Hydraulics of free overfall in Δ -shaped channels

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Abstract. In this paper, two methods are presented to analyse the free overfall in Δ -shaped (equilateral triangle-shaped) channels. First, the flow upstream of a free overfall from smooth horizontal or mildly sloping Δ -shaped channels is analysed theoretically to determine the end-depth-ratio (EDR), applying the momentum equation based on the Boussinesq approximation. Second, an alternate method for analysing free overfall in Δ -shaped channels is also presented where the flow over a free overfall in Δ -shaped channel is simulated by that over a sharp-crested weir to calculate the EDR. The method of estimation of discharge from the known end depth is also presented for both the methods. These approaches eliminate the need of an experimentally determined pressure coefficient. Experiments are conducted to verify the results obtained from the present methods. Comparisons of the computed and experimental results are satisfactory.

Keywords. Brink depth; equilateral triangle shaped channels; end depth; free overfall; hydraulics; one-dimensional flow; open channel flow; steady flow.

1. Introduction

A free overfall is a situation in which the flow finds a sudden drop in the channel base, causing the flow to separate from the solid boundary to form a free nappe. A significant characteristic is that there is a strong departure from hydrostatic distribution of pressure caused by the strong accelerated downflow in the vicinity of the drop. In open channels, free overfall offers the possibility of being used as a measuring device of discharge. Pioneer experimental research was carried out by Rouse (1936) in mildly sloping rectangular channels to determine the end-depth-ratio (EDR = end depth / critical depth), which was found to be 0.715. Since then a large number of investigations on free overfall have been carried out on various channels (Fathy & Shaarawi 1954; Delleur *et al* 1956; Diskin 1961; Smith 1962; Rajaratnam & Muralidhar 1964, 1968, 1970; Clarke 1965; Markland 1965; Anderson 1967; Strelkoff & Moayeri 1970; Bauer & Graf 1971; Ali & Sykes 1972; Chow & Han 1979; Hager 1983, 1999; Keller & Fong 1989; Ferro 1992, 1999; Montes 1992; Marchi 1993; Gupta *et al* 1993; Murty Bhallamudi 1994; Anastasiadou-Partheniou & Hatzigiannakis 1995; Clausnitzer & Hager 1997; Davis *et al* 1998; Dey 1998 2000, 2001).

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Solutions of the potential flow theory to determine the hydraulic aspects of overfalls were given by Markland (1965), Clarke (1965), Strelkoff & Moayeri (1970), Chow & Han (1979), Matthew (1991) and Montes (1992). Jaeger (1948) solved the momentum and energy equations using the Boussinesg approximation to calculate the EDR in horizontal rectangular channels. Rajaratnam & Muralidhar (1964b) presented experimental and analytical work on the overfall from circular channels. Anderson (1967) analysed the modified energy equation based on the Boussinesq approximation to determine the EDR for the rectangular overfall. The free vortex theory was applied by Ali & Sykes (1972) for trapezoidal overfalls. Hager (1983) solved the momentum and extended energy equations to analyse the rectangular overfall considering the streamline inclination and curvature. An analytical approach, termed theory of a direct fluid sheet, was put forward by Naghdi & Rubin (1981) to develop an exact solution of the non-linear equations. Marchi (1993) solved the two-dimensional overfall with the aid of the cnoidal wave theory. Empirical equations of EDR for trapezoidal overfalls were proposed by Gupta et al (1993). Also, the end depths in trapezoidal and exponential channels were analytically determined by Murty Bhallamudi (1994) using the momentum approach based on the Boussinesq approximation. Anastasiadou-Partheniou & Hatzigiannakis (1995) and Ferro (1999) simulated the free overfall by that over a sharp-crested weir. Analytical solutions for circular overfall given by Dey (1998b, 2001a) were based on the momentum equation and the simulation of a free overfall by that over a sharp-crested weir respectively. Dey (2001) also, studied the free overfall in elliptical channels. ISO 3874 (1977) and ISO 4371 (1984) recommended the flow estimation by the end depth method in rectangular and non-rectangular channels, respectively. The effect of bottom roughness on rectangular overfalls was experimentally studied by Delleur et al (1956), Rajaratnam et al (1976) and Kraijenhoff & Dommerholt (1977), and its mathematical solution was given by Dey (1998a, 2000). However, no attempt has so far been made to analyse the free overfall in Δ -shaped channels, which is a possible shape of a sewer.

In this paper, two separate methods are presented to analyse the free overfall in Δ -shaped channels. First, an analytical model for a free overfall from smooth horizontally laid or mildly sloping Δ -shaped channels is presented, applying a momentum approach based on the Boussinesq assumption. Second, an alternate approach for a free overfall in Δ -shaped channels is also presented, where the flow over a fall in a Δ -shaped channel is simulated by that over a sharp-crested weir to calculate the EDR and discharge. Both the methods eliminate the need for an experimentally determined pressure coefficient. The methods yield the EDR and discharge, which are verified by the experimental data. The above analyses are given for a flow regime approaching subcriticality. A flow regime approaching supercriticality being not so common in practice is beyond the realm of this study.

2. Experimental set-up and procedure

Experiments were conducted in two different horizontally laid Δ -shaped channels (made of transparent perspex), having sides of 18 cm (channel 1) and 12 cm (channel 2). The lengths of the channels were 4 m. Each channel was connected to an upstream supply. Water discharged through the downstream end of the channel into a measuring tank and finally drained into the reservoir. A valve in the upstream supply line controlled the discharge. The discharge was set by slowly opening the upstream valve until the desired height at the end section of the

 Table 1. Experimental data.

Channel	b (cm)	$\begin{array}{c} Q\\ (\mathrm{cm}^3\mathrm{s}^{-1}) \end{array}$	\hat{h}_c	\hat{h}_e	${ ilde h}_e$	Q
1	18	17824.41	0.6671	0.4744	0.7112	0.5932
		16007.64	0.6262	0.4506	0.7195	0.5327
		14595.46	0.5916	0.4172	0.7053	0.4857
		13639.59	0.5667	0.3906	0.6892	0.4539
		11373.10	0.5031	0.3600	0.7155	0.378
		11374.87	0.5032	0.3428	0.6812	0.378
		9261.11	0.4381	0.3089	0.7051	0.3082
		8253.22	0.4049	0.2839	0.7011	0.274
		7306.86	0.3724	0.2544	0.6832	0.2432
		6546.58	0.3453	0.2417	0.6999	0.217
		5935.18	0.3227	0.2272	0.7041	0.197
		5673.51	0.3128	0.2144	0.6855	0.188
		5036.94	0.2882	0.1994	0.6921	0.167
		4239.29	0.2559	0.1789	0.6991	0.141
		3385.21	0.2192	0.1561	0.7122	0.112
		2917.41	0.1979	0.1378	0.6961	0.097
		2484.03	0.1773	0.1239	0.6988	0.082
		1850.22	0.1450	0.1017	0.7012	0.061
		1249.03	0.1110	0.0783	0.7057	0.041
		786.83	0.0812	0.0561	0.6911	0.0262
2	12	7738.46	0.7344	0.5083	0.6922	0.709
		6778.14	0.6849	0.4833	0.7057	0.621
		5905.46	0.6325	0.4350	0.6878	0.541
		5288.86	0.5910	0.4250	0.7191	0.485
		5266.99	0.5895	0.4083	0.6927	0.483
		5014.46	0.5714	0.3983	0.6971	0.459
		4612.18	0.5414	0.3800	0.7019	0.423
		4126.17	0.5031	0.3583	0.7123	0.378
		4138.76	0.5041	0.3433	0.6811	0.379
		3459.38	0.4468	0.3208	0.7181	0.317
		3394.18	0.4410	0.3008	0.6821	0.311
		2915.30	0.3975	0.2800	0.7044	0.267
		2638.02	0.3711	0.2658	0.7163	0.241
		2357.93	0.3435	0.2408	0.7011	0.216
		2141.94	0.3215	0.2225	0.6921	0.196
		1803.38	0.2855	0.2042	0.7151	0.165
		1564.69	0.2589	0.1767	0.6824	0.143
		1252.70	0.2222	0.1567	0.7052	0.114
		1029.22	0.1941	0.1342	0.6911	0.094
		792.74	0.1624	0.1125	0.6928	0.072

channel resulted. Once it was reached, the corresponding discharge was recorded with the aid of a measuring tank. The end depths were measured carefully by a point gauge. Table 1 presents the experimental data.

3. First model of the EDR

This model is based on the assumption of pseudo-uniform flow, where frictional resistance being very small is balanced by the streamwise gravity component of force (Dey 1998). Apply-

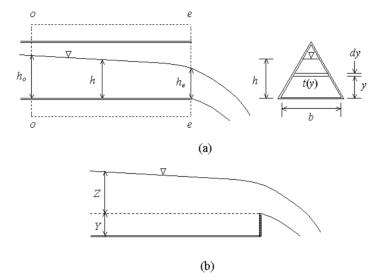


Figure 1. Definition sketch of (a) a free overfall in a Δ -shaped channel and (b) a weir flow.

ing the one-dimensional momentum equation between sections x = -L (far upstream of the end section) and x = -x for the flow situation under consideration (figure 1a), one obtains

$$f_o - f = \rho Q (\beta V - \beta_o V_o), \tag{1}$$

where f = total pressure force, $\rho = \text{mass density of fluid}$, Q = discharge, $\beta = \text{Boussinesq}$ coefficient, and V = mean flow velocity. Subscript 'o' refers to section x = -L. For simplicity, in this analysis, b is assumed to be unity. For a curvilinear flow with constant acceleration a_y normal to the direction of flow, the intensity of pressure p at y above the bottom is obtained from the integration of the Euler equation as

$$-\frac{\partial}{\partial y}(p + \rho g y) = \rho a_y,\tag{2}$$

where g = gravitational constant. According to the Boussinesq theory (Jaeger 1957), as the free surface curvature of a free overfall is relatively small and varies from a finite value at the surface to zero at the channel boundary, a linear variation of the streamline curvature with depth is assumed. Hence, the radius of curvature r of a streamline at y is written as

$$1/r \approx (y/h) (1/r_s), \tag{3}$$

where h = flow depth, and $r_s =$ radius of curvature of the free surface. As the free surface curvature is small, it can be approximated as

$$1/r_s \approx \mathrm{d}^2 h/\mathrm{d}x^2. \tag{4}$$

If the flow velocity at any depth equals the mean flow velocity V (which is a function of x), the vertical acceleration $a_v (= V^2/r)$ based on the above assumption is given by

$$a_y = ky, \tag{5}$$

where

$$k = (V^2/h) (d^2h/dx^2).$$
 (6)

The above assumption for the estimation of r_s was found to be adequate in many flow situations involving a small streamline curvature (Jaeger 1957). Using (5), (2) is integrated within *y* to *h* to obtain the expression for the pressure distribution as

$$p = \rho g(h - y) + o.5\rho k(h^2 - y^2).$$
⁽⁷⁾

The pressure force f at section x = -x is derived from

$$f = \int_0^h pt(y)dy,\tag{8}$$

where t(y) = width of the channel at y. It is expressed for a Δ -shaped channel of side b as

$$t(y) = b - (2/\sqrt{3})y.$$
 (9)

Thus, using (7) and (9) in (8), f is expressed as

$$f = \rho g z^{3} \frac{\hat{h}^{3}}{\sqrt{3}} \left[1 - \frac{\hat{h}}{3} \right] + \rho k z^{4} \frac{\hat{h}^{3}}{2\sqrt{3}} \left[\frac{4}{3} - \frac{\hat{h}}{2} \right], \tag{10}$$

where $\hat{h} = h/z$, and z = height of the channel, which is given by

$$z = (\sqrt{3}/2) \, b. \tag{11}$$

At the far upstream section (x = -L), k = 0 and \hat{h} is replaced by \hat{h}_o . Thus, the hydrostatic pressure force f_o obtained from (10) is

$$f_o = \rho g z^3 (\hat{h}^3 / \sqrt{3}) \left[1 - (\hat{h}_o / 3) \right], \tag{12}$$

where $\hat{h}_o = h_o/z$. The continuity equation between sections x = -L and x = -x is

$$Q = V_o A_o = V A, \tag{13}$$

where Q = discharge, and A = flow area. The flow area is expressed for a Δ -shaped channel as

$$A = (z^2/\sqrt{3})(2 - \hat{h})\hat{h}.$$
(14)

Using (10)–(14) and incorporating F_o into (1) with $\beta = \beta_o = 1$, yields

$$\hat{h}_{o}^{2}\left[1-\frac{\hat{h}_{o}}{3}\right]-\hat{h}^{2}\left[1-\frac{\hat{h}}{3}\right]-\frac{kz\hat{h}^{3}}{2g}\left[\frac{4}{3}-\frac{\hat{h}}{2}\right]$$
$$=\frac{F_{o}^{2}}{2}\cdot\frac{(2-\hat{h}_{o})^{3}\hat{h}_{o}^{3}}{1-\hat{h}_{o}}\left[\frac{1}{(2-\hat{h})\hat{h}}-\frac{1}{(2-\hat{h}_{o})\hat{h}_{o}}\right],$$
(15)

where

$$\mathbf{F}_o = \sqrt{6}\hat{Q}\{(1 - \hat{h}_o)^{1/2} / [(2 - \hat{h}_o)\hat{h}_o]^{1.5}\},\tag{16a}$$

$$\hat{Q} = Q/(g^{0.5}z^{2.5}). \tag{16b}$$

The EDR, which is the ratio of end depth (h_e) to critical depth (h_c) , is computed for a Δ -shaped channel using the preceding equations. According to Anderson (1967), the free surface profile is a continuous falling surface upstream and downstream of the end section. To be more explicit, the free surface of the flow passes through the brink and ends up as a parabolic trajectory of a gravity fall. Hence, the rate of change of slope of the free surface at the end section (x = 0), as was assumed by Anderson (1967), is

$$(d^2h/dx^2)_{x=0} = -g/V_e^2$$
(17)

where subscript *e* refers to the end section (x = 0). Using (17), k_e at the end section determined from (6) is

$$k_e = -g/h_e. \tag{18}$$

Applying (15) to the end section $(\hat{h} = \hat{h}_e)$ and substituting k_e from (18) in (15), a generalized equation for the EDR is derived as

$$\hat{h}_{o}^{2}\left[1-\frac{\hat{h}_{o}}{3}\right]-\hat{h}_{e}^{2}\left[1-\frac{\hat{h}_{e}}{3}\right]+\frac{\hat{h}_{e}^{2}}{2}\left[\frac{4}{3}-\frac{\hat{h}_{e}}{2}\right]$$
$$=\frac{F_{o}^{2}}{2}\cdot\frac{(2-\hat{h}_{o})^{3}\hat{h}_{o}^{3}}{1-\hat{h}_{o}}\left[\frac{1}{(2-\hat{h}_{e})\hat{h}_{e}}-\frac{1}{(2-\hat{h}_{o})\hat{h}_{o}}\right].$$
(19)

When the stream-wise slope of the channel is either horizontal or mild, the flow becomes critical $(h_o = h_e)$ upstream of the control section. Thus, the upstream Froude number F_o is unity. Introducing $F_o = 1$ and $\hat{h}_o = \hat{h}_c$ in (19), we get

$$\hat{h}_{c}^{2}\left[1-\frac{\hat{h}_{c}}{3}\right]-\hat{h}_{e}^{2}\left[1-\frac{\hat{h}_{e}}{3}\right]+\frac{\hat{h}_{e}^{2}}{2}\left[\frac{4}{3}-\frac{\hat{h}_{e}}{2}\right]$$
$$=\frac{1}{2}\cdot\frac{(2-\hat{h}_{c})^{3}\hat{h}_{c}^{3}}{1-\hat{h}_{c}}\left[\frac{1}{(2-\hat{h}_{e})\hat{h}_{e}}-\frac{1}{(2-\hat{h}_{c})\hat{h}_{c}}\right].$$
(20)

where c refers to a critical state of flow. Equation (20) is an implicit equation. Therefore, it is solved numerically, and the EDR \tilde{h}_e is calculated from the following non-dimensional equation:

$$\tilde{h}_e = h_e / h_c = \hat{h}_e / \hat{h}_c. \tag{21}$$

4. Second model of the EDR (alternate approach)

The flow over a free overfall in a Δ -shaped channel (figure 1b) can be assumed to be similar to the flow over a sharp-crested weir having same section with a crest Y = 0 and head above the

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crest $Z = h_o$ (Rouse 1936; Anastasiadou-Partheniou & Hatzigiannakis 1995; Ferro 1999). As is done to compute the discharge over a sharp-crested weir, a zero pressure distribution and parallel streamlines at the end section are assumed, neglecting the compaction of the nappe. The flow velocity at the end section is calculated by applying the Bernoulli equation on a streamline between the far upstream section at x = -L, where the pressure is hydrostatic, and the end section at x = 0. The discharge Q is computed using the following equation:

$$Q = C_d \sqrt{2g} \int_0^{h_o} t (H - y)^{1/2} \mathrm{d}y,$$
(22)

where $C_d = \text{coefficient}$ of discharge (= $C_v C_c$), $C_v = \text{coefficient}$ of velocity, $C_c = \text{coefficient}$ of contraction (= A_e/A_o), and H = total head. H at the far upstream section (x = -L) is given by

$$H = h_o + (V_o^2/2g).$$
(23)

Using (9) in(22), Q is expressed as

$$Q = 2\sqrt{2/3}C_v C_c z^{2.5} \sqrt{g} \int_0^{h_o} (1-\hat{y})(\hat{H}-\hat{y})^{1/2} d\hat{y},$$
(24)

where $\hat{y} = y/z$, and $\hat{H} = H/z$. The coefficient of contraction C_c can be expressed as

$$C_c = (2 - \hat{h}_e)\hat{h}_e / [(2 - \hat{h}_o)\hat{h}_o].$$
⁽²⁵⁾

Using (25) in (24) and normalizing, yields

$$\hat{Q} = 2\sqrt{2/3}C_v \frac{(2-\hat{h}_e)\hat{h}_e}{(2-\hat{h}_o)\hat{h}_o} \int_0^{\hat{h}_o} (1-\hat{y})(\hat{H}-\hat{y})^{1/2} \mathrm{d}\hat{y}.$$
(26)

Integrating (26) and using (16a), we can write

$$F_o \frac{3[\hat{h}_o(2-\hat{h}_o)]^{2.5}}{8C_v(1-\hat{h}_o)^{0.5}} = (2-\hat{h}_e)\hat{h}_e \left\{ (\hat{H}-\hat{h}_o)^{3/2} \left[\frac{1}{5} (2\hat{H}+3\hat{h}_o) - 1 \right] -\hat{H}^{3/2} \left(\frac{2}{5}\hat{H} - 1 \right) \right\}.$$
 (27)

Introducing Froude number in (23), \hat{H} can be given by

$$\hat{H} = \hat{h}_o + \frac{F_o^2}{4} \cdot \frac{(2 - \hat{h}_o)\hat{h}_o}{1 - \hat{h}_o}.$$
(28)

Introducing $F_o = 1$ and $\hat{h}_o = \hat{h}_c$ in (27) and (28), one gets

$$\frac{3[\hat{h}_c(2-\hat{h}_c)]^{2.5}}{8C_v(1-\hat{h}_c)^{0.5}} = (2-\hat{h}_e)\hat{h}_e\left\{(\hat{H}-\hat{h}_c)^{3/2}\left[\frac{1}{5}(2\hat{H}+3\hat{h}_c-1)\right] -\hat{H}^{3/2}\left(\frac{2}{5}\hat{H}-1\right)\right\}, \quad (29)$$

$$\hat{H} = \hat{h}_c + \frac{1}{4} \cdot \frac{(2 - \hat{h}_c)\hat{h}_c}{1 - \hat{h}_c}.$$
(30)

Equation (29) can be expressed as a quadratic equation. It is

$$\hat{h}_e^2 - 2\hat{h}_e + \lambda = 0, \tag{31}$$

where $\lambda = \xi_1/\xi_2$, and

$$\xi_1 = \frac{3[\hat{h}_c(2-\hat{h}_c)]^{2.5}}{8C_v(1-\hat{h}_c)^{0.5}}$$
(32a)

$$\xi_2 = (\hat{H} - \hat{h}_c)^{3/2} \left[\frac{1}{5} (2\hat{H} + 3\hat{h}_c) - 1 \right] - \hat{H}^{3/2} \left(\frac{2}{3}\hat{H} - 1 \right)$$
(32b)

The feasible solution of (31) is

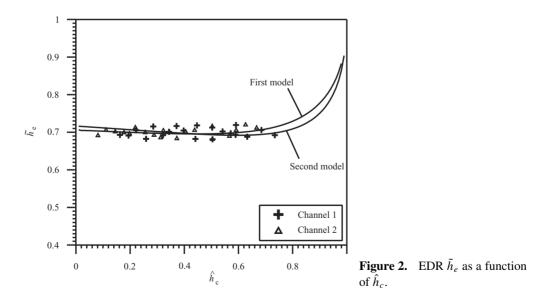
$$\hat{h}_e = 1 - (1 - \lambda)^{1/2}.$$
(33)

For a given \hat{h}_c , \hat{H} is computed from (30). Then, \hat{h}_e is solved from (33), and finally, EDR \tilde{h}_e is estimated from (21). As value of C_v for flow over free overfalls is not available as yet, (33) is required to be calibrated extensively. The experimental data were used to calibrate (33), making C_v a free parameter. For this purpose, the experimental data of \hat{h}_c and \hat{h}_e were used as source data. As the variation of estimated C_v is small, the mean value of C_v obtained as 0.998 was used here.

5. The discharge

The concept of free overfall from Δ -shaped channels is utilized to estimate the discharge using a known end depth. The equation of discharge obtained from continuity equation is

$$Q = A_o V_o. (34)$$



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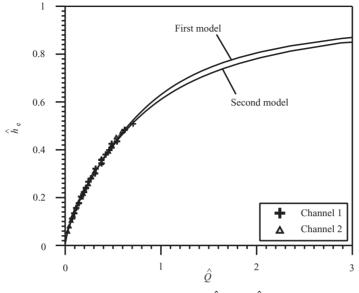


Figure 3. Variation of \hat{h}_e with \hat{Q} .

Introducing $F_o = 1$ and $\hat{h}_o = \hat{h}_c$ in (34), one gets

$$\hat{Q} = \frac{1}{\sqrt{6}} \cdot \frac{\left[(2 - \hat{h}_c)\hat{h}_c\right]^{1.5}}{(1 - \hat{h}_c)^{0.5}}.$$
(35)

The results of both EDR models can be used to evaluate non-dimensional discharge \hat{Q} from (35).

6. Results

The dependence of \tilde{h}_e on \tilde{c} is shown in figure 2. The curve obtained from the first model lies almost at the mid zone of the experimental data in the range of $0.111 \le \hat{h}_c \le .0.734$. For the present case, the EDR \tilde{h}_e has a value of around 0.695 up to $\hat{h}_c = 0.70$. The curve rises sharply from $\hat{h}_c = 0.80$. The curve obtained from this model corresponds closely to the experimental data with an accuracy of $\pm 5\%$. Using $C_v = 0.998$, the dependency of \tilde{h}_e on \tilde{h}_c obtained from the second model is also shown in figure 2. The EDR \tilde{h}_e varies almost linearly from 0.715 to 0.685 up to $\hat{h}_c = 0.70$. The curve obtained from the second model has an agreement with the experimental data and the first model. Non-dimensional discharge \hat{Q} is calculated using (35) for both the models. The variations of \hat{h}_e with \hat{Q} for both the models are presented in figure 3. The experimental observations are agreeable with the curves obtained from the present models with an accuracy of $\pm 5\%$. Figure 3 can be used to estimate the discharge from measured end-depth.

7. Conclusions

First, the free overfall in horizontal or mildly sloping Δ -shaped channels has been analysed applying the momentum equation based on the Boussinesq approximation. In sub-critical

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approaching flows, the EDR has been related to the critical depth and has been found to be around 0.695. The mathematical solutions have allowed estimation of discharge from the known end depth. Second, a simplified approach for computation of the end depth for a free overfall in Δ -shaped channels has been presented. The flow over a fall in a Δ -shaped channel has been simulated by that over a sharp-crested weir to calculate the end-depth ratio. The enddepth ratio is varying almost linearly from 0.715 to 0.685 for a critical depth-channel height ratio up to 0.70. The method of estimation of discharge from the known end depth has also been presented. Both the models have corresponded satisfactorily to the experimental data.

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