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## Integral representation of solutions of first-order linear partial differential equations, I

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# Integral Representation of Solutions of First-Order Linear Partial Differential Equations, I (*). 

 FRANÇOIS TREVES (**)dedicated to Hans Lewy

## Introduction.

Until now the proofs of the local solvability of the linear PDEs with simple real characteristics satisfying Condition (P) are strictly "existential» and based on a priori estimates (see [1], [5]). In the present paper we give an integral representation of solutions (in a small open set) of the equation

$$
\begin{equation*}
L u=f, \tag{1}
\end{equation*}
$$

in the (very) particular case where $L$ is a first-order linear partial differential operator with analytic coefficients, nondegenerate, satisfying Condition (P) (which, in these circumstances, is equivalent to being locally solvable). The right-hand side $f$ is assumed to be $C^{\infty}$ and the found solution $u$ is also $C^{\infty}$ (all this is local, in a fixed open neighborhood of the central point). Thus we answer, in this particular case, the question of the solvability within $C^{\infty}$-still open in the more general cases.

The techniques introduced in the present paper compel us to look at the local solvability of first-order linear PDEs from a new viewpoint, and to analyze in finer detail its geometric implications (see Ch. I). I believe they should lead to interesting results in more general set-ups. An outline of the main ideas of the paper can be found in [7].

[^0]
## Chapter I

## GENERAL CONSIDERATIONS

## 1. - A new formulation of the solvability condition $(P)$ for first-order linear PDEs.

Let $\Omega$ be an open subset of $\mathbb{R}^{N}(N \geqslant 2)$; the coordinates in $\mathbb{R}^{N}$ are denoted (at least for the moment) by $y^{1}, \ldots, y^{N}$. We consider a first-order linear partial differential operator

$$
\begin{equation*}
L=\sum_{j=1}^{N} \gamma^{j}(y) \frac{\partial}{\partial y^{j}}+\gamma^{0}(y), \tag{1.1}
\end{equation*}
$$

where the $\gamma^{j}(0 \leqslant j \leqslant N)$ are complex-valued $C^{\infty}$ functions in $\Omega$. We make throughout the hypothesis that $L$ is nowhere degenerate, that is,

$$
\begin{equation*}
\forall y \in \Omega, \quad \sum_{j=1}^{N}\left|\gamma^{j}(y)\right| \neq 0 \tag{1.2}
\end{equation*}
$$

We denote by $L_{0}$ the principal part of $L$, that is,

$$
L_{0}=\sum_{j=1}^{N} \gamma^{j}(y) \frac{\partial}{\partial y^{j}}
$$

Let then $y_{0}$ be an arbitrary point of $\Omega$. There is an open neighborhood $U \subset \Omega$ of $y_{0}$ and local coordinates in $U, x^{1}, \ldots, x^{n}, t$ (we set $n=N-1$ and write $\left.x=\left(x^{1}, \ldots, x^{n}\right)\right)$ such that, in $U$,

$$
\begin{equation*}
L=\zeta(x, t)\left\{\frac{\partial}{\partial t}+i \sum_{j=1}^{n} b^{j}(x, t) \frac{\partial}{\partial x^{j}}+c(x, t)\right\}, \tag{1.3}
\end{equation*}
$$

where $\zeta, b^{j}(1 \leqslant j \leqslant n)$, $c$ are $C^{\infty}$ functions in $U$; furthermore, $\zeta$ does not vanish at any point of $U$ and the $b^{j}$ are real-valued. We may in fact suppose that $U$ is a product-set

$$
\begin{equation*}
U=\left\{(x, t) \in \mathbb{R}^{n+1} ; x \in U_{0},|t|<T\right\} \tag{1.4}
\end{equation*}
$$

where $U_{0}$ is an open neighborhood of the origin and $T$ a number $>0$ (we are assuming, for simplicity, that the coordinates $x^{1}, \ldots, x^{n}, t$ all vanish at $y_{0}$ ). We set: $\boldsymbol{b}(x, t)=\left(b^{1}(x, t), \ldots, b^{n}(x, t)\right)\left(\in \mathbb{R}^{n}\right)$.

DEFINITION 1.1. We say that $L$ satisfies Condition ( $\mathbf{P}$ ) at the point $y_{0}$ if there is an open neighborhood $V \subset U$ of $y_{0}$ such that the following is true:
(1.5) In $V$, the vector field $\boldsymbol{b}(x, t)||\boldsymbol{b}(x, t)|$ is independent of $t$.

Although we have formulated (P) at $y_{0}$ in terms of particular coordinates, it can be proved (see [4]) that it does not depend on our choice of the coordinates (provided that the expression of $L$ be of the kind (1.3)). We say that $L$ satisfies Condition ( P ) in $\Omega$ if it so does at every point of $\Omega$.

Let us assume that ( P ) holds at $y_{0}$ and take the neighborhood $U$ equal to $V$ in Def. 1.1. Let us introduce the singular set

$$
\begin{equation*}
\mathcal{N}_{0}=\left\{x \in U_{0} ; \forall t,|t|<T, \boldsymbol{b}(x, t)=0\right\} . \tag{1.6}
\end{equation*}
$$

In $U_{0} \backslash \mathcal{N}_{0}, \boldsymbol{b} /|\boldsymbol{b}|$ is a $\boldsymbol{C}^{\infty}$ vector field, nowhere zero; we shall regard it as a first-order linear partial differential operator, without zero-order term, which we denote by

$$
\begin{equation*}
X=\sum_{j=1}^{n} v^{j}(x) \frac{\partial}{\partial x^{j}} \tag{1.7}
\end{equation*}
$$

We extend $v=\left(v^{1}, \ldots, v^{n}\right)$ as an arbitrary unit-vector in $\mathcal{N}_{0}$ (in general, $v$ will not be smooth throughout $U_{0}$ ). In $U$ we may then write

$$
\begin{equation*}
L=\zeta(x, t)\left\{\frac{\partial}{\partial t}+i|\boldsymbol{b}(x, t)| X+c(x, t)\right\} \tag{1.8}
\end{equation*}
$$

We find ourselves in the following situation: $U$ is the union of the "vertical» lines $x=x_{0} \in \mathcal{N}_{0}$, along which $\zeta^{-1} L_{0}=\partial / \partial t$, and of the cylinders $\Sigma=\Gamma \times]-T, T$, where $T$ is any integral curve of $X$ in $U_{0} \backslash \mathcal{N}_{0}$, cylinders on which $\zeta^{-1} L_{0}=\partial / \partial t+i|\boldsymbol{b}(x, t)| X$.

Assuming now that ( P ) holds at every point of $\Omega$, this leads to a foliation of $\Omega$, which is best seen when the coefficients of $L_{0}$ are analytic. Let us write $L_{0}=A+\sqrt{-1} B$, where $A$ and $B$ are real vector fields. Let us denote by $\mathfrak{g}(A, B)$ the real Lie algebra generated by $A$ and $B$ (for the commutation bracket $[A, B]=A B-B A$ ). When $A$ and $B$ are analytic vector fields, it is known (see [2]) that each point $y_{0}$ of $\Omega$ belongs to one, and only one, subset $\mathcal{M}$ of $\Omega$ having the following properties:
(1.9) $\mathcal{M}$ is a connected analytic submanifold of $\Omega$;
(1.10) the tangent space to $\mathcal{M}$ at anyone of its points, $y$, is exactly equal to the «freezing» of $\mathfrak{g}(A, B)$ at $y$;
(1.11) $\mathcal{H}$ is maximal for Properties (1.9) and (1.10).

We shall refer to the submanifolds $\mathcal{M}$ as the leaves defined by $L$. When the coefficients of $L_{0}$ are analytic, Condition ( P ) is equivalent with the local solvability of $L$ (here, at each point of $\Omega$ ). It can be subdivided into two parts:
(P1) the dimension of each leaf $\mathcal{M}$, defined by $L$, is either one or two.
Observe that (P1) is always true when the dimension of the surrounding space, i.e., of $\Omega$, is $\leqslant 2-$ even when $L$ is not locally solvable.
On an arbitrary two-dimensional leaf $\mathcal{M}$ the complex vector field $L_{0}$ defines a skew-symmetric real two-tensor, which it is natural to denote by

$$
\begin{equation*}
A \wedge B=-\frac{1}{2 i} L_{0} \wedge \bar{L}_{0} . \tag{1.12}
\end{equation*}
$$

(If we set $\alpha^{j}=\operatorname{Re} \gamma^{j}, \beta^{j}=\operatorname{Im} \gamma^{j}, j=1, \ldots, N$, the coordinates of $A \wedge B$ on the canonical basis $\partial / \partial y^{j} \wedge \partial / \partial y^{k}, 1 \leqslant j<k \leqslant N$, are $\alpha^{j} \beta^{k}-\alpha^{k} \beta^{j}$.) Locally on $\mathcal{M}$, we may always find a generator of the line bundle $\wedge^{2} T \cdot \mathcal{H}$ (in the coordinates $x, t$ used earlier we may take $\partial / \partial t \wedge X)$. Let $\theta$ be such a generator, say over an open subset $\mathcal{O}$ of $\mathcal{M}$. Then $A \wedge B=\varrho \theta$, where $\varrho$ is a realvalued (analytic) function in $\mathcal{O}$. Observe that the property that $\varrho$ does not change sign in $\mathcal{O}$ is independent of our choice of $\theta$; observe also that the zeroset of $\varrho$ is a proper analytic subset of $\mathcal{O}$. This gives a meaning to the second «part» of Property ( P ):
(P2) Restricted to any two-dimensional leaf $\mathcal{M}$ (defined by $L$ ) in $\Omega$, $-(1 / 2 i) L_{0} \wedge \bar{L}_{0}$ does not change sign.

Indeed, in the form (1.7), we have

$$
\begin{equation*}
-\frac{1}{2 i} L_{0} \wedge \bar{L}_{0}=|\boldsymbol{b}(x, t)|\left(\frac{\partial}{\partial t} \wedge X\right) . \tag{1.13}
\end{equation*}
$$

There is no need to point out that ( P ), stated as the conjunction of ( P 1 ) and (P2), is invariant under coordinates changes and also under multiplication of $L$ by nowhere vanishing complex-valued (analytic) functions.

Along any one-dimensional leaf (parametrized by $t$ ) the principal part $L_{0}$ is essentially $\partial / \partial t$. We shall see, in the course of the proof of our main result, that, by virtue of ( P 2 ), on any two-dimensional leaf, $L_{0}$ can be transformed (up to a scalar factor) into the «Cauchy-Riemann operator» $\partial / \partial t+i X$, via a homeomorphism naturally associated with $L_{0}$.

In the case of $C^{\infty}$ coefficients, the reformulation of Property ( P ) is more delicate. First of all it is not true, in general, that through each point $y_{0}$ of $\Omega$ passes a unique $C^{\infty}$ submanifold $\mathcal{M}$ with property (1.10). There is another
consequential difference: let us return to the local representation (1.8) and consider the restriction of $L$ to a cylinder $\Sigma=\Gamma \times]-T$, $T$, where $\Gamma$ is an integral curve of $X$ in $U_{0} \backslash \mathcal{N}_{0}$. When the coefficients of $L$ are analytic, $|\boldsymbol{b}(x, t)|$ is an analytic function on $\Sigma$; its zero-set intersects any vertical line $x=x_{0} \in \Gamma$ only on a locally finite set, otherwise $|\boldsymbol{b}|$ would vanish identically on such a line and we should have $x_{0} \in \mathcal{N}_{0}$, contrary to the definition of $\Gamma$. In particular the zero-set of $|\boldsymbol{b}|$ is a proper analytic subset of $\Sigma$. In the case of $C^{\infty}$ coefficients the zero-set of $|\boldsymbol{b}|$ might have a nonempty interior. It is submitted to the sole condition of not containing any vertical segment $\left.\left\{x_{0}\right\} \times\right]-T, T$. Requirement which is of course dependent on the length $T$ of the «time interval».

Nevertheless we may formulate (P) as the conjunction of (P1) and (P2), provided we incorporate to ( P 1 ) a statement as to the existence of the foliation $\{\mathcal{M}\}$. Leaves cannot anymore be required to have property (1.10) (example: $L=\partial / \partial t+i b(x, t)(\partial / \partial x)$, where $b \in C^{\infty}\left(\mathbb{R}^{2}\right)$ is real-valued and does not vanish anywhere, except at the origin, where all derivatives of $b$ vanish; there can be but one leaf, the whole plane, although $g(A, B)$ is one-dimensional at the origin).

Definition 1.2. Let $k$ be any integer such that $0 \leqslant k \leqslant N$. A $k$-dimensional leaf, defined by $L$ in $\Omega$, is a subset $\mathscr{H}$ of $\Omega$ having the following properties:
(1.14) $\mathcal{M}$ is a connected $C^{\infty}$ submanifold $\left(^{*}\right)$ of $\Omega$, of dimension $k$;
(1.15) the tangent space to $\mathcal{M}$ at anyone of its points, $y$, contains the "freezing" of $\mathfrak{g}(A, B)$ at $y$;
(1.16) the boundary $\left(^{(* *)}\right.$ of $\mathcal{M}$ is a union of leaves defined by $L$ in $\Omega$ whose dimension is $<k$;
$\mathcal{M}$ does not contain any leaf defined by $L$ in $\Omega$ whose dimension is $<k$.
With this definition we may now state:
(P1) $\Omega$ is the union of leaves defined by $L$, whose dimension is either one or two.
Observe that, because of Hypothesis (1.2), the dimension of $\mathfrak{g}(A, B)$ at every point is at least one; consequently there are no zero-dimensional leaves
(*) It is perhaps worth recalling what a $C^{\infty}$ submanifold $\mathcal{K}$ of $\Omega$ is: every point of $\mathcal{M}$ (and not necessarily every point of $\Omega$ !) has a neighborhood in which $\mathcal{M}$ is defined by the vanishing of a number of smooth functions whose differentials are linearly independent.
(**) We use the word «boundary» as in «manifold with boundary», not with its point-set topology meaning.
and, in virtue of (1.16), the one-dimensional leaves defined by $L$ must be without a boundary.

Let us prove that $(P)$ is equivalent with the conjunction of (P1) and (P2). First, suppose ( P ) holds at every point of $\Omega$. Let $\mathcal{M}$ denote a connected one-dimensional $C^{\infty}$ submanifold of $\Omega$, having property (1.15), and also the following one:
(1.18) Let $\left(U, x^{1}, \ldots, x^{n}, t\right)$ be a local chart in $\Omega$, yielding the representation (1.8) of L. Any segment $\left.\left\{x_{0}\right\} \times\right]-T, T\left[, x_{0} \in U_{0}\right.$, which intersects $\mathcal{M} \cap U$ is contained in $\mathcal{M}$.

The manifold $\mathcal{K}$ cannot have any boundary point $y_{0}$ in $\Omega$, as one sees by taking a local chart ( $U, x^{1}, \ldots, x^{n}, t$ ) as in (1.18), containing $y_{0}$. Thus, by Def. 1.2, $\mathcal{M}$ is a leaf of $L$ in $\Omega$; and every one-dimensional leaf of $L$ must have property (1.18). Let $F$ denote the union of all the one-dimensional leaves of $L$ in $\Omega$. Since, in any local chart like the one in (1.18), such leaves are unions of vertical segments $\left.\left\{x_{0}\right\} \times\right]-T, T\left[\right.$ with $x_{0} \in \mathcal{N}_{0}$, every point $y_{0} \in U$ which belongs to the closure of $F$ must lie on such a segment, from which it follows at once that $F$ must be closed.

Let now $\mathcal{M}$ denote a connected two-dimensional $C^{\infty}$ submanifold of $\Omega \backslash F$, satisfying (1.15) and (1.18), and maximal for these properties. Its boundary $\partial \mathcal{N}$ in $\Omega$ (see footnote (**) to p. 5) must also have property (1.18). By the maximality of $\mathcal{M}$, at no point of $\partial \mathcal{M}$ can the Lie algebra $\mathfrak{g}(A, B)$ be two-dimensional. Thus $\partial \mathcal{M}$ must be a union of one-dimensional leaves of $L$, in fact of at most two of them, since $\mathscr{H}$ is connected, and possibly of only one or of none. Thus $\mathcal{H}$ is a two-dimensional leaf of $L$. A moment of thought shows that, conversely, every two-dimensional leaf of $L$ in $\Omega$ is such a submanifold of $\Omega \backslash F$. Note that every $C^{\infty}$ submanifold of $\Omega \backslash F$, of dimension $\leqslant 2$, satisfying (1.15), must be entirely contained in some such leaf; and that any two such leaves cannot intersect without being identical. In particular, every point of $\Omega \backslash F$ is contained in one, and only one, twodimensional leaf of $L$.

That ( P 2 ) is a consequence of ( P ) has already been explained.
Suppose now that ( P 1 ) holds. Let $y_{0}$ be an arbitrary point of $\Omega$. By (1.2) we may assume that $L$ has the representation (1.3) in a local chart ( $U, x^{1}, \ldots, x^{n}, t$ ) centered at $y_{0}$. This also implies that every leaf $\mathcal{M}$ defined by $L$ in $\Omega$ (according to Def. 1.2), is equal, in $U$, to the union of vertical lines $x=x_{0}$ : As a consequence, every two-dimensional leaf $\mathcal{M}$ intersects the piece of "hyperplane» $\{(x, t) \in U ; t=0\}$ along a smooth curve $\Gamma \subset U_{0}$; and $\mathcal{M}$ is the cylinder $\Sigma=\Gamma \times]-T, T[$. Let $\tilde{X}$ be a smooth vector field tangent to $\Gamma$ and nowhere vanishing on $\Gamma$. From what we have just seen it follows
that, on $\Sigma, \zeta^{-1} L_{0}=\partial / \partial t+i \lambda(x, t) \tilde{X}$, and (P2) means exactly that $\lambda$ does not change sign in $\Sigma$ (if $\tilde{X}$ is a unit vector-field and if $\lambda$ is nonnegative, in the notation of (1.8) we have $\lambda=|\boldsymbol{b}(x, t)|$ and $\tilde{X}=X$ ).

A final remark: in the $C^{\infty}$ case, in contrast with what happens in the analytic case, the foliation defined by $L$ in a proper open subset of $\Omega$ can be strictly finer than the one induced by the foliation of $\Omega$.

## 2. - Reduction to flat right-hand sides.

We shall systematically use the following terminology:
Definition 2.1. Let $M$ be a $C^{\infty}$ manifold, $\varrho$ a nonnegative continuous function in $M$. We say that a function $f \in C^{\infty}(M)$ is $\varrho$-flat in $M$ if given any differential operator (with $C^{\infty}$ coefficients) $\mathbb{P}$ in $M$ and any integer ${ }^{\prime} k \geqslant 0$, $\varrho^{-k} \mathrm{P} f$ is a continuous function in $M$, and we write then $f \underset{e}{\sim} 0$.

It is convenient to introduce the notation:

$$
\begin{equation*}
\mathcal{E}_{e \text {-flat }}(M)=\left\{f \in C^{\infty}(M) ; f \text { is } \varrho \text {-flat in } M\right\}, \tag{2.1}
\end{equation*}
$$

(2.2) $\mathcal{D}_{o \cdot \text {-fat }}(M)=\left\{f \in \mathcal{E}_{o-\text {-fat }}(M)\right.$; supp $f$ is a compact subset of $\left.M\right\}$.

We shall comply throughout with the notation of Sect. 1. In particular, we reason locally, in the neighborhood $U$ given by (1.4). We assume that the «central point» is the origin in $\mathbb{R}^{n+1}$ and that $L$ is given by (1.3); we may even divide by $\zeta$ and take $L=L_{0}+c(x, t)$, with

$$
\begin{equation*}
L_{0}=\frac{\partial}{\partial t}+i \sum_{j=1}^{n} b^{j}(x, t) \frac{\partial}{\partial x^{j}} . \tag{2.3}
\end{equation*}
$$

We suppose that $\boldsymbol{b}=\left(b^{1}, \ldots, b^{n}\right)$ and $c$ are $C^{\infty}$ functions in an open neighborhood of $\bar{U}$ (which is compact), valued in $\mathbb{R}^{n}$ and $\mathbb{C}$ respectively.

The function $\varrho$ we use (in a neighborhood of $\bar{U}$ ) is the following:

$$
\begin{equation*}
\varrho(x, t)=\left|\int_{-T}^{t}\right| \boldsymbol{b}(x, s)|d s| . \tag{2.4}
\end{equation*}
$$

Following a suggestion of $L$. Nirenberg we begin by proving
Theorem 2.1. If $U$ is small enough, there is a continuous linear operator $E: C_{c}^{\infty}(U) \rightarrow C^{\infty}(U)$ such that $R=L E-I$ maps $C_{c}^{\infty}(U)$ into $\varepsilon_{e-f a t}(U)$.

Remark 2.1. In Th. 2.1 it is not assumed that $L$ is locally solvable.

Remark 2.2. By Def. 2.1 it is clear that $\delta_{e \text {-fat }}(M)$ carries a natural Fréchet space topology: the coarsest one which renders all the mappings $f \mapsto \varrho^{-k} \mathbb{P} f$ continuous, from $\mathcal{E}_{e \cdot \text { flat }}(M)$ into $C^{0}(M)$, as $k$ and $\mathbb{P}$ vary freely. The space $\mathscr{D}_{\varrho \text {-fiat }}(M)$ carries the derived $\mathcal{L} \mathcal{F}$-topology. It will be obvious that the operator $R$ is continuous for these topologies.

Proof. We apply Th. 1 of [6] (or else use almost-analytic extensions). If $U$ is small enough, for each $j=1, \ldots, n$, there is a complex-valued $C^{\infty}$ function $z^{j}=z^{j}\left(x, t, t^{\prime}\right)$ such that

$$
\begin{align*}
& L_{0} z^{j}{\underset{e}{0}}^{\sim} \text { in an open neighborhood of } \bar{U},  \tag{2.5}\\
& \left.z^{j}\right|_{t=t^{\prime}}=x^{j} \tag{2.6}
\end{align*}
$$

$\left(t^{\prime} \in[-T, T]\right)$. If the coefficients of $L_{0}$ are analytic, the equivalence (2.5) can be replaced by an exact equality $L_{0} z^{j}=0$ (because of the CauchyKovalevska theorem). Furthermore (according to Th. 1 of [6])

$$
\begin{equation*}
\left|z^{j}-x^{j}-i \int_{t^{\prime}}^{i} b^{j}(x, s) d s\right| \leqslant C \varrho(x, t) \tag{2.7}
\end{equation*}
$$

(where $C \rightarrow 0$ with $T$ ).
Application of Th. 1 of [6] yields (2.5) and (2.7) with $\varrho(x, t)$ replaced by $\left|\int_{i^{\prime}}^{t}\right| \boldsymbol{b}(x, s)|d s| ;$ but if $-T \leqslant t^{\prime} \leqslant t$, the latter quantity clearly does not exceed $\varrho(x, t)$. We write $z=\left(z^{1}, \ldots, z^{n}\right)$ and set, for arbitrary $f \in C_{c}^{\infty}(U)$,

$$
\begin{align*}
& E_{0} f(x, t)=(2 \pi)^{-n} \int_{-T}^{t} \int_{\xi \in \mathbb{R}_{n}} \exp \left[i z\left(x, t, t^{\prime}\right) \cdot \xi\right]  \tag{2.8}\\
& \cdot g\left(\xi \cdot \operatorname{Im} z\left(x, t, t^{\prime}\right)\right) \hat{f}\left(\xi, t^{\prime}\right) d t^{\prime} d \xi,\left(^{*}\right)
\end{align*}
$$

where $\hat{f}(\xi, t)$ is the Fourier transform of $f$ with respect to the $x$-variables, and $g \in C^{\infty}\left(\mathbb{R}^{1}\right), g(\tau)=1$ for $\tau>-1, g(\tau)=0$ for $\tau<-2$. It is checked at once that $E_{0}$ maps continuously $C_{c}^{\infty}(U)$ into $C^{\infty}(U)$. Furthermore, if $R_{0}=L_{0} E_{0}-I$, we have

$$
\begin{equation*}
R_{0} f(x, t)=(2 \pi)^{-n} \int_{-T}^{t} \int_{\mathbf{R}_{n}} \exp [i z \cdot \xi] R_{0}\left(x, t, t^{\prime}, \xi\right) \hat{f}\left(\xi, t^{\prime}\right) d \xi d t^{\prime} \tag{2.9}
\end{equation*}
$$

(*) This formula mimicks the construction of continuous almost-analytic extensions by Mather ([3]).
with

$$
\begin{equation*}
R_{0}\left(x, t, t^{\prime}, \xi\right)=\left\{i g(\xi \cdot \operatorname{Im} z) L_{0} z+g^{\prime}(\xi \cdot \operatorname{Im} z) L_{0}(\operatorname{Im} z)\right\} \cdot \xi \tag{2.10}
\end{equation*}
$$

$\left(z=z\left(x, t, t^{\prime}\right)\right)$. Whatever $k \in \mathbb{Z}_{+}$, for a suitable $C_{k}>0$,

$$
\begin{equation*}
\left|g^{\prime}(\xi \cdot \operatorname{Im} z)\right| \leqslant O_{k}|\xi \cdot \operatorname{Im} z|^{k} \tag{2.11}
\end{equation*}
$$

whence, combining (2.7) and (2.11),

$$
\begin{equation*}
\left|g^{\prime}(\xi \cdot \operatorname{Im} z) L_{0}(\operatorname{Im} z) \cdot \xi\right| \leqslant C_{k}^{\prime}|\xi|^{k+1} \varrho(x, t)^{k} \tag{2.12}
\end{equation*}
$$

On the other hand, by (2.5), we have

$$
\begin{equation*}
\left|L_{0} z\right| \leqslant C_{k}^{\prime \prime} \varrho(x, t)^{k} \tag{2.13}
\end{equation*}
$$

Since on the support of $g(\xi \cdot \operatorname{Im} x)$, we have $|\exp [i z \cdot \xi]| \leqslant e^{2}$, we see that

$$
\begin{equation*}
\left|R_{0} f(x, t)\right| \leqslant C_{k}^{\prime \prime} \varrho(x, t)^{k} \int_{-T}^{t} \int(1+|\xi|)^{k+1}\left|\hat{f}\left(\xi, t^{\prime}\right)\right| d \xi d t^{\prime} \tag{2.14}
\end{equation*}
$$

An analogous inequality can be obtained for every derivative of $R_{0} f$ with respect to $(x, t)$, which shows that $R_{0} f$ is $\varrho$-flat.

Let now $c_{1}(x, t) \in C_{c}^{\infty}(U)$ equal $c(x, t)$ in a subneighborhood $U_{1}$ of the origin, and set

$$
\begin{equation*}
E f=\exp \left[-E_{0} c_{1}\right] E_{0}\left(\exp \left[E_{0} c_{1}\right] f\right), \quad f \in C_{c}^{\infty}\left(U_{1}\right) \tag{2.15}
\end{equation*}
$$

We have, in $U_{1}$,

$$
\begin{aligned}
L E f & =\left(L_{0}+c_{1}\right)\left\{\exp \left[-E_{0} c_{1}\right] E_{0}\left(\exp \left[E_{0} c_{1}\right] f\right)\right\} \\
& =\exp \left[-E_{0} c_{1}\right]\left(L_{3}+c_{1}-L_{0} E_{0} c_{1}\right) E_{0}\left(\exp \left[E_{0} c_{1}\right] f\right) \\
& =f-\left(R_{0} c_{1}\right) f+\exp \left[-E_{0} c_{1}\right] R_{0}\left(\exp \left[E_{0} c_{1}\right] f\right)
\end{aligned}
$$

which shows that the statement of Th .2 .1 is verified, if $U_{1}$ is substituted for $U$ and if we define $R$ by

$$
\begin{equation*}
R f=\exp \left[-E_{0} c_{1}\right] R_{0}\left(\exp \left[E_{0} c_{1}\right] f\right)-\left(R_{0} c_{1}\right) f . \quad \text { Q.E.D. } \tag{2.16}
\end{equation*}
$$

## Chapter II

## CONSTRUCTION OF FUNDAMENTAL SOLUTIONS <br> WHEN THE COEFFICIENTS ARE ANALYTIC

## 1. - Statement of the theorem.

We use the notation of Ch. I. In particular, $L=L_{0}+c(x, t)$ and $L_{0}$ has the form (2.3), Ch. I. The coefficients of $L_{0}$ are now analytic in an open neighborhood of the origin in $\mathbb{R}^{n+1}$, which we take to be $\Omega$. In this chapter we prove:

Theorem 1.1. There is an open neighborhood $U \subset \subset \Omega$ of the origin in $\mathrm{R}^{n+1}$ and a continuous linear operator $K: C_{c}^{\infty}(U) \rightarrow C^{\infty}(U)$ such that $L K=I$, the identity of $C_{c}^{\infty}(U)$.

Let us note right-away that it suffices to prove the result when $c(x, t) \equiv 0$. For if $L_{0} K_{0}=I$ and $h=K_{0} c_{1}$, with $c_{1} \in O_{c}^{\infty}(U), c_{1}=e$ in an open neighborhood $U^{\prime} \subset U$ of 0 , we may take $K=e^{-h} K_{0} e^{h}$, which yields $L K=I$ in $U^{\prime}$. From now on we assume that $L=L_{0}$, i.e.

$$
\begin{equation*}
L=\frac{\partial}{\partial t}+i \sum_{j=1}^{n} b^{j}(x, t) \frac{\partial}{\partial x^{j}} \tag{1.1}
\end{equation*}
$$

in $\Omega$.
If we take Th. 2.1, Ch. I, into account, we see that Th. 1.1 will follow from the result below. We introduce and shall use throughout the following function:

$$
\begin{equation*}
r(x)=\left\{\int_{-T}^{T}|\boldsymbol{b}(x, s)|^{2} d s\right\}^{\frac{1}{z}} \tag{1.2}
\end{equation*}
$$

If we compare with the function $\varrho(x, t)$ defined in (2.4), Ch. I, we see that

$$
\begin{equation*}
\varrho(x, t)<\sqrt{(T+t)} r(x) \leqslant \sqrt{2 T} r(x) \tag{1.3}
\end{equation*}
$$

for $(x, t) \in \Omega,|t| \leqslant T$. Thus if we regard $r$ as a function in $\Omega$, we see that any $\varrho$-flat (Def. 2.1, Ch. I) $C^{\infty}$ function is also $r$-flat. In particular (see (2.1), Ch. I), $\varepsilon_{\text {e-fat }}(U) \subset \varepsilon_{r \text {-flat }}(U)$. We shall prove the following result:

THEOREM 1.2. If the open neighborhood $U \subset \subset \Omega$ of the origin is small enough, there is a linear operator $K_{1}: \mathfrak{D}_{r \text {-flat }}(U) \rightarrow \mathcal{E}_{r \text {-flat }}(U)$ (see (2.1), (2.2), Ch. 1) such that $L K_{1}=I$, the identity of $\mathfrak{D}_{r \text {-flat }}(U)$.

Let then $\zeta(x, t) \in C_{c}^{\infty}(U), \zeta(x, t)=1$ in an open subneighborhood $U^{\prime}$ of 0. Let $R$ be the operator in Th. 2.1, Ch. I, and set, for any $f \in C_{1}(U)$,

$$
\begin{equation*}
K f=E f-K_{1}[\zeta(x, t) R f] \tag{1.4}
\end{equation*}
$$

where $E$ is the operator in Th. 2.1, Ch. I. Obviously $K$ satisfies the requirements of Th. 1.1, if we substitute $U^{\prime}$ for $U$ (inspection of the proofs shows easily that $K_{1}$, as well as $R$, are continuous when $\mathscr{D}_{r \text {-flat }}(U)$ and $\mathcal{E}_{r \text {-fat }}(U)$ carry their natural topologies, and this implies the continuity of $K$ ).

## 2. - Determination of an across-the-board phase function.

From now on we suppose that

$$
\begin{equation*}
U_{0}=\left\{x \in \mathbb{R}^{n} ;|x|<R\right\}, \quad R>0 \tag{2.1}
\end{equation*}
$$

recalling that $\left.U=U_{0} \times\right]-T, T[$. We also recall that

$$
\begin{equation*}
\mathcal{N}_{0}=\{x \in \Omega ; \forall t,|t|<T, \boldsymbol{b}(x, t)=0\} \tag{2.2}
\end{equation*}
$$

Let us set

$$
\begin{equation*}
\sigma(z, t)=\sum_{k=1}^{n}\left[b^{k}(z, t)\right]^{2} \tag{2.3}
\end{equation*}
$$

where $z=x+i y$ varies in an open neighborhood of $\bar{U}+i\left\{y \in \mathbb{R}^{n} ;|y| \leqslant r_{0}\right\}$. Since $\sigma(x, t) \geqslant 0$ (for $x \in \mathbf{R}^{n}$ in a neighborhood of $\bar{U}$ ), there is a constant $M \geqslant 0$ such that

$$
\begin{equation*}
\left|\sigma_{x}(x, t)\right| \leqslant M \sqrt{\sigma(x, t)}, \quad \forall x \in \bar{U},|t|<T \tag{2.4}
\end{equation*}
$$

Of course, $\sqrt{\sigma(x, t)}=|\boldsymbol{b}(x, t)|$. We may write

$$
\begin{equation*}
\sigma(x+i y, t)=\sigma(x, t)+i y \cdot \sigma_{x}(x, t)+\tau_{2}(x, y, t) \tag{2.5}
\end{equation*}
$$

where $\left|\tau_{2}(x, y, t)\right| \leqslant M_{1}|y|^{2}$. If $x>0$ is small enough and if

$$
\begin{equation*}
|y|<x|\boldsymbol{b}(x, t)|, \tag{2.6}
\end{equation*}
$$

we obtain:

$$
\begin{equation*}
|\sigma(x+i y, t)-\sigma(x, t)|<\frac{1}{2} \sigma(x, t) \tag{2.7}
\end{equation*}
$$

Lemma 2.1. If $x>0$ is small enough, $\beta(x, t)=|\boldsymbol{b}(x, t)|$ can be extended as a holomorphic function of $z=x+i y$ in the region:

$$
\begin{equation*}
x \in U_{0} \backslash \mathcal{N}_{0}, \quad|y|<x \sup _{|s|<T}|\boldsymbol{b}(x, s)| \tag{2.8}
\end{equation*}
$$

for all $t,|t|<T(\varkappa$ is independent of $t)$.
Proof. According to what precedes the statement of Lemma 2.1, in the region

$$
\begin{equation*}
x \in D_{0} \backslash \mathcal{N}_{0}, \quad|y|<x|\boldsymbol{b}(x, t)| \tag{2.9}
\end{equation*}
$$

we may (see (2.7)) set $\beta(z, t)=\sqrt{\sigma(z, t)}$ (the second inequality in (2.9) demands $|\boldsymbol{b}(x, t)| \neq 0)$. If we set, in (2.9),

$$
\begin{equation*}
\boldsymbol{v}(z, t)=\beta(z, t)^{-1} b(z, t) \tag{2.10}
\end{equation*}
$$

we see, by analytic continuation from $z=x$ real, that $\partial_{t} v(z, t)=0$, and we may write $v(z)$ instead of $v(z, t)$ :

$$
\begin{equation*}
\beta(z, t) \boldsymbol{v}(z)=\boldsymbol{b}(z, t) \tag{2.11}
\end{equation*}
$$

Let $x_{0} \in U_{0} \backslash \mathcal{N}_{0}$ be arbitrary. Consider any number $\eta>0$ such that

$$
\begin{equation*}
\eta<\sup _{t \mid<T}|\boldsymbol{b}(x, t)| \tag{2.12}
\end{equation*}
$$

There is $t_{0},\left|t_{0}\right|<T$, such that $\beta\left(x_{0}, t_{0}\right)>\eta$. Actually, we may find $\eta_{1}>0$ such that

$$
\begin{equation*}
\left|x-x_{0}\right|<\eta_{1} \Rightarrow \beta\left(x, t_{0}\right)>\eta \tag{2.13}
\end{equation*}
$$

We apply (2.7) or, rather, its consequence, namely that

$$
\begin{equation*}
|y|<\varkappa \beta\left(x, t_{0}\right) \Rightarrow\left|\beta\left(x+i y, t_{0}\right)\right|>\frac{1}{\sqrt{2}} \beta\left(x, t_{0}\right) \tag{2.14}
\end{equation*}
$$

hence:

$$
\begin{equation*}
\left|x-x_{0}\right|<\eta_{1}, \quad|y|<\varkappa \beta\left(x, t_{0}\right) \tag{2.15}
\end{equation*}
$$

implies

$$
\begin{equation*}
\beta\left(x+i y, t_{0}\right)>\eta / \sqrt{2} . \tag{2.16}
\end{equation*}
$$

But then, in the region (2.15),

$$
\begin{equation*}
\boldsymbol{v}(x+i y)=\boldsymbol{b}\left(x+i y, t_{0}\right) / \beta\left(x+i y, t_{0}\right) \tag{2.17}
\end{equation*}
$$

is holomorphic and, since $\left|\boldsymbol{b}\left(z, t_{0}\right)\right| \geqslant\left|\beta\left(z, t_{0}\right)\right|$, nowhere vanishes. In particular, every point in the set (2.15) has an open neighborhood in which, for some $j=1, \ldots, n, v^{j}(x+i y)$ is nowhere zero. Since

$$
\beta(x+i y, t)=b^{3}(x+i y, t) / v^{s}(x+i y),
$$

we see that $\beta(z, t)$ can be extended as a holomorphic function to such a neighborhood. Letting

$$
\eta \rightarrow \sup _{|s|<T} \beta\left(x_{0}, s\right)
$$

proves the assertion in Lemma 2.1. Q.E.D.
Remark 2.1. Actually $\beta(x+i y, t)$ is a $C^{\infty}$ function of $t,|t|<T$, valued in the space of holomorphic functions of $x+i y$ in the set (2.8).

Remark 2.2. We have also shown that $|\boldsymbol{v}(z+i y)| \geqslant 1$ in the set (2.8) provided that $x>0$ is small enough.

Assume, as we may, that $T \leqslant \frac{1}{2}$. Then (cf. (1.2)):

$$
\begin{equation*}
r(x)=\left\{\int_{-T}^{T}|\boldsymbol{b}(x, s)|^{2} d s\right\}^{\xi} \leqslant \sup _{|s| \leqslant T}|\boldsymbol{b}(x, s)| . \tag{2.18}
\end{equation*}
$$

Lemma 2.2. If $x>0$ is small enough, the holomorphic function $\int_{-T}^{T} \beta(x+i y, s)^{2} d s$ does not vanish at any point $x+i y$ such that

$$
\begin{equation*}
x \in U_{0} \backslash \mathcal{N}_{0}, \quad|y|<x r(x) . \tag{2.19}
\end{equation*}
$$

Proof. We have $\beta(z, s)^{2}=\sigma(z, s)$ (see (2.3)). We have (cf. (2.4) and (2.5)):

$$
\begin{equation*}
\left|\int_{-T}^{T} \sigma(x+i y, s) d s-\int_{-T}^{T} \sigma(x, s) d s\right| \leqslant M \nsim r(x) \int_{-T}^{T} \beta(x, s) d s+2 T M_{1} \varkappa^{2} r(x)^{2} . \tag{2.20}
\end{equation*}
$$

On the other hand,

$$
\int_{-T}^{T} \beta(x, s) d s \leqslant \sqrt{2 T} r(x)
$$

whence, by (2.20),

$$
\begin{equation*}
\left|\int_{-T}^{T} \sigma(x+i y, s) d s-r(x)^{2}\right| \leqslant M_{2} \nsim r(x)^{2} . \tag{2.21}
\end{equation*}
$$

Lemma 2.2 follows from the fact that $r(x)>0$ if $x \in U_{0} \backslash \mathcal{N}_{0}$. Q.E.D.
Remark 2.3. Actually, as we see in (2.21) where we take $M_{2} x<\frac{1}{2}$, that is,

$$
\begin{equation*}
\left|\int_{-T}^{T} \sigma(x+i y, s) d s-r(x)^{2}\right| \leqslant \frac{1}{2} r(x)^{2} \tag{2.22}
\end{equation*}
$$

we may define the square-root,

$$
\begin{equation*}
r(x+i y)=\left\{\int_{-T}^{T} \beta(x+i y, s)^{2} d s\right\}^{\frac{1}{2}} \tag{2.23}
\end{equation*}
$$

which is holomorphic in the open set (2.19).
We are now going to study a Cauchy problem

$$
\begin{equation*}
\frac{\partial \varphi}{\partial t}+i \sum_{k=1}^{n} b^{k}(z, t) \frac{\partial \varphi}{\partial z^{k}}=g(z, t) \tag{2.24}
\end{equation*}
$$

in a region

$$
\begin{equation*}
x \in U_{0} \backslash \mathcal{N}_{0}, \quad|y|<\varkappa r(x), \quad|t|<T^{\prime} \leqslant T \tag{2.25}
\end{equation*}
$$

with initial condition,

$$
\begin{equation*}
\left.\varphi\right|_{t=0}=0 \tag{2.26}
\end{equation*}
$$

where $g$ will be eventually chosen, but in any event, is a $C^{\infty}$ function of $(x, y, t)$ in the region

$$
\begin{equation*}
x \in U_{0} \backslash \mathcal{N}_{0}, \quad|y|<\varkappa r(x), \quad|t|<T \tag{2.27}
\end{equation*}
$$

holomorphic with respect to $x+i y$.

Let $x_{0} \in U_{0} \backslash \mathcal{N}_{0}$ be arbitrary. We denote by $E_{s}(0<s<1)$ the space of continuous functions in the ball $\left\{z \in \mathbb{C}^{n} ;\left|z-x_{0}\right| \leqslant s \chi_{0} r\left(x_{0}\right)\right\}$, holomorphic in the interior. Here $x_{0}$ is chosen so as to have, if $z=x+i y$,

$$
\begin{equation*}
\left|z-x_{0}\right| \leqslant \mu_{0} r\left(x_{0}\right) \Rightarrow y<\varkappa r(x) \tag{2.28}
\end{equation*}
$$

where $x$ is the number in Lemma 2.2. Such a choice is indeed possible, for $\left|z-x_{0}\right| \leqslant \chi_{0} r\left(x_{0}\right)$ implies $\left|x-x_{0}\right| \leqslant \varkappa_{0} r\left(x_{0}\right)$ and $|y| \leqslant \varkappa_{0} r\left(x_{0}\right) \quad(z=x+i y)$, therefore $\left|r(x)-r\left(x_{0}\right)\right| \leqslant\left(\int_{-T}^{T}\left|\boldsymbol{b}(x, s)-\boldsymbol{b}\left(x_{0}, s\right)\right|^{2} \boldsymbol{d} s\right)^{\frac{1}{2}} \leqslant M\left|x-x_{0}\right| \leqslant M \varkappa_{0} r\left(x_{0}\right) \leqslant \frac{1}{2} r\left(x_{0}\right)$ if $M x_{0} \leqslant \frac{1}{2}$, and thus it implies $r\left(x_{0}\right) \leqslant 2 r(x)$, whence $|y|<x r(x)$ if $2 \varkappa_{0}<\varkappa$.

We shall denote by $h \mapsto\|h\|_{s}$ the (maximum) norm in $E_{s}$. We solve (2.24)-(2.26) by the standard iteration method: we set

$$
\begin{equation*}
\varphi(z, t)=\sum_{\nu=0}^{\infty} \varphi_{\nu}(z, t) \tag{2.29}
\end{equation*}
$$

with

$$
\begin{gather*}
\varphi_{0}(z, t)=\int_{0}^{t} g(z, s) d s  \tag{2.30}\\
\varphi_{\nu}(z, t)=-\int_{0}^{t} \sum_{k=1}^{n} b^{k}(z, s) \frac{\partial \varphi_{\nu-1}}{\partial z^{t}}(z, s) \mathrm{d} s, \quad \text { for } v>0 \tag{2.31}
\end{gather*}
$$

We shall prove that the series (2.29) converges in $E_{s_{0}}$ provided that $s_{0}$ is small enough (and that the same is true of the $t$-derivatives of the series). We are going to use the notation

$$
\begin{equation*}
B(x, t)=\int_{\mathbf{0}}^{t}\{|\boldsymbol{b}(x, s)|+\operatorname{Mr}(x)\} d s \tag{2.32}
\end{equation*}
$$

where $M>0$ is chosen so as to have

$$
\begin{equation*}
|\boldsymbol{b}(z, t)| \leqslant \beta(x, t)+M r(x) \tag{2.33}
\end{equation*}
$$

if $|z-x| \leqslant \kappa_{0} r(x)$ (cf. (2.21)).
We shall prove by induction on $\nu=0,1, \ldots$, that for suitable constants $C_{0}, C>0$, and all $s, 0<s<1$,

$$
\begin{equation*}
\left\|\varphi_{v}(\cdot, t)\right\|_{s} \leqslant C_{0}\left(\frac{C B\left(x_{0}, t\right)}{1-s}\right)^{v}, \quad|t|<T \tag{2.34}
\end{equation*}
$$

For $\nu=0$, (2.34) holds trivially. By Cauchy's inequalities and (2.33), we have for $\nu>0$,
(2.35) $\quad\left\|\varphi_{v}(\cdot, t)\right\|_{s} \leqslant$

$$
\begin{aligned}
& \leqslant \frac{1}{\varepsilon x_{0} r\left(x_{0}\right)}\left|\int_{0}^{t}\left[\beta\left(x_{0}, t\right)+M r\left(x_{0}\right)\right]\left\|\varphi_{\nu-1}\left(\cdot, t^{\prime}\right)\right\|_{s+\varepsilon} \mathrm{d} t^{\prime}\right| \leqslant \\
& \leqslant C_{0} \frac{C^{\nu-1}}{x_{0} r\left(x_{0}\right)} \frac{1}{\varepsilon} \frac{1}{(1-s-\varepsilon)^{\nu-1}}\left|\int_{0}^{t} B\left(x_{0}, t^{\prime}\right)^{\nu-1} \frac{\partial B}{\partial t}\left(x_{0}, t^{\prime}\right) d t^{\prime}\right| \leqslant \\
& \leqslant C_{0} \frac{C^{v-1}}{x_{0} r\left(x_{0}\right)} \frac{1}{\nu \varepsilon(1-s-\varepsilon)^{\nu-1}} B\left(x_{0}, t\right)^{\nu} .
\end{aligned}
$$

We take $\varepsilon=(1-s) /(\nu+1)$. Then

$$
\begin{equation*}
\left\|\varphi_{v}(\cdot, t)\right\|_{s} \leqslant C_{0}\left(\frac{C B\left(x_{0}, t\right)}{1-s}\right)^{v} \frac{1}{C x_{0} r\left(x_{0}\right)}\left(\frac{v+1}{v}\right)^{v} \tag{2.36}
\end{equation*}
$$

and we take

$$
\begin{equation*}
C \geqq \frac{e}{\chi_{0} r\left(x_{0}\right)} . \tag{2.37}
\end{equation*}
$$

This proves (2.34).
We note now that

$$
B(x, t) \leqslant \sqrt{|t|}\left(\int_{0}^{t}|\boldsymbol{b}(x, s)|^{2} d s\right)^{\frac{t}{t}}+M r(x)|t| \leqslant(1+M \sqrt{T}) r(x) \sqrt{|t|}
$$

hence, by (2.34) and (2.37),

$$
\begin{equation*}
\left\|\varphi_{\nu}(\cdot, t)\right\|_{s} \leqslant C_{0}\left[\frac{e(1+M \sqrt{T})}{(1-s) \varkappa_{0}}\right]^{v}|t|^{/ / 2} \tag{2.38}
\end{equation*}
$$

Finally we take $s \leqslant \frac{1}{2}$, and

$$
\begin{equation*}
|t| \leqslant T^{\prime}=\inf \left(T,\left[\frac{x_{0}}{2 e(1+M \sqrt{T})}\right]^{2}\right) \tag{2.39}
\end{equation*}
$$

and conclude that the series (2.29) converges in $C_{0}\left(\left[-T^{\prime}, T^{\prime}\right] ; E_{s}\right)$. From this and from the eq. (2.24) we derive easily that

$$
\varphi(z, t) \in C^{\infty}\left(\left[-T^{\prime}, T^{\prime}\right] ; E_{s}\right)
$$

We apply what precedes to the case where $g(z, t)=\beta(z, t) / i r(z)$. By virtue of Lemma 2.1 (if $T \leqslant \frac{1}{2}$ ) we know that $\beta(z, t)$ is holomorphic in the set (2.19), and depends smoothly on $(z, t)(|t| \leqslant T)$. By Lemma 2.2 and Remark 2.3 we know that $r(z)$ is holomorphic and nowhere zero in (2.19). We may state:

Lemma 2.3. Suppose that $\varkappa>0$ and $0<T^{\prime} \leqslant T$ are small enough. Then, in the region

$$
\begin{equation*}
x \in U_{0} \backslash \mathcal{N}_{0}, \quad|y|<\varkappa r(x), \quad|t|<T^{\prime} \tag{2.40}
\end{equation*}
$$

the Cauchy problem

$$
\begin{gather*}
\frac{\partial \varphi}{\partial t}+i \sum_{k=1}^{n} b^{k}(z, t) \frac{\partial \varphi}{\partial z^{k}}=\frac{1}{i} \frac{\beta(z, t)}{r(z)}  \tag{2.41}\\
\left.\varphi\right|_{t=0}=0 \tag{2.42}
\end{gather*}
$$

has a unique solution which is $C^{\infty}$ with respect to ( $x, y, t$ ) and holomorphic with respect to $z=x+i y$. It satisfies in (2.40), for $y=0$,

$$
\begin{equation*}
r(x)\left|\sum_{k=1}^{n} v^{k}(x) \frac{\partial \varphi}{\partial x^{k}}(x, t)\right| \leqslant C_{1}|t|^{\frac{1}{2}} \tag{2.43}
\end{equation*}
$$

and if $t^{\prime}$ is any other point in the interval $]-T^{\prime}, T^{\prime}[$,

$$
\begin{equation*}
\left|\varphi(x, t)-\varphi\left(x, t^{\prime}\right)-\frac{1}{i r(x)} \int_{t^{\prime}}^{t}\right| \boldsymbol{b}(x, s)|d s| \leqslant C_{1} \sup _{s \in\left[t t^{\prime}\right]}\left(|s|^{\frac{1}{2}}\right)\left|\int_{\boldsymbol{t}^{\prime}}^{t} \frac{|\boldsymbol{b}(x, s)|}{r(x)} d s\right| . \tag{2.44}
\end{equation*}
$$

We recall that $\beta(x, t)=|\boldsymbol{b}(x, t)|$ and $\boldsymbol{v}(x, t)=\boldsymbol{b}(x, t)| | \boldsymbol{b}(x, t) \mid$ (see (2.10)).
Proof. The existence has already been proved; the uniqueness is standard. We shall prove (2.43) and (2.44).

If we apply (2.30) and the estimates (2.38) we see that

$$
\left|\varphi(z, t)-\frac{1}{i} \int_{0}^{t} \frac{\beta(z, s)}{r(z)} d s\right| \leqslant C^{\prime}|t|^{\frac{1}{2}}
$$

If $\left|z-x_{0}\right|<\varkappa_{0} r\left(x_{0}\right)$ and if $\varkappa_{0}$ is small enough, we have

$$
\begin{gathered}
|\beta(z, s)| \leqslant \beta\left(x_{0}, s\right) \leqslant M^{\natural} r\left(x_{0}\right), \\
|r(z)| \geqslant \frac{1}{2} r\left(x_{0}\right),
\end{gathered}
$$

whence:

$$
|\varphi(z, t)| \leqslant 2\left|\int_{0}^{t} \frac{\beta\left(x_{0}, s\right)}{r\left(x_{0}\right)} d s\right|+2 M^{\natural}|t|+C^{\prime}|t|^{\xi} .
$$

But $\left|\int_{0}^{t} \beta\left(x_{0}, s\right) d s\right| \leqslant \sqrt{|t|} r\left(x_{0}\right)$, and therefore:

$$
\begin{equation*}
|\varphi(z, t)| \leqslant C^{\prime \prime}|t|^{\frac{1}{2}} . \tag{2.45}
\end{equation*}
$$

By Cauchy's inequalities:

$$
\left|\sum_{k=1}^{n} v^{k}(x) \frac{\partial \varphi}{\partial x^{k}}(x, t)\right| \leqslant \frac{1}{\kappa_{0} r(x)} \sup _{|z-x| \leqslant x_{0}(x)}|\varphi(z, t)|,
$$

and if $\chi_{0}$ is small enough, we derive (2.43) from (2.45).
Let us denote by $w(x, t)$ the left-hand side in (2.43). By integration of (2.41) with respect to $t$, between $t^{\prime}$ and $t$, we derive:

$$
\left|\varphi(x, t)-\varphi\left(x, t^{\prime}\right)+i \int_{t^{\prime}}^{t} \frac{\beta(x, s)}{r(x)} d s\right| \leqslant \int_{t^{\prime}}^{t} \frac{\beta(x, s)}{r(x)} w(x, s) d s
$$

Since, by (2.43), we have $w(x, s) \leqslant C_{1}| |^{\frac{1}{2}}$, we get indeed (2.44). Q.E.D.

## Appendix to Section 2

## Estimates for later use.

Lemma 2.4. To every $\alpha \in \mathbb{Z}_{+}^{n}$ there is a constant $C_{\alpha}>0$ such that

$$
\begin{equation*}
\left|\partial_{x}^{\alpha} v(x)\right| \leqslant C_{\alpha} r(x)^{-|x|}, \quad \forall x \in U_{0} \backslash \mathcal{N}_{0} . \tag{2.46}
\end{equation*}
$$

Proof. Let $x_{0} \in U_{0} \backslash \mathcal{N}_{0}$ be arbitrary. By the mean value theorem there is $t_{0},\left|t_{0}\right|<T$, such that $\left|\boldsymbol{b}\left(x_{0}, t_{0}\right)\right|=(1 / \sqrt{2 T}) r\left(x_{0}\right)(\neq 0)$.

For $x$ sufficiently near $x_{0}$ we may write $\boldsymbol{v}(x)=\boldsymbol{b}\left(x, t_{0}\right) /\left|\boldsymbol{b}\left(x, t_{0}\right)\right|$. The numerator, and the square of the denominator are $C^{\infty}$ functions in an open neighborhood of $\bar{U}_{0}$. Consequently, there is a constant $G_{\alpha}^{\prime}>0$, depending only on the derivatives of these functions (and not on $x_{0}$ ), such that, for $x$ near $x_{0}$,

$$
\begin{equation*}
\left|\partial^{\alpha} \boldsymbol{v}(x)\right| \leqslant C_{\alpha}^{\prime}\left|\boldsymbol{b}\left(x, t_{0}\right)\right|^{-|x|} \tag{2.47}
\end{equation*}
$$

Making $x=x_{0}$ in (2.47) yields (2.46) with $C_{\alpha}=C_{\alpha}^{\prime}(2 T)^{\mid \alpha / 2}$. $\quad$ Q.E.D.

Lemma 2.5. To every $\alpha \in \mathbb{Z}_{+}^{n}$ there is a constant $\tilde{C}_{\alpha}>0$ such that

$$
\begin{equation*}
\left|\partial_{x}^{\alpha} r(x)\right| \leqslant \tilde{C}_{\alpha} r(x)^{1-|\alpha|}, \quad \forall x \in U_{\mathbf{0}} \backslash \mathcal{N}_{0} . \tag{2.48}
\end{equation*}
$$

In particular, $r$ is uniformly Lipschitz continuous in $U_{0}$.
Indeed, $r^{2} \in C^{\infty}\left(\bar{U}_{0}\right)$.
Corollary 2.1. Given any $\alpha \in \mathbb{Z}_{+}^{n}$ there is a constant $\widetilde{\widetilde{O}}_{\alpha}>0$ such that

$$
\begin{equation*}
\left|\partial_{x}^{\alpha}[r(x) \boldsymbol{v}(x)]\right| \leqslant \widetilde{C}_{\alpha} r(x)^{1-|\alpha|}, \quad \forall x \in U_{0} \backslash \mathcal{N}_{0} \tag{2.49}
\end{equation*}
$$

In particular, the function equal to $r(x) v(x)$ in $U_{0} \backslash \mathcal{N}_{0}$ and to zero in $\mathcal{N}_{0}$ is uniformly Lipschitz continuous in $U_{0}$.

In the statements below $\varphi$ stands for the solution of (2.41)-(2.42).
Lemma 2.6. Given any $\alpha \in \mathbb{Z}_{+}^{n}$, there is a constant $C_{\alpha}^{\prime}>0$ such that

$$
\begin{equation*}
\left|\partial_{x}^{\alpha}\{X \varphi(x, t)\}\right| \leqslant C_{\alpha}^{\prime}|t|^{\frac{1}{2}} r(x)^{-\alpha-1}, \quad \forall x \in U_{0} \backslash \mathcal{N}_{0},|t|<T \tag{2.50}
\end{equation*}
$$

Proof. By Cauchy's inequalities and (2.45) we have (provided that $\varkappa_{0}$ is small enough):

$$
\begin{equation*}
\frac{1}{\alpha!}\left|\partial_{x}^{\alpha} \varphi(x, t)\right| \leqslant\left[\varkappa_{0} r(x)\right]^{-|\alpha|} \sup _{|z-x| \leqslant \varkappa_{0} r(x)}|\varphi(z, t)| \leqslant C^{\prime \prime} \varkappa_{0}^{-|\alpha|}|t|^{\frac{1}{2}} r(x)^{-|\alpha|} \tag{2.51}
\end{equation*}
$$

Combining (2.46) and (2.51) yields (2.50).
Corollary 2.2. $-\forall \alpha \in \mathbb{Z}_{+}^{n}$, there is a constant $\tilde{C}_{\alpha}^{\prime}>0$ such that

$$
\begin{equation*}
\left|\partial_{x}^{\alpha}\{r(x) X \varphi(x, t)\}\right| \leqslant C_{\alpha}^{\prime}|t|^{\frac{1}{2}} r(x)^{-|x|}, \quad \forall x \in U_{0} \backslash \mathcal{N}_{0},|t|<T \tag{2.52}
\end{equation*}
$$

Indeed, combine Lemmas 2.5 and 2.6.
Corollary 2.3. Whatever $f \in \mathscr{D}_{\text {r-flat }}(U)$, we also have $(r X \varphi) f \in \mathbb{D}_{r \text {-fat }}(U)$.

## 3. - Solution on the individual leaves.

In $U_{0} \backslash \mathcal{N}_{0}$ the vector field $X$ defined in (1.7), Ch. I ,

$$
\begin{equation*}
X=\sum_{j=1}^{n} v^{j}(x) \frac{\partial}{\partial x^{j}} \tag{3.1}
\end{equation*}
$$

is analytic and nowhere zero (see proof of Lemma 2.1). For any $x_{0} \in U_{0} \backslash \mathcal{N}_{0}$ we denote by $\Gamma_{x_{0}}$ the connected integral curve of $X$ through $x_{0}$, by $\Sigma_{x_{0}}$ the
two-dimensional «leaf» $\left.\Gamma_{x_{0}} \times\right]-T, T\left[\right.$. Writing $v=\left(v^{1}, \ldots, v^{n}\right)$ as before, let us denote by $x\left(\chi, x_{0}\right)$ the solution of the problem

$$
\begin{equation*}
\frac{d x}{d \chi}=r(x) \boldsymbol{v}(x),\left.\quad x\right|_{\chi=0}=x_{0} \tag{3.2}
\end{equation*}
$$

The function $r$ is defined in (1.2). The mapping

$$
\begin{equation*}
\chi \mapsto x\left(\chi, x_{0}\right) \tag{3.3}
\end{equation*}
$$

is a $C^{\infty}$ mapping and, in fact, a local diffeomorphism of an open interval $J\left(x_{0}\right)$ of $\mathbb{R}^{1}$ onto $\Gamma_{x_{0}}$. Conversely we may regard $\chi$ as a smooth function in a sufficiently small open arc in $\Gamma_{x_{0}}$, centered at $x_{0}$, specifically the solution of

$$
\begin{equation*}
r(x) X \chi=1,\left.\quad \chi\right|_{x=x_{0}}=0 \tag{3.4}
\end{equation*}
$$

Let us recall the standard relations, valid if $x, x_{1} \in \Gamma_{x_{0}}$ :

$$
\begin{align*}
& \chi\left(x_{0}, x_{1}\right)=-\chi\left(x_{1}, x_{0}\right)  \tag{3.5}\\
& \chi\left(x, x_{1}\right)=\chi\left(x, x_{0}\right)+\chi\left(x_{0}, x_{1}\right) \tag{3.6}
\end{align*}
$$

It is perhaps worth distinguishing the various possibilities:
(I) $\Gamma_{x_{0}}$ is a compact subset of $U_{0} \backslash \mathcal{N}_{0}$. This means that $x\left(\chi, x_{0}\right)$ is periodic with respect to $\chi$; then $J\left(x_{0}\right)=\mathbb{R}^{1}$ and (3.3) is a covering map;
(II) $\Gamma_{x_{0}}$ is noncompact in $U_{0} \backslash \mathcal{N}_{0}$; then (3.3) is a global diffeomorphism of $J\left(x_{0}\right)$ onto $\Gamma_{x_{0}}$.

In Case (II), $J\left(x_{0}\right)$ might have one finite boundary point in $\mathbb{R}^{1}$, two of them or none. But:

Lemma 3.1. If $J\left(x_{0}\right)$ has a finite boundary point $\chi_{0}$, then as $\chi \rightarrow \chi_{0}, x\left(\chi, x_{0}\right)$ goes to the boundary of $U_{0}$ (i.e., exits from every compact subset of $U_{0}$ ).

Proof. By Cor. 2.1 we know that $\left|r(x) \boldsymbol{v}(x)-r\left(x^{\prime}\right) \boldsymbol{v}\left(x^{\prime}\right)\right| \leqslant K\left|x-x^{\prime}\right|$ for some $K<+\infty$ and all $x, x^{\prime} \in U_{0}$. By the Picard iteration method applied to (3.2) we obtain

$$
\begin{equation*}
\left|x_{1}-x_{0}\right| \leqslant r\left(x_{1}\right)\left(\exp \left[K\left|\chi\left(x_{0}, x_{1}\right)\right|\right]-1\right) \tag{3.7}
\end{equation*}
$$

(we have tacitly exploited (3.5)). Suppose then that $\chi\left(x_{0}, x_{1}\right) \rightarrow \chi_{0} \in \partial J\left(x_{0}\right)$, $\left|\chi_{0}\right|<+\infty$; clearly we cannot have $r\left(x_{1}\right) \rightarrow 0$. On the other hand, since $r(x) X$ does not vanish in $U_{0} \backslash \mathcal{N}_{0}, x_{1}$ must go to the boundary of $U_{0} \backslash \mathcal{N}_{0}$, whence the conclusion.

An equivalent interpretation of Lemma 3.1 is that taking $\chi$ as the parameter on an integral curve $\Gamma_{x_{0}}$ of $X$ amounts to changing the metric along $\Gamma_{x_{0}}$ in such a way that the distance (for the new metric) from $x_{0}$ to $x$ tends to $+\infty$ whenever $x$ tends to $\mathcal{N}_{0}$. Actually the reasons for using $\begin{array}{r}r(x) \\ T\end{array}$ are even subtler than this, for using $\int_{-T}^{T}|\boldsymbol{b}(x, s)| d s$ instead of $r(x)=\left(\int_{-T}^{T}|\boldsymbol{b}(x, s)|^{2} d s\right)^{\frac{1}{2}}$ would also have had the preceding implication, but would not have had the consequence, repeatedly needed (cf., e.g., (2.43) and its proof), that

$$
\begin{equation*}
\frac{1}{r(x)} \int_{-T}^{T}|\boldsymbol{b}(x, s)| d s \tag{3.8}
\end{equation*}
$$

converges to zero with $T$.
Let then $\varphi$ be the phase-function of Lemma 2.3. We set

$$
z(x, t)=\chi\left(x, x_{0}\right)+\varphi(x, t), \quad x \in \Gamma_{x_{0}},|t|<T .
$$

(We should rather write $z\left(x, x_{0}, t\right)$ for indeed $z$ depends on $x_{0}$ ). Let us also write

$$
\omega(x, t)=|\boldsymbol{b}(x, t)| \mid r(x),
$$

whence

$$
\begin{equation*}
L=\frac{\partial}{\partial t}+i \omega(x, t) r(x) X . \tag{3.9}
\end{equation*}
$$

If we take (2.41) and (3.4) into account we see that

$$
\begin{equation*}
L z=0 \tag{3.10}
\end{equation*}
$$

and by (2.42), that

$$
\begin{equation*}
\left.z\right|_{t=0}=\chi\left(x, x_{0}\right) . \tag{3.11}
\end{equation*}
$$

We consider then the mapping

$$
\begin{equation*}
(\chi, t) \mapsto z=\chi+\varphi\left(x\left(\chi, x_{0}\right), t\right) . \tag{3.12}
\end{equation*}
$$

It is a $C^{\infty}$ mapping of the "slab"

$$
\begin{equation*}
\left.S\left(x_{0}\right)=J\left(x_{0}\right) \times\right]-T, T[ \tag{3.13}
\end{equation*}
$$

into $\mathbb{R}^{2}$. The following result provides, in a sense, another interpretation of the local solvability condition (P):

Lemma 3.2. If $T>0$ is small enough, the mapping (3.12) is a homeomorphism of $S\left(x_{0}\right)$ onto an open subset of $\mathbb{R}^{2}$. Its Jacobian determinant is given by

$$
\begin{equation*}
\frac{D(\operatorname{Re} x, \operatorname{Im} z)}{D(\chi, t)}=-\omega|1+r X \varphi|^{2} \tag{3.14}
\end{equation*}
$$

Proof. By (3.10) we have $z_{t}=-i|\boldsymbol{b}| X z$, hence $\bar{z}_{t}=i|\boldsymbol{b}| X \bar{z}$, and therefore

$$
\begin{equation*}
(\operatorname{Re} z)_{t}=|\boldsymbol{b}| X(\operatorname{Im} z), \quad(\operatorname{Im} z)_{t}=-|\boldsymbol{b}| X(\operatorname{re} z) \tag{3.15}
\end{equation*}
$$

By (3.4) we have $r(x) X=\partial / \partial \chi$, hence

$$
\begin{equation*}
(\operatorname{Re} z)_{t}=\omega \frac{\partial}{\partial \chi}(\operatorname{Im} z), \quad(\operatorname{Im} z)_{t}=-\omega \frac{\partial}{\partial \chi}(\operatorname{Re} z) \tag{3.16}
\end{equation*}
$$

and therefore

$$
\begin{equation*}
\frac{D(\operatorname{Re} z, \operatorname{Im} z)}{D(\chi, t)}=-\omega\left|\frac{\partial z}{\partial \chi}\right|^{2} \tag{3.17}
\end{equation*}
$$

By (3.8), $\partial z / \partial \chi=1+r \bar{X} \varphi$, whence (3.14).
In order to prove that (3.12) is a homeomorphism, it suffices to prove that it is injective. Suppose that

$$
\begin{equation*}
\chi+\varphi\left(x\left(\chi, x_{0}\right), t\right)=\chi^{\prime}+\varphi\left(x\left(\chi^{\prime}, x_{0}\right), t^{\prime}\right), \tag{3.18}
\end{equation*}
$$

that is:

$$
\begin{align*}
\left(\chi-\chi^{\prime}\right)+\left[\varphi\left(x\left(\chi, x_{0}\right), t\right)-\varphi( \right. & \left.\left.\left(\chi^{\prime}, x_{0}\right), t\right)\right]+  \tag{3.19}\\
& +\left[\varphi\left(x\left(\chi^{\prime}, x_{0}\right), t\right)-\varphi\left(x\left(\chi^{\prime}, x_{0}\right), t^{\prime}\right)\right]=0 .
\end{align*}
$$

By (3.4) and (2.43) we have:

$$
\begin{equation*}
\left|\varphi\left(x\left(\chi, x_{0}\right), t\right)-\varphi\left(x\left(\chi^{\prime}, x_{0}\right), t\right)\right| \leqslant\left|\int_{\chi^{\prime}}^{\chi}(r X \varphi)\left(x\left(s, x_{0}\right), t\right) d s\right| \leqslant C_{1}|t|^{\frac{1}{2}}\left|\chi-\chi^{\prime}\right| \tag{3.20}
\end{equation*}
$$

Concerning the third term in the left－hand side of（3．19）we apply（2．44）with $x=x\left(\chi^{\prime}, x_{0}\right)$ ，obtaining

$$
\left|\varphi(x, t)-\varphi\left(x, t^{\prime}\right)-\frac{1}{i} \int_{t^{\prime}}^{t} \omega(x, s) d s\right| \leqslant C_{1} \sqrt{ } \bar{T}\left|\int_{t^{\prime}}^{t} \omega(x, s) d s\right|,
$$

which，combined with（3．19）and（3．20），yields

$$
\begin{equation*}
\left|\left(\chi-\chi^{\prime}\right)+i \int_{t^{\prime}}^{t} \omega(x, s) d s\right| \leqslant C_{1} \sqrt{T}\left\{\left|\chi-\chi^{\prime}\right|+\left|\int_{t^{\prime}}^{t} \omega(x, s) d s\right|\right\} \tag{3.21}
\end{equation*}
$$

Therefore，if $C_{1} \sqrt{T}<\frac{1}{2}$ ，we must have：

$$
\begin{equation*}
\chi=\chi^{\prime}, \quad \int_{t^{\prime}}^{t} \omega(x, s) d s=0 \tag{3.22}
\end{equation*}
$$

But（by definition of $U_{0} \backslash \mathcal{N}_{0}$ and by the analyticity of $\boldsymbol{b}(x, t)$ with respect to $t) \omega(x, s)>0$ in any compact subinterval of $]-T, T[$ ，except possibly at a finite number of points．Therefore the second equation in（3．22）implies $t=t^{\prime}$ ．Q．E．D．

We look now at the effect of the mapping（3．12）on the operator $L$ ．Since $L=(L z) \partial_{z}+(L \bar{z}) \partial_{\bar{z}}$, hence，by（3．10），

$$
\begin{equation*}
L=(L \bar{z}) \partial_{\bar{z}} \tag{3.23}
\end{equation*}
$$

But（cf．（3．8）－（3．16）），$L \bar{z}=-2 i \omega X \bar{z}$ ，hence

$$
\begin{equation*}
L=-2 i \omega(1+r X \bar{\varphi}) \partial_{\bar{z}} \tag{3.24}
\end{equation*}
$$

Consider now an arbitrary function $f \in \mathscr{D}_{r \text {－fiat }}(U)$ ．If $x_{0} \in U_{0} \backslash \mathcal{N}_{0}$ ，by re－ striction $f$ defines a smooth function $f^{\hbar}\left(x, t ; x_{0}\right)$ on the leaf $\Sigma_{x}$ ．Via the mapping（3．3），$\chi \mapsto x\left(\chi, x_{0}\right), f^{\natural}\left(x, t ; x_{0}\right)$ defines a function $f^{\text {म月 }}\left(\chi, t ; x_{0}\right)$ in the slab（3．13），$\left.S\left(x_{0}\right)=J\left(x_{0}\right) \times\right]-T, T\left[\right.$ ．We observe that $f^{\text {能 }} \in C^{\infty}\left(S\left(x_{0}\right)\right)$ and we list a number of properties of $f^{\text {an }}$ ：
（3．25）the projection of the support of $f^{\text {月h }}$ on the $t$－axis is contained in a compact subset of $]-T, T[$ ；

$$
\begin{equation*}
\sup _{(\chi, t) \in S\left(x_{0}\right)} \mid f \text { मी }\left(\chi, t ; x_{0}\right) \mid<+\infty ; \tag{3.26}
\end{equation*}
$$

（3．27）if $J\left(x_{0}\right)$ has a finite boundary point $\chi_{0}, f^{\text {朋 }} \equiv 0$ in a full neigh－ borhood of $\left.\left\{\chi_{0}\right\} \times\right]-T, T[$ ．

Suppose now that $x_{1}$ is another point on the orbit $\Gamma_{x_{0}}$ of $x_{0}$ ：In view of（3．7）we have：

$$
\begin{equation*}
f^{\text {䶺 }}\left(\chi, t ; x_{1}\right)=f^{\text {吅 }}\left(\chi+\chi\left(x_{0}, x_{1}\right), t ; x_{0}\right) . \tag{3.28}
\end{equation*}
$$

Let now $O\left(x_{0}\right)$ be the open subset of $\mathbb{C}$ which is the image of the slab $S\left(x_{0}\right)$（in（3．13））under the mapping（3．12）．By Lemma 3.1 we may define a continuous bounded function in $O\left(x_{0}\right)$ ，

$$
\begin{equation*}
\tilde{f}\left(z ; x_{0}\right)=f^{\text {朐 }}\left(\chi, t ; x_{0}\right) \tag{3.29}
\end{equation*}
$$

where $(\chi, t) \in S\left(x_{0}\right)$ corresponds to $z$ by the inverse homeomorphism of（3．12）． We come now to the solution，in the leaf $\Sigma_{x_{0}}$ ，of the equation

$$
\begin{equation*}
L u=f \in \mathfrak{D}_{r \cdot \mathrm{ffat}}(U) \tag{3.30}
\end{equation*}
$$

Let us set $u(x, t)=v(x, t)+\int_{-T}^{t} f(x, s) d s$ ．The function $v$ must be a solution of

$$
\begin{equation*}
L v=-i \sum_{j=1}^{n} b^{j}(x, t) \int_{-T}^{t} \frac{\partial f}{\partial x^{j}}(x, s) d s \tag{3.31}
\end{equation*}
$$

We observe that the right－hand side in（3．31）belongs to $\mathcal{E}_{r-\mathrm{flat}}(U)$（it might fail to have a compact support with respect to $t$ ）but also that it vanishes wherever $|\boldsymbol{b}(x, t)|$ does．After multiplication by a cut－off function of $t$ ，we may assume that，in（3．31），the right－hand side is equal to

$$
\begin{equation*}
|\boldsymbol{b}| X g, \quad g \in \mathscr{D}_{r-\mathrm{flat}}(U) \tag{3.32}
\end{equation*}
$$

We switch now to the coordinates $(\operatorname{Re} z, \operatorname{Im} z)$ on the leaf $\Sigma_{x_{0}}$ ．By virtue of（3．24）we must now solve

$$
\begin{equation*}
\partial_{\bar{z}} \tilde{v}=\frac{i}{2}\left[(1+r X \tilde{\varphi})^{-1}(r X g)\right]^{\sim} \quad \text { in } O\left(x_{0}\right) \tag{3.33}
\end{equation*}
$$

It follows at once from Cor． 2.3 that the right－hand side in（3．33）is of the form $\widetilde{F}\left(z ; x_{0}\right)$ for an obvious $F \in \mathscr{D}_{r \text {－flat }}(U)$ ．We shall therefore write the in－ tegral expression of a solution $\tilde{v}$ of（3．33），that is，of

$$
\begin{equation*}
\partial_{\bar{z}} \tilde{v}=\tilde{F} \quad \text { in } O\left(x_{0}\right) \tag{3.34}
\end{equation*}
$$

In order to handle in a «uniform» manner all possible kinds of righthand sides $\widetilde{F}$, periodic, almost-periodic (at one end or at both), fastly decaying at infinity (also at one end or at both), etc., corresponding to the various kinds of orbits $\Gamma_{x_{0}}$ (cf. Fig. 1), we shall use a special fundamental solution


Fig. 1. - Examples of orbits of the vector field $X$ in two space dimension.
of $\partial / \partial \bar{z}$. This will be possible thanks to Property (3.25) and to the fact that the open set $O\left(x_{0}\right)$ is contained in a slab $|\operatorname{Im} z| \leqslant$ const. $T$. We observe that, if $h(z)$ is any entire function such that $h(0)=1$, we have

$$
\begin{equation*}
\left.\frac{\partial}{\partial \bar{z}}\left(\frac{h(z)}{\pi z}\right)=\delta \quad \text { (the Dirac measure in } \boldsymbol{R}^{2}\right) \tag{3.35}
\end{equation*}
$$

and we choose

$$
h(z)=\exp \left[-z^{2}\right],
$$

solving then (3.34) by

$$
\begin{equation*}
\tilde{v}\left(z ; x_{0}\right)=\frac{1}{\pi} \iint \frac{\exp \left[-\left(z-z^{\prime}\right)^{2}\right]}{z-z^{\prime}} \tilde{F}\left(z^{\prime} ; x_{0}\right) d\left(\operatorname{Re} z^{\prime}\right) d\left(\operatorname{Im} z^{\prime}\right) \tag{3.36}
\end{equation*}
$$

1) Convergence of the integral in (3.36).

We take a closer look at the open set $O\left(x_{0}\right)$, image of $S\left(x_{0}\right)=J\left(x_{0}\right) \times$ $\times]-T, T$ [ under the map $(\chi, t) \mapsto z=\chi+\varphi\left(x\left(\chi, x_{0}\right), t\right)$. From (2.44) (where we take $t^{\prime}=0$ ) we derive

$$
\begin{equation*}
\left|\varphi(x, t)+i \int_{0}^{t} \omega(x, s) d s\right| \leqslant C_{1} \sqrt{|t|}\left|\int_{0}^{t} \omega(x, s) d s\right| \tag{3.37}
\end{equation*}
$$

Note also that, whatever $x \in U_{0} \backslash \mathcal{N}_{0}$ and $t, 0<|t|<T$,

$$
\begin{equation*}
0<\left|\int_{0}^{t} \omega(x, s) d s\right| \leqslant \sqrt{|t|}\left(\int_{-T}^{T} \omega(x, s)^{2} d s\right)^{\frac{t}{2}}=\sqrt{|t|} \tag{3.38}
\end{equation*}
$$

We reach easily the following conclusions:
$O\left(x_{0}\right)$ is contained in the slab $\left\{z ;|\operatorname{Im} z| \leqslant \sqrt{T}+C_{1} T\right\} ;$
(3.40) If $\left.J\left(x_{0}\right) \subset\right] \chi_{0},+\infty\left[, O\left(x_{0}\right)\right.$ is contained in a half-space
$\operatorname{Re} z>\tilde{\chi}_{0}>-\infty$; if $\left.J\left(x_{0}\right) \subset\right]-\infty, \chi_{0}\left[, O\left(x_{0}\right) \subset\left\{z ; \operatorname{Re} z<\tilde{\chi}_{0}<+\infty\right\}\right.$.
(3.41) If $J\left(x_{0}\right)=\mathbb{R}^{1}, O\left(x_{0}\right)$ is an open neighborhood of the real axis in the z-plane.

Suppose that $z$ tends to the boundary of $O\left(x_{0}\right)$; this means (by Lemma 3.2) that $(\chi, t)$ tends to the boundary of $S\left(x_{0}\right)$. If then $F \in \mathscr{D}_{r \text {.flat }}(U)$ and $|t| \rightarrow T$, $F(x(\chi, t), t)$ will eventually be zero. If $|t|$ remains $\leqslant T^{\prime}<T$ then $\chi$ must tend either to $\pm \infty$ or to a finite boundary point $\chi_{0}$ of $J\left(x_{0}\right)$. By (3.27) we see that, also in the latter case, $F(x(\chi, t), t)$ will eventually be zero. This is not necessarily so when $\chi_{0} \rightarrow \pm \infty$ for then $x\left(\chi, x_{0}\right)$ might very well remain in a compact subset of $U_{0} \backslash \mathcal{N}_{0}$. But at any rate, if we denote by $\partial O\left(x_{0}\right)$ the boundary of $O\left(x_{0}\right)$ in the complex plane, that is, excluding the points at infinity, we see that
(3.42) whatever $F \in \mathcal{D}_{r \text {-fiat }}(U), \tilde{F}(z, t)$ vanishes in a neighborhood of $\partial O\left(x_{0}\right)$.

We see that $\tilde{F}$ can then be extended as a $C^{\infty}$ function in $\mathbb{R}^{2}$, which is bounded. Since $\exp \left[-z^{2}\right] / \pi z$ is integrable in every slab $|\operatorname{Im} z|<$ const. the convolu-
tion at the right in（3．36）defines a $C^{\infty}$ function in $\mathbb{R}^{2}$ ，which is bounded in every horizontal slab．

2）Formula（3．36）defines a function on the leaf $\Sigma_{x_{0}}$ ．
In the double integral at the right，in（3．36），we switch from the co－ ordinates $(\operatorname{Re} z, \operatorname{Im} z)$ to $(\chi, t)$ ．We set $\chi=\chi\left(x, x_{0}\right), \chi^{\prime}=\chi\left(x^{\prime}, x_{0}\right)$ ．The Jacobian determinant is given by（3．14）and we have $F=-(1 / 2 i)$ ． $\cdot(1+r X \bar{\varphi})^{-1}(r X g)$ ；the integral under consideration can be rewritten as

$$
\begin{align*}
\frac{-1}{2 \pi i} \iint \frac{\exp \left[-\left(z-z^{\prime}\right)^{2}\right]}{z-z^{\prime}}(r X g) \text { 印 }\left(\chi^{\prime},\right. & \left.t^{\prime} ; x_{0}\right)  \tag{3.43}\\
\cdot & {\left[1+(r X g)\left(x\left(\chi^{\prime}, x_{0}\right), t^{\prime}\right)\right] d \chi^{\prime} d t^{\prime} }
\end{align*}
$$

where

$$
\begin{equation*}
z=\chi+\varphi\left(x\left(\chi, x_{0}\right), t\right), \quad z^{\prime}=\chi^{\prime}+\varphi\left(x\left(\chi^{\prime}, x_{0}\right), t^{\prime}\right) \tag{3.44}
\end{equation*}
$$

The integration in（3．43）is performed over $S\left(x_{0}\right)$ or，which amounts to the same，over $\mathbb{R}^{2}$（since（ $\left.r X g\right)^{\text {国 }}$ vanishes identically in a neighborhood of $\partial S\left(x_{0}\right)$ ）． Let us denote by $v^{\natural \emptyset}\left(\chi, t ; x_{0}\right)$ the transfer of $\tilde{v}\left(z ; x_{0}\right)$ under the homeomor－ phism（3．12）；it is equal to（3．43）．We must check that $v^{\text {朋 }}\left(\chi, t ; x_{0}\right)$ is indeed the image，under the map（3．3），of a function $v^{\natural}\left(x, t ; x_{0}\right)$ on the leaf $\Sigma_{x_{0}}$ ．

For simplicity let us set

$$
\begin{equation*}
E(z)=\frac{1}{2 \pi i} \frac{\exp \left[-z^{2}\right]}{z}, \quad x=x\left(\chi, x_{0}\right), \quad x^{\prime}=x\left(\chi^{\prime}, x_{0}\right) \tag{3.45}
\end{equation*}
$$

We have：

$$
\begin{align*}
& v^{\text {朋 }}\left(\chi, t ; x_{0}\right)=  \tag{3.46}\\
& -\iint E\left[\chi-\chi^{\prime}+\varphi(x, t)-\varphi\left(x^{\prime}, t^{\prime}\right)\right](r X g)\left(x^{\prime}, t^{\prime}\right)\left[1+r\left(x^{\prime}\right) X \varphi\left(x^{\prime}, t^{\prime}\right)\right] d \chi^{\prime} d t^{\prime} .
\end{align*}
$$

We apply（3．5）－（3．6）：

$$
\begin{equation*}
\chi-\chi^{\prime}=\chi\left(x, x^{\prime}\right) \tag{3.47}
\end{equation*}
$$

We may also write

$$
\begin{equation*}
d \chi^{\prime}=-d\left[\chi\left(x, x^{\prime}\right)\right] \tag{3.48}
\end{equation*}
$$

regarding $x$ as fixed（or as a parameter）．Since $\Sigma_{x_{0}}=\Sigma_{x}$ in what precedes， we may define the following function of $(x, t), x \in U_{0} \backslash \mathcal{N}_{0},|t|<T$ ：

$$
\begin{align*}
& v(x, t)=\int_{\Sigma_{x}} \int E\left[\chi\left(x, x^{\prime}\right)+\varphi(x, t)-\varphi\left(x^{\prime}, t^{\prime}\right)\right](r X g)\left(x^{\prime}, t^{\prime}\right)  \tag{3.49}\\
& \cdot {\left[1+r\left(x^{\prime}\right) X \varphi\left(x^{\prime}, t^{\prime}\right)\right] d \chi\left(x, x^{\prime}\right) d t^{\prime} }
\end{align*}
$$

Then $v^{\natural \natural}\left(\chi, t ; x_{0}\right)$ is the image under (3.3) of the restriction $v^{\natural}\left(x, t ; x_{0}\right)$ of $v(x, t)$ to $\Sigma_{x_{0}}$.

In the next section we prove that, after setting $v(x, t)=0$ when $x \in \mathcal{N}_{0}$, we have $v \in \mathcal{E}_{r \text { rfat }}(U)$. By taking then, in (3.49),

$$
g(x, t)=-i \zeta(t) \int_{-T}^{t} f(x, s) d s
$$

$\left[\zeta \in \mathbb{C}^{\infty}\left(\mathbb{R}^{1}\right), \zeta(t)=1\right.$ if $t \leqq T^{\prime}<T, \zeta(t)=0$ if $\left.t>\frac{1}{2}\left(T+T^{\prime}\right)\right]$, we obtain the solution $u=v+g$ of (3.30) in $\left.U^{\prime}=U_{0} \times\right]-T^{\prime}, T^{\prime}[$, with the required properties $\left(f \mapsto u\right.$ defines a linear operator $\mathscr{D}_{r \text {-flat }}\left(U^{\prime}\right) \rightarrow \mathcal{E}_{r \text {-flat }}\left(U^{\prime}\right)$, which can be given an explicit integral representation; the estimates in Sect. 4 easily imply the continuity of this operator).

## 4. - Smoothness and flatness of the solution.

We begin by simplifying the expression (3.49). We take $\chi=\chi\left(x, x^{\prime}\right)$ as one of the two integration variables at the right (the other remains $t^{\prime}$ ), and regard $x^{\prime}$ as a function of $(\chi, x)$, defined as the solution of

$$
\begin{equation*}
\frac{d x^{\prime}}{d \chi}=-r\left(x^{\prime}\right) \boldsymbol{v}\left(x^{\prime}\right),\left.\quad x^{\prime}\right|_{\chi=0}=x \tag{4.1}
\end{equation*}
$$

It is convenient to let $\left(\chi, t^{\prime}\right)$ vary in the whole plane, although $x^{\prime}$ is not defined for all $\chi$ but only for those belonging to $-J(x)$. But we have seen (Lemma 3.1) that if $J(x) \neq \mathbf{R}^{1}$ and if $\chi_{0}$ is a boundary point of $J(x)$, then as $\chi \rightarrow-\chi_{0}$ (while $x$ remains fixed), $x^{\prime}$ will exit from any compact subset of $U_{0}$, in particular from the support of $g(\cdot, t)$. And by the standard results on ODES, as long as $x^{\prime}$ remains away from the boundary of $U_{0}$, it is a $C^{\infty}$ function of $(\chi, x)$ ( $x$ remains in $U_{0} \backslash \mathcal{N}_{0}$ ). Let us set

$$
\begin{equation*}
w=W(x ; \chi, t)=\left[1+r\left(x^{\prime}\right) X \varphi\left(x^{\prime}, t\right)\right] r\left(x^{\prime}\right) X g\left(x^{\prime}, t\right) ; \tag{4.2}
\end{equation*}
$$

also

$$
\begin{equation*}
Z=Z\left(x, t ; \chi, t^{\prime}\right)=\chi+\varphi(x, t)-\varphi\left(x^{\prime}, t^{\prime}\right) \tag{4.3}
\end{equation*}
$$

With this notation (3.49) reads

$$
\begin{equation*}
v(x, t)=\iint E\left[Z\left(x, t ; \chi, t^{\prime}\right)\right] \mathfrak{W}\left(x ; \chi, t^{\prime}\right) d \chi d t^{\prime} \tag{4.4}
\end{equation*}
$$

The integration in (4.4) is performed over $\mathbb{R}^{2} ;(x, t)$ ranges over $\left(U_{0} \backslash \mathcal{N}_{0}\right) \times$ $\times]-T, T$.

We avail ourselves of the following facts:
(4.5) $W$ is a $C^{\infty}$ function of $(x, \chi, t)$ in $\left.\left(U_{0} \backslash \mathcal{N}_{0}\right) \times \mathbb{R}^{1} \times\right]-T, T[$;
(4.6) $W$ is bounded;
(4.7) the projection on the $t$-axis of supp $\mathfrak{W}$ is contained in a compact subinterval of $]-T, T[$.

On the other hand, we derive from (2.43)

$$
\begin{equation*}
\left|\varphi\left(x, t^{\prime}\right)-\varphi\left(x^{\prime}, t^{\prime}\right)\right| \leqslant C_{0}^{\prime}|t|^{\frac{1}{2}} \chi\left(x, x^{\prime}\right) \tag{4.8}
\end{equation*}
$$

where $x \in U_{0} \backslash \mathcal{N}_{0}, x^{\prime} \in \Gamma_{x},\left|t^{\prime}\right|<T$; we may rewrite (2.44) as

$$
\begin{equation*}
\left|\varphi(x, t)-\varphi\left(x, t^{\prime}\right)+i \int_{i^{\prime}}^{t} \omega(x, s) d s\right| \leqslant C_{1} \sqrt{ } \bar{T}\left|\int_{i^{\prime}}^{t} \omega(x, s) d s\right| \tag{4.9}
\end{equation*}
$$

(here $|t|<T$ ), and by combining (4.8) and (4.9) we see that

$$
\begin{equation*}
\left|Z-\left\{\chi-i \int_{i^{\prime}}^{t} \omega(x, s) d s\right\}\right| \leqslant C \sqrt{T}\left|\chi-i \int_{i^{\prime}}^{t} \omega(x, s) d s\right| \tag{4.10}
\end{equation*}
$$

From all this it follows easily that $v$, given by (4.4), is a continuous function of $(x, t)$ in $\left.\left(U_{0} \backslash \mathcal{N}_{0}\right) \times\right]-T, T[$ (provided that $C \sqrt{T}$, in (4.10), be $<1$, which we may assume). We are now going to prove that it is a $C^{\infty}$ function of $(x, t)$ in that set and, at the end, that it is $r$-flat.

We shall need the following:
Lemma 4.1. To every $\alpha \in \mathbb{Z}_{+}^{n}, k \in \mathbb{Z}_{+}$, there are constants $C_{\alpha, k}, M_{\alpha, k}>0$ and an integer $d_{\alpha, k} \in \mathbb{Z}$ such that

$$
\begin{equation*}
\left|\partial_{x}^{\alpha} \partial_{\chi}^{k} x^{\prime}\right| \leqslant C_{\alpha, k} r\left(x^{\prime}\right)^{-d_{\alpha, k}} \exp \left(M_{\alpha, k}|\chi|\right) \tag{4.11}
\end{equation*}
$$

for all $x \in U_{0} \backslash \mathcal{N}_{0}, \chi \in-J(x)$.
Proof. The case $\alpha=0, k=0$ follows at once from (3.7), since

$$
\begin{equation*}
\left|x^{\prime}-x\right| \leqslant r\left(x^{\prime}\right)(\exp [K|\chi|]-1) \tag{4.12}
\end{equation*}
$$

Let us differentiate (4.1) with respect to $\chi$ and to $x$. If we set $\theta_{\alpha, k}=\partial_{x}^{\alpha} \partial_{\chi}^{k} x^{\prime}$, we obtain

$$
\begin{equation*}
\partial_{\chi} \theta_{\alpha, k}=\left[\partial_{x}(r \boldsymbol{v})\right]\left(x^{\prime}\right) \theta_{\alpha, k}+\sum_{|\beta| \leqslant|\alpha|+k}\left[\partial_{x}^{\beta}(r v)\right]\left(x^{\prime}\right) \mathscr{T}_{\alpha, \beta, k}(\theta), \tag{4.13}
\end{equation*}
$$

where $\int_{x, \beta, k}(\theta)$ denotes a polynomial with respect to the variables $\theta_{\gamma, l}$ with $\gamma_{j} \leqslant \alpha_{j}(j=1, \ldots, n), l \leqslant k$, and $|\gamma|+l<|\alpha|+k$. We apply Cor. 2.1, obtaining

$$
\begin{equation*}
\left|\partial_{\chi} \theta_{\alpha, k}\right| \leqslant C\left|\theta_{\alpha, k}\right|+\sum_{|\beta| \leqslant|\alpha|+k} \widetilde{\widetilde{C}} r\left(x^{\prime}\right)^{1-|\beta|}\left|T_{\alpha, \beta, k}(\theta)\right| \tag{4.14}
\end{equation*}
$$

We shall reason by induction on $|\alpha|$ and on $k$. First assume $k=0$. Then to (4.14) we may adjoin the initial conditions

$$
\begin{equation*}
\left.\theta_{\alpha, 0}\right|_{x=0}=\partial_{x}^{\alpha} x \tag{4.15}
\end{equation*}
$$

Thus, if $|\alpha|=1$ (in which case $\mathcal{T}_{\alpha, \beta, 0}(\theta) \equiv 0$ ), we obtain at once

$$
\begin{equation*}
\left|\theta_{\alpha, 0}\right| \leqslant \exp [C|\chi|] \tag{4.16}
\end{equation*}
$$

For $|\alpha|>1$, the right-hand side in (4.15) is zero. By induction on $|\alpha|$ we derive from (4.14)

$$
\begin{equation*}
\left|\partial_{\chi} \theta_{\alpha, 0}\right| \leqslant C\left|\theta_{\alpha, 0}\right|+C_{\alpha}^{\prime} r\left(x^{\prime}\right)^{-d_{\alpha}} \exp \left[M_{\alpha}|\chi|\right] \tag{4.17}
\end{equation*}
$$

We apply then Gronwall's inequality and obtain

$$
\begin{equation*}
\left|\theta_{\alpha, 0}\right| \leqslant C_{\alpha, 0} r\left(x^{\prime}\right)^{-d_{\alpha, 0}} \exp \left[M_{\alpha, 0}|\chi|\right] \tag{4.18}
\end{equation*}
$$

It suffices now to observe that the left-hand side in (4.14) can be rewritten as $\left|\theta_{\alpha . k+1}\right|$ and to reason by induction on $k$. Q.E.D.

We shall now differentiate $v$ (given by (4.4)) with respect to ( $x, t$ ). But since

$$
\begin{equation*}
\partial_{t} v-i|\boldsymbol{b}(x, t)| X v=|\boldsymbol{b}(x, t)| X g \tag{4.19}
\end{equation*}
$$

(see (3.31), (3.32)), it suffices to consider the derivatives of $v$ with respect to $x$. We have

$$
\begin{equation*}
\partial_{x}^{\alpha} v=\sum_{\alpha^{\prime} \leqslant \alpha}\binom{\alpha}{\alpha^{\prime}} \iint \partial_{\alpha^{\prime}}^{x}[E(Z)] \partial_{x}^{\alpha-\alpha^{\prime}} w\left(x ; \mathbb{Z}, t^{\prime}\right) d \chi d t^{\prime} \tag{4.20}
\end{equation*}
$$

where $\alpha^{\prime} \leqslant \alpha$ means $\alpha_{j}^{\prime} \leqslant \alpha_{j}$ for all $j=1, \ldots, n$. First, if $\left|\alpha^{\prime}\right| \geqslant 1$,

$$
\begin{equation*}
\partial_{x}^{\alpha^{\prime}} E(Z)=\sum_{j=1}^{\left|\alpha^{\prime}\right|} E^{(j)}(Z) \mathscr{T}_{j}\left(\partial_{x}^{\beta} Z\right) \tag{4.21}
\end{equation*}
$$

where $\mathscr{T}_{j}\left(\partial_{x}^{\beta} Z\right)$ is a polynomial with respect to the derivatives of $Z$ with respect to $x$, of order $\beta, 0<|\beta| \leqslant\left|\alpha^{\prime}\right|$. Since $Z=\chi+\varphi(x, t)-\varphi\left(x^{\prime}, t^{\prime}\right)$, we have

$$
\begin{equation*}
\partial_{x}=\left[1-\partial_{x} \varphi\left(x^{\prime}, t^{\prime}\right)\right] \partial_{z} \tag{4.22}
\end{equation*}
$$

and, by (4.1),

$$
\partial_{x} \varphi\left(x^{\prime}, t^{\prime}\right)=\varphi_{x}\left(x^{\prime}, t^{\prime}\right) \frac{\partial x^{\prime}}{\partial \chi}=-r\left(x^{\prime}\right) \sum v^{j}\left(x^{\prime}\right) \frac{\partial \varphi}{\partial x^{j}}\left(x^{\prime}, t^{\prime}\right)
$$

We apply once again (2.43); if $T>0$ is small enough,

$$
\begin{equation*}
\left|\partial_{\chi} \varphi\left(x^{\prime}, t^{\prime}\right)\right| \leqslant C_{1} \sqrt{T}<1 \tag{4.23}
\end{equation*}
$$

and $\left[1-\partial_{\chi} \varphi\left(x^{\prime}, t^{\prime}\right)\right]$ is invertible. Thus, by iteration,

$$
\begin{equation*}
E^{(j)}(Z)=\left(\frac{1}{1-\partial_{\chi} \varphi\left(x^{\prime}, t^{\prime}\right)} \frac{\partial}{\partial \chi}\right)^{j} E(Z) \tag{4.24}
\end{equation*}
$$

and thus, after integration by parts [which is legitimate: see remark following (4.33)], we see that $\partial_{x}^{\alpha} v$ is a linear combination of terms of the form

$$
\begin{equation*}
\iint E(Z)\left\{\frac{\partial}{\partial \chi}\left[\frac{-1}{1-\partial_{\chi} \varphi\left(x^{\prime}, t^{\prime}\right)}\right]\right\}^{j}\left[\mathscr{T}_{j}\left(\partial_{x}^{\beta} Z\right) \partial_{x}^{\alpha-\alpha^{\prime}} \mathscr{W}\left(x ; \chi, t^{\prime}\right)\right] d \chi d t^{\prime} \tag{4.25}
\end{equation*}
$$

We note that

$$
\begin{equation*}
\partial_{x}^{\beta} Z=\partial_{x}^{\beta} \varphi(x, t)-\sum_{\gamma \leqslant \beta}\left(\partial_{x}^{\gamma} \varphi\right)\left(x^{\prime}, t^{\prime}\right) \mathcal{Q}_{\gamma}\left(\partial_{x}^{2} x^{\prime}\right) \tag{4.26}
\end{equation*}
$$

where $\mathcal{Q}_{\gamma}$ is a polynomial with respect to the derivatives $\partial_{x}^{\lambda} x^{\prime}$ of $x^{\prime}$ with respect to $x$ of appropriate orders $\lambda$. If $k>0$,

$$
\begin{equation*}
\partial_{x}^{\beta} \partial_{x}^{k} \boldsymbol{Z}=-\sum_{|\gamma| \leqslant|\beta|+k}\left(\partial_{x}^{\gamma} \varphi\right)\left(x^{\prime}, t^{\prime}\right) \mathcal{Q}_{\gamma, k}\left(\partial_{x}^{\lambda} \partial_{\chi}^{l} x^{\prime}\right) \tag{4.27}
\end{equation*}
$$

Applying Leibniz formula in (4.25) and taking (4.26)-(4.27) into account
shows that (4.25), hence also $\partial_{x}^{\alpha} v$, is a linear combination of terms of the form

$$
\begin{align*}
\iint E(Z) & \mathcal{R}_{\mu, j}\left[\partial_{x}^{\beta} \varphi(x, t),\left(\partial_{x}^{\gamma} \varphi\right)\left(x^{\prime}, t^{\prime}\right), \partial_{x}^{\lambda} \partial_{x}^{l} x^{\prime}\right]  \tag{4.28}\\
\cdot & \partial_{x}^{\mu} w\left(x ; \chi, t^{\prime}\right)\left[1-\partial_{\chi} \varphi\left(x^{\prime}, t^{\prime}\right)\right]^{-2 j} d \chi d t^{\prime}
\end{align*}
$$

in (4.28), $\mathcal{R}_{\mu, j}$ is a polynomial with respect to the indicated arguments. Let us rewrite (4.28) as

$$
\begin{equation*}
v_{\mu, j}(x, t)=\iint E(Z) w_{\mu, j}\left(x, t ; \chi, t^{\prime}\right) d \chi d t^{\prime} \tag{4.29}
\end{equation*}
$$

Note that $w_{\mu, j}$ is a $C^{\infty}$ function of $\left(x, t, \chi, t^{\prime}\right)$ in the region

$$
\begin{equation*}
\left.x \in U_{0} \backslash \mathcal{N}_{0}, \quad t, t^{\prime} \in\right]-T, T\left[, \quad \chi \in \mathbb{R}^{1}\right. \tag{4.30}
\end{equation*}
$$

(cf. the remarks following (4.1)). The $t^{\prime}$-projection of $\operatorname{supp} w_{\mu, j}$ is contained in a compact subinterval of $]-T, T[$. Furthermore, as inspection of (4.28) shows, by virtue of (2.51) and (4.11), for suitable constants $C_{\mu, j}^{\prime}$, $M_{\mu, j}^{\prime}>0$ and an integer $d_{\mu, j}^{\prime} \geqslant 0$,

$$
\begin{align*}
& \left|w_{\mu, j}\left(x, t ; \chi, t^{\prime}\right)\right| \leqslant  \tag{4.31}\\
& \leqslant C_{\mu, j}^{\prime}\left[1+\frac{1}{r(x)}+\frac{1}{r\left(x^{\prime}\right)}\right]^{a_{\mu, 3}^{\prime}} \exp \left[M_{\mu, j}^{\prime}|\chi|\right]\left|\partial_{x}^{\mu} w\left(x ; \chi, t^{\prime}\right)\right|
\end{align*}
$$

By (4.2) and the results of the appendix of Sect. 2, we see immediately that $W$ is $r\left(x^{\prime}\right)$-flat. If we combine this fact with Lemma 4.1 we deduce that, for a suitable constant $M_{\mu}>0$ (depending only on $\mu$ ), for any $\nu \in \mathbb{Z}_{+}$and a suitable constant $C_{\mu, \nu}^{\prime \prime}>0$,

$$
\begin{equation*}
\left|\partial_{x}^{\mu} w\left(x ; \chi, t^{\prime}\right)\right| \leqslant C_{\mu, \nu}^{\prime \prime} r\left(x^{\prime}\right)^{\nu} \exp \left[M_{\mu}|\chi|\right] \tag{4.32}
\end{equation*}
$$

Combining this with (4.31) yields

$$
\begin{equation*}
\left|w_{\mu, j}\left(x, t ; \chi, t^{\prime}\right)\right| \leqslant C_{\mu, v, j}^{\prime \prime \prime} r\left(x^{\prime}\right)^{\nu}\left[1+\frac{1}{r(x)}\right]^{a_{\mu, s}^{\prime}} \exp \left[M_{\mu, j}^{\prime \prime}|\chi|\right] \tag{4.33}
\end{equation*}
$$

In (4.33) $\boldsymbol{v} \in \mathbb{Z}_{+}$is arbitrary.
The estimate (4.33) allows us to change slightly the integral representation (4.29) of $v_{\mu, j}$. Indeed, by (4.22),

$$
\frac{1}{Z}=\left(\frac{1}{1-\partial_{\chi} \varphi\left(x^{\prime}, t^{\prime}\right)} \frac{\partial}{\partial \chi}\right)^{2}[Z(\log \pm Z-1)]
$$

where $\log ^{ \pm}$denotes suitable branches of the logarithmic function. Since $w_{\mu, j}$ grows at most exponentially with $|\chi|$, whereas $E(Z)$ behaves like $\exp \left[-\chi^{2}\right]$ at infinity, we may integrate by parts, obtaining

$$
\begin{equation*}
v_{\mu, j}(x, t)=\iint \exp \left[-Z^{2}\right]\left[Z\left(\log ^{ \pm} Z-1\right] w_{\mu, j}^{\boxminus}\left(x, t ; \chi, t^{\prime}\right) d \chi d t^{\prime},\right. \tag{4.34}
\end{equation*}
$$

where $w_{\mu, j}^{\natural}$ is a function analogous to $w_{\mu, j}$ (cf. (4.25) and subsequent reasoning), in particular satisfies an inequality similar to (4.33):

$$
\begin{equation*}
\left|w_{\mu, j}^{\natural}\left(x, t ; \chi, t^{\prime}\right)\right| \leqslant C_{\mu, \nu, j}^{\natural} r\left(x^{\prime}\right)^{v}\left[1+\frac{1}{r(x)}\right]^{d_{\mu, j}^{\natural}} \exp \left[M_{\mu, j}^{\frac{1}{\natural}}|\chi|\right] \tag{4.35}
\end{equation*}
$$

( $\boldsymbol{v} \in \mathbb{Z}_{+}$arbitrary).
For any $M>0$ we denote by $v_{\mu, j}^{M}(x, t)$ the value of the integral at the right in (4.34), when the integration with respect to $\chi$ is restricted to the region

$$
\begin{equation*}
|\chi|>2 \sqrt{M}(1+|\log r(x)|)^{\frac{1}{2}} \tag{4.36}
\end{equation*}
$$

If we choose $M$ large enough, we see, by (4.10), that

$$
\begin{equation*}
\operatorname{Re} Z^{2} \geqq \frac{3}{4} \chi^{2}-\text { const. } \geqslant \frac{1}{2} \chi^{2}+M|\log r(x)| \tag{4.37}
\end{equation*}
$$

in the region (4.36), whatever $x \in U_{0} \backslash \mathcal{N}_{0},|t|<T$. Thus, there,

$$
\begin{equation*}
\left|\exp \left[-Z^{2}\right]\right| \leqslant r(x)^{\varepsilon M} \exp \left[-\chi^{2} / 2\right], \tag{4.38}
\end{equation*}
$$

where $\varepsilon=+1$ if $r(x) \leqslant 1, \varepsilon=-1$ if $r(x)>1$.
Suppose first that $x$ remains in a compact subset $K$ of $U_{0} \backslash \mathcal{N}_{0}$. We have, by (4.34), (4.35), (4.38),

$$
\begin{equation*}
\left|v_{\mu, j}^{M}(x, t)\right| \leqslant \text { const. } \int_{|\gamma|>2 \sqrt{M}} \exp \left[-\frac{1}{2} \chi^{2}+M_{\mu, j}^{\natural}|\chi|\right] \chi^{2} d \chi . \tag{4.39}
\end{equation*}
$$

Of course $\mu, j$ are fixed and so is $M_{\mu, j}^{\natural}$. We may choose $M$ so large that the right-hand side in (4.39) will not exceed any number $\delta>0$ given in advance. Thus, in order to study the continuity of $v_{\mu, j}(x, t), x \in K,|t|<T$, it suffices to study that of $\left(v_{\mu, j}-v_{\mu, j}^{M}\right)(x, t)$. But the latter continuity is evident, as the integrand and the domain of integration, in the integral expression of $\left(v_{\mu, j}-v_{\mu, j}^{M}\right)(x, t)$, depend continuously on $(x, t)$, and the integrand is uniformly $L^{1}$ with respect to $\chi, t^{\prime}$.

This proves that $v$ is a $C^{\infty}$ function in $\left.\left(U_{0} \backslash \mathcal{N}_{0}\right) \times\right]-T, T$. In order to complete the proof of Th. 1.2 we must prove that $v$ is $r$-flat.

We suppose now that $x$ is close to $\mathcal{N}_{0}$, in particular that $r(x)<1$. Using once more (4.35) and (4.38) we get

$$
\begin{equation*}
\left|v_{\mu, j}^{M}(x, t)\right| \leqslant \text { const. } r(x)^{M-d_{\mu, j}^{\natural}} \int_{\chi \mid>2 \sqrt{M}} \exp \left[-\frac{1}{2} \chi^{2}+M_{\mu, j}^{\natural}\right] \chi^{2} d \chi \tag{4.40}
\end{equation*}
$$

thus:

$$
\begin{equation*}
\left|v_{\mu, j}^{M}(x, t)\right| \leqslant C(M, \mu, j) r(x)^{M^{\prime}} \quad \text { if } M \geqslant M^{\prime}+a_{\mu, j}^{\nmid} \tag{4.41}
\end{equation*}
$$

We shall now estimate $v_{\mu, j}-v_{\mu, j}^{M}$. This difference is equal to the integral at the right in (4.34) but where the integration with respect to $\chi$ is restricted to the interval

$$
\begin{equation*}
|\chi| \leqslant 2 \sqrt{M}(1+|\log r(x)|)^{\frac{1}{2}} \tag{4.42}
\end{equation*}
$$

Lemma 4.2. There is a constant $O>0$ such that, for all $M>0$, if (4.42) holds, then

$$
\begin{equation*}
1-\Theta \leqslant\left|\frac{\log r\left(x^{\prime}\right)}{\log r(x)}\right| \leqslant 1+\Theta \tag{4.43}
\end{equation*}
$$

where $x^{\prime}=x^{\prime}(\chi, x)$ and $\Theta=2 \sqrt{M}(1+|\log r(x)|)^{\frac{1}{2}} /|\log r(x)|$.
Proof. We have (Lemma 2.5) $\left|\partial_{\chi} r\right|=|r X r| \leqslant C r$, hence

$$
\left|\log r(x)-\log r\left(x^{\prime}\right)\right|=\left|\int_{0}^{\chi} \frac{1}{r} \frac{\partial r}{\partial \chi} d \chi\right| \leqslant C|\chi|
$$

Combining this with (4.42) yields (4.43). Q.E.D.
Keeping $M$ fixed, we may find a neighborhood $\vartheta_{0}$ of $\mathcal{N}_{0}$ such that if $x \in \mathcal{V}_{0} \backslash \mathcal{N}_{0}, r(x)$ is so small that $\Theta<\frac{1}{2}$. But then, from the first inequality (4.43), we draw

$$
\begin{equation*}
r\left(x^{\prime}\right) \leqslant r(x)^{\frac{1}{2}} \quad \text { if } x^{\prime}=x^{\prime}(\chi, x) \text { and (4.42) holds } \tag{4.44}
\end{equation*}
$$

By (4.35) we see that, in the region (4.42), we have

$$
\begin{equation*}
\left|w_{\mu, j}^{\natural}\left(x, t ; \chi, t^{\prime}\right)\right| \leqslant C_{\mu, v, j}^{\natural \emptyset} \boldsymbol{q}^{\natural} r(x)^{\frac{z^{v} p-d_{\mu, j}}{\natural}} \exp \left[M_{\mu, j}^{\natural}|\chi|\right] . \tag{4.45}
\end{equation*}
$$

Reporting this in the integral at the right of (4.34), where the integration in $\chi$ is restricted to (4.42), we obtain

$$
\begin{align*}
& \left|v_{\mu, j}(x, t)-v_{\mu, j}^{M}(x, t)\right| \leqslant  \tag{4.46}\\
& \leqslant \mathrm{const} . r(x)^{\frac{1}{2} \nu-d_{\mu, j}} \int_{-\infty}^{+\infty} \exp \left[-\chi^{2}+M_{\mu, j}^{\natural}|\chi|\right] \chi^{2} d \chi \\
& \leqslant C^{\natural}(\mu, j) r(x)^{M^{\prime}} \quad \text { if } v \geqslant 2\left(M^{\prime}+d_{\mu, j}^{\natural}\right) . \quad \text { Q.E.D. }
\end{align*}
$$

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