R}^{d}}|y-z|^{2} d \nu_{1}(y)+\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d\left(m \delta_{(a, z)}+\pi_{2}\right) \\
& \geq m \operatorname{Var}\left(\nu_{1}\right)+d_{W}^{2}\left(\bar{\mu}, \nu_{\text {new }}\right),
\end{aligned}
$$

as desired.

Proof of Theorem 3.2. Assume that the claim does not hold, and consider $\mu_{n e w}$ defined by (3.4). Then, Lemmas 3.4 and 3.5 imply that

$$
\begin{aligned}
F_{\tau}[\mu]-F_{\tau}\left[\mu_{\text {new }}\right] & =\mathcal{W}[\mu]-\mathcal{W}\left[\mu_{\text {new }}\right]+\frac{1}{2 \tau}\left(d_{W}^{2}(\bar{\mu}, \mu)-d_{W}^{2}\left(\bar{\mu}, \mu_{\text {new }}\right)\right) \\
& \geq \frac{m}{2}\left(\lambda+\frac{1}{\tau}\right) \operatorname{Var}\left(\mu_{1}\right)>0
\end{aligned}
$$

contradicting the minimality of $\mu$.
Remark 3.6. The above property of minimizers in each step of the JKO scheme carries over to the limiting solution, thanks to the convergence of the JKO scheme towards curves of maximal slope and gradient flow solutions of Section 2, see Theorem 2.8. Therefore, solutions corresponding to initial data with a finite number of particles plus an orthogonal part remain so for all times, with a possibly decreasing number of particles in time, see also Proposition 4.5. Moreover, combining Corollary 3.3 with the convergence of the JKO scheme in Theorem 2.8 allows to recover Remark 2.10, i.e. the correspondence between
solutions of the ODE system (2.35) and gradient flow solutions of (1.2) with atomic initial measures.

## 4. Finite-time Total Collapse and Multiple Collapse by Stability

In this section, we focus on studying the large-time asymptotics of attractive nonOsgood potential, i.e. potentials satisfying assumptions (NL0)-(NL3) and (NL-FTBU).

We start by discussing the monotonicity assumption in (NL-FTBU). If the potential satisfies $w^{\prime}\left(0^{+}\right)>0$, i.e. it has a Lipschitz singularity at the origin, nearby particles move towards each other with a relative speed of about $2 w^{\prime}\left(0^{+}\right)$, and thus we expect the concentration in finite time. In case (NL-FTBUb), thanks to the non-Osgood condition, we do expect again concentration in finite time. In fact, in the case of a single particle subject to the potential $W(x)$, one easily checks that the particle reaches the origin in finite time. As we show in Theorem 4.3, compactly supported measures do collapse completely in finite time.
Remark 4.1 (No Oscillation Condition on the potential). Let us point out that the condition of $w^{\prime \prime}(r)$ being monotone decreasing in a right interval of 0 is not too restrictive. Actually, plain monotonicity of $w^{\prime \prime}$ in a right interval of 0 together with the non-Osgood condition, the nonnegativity of $w^{\prime}$, and the fact that $w^{\prime}\left(0^{+}\right)=0$, imply that $w^{\prime \prime}$ is monotone decreasing on a right interval of 0 (the only possibility to violate this condition would be that the second derivative oscillate wildly at 0 ). To see this, note that the monotonicity of $w^{\prime \prime}$ implies that $w^{\prime}$ is either convex or concave in an interval $\left(0, \varepsilon_{0}\right)$. But $w^{\prime}$ cannot be convex, as otherwise its graph would be below the graph of the linear function $r \mapsto\left(w^{\prime}\left(\epsilon_{0}\right) / \varepsilon_{0}\right) r$, which is not compatible with the integrability of $1 / w^{\prime}$ at 0 .

Let us start by showing the finite total collapse in the case of finite number of particles.
Proposition 4.2 (Finite Time Particles Collapse). Assume $W$ satisfies (NL0)-(NL3) and (NL-FTBU). Given the initial datum $\mu_{0}=\sum_{i=1}^{N} m_{i} \delta_{x_{i}^{0}}$ with center of mass

$$
x_{c}:=\sum_{i=1}^{N} m_{i} x_{i}^{0},
$$

let $\mu(t)$ denote the unique gradient flow solution with $\mu(0)=\mu_{0}$. Set $R_{0}$ to be the largest distance from the initial particles to the center of mass:

$$
R_{0}:=\max _{i=1, \ldots, N}\left|x_{i}^{0}-x_{c}\right| .
$$

Then there exists $T^{*}>0$, depending only on $R_{0}$ but not on the number of particles, such that $\mu(t)=\delta_{x_{c}}$ for $t \geq T^{*}$.

Proof. Let us define the curves $t \mapsto x_{i}(t), i=1, \ldots, N$ as the solution of the ODE system discussed in Remark 2.10.

$$
\dot{x}_{i}=-\overline{\sum_{j \in C(i)}} m_{j} \nabla W\left(x_{i}-x_{j}\right), \quad i=1, \ldots, N
$$

where $C(i)=\left\{j \in\{1, \ldots, N\}: j \neq i, x_{j}(t) \neq x_{i}(t)\right\}$. Recall also that we define the sum over empty set of indexes to be zero. Then, $\mu(t)=\sum_{i=1}^{N} m_{i} \delta_{x_{i}(t)}$, where possibly $x_{i}(t)=x_{j}(t)$ for some $i \neq j$.

Our claim is equivalent to saying that there exists $T^{*}>0$ such that $x_{i}(t)=x_{c}$ for all $t \geq T^{*}$ and $i=1, \ldots, N$. Note that, due to assumption (NL0) the center of mass of the particles is preserved in time for the solutions of the ODE system. Since the system is translation invariant, we can assume that $x_{c}=0$ without loss of generality.

We define the Lipschitz function $R(t)$ to be the distance of the furthest particle from the center of mass:

$$
R(t):=\max _{i=1, \ldots, N}\left|x_{i}(t)\right|
$$

Recall that $x_{i}$ are Lipschitz in time, and are $C^{1}$ for all but finitely many collision times $0=: T_{0}<T_{1}<T_{2}<\cdots<T_{l}<T_{l+1}:=+\infty$.

We first compute a differential inequality for the function $R(t)$. Due to assumption (NL-FTBU), for all $t \geq 0$ and all $i=1, \ldots, N$

$$
\begin{align*}
\frac{d^{+} x_{i}}{d t}:=\lim _{h \rightarrow 0^{+}} \frac{x_{i}(t+h)-x_{i}(t)}{h} & =-\sum_{j \in C(i)} m_{j} \nabla W\left(x_{i}-x_{j}\right) \\
& =-\sum_{j \in C(i)} m_{j} \frac{x_{i}-x_{j}}{\left|x_{i}-x_{j}\right|} w^{\prime}\left(\left|x_{i}-x_{j}\right|\right) \tag{4.1}
\end{align*}
$$

While it would have been sufficient to deal with the derivative $\frac{d x_{i}}{d t}$ which exists a.e., we wanted to highlight the fact that the right-hand derivative exists for all times, including the collision times. Using (4.1), we have

$$
\begin{align*}
\frac{d^{+}}{d t} R^{2}(t) & =\max _{\left\{i: x_{i}(t)=R(t)\right\}} \frac{d^{+}}{d t}\left|x_{i}\right|^{2} \\
& =\max _{\left\{i: x_{i}(t)=R(t)\right\}}-2 \sum_{j \in C(i)} m_{j} \frac{\left(x_{i}-x_{j}\right) \cdot x_{i}}{\left|x_{i}-x_{j}\right|} w^{\prime}\left(\left|x_{i}-x_{j}\right|\right) . \tag{4.2}
\end{align*}
$$

Note that since $R$ is Lipschitz, $\frac{d}{d t} R^{2}$ exists a.e. and is equal to $\frac{d^{+}}{d t} R^{2}$. Observe that for any $i$ as above, $\left(x_{i}-x_{j}\right) \cdot x_{i} \geq 0$ since all other particles are inside $\bar{B}(0, R(t))$. Using again assumption (NL-FTBU), we have $w^{\prime}\left(\left|x_{i}-x_{j}\right|\right)>0$ and thus $\frac{d^{+}}{d t} R(t) \leq 0$, from which we deduce that $R(t) \leq R_{0}$ for all $t \geq 0$. Let us distinguish two cases:

Case (a): $w^{\prime}\left(0^{+}\right)>0$. Let us define

$$
D:=\min _{r \in\left[0,2 R_{0}\right]} w^{\prime}(r)>0
$$

By coming back to 4.2), we deduce that for all $t \geq 0$

$$
\begin{aligned}
\frac{d^{+}}{d t} R(t)^{2} & \leq \max _{\left\{i: x_{i}(t)=R(t)\right\}}-2 D \sum_{j \in C(i)} m_{j} \frac{\left(x_{i}-x_{j}\right) \cdot x_{i}}{\left|x_{i}-x_{j}\right|} \\
& \leq \max _{\left\{i: x_{i}(t)=R(t)\right\}}-\frac{D}{R(t)} \sum_{j \neq i} m_{j}\left(x_{i}-x_{j}\right) \cdot x_{i}
\end{aligned}
$$

since $\left|x_{i}-x_{j}\right| \leq 2 R(t)$ for $j \neq i$ and $\left(x_{i}-x_{j}\right) \cdot x_{i} \geq 0$. It is easy to check, using the unit total mass of the measure and that the center of mass is zero, that for any $i$ as above

$$
\sum_{j \neq i} m_{j}\left(x_{i}-x_{j}\right) \cdot x_{i}=R(t)^{2}
$$

Hence $\frac{d^{+}}{d t} R(t) \leq-D$. We conclude that the claim of the proposition holds with $T^{*}=$ $R_{0} / D$.

Case (b): $w^{\prime}\left(0^{+}\right)=0$ together with the other assumptions in (NL-FTBUb). The function $w^{\prime}$ is then concave on $\left(0, \varepsilon_{0}\right)$. Together with the fact that $w^{\prime}\left(0^{+}\right)=0$ this implies that $w^{\prime}(r) / r$ is decreasing in $\left(0, \varepsilon_{0}\right)$. Without of loss of generality, we can assume that $\varepsilon_{0}<\varepsilon_{1}$, with $\varepsilon_{1}$ as in (NL-FTBUb).

Let us first show that $R(t)$ must reach values less than $\varepsilon_{0} / 2$ in finite time. Since $R(t)$ is decreasing, it suffices to consider the case $R_{0}>\varepsilon_{0} / 2$. Fix any time such that $R(t) \geq \varepsilon_{0} / 2$. Coming back to (4.2), we distinguish for any $i$ such that $R(t)=\left|x_{i}(t)\right|$, two sets of particles: $I$, where $\left|x_{i}-x_{j}\right| \leq \varepsilon_{0} / 2$, and $I I$, where $\left|x_{i}-x_{j}\right|>\varepsilon_{0} / 2$. For indexes in the set $I$ we can use that $w^{\prime}(r) / r$ is decreasing, while to handle the set $I I$ we define

$$
D:=\min _{r \in\left[\varepsilon_{0} / 2,2 R_{0}\right]} w^{\prime}(r)>0 .
$$

Using again $\left|x_{i}-x_{j}\right| \leq 2 R(t)$ for $j \neq i$ and $\left(x_{i}-x_{j}\right) \cdot x_{i} \geq 0$, we can write

$$
\frac{d^{+}}{d t} R^{2}(t) \leq \max _{\left\{i: x_{i}(t)=R(t)\right\}}\left\{-2 \frac{w^{\prime}\left(\varepsilon_{0}\right)}{\varepsilon_{0}} \sum_{(I)} m_{j}\left(x_{i}-x_{j}\right) \cdot x_{i}-\frac{D}{R(t)} \sum_{(I I)} m_{j}\left(x_{i}-x_{j}\right) \cdot x_{i}\right\} .
$$

Thanks to $R(t) \geq \varepsilon_{0} / 2$ and $w^{\prime}\left(\varepsilon_{0}\right) \geq D$, we can finally conclude that

$$
\frac{d^{+}}{d t} R^{2}(t) \leq \max _{\left\{i: x_{i}(t)=R(t)\right\}}-\frac{D}{R(t)} \sum_{j \neq i} m_{j}\left(x_{i}-x_{j}\right) \cdot x_{i}=-D R(t)
$$

for all times such that $R(t) \geq \varepsilon_{0} / 2$. Thus, there exists a time $\tau$ such that $R(t) \leq \varepsilon_{0} / 2$ for $t \geq \tau$.

We now refine the above argument for $t \geq \tau$ using that the distance between any two particles satisfies $\left|x_{i}-x_{j}\right| \leq 2 R(t) \leq \varepsilon_{0}$. Since $w^{\prime}(r) / r$ is decreasing on $\left(0, \varepsilon_{0}\right)$ we deduce that for times $t \geq \tau$

$$
\frac{d^{+}}{d t} R(t)^{2} \leq \max _{\left\{i: x_{i}(t)=R(t)\right\}}-\frac{w^{\prime}(2 R(t))}{R(t)} \sum_{j \neq i} m_{j}\left(x_{i}-x_{j}\right) \cdot x_{i}=-w^{\prime}(2 R(t)) R(t)
$$

so that $\frac{d}{d t} R(t) \leq-w^{\prime}(2 R(t)) / 2$ for almost all $t \geq \tau$. Using the non-Osgood condition, i.e. the integrability of $1 / w^{\prime}(r)$ at the origin, we conclude that $R(t)=0$ for a certain $T^{*}$ completely determined by the inequality $\frac{d}{d t} R(t) \leq-w^{\prime}(2 R(t)) / 2$.

Let us remark that this proof shows that the time of total collapse of the particles to their center of mass does not depend either on the number of particles or their masses, but only on $R_{0}$.

Making use of the stability result, the convergence of the particle method, and the total collapse for finite number of particles, we deduce the second main result of this work.

Theorem 4.3 (Finite Time Total Collapse). Assume $W$ satisfies (NL0)-(NL3) and (NL-FTBU). Let $\mu(t)$ denote the unique gradient flow solution starting from the probability measure $\mu_{0}$ with center of mass

$$
x_{c}:=\int_{\mathbb{R}^{d}} x d \mu_{0},
$$

supported in $\bar{B}\left(x_{c}, R_{0}\right)$. Then there exists $T^{*}$, depending only on $R_{0}$, such that $\mu(t)=\delta_{x_{c}}$ for all $t \geq T^{*}$.

Proof. As in the previous proposition, we can assume $x_{c}=0$. Given any compactly supported measure $\mu_{0}$ in $B\left(0, R_{0}\right)$ and any $\eta>0$, we can find a number of particles $N=N(\eta)$, a set of positions $\left\{x_{1}^{0}, \ldots, x_{N}^{0}\right\} \subset B\left(0, R_{0}\right)$, and masses $\left\{m_{1}, \ldots, m_{N}\right\}$, such that

$$
d_{W}\left(\mu_{0}, \sum_{i=1}^{N} m_{i} \delta_{x_{i}^{0}}\right) \leq \eta .
$$

Let us denote by $\mu_{\eta}(t)$ the particle solution associated to the initial datum $\mu_{\eta}(0)=$ $\sum_{i=1}^{N} m_{i} \delta_{x_{i}^{0}}$.

By Proposition 4.2, there exists a time $T^{*}$ independent of $N$ such that $\mu_{\eta}(t)=\delta_{0}$ for $t \geq T^{*}$. Hence, by the stability result in Theorem 2.13 we obtain

$$
d_{W}\left(\mu\left(T^{*}\right), \delta_{0}\right)=d_{W}\left(\mu\left(T^{*}\right), \mu_{\eta}\left(T^{*}\right)\right) \leq e^{-\lambda T^{*}} d_{W}\left(\mu_{0}, \sum_{i=1}^{N} m_{i} \delta_{x_{i}^{0}}\right) \leq e^{-\lambda T^{*}} \eta
$$

By the arbitrariness of $\eta$, we conclude that $\mu(t)=\delta_{0}$ for all $t \geq T^{*}$ as desired.

Remark 4.4 (Finite Time Total Collapse and Tail Behavior). The previous result can be generalized for measures which are not compactly supported by the following procedure. Let us consider the case in which $c_{0}:=\inf _{[0,+\infty)} w^{\prime}=w^{\prime}\left(0^{+}\right)>0$. Then the proof of case (a) in Proposition 4.2 shows that, if $\mu_{0}$ is supported in $B\left(x_{c}, R_{0}\right)$, then $\mu(t)=\delta_{x_{c}}$ for $t \geq R_{0} / c_{0}$. From this fact and the stability estimate, it is not difficult to show that for any initial datum $\mu_{0}$ decaying more than exponentially at infinity (say a gaussian), $\mu(t)$ converges exponentially fast to $\delta_{x_{c}}$ in infinite time. Indeed, if

$$
\mu_{0, R}:=\frac{\mu_{0}\left\lfloor B\left(x_{c}, R\right)\right.}{\mu_{0}\left(B\left(x_{c}, R\right)\right)},
$$

then one easily gets $d_{W}\left(\mu_{0}, \mu_{0, R}\right) \lesssim e^{-\bar{C} R}$ for any $\bar{C}>0$, and their centers of mass $x_{c}$ and $x_{c, R}$ are exponentially close too. Hence, if $\mu_{R}(t)$ denotes the solution starting from $\mu_{0, R}$, then $\mu_{R}\left(R / c_{0}\right)=\delta_{x_{c, R}}$. Therefore, choosing $\bar{C}>2|\lambda| / c_{0}$, we get

$$
d_{W}\left(\mu(t), \delta_{x_{c}}\right) \leq d_{W}\left(\mu(t), \mu_{c_{0} t}(t)\right)+\left|x_{c}-x_{c, c_{0} t}\right| \lesssim e^{-\lambda t} d_{W}\left(\mu_{0}, \mu_{0, c_{0} t}\right)+e^{-\bar{C} c_{0} t} \lesssim e^{-\bar{C} c_{0} t}
$$

as desired. As expected the tail behavior of the initial measure has to be fast enough to compensate the exponential growing bound in the stability when $\lambda<0$. On the other hand, if $\lambda \geq 0$ then we do not need any assumption on the initial datum to prove convergence in infinite time, although having estimates on the tails allows to prove better rates of convergence.

The aim of the following proposition is to show that, if we start with a measure which has some atomic part, then the atoms can only increase their mass. We present a proof based on particle approximations, an alternative approach is using the JKO-scheme, via Theorem 3.2,

Proposition 4.5 (Dirac Deltas can only increase mass). Let $\mu(t)$ denote the unique solution starting from the probability measure $\sum_{i=1}^{N} m_{i} \delta_{x_{i}^{0}}+\nu_{0}$, and define the curves $t \mapsto x_{i}(t), i=1, \ldots, N$, as the solution of the ODE

$$
\dot{x}_{i}(t)=-\left(\partial^{0} W * \mu(t)\right)\left(x_{i}(t)\right)
$$

Then $\mu(t) \geq \sum_{i=1}^{N} m_{i} \delta_{x_{i}(t)}$ for all $t \geq 0$, with possibly $x_{i}(t)=x_{j}(t)$ for some $t>0, i \neq j$.
Proof. This result is again an application of the result in the case of a finite number of particles, combined with the stability of solutions. Let us approximate $\nu_{0}$ with a sequence $\nu_{0}^{k}=m \sum_{j=1}^{k} \frac{1}{k} \delta_{y_{j}}$, with $m:=\nu_{0}\left(\mathbb{R}^{d}\right)$. Then the unique solution starting from $\sum_{i=1}^{N} m_{i} \delta_{x_{i}^{0}}+\nu_{0}^{k}$ is given by

$$
\mu^{k}(t)=\sum_{i=1}^{N} m_{i} \delta_{x_{i}^{k}(t)}+\sum_{j=1}^{k} \frac{m}{k} \delta_{y_{j}^{k}(t)},
$$

where $x_{i}^{k}(t)$ and $y_{j}^{k}(t)$ solve the ODE system

$$
\begin{aligned}
& \dot{x}_{i}^{k}=-\sum_{l \neq i, x_{l}^{k} \neq x_{i}^{k}} m_{j} \nabla W\left(x_{l}^{k}-x_{i}^{k}\right)-\sum_{l, y_{l}^{k} \neq x_{i}^{k}} \frac{m}{k} \nabla W\left(y_{l}^{k}-x_{i}^{k}\right), \quad i=1, \ldots, N, \\
& \dot{y}_{j}^{k}(t)=-\sum_{i, x_{i}^{k} \neq y_{l}^{k}} m_{i} \nabla W\left(x_{i}^{k}-y_{j}^{k}\right)-\sum_{l \neq j, y_{l}^{k} \neq y_{j}^{k}} \frac{m}{k} \nabla W\left(y_{l}^{k}-y_{j}^{k}\right), \quad j=1, \ldots, k .
\end{aligned}
$$

This gives in particular

$$
\begin{equation*}
\mu^{k}(t) \geq \sum_{i=1}^{k} m_{i} \delta_{x_{i}^{k}(t)} \tag{4.3}
\end{equation*}
$$

as measures, since the particles coming from the "discretization" of $\nu_{0}$ can only join the fixed particles $x_{i}$ but they will not split them. We now observe that the curves $t \mapsto x_{i}^{k}(t)$ are uniformly Lipschitz (locally in time). Indeed to obtain a bound on the velocity $\partial^{0} W * \mu$, by 1.5 it suffices to show that the second moments of the measures $\mu^{k}(t)$ are uniformly bounded, locally in time. To check this, we use as test function $|x|^{2}$ for a general gradient flow solution $\mu(t)$ of $(\overline{1.2})$, and exploiting the $\lambda$-convexity of $W$ we get

$$
\begin{aligned}
\frac{d}{d t} \int_{\mathbb{R}^{d}}|x|^{2} d \mu(t)(x) & =-2 \int_{\mathbb{R}^{d}} x \cdot\left(\partial^{0} W * \mu(t)\right) d \mu(t)(x) \\
& =-\int_{x \neq y}(x-y) \cdot(\nabla W(x)-\nabla W(y)) d \mu(t)(y) d \mu(t)(x) \\
& \leq-\lambda \int_{x \neq y}|x-y|^{2} d \mu(t)(y) d \mu(t)(x) \leq 4|\lambda| \int_{\mathbb{R}^{d}}|x|^{2} d \mu(t)(x) .
\end{aligned}
$$

Therefore, using the stability of solutions and Ascoli-Arzelà Theorem, up to a subsequence each curve $t \mapsto x_{i}^{k}(t)$ converges locally uniformly to a limit curve $t \mapsto x_{i}(t)$ which satisfies

$$
\dot{x}_{i}(t)=-\int_{\mathbb{R}^{d}} \partial^{0} W\left(y-x_{i}(t)\right) d \mu(t)(x), \quad i=1, \ldots, N .
$$

Taking the limit in the inequality (4.3) we get the desired result.
Finally, let us show that the blow up of the $L^{\infty}$ norm of a solution to (1.2) may occur at a time strictly less than the time of total collapse. In order to produce such a phenomenon, we shall work again with the ODE system (2.35) and then we argue by approximation. We first show a simple argument in a particular situation. We introduce
some notation following Proposition 4.2. Let us define the curves $t \mapsto x_{i}(t), i=1, \ldots, 2 N$ as the solution of the ODE system

$$
\frac{d x_{i}}{d t}=-\sum_{j \in C(i)} \frac{1}{2 N} \nabla W\left(x_{i}-x_{j}\right), \quad x_{i}(0)=x_{i}^{0}, \quad i=1, \ldots, 2 N
$$

so that $\mu(t)=\sum_{i=1}^{2 N} \frac{1}{2 N} \delta_{x_{i}(t)}$ is a gradient flow solution to 1.2). We define $x_{c_{1}}(t)$ and $x_{c_{2}}(t)$ to be the center of masses of the first $N$ and the last $N$ particles respectively. Let us consider the functions

$$
R_{1}(t):=\max _{i=1, \ldots, N}\left|x_{i}(t)-x_{c_{1}}(t)\right| \quad \text { and } \quad R_{2}(t):=\max _{i=N+1, \ldots, 2 N}\left|x_{i}(t)-x_{c_{2}}(t)\right|
$$

Finally, we denote by $\mu_{1}(t)$ and $\mu_{2}(t)$ the measures $\sum_{i=1}^{N} \frac{1}{2 N} \delta_{x_{i}(t)}$ and $\sum_{i=N+1}^{2 N} \frac{1}{2 N} \delta_{x_{i}(t)}$ respectively.
Proposition 4.6 (Multiple Collapse). Assume the potential $W$ satisfies (NL0)-(NL3), (NL-FTBUa), and $\lim _{x \rightarrow+\infty} w^{\prime}(x)=0$. There exist $r_{0}, d_{0}, T_{0}, T_{1}>0$ such that if $\max \left\{R_{1}(0), R_{2}(0)\right\} \leq r_{0}$ and $\left|x_{c_{1}}(0)-x_{c_{2}}(0)\right| \geq d_{0}$, then

$$
\mu_{1}(t)=\delta_{x_{c_{1}}(t)} \neq \mu_{2}(t)=\delta_{x_{c_{2}}(t)} \quad \text { for all } T_{0} \leq t<T_{1} .
$$

Proof. The ODE system satisfied by the particles is given by

$$
\frac{d x_{i}}{d t}=-\sum_{j \in C(i)} \frac{1}{2 N} \frac{x_{i}-x_{j}}{\left|x_{i}-x_{j}\right|} w^{\prime}\left(\left|x_{i}-x_{j}\right|\right), \quad i=1, \ldots, 2 N
$$

We distinguish two sets of particles: (I) the set of the first $N$ particles and (II) the set of last $N$ particles. Arguing as in Proposition 4.2, we obtain

$$
\frac{d^{+}}{d t} R_{1}^{2}(t)=\max _{\left\{i:\left|x_{i}(t)-x_{c_{1}}(t)\right|=R_{1}(t)\right\}}-\sum_{j \in C(i)} \frac{1}{N} \frac{\left(x_{i}-x_{j}\right) \cdot\left(x_{i}-x_{c_{1}}\right)}{\left|x_{i}-x_{j}\right|} w^{\prime}\left(\left|x_{i}-x_{j}\right|\right) .
$$

with $\left(x_{i}-x_{j}\right) \cdot\left(x_{i}-x_{c_{1}}\right) \geq 0$ for $j=1, \ldots, N$. Fix $d_{0}$ large enough such that $\left|w^{\prime}(r)\right| \leq$ $\frac{1}{4} w^{\prime}\left(0^{+}\right)$for $r \geq d_{0} / 2$. Then, as long as $\max \left\{R_{1}(t), R_{2}(t)\right\} \leq \frac{1}{8} d_{0}$ and $\left|x_{c_{1}}(t)-x_{c_{2}}(t)\right| \geq$ $\frac{3}{4} d_{0}$, we have that for some $i$ for which $\left|x_{i}(t)-x_{c_{1}}(t)\right|=R_{1}(t)$

$$
\begin{align*}
\frac{d^{+}}{d t} R_{1}^{2}(t) & \leq-\frac{w^{\prime}\left(0^{+}\right)}{2 N R_{1}(t)} \sum_{(I)}\left(x_{i}-x_{j}\right) \cdot\left(x_{i}-x_{c_{1}}\right)+\frac{\left|x_{i}-x_{c_{1}}\right|}{N} \sum_{(I I)}\left|w^{\prime}\left(\left|x_{i}-x_{j}\right|\right)\right| \\
& \leq-\frac{w^{\prime}\left(0^{+}\right)}{2} R_{1}(t)+\frac{w^{\prime}\left(0^{+}\right)}{4} R_{1}(t)=-\frac{w^{\prime}\left(0^{+}\right)}{4} R_{1}(t), \tag{4.4}
\end{align*}
$$

where we used

$$
\sum_{(I)}\left(x_{i}-x_{j}\right) \cdot\left(x_{i}-x_{c_{1}}\right)=N R_{1}(t)^{2} .
$$

By continuity in time of solutions, there exists $t_{*}>0$ small enough such that $\mid x_{c_{1}}(t)-$ $x_{c_{2}}(t) \left\lvert\, \geq \frac{3}{4} d_{0}\right.$ is satisfied for $0 \leq t \leq t_{*}$. Choosing $r_{0} \leq \min \left\{\frac{1}{8} d_{0}, \frac{w^{\prime}\left(0^{+}\right)}{8} t_{*}\right\}$ and using (4.4), we ensure that $\max \left\{R_{1}(t), R_{2}(t)\right\} \leq \frac{1}{8} d_{0}$ in $0 \leq t \leq t_{*}$ and $R_{1}\left(t_{*}\right)=0$. Analogously, we have that $R_{2}\left(t_{*}\right)=0$. Then, it is clear by continuity in time that we can choose $T_{0} \leq t_{*}<T_{1}$ such that the statement holds.

By a more refined analysis, one could produce an analogous result in case the potential $W$ satisfies (NL0)-(NL3), (NL-FTBUb), and $\lim _{x \rightarrow+\infty} w^{\prime}(x)=0$. For instance,
one can explicitly construct examples of particle configurations with special symmetries where one can check by tedious computations the multiple collapse phenomena. As a consequence, we obtain the following result

Corollary 4.7. Assume the potential $W$ satisfies (NL0)-(NL3), (NL-FTBU), and $\lim _{x \rightarrow+\infty} w^{\prime}(x)=0$. Then, there exists a nonnegative function $\rho_{0} \in C_{c}^{\infty}\left(\mathbb{R}^{d}\right)$ with unit mass and there two curves $x_{c_{k}}(t), k=1,2$, and $0<T_{0}<T_{1}$ such that the gradient flow solution associated with the initial datum $\rho_{0} d x$ satisfies

$$
\mu(t)=\frac{1}{2} \delta_{x_{c_{1}}(t)}+\frac{1}{2} \delta_{x_{c_{2}}(t)} \quad \text { and } \quad x_{c_{1}}(t) \neq x_{c_{2}}(t)
$$

for all $t \in\left(T_{0}, T_{1}\right)$.
It is clear from the previous proof that this two particle collapse can be generalized to multiple collapse situations with as many particle collapses as we want and choosing the time ordering of their collapses in any desired manner.

## 5. Confinement

In this section we consider the question if, for a fixed potential, solutions starting from data with uniformly bounded supports will have uniformly bounded supports for all time. If this is the case we say that confinement holds. In biological terms the question can be reformulated as follows: Will an initially localized population remain localized (regardless of the number of individuals) or will it spread to ever larger regions (depending on the initial population)? We prove two results on confinement for potentials that satisfy (NL-RAD). The first one gives an estimate on the evolution of the radius of the support of solutions starting from compactly supported data. For potentials that are strongly attractive at infinity, that is the ones satisfying (NL-CONF-strong), it implies that if the radius of the support is large, then it is decreasing. Heuristically, we can estimate the outward velocity of the particles that are the furthest from the center of mass. In particular for potentials satisfying (NL-CONF-strong), if the particles are far enough from the center of mass, then the attractive effects of the particles that are on the "opposite side" of the center of mass overwhelm the repulsive effects of the nearby particles. For sufficiently attractive potentials, with no repulsive part, this leads to an upper bound on the time of collapse.

For the potentials that are weakly-attractive at infinity, that is for ones which satisfy (NL-CONF-weak), we show that the support of solutions stays uniformly bounded for all times, with an explicit bound.

For variety, in order to contrast the techniques, we prove the confinement statements using two different approaches. For the first set of results, we use the JKO scheme to approximate the solution, and establish control on the support at each step of the JKO scheme. For the weak confinement we approximate the solution by atomic measures. For such an approximation the equation reduces to the ODE system discussed in Remark 2.10. The heart of the matter is proving confinement for the ODE approximation, with bounds independent of the number of particles.

We define for $r \geq R_{a}$

$$
\begin{equation*}
\sigma(r):=\inf _{s \geq r} w^{\prime}(s) \tag{5.1}
\end{equation*}
$$

Lemma 5.1. Assume that $W$ satisfies (NL0)-(NL3) and (NL-RAD). Let $r_{0}>2 R_{a}$, $\alpha=\frac{\sigma\left(r_{0}\right)}{8 \sqrt{2}}-C_{W}$, and le $\bar{\mu}$ be a compactly supported probability measure with center of mass at $x_{0}$ such that

$$
\operatorname{supp} \bar{\mu} \subset \bar{B}\left(x_{0}, r_{0}+\alpha \tau\right)
$$

for some $\tau>0$. Then, if $\mu \in \operatorname{argmin}_{\nu \in \mathcal{P}_{2}\left(\mathbb{R}^{d}\right)} F_{\tau}[\nu]$ it holds

$$
\operatorname{supp} \mu \subset \bar{B}\left(x_{0}, r_{0}\right)
$$

Here $C_{W}$ is defined by (1.9) and $F_{\tau}$ is the JKO functional (3.1). Note that $\alpha$ may be negative, in which case the only restriction on $\tau$ is that $r_{0}+\alpha \tau>0$ as otherwise the statement has no content.

Proof. As we did previously, we can assume without loss of generality that $x_{0}=0$. Since $\mathcal{W}$ is translation invariant, $\mu$ has center of mass 0 as well. We divide the proof in two steps

Step 1: The support does not grow faster than at the maximal repulsive speed $C_{W}$. More precisely, we first show that supp $\mu \subset \bar{B}\left(0, r_{0}+\left(\alpha+C_{W}\right) \tau\right)$. We do this by constructing a measure $\mu_{\text {new }}$ for which $F_{\tau}\left(\mu_{\text {new }}\right)<F_{\tau}(\mu)$ unless the support of $\mu$ is contained in the appropriate ball above.

Consider $\Pi_{r}$, the projection onto the ball $\bar{B}(0, r)$,

$$
\bar{x}=\Pi_{r}(x):= \begin{cases}x & \text { if }|x| \leq r \\ r \frac{x}{|x|} & \text { if }|x| \geq r\end{cases}
$$

Consider $r \geq r_{0}$ and define $\mu_{\text {new }}:=\Pi_{r \#} \mu$. Let $\pi$ be an optimal transportation plan between $\bar{\mu}$ and $\mu$. Consider $\pi_{\text {new }}:=\left(I \times \Pi_{r}\right)_{\#} \pi$. Note that $\pi_{\text {new }}$ is a transportation plan between $\bar{\mu}$ and $\mu_{\text {new }}$. Thus

$$
\begin{equation*}
d_{W}^{2}\left(\bar{\mu}, \mu_{\text {new }}\right) \leq \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-y|^{2} d \pi_{n e w}(x, y)=\int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}|x-\bar{y}|^{2} d \pi(x, y) \tag{5.2}
\end{equation*}
$$

where the notation $\bar{y}=\Pi_{r}(y)$ was used for simplicity. We claim that for all $x \in B\left(0, r_{0}+\right.$ $\alpha \tau)$ and all $y \in \mathbb{R}^{d}$

$$
|x-\bar{y}|^{2} \leq|x-y|^{2}+2\left(\alpha \tau+r_{0}-r\right)|y-\bar{y}| .
$$

The proof relies only on elementary geometric discussion of the cases $r_{0}+\alpha \tau<r$ and $r_{0}+\alpha \tau>r$, with subcases $r_{0}+\alpha \tau<|y|, r<|y| \leq r_{0}+\alpha \tau$, and $|y| \leq r$. While the proof is straightforward, it is not short, due to the need of distinguishing different cases. Thus we chose to leave the details to the reader. The above inequalities imply

$$
\begin{align*}
d_{W}^{2}\left(\bar{\mu}, \mu_{\text {new }}\right) & \leq \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}}\left[|x-y|^{2}+2\left(\alpha \tau+r_{0}-r\right)|y-\bar{y}|\right] d \pi(x, y) \\
& =d_{W}^{2}(\bar{\mu}, \mu)+2\left(\alpha \tau+r_{0}-r\right) \int_{|y|>r}|y-\bar{y}| d \mu(y) . \tag{5.3}
\end{align*}
$$



Figure 1. Relevant regions for $|x|>r$.

To estimate the change in the interaction energy we estimate the contributions from the "attractive" and "repulsive" parts:

$$
\begin{align*}
\mathcal{W}\left[\mu_{\text {new }}\right]-\mathcal{W}[\mu]= & \frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} W(\tilde{x}-\tilde{y}) d \mu_{\text {new }}(\tilde{x}) d \mu_{\text {new }}(\tilde{y}) \\
& -\frac{1}{2} \int_{\mathbb{R}^{d} \times \mathbb{R}^{d}} W(x-y) d \mu(y) d \mu(x) \\
= & \int_{|x|>r} \int_{|y| \leq r}[W(\bar{x}-y)-W(x-y)] d \mu(y) d \mu(x) \\
& +\frac{1}{2} \int_{|x|>r} \int_{|y|>r}[W(\bar{x}-\bar{y})-W(x-y)] d \mu(y) d \mu(x)  \tag{5.4}\\
\leq & \int_{|x|>r} \int_{A_{1}(x)}[W(\bar{x}-y)-W(x-y)] d \mu(y) d \mu(x) \\
& +\frac{1}{2} \int_{|x|>r} \int_{A_{2}(x)}[W(\bar{x}-\bar{y})-W(x-y)] d \mu(y) d \mu(x) \\
& \left.+\frac{1}{2} \int_{|x|>r} \int_{A_{3}(x)}[W(\bar{x}-\bar{y})-W(x-y)] d \mu(y) d \mu(x)\right\} I I \\
= & I+I I \leq I
\end{align*}
$$

where $A_{1}(x):=\left\{y:|y| \leq r,|\bar{x}-\bar{y}|<R_{a}\right\}, A_{2}(x):=\left\{y:|y|>r,|\bar{x}-\bar{y}|<R_{a}\right\}$, and $A_{3}(x):=\{y: x \cdot y<0\}$ are illustrated on Figure 1. Note that on the region we omitted above $R_{a} \leq|\bar{x}-\bar{y}| \leq|x-y|$, so the contribution is non-positive, which allowed us to omit it.

We first estimate $I$. To do so observe that, for $y \in A_{2}(x)$ and $|x-y| \leq R_{a}$, by definition of $C_{W}$ and $(1.9)$ we have

$$
W(\bar{x}-\bar{y})-W(x-y) \leq C_{W}|\bar{x}-\bar{y}-(x-y)| \leq C_{W}(|x-\bar{x}|+|y-\bar{y}|) .
$$

On the other hand, since $W$ is radial and increasing outside of $B\left(0, R_{a}\right)$, when $y \in A_{2}(x)$ and $|x-y|>R_{a}$ then

$$
\begin{aligned}
W(\bar{x}-\bar{y})-W(x-y) & \leq W(\bar{x}-\bar{y})-W\left(\Pi_{R_{a}}(x-y)\right) \leq C_{W}\left|\bar{x}-\bar{y}-\Pi_{R_{a}}(x-y)\right| \\
& \leq C_{W}|\bar{x}-\bar{y}-(x-y)| \leq C_{W}(|x-\bar{x}|+|y-\bar{y}|)
\end{aligned}
$$

where the inequality between the first and the second line follows from the fact that $\bar{x}-\bar{y} \in B\left(0, R_{a}\right)$ and $x-y \notin B\left(0, R_{a}\right)$. The estimate also holds for $y \in A_{1}(x)$, only that then $y=\bar{y}$. Therefore

$$
\begin{align*}
I \leq & \int_{|x|>r} \int_{A_{1}(x)} C_{W}|\bar{x}-x| d \mu(y) d \mu(x) \\
& +\frac{1}{2} \int_{|x|>r} \int_{A_{2}(x)}\left[C_{W}(|x-\bar{x}|+|y-\bar{y}|)\right] d \mu(y) d \mu(x) \\
= & C_{W} \int_{|x|>r}|x-\bar{x}| \mu\left(\left\{y:|\bar{x}-\bar{y}|<R_{a}\right\}\right) d \mu(x)  \tag{5.5}\\
\leq & C_{W} \int_{|x|>r}|x-\bar{x}| \mu\left(\left\{y: y \cdot \frac{x}{|x|} \geq \frac{r}{2}\right\}\right) d \mu(x)
\end{align*}
$$

where in the last inequality (which we only need for the refined argument) we used that if $|\bar{x}-\bar{y}|<R_{a}$ then $y \cdot \frac{x}{|x|} \geq r-R_{a} \geq \frac{r}{2}$ (recall that $r \geq r_{0} \geq 2 R_{a}$ ).

To obtain the first estimate on the radius of support of $\mu$ it is enough to note that the largest outward velocity of a particle is $C_{W}$. To obtain the appropriate statement at the level of the JKO scheme, we combine the above estimates (5.4), (5.5) and (5.3) and use that $\mu$ is a minimizer:

$$
\begin{aligned}
0 \leq F_{\tau}\left[\mu_{\text {new }}\right]-F_{\tau}[\mu] & \leq I+\frac{\alpha \tau+r_{0}-r}{\tau} \int_{|x|>r}|x-\bar{x}| d \mu(x) \\
& \leq\left(C_{W}+\alpha-\frac{r-r_{0}}{\tau}\right) \int_{|x|>r}|x-\bar{x}| d \mu(x)
\end{aligned}
$$

Thus $\int_{|x|>r}|x-\bar{x}| d \mu(x)=0$ if $r>r_{0}+\left(C_{W}+\alpha\right) \tau$, which implies

$$
\begin{equation*}
\operatorname{supp} \mu \subset \bar{B}\left(0, r_{0}+\left(C_{W}+\alpha\right) \tau\right) \tag{5.6}
\end{equation*}
$$

Step 2: Compensation between repulsion and attraction. Since the support of $\mu$ is bounded, we can consider $\bar{r}:=\inf \{s>0: \operatorname{supp} \mu \subseteq \bar{B}(0, s)\}$. Note that $\operatorname{supp} \mu \subseteq \bar{B}(0, \bar{r})$. Suppose that the claim of the Lemma does not hold. Then $\bar{r}>r_{0}$. Let $r=\frac{1}{2}\left(r_{0}+\bar{r}\right)$. Note that supp $\mu \not \subset \bar{B}(0, r)$ but that supp $\mu \subset B(0,2 r)$.

To refine the argument we need to estimate the effects of attraction, that is the term $I I$ in (5.4). We utilize the following inequality: If $y \cdot x<0$ then, since the angle between $x-\bar{x}$ and $\bar{y}-\bar{x}$ is greater than $3 \pi / 4,(x-\bar{x}) \cdot(\bar{x}-\bar{y}) \geq \frac{1}{\sqrt{2}}|x-\bar{x}||\bar{x}-\bar{y}|$. Therefore

$$
\begin{aligned}
|x-\bar{y}|^{2} & =|(x-\bar{x})+(\bar{x}-\bar{y})|^{2} \\
& \geq|x-\bar{x}|^{2}+2 \frac{1}{\sqrt{2}}|x-\bar{x}||\bar{x}-\bar{y}|+|\bar{x}-\bar{y}|^{2} \\
& \geq\left(\frac{1}{\sqrt{2}}|x-\bar{x}|+|\bar{x}-\bar{y}|\right)^{2}
\end{aligned}
$$

Consequently

$$
|x-y|-|\bar{x}-\bar{y}| \geq|x-\bar{y}|-|\bar{x}-\bar{y}| \geq \frac{1}{\sqrt{2}}|x-\bar{x}|
$$

We now estimate

$$
\begin{align*}
I I & \leq-\frac{1}{2} \int_{|x|>r} \int_{y \cdot x<0} \sigma(r)(|x-y|-|\bar{x}-\bar{y}|) d \mu(y) d \mu(x)  \tag{5.7}\\
& \leq-\frac{1}{2 \sqrt{2}} \int_{|x|>r} \sigma(r)|x-\bar{x}| \mu(\{y: x \cdot y<0\}) d \mu(x) .
\end{align*}
$$

We remark that if $\tau$ is small, more precisely when $0<\tau<\frac{r_{0}}{M\left(C_{W}+\alpha\right)}$ for some $M>0$ large, then, due to (5.6), $\sigma(r)$ above can be replaced by $\sigma_{M}(r):=\min _{s \in[r, 2(1+1 / M) r]} w^{\prime}(s)$.

We now use that the center of mass of $\mu$ is 0 in order to show that the measure of the set which is "repulsing" the particle at $|x|>r$ is bounded by a multiple of the measure of the set which is "attracting". In particular, $\int_{\mathbb{R}^{d}} x \cdot y d \mu(y)=0$ implies

$$
-\int_{y \cdot x<0} x \cdot y d \mu(y) \geq \int_{y \cdot x \geq \frac{r}{2}|x|} x \cdot y d \mu(y) .
$$

Thanks to this estimate, using that $\operatorname{supp} \mu \subset \bar{B}(0,2 r)$ and $2 R_{a}<r$, we obtain that for $|x|>r$

$$
2 r \mu(\{y: x \cdot y<0\}) \geq \frac{r}{2} \mu\left(\left\{y: y \cdot x \geq \frac{r}{2}|x|\right\}\right)
$$

Combining this with estimates (5.4), (5.5), and (5.7) yields

$$
\begin{aligned}
\mathcal{W}\left[\mu_{\text {new }}\right]-\mathcal{W}[\mu] & \leq \int_{|x|>r}\left(C_{W}-\frac{1}{8 \sqrt{2}} \sigma(r)\right)|x-\bar{x}| \mu\left(\left\{y: y \cdot x \geq \frac{r}{2}|x|\right\}\right) d \mu(x) \\
& \leq \int_{|x|>r}|x-\bar{x}|\left(C_{W}-\frac{1}{8 \sqrt{2}} \sigma(r)\right) d \mu(x) .
\end{aligned}
$$

The minimality of $\mu$, the above inequality and (5.3) imply

$$
0 \leq F_{\tau}\left[\mu_{\text {new }}\right]-F_{\tau}[\mu] \leq\left(C_{W}-\frac{1}{8 \sqrt{2}} \sigma(r)+\alpha\right) \int_{|x|>r}|x-\bar{x}| d \mu(x) .
$$

Since $C_{W}-\frac{1}{8 \sqrt{2}} \sigma(r)+\alpha<0$ we conclude that $\operatorname{supp} \mu \subset \bar{B}(0, r)$. Contradiction.
We use the lemma to obtain an upper bound on the rate at which the radius of support of a solution is changing and consequently a bound on the radius itself. More precisely for a compactly supported measure $\mu$ centered at $x_{0}$ we define the radius of support to be

$$
R(\mu)=\inf \left\{r>0: \mu\left(\mathbb{R}^{d} \backslash B\left(x_{0}, r\right)\right)=0\right\} .
$$

Note that $\operatorname{supp} \mu \subset \bar{B}\left(x_{0}, R(\mu)\right)$, where $\bar{B}\left(x_{0}, R\right)=\left\{x \in \mathbb{R}^{d}:\left|x-x_{0}\right| \leq R\right\}$.
Corollary 5.2. Assume $W$ satisfies (NL0)-(NL3) and (NL-RAD). Let $\mu_{0}$ be a compactly supported probability measure with center of mass at $x_{0}$ and radius of support $r_{0}$. Assume that $r_{0} \geq 2 R_{a}$. Let $\tilde{\sigma}(r):=\inf _{r \leq s \leq 2 r} w^{\prime}(s)$ for $r \geq R_{a}$. Then the solution $\mu(t)$ to (1.2) satisfies the following estimates:
(i) Let $r(t)$ be the solution of the $O D E$

$$
\left\{\begin{array}{l}
\frac{d r}{d t}=-\frac{\tilde{\sigma}(r)}{8 \sqrt{2}}+C_{W} \\
r(0)=r_{0}
\end{array}\right.
$$

If $R(\mu(t))>2 R_{a}$ then

$$
\limsup _{h \rightarrow 0+} \frac{R(\mu(t+h))-R(\mu(t))}{h} \leq r^{\prime}(t)
$$

Consequently for all $t \geq 0$

$$
\operatorname{supp} \mu(t) \subseteq \bar{B}\left(x_{0}, \bar{r}(t)\right)
$$

with $\bar{r}(t):=\max \left\{r(t), 2 R_{a}\right\}$.
(ii) Special case - attractive, radial potentials: Assume further that $W$ is radial, and such that $w(r)$ is an increasing function. Then $C_{W}=0$ and

$$
\operatorname{supp} \mu(t) \subseteq \bar{B}\left(x_{0}, r(t)^{+}\right)
$$

for all $t \geq 0$.
In both cases, if $W$ satisfies the assumption (NL-CON-strong) and the radius of the support is large enough, then it must be decreasing. Consequently for any compactly supported initial data the support of the solution is uniformly bounded.

We remark that this corollary complements the results on collapse of Section 4. Furthermore the quantitative estimate on the radius of support encoded in the ODE $\frac{d r}{d t}=$ $-c \tilde{\sigma}(r)$ can be used to show the finite time collapse for potentials satisfying the condition (NL-FTBU). On the other hand, the particle approximation that was used in proving the results of Section 4 can be used to prove this lemma as well.
Proof. Part (i) of the corollary with $\sigma(r)$ in place of $\tilde{\sigma}(r)$ follows easily from Lemma 5.1 as it gives the rate $\alpha$, at which the support of the minimizers of the JKO scheme is changing. To conclude, we only need to recall that the minimizers of the JKO scheme converge narrowly towards $\mu(t)$, and note that uniform bounds on the support of measures are preserved in the limit. Part (ii), is just a special case, since $R_{a}=0$.

We need to justify that $\tilde{\sigma}$ can be used instead of $\sigma$. This follows from the fact that, thanks to the remark below (5.7), for small $\tau$ we can improve the estimates on attractive part in Lemma 5.1 replacing $\sigma$ by $\sigma_{M}$. Since $M>0$ is arbitrary, letting $M \rightarrow+\infty$ we obtain the estimate with $\tilde{\sigma}$, as desired.

Note that if the assumption (NL-CON-strong) is satisfied then $\frac{d r}{d t} \leq 0$ whenever $r$ is large enough, more precisely in $r \geq \inf \left\{r>2 R_{a}: \sigma(r)>8 \sqrt{2} C_{W}\right\}$. Thus the support stays uniformly bounded.

For potentials satisfying (NL-CONF-weak) the above estimate on the rate at which the radius of support can change is not sufficient to show that the radius remains uniformly bounded in time. Thus we provide a different argument that also relies on the energy of the solution. For $r \geq R_{a}$ let

$$
\theta(r):=\inf _{s \geq r} w^{\prime}(s) \sqrt{s}
$$

Lemma 5.3 (Weak confinement for weakly attractive-at-infinity potentials). Assume that $W$ satisfies the conditions (NL0)-(NL3) and (NL-CONF-weak). Then, for every $R>0$, there exists $\bar{R} \geq R$, depending only on $R, C_{W}$ and $W$ (via the function $\theta$ ), such that the following holds: Let $x_{i}(t)$ be the solution of the ODE system considered in Remark 2.10

$$
\dot{x}_{i}=-\sum_{j \in C(i)} m_{j} \nabla W\left(x_{j}-x_{i}\right), \quad i=1, \ldots, N
$$

with $m_{j}>0, \sum_{j} m_{j}=1$, and $\sum_{j} m_{j} x_{j}(0)=0$. If $\left|x_{i}(0)\right| \leq R$ for $i=1, \ldots, N$, then

$$
\left|x_{i}(t)\right| \leq \bar{R} \quad \text { for all } t>0 \text { and } i=1, \ldots, N .
$$

Proof. The idea of the proof is as follows: Note that there are no direct energetic obstacles to prevent the support of the solution becoming large. That is the boundedness of the energy does not prevent a particle from traveling far, as long as its mass is small. However it turns out that for even a small particle to go far from the center of mass, there must exist a large mass nearby. That is for the small particle to go far, there must be particles of relatively large total mass which are "pushing" it out. However the existence of a large mass far from the center of mass does violate the fact that the energy is dissipated.

By adding a constant to $W$, we can assume that $W(x) \geq 0$ for all $x \in \mathbb{R}^{d}$. Let $\bar{R}$ be such that

$$
\begin{equation*}
\bar{R}>4 R_{a}, \bar{R}>R, \text { and } \theta\left(\frac{\bar{R}}{8}\right)>12 \sqrt{2 C_{W}\|W\|_{L^{\infty}(B(0,2 R))}} . \tag{5.8}
\end{equation*}
$$

Let us observe that for any $r>2 R_{a}$

$$
\begin{equation*}
w(r) \geq \frac{\sqrt{r}}{2} \theta\left(\frac{r}{2}\right) . \tag{5.9}
\end{equation*}
$$

This follows by noting that $w^{\prime}(s) \geq \theta(r / 2) / \sqrt{r}$ for all $s \in(r / 2, r)$, integrating from $r / 2$ to $r$, and using that $w(r / 2) \geq 0$.

Assume that the claim of the lemma does not hold. Since $x_{i}$ are $C^{1}$ for all but finitely many times, there exists $\tilde{R} \geq \bar{R}$ for which the inequalities (5.8) still hold and such that at the first time a particle reaches distance $\tilde{R}$ from the origin all of the particle trajectories are differentiable. Let $t_{1}$ be the first time that at which particle reaches the distance $\tilde{R}$ from the origin. Consider the relabeled ODE system (2.38) near time $t_{1}$. For notational simplicity, we keep the symbols $x_{i}$ and $m_{i}$ for particle positions and masses. We can assume that $\left|x_{1}\left(t_{1}\right)\right|=\tilde{R}$. Note that $\dot{x}_{1}\left(t_{1}\right) \cdot x_{1}\left(t_{1}\right) \geq 0$. Therefore

$$
\begin{equation*}
-\sum_{j \geq 2} m_{j} \nabla W\left(x_{1}(t)-x_{j}(t)\right) \cdot x_{1}(t) \geq 0 . \tag{5.10}
\end{equation*}
$$

We can assume that $x_{1}(t) /\left|x_{1}(t)\right|=e_{1}$. Let $J_{R}$ be the set of indexes of particles that at time $t_{1}$ are repulsing $x_{1}$, that is $J_{R}:=\left\{j: \nabla W\left(x_{1}\left(t_{1}\right)-x_{j}\left(t_{1}\right)\right) \cdot e_{1}<0\right\}, J_{A}:=$ $\left\{2, \ldots, N\left(t_{1}\right)\right\} \backslash J_{R}$, and $J_{a}=\left\{j: x_{j}\left(t_{1}\right) \cdot e_{1} \leq \tilde{R} / 2\right\}$ with $J_{a}^{c}$ its complementary set of indices. We notice that, since $\tilde{R}>2 R_{a}, J_{a} \subseteq J_{A}$. Using that at time $t_{1}$ all particles are contained in $\bar{B}(0, \tilde{R})$, it follows that

$$
\nabla W\left(x_{1}-x_{j}\right) \cdot e_{1} \geq \frac{1}{2} w^{\prime}\left(\left|x_{j}-x_{1}\right|\right) \text { for all } j \in J_{a}
$$

Furthermore, since 0 is the center of mass,

$$
m_{a}:=\sum_{j \in J_{a}} m_{j}=1-\sum_{j \in J_{a}^{c}} m_{j}=: 1-m_{a}^{c} \geq \frac{1}{3} .
$$

The argument is analogous to one in the proof of Lemma 5.1. Since the center of mass is zero, using the definition of $J_{a}$ and that all particles lie inside $\bar{B}(0, \tilde{R})$, we get

$$
\frac{\tilde{R}}{2} m_{a}^{c} \leq \sum_{j \in J_{a}^{c}} m_{j}\left(x_{j}\left(t_{1}\right) \cdot e_{1}\right)=-\sum_{j \in J_{a}} m_{j}\left(x_{j}\left(t_{1}\right) \cdot e_{1}\right) \leq \tilde{R} m_{a}=\tilde{R}\left(1-m_{a}^{c}\right)
$$

from which $m_{a}^{c} \leq \frac{2}{3}$. Let $m_{R}:=\sum_{j \in J_{R}} m_{j}$. From (5.10) it follows that

$$
\sum_{j \in J_{R}}-m_{j} \nabla W\left(x_{1}-x_{j}\right) \cdot e_{1} \geq \sum_{j \in J_{a}} m_{j} \nabla W\left(x_{1}-x_{j}\right) \cdot e_{1} \geq \sum_{j \in J_{a}} m_{j} \frac{1}{2} w^{\prime}\left(\left|x_{1}-x_{j}\right|\right)
$$

so that

$$
m_{R} C_{W} \geq \frac{1}{12 \sqrt{2 \tilde{R}}} \theta\left(\frac{\tilde{R}}{2}\right)
$$

which implies a lower bound on $m_{R}$.
Note that energy $\mathcal{W}[\mu(0)]$ is bounded by $\frac{1}{2}\|W\|_{L^{\infty}(B(0,2 R))}$. One the other hand, using that $\tilde{R}>4 R_{a}$,

$$
2 \mathcal{W}\left[\mu\left(t_{1}\right)\right] \geq \sum_{j \in J_{R}} \sum_{k \in J_{a}} m_{j} m_{k} W\left(x_{j}-x_{k}\right) \geq \frac{m_{R}}{3} \inf _{r \geq \tilde{R} / 4} w(r) .
$$

Using that $\mathcal{W}[\mu(0)] \geq \mathcal{W}\left[\mu\left(t_{1}\right)\right]$ and (5.9), we conclude that

$$
\begin{aligned}
\|W\|_{L^{\infty}(B(0,2 R))} & \geq \frac{m_{R}}{3} \inf _{r \geq \tilde{R} / 4} w(r) \\
& \geq \frac{1}{3}\left[\frac{1}{12 \sqrt{2 \tilde{R}} C_{W}} \theta\left(\frac{\tilde{R}}{2}\right)\right]\left[\frac{\sqrt{\tilde{R}}}{4} \theta\left(\frac{\tilde{R}}{8}\right)\right] \geq \frac{1}{144 \sqrt{2} C_{W}} \theta\left(\frac{\tilde{R}}{8}\right)^{2}
\end{aligned}
$$

which contradicts (5.8).
Arguing by approximation as in the proof of Theorem 4.3, we immediately obtain the following:

Corollary 5.4. Assume $W$ satisfies (NL0)-(NL3) and (NL-CONF-weak). Then, given a compactly supported probability measure $\mu_{0}$ with center of mass at $x_{0}$ such that supp $\mu_{0} \subset \bar{B}\left(x_{0}, R\right)$, there exists $\bar{R} \geq R$, depending only on $R, C_{W}$ and $W$, such that the solution $\mu(t)$ to (1.2) satisfies

$$
\operatorname{supp} \mu(t) \subset \bar{B}\left(x_{0}, \bar{R}\right) \quad \text { for all } t \geq 0
$$

Remark 5.5. It is useful, especially for biological applications, to note that the above claim holds when $\mu_{0}$ is an arbitrary (nonnegative) measure, with the bound on the support of $\mu(t)$ independent of the mass of $\mu_{0}$. This is due to the fact that the dynamics can be renormalized to mass one, using the following invariance of the equation: if $\mu(t)$ is a solution, so is $M \mu(M t)$.

Remark 5.6. There are many potentials for which the claim of the corollary does not hold. For instance, consider any $W$ positive in $B(0,1)$ and equal to zero outside. More interesting examples, which are mildly attractive at infinity, follow from the work of Theil 41].

We conclude the paper by making the following conjecture: The result of the corollary above holds if the condition (NL-CONF-weak) is replaced by the assumption that $w$ is increasing on $[R, \infty)$ for some $R$ and

$$
\lim _{r \rightarrow+\infty} w(r)=+\infty .
$$

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