Hierarchical Modeling and Adaptive Clustering for Real-time Summarization of Rush Videos

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Abstract— **In this paper, we provide detailed descriptions of a proposed new algorithm for video summarization, which are also included in our submission to TRECVID'08 on BBC rush summarization. Firstly, rush videos are hierarchically modeled using the formal language technique. Secondly, shot detection are applied to introduce a new concept of V-unit for structuring videos in line with the hierarchical model, and thus junk frames within the model are effectively removed. Thirdly, adaptive clustering is employed to group shots into clusters to determine retakes for redundancy removal. Finally, each most representative shot selected from every cluster is ranked according to its length and sum of activity level for summarization. Competitive results have been achieved to prove the effectiveness and efficiency of our proposed techniques, which are also fully implemented in the compressed domain. Our work does not require high-level semantics such as human object detection and audio signal analysis for summarization which provides a more flexible and general solution for this topic.**

Index Terms— **video rushes summarization, hierarchical modelling, adaptive clustering, TRECVID.**

I. INTRODUCTION

Video summarization, in which original videos are represented by either still-image based storyboard or short-clip based dynamic skimming, plays essential roles in efficient content-access, browsing and retrieval of large video databases [1-5]. In principle, the essential strategy is to choose the most meaningful parts of video to form the summary while ignoring the less important ones, which are often referred to as content of interests (COI). Consequently, how to define suitable COIs is inevitably dependent on both the application domain and the users upon whom the video is summarized. Due to the nature of its attractiveness and wide commercialization, sports video summarization has been intensively investigated among the existing efforts, covering soccer, baseball etc. [10, 13-14, 25, 34]. Other typical applications can be also found in news [32, 48], surveillance [6], movies [5, 21, 40, 42], home videos [28], and even stereoscopic sequences [45] as well as videotaped presentations [44]. Some general methodologies that can be applied to multiple application domains are also reported [8, 32]. To address the users' preferences, existing work also covered personalized and user-adaptive summarization techniques [10-11, 28]. Recent literature surveys on relevant techniques have been extensively reported in a number of sources [2, 17, 20, 36].

A. Related Work in Video Summarization

In general, existing attempts on video summarization can be characterized by four main steps, including i) video segmentation, ii) key frame extraction, iii) similarity-based clustering and iv) summary generation. Segmentation is used to partition original videos into small clips (shots and sub-shots) and then ranking these clips for summarization [6, 12-13]. To measure the similarity of clips, a group of most representative frames are extracted as key frames whilst many techniques have been proposed for key frame extraction [5-8, 11, 38, 44-45]. Meanwhile, the similarity between frames is measured by using simple histogram distance [1, 30, 32, 39-40, 42] and mutual information etc. [8]. In addition, selection of COIs including objects and events can be solved by introducing user-attention model and domain knowledge [3, 6, 41, 47]. In some work, graph theory [1, 46, 50] and dynamic programming [4, 9, 48] are applied for either video segmentation or optimal (suboptimal) clustering for summarization. In generating the summarized video, representative techniques include combination of key frames, video segments, or even a complex layout of these frames whose sizes are determined by their contained information [48].

Typically, video summarization is extracted by only using the information extracted from the video, called "internal summarization"[17]. In contrast, "external summarization" techniques employ additional information for interactive processing. The additional information includes manual annotation of the video such as those in MPEG-7 descriptors [31-32, 41] and knowledge about the users to achieve personalized summarization [10-11, 28]. For internal summarization, audio information is often utilized together with image features [14-15, 20, 26, 32, 34-35, 40-42], among which camera motion [8, 12, 16] and object motion [1, 7, 13, 44, 47] are frequently employed to model the significance of frames for summarization. Some work using text information overlaid to help with the video summarization is also reported [10].

In addition to these low level features, high level semantics are also extracted for more effective summarization. These semantics provide more accurate description of objects and events at higher level, in which representative techniques include object detection, tracking and event classification [6, 8, 13, 17, 45]. Since the defined objects and events are solely application dependent, such as human objects under surveillance environment and normal or abnormal events at an airport etc., it is normally difficult to extend these techniques to the task of general video summarization.

B. Summarization of Rush Videos in TRECVID

Unlike conventional video summarization, summarization of rush videos in TRECVID has some significant differences due to retakes in the unedited raw video sources [17-18]. These retake clips are from the same shot being captured under various circumstances, such as different camera positions or luminance conditions, changed background and even characters. In addition,

between or within these retakes there are junk frames which refer to unwanted and meaningless short clips, such as color bars, monochrome frames in white or black, etc. As a result, to complete video summarization for TRECKVID'08 rushes, retakes of the same shot need to be clustered and junk clips need to be eliminated.

As for video segmentation, shot boundary detection is usually employed [1, 8]. Since unedited rush videos are dominated by cuts, shot boundary detection becomes relatively easier. Normally, histogram and frame differences are measured and decision is then made via simple thresholding or complex classifying techniques for shot boundary detection. In thresholding, techniques reported include single threshold, multiple thresholds, or even adaptive thresholding, and classifiers can be SVM (support vector machine), or SOM (self-organizing maps neural network), etc. In addition, features can be extracted from pixel domain for accuracy or from compressed domain for efficiency.

To remove retakes, clustering of shots is applied by using KNN (k-nearest neighbors), PCA (principal component analysis), SIFT (scale invariant feature transform), agglomerative clustering, etc [18]. In most of these techniques, the similarity of two shots is measured by a combined similarity of each pair of their associated key frames. These key frames are representative images for each shot and they can be extracted either by sampling in a shot evenly, or targeted selection via certain criteria. The principle of those criteria are to choose frames of high differences from the two boundary frames in the shot or frames being midpoints between each pair of high curvature points from cumulative frame differences, etc. Since key frames are only separate points in a temporal clip of shots, this kind of clustering need to be further enhanced in order to achieve stronger robustness.

To rank segmented clips for summarization, detection of some high-level features is employed which include event detection, video object extraction, object tracking, face detection, and audio analysis [6, 14, 17-18]. Generally, clips of more human objects are considered to have more importance and hence assigned with higher ranks. Certain feature analysis can be used to remove junk frames, as these unwanted small clips are found of some fixed pattern in audio-visual appearances. It is worth noting that audio information can be useful in many aspects in this application, such as shot detection, filtering junk frames as well as clustering of retakes.

C. Contributions and Structure of the Paper

In this paper, we propose a new algorithm for video summarization, which is included in our submission for TRECVID'08 on BBC rush summarization. Firstly, input videos are modeled hierarchically where videos are structured with shot, sub-shots and other level of contents. Secondly, active or inactive segments in each sub-shot are attained on the basis of our defined activity level extracted from inter-frame difference. In addition, junk frames within each shot and between shots are also modeled and removed, and key frames are extracted. Based on these determined key frames, adaptive clustering is then applied to group retakes for redundancy removal. Finally, the most representative shot in each cluster is selected, and both its length and activity level are considered in determining the quota of distributed size for vide summarization.

The remaining part of this paper is organized as follows. In Section II, rush videos are modeled into a list of shot clusters including three categories of junk frames. Techniques on video structuring are presented in which shot and sub-shot are detected. Analysis and filtering of these junk frames are discussed in Section III. In Section IV, extraction of key frames from each shot and adaptive clustering of shots into clusters to filter retakes are described. How to generate summarized results is discussed in Section V. Experimental results and discussions are given in Section VI, and finally brief conclusions are drawn in Section VII.

II. Modeling and Video Structuring

In this section we will discuss how to model video rushes summarization in a top-to-bottom structure, and also how to segment videos into shots. Some essential concepts used are defined and explained including determination of V-units within shots and introducing *valid* and *active* frames in the shots.

A. Modeling

To achieve high performances of video summarization without compromising on its content descriptions, we propose to model videos in a hierarchical way containing several levels. Firstly, input videos are taken as a linear structure of sequential frames, which contains a list of shot clusters. Between each pair of clusters, there might be some junk frames like color bars, etc., namely H-cut, to indicate such changes. For each shot cluster, it has one or more retakes and each retake may contain three parts, i.e. start of retake (s_clip), video shot (shot) and end of retake (e_clip). In addition, each shot is divided into several V-units of continuous high activity levels, hence producing more important parts of the video for its summarizations. Inside the retakes, both s_clip and e_clip are junk frames and may refer to clapboard period and shaking camera period (after capturing), respectively.

Figure 1 illustrates our proposed hierarchical modeling and formal descriptions of rush videos, where the hierarchical structure is represented by formal language description. Details on how to decide various levels for video structuring is presented below, and how to filter and remove those junk frames is discussed in the next section.
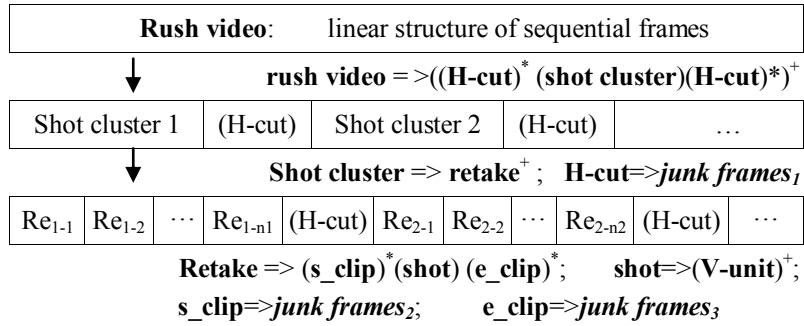

Figure 1. Formal description of our hierarchical model.

B. Shot Detection and Activity Level Determination

To achieve high efficiency and minimize the computing cost for the proposed algorithm, we extract the content features in compressed-domain. For each input frame f_i, its DC-images with Y, Cb and Cr components are extracted as $Y_{dc}^{(i)}, U_{dc}^{(i)}$ and $V_{dc}^{(i)}$, respectively. For the ith frame, its **DC-differencing image** is then defined as follows:

$$D(i) = \frac{|Y_{dc}^{(i)} - Y_{dc}^{(i+1)}| + |U_{dc}^{(i)} - U_{dc}^{(i+1)}| + |V_{dc}^{(i)} - V_{dc}^{(i+1)}|}{3} \tag{1}$$

For each $D(i)$, we extract **mean** and **standard derivation** represented as $\mu(i)$ and $\sigma(i)$. Let $p_1(i)$ and $p_2(i)$ be **two proportions** which represent the percentage of pixels in $D(i)$ that are larger than the two given thresholds $\lambda_1(i)$ and $\lambda_2(i)$. To characterize the distinction between cuts and non-cuts, we define: $\lambda_1(i) = \mu(i)/4 + 0.5$ and $\lambda_2(i) = \mu(i)/4$. Since $\lambda_1(i) > \lambda_2(i)$, we have $p_1(i) \le p_2(i)$. As $\lambda_1(i)$ and $\lambda_2(i)$ are dependent on $\mu(i)$, which is estimated in line with input videos, such design presents an adaptive thresholding mechanism, which makes $p_1(i)$ and $p_2(i)$ robust to the luminance changes across frames inside the video shot.

For most of the cuts, they are found appearing as a peak in the sequence of $\mu(i)$ and $\sigma(i)$. The peak here reflects the fact that frame difference is larger during a cut but turns smaller before or after the cut. Normally, larger $\mu(i)$, $\sigma(i)$ and $p_2(i)$ are more likely to indicate a potential cut. Rather than simply thresholding, we introduce three separate likelihoods, $\ell_i(\mu)$, $\ell_i(\sigma)$ and $\ell_i(p_2)$, and a combined cut likelihood ℓ_i for cut detection. The main reasons why the likelihoods in Eq. (2) are defined can be summarized as follows. Firstly, for cuts we have their $\mu(i)$ and $\sigma(i)$ values much larger than those of $\mu(i-1)$ and $\sigma(i-1)$, respectively. Therefore, $1-\mu(i-1)/\mu(i)$ and $1-\sigma(i-1)/\sigma(i)$ are good measures as likelihoods to indicator how likely a cut occurs. Secondly, a cut will lead to a large value of $p_2(i)$, where $p_2(i) \in [0,1]$, which corresponds to a relative large portion of changed blocks in the DC-image. For many cuts, their $p_2(i)$ values are found quite small, i.e. less than 0.5. To assign appropriate likelihoods to such cuts, we set the corresponding likelihoods as $sqrt(p_2(i))$ so that low values of $p_2(i)$ may still yield high likelihoods.

$$\ell_i(\mu) = 1 - \mu(i-1)/[3\mu(i)]$$
$$\ell_i(\sigma) = 1 - \sigma(i-1)/[2\sigma(i)] \qquad (2)$$
$$\ell_i(p_2) = sqrt(p_2(i))$$

$$\ell_i = [\ell_i(\mu) + \ell_i(\sigma) + \ell_i(p_2)]/3 \qquad (3)$$

It is worth noting that in our system ℓ_i is considered as an overall measurement of *activity level* within the frame. The reason here is that it reflects certain degree of content changes caused by either global motion such as camera movements or large local motion of moving objects. Such content changes will provide useful clues in extracting meaningful frames for summarization in which shots of high or low activity levels correspond to more or less interesting/exciting parts in a video.

When ℓ_i is larger than a threshold t_l, say 0.65, a cut candidate is claimed and further validated by using phase-correlation based similarity. In fact, this is a simplified version of our techniques in shot cut detection entered for TRECVID'07 competition on shot boundary detections. Further details can be found in [19].

C. V-units Determination

Following shot cut detections, the input video is segmented into a series of shots. Inside each shot, all the frames can be classified into two classes, referred to as valid frames (i.e. normal) and junk frames, where the latter covers those from H-cut, s_clip and e_clip as described above. For all the valid frames, we further classify them into active and inactive ones by checking if their associated activity levels are larger than a given threshold t_a or not. In this process, higher level of activity means apparent content changes in consecutive frames, which may refer to camera motion or large object motion. As a result, more priority should be given in formulating summarization videos.

In addition, we introduce a concept of V-unit, which is defined to describe continuous active frames within a shot. Since the movement of an actor or the camera may pause for a short period and show some gaps in the extracted active frames, it is necessary to extend the directly obtained V-unit to merge with its neighboring active frames provided that their gaps are small, i.e. less than a given gap threshold. In our proposed algorithm, we set this gap threshold as t_g =6 frames, which is equivalent to around 0.25 sec of real-time play at 25 frames per second. As human vision system is less sensitive to short video sequences, the V-unit candidates are further validated as such that the number of active frames included should be more than $2.5 t_g$, which corresponds to three-fifth

second of real-time play. If the gap between active frames is larger than t_g, the corresponding active frames will be regarded as the start of a new V-unit. Consequently, there can be more than one V-units in a shot. On the other hand, there can be no V-unit at all in a shot due to low level of activities or short length of active frames.

Figure 2 illustrates one example of such V-unit embedded inside a shot with feature curves and relevant information attached, which is extracted from the sequence of "MS2201020.mpg" inside the test data set given by TRECVID'08. As seen, from frame #0 to frame #180, continuous *activity level* curve is plotted under which typical frames are shown with their status as valid (normal) or junk. For junk frames, three further categories are also given. There are two shot changes in the plot between frame #21 and #22, and between #120 and #121, with which higher level of activities is associated. In addition, frames between #0 and #21 are all junk frames in H-cut category of color bar, and frames between #121 and #180 are all junk frames with clapboards in category of s_clip.

In the shot between frame #21 and frame #120, it contains valid frames from frame #21 to frame #73 and junk frames from frame #74 to frame #120. It is interesting to note that the junk frames of e_clip category involve motion in large microphones and sometimes it is difficult to filter these frames due to visual consistency. In other words, it is hard to say whether the moving objects are within the real scene or not without the domain knowledge. In this case, additional information such as speech signal might be useful as we can recognize corresponding command words from the director such as "cut", etc. Further, active frames from all valid frames are labeled to contain one continuous segment (from frame #24 to frame #42) and two separate frames (frame #22 and frame #49). Since we have t_g =6, the continuous segment is merged with the separate frame #22 and forms a whole V-unit. Other separate active frames are ignored.
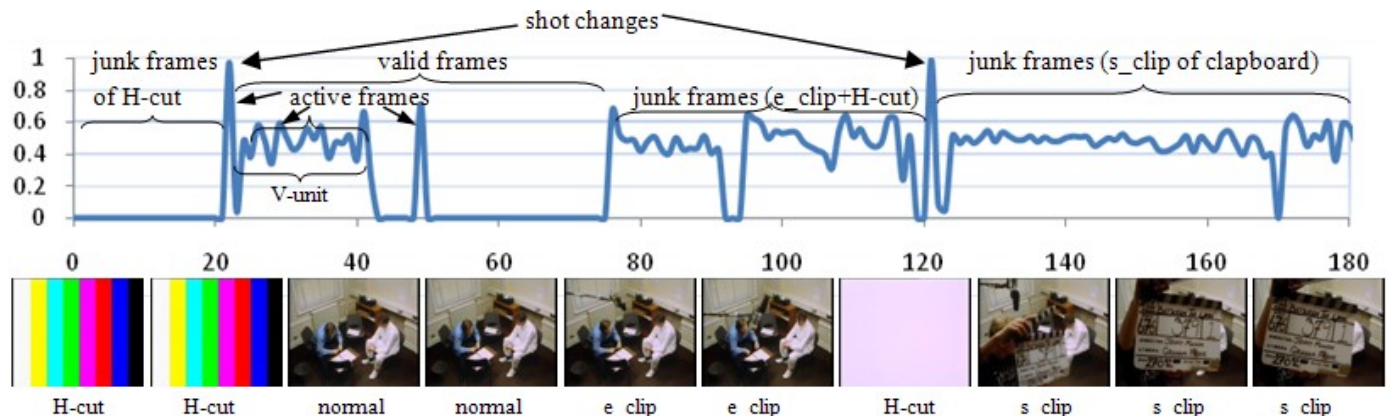

Figure 2. Explaining the concepts of "vUnit", "valid frames" and "active frames" using plotted curve of activity level (y-axis) vs. frames (x-axis), where representative frames are also shown which are categorized into normal frame and three kinds of junk frames (H-cut, s_clip and e_clip).

III. Filtering Junk Clips

To ensure that the V-unit extraction is effective and the interference from junk frames is minimized in generating video summarization, we propose a filtering technique to remove several typical junk frames, including those inside H-cuts, s_clips and e_clips.

A. Filtering H-cut Frames

As junk frames in H-cut contain color bars and monochrome frames in black/white etc. histogram analysis could be an effective way for their detection and removal. Figure 3 shows a typical example of junk frames inside a H-cut, where its luminance histogram is also illustrated. As seen, the bins contained in the histogram are very limited and discrete. Therefore, junk frames can

be detected and removed by examining the histogram of the component $Y_{dc}^{(i)}$ by exploiting such property. In other words, we can identify the highest peak in the histogram and then count the number of bins whose heights are no less than one-fifth of this peak to determine whether the frame is a junk or not. Let $n_c^{(i)}$ be the count for the number of bins greater than or equal to a threshold, say τ_c within 256 bins in total, junk frames are detected by the condition test: $n_c^{(i)} \geq \tau_c$.

To determine the threshold τ_c, we propose to use Bayesian minimum error classification criterion. Given a group of typical sample frames including both normal contents and H-cut images, n_c is obtained for each frame, and conditional probabilities of $p(normal \,|\, n_c)$ and $p(H-cut \,|\, n_c)$ are also calculated. The threshold τ_c is determined to satisfy:

$$\tau_c = \arg\min_{\tau}[\int_0^{\tau} p(normal\,|\,n_c)dn_c + \int_{\tau}^{255} p(H-cut\,|\,n_c)dn_c] \tag{4}$$
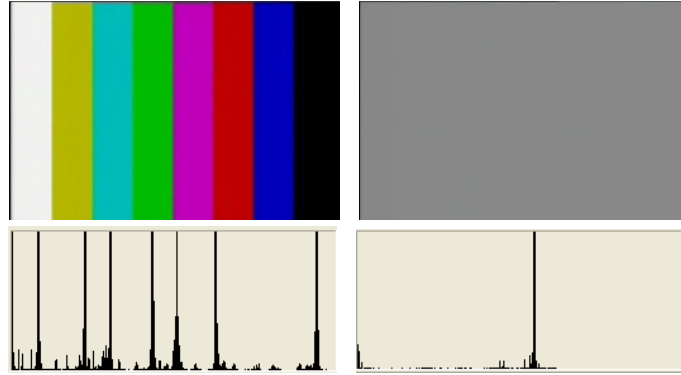

Figure 3. Examples of two junk frames from H-cut category (top) and their associated luminance histograms (bottom).

B. Filtering Clapboards from s_clip Frames

As for s_clip, it is mainly caused by clapboard as shown in Figure 4(a). When the clapboard moves in or out of the scene, an apparent change is caused, which can be exploited for its detection. However, to differentiate between this change from the content change used for cut detection, further analysis is required and some unique feature needs to be identified. To this end, we have examined a range of features including the associated luminance energy, which is defined as follows:

$$E_y(i) = E_{0\_y}^{-1} \sum_j [Y_{dc}^{(i)}(j)]^2 \tag{5}$$

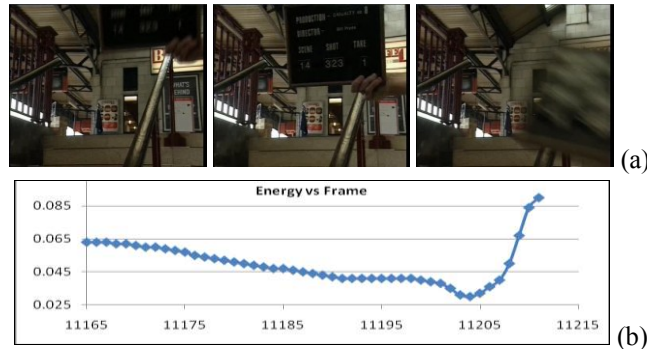where E_{0_y} is used to normalize $E_y(i)$ within [0,1].

Figure 4. Three frames to show the process of moving clapboard in and out of the scene (a) and change of energy during this process (b).

Figure 4 illustrates an example of such s_clip containing three clapboard frames and their corresponding energy values. As seen, the energy change across clapboard frames presents the feature that a slow decrease and then a fast increase is often incurred across these frames. This is because generally clapboards are slowly put in but quickly removed from the scene. Therefore, we identify the clapboards by detecting such energy changes, together with another cue for clapboard events, which is high activity level, referring to motion-caused apparent content changes. In addition, such clapboard events usually appear at the beginning of the detected shots, which is also taken into consideration in detecting such events.

C. Filtering e_clip Frames

In e_clips, junk frames are caused by irrelevant scenes, which are typically happened when the camera is still on after the request of "cut". Consequently, strong motions can be found in the captured images prior to a real cut, which is caused by the shaking camera in order to follow the command of "cut" and switch the camera off. According to strong motions and apparent content changes, this kind of junk frames may be classified as active frames and detected as V-unit. However, they can be eliminated by examining their visual appearances. Our model described in Section II actually specifies that all V-units prior to every detected shot cut are possible to be e_clip frames. They are validated if the two conditions are satisfied, which include: (i) there exist continuous frames with large activity levels in the V-unit; (ii) Content of the V-unit presents significantly large difference from that of its neighboring V-units within the same shot. Details in defining the content similarity between frames can be found in Section IV.

IV. Determining Retakes

With junk frames being removed and all shots being classified into V-units, the next step in our proposed algorithm for video summarization is to remove further redundancy caused by retakes. In practice, retakes are often generated by repetition of shooting the same scenes, events or activities, and thus directors can have a number of choices towards his or her final video production. To this end, retakes can be generally described as video shots with similar content, and thus redundancy exist among all such relevant video shots. As no prior knowledge is generally available about the retakes inside the input videos, we propose to cluster all the divided shots into content similar groups. As a result, all retakes are expected to be included in the same cluster, and thus selection of representative shot from each cluster could effectively remove all the retakes. In practice, however, the number of retakes is unknown and thus an adaptive clustering scheme is required in this case instead of those fixed clustering schemes.

A. Similarity of Selected Key-frames

First of all, we define three key frames for each V-unit including the first, the last, and the middle frame. The middle frame is of maximum activity level over the central half part of the V-unit. Similarity between key frames is measured by using histograms of their DC-images. Let $Y_{dc}^{(i)}$ and $Y_{dc}^{(j)}$ be two DC-images, and their luminance histograms are h_i and h_j with K bins. It is found from our investigation that histogram intersection, $c_s(i,j)$ as defined in (6), fails to provide appropriate similarity measurement in such a context, although it has been widely used in retrieval applications. Instead, we propose a histogram correlation $c_h(i,j)$ and image difference $c_d(i,j)$ instead. These are defined in equations (7) and (8):

$$c_s(i,j) = \sum_{k \in [1,K]} \min(h_i(k), h_j(k)) / K \qquad (6)$$

$$c_h(i,j) = \frac{\sum_k h_i(k)h_j(k)}{\sum_k [\max(h_i(k), h_j(k))]^2}, k \in [1, K] \tag{7}$$

$$c_d(i,j) = 1 - \frac{\sum_{m,n} |Y_{dc}^{(i)}(m,n) - Y_{dc}^{(j)}(m,n)|}{\min[\sum_{m,n} Y_{dc}^{(i)}(m,n), \sum_{m,n} Y_{dc}^{(j)}(m,n)]} \tag{8}$$

An overall similarity of images can be attained as:

$$c(i,j) = w(i,j)[c_h(i,j) + c_d(i,j)]/2 \tag{9}$$

$$w(i,j) = \frac{2n_c(i)n_c(j)}{[n_c(i)]^2 + [n_c(j)]^2} \frac{\min(e(i), e(j))}{\max(e(i), e(j))} \tag{10}$$

where $e(i)$ and $e(j)$ refer to the energy of the two DC-images $Y_{dc}^{(i)}$ and $Y_{dc}^{(j)}$, and $w(i,j) \leq 1$ is a weighting factor for the similarity value $c(i,j)$, which is calculated in considering their differences among the values of energy and among the values of $n_c(.)$. As seen in (10), large difference corresponds to a small weight value and vice versa. The closer $n_c(i)$ and $n_c(j)$ are in two frames, the more likely $w(i,j)$ is to be 1, and thus no punishment is made for the similarity $c(i,j)$. Otherwise, $c(i,j)$ is reduced due to the disparity between $n_c(i)$ and $n_c(j)$. Same rules are also applied to $e(i)$ and $e(j)$ as we require small difference of energy between similar frames.

B. Adaptive Shot Clustering

Retakes are essentially repetitive image clips of the same shot captured under various conditions, such as change of camera position, lighting configuration and acting rhythms, and each of them may be "cut" at anytime during the capturing process. Consequently, their contents and lengths may change, which have inevitably caused new problems for their detection. One main problem here is that each retake may be detected as a shot, thus we need to group all detected shots into clusters as such that each cluster contains all retakes of the same shot.

Similarity of shots is measured by the similarity between key frames in each shot. Let s_m and s_n be two shots and their corresponding sequences of key frames are v_m and v_n, respectively, the similarity of these two shots are denoted by $\rho(s_m, s_n)$, which is defined as follows.

$$\rho(s_m, s_n) = \frac{1}{|v_m|} \sum_{i \in v_m} \max_{j \in v_n}(c(i,j)) \tag{11}$$

where i and j are indexes of key frames in s_m and s_n, respectively, and $|v_m|$ denotes the number of key frames in s_m.

Let the list of shots form q clusters, an optimal number of q is decided by minimizing (12), i.e. minimizing d_{intra} whilst maximizing d_{inter}.

$$q = \arg\min_{q'} \left[\frac{d_{intra}(q')}{d_{inter}(q')} \right] \tag{12}$$

where $d_{intra}(q')$ and $d_{inter}(q')$ respectively denote intra-class compactness and inter-class disparity among shot clusters when they are grouped into q' classes.

For a given shot cluster g_c, its intra-class compactness is defined as the average dissimilarity between each pair of different shots within the cluster as follows.

$$d_{intra}(g_c) = \frac{2}{N_c(N_c-1)} \sum_{m,n} [1 - \rho(s_m, s_n)] \tag{13}$$

where N_c denotes the number of shots in g_c, and $1 - \rho(s_m, s_n)$ refers to dissimilarity between two shots s_m and s_n, and $s_m, s_n \in g_c$.

$d_{intra}(q)$ is defined as the average distance of all individual $d_{intra}(g_c)$ where $c \in [1,q]$, i.e.

$$d_{intra}(q) = q^{-1} \sum_{c=1}^{q} d_{intra}(g_c) \tag{14}$$

As for inter-class disparity, it is defined as an average distance between each pair of sequential clusters in (15). Here, calculating similarity between each pair of clusters is unnecessary due to the fact that retakes of one shot are adjacent (see our model in Section 2). Therefore, it is adequate to check the dissimilarity of sequentially clusters in determining $d_{inter}(q)$. This is shown below.

$$d_{inter}(q) = \frac{1}{q-1} \sum_{c=1}^{q-1} dist(g_c, g_{c+1}) \tag{15}$$

where $dist(g_c, g_{c+1})$ denotes distance of two clusters which is further defined in (16) as the average of the minimum distance between each shot in g_c and all other shots in g_{c+1}.

$$dist(g_c, g_{c+1}) = \frac{1}{N_c} \sum_{m \in g_c} \min_{n \in g_{c+1}} (1 - \rho(m,n)) \tag{16}$$

In (16), the minimum distance is utilized so that a very small distance can be obtained if retakes of the same shot are misclassified into two different clusters. Consequently, an overall inter-class cluster turns small in (15) which will help to correct such errors in applying (12) to determine the optimal class number q.

V. GENERATING VIDEO SUMMARIES

Following the proposed adaptive clustering of shots, all retakes are arranged within the same cluster. To complete the video summarization, therefore, we propose to select one representative shot out of each cluster to generate the final summarized video. In practice, as the length of retakes can vary since each of them can be cut in the middle upon the request of the director, we simply choose the most representative shot as the longest one in each cluster, in order to maximize the preservation of visual content for the original input videos. Consequently, summarization of each cluster is then done by selecting frames in the corresponding most representative shot, and all other shots in the cluster will be ignored in video summarization.

To meet the requirement set up by TRECKVID08, we allow an adjustable upper limit of the summarization ratio (between 0 and 1) in video summarization, i.e. the target video will have frames no more than a fixed percentage of the original video. Next, we will discuss how to assign the size quota to all selected and most representative shots from each cluster, and how to generate video summarization. The principle here is that, for those clips with lower activity level, the re-sampling rate is coarse, i.e., the interval between inserted frames is high. On the contrary, clips with higher activity level, the re-sampling rate would be fine. This is consistent with the expectations of our human perceptions in viewing videos. Relevant techniques are discussed in details as follows.

For each selected shot s, a value of rank is assigned by the summation of activity levels over all its valid frames as defined below:

$$r(s) = \sum_{i \in s} a_i \tag{17}$$

where a_i refers to the activity level of the ith valid frame inside shot s.

Let R_0 be the length of the original video in frames, the length of the summarization video should be no more than λR_0 frames, where λ is a predefined upper limit of the summarization ratio (TRECKVID'08 specifies $\lambda = 0.02$). Therefore, each ranked frame corresponds to $\lambda R_0 / R$ frames inside the summarization video, where $R = \sum_j r(s_j)$ is the length of summarization video. For the convenience of description, we call $\lambda R_0 / R$ as a *rank frame ratio*. According to the determined rank $r(s)$, shot s can be summarized into $r(s)\lambda R_0 / R$ frames.

To determine the specific value of $r(s)\lambda R_0 / R$ inside the shot s for summarization, we take the first *active* frame from each shot as the initial summarization video frame, and then carry out an iterative process to select the remaining frames. If frame i_1 has been selected, the next frame to be selected as denoted by i_2, should be the first *active* frame satisfying that the accumulated activity level between i_1 and i_2 is no less than the rank frame ratio $\lambda R_0 / R$.

$$\sum_{i_1 < i \le i_2} a_i \ge \lambda R_0 / R > \sum_{i_1 < i < i_2} a_i, \qquad i \in s \tag{18}$$

In (18), index i can be discontinuous as it only refers to *active* frames in the shot s.

It is worth noting that the above re-sampling is nonlinear and unevenly distributed over frames. In terms of the accumulated activity levels, however, the sampling process could be regarded as even. If a video clip contains high activity level caused by camera/object motion or content changes, for example, its re-sample rate becomes small. On the other hand, a video clip of low activity level will have a much higher re-sample rate due to its smooth contents contained. This is consistent with our understanding of video contents and identification of importance over sequence of videos. Some interesting results are shown and discussed in the next section.

As mentioned before, video clips with too short lengths are generally unnoticeable to our human vision system. To this end, only shots which are determined to have more than t_g frames of quota size are included in generating the summarization. Parameter t_g is defined in Section II(C) by considering the characteristics of human vision systems. On one hand, it can remove short-lived noisy events. On the other hand, it helps to further reduce the size of generated summarization. As a result, the final summarization will appear less than the predefined overall quota size $\lambda R_0 / R$.

After removal of short segments, the candidate frames are ready to generate the summarization. In general, the summary results can be another video sequence, a frame list or even a specially designed storyboard [48]. In our system, it is required that the summary videos should have a number of content factors the same as the original videos, which include compression standard, frame size and frame rate. However, for each candidate frame, we put some text information in the image to indicate its video source and original frame number (at the top-left) as well as our team name (at the bottom right). In addition, we also added one artificial frame between each pair of frames across a cut to indicate the scene change transition. This is done for the convenience of manual evaluation of our summarization results. An example of such generated video summarization is illustrated in Figure 5, where the middle frame is the artificial frame we added between the two frames, where a cut is detected.

Figure 5. Generated frames for video summarization with embedded texts and artificial one-frame dissolve.

VI. RESULTS AND DISCUSSIONS

The proposed model and techniques have been fully tested by using the data from TRECVID'08 and the relevant results and evaluations are reported below. Generally, video summarization is a subjective task in which the quality of the summarization is solely dependent on specific application domains. For example, sports video is emphasized more on some highlights such as a goal event, and for news and movie videos the contents of interest will be different. Therefore, clearly defining these interested events over a given data set in *a prior* is a must for further evaluations. The data set and evaluation rules of our proposed algorithm are described in details as follows.

A. Data Set and Evaluation Criteria

In 2008, the test data for BBC rushes has 39 video clips with about 1545500 frames (about 17.2 hours at 25fps) in MPEG-1 format in which the shortest and the longest sequences are less than 10 minutes and near 37 minutes, respectively. These test sequences are unedited video footages, which are extracted mainly from five series of BBC drama programs. These programs have covered a wide range of sources, including one historic drama in London in the early 20th century, a series on ancient Greece, a contemporary detective series, a police drama, series on emergency service and also miscellaneous scenes from other programs.

In the rush videos, indoor and outdoor scenes of people's daily life are included. As a result, the contents of interest are closely relevant to these activities, which are defined in two aspects including objects and events. For objects, they refer to both human actors and other entities. Regarding events, they are generally caused by movement of objects and cameras. To this end, we propose to consider the following four types of contents to generate the summarized videos:

1) Objects (no event or camera motion), like a car, an old woman, a room, etc.;
2) Objects under camera motions, such as pan to the car and zoom into the man, in fact only zoom in/out (including close-up) and pan are emphasized now;
3) Objects in events, such as people talking and red hot-air-balloon ascending;
4) Objects under camera motion whilst in an event.

With the defined contents of interest, nine criteria are utilized by TRECKVID08 to evaluate each group of generated summary results. There criteria are summarized and briefly described in Table 1 and further details can be found in [18].

Except DU, XD and RT, all other quantitative measurements above are obtained subjectively as the average or median judging results from three human observers in viewing each of the 39 summarized videos. In addition, TT and VT are used to evaluate the usability of the generated summary, i.e. how easy for a general user to seek for included contents and make a decision. Therefore, these criteria can be classified into three main groups, including: (i) objective measurements, such as DU, XD and RT; (ii) usability measurements, such as TT and VT; and (iii) subjective measurements, such as IN, JU, RE and TE. These will be utilized for evaluation and analysis of the corresponding results in the following sections.

Table 1. Descriptions of nine criteria used for evaluation.

Criteria	Comments
DU: duration of the summary in seconds	The upper limit is 2% of original videos; shorter summary will be considered better than longer ones.
XD: difference between target and actual summary size	Positive or negative XD values mean that the overall summary size is less or larger than the given upper limit, i.e. a successful/unsuccessful summary set.
IN: fraction of inclusions found in the summary	This stands for percentage of important events/objects within [0,1] included in the generated summary.
JU: degree of junk frames in the summary	This is measured in five levels from 1 to 5 and 5 means least junk videos found in the summarized videos.
RE: degree of duplicate video in the summary	This is also measured in five levels and 5 means least redundant contents found in the summary.
TE: degree of pleasant tempo/rhythm in the summary	This is also measured in five levels with 5 standing for the best.
TT: total time spent in judging the inclusions in seconds	This is used to check if the summary is easy for understanding when manually evaluated by users in searching certain events and objects
VT: total video play time except pause period in judging IN	Similar as TT
RT: total running time in seconds	This is used to evaluate the efficiency of each system proposed.

B. Overall Results

Due to repetitive shot retakes, these rushes have a great potential for efficient summarization. Some manual experiments have indicated that a 10% summary might be sufficient to cover all useful contents and exclude all the redundancy and meaningless junk frames. TRECKVID08 sets an upper limit of 2% for automatic video summarization. This year, there are 44 teams worldwide registered for this task, and eventually only 32 teams have made their submissions with 43 groups of results (excluding one incomplete submission). According to the final results announced by the organizer of TRECVID, the evaluation results of all the submissions are summarized in Table 2 and our results (in light-grey background with a system ID "BU_FHG.1") can be highlighted as follows.

- Measured in terms running time, our system spends only 9270s (6.07 times of real-time video playing), achieving the 4th fastest or the 3rd fastest (considering two submissions from GTI-UAM as one) whilst yielding competitive results under other criteria. If the benchmark provided by University of Carnegie Mellon is ignored, which only contains simple re-sampling of original input videos, our proposed algorithm achieves the 3rd fastest or the 2nd fastest;

- Measured in fraction of inclusions found in the summary, our results scored 0.57/0.58 in average/median evaluations, achieving the 7th/8th best among all the submissions. Note that the results of higher IN scores may contain more junk and repeated videos, i.e. less JU and RE scores;

- For duration of the summary, the average and median length of our submission is 22.92s and 22.9s, which is 8.79s and 7.94s less than the upper limit of 2% set up by TRECKVID'08.

Regarding the relative low TE score achieved in our results, there are two main reasons: Firstly, this criterion was only

introduced in the evaluation stage, which was unknown during the algorithm design and implementation. As a result, it was not taken into consideration when our algorithms were developed. Secondly, since the summarization generated by our approach is composed of separate frames, this will inevitably lead to low score of TE. One possible improvement is to generate summarization as a set of short clips with audio support, which will significantly enhance the scores of TE and IN yet it may degrade other scores such as RE and JU.

Table 2. Typical results from TRECVID'08 on BBC rush summarization in decreasing IN score order.

System	Objective measures			Usability		Subjective scores				Overall scores					
	DU	XD	RT	TT	VT	IN	JU	RE	TE	10*PE	rank	PF-0.1	rank	PF-0.15	rank
cmubase3.1	33.9	0.40	678	58.67	34.67	0.83	2.33	2.00	1.33	1.141	36	0.59	15	0.224	3
CMU.2	33.9	0.40	261939	56.67	35.67	0.81	3.00	2.00	1.67	1.434	24	0.41	31	0.063	32
CMU.1	33.9	0.40	261939	53.33	33.00	0.80	3.00	2.00	1.67	1.416	26	0.40	33	0.063	32
asahikasei.1	19.5	9.64	17417	34.67	20.00	0.69	3.00	3.00	1.67	3.185	1	1.19	1	0.277	1
VIREO.1	23.6	7.63	382298	38.00	25.00	0.67	3.67	3.00	2.67	3.126	2	0.86	4	0.126	13
UPMC-LIP6.1	33.6	0.82	144310	51.33	34.67	0.67	2.33	2.67	1.67	1.241	35	0.37	35	0.064	31
GTI-UAM.2	34.1	0.20	3915	48.00	36.67	0.58	3.33	3.00	2.67	1.699	15	0.74	10	0.215	4
BU_FHG.1	22.9	7.94	9270	38.67	24.67	0.58	3.00	3.00	2.00	2.279	7	0.91	3	0.232	2
ATTLabs.1	29.7	4.82	92098	46.00	31.33	0.58	2.67	3.00	2.33	1.564	18	0.49	20	0.090	20
ipan_uoi.1	28.0	5.17	35818	41.33	30.33	0.56	3.33	3.33	2.33	2.218	8	0.77	8	0.161	8
GTI-UAM.1	34.3	0.12	4746	46.67	37.00	0.55	3.33	3.00	2.67	1.602	17	0.68	12	0.193	7
nttlab.1	25.0	1.05	211026	42.33	27.00	0.50	2.67	3.00	1.67	1.602	16	0.47	21	0.075	27
DCU.2	33.3	1.43	49849	46.33	34.33	0.50	3.00	3.33	2.67	1.500	22	0.50	17	0.100	17
TokyoTech.1	32.4	1.58	172777	41.67	34.33	0.47	2.67	3.33	3.00	1.290	34	0.38	34	0.063	32
PolyU.1	26.0	3.07	128847	36.00	27.00	0.47	3.67	3.67	3.33	2.435	5	0.75	9	0.129	12
FXPAL.1	34.4	0.23	119020	44.67	36.00	0.47	3.33	3.33	3.33	1.515	21	0.47	32	0.082	24
ETIS.1	33.1	0.92	609233	47.33	34.00	0.47	3.00	3.67	2.00	1.563	19	0.41	30	0.056	37
ATTLabs.2	30.9	3.45	92098	41.00	33.00	0.47	3.00	3.00	3.00	1.369	30	0.43	28	0.079	25
UG.1	23.8	2.37	11757	35.00	28.00	0.45	3.33	3.33	2.67	2.097	10	0.82	6	0.201	6
DCU.1	33.1	1.30	51534	45.00	35.67	0.45	3.00	3.33	2.67	1.358	31	0.45	24	0.090	20
QUT_GP.1	21.5	7.17	31135	32.67	24.33	0.44	3.67	3.67	3.33	2.756	4	0.98	2	0.208	5
PicSOM.1	22.1	4.05	389344	32.33	25.00	0.44	3.33	3.33	3.00	2.208	9	0.60	14	0.088	23
FXPAL.2	34.4	0.23	118230	46.00	36.33	0.44	3.67	3.00	3.33	1.408	27	0.43	27	0.076	26
thu-intel.2	19.6	12.32	207654	31.67	21.67	0.42	3.67	3.67	3.00	2.886	3	0.84	5	0.135	11
thu-intel.1	28.1	4.09	149754	39.00	28.67	0.42	3.67	3.67	3.00	2.013	11	0.61	13	0.102	16
NII.2	32.6	0.75	34047	41.67	34.33	0.42	3.33	3.33	2.67	1.429	25	0.50	18	0.105	15
IRIM.2	34.4	-0.10	1661136	44.33	37.00	0.42	3.33	3.33	2.67	1.354	32	0.32	39	0.038	42
EURECOM.1	34.3	-0.01	295747	44.67	37.67	0.42	2.67	3.33	2.67	1.089	39	0.30	40	0.047	40
UEC.1	32.3	2.06	46291	43.00	34.33	0.39	2.67	3.33	3.00	1.074	40	0.36	36	0.073	28
IRIM.1	34.4	-0.08	610453	42.67	36.00	0.39	3.33	3.67	3.00	1.386	28	0.36	37	0.050	39
Brno.1	30.0	4.42	42505	38.00	31.67	0.36	3.00	3.67	3.00	1.321	33	0.45	25	0.092	19
NHKSTRL.1	32.3	0.90	25479	40.67	35.67	0.33	3.00	3.67	3.33	1.125	37	0.40	32	0.089	22
REGIM.1	28.0	2.65	56997	36.67	30.67	0.31	3.67	3.67	3.33	1.491	23	0.49	19	0.097	18
NII.1	20.6	13.32	891891	30.00	23.00	0.31	3.67	3.33	2.67	1.839	13	0.46	23	0.060	36
COST292.1	22.8	8.44	37666	31.00	24.67	0.31	3.67	4.00	3.33	1.996	12	0.69	11	0.143	10
JRS.2	14.0	14.20	55526	26.67	18.33	0.28	3.00	4.00	2.33	2.400	6	0.80	7	0.156	9
VIVA-LISTIC.1	22.1	3.92	133177	31.00	25.67	0.25	3.33	3.67	3.33	1.382	29	0.42	29	0.072	29
K-Space.2	34.1	0.02	278689	43.33	37.67	0.25	3.67	3.67	2.67	0.987	41	0.28	41	0.043	41
K-Space.1	19.7	11.62	293658	29.00	22.33	0.25	3.33	3.67	3.00	1.551	20	0.44	33	0.067	30
VIVA-LISTIC.2	22.1	2.92	104497	29.33	24.33	0.22	3.00	3.67	3.33	1.096	38	0.34	38	0.061	35
JRS.1	18.5	13.38	52473	25.33	20.00	0.22	3.67	4.00	3.33	1.746	14	0.58	16	0.115	14
Sheffield.1	50.1	-16.83	48826	61.67	54.00	0.14	3.00	3.67	3.33	0.308	43	0.10	43	0.021	43
GMRV-URJC.1	13.0	23.02	66623	21.67	19.00	0.08	3.33	4.00	3.33	0.820	42	0.27	42	0.051	38

As these nine measurement criteria are difficult to make specific analysis and unanimous indication for the performance interpretation, we propose a combined measurement PF below

$$PF = \frac{IN * RE * JU}{DU} \times RT^{-h} \tag{19}$$

If $h=0$, PF becomes PE, a special case which was defined in [22] as an overall score for summarization evaluation. Since XD can be determined by DU and the predefined upper limit of summary size, it is not used in our overall scoring. The other two objective measurements of DU and RT are utilized in our defined PF, where RT is the new factor introduced in comparison with PE. We think this is important as RT is a good indicator to show the complexity of a summarization algorithm for practical implementation and applications, and the parameter $h>0$ is used to adjust the weight or influence of RT in PF.

If h is too large, say $h>h_1=0.45$, the whole results become very similar to the rank of RT only which is inappropriate in such a context. In contrast, if h is too small, say $h<h_0=0.04$, the effect of RT becomes meaningless. In practice, we have $2h_0<h<h_1/2$, i.e. $0.09<h<0.23$ and $h=0.15$ is suggested. Consequently, we propose to carry out the following overall evaluation.

- Considering PE, our results are ranked the 7th best among 43 groups of results from 32 teams. If the running time RT is also considered and thus the overall score is revised as PF, our results will be ranked as the 3rd or the 2nd best.

To provide a clearer picture for the status of the proposed algorithm in comparison with the existing techniques, we make a comparative analysis upon the differences between the proposed algorithm and others with better PE/PF scores, which include "asahikasei.1", "VIREO.1", "thu-intel.2", "QUT_GP.1", "PolyU.1" and "JRS.2" in TRECKVID08. While details of the work in "asahikasei.1" are not clear, the main techniques used in "VIREO.1" include object and face detection, camera motion estimation, key-point matching and tracking, audio classification and speech recognition, and it also needs supervised learning of typical samples before removal of junk frames. In "thu-intel.2", face detection and audio analysis are required, together with motion magnitude for clustering and optical character detector for detecting clapboards. In "QUT_GP.1", a spanning tree is employed for clustering with detected faces for summarization. "PolyU.1" utilizes both audio and visual information for summarization with removal and pruning of shots and key frame selection. In "JRS.2", hidden Markov model and rule-based approach are used with detected faces for summarization.

In summary, all the systems above require complex processing to detect high-level semantic objects for summarization such as face detection, audio analysis and feature tracking, etc. Since face and audio information is not always available, this has constrained the applications of these methods. In contrast, our proposed algorithm does not include any complex processing above yet operating entirely in compressed domain. Therefore, our proposed algorithm is more suitable for generic summarization, where real-time analysis and implementation is required, which is very essential for content-based online search and retrieval.

C. Intermediate Results

There are four main groups of intermediate results produced during the processing, which include those from shot cut detection, key frame extraction, filtering junk frames and clustering of retakes. In the following, some typical intermediate results are also presented and analyzed in details to show the performance of the proposed algorithm.

Firstly, shot change detection is utilized to segment the original videos into clips of shots. As mentioned earlier, special editing effects such as fade, dissolve and wipe, etc. are excluded from unedited video rushes, hence only cut detection is necessary for our test data. Regarding overall performance, cut detection achieves 99.1% as recall rate and 98.9% as precision rate, which is better than our results reported in [19] due to the fact that the test data sets given this year are relative simpler and no gradual transitions are included. Figure 6 illustrates examples of our detected cuts from one of the test sequences, in which only the first eight shot changes are shown with their boundary frames and associated cut likelihood. It is interesting to see all the likelihoods are above 90% even there is quite large common background when the sixth cut occurs.

Figure 6. Examples of first eight cuts detected from MRS336853.mpg sequence with their start/end frames and associated cut likelihoods.

According to the cuts given in Figure 6, we have eight detected shot candidates which can be summarized in Table 3 while the information for the ninth cut is incomplete. In Table 3, the first two shot candidates are junk frames belonging to H-cut, and the other ones are of normal contents. There are four shot candidates ranging from the third to the sixth in Table 3 which forms five retakes of similar contents, though the contents in the third and the seventh candidate cuts cannot be discovered in Figure 6 due to the fact that they have either almost the same start and end frames, or inconsistent boundary frames. This has indicated that shot similarity cannot be simply measured by their two boundary frames, hence sub-shots of V-unit is introduced and extracted for more accurate matching.

Table 3. Obtained shot candidates corresponding to the detected cuts in Figure 6.

Shot candidates	1st	2nd	3rd	4th	5th	6th	7th	8th
Start frame	0	249	808	1840	2608	3168	3657	4285
End frame	248	807	1839	2607	3167	3656	4284	5244
Type	H-cut	H-cut	Normal	Normal	Normal	Normal	Normal	Normal
Real shot index	N/A	N/A	1st	1st	1st	1st	1st	2nd
No. of V-units	N/A	N/A	4	1	1	1	1	2
Valid frames	N/A	N/A	1030	766	554	487	626	958
Active frames	N/A	N/A	488	159	234	201	189	460

According to the five retakes of the 1st real shot in Table 3, there are four V-units extracted for the first retake and one for each of the other four retakes, respectively. Figure 7 shows three key frames extracted from each of the determined V-units for comparisons, where the first two rows are for the first retake and the other two rows for the remaining four retakes. As a matter of fact, the retakes of similar contents can be easily identified by the extracted key frames from the V-Units: V_1_4, V_2_1, V_3_1, V_4_1 and V_5_1. From the middle key frame to the end of each V-unit, it takes 220, 125, 126, 70 and 92 frames in the five retakes, respectively, which hints a fast camera motion of least frames in the fourth retake to change the camera focus from the man to the signboard. Due to this fast camera motion, the extracted middle key frame in V_4_1 is inconsistent with those from other four retakes, which may cause inaccurate shot similarity derived from key frames. However, this error can be recovered by the clustering results as shot similarity is defined as the sum of maximum similarity between each pair of key frames, see $\rho(m,n)$ as defined in (11). As a result, inaccurate detection of one key frame is not vital, and thus our proposed algorithm achieves certain level of robustness. Finally, the generated summary frames of the five retakes are illustrated in Figure 8.

Figure 7. List of key frames extracted for each V-unit of the first shot containing five retakes.

Figure 8 illustrates the frames determined for summarization for each of the four V-units. Since the whole sequence has 52240 frames, the target quota is 1044 frames as 2% of the full length and there is a quota of 29 frames assigned to the clustered five retakes. For the four V-units, the corresponding numbers of the selected frames for summarization are 1, 2, 8 and 18 frames, respectively. Due to nonlinear sampling of the original video, the frame numbers extracted for each V-unit might have different intervals. However, this has the potential to maximize the effectiveness of contents of interest represented by active frames, in order to achieve meaningful video summarization.

Figure 8. List of final summarization results of the five retakes in Figure 6 and Table 3.

D. Error Analysis

In the following, we discuss the reasons of relatively limited scores on IN, RE and JU achieved by the proposed algorithm, which has been used for an overall evaluation of the summarization result. In our proposed modelling, junk frames are categorized into three classes, i.e. H-cut, s_clip and e_clip, and it is found that those junk frames failing the proposed filter are all belong to the last two categories. Our model in filtering s_clip relies on apparent energy changes, and thus it requires large clapboards in the scene. For junk frames inside e_clip, similar problem has been observed that visual indicators alone as described in previous sections are often insufficient, and in this circumstance, inclusion of audio information such as detecting "cut" command could provide more information for further improvement.

Regarding redundant contents in the summarized results, the error is mainly caused by strong motions in large areas within the video, such as fast camera movement and large background movement of water, etc. This kind of motion will lead to inaccurate extraction of key frames in effective clustering of retakes since the low similarity between frames will lead to unreliable new clusters. Then, retakes of same shot are put in two or more clusters and redundant contents are produced when summarized frames are extracted from each of the clusters. This can be further resolved by extracting more key frames and also introducing motion compensation strategy.

The lost score for the proposed algorithm under the criterion IN is mainly due to insufficient representative frames of certain events/objects, as noticeable visual perception requires at least 10 frames or 0.5 second. Specifically, the insufficiency can be analyzed in terms of two cases: one is short appeared objects/events in the original video, and the other is caused by summarization whilst useful contents are abandoned due to limited quotas in assigning valid frames. In the second case, IN score can be further improved with increased quota frames, which can be achieved by reducing junk frames and redundancy under fixed overall quota frames, i.e. improving RE and JU scores. In other words, these three measures are correlated hence an overall measurement is required such as our introduced PF.

E. Further Evaluation using Other Video Contents

In this section, the proposed method is applied to other video contents rather than rush videos to further evaluate its effectiveness. Since no retakes and junk frames are contained in these videos, a simplified version of our algorithm is employed

which only includes activity-level extraction, key frame determination and summary generation. Meanwhile, another group of key frames are extracted for summarization using the curvature points of the accumulative activity-level curve which has been widely used in many systems [7, 37]. The two schemes in key frame extraction and video summarization are compared over three sequences containing news, sports and movie, and the results are shown in Table 4. Please note only the inclusion of objects/events are utilized as the criterion in this experiment; and each summarized video are manually scored by three individuals and the average score is then obtained and listed in Table 4 for comparison.

In Table 4, three quota values are specified as the target size ratio of the summarized video against the original one, including 5%, 10% and 15%. "Ref" and "Our" respectively denote results using curvature points and our approach. As can be seen, the results from our approach slightly outperform those using curvature based method. This is mainly due to the fact that we extract key frames of equal temporal variance which makes it less sensitive to noised curvatures. Although for rush videos a low summarization quota of 2% is allowable to generate an inclusion rate of about 60%, a high quota over 10% is needed to generate the similar inclusion rate for general videos as they contain much less redundancy than rush videos. Under a given summarization quota of 15%, our approach can successfully retain over 70% of the main objects and events.

Table 4. Evaluation of our algorithm using other video contents.

Sequences/ Results	Quota=5%		Quota=10%		Quota=15%	
	Ref	Our	Ref	Our	Ref	Our
Movie	48.7%	51.4%	59.6%	61.5%	69.6%	72.6%
News	51.1%	52.8%	61.4%	62.6%	71.2%	74.4%
Sports	46.3%	49.7%	58.3%	60.9%	67.1%	71.6%

VII. CONCLUSIONS

In this paper, we described a new algorithm for rush summarization in TRECVID'08, which illustrates that competitive performances can be achieved without complex signal processing techniques, such as those including face detection, feature tracking and audio analysis etc. adopted by other participating teams. In addition, we have also demonstrated that compressed-domain processing is not only efficient but also effective in such a context. Our hierarchical modeling, adaptive clustering and activity-level based summarization generation are found very useful in achieving robust summarization of rush videos. Further improvement could be made by introducing new techniques towards more accurate key frame extraction, more junk frames removal, and more inclusion of interesting contents.

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