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## Inter-comparison of Low-cost Sensors for Measuring the Mass Concentration of Occupational Aerosols

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### Abstract

Low-cost sensors are effective for measuring the mass concentration of ambient aerosols and secondhand smoke in homes, but their use at concentrations relevant to occupational settings has not been demonstrated. We measured the concentrations of four aerosols (salt, Arizona road dust, welding fume, and diesel exhaust) with three types of low-cost sensors (a DC1700 from Dylas and two commodity sensors from Sharp), an aerosol photometer, and reference instruments at concentrations up to 6500  $\mu\text{g}/\text{m}^3$ . Raw output was used to assess sensor precision and develop equations to compute mass concentrations. EPA and NIOSH protocols were used to assess the mass concentrations estimated with low-cost sensors compared to reference instruments. The detection efficiency of the DC1700 ranged from 0.04% at 0.1  $\mu\text{m}$  to 108% at 5  $\mu\text{m}$ , as expected, although misclassification of fine and coarse particles was observed. The raw output of the DC1700 had higher precision (lower coefficient of variation, CV = 7.4%) than that of the two sharp devices (CV = 25% and 17%), a finding attributed to differences in manufacturer calibration. Aerosol type strongly influenced sensor response, indicating the need for on-site calibration to convert sensor output to mass concentration. Once calibrated, however, the mass concentration estimated with low-cost sensors was highly correlated with that of reference instruments ( $R^2=0.99$ ). These results suggest that the DC1700 and Sharp sensors are useful in estimating aerosol mass concentration for aerosols at concentrations relevant to the workplace.

### Introduction

Environmental and occupational exposures to fine particulate matter (particles smaller than 2.5  $\mu\text{m}$ ) and coarse particulate matter (particles between 2.5  $\mu\text{m}$  and 10  $\mu\text{m}$ ) have been associated with adverse health effects and increased mortality rates (Grant 2009; Dockery et al. 1993). Such exposures include dust, sea salt, automobile exhaust, industrial emissions, welding fumes, sawdust, animal waste, and crop dust (Seinfeld and Pandis 2012). Exposure

to specific aerosols lead to specific adverse health outcomes: Coal mine dust to adverse respiratory changes (Henneberger and Attfield 1997); welding fume to respiratory diseases and lung cancer (Antonini 2003); and diesel fume to pulmonary disease (Hart et al. 2012) and lung cancer (Lipsett and Campleman 2000).

The United States government uses mass-based regulations to protect the public and workers from harmful exposure from inhalation of harmful particles. The National Ambient Air Quality Standards (NAAQSs) under the authority of the Environmental Protection Agency (EPA) specify that states maintain the mass concentration of ambient particles smaller than 2.5  $\mu\text{m}$  ( $\text{PM}_{2.5}$ ) below 35  $\mu\text{g}/\text{m}^3$  daily and 15  $\mu\text{g}/\text{m}^3$  annually, and the mass concentration of particles smaller than 10  $\mu\text{m}$  ( $\text{PM}_{10}$ ) below 150  $\mu\text{g}/\text{m}^3$  daily (EPA 2013). In the workplace, employers must demonstrate that the personal exposures of workers do not exceed occupational exposure limits set by the Occupational Safety and Health Administration (OSHA). The 8-hour, time-weighted average exposure limit for particles not otherwise specified is 15,000  $\mu\text{g}/\text{m}^3$  for total dust with lower, sometimes much lower, values for specific compounds (OSHA 2006). The Mine Safety and Health Administration (MSHA) also has 8-hour, time-weighted average exposure limits to protect miners (MSHA 2014-a). These agencies specify the use of filter-based samplers to measure aerosol mass concentrations, calculated as the mass of particles collected on the filter determined gravimetrically divided by the volume of air sampled. Although measurements made with these samplers have high accuracy and precision, gravimetric sampling and analysis is time-consuming and yields no indication on the temporal variation in mass concentrations.

In some cases, these agencies allow for the use of instruments based on principles other than gravimetric measurement as long as they pass rigorous equivalency testing. For example, MSHA has mandated the use of miniaturized tapered element oscillating microbalances (TEOMs) for personal sampling in underground mines (MSHA 2014-b). Although these instruments are compact and provide measurements highly correlated with those from gravimetric sampling, they are expensive ( $> \$15,000$ ). The EPA defines fairly stringent criteria for equivalent sampling methods—Federal Equivalent Methods (FEMs)—in 40 CFR Part 53 (EPA 2006). Instruments meeting these criteria that have been deemed FEMs by the EPA include an ambient version of the TEOM and beta attenuation monitors (BAMs). These instruments provide continuous, real-time mass concentration (Grover et al. 2005; Macias and Husar 1976; Takahashi et al. 2008), but are expensive ( $> \$20,000$ ) and large. OSHA has no such equivalency procedure.

Instruments based on light scattering enable real-time measurement of particle concentrations at substantially lower cost than gravimetric and equivalent methods. Integrating nephelometers, for example, measure the light scattered by an assembly of particles over a wide range of angles, and has to be correlated with mass concentration (Heintzenberg and Charlson 1996). Photometers provide a real-time indication of mass concentration inferred from the light scattered by an assembly of particles over a small angle, typically at 90 degrees from the incident light (Görner et al. 1995). Photometers, such as the personal DataRAM (pDR-1500, Thermo Scientific, USA) and DustTrakII (8532; TSI, USA) are portable photometers often used to monitor occupational exposures. Optical particle counters (OPCs) use the magnitude of light scattered to provide real-time number

concentration measurements for different particle sizes (Peters et al. 2006). We refer to these devices as medium-cost with nephelometers and photometers typically ranging from \$3,000 to \$10,000 and OPCs from \$7,000 to \$15,000.

Recently, several manufacturers have introduced low-cost (<\$400) aerosol sensors that use light scattering to provide information on airborne particle concentration. The DC1700 (~\$400, Dylos Corporation, USA) is a commercially-available laser particle counter marketed for home use in a complete, ready-to-use package (with fan to pull air through, digital readout, and data logging capabilities) that provides the number concentration of fine and coarse particles (Unger 2011). Sharp Electronics have introduced extremely low-cost sensors based on the photometric response (Sharp GP, \$12, GP2Y1010AU0F; and Sharp DN, \$21, DN7C3CA006, Sharp Electronics, Japan). These sensors are intended for integration into other products, such as air conditioners and air purifiers, and consequently require a microcontroller for data logging if used for air sampling.

Environmental and indoor studies have shown that the low-cost sensors correlate well with mass concentration measured by medium- and high-cost instruments (Wang et al. 2015; Steinle et al. 2015; Holstius et al. 2014; Northcross et al. 2013). Semple et al. (2013) tested the DC1700 against a photometer (AM510, SidePak) for indoor exposure to quantify second-hand smoke concentrations, and reported a 0.86 coefficient of determination ( $R^2$ ). In an urban setting, Holstius et al. (2014) observed that the [number or mass concentration measured with the DC1700 agreed well ( $R^2 = 0.99$ ) with that measured with an OPC (~\$12,000, GRIMM, Model 1.108, GRIMM Aerosol Technixk GmbH & Co., Ainring, Germany). Steinle et al. (2015) found that number concentration measured with the DC1700 agreed well with mass concentrations measured with a TEOM (Thermo Fisher Scientific Inc., USA) in urban ( $R^2 = 0.7$ ) and rural areas ( $R^2 = 0.9$ ). For the Sharp GP sensor compared to the DustTrak DRX 8553 (TSI, USA), Budde et al. (2012) observed a mean absolute error of less than  $20 \mu\text{g}/\text{m}^3$  for concentrations that ranged from  $20 \mu\text{g}/\text{m}^3$  to  $160 \mu\text{g}/\text{m}^3$ . Wang et al. (2015) found a high correlation ( $R^2$ ) of 0.98 between the Sharp GP sensor and a SidePak (TSI Inc., USA). Literature is unavailable on the effectiveness of these sensors for use in the workplace with occupational aerosols.

Thus, the objective of the current study was to evaluate the performance of low-cost aerosol sensors (DC1700 and two Sharp sensors) for different aerosols and at high concentrations that often occur in occupational settings. First, we assessed the ability of the DC1700 to properly count and size particles into fine and coarse bins. We assessed the sensor precision and developed equations to convert sensor raw output into mass concentration. We then compared the estimated mass concentrations to those measured with high-cost instruments adjusted to gravimetric mass.

## Methods and Materials

### Low-cost Sensors

The specifications for all aerosol instruments used in this study are listed in Table 1. All medium-cost and high-cost instruments were calibrated and maintained before the experiment. All low-cost sensors were new and used for the first time. Prior to starting the

experiments in 2014, we identified low-cost sensors from six vendors (the three tested in this work and two additional sensors from Shinyei and SYhitech). We were unable to obtain reliable results from the Shinyei sensor and ultimately decided not to test the SYhitech sensor due to resource limitations.

The DC1700 displays and stores particle number concentration (in particles/0.01 ft<sup>3</sup>) in two size ranges: larger than 0.5  $\mu\text{m}$  (referred to as the small bin, although this bin includes *small and large* particles); and larger than 2.5  $\mu\text{m}$  (referred to as the large bin). To stay aligned with system international units, we converted DC1700 number concentrations to particles/cm<sup>3</sup>. According to the manufacturer, particle coincidence is less than 10% for concentrations less than 106 particles/cm<sup>3</sup>, although the instrument provides data well above this. Concentrations greater than 231 particles/cm<sup>3</sup> cause the internal logging register to roll over to zero, causing unreliable measurements at high concentration (Semple et al. 2013). The DC1700 is a standalone device designed by the manufacturer for in-home use that immediately works without effort or modification.

Two models of Sharp dust sensors were tested in this work: the Sharp GP and the Sharp DN. The sensing region of both sensors is compact (0.046 m  $\times$  0.03 m  $\times$  0.0176 m) with an infrared diode that illuminates an assembly of particles, and a phototransistor positioned at 90° from the incident light that captures light scattered by the particles. As specified by the manufacturer, the sensitivity of the Sharp GP sensor (0.5 V/0.1 mg/m<sup>3</sup>) is half that of the Sharp DN sensor (1 V/0.1 mg/m<sup>3</sup>). The Sharp GP has no accommodation to move the aerosol through the device. In contrast, the Sharp DN has a virtual impactor on the inlet and a fan on the outlet of the sensing zone. Particles smaller than 2.5  $\mu\text{m}$  pass through the virtual impactor with the minor flow entering the sensing zone. We programmed a microcomputer to acquire and record data every four seconds.

### Detection Efficiency of the DC1700

We measured the detection efficiency of the DC1700 for seven monodisperse particle sizes, using the experimental set up shown in Figure 1. A Collision-type nebulizer (Airlife, USA) containing salt solution (NaCl 0.9 wt. %, Fisher Scientific, USA) was used to generate airborne droplets, which were then dried to form solid salt particles. These polydispersed salt particles were passed through an electrostatic classifier (EC; 3080, TSI, USA) to produce monodispersed salt particles of 0.1  $\mu\text{m}$ , 0.2  $\mu\text{m}$ , and 0.3  $\mu\text{m}$  size. The 0.1  $\mu\text{m}$ , 0.2  $\mu\text{m}$ , and 0.3  $\mu\text{m}$  mobility diameters were converted to aerodynamic diameters with parameters from Table S1 (online supplemental information). The equivalent aerodynamic diameters were 0.16  $\mu\text{m}$ , 0.3  $\mu\text{m}$ , and 0.4  $\mu\text{m}$ , respectively. Larger monodispersed particles were produced with a vibrating orifice aerosol generator (VOAG; 3450, TSI, USA). The VOAG was operated with a 20- $\mu\text{m}$  orifice, oleic acid as the solute (A195–500, Fisher Scientific, USA), and isopropanol as the solvent (A464-4, Fisher Scientific, USA). The solute-to-solution volume ratios were 1:64000, 1:2370, and 1:517 to generate 1.3  $\mu\text{m}$ , 2  $\mu\text{m}$ , 3  $\mu\text{m}$ , and 5  $\mu\text{m}$  particle sizes, respectively. The liquid feed rate ranged from  $2.3 \times 10^{-5}$  to  $4.2 \times 10^{-5}$  cm<sup>3</sup>/min and a frequency range of 68 – 87 kHz.

Monodispersed aerosols were passed into a sampling chamber (0.26 m  $\times$  0.31 m  $\times$  0.15 m). A DC1700 was positioned inside the sampling chamber with the reference instruments

outside sampling directly from the chamber. The reference instruments consisted of a condensation particle counter (CPC; 3007, TSI, United States) for particles smaller than 0.3  $\mu\text{m}$  and an aerodynamic particle sizer (APS; 3321, TSI, United States) for particles larger than 1.0  $\mu\text{m}$ . The APS was also used to verify the sizing of particles larger than 0.5  $\mu\text{m}$ . An SMPS (SMPS; SMPS-C 5.402, Grimm, Germany) with an impactor (cutoff diameter of 0.804  $\mu\text{m}$ ) was used to verify the monodispersed particle generation, and to ensure minimal submicrometer aerosol particle sizes were generated by the VOAG (<10 particles/cm<sup>3</sup>).

For each particle size (0.1, 0.2, 0.3, 1.3, 2, 3, and 5  $\mu\text{m}$ ), particle number concentration was sampled for 10 minutes with the DC1700 and reference instruments. We averaged the CPC and APS data to match the one-minute data from DC1700. The detection efficiency ( $\eta_D$ ) was calculated for the fine (particles between 0.5–2.5  $\mu\text{m}$ ), coarse (particles larger than 2.5  $\mu\text{m}$ ), and total (particles larger than 0.5  $\mu\text{m}$ ) particles as follows:

$$\eta_D = \frac{N_{DC1700}}{N_{Ref}} \times 100 \quad (1)$$

where  $N_{DC1700}$  is the number concentration measured by DC1700 and  $N_{Ref}$  is the number concentration measured by reference instrument. A different number concentration was used for different particle sizes: fine particles were calculated by subtracting the number concentration reported in large bin by that reported in the small bin; coarse particles were that reported in the large bin; and total particles were that reported in the small bin.

## Performance of Low-cost Sensors

**Experimental Set Up**—The experimental set up for performance tests is shown in Figure 2-A. The test chamber consisted of a mixing zone (0.64 m  $\times$  0.64 m  $\times$  0.66 m) and a sampling zone (0.53 m  $\times$  0.64 m  $\times$  0.66 m), divided by a perforated plate positioned in the middle of the test chamber. The perforated plate contained 600 evenly spaced holes, each with a diameter of 0.6 cm. The perforated plate provided a homogenous airflow with no dead zones inside the sampling zone. The aerosol from the generation systems was diluted by clean air from two HEPA filters (0.25 m<sup>3</sup>/min) and mixed with a small fan in the mixing zone. The wind speed in the sampling zone was 0.01 m/s, resulting in a Reynold number of 400 (laminar flow). Three of each low-cost sensor (DC1700, Sharp DN, and Sharp GP) and one pDR-1500 operated with an inlet cyclone (cut-off diameter of 10  $\mu\text{m}$ ) were positioned in the sampling zone. The pDR-1500 was operated in active mode with a 37-mm glass microfiber filter (934-AH, Whatman, USA) at the outlet. The high-cost reference instruments were outside the test chamber, with direct sampling from the sampling zone.

Five polydispersed aerosols were generated using four different aerosol generation systems as depicted in Figure 2-B. Salt is a common environmental aerosol and a common test aerosol used to evaluate aerosol instruments. Arizona road dust is representative of a coarse mineral dust (Curtis et al. 2008) commonly found in environment and occupational settings and commonly used to calibrate direct-reading instruments. Diesel fumes are common in environmental and occupational settings, and welding fume is a critical occupational hazard. To achieve two aerosols of different size with the same refractive index, salt aerosols were

generated using a Collison-type nebulizer (Airlife, company, USA) using two salt solutions (mass fractions of 0.9% and 5%) (Figure 2-B(I)). This aerosol was diluted with clean air and mixed in a chamber (0.1 m<sup>3</sup>) to achieve desired concentrations. We used a fluidized bed aerosol generator (3400A, TSI, USA) to aerosolize Arizona road dust (Fine Grade, Part No. 1543094., Powder Technology INC., Arden Hills, MN) with the concentration adjusted by controlling the feed rate of the dust entering the fluidized bed (Figure 2-B(II)). Diesel fumes were produced as exhaust from a diesel electric generator (DG6LE, Red Hawk Equipment, USA) with a valve used to waste fume and control concentrations (Figure 2-B(III)). Welding fumes were generated with a welding system (0.03 inch Flux-Corded MIG Wire, Campbell Hausfeld, USA) operated inside a sandblast cabinet (Item 62454, Central Pneumatic, Byron Center, USA) [Figure 2-B(IV)]. To control concentrations, varying amounts of HEPA filtered air were used to push the fume from the cabinet to the sampling chamber.

The concentration of aerosols in the test chamber for each experiment fell into various ranges dependent on three factors: 1) measureable range of the DC1700 (0 – 231 particles/cm<sup>3</sup>); 2) maximum aerosol concentration of our experimental set up and equipment; and 3) concentration levels that range from 0 – 6500 µg/m<sup>3</sup>. Although concentrations were lower than OSHA's occupational exposure limit for particles not otherwise specified (15,000 µg/m<sup>3</sup>), these concentrations are relevant to the needs of practicing industrial hygienists, who often take action to control contaminants when concentrations reach one-tenth the limit. Steady-state concentrations of test aerosols were maintained at different levels. Aerosol size distribution varied by particle type, but was approximately the same for each concentration level of the same aerosol type, except for diesel fume (Figure S2 in online supplemental information). For each level, the number concentration by size was measured with the SMPS three times after reaching steady-state concentration. The APS was set to record particles number concentration by size every minute throughout the experiment. Prior to starting experiments, the air in the chamber was confirmed to be clean with the pDR-1500 (0 µg/m<sup>3</sup>) and the CPC-3007 (0 particles/cm<sup>3</sup>).

**Precision and Response of Sensors**—As a measure of sensor precision, we calculated the coefficient of variation (CV) of the raw sensor output (number concentration for DC1700 and voltage for the Sharp sensors) and after conversion to mass concentration (described below). For each minute, CV was calculated as (NIOSH 2012):

$$CV = \frac{\sigma}{\mu} \quad (2)$$

where  $\sigma$  is the standard deviation and  $\mu$  is the mean of the measurements from the three replicate sensors of the same type. The average of one-minute CVs obtained over all concentrations for a given aerosol were reported for each sensor. EPA's acceptable CV values for test instruments are up to 10% (EPA 2016). NIOSH does not have a specific acceptable value for CV.

**Evaluation of Low-cost Sensors to Estimate Mass Concentration**—We used the pDR-1500 to develop equations to convert raw output from the low-cost sensors to mass



concentration. The pDR-1500 was selected as a small and portable device within the budget of many corporate industrial hygiene programs that may then potentially be used to develop correction models in the field. For each aerosol type, the mass concentrations from the single pDR-1500 were averaged to match the one-minute DC1700 measurements. These values were then adjusted by multiplying by the mass concentration measured gravimetrically with the glass microfiber filter internal to the pDR-1500 and dividing by the average of unadjusted mass concentration from pDR-1500 over the entire experiment. Different filters were used for each aerosol type measured. Linear regression was used to determine the best-fit line between the 1-minute paired number concentrations of the DC1700 (small bin or total particles) and the corrected pDR-1500 mass concentrations. For the Sharp sensors, linear regression was used between the 1-minute paired Sharp voltages and the corrected pDR-1500 mass concentrations.

We evaluated the mass concentrations estimated for the low-cost sensors with reference to gravimetrically-adjusted mass concentration measured with the SMPS and APS following procedures specified by EPA for FEMs (40 CFR Part 53, Subpart C and 40 CFR Part 58) and NIOSH for evaluating direct-reading gas instruments (NIOSH 2012). For each three-minute SMPS measurement, the number concentration by electrical equivalent mobility diameter from the SMPS and the number concentration by aerodynamic diameter from the APS were converted to mass concentration by volume equivalent diameter, using the particle density and shape factor provided in Table S1 (online supplemental information). The reference mass concentration was calculated as SMPS/APS mass concentrations summed over all sizes multiplied by the mass concentration measured gravimetrically with the glass microfiber filter internal to the pDR-1500 and divided by the mean of unadjusted SMPS/APS mass concentrations over the entire experiment. Three-minute averages of mass concentrations from the low-cost sensors and the pDR-1500 were calculated to correspond in time with the reference concentrations. For each aerosol and sensor, Pearson coefficient ( $r$ ), coefficient of determination ( $R^2$ ), slope, and intercept between the sensor and reference mass concentration were determined using linear regression.

The bias ( $B$ ) was calculated as (EPA 2016):

$$B = \frac{1}{n} \sum \frac{y_i - x_i}{x_i} \quad (3)$$

where  $y$  is the estimated mass concentrations for low-cost sensor from the regression models,  $x$  is the gravimetrically filter corrected SMPS and APS mass concentrations, and  $n$  is the number of data pairs.

These parameters were compared to acceptance criteria from EPA and NIOSH. For EPA, the linear regression between measurements made with a candidate and reference instrument must have a slope of  $1 \pm 0.1$ , a y-intercept of  $0 \pm 5 \mu\text{g}/\text{m}^3$ , and an  $r \geq 0.97$  (40 CFR Part 53, Subpart C, Table C-4). EPA also specified that percent bias should be within  $\pm 10\%$  (40 CFR Part 58). For NIOSH, candidate and reference instruments must exhibit a slope of  $1 \pm 0.1$

and a percent bias of  $\pm 10\%$ . NIOSH does not have criteria for the y-intercept (NIOSH 2012).

## Results and Discussion

### Detection Efficiency of the DC1700

The detection efficiency of the DC1700 by particle size is shown in Figure 3. Detection efficiency for fine particles was low ( $< 2\%$ ) for sub-micrometer particles, increased to 52% for 1.3- $\mu\text{m}$  particles, and then decreased to 29% for 5- $\mu\text{m}$  particles. In contrast, detection efficiency for coarse particles consistently increased with particle size from 0% at 0.16  $\mu\text{m}$ , to 10% at 1.3  $\mu\text{m}$ , and 82% at 5  $\mu\text{m}$ . Together, the total (fine + coarse) detection efficiency increased as particle size increased from 0.04% at 0.16  $\mu\text{m}$  to greater than 100% at 5  $\mu\text{m}$ .

The fact that detection efficiency was extremely low for particles smaller than 0.5  $\mu\text{m}$  agrees with manufacturer specifications and is consistent with the fact that very little light is scattered by sub-0.5- $\mu\text{m}$  particles. However, it was surprising to find that the DC1700 incorrectly classified particles larger than 2.5  $\mu\text{m}$  as fine particles (e.g., 29% of 5- $\mu\text{m}$  particles classified as fine, Figure 3), when the detection efficiency should be zero. Similarly, the DC1700 misclassified sub-2.5- $\mu\text{m}$  into the coarse bin (e.g., 10% of 1.3- $\mu\text{m}$  particles were classified as coarse). The classification of the coarse and fine bins are based on the proprietary table in the DC1700 firmware. It is not clear why this misclassification occurred. For the remainder of the study, only the total fraction measured by the DC1700 was used, which corresponds to the small bin. The decision was based on two factors: total detection efficiency increased with particle size; and coarse and fine particles were highly correlated ( $R^2 = 0.98$ ).

### Performance of Low-cost Sensors

Performance of low-cost sensors are presented for mass concentrations less than 5000  $\mu\text{g}/\text{m}^3$ . This decision was based on diesel fume experiments (Figure S1 in online supplemental information) in which the relationship between mass concentration measured with the pDR-1500 and the reference instrument was linear for concentrations  $< 5000 \mu\text{g}/\text{m}^3$  but non-linear for greater concentrations. We attribute the non-linear relationship for extremely high concentrations to particle coincidence in the sensing zone of the pDR-1500.

**Precision and Response of Sensors**—Table 2 summarizes the precision expressed as the coefficient of variation (CV) calculated for raw data and converted mass concentration data by sensor and aerosol type. Scatter plots of raw sensor response relative to reference mass concentrations (i.e., filter-corrected SMPS and APS data) are shown for the DC1700 in Figure 4, and for the Sharp DN and Sharp GP in Figure 5. The x-axis error bars in these figures (the standard deviation of reference measurements) indicate the variability of mass concentration at each steady state. The y-axis error bars (the standard deviation within sensor type) indicate a combination of within-sensor precision and concentration variability. We displayed Figure 5 with log-log axes to allow all data to be visible (particularly for the Sharp GP) and Figure 4 in the same way for consistency. Based on the raw measurements, the DC1700 exhibited the best precision of the three sensors with the lowest CV (2.2–14%



for the small bin; and 5–15% for the large bin) and smallest error bars in the response curves (Figure 4). For the Sharp sensors, the CV was high for most cases, varying from 17–30% for the Sharp DN and 2–51% for the Sharp GP.

Sensor precision is an important factor for determining an approach to estimate mass concentration from their response. The good precision of the DC1700, presumably stemming from the fact that the factory calibrates each sensor (Northcross et al. 2013), suggests that all DC1700s can be treated similarly when estimating mass concentration. In contrast, the Sharp sensors are substantially less precise, indicating the need to treat each sensor independently when computing mass concentration. In regards to the Sharp GP sensor, Budde et al. (2012) correlated multiple Sharp sensors with a DustTrak and reported that each sensor has different measurements. The author attributes these differences to fact that the Sharp sensors are not factory calibrated to reproduce the same values. Wang et al. (2015) measured the precision of the Sharp GP sensor, and found that the standard deviation among devices increased with mass concentrations, concluding that the Sharp GP sensors have low precision. To our knowledge, no one has reported the precision of the DC1700.

For all sensors, aerosol type strongly influenced sensor response. The response relative to reference mass concentration for the DC1700 (Figure 4) was linear for low concentrations and deviates from linearity for particle concentrations greater than 106 particles/cm<sup>3</sup>. The change in response relative to change in mass concentration (slope) was greatest for the salt aerosol, with both salt solutions having similar slopes. The slopes for welding fume and Arizona road dust were similar but less than that for salt aerosol. The slope was the least for the diesel fume, dramatically different from that of the other aerosols. In contrast, the response of the Sharp sensors (Figure 5 and Figure 6) was linear for all aerosols, except for the diesel fume. The Sharp DN (Figure 5(A)) and Sharp GP (Figure 5(B)) response curves had similar correlations but with different magnitudes. The slope of the Sharp sensors was similar to that of the DC1700, except for the fact that the slope was lower for welding fume than diesel fume. The response of the Sharp GP voltage with the mass concentrations for Arizona road dust was inconsistent with the manufacturer's published data (Sharp 2006).

The different responses for the low-cost sensors to different aerosol types is a clear indication that each sensor needs to be correlated independently with a reference instrument for different aerosol environments. Particle size distribution, refractive index, and shape affect particle light scattering. The mass median diameters (MMDs) and geometric standard deviations (GSDs) of each aerosol obtained from SMPS and APS data differed substantially (Table 3). The MMD for the 5% salt solution is higher than the 0.9% salt solution, which was expected. The MMD for the Arizona road dust was around 2.6  $\mu\text{m}$ . We did not calculate MMDs and GSDs for the diesel fume and welding fume aerosols because the size distributions were multimodal (see Figure S2 and Figure S3 in online supplemental information, respectively). A complicating factor is that the particle size distribution of the diesel fume changed for different concentration levels (Figure S2 in online supplemental information). The refractive index for the salt aerosol, dust, diesel fume, and welding fumes are 1.544, 1.51, 1.465, and 1.8, respectively. Since both salt aerosols have nearly identical slopes but different MMDs, we can infer that the refractive index has a role in the response. Northcross et al. (2013) and Wang et al. (2015) both suggest that the refractive index plays a

role in response variation for different aerosol types. We observed that the response of the DC1700 to diesel fumes was substantially different than that for other aerosols. This finding may relate to the fact that the refractive index of diesel fume has a high absorption component or that the size distribution shifted with particle concentration.

The finding that the response of the DC1700 for high concentrations ( $>106$  particles/cm<sup>3</sup>) is non-linear was expected. The non-linear response above 106 particles/cm<sup>3</sup> is consistent with coincidence as specified by the manufacturer. The performance of the DC1700 was analyzed for number concentrations below 106 particles/cm<sup>3</sup>. This number concentration is equivalent to a mass concentration of 500 µg/m<sup>3</sup> for both the 0.9% and 5% salt solutions, 1200 µg/m<sup>3</sup> for Arizona road dust, 6300 µg/m<sup>3</sup> for diesel fume, and 2200 µg/m<sup>3</sup> for welding fume (Figure 4). For the Sharp GP sensor, Wang et al. (2015) found similar linear response between the low-cost sensor and the SMPS for measuring NaCl particles. Steinle et al. (2014), Holtius et al. (2014), Klepeis et al. (2013), and Northcross et al. (2013) all observed a linear relationship for relatively low concentrations ( $<300$  µg/m<sup>3</sup>), whereas Semple et al. (2013) found a non-linear relationship for concentrations that exceeded 1000 µg/m<sup>3</sup>.

**Evaluation of Low-cost Sensors to Estimate Mass Concentration**—Linear equations used to convert sensor raw output to gravimetrically adjusted mass concentration measured with the pDR-1500 are shown by aerosol type in Table 4. For the DC1700, we only fit data for number concentrations  $<106$  particles/cm<sup>3</sup> (small bin) to avoid issues with coincidence. Limiting the data to concentrations below 106 particles/cm<sup>3</sup> resulted in good linear fit with an R<sup>2</sup> value ranging from 0.91 for welding fume to 0.99 for 5% salt solution. For the Sharp sensors, we determined a linear equation unique to each sensor and aerosol because of their low precision. These equations are not shown in this manuscript because they cannot be used for other Sharp sensors, even for the same aerosol type.

We calculated again the CV values for the low-cost sensors based on the mass concentrations, as shown in Table 2. Based on the estimated mass concentrations, all the low-cost sensors have a low CV value that ranged from 1–8%. The low CV values based on the estimated mass concentrations are an indication that any sensor can be used to estimate mass concentrations once calibrated for an aerosol type.

Good agreement was observed between mass concentrations measured with the pDR-1500 and reference mass concentrations (from SMPS APS data; Table 5). Values of  $r$  were all high and the slope values were close to unity (ideal). The coefficient of determination (R<sup>2</sup>) ranged from 0.98 to 0.99. Biases were low ranging from –1.1% for welding fume to –9.1% for diesel fume. These results suggest that the pDR-1500 is a good medium cost device that can be used to determine regression models for the low-cost sensors.

Table 6 summarize the evaluation of mass concentrations estimated with the DC1700 relative to those measured with the SMPS and APS. Values of  $r$  and R<sup>2</sup> were high (an ideal value is 1). However, slopes were closer to unity and biases were  $<10\%$  for the salt and welding fume aerosols but exceeded 18% for the Arizona road dust and diesel fume aerosols. The DC1700 calculated mass concentrations with the reference mass concentrations are shown in Figure S4 (online supplemental information). The points in

Figure S4 approach the one to one line. Northcross et al. (2013) also reported the linear regression between the mass concentrations estimated from the DC1700 to those from a reference instrument for three ambient sampling periods. In that work, the slope and  $R^2$  values varied between 0.95–1.96 and 0.81–0.99, respectively. These higher slope and lower  $R^2$  values compared to our work may be because their study was conducted in an uncontrolled ambient setting with many different particle types sampled simultaneously.

Table 7(A) and 7(B) summarize the evaluation of the Sharp DN and Sharp GP sensors, respectively. Both Sharp sensors behaved similarly. For a given aerosol, the values of slope and intercept were similar for the Sharp DN and Sharp GP sensors. For example, the Sharp DN for the 0.9% salt solution experiment measured a maximum of 2.9 volts, whereas the Sharp GP only measured 0.9 volts for the same experiment. Slopes for both sensors were near unity, ranging from 0.9 to 1.3. The coefficient of determination ( $R^2$ ) ranged from 0.95 to 0.99. Biases for the sharp sensors, ranging from  $-9.8\%$  to  $5.2\%$ , were substantially lower than those observed for the DC1700 (Table 6). The fact that these values were similar for both Sharp sensors can be attributed to the fact that mass concentrations were estimated from correlations with the pDR-1500. The Sharp sensors calculated mass concentrations compared to the reference mass concentrations are shown in Figure S5 (online supplemental information). The points in Figure S5 approach the one to one line.

Bias in mass concentrations estimated with the DC1700 and reference instruments met the acceptance criterion for 0.9% salt solution, 5% salt solution, and the welding fume, but not for the other two aerosols. The correlation coefficient met EPA's criterion for all the aerosols except diesel fume. The slopes for all aerosols (excluding dust and 5% salt solution) met acceptance criterion. However, no intercepts met the acceptance criterion. For the Sharp sensors, bias and correlation coefficients met acceptance criteria. Slopes met the criterion, except for 0.9% salt and Arizona road dust aerosols. Only the intercept for 5% salt solution met the EPA criterion.

There are three main limitations to this study. The detection efficiency of the DC1700 (Figure 3) was measured using two aerosol types (salt for particles smaller than  $0.3 \mu\text{m}$  and an oleic acid for particles larger than  $1.3 \mu\text{m}$ ), which have different refractive indexes. For diesel and welding fume, assumed values for density and shape factor introduced uncertainties in reference mass concentrations from SMPS and APS data. Particles larger than 300 nm were assumed to have a constant shape factor, although Park et al. (2004) reported that shape factor increases with particle size for diesel fume and Kim et al. (2009) reported the same for welding fumes. We also assumed a constant density for diesel fume, although Park et al. (2004) report that density decreases with particles larger than 300 nm. Lastly, the difference in MMD between salt aerosols was smaller than anticipated, yielding little information on the effect of size on sensor response.

## Conclusion

We evaluated the performance of DC1700, Sharp GP, and Sharp DN low-cost sensors to measure the mass concentration of aerosols at concentrations relevant to occupational settings. The DC1700 is a stand-alone device that can be used without modification, whereas

the Sharp sensors need a microcomputer for data acquisition and logging. The detection efficiency of the DC1700 was low (<5% for particles smaller than 0.3  $\mu\text{m}$ ), increasing to 60% for 1.3- $\mu\text{m}$ , and to ~100% for particles larger than 3  $\mu\text{m}$ . We observed substantial misclassification of fine and coarse particles. The precision of the DC1700 sensor was high (low CVs between 2%–15%), whereas that for the raw output of the Sharp sensors was more variable (between 2%–51%). Although the response of the low-cost sensors was dependent on aerosol concentration, regression of sensor output to filter-corrected mass concentrations measured with commercial mass photometer (pDR-1500) was highly effective, resulting in  $R^2 > 0.97$  and reasonable bias for all sensors and aerosols. After calibration, all sensors also had high precision (<8%). This work demonstrates that once calibrated low-cost sensors can be used to measure aerosols in occupational settings at concentrations of relevance to action levels (1/10<sup>th</sup> OSHAs exposure limit for particles not otherwise specified). In future work, we will evaluate the effectiveness of using a network of low-cost sensors to assess aerosol concentrations in a field study conducted in several workplaces.

## Supplementary Material

Refer to Web version on PubMed Central for supplementary material.

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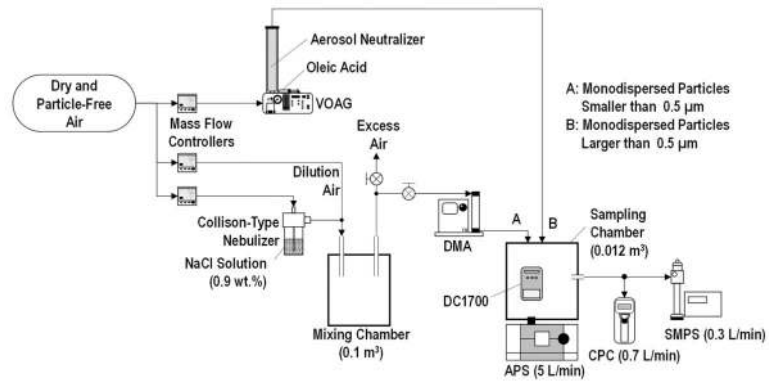
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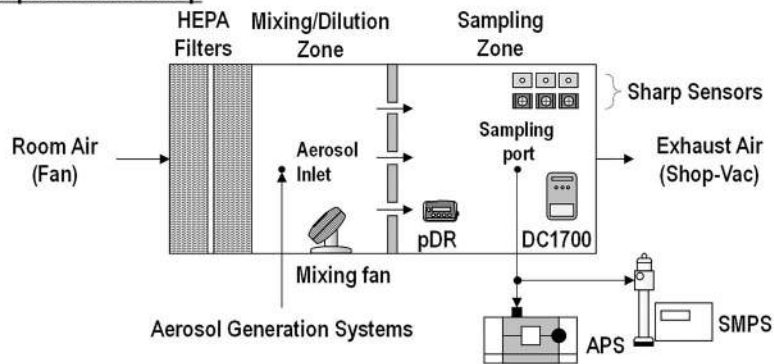
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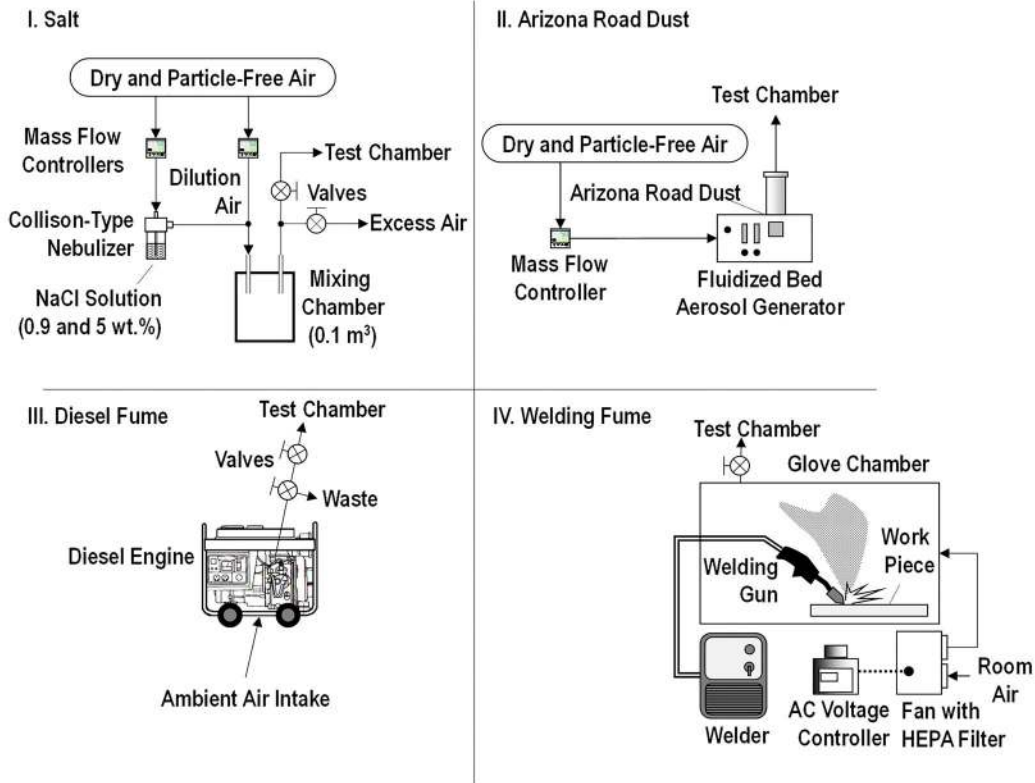


**Figure 1.**  
Experimental set up used to measure the detection efficiency of the DC1700.

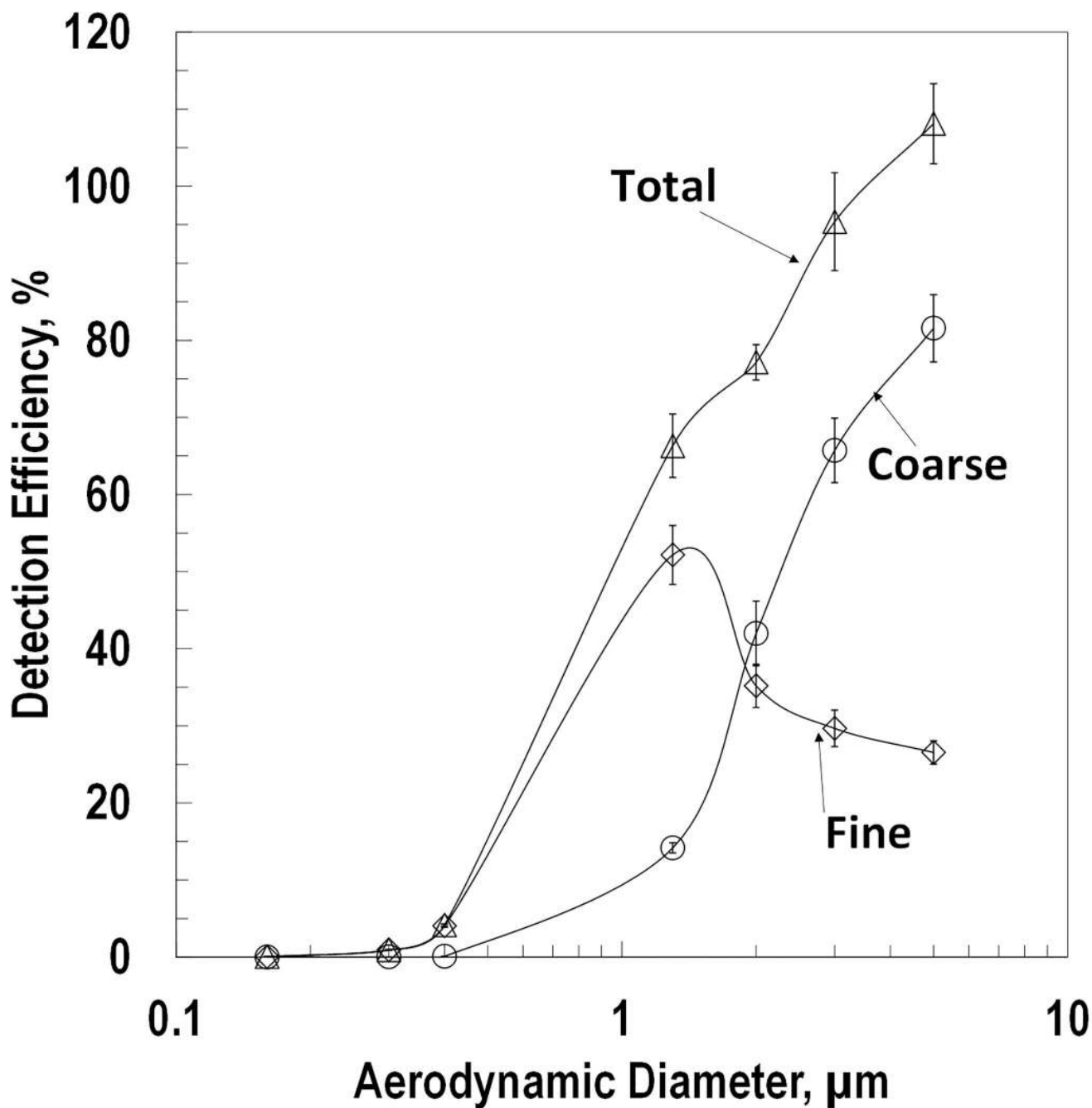
**A. Experimental Set Up**



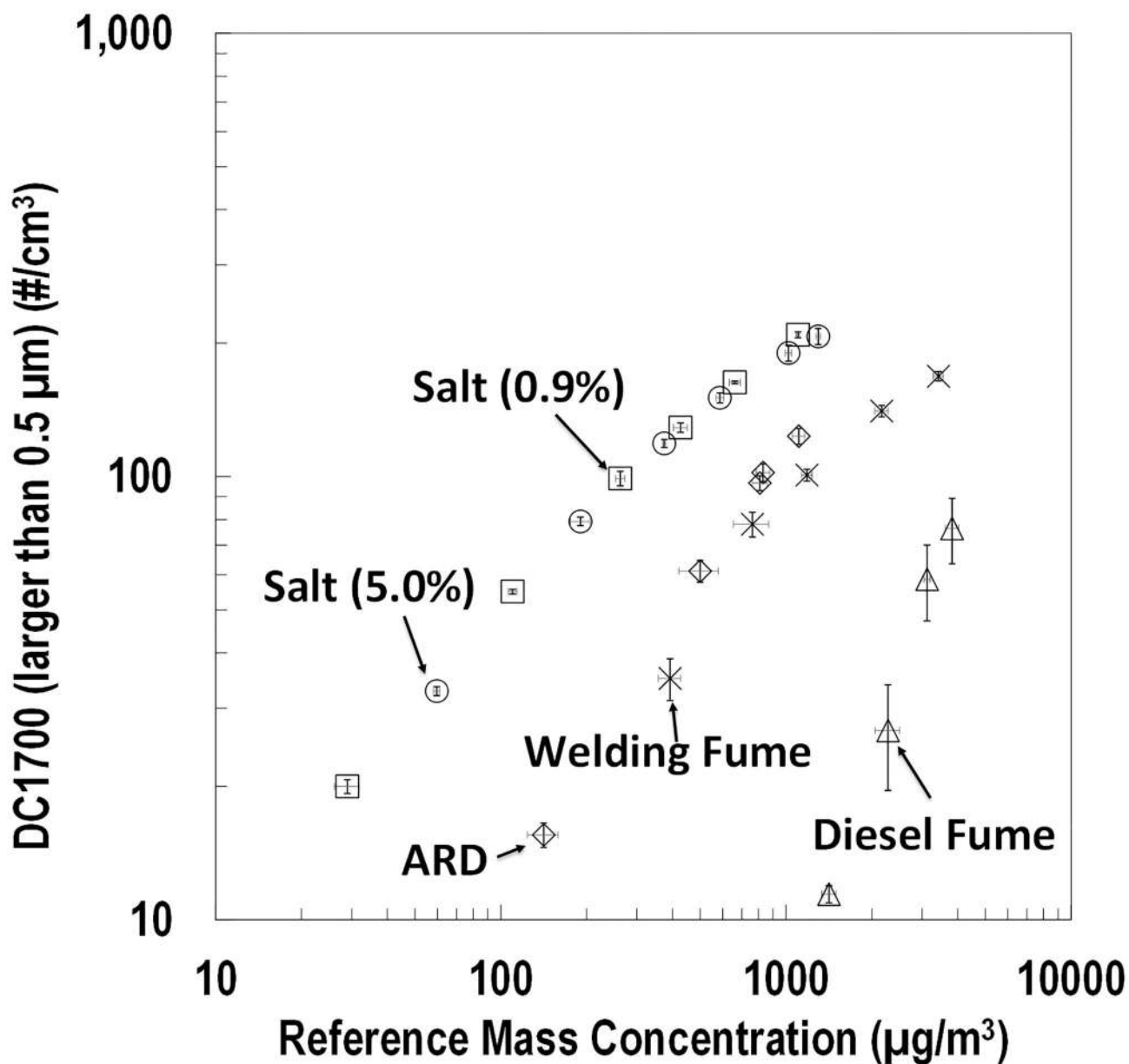
**B. Aerosol Generation Systems**



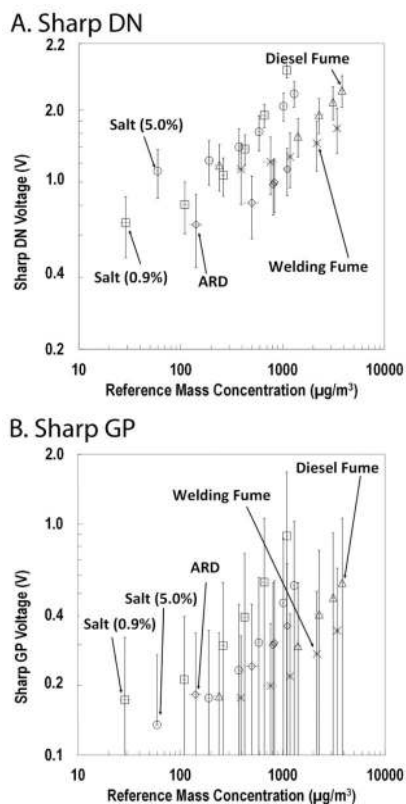
**Figure 2.** Experimental set up used to determine the performance of low-cost sensors shown in Panel A. Schematic diagrams of aerosol generation systems shown in Panel B.



**Figure 3.** Detection efficiency of the DC1700 by aerodynamic diameter. Particles smaller than  $0.5 \mu\text{m}$  were generated with a nebulizer followed by electrical classification, and the reference concentration was measured with the CPC. Particles larger than  $1 \mu\text{m}$  were generated with the VOAG, and the reference concentration was measured with the APS. Total (fine + coarse) corresponds with the “small bin” of the DC1700 and coarse corresponds with the “large bin” of the Dylos. Fine was calculated as the small bin minus the large bin.



**Figure 4.** Raw output of the DC1700 relative to reference mass concentration for DC1700. Reference mass concentration was calculated by correcting SMPS+APS data with mass concentration measured with a gravimetric filter for each aerosol. The error bars represent one standard deviation.



**Figure 5.** Raw output of the low-cost sensors relative to reference mass concentration for: A) Sharp DN; B) Sharp GP. Reference mass concentration was calculated by correcting SMPS+APS data with mass concentration measured with a gravimetric filter for each aerosol. The error bars represent one standard deviation.

**Table 1**

Aerosol measurement instruments specifications used in the current work

Device	Cost Category	Cost (\$)	Size (m) (H×W×D)	Weight (g)	Sampling flow	Size Range	Concentration Range
DC 1700	Low	425	0.18×0.11×0.08	544	NA	> 0.5 $\mu\text{m}$ > 2.5 $\mu\text{m}$	0–10 <sup>6</sup> #/cm <sup>3</sup> *
Sharp GP	Low	12	0.046×0.03×0.02	15	NA	≥0.5 $\mu\text{m}$	0.5 V/(0.1 mg/m <sup>3</sup> )
Sharp DN	Low	21	0.05×0.044×0.02	52	NA	≥0.5 $\mu\text{m}$	1 V/(0.1 mg/m <sup>3</sup> )
pDR-1500	Medium	<10,000	0.181×0.143×0.08	1200	1.0–3.5 L/min	1.0 to 10 $\mu\text{m}$	0.001–400 mg/m <sup>3</sup>
CPC 3007	Medium		0.14×0.14×0.292	1700	0.7 L/min	10–1000 nm	1–10 <sup>5</sup> particles/cm <sup>3</sup>
SMPS/CPC(GRIMM)	High	~60,000			1 L/min	5 nm – 1,000 nm	1–10 <sup>7</sup> particles/cm <sup>3</sup>
APS 3321	High	~20,000	0.18×0.3×0.38	10,000	5 L/min	0.5–20 $\mu\text{m}$	10,000 particles/cm <sup>3</sup>

\* Less than 10% coincidence loss at 10<sup>6</sup> particles/cm<sup>3</sup> based on the specifications provided directly from the manufacturer



Precision of low-cost sensors raw output (raw) and calculated mass concentration based on the regression model (mass) expressed as the mean coefficient of variation (CV, %) by aerosol type.

**Table 2**

Aerosol	DC1700				Sharp DN		Sharp GP	
	Small Bin		Large Bin		Voltage	mass	Voltage	mass
	number	concentration	mass	raw				
0.9% Salt Aerosol	2.2	1.4	7.2	-	27	5.9	14	5.9
5% Salt Aerosol	2.2	1.4	15	-	24	5.4	51	4.8
Arizona Road Dust	4.3	3.1	5.0	-	27	1.7	5.0	1.9
Diesel Fume	14	1.8	12	-	17	0.8	15	0.9
Welding Fume	9.0	8.0	14	-	30	7.1	2.0	1.7
Overall Mean	7.4	3.1	11	-	25	4.2	17	3.1

**Table 3**

The average calculated mass median diameter (MMD) and geometric standard deviation (GSD) for each aerosol based on the SMPS and APS data.

Aerosol	MMD + Standard deviation ( $\mu\text{m}$ )	GSD + Standard deviation
0.9% Salt Solution	0.58 $\pm$ 0.04	1.80 $\pm$ 0.04
5% Salt Solution	0.81 $\pm$ 0.01	1.60 $\pm$ 0.08
Arizona Road Dust	2.63 $\pm$ 0.09	1.00 $\pm$ 0.06
Diesel Fume	Multimodal distribution, two modes* (Figure S2 in Supplemental Information, SI)	
Welding Fume	Multimodal distribution two modes* (Figure S3 in Supplemental Information, SI)	

\* Multimodal MMD and CMD were not calculated for this work

**Table 4**

Regression equations to estimate mass concentration ( $y$  in  $\mu\text{g}/\text{m}^3$ ) from DC1700 number concentration ( $x$  = small bin particles/ $\text{cm}^3$ ). For particle concentrations ( $x$ ) less than 106 particles/ $\text{cm}^3$

<b>Aerosol</b>	<b>Equation</b>	<b>R<sup>2</sup></b>
0.9% Salt Aerosol	$y = 2.6 \times x - 22$	0.96
5% Salt Aerosol	$y = 6.2 \times x - 153$	0.99
Arizona Road Dust	$y = 8.6 \times x + 98$	0.98
Diesel Fume	$y = 54 \times x + 511$	0.91
Welding Fume	$y = 12 \times x - 12$	0.96

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Evaluation of mass concentrations measured with the pDR-1500 with reference to those measured with the SMPS and APS.

**Table 5**

Aerosol	Data Pairs	Slope $\pm$ Std. Error	Intercept $\pm$ Std. Error	r	R <sup>2</sup>	% Bias
0.9% Salt Aerosol	21	1.2 $\pm$ 0.02	-46 $\pm$ 12	0.99 <sup>1</sup>	0.99	-3.4 <sup>1,2</sup>
5% Salt Aerosol	21	0.9 $\pm$ 0.006 <sup>1,2</sup>	-5.0 $\pm$ 4.0 <sup>1</sup>	0.99 <sup>1</sup>	0.99	4.6 <sup>1,2</sup>
Arizona Road Dust	18	1.3 $\pm$ 0.04	-54 $\pm$ 14	0.99 <sup>1</sup>	0.98	-2.0 <sup>1,2</sup>
Diesel Fume	21	1.1 $\pm$ 0.02 <sup>1,2</sup>	28 $\pm$ 66	0.99 <sup>1</sup>	0.99	-9.1 <sup>1,2</sup>
Welding Fume	18	1.0 $\pm$ 0.02 <sup>1,2</sup>	-55 $\pm$ 24	0.99 <sup>1</sup>	0.99	-1.1 <sup>1,2</sup>

<sup>1</sup> meets EPA criterion

<sup>2</sup> meets NOISH criterion

Table 6  
 Evaluation of mass concentrations estimated with the DC1700 with reference to those measured with the SMPS and APS. Based on DC1700 particle concentrations less than 106 particles/cm<sup>3</sup>

Aerosol	Data Pairs	Slope ± Std. Error	Intercept ± Std. Error	r	R <sup>2</sup>	% Bias
0.9% Salt	21	0.9 ± 0.04 <sup>1,2</sup>	14 ± 7.0	0.99 <sup>1</sup>	0.98	4.0 <sup>1,2</sup>
5% Salt	21	0.8 ± 0.05	21 ± 7.0	0.99 <sup>1</sup>	0.98	7.0 <sup>1,2</sup>
Arizona Road Dust	18	1.2 ± 0.04	10 ± 26	0.98 <sup>1</sup>	0.98	-18
Diesel Fume	21	1.1 ± 0.05 <sup>1,2</sup>	-51 ± 23	0.95	0.91	-38
Welding Fume	18	0.9 ± 0.07 <sup>1,2</sup>	71 ± 67	0.98 <sup>1</sup>	0.95	-3.0 <sup>1,2</sup>

<sup>1</sup> meets EPA criterion

<sup>2</sup> meets NOISH criterion

**Table 7**

Evaluation of mass concentrations estimated with the Sharp sensors with reference to those measured with the SMPS and APS.

Aerosol	Data Pairs	Slope $\pm$ Std. Error	Intercept $\pm$ Std. Error	Error ( $\mu\text{g}/\text{m}^3$ )	r	R <sup>2</sup>	% Bias
<b>A. Sharp DN</b>							
0.9% Salt Aerosol	21	1.2 $\pm$ 0.02	-34 $\pm$ 14		0.99 <sup>1</sup>	0.99	-3.7 <sup>1,2</sup>
5% Salt Aerosol	21	0.9 $\pm$ 0.006 <sup>1,2</sup>	-5.0 $\pm$ 5.0 <sup>1</sup>		0.99 <sup>1</sup>	0.99	5.2 <sup>1,2</sup>
Arizona Road Dust	18	1.3 $\pm$ 0.04	-55 $\pm$ 30		0.99 <sup>1</sup>	0.98	-5.8 <sup>1,2</sup>
Diesel Fume	21	1.1 $\pm$ 0.05 <sup>1,2</sup>	3.3 $\pm$ 65 <sup>1</sup>		0.99 <sup>1</sup>	0.99	-9.8 <sup>1,2</sup>
Welding Fume	18	1.0 $\pm$ 0.02 <sup>1,2</sup>	-57 $\pm$ 31		0.99 <sup>1</sup>	0.99	-1.3 <sup>1,2</sup>
<b>B. Sharp GP</b>							
0.9% Salt Aerosol	21	1.2 $\pm$ 0.02	-33 $\pm$ 14		0.99 <sup>1</sup>	0.99	-3.8 <sup>1,2</sup>
5% Salt Aerosol	21	0.9 $\pm$ 0.006 <sup>1,2</sup>	-0.6 $\pm$ 5.0 <sup>1</sup>		0.99 <sup>1</sup>	0.99	4.6 <sup>1,2</sup>
Arizona Road Dust	18	1.3 $\pm$ 0.03	-56 $\pm$ 26		0.99 <sup>1</sup>	0.98	-6.3 <sup>1,2</sup>
Diesel Fume	21	1.1 $\pm$ 0.025 <sup>1,2</sup>	8.2 $\pm$ 66		0.97 <sup>1</sup>	0.95	-9.3 <sup>1,2</sup>
Welding Fume	18	1.0 $\pm$ 0.01 <sup>1,2</sup>	-55 $\pm$ 25		0.99 <sup>1</sup>	0.99	-2.4 <sup>1,2</sup>

<sup>1</sup> meets EPA criterion

<sup>2</sup> meets NOISH criterion