

Graph Filter Banks with M -Channels, Maximal Decimation, and Perfect Reconstruction

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Caltech

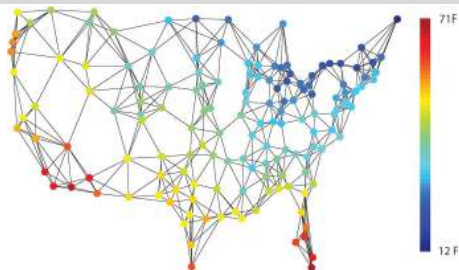
Outline

- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks
 - Extending Classical Tools to Graph Case
- 3 Multirate Processing of Graph Signals
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 Some Examples

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What is a Graph Signal ?



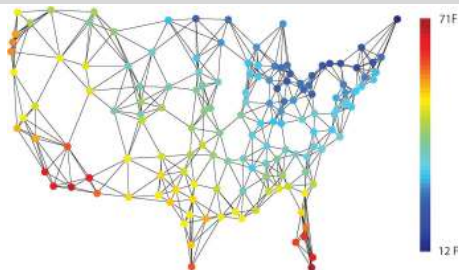
$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_i \\ \vdots \\ x_N \end{bmatrix} \in \mathcal{C}^N$$

¹ A. Sandryhaila and J. M. F. Moura. “Discrete Signal Processing on Graphs: Frequency Analysis”. In: *IEEE Trans. Signal Process.* 62.12 (2014), pp. 3042–3054.

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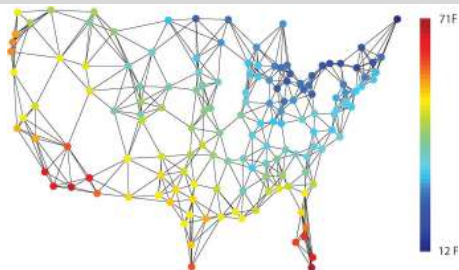
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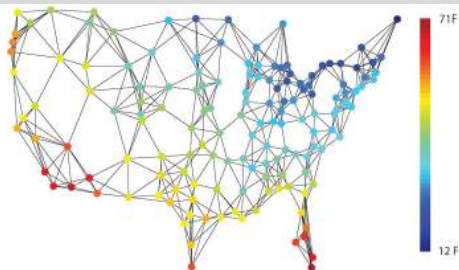
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\mathbf{V} = graph Fourier Basis, \mathbf{V}^{-1} = graph Fourier Transform

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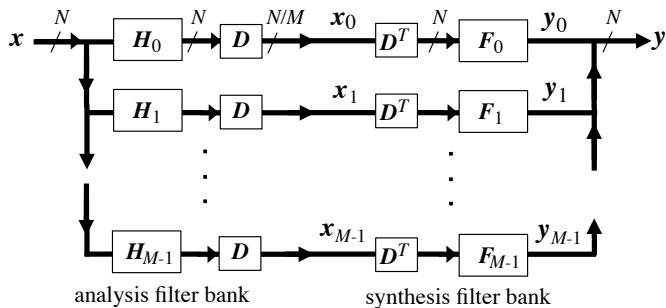
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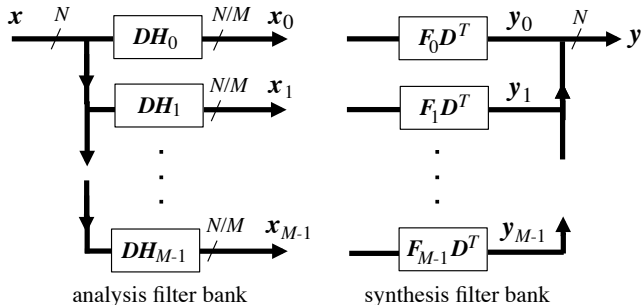
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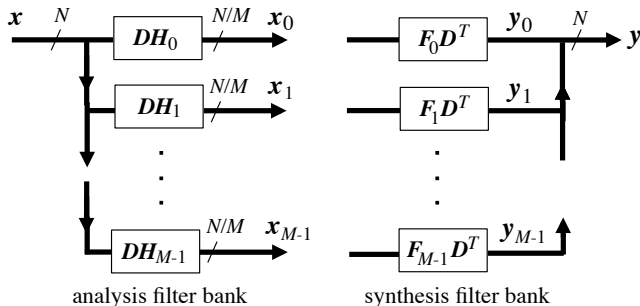
Maximally Decimated M -Channel Filter Banks



M -Channel Filter Banks (Brute-Force)

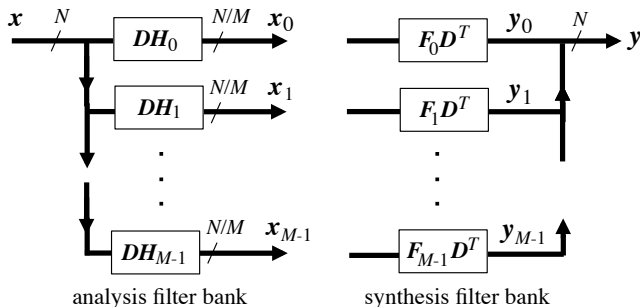


M -Channel Filter Banks (Brute-Force)



$$\mathbf{H}_{anal} = \begin{bmatrix} DH_0 \\ \vdots \\ DH_{M-1} \end{bmatrix}, \quad \mathbf{F}_{syn} = [F_0 D^T \quad \dots \quad F_{M-1} D^T]$$

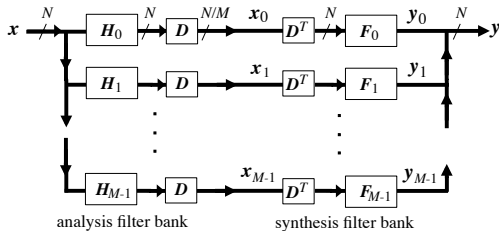
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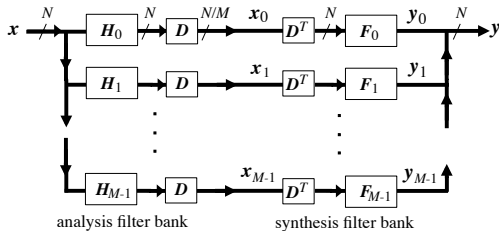
$$\mathbf{F}_{syn} \mathbf{H}_{anal} = \mathbf{I}$$

Problems with Brute-Force



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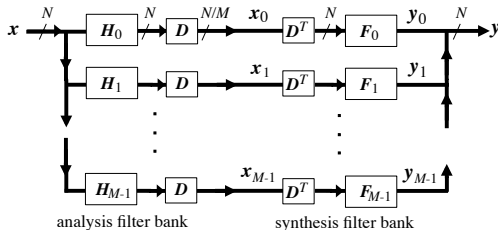
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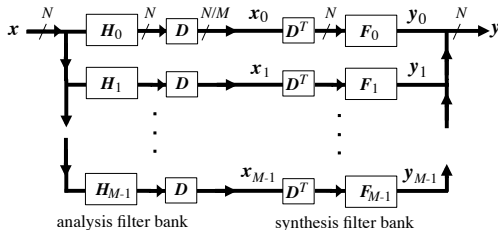
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Filter Design



Matrix Inversion Problem

Problems with Brute-Force



Relation with A ?

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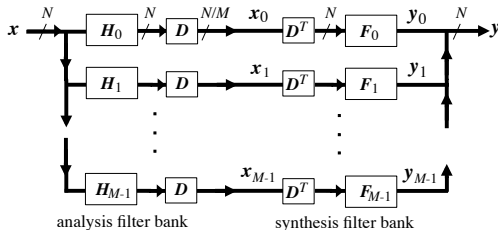
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Computational Complexity = $O(N^2)$

Filter Design



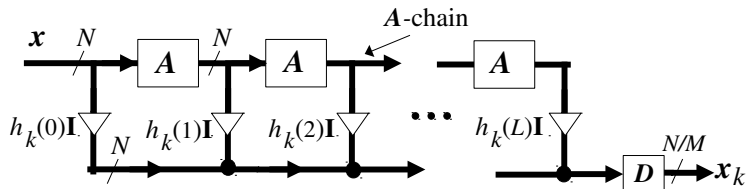
Matrix Inversion Problem

Polynomials

$$\mathbf{H}_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + h_k(2) \mathbf{A}^2 + \dots + h_k(L) \mathbf{A}^L$$

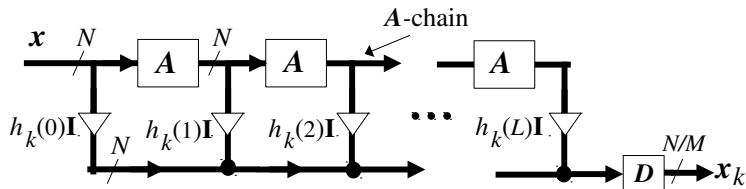
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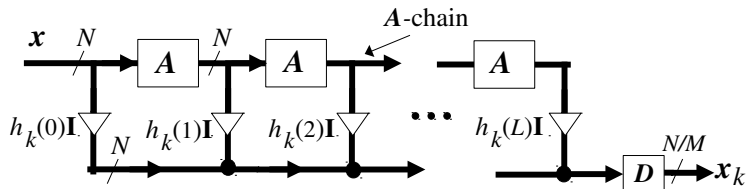
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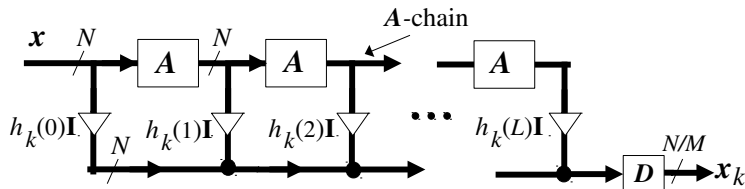


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\mathbf{A} has simple entries, e.g. $\{0, 1, -1\}$, $\Rightarrow \mathbf{A} \mathbf{x}$ has negligible complexity

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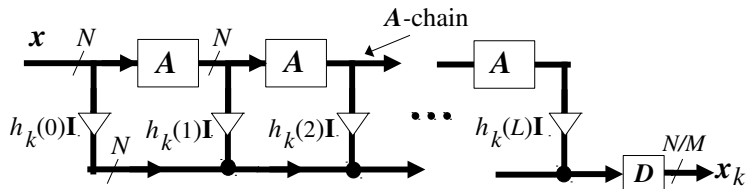
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$$L \ll N$$

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$$\mathbf{D} : C^N \rightarrow C^{N/M}$$

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Assume an appropriate permutation (labeling) of the nodes

Keep the first N/M samples

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Definition (Canonical Decimator)

$$\mathbf{D} = \begin{bmatrix} \mathbf{I}_{N/M} & \mathbf{0}_{N/M} & \cdots & \mathbf{0}_{N/M} \end{bmatrix} \in \mathbb{C}^{(N/M) \times N},$$

which retains the first N/M samples of the given graph signal.

M -fold Expansion

$$U : C^{N/M} \rightarrow C^N$$

M -fold Expansion

$$\mathbf{U} : \mathcal{C}^{N/M} \rightarrow \mathcal{C}^N$$

Given the decimator $\mathbf{D} = \left[\mathbf{I}_{N/M} \quad \mathbf{0}_{N/M} \quad \cdots \quad \mathbf{0}_{N/M} \right]$

$$\mathbf{U} = \mathbf{D}^T = \begin{bmatrix} \mathbf{I}_{N/M} \\ \mathbf{0}_{N/M} \\ \vdots \\ \mathbf{0}_{N/M} \end{bmatrix} \in \mathcal{C}^{N \times (N/M)}$$

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$$DU = I$$

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$$D^T = \arg \min_U \|U\|_F \quad \text{s.t.} \quad DU = I$$

M -block cyclic graphs

^a[O. Teke and P. P. Vaidyanathan](#). "Extending Classical Multirate Signal Processing Theory to Graphs". *IEEE Trans. Signal Process.* (Submitted).

^b

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(Under suitable permutation)

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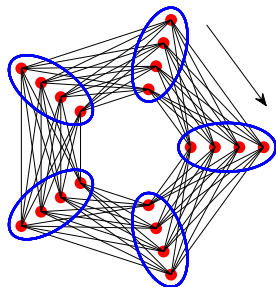
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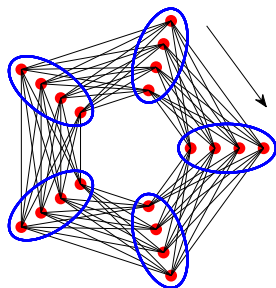
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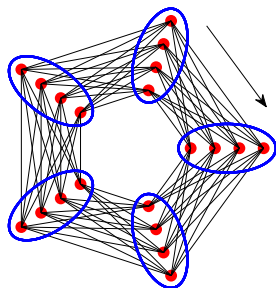
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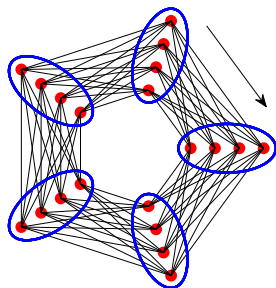
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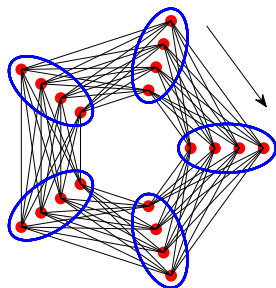
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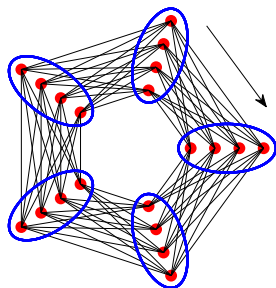
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- 5 **Unique eigenvalue & eigenvector structure** ^{a b}

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^bD. S. Watkins. "Product eigenvalue problems" *SIAM Review*, 2005

Spectrum Folding - Aliasing

Let x be a graph signal

$$y = D^T D x$$

Spectrum Folding - Aliasing

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$$y = D^T D x$$

$$x = \begin{bmatrix} x_1 \\ \vdots \\ x_{\frac{N}{M}} \\ x_{\frac{N}{M}+1} \\ \vdots \\ \vdots \\ \vdots \\ x_N \end{bmatrix}$$

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What is the relation between \hat{x} and \hat{y} ?

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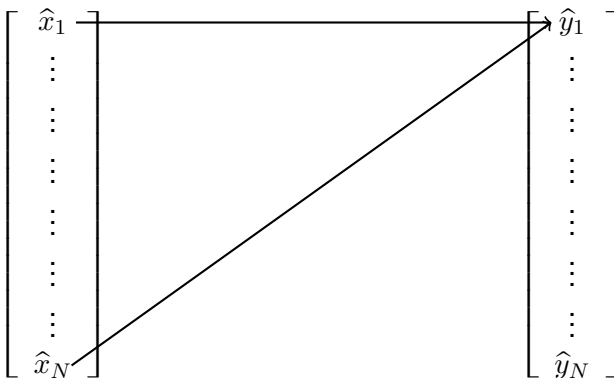
$$\hat{y} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{x}$$

$$\begin{bmatrix} \hat{x}_1 \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \hat{x}_N \end{bmatrix}$$

$$\begin{bmatrix} \hat{y}_1 \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ \hat{y}_N \end{bmatrix}$$

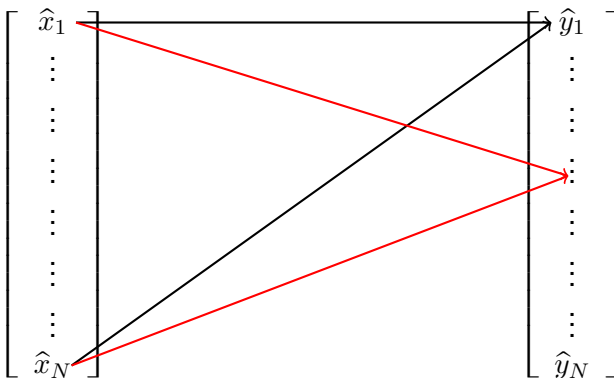
What is the relation between \hat{x} and \hat{y} ?

$$\hat{y} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{x}$$



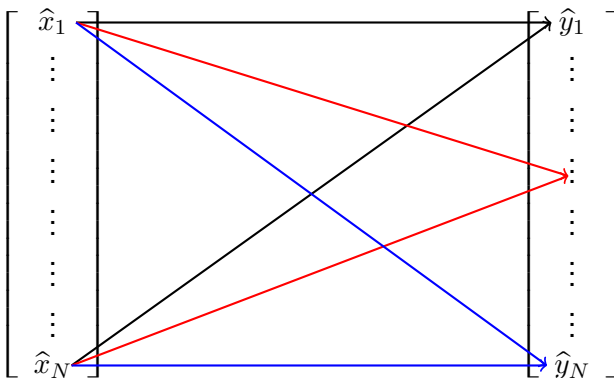
What is the relation between \hat{x} and \hat{y} ?

$$\hat{y} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{x}$$



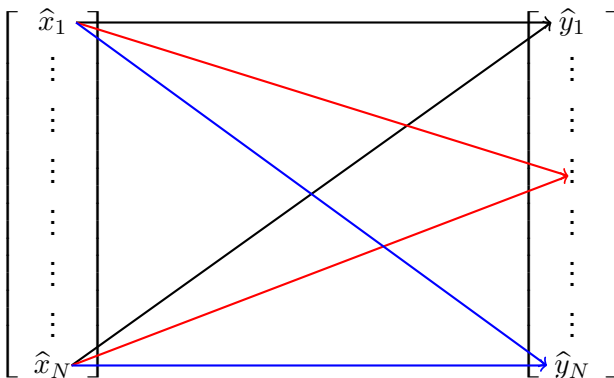
What is the relation between \hat{x} and \hat{y} ?

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What is the relation between \hat{x} and \hat{y} ?

$$\hat{y} = \mathbf{V}^{-1} \mathbf{D}^T \mathbf{D} \mathbf{V} \hat{x}$$



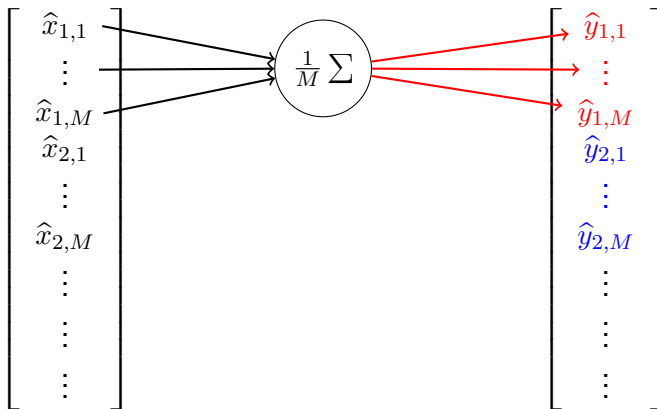
No "simple" relation in general!

Spectrum Folding on M -Block Cyclic Graphs

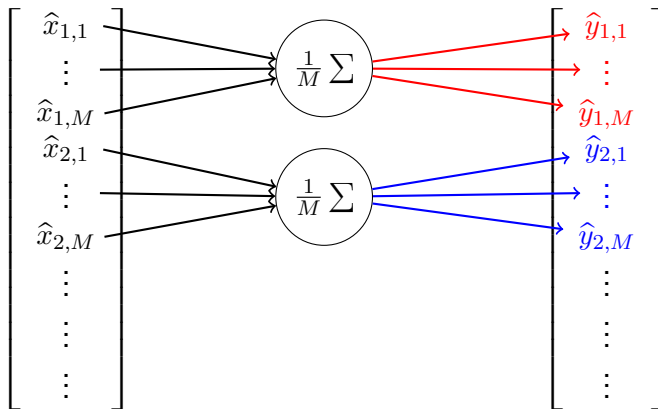
$$\begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

$$\begin{bmatrix} \hat{y}_{1,1} \\ \vdots \\ \hat{y}_{1,M} \\ \hat{y}_{2,1} \\ \vdots \\ \hat{y}_{2,M} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

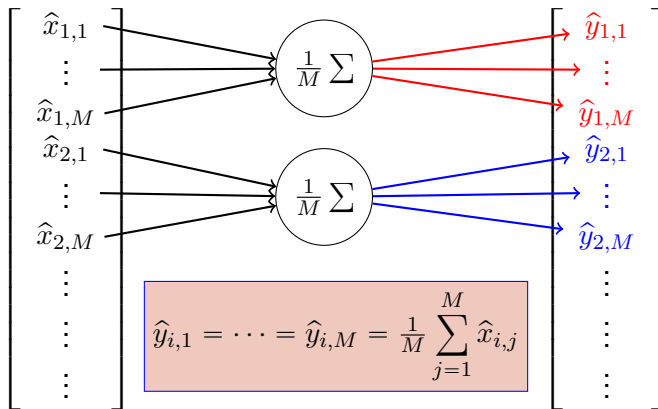
Spectrum Folding on M -Block Cyclic Graphs



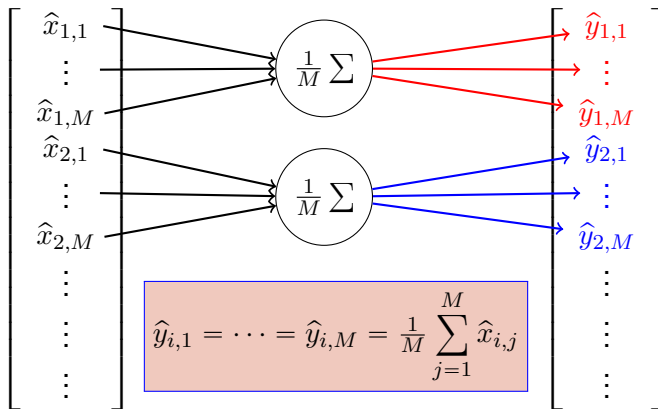
Spectrum Folding on M -Block Cyclic Graphs



Spectrum Folding on M -Block Cyclic Graphs



Spectrum Folding on M -Block Cyclic Graphs



$M = 2 \Leftrightarrow$ Bi-partite ⁴

⁴S.K. Narang and A. Ortega. "Perfect Reconstruction Two-Channel Wavelet Filter Banks for Graph Structured Data". *IEEE Trans. Signal Process.* 60.6 (2012), pp. 2786–2799.

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[k^{th} \text{ band limited}]{} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[k^{th}]{band\ limited} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{D^T D}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\hat{x} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[k^{th}]{band\ limited} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{D^T D} \hat{y} = \begin{bmatrix} \hat{y}_{1,1} \\ \vdots \\ \hat{y}_{1,M} \\ \hat{y}_{2,1} \\ \vdots \\ \hat{y}_{2,M} \\ \hat{y}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Band-Limited Signals & Decimation on M -Block Cyclic

Let x be a graph signal

$$\begin{aligned}
 \hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} &\xrightarrow[k^{th}]{band\ limited} \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow{D^T D} \hat{\mathbf{y}} = \begin{bmatrix} \hat{y}_{1,1} \\ \vdots \\ \hat{y}_{1,M} \\ \hat{y}_{2,1} \\ \vdots \\ \hat{y}_{2,M} \\ \hat{y}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}
 \end{aligned}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[\text{(interpolation)}]{\mathbf{z} = \mathbf{F}\mathbf{y}}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[\text{(interpolation)}]{\mathbf{z} = \mathbf{F}\mathbf{y}} \hat{\mathbf{z}} = \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ 0 \\ 0 \\ \vdots \\ \vdots \end{bmatrix} = \hat{\mathbf{x}}$$

Interpolation Filter on M -Block Cyclic Graphs

$$\hat{\mathbf{y}} = \frac{1}{M} \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,1} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,1} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} \xrightarrow[\text{(interpolation)}]{\mathbf{z} = \mathbf{F}\mathbf{y}} \hat{\mathbf{z}} = \begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ 0 \\ \hat{x}_{3,1} \\ 0 \\ 0 \\ \vdots \\ \vdots \end{bmatrix} = \hat{\mathbf{x}}$$

Not true for an arbitrary \mathbf{x} !

For k^{th} -band-limited signals, \mathbf{x} can be recovered from $D\mathbf{x}$

M -Channel Filter-Banks on M -Block Cyclic Graphs

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

M -Channel Filter-Banks on M -Block Cyclic Graphs

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} = \underbrace{\begin{bmatrix} \hat{x}_{1,1} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{2,1} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{3,1} \\ 0 \\ \vdots \\ 0 \\ \vdots \end{bmatrix}}_{\hat{\mathbf{x}}_1 = 1^{st}} + \underbrace{\begin{bmatrix} 0 \\ \hat{x}_{1,2} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,2} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,2} \\ \vdots \\ 0 \\ \vdots \end{bmatrix}}_{\hat{\mathbf{x}}_2 = 2^{nd}} + \cdots + \underbrace{\begin{bmatrix} 0 \\ \vdots \\ 0 \\ \hat{x}_{1,M} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{2,M} \\ 0 \\ \vdots \\ 0 \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix}}_{\hat{\mathbf{x}}_M = M^{th}}$$

M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix}$$

M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{x}}_k =]{\mathbf{H}_k} \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix}$$

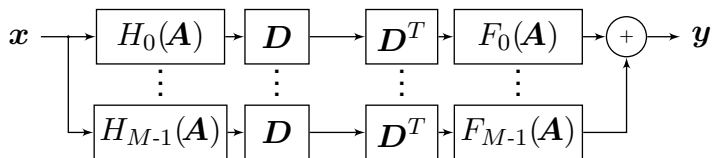
M -Channel Filter-Banks (k^{th} -Channel)

$$\hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{x}}_k =]{\mathbf{H}_k} \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{y}}_k =]{\mathbf{D}^T \mathbf{D}} \frac{1}{M} \begin{bmatrix} \hat{x}_{1,k} \\ \hat{x}_{1,k} \\ \vdots \\ \hat{x}_{1,k} \\ \hat{x}_{2,k} \\ \hat{x}_{2,k} \\ \vdots \\ \hat{x}_{2,k} \\ \hat{x}_{3,k} \\ \hat{x}_{3,k} \\ \vdots \\ \hat{x}_{3,k} \\ \vdots \end{bmatrix}$$

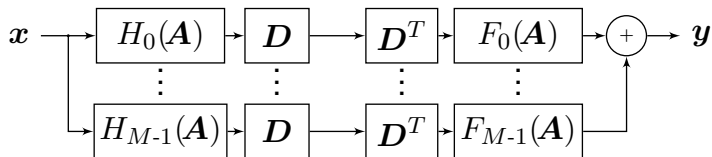
M -Channel Filter-Banks (k^{th} -Channel)

$$\begin{aligned}
 \hat{\mathbf{x}} = \begin{bmatrix} \hat{x}_{1,1} \\ \hat{x}_{1,2} \\ \vdots \\ \hat{x}_{1,M} \\ \hat{x}_{2,1} \\ \hat{x}_{2,2} \\ \vdots \\ \hat{x}_{2,M} \\ \hat{x}_{3,1} \\ \hat{x}_{3,2} \\ \vdots \\ \hat{x}_{3,M} \\ \vdots \end{bmatrix} & \xrightarrow[\hat{\mathbf{x}}_k =]{\mathbf{H}_k} \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{y}}_k =]{\mathbf{D}^T \mathbf{D}} \frac{1}{M} \begin{bmatrix} \hat{x}_{1,k} \\ \hat{x}_{1,k} \\ \vdots \\ \hat{x}_{1,k} \\ \hat{x}_{2,k} \\ \hat{x}_{2,k} \\ \vdots \\ \hat{x}_{2,k} \\ \hat{x}_{3,k} \\ \hat{x}_{3,k} \\ \vdots \\ \hat{x}_{3,k} \\ \vdots \end{bmatrix} \xrightarrow[\hat{\mathbf{z}}_k =]{\mathbf{F}_k} \begin{bmatrix} 0 \\ \hat{x}_{1,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{2,k} \\ \vdots \\ 0 \\ 0 \\ \hat{x}_{3,k} \\ \vdots \\ 0 \\ \vdots \end{bmatrix}
 \end{aligned}$$

M -Channel FB on M -Block Cyclic Graphs (Details)

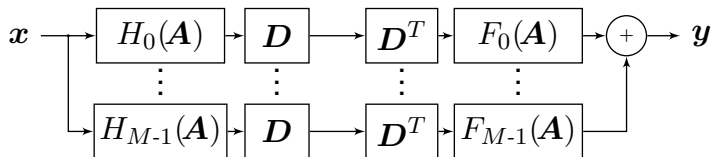


M -Channel FB on M -Block Cyclic Graphs (Details)



$$\mathbf{F}_k = M \mathbf{H}_k$$

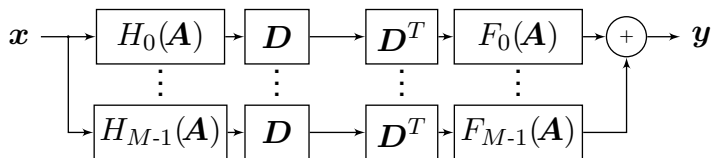
M -Channel FB on M -Block Cyclic Graphs (Details)



$$\mathbf{F}_k = M \mathbf{H}_k$$

$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1}$$

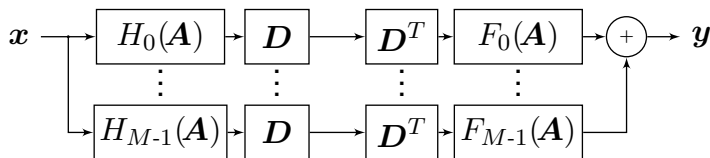
M -Channel FB on M -Block Cyclic Graphs (Details)



$$\mathbf{F}_k = M \mathbf{H}_k$$

$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1} \quad H_k(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi k}{M} \leq \omega \leq \frac{2\pi(k+1)}{M}, \\ 0, & \text{otherwise,} \end{cases}$$

M -Channel FB on M -Block Cyclic Graphs (Details)

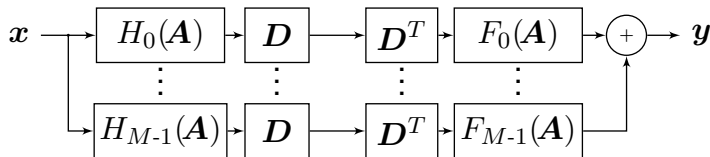


$$\mathbf{F}_k = M \mathbf{H}_k$$

$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1} \quad H_k(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi k}{M} \leq \omega \leq \frac{2\pi(k+1)}{M}, \\ 0, & \text{otherwise,} \end{cases}$$

$$\mathbf{H}_k \stackrel{?}{=} H_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + \dots + h_k(L) \mathbf{A}^L$$

M -Channel FB on M -Block Cyclic Graphs (Details)



$$\mathbf{F}_k = M \mathbf{H}_k$$

$$\mathbf{H}_{k-1} = \mathbf{V} \left(\mathbf{I} \otimes \mathbf{e}_k \mathbf{e}_k^T \right) \mathbf{V}^{-1} \quad H_k(e^{j\omega}) = \begin{cases} 1, & \frac{2\pi k}{M} \leq \omega \leq \frac{2\pi(k+1)}{M}, \\ 0, & \text{otherwise,} \end{cases}$$

$$\mathbf{H}_k \stackrel{?}{=} H_k(\mathbf{A}) = h_k(0) \mathbf{A}^0 + h_k(1) \mathbf{A}^1 + \dots + h_k(L) \mathbf{A}^L$$

\mathbf{A} needs to have **distinct eigenvalues**.^{5 6}

⁵O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

⁶A. Sandryhaila and J. M. F. Moura. "Discrete Signal Processing on Graphs". *IEEE Trans. Signal Process.* 61.7 (2013)

Is M -Block Cyclic Property Necessary?

$$M\text{-Block Cyclic}^7 \Leftrightarrow \begin{cases} \text{Eigenvector Property : } \mathbf{v}_{i,j+k} = \mathbf{\Omega}^k \mathbf{v}_{i,j} \\ \text{Eigenvalue Property : } \lambda_{i,j+k} = w^k \lambda_{i,j} \end{cases}$$

⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

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For any polynomial $H(\mathbf{A})$

$$H(\mathbf{Q}\mathbf{A}\mathbf{Q}^{-1}) = \mathbf{Q} H(\mathbf{A}) \mathbf{Q}^{-1} \text{ for any invertible } \mathbf{Q}$$

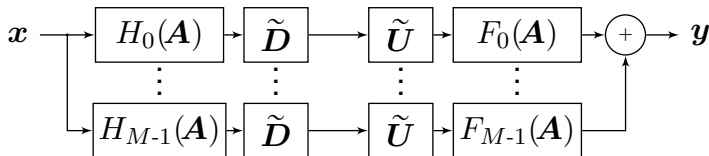
⁷O. Teke and P. P. Vaidyanathan. "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

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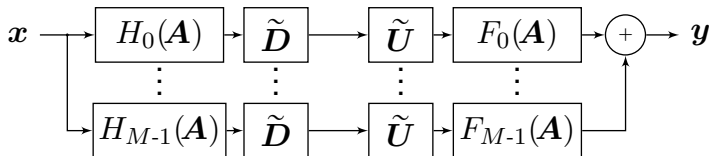
⁷O. Teke and P. P. Vaidyanathan, "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Is M -Block Cyclic Property Necessary?

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For any polynomial $H(A)$

$$H(QAQ^{-1}) = QH(A)Q^{-1} \text{ for any invertible } Q$$



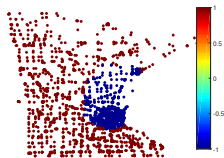
\tilde{D} and \tilde{U} have higher complexity, but **no restrictive assumptions** on A .

⁷O. Teke and P. P. Vaidyanathan, "Extending Classical Multirate Signal Processing Theory to Graphs – Part I: Fundamentals". *IEEE Trans. Signal Process.* (Submitted).

Outline

- 1 Introduction to Graph Signal Processing
 - Graph Signals
- 2 Purpose: M -Channel Filter Banks
 - Extending Classical Tools to Graph Case
- 3 Multirate Processing of Graph Signals
 - Decimation & Expansion
 - M -Block Cyclic Graphs
 - Concept of Spectrum Folding
 - More Results for M -Block Cyclic
- 4 Some Examples

Examples

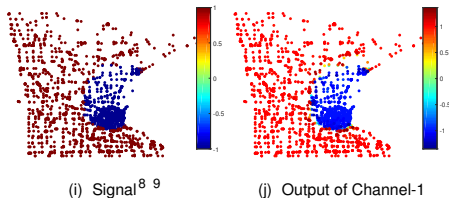


(a) Signal^{8 9}

⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

⁹D. K. Hammond, P. Vandergheynst, and R. Gribonval. The spectral graph wavelets toolbox. [Online]. <http://wiki.epfl.ch/sgwt>

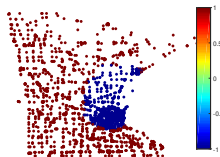
Examples



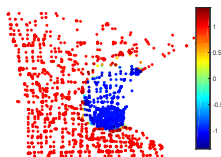
⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

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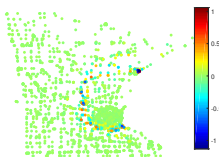
Examples



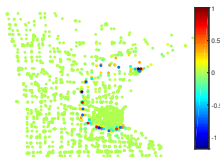
(q) Signal^{8 9}



(r) Output of Channel-1



(s) Output of Channel-2

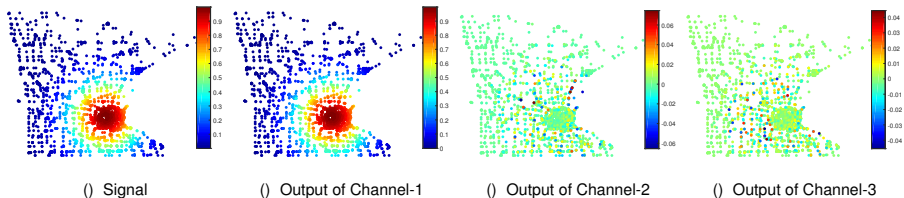
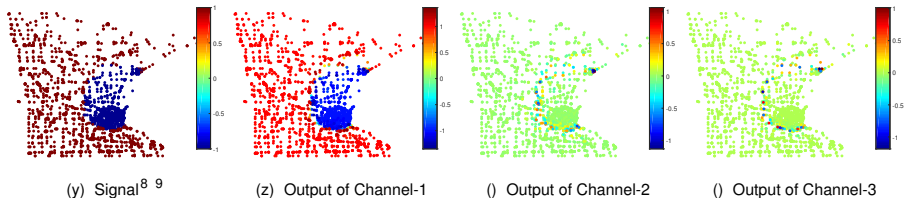


(t) Output of Channel-3

⁸S. Narang and A. Ortega. (2013) Graph bior wavelet toolbox. [Online]. http://biron.usc.edu/wiki/index.php/Graph_Filterbanks

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Examples



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⁹D. K. Hammond, P. Vandergheynst, and R. Gribonval. The spectral graph wavelets toolbox. [Online]. <http://wiki.epfl.ch/sgwt>

Conclusions

- Brute-Force Filter Banks
- Decimator
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Conclusions

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Any questions?

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