Holomorphic convexity and Carleman approximation by entire functions on Stein manifolds

Per Erik Manne · Erlend Fornæss Wold · Nils Øvrelid

Received: 26 January 2010 / Revised: 19 June 2010 / Published online: 27 November 2010 © The Author(s) 2010. This article is published with open access at Springerlink.com

Abstract We give necessary and sufficient conditions for totally real sets in Stein manifolds to admit Carleman approximation of class C^k , k > 1, by entire functions.

Mathematics Subject Classification (2000) 32E20 · 32E30 · 32V40

1 Introduction

In 1927, Carleman [2] proved a remarkable extension of Weierstrass' approximation theorem: If $f, \epsilon \in \mathcal{C}(\mathbb{R})$ are continuous functions on the real line in the complex plane, ϵ strictly positive, then there exists an entire function $g \in \mathcal{O}(\mathbb{C})$ such that $|g(x) - f(x)| < \epsilon(x)$ for all $x \in \mathbb{R}$. This theorem has been generalized to one-dimensional sets in \mathbb{C}^N by Alexander [1], who proved in 1979 the same result for smoothly embedded curves in \mathbb{C}^N , and more recently, in 2002, by Gauthier and Zeron [5], who gave a proof in the case of locally rectifiable curves with trivial topology in \mathbb{C}^N .

This paper was completed while Per Erik Manne was Visiting Scholar at the University of Michigan, and he thanks for the hospitality shown him during this stay.

P. E. Manne (⋈)

Department of Finance and Management Science, Norwegian School of Economics and Business Administration, Helleveien 30, 5045 Bergen, Norway e-mail: per.manne@nhh.no

E. F. Wold · N. Øvrelid

Department of Mathematics, University of Oslo, PO Box 1053, Blindern, 0316 Oslo, Norway e-mail: erlendfw@math.uio.no

N. Øvrelid

e-mail: nilsov@math.uio.no



We treat the case of higher dimensional totally real manifolds and, more generally, totally real sets. A totally real set M in a Stein manifold X is said to admit Carleman approximation if there for each $f, \epsilon \in \mathcal{C}(M), \epsilon$ strictly positive, exists an entire function $g \in \mathcal{O}(X)$ such that $|g(x) - f(x)| < \epsilon(x)$ for all $x \in M$. If M is a totally real manifold of class \mathcal{C}^k , it is also possible to consider \mathcal{C}^k Carleman approximation of $f \in \mathcal{C}^k(M)$ by $g \in \mathcal{O}(X)$; if $X = \mathbb{C}^N$ then this is obtained by requiring all partial derivatives of g - f along M of order $\leq k$ to be smaller than $\epsilon(x)$ at each $x \in M$. We show in Sect. 2.2 how to define \mathcal{C}^k Carleman approximation on totally real sets of class \mathcal{C}^k in Stein manifolds, and the main object of the paper is to give necessary and sufficient conditions for \mathcal{C}^k Carleman approximation on totally real sets of class \mathcal{C}^k , $k \geq 1$, to be possible.

Totally real affine linear subspaces of \mathbb{C}^N always allow Carleman approximation, as was shown by Hoischen [7] and Scheinberg [14]. For more general sets, extra conditions must be imposed. Firstly, we need the totally real set in question to be polynomially convex, or holomorphically convex if the ambient space is a Stein manifold. However, a recent construction by the second author [18] shows that polynomial convexity alone is not sufficient: There exists a smoothly embedded polynomially convex totally real surface in \mathbb{C}^3 which does not allow Carleman approximation. We will therefore in addition require that the set has what we call bounded exhaustion hulls, or E-hulls, in the ambient space; see Definition 2.1. This condition is present in proofs of Carleman approximation in, e.g., [2,16], and we are able to show that it is a necessary condition for \mathcal{C}^k Carleman approximation, $k \geq 1$.

We give some examples to illustrate these notions. If $M \subset \mathbb{C}^N$ is a locally rectifiable curve with trivial topology, then it will be polynomially convex and have bounded E-hulls, as is shown in [1,5], building upon fundamental work by Stolzenberg [16]. Another example satisfying both conditions is given by any Lipschitz graph over \mathbb{R}^N with Lipschitz constant $\alpha < 1$; see Proposition 4.2. A third example is given in the one-dimensional case $M \subset G \subset \mathbb{C}$; the condition of bounded E-hulls is then equivalent to requiring the complement of M in G to be locally connected at infinity. This is also a necessary condition in Nersesjan's approximation theorem [12] (see Remarks 2.2 and 2.8). The example in [18] mentioned above is polynomially convex, but does not have bounded E-hulls. There are also simple examples of $M \subset \mathbb{C}$ which are polynomially convex, but does not have bounded E-hulls; see [4]. These examples are not totally real sets, however.

It is shown in [8] that for a totally real manifold $M \subset \mathbb{C}^N$ of real dimension at most N-1, the condition of polynomial convexity and the condition of bounded E-hulls are both generic, so that any sufficiently small \mathcal{C}^1 perturbation of M will be polynomially convex and have bounded E-hulls.

Our main result can then be stated as follows:

Theorem 1.1 Let X be a Stein manifold, and let $M \subset X$ be a totally real set of class C^k with k > 1.

- (a) M admits C^k Carleman approximation if and only if M is holomorphically convex and has bounded E-hulls in X.
- (b) If any of the equivalent conditions in (a) are satisfied, then M admits C^k Carleman approximation with interpolation.



The notion of C^k Carleman approximation is made more precise by Definitions 2.3 and 2.6, which use the same setup as in [11]. One useful consequence of Theorem 1.1 (see Corollary 3.2) is that the set M has a Runge and Stein neighborhood basis.

In light of Theorem 1.1, it is natural to expect that polynomial convexity and the property of having bounded E-hulls are both necessary conditions for admitting Carleman approximation of *continuous* functions. The methods of this article do not seem to provide a proof of that.

The fact that the conditions in (a) are sufficient to obtain C^k Carleman approximation was proved by the first author in the unpublished work [10].

2 Preliminaries

If X is a complex manifold, we let $\mathcal{O}(X)$ denote the holomorphic functions on X. If $K \subset X$ is a compact set, we let $\mathcal{O}(K)$ denote the continuous functions on K which are restrictions of holomorphic functions on some open neighborhood of K. The neighborhood may depend on the function. We will always assume that the manifold X is equipped with some riemannian metric giving rise to a distance |x - x'| for $x, x' \in X$.

2.1 Holomorphic convexity and exhaustion hulls

If M is a compact subset of a complex manifold X, we define, as usual, the *holomorphically convex hull* of M to be

$$\widehat{M}_{\mathcal{O}(X)} = \{ x \in X; |f(x)| \le ||f||_M, \forall f \in \mathcal{O}(X) \}.$$

If $X = \mathbb{C}^N$ for some N, we drop the subscript $\mathcal{O}(X)$. The hull then coincides with the polynomial hull of M.

If M is a closed, noncompact set, we define the hull of M by

$$\widehat{M}_{\mathcal{O}(X)} = \bigcup_{k=1}^{\infty} \widehat{M^k}_{\mathcal{O}(X)},$$

where $\{M^k\}$ is a normal exhaustion of M. Note that the definition of $\widehat{M}_{\mathcal{O}(X)}$ is independent of the exhaustion. We call M holomorphically convex if $\widehat{M}_{\mathcal{O}(X)} = M$. If $X = \mathbb{C}^N$ and $\widehat{M}_{\mathcal{O}(\mathbb{C}^N)} = M$, we call M polynomially convex; in other words, this means that M can be exhausted by polynomially convex compact subsets.

For a closed set $M \subset X$, we let h(M) denote the set

$$h(M) = \overline{\widehat{M}_{\mathcal{O}(X)} \setminus M}.$$

Definition 2.1 Let $E = \{E^k\}$ be a normal exhaustion of X. We say that M has bounded exhaustion hulls (or E-hulls) in X if the set $h(E^k \cup M)$ is compact in X for all choices of k. Note that this property is independent of the exhaustion E.

Remark 2.2 If $G \subset \mathbb{C}$ is a domain and $M \subset G$ is a closed subset, then M is holomorphically convex iff $G^* \setminus M$ is connected, and M has bounded E-hulls iff $G^* \setminus M$ is locally



connected at infinity iff $G \setminus M$ has no bounded component, where $G^* = G \cup \{\infty\}$ is the one-point compactification of G (see [4]).

2.2 Pointwise seminorms

Let $M \subset X$ be some set and let $k \in \mathbb{Z}_+$. For each point $x \in M$ we introduce an equivalence relation on germs of \mathcal{C}^k -smooth complex-valued functions at x, namely $f_x \sim g_x$ if and only if f - g vanishes to order k at x. The set of equivalence classes, denoted by \mathcal{J}_x^k , forms in a natural way a finite dimensional complex vector space called the k-jet space at the point x. The collection of all k-jet spaces for all points $x \in M$ forms in a natural way a complex vector bundle $\mathcal{J}^k(X, M)$ over M, where transition functions can be expressed in terms of transition functions (and their derivatives) on X.

To any \mathcal{C}^k -smooth function f on X, we associate a continuous section $\mathcal{J}^k(f)$ of $\mathcal{J}^k(X,M)$ by $\mathcal{J}^k(f)(x) := [f_x]$. Let $|\cdot|$ be a fiberwise norm on $\mathcal{J}^k(X,M)$ that varies continuously with x, *i.e.*, for any local section $s \in \Gamma(\mathcal{J}^k(X,M)|_{M\cap U})$, where U is an open subset of X, the funtion $s \mapsto |s(s)|$ is continuous. Finally, we define the pointwise seminorms

$$|f|_{k,x} = |\mathcal{J}^k(f)(x)|$$

whenever $f \in \mathcal{C}^k(U)$ and $x \in M \cap U$, where U is an open subset of X.

Definition 2.3 Let X be a complex manifold, let $M \subset X$ be a closed set, and let $|\cdot|_{k,x}$ be a pointwise seminorm on M. Let \mathcal{F} be a family of complex-valued functions contained in $\mathcal{C}^k(X)$. We say that M admits \mathcal{C}^k Carleman approximation of functions in \mathcal{F} if there for every function $f \in \mathcal{F}$ and every strictly positive function $\epsilon \in \mathcal{C}(M)$ exists an entire function $g \in \mathcal{O}(X)$ with

$$|g - f|_{k,x} < \epsilon(x)$$

for all $x \in M$.

Remark 2.4 If we make another choice of pointwise seminorm $|\cdot|'_{k,x}$, we have

$$C(x)^{-1}|f|_{k,x} \le |f|'_{k,x} \le C(x)|f|_{k,x}$$

for some positive continuous function C on M. In particular, the validity of C^k Carleman approximation is independent of the choice of the norm.

Definition 2.5 We recall that a manifold M contained in a complex manifold X is said to be totally real if at all points $p \in M$ the tangent space T_pM contains no complex line. We say that a set $M \subset X$ is a totally real set of class C^k , $k \ge 1$, if M is closed and locally contained in a totally real C^k -manifold.

It is shown in [6] that M is a totally real set of class \mathcal{C}^k if and only if we can write $M = \rho^{-1}(0)$ for some non-negative real \mathcal{C}^{k+1} -function ρ which is strictly plurisubharmonic on some neighborhood of M.



Definition 2.6 Let X be a complex manifold and let M be a totally real set of class \mathcal{C}^k in X. Let $f \in \mathcal{C}^k(X)$ for some $k \geq 1$. If $[\overline{\partial}(D^\alpha f)](x) = 0$ for all $x \in M$ and all $|\alpha| \leq k - 1$, where $D^\alpha = \frac{\partial^{|\alpha|}}{\partial z_1^{\alpha_1} ... \partial z_N^{\alpha_N}}$ for some holomorphic coordinate system $z = (z_1, \ldots, z_N)$ near x, then we say that f is $\overline{\partial}$ -flat to order k along M, and we write $f \in \mathcal{H}_k(X, M)$. We declare $f \in \mathcal{H}_0(X, M)$ for any continuous $f \in \mathcal{C}(X)$.

Note that $\mathcal{H}_k(X, M)$ is closed under multiplication, and hence becomes an algebra. We will in this paper be interested in \mathcal{C}^k Carleman approximation of functions in $\mathcal{H}_k(X, M)$.

When M is a totally real manifold of class \mathcal{C}^k , it is possible to consider \mathcal{C}^k -approximation by entire functions of functions defined only on M. If M is a totally real set, then it is possible to cover it by totally real manifolds M_j and use \mathcal{C}^k -functions f_j on M_j which fit together suitably to obtain \mathcal{C}^k -objects on M to approximate. The following proposition can then be used to show that M will admit Carleman approximation with this definition if and only if it does so as defined in Definition 2.3.

Proposition 2.7 Let X be a complex manifold, and let $M \subset X$ be a totally real set of class C^k . Let $f \in C^k(X)$ be any function. Then there exists a function $g \in C^k(X)$ such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and such that g(x) = f(x) for all $x \in M$ and $x \in M$ and $x \in M$ for all $x \in M$ and $x \in M$ for all $x \in M$ for all x

Proof There are a locally finite open cover $\{U_i\}_{i=1}^{\infty}$ of M and totally real manifolds $M_i \subset U_i$ of maximal real dimension N such that $M \cap U_i \subset M_i$ for each i. Consider the restriction $f|_{M_i}$. Since M_i is of maximal dimension, the Cauchy-Riemann equations determine at each point $x \in M_i$ a unique $\bar{\partial}$ -flat k-jet agreeing with $j_x^k(f)$ along M_i . By Whitney's extension theorem [17], $f|_{M_i}$ can be extended to a function $f_i \in \mathcal{C}^k(U_i)$ which is $\bar{\partial}$ -flat along M_i . Let $\phi_i \in \mathcal{C}^k(X)$ be functions with $\operatorname{Supp}(\phi_i) \subset U_i$ and such that $\sum \phi_i = 1$ for all $x \in M$. Again, by Whitney's extension theorem, there are $\tilde{\phi}_i \in \mathcal{H}_k(U_i, M_i)$ which extend $\phi_i|_{M_i}$. It is possible to extend by the zero function wherever $\phi_i|_{M_i}$ is locally zero, and away from M_i the extension can be arbitrary. We can thus obtain $\operatorname{Supp}(\tilde{\phi}_i) \subset U_i$, and defining $\tilde{\phi}_i \equiv 0$ on $X \setminus U_i$ we get $\tilde{\phi}_i \in \mathcal{H}_k(X, M)$. Then $g = \sum \tilde{\phi}_i f_i \in \mathcal{H}_k(X, M)$ is well defined, and at each $x \in M$ we have $g(x) = \sum \tilde{\phi}_i(x) f_i(x) = \sum \phi_i(x) f(x) = f(x)$.

Remark 2.8 In the one-dimensional case, Nersesjan's theorem [12] (see also [4]) characterizes sets which admit Carleman approximation of functions in A(M): If $G \subset \mathbb{C}$ is a domain and $M \subset G$ is a closed and proper subset, then M admits Carleman approximation of functions in A(M) iff (i) $G^* \setminus M$ is connected, (ii) $G^* \setminus M$ is locally connected at ∞ , and (iii) for any compact $K \subset G$ there is a neighborhood V of ∞ in G^* such that no component of M° intersects both K and V. Here $G^* = G \cup \{\infty\}$, as in Remark 2.2. Note that (iii) is vacuously satisfied whenever M has empty interior, and (i) and (ii) will then characterize sets which admit Carleman approximation of functions in C(M).

3 The sufficient condition

The goal of this section is to prove the sufficiency in Theorem 1.1. We prove the more general result:



Theorem 3.1 Let X be a Stein manifold and let $M \subset X$ be a totally real set which is holomorphically convex and has bounded E-hulls in X. Then the following holds: For any compact set $K \subset X$ with $K \cup M$ holomorphically convex, $A = \{a_i\}_{i=1}^{\infty}$ and $B = \{b_i\}_{i=1}^{\infty}$ discrete sequences of points in X with $A \subset M$ and $B \subset X \setminus (K \cup M)$, $C = \{c_i\}_{i=1}^{m} \subset K$ a finite set of points, $\{q_i\}_{i=1}^{\infty}$ a collection of germs of holomorphic functions at the points b_i , $\{d_i\}_{i=0}^{\infty} \subset \mathbb{N}$, $f \in C(K \cup M) \cap O(K)$, and $\epsilon \in C(K \cup M)$ a strictly positive function, there exists a $g \in O(X)$ such that

- (i) $|g(x) f(x)| < \epsilon(x)$ for all $x \in K \cup M$,
- (ii) g(x) = f(x) for all $x \in A$,
- (iii) $g(x) q_i(x) = O(|x b_i|^{d_i+1})$ as $x \to b_i$ for all $i \in \mathbb{N}$, and
- (iv) $g(x) f(x) = O(|x c_i|^{d_0 + 1})$ as $x \to c_i$ for i = 1, ..., m.

If, in addition, M is a totally real set of class C^k and $f \in \mathcal{H}_k(X, M)$, we may additionally achieve that

- (i)' $|g f|_{k,x} < \epsilon(x)$ for all $x \in M$, and
- (ii)' $|g f|_{k,x} = 0 \text{ for all } x \in A.$

Before we attend to the proof of this theorem, we give a useful corollary.

Corollary 3.2 Let X and M be as in the previous theorem, and let $K \subset X$ be a compact set such that $K \cup M$ is holomorphically convex. Then $K \cup M$ has a Runge and Stein neighborhood basis.

Proof Let U be an arbitrary neighborhood around $K \cup M$. As in the compact case, we will define an analytic polyhedron $\Omega \subset U$, but we will need infinitely many defining functions. Let $\{X_j\}_{j=1}^{\infty}$ be a compact exhaustion of X such that $X_j \cup M$ is holomorphically convex for each $j \in \mathbb{N}$, and where $X_1 = K$.

If $\partial U = \emptyset$, we define $\Omega = U$. Otherwise, for each point $q \in \partial U$, choose j maximal such that $q \notin X_j$. By Theorem 3.1 there exists a function $f_q \in \mathcal{O}(X)$ such that $f_q(q) = 2$ and such that $|f_q(x)| < 1$ for all $x \in X_j \cup M$. Let $\{q_i\}_{i=1}^{\infty} \subset \partial U$ be a discrete sequence of points in X such that the set

$$\{x \in X; |f_{q_i}(x)| > \frac{3}{2} \text{ for some } i \in \mathbb{N}\}$$

covers ∂U . Define

$$\Omega = \{ x \in U; |f_{q_i}(x)| < 1 \text{ for all } i \in \mathbb{N} \}.$$

The set Ω is open. To see this, let $p \in \Omega$ be any point, and let $V \subset \subset X$ be an open set containing p. Then $V \subset X_j$ for some j, and since $\{q_i\}$ is discrete in X, we obtain for all sufficiently large i that $|f_{q_i}(x)| < 1$ for all $x \in V$. Hence $\Omega \cap V$ is a finite intersection of open sets.

Let $C \subset \Omega$ be compact. We claim that $\widehat{C}_{\mathcal{O}(X)} \cap \Omega$ is compact in Ω . Assume that this is not the case. Since $\widehat{C}_{\mathcal{O}(X)}$ is compact in X, there is a sequence of points $x_j \in \widehat{C}_{\mathcal{O}(X)}$ converging to a point $x \in \partial \Omega$. Then either $x \in \partial U$ or $x \in U$. If $x \in \partial U$, there exists an $i \in \mathbb{N}$ such that $x \in \{|f_{q_i}| > \frac{3}{2}\}$, which is a contradiction since $\|f_{q_i}\|_C < 1$. If $x \in U$, there exists an $i \in \mathbb{N}$ such that $|f_{q_i}(x)| \geq 1$, which is a contradiction for the same reason.



We then have

$$\widehat{C}_{\mathcal{O}(\Omega)} \subset \widehat{C}_{\mathcal{O}(X)} \cap \Omega \subset\subset \Omega$$
,

and this shows that Ω is Runge and Stein.

We will prove Theorem 3.1 by an induction procedure, where we approximate on larger and larger compact sets. First we need a version of the Oka-Weil approximation theorem, which we will call the Oka-Weil theorem with jet interpolation. Finite jet interpolation is possible on manifolds more general than Stein manifolds, and we include a brief discussion.

Definition 3.3 Let X be a complex manifold. Given a finite set of points $A = \{a_1, \ldots, a_m\}$ and an integer $d \in \mathbb{N}$, we let \mathcal{J}_A^d denote the vector space of d-jets at the points a_i .

Definition 3.4 We say that a complex manifold X admits *finite jet interpolation with bounds* if the following holds: For any compact set $K \subset X$, any finite set of points $A = \{a_1, \ldots, a_m\} \subset X$ without repetition, any norm $|\cdot|$ on \mathcal{J}_A^d , and any integer $d \in \mathbb{N}$, there exists a constant C such that for all $j \in \mathcal{J}_A^d$ there exists a function $f \in \mathcal{O}(X)$ with $j_{a}^d(f) = j_i$ for $i = 1, \ldots, m$ and $||f||_K \leq C|j|$.

Definition 3.5 Let X be a complex manifold. Given a compact set $K \subset X$ and a function $g \in \mathcal{O}(K)$, we say that g admits uniform approximation on K if there exists a sequence $\{f_j\}_{j=1}^{\infty} \subset \mathcal{O}(X)$ such that $f_j \to g$ uniformly on K. If, additionally, we for any finite set of points $A = \{a_1, \ldots, a_m\} \subset K^{\circ}$ and any integer $d \in \mathbb{N}$ may also achieve that $j_{a_j}^d(f_j - g) = 0$ for $i = 1, \ldots, m$ and for all $j \in \mathbb{N}$, we say that g admits uniform approximation with jet interpolation on K.

Lemma 3.6 Let X be a complex manifold that admits finite jet interpolation with bounds, let $K \subset X$ be a compact set, and let $g \in \mathcal{O}(K)$. If g admits uniform approximation on K then g admits uniform approximation with jet interpolation on K.

Proof Let $f_j \in \mathcal{O}(X), j \in \mathbb{N}$, be functions such that $f_j \to g$ uniformly on K, and let $A = \{a_1, \ldots, a_m\} \subset K^\circ$. Let $h_j \in \mathcal{O}(X)$ be functions such that $j_{a_i}^d(h_j) = j_{a_i}^d(f_j - g)$ for $i = 1, \ldots, m$ and $\|h_j\|_K \le C|\mathcal{J}^d(f_j - g)|$ for all $j \in \mathbb{N}$, where $\mathcal{J}^d(f_j - g)$ is the element in \mathcal{J}_A^d induced by $f_j - g$. By the Cauchy inequalities, $|\mathcal{J}^d(f_j - g)| \to 0$ as $j \to \infty$. It follows that $f_j - h_j \to g$ uniformly on K and interpolates the jets of g on A. □

Proposition 3.7 Let X be a complex manifold. Then X admits finite jet interpolation with bounds if and only if $\mathcal{O}(X)$ separates points and local coordinates are given by entire functions.

Proof One of the implications is clear. The other implication will follow from:

Lemma 3.8 Let X be a complex manifold such that $\mathcal{O}(X)$ separates point and such that local coordinates are given by globally defined functions. Let $A = \{a_1, \ldots, a_m\} \subset X$ be distinct points and let $d \in \mathbb{N}$. Then there exists a function $f \in \mathcal{O}(X)$ such that



(i)
$$f(x) = O(\|x - a_i\|^{d+1})$$
 as $x \to a_i$ for $i = 1, ..., m-1$, and
(ii) $f(x) = 1 + O(\|x - a_m\|^{d+1})$ as $x \to a_m$.

(ii)
$$f(x) = 1 + O(||x - a_m||^{d+1})$$
 as $x \to a_m$

Before we prove this, we show how the proposition follows. Let f_i , i = 1, ..., m, be functions as in the lemma, but with a_i in place of a_m , so that f_i is tangent to 1 to order d at a_i and vanishes to order d at the other points in A. Let a compact set $K \subset X$ be given, and choose the constant C_1 such that $||f_i||_K \leq C_1$ for $i = 1, \ldots, m$. Let $z^i = \{z_1^i, \dots, z_N^i\}$ be local coordinates at a_i given by entire functions with $z^i(a_i) = 0$ for i = 1, ..., m. Since all the z_i^i s are bounded on K and any d-jet at a_i can be expressed as a polynomial in the z_i^i s, it is clear that there exists a constant C_2 such that for any d-jet j_i^d at a_i there is an entire function g_i with $j_{a_i}^d(g_i) = j_i^d$ and $||g_i||_K \le$ $C_2|j_i^d|$. The function $g = \sum_{i=1}^m f_i \cdot g_i$ now interpolates the given jet to order d, and $||g||_K \leq mC_1C_2|j^d|.$

We proceed to prove the lemma. Note first that it is enough to prove it in the case that m = 2. Given that, one constructs functions f_i such that f_i is 1 to order d at a_m and zero to order d at a_i for i = 1, ..., m-1 and then defines $f := \prod_{i=1}^m f_i$.

Let $z_1, ..., z_N$ be local coordinates near a_1 and let $w_1, ..., w_N$ be local coordinates near a_2 , all given by entire functions and such that $z(a_1) = w(a_2) = 0$. Since $\mathcal{O}(X)$ separates points, we may assume that $z_i(a_2) \neq 0$ for i = 1, ..., N. By choosing polynomials in the z_i s, we can create entire functions that vanish to any given order at a_1 . In particular, there exists an entire function $g(x) = P(z_1(x), \dots, z_N(x))$ such that g vanishes to order d at a_1 and such that $g(a_2) = 1$. Expanding g at a_2 gives that

$$g(x) = 1 + P_s(w_1(x), \dots, w_N(x)) + h.o.t.,$$

where P_s is a homogenous polynomial of degree s. Consider the function $g(x) \cdot (1 - x)$ $P_s(w_1(x), \ldots, w_N(x))$. This function will be tangent to 1 to some order greater than s. Proceed like this until a function which is tangent to a sufficiently high degree is obtained.

Theorem 3.9 Let X be a Stein manifold and let $K \subset X$ be a holomorphically convex compact set. Then K admits uniform approximation with jet interpolation of any function $f \in \mathcal{O}(K)$.

Proof It is well known that K admits uniform approximation of any function $f \in$ $\mathcal{O}(K)$, and so this follows from Lemma 3.6 and Proposition 3.7.

We will build up to the proof of Theorem 3.1 through two simpler approximation results; first we approximate functions supported on small subsets of $M \setminus K$, and then we approximate functions whose support does not intersect K. Along the way we give some useful corollaries.

Proposition 3.10 Let X be a complex manifold, $K \subset X$ a compact set, $M \subset X$ a totally real set of class C^k , $M_0 \subset M$ compact, and assume that $K \cup M_0$ is a Stein compactum. Then for any point $p \in M_0 \setminus K$, any open neighborhood V of p, and any set of points $\{a_i\}_{i=1}^m \subset (K \cup M_0) \setminus V$, there exist a neighborhood $U' \subset V$ of p and a Stein neighborhood Ω of $K \cup M_0$ such that the following hold: For any $f \in \mathcal{H}_k(X, M)$ with $\operatorname{Supp}(f) \subset U'$ and any $d \in \mathbb{N}$, there exists a sequence $\{g_j\}_{j=1}^{\infty} \subset \mathcal{O}(\Omega)$ satisfying



- (i) $|g_j f|_{k,x} \to 0$ uniformly on $K \cup M_0$ as $j \to \infty$,
- (ii) $|g_j f|_{k,p} = 0$, and (iii) $g_j(x) = O(|x a_i|^{d+1})$ as $x \to a_i$ for i = 1, ..., m.

Proof Since M is locally contained in a totally real manifold of maximal (real) dimension N, there exists an open neighborhood V of p with $V \cap K = \emptyset$ and a closed, totally real submanifold M_V of V of dimension N such that $V \cap M \subset M_V$. We may assume that $f \in \mathcal{H}_k(U, M_V)$. By [9], p. 522, there are neighborhoods

$$U' \subset \subset U'' \subset \subset U \subset \subset V$$

of p and a neighborhood $W \subset U$ of $M \cap \partial U''$ such that if $f \in \mathcal{H}_k(U, M_V \cap U)$ has compact support in U', there is a sequence of holomorphic functions $\{h_i\}_{i=1}^{\infty} \subset \mathcal{O}(U)$ such that $|h_j - f|_{k,x} \to 0$ uniformly on $M_V \cap U$ as $j \to \infty$ and such that $||h_j||_W \to 0$ uniformly (see the remark after this proof). By the Oka-Weil theorem with jet interpolation, we may assume that $|h_j - f|_{k,p} = 0$ for all j.

Let $\{\Omega_j\}_{j=1}^{\infty}$ be a Stein neighborhood basis of $K \cup M_0$, and define $U_j^1 = \Omega_j \cap U''$ and $U_i^2 = (\Omega_j \setminus U'') \cup (W \cap \Omega_j)$. If j is large enough, we have that U_i^2 is an open set, and clearly $\Omega_j = U_j^1 \cup U_j^2$ and $U_j^1 \cap U_j^2 \subset W$. Fix a j large enough so that this holds, and drop the subscript j.

We solve a Cousin problem on Ω with respect to the cover U^1 , U^2 . By the solution of Cousin I with estimates (see, e.g., [13], p. 304), there are sequences of functions $g_j^i \in \mathcal{O}(U^i)$ such that $h_j = g_j^1 - g_j^2$ on $U^1 \cap U^2$ and such that $g_j^i \to 0$ uniformly on compact subsets of U^i as $j \to \infty$. By Oka-Weil with jet interpolation, we may assume that all g_i^1 vanish to order k at p, and that all g_i^2 vanish to order d at the points a_i . Keeping in mind the Cauchy inequalities, we see that the sequence defined by $g_j = h_j - g_j^1$ on U^1 and $g_j = -g_j^2$ on U^2 satisfies the conclusions of the proposition.

Remark 3.11 In [9] the approximation result is stated as follows. Given a C^k -smooth function f on M_V with support in $M_V \cap U'$ there exist functions h_i holomorphic on U such that the h_i s approximate f in C^k -norm on M_V . Since in our case the Cauchy-Riemann equations for f along M_V are satisfied to order k, and since M_V is of maximal dimension, it follows that $|h_i - f|_{k,x} \to 0$ as $j \to \infty$.

The following corollary will be used in Sect. 4.

Corollary 3.12 Any point $p \in M_0 \setminus K$ is a peak point for the uniform closure of $\mathcal{O}(\Omega)|_{K\cup M_0}$. If $X=\mathbb{C}^N$ and $K\cup M_0$ is polynomially convex, then any $p\in M_0\setminus K$ is a peak point for $\mathcal{P}(K \cup M_0)$.

Proof This is obvious.

Proposition 3.13 Let X be a Stein manifold, $K \subset X$ a compact set, $M \subset X$ a totally real set, $M_0 \subset M$ compact, and assume that $K \cup M_0$ is holomorphically convex. Then for any $f \in \mathcal{C}(X)$ with $\operatorname{Supp}(f) \cap K = \emptyset$, $\{b_i\}_{i=1}^n \subset X \setminus (K \cup M) \text{ and } \{c_i\}_{i=1}^m \subset K$ finite sets of points, q_i germs of holomorphic functions at the points b_i , and $d \in \mathbb{N}$, there exists a sequence $\{h_j\}_{j=1}^{\infty} \subset \mathcal{O}(X)$ such that



- (i) $||h_j f||_{K \cup M_0} \to 0$ as $j \to \infty$, (ii) $h_j(x) q_i(x) = O(|x b_i|^{d+1})$ as $x \to b_i$ for i = 1, ..., n, and (iii) $h_j(x) = O(|x c_i|^{d+1})$ as $x \to c_i$ for i = 1, ..., m.

If, in addition, M is a totally real set of class C^k , $\{a_i\}_{i=1}^s \subset M_0 \setminus K$ is a finite set of points, and $f \in \mathcal{H}_k(X, M)$, then we can also obtain

- (iv) $|h_j f|_{k,x} \to 0$ uniformly on M_0 as $j \to \infty$, and
- (v) $|h_i f|_{k,a_i} = 0$ for i = 1, ..., s.

Proof Let U be a neighborhood of K which does not meet Supp(f) and which does not contain any a_i , and let $M_0' = \overline{M_0 \setminus U}$. At each point $p \in M_0'$, let V_p be an open neighborhood such that $\overline{V_p} \cap K = \emptyset$ and such that V_p contains none of the a_i , except possibly if $p = a_i$ for some i. Choose neighborhoods $U'_p \subset V_p$ as in Proposition 3.10. Let $\{U'_{p_i}\}_{i=1}^t$ be a finite cover of M'_0 such that $p_i = a_i$ for $i = 1, \ldots, s$, and let M_i denote the open set $M \cap U'_{p_i}$ for i = 1, ..., t. Let $\phi^i \in \mathcal{C}^k_0(U'_{p_i})$ be functions for $i=1,\ldots,t$ such that $\sum_{i=1}^t \phi^i(x)=1$ for all $x\in M_0'$. As in the proof of Proposition 2.7, we may assume that each ϕ^i is $\bar{\partial}$ -flat to order k along M. Then

$$f|_{M_0} = \sum_{i=1}^t \phi^i \cdot f,$$

where each $\phi^i \cdot f \in \mathcal{H}_k(X, M)$. For each i, choose a Stein neighborhood Ω_i of $K \cup M_0$ such that $b_j \notin \overline{\Omega}_i$ for all j and such that there is a sequence $\{g_i^i\}_{i=1}^\infty \subset \mathcal{O}(\Omega_i)$ approximating $\phi^i \cdot f$ in accordance with Proposition 3.10. Let $\Omega = \bigcap_{i=1}^t \Omega_i$ and let $\tilde{g}_j = \sum_{i=1}^t g_i^i$. Then $\{\tilde{g}_j\}_{j=1}^\infty$ satisfies claims (i), (iii), (iv), and (v) of the present proposition, but with Ω in place of X.

For i = 1, ..., n, let W_i be a neighborhood of the point b_i such that q_i has a representative which is holomorphic on W_i , $W_i \cap \Omega = \emptyset$, and such that $W_i \cap W_j = \emptyset$ whenever $i \neq j$. Define a sequence of functions $\{g_j\}_{j=1}^{\infty} \subset \mathcal{O}(\Omega \cup (\bigcup_{i=1}^n W_i))$ by $g_i = \tilde{g}_i$ on Ω and $g_i = q_i$ on W_i for $i = 1, \dots, n$. Since $K \cup M_0 \cup \{b_1, \dots, b_n\}$ is holomorphically convex, we can apply the Oka-Weil theorem with jet interpolation to approximate the g_j by entire functions. We thus obtain $\{h_j\}_{j=1}^{\infty} \subset \mathcal{O}(X)$ with all the required properties of the present proposition.

The following corollary will be used in Sect. 4.

Corollary 3.14 With X, M_0 , and K as in the previous proposition, if $f \in C(K \cup M_0)$ satisfies $f|_K \equiv 1$, then f is in the uniform closure of $\mathcal{O}(X)|_{K \cup M_0}$.

Proof The function 1-f can be uniformly approximated on $K \cup M_0$ by continuous functions which vanish on some (varying) neighborhood of K. Now apply Proposition 3.13.

Proof of Theorem 3.1. Without loss of generality, $\epsilon(x) < 1$ for all $x \in K \cup M$. Let $\{K_j\}_{j=0}^{\infty}$ be a normal exhaustion of X such that $K_j \cup M$ is holomorphically convex for each j. We may assume that $K_0 = K$ and that $f \in \mathcal{O}(K_2)$. For j = 1, 2, ..., let



 $\chi_j \in \mathcal{C}_0^{\infty}(X)$ be a cutoff function such that $\chi_j \equiv 1$ near K_j and such that $\operatorname{Supp}(\chi_j) \subset$ K_{i+1}° . As in the proof of Proposition 2.7, we may assume that χ_j is $\bar{\partial}$ -flat along M for each j. For $j = 1, 2, ..., \text{let } C_i \in \mathbb{R}$ be a constant such that $|\chi_i \cdot F|_{k,x} \leq C_i \cdot |F|_{k,x}$ for all $x \in M$ and all $F \in C^k(X)$. Choose the constants such that $1 \le C_j \le C_{j+1}$ for all j.

We will construct a sequence of approximating functions by induction, and the following is our inductive hypothesis I_i for $j \ge 1$: We have constructed functions $g_s \in \mathcal{O}(X)$ for s = 0, ..., j such that

(a)
$$|g_i - f|_{k,x} < \sum_{s=1}^{j} 2^{-s-1} \epsilon(x)$$
 for all $x \in K \cup (M \cap K_{j+1})$

(a)
$$|g_j - f|_{k,x} < \sum_{s=1}^{j} 2^{-s-1} \epsilon(x)$$
 for all $x \in K \cup (M \cap K_{j+1})$,
(b) $|g_j - f|_{k,x} < \frac{2^{-j-1}}{C_i} \epsilon(x)$ for all $x \in M \cap \overline{K_{j+1} \setminus K_j}$,

- (c) $||g_j g_{j-1}||_{K_{j-1}} < 2^{-j}$,
- (d) $|g_j f|_{k,x} = 0$ for all $x \in A \cap K_{j+1}$, and
- (e) $g_i(x) q_i(x) = O(|x b_i|^{d_i})$ as $x \to b_i$ for all $b_i \in B \cap K_i$.
- (f) $g_i(x) f(x) = O(|x c_i|^{d_0})$ as $x \to c_i$ for all $c_i \in C$.

By the assumption that $f \in \mathcal{O}(K_2)$, we get a function $g_1 \in \mathcal{O}(X)$ satisfying conditions (a) and (c)-(f) by applying the Oka-Weil theorem with jet interpolation. Let $g_0 = g_1$, so that I_1 is satisfied.

Assume that I_i holds for some $j \ge 1$. Let $d' = \max\{d_i; b_i \in B \cap K_{i+1}\}$. The support of the function $f_i = (1 - \chi_i) \cdot (f - g_i)$ does not intersect K_i , so we may apply Proposition 3.13 to get a function $h_i \in \mathcal{O}(X)$ satisfying

(g)
$$|h_j - f_j|_{k,x} < \frac{2^{-j-2}}{C_{j+1}} \epsilon(x)$$
 for all $x \in K_j \cup (M \cap K_{j+2})$,

- (h) $|h_j f_j|_{k,x} = 0$ for all $x \in A \cap K_{j+2}$,
- (i) $h_i(x) = O(|x b_i|^{d'+1})$ as $x \to b_i$ for all $b_i \in B \cap K_i$,
- (j) $h_i(x) (g_i q_i)(x) = O(|x b_i|^{d'+1})$ as $x \to b_i$ for all $b_i \in B \cap (K_{i+1} \setminus K_i)$,
- (k) $h_i(x) = O(|x c_i|^{d_0 + 1})$ as $x \to c_i$ for all $c_i \in C$.

It follows from (g) that $||h_j||_{K_i} < 2^{-j-1}$. Let $g_{j+1} = g_j + h_j$; then

$$|g_{j+1} - f|_{k,x} \le |h_j - f_j|_{k,x} + |\chi_j(g_j - f)|_{k,x}$$

for all $x \in K \cup M$, and it is straightforward to verify that g_{i+1} satisfies the conditions in I_{i+1} .

Let $\{g_j\}_{j=1}^{\infty} \subset \mathcal{O}(X)$ be a sequence constructed by the inductive procedure. It is straightforward to verify that g_i converges to a limit $g \in \mathcal{O}(X)$ satisfying all the claims of the theorem.

4 The necessary condition

Having verified the sufficiency in Theorem 1.1, it remains to show the following:

Theorem 4.1 Let X be a Stein manifold and let $M \subset X$ be a totally real set that admits \mathcal{C}^1 Carleman approximation of functions in $\mathcal{H}_1(X,M)$. Then M is holomorphically convex and has bounded E-hulls in X.



We first note that it is enough to prove this theorem in the case that $X = \mathbb{C}^N$ for some $N \in \mathbb{N}$. It is well known that if M admits uniform approximation of continuous functions on compact sets, then M is holomorphically convex. By the embedding theorem of Remmert, the pair (X, M) embeds holomorphically as closed submanifolds of \mathbb{C}^N , and by Cartan's Theorem B, the image M_0 of M admits Carleman approximation. If M_0 has bounded E-hulls in \mathbb{C}^N , then clearly M has bounded E-hulls in X.

We start by establishing a sufficient condition on certain closed sets for being polynomially convex and having bounded E-hulls in \mathbb{C}^N , recalling that polynomial convexity of closed sets is defined in terms of normal exhaustions. Write \mathbb{C}^N as a decomposition $\mathbb{C}^N = (\mathbb{R}^k \times \mathbb{R}^{N-k}) \oplus i\mathbb{R}^N$, $1 \le k \le N$. A graph Z over a set $S \subset \mathbb{R}^k$ is a set

$$Z = \{z = (x, y) + iw \in \mathbb{C}^N; y = \phi(x), w = \psi(x), x \in S\},\$$

where $\phi: S \to \mathbb{R}^{N-k}$ and $\psi: S \to \mathbb{R}^N$ are continuous functions.

Proposition 4.2 Let $Z \subset \mathbb{C}^N$ be a graph over a closed set $S \subset \mathbb{R}^k$, as above, and assume that there is some $\beta < 1$ such that $\psi : S \to \mathbb{R}^N$ satisfies the Lipschitz condition $\|\psi(x) - \psi(x')\| \le \beta \|x - x'\|$ for all $x, x' \in S$. Then Z is polynomially convex and has bounded E-hulls in \mathbb{C}^N .

Proof We first observe that there is no loss in generality in assuming k = N, as Z also is a Lipschitz graph with the same β over the set $\{(x, \phi(x)); x \in S\} \subset \mathbb{R}^N$. We therefore assume that $Z = \{x + i\psi(x); x \in S\}$ with $S \subset \mathbb{R}^N$. By Kirszbraun's theorem (see, e.g., [3]), ψ extends to a Lipschitz function $\tilde{\psi} : \mathbb{R}^N \to \mathbb{R}^N$ with the same Lipschitz constant β as ψ . Let

$$\tilde{Z} := \{ x + i\tilde{\psi}(x); x \in \mathbb{R}^N \} \supset Z.$$

To see that Z is polynomially convex, let $w_0 \in \mathbb{C}^N \setminus Z$, and let $z_0 \in \tilde{Z}$ be such that $\operatorname{Re}(z_0) = \operatorname{Re}(w_0)$, where we do not exclude the possibility that $z_0 = w_0$. Define $g(z) = \sum_{j=1}^N (z_j - (z_0)_j)^2$; then $\operatorname{Re}(g(w_0)) \leq 0$ and $\operatorname{Re}(g(z)) \geq 0$ for all $z \in \tilde{Z}$. If we set $f = \exp(-g)$, then $|f(w_0)| > \sup_{z \in Z} |f(z)|$. Approximating f by polynomials, we get that Z can be exhausted by polynomially convex compact sets.

Next we consider E-hulls, and we may assume that the origin is contained in Z. Let $K_R = \{z = x + iy \in \mathbb{C}^N; \|x\| \le R, \|y\| \le R\}$; it suffices to show that $h(K_R \cup Z)$ is bounded for each R > 0. Choose $R' > \frac{2R}{1-\beta}$, and let $P_{R'} = \{x + iy \in \mathbb{C}^N; \|x\| \le R', \|y\| \le 2R'\}$. Choose any $w_0 = u_0 + iv_0 \in \mathbb{C}^N \setminus (P_{R'} \cup Z)$.

If $w_0 \notin \tilde{Z}$, then there is $z_0 = x_0 + iy_0 \in \tilde{Z}$ such that $||x_0|| \ge R'$ and $||x_0 - u_0|| < ||y_0 - v_0||$. Define $g(z) = \sum_{j=1}^N (z_j - (z_0)_j)^2$; then $\text{Re}(g(w_0)) < 0$, if $z \in Z$ then $\text{Re}(g(z)) \ge 0$ by the Lipschitz condition, and if $z \in K_R$ then

$$\operatorname{Re}(g(z)) = \|x - x_0\|^2 - \|y - y_0\|^2 \ge (\|x_0\| - R)^2 - (\beta \|x_0\| + R)^2 > 0$$

by the choices made above.

If $w_0 \in Z$, then let $z_0 = w_0$ and define g(z) as above. We get that $g(w_0) = 0$ and that Re(g(z)) > 0 for all $z \in K_R \cup Z$.

In any case, it follows that $w_0 \notin h(K_R \cup Z)$, and hence that $h(K_R \cup Z) \subset P_{R'}$. \square



Proposition 4.3 Let $K \subset \mathbb{C}^N$ be compact, let $F : \mathbb{C}^N \to \mathbb{C}^M$ be an entire function, and let Y = F(K). For a point $y \in Y$, let F_y denote the fiber $F^{-1}(y)$, and let K_y denote the restricted fiber $F_y \cap K$. If $y \in Y$ is a peak point for the algebra $\mathcal{P}(Y)$, then

$$\widehat{K} \cap F_y = \widehat{K}_y.$$

Proof Since F_y is an analytic set, we have that $\widehat{K}_y \subset F_y$, so clearly $\widehat{K} \cap F_y \supset \widehat{K}_y$. For the other inclusion, let $x \in F_y$, $x \notin \widehat{K}_y$. Choose a polynomial P with $P(x) = 1 > \|P\|_{K_y}$. There is a neighborhood V of y such that |P| < 1 on $F^{-1}(V) \cap K$, and there is a function $Q \in \mathcal{P}(Y)$ such that Q(y) = 1 and |Q| < 1 on $Y \setminus \{y\}$. For a large enough integer $m \in \mathbb{N}$, we define $f = P \cdot (Q \circ F)^m$ and get that $f(x) = 1 > \|f\|_K$. Since Q is approximable by polynomials, we get that $x \notin \widehat{K}$.

Proposition 4.4 Let M be a totally real set of class C^k in \mathbb{C}^N , $k \geq 1$. If M admits C^1 Carleman approximation, then there exists a holomorphic map $F: \mathbb{C}^N \to \mathbb{C}^{2N}$ such that $F|_M$ is proper, and F(M) is a totally real set of class C^k which is polynomially convex and has bounded E-hulls in \mathbb{C}^{2N} .

Proof Let $R: \mathbb{C}^N \to \mathbb{R}^{2N}$ denote the real coordinate map

$$z = (z_1, \ldots, z_N) \mapsto (x_1, \ldots, x_{2N}),$$

where $z_j = x_{2j-1} + \mathrm{i} x_{2j}$ for $j = 1, \dots, N$, and let M_0 denote the set $M_0 = R(M)$. We regard M_0 as a subset of $\mathbb{R}^{2N} \oplus \{0\} \subset \mathbb{R}^{2N} \oplus \mathrm{i} \mathbb{R}^{2N} = \mathbb{C}^{2N}$.

By Proposition 2.7, there is a function $\tilde{R} \in C^1(\mathbb{C}^N)$ such that $\tilde{R}(z) = R(z)$ for all $z \in M$ and such that \tilde{R} is $\overline{\partial}$ -flat along M. The map \tilde{R} can be approximated arbitrarily well in C^1 -norm on M by a holomorphic map $F = f + ig : \mathbb{C}^N \to \mathbb{C}^{2N}$, *i.e.*, for any strictly positive, continuous function δ on M, we may find F such that

- (i) $|f \tilde{R}|_{1,x} < \delta(x)$ and
- (ii) $|g|_{1,x} < \delta(x)$

for all $x \in M$. If δ is chosen small enough, then $f|_M$ is an embedding. Defining $\psi := g \circ f^{-1} : S \to \mathbb{R}^{2N}$, we get that $Z = (f + \mathrm{i}g)(M)$ is a graph $\{(x, \psi(x))\}$ over S := f(M). Since $\|\tilde{R}(x) - \tilde{R}(y)\| = \|x - y\|$ for all $x, y \in M$, where $\|\cdot\|$ denotes the euclidean norm on \mathbb{R}^{2N} , we may choose δ small enough such that

(iii)
$$||f(x) - f(y)|| \ge \frac{2}{3} ||x - y||$$
 for all $x, y \in M$

and such that

(iv)
$$||g(x) - g(y)|| \le \frac{1}{2} ||x - y||$$
 for all $x, y \in M$.

For $x', y' \in S$, we write x' = f(x), y' = f(y). It follows from (iii) and (iv) that $\|\psi(x') - \psi(y')\| = \|g(x) - g(y)\| \le \frac{3}{4}\|x' - y'\|$. By Proposition 4.2, we get that Z is polynomially convex and has bounded E-hulls in \mathbb{C}^{2N} .

We may now tie the previous results together into a proof of Theorem 4.1.

Proof of Theorem 4.1. As already noted, it is enough to prove the theorem in the case where $X = \mathbb{C}^N$. It is a well known fact that M has to be polynomially convex for



approximation to hold (see, e.g., [15]). Let $K \subset \mathbb{C}^N$ be a compact set; we have to show that $h(K \cup M)$ is bounded.

Let $F: \mathbb{C}^N \to \mathbb{C}^{2N}$ be in accordance with Proposition 4.4, and let M_0 denote the image $M_0 = F(M)$. Since M_0 has bounded E-hulls in \mathbb{C}^{2N} , there exists R > 0 such that

$$h(F(K) \cup M_0) \subset R\overline{\mathbb{B}},$$

where \mathbb{B} is the open unit ball in \mathbb{C}^{2N} .

Let $X \subset K \cup M$ be a compact set, and let Y = F(X). We first show that $h(X) \subset F^{-1}(R\overline{\mathbb{B}})$. Let $x \in \mathbb{C}^N \setminus X$ be such that $\|F(x)\| > R$. If $F(x) \notin Y$, then there exist a polynomial P such that $\|P(F(x))\| > \|P\|_Y = \|P(F)\|_X$, and hence $x \notin \widehat{X}$. If $F(x) = y \in Y$, then y is a peak point for P(Y) by Proposition 3.12, and by Lemma 4.3 it follows that $\widehat{X} \cap F_y = \widehat{X}_y$. Since X_y consists of only one point, it follows that $x \notin \widehat{X}$, and hence we must have $h(X) \subset F^{-1}(R\overline{\mathbb{B}})$.

Since $F|_M$ is proper, we have that $M \cap F^{-1}(R\overline{\mathbb{B}})$ is compact, and hence also $(K \cup M) \cap F^{-1}(R\overline{\mathbb{B}})$ is compact. To finish the proof, we show that $h(X) = h(X \cap F^{-1}(R\overline{\mathbb{B}})) \subset h((K \cup M) \cap F^{-1}(R\overline{\mathbb{B}}))$, where the last set is independent of X.

Let $C = [X \cap F^{-1}(R\overline{\mathbb{B}})]$, and let $x \in \mathbb{C}^N \setminus C$ with $|F(x)| \leq R$. If $F(x) \notin \widehat{Y}$, then clearly $x \notin \widehat{X}$. If $F(x) \in \widehat{Y}$, use Corollary 3.14 to obtain an $f \in \mathcal{P}(\widehat{Y})$ such that $f \equiv 1$ on $\widehat{Y} \cap R\overline{\mathbb{B}}$ and |f| < 1 on $\widehat{Y} \setminus R\overline{\mathbb{B}} = Y \setminus R\overline{\mathbb{B}}$. Let P be a polynomial such that $P(x) = 1 > \|P\|_C$; then the function $g := P \cdot (f \circ F)^m$ will satisfy $g(x) = 1 > \|g\|_X$ if m is large enough. Since g can be approximated by polynomials, the result follows.

Open Access This article is distributed under the terms of the Creative Commons Attribution Noncommercial License which permits any noncommercial use, distribution, and reproduction in any medium, provided the original author(s) and source are credited.

References

- 1. Alexander, H.: A Carleman theorem for curves in \mathbb{C}^n . Math. Scand. **45**(1), 70–76 (1979)
- Carleman, T.: Sur un théorème de Weierstrass. Arkiv för Matematik, Astronomi och Fysik 20B(4), 1–5 (1927)
- Federer, H.: Geometric Measure Theory. Die Grundlehren der mathematischen Wissenschaften, Band 153. Springer, New York (1969)
- 4. Gaier, D.: Lectures on Complex Approximation. Birkhäuser, Boston (1987)
- 5. Gauthier, P.M., Zeron, E.: Approximation on arcs and dendrites going to infinity in \mathbb{C}^n . Canada Math. Bull. **45**(1), 80–85 (2008)
- Harvey, F.R., Wells, R.O.: Zero sets of non-negative strictly plurisubharmonic functions. Math. Ann. 201, 165–170 (1973)
- Hoischen, L.: Eine Verschärfung eines Approximationssatzes von Carleman. J. Approx. Theory 9, 272–277 (1973)
- Løw, E., Wold, E.F.: Polynomial convexity and totally real manifolds. Complex Var. Elliptic Equ. 54, 265–281 (2009)
- Manne, P.E.: Carleman approximation on totally real submanifolds of a complex manifold. Several Complex Variables. In: Fornæss J.E. (ed.) Proceedings of the Mittag-Leffler Institute, 1987–1988, Princeton University Press, New Jersey (1993)



- Manne, P.E.: Carleman approximation in several complex variables. Ph.D. Thesis, University of Oslo (1993)
- Manne, P.E.: Carleman approximation on totally real subsets of class C^k. Math. Scand. 74, 313–319 (1994)
- Nersesjan, A.H.: On Carleman sets (Russian). Izv. Akad. Nauk Armjan. SSR Ser. Mat. 6, 465–471 (1971)
- 13. Range, R.M.: Holomorphic Functions and Integral Representations in Several Complex Variables. Graduate Texts in Mathematics, 108. Springer, New York (1986)
- 14. Scheinberg, S.: Uniform approximation by entire functions. J. Anal. Math. 29, 16-18 (1976)
- 15. Stout, E.L.: Polynomial Convexity. Progress in Mathematics, 261. Birkhäuser, Boston (2007)
- 16. Stolzenberg, G.: Uniform approximation on smooth curves. Acta Math. 115, 185–198 (1966)
- Whitney, H.: Analytic extensions of differentiable functions defined in closed sets. Trans. Amer. Math. Soc. 36, 63–89 (1934)
- Wold, E.F.: A counterexample to uniform approximation on totally real manifolds in C³. Michigan Math. J. 58, 281–289 (2009)

