Hybrid Steepest Descent Method for Variational Inequality Problem over Fixed Point Sets of Certain Quasi-Nonexpansive Mappings

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We are trying to solve: in Real Hilbert Sp  $\mathcal{H}$ 

**Variational Inequality Problem over** Fix(T) — For given  $T : \mathcal{H} \to \mathcal{H}$  and  $\Theta : \mathcal{H} \to \mathbb{R}$  (Convex func.), Find $u^* \in Fix(T) := \{x \in \mathcal{H} \mid T(x) = x\}$  closed convex s.t.  $\langle u - u^*, \Theta'(u^*) \rangle \ge 0, \forall u \in Fix(T).$ 

For T: Convex Projection  $\Rightarrow$  Gradient Projection Method (Goldstein'64/Levitin&Polyak'66)

- We propose Hybrid Steepest Descent Method

T: H → H Nonexpansive Mapping
 (Yamada et al '96— / Deutsch & Yamada '98 / Yamada '01)
 Appl: Convexly Constrained Inverse Problems
 T: H → H Quasi-Nonexpansive(Yamada&Ogura'03)

Appl: Optimization of Fixed Point of Subgradient Projector

### Part 1

# **Background / Preliminaries**

### Original Idea of Gradient Projection Method



- Gradient Projection Method (1964-)  $u_{n+1} := P_K(u_n - \lambda_{n+1}\Theta'(u_n)),$ n = 0, 1, 2, ...

under certain conditions —

converges (strongly / weakly) to a solution to

Smooth Convex Optimization Problem (P1)  $\neg$ 

Minimize  $\Theta: \mathcal{H} \to \mathbb{R}$  G-differentiable convex func.

Subject to  $x \in K (\subset \mathcal{H})$  closed convex set

where  $\mathcal{H}$ : Real Hilbert Space

**NOTE:**  $u^* \in K$  is a solution of (P1)

 $\Leftrightarrow u^* \in K \text{ satisfies } \langle u - u^*, \Theta'(u^*) \rangle \geq 0, \forall u \in K.$ 

## Part 2

### **Hybrid Steepest Descent Method**

From Projection to Nonexpansive Mapping / Quasi-Nonexpansive Mapping  $T: \mathcal{H} \to \mathcal{H}$  is called  $\kappa$ -Lipschitzian if  $\exists \kappa > 0$  s.t.

$$||T(x) - T(y)|| \leq \kappa ||x - y||$$
 for all  $x, y \in \mathcal{H}$ .

If  $\kappa = 1$  —

• 
$$T: \mathcal{H} \to \mathcal{H}$$
 is **Nonexpansive mapping**.

• 
$$Fix(T) := \{x \in \mathcal{H} \mid T(x) = x\}$$
 is closed convex.

• Generalization 
$$\kappa < 1 \Rightarrow \kappa < 1$$
 or  $\kappa = 1$   
broadens **Fixed Point Theory** significantly.

• Many choices of 
$$T$$
 s.t.  $Fix(T) = K$ , e.g.,  
 $Fix\left(\sum_{i=1}^{m} w_i T_i\right) = \bigcap_{i=1}^{m} Fix(T_i)$  if  $\bigcap_{i=1}^{m} Fix(T_i) \neq \emptyset$ .

Is It Possible to Extend from **Gradient Projection Method**  $v_{n+1} := P_K(v_n - \lambda_{n+1}\Theta'(v_n))$ to  $v_{n+1} := T(v_n - \lambda_{n+1} \Theta'(v_n))$ where  $T : \mathcal{H} \to \mathcal{H}$ : Nonexpansive Mapping

# for Minimizing $\Theta$ over Fix(T)?

#### To Answer to the Question, we introduce

- Hybrid Steepest Descent Method (Yamada et al, 1996—), $u_{n+1} := T(u_n) - \lambda_{n+1} \Theta'(T(u_n))$ where  $T: \mathcal{H} \to \mathcal{H}$ : Nonexpansive Mapping



#### In short,

#### Hybrid Steepest Descent Method (Yamada2001):

$$u_{n+1} := T(u_n) - \lambda_{n+1} \Theta'(T(u_n))$$

can minimize  $\Theta$  over Fix(T),

#### where

 $T: \mathcal{H} \to \mathcal{H}$ : nonexpansive, and  $(\lambda_n)_{n=1}^{\infty} \subset \mathbb{R}^+$ : slowly decreasing.

#### Sequence Generation by Hybrid Steepest Descent Method



#### Hybrid Steepest Descent Method (Yamada 2001)

Suppose that

(a)  $T: \mathcal{H} \rightarrow \mathcal{H}$ : Nonexp. mapping,

(b)  $\Theta : \mathcal{H} \to \mathbb{R}$ :Convex function,

(c)  $\Theta'$ : Lipschitzian & Strongly monotone over  $T(\mathcal{H})$ ,

(d)  $(\lambda_n)_{n\geq 1}\subset [0,\infty)$  satisfies

(i) 
$$\lim_{n \to \infty} \lambda_n = 0$$
, (ii)  $\sum_{n \ge 1} \lambda_n = \infty$ , (iii)  $\sum_{n \ge 1} |\lambda_n - \lambda_{n+1}| < \infty$ .

 $\underbrace{u_{n+1} := T(u_n) - \lambda_{n+1} \Theta'(T(u_n))}_{\text{satisfies}}$ 

s- $\lim_{n\to\infty} u_n = u^* \in \arg \inf_{x\in Fix(T)} \Theta(x)$ . (Unique)

If we specially choose  $\Theta(x) := \frac{1}{2} ||x - a||^2$ in the Hybrid Steepest Descent Method, Halpern ('67), P.L.Lions ('77), Wittmann ('92)  $\neg$  $u_{n+1} := \lambda_{n+1}a + (1 - \lambda_{n+1})T(u_n),$ converges strongly to  $P_{Fix(T)}(a)$ , where  $T: \mathcal{H} \rightarrow \mathcal{H}$ : nonexpansive, and  $(\lambda_n)_{n=1}^{\infty} \subset \mathbb{R}^+$ : slowly decreasing.

More general cyclic versions were given by

P.L. Lions (1977) and H.H. Bauschke (1996)

#### <u>Generalization of $\Theta$ </u>

Θ': Lipschitzian & Paramonotone (Ogura, Yamada 2002)

### **Robust Hybrid Steepest Descent Method**

$$u_{n+1} := T_{(n)}(u_n) - \lambda_{n+1}\Theta'(T_{(n)}(u_n))$$

where 
$$T_{(n)} := (1 - t_{n+1})I + t_{n+1}T$$

is gifted with **notable numerical robustness**.

For detail, see Contemporary Mathematics 313 (2002)

Generalized Inverse Problem	
Let	$K \subset \mathcal{H}$ : a closed convex set,
	$\Psi:\mathcal{H} ightarrow\mathbb{R}$ : the 1st convex function,
satisfying	
	$K_{\Psi} := \arg \inf_{x \in K} \Psi(x) \neq \emptyset.$
Then the problem is	
Find a point $x^* \in \arg \inf_{x \in K_{\Psi}} \Theta(x) =: \Gamma(\neq \emptyset)$ ,	
where $\Theta:\mathcal{H} ightarrow\mathbb{R}$ is the 2nd convex function.	

# Suppose that $\Psi' : \mathcal{H} \to \mathcal{H}$ (G-derivative) is $\gamma$ -Lipschitzian. $\downarrow \downarrow$ Apply Hybrid Steepest Descent Method $u_{n+1} := T(u_n) - \lambda_{n+1} \Theta'(T(u_n)),$ $[T := P_K(I - \nu \Psi'), \quad \forall \nu \in (0, 2/\gamma]]$ Solves the Problem, i.e., $\lim_{n \to \infty} d(u_n, \Gamma) = 0.$

NOTE: Projected Landweber Iteration (Eicke 1992):

$$v_{n+1} := P_K \left( \lambda_{n+1} A^* \boldsymbol{b} + \beta_n (I - \lambda_{n+1} A^* A) v_n \right)$$

is the simplest realization for  $\Theta(x) := \frac{1}{2} ||x||^2$  and  $\Psi(x) := \frac{1}{2} ||A(x) - b||_o^2$  ( $A : \mathcal{H} \to \mathcal{H}_o$ : bdd linear).

### Part 3

### **Hybrid Steepest Descent Method**

From Nonexpansive Mapping to Quasi-Nonexpansive Mapping

#### **Quasi-Nonexpansive Mapping**

 $T: \mathcal{H} \to \mathcal{H}$  is called *Quasi-Nonexpansive* if

$$||T(x) - T(f)|| \leq ||x - f||, \ \forall (x, f) \in \mathcal{H} \times Fix(T).$$

In this case,

$$Fix(T) := \{x \in \mathcal{H} \mid T(x) = x\}$$

is closed convex set.

# Quasi-nonexpansive mapping T is not necessarily continuous.



### **Next Example shows**

The level set of continuous convex function can be expressed as Fixed Point Set of Simple Quasi-Nonexpansive Mapping.

**Example** (Subgradient Projection  $T_{sp(\Phi)}$ ) Subgradient Projection for Cont. convex function  $\Phi$  $T_{sp(\Phi)}: x \mapsto \begin{cases} x - \frac{\Phi(x)}{\|g(x)\|^2}g(x) & \text{if } \Phi(x) > 0\\ x & \text{if } \Phi(x) \le 0, \end{cases}$ where  $g(x) \in \partial \Phi(x)$  : subgradient of  $\Phi$  at  $x \in \mathcal{H}$ . See for example (Bauschke & Combettes '01) -•  $T_{sp(\Phi)}$  :  $(\frac{1}{2}$ -averaged) quasi-nonexpansive, •  $Fix(T_{sp(\Phi)}) = \{x \in \mathcal{H} \mid \Phi(x) \le 0\} =: \text{lev}_{<0}\Phi$ 

#### Subgradient Projection : Approximation of Convex Projection



$$Fix\left(T_{sp(\Phi)}\right) = lev_{\leq 0}(\Phi)$$

# Is It Possible to Extend from

$$\begin{array}{l} \underline{u_{n+1}} \mathrel{\mathop:}= T(u_n) - \lambda_{n+1} \Theta'\left(T(u_n)\right) \\ \text{where } T \mathrel{\mathop:} \mathcal{H} \rightarrow \mathcal{H} \mathrel{\mathop:} \text{Nonexpansive} \\ \hline \mathbf{to} \\ \\ \underline{u_{n+1}} \mathrel{\mathop:}= T(u_n) - \lambda_{n+1} \Theta'\left(T(u_n)\right) \\ \text{where } T \mathrel{\mathop:} \mathcal{H} \rightarrow \mathcal{H} \mathrel{\mathop:} \mathbf{Quasi-Nonexpansive} \end{array}$$

## for Minimizing $\Theta$ over Fix(T)?

Quasi-shrinking (Yamada & Ogura '03) -Let  $T: \mathcal{H} \to \mathcal{H}$ : quasi-nonexpansive with  $Fix(T) \cap C \neq \emptyset$  for  $\exists C \subset \mathcal{H}$ : closed convex set.  $T: \mathcal{H} \to \mathcal{H}$  is called *quasi-shrinking* on C if  $D: r \in [0,\infty) \mapsto$  $\begin{cases} \inf_{u \in \triangleright(Fix(T),r) \cap C} d(u,Fix(T)) - d(T(u),Fix(T)) \\ \text{if } \triangleright(Fix(T),r) \cap C \neq \emptyset \\ \infty \qquad \text{otherwise} \end{cases}$ otherwise satisfies  $D(r) = 0 \Leftrightarrow r = 0$ .

where  $\triangleright(Fix(T),r) := \{x \in \mathcal{H} \mid d(x,Fix(T)) \geq r\}.$ 

#### Hybrid Steepest Descent Method (Quasi-Nonexpansive)

Suppose that (a) $T : \mathcal{H} \to \mathcal{H}$ : Quasi-Nonexpansive, (b) $\Theta'$ :  $\kappa$ -Lipschitzian&  $\eta$ -Strongly monotone over  $T(\mathcal{H})$ , (c) $\exists f \in Fix(T)$ , s.t. T is quasi-shrinking on

### Proposition Suppose $\Phi : \mathcal{H} \to \mathbb{R}$ (cont. convex function) satisfies • $\text{lev}_{<0}\Phi \neq \emptyset$ and • $\partial \Phi$ bounded. Define $T_{\alpha} := (1 - \alpha)I + \alpha T_{sp(\Phi)} \ (\alpha \in (0, 2)).$ Then (a) If dim( $\mathcal{H}$ ) $< \infty$ , $\Rightarrow$ $T_{\alpha}$ : quasi-shrinking on any bdd closed convex C satisfying $C \cap \text{lev}_{<0} \Phi \neq \emptyset$ . (b) If $\Phi' \in \partial \Phi$ : Uniformly monotone over $\mathcal{H}$ , $T_{\alpha}$ : quasi-shrinking on any bdd closed convex C satisfying $C \cap \text{lev}_{\leq 0} \Phi \neq \emptyset$ .

#### <u>Hybrid Steepest Descent Method</u> (for $T_{sp(\Phi)}$ )



**Hybrid Steepest Descent Method** (for  $T_{sp(\Phi)}$  over K)

Suppose that (a)  $\Phi : \mathcal{H} \to \mathbb{R}$ : **Cont. Convex** with  $\partial \Phi$ : **bdd**, (b) K: **bdd** closed convex set s.t.  $lev_{<0}\Phi \cap K \neq \emptyset$ , (c) $\Theta'$ : Lipschitzian& Paramonotone over K, When dim $(\mathcal{H}) < \infty$ With  $(\lambda_n)_{n\geq 1} \subset [0,\infty)$  s.t. (i)  $\lim_{n\to\infty} \lambda_n = 0$ , (ii)  $\sum \lambda_n = \infty$ ,  $u_{n+1} := P_K T_\alpha(u_n) - \lambda_{n+1} \Theta'(P_K T_\alpha(u_n))$ satisfies  $\lim_{n\to\infty} d(u_n, \Gamma) = 0,$ where  $\Gamma := \arg \inf_{K \cap \operatorname{lev}_{\leq 0} \Phi} \Theta(x) \neq \emptyset$ .

# For related results to this talk, See for example :

#### Hybrid Steepest Descent Method and Its Applications

- I. Yamada: "The hybrid steepest descent method for the variational inequality problem over the intersection of fixed point sets of nonexpansive mappings," pp.473–504, in <u>Inherently Parallel Algorithm for Feasibility and</u> <u>Optimization and Their Applications</u>, Elsevier 2001.
- I. Yamada, N. Ogura and N. Shirakawa: "A numerically robust hybrid steepest descent method for the convexly constrained generalized inverse problems," pp.269-305, in Inverse Problems, Image Analysis, and Medical Imaging, <u>Contemporary Mathematics</u>, 313, Amer. Math. Soc., 2002.

- K. Slavakis, I. Yamada and K. Sakaniwa: "Computation of symmetric positive definite Toeplitz matrices by the Hybrid Steepest Descent Method," *Signal Processing*, vol.83, pp.1135–1140, 2003.
- H.K. Xu and T.H. Kim: "Convergence of hybrid steepest descent methods for variational inequalities," <u>Journal of Optimization Theory and Applications</u>, vol. 119, no. 1, pp.185–201, 2003.
- 5. I. Yamada and N. Ogura: "Two Generalizations of the Projected Gradient Method for Convexly Constrained Inverse Problems — Hybrid steepest descent method, Adaptive projected subgradient method," *Proceedings of NANIT'03*, RIMS, Kyoto, Dec., 2003.

# Thank you very much !!

### What is Subgradient ?

Subgradient of  $\Phi$  at xLet  $\Phi : \mathcal{H} \to \mathbb{R}$  : Cont. Convex Function. $\psi$  $\partial \Phi(x) := \{s \in \mathcal{H} : \langle y - x, s \rangle + \Phi(x) \leq \Phi(y), \forall y \in \mathcal{H} \}$  $\neq \emptyset$ . $\forall s \in \partial \Theta(x)$  is called Subgradient of  $\Phi$  at x.

- $0 \in \partial \Phi(x) \Leftrightarrow \Phi(x) = \min_{y \in \mathcal{H}} \Phi(y).$
- $\partial \Phi(x) = \{ \nabla \Phi(x) \}$  if  $\Phi$ :G-differentiable at x.
- $\Rightarrow$  generalization of Gradient.

#### Subgradient: a generalization of Gradient

