# HOMOTOPY INVARIANTS OF NONORIENTABLE 4-MANIFOLDS 

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#### Abstract

We define a $\mathbf{Z}_{4}$-quadratic function on $\pi_{2}$ for nonorientable 4manifolds and show that it is a homotopy invariant. We then use it to distinguish homotopy types of certain manifolds that arose from an analysis of toral action on nonorientable 4-manifolds.


## 1. Introduction

The oriented homotopy type or even the topological type of a closed simplyconnected smooth 4-manifold is determined by the intersection pairing on $\mathbf{H}^{2}$ $[8,1]$. If the fundamental group is nontrivial, there are three immediate homotopy invariants supported on the 3 -skeleton: $\pi_{1}, \pi_{2}$ as a $\mathbf{Z}\left[\pi_{1}\right]$-module, and the first $k$-invariant. There is also an immediate global homotopy invariant, the equivariant intersection pairing on $\pi_{2}$ with respect to the action of $\pi_{1}$. Surprisingly, no other invariants have garnered much attention so far. However it has been shown that these are actually enough to determine the homotopy types of orientable closed 4 -manifolds (or just Poincaré complexes) with special finite fundamental groups [6, 2].

We will show here by examples that this fails for nonorientable smooth 4manifolds at a very primitive stage by using two invariants: the $\mathbf{Z}_{2}$-intersection pairing on $\mathrm{H}^{2}$, and a $\mathbf{Z}_{4}$-quadratic function $q$ on $\pi_{2} \otimes \mathbf{Z}_{2}$. Our invariants are not entirely new, but the independence of the first one to the above four invariants and a geometric proof of the homotopy invariance of the second one are new.

Our quadratic function can be derived from Wall's self-intersection $\mu$ [7]. However we use another definition which is more convenient for showing its homotopy invariance. We work this out in the next section. Then we discuss three nonorientable 4-manifolds doubly covered by $S^{2} \times S^{2}$, and use our invariants to distinguish their homotopy types in the last section. In fact, the quadratic function was devised to distinguish these manifolds, which arose from an analysis by Myung Ho Kim of 2-dimensional toral actions on nonorientable 4-manifolds.

After completing this paper, Ian Hambleton pointed out to us that our invariant $q$, the $\mathbf{Z}_{4}$-quadratic function on $\pi_{2} \otimes \mathbf{Z}_{2}$, can be evaluated as the difference between a self-intersection number and the Browder-Liversay invariant in the orientable double cover. The unobvious but key connection can be found in

[^0]Lemma 4.6 of [10]. Hambleton and Milgram gave a homotopy theoretic definition of the Browder-Liversay invariant in [11]. Hence the homotopy invariance of $q$ would already follow from [10, 11]. Our geometric proof of the homotopy invariance of the $q$-invariant seems to have intrinsic interest.

Ian Hambleton also kindly pointed out to us a mistake in our earlier version. We wish to express our thanks for Professor Hambleton for his interest and helpful comments. We also thank the referee for his suggestions.

## 2. A $\mathbf{Z}_{4}$-QUADRATIC FUNCTION

Let $M$ be a closed smooth 4 -manifold with a base point. The invariant we shall define does make sense for all smooth manifolds but contains something new only if $M$ is nonorientable. Thus, to avoid unnecessary complications, we assume $M$ is nonorientable throughout this section. Choose elements $x$ and $y$ of $\pi_{2}(M)$ and represent them by transversely immersed 2-spheres $S_{x}$ and $S_{y}$ which also mutually intersect transversely. We denote by $x \cdot y$ the number of mutual intersections of $S_{x}$ and $S_{y}$ modulo 2. The value is the usual $\mathbf{Z}_{2}$-intersection number of those cycles, however since our domain is $\pi_{2}$, the bilinear form is not quite the same as the homology intersection. For example, it may be singular. Another description of $\cdot$ is the $\mathbf{Z}_{2}$-reduction of the argumented equivariant intersection on $\pi_{2}$.

Let $\widetilde{M}$ be the orientable double cover of $M$ with a base point which comes down to that of $M$. Then, fixing an orientation of $\widetilde{M}$, we define a function $q$ with values in $\mathbf{Z}_{4}$ for $x \in \pi_{2}(M)$ by

$$
q(x)=\chi\left(\nu\left(S_{x}\right)\right)+2 \# \text { self } S_{x} \text { modulo } 4
$$

Here $\nu\left(S_{x}\right)$ is the normal bundle of $S_{x}$ (we regard $S_{x}$ as a sphere by ignoring its self-intersection). Since we specified a homotopy class $x$ and fixed the base point on $\widetilde{M}, S_{x}$ has a unique lift $\widetilde{S}_{x}$ in $\widetilde{M}$. In particular, their normal bundles are canonically isomorphic with each other. We will identify $S_{x}$ with $\widetilde{S}_{x}$ through this lifting when we are concerned with the normal bundle. $\chi()$ is the Euler class evaluated with respect to the orientation of $\widetilde{M}$. More precisely, $\chi\left(\nu\left(S_{x}\right)\right)$ is the Euler number evaluated with the local orientation induced from one on $\nu\left(\widetilde{S}_{x}\right)$, or equivalently the number to be identified with $\chi\left(\nu\left(\widetilde{S}_{x}\right)\right)$. The Euler class makes sense as an integer. self $S_{x}$ is the set of self-intersections of $S_{x}$ and \# stands for its cardinality.

Lemma 1. $q$ is a well-defined $\mathbf{Z}_{4}$-quadratic function with respect to $\cdot$, namely,
(1) $q(n x)=n^{2} q(x)$ (in particular, $q(-x)=q(x)$ ), and
(2) $q(x+y)-q(x)-q(y)=2 x \cdot y \quad$ (4).

When we choose the other orientation of $\widetilde{M}, q$ becomes $-q$.
Proof. By Whitney [9] (cf. Matsumoto [5]), homotopic spheres in this dimension are connected by a finite sequence of regular homotopies and homotopies of creating or killing small Whitney singularities. The regular homotopy obviously does not change the value of $q$. When we create or kill a Whitney singularity, we add or subtract one self-intersection and thereby change its Euler class by $\pm 2$ according to the sign of intersection. Hence this operation does not change $q$ either. Properties (1) and (2) are quite easy to verify.

Remark. If $M$ is orientable, $q$ still makes sense by orienting $M$; then $q$ is the homology self-intersection number of the cycle represented by $S_{x}$ modulo 4 and hence there is nothing new.
Theorem 2. The equivalence class of $q(q \sim-q)$ is a homotopy invariant. More precisely, if $f: M \rightarrow N$ is a homotopy equivalence, then

$$
q_{M}(x)=q_{N}\left(f_{*}(x)\right) \quad \text { for all } x \in \pi_{2}(M)
$$

with respect to relevant orientations of the orientable double covers $\widetilde{M}$ and $\widetilde{N}$.
The proof of Theorem 2 occupies the rest of this section. First of all, take the lift $\tilde{f}: \widetilde{M} \rightarrow \tilde{N}$ of $f$ which preserves the base points, and then orient $\widetilde{M}$ and $\tilde{N}$ so that $\tilde{f}$ is of degree one. Choose a transversely immersed oriented 2-sphere $S$ in $M$ representing $x$. By property (1) of Lemma $1, q(x)$ is independent of the orientation of $S$, but, nevertheless, we shall use an orientation to simplify our computations.

Homotop $f$ so that the restriction of $f$ to $S$ is an immersion with transverse image and so that $f$ extends to a bundle map: $\nu(S) \rightarrow \nu(f(S))$. This is attained by first perturbing $f$ so that it becomes an immersion on $S$ with transverse image. Then since $\tilde{f}$ is a degree one homotopy equivalence, the cycles $\tilde{S}$ and $\tilde{f}(\tilde{S})$ must have the same homological intersection number, which is equal modulo 2 to the Euler class of the normal bundle. In particular, $\chi(\nu(S)) \equiv \chi(\nu(f(S)))(2)$. Thus, by homotoping $f$ by creating or killing small Whitney singularities, we can attain the identity $\chi(\nu(S))=\chi(\nu(f(S)))$. It is then obvious how to homotop $f$ to a bundle map on $\nu(S)$.

We adopt the following convention for orienting $f(S)$. Since $S$ is oriented, $\nu(S)$ is compatibly oriented by the orientation of $\widetilde{M}$. Then since $f$ extends to a bundle map, $\nu(f(S))$ admits an induced orientation. The orientation of $f(S)$ is to be the one that is compatible with the orientation of $\tilde{N}$. We denote $f(S)$ with this orientation by $S^{\prime}$.

The orientation of $S^{\prime}$ might be different from the orientation induced from one on $S$ by $f$. The reason why we take this convention is to make the sign of the degree of $f$ near $S$ clear. The degree of $\left.f\right|_{S}$ is 1 or -1 according to whether the orientation of $S^{\prime}$ agrees with the orientation induced by $f$ on $f(S)$ or not.

Homotop $f$ further fixing a neighborhood of $S$ so that $f$ is transverse regular to $S^{\prime}$. This means, in part, that at the self-intersection points of $S^{\prime}$, $f$ is a diffeomorphism near each of their preimages. For we may perturb $f$ near the preimage of the self-intersection points and then perturb $f$ near the preimage of $S^{\prime}-$ \{neighborhoods of self-intersections\}. Note that now there are no "manifold points" in the preimage of self-intersections by $f$ since $f$ is a diffeomorphism around them.

The inverse image $f^{-1}\left(S^{\prime}\right)$ then consists of transversely immersed connected surfaces $C_{j}, j=0,1, \ldots, n$, including $S$, with mutually transverse intersections. Since each $C_{j}$ behaves much like a connected component, we call it a component of the inverse image. Namely $f^{-1}\left(S^{\prime}\right)=\bigcup_{j} C_{j}$, where each $C_{j}$ is a component in our sense. We assume that $S=C_{0}$.
Lemma 3. Each $C_{j}$ lifts to $\widetilde{M}$. Moreover, each $C_{j}$ is an orientable surface with transverse self-intersections.

Proof. Since $S^{\prime}$ is a 2 -sphere with self-intersections, it lifts to $\tilde{N}$. In particular, the preimage of $S^{\prime}$ in $\widetilde{N}$ has two components in our sense. Think of the preimage of $C_{j}$ in $\widetilde{M}$. Since it is mapped to the preimage of $S^{\prime}$ by $\tilde{f}$, it must contain at least two and hence exactly two components. This means that $C_{j}$ is liftable.

By transverse regularity, $\nu\left(C_{j}\right)$ is a pullback of $\nu\left(S^{\prime}\right)$ by $\left.f\right|_{C_{j}}$, and it is orientable since $\nu\left(S^{\prime}\right)$ is orientable. As $C_{j}$ and hence $\nu\left(C_{j}\right)$ lifts to an orientable manifold $\widetilde{M}, C_{j}$ itself must be an orientable surface.

The component $C_{j}$ has a unique lift which maps to $\tilde{S}^{\prime}$ by $\tilde{f}$. For our convenience, we denote it by $\widetilde{C}_{j}$. As we have been doing for $S$, we shall identify $C_{j}$ and $\widetilde{C}_{j}$ when we are concerned with the normal bundle.

Orient $C_{j}$ by the following procedure. Since $S^{\prime}$ was oriented, $\nu\left(S^{\prime}\right)$ has a compatible orientation with one on $\tilde{N}$. Since $f$ is transverse regular to $S^{\prime}$, $\nu\left(C_{j}\right)$ gets an induced orientation. We then orient $C_{j}$ to be compatible with the orientation of $\widetilde{M}$. This is opposite to our previous procedure of orienting $S^{\prime}$ from the orientation of $S$, but we do recover the correct orientation for $C_{0}=S$. From now on we use the notation $C_{j}$ to represent an oriented surface.

Since each $C_{j}$ is now oriented, the degree of $\left.f\right|_{D_{j}}$, which we denote by $d_{j}$, is defined as an integer satisfying $f_{*}\left(\left[C_{j}\right]\right)=d_{j}\left[S^{\prime}\right]$, where the notation [*] denotes the integral homology class. For instance, $d_{0}= \pm 1$. We should also note here that $\left[C_{j}\right]=d_{j} d_{0}[S]$ since $f$ is homotopy equivalence.

We have two identities by the convention:

$$
\chi\left(\nu\left(C_{j}\right)\right)=d_{j} \chi\left(\nu\left(S^{\prime}\right)\right) \quad \text { and } \quad \sum_{j} d_{j}=1
$$

The Euler class for $\nu\left(C_{j}\right)$ in the first identity is evaluated with respect to our orientation convention. The second identity is the result of the fact that $\tilde{f}$ is of degree one in our orientation and verified by choosing a generic point on $S^{\prime}$ and checking how we count the degree of $\tilde{f}$ by $d_{j}$ 's.

We distinguish self-intersections according to their liftability to $\widetilde{M}$. Suppose $C$ is a transversely immersed surface in $M$ which has a specified lift $\widetilde{C}$ in $\widetilde{M}$. We let $R_{C}$ be the set of self-intersections of $C$ which lift to be self-intersections of $\tilde{C}$, and let $Q_{C}$ be those which do not. Obviously self $C$ is a disjoint union of $R_{C}$ and $Q_{C}$. The difference between these two is that $R_{C}$ contributes to the homological self-intersection number of $\widetilde{C}$ but $Q_{C}$ does not.

Lemma 4. $f\left(Q_{C}\right)$ is contained in $Q_{S^{\prime}}$ and $f\left(R_{C}\right)$ is contained in $R_{S^{\prime}}$.
Proof. Let $\omega_{M}: \pi_{1}(M) \rightarrow \mathbf{Z}_{2}$ be the corresponding homomorphism to the first Stiefel-Whitney class. Then to each self-intersection point of $C$, we assign the value of $\omega_{M}$ for a smooth path on $C$ which starts from the point in question and comes back to the same point from the other branch. This is a well-defined function since $C$ lifts, and the liftability of the point as a self-intersection point to $\widetilde{M}$ is classified by its value.

Since $f$ is homotopy equivalent, it sends the orientable subgroup in $\pi_{1}(M)$ to that of $\pi_{1}(N)$ and hence $\omega_{M}=\omega_{N} \circ f$. Therefore the liftability of selfintersection points in $C$ corresponds by means of $f$ to the liftability of selfintersection points in $S^{\prime}$ 。 $\square$

## Lemma 5.

$$
\begin{cases}\# R_{C_{j}} \equiv 0(2) & \text { if } d_{j} \equiv 0(4) \\ \# R_{C_{j}}-\# R_{S^{\prime}} \equiv 0(2) & \text { if } d_{j} \equiv 1(4) \\ \# R_{C_{j}} \equiv \chi\left(\nu\left(S^{\prime}\right)\right)(2) & \text { if } d_{j} \equiv 2(4) \\ \# R_{C_{j}}-\# R_{S^{\prime}} \equiv \chi\left(\nu\left(S^{\prime \prime}\right)\right)(2) & \text { if } d_{j} \equiv 3(4)\end{cases}
$$

Proof. Recall the identity $f_{*}\left[C_{j}\right]=d_{j}\left[S^{\prime}\right]$ and hence $\tilde{f}_{*}\left[\widetilde{C}_{j}\right]=d_{j}\left[\widetilde{S}^{\prime}\right]$. Since $\tilde{f}$ is a degree one homotopy equivalence, the homological self-intersection number of corresponding elements must be the same. We thus get

$$
\left[\widetilde{C}_{j}\right] \cdot\left[\widetilde{C}_{j}\right]=d_{j}^{2}\left[\widetilde{S}^{\prime}\right] \cdot\left[\widetilde{S}^{\prime}\right]
$$

The left-hand side is equal to $\chi\left(\nu\left(C_{j}\right)\right)+2 \sum$ self $\widetilde{C}_{j}$, where the summation here involves the sign of self-intersections. On the other hand, the right hand side is equal to $d_{j}^{2}\left(\chi\left(\nu\left(S^{\prime}\right)\right)+2 \sum \operatorname{self} \widetilde{S}^{\prime}\right)$. Notice here that we have the identities: $\sum \operatorname{self} \widetilde{C}_{j} \equiv \# R_{C_{j}}(2), \sum \operatorname{self} \widetilde{S}^{\prime} \equiv \# R_{S^{\prime}}(2)$, and $\chi\left(\nu\left(C_{j}\right)\right)=d_{j} \chi\left(\nu\left(S^{\prime}\right)\right)$. Thus, by substituting these identities into the first one, we have

$$
\begin{equation*}
d_{j}\left(d_{j}-1\right) \chi\left(\nu\left(S^{\prime}\right)\right) \equiv 2\left(\# R_{C_{j}}-d_{j}^{2} \# R_{S^{\prime}}\right) \tag{4}
\end{equation*}
$$

The congruences in the statement of the lemma are consequences of this congruence as $d_{j}$ varies modulo 4.
Lemma 6. $\# Q_{S^{\prime}} \equiv \sum_{j} \# Q_{C_{j}}(2)$.
Proof. Let $A_{j}$ be the difference set $\left.f\right|_{C_{j}}{ }^{-1}\left(Q_{S^{\prime}}\right)-Q_{C_{j}}$ and let $B_{j}$ be the set $\left.f\right|_{C_{j}}{ }^{-1}\left(R_{S^{\prime}}\right)-R_{C_{j}}$ corresponding to liftable intersections. In other words, $A_{j}$ is the set of points in $C_{j}$ which intersect with another component of $f^{-1}\left(S^{\prime}\right)$ and which map to unliftable self-interactions of $S^{\prime}$, and $B_{j}$ is the corresponding set mapping to liftable self-intersections. The obvious identity obtained from Lemma 4 and transverse regularity of $f$ to self $S^{\prime}$ yields

$$
\# f^{-1}\left(Q_{S^{\prime}}\right)=\sum_{j} \# Q_{C_{j}}+\frac{1}{2} \sum_{j} A_{j}
$$

The left-hand side is equal modulo 2 to $(\operatorname{deg} f) \# Q_{S^{\prime}} \equiv \# Q_{S^{\prime}}(2)$. Thus it is enough to show that the last term of the identity is even.

We first count the number of mutual intersections,

$$
\begin{align*}
\frac{1}{2} \sum_{j}\left(\# A_{j}+\# B_{j}\right) & =\sum_{i<j} \# C_{i} \cap C_{j} \\
& \equiv \sum_{i<j} d_{i} d_{0}[S] \cdot d_{j} d_{0}[S]  \tag{2}\\
& \equiv \sum_{i<j} d_{i} d_{j}(\chi(\nu(S))+2 \# \operatorname{self} S)  \tag{2}\\
& \equiv \sum_{i<j} d_{i} d_{j} \chi(\nu(S))
\end{align*}
$$

Another obvious identity obtained from Lemma 4 and transverse regularity of $f$ on self $S^{\prime}$ is

$$
\# f^{-1}\left(R_{S^{\prime}}\right)=\sum_{j} \# R_{C_{j}}+\frac{1}{2} \sum_{j} \# B_{j} .
$$

The left-hand side is equal modulo 2 to $(\operatorname{deg} f) \# R_{S^{\prime}} \equiv \sum_{j} d_{j} \# R_{S^{\prime}}(2)$. Hence we have

$$
\begin{align*}
\frac{1}{2} \sum_{j} \# B_{j} & \equiv \sum_{j} d_{j} \# R_{S^{\prime}}-\sum_{j} \# R_{C_{j}}  \tag{2}\\
& \equiv \sum_{j}\left(d_{j} \# R_{S^{\prime}}-\# R_{C_{j}}\right)  \tag{2}\\
& \equiv\left(\sum_{d_{j} \equiv 0(4)}+\sum_{d_{j} \equiv 1(4)}+\sum_{d_{j} \equiv 2(4)}+\sum_{d_{j} \equiv 3(4)}\right)\left(d_{j} \# R_{S^{\prime}}-\# R_{C_{j}}\right)  \tag{2}\\
& \equiv \sum_{d_{j} \equiv 2,3} \chi\left(\nu\left(S^{\prime}\right)\right)  \tag{2}\\
& \equiv \sum_{d_{j} \equiv 2,3} d_{0} \chi(\nu(S))
\end{align*}
$$

by Lemma 5. The term we are interested in now becomes

$$
\begin{equation*}
\frac{1}{2} \sum_{j} \# A_{j} \equiv\left(\sum_{i<j} d_{i} d_{j}+\sum_{d_{i} \equiv 2,3} d_{0}\right) \chi(\nu(S)) \tag{2}
\end{equation*}
$$

We conclude the lemma by showing that the coefficient of $\chi(\nu(S))$ is even. Let $D_{k}$ be the number of $d_{j}$ 's whose residue modulo 4 is $k$. Since the sum of the $d_{j}$ 's is equal to 1 , we obtain

$$
\begin{equation*}
0 \cdot D_{0}+1 \cdot D_{1}+2 \cdot D_{2}+3 \cdot D_{3} \equiv 1 \tag{4}
\end{equation*}
$$

Then we can easily obtain

$$
\begin{equation*}
\frac{1}{2}\left(D_{1}+D_{3}\right)\left(D_{1}+D_{3}-1\right) \equiv\left(D_{2}+D_{3}\right) \tag{2}
\end{equation*}
$$

The left-hand side is the first summation in the coefficient, while the right-hand side is the last one.

Proof of Theorem 2. Since $q_{N}\left(f_{*}(x)\right)=q_{N}\left(-f_{*}(x)\right)$ by Lemma 1, we are allowed to use our oriented 2-sphere $S^{\prime}$ to compute $q_{N}\left(f_{*}(x)\right)$. The difference of their value is

$$
q_{M}(x)-q_{N}\left(f_{*}(x)\right)=\chi(\nu(S))-\chi\left(\nu\left(S^{\prime}\right)\right)+2\left(\# R_{S}-\# R_{S^{\prime}}\right)+2\left(\# Q_{S}-\# Q_{S^{\prime}}\right)
$$

By Lemma 5, the first four terms cancel each other modulo 4. We will show that the last two terms also cancel by deriving a contradiction from the opposite supposition.

Hence assume that $\# Q_{S} \not \equiv \# Q_{S^{\prime}}(2)$. We first claim that there is a component $C$ of $f^{-1}\left(S^{\prime}\right)$ so that $\# Q_{C} \not \equiv \# Q_{d S}(2)$, where $d$ is the degree of $\left.f\right|_{C}$ times $d_{0}$, and $d S$ is a cycle representing $d[S]=[C]$ obtained by taking $d$ "parallel" cross-sections of $\nu(S)$ with mutual transverse intersections.

The self-intersections of $d S$ either are produced due to nontriviality of the Euler class of $\nu(S)$ or inherit the self-intersections of $S$. The second one forms a lattice in a small neighborhood of each self-intersection of $S$. Since $d S$ is contained in $\nu(S)$, it has a unique lift $d \widetilde{S}$ contained in $\nu(\widetilde{S})$. The self-intersections due to nontrivial Euler class all are liftable to $d \widetilde{S}$. The lattice
intersections around $R_{S}$ are also all liftable. But those around $Q_{S}$ are certainly not, and each point in $Q_{S}$ produces $d^{2}$ unliftable self-intersections. Thus we get a nice numerical property $\# Q_{d S}=d^{2} \# Q_{S}$.

We take all congruences modulo 2 in the verification of our claim. Suppose $\# Q_{S^{\prime}} \equiv 1$. Then $\# Q_{S} \equiv 0$ by the supposition. Hence there must be another component $C$ with $\# Q_{C} \equiv 1$ by Lemma 6 . Then, since $\# Q_{d S}=d^{2} \# Q_{S} \equiv 0$ is not equal to $\# Q_{C}$, we are done.

Suppose $\# Q_{S^{\prime}} \equiv 0$. Then $\# Q_{S} \equiv 1$ by the supposition. In this case, by Lemma 6, the number of $C_{j}$ 's with $\# Q_{C_{j}} \equiv 1$ must be even. If one such $C_{j}$ has even degree, let it be $C$. Then $\# Q_{d S}=d^{2} \# Q_{S} \equiv 0$ which is not equal to $\# Q_{C}$ and we are done. When all of the $C_{j}$ 's with $\# Q_{C_{j}} \equiv 1$ have odd degree, since there is an even number of such $C_{j}$ 's, there must be another component $C_{i}$ with $\# Q_{C_{i}} \equiv 0$ and odd degree because the total degree is 1 , which is odd. Thus let that component be $C$. Then $\# Q_{d S}=d^{2} \# Q_{S} \equiv 1$ which is not equal to $\# Q_{C}$ and we have now established the claim.

We finish the proof of invariance by getting a contradiction. Recall that $C$ is homologous to $d S$. Surger $C$ and $d S$ respectively in $M$ by removing a small neighborhood of each liftable intersection in $R_{C}$ and $R_{d S}$ and then sewing back an annulus with the compatible orientation. Denote the resultant immersed surfaces by $C^{*}$ and $d S^{*}$. The surgery does not change their homology class, and they are still homologous to each other. Since we surgered around the liftable self-intersections, the resultants lift to $\widetilde{M}$ also. Choose their unique lifts $\widetilde{C}^{*}$ and $d \widetilde{S}^{*}$ corresponding to $\widetilde{C}$ and $d \widetilde{S}$. These are homologous since $\tilde{f}$ is a homotopy equivalence and $\tilde{f}_{*}\left(\left[\widetilde{C}^{*}\right]\right)=\tilde{f}_{*}\left(\left[d \widetilde{S}^{*}\right]\right)$. Also since we surgered on all the liftable self-intersections, they turn out to be embedded surfaces. Thus they are $L$-equivalent, that is, there is a proper orientable submanifold $V$ in $\widetilde{M} \times[0,1]$ so that $V \cap \widetilde{M} \times\{0\}=\widetilde{C}^{*}$ and $V \cap \widetilde{M} \times\{1\}=-d \widetilde{S}^{*}$. Then perturb $V$ slightly without moving a neighborhood of the boundary; we may assume that $V$ has a transverse image in $M \times[0,1]$. Hence its self-intersectional singularity forms a 1 -dimensional proper submanifold in $M \times[0,1]$. Each nonclosed component of the singularity has two end points at the boundary, which are the members of the unliftable self-intersections $Q_{C} \cup Q_{d S}$. But this set was claimed and shown to have an odd number of elements. This is a contradiction.

Remark. Our quadratic function can be derived from Wall's self-intersection $\mu$ [7]. It is defined in our case on $\pi_{2}$ of the associated Stiefel bundle over $M$ with values in $\lambda=\mathbf{Z}\left[\pi_{1}\right]$ modulo some ambiguity. This homotopy group is identified with the set of regular homotopy classes of a 2 -sphere in $M$. The ambiguity will disappear if we reduce its image to $\mathbf{Z}_{2}\left[\mathbf{Z}_{s}\right]$ by the homomorphism: $\pi_{1}(M) \rightarrow$ $Z_{2}$ associated to the first Stiefel-Whitney class and the $\mathbf{Z}_{2}$ reduction of the coefficients. Furthermore, if we compose the collapsing map of the constant factor: $\mathbf{Z}_{2}\left[\mathbf{Z}_{2}\right] \cong \mathbf{Z}_{2} \oplus \mathbf{Z}_{2} \rightarrow \mathbf{Z}_{2}: a+b g \rightarrow b$, to the reduction, then $\mu$ comes down to the map from $\pi_{2}(M)$. Let us denote this map by $\mu^{*}: \pi_{2}(M) \rightarrow \mathbf{Z}_{2}$. Then since $\mu^{*}(x) \equiv \# Q_{S_{x}}(2)$, we have the identity

$$
q(x)=\chi\left(\nu\left(S_{x}\right)\right)+2 \# R_{S_{x}}+2 \mu^{*}(x)=\left[\widetilde{S}_{x}\right] \cdot\left[\widetilde{S}_{x}\right]+2 \mu^{*}(x)
$$

## 3. Examples

The invariants are practical tools to detect the homotopy type of manifolds. Hence it would be instructive to compute them from concrete examples. We present here three nonorientable manifolds with the same 3 -skeleton and see how the invariants work. The computation shows the nontriviality of the $\mathbf{Z}_{2}$ intersection pairing and $q$-function, and their independence to the other invariants, and unfortunately leaves a few unanswered questions.

Start with a $D^{2}$-bundle over $S^{2}$ with Euler class $2 n$. Denote it by $E_{n}$. The boundary of $E_{n}$ is a circle bundle over $S^{2}$. It admits a free involution $\tau_{0}$ rotating each fiber half, and another free involution $\tau_{1}$ rotating each fiber half and simultaneously rotating the base half along some axis. On $E_{n}$, we identify the orbits of $\tau_{j}$ on the boundary of $E_{n}$ with points. We shall denote this quotient space by $N_{n j}=E_{n} / \tau_{j}, j=0,1$.

Split the base $S^{2}$ into two disks $D_{+}$and $D_{-}$along the equator perpendicular to the axis of rotation. Over $D_{+}$and $D_{-}$the fibration $E_{n}$ is split into $E_{n}^{+}$and $E_{n}^{-}$. Both involutions leave each component invariant and we get the decomposition $N_{n j}=E_{n}^{+} / \tau_{j} \cup E_{n}^{-} / \tau_{j}$, where these two parts are diffeomorphic to each other. From this decomposition it can be seen that $N_{n 0}$ is diffeomorphic to $S^{2} \times R P^{2} \cong N_{00}$ and that $N_{n 1}$ is diffeomorphic to either $N_{01}$ or $N_{11}$ according to whether $n$ is even or odd. For example, with $\tau_{0}, E_{n}^{+} / \tau_{0}$ and $E_{n}^{-} / \tau_{0}$ are two copies of $D^{2} \times R P^{2}$ glued together by a diffeomorphism $f_{n}$ along $S^{1} \times R P^{2}$. The diffeomorphism, which is isotopic to the identity, extends to a diffeomorphism from $N_{00}=D_{+} \times R P^{2} \cup_{\text {id }} D_{-} \times R P^{2}$ to $N_{n 0}=D_{+} \times R P^{2} \cup_{f_{n}} D_{-} \times R P^{2}$. On the other hand, $E_{n} / \tau_{1}=E_{n}^{+} / \tau_{1} \cup_{g_{n}} E_{n}^{-} / \tau_{1}$ is the union of two nontrivial 2-disk bundles over $R P^{2}$. The glueing mapping $g_{n}$ is defined over the equator on the twisted $S^{2}$-bundle over $S^{1}$. This time $g_{n}$, because of $\tau_{1}$, is isotopic to $g_{n+2}$ and we get a diffeomorphism of $N_{n 1}$ to $N_{01}$ if $n$ is even and to $N_{11}$ if $n$ is odd.

Let us review the invariants of $N_{00}=S^{2} \times R P^{2}$. It has $\pi_{1} \cong \mathbf{Z}_{2}$ and $\pi_{2} \cong$ $\mathbf{Z} \oplus \mathbf{Z}$ generated by each factor, say $x$ and $y$. Then the action of $\pi_{1}$ is given by $(x, y) \rightarrow(x,-y)$. Since $\pi_{1}$ twists the second factor of $\pi_{2}, \mathrm{H}^{3}\left(\pi_{1} ; \pi_{2}\right) \cong$ $\mathbf{Z}_{2}$. The first $k$-invariant is supported by an embedded $R P^{2}$, and hence is nontrivial.

If we let $e$ be a 2-disk in $E_{n}$ bounded by the invariant circle on $\partial E_{n}$, $e \cup \partial E_{n} / \tau_{1}$ forms a 3-skeleton of $N_{n 1}$. It is homeomorphic to $e \cup \partial E_{n} / \tau_{0}$, which is a 3-skeleton of $N_{00}$. Hence each $N_{n 1}$ has a common 3-skeleton with $N_{00}$ up to homotopy. In particular, they share $\pi_{1}, \pi_{2}$ as a $\Lambda$-module and the unique nontrivial first $k$-invariant in $\mathrm{H}^{3}\left(\pi_{1} ; \pi_{2}\right) \cong \mathbf{Z}_{2}$ with $N_{00}$. Since $\tau_{1}$ is isotopic to the identity, both $N_{01}$ and $N_{11}$ are doubly covered by the double of $E_{n}$, which is diffeomorphic to $S^{2} \times S^{2}$. On the other hand, every orientation reversing involution induces the automorphism of $\pi_{2}\left(S^{2} \times S^{2}\right)$ described by $(x, y) \rightarrow(x,-y)$ up to base change. Hence this fact forces $N_{01}$ and $N_{11}$ to have the same equivariant intersection paring on $\pi_{2}$ with $N_{00}$.

Homotopy invariants. $N_{00}$ has the hyperbolic $\mathbf{Z}_{2}$-intersection pairing and the others have the standard one, while $N_{01}$ has a trivial $q$-function and the others have a nontrivial one. In particular, they are not mutually homotopy equivalent to each other.

Computation. The $\mathbf{Z}_{2}$-intersection pairing of $N_{00}$ is obvious. To compute it for the others, recall the decomposition $N_{n 1}=E_{n}^{+} / \tau_{1} \cup E_{n}^{-} / \tau_{1}$. Each factor, as we have observed, is a disk bundle over $R P^{2}$, and its boundary is a nonorientable bundle. The exact sequence for this pair shows that its spine, $R P^{2}$, is a self dual Poincaré dual class in $E_{n}^{ \pm} / \tau_{1}$. Using this fact and the Mayer-Vietoris exact sequence, we can verify that $H^{2}\left(N_{n 1} ; \mathbf{Z}_{2}\right)$ for all $n$ is isomorphic to $\mathbf{Z}_{2} \oplus \mathbf{Z}_{2}$ and has the standard (odd) form.

To compute $q$-functions for $N_{00}$ and $N_{11}$, look at $E_{1} / \tau_{j}(j=0,1)$ and find an embedded $S^{2}$ with Euler class 2 as the zero section of $E_{1}$. In particular, their $q$-functions are nontrivial. To compute it for $N_{01}$, recall that the $q$ function is $\mathbf{Z}_{4}$-quadratic. Thus we only need to know values of two primitive independent elements of $\pi_{2}\left(N_{01}\right) \cong \mathbf{Z} \oplus \mathbf{Z}$. An element to compute easily is the zero section of $E_{0}$ whose value is zero. The other element to compute easily is the sphere lying on $\partial\left(E_{0}^{+} / \tau_{1}\right)$. Since this is an embedded sphere with trivial normal bundle, its value is also zero. It is then obvious by looking at the universal cover that these two form a primitive pair of $\pi_{2}\left(N_{01}\right)$, and the $q$-function of $N_{01}$ is trivial.

Remark. Hambleton and Kreck suggested the connection between $k$-invariants and $\mathbf{Z}_{2}$-intersection pairings in [2]. However our examples show that they are rather independent, at least in the nonorientable case.

Finally, we review these examples from homotopy theoretic viewpoints. Take a 3-skeleton of $N_{00}=S^{2} \times R P^{2}$ sitting as $K=S^{2} \times R P^{1} \cup * \times R P^{2} . N_{00}$ is then a union of $K$ and a single 4 -cell $e^{4}$. The universal cover $\widetilde{K}$ of $K$ is homeomorphic to $S^{2} \times S^{1} \cup e \cup e^{\prime}$, where $e$ and $e^{\prime}$ are 2-cells attached to $* \times S^{1}$ canonically. The covering transformation acts on $\widetilde{K}$ by the (identity) $\times$ (halfrotation) on the $S^{2} \times S^{1}$ part and by the antipodal map on $e \cup e^{\prime}=S^{2}$. On the other hand, $\widetilde{K}$ has the homotopy type $S^{2} \vee S^{2} \vee S^{3}$, where the first two $S^{2}$ correspond to $S^{2} \times *$ and $e \cup e^{\prime}$ respectively. Hence $\pi_{3}(K) \cong \pi_{3}(\tilde{K})$ is isomorphic to $\mathbf{Z}^{4}$. The generators can be described by $g_{1}$ and $g_{2}$, the Hopf maps to the first two spheres, $g_{3}$, the Whitehead product to $S^{2} \vee S^{2}$, and $g_{4}$, the standard degree one map to the $S^{3}$ factor.

Lemma 7. The action of the covering transformation $T$ on $\pi_{3}(\widetilde{K}) \cong \pi_{3}(K)$ is given by $T\left(g_{j}\right)=g_{j}$ for $j=1,2, T\left(g_{3}\right)=-g_{3}$ and $T\left(g_{4}\right)=g_{3}+g_{4}$.
Sketch of proof. The action for $g_{1}$ and $g_{3}$ should be obvious. The action for $g_{2}$ is identical because the reflection map on the base sphere of the Hopf fibration is covered by an orientation preserving map of $S^{3}$.

We roughly sketch how to get the last claim. Let us decompose $S^{3}$ into two solid tori $U$ and $V$. Thicken two 2-cells in $\widetilde{K}$ by producing $D^{2}$ so that $e \times D^{2}$ attaches to $S^{2} \times S^{1}$ in a tubular neighborhood of $* \times S^{1}$. The complement $W$ of its attaching part in $S^{2} \times S^{1}$ is also a solid torus. Then the map $g_{4}$ is the map sending $U$ to the complement $W$ and $V$ to $e \cup D^{2}$, while $T\left(g_{4}\right)$ maps $U$ to the same $W$ but $V$ to $e^{\prime} \cup D^{2}$. Then it is not hard to find a homotopy of the map $T\left(g_{4}\right)-g_{4}$ to the Whitehead product $g_{3}$ which maps $U$ to $S^{2} \times *$ and $V$ to $e \cup e^{\prime}$.

By attaching a 4-cell to $K$ by a glueing map $\gamma \in \pi_{3}(K) \cong \mathbf{Z}^{4}$, we obtain a 4-complex $K_{\gamma}=K \cup_{\gamma} e^{4}$. Since the $N_{n, j}$ 's have a common 3-skeleton, they
all are so obtained. But not all $\gamma$ 's produces a manifold or even a Poincaré complex. Also, different $\gamma$ 's might produce homotopy equivalent complexes.

Poincaré complexes. If $\gamma=g_{4}, g_{4}+g_{1}, g_{4}+g_{2}$, or $g_{4}+g_{1}+g_{2}$, then $K_{\gamma}$ is a Poincaré complex doubly covered by a homotopy $S^{2} \times S^{2}$. They are not mutually homotopy equivalent.
Computation. Suppose that $K_{\gamma}$ is a Poincaré complex. Then since $\mathbf{H}_{3}\left(K_{\gamma}\right)$ is trivial, the Hurewicz image of $\gamma$ must generate $\mathrm{H}_{3}(\widetilde{K})$ as a $\mathrm{Z}\left[\pi_{1}\right]$-module. In our case, the only $g_{4}$ factor in $\pi_{3}(K)$ survives in the image. Also we must have a nonsingular symmetric bilinear form on $\pi_{2}(K) \cong \pi_{2}\left(K_{\gamma}\right)$, which corresponds to the intersection form on $\mathrm{H}_{2}\left(\widetilde{K}_{y}\right)$. In our case, the direct summand of $\pi_{3}(K)$ generated by $g_{1}, g_{2}, g_{3}$ is identified with the set of symmetric bilinear forms on $\pi_{2}(K)$ (cf. [3]), and $(1-T) \gamma$ represents the form on $\pi_{2}(\widetilde{K})$. If both properties are satisfied, then $K_{\gamma}$ is a Poincaré complex.

It is then quite easy by Lemma 7 to compute which $\gamma$ produces a Poincaré complex. To rule out obvious homotopic examples, observe that $K_{\gamma}$ is homotopy equivalent to $K_{-\gamma}$ and $K_{T(\gamma)}$. Hence one significant family of $K_{\gamma}$ 's having the form $-g_{3}$ on $\pi_{2}\left(K_{\gamma}\right)$ is obtained by the sum of $g_{4}$ with arbitrary linear combinations of $g_{1}$ and $g_{2}$. Since we chose $-g_{3}$ for the intersection form, each $K_{\gamma}$ is doubly covered by a homotopy $S^{2} \times S^{2}$.

On the other hand, suppose that there is a homotopy equivalence $f: K_{\gamma^{\prime}} \rightarrow$ $K_{\gamma}$ so that $f$ is the identity on a 2 -skeleton $K^{(2)}$. Since there certainly exists a continuous extension of $\left.f\right|_{K^{(2)}}$ from $K_{\gamma^{\prime}}$, the obstruction class defined by $\left.f\right|_{K^{(3)}}$ in $\mathrm{H}^{4}\left(K_{\gamma^{\prime}} ; \pi_{3}\left(K_{\gamma}\right)\right)$ must vanish. By Poincaré duality with Wall's twisted coefficients (see Wall [7, p. 25]), we have the isomorphisms

$$
\mathrm{H}^{4}\left(K_{\gamma^{\prime}} ; \pi_{3}\left(K_{\gamma}\right)\right) \cong \mathrm{H}_{0}^{t}\left(K_{\gamma^{\prime}} ; \pi_{3}\left(K_{\gamma}\right)\right) \cong \pi_{3}\left(K_{\gamma}\right) \otimes_{\Lambda} \mathbf{Z}
$$

and the obstruction element is represented by $\gamma^{\prime}$. Thus consider an epimorphism $\pi_{3}(K) \rightarrow \pi_{3}\left(K_{\gamma}\right) \otimes_{\Lambda} \mathbf{Z}$. It descends to $\pi_{3}(K) \otimes_{\Lambda} \mathbf{Z} \rightarrow \pi_{3}\left(K_{\gamma}\right) \otimes_{\Lambda} \mathbf{Z}$, where the domain is isomorphic to $\mathbf{Z}_{2} \oplus \mathbf{Z}_{2} \oplus \mathbf{Z}$ generated by $g_{1}, g_{2}$, and $g_{4}$ in each summand. Hence, letting $\left\{\gamma, \gamma^{\prime}\right\}$ be any pair in $\left\{g_{4}, g_{4}+g_{1}, g_{4}+g_{2}, g_{4}+g_{1}+\right.$ $\left.g_{2}\right\}$, we can verify that the $K_{\gamma}$ 's are homotopically distinct from each other, at least fixing $K^{(2)}$.

Then it can be shown without too much difficulty that $N_{00}, N_{01}, N_{11}$ actually correspond to the elements $\gamma=g_{4}, g_{4}+g_{1}, g_{4}+g_{1}+g_{2}$, respectively. Also, Hambleton and Milgram showed in $[11, \S 3]$ that the Poincaré complex defined by $\gamma=g_{4}+g_{2}\left(J+\eta_{1}\right.$ in their notation $)$ is not homotopy equivalent to a topological manifold. Hence they are actually homotopically distinct.

We would like to finish this paper by asking the following
Question. Does the set of six invariants appearing here determine the homotopy type of a nonorientable 4-dimensional Poincaré complex with $\pi_{1} \cong \mathbf{Z}_{2}$ ?

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