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5 **Influence of spatial variability on slope reliability**  
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8 **using 2-d random fields**  
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18 **Abstract:** The paper investigates the probability of failure of slopes using both traditional  
19 and more advanced probabilistic analysis tools. The advanced method, called the  
20 Random Finite Element Method (RFEM), uses elastoplasticity in a finite element model  
21 combined with random field theory in a Monte-Carlo framework. The traditional method,  
22 called the First Order Reliability Method (FORM), computes a reliability index which is  
23 the shortest distance (in units of directional equivalent standard deviations) from the  
24 equivalent mean-value point to the limit state surface, and estimates the probability of  
25 failure from the reliability index. Numerical results show that simplified probabilistic  
26 analyses in which spatial variability of soil properties is not properly accounted for, can  
27 lead to unconservative estimates of the probability of failure if the coefficient of variation  
28 of the shear strength parameters exceeds a critical value. The influences of slope  
29 inclination, factor of safety (based on mean strength values) and cross correlation  
30 between strength parameters on this critical value have been investigated by parametric  
31 studies in this paper. The results indicate when probabilistic approaches which do not  
32 model spatial variation may lead to unconservative estimates of slope failure probability  
33 and when more advanced probabilistic methods are warranted.  
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46 **Keywords:** Slope stability, Finite element method, Probability of failure, Spatial  
47 correlation.  
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## Introduction

Slope stability analysis is a branch of geotechnical engineering that is highly amenable to probabilistic treatment, and has received considerable attention in the literature. The earliest papers appeared in the 1970s (e.g. Matsuo and Kuroda 1974, Alonso 1976, Tang et al. 1976, Vanmarcke 1977) and have continued steadily (e.g. D'Andrea and Sangrey 1982, Chowdhury and Tang 1987, Li and Lumb 1987, Oka and Wu 1990, Mostyn and Li 1993, Lacasse 1994, Christian et al. 1994, Chowdhury and Xu 1995, Wolff 1996, Christian 1996, Lacasse and Nadim 1996, Low 1996, Low and Tang 1997, Low et. al, 1998, Hassan and Wolff 1999, Whitman 2000, Duncan 2000, El-Ramly et al. 2002, Low 2003, Bhattacharya et. al, 2003, Griffiths and Fenton 2004, Babu and Mukesh 2004, Xu and Low 2006, Low et al. 2007, Cho 2007, Shinoda 2007). In spite of this activity, the geotechnical profession is slow to adopt probabilistic approaches to geotechnical design, especially in traditional problems such as slopes and foundations. In particular, while the importance of spatial correlation (or auto-correlation) and local averaging of statistical geotechnical properties has long been recognized by some investigators (e.g. Mostyn and Soo 1990), it is still regularly omitted from many probabilistic slope stability analyses. Griffiths and Fenton (2004) studied slope stabilities using Random Finite Element Method (RFEM), which combines elasto-plastic finite element analysis with random fields generated using the Local Average Subdivision Method (Fenton and Vanmarcke 1990). The results indicated that traditional probabilistic analyses, in which spatial variability is ignored by implicitly assuming perfect correlation, can lead to unconservative estimates of the probability of failure. This paper thoroughly investigates this observation by assessing the influence of the spatial correlation length and coefficient of variation of strength parameters on slope stability across a wide range of parametric variations. Numerical results show that for a given value of the spatial correlation length, there is a critical value of the coefficient of variation of strength parameters, above which FORM, if spatial variation is not modeled, underestimates the probability of failure and is therefore unconservative. The influence of slope inclination, factor of safety (based on mean strength values) and cross correlation between strength parameters on the critical value of the coefficient of variation has been investigated by parametric studies, indicating when more advanced probabilistic methods are warranted.

In spite of the fact that most traditional Limit Equilibrium Method (LEM) existing in literature do not consider spatial variability, some investigators have combined the LEM with random field theory (e.g. Li and Lumb, 1987, Mostyn and Soo 1990, Low and Tang

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4 1997, El-Ramly et al. 2002, Low 2003, Babu and Mukesh 2004, Low et al. 2007, Cho  
5 2007, Slope/W 2007 Version). However, the inherent nature of LEM is that it leads to a  
6 critical failure surface, which in 2-d analysis appears as a line which could be  
7 non-circular. The influence of the random field is only taken into account along the line  
8 and is therefore one-dimensional. All results obtained by the previously mentioned  
9 implementations indicate that increasing the spatial correlation length leads to an  
10 increased probability of failure irrespective of the variance of the shear strength  
11 parameters. Some of the results presented in the current paper however, indicate that both  
12 the spatial correlation length and the input variances can affect the probability of failure.  
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20 Both undrained  $\phi_u = 0$  and drained  $c', \tan\phi'$  slopes are considered with the slope  
21 profile shown in Fig. 1. In this study, the slope has height  $H = 10.0$  m, foundation depth  
22 ratio  $D = 2$ , and soil unit weight,  $\gamma_{sat}$  (or  $\gamma$ ) =  $20.0$  kN/m<sup>3</sup>, which are all held constant.  
23 For undrained slopes, the shear strength  $c_u$  is assumed to be a random variable and  
24 expressed in a dimensionless form given by  $C_u = c_u / (\gamma_{sat} H)$ . For drained slopes, both  
25 the shear strength  $c'$ , expressed in the dimensionless form  $C' = c' / (\gamma H)$ , and the  
26 tangent of the friction angle,  $\tan\phi'$ , are assumed to be random variables. Three different  
27 slope angles  $\alpha$  are considered:  $\alpha = 18.4^\circ$  (3:1 slope),  $\alpha = 26.6^\circ$  (2:1 slope) and  
28  $\alpha = 45^\circ$  (1:1 slope).  
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### 36 Probabilistic descriptions of strength parameters

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39 In this study, the shear strength parameters  $C_u$ ,  $C'$  and  $\tan\phi'$  are assumed to be  
40 random variables characterized statistically by lognormal distributions (i.e. the logarithms  
41 of the properties are normally distributed). The lognormal distribution will be applied at  
42 the point level. The lognormal distribution is one of many possible choices (e.g. Fenton  
43 and Griffiths 2008) however it offers the advantage of simplicity, in that it is arrived by a  
44 simple nonlinear transformation of the classical normal (Gaussian) distribution.  
45 Lognormal distributions guarantee that the random variable is always positive, and in  
46 addition to the current authors, it has been advocated and used by several other  
47 investigators as a reasonable model for physical soil properties (e.g. Parkin *et al.* 1988,  
48 Parkin and Robinson 1992, Gui *et al.* 2000, Nour *et al.* 2002, Massih *et al.* 2008). The  
49 RFEM methodology has been described in detail in other publications (e.g. Fenton and  
50 Griffiths 2008), so only a brief description will be repeated here for the random variable  
51  $C_u$ . An identical procedure is applied to  $C'$  and  $\tan\phi'$ .  
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The lognormally distributed undrained shear strength  $C_u$  has three parameters; the mean,  $\mu_{C_u}$ , the standard deviation  $\sigma_{C_u}$  and the spatial correlation length. The variability of  $C_u$  can conveniently be expressed by the dimensionless coefficient of variation defined as

$$v_{C_u} = \frac{\sigma_{C_u}}{\mu_{C_u}} \quad (1)$$

The parameters of the normal distribution (of the logarithm of  $C_u$ ) can be obtained from the standard deviation and mean of  $C_u$  as follows:

$$\sigma_{\ln C_u} = \sqrt{\ln(1 + v_{C_u}^2)} \quad (2)$$

$$\mu_{\ln C_u} = \ln \mu_{C_u} - \frac{1}{2} \sigma_{\ln C_u}^2 \quad (3)$$

Inverting Eqs. (2) and (3) gives the mean and standard deviation of  $C_u$ :

$$\mu_{C_u} = \exp\left(\mu_{\ln C_u} + \frac{1}{2} \sigma_{\ln C_u}^2\right) \quad (4)$$

$$\sigma_{C_u} = \mu_{C_u} \sqrt{\exp(\sigma_{\ln C_u}^2) - 1} \quad (5)$$

A third parameter, the spatial correlation length  $\theta_{\ln C_u}$ , will also be considered in this study. Since the actual undrained shear strength field is lognormally distributed, its logarithm yields an “underlying” normally distributed (or Gaussian) field. The spatial correlation length is measured with respect to this underlying field, that is, with respect to  $\ln C_u$ . In particular, the spatial correlation length ( $\theta_{\ln C_u}$ ) describes the distance over which the spatially random values will tend to be significantly correlated in the underlying Gaussian field. Thus, a large value of  $\theta_{\ln C_u}$  will imply a smoothly varying field, while a small value will imply a ragged field.

In this work, an exponentially decaying (Markovian) correlation function is used of the form:

$$\rho(\tau) = e^{-\frac{2\tau}{\theta_{\ln C_u}}} \quad (6)$$

where  $\rho(\tau)$  is the correlation coefficient between properties assigned to two points in the random field separated by an absolute distance  $\tau$ .

In the current study, the spatial correlation length has been non-dimensionalized by dividing it by the height of the embankment  $H$  and will be expressed in the form,

$$\Theta_{C_u} = \theta_{\ln C_u} / H \quad (7)$$

Figs. 2a and b show typical failure mechanisms corresponding to different spatial correlation lengths. Fig. 2a shows a relatively low spatial correlation length of  $\Theta_{C_u} = 0.2$  and Fig. 2b shows a relatively high spatial correlation length of  $\Theta_{C_u} = 2$ . The figures depict the variation of  $\ln C_u$ , and have been scaled in such a way that dark and light regions depict “strong” and “weak” soil respectively. Black represents the strongest element, and white the weakest in the particular realization. It should be emphasized that both these shear strength distributions come from the same lognormal distribution (same mean and standard deviation) and it is only the spatial correlation length that is different. A great benefit of RFEM is that the shape and location of the failure surface is not determined *a priori* and the algorithm is able to “seek out” the most critical path through the heterogeneous soil mass (e.g. Griffiths *et al.* 2006).

The input parameters relating to the mean, standard deviation and spatial correlation length are assumed to be defined at the “point” level. While statistics at this resolution are obviously impossible to measure in practice, they represent a fundamental baseline of the inherent soil variability which can be corrected through local averaging to take account of the sample size. In the context of the RFEM approach, each finite element is assigned a constant property. The “sample” is represented by the size of each finite element used to discretize the slope. If the point distribution is normal, local averaging results in a reduced variance but the mean is unaffected. In a lognormal distribution however, both the mean and the standard deviation are reduced by local averaging. Following local averaging, the adjusted statistics  $\mu_{C_{uA}}, \sigma_{C_{uA}}$  represent the mean and standard deviation of the lognormal field that is actually mapped onto the finite element mesh. Further details can be found in Griffiths and Fenton (2004).

In the limit as  $\Theta_{C_u} \rightarrow 0$ , local averaging removes all variance ( $\sigma_{C_{uA}} \rightarrow 0$ ), and the mean tends to the median, thus

$$\mu_{C_{uA}} \rightarrow \text{Median}_{C_u} = \exp(\mu_{\ln C_u}) = \exp\left(\ln \mu_{C_u} - \frac{1}{2} \sigma_{\ln C_u}^2\right) = \frac{\mu_{C_u}}{\sqrt{1 + v_{C_u}^2}} \quad (8)$$

## Traditional probabilistic methods

### Undrained slope

In this paper the term “traditional probabilistic methods” refers to probabilistic methods (whether using Monte-Carlo simulation or FORM) which do not explicitly take account of the spatial correlation length, hence slopes are assumed to be uniform (spatially constant properties) with  $C_u$  selected randomly from a lognormal distribution. The traditional probabilistic methods imply a spatial correlation length  $\Theta_{C_u} = \infty$ , so no local averaging is applicable.

Since there is only one random variable in an undrained analysis, the probability of failure ( $p_f$ ) is simply equal to the probability that the shear strength parameter  $C_u$  will be less than  $C_{u,FS=1}$ , where  $C_{u,FS=1}$  is the value that results in a factor of safety  $FS$  equal to unity. Quantitatively, this equals the area beneath the probability density function corresponding to  $C_u \leq C_{u,FS=1}$ . For example for  $\alpha = 26.6^\circ$ ,  $C_{u,FS=1} = 0.17$  and  $C_{u,FS=1.47} = 0.25$  (from Taylor’s charts or limit equilibrium), so if we let  $\mu_{C_u} = 0.25$  and  $\sigma_{C_u} = 0.125$  ( $\nu_{C_u} = 0.5$ ), Eqs. (2) and (3) give that the mean and standard deviation of the underlying normal distribution are  $\mu_{\ln C_u} = -1.489$  and  $\sigma_{\ln C_u} = 0.472$  respectively. The probability of failure is therefore given by:

$$p_f = P(C_u < 0.17) = \Phi\left(\frac{\ln 0.17 - \mu_{\ln C_u}}{\sigma_{\ln C_u}}\right) = 0.281 \quad (9)$$

where  $\Phi \cdot$  is the cumulative standard normal distribution function.

In order to investigate the influence of  $FS$  on  $p_f$ , and for  $\mu_{C_u} = C_{u,FS=1.25} = 0.21$ ,  $\mu_{C_u} = C_{u,FS=1.47} = 0.25$  and  $\mu_{C_u} = C_{u,FS=1.70} = 0.29$ , the probability of failure corresponding to different  $\nu_{C_u}$  can be easily obtained, and are listed in Table 1. For the purposes of our parametric studies, it was necessary to push the  $\nu_{C_u}$  up as high as 1.5 in some cases in order to find the critical value at which the traditional method ceases to be conservative.

While considering the influence of the slope inclination, it may be noted that in an undrained slope, the slope inclination makes no difference to  $p_f$  if  $FS$  (based on the mean) is the same in all cases. Thus the  $p_f$  values shown in Table 1 apply to any slope inclination.

## FORM and the Hasofer-Lind reliability index

The first order reliability method (FORM) is a process which can be used to estimate the probability of failure of systems involving multiple random variables with given probability density functions, in relation to a “limit state” function that separates the failure domain from the safe domain. Xu and Low (2006) used FORM combined with the finite element method to estimate the probability of failure of slopes. The conventional FORM based on the Hasofer-Lind reliability index (Hasofer and Lind 1974),  $\beta_{HL}$ , assumes that the mean values of random variables lie on the safe side of the limit state function. The method then obtains the reliability index, which is related to the minimum distance, in directional standard deviation units, between the mean values and the limit state surface. The conceptual and implementation barriers surrounding the use of  $\beta_{HL}$  for correlated normals and the FORM for correlated non-normals can largely be overcome as shown by Low and Tang (1997, 2004). Calculation of the reliability index involves an iterative optimization process, in which the minimum value of a matrix calculation is found, subject to the constraint that the values are on the limit state surface. Commonly used software packages (e.g. Excel and Matlab) are easily adapted to perform the optimization (see e.g. [www.mines.edu/~vgriffit/FORM](http://www.mines.edu/~vgriffit/FORM)). Once the reliability index (the distance between the means and the closest failure point) has been determined, the method assumes a “first order” limit state function tangent to the  $\beta$  contour, and the probability of failure,  $p_f$  follows from

$$p_f = 1 - \Phi \beta \quad (10)$$

It should be noted that the reliability index is given a negative value if  $p_f > 50\%$  (e.g. Low 2005).

If dealing with two random variables, the “first order” assumption results in a straight line limit state function, in which case  $p_f$  is the volume under the bi-variate probability density function on the failure side of the line. A similar concept applies to cases involving multiple random variables.

Each reliability analysis requires a limit state function, which defines safe or unsafe performance. Limit states could relate to strength failure, serviceability failure, or anything else that describes unsatisfactory performance. The limit state function,  $g$ , is customarily defined

$$\begin{aligned}
g(X_1, X_2, \dots, X_N) \geq 0 &\longrightarrow \text{Safe} \\
g(X_1, X_2, \dots, X_N) < 0 &\longrightarrow \text{Failure}
\end{aligned}
\tag{11}$$

where  $X_1, X_2, \dots, X_N$  are the input random variables. An advantage of the Hasofer-Lind index  $\beta_{HL}$  for correlated normal variates and the FORM index  $\beta$  for correlated non-normal variates is that the result it gives is not affected by the form of the limit state function. For example, the limit state function could be defined as the resistance minus the load, the factor of safety minus one, the logarithm of the factor of safety or some other algebraic combination without influencing the computed value of  $\beta_{HL}$  or  $\beta$ .

The limit state function can sometimes be determined directly from theory, or for more complex systems, the Response Surface Method (e.g., Melchers, 1999) needs to be used. The basic idea of the Response Surface Method is to approximate the limit state boundary by an explicit function of the random variables, and to improve the approximation via iterations

In detail, the determination of  $\beta$  in FORM is an iterative process (as explained by Haldar and Mahadevan 2000, for example). An alternative interpretation involving an equivalent hyperellipsoid was given in Low and Tang (2004) and Low (2005) as follows:

$$\beta = \min_{g=0} \sqrt{\left\{ \frac{X_i - \mu_i^N}{\sigma_i^N} \right\}^T R^{-1} \left\{ \frac{X_i - \mu_i^N}{\sigma_i^N} \right\}} \quad i=1,2,\dots,n \tag{12}$$

where  $X_i$  is the  $i^{\text{th}}$  random variable,  $\mu_i^N$  is the equivalent normal mean of the  $i^{\text{th}}$  random variable,  $\sigma_i^N$  is the equivalent normal standard deviation of the  $i^{\text{th}}$  random variable,  $\{(X_i - \mu_i^N)/\sigma_i^N\}$  is the vector of  $n$  random variables reduced to standard normal space and  $R$  is the correlation matrix.

#### Drained slope

For slopes of  $c' - \tan \phi'$  soils, no analytical equation exists which can serve as a limit state function. The Response Surface Method (e.g. Xu and Low, 2006) has been introduced in this study. This can be accomplished, for example, by fitting a curve to the results from several finite element analyses using the strength reduction method (e.g., Griffiths and Lane 1999). This method involves applying gravity loads to the finite element mesh and systematically weakening the soil until a sufficient number of elements have yielded to allow the formation of a failure mechanism.



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4 For example, with two ( $n = 2$ ) random variables a quadratic surface without cross-terms  
5 with five ( $2n + 1 = 5$ ) constants of the form  
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$$FS \ln C', \ln \tan \phi' = a_1 + a_2 \ln C' + a_3 \ln \tan \phi' + a_4 \ln C'^2 + a_5 \ln \tan \phi'^2 \quad (13)$$

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11 could be used to approximate the factor of safety function.  
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14 The limit state function could then be defined as the factor of safety function minus one,  
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$$g \ln C', \ln \tan \phi' = FS \ln C', \ln \tan \phi' - 1 \quad (14)$$

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20 In order to find the five constants in Eq. (13), five finite element analyses were run. For  
21 each random variable, its equivalent normal mean value,  $\mu_i^N$  and two other  
22 values  $\mu_i^N \pm m\sigma_i^N$  were sampled while fixing the other random variable at its equivalent  
23 normal mean value. Some investigators (e.g. Xu and Low 2006, Griffiths et al. 2007)  
24 have related the two other sampling points to some factor of the standard deviation given  
25 by  $m$ . A popular choice is  $m = 1$  which will be used later in this section. For cases  
26 involving high  $\nu$ , the use of  $m = 1$  leads to some sampling points being far from the  
27 central sampling point and thus, the performance function may not always be defined  
28 with accuracy in the zone of interest (i.e. near the tentative design point). For slope  
29 reliability analysis however, limit state functions for slopes have been shown to be quite  
30 linear in the space of cohesion and friction angle (e.g. Mostyn and Li 1993, Low et al.  
31 1998), so  $p_f$  is rather insensitive to the choice of  $m$ .  
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41 Since the design point is not known in advance, the limit state function is initially derived  
42 at the equivalent normal mean which gives a first approximation of the design point. This  
43 design point can be far from the optimal one and may lead to incorrect results. The  
44 current work uses the following iteration procedure (e.g. Tadjiria et al. 2000), which  
45 leads to the limit state function being approximated at the design point.  
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- 51 1) Derive the limit state function at the equivalent normal mean values.
- 52 2) Use FORM to obtain the design point and hence  $p_f$ .
- 53 3) Update the limit state function using the design point just found.
- 54 4) Use FORM to update the design point and hence  $p_f$ .
- 55 5) Repeat 3) to 4) until convergence when two successive values of  $p_f$  is smaller  
56 than a prescribed tolerance.  
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The factor of safety at the design point should equal one at convergence.

In order to investigate the influence of slope inclination and the  $FS$  (based on the mean) on the critical value of coefficient of variation, five slopes have been analyzed using FORM. The mean values that would result in the target  $FS$  values for different slope inclinations are shown in Table 2. The investigation will consider a 2:1 slope with three different  $FS$  values, and a  $FS = 1.47$  slope with three different slope inclinations.

In the present work,  $C'$  and  $\tan \phi'$  are assumed to be lognormally distributed. The mean value of  $C'$  can be retrieved from the values in Table 2 as  $\mu_{C'} = \mu_c / (\gamma H)$ .

Since  $\beta$  is defined in the normal space, transformations of Eqn. (2) and (3) need to be applied and the optimization will be performed in normal space. The five sample points in the normal space will be  $\mu_{\ln C'} - \sigma_{\ln C'}$ ,  $\mu_{\ln C'}$ ,  $\mu_{\ln C'} + \sigma_{\ln C'}$ ,  $\mu_{\ln(\tan \phi')}$ ,  $\mu_{\ln(\tan \phi')} - \sigma_{\ln(\tan \phi')}$ , and  $\mu_{\ln(\tan \phi')}$ .

Since these sample points depend on the input coefficient of variation, five deterministic analyses need to be performed for each  $\nu$ . In the present study, for the sake of simplicity, the coefficients of variation relating to cohesion and friction are assumed to be equal, thus

$$\nu = \nu_{C'} = \nu_{\tan \phi'} \quad (15)$$

It may be noted that since the five deterministic analyses must be performed in the real space, actual properties were retrieved by raising  $e$  (the base of the natural logarithm) to the five sample points mentioned above. The coefficients of the limit state function for the case when  $\nu = 0.5$  used in Eqs. (13) and (14) are shown in Table 3.

Some investigators (e.g. Rackwitz 2000) believe that the cross-correlation  $\rho$  between  $\ln C'$  and  $\ln(\tan \phi')$  is negative, however, this is still a controversial area in need of more realistic data. Since a positive cross correlation coefficient ( $\rho$ ) between  $\ln C'$  and  $\ln(\tan \phi')$  gives higher values of  $p_f$  and is therefore conservative,  $\rho$  is initially assigned a value of 0.5, although other values in the range  $-0.5 < \rho < 0.5$  are considered later in this paper.

For the case of  $\nu = 0.5$ , the limit state functions for the 2:1 slope with three different  $FS$  values (based on the mean) are shown in the standard normal space along with contours of  $\beta$  in Fig. 3. Also shown in Fig. 3 are the three contours of  $\beta$  that just

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4 touch the three limit state functions corresponding to  $FS=1.25$  ,  $FS=1.47$  and  
5  $FS=1.70$  indicating reliability indices of 0.2750, 0.6892 and 1.0396 respectively. The  
6 corresponding  $p_f$  are thus determined using Eq. (10) to be 0.392, 0.245 and 0.149. It  
7 should be noted that in this standard normal plotting space, the contours of  $\beta$  are  
8 functions only of  $\rho$  , while the limit state function lines are functions of  $FS$  and  $\nu$  . The  
9 corresponding plot in real space is shown in Fig. 4. In this plotting space, the contours of  
10  $\beta$  are now functions of  $FS, \nu$  and  $\rho$  , while the limit states remain functions of  
11  $FS$  and  $\nu$  . The proximity of the limit state functions to each other in the real space is  
12 striking. Two of the lines are almost identical.

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20 Fig. 5 shows the influence of  $\nu$  on the limit state function in the standard normal space for  
21 the case of  $FS=1.47$  . It can be seen that larger values of  $\nu$  result in the limit state  
22 function being closer to the mean value, indicating lower  $\beta$  and higher  $p_f$  values.

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27 The limit state functions in standard normal space for three different slope inclinations  
28 are shown in Fig. 6 for the case when  $FS=1.47$  . The  $\beta=0.6892$  contour is exactly  
29 tangent to the 2:1 limit state line, but almost tangent to the other two lines, emphasizing  
30 again that the slope inclination makes little difference to  $p_f$  for slopes with the same  
31  $FS$  (based on the mean). Table 4 summarizes the computed  $p_f$  for all cases considered.

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36 The influence of  $\rho$  on slope probability of failure has also been investigated in this  
37 paper. Results shown in Table 5 indicate that when the mean values are on the safe side  
38 of the limit state function  $p_f < 0.5$  positive  $\rho$  is conservative because it gives  
39 higher probabilities of failure than negative  $\rho$  . If the equivalent normal mean values lie  
40 in the unsafe side of the limit state function  $p_f > 0.5$  however, the opposite is true,  
41 with positive  $\rho$  giving lower probabilities of failure. The explanation lies in the fact  
42 that irrespective of the location of the equivalent normal mean values relative to the limit  
43 state function, positive  $\rho$  always results in the  $\beta$  contours touching the limit state  
44 function at lower absolute values of  $\beta$  than when  $\rho$  is negative. Since  $\beta$  is  
45 interpreted as being positive when  $p_f < 0.5$  and negative when  $p_f > 0.5$  , Eq. (10) will  
46 lead to lower  $p_f$  when  $\rho$  is positive since the resulting  $\beta$  will be less negative than  
47 when  $\rho$  is negative.

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56 Figs. 7 and 8 show the influence of  $\rho$  when  $\nu=0.5$  and  $\nu=1.5$  . The mean values lie  
57 in the safe region when  $\nu=0.5$  and the unsafe region when  $\nu=1.5$  .

## Random finite element method

In this section, the results of full nonlinear RFEM analyses with Monte-Carlo simulations are compared with results from FORM.

The RFEM involves the generation and mapping of a random field of properties onto a finite element mesh. The current on-line RFEM codes have implemented only normal, lognormal and bounded distributions (Fenton and Griffiths, 2008). There is no restriction however on the type of distribution that could be modeled by RFEM, providing a normal transformation is available (e.g. Fig. 5 in Low and Tang 2007). Since the random field in RFEM is generated in the underlying normal space, it is easy to map this normal distribution to some other distribution types. Full account is taken of local averaging and variance reduction (Fenton and Vanmarcke 1990) over each element, and an exponentially decaying (Markov) spatial correlation function is incorporated. The random field is initially generated and properties assigned to the elements. After application of gravity loads, if the algorithm is unable to converge within a user-defined iteration ceiling (see e.g. Griffiths and Lane 1999), the implication is that no stress distribution can be found that is simultaneously able to satisfy both the Mohr-Coulomb failure criterion and global equilibrium. If the algorithm is unable to satisfy these criteria failure is said to have occurred. The analysis is repeated numerous times using Monte-Carlo simulations. Each realization of the Monte-Carlo process involves the same mean, standard deviation and spatial correlation length of soil properties, however the spatial distribution of properties varies from one realization to the next. Following a “sufficient” number of realizations, the  $p_f$  can be easily estimated by dividing the number of failures by the total number of simulations. The analysis has the option of including cross correlation between properties and anisotropic spatial correlation lengths (e.g. the spatial correlation length in a naturally occurring stratum of soil is often higher in the horizontal direction). Further details of RFEM can be found in Griffiths and Fenton (2004) and Fenton and Griffiths (2008).

A typical mesh is shown in Fig. 2, which has 910 finite elements, and thus contains 910 random variables for an undrained  $\phi_u = 0$  slope and 1820 for a drained  $c', \phi'$  slope. Two thousand simulations were used in most cases, while five thousand simulations were used for high spatial correlation lengths ( $\Theta \geq 1.0$ ) and high input coefficients of variation ( $v \geq 1.0$ ). The aim of this paper is to find  $v_{crit}$ , and the minimum corresponding value of  $p_f$  observed in the parametric studies was about 10%. If the maximum error of  $p_f$  is

0.01 at a confidence level 90%, the required number of realization is 2435 (see e.g., Fenton and Griffiths 2008). It can therefore be said that 2000 simulations is nearly adequate to achieve this target error bound. The CPU time depends on  $p_f$  and runs to about 10 minutes if  $p_f = 0$  and two hours if  $p_f = 1$  (every simulation hits the iteration ceiling) on a T7700@2.4GHz laptop for two thousand simulations.

Undrained  $\phi_u = 0$  slope

The value of  $\mu_{C_u}$  was fixed at  $C_{u,FS=1.47}$ , while  $v_{C_u}$  was varied in the range  $v_{C_u} = 0.1, 0.2, \dots, 1.0$ , and  $\Theta_{C_u}$  was varied in the range  $\Theta_{C_u} = \{1/32, 1/16, \dots, 4\}$ . Figs. 9, 10 and 11 show the probability of failure estimated by RFEM for the three slopes compared with the  $\Theta_{C_u} = \infty$  result obtained by FORM or Monte-Carlo simulations.

It can be seen that ignoring spatial variation underestimates the probability of failure when  $v_{C_u}$  is relatively high and overestimates the probability of failure when  $v_{C_u}$  is relatively low. The intersections of the  $\Theta_{C_u} = \infty$  line with other lines gives the  $v_{crit}$  at which the  $\Theta_{C_u} = \infty$  approach (i.e. no spatial variation) ceases to be conservative. A plot of  $v_{crit}$  verses  $\Theta_{C_u}$  is shown in Fig. 12. It can be seen that ignoring spatial variation will underestimate the probability of failure at lower values of  $v_{crit}$  for steeper slopes than for flatter slopes. In the case of steeper slopes  $v_{crit}$  could be as low as 0.27. Typical ranges of  $v_{C_u}$  as reported for example by Lee et al. (1983), Lacasse and Nadim (1996) and Lumb (1974) are 0.05~0.5. It may be noted that from Fig. 12 that ignoring spatial variation will always underestimate  $p_f$  for a 1:1 slope when  $\Theta_{C_u} > 0.5$ .

If spatial variation is ignored, the slope inclination made no difference to  $p_f$  if  $FS$  (based on the mean) is the same in all cases, but using RFEM, the  $p_f$  of a steeper slope was higher than that of flatter slope. The reason for this is that RFEM allows the failure mechanism to “seek out” the most critical path through the heterogeneous soil mass. For flatter undrained slopes, the failure mechanism is nearly always deep and passes through the foundation soils. For steeper slopes, the failure mechanism has more choice, and may go through the toe or pass through the deeper foundation soils, leading to a higher  $p_f$ .

In order to investigate the influence of the factor of safety on a single slope, similar computations were carried out for 2:1 slopes with  $\mu_{C_u} = C_{u,FS=1.25}$  and  $\mu_{C_u} = C_{u,FS=1.70}$ . Results in Fig. 13 show that ignoring spatial variation will underestimate the probability

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4 of failure at lower values of  $v_{crit}$  for low  $FS$  slopes than high  $FS$  slopes, where  $FS$  is  
5 based on the mean.  
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9 It should be noted that the  $v_{crit}$  corresponding to  $\Theta_{C_u} = 0.0$  in each case was obtained  
10 analytically from Eq. (8). The  $v_{crit}$  in these cases is the value that causes the median to  
11 equal  $C_{u,FS=1.0}$ .  
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16 Drained  $C' - \tan \phi'$  slope  
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18 The spatial correlation lengths of  $C'$  and  $\tan \phi'$  are assumed to be the same. That is  
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$$\Theta = \Theta_{C'} = \Theta_{\tan \phi'} \quad (16)$$

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23 and all other parameters are varied in the same range as in the previous section. Figs. 14,  
24 15 and 16 show the probability of failure computed by RFEM for the three slopes with  
25 the  $\Theta = \infty$  results obtained by FORM or Monte-Carlo simulations.  
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29 It can be seen from Figs. 14, 15 and 16 that the slope inclination has little influence on  
30 the  $p_f$  and that ignoring spatial variation underestimates the probability of failure when  
31  $v$  is relatively high and overestimates the probability of failure when  $v$  is relatively  
32 low. The intersections of the  $\Theta = \infty$  line with other lines give the  $v_{crit}$  above which the  
33  $\Theta = \infty$  approach (i.e. ignoring spatial variation) ceases to be conservative. The  $v_{crit}$   
34 verses  $\Theta$  relationship is plotted in Fig. 17 which demonstrates that the  $v_{crit}$  is almost  
35 independent of the slope inclination. This is different from the undrained slope where  
36  $v_{crit}$  was lower for steeper slopes. RFEM results are less sensitive to slope inclination,  
37 and more like those given by ignoring spatial variation for drained  $c', \phi'$  slopes than  
38 undrained slopes, because the failure mechanism for nearly all slope inclinations tends to  
39 pass through the toe.  
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49 In order to investigate the influence of the factor of safety (based on the means), similar  
50 computations were carried out for 2:1 slopes with  $FS = 1.25$  and  $FS = 1.70$ . Results in  
51 Fig. 18 show that  $v_{crit}$  is lower for low  $FS$  slopes (based on the mean). This is a  
52 similar trend to that observed for undrained slopes.  
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57 Finally, the influence of the cross correlation between  $\ln C'$  and  $\ln(\tan \phi')$  was  
58 investigated, for 2:1 slopes by performing additional RFEM runs with  $\rho = 0$  and  
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4  $\rho = -0.5$ . Results in Fig. 19 show that  $v_{crit}$  is lower when  $\ln C'$  and  $\ln(\tan \phi')$  are  
5 positively correlated than when they are negatively correlated. It should be noted that  
6 RFEM always gave the highest  $p_f$  when  $\rho = 0.5$  and the lowest  $p_f$  when  $\rho = -0.5$   
7 irrespective of whether  $p_f > 0.5$  or  $p_f < 0.5$ . Ignoring spatial variation, however, gave  
8 the opposite trend for  $p_f > 0.5$  and  $p_f < 0.5$  as described previously.  
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14 The range of  $v_{\phi'}$  reported, for example by Lee et al. 1983, Lacasse and Nadim 1996 and  
15 Lumb 1974 is 0.02~0.56 (the corresponding range of  $v_{\tan \phi'}$  would be 0.03~0.74 when  
16  $\phi' = 30^\circ$ ). It was observed that  $v_{crit}$  was higher when  $\rho$  was negative than when it was  
17 positive as shown in Fig. 19. Some investigators (e.g. Rackwitz 2000) have suggested  
18 that  $\rho \approx -0.5$ . The minimum  $v_{crit}$  obtained in this paper (based on  $\tan \phi'$ ) is 0.56 for  
19 the 2:1 drained slope with  $FS = 1.25$  and a positive  $\rho = 0.5$ . Lower  $v_{crit}$  values will  
20 be observed in steeper slopes and/or slopes with lower  $FS$ .  
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27 It should be noted that the  $v_{crit}$  corresponding to  $\Theta = 0.0$  can be obtained analytically.  
28 As shown in Eq. (8), in the limit as  $\Theta \rightarrow 0$ , local averaging removes all variance, and the  
29 mean tends to the Median, thus  
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$$32 \mu_{C'A} = \frac{\mu_{C'}}{\sqrt{1 + v_{crit}^2}} \quad (17)$$

$$33 \mu_{\tan \phi'A} = \frac{\mu_{\tan \phi'}}{\sqrt{1 + v_{crit}^2}} \quad (18)$$

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40 where the subscript  $A$  denotes a local average. In this case, the slope will be uniform with  
41 the strength parameters set equal to their median as given by equations (17) and (18)  
42 everywhere. The value of  $v_{crit}$  that would give  $FS = 1.0$  can be obtained by  
43 substituting Eqs. (17) and (18) into Eq. (13)  
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$$47 \begin{aligned} & FS \ln \mu_{C'A}, \ln \mu_{\tan \phi'A} \\ & = a_1 + a_2 \ln \left( \frac{\mu_{C'}}{\sqrt{1 + v_{crit}^2}} \right) + a_3 \ln \left( \frac{\mu_{\tan \phi'}}{\sqrt{1 + v_{crit}^2}} \right) + a_4 \left( \ln \left( \frac{\mu_{C'}}{\sqrt{1 + v_{crit}^2}} \right) \right)^2 + a_5 \left( \ln \left( \frac{\mu_{\tan \phi'}}{\sqrt{1 + v_{crit}^2}} \right) \right)^2 \quad (19) \\ & = 1.0 \end{aligned}$$

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54 The five coefficients  $a_1, a_2, \dots, a_5$  depend on  $v$  so an iterative process has been used to  
55 solve Eq. (19). The solution gives the value of  $v_{crit}$  below which  $p_f = 0$  and above  
56 which  $p_f = 1$ .  
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## Concluding remarks

The paper has investigated the probability of slope failure using FEM combined with FORM without spatial variation and more advanced (RFEM) probabilistic analysis tools. The term RFEM denotes FEM combined with Monte-Carlo simulation with spatial variation properly taken into accounts. The RFEM enables the failure mechanism to “seek out” the weakest path through the heterogeneous soil mass which can lead to higher probabilities of failure than would be predicted by ignoring spatial variation. The numerical studies have shown that ignoring spatial variation will lead to unconservative estimates of the probability of slope failure if the coefficient of variation of the input shear strength parameters exceeds a critical value  $v_{crit}$ . The lower the value of  $v_{crit}$ , the more likely it is that ignoring spatial variation will underestimate the probability of failure for typical ranges of soil variability. The paper has presented graphs to indicate the magnitude of  $v_{crit}$  for different parametric combinations, from which readers can decide whether ignoring spatial variation (i.e., assuming perfect spatial correlation) is appropriate and conservative for use with their specific soil parameters. The lognormal distribution as used in this study is believed to be a reasonable model of soil strength although a thorough comparison of distribution types in the context of RFEM is a topic for future research.

In summary:

1.  $v_{crit}$  is lower for slopes with low factors of safety (based on the mean) than for slopes with high factors of safety.
2.  $v_{crit}$  is lower for steeper slopes than less steep slopes under undrained  $\phi_u = 0$  conditions. Slope steepness was found to have little influence on  $v_{crit}$  in drained  $c', \phi'$  slopes.
3.  $v_{crit}$  is lower if the strength parameters  $c'$  and  $\tan \phi'$  are positively correlated than if they are negatively correlated.



## Notation

The following symbols are used in this paper:

$c'$	drained cohesion
$c_u$	undrained cohesion
$C'$	dimensionless drained cohesion
$C_u$	dimensionless undrained cohesion
$C_{u,FS=1}$	dimensionless undrained cohesion when $FS = 1.0$
$C_{u,FS=1.25}$	dimensionless undrained cohesion when $FS = 1.25$
$C_{u,FS=1.47}$	dimensionless undrained cohesion when $FS = 1.47$
$C_{u,FS=1.70}$	dimensionless undrained cohesion when $FS = 1.70$
$D$	foundation depth ratio
$FS$	factor of safety
$H$	slope height
$m$	constant used for sampling limit state function
$n$	number of random variables
$p_f$	probability of failure
$R$	correlation matrix
$X_i$	random variable
$\alpha$	slope angle
$\beta$	FORM reliability index
$\beta_{HL}$	the Hasofer-Lind reliability index
$\gamma$	soil unit weight
$\gamma_{sat}$	saturated soil unit weight
$\theta_{\ln C_u}$	spatial correlation length of undrained cohesion

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5	$\Theta$	dimensionless spatial correlation length
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7	$\Theta_{C_u}$	dimensionless spatial correlation length of undrained cohesion
8		
9	$\Theta_{C'}$	dimensionless spatial correlation length of drained cohesion
10		
11	$\Theta_{\tan \phi'}$	dimensionless spatial correlation length of drained tangent friction angle
12		
13	$\mu_{C_{uA}}$	mean dimensionless undrained cohesion after local averaging
14		
15	$\mu_{C'A}$	mean dimensionless drained cohesion after local averaging
16		
17	$\mu_{\ln C_u}$	equivalent normal mean of undrained cohesion
18		
19	$\mu_i^N$	equivalent normal mean of the $i^{th}$ random variable
20		
21	$\mu_{\tan \phi'A}$	mean tangent drained friction angle after local averaging
22		
23	$\nu$	coefficient of variation
24		
25	$\nu_{C_u}$	coefficient of variation of dimensionless undrained cohesion
26		
27	$\nu_{C'}$	coefficient of variation of dimensionless drained cohesion
28		
29	$\nu_{\tan \phi'}$	coefficient of variation of tangent drained friction angle
30		
31	$\nu_{crit}$	critical coefficient of variation
32		
33	$\rho$	cross correlation coefficient
34		
35	$\rho \tau$	correlation coefficient between properties assigned to two points
36		
37	$\sigma_{C_u}$	standard deviation of dimensionless undrained cohesion
38		
39	$\sigma_{C_{uA}}$	standard deviation of dimensionless undrained cohesion after local averaging
40		
41	$\sigma_{\ln C_u}$	equivalent normal standard deviation of undrained cohesion
42		
43	$\sigma_i^N$	equivalent normal standard deviation of the $i^{th}$ random variable
44		
45	$\tau$	absolute distance between two points in a random field
46		
47	$\phi_u$	undrained friction angle
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49	$\phi'$	drained friction angle
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51	$\Phi \bullet$	the cumulative standard normal distribution function.
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Table 1.  $p_f$  corresponding to different  $v_{C_u}$  for an undrained slope

$v_{C_u}$	$\mu_{C_u} = C_{u,FS=1.25}$	$\mu_{C_u} = C_{u,FS=1.47}$	$\mu_{C_u} = C_{u,FS=1.70}$
0.1	0.014	0.0	0.0
0.2	0.152	0.032	0.004
0.3	0.270	0.122	0.048
0.4	0.350	0.209	0.118
0.5	0.407	0.281	0.187
0.6	0.450	0.338	0.248
0.7	0.485	0.384	0.300
0.8	0.514	0.422	0.343
0.9	0.538	0.454	0.381
1.0	0.559	0.481	0.412
1.1	0.577	0.505	0.440
1.2	0.593	0.525	0.464
1.3	0.607	0.544	0.485
1.4	0.620	0.560	0.504
1.5	0.632	0.574	0.521

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Table 2 Strength parameters of the five slopes

Slope	<i>FS = 1.25</i>		<i>FS = 1.47</i>		<i>FS = 1.70</i>	
	$\mu_{c'}$	$\mu_{\tan\phi'}$	$\mu_{c'}$	$\mu_{\tan\phi'}$	$\mu_{c'}$	$\mu_{\tan\phi'}$
3:1			15.00	0.21		
2:1	15.73	0.23	18.50	0.27	21.40	0.31
1:1			26.00	0.36		



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Table 3 Coefficients of the limit state function for  $\nu = 0.5$

Slope	$a_1$	$a_2$	$a_3$	$a_4$	$a_5$
2:1, $FS = 1.25$	5.3045	1.6132	1.1186	0.2017	0.1793
2:1, $FS = 1.47$	5.1821	1.5026	1.1212	0.1793	0.1793
2:1, $FS = 1.70$	5.1765	1.5019	1.1204	0.1793	0.1793
3:1, $FS = 1.47$	5.9713	1.5081	1.5442	0.1793	0.2465
1:1, $FS = 1.47$	4.7636	1.8096	0.7733	0.2465	0.1344

Table 4.  $p_f$  corresponding to different  $v$ ,  $FS$  and slope inclinations

$v$	$FS = 1.25$ (2:1 slope)	$FS = 1.47$ (2:1 slope)	$FS = 1.70$ (2:1 slope)	$FS = 1.47$ (3:1 slope)	$FS = 1.47$ (1:1 slope)
0.1	0.007	0.000	0.000	0.000	0.000
0.2	0.124	0.015	0.001	0.018	0.017
0.3	0.231	0.091	0.029	0.085	0.091
0.4	0.331	0.167	0.089	0.166	0.169
0.5	0.392	0.245	0.149	0.247	0.248
0.6	0.438	0.319	0.216	0.318	0.321
0.7	0.479	0.363	0.274	0.363	0.365
0.8	0.513	0.409	0.322	0.410	0.408
0.9	0.546	0.441	0.360	0.441	0.442
1.0	0.571	0.475	0.399	0.475	0.475
1.1	0.585	0.509	0.430	0.500	0.509
1.2	0.608	0.527	0.462	0.527	0.527
1.3	0.622	0.549	0.479	0.548	0.548
1.4	0.639	0.569	0.508	0.568	0.568
1.5	0.650	0.588	0.523	0.586	0.587

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Table 5.  $p_f$  corresponding to different  $\rho$  and  $v$  with  $FS=1.47$  for a 2:1 slope

$v$	$\rho = 0.5$	$\rho = 0.0$	$\rho = -0.5$
0.1	0.000	0.000	0.000
0.2	0.015	0.004	0.000
0.3	0.091	0.051	0.010
0.4	0.167	0.118	0.047
0.5	0.245	0.199	0.116
0.6	0.319	0.282	0.208
0.7	0.363	0.334	0.272
0.8	0.409	0.389	0.345
0.9	0.441	0.428	0.399
1.0	0.475	0.469	0.457
1.1	0.509	0.512	0.516
1.2	0.527	0.533	0.547
1.3	0.549	0.560	0.584
1.4	0.569	0.584	0.618
1.5	0.588	0.607	0.649

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8 Fig. 1. Slope profile  
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10 Fig. 2. Influence of the spatial correlation length in RFEM analysis  
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13 Fig. 3. Limit state functions for a 2:1 slope and  $\beta$  contours in standard normal space  
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16 ( $\nu=0.5, \rho = 0.5$ )  
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19 Fig. 4. Limit state functions for a 2:1 slope and tangent  $\beta$  contours in real space  
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22 ( $\nu=0.5, \rho = 0.5$ )  
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25 Fig. 5. Influence of  $\nu$  on the limit state function for a 2:1 slope with  $FS = 1.47$  (based on  
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27 the means) in standard normal space ( $\rho = 0.5$ )  
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30 Fig. 6. Influence of slope inclination on the limit state functions for a slope with  
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33  $FS = 1.47$  (based on the means) in standard normal space ( $\nu=0.5, \rho = 0.5$ )  
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36 Fig. 7. Influence of  $\rho$  on  $p_f$  for a 2:1 slope with  $FS = 1.47$  (based on the means) in  
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38 standard normal space when  $p_f < 0.5$  and  $\nu = 0.5$  ( $g$  is performance function).  
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41 Fig. 8. Influence of  $\rho$  on  $p_f$  for a 2:1 slope with  $FS = 1.47$  (based on the means) in  
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43 standard normal space when  $p_f > 0.5$  and  $\nu = 1.5$  ( $g$  is performance function).  
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46 Fig. 9. RFEM results giving  $p_f$  of a 3:1 undrained slope with  $FS = 1.47$  (based on  
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48 the mean)  
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51 Fig. 10. RFEM results giving  $p_f$  of a 2:1 undrained slope with  $FS = 1.47$  (based on the  
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5 Fig. 11. RFEM results giving  $p_f$  of a 1:1 undrained slope with  $FS = 1.47$  (based on the  
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10 Fig. 12.  $v_{crit}$  vs.  $\Theta_{C_u}$  for different inclinations of an undrained slope with  $FS = 1.47$   
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14 Fig. 13.  $v_{crit}$  vs.  $\Theta_{C_u}$  for different  $FS$  values (based on the mean) for a 2:1 undrained  
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24 means)  $\rho = 0.5$

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29 means)  $\rho = 0.5$

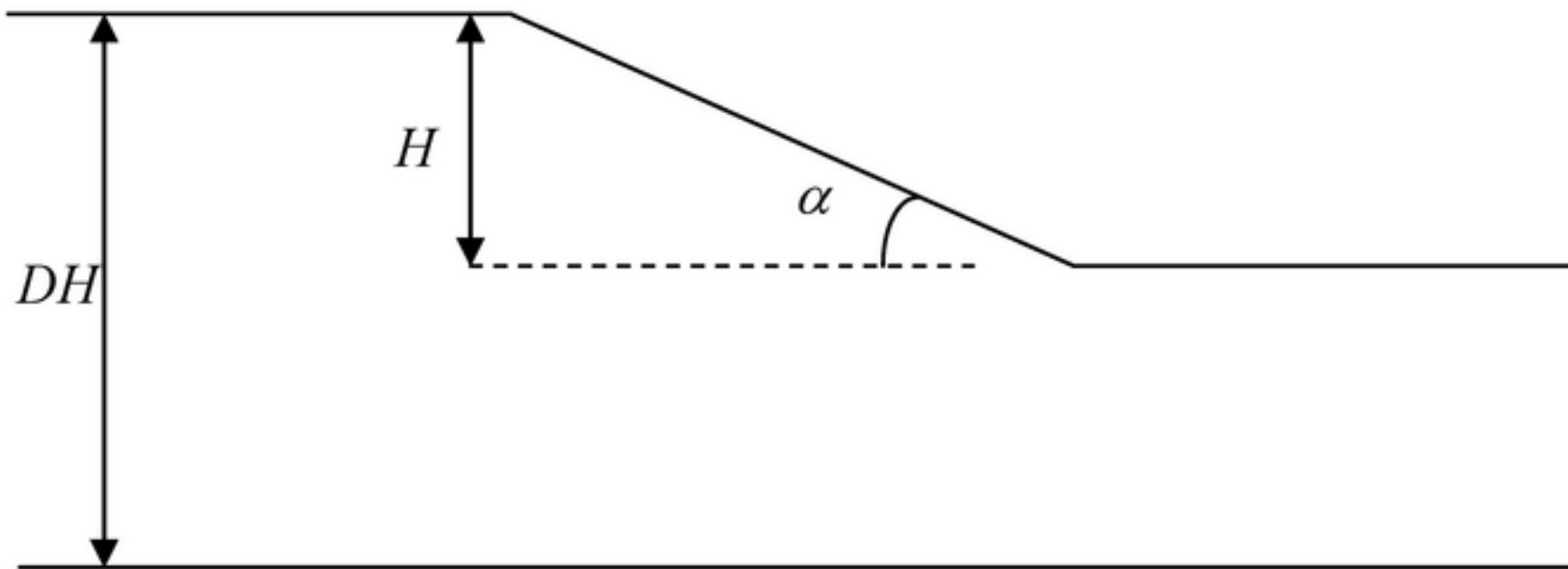
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31 Fig. 16. RFEM results giving  $p_f$  of a 1:1 drained slope with  $FS = 1.47$  (based on the  
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34 means)  $\rho = 0.5$

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36 Fig. 17.  $v_{crit}$  vs.  $\Theta$  for different slope inclinations for a drained slope with  $FS = 1.47$   
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39 (based on the means)  $\rho = 0.5$

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41 Fig. 18.  $v_{crit}$  vs.  $\Theta$  for different  $FS$  values (based on the means) for a 2:1 drained  
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44 slope  $\rho = 0.5$

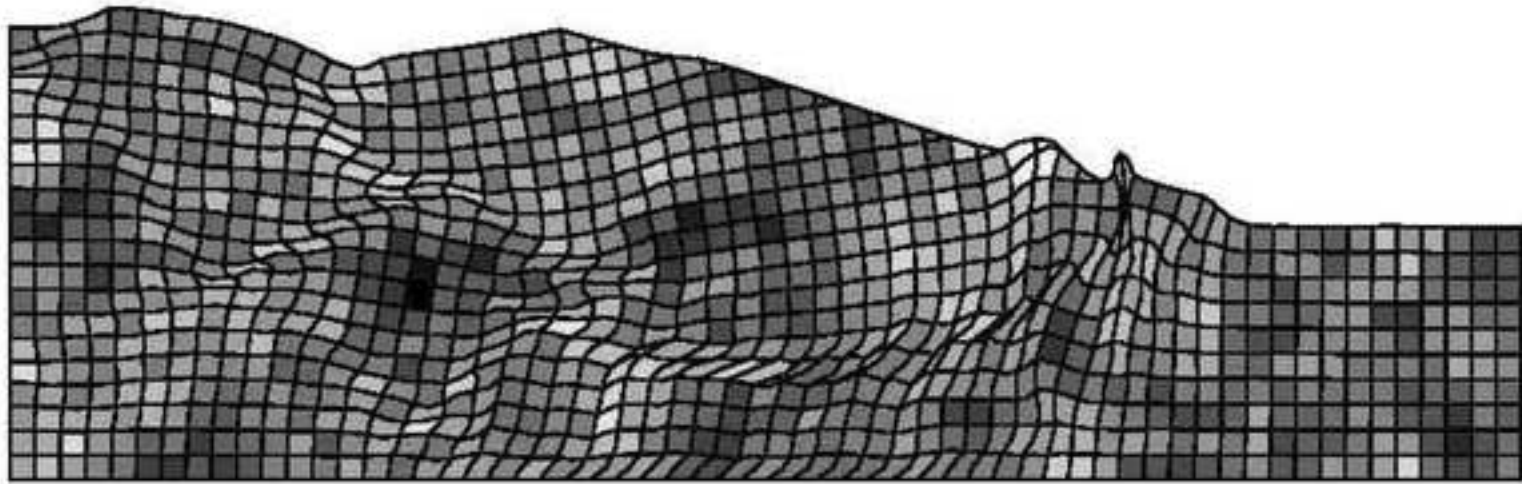
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46 Fig. 19.  $v_{crit}$  vs.  $\Theta$  for different  $\rho$  values for a 2:1 drained slope with  $FS = 1.47$   
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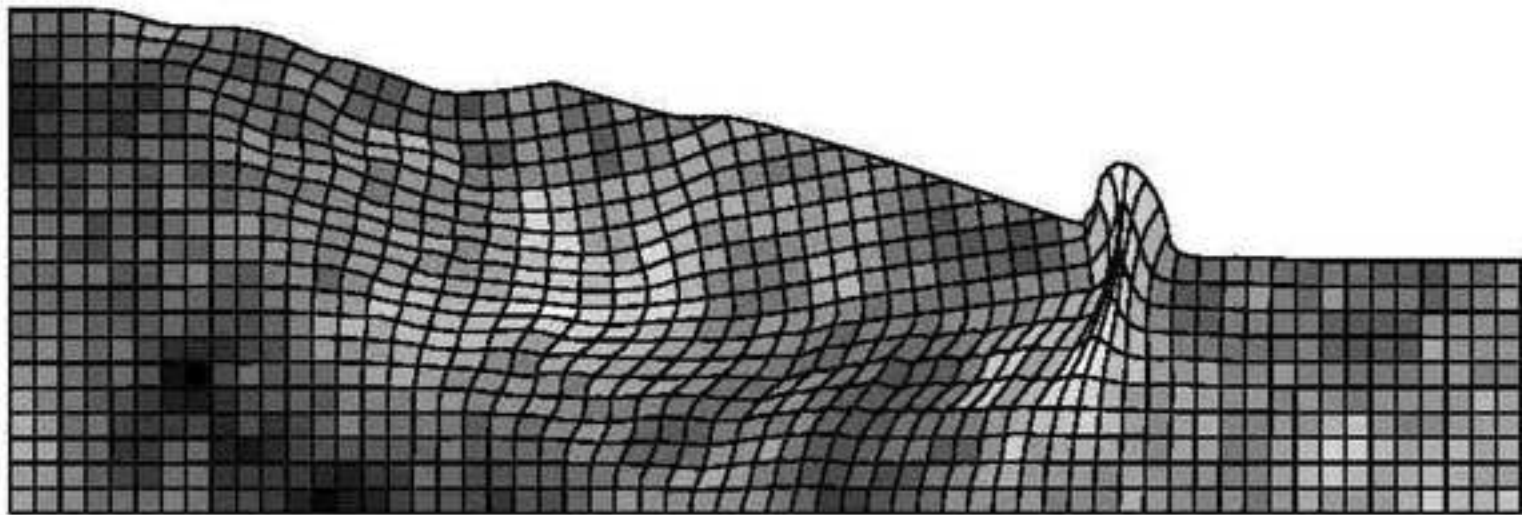


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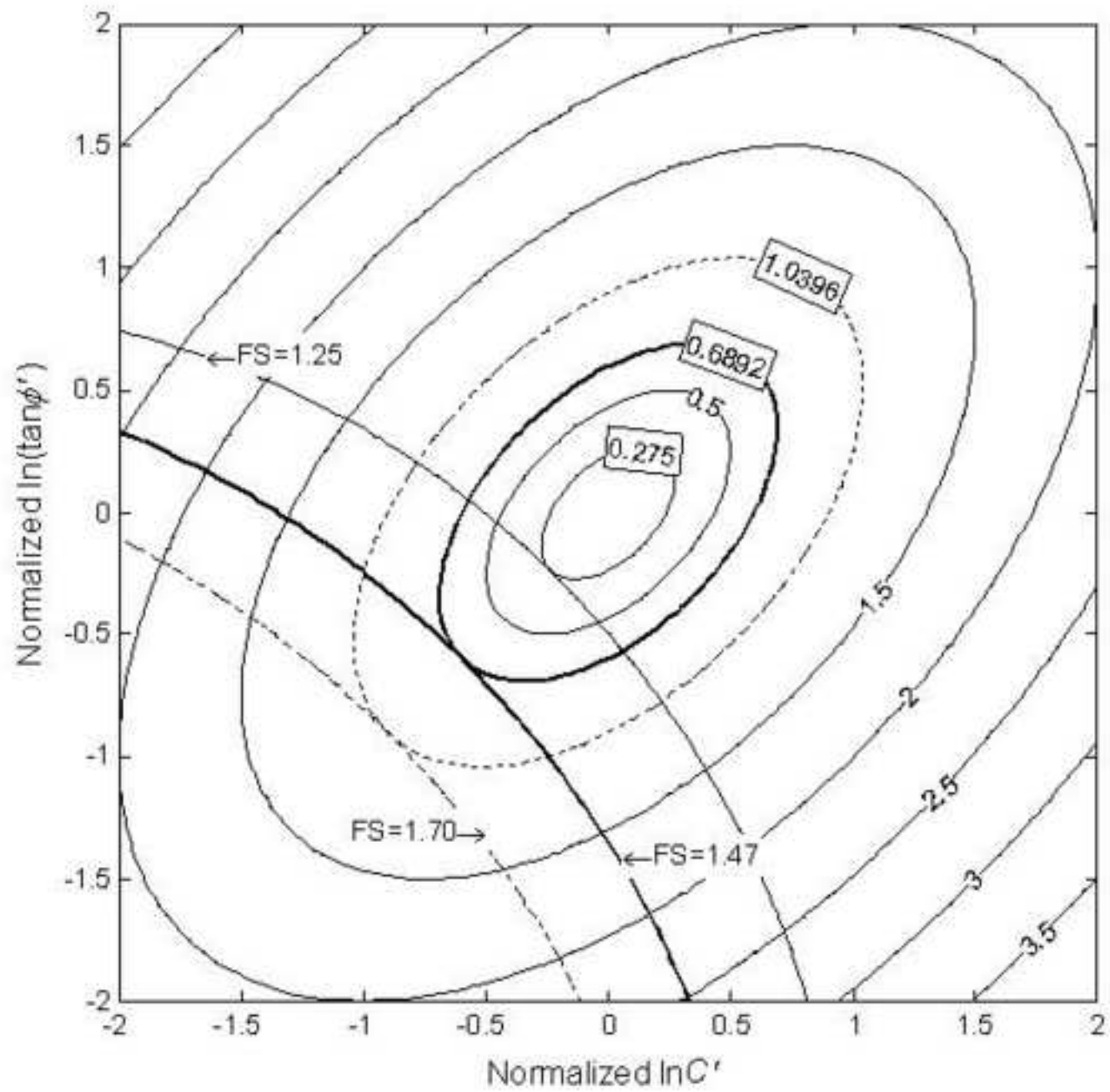


a)  $\Theta_{C_u} = 0.2$



b)  $\Theta_{C_u} = 2$

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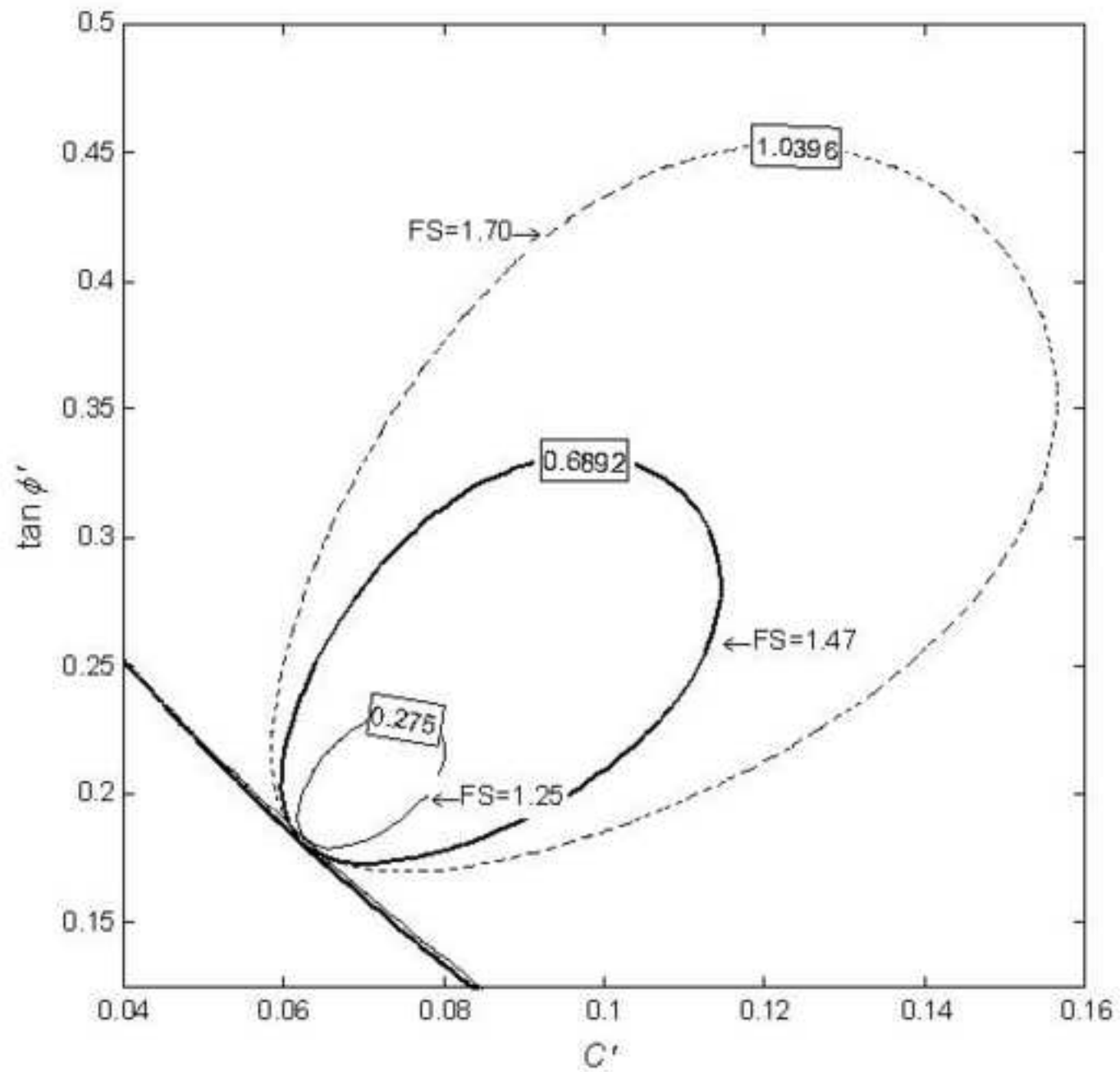


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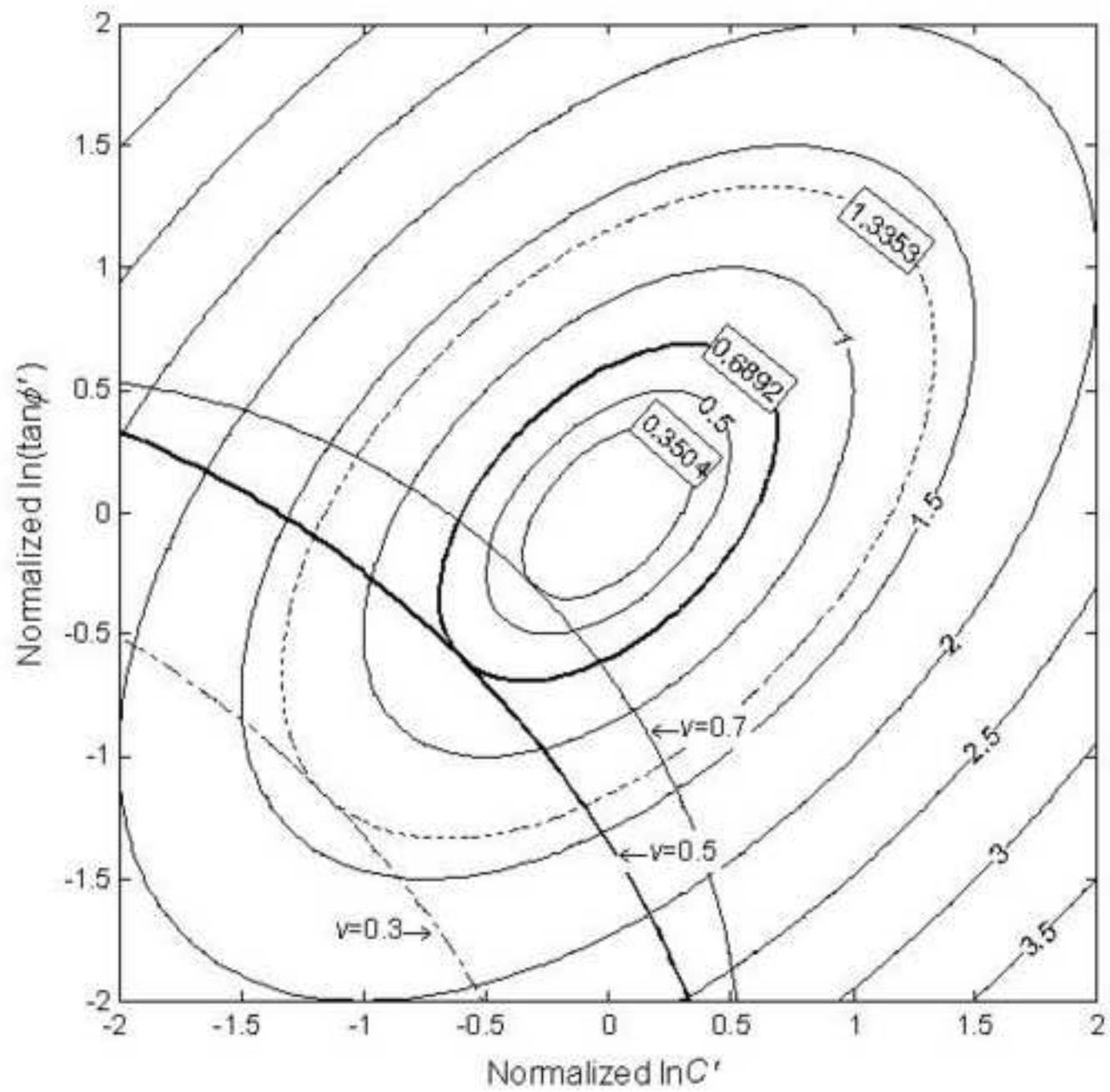


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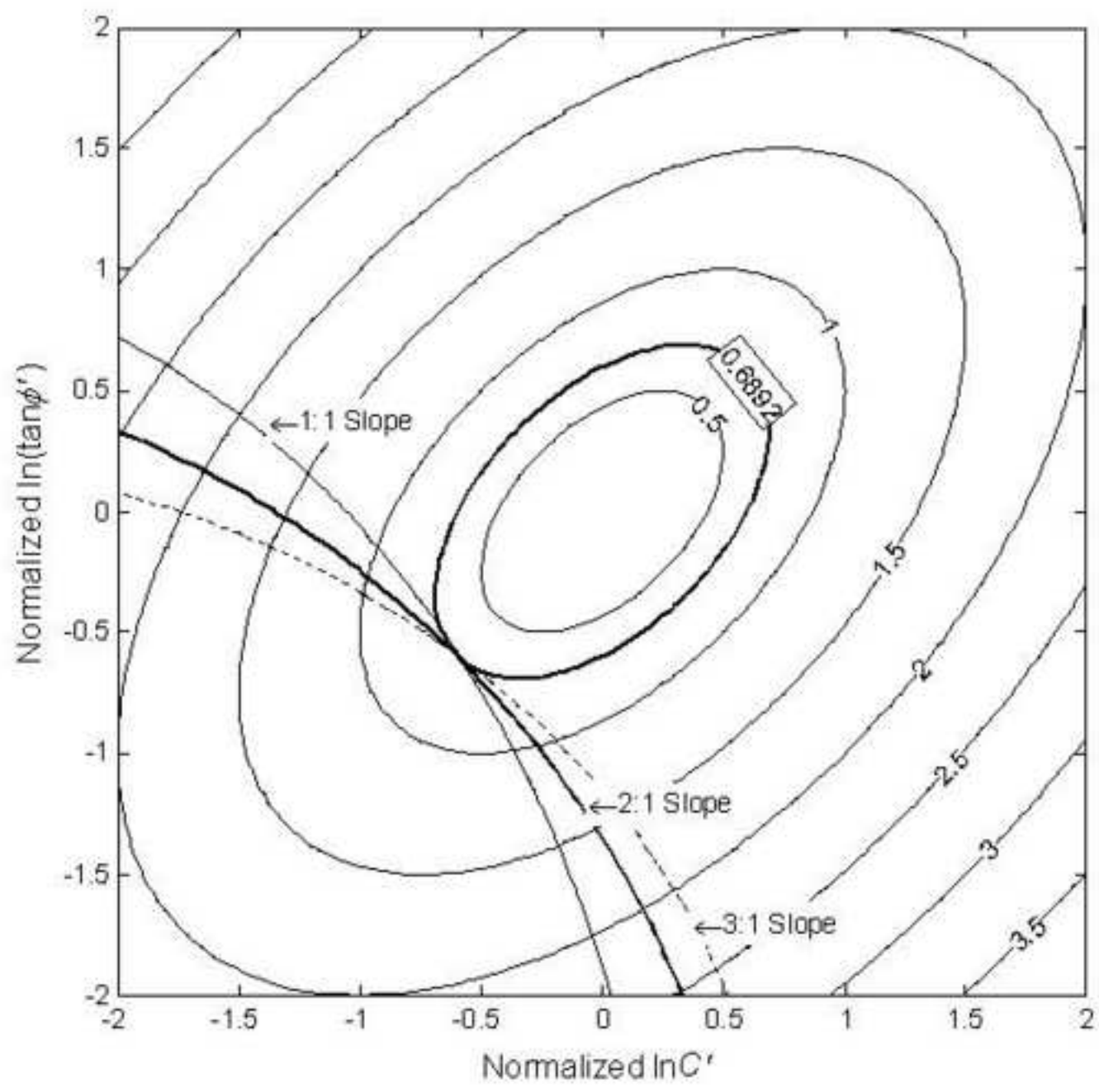


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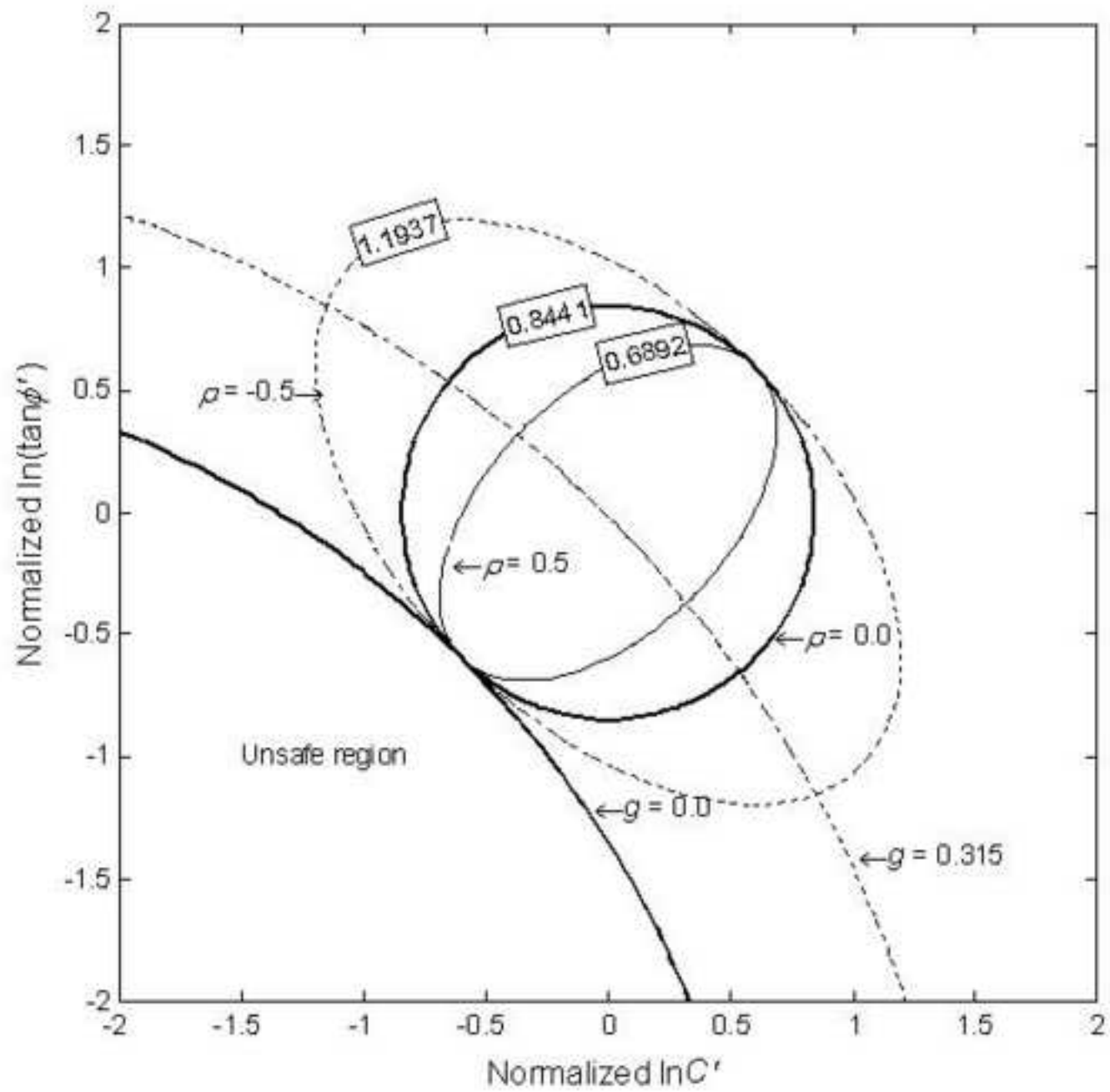


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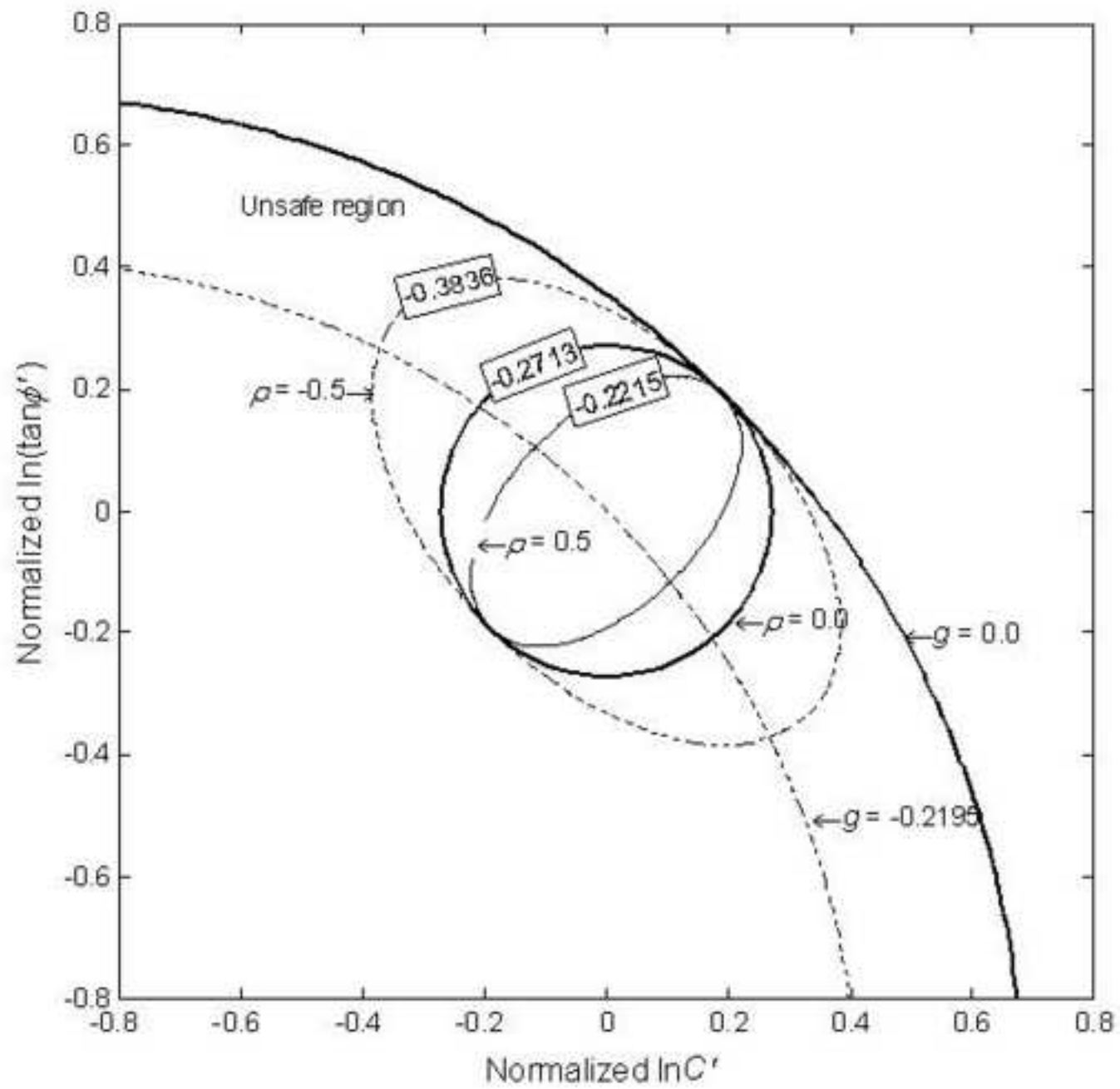


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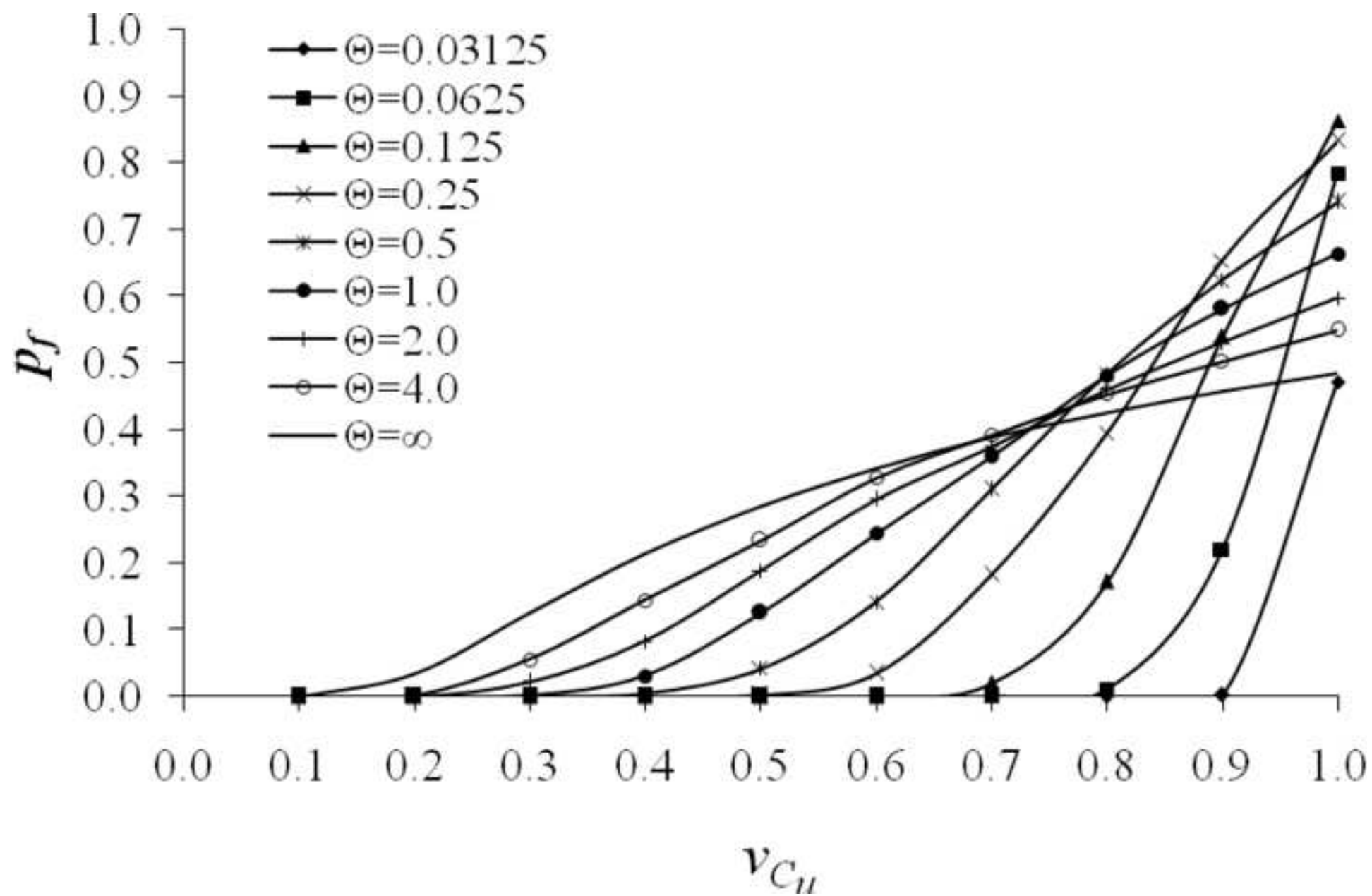


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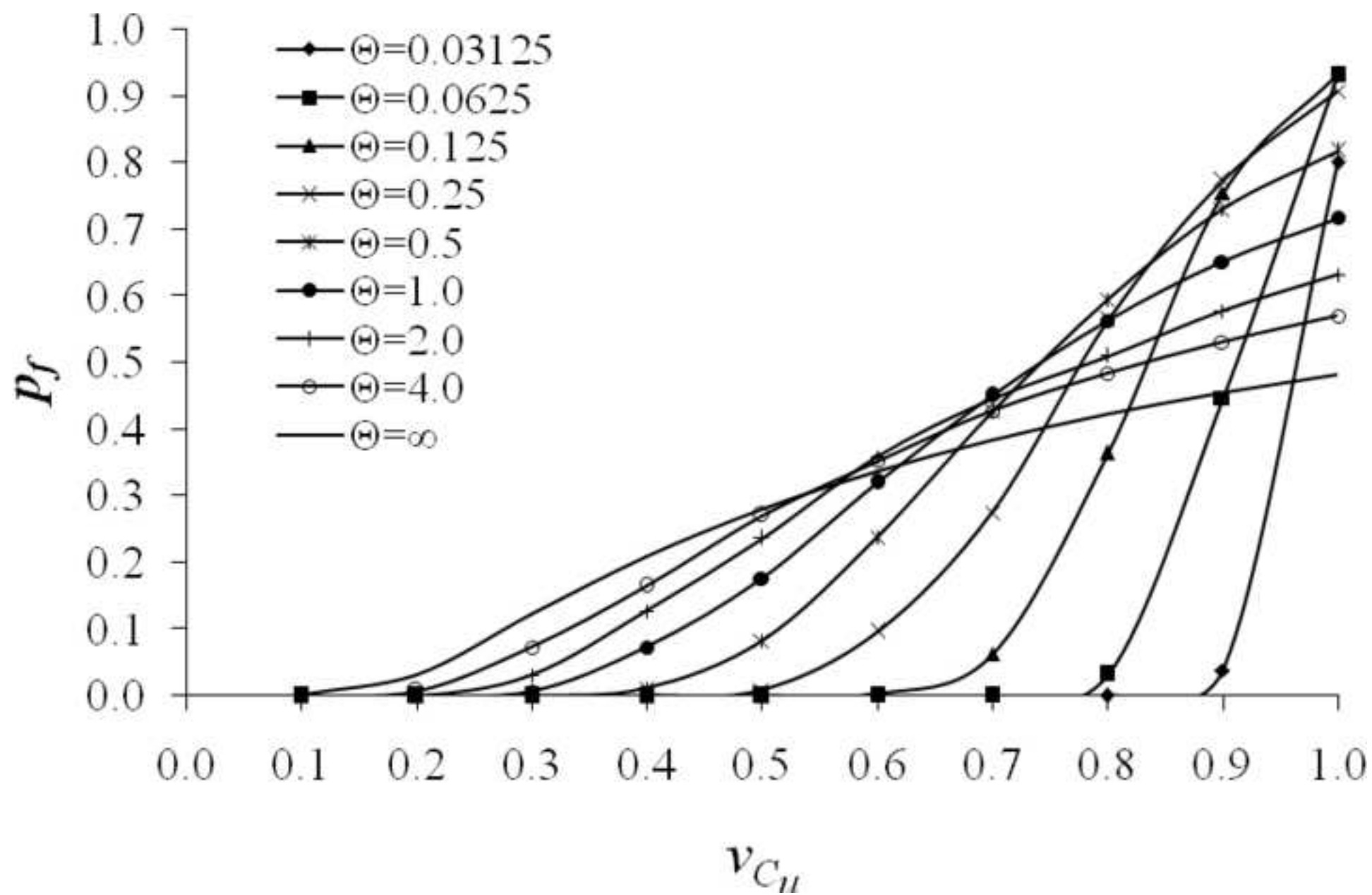






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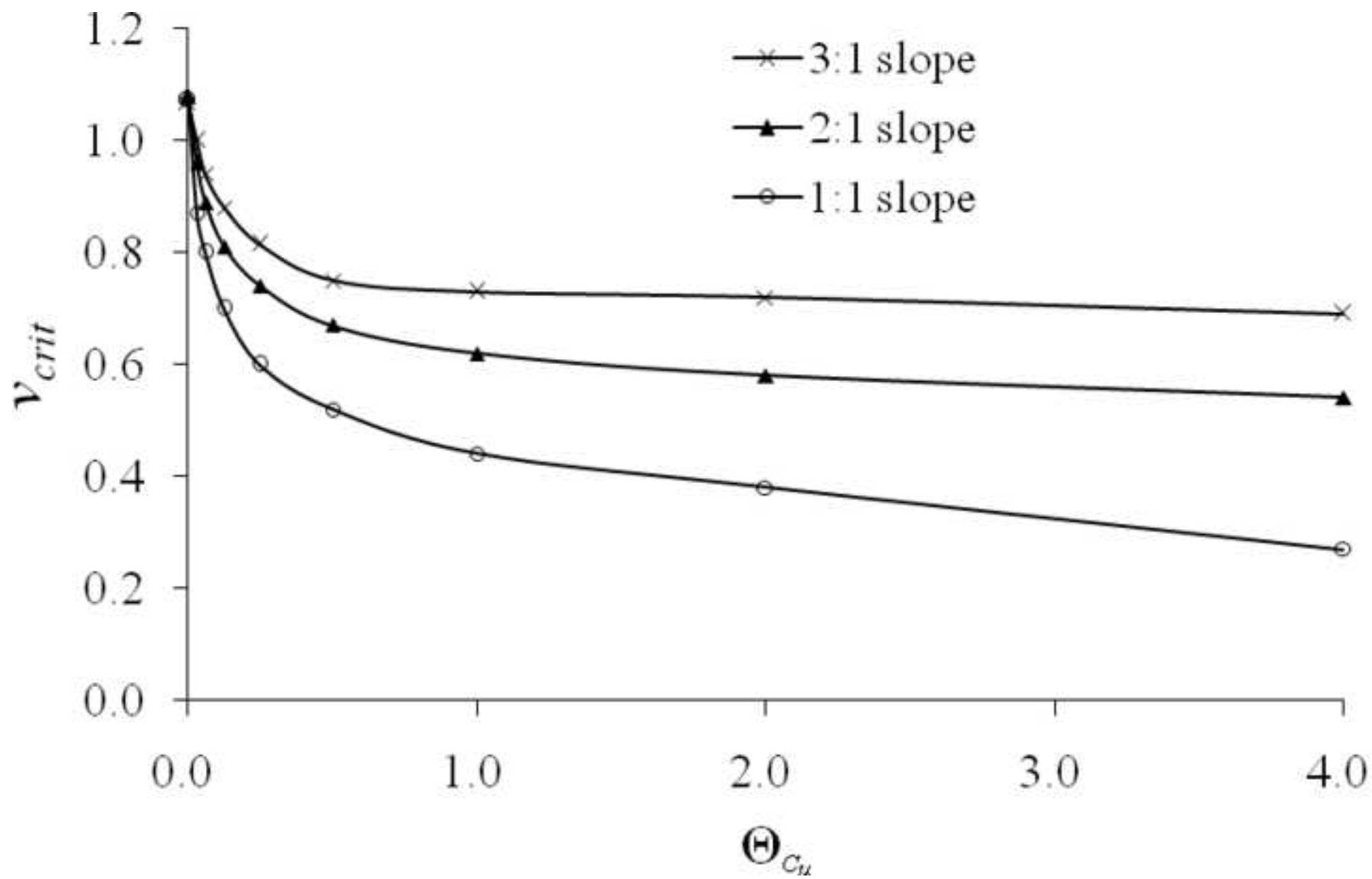


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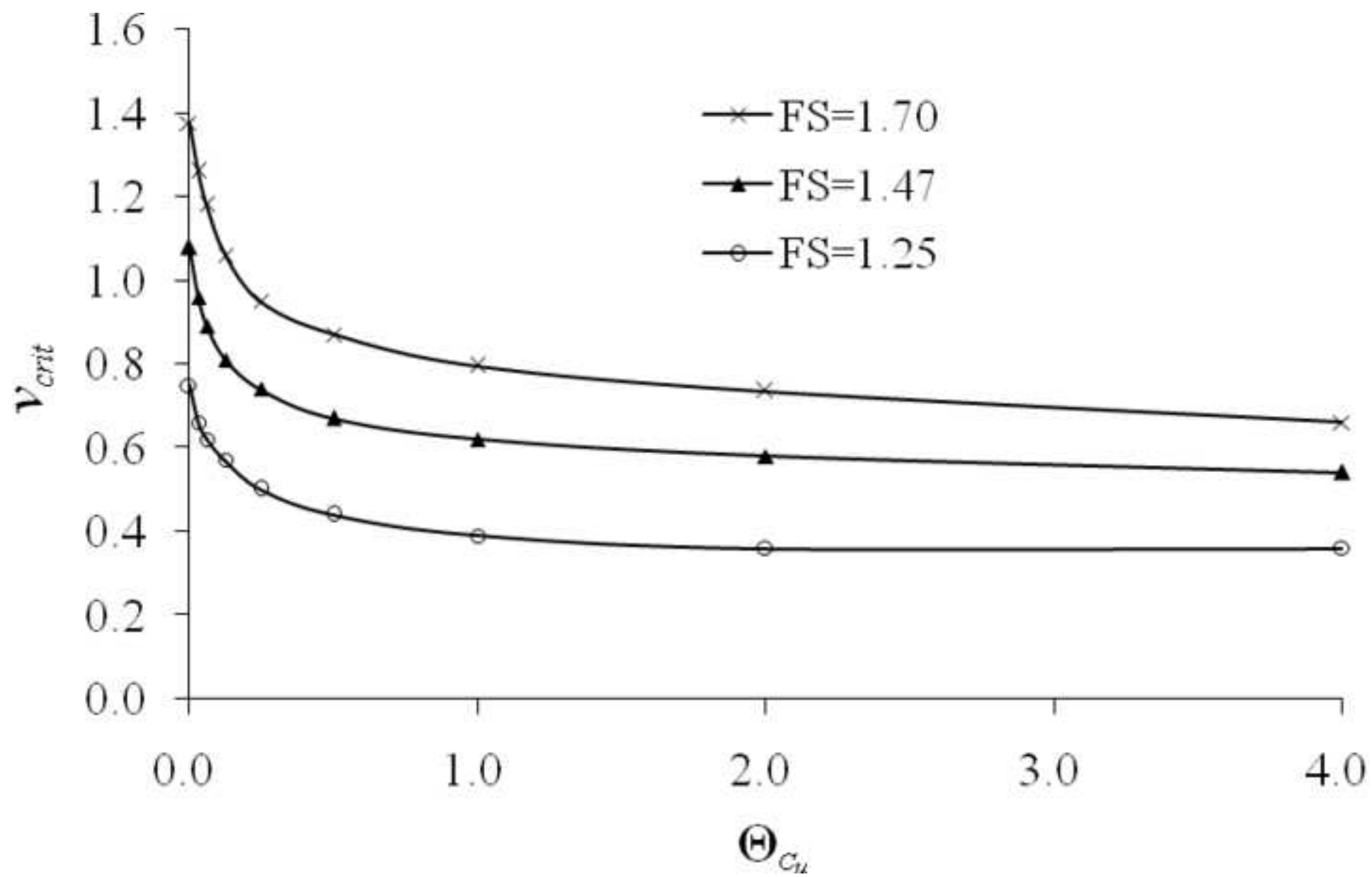


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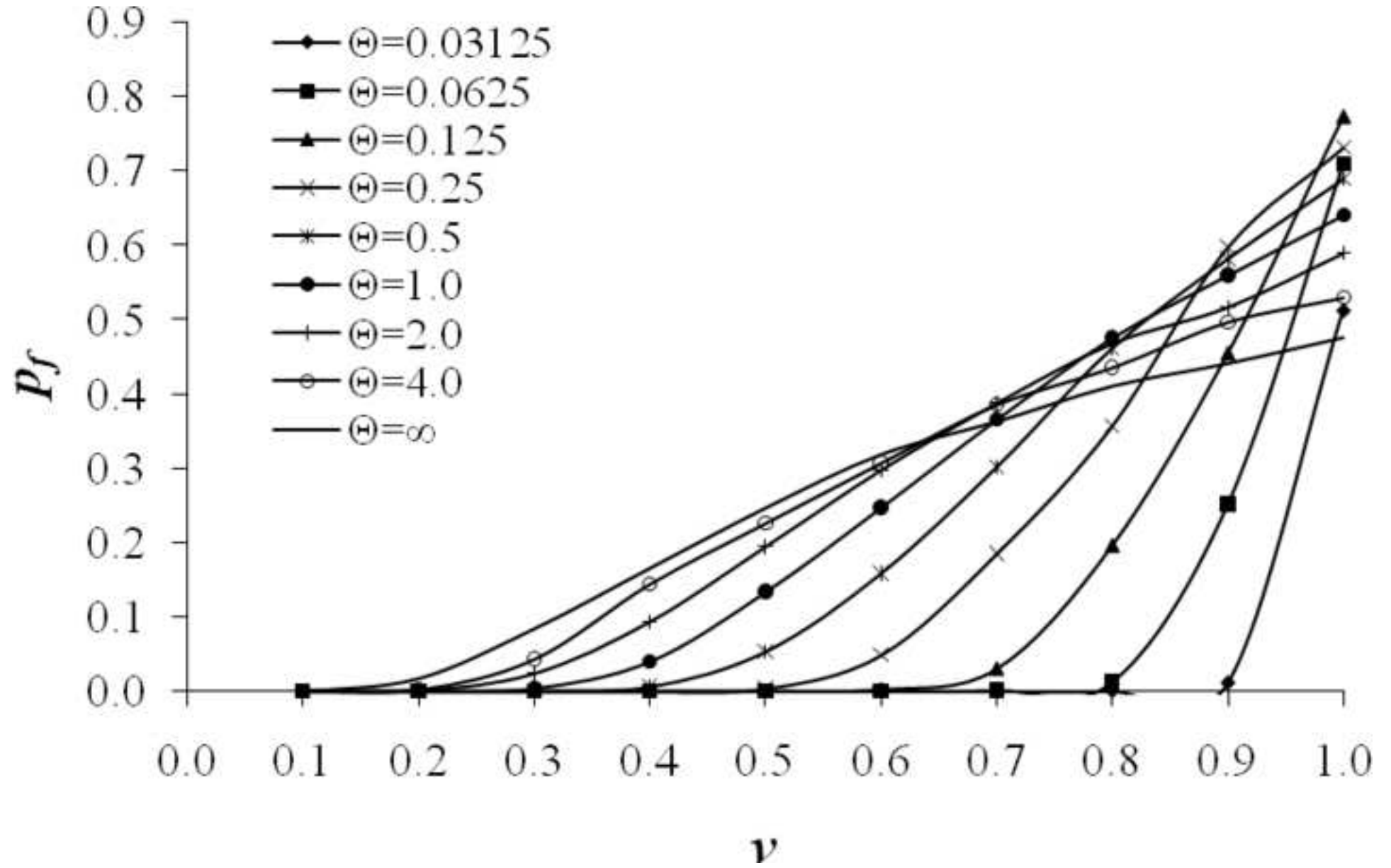


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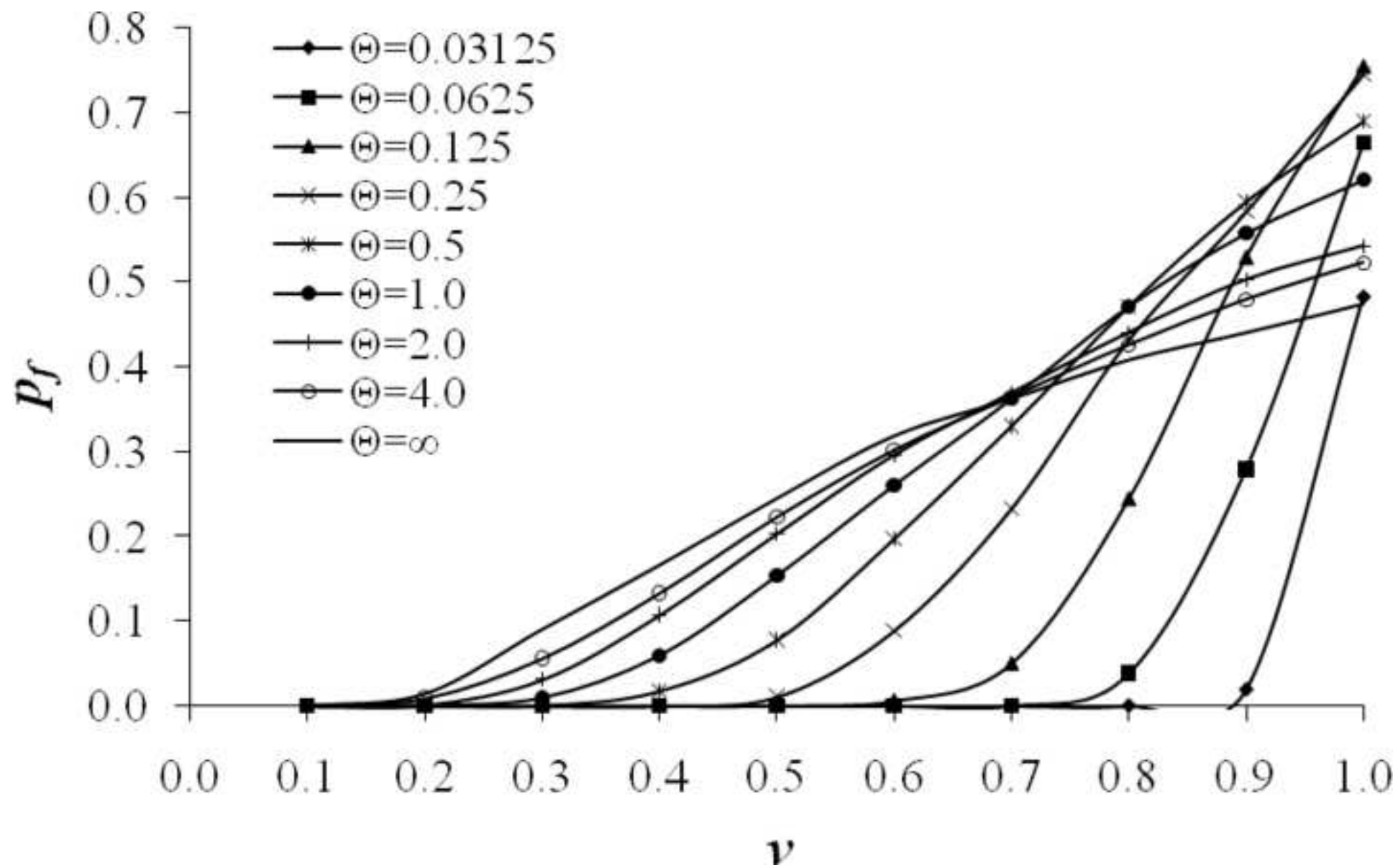


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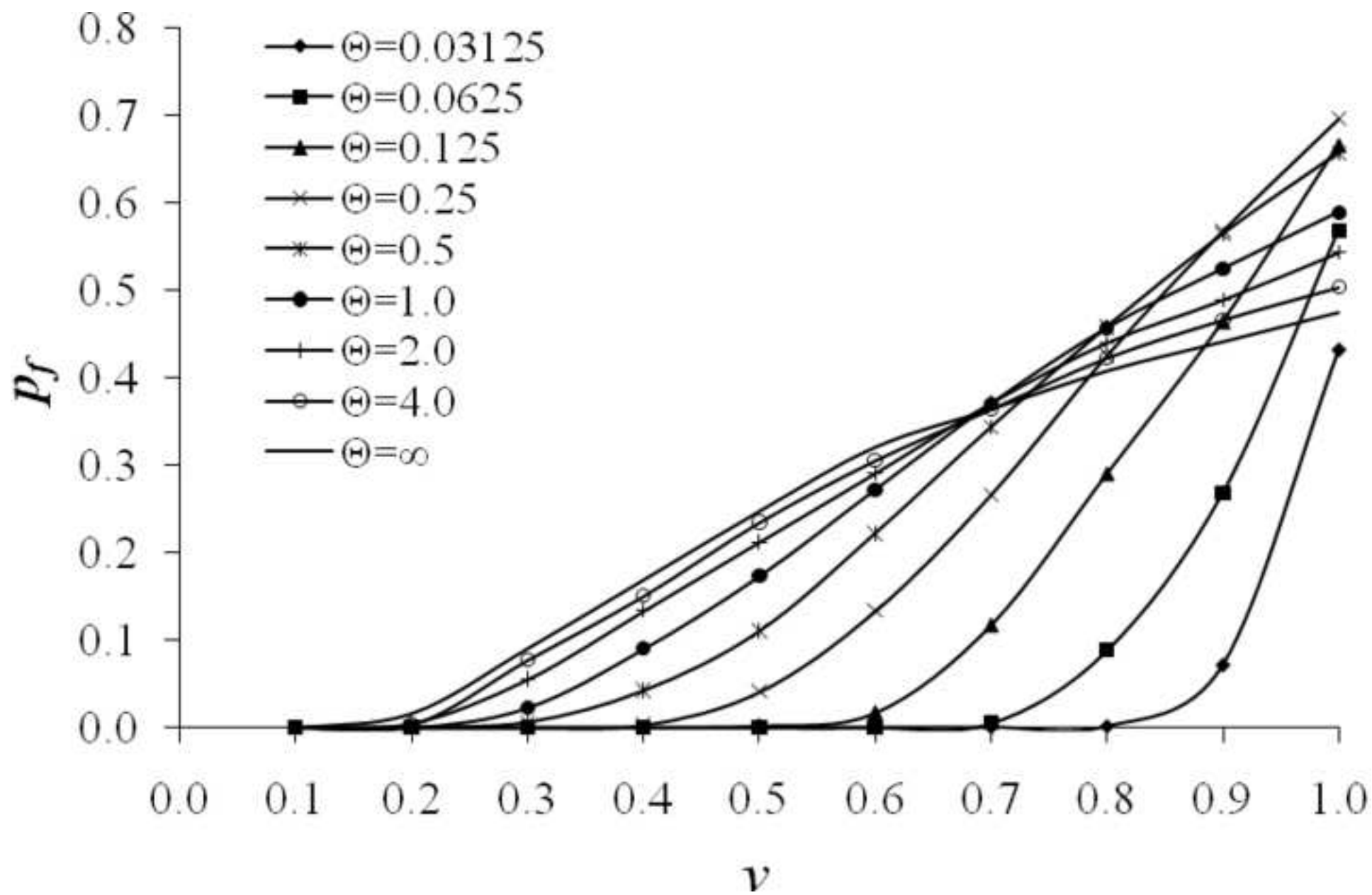


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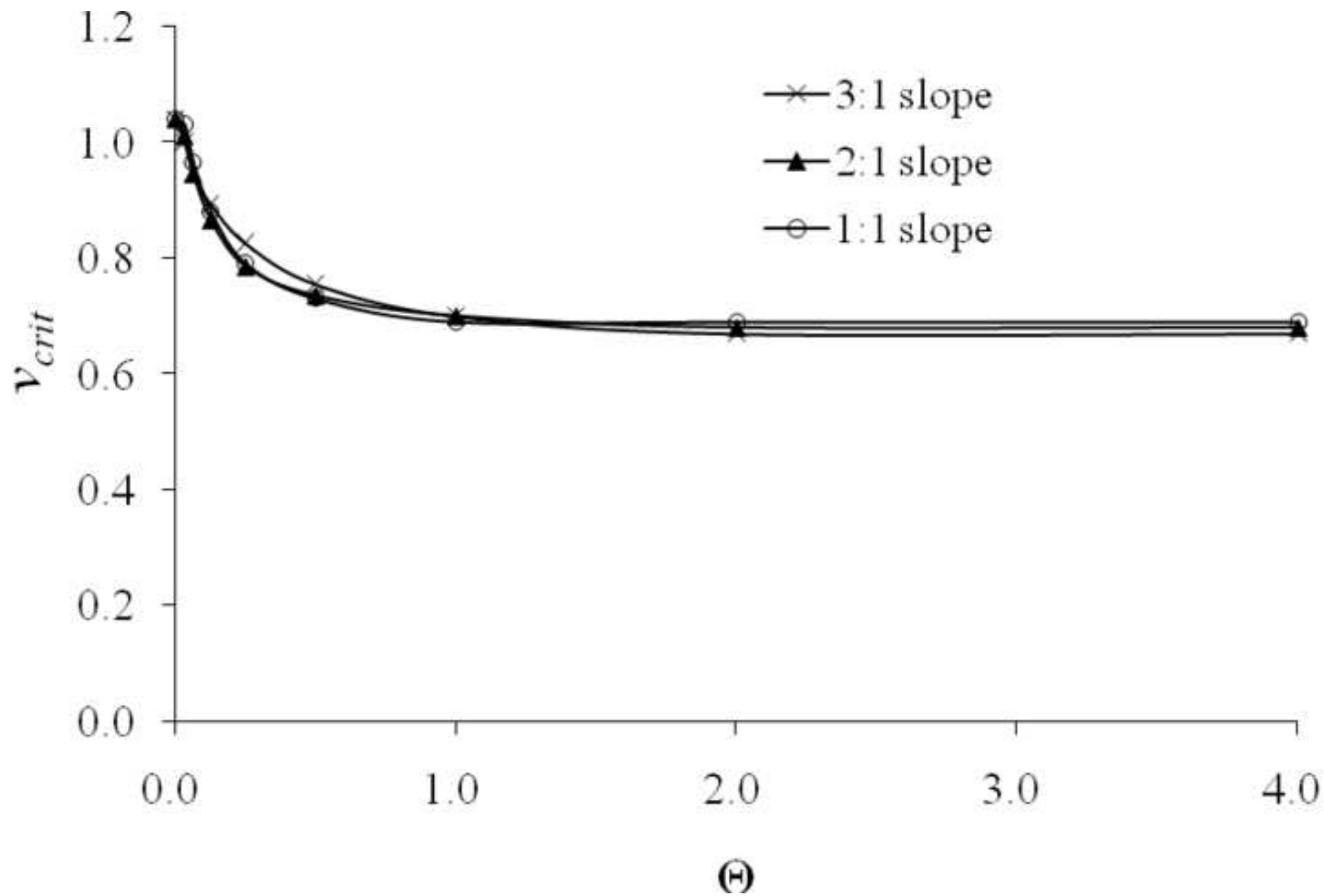


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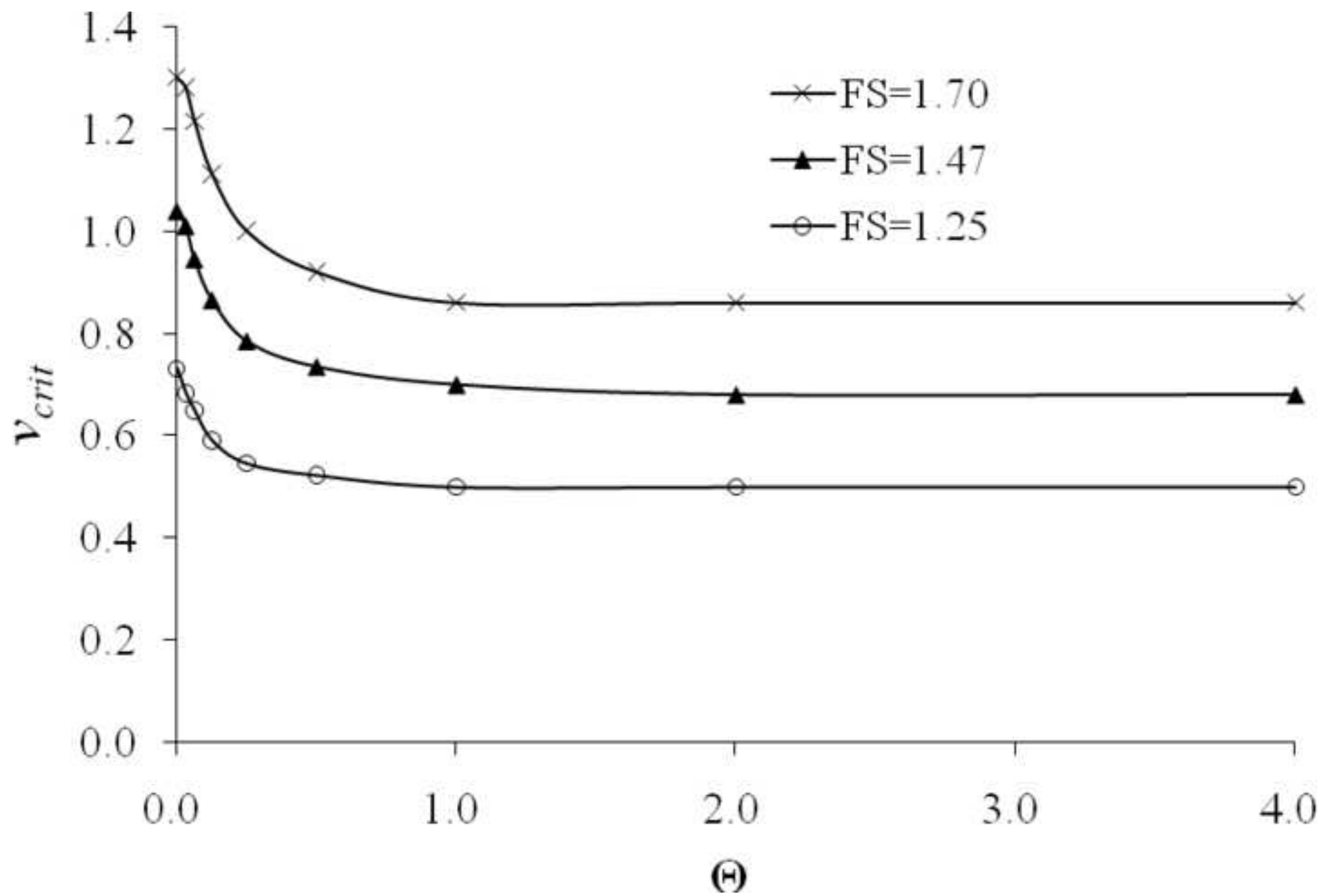


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