# ESTIMATION OF FINITE POPULATION VARIANCE USING AUXILIARY INFORMATION IN SAMPLE SURVEYS 

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## 1. INTRODUCTION

The problem of estimating the finite population mean in the presence of an auxiliary variable has been widely discussed in the finite population sampling literature. However in practice, the problem of estimation of population variance also assumes importance. Like finite population mean estimators, few authors including (Das and Tripathi 1978); (Isaki, 1983); (Srivastava and Jhajj, 1980); (Biradar and Singh, 1988); (Singh et al.,1988, 2003); (Cebrian and Garcia ,1997); (Kadilar and Cingi, 2007); ( Grover, 2007); (Shabbir and Gupta, 2007); (Singh and Vishwakarma, 2008); ( Singh and Solanki, 2009, 2010, 2013a, 2013b,); (Solanki and Singh, 2013) and others have paid their attention towards the estimation of population variance in the presence of auxiliary information.

Consider the finite population $U:\left\{U_{1}, U_{2}, \ldots, U_{N}\right\}$ consisting of $N$ units. Let $Y$ and $X$ denote the study variable and auxiliary variable taking values $y_{i}$ and $x_{i}$ respectively on the $i^{\text {th }}$ unit $U_{i}$ of the population $U$. The problem is to estimate the population variance $S_{y}^{2}$ of the study variable $Y$ using information on the population variance $S_{x}^{2}$ of the auxiliary variable $X$ which is highly correlated with the study variable $Y$. Let a sample of size $n$ be drawn by simple random sampling without replacement (SRSWOR) from the population $U$. It is assumed that the population size $N$ is large as compared to $n$ so that finite population correction term is ignored.

The usual unbiased estimator of the population variance of the study variable $Y$ is defined by

$$
\begin{equation*}
t_{0}=s_{y}^{2}=(n-1)^{-1} \sum_{i=1}^{n}\left(y_{i}-\bar{y}\right)^{2} \tag{1.1}
\end{equation*}
$$

where $\bar{y}=n^{-1} \sum_{i=1}^{n} y_{i}$ is the sample mean of study variable $Y$.
Using information on the population variance $S_{x}^{2}$ of the auxiliary variable $X$, Isaki (1983) suggested a ratio-type estimator of as

$$
\begin{equation*}
t_{1}=s_{y}^{2}\left(S_{x}^{2} / s_{x}^{2}\right) \tag{1.2}
\end{equation*}
$$

where is an unbiased estimator of the population variance with and $\bar{X}=N^{-1} \sum_{i=1}^{N} x_{i}$.
Motivated by Bahl and Tuteja (1991), Singh et al. (2009) suggested a ratio-type exponential estimator of the population variance as

$$
\begin{equation*}
t_{2}=s_{y}^{2} \exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right) \tag{1.3}
\end{equation*}
$$

It is very well known that the mean squared error (MSE) or variance (Var) of the usual unbiased estimator $s_{y}^{2}$ under SRSWOR is approximately, for large n ,

$$
\begin{equation*}
\operatorname{MSE}\left(s_{y}^{2}\right)=\operatorname{Var}\left(s_{y}^{2}\right)=n^{-1} S_{y}^{4}\left(\delta_{40}-1\right) \tag{1.4}
\end{equation*}
$$

where $\quad \delta_{p q}=\left(\mu_{p q} / \mu_{20}^{p / 2} \mu_{02}^{q / 2}\right), \quad \mu_{p q}=N^{-1} \sum_{i=1}^{N}\left(y_{i}-\bar{Y}\right)^{p}\left(x_{i}-\bar{X}\right)^{q} \quad(p, q$ being nonnegative integers) and $\bar{Y}=N^{-1} \sum_{i=1}^{N} y_{i}$.

To the first degree of approximation the biases and mean squared errors (MSEs) of $t_{1}$ and $t_{2}$ are respectively given by

$$
\begin{gather*}
\operatorname{Bias}\left(t_{1}\right)=n^{-1} S_{y}^{2}\left(\delta_{04}-1\right)(1-c)  \tag{1.5}\\
\operatorname{Bias}\left(t_{2}\right)=\frac{S_{y}^{2}}{8 n}\left(\delta_{04}-1\right)(3-4 c)  \tag{1.6}\\
\operatorname{MSE}\left(t_{1}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+\left(\delta_{04}-1\right)(1-2 c)\right]  \tag{1.7}\\
\operatorname{MSE}\left(t_{2}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+(1 / 4)\left(\delta_{04}-1\right)(1-4 c)\right] \tag{1.8}
\end{gather*}
$$

where $c=\left[\left(\delta_{22}-1\right) /\left(\delta_{04}-1\right)\right]$.
In this paper motivated by Singh and Vishwakarma (2009), we have proposed some estimators of population variance of the study variable $Y$ based on arithmetic mean, geometric mean and harmonic mean of the estimators $\left(t_{0}, t_{1}\right),\left(t_{0}, t_{2}\right),\left(t_{1}, t_{2}\right)$ and $\left(t_{0}, t_{1}, t_{2}\right)$. Properties of the suggested estimators are studied under large sample approximation. An empirical study is carried out in support of the present study.

## 2. SUGGESTED Estimators

In this section we have suggested some estimators of population variance based on usual unbiased estimator, usual ratio estimators and estimator due to Singh et al. (2009). The properties of suggested estimators have been obtained up to first degree of approximation
2.1 The estimators based on $t_{0}$ and $t_{1}$

Taking the arithmetic mean $(A M)$, geometric mean $(G M)$ and harmonic mean $(H M)$ of the estimators $t_{0}$ and $t_{1}$ we get the following estimator of the population variance respectively as

$$
\begin{gather*}
t_{3}^{(A M)}=\frac{1}{2}\left(t_{0}+t_{1}\right)=\left(\frac{s_{y}^{2}}{2}\right)\left(1+\frac{S_{x}^{2}}{s_{x}^{2}}\right)  \tag{2.1}\\
t_{3}^{(G M)}=\left(t_{0} t_{1}\right)^{1 / 2}=s_{y}^{2}\left(S_{x} / s_{x}\right)  \tag{2.2}\\
t_{3}^{(H M)}=\frac{2}{\left(\frac{1}{t_{0}}+\frac{1}{t_{1}}\right)}=\frac{2 s_{y}^{2}}{\left(1+\frac{s_{x}^{2}}{S_{x}^{2}}\right)} \tag{2.3}
\end{gather*}
$$

To the first degree of approximation, the biases and mean squared errors of $t_{3}^{(A M)}, t_{3}^{(G M)}$ and $t_{3}^{(H M)}$ are respectively given by

$$
\begin{gather*}
\operatorname{Bias}\left(t_{3}^{(A M)}\right)=\left(S_{y}^{2} / 2 n\right)\left(\delta_{04}-1\right)(1-c)  \tag{2.4}\\
\operatorname{Bias}\left(t_{3}^{(G M)}\right)=\left(S_{y}^{2} / 8 n\right)\left(\delta_{04}-1\right)(3-4 c)  \tag{2.5}\\
\operatorname{Bias}\left(t_{3}^{(H M)}\right)=\left(S_{y}^{2} / 4 n\right)\left(\delta_{04}-1\right)(1-2 c)  \tag{2.6}\\
\operatorname{MSE}\left(t_{3}^{(A M)}\right)=\operatorname{MSE}\left(t_{3}^{(G M)}\right)=\operatorname{MSE}\left(t_{3}^{(H M)}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+\frac{\left(\delta_{04}-1\right)}{4}(1-4 c)\right] \tag{2.7}
\end{gather*}
$$

### 2.2 The estimators based on $t_{0}$ and $t_{2}$

The estimators of $S_{y}^{2}$ based on $A M, G M$ and $H M$ of the estimators $t_{0}$ and $t_{2}$ are respectively defined as

$$
\begin{equation*}
t_{4}^{(A M)}=\frac{1}{2}\left(t_{0}+t_{2}\right)=\left(\frac{s_{y}^{2}}{2}\right)\left(1+\exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right) \tag{2.8}
\end{equation*}
$$

$$
\begin{align*}
& t_{4}^{(G M)}=\left(t_{0} t_{2}\right)^{1 / 2}=s_{y}^{2} \exp \left(\frac{1}{2}\left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right)  \tag{2.9}\\
& t_{4}^{(H M)}=\frac{2}{\left(\frac{1}{t_{0}}+\frac{1}{t_{2}}\right)}=\frac{2 s_{y}^{2}}{\left\{1+\exp \left(\frac{s_{x}^{2}-S_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right\}} \tag{2.10}
\end{align*}
$$

To the first degree of approximation, the biases and MSEs of $t_{4}^{(A M)}, t_{4}^{(G M)}$ and $t_{4}^{(H M)}$ are respectively given by

$$
\begin{gather*}
\operatorname{Bias}\left(t_{4}^{(A M)}\right)=\left(S_{y}^{2} / 16 n\right)\left(\delta_{04}-1\right)(3-4 c)  \tag{2.11}\\
\operatorname{Bias}\left(t_{4}^{(G M)}\right)=\left(S_{y}^{2} / 32 n\right)\left(\delta_{04}-1\right)(5-8 c)  \tag{2.12}\\
\operatorname{Bias}\left(t_{4}^{(H M)}\right)=\left(S_{y}^{2} / 8 n\right)\left(\delta_{04}-1\right)(1-2 c)  \tag{2.13}\\
\operatorname{MSE}\left(t_{4}^{(A M)}\right)=\operatorname{MSE}\left(t_{4}^{(G M)}\right)=\operatorname{MSE}\left(t_{4}^{(H M)}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+\frac{\left(\delta_{04}-1\right)}{16}(1-8 c)\right] \tag{2.14}
\end{gather*}
$$

### 2.3 The estimators based on $t_{1}$ and $t_{2}$

We propose the following estimators of $S_{y}^{2}$ based on $A M, G M$ and $H M$ of the estimators respectively $t_{1}$ and $t_{2}$ as

$$
\begin{gather*}
t_{5}^{(A M)}=\frac{1}{2}\left(t_{1}+t_{2}\right)=\left(\frac{s_{y}^{2}}{2}\right)\left(\frac{S_{x}^{2}}{s_{x}^{2}}+\exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right)  \tag{2.15}\\
t_{5}^{(G M)}=\left(t_{1} t_{2}\right)^{1 / 2}=s_{y}^{2}\left(\frac{S_{x}}{s_{x}}\right) \exp \left(\frac{1}{2}\left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right) \tag{2.16}
\end{gather*}
$$

$$
\begin{equation*}
t_{5}^{(H M)}=\frac{2}{\left(\frac{1}{t_{1}}+\frac{1}{t_{2}}\right)}=\frac{2 s_{y}^{2}}{\left\{\frac{s_{x}^{2}}{S_{x}^{2}}+\exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right\}} \tag{2.17}
\end{equation*}
$$

To the first degree of approximation, the biases and MSEs of $t_{5}^{(A M)}, t_{5}^{(G M)}$ and $t_{5}^{(H M)}$ are respectively given by

$$
\begin{gather*}
\operatorname{Bias}\left(t_{5}^{(A M)}\right)=\left(S_{y}^{2} / 16 n\right)\left(\delta_{04}-1\right)(11-12 c)  \tag{2.18}\\
\operatorname{Bias}\left(t_{5}^{(G M)}\right)=\left(3 S_{y}^{2} / 32 n\right)\left(\delta_{04}-1\right)(7-8 c)  \tag{2.19}\\
\operatorname{Bias}\left(t_{5}^{(H M)}\right)=\left(S_{y}^{2} / 8 n\right)\left(\delta_{04}-1\right)(5-6 c)  \tag{2.20}\\
\operatorname{MSE}\left(t_{5}^{(A M)}\right)=\operatorname{MSE}\left(t_{5}^{(G M)}\right)=\operatorname{MSE}\left(t_{5}^{(H M)}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+\frac{3\left(\delta_{04}-1\right)}{16}(3-8 c)\right] \tag{2.21}
\end{gather*}
$$

2.4 The estimators based on $t_{0}, t_{1}$ and $t_{2}$

We define the following estimators of $S_{y}^{2}$ based on $A M, G M$ and $H M$ of the estimators $t_{0}, t_{1}$ and $t_{2}$ respectively as

$$
\begin{gather*}
t_{6}^{(A M)}=\frac{1}{2}\left(t_{0}+t_{1}+t_{2}\right)=\left(\frac{s_{y}^{2}}{3}\right)\left(1+\frac{S_{x}^{2}}{s_{x}^{2}}+\exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right)  \tag{2.22}\\
t_{6}^{(G M)}=\left(t_{0} t_{1} t_{2}\right)^{1 / 2}=s_{y}^{2}\left(\frac{S_{x}}{s_{x}}\right)^{2 / 3} \exp \left(\frac{1}{3}\left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right)  \tag{2.23}\\
t_{6}^{(H M)}=\frac{3}{\left(\frac{1}{t_{0}}+\frac{1}{t_{1}}+\frac{1}{t_{2}}\right)}=\frac{3 s_{y}^{2}}{\left\{1+\frac{s_{x}^{2}}{S_{x}^{2}}+\exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right\}} \tag{2.24}
\end{gather*}
$$

To the first degree of approximation, the biases and MSEs of $t_{6}^{(A M)}, t_{6}^{(G M)}$ and $t_{6}^{(H M)}$ are respectively given by

$$
\begin{gather*}
\operatorname{Bias}\left(t_{6}^{(A M)}\right)=\left(S_{y}^{2} / 24 n\right)\left(\delta_{04}-1\right)(11-12 c)  \tag{2.25}\\
\operatorname{Bias}\left(t_{6}^{(G M)}\right)=\left(S_{y}^{2} / 8 n\right)\left(\delta_{04}-1\right)(3-4 c)  \tag{2.26}\\
\operatorname{Bias}\left(t_{6}^{(H M)}\right)=\left(S_{y}^{2} / 24 n\right)\left(\delta_{04}-1\right)(7-12 c)  \tag{2.27}\\
\operatorname{MSE}\left(t_{6}^{(A M)}\right)=\operatorname{MSE}\left(t_{6}^{(G M)}\right)=\operatorname{MSE}\left(t_{6}^{(H M)}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+\frac{\left(\delta_{04}-1\right)}{4}(1-4 c)\right] \tag{2.28}
\end{gather*}
$$

## 3. Efficiency comparisons

From (1.4), (1.7), (1.8), (2.7), (2.14), (2.21) and (2.28), we have

$$
\begin{gather*}
\operatorname{MSE}\left(t_{1}\right)-\operatorname{MSE}\left(s_{y}^{2}\right)=\left(S_{y}^{4} / n\right)\left(\delta_{04}-1\right)(1-2 c)  \tag{3.1}\\
\operatorname{MSE}\left(t_{2}\right)-\operatorname{MSE}\left(s_{y}^{2}\right)=\left(S_{y}^{4} / 4 n\right)\left(\delta_{04}-1\right)(1-4 c)  \tag{3.2}\\
\operatorname{MSE}\left(t_{3}^{(j)}\right)-\operatorname{MSE}\left(s_{y}^{2}\right)=\left(S_{y}^{4} / 4 n\right)\left(\delta_{04}-1\right)(1-4 c)  \tag{3.3}\\
\operatorname{MSE}\left(t_{4}^{(j)}\right)-\operatorname{MSE}\left(s_{y}^{2}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(1-8 c)  \tag{3.4}\\
\operatorname{MSE}\left(t_{5}^{(j)}\right)-\operatorname{MSE}\left(s_{y}^{2}\right)=\left(3 S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(3-8 c)  \tag{3.5}\\
\operatorname{MSE}\left(t_{6}^{(j)}\right)-\operatorname{MSE}\left(s_{y}^{2}\right)=\left(S_{y}^{4} / 4 n\right)\left(\delta_{04}-1\right)(1-4 c) \tag{3.6}
\end{gather*}
$$

where ( $\mathrm{j}=\mathrm{AM}, \mathrm{GM}, \mathrm{HM}$ ).
It is observed from (3.1)-(3.6) that the estimators $t_{1}, t_{2}$ and $t_{i}^{(j)},(i=3,4,5,6 ; j=A M, G M, H M)$ are better than usual unbiased estimator $s_{y}^{2}$ respectively if

$$
\begin{align*}
& c>(1 / 2),  \tag{3.7}\\
& c>(1 / 4),  \tag{3.8}\\
& c>(1 / 4), \tag{3.9}
\end{align*}
$$

$$
\begin{align*}
& c>(1 / 8),  \tag{3.10}\\
& c>(3 / 8),  \tag{3.11}\\
& c>(1 / 4) . \tag{3.12}
\end{align*}
$$

From (3.7)-(3.12) it follows that the sufficient condition for the estimators $t_{1}, t_{2}$ and $t_{i}^{(j)}, \quad(i=$ $3,4,5,6 ; j=A M, G M, H M)$ to be better than the usual unbiased estimator $s_{y}^{2}$ is $c>(1 / 2)$.
From (1.7), (1.8), (2.7), (2.14), (2.21) and (2.28), we have

$$
\begin{align*}
& \operatorname{MSE}\left(t_{2}\right)-\operatorname{MSE}\left(t_{1}\right)=\left(S_{y}^{4} / n\right)\left(\delta_{04}-1\right)\left(c-\frac{3}{4}\right),  \tag{3.13}\\
& \operatorname{MSE}\left(t_{3}^{(j)}\right)-\operatorname{MSE}\left(t_{1}\right)=\left(S_{y}^{4} / n\right)\left(\delta_{04}-1\right)\left(c-\frac{3}{4}\right),  \tag{3.14}\\
& \operatorname{MSE}\left(t_{4}^{(j)}\right)-\operatorname{MSE}\left(t_{1}\right)=\left(S_{y}^{4} / n\right)\left(\delta_{04}-1\right)\left(c-\frac{5}{8}\right),  \tag{3.15}\\
& \operatorname{MSE}\left(t_{5}^{(j)}\right)-\operatorname{MSE}\left(t_{1}\right)=\left(S_{y}^{4} / 2 n\right)\left(\delta_{04}-1\right)\left(c-\frac{7}{8}\right),  \tag{3.16}\\
& \operatorname{MSE}\left(t_{6}^{(j)}\right)-\operatorname{MSE}\left(t_{1}\right)=\left(S_{y}^{4} / n\right)\left(\delta_{04}-1\right)\left(c-\frac{3}{4}\right), \tag{3.17}
\end{align*}
$$

where ( $\mathrm{j}=\mathrm{AM}, \mathrm{GM}, \mathrm{HM}$ ).
From (3.13)-(3.17), we get that the estimators.$t_{2}$. and $t_{i}^{(j)},(i=3,4,5,6 ; j=A M, G M, H M)$ are better than the usual ratio estimator $t_{1}$ respectively if

$$
\begin{align*}
& c<(3 / 4),  \tag{3.18}\\
& c<(3 / 4)  \tag{3.19}\\
& c<(5 / 8)  \tag{3.20}\\
& c<(7 / 8)  \tag{3.21}\\
& c<(3 / 4) \tag{3.22}
\end{align*}
$$

Thus it follows from (3.18)-(3.22) that the sufficient condition that the estimators $t_{2}$ and $t_{i}^{(j)},(i=$
$3,4,5,6 ; j=A M, G M, H M)$ to be better than the usual ratio estimator $t_{1}$ if $c<(5 / 8)$.
From (1.8), (2.7), (2.14), (2.21) and (2.28), we have

$$
\begin{gather*}
\operatorname{MSE}\left(t_{3}^{(j)}\right)-\operatorname{MSE}\left(t_{2}\right)=0  \tag{3.23}\\
\operatorname{MSE}\left(t_{4}^{(j)}\right)-\operatorname{MSE}\left(t_{2}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(8 c-3)  \tag{3.24}\\
\operatorname{MSE}\left(t_{5}^{(j)}\right)-\operatorname{MSE}\left(t_{2}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(5-8 c)  \tag{3.25}\\
\operatorname{MSE}\left(t_{6}^{(j)}\right)-\operatorname{MSE}\left(t_{2}\right)=0 \tag{3.26}
\end{gather*}
$$

where $(j=A M, G M, H M)$.
It is observed from (3.23) and (3.26) that the estimators $t_{2}, t_{3}^{(j)}$ and $t_{6}^{(j)},(j=A M, G M, H M)$ are equally efficient. Further it is also observed from (3.24) and (3.25) that the estimators $t_{4}^{(j)}$ and $t_{5}^{(j)}$, ( $j=A M, G M, H M$ ) are better than the estimators $t_{2}$ respectively if

$$
\begin{align*}
& c<(3 / 8),  \tag{3.27}\\
& c>(5 / 8) \tag{3.28}
\end{align*}
$$

From (2.7), (2.14) and (2.21), we have

$$
\begin{align*}
& \operatorname{MSE}\left(t_{4}^{(j)}\right)-\operatorname{MSE}\left(t_{3}^{(j)}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(8 c-3)  \tag{3.29}\\
& \operatorname{MSE}\left(t_{5}^{(j)}\right)-\operatorname{MSE}\left(t_{3}^{(j)}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(5-8 c) \tag{3.30}
\end{align*}
$$

where $(j=A M, G M, H M)$.
We note from (3.29) and (3.30) that the estimators $t_{4}^{(j)}$ and $t_{5}^{(j)}$ are better than the estimators $t_{3}^{(j)}$, ( $j=A M, G M, H M$ ) respectively if

$$
\begin{align*}
& c<(3 / 8),  \tag{3.31}\\
& c>(5 / 8) . \tag{3.32}
\end{align*}
$$

From (2.14), (2.21) and (2.28), we have

$$
\begin{align*}
& \operatorname{MSE}\left(t_{5}^{(j)}\right)-\operatorname{MSE}\left(t_{4}^{(j)}\right)=\left(S_{y}^{4} / 2 n\right)\left(\delta_{04}-1\right)(1-2 c)  \tag{3.33}\\
& \operatorname{MSE}\left(t_{6}^{(j)}\right)-\operatorname{MSE}\left(t_{4}^{(j)}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(3-8 c) \tag{3.34}
\end{align*}
$$

where $(j=A M, G M, H M)$.

Expressions (3.33) and (3.34) indicate that estimators $t_{5}^{(j)}$ and $t_{6}^{(j)}$ are better than $t_{4}^{(j)}, \quad(j=A M$, $G M, H M$ ) respectively if

$$
\begin{align*}
& c>(1 / 2)  \tag{3.35}\\
& c>(3 / 8) \tag{3.36}
\end{align*}
$$

It is obvious from (3.35) and (3.36) that $c>(1 / 2)$ is a sufficient condition for the estimators $t_{5}^{(j)}$ and $t_{6}^{(j)}$ to be more efficient than the estimators $t_{4}^{(j)},(j=A M, G M, H M)$.
Further from (2.21) and (2.28), we have

$$
\begin{equation*}
\operatorname{MSE}\left(t_{5}^{(j)}\right)-\operatorname{MSE}\left(t_{6}^{(j)}\right)=\left(S_{y}^{4} / 16 n\right)\left(\delta_{04}-1\right)(5-8 c) \tag{3.37}
\end{equation*}
$$

which is positive if

$$
\begin{equation*}
c<(5 / 8) . \tag{3.38}
\end{equation*}
$$

Thus the estimators $t_{6}^{(j)}$ are better than $t_{5}^{(j)},(j=A M, G M, H M)$ if $c<(5 / 8)$.

## 4. EMPIRICAL STUDY

To have tangible idea about the absolute relative efficiency of the proposed estimators over their competitors numerically, we consider three natural population data sets. The descriptions of the population data sets are given in Table 1.

TABLE 1:
Population data sets.

| Population | $N$ | $n$ | $\delta_{40}$ | $\delta_{04}$ | $\delta_{22}$ | $c$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| I: Murthy (1967, p. 226) | 80 | 10 | 2.2667 | 3.65 | 2.3377 | 0.5408 |
| $\quad Y:$ Output. |  |  |  |  |  |  |
| $X:$ Number of workers. |  |  |  |  |  |  |
|  | II: Murthy (1967, p. 127) | 80 | 10 | 2.3730 | 2.0193 | 1.6757 |
| $\quad Y:$ Cultivated area (in acres). |  |  |  |  |  |  |
| $\quad X:$ Area in square miles. |  |  |  |  |  |  |
| III: Sukhatme and Sukhatme (1970, p. 185) |  |  |  |  |  |  |
| $\quad Y:$ Area under wheat in 1937 (in acres). | 80 | 10 | 3.5469 | 3.2816 | 2.6601 | 0.7276 |
| $\quad X:$ Cultivated area in 1931. |  |  |  |  |  |  |

We have computed the percent absolute relative biases (PARBs) of different estimators of $S_{y}^{2}$ by using the formula:

$$
\begin{equation*}
\operatorname{PARB}(t)=\left|\frac{\operatorname{Bias}(t)}{\left(S_{y}^{2} / n\right)}\right| \times 100 \tag{4.1}
\end{equation*}
$$

where $t=t_{1}, t_{2}$ and $t_{i}^{(j)},(i=2,3,4,5,6 ; j=A M, G M, H M)$.
Further we have computed the percent relative efficiencies (PREs) of the various estimators of $S_{y}^{2}$ with respect to usual unbiased estimator $s_{y}^{2}$ by using the formula:

$$
\begin{equation*}
\operatorname{PRE}\left(t, s_{y}^{2}\right)=\frac{\operatorname{MSE}\left(s_{y}^{2}\right)}{\operatorname{MSE}(t)} \times 100 \tag{4.2}
\end{equation*}
$$

where $t=t_{1}, t_{2}$ and $t_{i}^{(j)},(i=2,3,4,5,6 ; j=A M, G M, H M)$ and findings are summarized in Tables 2 and 3.
It is observed from Tables 2 and 3 that
(i) The proposed estimator $t_{4}^{(A M)}$ has least $P A R B$ bias comparatively to other estimators in all the three populations. It follows that the proposed estimator $t_{4}^{(A M)}$ is less biased among all the estimators.
(ii) The proposed estimators $t_{3}^{(j)}$ and $t_{6}^{(j)}$ have largest $\operatorname{PRE}(=214.15)$ at par with the (Singh et al., 2009) estimator $t_{2}$ in the population I. However the PARB of the estimator $t_{3}^{(H M)}$ is less than $t_{1}, t_{2}, t_{3}^{(A M)}, t_{3}^{(G M)}, t_{4}^{(G M)}, t_{5}^{(j)}$ and $t_{6}^{(j)},(j=A M, G M, H M)$. So the estimator $t_{3}^{(H M)}$ is to be preferred over $s_{y}^{2}, t_{1}, t_{2}, t_{3}^{(A M)}, t_{3}^{(G M)}, t_{4}^{(j)}, t_{5}^{(j)}$ and $t_{6}^{(j)},(j=A M, G M$, $H M)$ in the population data set I .
(iii) The proposed estimators $t_{5}^{(j)}$ have larger efficiency than the estimators $s_{y}^{2}, t_{1}, t_{2}, t_{3}^{(j)}$, $t_{4}^{(j)}$ and $t_{6}^{(j)},(j=A M, G M, H M)$ in both population data sets II and III.

TABLE 2:
The PARBs of different estimators.

| Estimator | Population |  |  |
| :--- | ---: | ---: | ---: |
|  | I | II | III |
|  | PARB | PARB | PARB |
| $t_{1}$ | 131.23 | 34.36 | 62.15 |
| $t_{2}$ | 32.49 | 35.51 | 20.44 |
| $t_{3}^{(A M)}$ | 65.62 | 17.18 | 31.08 |
| $t_{3}^{(G M)}$ | 32.49 | 4.44 | 2.56 |
| $t_{3}^{(H M)}$ | 0.64 | 8.30 | 25.97 |
| $t_{4}^{(A M)}$ | 0.16 | 0.02 | 0.01 |
| $t_{4}^{(G M)}$ | 7.96 | 0.97 | 5.85 |
| $t_{4}^{(H M)}$ | 0.32 | 4.15 | 12.98 |
| $t_{5}^{(A M)}$ | 81.86 | 19.40 | 32.35 |
| $t_{5}^{(G M)}$ | 73.58 | 16.21 | 25.22 |
| $t_{5}^{(H M)}$ | 65.30 | 13.03 | 18.09 |
| $t_{6}^{(A M)}$ | 54.57 | 12.93 | 21.57 |
| $t_{6}^{(G M)}$ | 32.49 | 4.44 | 2.56 |
| $t_{6}^{(H M)}$ | 10.41 | 4.06 | 16.46 |

TABLE 3:
The PREs of different estimators.

| Estimator | Population |  |  |
| :--- | ---: | ---: | ---: |
|  | I | II | III |
|  | PRE | PRE | PRE |
| $s_{y}^{2}$ | 100.00 | 100.00 | 100.00 |
| $t_{1}$ | 102.05 | 131.91 | 168.86 |
| $t_{2}$ | 214.15 | 144.20 | 174.78 |
| $t_{3}^{(j)}$ | 214.15 | 144.20 | 174.78 |
| $t_{4}^{(j)}$ | 165.91 | 124.95 | 136.97 |
| $t_{5}^{(j)}$ | 168.72 | 147.19 | 190.05 |
| $t_{6}^{(j)}$ | 214.15 | 144.20 | 174.78 |
| $(j=A M, G M, H M)$ |  |  |  |

## 5. CONCLUSION

In this article we have suggested some estimators of population variance which are based on arithmetic mean, geometric mean and harmonic mean of the usual unbiased, usual ratio and (Singh et al., 2009) estimators. The expressions of bias and mean squared error of proposed estimators have been derived up to first degree of approximation. The theoretical conditions under which the proposed estimators are more efficient than usual unbiased, usual ratio and (Singh et al., 2009) estimators have been obtained. The empirical study shows that in the performances of proposed estimators are better than the other existing estimators i.e. the proposed estimators have larger PREs and least PARBs in comparisons of others. Thus we recommend the proposed estimators in practice. However this conclusion can not be extrapolated due to limited empirical study.

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## SUMMARY

## Estimation of finite population variance using auxiliary information in sample surveys

This paper addresses the problem of estimating the finite population variance using auxiliary information in sample surveys. Motivated by (Singh and Vishwakarma, 2009) some estimators of finite population variance have been suggested along with their properties in simple random sampling. The theoretical conditions under which the proposed estimators are more efficient than usual unbiased, usual ratio and (Singh et al., 2009) estimators have been obtained. Numerical illustrations are given in support of the present study.

Keywords: Study variable; Auxiliary variable; Arithmetic mean; Geometric mean; Harmonic mean; Bias; Mean squared error

## APPENDIX I

To obtain the biases and mean squared errors of the estimators $t_{i}^{(A M)}, t_{i}^{(G M)}$ and $t_{i}^{(H M)},(i=3$, $4,5,6)$ we define the following classes of estimators of population variance $S_{y}^{2}$ as

$$
\begin{align*}
& t_{A M}=\left(\alpha_{0} t_{0}+\alpha_{1} t_{1}+\alpha_{2} t_{2}\right), \quad\left(\alpha_{0}+\alpha_{1}+\alpha_{2}\right)=1 \\
&= s_{y}^{2}\left[\alpha_{0}+\alpha_{1}\left(\frac{S_{x}^{2}}{s_{x}^{2}}\right)+\alpha_{2} \exp \left(\frac{S_{x}^{2}-s_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right]  \tag{I.1}\\
& t_{G M}=\left(t_{0}^{\alpha_{0}} t_{1}^{\alpha_{1}} t_{2}^{\alpha_{2}}\right),\left(\alpha_{0}+\alpha_{1}+\alpha_{2}\right)=1 \\
&=s_{y}^{2}\left(\frac{S_{x}^{2}}{s_{x}^{2}}\right)^{\alpha_{1}} \exp \left(\frac{\alpha_{1}\left(S_{x}^{2}-s_{x}^{2}\right)}{S_{x}^{2}+s_{x}^{2}}\right)  \tag{I.2}\\
& t_{H M}=\frac{1}{\left(\frac{\alpha_{0}}{t_{0}}+\frac{\alpha_{1}}{t_{1}}+\frac{\alpha_{2}}{t_{2}}\right), \quad\left(\alpha_{0}+\alpha_{1}+\alpha_{2}\right)=1} \\
&= s_{y}^{2}  \tag{I.3}\\
& {\left[\alpha_{0}+\alpha_{1}\left(\frac{s_{x}^{2}}{S_{x}^{2}}\right)+\alpha_{2} \exp \left(\frac{s_{x}^{2}-S_{x}^{2}}{S_{x}^{2}+s_{x}^{2}}\right)\right] }
\end{align*}
$$

We write

$$
s_{y}^{2}=S_{y}^{2}\left(1+e_{0}\right) \text { and } s_{x}^{2}=S_{x}^{2}\left(1+e_{1}\right)
$$

such that

$$
E\left(e_{0}\right)=E\left(e_{1}\right)=0
$$

and to the first degree of approximation (ignoring finite population correction term)

$$
\left.\begin{array}{l}
E\left(e_{0}^{2}\right)=n^{-1}\left(\delta_{40}-1\right) \\
E\left(e_{1}^{2}\right)=n^{-1}\left(\delta_{04}-1\right) \\
E\left(e_{0} e_{1}\right)=n^{-1}\left(\delta_{04}-1\right) c
\end{array}\right\}
$$

where

$$
c=\left(\delta_{22}-1\right)\left(\delta_{04}-1\right)^{-1}, \quad \delta_{p q}=\left(\mu_{p q} / \mu_{20}^{p / 2} \mu_{02}^{q / 2}\right), \quad \mu_{p q}=N^{-1} \sum_{i=1}^{N}\left(y_{i}-\bar{Y}\right)^{p}\left(x_{i}-\bar{X}\right)^{q}
$$

( $p, q$ being non-negative integers).

Expressing (I.1) in terms of $e$ 's we have

$$
\begin{aligned}
t_{A M} & =S_{y}^{2}\left(1+e_{0}\right)\left[\alpha_{0}+\alpha_{1}\left(1+e_{1}\right)^{-1}+\alpha_{2} \exp \left(\frac{-e_{1}}{2+e_{1}}\right)\right] \\
& =S_{y}^{2}\left(1+e_{0}\right)\left[\alpha_{0}+\alpha_{1}\left(1-e_{1}+e_{1}^{2}-\ldots\right)+\alpha_{2}\left\{1-\frac{e_{1}}{2}\left(1+\frac{e_{1}}{2}\right)^{-1}+\frac{e_{1}^{2}}{8}\left(1+\frac{e_{1}}{2}\right)^{-2}-\ldots\right\}\right] \\
& =S_{y}^{2}\left(1+e_{0}\right)\left[1+\alpha_{1}\left(-e_{1}+e_{1}^{2}-\ldots\right)+\alpha_{2}\left\{-\frac{e_{1}}{2}\left(1-\frac{e_{1}}{2}+\ldots\right)+\frac{e_{1}^{2}}{8}\left(1+\frac{e_{1}}{2}\right)^{-2}-\ldots\right\}\right] \\
& =S_{y}^{2}\left(1+e_{0}\right)\left[1-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}+\left(\alpha_{1}+\frac{\alpha_{2}}{4}+\frac{\alpha_{2}}{8}\right) e_{1}^{2}-\ldots\right] \\
& \cong S_{y}^{2}\left[1+e_{0}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}+\left(\alpha_{1}+\frac{3 \alpha_{2}}{8}\right) e_{1}^{2}\right]
\end{aligned}
$$

or

$$
\begin{equation*}
\left(t_{A M}-S_{y}^{2}\right) \cong S_{y}^{2}\left[e_{0}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}+\left(\alpha_{1}+\frac{3 \alpha_{2}}{8}\right) e_{1}^{2}\right] \tag{I.4}
\end{equation*}
$$

Taking expectation of both sides of (I.4), we get the bias of $t_{A M}$ to the first degree of approximation as

$$
\begin{equation*}
\operatorname{Bias}\left(t_{A M}\right)=n^{-1} S_{y}^{2}\left(\delta_{04}-1\right)\left[\left(\alpha_{1}+\frac{3 \alpha_{2}}{8}\right)-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) c\right] \tag{I.5}
\end{equation*}
$$

Squaring both sides of (I.4) and neglecting terms of $e$ 's having power greater than two we have

$$
\begin{equation*}
\left(t_{A M}-S_{y}^{2}\right)^{2}=S_{y}^{4}\left[e_{0}^{2}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2} e_{1}^{2}-2\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}\right] \tag{I.6}
\end{equation*}
$$

Taking expectation of both sides of (I.6) we get the mean squared error of $t_{A M}$ to the first degree of approximation as

$$
\begin{equation*}
\operatorname{MSE}\left(t_{A M}\right)=n^{-1} S_{y}^{4}\left[\left(\delta_{40}-1\right)+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)\left(\delta_{04}-1\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}-2 c\right)\right] \tag{I.7}
\end{equation*}
$$

Putting $\left(\alpha_{0}, \alpha_{1}, \alpha_{2}\right)=\left(\frac{1}{2}, \frac{1}{2}, 0\right),\left(\frac{1}{2}, 0, \frac{1}{2}\right),\left(0, \frac{1}{2}, \frac{1}{2}\right)$ and $\left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$ in (I.5) and (I.7) one can easily get the biases and mean squared errors of the estimators $t_{i}^{(A M)},(i=3,4,5,6)$ respectively given in ((2.4), (2.7)); ((2.11), (2.14)); ((2.18), (2.21)) and ((2.25), (2.28)).

Expressing the class of estimators $t_{G M}$ in terms of $e$ 's, we have

$$
\begin{aligned}
t_{G M} & =S_{y}^{2}\left(1+e_{0}\right)\left(1+e_{1}\right)^{-\alpha_{1}} \exp \left(\frac{-\alpha_{2} e_{1}}{2+e_{1}}\right) \\
& =S_{y}^{2}\left(1+e_{0}\right)\left(1+e_{1}\right)^{-\alpha_{1}} \exp \left(\frac{-\alpha_{2} e_{1}}{2}\left(1+\frac{e_{1}}{2}\right)^{-1}\right) \\
& =S_{y}^{2}\left(1+e_{0}\right)\left\{1-\alpha_{1} e_{1}+\frac{\alpha_{1}\left(\alpha_{1}+1\right)}{2} e_{1}^{2}-\ldots\right\}\left\{1-\frac{\alpha_{2} e_{1}}{2}\left(1+\frac{e_{1}}{2}\right)^{-1}+\frac{\alpha_{2}^{2} e_{1}^{2}}{8}\left(1+\frac{e_{1}}{2}\right)^{-2}-\ldots\right\} \\
& =S_{y}^{2}\left(1+e_{0}\right)\left\{1-\alpha_{1} e_{1}+\frac{\alpha_{1}\left(\alpha_{1}+1\right)}{2} e_{1}^{2}-\ldots\right\}\left\{1-\frac{\alpha_{2} e_{1}}{2}\left(1-\frac{e_{1}}{2}+\ldots\right)+\frac{\alpha_{2}^{2} e_{1}^{2}}{8}\left(1-e_{1}+\ldots\right)\right\} \\
& =S_{y}^{2}\left[1+e_{0}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}+\left(\frac{\alpha_{1} \alpha_{2}}{2}+\frac{\alpha_{1}\left(\alpha_{1}+1\right)}{2}+\frac{\alpha_{2}\left(2+\alpha_{2}\right)}{8}\right) e_{1}^{2}+.\right.
\end{aligned}
$$

or

$$
\begin{equation*}
\left(t_{G M}-S_{y}^{2}\right) \cong S_{y}^{2}\left[e_{0}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}+\left(\frac{\alpha_{1} \alpha_{2}}{2}+\frac{\alpha_{1}\left(\alpha_{1}+1\right)}{2}+\frac{\alpha_{2}\left(2+\alpha_{2}\right)}{8}\right) e_{1}^{2}\right] \tag{I.8}
\end{equation*}
$$

Taking the expectation of both sides of (I.8), we get the bias of $t_{G M}$ to the first degree of approximation as

$$
\begin{align*}
\operatorname{Bias}\left(t_{G M}\right) & =\left(S_{y}^{2} / 8 n\right)\left(\delta_{04}-1\right)\left[4 \alpha_{1}\left(\alpha_{1}+1\right)+4 \alpha_{1} \alpha_{2}+\alpha_{2}\left(2+\alpha_{2}\right)-8\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) c\right] \\
& =\left(S_{y}^{2} / 2 n\right)\left(\delta_{04}-1\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}+1-2 c\right) \tag{I.9}
\end{align*}
$$

Squaring both sides of (I.8) and neglecting terms of $e$ 's having power greater than two we have

$$
\begin{equation*}
\left(t_{G M}-S_{y}^{2}\right)^{2}=S_{y}^{4}\left[e_{0}^{2}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2} e_{1}^{2}-2\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}\right] \tag{I.10}
\end{equation*}
$$

Taking expectation of both sides of (I.10), we get the mean squared error of $t_{G M}$ to the first degree of approximation as

$$
\begin{equation*}
\operatorname{MSE}\left(t_{G M}\right)=\left(S_{y}^{4} / n\right)\left[\left(\delta_{40}-1\right)+\left(\delta_{04}-1\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}-2 c\right)\right] \tag{I.11}
\end{equation*}
$$

Substituting the values of $\left(\alpha_{0}, \alpha_{1}, \alpha_{2}\right)=\left(\frac{1}{2}, \frac{1}{2}, 0\right),\left(\frac{1}{2}, 0, \frac{1}{2}\right),\left(0, \frac{1}{2}, \frac{1}{2}\right)$ and $\left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$ in (I.9) and (I.11) one can easily get the biases and mean squared errors of the estimators $t_{i}^{(G M)},(i=3,4$,
$5,6)$ respectively given in ((2.5), (2.7)); ((2.12), (2.14));((2.19), (2.21)) and ((2.26), (2.28)).
Expressing the class of estimators $t_{H M}$ in terms of $e$ 's we have

$$
\begin{aligned}
t_{H M} & =\frac{S_{y}^{2}\left(1+e_{0}\right)}{\left[\alpha_{0}+\alpha_{1}\left(1+e_{1}\right)+\alpha_{2} \exp \left(\frac{e_{1}}{2+e_{1}}\right)\right]} \\
& =\frac{S_{y}^{2}\left(1+e_{0}\right)}{\left[\alpha_{0}+\alpha_{1}\left(1+e_{1}\right)+\alpha_{2} \exp \left(\frac{e_{1}}{2}\left(1+\frac{e_{1}}{2}\right)^{-1}\right)\right]} \\
& =\frac{S_{y}^{2}\left(1+e_{0}\right)}{\left[\alpha_{0}+\alpha_{1}\left(1+e_{1}\right)+\alpha_{2}\left\{1+\frac{e_{1}}{2}\left(1+\frac{e_{1}}{2}\right)^{-1}+\frac{e_{1}^{2}}{8}\left(1+\frac{e_{1}}{2}\right)^{-2}+\ldots\right\}\right]} \\
& =\frac{S_{y}^{2}\left(1+e_{0}\right)}{\left[1+\alpha_{1} e_{1}+\alpha_{2}\left\{\frac{e_{1}}{2}\left(1-\frac{e_{1}}{2}+\ldots\right)+\frac{e_{1}^{2}}{8}\left(1-e_{1}+\ldots\right)\right\}\right]} \\
& =S_{y}^{2}\left(1+e_{0}\right) \\
& =S_{y}^{2}\left(1+e_{0}\right)\left[1+\left\{\left(\alpha_{0}\right)\left[1-\left\{\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\frac{\alpha_{2}}{8} e_{1}^{2}+\ldots\right\}\right]_{1}\left(\frac{e_{1}}{2}-\frac{e_{1}^{2}}{8}+\ldots\right) e_{1}-\frac{\alpha_{2}}{8} e_{1}^{2}+\ldots\right\}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2} e_{1}^{2}+\ldots\right] \\
& =S_{y}^{2}\left(1+e_{0}\right)\left[1-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}+\left\{\frac{\alpha_{2}}{8}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2}\right\} e_{1}^{2}+\ldots\right] \\
& \cong S_{y}^{2}\left[1+e_{0}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}+\left\{\frac{\alpha_{2}}{8}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2}\right\} e_{1}^{2}\right]
\end{aligned}
$$

or

$$
\begin{equation*}
\left(t_{H M}-S_{y}^{2}\right) \cong S_{y}^{2}\left[e_{0}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{1}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}+\left\{\frac{\alpha_{2}}{8}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2}\right\} e_{1}^{2}\right] \tag{I.12}
\end{equation*}
$$

Taking expectation of both sides of (I.12), we get the bias of $t_{H M}$ to the first degree of approximation as

$$
\begin{align*}
\operatorname{Bias}\left(t_{H M}\right) & =\left(S_{y}^{2} / n\right)\left(\delta_{04}-1\right)\left[\frac{\alpha_{2}}{8}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2}-\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) c\right] \\
& =\left(S_{y}^{2} / n\right)\left(\delta_{04}-1\right)\left[\frac{\alpha_{2}}{8}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}-c\right)\right] \tag{I.13}
\end{align*}
$$

Squaring both sides of (I.12) and neglecting terms of $e$ 's having power greater than two we have

$$
\begin{equation*}
\left(t_{H M}-S_{y}^{2}\right)^{2}=S_{y}^{4}\left[e_{0}^{2}+\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)^{2} e_{1}^{2}-2\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right) e_{0} e_{1}\right] \tag{I.14}
\end{equation*}
$$

Taking expectation of both sides of (I.14), we get the mean squared error of $t_{H M}$ to the first degree of approximation as

$$
\begin{equation*}
\operatorname{MSE}\left(t_{H M}\right)=\left(S_{y}^{4} / n\right)\left[\left(\delta_{40}-1\right)+\left(\delta_{04}-1\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}\right)\left(\alpha_{1}+\frac{\alpha_{2}}{2}-2 c\right)\right] \tag{I.15}
\end{equation*}
$$

Substituting the values of $\left(\alpha_{0}, \alpha_{1}, \alpha_{2}\right)=\left(\frac{1}{2}, \frac{1}{2}, 0\right),\left(\frac{1}{2}, 0, \frac{1}{2}\right),\left(0, \frac{1}{2}, \frac{1}{2}\right)$ and $\left(\frac{1}{3}, \frac{1}{3}, \frac{1}{3}\right)$ in (I.13) and (I.15) one can easily get the biases and mean squared errors of the estimators $t_{i}^{(G M)}$, $(i=3,4,5,6)$ respectively given in ((2.6), (2.7)); ((2.13), (2.14)); ((2.20), (2.21)) and ((2.27), (2.28)).

