

**HANDBOOK of
GRAPH GRAMMARS and
COMPUTING by GRAPH
TRANSFORMATION**

HANDBOOK OF GRAPH GRAMMARS AND COMPUTING BY GRAPH TRANSFORMATION

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Volume 1
FOUNDATIONS

HANDBOOK of GRAPH GRAMMARS and COMPUTING by GRAPH TRANSFORMATION

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Preface

Graph grammars originated in the late 60's, motivated by considerations about pattern recognition, compiler construction, and data type specification. Since then the list of areas which have interacted with the development of graph grammars has grown impressively. Besides the aforementioned areas it includes software specification and development, VLSI layout schemes, database design, modelling of concurrent systems, massively parallel computer architectures, logic programming, computer animation, developmental biology, music composition, visual languages, and many others. Graph grammars are interesting from the theoretical point of view because they are a natural generalization of formal language theory based on strings and the theory of term rewriting based on trees.

The wide applicability of graph grammars is due to the fact that graphs are a natural way of describing complex situations on an intuitive level. Moreover, the graph transformations associated with a graph grammar bring "dynamic behaviour" to such descriptions, because they model the evolution of graphical structures. Therefore graph grammars and graph transformations become attractive as a "programming paradigm" for software and graphical interfaces.

Over the last 25-odd years graph grammars have developed at a steady pace into a theoretically sound and well-motivated research field. In particular, they are now based on solid foundations, presented in this volume. It includes a state-of-the-art presentation of the foundations of all basic approaches to graph grammars and computing by graph transformations.

The two most basic choices for rewriting a graph are *node replacement* and *edge replacement*, or, in the more general setting of hypergraphs, *hyperedge replacement*. In a node replacement graph grammar a node of a given graph is replaced by a new subgraph which is connected to the remainder of the graph by new edges depending on how the node was connected to it. In a hyperedge replacement graph grammar a hyperedge of a given hypergraph is replaced by a new subhypergraph which is glued to the remainder of the hypergraph by fusing (identifying) some nodes of the subhypergraph with some nodes of the remainder of the hypergraph depending on how the hyperedge was glued to it. Chapter 1 surveys the theory of node replacement graph grammars concentrating mainly on "context-free" (or "confluent") node replacement graph grammars, while Chapter 2 surveys the theory of hyperedge replacement graph grammars. Both types of graph grammars naturally generalize the context-free string grammars.

The gluing of graphs plays also a central role in the *algebraic approach* to graph transformations, where a subgraph, rather than a node or an edge only, can be replaced by a new subgraph (generalizing in this way arbitrary type-0 Chomsky string grammars). Originally, the rewriting of graphs based on gluing has been formulated by the so-called *double pushout* in the category of graphs and total graph morphisms. More recently a *single pushout* in the category of graphs and partial graph morphisms has been used for this purpose. Chapter 3 gives an overview of the double pushout approach, and Chapter 4 gives an overview of the single pushout approach; it also presents a detailed comparison of the two approaches.

Graphs may be considered as *logical structures* and so one can express formally their properties by logical formulas. Consequently classes of graphs may be described by formulas of appropriate logical languages. Such logical formulas are used as finite devices, comparable to grammars and automata, to specify classes of graphs and to deduce properties of such classes from their logical descriptions. Chapter 5 surveys the relationships between monadic second-order logic and the context-free graph grammars of Chapters 1 and 2.

The research on graph transformations leads to a careful re-thinking of the formal framework that should be used for the specification of graphs. The theory of *2-structures*, a specific relational framework, has turned out to be fruitful for the investigation of graphs especially in their relationship to graph transformations. The “static part” of the theory of 2-structures allows to obtain rather strong decomposition results for graphs, while the “dynamic part” of the theory employs group theory to consider transformations of graphs as encountered in networks. Chapter 6 presents the basic theory of 2-structures.

In order to specify classes of graphs and graph transformations as they occur in various applications (e.g. databases and database manipulations) one often needs quite powerful extensions of the basic mechanisms of graph replacement systems. One such extension is to control the order of application of the graph replacement rules. Chapter 7 presents a basic framework for *programmed graph replacement* systems based on such a control.

We believe that this volume together with the two forthcoming volumes - on specification and programming, and on concurrency - provide the reader with a rather complete insight into the mathematically challenging area of graph grammars which is well motivated by its many applications to computer science and beyond.

My thanks go first of all to the graph grammar community - the enthusiastic group of researchers, often with very different backgrounds, spread all over the world - for providing a very stimulating environment for the work on graph grammars. Perhaps the main driving force in this community during the last 7 years was the ESPRIT Basic Research Working Group COMPUGRAPH (Computing by Graph Transformation) in the period March 1989 - February 1992, followed by the ESPRIT Basic Research Working Group COMPUGRAPH II in the period October 1992 - March 1996. The initial planning of the handbook took place within the COMPUGRAPH project, and most of Volume I of the handbook has been written within the COMPUGRAPH period. The European Community is also founding now the TMR network GETGRATS (General Theory of Graph Transformation Systems) for the period from September 1996 to August 1999. We hope to complete volumes II and III of the handbook within the GETGRATS project. The gratitude of the graph grammar community goes to the European Community for the generous support of our research. We are also indebted to H. Ehrig and his Berlin group for managing the COMPUGRAPH and COMPUGRAPH II Working Groups, and to A. Corradini and U. Montanari for their work in preparing the GETGRATS project.

I am very grateful to all the authors of the chapters of this volume for their cooperation, and to the Advisory Board: B. Courcelle, H. Ehrig, G. Engels, D. Janssens, H.-J. Kreowski and U. Montanari, for their valuable advice.

Finally, very special thanks go to Perdita L  hr for her help in transforming all the separate chapters into a homogeneous and readable volume as it is now. Neither she nor myself could foresee how much work it would be - but due to her efforts we could bring the project to a happy end.

G. Rozenberg
Managing Editor
Leiden, 1996

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