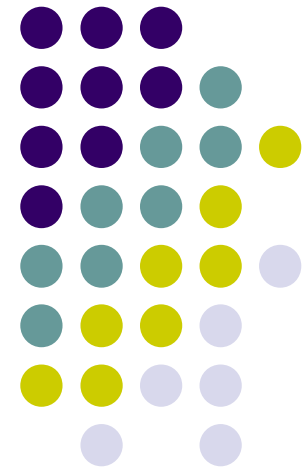


Implementation of Ant Colony Optimization Algorithm For Mobile Ad Hoc Network Applications: OpenMP Experiences

Mohammad Towhidul Islam
Parimala Thulasiraman
Ruppa K. Thulasiram

Presented by James Freckleton





Presentation Outline

- Optimisation problem to solve:
Routing in mobile ad hoc networks
- Ant colony optimisation
- An ant-based solution:
The source update algorithm
- OpenMP implementation of the algorithm



Mobile Ad Hoc Networks

- These networks consist of a group of mobile wireless nodes
- Nodes communicate in a distributed way
- Nodes dynamically form a network on the fly
- Each node operates as both host and router
- Nodes operate on low power batteries, which limits range
- Out-of-range nodes are reached through intermediate nodes (or hops)



Mobile Ad Hoc Networks

- Used when the geographical nature of the system is unknown
- Also used in situations where communication must be entirely distributed
- Applications include:
 - Health
 - Military
 - One Laptop Per Child organisation
 - VANet (Vehicular ad hoc networks)

Ant Colony Optimisation



- Used for “hard” problems that can be reduced to finding optimal paths through graphs
- Stigmergy: Ants communicate by modifying their local environment (laying pheromone)
- Positive feedback: The higher the pheromone content on a path, the greater probability it is a good solution
- Ants act like mobile nodes in MANets: they both create paths dynamically



Ant Colony Optimisation

- This is an inherently parallelisable metaheuristic, and so is appropriate to tackle routing in MANets
- This approach has been used to “solve” previously intractable instances of:
 - Graph colouring problem
 - Travelling salesman problem
 - Quadratic assignment problem
 - Vehicle routing problem

Previous Approaches To Implementing MANets



- Multipoint relays
 - These are selected nodes which forward broadcast messages during the flooding process
- Hybrid routing
 - Reactive: discovers paths only when required
 - Pro-active: active paths rebuilt from scratch every 3 seconds
- Route request messages
 - Contains source, destination, and lifespan data

Ant Colony Optimisation Algorithm for MANets



- MANet is a graph, $\mathbf{G} = (\mathbf{V}, \mathbf{E})$; the problem is to find the best path between source node \mathbf{S} and destination node \mathbf{D}
- Each edge $\mathbf{e}(\mathbf{v}_i, \mathbf{v}_j)$ has an amount of pheromone $\boldsymbol{\varphi}(\mathbf{v}_i, \mathbf{v}_j)$ and the connection “time”, $\mathbf{w}(\mathbf{v}_i, \mathbf{v}_j)$
- Each ant maintains a **VisitedHop** array, an elapsed exploration time **TotalTime**, and a **Stack** containing all nodes that may give a promising path to \mathbf{D}
- Each node \mathbf{i} has a routing table of size $\mathbf{N} * \mathbf{d}_i$, where \mathbf{N} is the number of nodes and \mathbf{d}_i is the degree of \mathbf{i}
- The algorithm is run on all possible **S-D** pairs

The Source Update Algorithm Over A Single S-D Pair



TotalTime \leftarrow 0

Stack \leftarrow (S, TotalTime)

VisitedHop[S] \leftarrow 1

Current \leftarrow S

While (Current \neq D)

 NextHop \leftarrow (empty)

 if (exists(unvisited adjacent node))

 NextHop \leftarrow (unvisited adjacent node)

 else

 NextHop \leftarrow unvisited(max{ ϕ (current, adjacent nodes)})

 if (NextHop = (empty))

 Pop Stack

 (Current, TotalTime) \leftarrow Stack

 else

 MoveTo(NextHop)



MoveTo(NextHop)

PreHop \leftarrow Current

Current \leftarrow NextHop

TotalTime \leftarrow TotalTime + W(PreHop,Current)

/ Update pheromone concentration for path from S to the current node */*

/ ϵ is a user-supplied parameter */*

$\varphi(\text{PreHop},S) \leftarrow \varphi(\text{PreHop},S) + \epsilon / (T(S,\text{PreHop}) + w(\text{PreHop},\text{Current}))$

/ Evaporate pheromone on other paths by a given quantity, E */*

$\varphi(v_a,S) \leftarrow (1-E)\varphi(v_a,S)$, for every adjacent v_a

Stack \leftarrow (Current, TotalTime)

VisitedHop[Current] \leftarrow 1

The Source Update Algorithm Over A Single S-D Pair



/* Launch backward ant after forward path from S to D has been completed */

While (Current \neq S)

PreHop \leftarrow Current

(Current, TotalTime) \leftarrow Stack

$T' = T(S, D) - \text{TotalTime}$

/* Update the pheromone quantity of the active link */

$\varphi(\text{Current}, D) \leftarrow \varphi(\text{Current}, D) + \varepsilon / T'$

/* Update the routing table for the Current node (not shown here) */

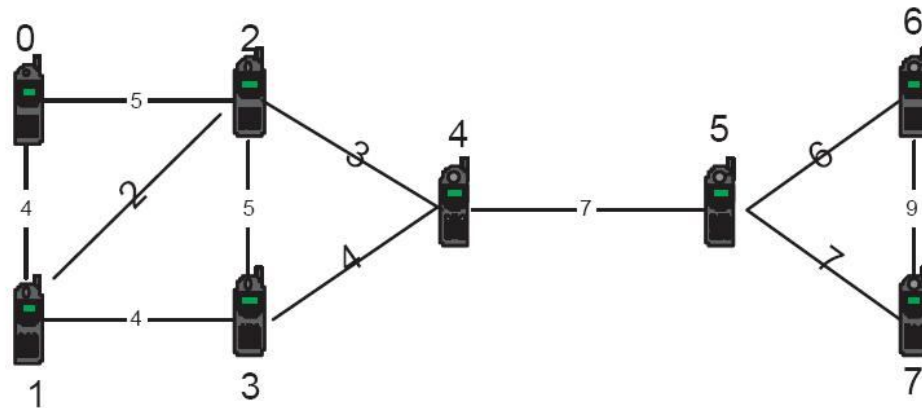
Stack \leftarrow (Current, TotalTime)

VisitedHop[Current] = 1

An Example Illustrating the Source Update Algorithm



- Consider the following network:



- Assume the ant is moving from source $S = 3$ to destination $D = 6$, and assume the ant has selected the next link as $NextHop = 4$
- As a result, the current node $Current$ is set to 4
- At this point, node 4's routing table is updated by the ant

An Example Illustrating the Source Update Algorithm



- Next hop node isn't chosen by looking at the individual links from *Current* to its neighbour
- Instead, we look at the best path that will reach a destination from a particular node
- Since all nodes have been visited by previous ants, this ant looks at pheromone concentration and picks $NextHop = 5$
- This is reflected in the updated routing tables

An Example Illustrating the Source Update Algorithm



Before the source update:

Network Node	0		1		2		3		4		5		6		7		Total	
2	1	1	97.6	8	111.7	5	38.7	5	0	0	0	1	0	2	0	1	249	23
3	42	7	1	1	11.7	4	32.8	4	0	0	0	0	0	1	0	1	87.5	18
5	0	0	0	1	0	0	0	1	0	0	140	10	67	10	64	10	271	34

After the source update:

Network Node	0		1		2		3		4		5		6		7		Total	
2	1	1	97.6	8	111.7	5	27.1	5	0	0	0	1	0	2	0	1	237.4	23
3	42	7	1	1	11.7	4	57.8	5	0	0	0	0	0	1	0	1	112.5	19
5	0	0	0	1	0	0	0	1	0	0	140	10	67	11	64	10	271	34



OpenMP Implementation

- The above algorithm was designed to be implemented on parallel processors
- OpenMP is a language supporting such parallelisation (along with multithreading)
- Tests were run on an 8-node 7.5GB shared memory architecture running Linux RedHat 7.1
- Each node contained an Intel Xeon processor, clocked at 700 MHz
- All networks were generated by the NETGEN random graph generator



Results

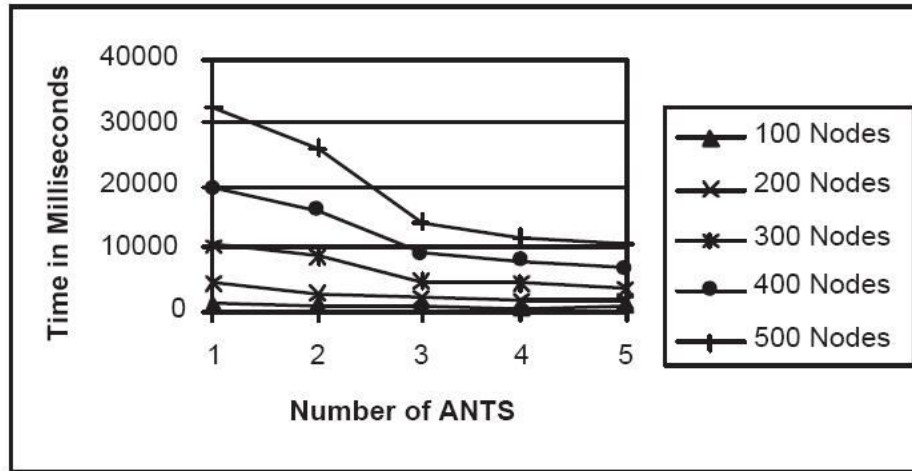


Figure 1: The performance of the algorithm is dependent on the number of nodes and ants

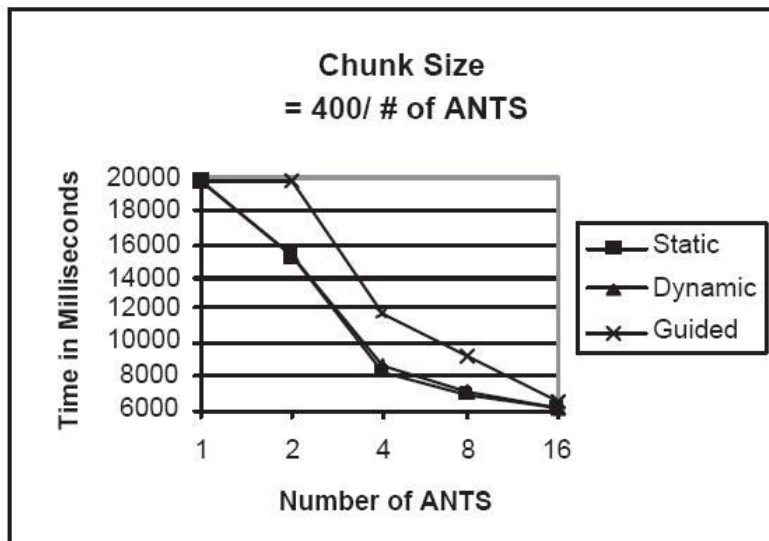


Figure 2: The performance of the algorithm when taking into account various scheduling methods



Evaluation

- The analysis and simulations of the protocol on shared memory architectures were strong
- However, no realistic simulations among MANets were undertaken, and so bandwidth constraints may affect results
- The paper itself presents a thorough overview; it is rarely vague on details (such as “best path”)

Summary



- Topology of Mobile ad hoc networks is chaotic
- Ant Colony Optimisation is an inherently parallelisable search technique
- It has similar properties to MANets
- A new ACO-based algorithm finds optimal routes
- OpenMP was used to implement this algorithm
- This implementation compares favourably with others such as MPI