

# Integrating BDI Reasoning into Agent Based Modelling and Simulation

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# Outline

- 1 Motivation
- 2 Belief Desire Intention (BDI) Agents
- 3 Framework
- 4 Interaction and Synchronisation
- 5 Conclusion

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# Policy and Planning



Many policy and planning tasks benefit from exploration via simulation.

# Modelling of Human Behaviour



Need to model the **behaviour** of different **people/roles**.

- Humans are **reactive** - but **not entirely**.
- They typically have **goals and plans** that extend over a **period of time**.
- They make and **adjust decisions** based on the **unfolding situation**.
- They **know what** they have been doing **and why** - this is part of what they do next.
- The **BDI agent paradigm** captures these aspects well.

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# BDI Agent Systems Useful in Many Applications



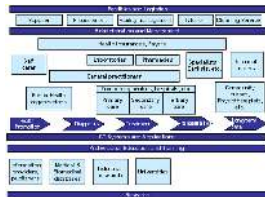
**Unmanned (Aerial) Vehicles**



**Trading Agents**



**Logistics**



**E-Health**



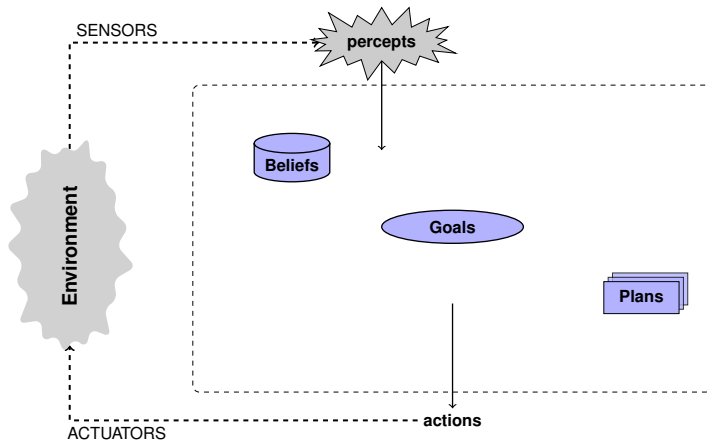
**Air Traffic Control**

BDI (Belief Desire Intention) agents have been used in many **successful applications** in **complex environments**.

# BDI Agent Oriented Programming

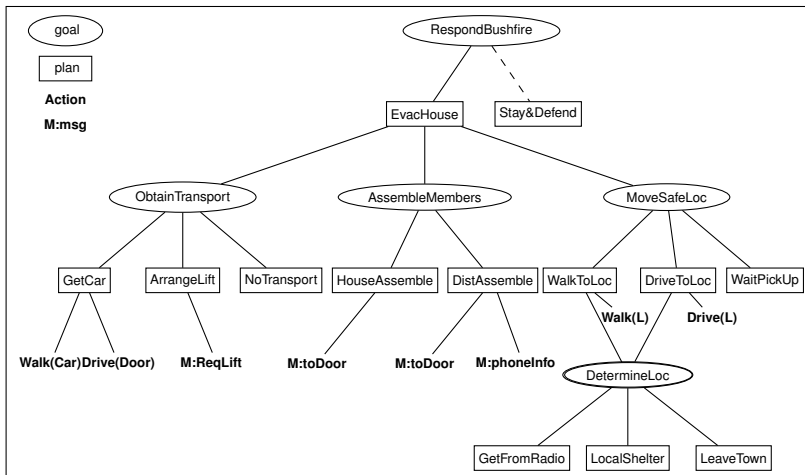
- BDI Agent-Oriented Programming provides abstraction at the level of **mental attitudes** to explain the operation of a system. **Beliefs, Desires, Intentions**.
- The **modularity of plans** makes it easy to develop complexity **incrementally**.
- The **goal oriented** approach makes it suitable for use in **dynamic environments**.
- Many **efficient and powerful** development environments available. **JACK, Jadex, Jason, PRS, 2APL, ...**
- BDI agent programs are **fast to develop**. A 2006 study showed:
  - Gain compared to Java programming **500%**.

# Belief-Desire-Intention (BDI) Agent Architecture

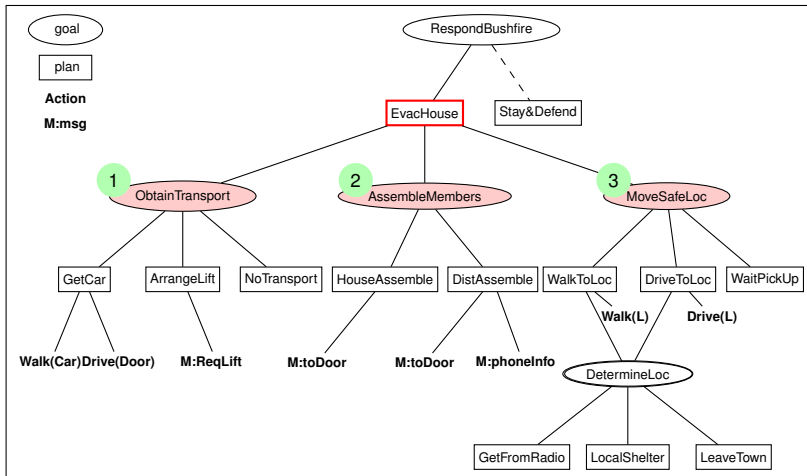


Percepts in, actions out. Internally, beliefs, goals and plans.

# Example Plan Structure

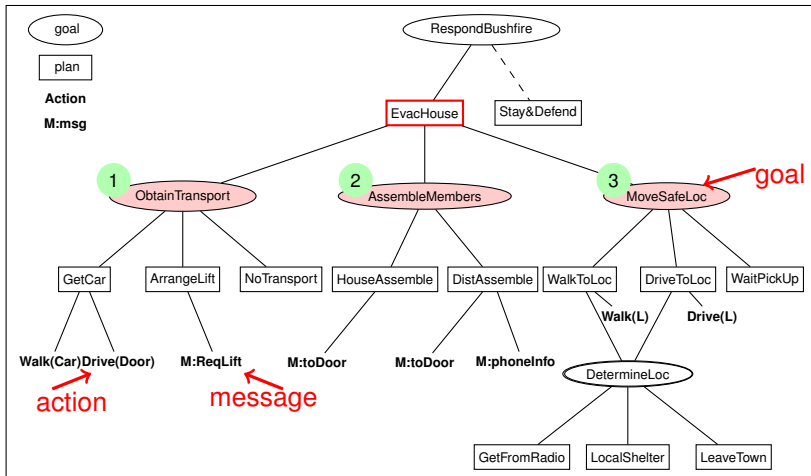


# Example Plan Structure



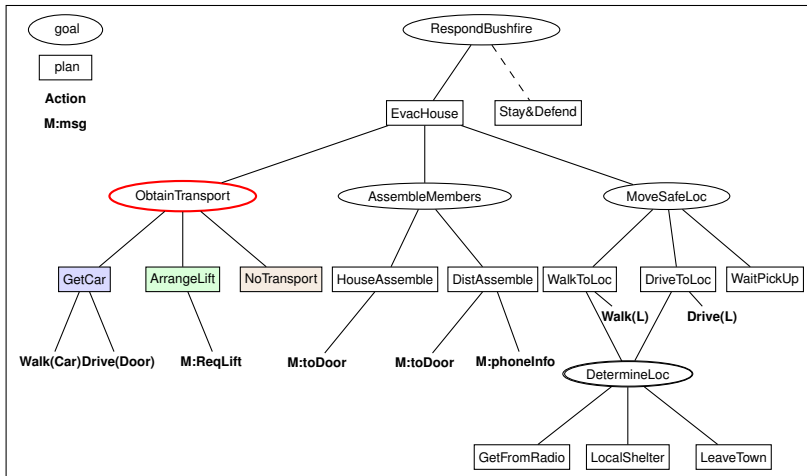
A plan is a **sequence of steps**

# Example Plan Structure



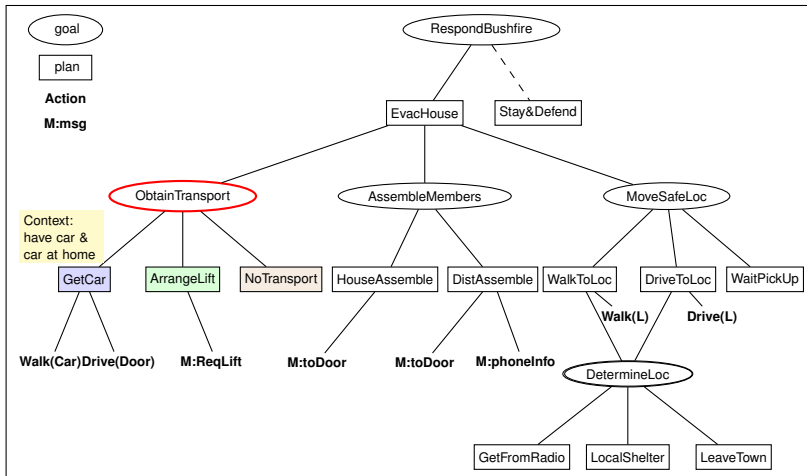
A step can be a **goal**, an **action**, a **message** to another agent, or some **computation**.

# Example Plan Structure



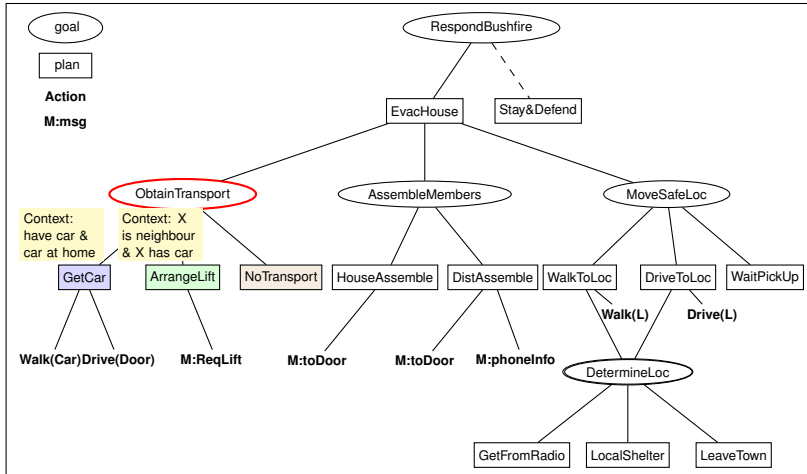
A goal may have **different plans**, for achieving it in **different situations**.

# Example Plan Structure



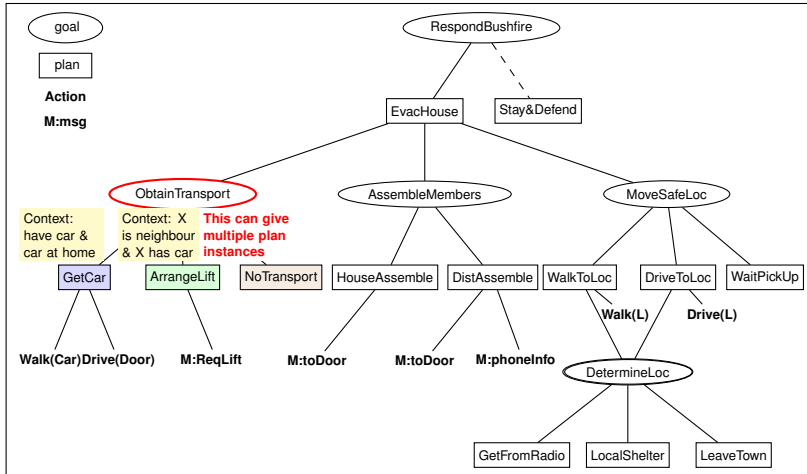
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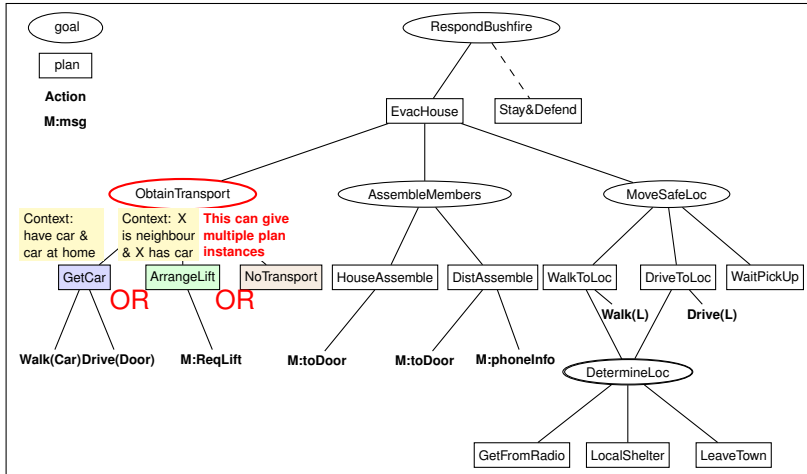
A goal may have **different plans**, for achieving it in **different situations**.

# Example Plan Structure



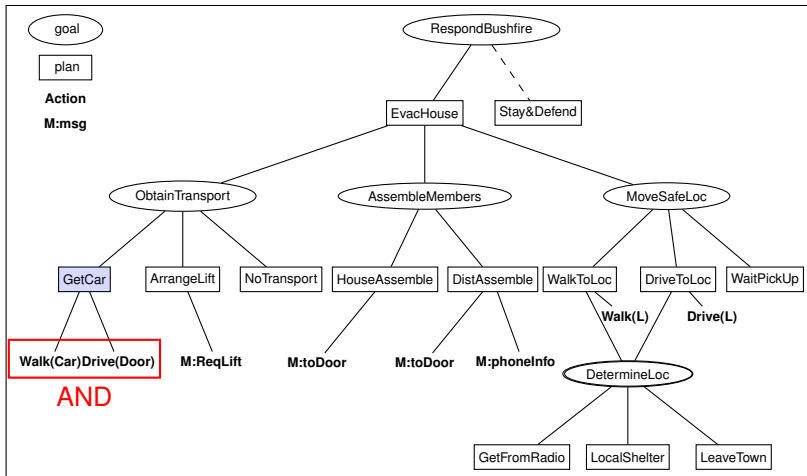
A goal may have **different plans**, for achieving it in **different situations**.

# Example Plan Structure



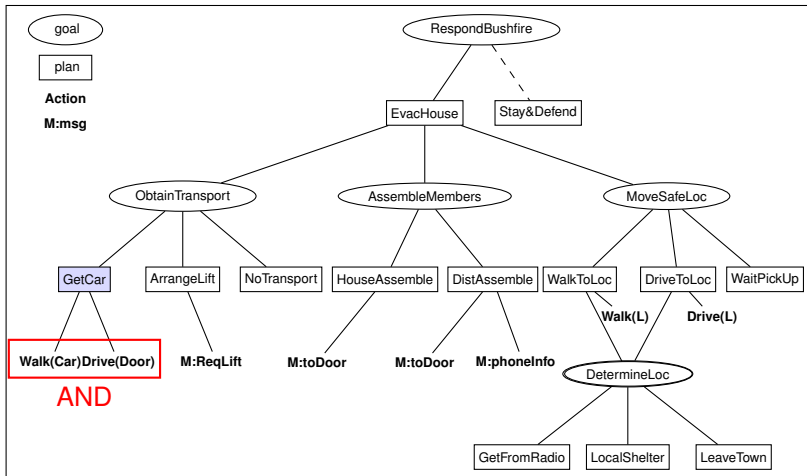
For a goal to succeed **one of the plans** must succeed. If one fails **try another**.

# Example Plan Structure



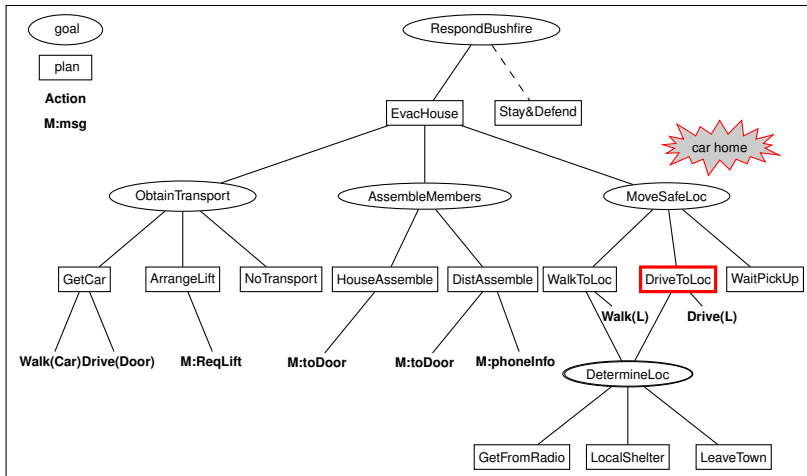
For a plan to succeed, **all** steps must succeed.

# Example Plan Structure



If things fail, **recovery** happens as locally as possible

# Example Plan Structure



Plan selection **responsive** to changing environment.

# Advantages

- **Intuitive** representation
- Late **selection**: situation aware...
- Plan failure - **retry** new plan. **Committed** to choices, like **humans**.
- Agent is **responsive** to environmental changes.
- Huge number of **options** possible - over 2 million for modest tree.  
(Subgoal steps 4, Choices 2, Depth 3)

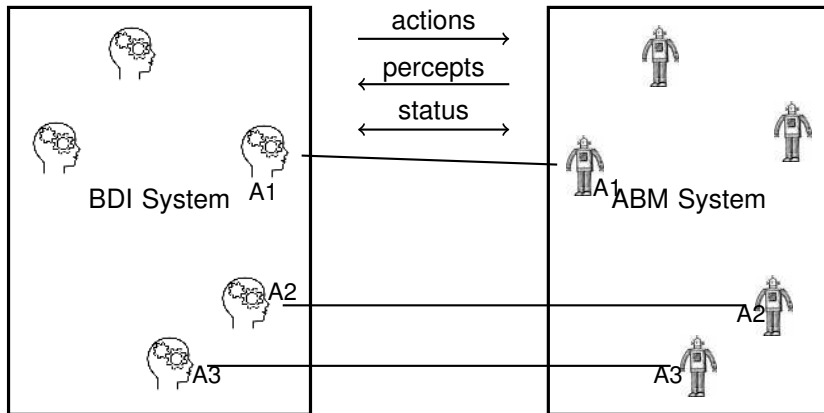
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# Framework Overview

Agent	Action	Status
A1	act2	initiate
A2	act3	initiate
A3	act1	initiate

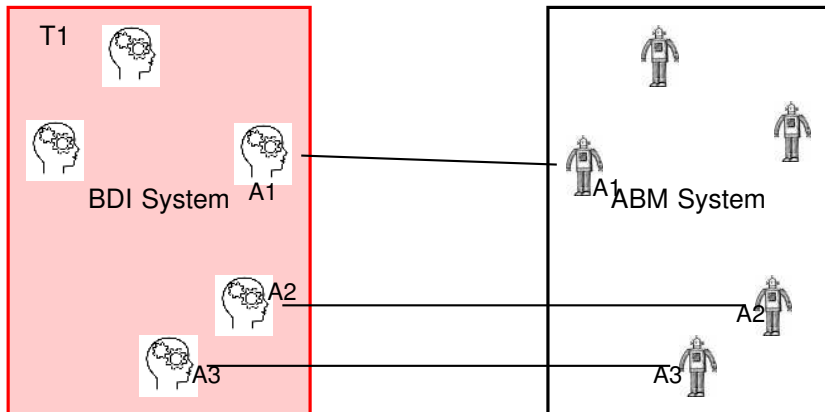
Agent	Action	Status
A2		
A3	act1	



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A1	act2	initiate
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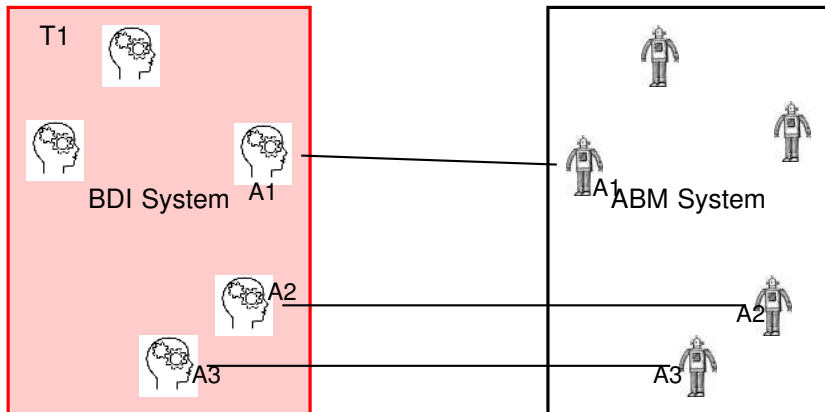
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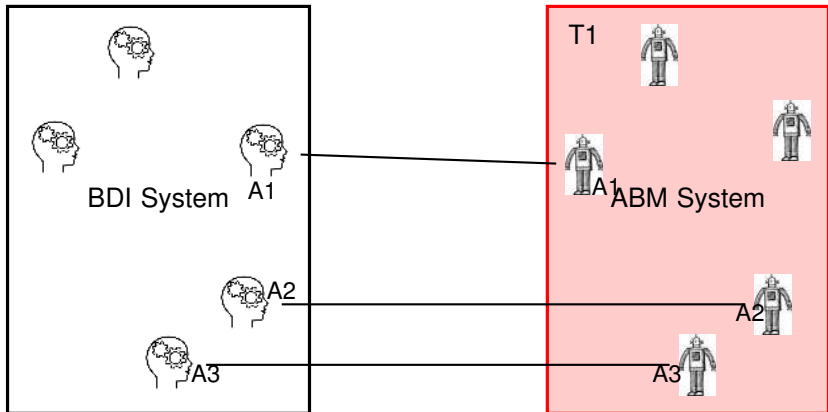
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A1	act2	initiate
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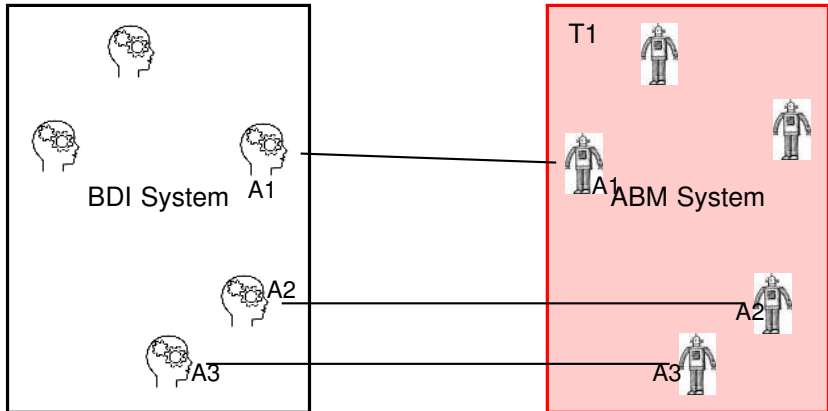
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A1	act2	initiate
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Agent	Action	Status
A1	act2	initiate
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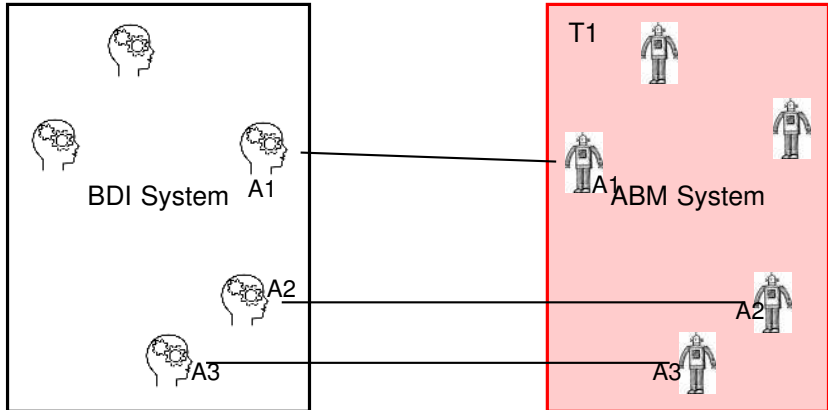
Agent	Action	Status
A1	act2	running
A2	act3	running
A3	act1	running



# Framework Overview

Agent	Action	Status
A1	act2	initiate
A2	act3	initiate
A3	act1	initiate

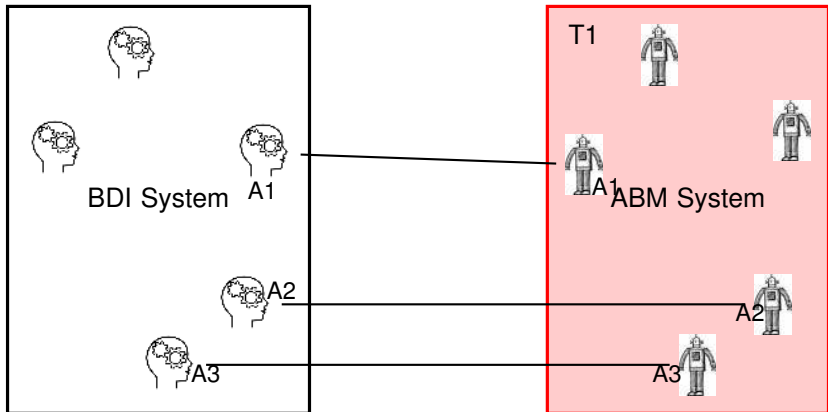
Agent	Action	Status
A1	act2	pass
A2	act3	running
A3	act1	running



# Framework Overview

Agent	Action	Status
A1	act2	initiate
A2	act3	initiate
A3	act1	initiate

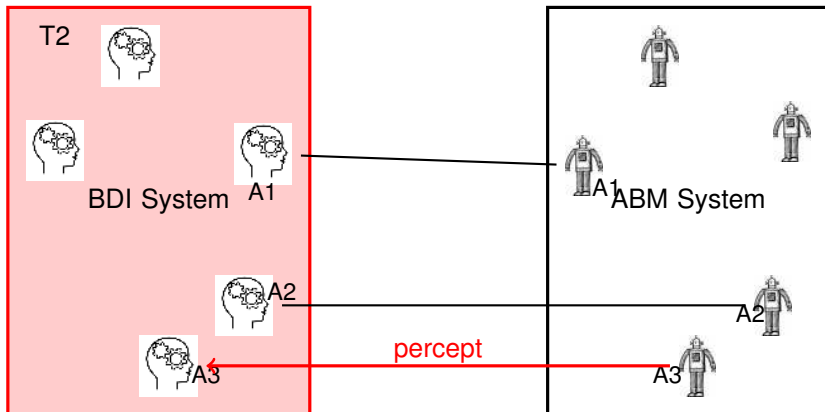
Agent	Action	Status
A1	act2	pass
A2	act3	fail
A3	act1	running



# Framework Overview

Agent	Action	Status
A1	act2	pass
A2	act3	fail
A3	act1	running

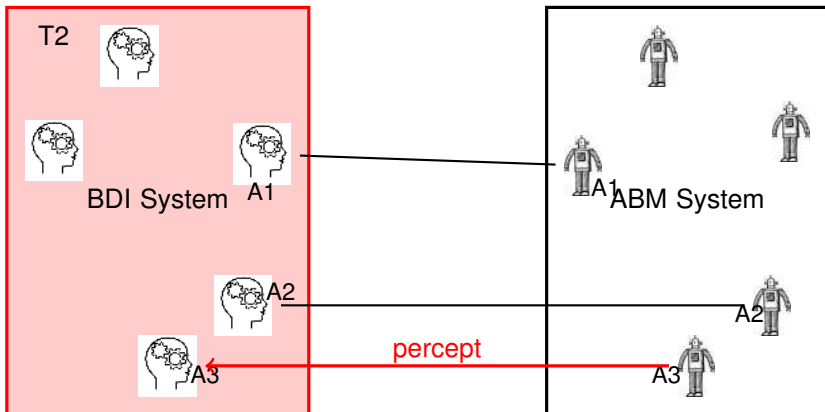
Agent	Action	Status
A1	act2	pass
A2	act3	fail
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# Framework Overview

Agent	Action	Status
A2	act3	fail
A3	act1	running

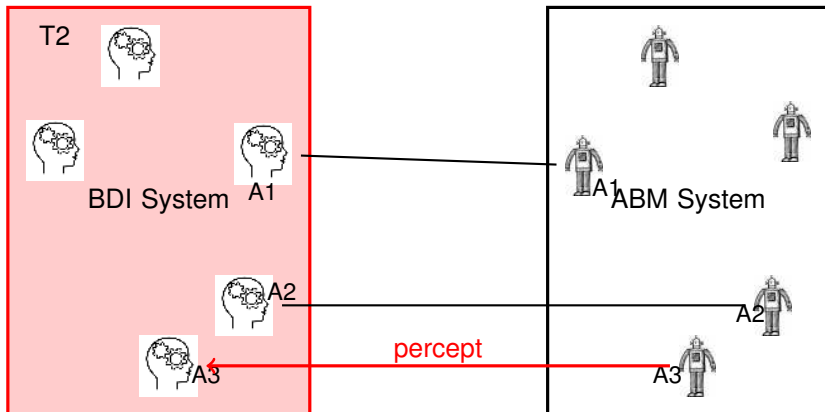
Agent	Action	Status
A1	act2	pass
A2	act3	fail
A3	act1	running



# Framework Overview

Agent	Action	Status
A2	act7	initiate
A3	act1	running

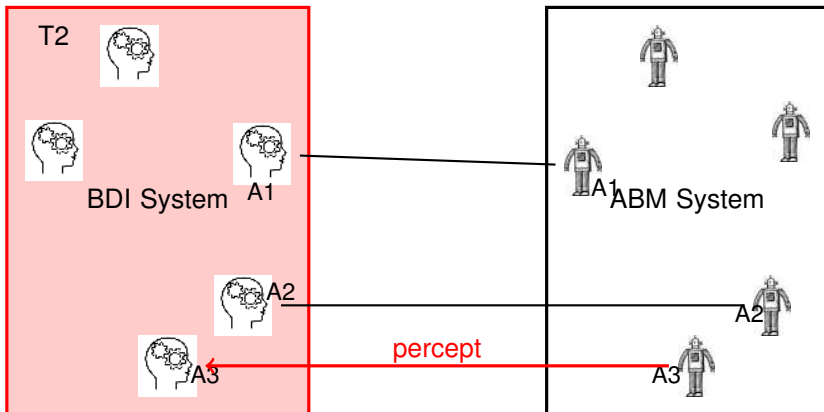
Agent	Action	Status
A1	act2	pass
A2	act3	fail
A3	act1	running



# Framework Overview

Agent	Action	Status
A2	act7	initiate
A3	act1	dropped

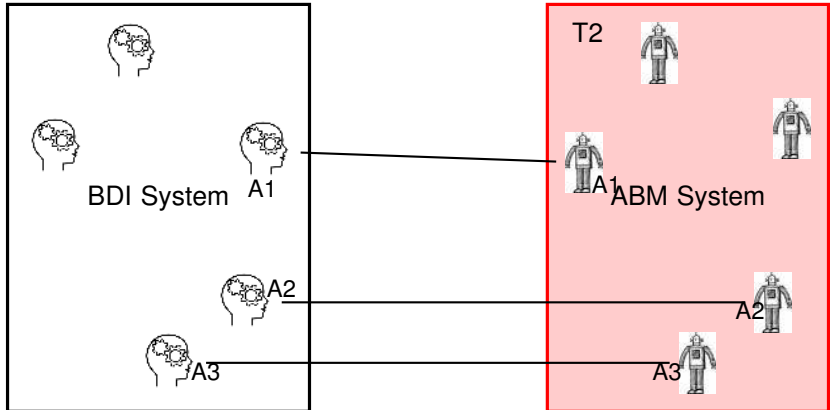
Agent	Action	Status
A1	act2	pass
A2	act3	fail
A3	act1	running



# Framework Overview

Agent	Action	Status
A2	act7	initiate
A3	act1	dropped

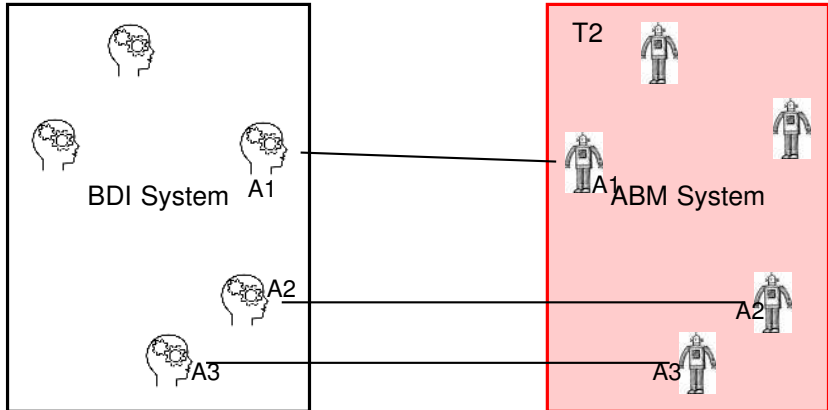
Agent	Action	Status
A2	act7	initiate
A3	act1	dropped



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Agent	Action	Status
A2	act7	initiate
A3	act1	dropped

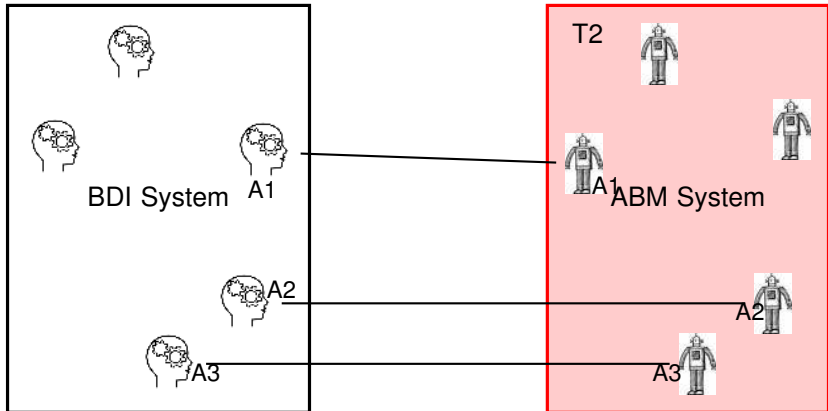
Agent	Action	Status
A2	act7	initiate



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Agent	Action	Status
A2	act7	initiate
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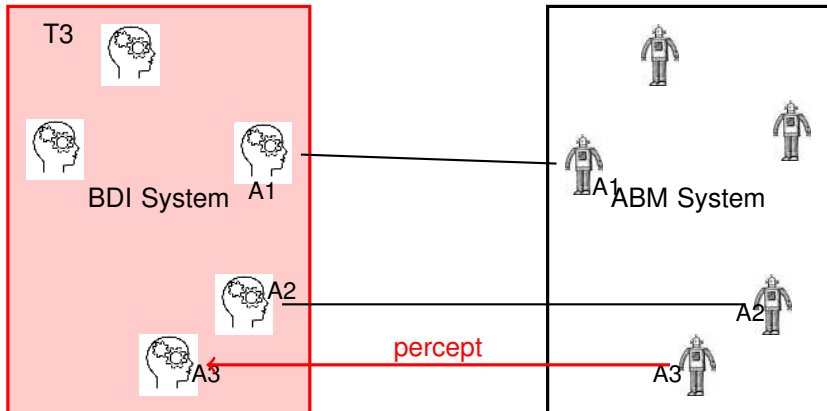
Agent	Action	Status
A2	act7	running



# Framework Overview

Agent	Action	Status
A2	act7	running

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A2	act7	running



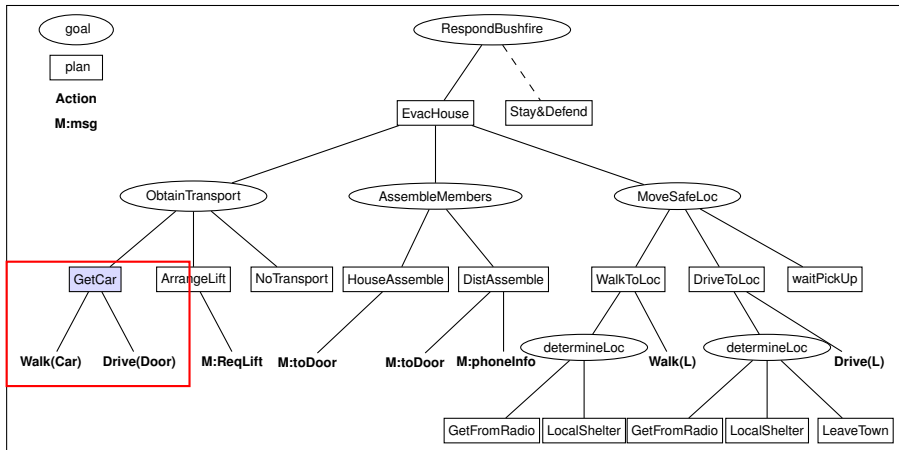
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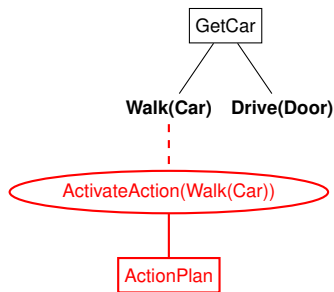
# The Interface

- **Actions:**  $\langle id, parameters, status \rangle$
- **Percepts:**  $\langle type, value \rangle$  (value may be a complex object)
- **BDI sensing actions.**
  - While processing BDI can **request information** from ABM counterpart.
  - **No effect** on environment, but may include computation.
  - (E.g. **get current location.**)
- Anything that **changes** the environment must be a **BDI action.**

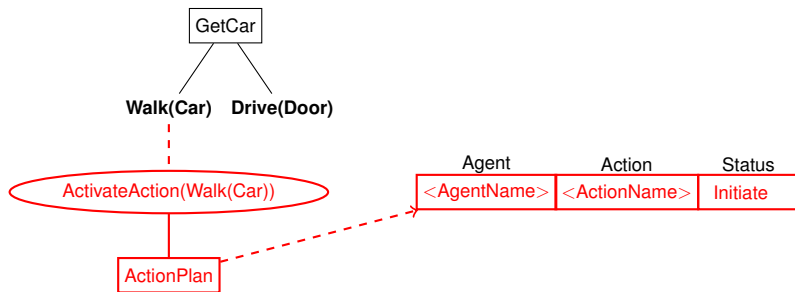
# Generic Action Plan



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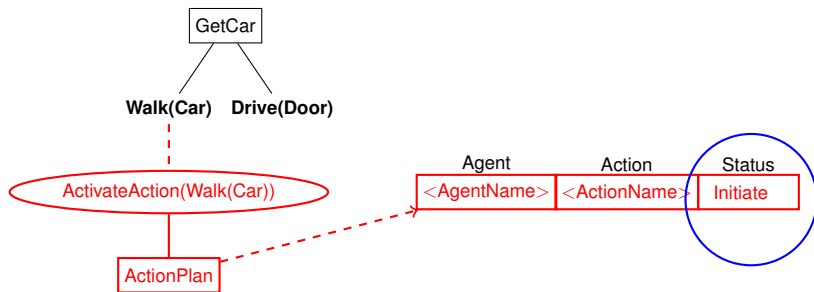


# Generic Action Plan



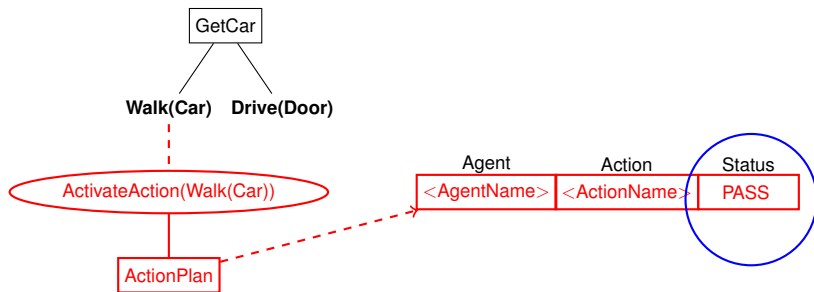
1) **Write** action info for sending to ABM

# Generic Action Plan



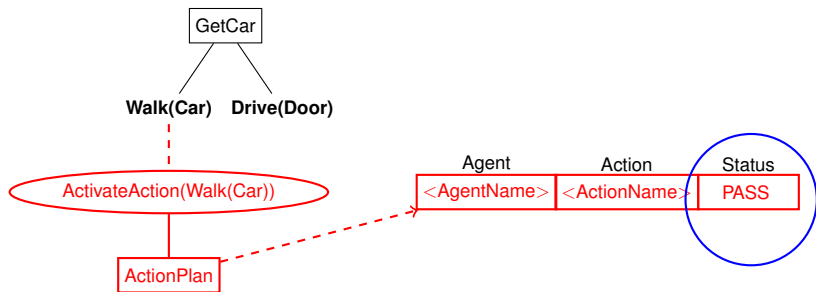
## 2) Monitor action status

# Generic Action Plan



## 3) Respond to **status**

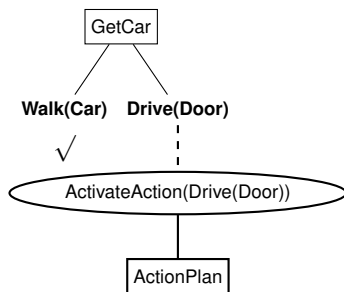
# Generic Action Plan



### 3) Respond to **status**

Status = **PASS**, succeed plan which propagates up; Continue to next step.

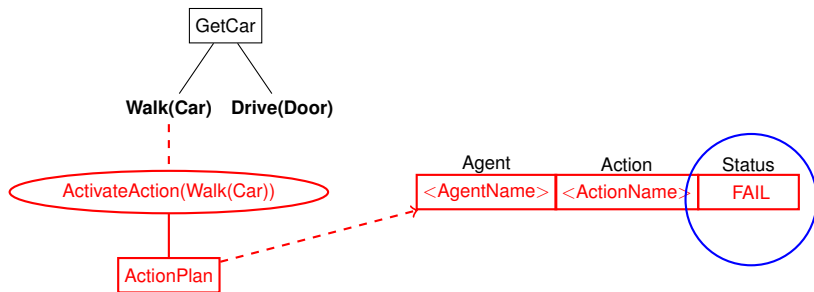
# Generic Action Plan



## 3) Respond to **status**

Status = **PASS**, succeed plan which propagates up; Continue to next step.

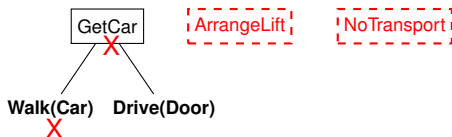
# Generic Action Plan



### 3) Respond to **status**

Status = **FAIL**, fail plan, propagates up; Plan fails.

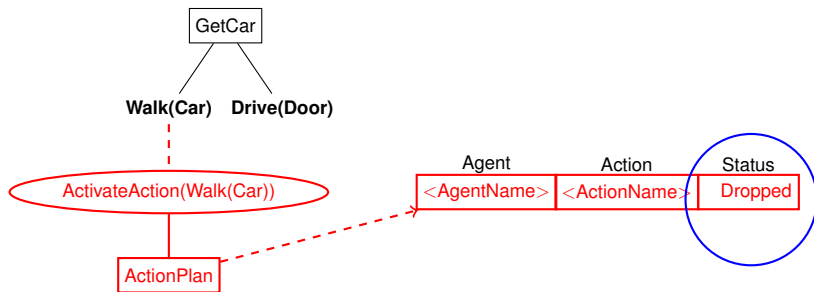
# Generic Action Plan



## 3) Respond to status

Status = **FAIL**, fail plan, propagates up; Plan fails.

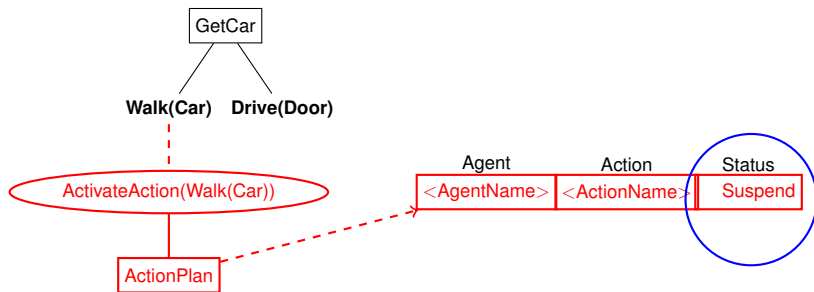
# Generic Action Plan



3) Respond to **status**

Status = **Dropped**, Same as fail, but BDI initiated.

# Generic Action Plan



3) Respond to **status**

Status = **Suspend** (also BDI initiated). No stepping on ABM side

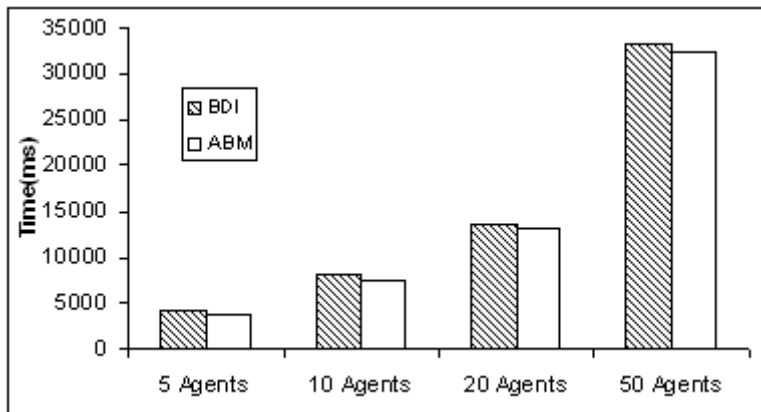
# Synchronisation Issues

- BDI and ABM **take it in turn** to run (BDI if needed)
  - System execution time should not affect conceptual model.
  - BDI runs only if **action status change** or **percept generated**.
- ABM systems generally use **time-steps**; BDI are generally **event based**, reacting to an external environment.
  - We use time-steps as basic model.
  - BDI system runs until each agent has **finished its reasoning**, possibly posting an action.
  - Depending on implementation platform, may require some care to **detect end of BDI step**.

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# Efficiency Evaluation



# Conclusion

- Successfully integrated **existing BDI (JACK) and ABM (Repast)** systems.
- Evaluation showed **minimal efficiency cost**.
- BDI representation supports **easier specification** of goal directed human behaviour **over multiple time-steps**.
- One next step is **graphical interface** for BDI specification.
- Also plan to work with social scientists to **map SS models of human behavior** to BDI style representations for richer simulation.

# Questions

