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# Global well-posedness of the Euler-Korteweg system for small irrotational data 

Corentin Audiard ${ }^{* \dagger}$ and Boris Haspot ${ }^{\ddagger}$


#### Abstract

The Euler-Korteweg equations are a modification of the Euler equations that takes into account capillary effects. In the general case they form a quasi-linear system that can be recast as a degenerate Schrödinger type equation. Local well-posedness (in subcritical Sobolev spaces) was obtained by Benzoni-Danchin-Descombes in any space dimension, however, except in some special case (semi-linear with particular pressure) no global wellposedness is known. We prove here that under a natural stability condition on the pressure, global well-posedness holds in dimension $d \geq 3$ for small irrotational initial data. The proof is based on a modified energy estimate, standard dispersive properties if $d \geq 5$, and a careful study of the nonlinear structure of the quadratic terms in dimension 3 and 4 involving the theory of space time resonance.


## Résumé

Les équations d'Euler-Korteweg sont une modification des équations d'Euler prenant en compte l'effet de la capillarité. Dans le cas général elles forment un système quasi-linéaire qui peut se reformuler comme une équation de Schrödinger dégénérée. L'existence locale de solutions fortes a été obtenue par Benzoni-Danchin-Descombes en toute dimension, mais sauf cas très particuliers il n'existe pas de résultat d'existence globale. En dimension au moins 3 , et sous une condition naturelle de stabilité sur la pression on prouve que pour toute donnée initiale irrotationnelle petite, la solution est globale. La preuve s'appuie sur une estimation d'énergie modifiée. En dimension au moins 5 les propriétés standard de dispersion suffisent pour conclure tandis que les dimensions 3 et 4 requièrent une étude précise de la structure des nonlinéarités quadratiques pour utiliser la méthode des résonances temps espaces.

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## 1 Introduction

The compressible Euler-Korteweg equations read

$$
\left\{\begin{array}{l}
\partial_{t} \rho+\operatorname{div}(\rho u)=0,(x, t) \in \mathbb{R}^{d} \times I  \tag{1.1}\\
\partial_{t} u+u \cdot \nabla u+\nabla g(\rho)=\nabla\left(K(\rho) \Delta \rho+\frac{1}{2} K^{\prime}(\rho)|\nabla \rho|^{2}\right),(x, t) \in \mathbb{R}^{d} \times I \\
\left.(\rho, u)\right|_{t=0}=\left(\rho_{0}, u_{0}\right), x \in \mathbb{R}^{d}
\end{array}\right.
$$

Here $\rho$ is the density of the fluid, $u$ the velocity, $g$ the bulk chemical potential, related to the pressure by $p^{\prime}(\rho)=\rho g^{\prime}(\rho) . K(\rho)>0$ corresponds to the capillary coefficient. On the left hand side we recover the Euler equations, while the right hand side of the second equation contains the so called Korteweg tensor, which is intended to take into account capillary effects and models in particular the behavior at the interfaces of a liquid-vapor mixture. The system arises in various settings: the case $K(\rho)=\kappa / \rho$ corresponds to the so-called equations of quantum hydrodynamics (which are formally equivalent to the Gross-Pitaevskii equation through the Madelung transform, on this topic see the survey of Carles et al [10]).
As we will see, in the irrotational case the system can be reformulated as a quasilinear Schrödinger equation, this is in sharp contrast with the non homogeneous incompressible case where the system is hyperbolic (see [9]). For a general $K(\rho)$, local well-posedness was proved in [6]. Moreover (1.1) has a rich structure with special solutions such as planar traveling waves, namely solutions that only depend on $y=t-x \cdot \xi, \xi \in \mathbb{R}^{d}$, with possibly $\lim _{\infty} \rho(y) \neq \lim _{-\infty} \rho(y)$. The orbital stability and instability of such solutions has been largely studied over the last ten years (see [7] and the review article of Benzoni-Gavage [8]). The
existence and non uniqueness of global non dissipative weak solutions 1 in the spirit of De Lellis-Szekelehidi [12]) was tackled by Donatelli et al [13], while weak-strong uniqueness has been very recently studied by Giesselman et al [18.
Our article deals with a complementary issue, namely the global well-posedness and asymptotically linear behaviour of small smooth solutions near the constant state $(\rho, u)=(\bar{\rho}, 0)$. To our knowledge we obtain here the first global well-posedness result for (1.1) in the case of a general pressure and capillary coefficient. This is in strong contrast with the existence of infinitely many weak solutions from [13.
A precise statement of our results is provided in theorems 2.1 [2.2 of section 2, but first we will briefly discuss the state of well-posedness theory, the structure of the equation, and the tools available to tackle the problem. Let us start with the local well-posedness result from 6].

Theorem 1.1. For $d \geq 1$, let $(\bar{\rho}, \bar{u})$ be a smooth solution whose derivatives decay rapidly at infinity, $s>1+d / 2$. Then for $\left(\rho_{0}, u_{0}\right) \in(\bar{\rho}, \bar{u})+H^{s+1}\left(\mathbb{R}^{d}\right) \times H^{s}\left(\mathbb{R}^{d}\right)$, $\rho_{0}$ bounded away from 0 , there exists $T>0$ and a unique solution $(\rho, u)$ of (1.1) such that $(\rho-\bar{\rho}, u-\bar{u})$ belongs to $C\left([0, T], H^{s+1} \times H^{s}\right) \cap C^{1}\left([0, T], H^{s-1} \times H^{s-2}\right)$ and $\rho$ remains bounded away from 0 on $[0, T] \times \mathbb{R}^{d}$.

We point out that [6] includes local well-posedness results for nonlocalized initial data (e.g. theorem 6.1). The authors also obtained several blow-up criterions. In the irrotational case it reads:

Blow-up criterion: for $s>1+d / 2,(\rho, u)$ solution on $[0, T) \times \mathbb{R}^{d}$ of 1.1), the solution can be continued beyond $T$ provided

1. $\rho\left([0, T) \times \mathbb{R}^{d}\right) \subset J \subset \mathbb{R}^{+*}, J$ compact and $K$ is smooth on a neighbourhood of $J$.
2. $\int_{0}^{T}\left(\|\Delta \rho(t)\|_{\infty}+\|\operatorname{div} u(t)\|_{\infty}\right) d t<\infty$.

These results relied on energy estimates for an extended system that we write now. If $\mathcal{L}$ is a primitive of $\sqrt{K / \rho}$, setting $L=\mathcal{L}(\rho), w=\sqrt{K / \rho} \nabla \rho=\nabla L, a=\sqrt{\rho K(\rho)}$, from basic computations we verify (see [6]) that the equations on ( $L, u, w$ ) are

$$
\left\{\begin{array}{l}
\partial_{t} L+u \cdot \nabla L+a \operatorname{div} u=0, \\
\partial_{t} u+u \cdot \nabla u-w \cdot \nabla w-\nabla(a \operatorname{div} w)=-\nabla g, \\
\partial_{t} w+\nabla(u \cdot w)+\nabla(a \operatorname{div} w)=0,
\end{array}\right.
$$

or equivalently for $z=u+i w$

$$
\left\{\begin{array}{l}
\partial_{t} L+u \cdot \nabla L+a \operatorname{div} u=0  \tag{1.2}\\
\partial_{t} z+u \cdot \nabla z+i(\nabla z) \cdot w+i \nabla(a \operatorname{div} z)=\nabla \widetilde{g}(L) .
\end{array}\right.
$$

Here we set $\widetilde{a}(L)=a \circ \mathcal{L}^{-1}(L), \widetilde{g}(L)=g \circ \mathcal{L}^{-1}(L)$ which are well-defined since $\sqrt{K / \rho}>0$ thus $\mathcal{L}$ is invertible.
This change of unknown clarifies the underlying dispersive structure of the model as the second

[^1]equation is a quasi-linear degenerate Schrödinger equation. It should be pointed out however that the local existence results of [6] relied on $H^{s}$ energy estimates rather than dispersive estimates. On the other hand, we constructed recently in [4] global small solutions to (1.1) for $d \geq 3$ when the underlying system is semi-linear, that is $K(\rho)=\kappa / \rho$ with $\kappa$ a positive constant and for $g(\rho)=\rho-1$. This case corresponds to the equations of quantum hydrodynamics. The construction relied on the so-called Madelung transform, which establishes a formal correspondance between these equations and the Gross-Pitaevskii equation, and recent results on scattering for the Gross-Pitaevskii equation [20] 22]. Let us recall for completeness that $1+\psi$ is a solution of the Gross-Pitaevskii equation if $\psi$ satisfies
\[

$$
\begin{equation*}
i \partial_{t} \psi+\Delta \psi-2 \operatorname{Re}(\psi)=\psi^{2}+2|\psi|^{2}+|\psi|^{2} \psi . \tag{1.3}
\end{equation*}
$$

\]

For the construction of global weak solutions (no uniqueness, but no smallness assumptions) we refer also to the work of Antonelli-Marcati [1, 2].
In this article we consider perturbations of the constant state $\rho=\rho_{c}, u=0$ for a general capillary coefficient $K(\rho)$ that we only suppose smooth and positive on an interval containing $\rho_{c}$. In order to exploit the dispersive nature of the equation we need to work with irrotational data $u=\nabla \phi$ so that (1.2) reduces to the following system (where $L_{c}=\mathcal{L}\left(\rho_{c}\right)$ which has obviously similarities with (1.3) (more details are provided in sections 3 and 4):

$$
\left\{\begin{array}{l}
\partial_{t} \phi-\Delta\left(L-L_{c}\right)+\widetilde{g}^{\prime}\left(L_{c}\right)\left(L-L_{c}\right)=\mathcal{N}_{1}(\phi, L)  \tag{1.4}\\
\partial_{t}\left(L-L_{c}\right)+\Delta \phi=\mathcal{N}_{2}(\phi, L)
\end{array}\right.
$$

The sytem satisfies the dispersion relation $\tau^{2}=|\xi|^{2}\left(\widetilde{g}^{\prime}\left(L_{c}\right)+|\xi|^{2}\right)$, and the $\mathcal{N}_{j}$ are at least quadratic nonlinearities that depend on $L, \phi$ and their derivatives (the system is thus quasilinear). We also point out that the stability condition $\tilde{g}^{\prime}\left(L_{c}\right) \geq 0$ is necessary in order to ensure that the solutions in $\tau$ of the dispersion relation are real.
The existence of global small solutions for nonlinear dispersive equations is a rather classical topic which is impossible by far to describe exhaustively in this introduction. We shall yet underline the main ideas that are important for our work here.

Dispersive estimates For the Schrödinger equation, two key tools are the dispersive estimate

$$
\begin{equation*}
\left\|e^{i t \Delta} \psi_{0}\right\|_{L^{q}\left(\mathbb{R}^{d}\right)} \lesssim \frac{\left\|\psi_{0}\right\|_{L^{2}}}{t^{d(1 / 2-1 / q)}} \tag{1.5}
\end{equation*}
$$

and the Strichartz estimates

$$
\begin{array}{r}
\left\|e^{i t \Delta} \psi_{0}\right\|_{L^{p}\left(\mathbb{R}, L^{q}\left(\mathbb{R}^{d}\right)\right)} \lesssim\left\|\psi_{0}\right\|_{L^{2}}, \frac{2}{p}+\frac{d}{q}=\frac{d}{2}, \\
\left\|\int_{0}^{t} e^{i(t-s) \Delta} f(s) d s\right\|_{L^{p}\left(\mathbb{R}, L^{q}\left(\mathbb{R}^{d}\right)\right)} \lesssim\|f\|_{L^{p_{1}^{\prime}}\left(\mathbb{R}, L^{L_{1}^{\prime}}\left(\mathbb{R}^{d}\right)\right.}, \frac{2}{p_{1}}+\frac{d}{q_{1}}=\frac{d}{2} . \tag{1.7}
\end{array}
$$

Both indicate decay of the solution for long time in $L^{p}\left(L^{q}\right)$ spaces, it is of course of interest when we wish to prove the existence of global strong solution since it generally require some damping behavior for long time. Due to the pressure term the linear structure of our system
is actually closer to the one of the Gross-Pitaevskii equation (see (1.3)), but the estimates are essentially the same as for the Schrödinger equation. Local smoothing is also an interesting feature of Schrödinger equations, in particular for the study of quasilinear systems. A result in this direction was obtained by the first author in [3] but we will not need it here. The main task of our proof will consist in proving dispersive estimates of the type 1.5 for long time, it is related to the notion of scattering for the solution of the dispersive equations. Let us recall now some classical result on the theory of the scattering for the Schrödinger equations and the Gross Pitaevskii equation.

Scattering Let us consider the following nonlinear Schrödinger equation

$$
i \partial_{t} \psi+\Delta \psi=\mathcal{N}(\psi)
$$

Due to the dispersion, when the nonlinearity vanishes at a sufficient order at 0 and the initial data is sufficiently small and localized, it is possible to prove that the solution is global and the integral $\int e^{-i s \Delta} \mathcal{N}(\psi(s)) d s$ converges in $L^{2}\left(\mathbb{R}^{d}\right)$, so that there exists $\psi_{+} \in L^{2}\left(\mathbb{R}^{d}\right)$ such that

$$
\left\|\psi(t)-e^{i t \Delta} \psi_{+}\right\|_{L^{2}} \longrightarrow_{t \rightarrow \infty} 0
$$

In this case, it is said that the solution is asymptotically linear, or scatters to $\psi_{+}$.
In the case where $\mathcal{N}$ is a general power-like non-linearity, we can cite the seminal work of Strauss [27]. More precisely if $\mathcal{N}(a)=O_{0}\left(|a|^{p}\right)$, global well-posedness for small data in $H^{1}$ is merely a consequence of Strichartz estimates provided $p$ is larger than the so-called Strauss exponent

$$
\begin{equation*}
p_{S}(d)=\frac{\sqrt{d^{2}+12 d+4}+d+2}{2 d} \tag{1.8}
\end{equation*}
$$

For example scattering for quadratic nonlinearities (indepently of their structure $\phi^{2}, \bar{\phi}^{2},|\phi|^{2} \ldots$ ) can be obtained for $d \geq 4$, indeed $p_{S}(3)=2$. The case $p \leq p_{S}$ is much harder and is discussed later.

Mixing energy estimates and dispersive estimates If $\mathcal{N}$ depends on derivatives of $\phi$, due to the loss of derivatives the situation is quite different and it is important to take more precisely into account the structure of the system. In particular it is possible in some case to exhibit energy estimates which often lead after a Gronwall lemma to the following situation:
$\forall N \in \mathbb{N},\|\phi(t)\|_{H^{N}} \leq\left\|\phi_{0}\right\|_{H^{N}} \exp \left(C_{N} \int_{0}^{t}\|\phi(s)\|_{W^{k, \infty}}^{p-1} d s\right), k$ "small" and independent on $N$.
A natural idea consists in mixing energy estimates in the $H^{N}$ norm, $N$ "large", with dispersive estimates : if one obtains

$$
\left\|\int_{0}^{t} e^{i(t-s) \Delta} \mathcal{N} d s\right\|_{W^{k, \infty}} \lesssim \frac{\|\psi\|_{H^{N} \cap W^{k, \infty}}^{p}}{t^{\alpha}}, \alpha(p-1)>1
$$

then setting $\|\psi\|_{X_{T}}=\sup _{[0, T]}\|\psi(t)\|_{H^{N}}+t^{\alpha}\|\psi(t)\|_{W^{k, \infty}}$ the energy estimate yields for small data

$$
\|\psi\|_{X_{T}} \lesssim\left\|\psi_{0}\right\|_{H^{N}} \exp \left(C\|\psi\|_{X}^{p-1}\right)+\|\psi\|_{X_{T}}^{p}+\varepsilon
$$

so that $\|\psi\|_{X_{T}}$ must remain small uniformly in $T$. This strategy seems to have been initiated independently by Klainerman and Ponce [24] and Shatah [25]. If the energy estimate is true, this method works "straightforwardly" and gives global well-posedness for small initial data (this is the approach from section 4) if

$$
\begin{equation*}
p>\widetilde{p}(d)=\frac{\sqrt{2 d+1}+d+1}{d}>p_{S}(d) \tag{1.9}
\end{equation*}
$$

Again, there is a critical dimension: $\widetilde{p}(4)=2$, thus any quadratic nonlinearity can be handled with this method if $d \geq 5$.

Normal forms, space-time resonances When $p \leq p_{S}$ (semi-linear case) or $\widetilde{p}$ (quasi-linear case), the strategies above can not be directly applied, and one has to look more closely at the structure of the nonlinearity. For the Schrödinger equation, one of the earliest result in this direction was due to Cohn [11] who proved (extending Shatah's method of normal forms [26]) the global well-posedness in dimension 2 of

$$
\begin{equation*}
i \partial_{t} \psi+\Delta \psi=i \nabla \bar{\psi} \cdot \nabla \bar{\psi} \tag{1.10}
\end{equation*}
$$

The by now standard strategy of proof was to use a normal form that transformed the quadratic nonlinearity into a cubic one, and since $3>\widetilde{p}(2) \simeq 2.6$ the new equation could be treated with the arguments from [24]. In dimension 3, similar results (with very different proofs using vector fields method and time non resonance) were then obtained for the nonlinearities $\psi^{2}$ and $\bar{\psi}^{2}$ by Hayashi, Nakao and Naumkin [23] (it is important to observe that the quadratic nonlinearity is critical in terms of Strauss exponent for the semi-linear case when $d=3$ ). The existence of global solutions for the nonlinearity $|\psi|^{2}$ is however still open (indeed it corresponds to a nonlinearity where the set of time and space non resonance is not empty, we will give more explanations below on this phenomenon).
More recently, Germain-Masmoudi-Shatah [16] [15] [14] and Gustafson-Nakanishi-Tsai [21] [22] shed a new light on such issues with the concept of space-time resonances. To describe it, let us rewrite the Duhamel formula for the profile of the solution $f=e^{-i t \Delta} \psi$, in the case 1.10 :
$f=\psi_{0}+\int_{0}^{t} e^{-i s \Delta} \mathcal{N}\left(e^{i s \Delta} \psi\right) d s \Leftrightarrow \widehat{f}=\widehat{\psi_{0}}+\int_{0}^{t} \int_{\mathbb{R}^{d}} e^{i s\left(|\xi|^{2}+|\eta|^{2}+|\xi-\eta|^{2}\right)} \eta \cdot(\xi-\eta) \widehat{\bar{f}}(\eta) \widehat{\bar{f}}(\xi-\eta) d \eta d s$
In order to take advantage of the non cancellation of $\Omega(\xi, \eta)=|\xi|^{2}+|\eta|^{2}+|\xi-\eta|^{2}$ one might integrate by part in time, and from the identity $\partial_{t} f=-i e^{-i t \Delta} \mathcal{N}(\psi)$, we see that this procedure effectively replaces the quadratic nonlinearity by a cubic one, ie acts as a normal form.
On the other hand, if $\mathcal{N}(\psi)=\psi^{2}$ the phase becomes $\Omega(\xi, \eta)=|\xi|^{2}-|\eta|^{2}-|\xi-\eta|^{2}$, which cancels on a large set, namely the "time resonant set"

$$
\begin{equation*}
\mathcal{T}=\{(\xi, \eta): \Omega(\xi, \eta)=0\}=\{\eta \perp \xi-\eta\} \tag{1.12}
\end{equation*}
$$

The remedy is to use an integration by part in the $\eta$ variable using $e^{i s \Omega}=\frac{\nabla_{\eta} \Omega}{i s\left|\nabla_{\eta} \Omega\right|^{2}} \nabla_{\eta}\left(e^{i s \Omega}\right)$, it does not improve the nonlinearity, however we can observe a gain of time decay in $1 / s$. This justifies to define the "space resonant set" as

$$
\begin{equation*}
\mathcal{S}=\left\{(\xi, \eta): \nabla_{\eta} \Omega(\xi, \eta)=0\right\}=\{\eta=-\xi-\eta\} \tag{1.13}
\end{equation*}
$$

as well as the space-time resonant set

$$
\begin{equation*}
\mathcal{R}=\mathcal{S} \cap \mathcal{T}=\left\{(\xi, \eta): \Omega(\xi, \eta)=0, \nabla_{\eta} \Omega(\xi, \eta)=0\right\} \tag{1.14}
\end{equation*}
$$

For $\mathcal{N}(\psi)=\psi^{2}$, we simply have $\mathcal{R}=\{\xi=\eta=0\}$; using the previous strategy Germain et al [16] obtained global well-posedness for the quadratic Schrödinger equation.
Finally, for $\mathcal{N}(\psi)=|\psi|^{2}$ similar computations lead to $\mathcal{R}=\{\xi=0\}$, the "large" size of this set might explain why this nonlinearity is particularly difficult to handle.

Smooth and non smooth multipliers The method of space-time resonances in the case $(\nabla \bar{\phi})^{2}$ is particularly simple because after the time integration by part, the Fourier transform of the nonlinearity simply becomes

$$
\frac{\eta \cdot(\xi-\eta)}{|\xi|^{2}+|\eta|^{2}+|\xi-\eta|^{2}} \partial_{s} \widehat{\bar{\psi}}(\eta) \widehat{\bar{\psi}}(\xi-\eta)
$$

where the multiplier $\frac{\eta \cdot(\xi-\eta)}{|\xi|^{2}+|\eta|^{2}+|\xi-\eta|^{2}}$ is of Coifman-Meyer type, thus in term of product laws it is just a cubic nonlinearity. We might naively observe that this is due to the fact that $\eta \cdot(\xi-\eta)$ cancels on the resonant set $\xi=\eta=0$. Thus one might wonder what happens in the general case if the nonlinearity writes as a bilinear Fourier multiplier whose symbol cancels on $\mathcal{R}$. In [14], the authors treated the nonlinear Schrödinger equation for $d=2$ by assuming that the nonlinearity is of type $B[\psi, \psi]$ or $B[\bar{\psi}, \bar{\psi}]$, with $B$ a bilinear Fourier multiplier whose symbol is linear at $|(\xi, \eta)| \leq 1$ (and thus cancels on $\mathcal{R}$ ). Concerning the Gross-Pitaevskii equation (1.3), the nonlinear terms include the worst one $|\psi|^{2}$ but Gustafson et al [22] managed to prove global existence and scattering in dimension 3 , one of the important ideas of their proof was a change of unknown $\psi \mapsto Z$ (or normal form) that replaced the nonlinearity $|\psi|^{2}$ by $\sqrt{-\Delta /(2-\Delta)}|Z|^{2}$ which compensates the resonances at $\xi=0$. To some extent, this is also a strategy that we will follow here.
Finally, let us point out that the method of space-time resonances proved remarkably efficient for the water wave equation [15] partially because the group velocity $|\xi|^{-1 / 2} / 2$ is large near $\xi=0$, while it might not be the most suited for the Schrödinger equation whose group velocity $2 \xi$ cancels at $\xi=0$. The method of vector fields is an interesting alternative, and this approach was later chosen by Germain et al in [17] to study the capillary water waves (in this case the group velocity is $\left.3|\xi|^{1 / 2} / 2\right)$. Nevertheless, in our case the term $\widetilde{g}\left(L_{c}\right)$ in 1.4 induces a lack of symetry which seems to limit the effectiveness of this approach.

Plan of the article In section 2 we introduce the notations and state our main results. Section 3 is devoted to the reformulation of (1.1) as a non degenerate Schrödinger equation, and
we derive the energy estimates in "high" Sobolev spaces. We use a modified energy compared with [6] in order to avoid some time growth of the norms. In section 4 we prove our main result in dimension at least 5 . Section 5 begins the analysis of dimensions 3 and 4, which is the heart of the paper. We only detail the case $d=3$ since $d=4$ follows the same ideas with simpler computations. We first introduce the functional settings, a normal form and check that it defines an invertible change of variable in these settings, then we bound the high order terms (at least cubic). In section 6 we use the method of space-time resonances (similarly to [22]) to bound quadratic terms and close the proof of global well-posedness in dimension 3. The appendix provides some technical multipliers estimtes required for section 6.

## 2 Main results, tools and notations

The results As pointed out in the introduction, we need a condition on the pressure.
Assumption 2.1. Throughout all the paper, we work near a constant state $\rho=\rho_{c}>0, u=0$, with $g^{\prime}\left(\rho_{c}\right)>0$.

In the case of the Euler equation, this standard condition implies that the linearized system

$$
\left\{\begin{array}{l}
\partial_{t} \rho+\rho_{c} \operatorname{div} u=0, \\
\partial_{t} u+g^{\prime}\left(\rho_{c}\right) \nabla \rho=0 .
\end{array}\right.
$$

is hyperbolic, with eigenvalues (sound speed) $\pm \sqrt{\rho_{c} g^{\prime}\left(\rho_{c}\right)}$.
Theorem 2.1. Let $d \geq 5, \rho_{c} \in \mathbb{R}^{+*}, u_{0}=\nabla \phi_{0}$ be irrotational. For $(n, k) \in \mathbb{N}, k>2+$ $d / 4,2 n+1 \geq k+2+d / 2$, there exists $\delta>0$, such that if

$$
\left\|u_{0}\right\|_{H^{2 n} \cap W^{k-1,4 / 3}}+\left\|\rho_{0}-\rho_{c}\right\|_{H^{2 n+1} \cap W^{k, 4 / 3}} \leq \delta
$$

then the unique solution of (1.1) is global with $\left\|\rho-\rho_{c}\right\|_{L^{\infty}\left(\mathbb{R}^{+} \times \mathbb{R}^{d}\right)} \leq \frac{\rho_{c}}{2}$.
Theorem 2.2. Let $d=3$ or 4 , $u=\nabla \phi_{0}$ irrotational, $k>2+d / 4$, there exists $\delta>0, \varepsilon>0$, small enough, $n \in \mathbb{N}$ large enough, such that for $\frac{1}{p}=\frac{1}{2}-\frac{1}{d}-\varepsilon$, if

$$
\left\|u_{0}\right\|_{H^{2 n}}+\left\|\rho_{0}-\rho_{c}\right\|_{H^{2 n+1}}+\left\|x u_{0}\right\|_{L^{2}}+\left\|x\left(\rho_{0}-\rho_{c}\right)\right\|_{L^{2}}+\left\|u_{0}\right\|_{W^{k-1, p^{\prime}}}+\left\|\rho_{0}-\rho_{c}\right\|_{W^{k, p^{\prime}}} \leq \delta,
$$

then the solution of (1.1) is global with $\left\|\rho-\rho_{c}\right\|_{L^{\infty}\left(\mathbb{R}^{+} \times \mathbb{R}^{d}\right)} \leq \frac{\rho_{c}}{2}$.
Remark 2.1. While the proof implies to work with the velocity potential, we only need assumptions on the physical variables velocity and density.
Remark 2.2. Actually we prove a stronger result: in the appropriate variables the solution scatters. Let $\mathcal{L}$ be the primitive of $\sqrt{K / \rho}$ such that $\mathcal{L}\left(\rho_{c}\right)=1, L=\mathcal{L}(\rho), \mathcal{H}=\sqrt{-\Delta\left(\widetilde{g}^{\prime}(1)-\Delta\right)}$, $\mathcal{U}=\sqrt{-\Delta /\left(\widetilde{g}^{\prime}(1)-\Delta\right)}, f=e^{-i t \mathcal{H}}(\mathcal{U} \phi+i L)$, then there exists $f_{\infty}$ such that

$$
\forall s<2 n+1,\left\|f(t)-f_{\infty}\right\|_{H^{s} \cap L^{2} /\langle x\rangle} \rightarrow_{t \rightarrow \infty} 0 .
$$

The analogous result is true in dimension $\geq 5$ with $t^{-d / 2+1}$ for the convergence rate in $L^{2}$. See section 6.4 for a discussion in dimension 3. It is also possible to quantify how large $n$ should be (at least of order 20, see remark 6.3). In both theorems, the size of $k$ and $n$ can be slightly decreased by working in fractional Sobolev spaces, but since it would remain quite large we chose to avoid these technicalities.

Some tools and notations Most of our tools are standard analysis, except a singular multiplier estimate.

Functional spaces The usual Lebesgue spaces are $L^{p}$ with norm $\|\cdot\|_{p}$, the Lorentz spaces are $L^{p, q}$. If $\mathbb{R}^{+}$corresponds to the time variable, and for $B$ a Banach space, we write for short $L^{p}\left(\mathbb{R}^{+}, B\right)=L_{t}^{p} B$, similarly $L^{p}([0, T], B)=L_{T}^{p} B$.
The Sobolev spaces are $W^{k, p}=\left\{u \in L^{p}: \forall|\alpha| \leq k, D^{\alpha} u \in L^{p}\right\}$. We also use homogeneous spaces $\dot{W}^{k, p}=\left\{u \in L_{l o c}^{1}: \forall|\alpha|=k, D^{\alpha} u \in L^{p}\right\}$. We recall the Sobolev embedding

$$
\forall k p<d, \dot{W}^{k, p}\left(\mathbb{R}^{d}\right) \hookrightarrow L^{q, p} \hookrightarrow L^{q}, q=\frac{d p}{d-k q}, \forall k p>d, W^{k, p}\left(\mathbb{R}^{d}\right) \hookrightarrow L^{\infty}
$$

If $p=2$, as usual $W^{k, 2}=H^{k}$, for which we have equivalent norm $\int_{\mathbb{R}^{d}}\left(1+|\xi|^{2}\right)^{k}|\widehat{u}|^{2} d \xi$, we define in the usual way $H^{s}$ for $s \in \mathbb{R}$ and $\dot{H}^{s}$ for which the embeddings remain true. The following dual estimate will be of particular use

$$
\forall d \geq 3,\|u\|_{\dot{H}^{-1}} \lesssim\|u\|_{L^{2 d /(d+2)}}
$$

We will use the following Gagliardo-Nirenberg type inequality (see for example [28])

$$
\begin{equation*}
\forall l \leq p \leq k-1 \text { integers },\left\|D^{l} u\right\|_{L^{2 k / p}} \lesssim\|u\|_{L^{2 k /(p-l)}}^{(k-p) /(k+l-p)}\left\|D^{k+l-p} u\right\|_{L^{2}}^{l /(k+l-p)} \tag{2.1}
\end{equation*}
$$

and its consequence

$$
\begin{equation*}
\forall|\alpha|+|\beta|=k,\left\|D^{\alpha} f D^{\beta} g\right\|_{L^{2}} \lesssim\|f\|_{\infty}\|g\|_{\dot{H}^{k}}+\|f\|_{\dot{H}^{k}}\|g\|_{\infty} \tag{2.2}
\end{equation*}
$$

Finally, we have the basic composition estimate (see [5]): for $F$ smooth, $F(0)=0, u \in$ $L^{\infty} \cap W^{k, p}$ then ${ }^{2}$

$$
\begin{equation*}
\left.\|F(v)\|_{W^{k, p}} \lesssim C\left(k,\|u\|_{\infty}\right)\right)\|u\|_{W^{k, p}} \tag{2.3}
\end{equation*}
$$

Non standard notations Since we will often estimate indistinctly $z$ or $\bar{z}$, we follow the notations introduced in [22]: $z^{+}=z, z^{-}=\bar{z}$, and $z^{ \pm}$is a placeholder for $z$ or $\bar{z}$. The Fourier transform of $z$ is as usual $\widehat{z}$, however we also need to consider the profile $e^{-i t H} z$, whose Fourier transform will be denoted $\widetilde{z^{ \pm}}:=e^{\mp i t H} \widehat{z^{ \pm}}$.
When there is no ambiguity, we write $W^{k, \frac{1}{p}}$ (or $L^{\frac{1}{p}}$ ) instead of $W^{k, p}$ (or $L^{p}$ ) since it is convenient to use Hölder's inequality.

[^2]Multiplier theorems We remind that the Riesz multiplier $\nabla /|\nabla|$ is bounded on $L^{p}, 1<$ $p<\infty$. A bilinear Fourier multiplier is defined by its symbol $B(\eta, \xi)$, it acts on $(f, g) \in \mathcal{S}\left(\mathbb{R}^{d}\right)$

$$
\widehat{B[f, g]}(\xi)=\int_{\mathbb{R}^{d}} B(\eta, \xi-\eta) \widehat{f}(\eta) \widehat{g}(\xi-\eta) d \eta
$$

Theorem 2.3 (Coifman-Meyer). If $\partial_{\xi}^{\alpha} \partial_{\eta}^{\beta} B(\xi, \eta) \lesssim(|\xi|+|\eta|)^{-|\alpha|-|\beta|}$, for sufficiently many $\alpha, \beta$ then for any $1<p, q \leq \infty, 1 / r=1 / p+1 / q$,

$$
\|B(f, g)\|_{r} \lesssim\|f\|_{p}\|g\|_{q} .
$$

If moreover $\operatorname{supp}(B(\eta, \xi-\eta)) \subset\{|\eta| \gtrsim|\xi-\eta|\},(p, q, r)$ are finite and $k \in \mathbb{N}$ then

$$
\left\|\nabla^{k} B(f, g)\right\|_{r} \lesssim\left\|\nabla^{k} f\right\|_{p}\|g\|_{q} .
$$

Mixing this result with the Sobolev embedding, we get for $2<p \leq \infty, \frac{1}{p}+\frac{1}{q}=\frac{1}{2}$

$$
\begin{equation*}
\|f g\|_{H^{s}} \lesssim\|f\|_{L^{p}}\|g\|_{H^{s, q}}+\|g\|_{L^{p}}\|f\|_{H^{s, q}} \lesssim\|f\|_{L^{p}}\|g\|_{H^{s+d / p}}+\|g\|_{L^{p}}\|f\|_{H^{s+d / p}} . \tag{2.4}
\end{equation*}
$$

Due to the limited regularity of our multipliers, we will need a multiplier theorem with loss from [19] (and inspired by corollary 10.3 from [22]). Let us first describe the norm on symbols: for $\chi_{j}$ a smooth dyadic partition of the space, $\operatorname{supp}\left(\chi_{j}\right) \subset\left\{2^{j-2} \leq|x| \leq 2^{j+2}\right\}$

$$
\|B(\eta, \xi-\eta)\|_{\tilde{L}_{\xi}^{\infty} \dot{B}_{2,1, \eta}^{s}}=\left\|2^{j s} \chi_{j}(\nabla)_{\eta} B(\eta, \xi-\eta)\right\|_{l^{1}\left(\mathbb{Z}, L_{\xi}^{\infty} L_{\eta}^{2}\right)}
$$

The norm $\|B(\xi-\zeta, \zeta)\|_{\tilde{L}_{\xi}^{\infty} \dot{B}_{2,1, \zeta}^{s}}$ is defined similarly. In practice, we rather estimate $\|B\|_{L_{\xi}^{\infty} \dot{H}^{s}}$ and use the interpolation estimate (see [22])

$$
\|B\|_{\tilde{L}_{\xi}^{\infty} \dot{B}_{2,1, \eta}^{s}} \lesssim\|B\|_{L_{\xi}^{\infty} \dot{H}^{s_{1}}}^{\theta}\|B\|_{L_{\xi}^{\infty} \dot{H}^{s_{2}}}^{1-\theta}, s=\theta s_{1}+(1-\theta) s_{2} .
$$

We set $\|B\|_{\left[B^{s}\right]}=\min \left(\|B(\eta, \xi-\eta)\|_{\tilde{L}_{\xi}^{\infty} \dot{B}_{2,1, \eta}^{s}},\|B(\xi-\zeta, \zeta)\|_{\tilde{L}_{\xi}^{\infty} \dot{B}_{2,1, \zeta}^{s}}\right)$. The rough multiplier theorem is the following:
Theorem 2.4 ([19). Let $0 \leq s \leq d / 2, q_{1}, q_{2}$ such that $\frac{1}{q_{2}}+\frac{1}{2}=\frac{1}{q_{1}}+\left(\frac{1}{2}-\frac{s}{d}\right){ }^{3}$. and $2 \leq q_{1}^{\prime}, q_{2} \leq \frac{2 d}{d-2 s}$, then

$$
\|B(f, g)\|_{L^{q_{1}}} \lesssim\|B\|_{\left[B^{s}\right]}\|f\|_{L^{q_{2}}}\|g\|_{L^{2}}
$$

Furthermore for $\frac{1}{q_{2}}+\frac{1}{q_{3}}=\frac{1}{q_{1}}+\left(\frac{1}{2}-\frac{s}{d}\right), 2 \leq q_{i} \leq \frac{2 d}{d-2 s}$ with $i=2,3$,

$$
\|B(f, g)\|_{L^{q_{1}}} \lesssim\|B\|_{\left[B^{s}\right]}\|f\|_{L^{q_{2}}}\|g\|_{L^{q_{3}}}
$$

[^3]Dispersion for the group $e^{-i t H}$ According to 1.4, the linear part of the equation reads $\partial_{t} z-i \mathcal{H} z=0$, with $\mathcal{H}=\sqrt{-\Delta\left(\widetilde{g}^{\prime}\left(L_{c}\right)-\Delta\right)}$ (see also section 4). We will use a change of variable to reduce it to $\widetilde{g}^{\prime}\left(L_{c}\right)=2$, set $H=\sqrt{-\Delta(2-\Delta)}$, and use the dispersive estimate from [20, the version in Lorentz spaces follows from real interpolation as pointed out in [22].
Theorem 2.5 ([20] [22]). For $2 \leq p \leq \infty, s \in \mathbb{R}, U=\sqrt{-\Delta /(2-\Delta)}$, we have

$$
\left\|e^{i t H} \varphi\right\|_{\dot{B}_{p, 2}^{s}} \lesssim \frac{\left\|U^{(d-2)(1 / 2-1 / p)} \varphi\right\|_{\dot{B}_{p^{\prime}, 2}^{s}}}{t^{d(1 / 2-1 / p)}}
$$

and for $2 \leq p<\infty$

$$
\left\|e^{i t H} \varphi\right\|_{L^{p, 2}} \lesssim \frac{\left\|U^{(d-2)(1 / 2-1 / p)} \varphi\right\|_{L^{p^{\prime}, 2}}}{t^{d(1 / 2-1 / p)}}
$$

Remark 2.3. The slight low frequency gain $U^{(d-2)(1 / 2-1 / p)}$ is due to the fact that $H(\xi)=$ $|\xi| \sqrt{2+|\xi|^{2}}$ behaves like $|\xi|$ at low frequencies, which has a strong angular curvature and no radial curvature.
Remark 2.4. Combining the dispersion estimate and the celebrated $T T^{*}$ argument, Strichartz estimates follow

$$
\left\|e^{i t H} \varphi\right\|_{L^{p} L^{q}} \lesssim\left\|U^{\frac{d-2}{2}(1 / 2-1 / p)} \varphi\right\|_{L^{2}}, \frac{2}{p}+\frac{d}{q}=\frac{d}{2}, 2 \leq p \leq \infty
$$

however the dispersion estimates are sufficient for our purpose.

## 3 Reformulation of the equations and energy estimate

As observed in [6], setting $w=\sqrt{K / \rho} \nabla \rho, \mathcal{L}$ the primitive of $\sqrt{K / \rho}$ such that $\mathcal{L}\left(\rho_{c}\right)=1$, $L=\mathcal{L}(\rho), z=u+i w$ the Euler-Korteweg system rewrites

$$
\begin{aligned}
\partial_{t} L+u \cdot \nabla L+a(L) \operatorname{div} u & =0, \\
\partial_{t} u+u \cdot \nabla u-w \cdot \nabla w-\nabla(a(L) \operatorname{div} w) & =-\widetilde{g}^{\prime}(L) w, \\
\partial_{t} w+\nabla(u \cdot w)+\nabla(a(L) \operatorname{div} u) & =0,
\end{aligned}
$$

where the third equation is just the gradient of the first. Setting $l=L-1$, in the potential case $u=\nabla \phi$, the system on $\phi, l$ then reads

$$
\left\{\begin{array}{l}
\partial_{t} \phi+\frac{1}{2}\left(|\nabla \phi|^{2}-|\nabla l|^{2}\right)-a(1+l) \Delta l=-\widetilde{g}(1+l)  \tag{3.1}\\
\partial_{t} l+\nabla \phi \cdot \nabla l+a(1+l) \Delta \phi=0
\end{array}\right.
$$

with $\widetilde{g}(1)=0$ since we look for integrable functions. As a consequence of the stability condition (2.1), up to a change of variables we can and will assume through the rest of the paper that

$$
\begin{equation*}
\tilde{g}^{\prime}(1)=2 . \tag{3.2}
\end{equation*}
$$

The number 2 has no significance except that this choice gives the same linear part as for the Gross-Pitaevskii equation linearized near the constant state 1.

Proposition 3.1. Under the following assumptions

- $\left(\nabla \phi_{0}, l\right) \in H^{2 n} \times H^{2 n+1}$
- Normalized (2.1): $\tilde{g}^{\prime}(1)=2$
- $L(x, t)=1+l(x, t) \geq m>0$ for $(x, t) \in \mathbb{R}^{d} \times[0, T]$,
then for $n>d / 4+1 / 2$, there exists a continuous function $C$ such that the solution of (3.1) satisfies the following estimate

$$
\left.\left.\begin{array}{l}
\|\nabla \phi\|_{H^{2 n}}+\|l\|_{H^{2 n+1}} \\
\leq\left(\left\|\nabla \phi_{0}\right\|_{H^{2 n}}+\left\|l_{0}\right\|_{H^{2 n+1}}\right) \exp \left(\int _ { 0 } ^ { \mathrm { t } } \mathrm { C } \left(\|l\|_{\mathrm{L}^{\infty}},\right.\right.
\end{array} \quad\left\|\frac{1}{\mathrm{l}+1}\right\|_{\mathrm{L}^{\infty}},\|\mathrm{z}\|_{\mathrm{L}^{\infty}}\right)\right] \text {. } \begin{aligned}
\left.\leq\left(\|\nabla \phi(s)\|_{W^{1, \infty}}+\|l(s)\|_{W^{2, \infty}}\right) d s\right)
\end{aligned}
$$

where $z(s)=\nabla \phi(s)+i \nabla w(s)$.
This is almost the same estimate as in [6] but for an essential point: in the integrand of the right hand side there is no constant added to $\|\nabla \phi(s)\|_{W^{1, \infty}}+\|l(s)\|_{W^{2, \infty}}$, the price to pay is that we can not control $\phi$ but its gradient (this is naturel since the difficulty is related to the low frequencies). Before going into the detail of the computations, let us underline on a very simple example the idea behind it. We consider the linearized system

$$
\begin{array}{r}
\partial_{t} \phi-\Delta l+2 l=0 \\
\partial_{t} l+\Delta \phi=0 \tag{3.4}
\end{array}
$$

Multiplying (3.3) by $\phi$, (3.4) by $l$, integrating and using Young's inequality leads to the "bad" estimate

$$
\frac{d}{d t}\left(\|\phi\|_{L^{2}}^{2}+\|l\|_{L^{2}}^{2}\right) \lesssim 2\left(\|\phi\|_{L^{2}}^{2}+\|l\|_{L^{2}}^{2}\right)
$$

on the other hand if we multiply $(3.3)$ by $-\Delta \phi,(3.4)$ by $(-\Delta+2) l$ we get

$$
\frac{d}{d t} \int_{\mathbb{R}^{d}}\left(\frac{|\nabla l|^{2}+|\nabla \phi|^{2}}{2}+l^{2}\right) d x=0
$$

the proof that follows simply mixes this observation with the gauge method from [6].
Proof. Let us start with the equation on $z=\nabla \phi+i \nabla l=u+i w$, we remind that $\widetilde{g}^{\prime}(1)=2$, so that we write it

$$
\begin{equation*}
\partial_{t} z+z \cdot \nabla z+i \nabla(a \operatorname{div} z)=-2 w+\left(2-\tilde{g}^{\prime}(1+l)\right) w \tag{3.5}
\end{equation*}
$$

We shortly recall the method from [6] that we will slightly simplify since we do not need to work in fractional Sobolev spaces. Due to the quasi-linear nature of the system (and in particular the bad "non transport term" $i w \cdot \nabla z$ ), it is not possible to directly estimate $\|z\|_{H^{2 n}}$ by energy
estimates, instead one uses a gauge function $\varphi_{n}(\rho)$ and control $\left\|\varphi_{n} \Delta^{n} z\right\|_{L^{2}}$. When we take the product of 3.5 with $\varphi_{n}$ real, a number of commutators appear:

$$
\begin{gather*}
\varphi_{n} \Delta^{n} \partial_{t} z=\partial_{t}\left(\varphi_{n} \Delta^{n} z\right)-\left(\partial_{t} \varphi_{n}\right) \Delta^{n} z=\partial_{t}\left(\varphi_{n} \Delta^{n} z\right)+C_{1}  \tag{3.6}\\
\varphi_{n} \Delta^{n}(u \cdot \nabla z)=u \cdot \nabla\left(\varphi_{n} \Delta^{n} z\right)+\left[\varphi_{n} \Delta^{n}, u \cdot \nabla\right] z:=u \cdot \nabla\left(\varphi_{n} \Delta^{n} z\right)+C_{2}  \tag{3.7}\\
i \varphi_{n} \Delta^{n}(w \cdot \nabla z)=i w \cdot \nabla\left(\varphi_{n} \Delta^{n} z\right)+\left[\varphi_{n} \Delta^{n}, w \cdot \nabla\right] z:=i w \cdot \nabla\left(\varphi_{n} \Delta^{n} z\right)+C_{3} \tag{3.8}
\end{gather*}
$$

The term $\nabla(a \operatorname{div} z)$ requires a bit more computations:

$$
i \varphi_{n} \Delta^{n} \nabla(a \operatorname{div} z)=i \nabla\left(\varphi_{n} \Delta^{n}(a \operatorname{div} z)\right)-i\left(\nabla \varphi_{n}\right) \Delta^{n}(a \operatorname{div} z)
$$

then using recursively $\Delta(f g)=2 \nabla f \cdot \nabla g+f \Delta g+(\Delta f) g$ we get

$$
\Delta^{n}(a \operatorname{div} z)=a \operatorname{div} \Delta^{n} z+2 n(\nabla a) \cdot \Delta^{n} z+C
$$

where $C$ contains derivatives of $z$ of order at most $2 n-1$, so that

$$
\begin{align*}
i \varphi_{n} \Delta^{n} \nabla(a \operatorname{div} z)= & i \nabla\left(\varphi_{n}\left(a \operatorname{div} \Delta^{n} z+2 n(\nabla a) \cdot \Delta^{n} z\right)\right)-i \nabla \varphi_{n} a \operatorname{div} \Delta^{n} z+i \nabla\left(\varphi_{n} C\right) \\
= & i \nabla\left(a \operatorname{div}\left(\varphi_{n} \Delta^{n} z\right)\right)+2 i n \nabla a \cdot \varphi_{n} \nabla \Delta^{n} z-i a\left(\nabla+I_{d} \operatorname{div}\right) \Delta^{n} z \cdot \nabla \varphi_{n} \\
& +C_{4} \tag{3.9}
\end{align*}
$$

where $C_{4}$ contains derivatives of $z$ of order at most $2 n$ and by notation $I_{d} \operatorname{div} \Delta^{n} z \cdot \nabla \varphi_{n}=$ $\operatorname{div} \Delta^{n} z \nabla \varphi_{n}$. Finally, we define $C_{5}=-\varphi_{n} \Delta^{n}\left(\left(2-\widetilde{g}^{\prime}(1+l)\right) w\right)$. The equation on $\varphi_{n} \Delta^{n} z$ thus reads

$$
\begin{align*}
\partial_{t}\left(\varphi_{n} \Delta^{n} z\right)+u \cdot \nabla\left(\varphi_{n} \Delta^{n} z\right) & +i \nabla\left(a \operatorname{div}\left(\varphi_{n} \Delta^{n} z\right)\right)+i w u \cdot \nabla\left(\varphi_{n} \Delta^{n} z\right)+2 \varphi_{n} \Delta^{n} w=  \tag{3.10}\\
& -\sum_{1}^{5} C_{k}-2 i n \varphi_{n} \nabla \Delta^{n} z \cdot \nabla a+i a\left(\nabla+I_{d} \operatorname{div}\right) \Delta^{n} z \cdot \nabla \varphi_{n} \tag{3.11}
\end{align*}
$$

Taking the scalar product with $\varphi_{n} \Delta^{n} z$, integrating and taking the real part gives for the first three terms

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t} \int_{\mathbb{R}^{d}}\left(\varphi_{n} \Delta^{n} z\right)^{2} d x-\frac{1}{2} \int_{\mathbb{R}^{d}} \operatorname{div} u\left|\varphi_{n} \Delta^{n} z\right|^{2} d x \tag{3.12}
\end{equation*}
$$

And we are left to control the remainder terms from 3.8, 3.9. Using $w=\frac{a}{\rho} \nabla \rho, \varphi_{n}=\varphi_{n}(\rho)$, we rewrite

$$
\begin{align*}
& i \varphi_{n} w \cdot \nabla\left(\Delta^{n} z\right)+ 2 n i \varphi_{n} \nabla\left(\Delta^{n} z\right) \cdot \nabla a-i a \nabla\left(\Delta^{n} z\right) \cdot \nabla \varphi_{n}-i a \nabla \varphi_{n} \operatorname{div} \Delta^{n} z \\
&=i \varphi_{n}\left(w \cdot \nabla-\frac{a \nabla \varphi_{n}}{\varphi_{n}} \cdot \nabla-\frac{a \nabla \varphi_{n}}{\varphi_{n}} \operatorname{div}+2 n \nabla a \cdot \nabla\right) \Delta^{n} z \\
&=i \varphi_{n}\left[\left(\frac{a}{\rho}-a \frac{\varphi_{n}^{\prime}}{\varphi_{n}}\right) \nabla \rho \cdot \nabla-\frac{a \varphi_{n}^{\prime}}{\varphi_{n}} \nabla \rho \operatorname{div}+2 n a^{\prime} \nabla \rho \cdot \nabla\right] \Delta^{n} z \tag{3.13}
\end{align*}
$$

If the div operator was a gradient, the most natural choice for $\varphi_{n}$ would be to take

$$
\frac{a}{\rho}-\frac{2 a \varphi_{n}^{\prime}}{\varphi_{n}}+2 n a^{\prime}=0 \Leftrightarrow \frac{\varphi_{n}^{\prime}}{\varphi_{n}}=\frac{1}{2 \rho}+\frac{n a^{\prime}}{a} \Leftarrow \varphi_{n}(\rho)=a^{n}(\rho) \sqrt{\rho}
$$

For this choice the remainder (3.13) rewrites

$$
\left[\left(\frac{a}{\rho}-a \frac{\varphi_{n}^{\prime}}{\varphi_{n}}\right) \nabla \rho \cdot \nabla-\frac{a \varphi_{n}^{\prime}}{\varphi_{n}} \nabla \rho \operatorname{div}+2 n a^{\prime} \nabla \rho \cdot \nabla\right] \Delta^{n} z=\left(\frac{a}{2 \rho}+n a^{\prime}\right) \nabla \rho \cdot\left(\nabla-I_{d} \operatorname{div}\right) \Delta^{n} z
$$

Using the fact that $\varphi_{n}\left(a /(2 \rho)+n a^{\prime}\right)(\rho) \nabla \rho$ is a real valued gradient, and setting $z_{n}=\Delta^{n} z$, we see that the contribution of 3.13 in the energy estimate is actually 0 from the following identity (with the Hessian Hess $H$ ):

$$
\begin{aligned}
\operatorname{Im} \int_{\mathbb{R}^{d}} \overline{z_{n}} \cdot\left(\nabla-I_{d} \operatorname{div}\right) z_{n} \cdot \nabla H(\rho) d x & =\operatorname{Im} \int_{\mathbb{R}^{d}} \overline{z_{i, n}} \partial_{j} z_{i, n} \partial_{j} H-\overline{z_{i, n}} \partial_{j} z_{j, n} \partial_{i} H \\
& =\operatorname{Im} \int_{\mathbb{R}^{d}}^{\overline{z_{n}}} \overline{H e s s} H z_{n}-\Delta H\left|z_{n}\right|^{2} \\
& =0 . \quad-\partial_{j} H z_{i, n}\left(\overline{\partial_{j} z_{i, n}}-\overline{\partial_{i} z_{j, n}}\right) d x
\end{aligned}
$$

We have used the fact that $z$ is irrotationnal. Finally, we have obtained

$$
\begin{equation*}
\frac{1}{2} \frac{d}{d t} \int\left\|\varphi_{n} \Delta^{n} z\right\|_{L^{2}}^{2} d x-\frac{1}{2} \int_{\mathbb{R}^{d}}(\operatorname{div} u)\left|\varphi_{n} \Delta^{n} z\right|^{2}=-\int \sum_{1}^{5} C_{k} \varphi_{n} \Delta^{n} \bar{z} d x-2 \int \varphi_{n}^{2} \Delta^{n} w \Delta^{n} u d x \tag{3.14}
\end{equation*}
$$

Note that the terms $C_{k} \varphi_{n} \Delta^{n} z$ are cubic while $\varphi_{n} \Delta^{n} w \Delta^{n} u$ is only quadratic, thus we will simply bound the first ones while we will need to cancel the later.

Control of the $C_{k}$ : From their definition, it is easily seen that the $\left(C_{k}\right)_{2 \leq i \leq 4}$ only contain terms of the kind $\partial^{\alpha} f \partial^{\beta} g$ with $f, g=u$ or $w,|\alpha|+|\beta| \leq 2 n$, thus

$$
\forall 2 \leq k \leq 4,\left|\int C_{k} \varphi_{n} \Delta^{n} z d x\right| \lesssim \sum_{|\alpha|+|\beta|=2 n, f, g=u \text { or } w}\left\|\partial^{\alpha} f \partial^{\beta} g\right\|_{L^{2}}\|z\|_{H^{2 n}}
$$

When $|\alpha|=0,|\beta|=2 n$, we have obviously $\left\|f \partial^{\beta} g\right\|_{L^{2}} \lesssim\|f\|_{\infty}\|g\|_{H^{2 n}}$, while the general case $\left\|\partial^{\alpha} f \partial^{\beta} g\right\|_{2} \lesssim\|f\|_{\infty}\|g\|_{H^{2 n}}+\|g\|_{\infty}\|f\|_{H^{2 n}}$ is Gagliardo-Nirenberg'interpolation inequality (2.2). We deduce

$$
\forall 2 \leq k \leq 4,\left|\int C_{k} \varphi_{n} \Delta^{n} z d x\right| \lesssim\|z\|_{\infty}\|z\|_{H^{2 n}}^{2}
$$

Let us deal now with $C_{1}=-\partial_{t} \varphi_{n} \Delta^{n} z$, since $\partial_{t} \varphi_{n}=-\varphi_{n}^{\prime} \operatorname{div}(\rho u)$ we have

$$
\left|\int_{\mathbb{R}^{d}} C_{1} \varphi_{n} \Delta^{n} \bar{z} d x\right| \lesssim F\left(\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\left(\|u\|_{W^{1, \infty}}+\|z\|_{L^{\infty}}^{2}\right)\|z\|_{H^{2 n}}^{2}\right.
$$

with $F$ a continuous function.
We now estimate the contribution of $C_{5}=-\varphi_{n} \Delta^{n}\left(\left(2-\widetilde{g}^{\prime}(1+l)\right) w\right)$ : since $\widetilde{g}^{\prime}(1)=2$, from the composition rule 2.3) we have $\left\|\widetilde{g}^{\prime}(1+l)-2\right\|_{H^{2 n}} \lesssim F_{1}\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\|l\|_{H^{2 n}}$ with $F_{1}$ a continuous function with $F_{1}(0, \cdot)=0$ so that

$$
\begin{array}{r}
\left|\int_{\mathbb{R}^{d}} C_{5} \varphi_{n} \Delta^{n} \bar{z} d x\right| \lesssim\left\|\left(2-\widetilde{g}^{\prime}\right) w\right\|_{H^{2 n}}\|z\|_{H^{2 n}} \lesssim\left(\left\|\left(2-\widetilde{g}^{\prime}(1+l)\right)\right\|_{L^{\infty}}\|z\|_{H^{2 n}}\right. \\
\left.+F_{1}\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\|l\|_{H^{2 n}}\|z\|_{\infty}\right)\|z\|_{H^{2 n}}
\end{array}
$$

To summarize, for any $1 \leq k \leq 5$, we have

$$
\begin{equation*}
\left|\int_{\mathbb{R}^{d}} C_{k} \varphi_{n} \Delta^{n} z d x\right| \lesssim F_{2}\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\left(\|l\|_{\infty}+\|z\|_{W^{1, \infty}}+\|z\|_{L^{\infty}}^{2}\right)\left(\|l l\|_{H^{2 n}}^{2}+\|z\|_{H^{2 n}}^{2}\right), \tag{3.15}
\end{equation*}
$$

with $F_{2}$ a continuous function.
Cancellation of the quadratic term We start with the equation on $l$ to which we apply $\varphi_{n} \Delta^{n}$, multiply by $\varphi_{n}\left(\Delta^{n} l\right) / a$ and integrate in space

$$
\int_{\mathbb{R}^{d}} \frac{\varphi_{n}^{2}}{a} \Delta^{n} l \partial_{t} \Delta^{n} l+\frac{\varphi_{n}^{2}}{a}\left(\Delta^{n} l\right) \Delta^{n}(\nabla \phi \cdot \nabla l)+\varphi_{n}^{2} \Delta^{n} l \frac{\Delta^{n}(a \Delta \phi)}{a}=0 .
$$

Commuting $\Delta^{n}$ and $a$, and using an integration by part, this rewrites

$$
\begin{aligned}
& \frac{1}{2} \frac{d}{d t} \int_{\mathbb{R}^{d}} \frac{\varphi_{n}^{2}}{a}\left(\Delta^{n} l\right)^{2} d x-\int_{\mathbb{R}^{d}} \frac{d}{d t}\left(\frac{\varphi_{n}^{2}}{2 a}\right)\left|\Delta^{n} l\right|^{2} d x+\int_{\mathbb{R}^{d}} \frac{\varphi_{n}^{2}}{a}\left(\Delta^{n} l\right) \Delta^{n}(\nabla \phi \cdot \nabla l) \\
& +\int_{\mathbb{R}^{d}} \varphi_{n}^{2} \Delta^{n} l \Delta \Delta^{n} \phi d x+\frac{\varphi_{n}^{2}}{a} \Delta^{n} l\left[\Delta^{n}, a\right] \Delta \phi d x \\
& \frac{1}{2} \frac{d}{d t} \int_{\mathbb{R}^{d}} \frac{\varphi_{n}^{2}}{a}\left(\Delta^{n} l\right)^{2} d x-\int_{\mathbb{R}^{d}} \frac{d}{d t}\left(\frac{\varphi_{n}^{2}}{2 a}\right)\left|\Delta^{n} l\right|^{2} d x+\int_{\mathbb{R}^{d}} \frac{\varphi_{n}^{2}}{a}\left(\Delta^{n} l\right) \Delta^{n}(\nabla \phi \cdot \nabla l) \\
& -\int_{\mathbb{R}^{d}} \varphi_{n}^{2} \nabla \Delta^{n} l \cdot \nabla \Delta^{n} \phi d x-\int_{\mathbb{R}^{d}} \Delta^{n} l \nabla \varphi_{n}^{2} \cdot \nabla \Delta^{n} \phi d x+\frac{\varphi_{n}^{2}}{a} \Delta^{n} l\left[\Delta^{n}, a\right] \Delta \phi d x
\end{aligned}
$$

We remark that the integrand in the right hand side only depends on $l, \nabla \phi$ and their derivatives, therefore using the same commutator arguments as previously, we get the bound

$$
\begin{align*}
\frac{1}{2} \frac{d}{d t} \int_{\mathbb{R}^{d}} \frac{\varphi_{n}^{2}}{a} & \left(\Delta^{n} l\right)^{2} d x-\int_{\mathbb{R}^{d}} \varphi_{n}^{2}\left(\Delta^{n} \nabla \phi\right) \Delta^{n} \nabla l d x  \tag{3.16}\\
& \lesssim F_{3}\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\left(\|l\|_{\infty}+\|z\|_{W^{1, \infty}}+\|z\|_{L^{\infty}}^{2}\right)\left(\|l\|_{H^{2 n}}^{2}+\|z\|_{H^{2 n}}^{2}\right)
\end{align*}
$$

with $F_{3}$ a continuous function. Now if we add (3.14) to $2 \times(3.16$ and use the estimates on $\left(C_{k}\right)$ we obtain

$$
\begin{aligned}
& \frac{1}{2} \frac{d}{d t} \int\left\|\varphi_{n} \Delta^{n} z\right\|_{L^{2}}^{2}+\left\|\Delta^{n} l\right\|_{L^{2}}^{2} d x \\
& \quad \lesssim F_{4}\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\left(\|l\|_{\infty}+\|z\|_{W^{1, \infty}}+\|z\|_{L^{\infty}}^{2}\right)\left(\|l\|_{H^{2 n}}^{2}+\|z\|_{H^{2 n}}^{2}\right)
\end{aligned}
$$

with $F_{4}$ a continuous function. The conclusion then follows from Gronwall's lemma.

## 4 Global well-posedness in dimension larger than 4

We first make a further reduction of the equations that will be also used for the cases $d=3,4$, namely we rewrite it as a linear Schrödinger equation with some remainder. In addition to $\widetilde{g}^{\prime}(1)=2$, we can also assume $a(1)=1$, so that (3.1) rewrites ${ }^{4}$

$$
\left\{\begin{array}{l}
\partial_{t} \phi-\Delta l+2 l=(a(1+l)-1) \Delta l-\frac{1}{2}\left(|\nabla \phi|^{2}-|\nabla l|^{2}\right)+(2 l-\widetilde{g}(1+l)),  \tag{4.1}\\
\partial_{t} l+\Delta \phi=-\nabla \phi \cdot \nabla l+(1-a(1+l)) \Delta \phi .
\end{array}\right.
$$

The linear part precisely corresponds to the linear part of the Gross-Pitaevskii equation. In order to diagonalize it, following [20] we set

$$
U=\sqrt{\frac{-\Delta}{2-\Delta}}, H=\sqrt{-\Delta(2-\Delta)}, \phi_{1}=U \phi, l_{1}=l .
$$

The equation writes in the new variables

$$
\left\{\begin{array}{l}
\partial_{t} \phi_{1}+H l_{1}=U\left(\left(a\left(1+l_{1}\right)-1\right) \Delta l_{1}-\frac{1}{2}\left(\left|\nabla U^{-1} \phi_{1}\right|^{2}-\left|\nabla l_{1}\right|^{2}\right)+\left(2 l_{1}-\widetilde{g}\left(1+l_{1}\right)\right)\right),  \tag{4.2}\\
\partial_{t} l_{1}-H \phi_{1}=-\nabla U^{-1} \phi_{1} \cdot \nabla l_{1}-\left(1-a\left(1+l_{1}\right)\right) H U^{-1} \phi_{1} .
\end{array}\right.
$$

More precisely, if we set $\psi=\phi_{1}+i l_{1}, \psi_{0}=\left.(U \phi+i l)\right|_{t=0}$, the Duhamel formula gives

$$
\begin{align*}
\psi(t)= & e^{i t H} \psi_{0}+\int_{0}^{t} e^{i(t-s) H} \mathcal{N}(\psi(s)) d s  \tag{4.3}\\
\text { with } \mathcal{N}(\psi)= & U\left(\left(a\left(1+l_{1}\right)-1\right) \Delta l_{1}-\frac{1}{2}\left(\left|\nabla U^{-1} \phi_{1}\right|^{2}-\left|\nabla l_{1}\right|^{2}\right)+\left(2 l_{1}-\widetilde{g}\left(1+l_{1}\right)\right)\right) \\
& +i\left(-\nabla U^{-1} \phi_{1} \cdot \nabla l_{1}-\left(1-a\left(1+l_{1}\right)\right) H \phi\right) \tag{4.4}
\end{align*}
$$

We underline that for low frequencies the situation is more favorable than for the GrossPitaevskii equation, as all the terms where $U^{-1}$ appears already contain derivatives that compensate this singular multiplier. Note however that the Gross-Pitaevskii equations are formally equivalent to this system via the Madelung transform in the special case $K(\rho)=\kappa / \rho$, so our computations are a new way of seeing that these singularities can be removed in appropriate variables. Let us now state the key estimate:
Proposition 4.1. Let $d \geq 5, T>0, k \geq 2, N \geq k+2+d / 2$, we set $\|\psi\|_{X_{T}}=\|\psi\|_{L^{\infty}\left([0, T], H^{N}\right)}+$ $\sup _{t \in[0, T]}(1+t)^{d / 4}\|\psi(t)\|_{W^{k, 4}}$, then the solution of 4.3 satisfies

$$
\forall t \in[0, T],\|\psi(t)\|_{W^{k, 4}} \lesssim \frac{\left\|\psi_{0}\right\|_{W^{k, 4 / 3}}+\left\|\psi_{0}\right\|_{H^{N}}+G\left(\|\psi\|_{X_{t}},\left\|_{1+l_{1}}^{1+l_{1}}\right\|_{L_{t}^{\infty}\left(L^{\infty}\right)}\right)\|\psi\|_{X_{T}}^{2}}{(1+t)^{d / 4}},
$$

with $G$ a continuous function.

[^4]Proof. We start with 4.3. From the dispersion estimate (2.5) and the Sobolev embedding, we have for any $t \geq 0$
$(1+t)^{d / 4}\left\|e^{i t H} \psi_{0}\right\|_{W^{2,4}} \lesssim(1+t)^{d / 4} \min \left(\frac{\left\|U^{(d-2) / 4} \psi_{0}\right\|_{W^{2,4 / 3}}}{t^{d / 4}},\left\|\psi_{0}\right\|_{H^{N}}\right) \lesssim\left\|\psi_{0}\right\|_{W^{2,4 / 3}}+\left\|\psi_{0}\right\|_{H^{N}}$.
The only issue is thus to bound the nonlinear part. Let $f, g$ be a placeholder for $l_{1}$ or $U^{-1} \phi_{1}$, there are several kind of terms : $\nabla f \cdot \nabla g,\left(a\left(1+l_{1}\right)-1\right) \Delta f, 2 l_{1}-\widetilde{g}\left(1+l_{1}\right),|\nabla f|^{2},|\nabla g|^{2}$, $\left(a\left(1+l_{1}\right)-1\right) H g$. The estimates for $0 \leq t \leq 1$ are easy (it corresponds to the existence of strong solution in finite time), so we assume $t \geq 1$ and we split the integral from (4.3) between $[0, t-1]$ and $[t-1, t]$. For the first kind we have from the dispersion estimate and (2.4):

$$
\begin{aligned}
\left\|\int_{0}^{t-1} e^{i(t-s) H} \nabla f \cdot \nabla g d s\right\|_{W^{k, 4}} & \lesssim \int_{0}^{t-1} \frac{\|\nabla f \cdot \nabla g\|_{W^{k, 4 / 3}}}{(t-s)^{d / 4}} d s \\
& \lesssim \int_{0}^{t-1} \frac{\|\nabla f\|_{H^{k}}\|\nabla g\|_{W^{k-1,4}}}{(t-s)^{d / 4}} d s \\
& \lesssim\|\psi\|_{X_{t}}^{2} \int_{0}^{t-1} \frac{1}{(t-s)^{d / 4}(1+s)^{d / 4}} d s \\
& \lesssim \frac{\|\psi\|_{X_{t}}^{2}}{t^{d / 4}} .
\end{aligned}
$$

(actually we should also add on the numerator $\|\nabla f\|_{W^{k-1,4}}\|\nabla g\|_{H^{k}}$, but since $f, g$ are symmetric placeholders we omit this term). We have used the fact that $\nabla U^{-1}$ is bounded on $W^{1, p} \rightarrow L^{p}, 1<p<\infty$ so that $\|\nabla f(s)\|_{H^{k}} \lesssim\|f\|_{X_{t}}$ for $s \in[0, t],(1+s)^{d / 4}\|\nabla g\|_{W^{k-1,4}} \lesssim\|g\|_{X_{t}}$. For the second part on $[t-1, t]$ we use the Sobolev embedding $H^{d / 4} \hookrightarrow L^{4}$ and (2.4):

$$
\begin{aligned}
\left\|\int_{t-1}^{t} e^{i(t-s) H}(\nabla f \cdot \nabla g) d s\right\|_{W^{k, 4}} \lesssim \int_{t-1}^{t}\|\nabla f \cdot \nabla g\|_{H^{k+d / 4}} d s & \lesssim \int_{t-1}^{t}\|\nabla f\|_{L^{4}}\|\nabla g\|_{H^{k+d / 2}} d s \\
& \lesssim\|\psi\|_{X_{t}}^{2} \int_{t-1}^{t} \frac{1}{(1+s)^{\frac{d}{4}}} d s \\
& \lesssim \frac{\|\psi\|_{X_{t}}^{2}}{(1+t)^{d / 4}} .
\end{aligned}
$$

The terms of the kind $\left(a\left(1+l_{1}\right)-1\right) \Delta f$ are estimated similarly: splitting the integral over $[0, t-1]$ and $[t-1, t]$,

$$
\begin{aligned}
\left\|\int_{0}^{t-1} e^{i(t-s) H}\left(a\left(1+l_{1}\right)-1\right) \Delta f d s\right\|_{W^{k, 4}} & \lesssim \int_{0}^{t-1} \frac{\left\|a\left(1+l_{1}\right)-1\right\|_{W^{k, 4}}\|\Delta f\|_{H^{k}}}{(t-s)^{d / 4}} d s \\
& \lesssim \int_{0}^{t-1} \frac{\left\|a\left(1+l_{1}\right)-1\right\|_{W^{k, 4}}\|\nabla f\|_{H^{k+1}}}{(t-s)^{d / 4}} d s
\end{aligned}
$$

As for the first kind terms, from the composition estimate we deduce that:

$$
\left\|a\left(1+l_{1}\right)-1\right\|_{W^{k, 4}} \lesssim F\left(\left\|l_{1}\right\|_{L_{t}^{\infty}\left(L^{\infty}\right)},\left\|\frac{1}{1+l_{1}}\right\|_{L_{t}^{\infty}\left(L^{\infty}\right)}\right)\left\|l_{1}\right\|_{W^{k, 4}},
$$

with $F$ continuous, we can bound the integral above by $F\left(\|\psi\|_{X_{t}},\left\|\frac{1}{1+l_{1}}\right\|_{L_{t}^{\infty}\left(L^{\infty}\right)}\right)\|\psi\|_{X}^{2} / t^{5 / 4}$. For the integral over $[t-1, t]$ we can again do the same computations using the composition estimates $\left\|a\left(1+l_{1}\right)-1\right\|_{H^{k+d / 2}} \lesssim F_{1}\left(\left\|l_{1}\right\|_{L_{t}^{\infty}\left(L^{\infty}\right)},\left\|\frac{1}{1+l_{1}}\right\|_{L_{t}^{\infty}\left(L^{\infty}\right)}\right)\left\|l_{1}\right\|_{H^{k+d / 2}}$ with $F_{1}$ continuous. The restriction $N \geq k+2+d / 2$ comes from the fact that we need $\|\Delta f\|_{H^{k+d / 2}} \lesssim\|f\|_{X}$.
Writing $2 l_{1}-\widetilde{g}\left(1+l_{1}\right)=l_{1}\left(2-\widetilde{g}\left(l_{1}\right) / l_{1}\right)$ we see that the estimate for the last term is the same as for $\left(a\left(1+l_{1}\right)-1\right) \Delta f$ but simpler so we omit it. The other terms can be also handled in a similar way.

End of the proof of theorem (2.1) We fix $k>2+d / 4, n$ such that $2 n+1 \geq k+2+d / 2$, and use these values for $X_{T}=L^{\infty}\left([0, T], H^{2 n+1} \cap(1+t)^{-d / 4} W^{k, 4}\right)$. First note that since $\mathcal{L}$ is a smooth diffeomorphism near 1 and $u_{0}=\nabla \phi_{0}$, we have

$$
\begin{aligned}
\left\|u_{0}\right\|_{H^{2 n} \cap W^{k-1,4 / 3}}+\left\|\rho_{0}-\rho_{c}\right\|_{H^{2 n+1} \cap W^{k, 4 / 3}} & \sim\left\|\left(U \phi_{0}, \mathcal{L}^{-1}\left(1+l_{0}\right)-1\right)\right\|_{\left(H^{2 n+1} \cap W^{k, 4 / 3}\right)^{2}} \\
& \sim\left\|\psi_{0}\right\|_{H^{2 n+1} \cap W^{k, 4 / 3}},
\end{aligned}
$$

if $\left\|l_{0}\right\|_{\infty}$ is small enough. In particular we will simply write the smallness condition in term of $\psi_{0}$. Now using the embedding $W^{k, 4} \hookrightarrow W^{2, \infty}$, the energy estimate of proposition (3.1) implies

$$
\|\psi(t)\|_{H^{2 n+1}} \leq\left\|\psi_{0}\right\|_{H^{2 n+1}} \exp \left(C \int_{0}^{t} H\left(\|\psi\|_{X_{s}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\left(\|\psi\|_{W^{k, 4}}+\|\psi\|_{W^{k-1,4}}^{2}\right) d s\right) .
$$

Combining it with the decay estimate of proposition (4.1) we get with $G$ and $H$ continuous:

$$
\begin{aligned}
& \|\psi\|_{X_{T}} \leq C_{1}\left(\left\|\psi_{0}\right\|_{W^{k, 4 / 3}}+\left\|\psi_{0}\right\|_{H^{2 n+1}}+\|\psi\|_{X_{T}}^{2} G\left(\|\psi\|_{X_{T}},\left\|\frac{1}{1+l_{1}}\right\|_{L_{T}^{\infty}\left(L^{\infty}\right)}\right)\right. \\
& +\left\|\psi_{0}\right\|_{H^{N}} \exp \left(C \int_{0}^{T} H\left(\|\psi\|_{X_{T}},\left\|\frac{1}{l+1}\right\|_{L_{T}^{\infty}\left(L^{\infty}\right)}\right)\left(\|\psi\|_{W^{k, 4}}+\|\psi\|_{W^{k-1,4}}^{2}\right) d s\right. \\
& \leq C_{1}\left(\left\|\psi_{0}\right\|_{W^{k, 4 / 3}}+\left\|\psi_{0}\right\|_{H^{N}}+\|\psi\|_{X_{T}}^{2} G\left(\|\psi\|_{X_{T}},\left\|\frac{1}{1+l_{1}}\right\|_{L_{T}^{\infty}\left(L^{\infty}\right)}\right)\right. \\
& \left.\quad+\left\|\psi_{0}\right\|_{H^{2 n+1}} \exp \left(C^{\prime}\|\psi\|_{X_{T}} H\left(\|\psi\|_{X_{T}},\left\|\frac{1}{l+1}\right\|_{L_{T}^{\infty}\left(L^{\infty}\right)}\right)\right)\right) .
\end{aligned}
$$

From the usual bootstrap argument, we find that for $\left\|\psi_{0}\right\|_{W^{k, 4 / 3}}+\left\|\psi_{0}\right\|_{H^{N}} \leq \varepsilon$ small enough then for any $T>0,\|\psi\|_{X_{T}} \leq 3 C_{1} \varepsilon$ (it suffices to note that for $\varepsilon$ small enough, the application $m \mapsto C_{1}\left(\varepsilon+\varepsilon e^{C^{\prime} m}+m^{2}\right)$ is smaller than $m$ on some interval $\left.[a, b] \subset\right] 0, \infty\left[\right.$ with $\left.a \simeq 2 C_{1} \varepsilon\right)$. In particular $\|l\|_{\infty} \lesssim \varepsilon$ and up to diminishing $\varepsilon$, we have

$$
\left\|\rho-\rho_{c}\right\|_{L^{\infty}\left([0, T] \times \mathbb{R}^{d}\right)}=\left\|\mathcal{L}^{-1}(1+l)-\rho_{c}\right\|_{\infty} \leq \rho_{c} / 2
$$

This estimate and the $H^{2 n+1}$ bound allows to apply the blow-up criterion of [6] to get global well-posedness.

## 5 The case of dimension $\mathrm{d}=3,4$ : normal form, bounds for cubic and quartic terms

In dimension $d=4$ the approach of section 4 fails, and $d=3$ is even worse. Thus we need to study more carefully the structure of the nonlinearity. We start with 4.2$)$, that we rewrite in complex form

$$
\begin{align*}
\partial_{t} \psi-i H \psi= & U\left[(a(1+l)-1) \Delta l-\frac{1}{2}\left(|\nabla \phi|^{2}-|\nabla l|^{2}\right)+(2 l-\widetilde{g}(1+l))\right] \\
& +i[-\nabla \phi \cdot \nabla l+(1-a(1+l)) \Delta \phi)] \\
= & U \mathcal{N}_{1}(\phi, l)+i \mathcal{N}_{2}(\phi, l)=\mathcal{N}(\psi) \tag{5.1}
\end{align*}
$$

As explained in the introduction (see (1.11)), we can rewrite the Duhamel formula in term of the profile $e^{-i t H} \psi$. In particular, (the Fourier transform of) quadratic terms read

$$
\begin{equation*}
I_{\text {quad }}=e^{i t H(\xi)} \int_{0}^{t} e^{-i s(H(\xi) \mp H(\eta) \mp H(\xi-\eta))} B(\eta, \xi-\eta) \widetilde{\psi^{ \pm}}(\eta) \widetilde{\psi^{ \pm}}(\xi-\eta) d \eta d s \tag{5.2}
\end{equation*}
$$

where we remind the notation $\widetilde{\psi^{ \pm}}=e^{\mp i t H} \widehat{\psi^{ \pm}}$, and $B$ is the symbol of a bilinear multiplier. For some $\varepsilon>0$ to choose later, $1 / p=1 / 6-\varepsilon, T>0$ we set with $N=2 n+1$ :

$$
\begin{cases}\|\psi\|_{Y_{T}} & =\left\|x e^{-i t H} \psi\right\|_{L_{T}^{\infty}\left(L^{2}\right)}+\left\|\langle t\rangle^{1+3 \varepsilon} \psi\right\|_{L_{T}^{\infty}\left(W^{k, p}\right)}  \tag{5.3}\\ \|\psi\|_{X(t)} & =\|\psi(t)\|_{H^{N}}+\left\|x e^{-i t H} \psi(t)\right\|_{L^{2}}+\left\|\langle t\rangle^{1+3 \varepsilon} \psi(t)\right\|_{W^{k, p}} \\ \|\psi\|_{X_{T}} & =\sup _{[0, T)}\|\psi\|_{X(t)}\end{cases}
$$

From the embedding $W^{3, p} \subset W^{2, \infty}$, proposition 3.1 implies

$$
\|\psi\|_{L_{T}^{\infty} H^{2 n+1}} \lesssim\left\|\psi_{0}\right\|_{H^{2 n+1}} \exp \left(C\left(\|l\|_{L^{\infty}},\left\|\frac{1}{l+1}\right\|_{L^{\infty}}\right)\left(\|\psi\|_{X_{T}}+\|\psi\|_{X_{T}}^{2}\right)\right)
$$

with $C$ a continuous function. Thus the main difficulty of this section will be to prove $\left\|I_{\text {quad }}\right\|_{Y_{T}} \lesssim\|\psi\|_{X_{T}}^{2}$, uniformly in $T$. Combined with the energy estimate (5) and similar (easier) bounds for higher order terms, this provides global bounds for $\psi$ which imply global well-posedness.
In order to perform such estimates we can use integration by part in (5.2) either in $s$ or $\eta$ (for the relevance of this procedure, see the discussion on space time resonances in the introduction). It is thus essential to study where and at which order we have a cancellation of $\Omega_{ \pm, \pm}(\xi, \eta)=H(\xi) \pm H(\eta) \pm H(\xi-\eta)$ or $\nabla_{\eta} \Omega_{ \pm \pm}$. We will denote abusively $H^{\prime}(\xi)=\frac{2+2|\xi|^{2}}{\sqrt{2+|\xi|^{2}}}$ the radial derivative of $H$ and note that $\nabla H(\xi)=H^{\prime}(\xi) \xi /|\xi|$, we also point out that $H^{\prime}(r)=\frac{2+2 r^{2}}{\sqrt{2+r^{2}}}$ is stricly increasing.

There are several cases that have some similarities with the situation for the Schrödinger equation, see | $1.12 \mid 1.13$ | 1.14 | for the definition of the resonant sets $\mathcal{T}, \mathcal{S}, \mathcal{R}$. |
| :---: | :---: | :---: |

- $\Omega_{++}=H(\xi)+H(\eta)+H(\xi-\eta) \gtrsim(|\xi|+|\eta|+|\xi-\eta|)(1+|\xi|+|\eta|+|\xi-\eta|)$, the time resonant set is reduced to $\mathcal{T}=\{\xi=\eta=0\}$,
- $\Omega_{--}=H(\xi)-H(\eta)-H(\xi-\eta)$, we have $\nabla_{\eta} \Omega_{--}=H^{\prime}(\eta) \frac{\eta}{|\eta|}+H^{\prime}(\xi-\eta) \frac{\eta-\xi}{|\eta-\xi|}$. From basic computations

$$
\nabla_{\eta} \Omega_{--}=0 \Rightarrow\left\{\begin{array} { l } 
{ H ^ { \prime } ( \eta ) = H ^ { \prime } ( \xi - \eta ) } \\
{ \frac { \xi - \eta } { | \eta - \xi | } = \frac { \eta } { | \eta | } }
\end{array} \Rightarrow \left\{\begin{array}{l}
|\eta|=|\xi-\eta| \\
\xi=2 \eta
\end{array}\right.\right.
$$

On the other hand $\Omega_{--}(2 \eta, \eta)=H(2 \eta)-2 H(\eta)=0 \Leftrightarrow \eta=0$, thus $\mathcal{R}=\{\xi=\eta=0\}$.

- $\Omega_{-+}=H(\xi)-H(\eta)+H(\xi-\eta)$, from similar computations we find that the space-time resonant set is $\mathcal{R}=\mathcal{S}=\{\xi=0\}$. The case $\Omega_{+-}$is symmetric.

The fact that the space-time resonant set for $\Omega_{+-}$is not trivial explains why it is quite intricate to bound quadratic terms. An other issue pointed out in [22] for their study of the GrossPitaevskii equation is that the small frequency "parallel" resonances are worse than for the nonlinear Schrödinger equation. Namely near $\xi=\varepsilon \eta, \eta \ll 1$ we have
$H(\varepsilon \eta)-H(\eta)+H((\varepsilon-1) \eta) \sim \frac{-3 \varepsilon|\eta|^{3}}{2 \sqrt{2}}=\frac{-3|\xi||\eta|^{2}}{2 \sqrt{2}}$, while $|\varepsilon \eta|^{2}-|\eta|^{2}+|(1-\varepsilon) \eta|^{2} \sim-2|\eta||\xi|$,
we see that integrating by parts in time causes twice more loss of derivatives than prescribed by Coifman-Meyer's theorem, and there is no hope even for $\xi / \Omega$ to belong to any standard class of multipliers. Thus it seems unavoidable to use the rough multiplier theorem 2.4 .

### 5.1 Normal form

In view of the discussion above, the frequency set $\{(\xi, \eta): \xi=0\}$ is expected to raise some special difficulty. On the other hand the real part of the nonlinearity in (5.1) is better behaved than the imaginary part since it has the operator $U(\xi)$ in factor whose cancellation near $\xi=0$ should compensate the resonances. In the spirit of [22] we will use a normal form in order to have a similar cancellation on the imaginary part. In order to write the nonlinearity as essentially quadratic we set $a^{\prime}(1)=\alpha$, and rewrite

$$
\begin{equation*}
\operatorname{Im}(\mathcal{N})(\psi)=-\alpha l \Delta \phi-\nabla \phi \cdot \nabla l+[(1+\alpha l-a(1+l)) \Delta \phi]=-\alpha l \Delta \phi-\nabla \phi \cdot \nabla l+R \tag{5.4}
\end{equation*}
$$

From now on, we will use the notation $R$ as a placeholder for remainder terms that should be at least cubic. The detailed analysis of $R$ will be provided in section 5.2. At the Fourier level, the quadratic terms $-\alpha l \Delta \phi-\nabla \phi \cdot \nabla l$ can be written as follows:

$$
\begin{equation*}
-\alpha l \Delta \phi-\nabla \phi \cdot \nabla l=-\alpha \operatorname{div}(l \nabla \phi)+(\alpha-1) \nabla \phi \cdot \nabla l \tag{5.5}
\end{equation*}
$$

We define the change of variables as $l \rightarrow l-B[\phi, \phi]+B[l, l]$, with $B$ a symmetric bilinear multiplier to choose later. We have

$$
\begin{align*}
& \partial_{t}(-B[\phi, \phi]+B[l, l])=2 B[ \phi,(-\Delta+2) l]+2 B[-\Delta \phi, l] \\
&+2 B\left[\phi, \mathcal{N}_{1}(\phi, l)\right]+2 B\left[\mathcal{N}_{2}(\phi, l), l\right]  \tag{5.6}\\
&=2 B[\phi,(-\Delta+2) l]+2 B[-\Delta \phi, l]+R,
\end{align*}
$$

where the quadratic terms amount to a bilinear Fourier multiplier $B^{\prime}[\phi, l]$, with symbol $B^{\prime}(\eta, \xi-$ $\eta)=2 B(\eta, \xi-\eta)\left(|\eta|^{2}+2+|\xi-\eta|^{2}\right)$. The evolution equation on $l_{1}=l-B(\phi, \phi)+B(l, l)$ is using (5.5), (5.6)

$$
\begin{array}{r}
\partial_{t} l_{1}+\Delta \phi=B^{\prime \prime}(\phi, l)-\alpha \operatorname{div}(l \nabla \phi)+R, \\
B^{\prime \prime}(\eta, \xi-\eta)=2 B(\eta, \xi-\eta)\left(2+|\eta|^{2}+|\xi-\eta|^{2}\right)+(1-\alpha) \eta \cdot(\xi-\eta) .
\end{array}
$$

The natural choice is thus to take (note that if $\alpha=1$ the normal form is just the identity)

$$
B(\eta, \xi-\eta)=\frac{(\alpha-1) \eta \cdot(\xi-\eta)}{2+|\eta|^{2}+|\xi-\eta|^{2}} .
$$

For this choice, we have then:

$$
\begin{equation*}
\partial_{t} l_{1}+\Delta \phi=-\alpha \operatorname{div}(l \nabla \phi)+R, \tag{5.7}
\end{equation*}
$$

In addition from (4.1) we get:

$$
\begin{align*}
\partial_{t} \phi-\Delta l_{1}+2 l_{1}= & -\Delta b(\phi, l)+2 b(\phi, l)+(a(1+l)-1) \Delta l-\frac{1}{2}\left(|\nabla \phi|^{2}-|\nabla l|^{2}\right)  \tag{5.8}\\
& +(2 l-\widetilde{g}(1+l)),
\end{align*}
$$

with $l_{1}=l-B[\phi, \phi]+B[l, l]=l+b(\phi, l)$. Setting $\phi_{1}=U \phi$ the system becomes:

$$
\begin{aligned}
\partial_{t} \phi_{1}+H l_{1} & =U\left(\alpha l \Delta l-\frac{1}{2}\left(\left|\nabla U^{-1} \phi_{1}\right|^{2}-|\nabla l|^{2}\right)+(-\Delta+2) b(\phi, l)-\widetilde{g}^{\prime \prime}(1) l^{2}\right)+R, \\
\partial_{t} l_{1}-H \phi_{1} & =-\alpha \operatorname{div}(l \nabla \phi)+R .
\end{aligned}
$$

Final form of the equation Finally, if we replace in the quadratic terms $l=l_{1}-b(\phi, l)$ and set $z=\phi_{1}+i l_{1}$ we obtain

$$
\begin{align*}
\partial_{t} z-i H z= & U\left(\alpha l_{1} \Delta l_{1}-\frac{1}{2}\left(\left|\nabla U^{-1} \phi_{1}\right|^{2}-\left|\nabla l_{1}\right|^{2}-\widetilde{g}^{\prime \prime}(1) l_{1}^{2}\right)+(-\Delta+2) b\left(\phi, l_{1}\right)\right)-i \alpha \operatorname{div}\left(l_{1} \nabla \phi\right) \\
& +U\left(\alpha \left(-b(\phi, l) \Delta l_{1}-l_{1} \Delta b(\phi, l)+b(\phi, l) \Delta b(\phi, l)-2 \nabla b(\phi, l) \cdot \nabla l+|\nabla b(\phi, l)|^{2}\right.\right. \\
& \left.\left.+(-\Delta+2)\left(-2 B\left[l_{1}, b(\phi, l)\right]+B[b(\phi, l), b(\phi, l)]\right)-\widetilde{g}^{\prime \prime}(1)(b(\phi, l))^{2}+2 \widetilde{g}^{\prime \prime}(1) l_{1} b(\phi, l)\right)\right) \\
= & Q(z)+R:=\mathcal{N}_{z}, \\
& +i \alpha \operatorname{div}(b(\phi, l) \nabla \phi)+R \tag{5.9}
\end{align*}
$$

where $Q(z)$ contains the quadratic terms (the first line), $R$ the cubic and quartic terms.
Remark 5.1. It is noticeable that this change of unknown is not singular in term of the new variable $\phi_{1}=U \phi$, indeed $B(\phi, \phi)=\widetilde{B}(\nabla \phi, \nabla \phi)$ where $\widetilde{B}(\eta, \xi-\eta)=\frac{\alpha-1}{\left(2+|\eta|^{2}+|\xi-\eta|^{2}\right)}$ is smooth, so that $B(\phi, \phi)=\widetilde{B}\left(\nabla U^{-1} \phi_{1}, \nabla U^{-1} \phi_{1}\right)$ acts on $\phi_{1}$ as a composition of smooth bilinear and linear multipliers.

It remains to check that the normal form is well defined in our functional framework. We shall also prove that is cancels asymptotically.

Proposition 5.2. For $N>4, k \geq 2$, the $\operatorname{map} \phi_{1}+i l \mapsto z:=\phi_{1}+i(l+b(\phi, l))$ is bi-Lipschitz on the neighbourhood of 0 in $X_{\infty}$, Moreover, $\psi=\phi_{1}+i l$ and $z$ have the same asymptotic as $t \rightarrow \infty$ :

$$
\|\psi-z\|_{X(t)}=O\left(t^{-1 / 2}\right)
$$

Proof. The terms $B[\phi, \phi]$ and $B[l, l]$ are handled in a similar way, we only treat the first case which is a bit more involved as we have the singular relation $\phi=U^{-1} \phi_{1}$. Note that $B[\phi, \phi]=$ $\widetilde{B}(\nabla \phi, \nabla \phi)$, with $\widetilde{B}[\eta, \xi-\eta]=(\alpha-1) \frac{1}{2+|\eta|^{2}+|\xi-\eta|^{2}}$, and $\nabla U^{-1}=\langle\nabla\rangle \circ R_{i}$ so there is no real issue as long as we avoid the $L^{\infty}$ space. Also, we split $B=B \chi_{|\eta| \gtrsim|\xi-\eta|}+B\left(1-\chi_{|\eta| \gtrsim|\xi-\eta|}\right)$ where $\chi$ is smooth outside $\eta=\xi=0$, homogeneous of degree 0 , equal to 1 near $\{|\xi-\eta|=0\} \cap \mathbb{S}^{2 d-1}$ and 0 near $\{|\eta|=0\} \cap \mathbb{S}^{2 d-1}$. As can be seen from the change of variables $\zeta=\xi-\eta$, these terms are symmetric so we can simply consider the first case.
By interpolation, we have:

$$
\begin{equation*}
\forall 2 \leq q \leq p,\|\psi\|_{W^{k, q}} \lesssim\|\psi\|_{X(t)} /\langle t\rangle^{3(1 / 2-1 / q)} \tag{5.10}
\end{equation*}
$$

For the $H^{N}$ estimate we have from the Coifman-Meyer theorem (since the symbol $\widetilde{B}$ has the form $\frac{1}{2+|\eta|^{2}+|\xi-\eta|^{2}}$, the embedding $H^{1} \mapsto L^{3}$ and the boundedness of the Riesz multiplier,

$$
\left\|B\left[U^{-1} \phi_{1}, U^{-1} \phi_{1}\right]\right\|_{H^{N}} \lesssim\left\|\nabla U^{-1} \phi_{1}\right\|_{W^{N-2,3}}\left\|\nabla U^{-1} \phi_{1}\right\|_{L^{6}} \lesssim\left\|\phi_{1}\right\|_{X(t)}^{2} /\langle t\rangle .
$$

For the weighted estimate $\left\|x e^{-i t H} B[\phi, \phi]\right\|_{L^{2}}$, since $\phi=U^{-1}(\psi+\bar{\psi}) / 2$, we have a collection of terms that read in the Fourier variable:

$$
\mathcal{F}\left(x e^{-i t H} B\left[U^{-1} \psi^{ \pm}, U^{-1} \psi^{ \pm}\right]\right)=\nabla_{\xi} \int e^{-i t \Omega_{ \pm \pm}} B_{1}(\eta, \xi-\eta) \tilde{\psi}^{ \pm}(\eta) \tilde{\psi}^{ \pm}(\xi-\eta) d \eta
$$

where $B_{1}=\frac{\eta U^{-1}(\eta) \cdot(\xi-\eta) U^{-1}(\xi-\eta)}{2+|\eta|^{2}+|\xi-\eta|^{2}} \chi_{|\eta| \gtrsim|\xi-\eta|}, \Omega_{ \pm \pm}=-H(\xi) \mp H(\eta) \mp H(\xi-\eta)$.
If the derivative hits $B_{1}$, in the worst case it adds a singular term $U^{-1}(\xi-\eta)$, so that from the embedding $\dot{H}^{1} \hookrightarrow L^{6}$

$$
\begin{aligned}
\left\|\int e^{-i t \Omega_{ \pm \pm}}\left(\nabla_{\xi} B_{1}\right) \tilde{\psi}^{ \pm}(\eta) \tilde{\psi}^{ \pm}(\xi-\eta) d \eta\right\|_{L^{2}}=\left\|\nabla_{\xi} B_{1}\left[\psi^{ \pm}, \psi^{ \pm}\right]\right\|_{L^{2}} & \lesssim\left\|U^{-1} \psi\right\|_{W^{1,6}}\|\psi\|_{W^{1,3}} \\
& \lesssim\|\psi\|_{X(t)}^{2} /\langle t\rangle^{1 / 2} .
\end{aligned}
$$

If the derivative hits $\widetilde{\psi}^{ \pm}(\xi-\eta)$ we use the fact that the symbol $\frac{\langle\xi-\eta\rangle^{2} \chi|\eta| \gtrsim|\xi-\eta|}{2+|\eta|^{2}+|\xi-\eta|^{2}}$ is of CoifmanMeyer type

$$
\begin{aligned}
\left\|\int e^{i t \Omega_{ \pm \pm}} B_{1}(\eta, \xi-\eta) \tilde{\psi}^{ \pm}(\eta) \nabla_{\xi} \tilde{\psi}^{ \pm}(\xi-\eta) d \eta\right\|_{L^{2}} & \lesssim\|\langle\nabla\rangle \psi\|_{L^{6}}\left\|\langle\nabla\rangle^{-2}\langle\nabla\rangle e^{i t H} x e^{-i t H} \psi\right\|_{L^{3}} \\
& \lesssim\|\psi\|_{X(t)}^{2} /\langle t\rangle .
\end{aligned}
$$

Finally, if the derivative hits $e^{-i t \Omega_{ \pm \pm}}$we note that $\nabla_{\xi} \Omega_{ \pm \pm}=\nabla_{\xi} H(\xi) \mp \nabla_{\xi} H(\xi-\eta)$, where both term are multipliers of order 1 so

$$
\begin{aligned}
\left\|\int e^{i t \Omega_{ \pm \pm}} i t\left(\nabla_{\xi} \Omega_{ \pm \pm}\right) B_{1} \tilde{\psi}^{ \pm}(\eta) \tilde{\psi}^{ \pm}(\xi-\eta) d \eta\right\|_{L^{2}} & \lesssim t\|\psi\|_{W^{1,3}}\|\psi\|_{W^{1,6}} \\
& \lesssim\|\psi\|_{X(t)}^{2} /\langle t\rangle^{1 / 2} .
\end{aligned}
$$

The $W^{k, p}$ norm is also estimated using the Coifman-Meyer theorem and the boundedness of the Riesz multipliers:

$$
\left\|B_{1}\left[\psi^{ \pm}(t), \psi^{ \pm}(t)\right]\right\|_{W^{k, p}} \lesssim\|\psi\|_{W^{k-1,1 / 12-\varepsilon / 2}}^{2} \lesssim\|\psi\|_{W^{k, 1 / 6-\varepsilon}}^{2} \lesssim \frac{\|\psi\|_{X(t)}^{2}}{\langle t\rangle^{2+6 \varepsilon}}
$$

Gluing all the estimates we have proved

$$
\left\|B\left[U^{-1} \psi, U^{-1} \psi\right]\right\|_{X(t)}^{2} \lesssim\|\psi\|_{X(t)}^{2} /\langle t\rangle^{1 / 2},\left\|B\left[U^{-1} \psi, U^{-1} \psi\right]\right\|_{X}^{2} \lesssim\|\psi\|_{X}^{2},
$$

thus using the second estimate we obtain from a fixed point argument that the map $\phi_{1}+i l \mapsto$ $\phi_{1}+i(l-B[\phi, \phi]+B[l, l])$ defines a diffeomorphism on a neighbourhood of 0 in $X$. The first estimate proves the second part of the proposition.

With similar arguments, we can also obtain the following:
Proposition 5.3. Let $z_{0}=U \phi_{0}+i\left(l_{0}-B\left[\phi_{0}, \phi_{0}\right]+B\left[l_{0}, l_{0}\right]\right)$, the smallness condition of theorem (2.2) is equivalent to the smallness of $\left\|z_{0}\right\|_{H^{2 n+1}}+\left\|x z_{0}\right\|_{L^{2}}+\left\|z_{0}\right\|_{W^{k, p}}$.

### 5.2 Bounds for cubic and quartic nonlinearities

Let us first collect the list of terms in $R$ (see (5.4), (5.6), (5.9) ) with $b=b(\phi, l)$ :

$$
\begin{aligned}
& \left(1+\alpha l-(a(1+l)) \Delta \phi, B\left[\phi, \mathcal{N}_{1}(\phi, l)\right], B\left[\mathcal{N}_{2}(\phi, l), l\right], i \alpha \operatorname{div}(b \nabla \phi),\right. \\
& U\left(\alpha\left(-b \Delta l_{1}-l_{1} \Delta b+b \Delta b-2 \nabla b \cdot \nabla l+|\nabla b|^{2}(-\Delta+2) b(\phi,-b)-2 B\left[l_{1}, b\right]+B[b, b]\right) .\right.
\end{aligned}
$$

We note that they are all either cubic (for example $B\left[\phi,|\nabla \phi|^{2}\right]$ ) or quartic (for example $B[b, b]$ ). $B$ is a smooth bilinear multiplier and as we already pointed out, $\phi$ always appears with a gradient, we can replace everywhere $\phi$ by $\phi_{1}=U \phi$ up to the addition of Riesz multipliers.
Since the estimates are relatively straighforward, we only detail the case of the cubic term $B\left[\phi,|\nabla \phi|^{2}\right]$ which comes from $B\left[\phi, \mathcal{N}_{1}(\phi)\right]$ (quartic terms are simpler). Since $\phi=U^{-1}(\psi+\bar{\psi}) / 2$ we are reduced to bound in $Y_{T}$ (see 5.3) terms of the form

$$
I(t)=\int_{0}^{t} e^{i(t-s) H} B\left[U^{-1} \psi^{ \pm},\left|U^{-1} \nabla \psi^{ \pm}\right|^{2}\right] d s
$$

Proposition 5.4. For any $T>0$, we have the a priori estimate

$$
\sup _{[0, T]}\|I(t)\|_{Y_{T}} \lesssim\|\psi\|_{X_{T}}^{3} .
$$

## Proof. The weighted bound

First let us write

$$
\begin{aligned}
& x e^{-i t H} I(t)=\int_{0}^{t} e^{-i s H}\left(\left(-i s \nabla_{\xi} H\right) B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]+B\left[U^{-1} \psi^{ \pm}, x\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right. \\
& \\
& \left.\quad+\nabla_{\xi} B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right) d s \\
& =I_{1}(t)+I_{2}(t)+I_{3}(t)
\end{aligned}
$$

Taking the $L^{2}$ norm and using the Strichartz estimate with $\left(p^{\prime}, q^{\prime}\right)=(2,6 / 5)$ we get

$$
\begin{aligned}
\left\|I_{1}\right\|_{L_{T}^{\infty} L^{2}} & \lesssim\left\|\left(s \nabla_{\xi} H\right) B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right\|_{L^{2}\left(L^{6 / 5}\right)} \\
& \lesssim\left\|s B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right\|_{L^{2}\left(W^{1,6 / 5}\right)}, \\
\left\|I_{2}\right\|_{L_{T}^{\infty} L^{2}} & \lesssim\left\|B\left[U^{-1} \psi^{ \pm}, x\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right\|_{L^{2}\left(L^{6 / 5}\right)} .
\end{aligned}
$$

We have then from Coifman-Meyer's theorem, Hölder's inequality, continuity of the Riez operator and 5.10

$$
\begin{align*}
& \left\|s B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right\|_{L_{T}^{2}\left(W^{1,6 / 5}\right)} \lesssim\|s\| \psi\left\|_{W^{2,6}}^{2}\right\| \psi\left\|_{H^{2}}\right\|_{L_{T}^{2}} \lesssim\|\psi\|_{X_{T}}^{3}  \tag{5.11}\\
& \left\|I_{2}\right\|_{L_{T}^{\infty}\left(L^{2}\right)} \lesssim\| \| \psi\left\|_{W^{1,6}}\right\| x\left(\nabla U^{-1} \psi^{ \pm}\right)^{2}\left\|_{L^{\frac{3}{2}}}\right\|_{L_{T}^{2}}
\end{align*}
$$

The loss of derivatives in $I_{2}$ can be controlled thanks to a paraproduct: let $\left(\chi_{j}\right)_{j \geq 0}$ with $\sum \chi_{j}(\xi)=1, \operatorname{supp}\left(\chi_{0}\right) \subset B(0,2), \operatorname{supp}\left(\chi_{j}\right) \subset\left\{2^{j-1} \leq \xi \leq 2^{j+1}\right\}, j \geq 1$, and set $\widehat{\Delta_{j} \psi}:=\chi_{j} \widehat{\psi}$, $S_{j} \psi=\sum_{0}^{j} \Delta_{k} \psi$. Then

$$
\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}=\sum_{j \geq 0}\left(\nabla U^{-1} S_{j} \psi^{ \pm}\right)\left(\nabla U^{-1} \Delta_{j} \psi^{ \pm}\right)+\sum_{j \geq 1}\left(\nabla U^{-1} S_{j-1} \psi^{ \pm}\right)\left(\nabla U^{-1} \Delta_{j} \psi^{ \pm}\right)
$$

For any term of the first scalar product we have

$$
\begin{aligned}
x\left(\left(\partial_{k} U^{-1} S_{j} \psi^{ \pm}\right)\left(\partial_{k} U^{-1} \Delta_{j} \psi^{ \pm}\right)\right)= & \left(\partial_{k} U^{-1} S_{j} x \psi^{ \pm}\right)\left(\partial_{k} U^{-1} \Delta_{j} \psi^{ \pm}\right) \\
& +\left(\left[x, \partial_{k} U^{-1} S_{j}\right] \psi^{ \pm}\right)\left(\partial_{k} U^{-1} \Delta_{j} \psi^{ \pm}\right)
\end{aligned}
$$

From Hölder's inequality, standard commutator estimates, the Besov embedding $W^{3,6} \hookrightarrow B_{6,1}^{2}$ and (6.1) we get

$$
\begin{array}{r}
\sum_{j}\left\|\left(\partial_{k} U^{-1} S_{j} x \psi^{ \pm}\right)\left(\partial_{k} U^{-1} \Delta_{j} \psi^{ \pm}\right)\right\|_{L^{3 / 2}} \lesssim \sum_{j} 2^{j}\|x \psi\|_{L^{2}} 2^{j}\left\|\Delta_{j} \psi\right\|_{L^{6}} \lesssim\|x \psi\|_{L^{2}}\|\psi\|_{W^{3,6}},( \\
\sum_{j}\left\|\left(\left[x, \partial_{k} U^{-1} S_{j}\right] \psi^{ \pm}\right)\left(\partial_{k} U^{-1} \Delta_{j} \psi^{ \pm}\right)\right\|_{L 3 / 2} \lesssim\left\|U^{-1} \psi\right\|_{H^{1}}\|\psi\|_{W^{1,6}} \lesssim\|\psi\|_{X_{T}}^{2} /\langle t\rangle .( \tag{5.13}
\end{array}
$$

Moreover, $x \psi=x e^{i t H} e^{-i t H} \psi=e^{i t H} x e^{-i t H} \psi+i t \nabla_{\xi} H \psi$ so that :

$$
\|x \psi(t)\|_{L^{2}} \lesssim\langle t\rangle\|\psi\|_{X_{T}}
$$

Similar computations can be done for $\sum_{j \geq 1}\left(\nabla U^{-1} S_{j-1} \psi^{ \pm}\right)\left(\nabla U^{-1} \Delta_{j} \psi^{ \pm}\right)$, finally 5.12, 5.13 and (5.10 imply

$$
\left\|x\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right\|_{L^{3 / 2}} \lesssim\|\psi\|_{X_{T}}^{2}
$$

Plugging the last inequality in 5.11 we can conclude

$$
\left\|I_{2}\right\|_{L_{T}^{\infty} L^{2}} \lesssim\| \| \psi\left\|_{X_{T}}^{3} /\langle t\rangle\right\|_{L_{T}^{2}} \lesssim\|\psi\|_{X_{T}}^{3}
$$

The $W^{k, p}$ decay We can apply the dispersion estimate in the same way as in section 4 .

$$
\begin{align*}
\left\|\int_{0}^{t-1} e^{i(t-s) H} B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right] d s\right\|_{W^{k, p}} & \lesssim \int_{0}^{t-1} \frac{\left\|B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right]\right\|_{W^{k, p^{\prime}}}}{(t-s)^{1+3 \varepsilon}} d s \\
& \lesssim \int_{0}^{t-1} \frac{\left\|\nabla U^{-1} \psi\right\|_{W^{k, 3 p^{\prime}}}^{3}}{(t-s)^{1+3 \varepsilon}} \\
& \lesssim \int_{0}^{t-1} \frac{\|\psi\|_{W^{k+1,3 p^{\prime}}}^{3}}{(t-s)^{1+3 \varepsilon}} \tag{5.14}
\end{align*}
$$

We then use interpolation and the estimate with $q=p^{\prime}$, we have then:

$$
\|\psi\|_{W^{k+1,3 p^{\prime}}} \lesssim\|\psi\|_{W^{k, 3 p^{\prime}}}^{(J-1) / J}\|\psi\|_{W^{k+J, 3 p^{\prime}}}^{1 / J}\|\psi(t)\|_{W^{k, 3 p^{\prime}}} \lesssim \frac{\|\psi\|_{X_{T}}}{(1+t)^{2 / 3-\varepsilon}}
$$

Since $3 p^{\prime}<6$, we have $\|\psi\|_{W^{k+J, 3 p^{\prime}}} \lesssim\|\psi\|_{H^{k+J+1}}$ by Sobolev embedding, so that for $\varepsilon$ small enough, $J$ large enough such that $(2-3 \epsilon)\left(1-\frac{1}{J}\right) \geq 1+3 \epsilon$ (but $J \leq N-k-1$ ) we observe that:

$$
\|\psi\|_{W^{k+1,3 p^{\prime}}}^{3} \lesssim \frac{\|\psi\|_{X_{T}}^{3}}{\langle t\rangle^{1+3 \epsilon}}
$$

Plugging this inequality in (5.14) we conclude that:

$$
\int_{0}^{t-1} \frac{\|\psi\|_{W^{k+1,3 p^{\prime}}}^{3}}{(t-s)^{1+3 \varepsilon}} \lesssim \frac{\|\psi\|_{X_{T}}^{3}}{\langle t\rangle^{1+3 \varepsilon}}
$$

For the integral on $[t-1, t]$ it suffices to bound $\left\|\int_{t-1}^{t} e^{i(t-s) H} B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right] d s\right\|_{W^{k, p}} \lesssim$ $\left\|\int_{t-1}^{t}\right\| B\left[U^{-1} \psi^{ \pm},\left(U^{-1} \nabla \psi^{ \pm}\right)^{2}\right] d s \|_{H^{k+2}}$ and follow the argument of the proof of proposition 4.1.

## 6 Bounds for quadratic nonlinearities in dimension 3, end of proof

The following proposition will be repeatedly used (see proposition 4.6 [4] or [22]).
Proposition 6.1. We have the following estimates with $0 \leq \theta \leq 1$ :

$$
\begin{equation*}
\|\psi(t)\|_{\dot{H}^{-1}} \lesssim\|\psi(t)\|_{X(t)} \tag{6.1}
\end{equation*}
$$

$$
\begin{gather*}
\left\|U^{-2} \psi\right\|_{L^{6}} \lesssim\|\psi(t)\|_{X(t)}  \tag{6.2}\\
\left\||\nabla|^{-2+\frac{5 \theta}{3}} \psi_{<1}(t)\right\|_{L^{6}} \lesssim \min \left(1, t^{-\theta}\right)\|\psi(t)\|_{X(t)}  \tag{6.3}\\
\left\||\nabla|^{\theta} \psi_{\geq 1}(t)\right\|_{L^{6}} \lesssim \min \left(t^{-\theta}, t^{-1}\right)\|\psi(t)\|_{X(t)} \\
\left\|U^{-1} \psi(t)\right\|_{L^{6}} \lesssim\langle t\rangle^{-\frac{3}{5}}\|\psi(t)\|_{X(t)} \tag{6.4}
\end{gather*}
$$

In this section, we will assume $\|\psi\|_{X_{T}} \ll 1$, for the only reason that

$$
\forall m>2,\|\psi\|_{X_{T}}^{2}+\|\psi\|_{X_{T}}^{m} \lesssim\|\psi\|_{X_{T}}^{2} .
$$

All computations that follow can be done without any smallness assumption, but they would require to always add in the end some $\|\psi\|_{X_{T}}^{m}$, that we avoid for conciseness.

### 6.1 The $L^{p}$ decay

We now prove decay for the quadratic terms in (5.9), namely

$$
\langle t\rangle^{1+3 \varepsilon}\left\|\int_{0}^{t} e^{i(t-s) H} Q(z)(s) d s\right\|_{W^{k, p}} \lesssim\|z\|_{X_{T}}^{2}
$$

For $t \leq 1$, the estimate is a simple consequence of the product estimate $\|Q(z)\|_{H^{k+2}} \lesssim\|z\|_{H^{N}}^{2}$ and the boundedness of $e^{i t H}: H^{s} \mapsto H^{s}$. Thus we focus on the case $t \geq 1$ and note that it is sufficient to bound $t^{1+3 \varepsilon}\left\|\int_{0}^{t} e^{i(t-s) H} Q(z)(s) d s\right\|_{W^{k, p}}$.
We recall that the quadratic terms have the following structure (see 5.9)
$Q(z)=U\left(\alpha l_{1} \Delta l_{1}-\frac{1}{2}\left(\left|\nabla U^{-1} \phi_{1}\right|^{2}-\left|\nabla l_{1}\right|^{2}-\widetilde{g}^{\prime \prime}(1) l_{1}^{2}\right)+(-\Delta+2) b\left(\phi, l_{1}\right)\right)-i \alpha \operatorname{div}\left(l_{1} \nabla U^{-1} \phi_{1}\right)$,
where $b=-B[\phi, \phi]+B\left[l_{1}, l_{1}\right], B(\eta, \xi-\eta)=\frac{(\alpha-1) \eta \cdot(\xi-\eta)}{2+|\eta|^{2}+|\xi-\eta|^{2}}$ so that any term in $Q$ is of the form $\left(U \circ B_{j}\right)\left[z^{ \pm}, z^{ \pm}\right], j=1 \cdots 5$ where $B_{j}$ satisfies $B_{j}(\eta, \xi-\eta) \lesssim 2+|\eta|^{2}+|\xi-\eta|^{2}$.

### 6.1.1 Splitting of the phase space

We split the phase space $(\eta, \xi)$ in non time resonant and non space resonant sets: let $\left(\chi^{a}\right)_{a \in 2^{\mathbb{Z}}}$ standard dyadic partition of unity: $\chi^{a} \geq 0, \operatorname{supp}\left(\chi^{a}\right) \subset\{|\xi| \sim a\}, \forall \xi \in \mathbb{R}^{3} \backslash\{0\}, \sum_{a} \chi^{a}(\xi)=1$. We define the frequency localized symbol $B_{j}^{a, b, c}=\chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\zeta) B_{j}$.
Note that due to the relation $\xi=\eta+\zeta$, we have only to consider $B_{j}^{a, b, c}$ when $a \lesssim b \sim c, b \lesssim$ $c \sim a$ or $c \lesssim a \sim b$. We will define in the appendix two disjoint sets of indices $\mathcal{N} \mathcal{T}, \mathcal{N} \mathcal{S}$ such that $\mathcal{N} \mathcal{T} \cup \mathcal{N S}=\mathbb{Z}^{3}$ and which correspond, in a sense precised by lemma 6.16.2 to non time resonant and non space resonant frequencies. Provided such sets have been constructed, we write

$$
\begin{aligned}
\sum_{a, b, c} \int_{0}^{t} e^{i(t-s) H} U B_{j}^{a, b, c}\left[z^{ \pm}, z^{ \pm}\right](s) d s & =\int_{0}^{t} e^{i(t-s) H} \sum_{a, b, c \in \mathcal{N T} \mathcal{T}} U B_{j}^{a, b, c, T}+\sum_{a, b, c \in \mathcal{N S}} U B_{j}^{a, b, c, X} d s \\
& :=\sum_{a, b, c \in \mathcal{N T} \mathcal{T}} I^{a, b, c, T}+\sum_{a, b, c \in \mathcal{N S}} I^{a, b, c, X}
\end{aligned}
$$

For $(a, b, c) \in \mathcal{N} \mathcal{T}$ (resp. $\mathcal{N S}$ ) we will use an integration by parts in time (resp. in the "space" variable $\eta$ ).

### 6.1.2 Control of non time resonant terms

The generic frequency localized quadratic term is

$$
e^{i t H(\xi)} \int_{0}^{t} \int_{\mathbb{R}^{d}}\left(e^{-i s(H(\xi) \mp H(\eta) \mp H(\xi-\eta)} U(\xi) B_{j}^{a, b, c, T}(\eta, \xi-\eta) \widetilde{z^{ \pm}}(s, \eta) \widetilde{z^{ \pm}}(s, \xi-\eta)\right) d \eta d s(6.6)
$$

Regardless of the $\pm$, we set $\Omega=H(\xi) \mp H(\eta) \mp H(\xi-\eta)$. An integration by part in $s$ gives using the fact that $e^{-i s \Omega}=\frac{-1}{i \Omega} \partial_{s}\left(e^{i s \Omega}\right)$ and $\partial_{s} \widetilde{z^{ \pm}}(\eta)=e^{\mp i s H(\eta)}\left(\mathcal{N}_{z}\right)^{ \pm}(\eta), \partial_{s} \widetilde{z^{ \pm}}(\xi-\eta)=$ $e^{\mp i s H(\xi-\eta)}\left(\mathcal{N}_{z}\right)^{ \pm}(\xi-\eta)$ :

$$
\begin{align*}
I^{a, b, c, T}= & \mathcal{F}^{-1}\left(e^{i t H(\xi)}\left(\int_{0}^{t} \int_{\mathbb{R}^{N}}\left(\frac{1}{i \Omega} e^{-i s \Omega} U(\xi) B_{j}^{a, b, c, T}(\eta, \xi-\eta) \partial_{s}\left(\widetilde{z^{ \pm}}(\eta) \widetilde{z^{ \pm}}(\xi-\eta)\right)\right) d \eta d s\right)\right. \\
- & {\left[\mathcal{F}^{-1}\left(e^{i t H(\xi)}\left(\int_{\mathbb{R}^{N}}\left(\frac{1}{i \Omega} e^{-i s \Omega(\xi, \eta)} U(\xi) B_{j}^{a, b, c, T}(\eta, \xi-\eta) \widetilde{z^{ \pm}}(\eta) \widetilde{z^{ \pm}}(\xi-\eta)\right)\right) d \eta d s\right)\right]_{0}^{t} } \\
= & \int_{0}^{t} e^{i(t-s) H}\left(\mathcal{B}_{3}^{a, b, c, T}\left[\left(\mathcal{N}_{z}\right)^{ \pm}, z^{ \pm}\right]+\mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm},\left(\mathcal{N}_{z}\right)^{ \pm}\right]\right) d s \\
& -\left[e^{i(t-s) H} \mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm}, z^{ \pm}\right]\right]_{0}^{t} \tag{6.7}
\end{align*}
$$

with $\mathcal{B}_{3}^{a, b, c, T}(\eta, \xi-\eta)=\frac{U(\xi)}{i \Omega} \chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\xi-\eta) B_{j}(\eta, \xi-\eta)$.
In order to use the rough multiplier estimate from theorem 2.4 , we need to control $\mathcal{B}_{3}^{a, b, c, T}$. The following lemma extends to our settings the crucial multiplier estimates from [22].

Lemma 6.1. Let $m=\min (a, b, c), M=\max (a, b, c), l=\min (b, c)$. For $0<s<2$, we have

$$
\begin{equation*}
\text { if } M \gtrsim 1,\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{s}\right]} \lesssim \frac{\langle M\rangle l^{\frac{3}{2}-s}}{\langle a\rangle} \text {, if } M \ll 1,\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{s}\right]} \lesssim l^{1 / 2-s} M^{-s} . \tag{6.8}
\end{equation*}
$$

We postpone the proof to the appendix.
Remark 6.2. We treat differently $M$ small and $M$ large since we have a loss of derivative on the symbol in low frequencies. Let us mention that the estimate 6.8 can be written simply as follows:

$$
\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{s}\right]} \lesssim \frac{\langle M\rangle\langle l\rangle l^{\frac{1}{2}-s} U(M)^{-s}}{\langle a\rangle}
$$

Lets us start by estimating the first term in 6.7): we split the time integral between $[0, t-1]$ and $[t-1, t]$. The sum over $a, b, c$ involves three cases: $b \lesssim a \sim c, c \lesssim a \sim b$ and $a \lesssim b \sim c$.

The case $\boldsymbol{b} \lesssim \boldsymbol{a} \sim \boldsymbol{c}: \quad$ for $k_{1} \in[0, k]$ we have from theorem 2.4 with $\sigma=1+3 \varepsilon$ :

$$
\begin{align*}
& \left\|\nabla^{k_{1}} \int_{0}^{t-1} e^{i(t-s) H} \sum_{b \lesssim a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{p}} \\
& \lesssim \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} \sum_{b \lesssim a \sim c}\langle a\rangle^{k_{1}}\left\|\mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right]\right\|_{L^{p^{\prime}}} d s, \\
& \lesssim \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}}\left(\sum_{b \lesssim a \sim c \lesssim 1} a b\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]}\left\|U^{-1} Q(z)\right\|_{L^{2}}\left\|U^{-1} z\right\|_{L^{2}}\right. \\
& \left.\quad \quad+\sum_{b \lesssim a \sim c, 1 \lesssim a}\langle c\rangle^{-N+k} U(b)\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]}\left\|U^{-1} Q(z)\right\|_{L^{2}}\left\|\langle\nabla\rangle^{N} z\right\|_{L^{2}}\right) d s+\mathcal{R} \tag{6.9}
\end{align*}
$$

where $\mathcal{R}=\int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} \sum_{b \lesssim a \sim c}\langle a\rangle^{k_{1}}\left\|\mathcal{B}_{3}^{a, b, c, T}\left[R^{ \pm}, z^{ \pm}\right]\right\|_{L^{p^{\prime}}} d s$. Using lemma 6.1 we have, provided $\epsilon<\frac{1}{12}$ and $N-k-\frac{1}{2}+3 \epsilon>0$ :

$$
\begin{aligned}
& \sum_{b \lesssim a \sim c \lesssim 1} a b\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]} \lesssim \sum_{a \lesssim 1} \sum_{b \lesssim a} a b b^{1 / 2-1-3 \varepsilon} a^{-1-3 \varepsilon} \lesssim \sum_{a \lesssim 1} a^{1 / 2-6 \varepsilon} \lesssim 1, \\
& \sum_{b \lesssim a \sim c, a \gtrsim 1} U(b)\langle c\rangle^{-N+k}\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]} \lesssim \sum_{a \gtrsim 1} \sum_{b \lesssim a} U(b) \frac{b^{\frac{1}{2}-3 \epsilon}}{a^{N-k}} \lesssim \sum_{a \gtrsim 1} \frac{1}{a^{N-k}}+\sum_{a \gtrsim 1} \frac{1}{a^{N-k-\frac{1}{2}+3 \epsilon}} \lesssim 1 .
\end{aligned}
$$

Using the gradient structure of $Q(z)$ (see 5.9) :

$$
\begin{equation*}
\left\|U^{-1} Q(z)\right\|_{L^{2}} \lesssim\|z\|_{W^{2,4}}^{2} \lesssim\|z\|_{W^{2,6}}^{\frac{3}{2}}\|z\|_{H^{2}}^{\frac{1}{2}} \tag{6.10}
\end{equation*}
$$

so that if we combine these estimates with (6.1), we get

$$
\begin{aligned}
\left\|\nabla^{k_{1}} \int_{0}^{t-1} e^{i(s-t) H} \sum_{b \leq a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[Q(z)^{ \pm}, z\right] d s\right\|_{L^{p}} & \lesssim\|z\|_{X}^{3} \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} \frac{1}{\langle s\rangle^{\frac{3}{2}}} d s \\
& \lesssim \frac{\|z\|_{X}^{3}}{t^{1+3 \varepsilon}} .
\end{aligned}
$$

We bound now $\mathcal{R}$ from (6.9): contrary to the quadratic terms, cubic terms have no gradient structure, however the nonlinearity is so strong that we can simply use $\left\|1_{|\eta| \lesssim 1} U^{-1} R\right\|_{2} \lesssim$ $\|R\|_{L^{6 / 5}}$. Using the same computations as for quadratic terms we get

$$
\begin{aligned}
& \left\|\nabla^{k_{1}} \int_{0}^{t-1} e^{i(t-s) H} \sum_{b \leq a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[R, z^{ \pm}\right] d s\right\|_{L^{p}} \\
& \quad \lesssim \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}}\left(\left\|1_{\{|\eta| \lesssim 1\}} U^{-1} R\right\|_{L^{2}}\left\|U^{-1} z\right\|_{L^{2}}+\left\|U^{-1} R\right\|_{L^{2}}\left\|\langle\nabla\rangle^{N} z\right\|_{L^{2}}\right) d s .
\end{aligned}
$$

According to (5.9) the cubic terms involve only smooth multipliers and do not contain derivatives of order larger than 2 , thus we can generically treat them like $\left(\langle\nabla\rangle^{2} z\right)^{3}$ using the proposition 5.2, we have then:

$$
\|R\|_{L^{6 / 5}} \lesssim\|z\|_{H^{2}}\|z\|_{W^{2,6}}^{2} \lesssim \frac{\|z\|_{X}^{3}}{\langle t\rangle^{2}},\|R\|_{L^{2}} \lesssim\|z\|_{W^{2,6}}^{3} \lesssim \frac{\|z\|_{X}^{3}}{\langle t\rangle^{2}} .
$$

This closes the estimate as $\int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}\langle s\rangle^{2}} d s \lesssim \frac{1}{t^{1+3 \varepsilon}}$. We proceed similarly for the quartic terms.
It remains to deal with the term $\int_{t-1}^{t}$, using Sobolev embedding we have:

$$
\left\|\nabla^{k_{1}} \int_{t-1}^{t} e^{i(t-s) H} \sum_{b \lesssim a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{p}} \lesssim \int_{t-1}^{t}\|(\cdots)\|_{H^{k_{2}}} d s,
$$

with $k_{2}=k+1+3 \varepsilon$. Again, with $\sigma=1+3 \varepsilon$ we get using theorem 2.4 and Sobolev embedding:

$$
\begin{aligned}
& \| \nabla^{k_{1}} \int_{t-1}^{t} e^{i(t-s) H} \\
& \lesssim \sum_{b \lesssim a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\left\|_{L^{p}} \lesssim \int_{t-1}^{t}\right\| \sum_{b \lesssim a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] \|_{H^{k_{2}}} d s \\
& \lesssim \int_{b \lesssim a \sim c \lesssim 1}^{t}\left(\sum_{b \| \mathcal{B}_{3}^{a, b, c, T}}\left\|_{\left[B^{\sigma}\right]}\right\| U^{-1} Q\left\|_{L^{2}}\right\| U^{-1} z \|_{L^{p}}\right. \\
&\left.\quad+\sum_{b \lesssim a \sim c, 1 \lesssim a} U(b) a^{k_{2}-(N-1-3 \epsilon)}\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]}\left\|U^{-1} Q\right\|_{L^{2}}\left\|\langle\nabla\rangle^{N} z\right\|_{L^{2}}\right) d s+\mathcal{R},
\end{aligned}
$$

where $\mathcal{R}$ contains higher order terms that are easily controlled. Using $\left\|U^{-1} z\right\|_{L^{p}} \lesssim\|z\|_{H^{2}}$ and the same estimates as previously, we can conclude provided that $N$ is sufficiently large:

$$
\left\|\nabla^{k_{1}} \int_{t-1}^{t} e^{i(t-s) H} \sum_{b \lesssim a \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{p}} \lesssim\|u\|_{X}^{3} \int_{t-1}^{t} \frac{1}{\langle s\rangle^{3 / 2}} d s \lesssim \frac{\|z\|_{X}^{3}}{t^{1+3 \varepsilon}} .
$$

The case $\boldsymbol{c} \lesssim \boldsymbol{a} \sim \boldsymbol{b} \quad$ As for $b \lesssim a \sim c$ we start with

$$
\begin{aligned}
\| \nabla^{k_{1}} \int_{1}^{t-1} e^{i(t-s) H} & \sum_{c \lesssim a \sim b} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s \|_{L^{p}} \\
\lesssim \int_{1}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} & \left(\sum_{c \lesssim a \sim b \lesssim 1} b c\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]}\left\|U^{-1} Q(z)\right\|_{L^{2}}\left\|U^{-1} z\right\|_{L^{2}}\right. \\
& \left.\quad+\sum_{c \lesssim a \sim b, 1 \lesssim a}\langle b\rangle^{-1}\left\|\mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]}\left\|\langle\nabla\rangle^{k+1} Q(z)\right\|_{L^{2}}\|z\|_{L^{2}}\right) d s+\mathcal{R} .
\end{aligned}
$$

with $\sigma=1+3 \varepsilon$ and $\mathcal{R}$ contains the other nonlinear terms (which, again, we will not detail). This case is symmetric from $b \lesssim a \sim c$ except for the term $\left\|\langle\nabla\rangle^{k+1} Q(z)\right\|_{L^{2}}$, which is estimated
as follows. Let $1 / q=1 / 3+\varepsilon, k_{3}=\frac{1}{2}-3 \varepsilon$. If $k+2+k_{3} \leq N$ then using the structure of $Q$ (see (6.5)) and Gagliardo Nirenberg inequalities we get:

$$
\left\|\langle\nabla\rangle^{k+1} Q(z)\right\|_{L^{2}} \lesssim\|z\|_{W^{2, p}}\|z\|_{W^{k+3, q}} \lesssim\|z\|_{W^{2, p}}\|z\|_{H^{k+3+k_{3}}} \lesssim\|z\|_{X}^{2} /\langle t\rangle^{1+3 \varepsilon}
$$

Using the multiplier bounds as for the case $b \lesssim a \sim c$, we obtain via the lemma 6.1:

$$
\begin{aligned}
\left\|\nabla^{k_{1}} \int_{0}^{t-1} e^{i(t-s) H} \sum_{c \lesssim a \sim b} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{p}} & \lesssim\|z\|_{X}^{3} \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} \frac{1}{\langle s\rangle^{(1+3 \varepsilon)}} d s \\
& \lesssim \frac{\|z\|_{X}^{3}}{t^{1+3 \varepsilon}}
\end{aligned}
$$

The bound for the integral on $[t-1, t]$ is obtained by similar arguments.

The case $\boldsymbol{a} \lesssim \boldsymbol{b} \sim \boldsymbol{c}$ We have using theorem 2.4 and the fact that the support of $\mathcal{F}\left(\sum_{a \lesssim b} a^{k_{1}} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right]\right)$is localized in a ball $B(0, b)$ :

$$
\begin{aligned}
& \left\|\nabla^{k_{1}} \int_{0}^{t-1} e^{i(t-s) H} \sum_{a \lesssim b \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{p}} \\
& \lesssim \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}}\left\|\sum_{a \lesssim b \sim c} a^{k_{1}} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right]\right\|_{L^{p^{\prime}}} d s \\
& \lesssim \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} \sum_{b \sim c} \frac{1}{\langle b\rangle^{N-2}} U(b) U(c)\left\|\sum_{a \lesssim b}\langle a\rangle^{k} \mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]}\left\|U^{-1} Q(z)\right\|_{L^{2}}\left\|U^{-1}\langle\nabla\rangle^{N} z\right\|_{L^{2}} d s \\
& \quad+\mathcal{R}
\end{aligned}
$$

where as previously, $\mathcal{R}$ is a remainder of higher order terms that are not difficult to bound. We observe that for any symbols $\left(B^{a}(\xi, \eta)\right)$ such that

$$
\forall \eta,\left|a_{1}-a_{2}\right| \geq 2 \Rightarrow \operatorname{supp}\left(B^{a_{1}}(\cdot, \eta)\right) \cap \operatorname{supp}\left(B^{a_{2}}(\cdot, \eta)\right)=\emptyset
$$

then

$$
\begin{equation*}
\left\|\sum_{a} B^{a}\right\|_{\left[B^{\sigma}\right]} \lesssim \sup _{a}\left\|B^{a}\right\|_{\left[B^{\sigma}\right]} \tag{6.11}
\end{equation*}
$$

This implies using lemma 6.1 and provided that $N$ is large enough:

$$
\begin{aligned}
\sum_{b \sim c} \frac{1}{\langle b\rangle^{N-2}} U(b) U(c)\left\|\sum_{a \lesssim b}\langle a\rangle^{k} \mathcal{B}_{3}^{a, b, c, T}\right\|_{\left[B^{\sigma}\right]} & \lesssim \sum_{b} \frac{1}{\langle b\rangle^{N-2}} U(b)^{2} \sup _{a \lesssim b}\langle a\rangle^{k} \frac{b^{\frac{1}{2}-\sigma} U(M)^{-\sigma}\langle b\rangle\langle M\rangle}{\langle a\rangle} \\
& \lesssim \sum_{b} \frac{U(b)^{5 / 2-2 \sigma}}{\langle b\rangle^{N+\sigma-k-7 / 2}} \lesssim 1
\end{aligned}
$$

We have finally using 6.10):

$$
\begin{aligned}
\left\|\nabla^{k_{1}} \int_{0}^{t-1} e^{i(t-s) H} \sum_{a \lesssim b \sim c} \mathcal{B}_{3}^{a, b, c, T}\left[\mathcal{N}_{z}^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{p}} & \lesssim\|z\|_{X}^{3} \int_{0}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}} \frac{1}{\langle s\rangle^{3 / 2}} d s \\
& \lesssim \frac{\|u\|_{X}^{3}}{t^{1+3 \varepsilon}}
\end{aligned}
$$

We proceed in a similar way to deal with the integral on $[t-1, t]$. This end the estimate for the first term in (6.7).

The second term is symmetric from the first, it remains to deal with the boundary term: $\left\|\nabla^{k_{1}}\left[e^{i(t-s) H} \mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm}, z^{ \pm}\right]\right]_{0}^{t}\right\|_{L^{p}}$. We have:

$$
\begin{align*}
\left\|\left[\nabla^{k_{1}} e^{i(t-s) H} \mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm}, z^{ \pm}\right]\right]_{0}^{t}\right\|_{L^{p}} \leq & \left\|\nabla^{k_{1}} e^{-i t H} \mathcal{B}_{3}^{a, b, c, T}\left[z_{0}^{ \pm}, z_{0}^{ \pm}\right]\right\|_{L^{p}}  \tag{6.12}\\
& +\left\|\nabla^{k_{1}} \mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm}(t), z^{ \pm}(t)\right]\right\|_{L^{p}}
\end{align*}
$$

The first term on the right hand-side of 6.12 is easy to deal with using the dispersive estimates of the theorem 2.5 . For the second term we focus on the case $b \lesssim a \sim c$, the other areas can be treated in a similar way. Using proposition 6.1, Sobolev embedding and the rough multiplier theorem 2.4 with $s=1+3 \epsilon, q_{1}=q_{2}=q_{3}=p$ (which verifies $2 \leq p=\frac{6}{3-2 \epsilon}$ ) we have:

$$
\begin{aligned}
\sum_{b \lesssim a \sim c \precsim 1}\left\|\nabla^{k_{1}} \mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm}(t), z^{ \pm}(t)\right]\right\|_{L^{p}} & \lesssim \sum_{b \lesssim a \sim c} b^{-\frac{1}{2}-3 \epsilon} a^{-1-3 \epsilon} U(b) U(c)\left\|U^{-1} z\right\|_{L^{p}}^{2} \\
& \lesssim \sum_{b \lesssim a \sim c} b^{-\frac{1}{2}-3 \epsilon} a^{-1-3 \epsilon} U(b) U(c)\left\|U^{-1+3 \epsilon} z\right\|_{L^{6}}^{2} \lesssim \frac{\|z\|_{X}^{2}}{\langle t\rangle^{\frac{6}{5}+6 \epsilon}}, \\
\sum_{b \lesssim a \sim c, a \gtrsim 1}\left\|\nabla^{k_{1}} \mathcal{B}_{3}^{a, b, c, T}\left[z^{ \pm}(t), z^{ \pm}(t)\right]\right\|_{L^{p}} & \lesssim \sum_{b \lesssim a \sim c, a \gtrsim 1} \frac{\langle a\rangle^{k_{1}} b^{1 / 2-3 \epsilon}}{\langle a\rangle^{k_{1}+1}}\|z\|_{L^{p}}\|z\|_{W^{k_{1}+1, p}} \lesssim \frac{\|z\|_{X}^{2}}{\langle t\rangle^{\frac{3}{2}(1+\epsilon)}}
\end{aligned}
$$

where in the last inequality we also used $\|z\|_{W^{k+1,6}}^{2} \lesssim\|z\|_{W^{k, p}}\|z\|_{W^{k+2, p}} \lesssim\|z\|_{W^{k, p}}\|z\|_{H^{N}}$.

### 6.1.3 Non space resonance

In this section we treat the term $\sum_{a, b, c} I^{a, b, c, X}$. Since control for $t$ small just follows from the $H^{N}$ bounds, we focus on $t \geq 1$, and first note that the integral over $[0,1] \cup[t-1, t]$ is easy to estimate.

Bounds for $\left(\int_{0}^{1}+\int_{t-1}^{t}\right) e^{i(t-s) H} Q(z) d s$
In order to estimate $\left\|\nabla^{k_{1}} \int_{t-1}^{t} e^{i(t-s) H} Q(z) d s\right\|_{L^{p}}$, with $k_{1} \in[0, k]$ we can simply use Sobolev's embedding ( $\left.H^{k+2} \hookrightarrow W^{k, p}, H^{N} \hookrightarrow W^{k+4, q}\right)$ and a Gagliardo-Nirenberg type inequality (2.4)
with $\frac{1}{2}=\frac{1}{q}+\frac{1}{p}$ :

$$
\begin{aligned}
\left\|\int_{t-1}^{t} \nabla^{k_{1}} e^{i(t-s) H} Q(z) d s\right\|_{L^{p}} & \lesssim \int_{t-1}^{t}\|Q(z)\|_{H^{k+2}} d s \\
& \lesssim \int_{t-1}^{t}\|z\|_{W^{k+4, q}}\|z\|_{W^{k, p}} d s \\
& \lesssim\|z\|_{X}^{2} \int_{t-1}^{t} \frac{1}{\langle s\rangle^{1+3 \varepsilon}} d s \lesssim \frac{\|z\|_{X}^{2}}{\langle t\rangle^{1+3 \varepsilon}}
\end{aligned}
$$

The estimate on $[0,1]$ follows from similar computations using Minkowski's inequality and the dispersion estimate from theorem 2.5 .

## Frequency splitting

Since we only control $x e^{-i t H} z$ in $L^{\infty} L^{2}$, in order to handle the loss of derivatives we follow the idea from [15] which corresponds to distinguish low and high frequencies with a threshold frequency depending on $t$. Let $\theta \in C_{c}^{\infty}\left(\mathbb{R}^{+}\right),\left.\theta\right|_{[0,1]}=1, \operatorname{supp}(\theta) \subset[0,2], \Theta(t)=\theta\left(\frac{|D|}{t^{\delta}}\right)$, for any quadratic term $B_{j}[z, z]$, we write

$$
B_{j}\left[z^{ \pm}, z^{ \pm}\right]=\overbrace{B_{j}\left[(1-\Theta(t)) z^{ \pm}, z^{ \pm}\right]+B_{j}\left[\Theta(t) z^{ \pm},(1-\Theta)(t) z^{ \pm}\right]}^{\text {high frequencies }}+\overbrace{B_{j}\left[\Theta(t) z^{ \pm}, \Theta(t) z^{ \pm}\right]}^{\text {low frequencies }} .
$$

## High frequencies

Using the dispersion theorem 2.5, Gagliardo-Nirenberg estimate (2.4) and Sobolev embedding we have for $\frac{1}{p_{1}}=\frac{1}{3}+\varepsilon$ and for any quadratic term of $Q$ writing under the form $U B_{j}\left[z^{ \pm}, z^{ \pm}\right]$:

$$
\begin{align*}
& \left\|\int_{1}^{t-1} e^{i(t-s) H}\left(U B_{j}\left[(1-\Theta(t)) z^{ \pm}, z^{ \pm}\right]+U B_{j}\left[\Theta(t) z,(1-\Theta)(t) z^{ \pm}\right]\right) d s\right\|_{W^{k, p}} \\
& \leq \int_{1}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}}\|z\|_{W^{k+2, p_{1}}}\|(1-\Theta(s)) z\|_{H^{k+2}} d s  \tag{6.13}\\
& \leq \int_{1}^{t-1} \frac{1}{(t-s)^{1+3 \varepsilon}}\|z\|_{H^{N}}^{2} \frac{1}{s^{\delta(N-2-k)}} d s
\end{align*}
$$

choosing $N$ large enough so that $\delta(N-2-k) \geq 1+3 \varepsilon$, we obtain the expected decay.

## Low frequencies

Following the section 6.1.2, we have to estimate quadratic term of the form $U B_{j}\left[z^{ \pm}, z^{ \pm}\right]$wich leads to consider:

$$
\mathcal{F} I_{3}^{a, b, c, X}=e^{i t H(\xi)} \int_{1}^{t-1} \int_{\mathbb{R}^{N}}\left(\left(e^{-i s \Omega} U B_{j}^{a, b, c, X}(\eta, \xi-\eta) \widetilde{\Theta z^{ \pm}}(s, \eta) \widetilde{\Theta z^{ \pm}}(s, \xi-\eta)\right) d \eta d s\right.
$$

with $\Omega=H(\xi) \mp H(\eta) \mp H(\xi-\eta)$. Using $e^{-i s \Omega}=\frac{i \nabla_{\eta} \Omega}{s\left|\nabla_{\eta} \Omega\right|^{2}} \cdot \nabla_{\eta} e^{-i s \Omega}$ and denoting $R i=\frac{\nabla}{|\nabla|}$ the Riesz operator, $\Theta^{\prime}(t):=\theta^{\prime}\left(\frac{|D|}{t^{\delta}}\right), J=e^{i t H} x e^{-i t H}$, an integration by part in $\eta$ gives:

$$
\begin{gather*}
I_{3}^{a, b, c, X}=-\mathcal{F}^{-1}\left(e ^ { i t H ( \xi ) } \left(\int _ { 1 } ^ { t - 1 } \frac { 1 } { s } \int _ { \mathbb { R } ^ { N } } \left(e^{-i s \Omega(\xi, \eta)} \mathcal{B}_{1, j}^{a, b, c, X}(\eta, \xi-\eta) \cdot \nabla_{\eta}\left[\Theta \widetilde{z^{ \pm}}(\eta) \widetilde{\Theta z^{ \pm}}(\xi-\eta)\right]\right.\right.\right. \\
\left.\left.+\mathcal{B}_{2, j}^{a, b, c, X}(\eta, \xi-\eta) \widetilde{\Theta z^{ \pm}}(\eta) \widetilde{\Theta z^{ \pm}}(\xi-\eta) d \eta\right) d s\right) \\
=-\int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H}\left(\mathcal{B}_{1, j}^{a, b, c, X}\left[\Theta(s)(J z)^{ \pm}, \Theta(s) z^{ \pm}\right]-\mathcal{B}_{1, j}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \Theta(s)(J z)^{ \pm}\right]\right. \\
\left.+\mathcal{B}_{2, j}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \Theta(s) z^{ \pm}\right]\right) d s \\
-\int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H}\left(\mathcal{B}_{1, j}^{a, b, c, X}\left[\frac{1}{s^{\delta}} R i \Theta^{\prime}(s) z^{ \pm}, \Theta(s) z^{ \pm}\right]\right. \\
 \tag{6.14}\\
\left.-\mathcal{B}_{1, j}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \frac{1}{s^{\delta}} R i \Theta^{\prime}(s) z^{ \pm}\right]\right) d s .
\end{gather*}
$$

with:

$$
\mathcal{B}_{1, j}^{a, b, c, X}=\frac{U(\xi) \nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}} B_{j}^{a, b, c, X}, \mathcal{B}_{2, j}^{a, b, c, X}=\nabla_{\eta} B_{1, j}^{a, b, c, X} .
$$

The following counterpart of lemma 6.1 slightly improves the estimates from [22].
Lemma 6.2. Denoting $M=\max (a, b, c), m=\min (a, b, c)$ and $l=\min (b, c)$ we have:

- If $M \ll 1$ then for $0 \leq s \leq 2$ :

$$
\begin{equation*}
\left\|\mathcal{B}_{1, j}^{a, b, c, X}\right\|_{\left[B^{s}\right]} \lesssim l^{\frac{3}{2}-s} M^{1-s},\left\|\mathcal{B}_{2, j}^{a, b, c, X}\right\|_{H^{s}} \lesssim l^{\frac{1}{2}-s} M^{-s}, \tag{6.15}
\end{equation*}
$$

- If $M \gtrsim 1$ then for $0 \leq s \leq 2$ :

$$
\begin{equation*}
\left\|\mathcal{B}_{1, j}^{a, b, c, X}\right\|_{\left[B^{s}\right]} \lesssim\langle M\rangle^{2} l^{3 / 2-s}\langle a\rangle^{-1},\left\|\mathcal{B}_{2, j}^{a, b, c, X}\right\|_{\left[B^{s}\right]} \lesssim\langle M\rangle^{2} l^{1 / 2-s}\langle a\rangle^{-1} \tag{6.16}
\end{equation*}
$$

We now use these estimates to bound the first term of 6.14). Since they are independent of $j$ we now drop this index for concision. As in paragraph 6.1.2 the $j$ index is dropped for conciseness, and there are three areas to consider: $b \lesssim c \sim a, c \lesssim c \lesssim a \sim b, a \lesssim b \sim c$.

The case $\boldsymbol{c} \lesssim \boldsymbol{a} \sim \boldsymbol{b}$ Let $\varepsilon_{1}>0$ to be fixed later. Using Minkowski's inequality, dispersion and the rough multiplier theorem 2.4 with $s=1+\varepsilon_{1}, \frac{1}{q}=1 / 2+\epsilon-\frac{\epsilon_{1}}{3}$ for $a \lesssim 1$,
$s=4 / 3, \frac{1}{q_{1}}=7 / 18+\epsilon$ for $a \gtrsim 1$ we obtain

$$
\begin{aligned}
& \left\|\nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H} \sum_{c \lesssim a \sim b} \mathcal{B}_{1}^{a, b, c, X}\left[\Theta(s)(J z)^{ \pm}, \Theta(s) z^{ \pm}\right] d s\right\|_{L^{p}} \\
& \left.\lesssim \int_{1}^{t-1} \frac{1}{s(t-s)^{1+3 \varepsilon}} \sum_{c \lesssim a \sim b \lesssim 1}\left\|\mathcal{B}_{1}^{a, b, c, X}\right\|_{\left[B^{\left.1+\varepsilon_{1}\right]}\right.}\|\Theta(s) J z\|_{L^{2}} \| \Theta(s) z\right] \|_{L^{q}} \\
& \left.\left.\quad+\sum_{c \lesssim a \sim b, 1 \lesssim a \lesssim s^{\delta}} a^{k}\left\|\mathcal{B}_{1}^{a, b, c, X}\right\|_{\left[B^{4 / 3}\right]}\|\Theta(s) J z\|_{L^{2}} \| \Theta(s) z\right] \|_{L^{q_{1}}}\right) d s \\
& \lesssim \int_{1}^{t-1} \frac{1}{s(t-s)^{1+3 \varepsilon}}\left(\sum_{a \lesssim 1} \sum_{c \lesssim a \sim b}\left\|\mathcal{B}_{1}^{a, b, a, X}\right\|_{\left[B^{\left.1+\varepsilon_{1}\right]}\right.}\|\Theta(s) J z\|_{L^{2}} \| \Theta(s) z\right] \|_{L^{q}} \\
& \left.\left.\quad+\sum_{1 \lesssim a \lesssim s^{\delta}} a^{k} \sum_{c \lesssim a \sim b}\left\|\mathcal{B}_{1}^{a, b, c, X}\right\|_{\left[B^{4 / 3}\right]}\|\Theta(s) J z\|_{L^{2}} \| \Theta(s) z\right] \|_{L^{q_{1}}}\right) d s
\end{aligned}
$$

Using lemma 6.2 and interpolation we have for $\varepsilon_{1}<1 / 4$ and $\varepsilon_{1}-3 \varepsilon>0$,

$$
\begin{aligned}
& \sum_{a \lesssim 1} \sum_{c \lesssim a \sim b}\left\|\mathcal{B}_{1}^{a, b, c, X}\right\|_{\left[B^{1+\varepsilon_{1}}\right]} \lesssim \sum_{a \lesssim 1} a^{1-\left(1+\varepsilon_{1}\right)} \sum_{c \lesssim a} c^{\frac{3}{2}-\left(1+\varepsilon_{1}\right)} \lesssim 1 \\
& \|\psi(s)\|_{L^{q}} \lesssim\|\psi(s)\|_{L^{p}}^{\frac{\epsilon_{1}-3 \epsilon}{1+3 \epsilon}}\|\psi(s)\|_{L^{2}}^{1-\frac{\epsilon_{1}-3 \epsilon}{1+3 \epsilon}} \lesssim \frac{\|\psi\|_{X}}{s^{\varepsilon_{1}-3 \varepsilon}}
\end{aligned}
$$

In high frequencies we have:

$$
\sum_{1 \lesssim a \lesssim s^{\delta}} a^{k} \sum_{c \lesssim a \sim b} \frac{\langle M\rangle^{2} c^{3 / 2-4 / 3}}{\langle a\rangle} \lesssim s^{\delta(k+7 / 6)},\|\psi(s)\|_{L^{q_{1}}} \lesssim \frac{\|\psi\|_{X}}{s^{1 / 3-3 \varepsilon}}
$$

Finally we conclude that if $\min \left(\varepsilon_{1}-3 \varepsilon, 1 / 3-3 \varepsilon-\delta(k+7 / 6)\right) \geq 3 \varepsilon$ (this choice is possible provided $\varepsilon$ and $\delta$ are small enough):

$$
\begin{aligned}
\| \nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{-i(t-s) H}\left(\sum_{a, b, c} \mathcal{B}_{1}^{a, b, c, X}\left[\Theta(s)(J z)^{ \pm}, \Theta(s) z^{ \pm}\right] d s \|_{L^{p}}\right. & \lesssim \int_{1}^{t-1} \frac{\|z\|_{X}^{2}}{s^{1+3 \varepsilon}(t-s)^{1+3 \varepsilon}} d s \\
& \lesssim \frac{\|z\|_{X}^{2}}{t^{1+3 \varepsilon}}
\end{aligned}
$$

The case $b \lesssim c \sim a$ is very similar, the case $a \lesssim b \sim c$ involves an infinite sum over $a$ which can be handled as in the non time resonant case with observation (6.11). The term $\nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H} \mathcal{B}_{1}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \Theta(s)(J z)^{ \pm}\right] d s$ is symmetric while the terms

$$
\begin{aligned}
\| \nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H} & \left(\mathcal{B}_{1}^{a, b, c, X}\left[\frac{1}{s^{\delta}} \operatorname{Ri}^{\prime}(s) z^{ \pm}, \Theta(s) z^{ \pm}\right]\right. \\
& \left.-\mathcal{B}_{1}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \frac{1}{s^{\delta}} \operatorname{Ri}^{\prime}(s) z^{ \pm}\right]\right) d s \|_{L^{p}}
\end{aligned}
$$

are simpler since there is no weighted term $J z$ involved.
The last term to consider is

$$
\left\|\nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H} \sum_{a, b, c} \mathcal{B}_{2}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \Theta(s) z^{ \pm}\right] d s\right\|_{L^{p}}
$$

Let us start with the zone $b \lesssim a \sim c$. We use the same indices as for $\mathcal{B}_{1}^{a, b, c}: s=1+\varepsilon_{1}$, $\frac{1}{q}=1 / 2+\varepsilon-\varepsilon_{1} / 3, s_{1}=4 / 3, \frac{\tilde{1}}{q_{1}}=7 / 18+\varepsilon$,

$$
\begin{align*}
& \| \nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H} \\
& \lesssim \sum_{b \lesssim a} \mathcal{B}_{2}^{a, b, c, X}\left[\Theta(s) z^{ \pm}, \Theta(s) z^{ \pm}\right] d s \|_{L^{p}} \\
& \lesssim \int_{1}^{t-1} \frac{1}{s(t-s)^{1+3 \varepsilon}}\left(\sum_{a \lesssim 1} \sum_{b \lesssim a \sim c} U(b) U(c)\left\|\mathcal{B}_{2}^{a, b, c, X}\right\|_{\left[B^{\left.1+\varepsilon_{1}\right]}\right.}\left\|U^{-1} \Theta(s) z\right\|_{L^{2}} \| U^{-1} \Theta(s) z\right] \|_{L^{q}}  \tag{6.17}\\
& \left.\left.\quad+\sum_{1 \lesssim a \lesssim s^{\delta}} a^{k} \sum_{b \lesssim a \sim c} \frac{U(b)}{\langle c\rangle^{k}}\left\|\mathcal{B}_{2}^{a, b, c, X}\right\|_{\left[B^{4 / 3]}\right.}\left\|U^{-1} \Theta(s) z\right\|_{L^{2}} \|\langle\nabla\rangle^{k} \Theta(s) z\right] \|_{L^{q_{1}}}\right) d s
\end{align*}
$$

For $M \lesssim 1$ we have if $\varepsilon_{1}<1 / 4$ :

$$
\sum_{a \lesssim 1} \sum_{b \lesssim c \sim a} U(b) U(c)\left\|\mathcal{B}_{2}^{a, b, c, X}\right\|_{\left[B^{1+\varepsilon_{1}}\right]} \lesssim \sum_{a \lesssim 1} \sum_{b \lesssim c \sim a} b^{1 / 2-\varepsilon_{1}} a^{-\varepsilon_{1}} \lesssim 1 .
$$

Furthermore we have from proposition 6.1.

$$
\left\|U^{-1} \psi(s)\right\|_{L^{2}} \lesssim\|\psi\|_{X},\left\|U^{-1} \psi(s)\right\|_{L^{q}} \lesssim\left\|U^{-1} \psi\right\|_{L^{2}}^{1-\varepsilon_{1}+3 \varepsilon}\left\|U^{-1} \psi\right\|_{L^{6}}^{\varepsilon_{1}-3 \varepsilon} \lesssim \frac{\|\psi\|_{X}}{s^{\frac{3\left(\varepsilon_{1}-3 \varepsilon\right)}{5}}},
$$

Now for $M \gtrsim 1$

$$
\sum_{1 \lesssim a \lesssim s^{\delta}} a^{k} \sum_{b \lesssim \sim \sim a} \frac{U(b)\langle M\rangle^{2} b^{1 / 2-4 / 3}}{\langle a\rangle\langle c\rangle^{k}} \lesssim \sum_{1 \lesssim a \lesssim s^{\delta}} a \lesssim s^{\delta}, \quad\left\|\langle\nabla\rangle^{k} \Theta(s) z\right\|_{L^{q_{1}}} \lesssim \frac{\|z\|_{X}}{s^{1 / 3-3 \varepsilon}} .
$$

If $\min \left(3\left(\varepsilon_{1}-3 \varepsilon\right) / 5,1 / 3-3 \varepsilon-\delta\right) \gtrsim 3 \varepsilon$, injecting these estimates in (6.17) gives

$$
\| \nabla^{k_{1}} \int_{1}^{t-1} \frac{1}{s} e^{i(t-s) H}\left(\sum_{b \lesssim c \sim a} \mathcal{B}_{2}^{a, b, c, X}[\Theta(s) J z, \Theta(s) z] d s \|_{L^{p}} \lesssim \int_{1}^{t-1} \frac{\|z\|_{X}^{2}}{(t-s)^{1+3 \varepsilon} s^{1+3 \varepsilon}} d s \lesssim \frac{\|z\|_{X}^{2}}{t^{1+3 \varepsilon}} .\right.
$$

The two other cases $c \lesssim a \sim b$ and $a \lesssim b \sim c$ can be treated in a similar way, we refer again to the observation (6.11) in the case $a \lesssim b \sim c$.
It concludes this section, the combination of paragraphs 6.1.2 and 6.1.3 gives

$$
\left\|\int_{0}^{t} e^{i(t-s) H} Q(z(s)) d s\right\|_{W^{k, p}} \lesssim \frac{\|z\|_{X}^{2}+\|z\|_{X}^{3}}{\langle t\rangle^{1+3 \varepsilon}} .
$$

Remark 6.3. From the energy estimate, we recall that we need $k \geq 3$ (see (5.3)). The strongest condition on $N$ seems to be $(N-2-k) \delta>1$. In the limit $\varepsilon \rightarrow 0$, we must have at least $1 / 3-\delta(k+7 / 6)>0$, so that $N \geq 18$.

### 6.2 Bounds for the weighted norm

The estimate for $\left\|x \int_{0}^{t} e^{-i s H} B_{j}[z, z] d s\right\|_{L^{2}}$ can be done with almost the same computations as in section 10 from [22]. The only difference is that Gustafson et al deal with nonlinearities without loss of derivatives. As we have seen in paragraph 6.1, the remedy is to use appropriate frequency truncation, so we will only give a sketch of proof for the bound in this paragraph.

First reduction Applying $x e^{-i t H}$ to the generic bilinear term $U \circ B_{j}\left[z^{ \pm}, z^{ \pm}\right]$, we have for the Fourier transform:

$$
\begin{equation*}
\mathcal{F}\left(x e^{-i t H} \int_{0}^{t} e^{i(t-s) H} U B_{j}\left[z^{ \pm}, z^{ \pm}\right]\right)=\int_{0}^{t} \int_{\mathbb{R}^{d}} \nabla_{\xi}\left(e^{-i s \Omega} U B_{j}(\eta, \xi-\eta) \widetilde{z^{ \pm}}(s, \eta) \widetilde{z^{ \pm}}(s, \xi-\eta)\right) d \eta d s \tag{6.18}
\end{equation*}
$$

As the $X_{T}$ norm only controls $\|J z\|_{L^{2}}$, we have to deal with the loss of derivative in the nonlinearities. It is then convenient that $\xi-\eta \lesssim \eta$ in order to absorb the loss of derivatives; to do this we use a cut-off function $\theta(\xi, \eta)$ which is valued in $[0,1]$, homogeneous of degree 0 , smooth outside of $(0,0)$ and such that $\theta(\xi, \eta)=0$ in a neighborhood of $\{\eta=0\}$ and $\theta(\xi, \eta)=1$ in a neighborhood of $\{\xi-\eta=0\}$ on the sphere. Using this splitting we get two terms

$$
\begin{align*}
& \int_{0}^{t} \int_{\mathbb{R}^{d}} \nabla_{\xi}\left(e^{-i s \Omega} U B_{j}(\eta, \xi-\eta) \theta(\xi, \eta) \widetilde{z^{ \pm}}(s, \eta) \widetilde{z^{ \pm}}(s, \xi-\eta)\right) d \eta d s,  \tag{6.19}\\
& \int_{0}^{t} \int_{\mathbb{R}^{d}} \nabla_{\xi}\left(e^{-i s \Omega}(1-\theta(\xi, \eta)) U B_{j}(\eta, \xi-\eta) \widetilde{z^{ \pm}}(s, \eta) \widetilde{z^{ \pm}}(s, \xi-\eta)\right) d \eta d s .
\end{align*}
$$

By symmetry it suffices to consider the first one which corresponds to a region where $|\eta| \gtrsim$ $|\xi|,|\xi-\eta|$ so that we avoid loss of derivatives for $\nabla_{\xi} \widetilde{z^{ \pm}}(s, \xi-\eta)$.

An estimate in a different space and high frequency losses Depending on which term $\nabla_{\xi}$ lands, the following integrals arise:

$$
\begin{aligned}
\mathcal{F} I_{1} & =\int_{0}^{t} \int_{\mathbb{R}^{N}} e^{-i s \Omega} \nabla_{\xi}^{(\eta)}\left(\theta(\xi, \eta) U B_{j}(\eta, \xi-\eta)\right) \widetilde{z^{ \pm}}(s, \eta) \widetilde{z^{ \pm}}(s, \xi-\eta) d \eta d s, \\
\mathcal{F} I_{2} & =\int_{0}^{t} \int_{\mathbb{R}^{N}} e^{-i s \Omega} \theta(\xi, \eta) U B_{j}(\eta, \xi-\eta) \widetilde{z^{ \pm}}(s, \eta) \nabla_{\xi}^{(\eta)} \widetilde{z^{ \pm}}(s, \xi-\eta) d \eta d s, \\
\mathcal{F} I_{3} & =\int_{0}^{t} \int_{\mathbb{R}^{N}} e^{-i s \Omega}\left(i s \nabla_{\xi} \Omega\right) \theta(\xi, \eta) U B_{j}(\eta, \xi-\eta) \widetilde{z^{ \pm}}(s, \eta) \widetilde{z^{ \pm}}(s, \xi-\eta) d \eta d s \\
& :=\mathcal{F}\left(\int_{0}^{t} e^{-i s H}{ }_{s} \mathcal{B}_{j}\left[z^{ \pm}, z^{ \pm}\right] d s\right),
\end{aligned}
$$

with:

$$
\mathcal{B}_{j}(\eta, \xi-\eta)=\left(i s \nabla_{\xi} \Omega\right) \theta(\xi, \eta) U B_{j}(\eta, \xi-\eta) .
$$

The control of the $L^{2}$ norm of $I_{1}$ and $I_{2}$ is not a serious issue: basically we deal here with smooth multipliers, and from the estimate $\left\|z x e^{-i t H} z\right\|_{L_{T}^{1} L^{2}} \lesssim\|z\|_{L_{T}^{1} L^{\infty}}\left\|x e^{-i t H} z\right\|_{L_{T}^{\infty} L^{2}} \lesssim\|z\|_{X_{T}}^{2}$ it is apparent that we can conclude. The only point is that we can control the loss of derivative
on $J z$ via the truncation function $\theta_{1}$ and it suffices to absorb the loss of derivatives by $z$. Due to the $s$ factor, the case of $I_{3}$ is much more intricate and requires to use again the method of space-time resonances.
Let us set

$$
\begin{aligned}
& \|z\|_{S_{T}}=\|z\|_{L_{T}^{\infty} H^{1}}+\left\|U^{-1 / 6} z\right\|_{L_{T}^{2} W^{1,6}} \\
& \|z\|_{W_{T}}=\left\|x e^{-i t H} z\right\|_{L_{T}^{\infty} H^{1}}
\end{aligned}
$$

Gustafson et al prove in [22] the key estimate

$$
\left\|\int_{0}^{t} e^{-i s H} s B\left[z^{ \pm}, z^{ \pm}\right] d s\right\|_{L_{T}^{\infty} L^{2}} \lesssim\|z\|_{S_{T} \cap W_{T}}^{2}
$$

where $B$ is a class of multipliers very similar to our $\mathcal{B}_{j}$, the only difference being that they are associated to semi-linear nonlinearities, and thus cause no loss of derivatives at high frequencies. We point out that the $S_{T}$ norm is weaker than the $X_{T}$ norm, indeed $\left\|U^{-1 / 6} z\right\|_{L_{T}^{2} W^{1,6}} \lesssim$ $\|z\|_{L_{T}^{2} W^{2,9 / 2}} \lesssim\|z\|_{X_{T}}\left\|1 /\langle t\rangle^{5 / 6}\right\|_{L_{T}^{2}} \lesssim\|z\|_{X_{T}}$. Moreover we have already seen how to deal with high frequency loss of derivatives by writing (see paragraph 6.1.3)

$$
\begin{equation*}
\mathcal{B}_{j}\left[z^{ \pm}, z^{ \pm}\right]=\mathcal{B}_{j}\left[1-\Theta(t) z^{ \pm}, z^{ \pm}\right]+\mathcal{B}_{j}\left[\Theta(t) z^{ \pm}, z^{ \pm}\right] \tag{6.20}
\end{equation*}
$$

Let $1 / q=1 / 3+\varepsilon$, the first term is estimated using Sobolev embedding and the fact that $N$ is large enough compared to $\delta$ :

$$
\begin{aligned}
\left\|\int_{0}^{t} \int_{\mathbb{R}^{N}} e^{-i s H} s \mathcal{B}_{j}\left[z^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{2}} \lesssim \int_{0}^{t} s\|(1-\Theta(s)) z\|_{W^{3, q}}\|z\|_{W^{3, p}} d s & \lesssim \int_{0}^{t} \frac{\|z\|_{H^{N}}\|z\|_{X_{T}}}{\langle s\rangle^{(N-4) \delta}} d s \\
& \lesssim\|z\|_{X_{T}}^{2}
\end{aligned}
$$

The estimate of the second term of (6.20) follows from the (non trivial) computations in [22], section 10. They are very similar to the analysis of the previous section (based on the method of space-time resonances), for the sake of completeness we reproduce hereafter a small excerpt from their computations.
As in section 6.1, one starts by splitting the phase space

$$
\int_{0}^{t} e^{i(t-s) H} s \mathcal{B}_{j}\left[\Theta(s) z^{ \pm}, z^{ \pm}\right] d s=\sum_{a, b, c} \int_{0}^{t} e^{i(t-s) H} s\left(\mathcal{B}_{j}^{a, b, c, T}+\mathcal{B}_{j}^{a, b, c, X}\right)\left[\Theta(s) z^{ \pm}, z^{ \pm}\right] d s
$$

For the time non-resonant terms, an integration by parts in $s$ implies:

$$
\begin{align*}
& \int_{0}^{t} e^{i(t-s) H} s \mathcal{B}_{j}^{a, b, c, T}\left[\Theta(s) z^{ \pm}, z^{ \pm}\right] d s \\
&=-\int_{0}^{t} e^{i s H}\left(\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left[\Theta(s) z^{ \pm}, z^{ \pm}\right] d s+\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left[s \Theta(s) \mathcal{N}_{z}^{ \pm}, z^{ \pm}\right]\right. \\
&\left.+\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left[\Theta(s) z^{ \pm}, s \mathcal{N}_{z}^{ \pm}\right]+\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left[-\delta s^{-\delta} \Theta(s)|\nabla| z^{ \pm}, z^{ \pm}\right]\right) d s \\
&+\left[e^{i s H}\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left[s \Theta(s) z^{ \pm}, z^{ \pm}\right]\right]_{0}^{t} \tag{6.21}
\end{align*}
$$

with:

$$
\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}=\frac{1}{\Omega} \mathcal{B}_{j}^{a, b, c, T}=\frac{i \nabla_{\xi} \Omega}{\Omega} B_{j}^{a, b, c, T} \theta(\xi, \eta),
$$

We only consider the second term in the right hand side of (6.21), in the case $c \lesssim b \sim a$. All the other terms can be treated in a similar way. The analog of lemma 6.1 in these settings is the following:
Lemma 6.3. Denoting $M=\max (a, b, c), m=\min (a, b, c)$ and $l=\min (b, c)$ we have:

$$
\begin{equation*}
\left\|\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\right\|_{\left[H^{s}\right]} \lesssim\langle M\rangle^{2}\left(\frac{\langle M\rangle}{M}\right)^{s} l^{\frac{3}{2}-s}\langle a\rangle^{-1} . \tag{6.22}
\end{equation*}
$$

We have then by applying theorem 2.4

$$
\begin{align*}
\| \int_{0}^{T} e^{-i s H} \sum_{c \lesssim a \sim b}\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}[ & {\left[s \Theta(s) \mathcal{N} z^{ \pm}, z^{ \pm}\right] d s \|_{L^{2}} } \\
& \lesssim\left\|\sum_{c \lesssim a \sim b} \frac{U(c)}{\langle b\rangle^{2}}\right\|\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left\|_{\left[B^{1+\varepsilon}\right]}\right\| s\langle\nabla\rangle^{2} \mathcal{N}_{z}\left\|_{L^{2}}\right\| U^{-1} z\left\|_{L^{\infty}\left(L^{6}\right)}\right\|_{L_{T}^{1}} \tag{6.23}
\end{align*}
$$

From lemma 6.3 we find

$$
\begin{align*}
\sum_{c \lesssim a \sim b} U(c)\left\|\left(\mathcal{B}_{3}^{\prime}\right)^{a, b, c, T}\right\|_{\left[B^{1}\right]} & \lesssim \sum_{c \lesssim a} \frac{U(c)}{\langle a\rangle^{2}}\langle a\rangle^{2} a^{-1} c^{\frac{1}{2}},  \tag{6.24}\\
& \lesssim \sum_{a \leq 1} a^{1 / 2}+\sum_{a \geq 1} a^{-1 / 2} \lesssim 1 .
\end{align*}
$$

Next we have (as previously forgetting cubic and quartic nonlinearities)

$$
\left\|\langle\nabla\rangle^{2} \mathcal{N}_{z}\right\|_{L^{2}} \lesssim\|z\|_{W^{4,4}}^{2} \lesssim\|z\|_{X_{T}}^{2} /\langle s\rangle^{3 / 2},
$$

and from (6.4) $\left\|U^{-1} z(s)\right\|_{L^{6}} \lesssim\langle s\rangle^{-3 / 5}$ so that

$$
\left\|\int_{0}^{T} e^{-i s H} \sum_{c \lesssim a \sim b}\left(\mathcal{B}_{j}^{\prime}\right)^{a, b, c, T}\left[s \mathcal{N} z^{ \pm}, z^{ \pm}\right] d s\right\|_{L^{2}} \lesssim\| \| z\left\|_{X_{T}}^{3}\langle s\rangle^{-21 / 10}\right\|_{L_{T}^{1}} \lesssim\|z\|_{X_{T}}^{3} .
$$

### 6.3 Existence and uniqueness

The global existence follows from the same argument as in dimension larger than 4: for $N=3,4$ combining the energy estimate (proposition 3.1), the a priori estimates for cubic, quartic (section 5.2) and quadratic nonlinearities (section 6) and the proposition 5.2 we have uniformly in $T$

$$
\begin{aligned}
&\|\psi\|_{X_{T}} \leq C_{1}\left(\left\|\psi_{0}\right\|_{W^{k, 4 / 3}}+\left\|\psi_{0}\right\|_{H^{N}}+\|\psi\|_{X_{T}}^{2} G\left(\|\psi\|_{X_{T}},\left\|\frac{1}{1+l_{1}}\right\|_{L_{T}^{\infty}\left(L^{\infty}\right)}\right)\right. \\
&\left.+\left\|\psi_{0}\right\|_{H^{2 n+1}} \exp \left(C^{\prime}\|\psi\|_{X_{T}} H\left(\|\psi\|_{X_{T}},\left\|\frac{1}{l+1}\right\|_{L_{T}^{\infty}\left(L^{\infty}\right)}\right)\right)\right)
\end{aligned}
$$

with $G$ and $H$ continuous functions so that from the standard bootstrap argument and the blow up criterion (see page 3) the local solution is global.

### 6.4 Scattering

It remains to prove that $e^{-i t H} \psi(t)$ converges in $H^{s}\left(\mathbb{R}^{3}\right), s<2 n+1$. This is a consequence of the following lemma:

Lemma 6.4. For any $0 \leq t_{1} \leq t_{2}$, we have

$$
\begin{equation*}
\left\|\int_{t_{1}}^{t_{2}} e^{i s H} \mathcal{N} \psi d s\right\|_{L^{2}} \lesssim \frac{\|\psi\|_{X}^{2}}{\left(t_{1}+1\right)^{1 / 2}} . \tag{6.25}
\end{equation*}
$$

Proof. We focus on the quadratic terms since the cubic and quartic terms give even stronger decay. From Minkowski and Hölder's inequality and the dispersion $\|\psi\|_{L^{p}} \leq \frac{\|\psi\|_{X}}{\langle\langle \rangle+3(1 / 2-1 / p)}$ :

$$
\begin{aligned}
\left\|\int_{t_{1}}^{t_{2}} e^{-i(t-s) H} \mathcal{N} \psi d s\right\|_{L^{2}} \lesssim \int_{t_{1}}^{t_{2}}\left\|\langle\nabla\rangle^{2} \psi\langle\nabla\rangle^{2} \psi\right\|_{L^{2}} d s, & \lesssim \int_{t_{1}}^{t_{2}}\left\|\langle\nabla\rangle^{2} \psi\right\|_{L^{4}}^{2} d s \\
& \lesssim\|\psi\|_{X}^{2} \int_{t_{1}}^{t_{2}} \frac{1}{\langle s\rangle^{d / 2}} d s
\end{aligned}
$$

Interpolating between the uniform bound in $H^{2 n+1}$ and the decay in $L^{2}$ we get

$$
\left\|e^{-i t_{1} H} \psi\left(t_{1}\right)-e^{-i t_{2} H} \psi\left(t_{2}\right)\right\|_{H^{s}} \lesssim 1 /\left\langle t_{1}\right\rangle^{(2 n+1-s) /(4 n+2)},
$$

thus $e^{-i t H} u$ converges in $H^{s}$ for any $s<2 n+1$. For $d=3$, the convergence of $x e^{-i t H} \psi$ in $L^{2}$ follows from an elementary but cumbersome inspection of the proof of boundedness of $x e^{-i t H} \psi$. If one replaces everywhere $\int_{0}^{t} x e^{-i s H} \mathcal{N}_{z} d s$ by $\int_{t_{1}}^{t_{2}} x e^{-i s H^{\prime}} \mathcal{N}_{z} d s$, every estimates ends up with $\|\psi\|_{X}^{2} \int_{t_{1}}^{t_{2}} /(1+s)^{1+\varepsilon^{\prime}} d s, k=2,3,4, \varepsilon^{\prime}>0$, so that $x e^{-i t H} \psi$ is a Cauchy sequence in $L^{2}$. A careful inspection of the proof would also allow to quantify the value of $\varepsilon^{\prime}$.

## A The multiplier estimates

The aim of this section is to provide a brief sketch of proof of lemmas 6.2 and 6.1 , let us recall that $\mathcal{B}_{1}, \mathcal{B}_{2}$ and $\mathcal{B}_{3}$ depend on the phase $\Omega=H(\xi) \mp H(\eta) \mp H(\xi-\eta)$ in the following way

$$
\begin{aligned}
& \mathcal{B}_{3}^{a, b, c, T}=\frac{B_{j}}{\Omega} U(\xi) \chi^{a} \chi^{b} \chi^{c}, \\
& \mathcal{B}_{1, j}^{a, b, c, X}=\frac{B_{j} \nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}} U(\xi) \chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\xi-\eta), \\
& \mathcal{B}_{2, j}^{a, b, c, X}=\nabla_{\eta}\left(B_{j} \frac{\nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}} U(\xi) \chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\xi-\eta)\right),
\end{aligned}
$$

Recall the notations:

$$
\begin{align*}
& |\xi| \sim a,|\eta| \sim b,|\zeta| \sim c \\
& M=\max (a, b, c), m=\min (a, b, c), l=\min (b, c) \tag{A.1}
\end{align*}
$$

The function $\chi_{a}$, resp. $\chi_{b}, \chi_{c}$, are smooth cut-off functions that localize near $|\xi| \sim a$ (resp $|\eta| \sim b,|\zeta| \sim c)$. We set as in [22]:

$$
\begin{equation*}
\alpha=|\hat{\zeta}-\hat{\xi}|, \beta=|\hat{\zeta}+\hat{\eta}|, \eta^{\perp}=\hat{\xi} \times \eta \tag{A.2}
\end{equation*}
$$

As a first reduction, we point out that the $B_{j}^{\prime} s$ satisfy the pointwise estimate

$$
\begin{equation*}
\nabla^{k} B_{j}(\eta, \xi-\eta) \mid \lesssim\langle M\rangle^{2} l^{-k} \tag{A.3}
\end{equation*}
$$

We will see that the term $l^{-k}$ causes less loss of derivatives than if $\nabla_{\eta}$ hits $1 / \Omega$ and $\left|\nabla_{\eta} \Omega\right|$, so that it will be sufficient to derive pointwise estimates for $\nabla^{k}(U / \Omega), \nabla^{k}\left(U \nabla_{\eta} \Omega /\left|\nabla_{\eta} \Omega\right|^{2}\right.$, and then multiply them by $\left\langle M^{2}\right\rangle$ to obtain pointwise estimates for the full multiplier.

## A. 1 The + - case

If $\Omega=H(\xi)+H(\eta)-H(\xi-\eta)$ Gustafson et al in [22] decompose the $(\xi, \eta, \zeta)$ region (with $\zeta=\xi-\eta$ ) into the following five cases where each later case excludes the previous ones:

1. $|\eta| \sim|\xi| \gg|\zeta|$ (or $c \ll b \sim a$ ) temporally non-resonant.
2. $\alpha>\sqrt{3}$ temporally non-resonant.
3. $|\zeta| \geq 1$ spatially non-resonant.
4. $\left|\eta^{\perp}\right| \ll M|\eta|$ temporally non resonant.
5. Otherwise spatially non-resonant.

The estimates of lemmas 6.2 |p.1 are essentially a consequence of the pointwise estimates in [22], section 11, except in the fifth case where we provide a necessary improvement. We sketch all five cases for completeness,

1. If $|\eta| \sim|\xi| \gg|\zeta|$, we have

$$
\begin{gather*}
|\Omega|=\Omega=H(\xi)+H(\eta)-H(\zeta) \geq H(M) \sim M\langle M\rangle  \tag{A.4}\\
\left|\nabla_{\zeta} \Omega\right| \lesssim|\nabla H(\eta)| \lesssim\langle M\rangle,\left|\nabla_{\zeta}^{2} \Omega\right| \lesssim \frac{\langle m\rangle}{m} \tag{A.5}
\end{gather*}
$$

From these estimates, the $B_{j}$ estimate (A.3), the volume bound $|\{|\zeta| \sim m\}| \sim m^{3}$ and an interpolation argument we obtain $\left\|\frac{\overline{U(\xi)} B_{j}}{\Omega} \chi^{a} \chi^{b} \chi^{c}\right\|_{L_{\xi}^{\infty}\left(\dot{H}_{\zeta}^{s}\right)} \lesssim m^{\frac{3}{2}-s}$, which is better than (6.8).
2. In the second case $\alpha>\sqrt{3}$ so that $|\zeta| \sim|\eta| \gtrsim|\xi|$.

We cut-off the multipliers by: $\chi_{[\alpha]}=\Gamma(\hat{\xi}-\hat{\zeta})$, for a fixed $\Gamma \in C^{\infty}\left(\mathbb{R}^{3}\right)$ satisfying $\Gamma(x)=1$ for $|x| \geq \sqrt{3}$ and $\Gamma(x)=0$ for $|x| \leq \frac{3}{2}$. In this region,

$$
\begin{gather*}
|\Omega| \geq\langle M\rangle|\xi| \sim\langle M\rangle m,\left|\nabla_{\eta} \Omega\right| \lesssim \frac{M m}{\langle M\rangle}+\frac{\langle M\rangle m}{M} \lesssim \frac{|\Omega|}{M},  \tag{A.6}\\
\left|\nabla_{\eta}^{2} \Omega\right|=\left|\nabla^{2} H(\eta)-\nabla^{2} H(\zeta)\right|=\left|\nabla^{2} H(\eta)-\nabla^{2} H(-\zeta)\right| \lesssim \frac{\langle M\rangle m}{M^{2}} \lesssim \frac{|\Omega|}{M^{2}} . \tag{A.7}
\end{gather*}
$$

As a consequence:

$$
\begin{equation*}
\left\|\frac{U(\xi)}{\Omega} \chi_{[\alpha \mid} \chi^{a} \chi^{b} \chi^{c}\right\|_{L_{\xi}^{\infty}\left(\dot{H}_{\eta}^{s}\right)} \lesssim \frac{\langle M\rangle^{2}}{m\langle M\rangle} \frac{M^{\frac{3}{2}}}{M^{s}} \frac{m}{\langle m\rangle}=\frac{\langle M\rangle M^{\frac{3}{2}-s}}{\langle m\rangle} \sim \frac{\langle M\rangle l^{\frac{3}{2}-s}}{\langle a\rangle} . \tag{A.8}
\end{equation*}
$$

Remark A.1. The use of the normal form is essential here as for general $B_{j}^{a, b, c}$ we would obtain in equation A.8:

$$
\begin{equation*}
\left\|\frac{U(\xi)}{\Omega} \chi_{[\alpha \mid} \chi^{a} \chi^{b} \chi^{c}\right\|_{L_{\xi}^{\infty}\left(\dot{H}_{\eta}^{s}\right)} \lesssim \frac{b^{3 / 2}}{m\langle M\rangle M^{s}\langle m\rangle} \tag{A.9}
\end{equation*}
$$

and the term $\frac{1}{m}$ could not be controlled. The same issue applies for the next areas.
3. The case $M \sim|\zeta| \gtrsim 1$ and $\alpha<\sqrt{3}$. We remind that the symbols to estimate are:

$$
\begin{equation*}
\frac{\nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}} U(\xi) \chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\xi-\eta), \nabla_{\eta} \cdot\left(\left(\mathcal{B}_{1}^{a, b, c, X}\right)^{\prime}\right) \tag{A.10}
\end{equation*}
$$

According to [22], the pointwise estimates in this region are

$$
\begin{equation*}
\left|\nabla_{\eta} \Omega\right| \sim||\zeta|-|\eta||+\langle\eta\rangle \beta \gtrsim|\xi|,\left|\nabla_{\eta}^{k} \Omega\right| \lesssim \frac{\langle\zeta\rangle}{|\zeta|}|\xi||\eta|^{1-k} \lesssim|\xi||\eta|^{1-k} . \tag{A.11}
\end{equation*}
$$

Differentiating causes the same growth near $|\eta|=0$ as in A.3), we deduce for $s \in[0,2]$

$$
\begin{align*}
& \left\|B_{j} \frac{\nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}} \chi_{[\alpha]}^{C} U(\xi) \chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\xi-\eta)\right\|_{\dot{H}_{\eta}^{s}} \lesssim \frac{\langle M\rangle^{2} b^{\frac{3}{2}}}{a b^{s}} U(a)=\langle M\rangle^{2} l^{\frac{3}{2}-s}\langle a\rangle^{-1},  \tag{A.12}\\
& \left\|\nabla_{\eta} \cdot\left(\frac{\nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}} \cdot B_{j} \chi_{[\alpha]}^{C} U(\xi) \chi^{a}(\xi) \chi^{b}(\eta) \chi^{c}(\xi-\eta)\right)\right\|_{\dot{H}_{\eta}^{s}} \lesssim l^{\frac{1}{2}-s}\langle a\rangle^{-1} .
\end{align*}
$$

4. The case $\left|\eta^{\perp}\right| \ll M|\eta|$ corresponds to a low frequency region, where the symbol has a "wave-like" behaviour. In this region

$$
\begin{equation*}
1 \gg M \sim|\zeta|, \alpha<\sqrt{3},\left|\eta^{\perp}\right|=|\eta||\sin (\widehat{(\eta, \xi)})| \ll M|\eta| \tag{A.13}
\end{equation*}
$$

The localization uses the (singular) cut-off multiplier $\chi_{[\perp]}=\chi\left(\frac{\left|\eta^{\perp}\right|}{100 \mathrm{Mb}}\right)$ with $\chi \in$ $C_{0}^{\infty}(\mathbb{R})$ satisfying $\chi(u)=1$ for $|u| \leq 1$ and $\chi(u)=0$ for $|u| \geq 2$. In particular
$\left|\nabla_{\eta}^{k} \chi_{[\perp]}\right| \lesssim\left(\frac{1}{M b}\right)^{k}$, for all $k \geq 1$. The worst case is $M=|\zeta|$, in this case $\Omega$ does not cancel thanks to the slight radial convexity of $H$ :

$$
\begin{equation*}
\Omega=H(\xi+\eta)-H(\xi)-H(\eta) \sim \frac{|\xi||\eta|(|\xi|+|\eta|)}{\langle\xi\rangle+\langle\eta\rangle} \sim M^{2} m,\left|\nabla_{\eta} \Omega\right| \ll|\xi| \tag{A.14}
\end{equation*}
$$

For higher derivatives we have:

$$
\begin{equation*}
\left|\nabla_{\eta}^{1+k} \Omega\right|=\left|\nabla^{k+1} H(\eta)-\nabla^{k+1} H(\zeta)\right| \lesssim \frac{|\xi|}{M|\eta|^{k}},\left|\nabla_{\eta}^{k} B_{j}\right| \lesssim l^{-k} \tag{A.15}
\end{equation*}
$$

For $|\eta| \sim b,\left|\eta^{\perp}\right| \ll M b$, the region has for volume bound $b(M b)^{2}=M^{2} b^{3}$, we get by integration (for $s$ integer) and interpolation

$$
\begin{equation*}
\left\|\frac{U(\xi)}{\Omega} \chi_{[\perp]} \chi_{[\alpha]}^{C} \chi^{a} \chi^{b} \chi^{c}\right\|_{L_{\eta}^{2}} \lesssim \frac{U(a)\left(M^{2} b^{3}\right)^{1 / 2}}{M^{2} m(M b)^{s}} \lesssim l^{\frac{1}{2}-s} M^{-s} \tag{A.16}
\end{equation*}
$$

5. In the last case we need a slight refinement of the symbol estimates from [22]: in the fifth area, $\left|\eta^{\perp}\right| \gtrsim M b \sim|\zeta||\eta|, M \sim|\zeta| \ll 1, \alpha=|\widehat{\zeta}-\widehat{\xi}| \leq \sqrt{3}$.
We have $\left|\nabla_{\eta} \Omega\right|=\left|H^{\prime}(|\eta|) \widehat{\eta}+H^{\prime}(|\zeta|) \widehat{\zeta}\right| \sim H^{\prime}(|\eta|)-H^{\prime}(|\zeta|)+|\widehat{\eta}+\widehat{\zeta}| \geq|\widehat{\eta}+\widehat{\zeta}|$, and

$$
|\widehat{\eta}+\widehat{\zeta}| \geq \frac{|\eta \wedge \zeta|}{|\eta||\zeta|}=\frac{|\eta \wedge(\xi-\eta)|}{|\eta||\zeta|}=\frac{|\eta \wedge \xi|}{|\eta||\zeta|}=\frac{\left|\eta^{\perp}\right||\xi|}{|\eta||\zeta|}
$$

indeed, if $\eta, \zeta$ form an angle $\theta,|\eta \wedge \zeta|=|\eta||\zeta||\sin \theta|$ and $|\widehat{\eta}+\widehat{\zeta}| \geq \mid \sin \theta) \mid$. Thus $\left|\nabla_{\eta} \Omega\right| \gtrsim$ $|\xi|\left|\eta^{\perp}\right| /(|\eta||\zeta|) \gtrsim|\xi|$ (in [22], the authors only used $\left.\left|\nabla_{\eta} \Omega\right| \gtrsim|\zeta||\xi|\right)$.
For the higher derivatives, we combine A.15 with $\left|\nabla_{\eta} \Omega\right| \gtrsim|\xi|\left|\eta^{\perp}\right| /|\eta||\zeta|$ to get

$$
\begin{equation*}
\forall k \geq 2, \frac{\left|\nabla_{\eta}^{k} \Omega\right|}{\left|\nabla_{\eta} \Omega\right|} \lesssim \frac{|\xi|}{M|\eta|^{k-1} \beta} \lesssim \frac{1}{|\eta|^{k-2}\left|\eta^{\perp}\right|} \tag{A.17}
\end{equation*}
$$

so that we have the pointwise estimate

$$
\left|\nabla_{\eta}^{k} \frac{\nabla_{\eta} \Omega}{\left|\nabla_{\eta} \Omega\right|^{2}}\right| \sim \frac{1}{|\nabla \Omega|}\left(\frac{\left|\nabla_{\eta}^{2} \Omega\right|}{\left|\nabla_{\eta} \Omega\right|}\right)^{k} \lesssim \frac{1}{|\xi|\left|\eta^{\perp}\right|^{k}}
$$

Following [22], we then use a dyadic decomposition $\left|\eta^{\perp}\right| \sim \mu \in 2^{j} \mathbb{Z}, M b \lesssim \mu \lesssim b$. For each $\mu$ integrating gives a volume bound $\mu b^{1 / 2}$ and using interpolation we get for $s>1$

$$
\left\|U(\xi) /\left|\nabla_{\eta} \Omega\right|\right\|_{\dot{H}_{\eta}^{s}} \lesssim \sum_{M b \lesssim \mu \lesssim b} \frac{U(a) \mu b^{1 / 2}}{a \mu^{s}} \sim l^{3 / 2-s} M^{1-s}
$$

## A. 2 The other cases

The -+ case This case is clearly symmetric from the +- case.

The -- case The decomposition follows the same line as in $[22]$. Note however that the analysis is simpler at least for $M \geq 1$. Indeed in this area $\left|\nabla_{\eta} \Omega\right| \sim\left|H^{\prime}(\eta)-H^{\prime}(\zeta)\right|+\mid \widehat{\eta}-$ $\widehat{\zeta}|\gtrsim||\eta|-|\zeta||+|\widehat{\eta}-\widehat{\zeta}| \sim| \eta-\zeta \mid$ so that we might split it as $\{|\eta-\zeta| \gtrsim \max (|\eta|,|\zeta|)\}$ and $\{|\eta-\zeta| \ll \max (|\eta|,|\zeta|)\}$. The first region is obviously space non resonant. The second region is time non resonant, indeed since $M \gtrsim 1$ we have in this region $|\xi| \sim|\eta| \sim|\zeta| \gtrsim 1$. Using a Taylor development gives
$H(\xi)-H(\eta)-H(\zeta)=H(2 \eta+\zeta-\eta)-H(\eta)-H(\eta+\zeta-\eta)=H(2 \eta)-2 H(\eta)+O(\langle a\rangle|\zeta-\eta|)$,
this last quantity is bounded from below by $|\eta|^{2}$ for $|\eta| \gtrsim 1,|\zeta-\eta|$ small enough.
For $M<1$, we can follow the same line as for $Z \bar{Z}$ by inverting the role of $\xi$ and $\zeta$. Note that the improved estimate in the last area relied on $\left|\nabla_{\eta} \Omega_{+-}\right| \gtrsim|\widehat{\eta}+\widehat{\zeta}| \geq\left|\eta^{\perp}\right| \xi \mid /(|\eta||\zeta|)$ and can just be replaced by $\left|\nabla_{\eta} \Omega_{--}\right| \gtrsim|\widehat{\eta}-\widehat{\zeta}| \geq\left|\eta^{\perp}\right| \xi \mid /(|\eta||\zeta|)$.

The ++ case We have $\Omega=H(\xi)+H(\eta)+H(\zeta) \gtrsim(|\xi|+|\eta|+|\zeta|)(1+|\xi|+|\eta|+|\zeta|)$, the area is time non resonant.

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[^1]:    ${ }^{1}$ These global weak solution do not verify the energy inequality

[^2]:    ${ }^{2} k \in \mathbb{R}^{+}$is allowed, but not needed.

[^3]:    ${ }^{3}$ We write the relation between $\left(q_{1}, q_{2}\right)$ in a rather odd way in order to emphasize the similarity with the standard Hölder's inequality.

[^4]:    ${ }^{4}$ The assumption $a(1)=1$ should add some constants in factor of the nonlinear terms, we will neglect it as it will be clear in the proof that multiplicative constants do not matter.

