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ESTIMATED STICKY PRICE MODEL

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ABSTRACT

This paper evaluates alternative rules by which the Fed may set interest rates using the small model of the U.S. economy estimated in Rotemberg and Woodford (1997). Our main substantive finding is that low and stable inflation together with stable interest rates can be achieved by letting the funds rate respond positively to inflation while also responding, with a coefficient bigger than one, to the lagged funds rate itself. A rule in which the interest rate is set in this extremely simple way does almost as well as a more complicated rule which is optimal in our setting, in the sense of maximizing expected utility to the representative household. Furthermore, when the funds rate responds to inflation only with a delay, due to delay in the availability of inflation data, performance under the rule is only slightly reduced.

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This paper seeks to evaluate monetary policy rules which generalize the rule proposed by Taylor (1993). In particular, we consider rules in which the Fed sets the Federal funds rate as a function of the history of inflation, output and the Federal funds rate itself. Even though this is not part of Taylor's original formulation, we introduce the possibility that the Federal funds rate depends on the history of the funds rate itself in order to allow for interest-rate smoothing of the kind that appears to be an important feature of current Fed policy. We also consider the character of optimal policy, *i.e.*, the policy that maximizes the utility of the representative agent, assuming unlimited information about the exogenous disturbances to the economy. We then compare optimal policy in this unrestricted sense with the best rule of the generalized-Taylor family.

We evaluate these rules under the assumption that interest rate, inflation and output determination in the U.S. economy can be compactly represented by the small structural model whose parameters we estimate in Rotemberg and Woodford (1997). This is a rational expectations model derived from explicit intertemporal optimization, in which firms are unable to change their prices every period, and in which purchases are determined somewhat in advance of when they actually take place. In evaluating different monetary rules we use two approaches. The first approach is simply to compute the welfare of the representative household according to our model of the U.S. economy. Because this places great strain on the assumptions that the model contains accurate descriptions of the preferences of American residents, and that we have correctly identified the nature of the real disturbances to which monetary stabilization policy must respond, we also study separately the variability of output, inflation, and interest rates induced by different policy rules. This latter way of characterizing economic performance under alternative rules is less dependent upon the "deep structural" interpretation of the residuals in our structural equations, although it is, of course, still dependent upon the specification of those structural equations and upon the statistical properties of their disturbance terms.

We proceed as follows. In section 1, we describe the structure of the model, which is discussed more thoroughly in Rotemberg and Woodford (1997, 1998). Section 2 is devoted

to the analysis of simple policy rules that represent variations upon the rule proposed by Taylor (1993), while section 3 considers optimal policy. Section 4 concludes.

1 A Framework for Analysis

We begin by reviewing the structure of the estimated sticky-price model developed in Rotemberg and Woodford (1997). This also allows us to derive the utility-based measure of dead-weight loss due to price-level instability that is the basis for our subsequent discussion of optimal policy.

1.1 A Small, Structural Model of the U.S. Economy

We suppose that there is a continuum of households indexed by i where i runs between 0 and 1. Each of these households produces a single good while it consumes the composite good. The utility of household i at t is given by

$$E_t \sum_{T=t}^{\infty} \beta^{(T-t)} [u(C_T^i; \xi_T) - v(y_T^i; \xi_T)], \quad (1.1)$$

where β is a discount rate, y_t^i is the household's production of its own good and ξ_t is a vector of preference (or technological) disturbances. The argument C_t^i represents an index of the household's purchases of the continuum of differentiated goods produced in the economy. Following Dixit and Stiglitz (1977), this index is given by

$$C_t^i \equiv \left[\int_0^1 c_t^i(z)^{\frac{\theta-1}{\theta}} dz \right]^{\frac{\theta}{\theta-1}} \quad (1.2)$$

where $c_t^i(z)$ is the quantity purchased of good z , and the constant elasticity of substitution θ is assumed to be greater than one. We assume that all purchasers, including the government, care only about an aggregate of the form (1.2). As usual, this implies that the total demand $y_t(z)$ for differentiated good z is given by a constant-elasticity demand function

$$y_t^z = Y_t \left(\frac{p_t(z)}{P_t} \right)^{-\theta}, \quad (1.3)$$

where $p_t(z)$ is the period t price of good z , P_t is the price index defined by

$$P_t \equiv \left[\int_0^1 p_t(z)^{1-\theta} dz \right]^{\frac{1}{1-\theta}}, \quad (1.4)$$

and Y_t measures aggregate demand for the composite good defined by (1.2).

One of the delays we assume is that households must choose their index of purchases C_t^i at date $t - 2$. As we show in Rotemberg and Woodford (1997) this, or an assumption like it, seems necessary if one wishes to explain the response of U.S. GDP to monetary disturbances, because this response is itself delayed by about two quarters. This delay implies that the standard Euler equation for optimal intertemporal allocation of consumption spending need not hold, except (approximately) conditional upon information available two periods in advance. Because C_t^i is chosen in advance, household optimization requires only that

$$E_t[u_C(C_{t+2}^i; \xi_{t+2})] = E_t[\lambda_{t+2}^i P_{t+2}], \quad (1.5)$$

where λ_t^i is a Lagrange multiplier indicating the marginal utility for household i of additional nominal income in period t . Assuming borrowing limits that never bind in equilibrium, these marginal utilities of income must satisfy

$$\lambda_t^i = \beta R_t E_t \lambda_{t+1}^i, \quad (1.6)$$

where R_t is the gross return on a riskless nominal one-period asset in which the household invests at t . We assume the existence of complete insurance markets, so that all households consume the same amount at any time, and have the same marginal utility of income. Then equations (1.5) and (1.6) also hold when we drop the i superscripts, and interpret them as equations relating aggregate consumption C_t to the marginal utility of income λ_t of the representative household. However, because of the conditional expectations in (1.5), these two equations still do not imply the standard Euler equation relating aggregate consumption spending in two consecutive periods to the real rate of return between those two periods. Finally, substituting into (1.5) the equilibrium requirement that $C_t = Y_t - G_t$, where G_t represents exogenous variation in government purchases of the composite good, we obtain

an equilibrium relation between the index of aggregate demand Y_t and variations in the marginal utility of income, which provides the crucial link in our model between interest rate variations and aggregate demand.

For our numerical work, we rely upon log-linear approximations to the model's structural equations. We assume an equilibrium in which the economy always stays near a steady state path, which represents a stationary, deterministic equilibrium in the case of no exogenous disturbances ($\xi_t = 0$ and $G_t = \bar{G}$ at all times) and a monetary policy consistent with stable prices. In this steady state, output is constant at a level \bar{Y} (defined below), and consumption is constant at the level $\bar{C} \equiv \bar{Y} - \bar{G}$.¹ It follows that the marginal utility of real income, $\lambda_t P_t$, is also constant, at the value $\bar{\lambda} \equiv u_C(\bar{C}; 0)$. We log-linearize the structural equations of the model around these steady-state values. Percentage deviations in the marginal utility of consumption $u_C(C_t; \xi_t)$ around the steady-state value $u_C(\bar{C}; 0)$ can be written as $-\bar{\sigma}(\hat{C}_t - \bar{C}_t)$, where $\hat{C}_t \equiv \log(C_t/\bar{C})$, \bar{C}_t is an exogenous shift variable (a certain linear combination of the elements of ξ_t),² and $\bar{\sigma} \equiv -u_{CC}\bar{C}/u_C$, where the partial derivatives are evaluated at the steady-state level of consumption. With this substitution, the log-linear approximations to (1.5) and (1.6) are given by

$$-\bar{\sigma} E_{t-2}[\hat{C}_t - \bar{C}_t] = E_{t-2}[\hat{\lambda}_t], \quad (1.7)$$

$$\hat{\lambda}_t = \hat{R}_t - \pi_{t+1} + E_t \hat{\lambda}_{t+1}, \quad (1.8)$$

where $\hat{R}_t \equiv \log(R_t/R^*) = \log(\beta R_t)$ is the percentage deviation of the short-run nominal interest rate from its steady-state value, $\pi_t \equiv \log(P_t/P_{t-1})$ is the inflation rate, and $\hat{\lambda}_t \equiv \log(\lambda_t P_t/\bar{\lambda})$ measures the percentage deviation of the marginal utility of real income from its steady-state value. (Equation (1.8) refers to actual rather than expected inflation because inflation π_{t+1} is known with certainty at date t in our model.)

A similar log-linear approximation to the market-clearing condition allows us to replace $\hat{C}_t - E_{t-2}\bar{C}_t$ with $s_C^{-1}(\hat{Y}_t - \hat{G}_t)$, where $s_C \equiv \bar{C}/\bar{Y}$, $\hat{Y}_t \equiv \log(Y_t/\bar{Y})$, and \hat{G}_t collects the exogenous disturbance terms that shift the relation between aggregate demand and the

marginal utility of consumption. Substituting this into (1.7) yields

$$E_{t-2}\hat{\lambda}_t = -\sigma E_{t-2}[\hat{Y}_t - \hat{G}_t], \quad (1.9)$$

where $\sigma \equiv s_C^{-1}\tilde{\sigma}$. Then taking the conditional expectation of (1.8) two periods earlier, and substituting (1.9), we obtain

$$E_{t-2}[\hat{Y}_t - \hat{G}_t] = -\sigma^{-1}E_{t-2}[\hat{R}_t - \pi_{t+1}] + E_{t-2}[\hat{Y}_{t+1} - \hat{G}_{t+1}]. \quad (1.10)$$

(Thus, in our log-linear approximation, the standard Euler equation does hold, but only conditional upon lagged information.) Solving forward, we may equivalently write

$$\hat{Y}_t = \hat{G}_t - \sigma^{-1}E_{t-2}\sum_{T=t}^{\infty}[\hat{R}_T - \pi_{T+1}]. \quad (1.11)$$

Equation (1.11) plays a role analogous to the “IS equation” of traditional Keynesian models, but is consistent with intertemporal optimization.³ It relates output to the long run real interest rate (with a negative sign) and to autonomous spending disturbances. The latter include both disturbances to private impatience to consume resources, and to government spending, summarized in the composite disturbance term \hat{G}_t . We assume that \hat{G}_t is determined at $t - 1$, so that it is determined after C_t has already been chosen, but in time for the central bank to adjust the period t interest rate R_t in response to it. Letting \hat{G}_t be determined after \hat{C}_t ensures that output is not predetermined as of $t - 2$ (i.e., it allows us an interpretation for the output innovations in our VAR model of the U.S. data), even though output responds with a two period delay to exogenous disturbances to monetary policy.

The source of the real effects of monetary policy in our model is that prices do not adjust immediately to shocks. Following Calvo (1983), we assume that prices are changed at exogenous random intervals.⁴ Specifically, a fraction $(1 - \alpha)$ of sellers get to choose a new price at the end of any given period, whereas the others must continue using their old prices. Of those who get to choose a new price, a fraction γ start charging the new price at the beginning of the next period. The remaining fraction $(1 - \gamma)$ must wait until the following period to charge the new price or, put differently, they must post their prices one

quarter in advance. These assumed delays explain why no prices respond in the quarter of the monetary disturbance and why the largest response of inflation to a monetary shock takes place only two quarters after the shock.

Let p_t^1 denote the price set by sellers that decide at date $t - 1$ upon a new price to take effect at date t , and p_t^2 the price set by sellers that decide at date $t - 2$ upon a new price to take effect only two periods later. These prices are chosen to maximize the contributions to expected utility resulting from sales revenues on the one hand, and the disutility of output supply on the other, at each of the future dates and in each of the future states in which the price commitment still applies. This means that p_t^1 is chosen to maximize

$$\Phi_{t-1}(p) \equiv E_{t-1} \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} \left[\lambda_T (1 - \tau) p Y_T \left(\frac{p}{P_T} \right)^{-\theta} - v \left(Y_T \left(\frac{p}{P_T} \right)^{-\theta} ; \xi_T \right) \right] \quad (1.12)$$

over p . Here we have substituted the demand function (1.3) into the household's objective function, written λ_T for the marginal utility (in units of period T utility flow) of additional nominal income during period T , and assumed that revenues each period are taxed at the constant rate τ .⁵ The factor α^{T-t} appears as the probability that the price that is charged beginning in period t is still in effect in period $T \geq t$ (where we assume that this contingency is independent of all aggregate disturbances). Note that our assumption of complete contingent claims markets (including full opportunities for households to insure one another against idiosyncratic risk associated with different timing of their price changes) implies that the marginal utility of income process $\{\lambda_T\}$ is the same for all households, and can be treated as an exogenous stochastic process by an individual household (whose pricing decisions will have only a negligible effect upon aggregate prices, aggregate incomes, and aggregate spending decisions). Similarly, an individual household treats the processes $\{P_T, Y_T\}$ as exogenous in choosing its desired price. The optimizing choice of p_t^1 then must satisfy the first-order condition

$$\Phi'_{t-1}(p_t^1) = 0, \quad (1.13)$$

where the prime denotes the derivative with respect to p in the explicit expression given in (1.12).

As before, we wish to log-linearize this equilibrium condition around a steady state in which $Y_t = \bar{Y}$, $P_t/P_{t-1} = 1$, $p_t^1/P_t = 1$, and $\lambda_t P_t = \bar{\lambda}$ at all times. (The requirement that these constant values satisfy (1.13) when $\xi_t = 0$ at all times determines the steady-state value \bar{Y} .⁶) Percentage deviations of $v_y(y_t^j; \xi_t)$ from its steady-state value can be written as $\omega(\hat{y}_t^j - \bar{Y}_t)$, where $\omega \equiv v_{yy}\bar{Y}/v_y$, with partial derivatives evaluated at the steady state, $\hat{y}_t^j \equiv \log(y_t^j/\bar{Y})$, and \bar{Y}_t is a certain linear function of ξ_t . Using this notation, the log-linear approximation to (1.13) takes the form

$$E_{t-1} \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [(\hat{\lambda}_T + \hat{Y}_T - (\theta - 1)\hat{p}_{t,T}^1) - \omega(\hat{Y}_T - \theta\hat{p}_{t,T}^1 - \bar{Y}_T) - (\hat{Y}_T - \theta\hat{p}_{t,T}^1)] = 0, \quad (1.14)$$

where in addition $\hat{p}_{t,T}^1 \equiv \log(p_t^1/P_T)$. Introducing the notation $\hat{X}_t \equiv \frac{1-\alpha}{\alpha} \log(p_t^1/P_t)$,⁷ so that $\hat{p}_{t,T}^1 = \frac{\alpha}{1-\alpha} \hat{X}_t - \sum_{s=t+1}^T \pi_s$, we can solve (1.14) to obtain

$$\hat{X}_t = \frac{1-\alpha}{\alpha} \frac{1-\alpha\beta}{1+\omega\theta} E_{t-1} \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [-\hat{\lambda}_T + \omega(\hat{Y}_T - \bar{Y}_T) + (1+\omega\theta) \sum_{s=t+1}^T \pi_s] \quad (1.15)$$

as the optimizing choice of the relative price in period t of goods with new prices chosen just the period before.

We can use (1.9) to eliminate the $E_{t-1}\hat{\lambda}_T$ terms in (1.15), for all $T > t$. Taking the conditional expectation of (1.8) at $t-1$, and using (1.9), we see that we can also write

$$E_{t-1}\hat{\lambda}_t = \phi_{t-1} - \sigma E_{t-1}[\hat{Y}_t - \hat{G}_t], \quad (1.16)$$

where

$$\begin{aligned} \phi_t &\equiv E_t[\hat{R}_{t+1} - \pi_{t+2} - \sigma(\hat{Y}_{t+2} - \hat{G}_{t+2} - \hat{Y}_{t+1} + \hat{G}_{t+1})] \\ &= E_{t-1} \sum_{T=t}^{\infty} (\hat{R}_T - \pi_{T+1}) - E_{t-2} \sum_{T=t}^{\infty} (\hat{R}_T - \pi_{T+1}). \end{aligned} \quad (1.17)$$

Note that the final equality in (1.17) follows from substitution of (1.11). Then, substituting (1.9) and (1.16) into (1.15), we obtain

$$\hat{X}_t = \frac{1-\alpha}{\alpha} \frac{1-\alpha\beta}{1+\omega\theta} \left[E_{t-1} \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [(\sigma + \omega)(\hat{Y}_T - \hat{Y}_T^S) + (1+\omega\theta) \sum_{s=t+1}^T \pi_s] - \phi_{t-1} \right],$$

$$= \frac{1-\alpha}{\alpha} \frac{1-\alpha\beta}{1+\omega\theta} \left[E_{t-1} \sum_{T=t}^{\infty} (\alpha\beta)^{T-t} [(\sigma+\omega)(\hat{Y}_T - \hat{Y}_T^S) + (1+\omega\theta) \frac{\alpha\beta}{1-\alpha\beta} \pi_{T+1}] - \phi_{t-1} \right], \quad (1.18)$$

where

$$\hat{Y}_t^S \equiv \frac{\omega}{\omega+\sigma} E_{t-1} \bar{Y}_t + \frac{\sigma}{\omega+\sigma} \hat{G}_t$$

is a composite exogenous disturbance. We can think of \hat{Y}_t^S as representing variation in the “natural” or “potential” level of output, since it is expected deviations $\hat{Y} - \hat{Y}^S$, rather than deviations in the level of output relative to trend, that results in a desire by price-setters to increase the *relative* price of their goods, which in equilibrium requires inflation of the average level of prices. (An equilibrium in which no prices are ever changed is consistent with (1.18) as long as $\hat{Y}_t = \hat{Y}_t^S$ at all times, and interest rates vary so as to ensure that $\phi_t = 0$ at all times. Note that the latter condition ensures that (1.10) and hence (1.11) are also satisfied at all times.)

We turn next to the price-setting decision of sellers that choose a new price p_t^2 at $t-2$ to apply beginning in period t . Because such a price is expected to apply in periods $t+j$ with exactly the same probabilities as for the price p_t^1 , the objective of these sellers is simply $E_{t-2} \Phi_{t-1}(p)$, and the first-order condition that determines p_t^2 is given by $E_{t-2} \Phi'_{t-1}(p_t^2) = 0$. Comparison with (1.13) implies that, in our log-linear approximation,

$$\log p_t^2 = E_{t-2} \log p_t^1. \quad (1.19)$$

Finally, our definition of the price index (1.4) implies that this index evolves according to

$$P_t = [\alpha P_{t-1}^{1-\theta} + (1-\alpha)\gamma(p_t^1)^{1-\theta} + (1-\alpha)(1-\gamma)(p_t^2)^{1-\theta}]^{1/(1-\theta)}.$$

Dividing both sides by P_t , log-linearizing, and substituting (1.19), we obtain

$$\pi_t = \gamma \hat{X}_t + (1-\gamma) \left[E_{t-2} \hat{X}_t - \frac{1-\alpha}{\alpha} (\pi_t - E_{t-2} \pi_t) \right].$$

Taking the conditional expectation of both sides at $t-2$, one observes that $E_{t-2} \pi_t = E_{t-2} \hat{X}_t$.

Substitution of this then allows the equation to be written in the form

$$\pi_t = \psi \hat{X}_t + (1-\psi) E_{t-2} \hat{X}_t, \quad (1.20)$$

where $\psi \equiv \gamma\alpha/[1-\gamma(1-\alpha)]$. This indicates how aggregate inflation results from the incentives of individual price-setters to choose a higher relative price.

These results may be collected in the form of an implied aggregate supply relation between inflation variation and deviations of output from potential. Equation (1.18) may be expressed in quasi-differenced form as

$$\begin{aligned}\hat{X}_t &= \kappa(\hat{Y}_t - \hat{Y}_t^S) + (1-\alpha)\beta E_{t-1}\pi_{t+1} + \alpha\beta E_{t-1}\hat{X}_{t+1} - \frac{\kappa}{\sigma+\omega}\phi_{t-1} \\ &= \kappa(\hat{Y}_t - \hat{Y}_t^S) + \beta E_{t-1}\hat{X}_{t+1} - \frac{\kappa}{\sigma+\omega}\phi_{t-1},\end{aligned}\tag{1.21}$$

where $\kappa \equiv (1-\alpha)(1-\alpha\beta)(\omega+\sigma)/\alpha(1+\omega\theta)$, and the second line follows from the fact that (1.20) implies that $E_{t-2}\pi_t = E_{t-2}\hat{X}_t$. Solving this forward, we obtain

$$\hat{X}_t = \kappa E_{t-1} \left\{ \sum_{T=t}^{\infty} \beta^{T-t} (\hat{Y}_T - \hat{Y}_T^S) \right\} - \frac{\kappa}{\sigma+\omega} \phi_{t-1},$$

where we have used the fact that (1.17) implies that $E_{t-1}\phi_t = 0$. Substitution of this into (1.20) then yields

$$\begin{aligned}\pi_t &= (1-\psi)E_{t-2}\pi_t + \psi \left[\kappa E_{t-1} \sum_{T=t}^{\infty} \beta^{T-t} (Y_T - Y_T^S) \right. \\ &\quad \left. - \frac{\kappa}{\omega+\sigma} \left(E_{t-1} \sum_{T=t}^{\infty} (\hat{R}_T - \pi_{T+1}) - E_{t-2} \sum_{T=t}^{\infty} (\hat{R}_T - \pi_{T+1}) \right) \right].\end{aligned}\tag{1.22}$$

This is our aggregate supply (AS) equation, relating inflation variation to deviations of output from potential. Because prices are set in advance, expectations of future increases in output relative to Y^S also raise prices. In addition, inflation declines when the long term real interest rate at t is higher than had been expected at $t-1$. The reason for this is that such upwards revisions raise the returns households can expect to earn from their revenues at t . As a result, they are inclined to raise these revenues by cutting their prices. Only surprise variations in the long rate contribute to this term, because only those variations result in changes in the current marginal utility of income that are not reflected in the current level of aggregate consumption demand, and hence in the output gap.

To complete our model specification, we posit that interest rates are set according to a

feedback rule of the form

$$r_t - r^* = \sum_{j=0}^{m_\pi} a_j (\pi_{t-j} - \pi^*) + \sum_{j=0}^{m_Y} b_j \hat{Y}_{t-j} + \sum_{j=1}^{m_R} c_j (r_{t-j} - r^*) \quad (1.23)$$

Here r_t is the continuously-compounded nominal interest rate (identified with $\log R_t$ in terms of our theoretical model, and with the Federal funds rate in our empirical implementation of the model), r^* is the steady-state value of r implied by the policy rule, and π^* is the steady-state inflation rate implied by the rule. In equilibrium, the steady state nominal interest rate r^* must equal the sum of the equilibrium steady state real interest rate ρ and the steady state inflation rate π^* . Thus, if ρ is independent of the monetary policy rule (as our model implies⁸), the monetary authority's choice of π^* implies a value for r^* . Thus the pair of values π^* and r^* represent only a single free parameter in the specification of the policy rule, which we shall treat in the subsequent discussion as the choice of π^* .⁹

The aim of our paper is to discuss the effects of alternative rules of the form of (1.23). In our discussion, we will generally treat separately the effects of the parameters a_i , b_i and c_i , which indicate how the interest rate reacts to the history of the economy, and the effects of the choice of π^* . This is because, in our log-linear approximation to the model's equilibrium conditions, the parameter π^* has no effect upon the implied responses to shocks (and hence upon the equilibrium variability of the various state variables), while the parameters a_i , b_i , c_i have no effect upon the implied steady state (and hence upon the average equilibrium values of the state variables). We may thus study separately the determination of the steady state and the determination of fluctuations around the steady state, and different parameters of the policy rule matter for each of these investigations. Our overall welfare criterion (discussed in the next subsection) depends, however, upon both aspects of equilibrium, and so upon both sets of policy parameters.

Our complete model of the economy consists of the IS and AS equations (1.11) and (1.22) together with the monetary policy rule (1.23). To evaluate the effect of changing the monetary rule we need to know both the parameters of the model as well as the stochastic process for the two structural disturbances, \hat{G}_t and \hat{Y}_t^S , the first of which affects only our IS

equation while the second affects only our AS equation. In Rotemberg and Woodford (1997, 1998) we describe both our method for estimating and calibrating the behavioral parameters as well as our approach to reconstructing the structural disturbances and their stochastic process. Here we give an outline of this approach.

We start with a recursive VAR model of the state vector¹⁰

$$Z_t = [\hat{r}_t, \hat{\pi}_{t+1}, \hat{Y}_{t+1}]' \quad (1.24)$$

where $\hat{r}_t \equiv r_t - r^*$ and $\pi_t \equiv \pi_t - \pi^*$.¹¹ We estimate a system of the form

$$\bar{Z}_t = B\bar{Z}_{t-1} + U\bar{e}_t \quad (1.25)$$

where the vector \bar{Z}_t is the transpose of $[Z'_t, Z'_{t-1}, Z'_{t-2}]$, and U is a lower triangular matrix with ones on the diagonal and nonzero off-diagonal elements only in the first three rows, the off-diagonal elements of which are estimated so as to make the residuals in \bar{e}_t orthogonal to one another. The first three rows of the vectors \bar{e}_t contain the VAR residuals $e_{1,t}$, $e_{2,t}$ and $e_{3,t}$, while the other elements are zero. The number of lags included in our VAR is sufficient to eliminate nearly all evidence of serial correlation in the disturbances.

The first equation in this VAR is our estimate of the monetary policy rule. This estimated rule has the same structure as (1.23), except that it also includes a white noise residual $e_{1,t}$. Note that while the interest rate comes first in the casual ordering, the timing of the variables ensures that the interest rate in period t responds to inflation and output in period t , while these variables only react to lagged interest rates. We suppose that $e_{1,t}$ is independent of the two “real” disturbances \hat{Y}_t^S and \hat{G}_t so that it is exclusively a monetary policy disturbance. (Note that these identifying assumptions are ones that are implied by the decision lags assumed in our theoretical model.) Under these assumptions, we can estimate not only the coefficients of the historical monetary policy rule, but also the impulse responses of output, inflation and the interest rate to a monetary policy disturbance. We can then recover most of the structural parameters of our model by minimizing the discrepancy between the estimated responses of these variables to the monetary disturbance $e_{1,t}$ and the responses predicted by

our theoretical model when the systematic part of the monetary policy rule is given by the estimated coefficients in (1.23).¹² By calibrating the remaining parameters on the basis of other evidence, we obtain numerical values for the model parameters α , β , γ , σ , θ and ω . These are, respectively, .66, .99, .63, .16, 7.88 and .47, so that κ equals .024 and ψ equals .53.

Armed with our parameter values and the VAR, we can reconstruct the stochastic processes for the structural disturbances as follows.¹³ Equation (1.11) gives \hat{G}_t as the sum of \hat{Y}_t and σ times the expected long term real rate. Given that the VAR allows us to forecast both inflation and interest rates, this expected long term real rate is a function of \bar{Z}_t . Similarly, solving (1.20) for \hat{X}_t as a function of inflation and expected inflation, and substituting this into (1.21), we find that \hat{Y}_t^S must be given by

$$\hat{Y}_t^S = \hat{Y}_t - \frac{1}{\kappa\psi}\pi_t + \frac{1-\psi}{\kappa\psi}E_{t-2}\pi_t + \frac{\beta}{\kappa}E_{t-1}\pi_{t+1} - \frac{1}{\omega+\sigma}\phi_{t-1}.$$

Furthermore, using (1.17), the last term in this equation can be written as a function of expectations of future interest rates and inflation rates, as of periods $t-1$ and $t-2$. Using the VAR to forecast future variables, the right hand side of the equation then depends just on \bar{Z}_{t-1} , on \bar{Z}_{t-2} , and on the model parameters. It is thus straightforward to use the structural parameters as well as the matrices T and A to compute matrices C and D such that

$$s_t \equiv [\hat{G}_{t+1}, \hat{Y}_{t+1}^S]' = C\bar{Z}_{t-1} + D\bar{e}_t. \quad (1.26)$$

The resulting historical time series for the two disturbances s_t could then be identified with the residuals of the model's structural equations.

If the model fit the properties of the U.S. time series perfectly, the vector s_t constructed in this way would be orthogonal to the identified monetary policy disturbance $e_{1,t}$. In practice, the right hand side of (1.26) does depend upon the first element of the vector of VAR residuals \bar{e}_t , which we identify as the monetary policy disturbance. Perhaps more troubling is the observation that if the real disturbances s_t are generated by a law of motion of the kind implied by conjoining (1.26) with equation (1.25) for the evolution of \bar{Z}_t , then we should not

expect all three of the independent structural disturbances \bar{e}_t that matter for the evolution of s_t to be revealed by data on the three variables in Z_t alone. (This is because one of the VAR innovations corresponds to the monetary policy shock, so that only the other two orthogonal innovations can reveal information about the real disturbances.) But this would mean that forecasts of the future values of the variables in Z_t using the VAR should not correspond, in principle, to the expectations of these variables conditional upon the public's information set (assuming that the public has complete information about the structural disturbances); and thus our method for identifying the historical series for our structural equation residuals would not be internally consistent.

We prefer instead to work with a theoretical model not subject to this last problem, *i.e.*, one in which the evolution of the real disturbances s_t depends only upon two orthogonal disturbances each period, which then should in principle correspond to the two VAR residuals \bar{e}_{2t} and \bar{e}_{3t} . The structural disturbances s_t of our theoretical model then have moments that do not correspond precisely to those of the residuals of our model equations; but this discrepancy will exist only insofar as our model (quite apart from the law of motion chosen for the structural disturbances) is in fact inconsistent with the estimated VAR (and in particular, with the estimated impulse responses to a monetary policy shock). We accordingly consider a law of motion

$$s_t = CZ_{t-1}^\dagger + D^\dagger e_t^\dagger \quad (1.27)$$

for the structural disturbances, where the matrix C is the one referred to in (1.26), D^\dagger corresponds to D with the first column deleted, e_t^\dagger is a vector of two orthogonal white noise disturbances (which correspond to \bar{e}_{2t} and \bar{e}_{3t}). Here Z_t^\dagger is a vector of exogenous state variables that evolve according to

$$Z_t^\dagger = BZ_{t-1}^\dagger + U^\dagger e_t^\dagger, \quad (1.28)$$

where B is the same as in (1.25), and U^\dagger corresponds to U with the first column deleted.

Note that because the elements of Z_t^\dagger refer to exogenous states (underlying states for the dynamics of the real disturbances s_t), unlike the elements of \bar{Z}_t (which correspond to

endogenous variables of our model), this specification does *not* imply the existence of any feedback from the evolution of the endogenous variables to the exogenous disturbance processes s_t . What this construction *does* guarantee is that the empirical impulse response functions of inflation, output and interest rates to the two VAR disturbances orthogonal to the monetary policy shock are identical to the impulse responses predicted by our theoretical model. This property of the predicted impulse responses is independent of the structural parameters assumed in the model. Thus, given this method for constructing the laws of motion for the real disturbances, only the estimated responses to the monetary policy shock contain any information that can be used to help identify the structural parameters. This is our justification for the strategy that we use for parameter estimation, mentioned above.

It is worth noting that the stochastic processes for the real disturbances that we obtain with this method imply a great deal of variability for both \hat{G}_t and \hat{Y}_t^S . For example, the standard deviations of these two series are 29.5 and 13.7 percent respectively.¹⁴ This extreme volatility is consistent with the fact that the literature reports many “failures” in fitting equations very similar to our IS and AS curves by either ordinary least squares or by using lags as instruments. Our interpretation of these “failures” is that they say simply that these equations are subject to disturbances whose variance is large and whose serial correlation pattern is rich (so that they are correlated with the lags that are used as instruments).

In this paper, we evaluate monetary rules by evaluating how well they perform when the economy is buffeted by these shocks to \hat{G} and \hat{Y}^S . In other words, we are asking how the U.S. economy would perform if it were subject to structural disturbances whose properties are the same as those which have affected it in the past while, at the same time, the way interest rates are set by the central bank is different. Because the structural equations (1.11) and (1.22) follow simply from the Euler equations for optimal intertemporal behavior on the part of households, and so can be derived without reference to any particular specification of the monetary policy rule, they should remain invariant under contemplated changes in that rule. Thus our stochastic simulation methodology responds to the Lucas (1976) critique of more traditional methods of econometric policy evaluation.¹⁵

1.2 The Welfare Loss from Price-Level Instability

One of the primary advantages of our derivation of our structural equations from explicit optimizing foundations is that we are able to evaluate alternative monetary policy rules in terms of their welfare effects. Specifically, we consider the effects upon the average level of welfare

$$W = E\{u(C_t; \xi_t) - \int_0^1 v(y_t(z); \xi_t) dz\} \quad (1.29)$$

in the stationary equilibrium associated with one or another policy rule within the class that we consider.

Here the expectation is over alternative possible histories of the preference shocks ξ_t (which include the effects of technology shocks, since technological possibilities are implicit in our assumed disutility of supplying output). We only consider the welfare associated with alternative stationary rational expectations equilibria, in which all relative quantities are stationary and all quantities are trend-stationary. Thus we can evaluate an unconditional expectation in (1.29) for each of the equilibria that we consider. We also restrict our attention to monetary policy rules which result in unique stationary rational expectations equilibria (in terms of inflation, all relative prices, detrended output, and all relative quantities); we thus obtain a unique welfare measure for each policy rule in the admissible set. Given that we evaluate the unconditional expectation, rather than conditioning upon the current state of the economy at some particular date at which the policy choice is to be made, the criterion (1.29) is equivalent to comparing equilibria on the basis of the average level of expected utility of the households in our model (for the unconditional expectation of the latter quantity is simply $(1 - \beta)^{-1}W$). We evaluate the unconditional expectation in order to obtain a policy evaluation criterion that is not subject to any problem of time consistency.¹⁶

Following Rotemberg and Woodford (1998), we take a second-order Taylor series approximation of this welfare measure around the steady-state values of the stationary variables that affect utility. The “steady-state values” represent the constant equilibrium values of these variables in the absence of real disturbances, and in the case of a deterministic mone-

tary policy consistent with zero inflation.¹⁷ The steady state considered for this purpose also involves a tax rate τ which is set so that the steady-state level of output is efficient. (This involves a small output *subsidy*, in order to counteract the distortion caused by monopoly power.) Consideration of a Taylor series expansion around these values means that our approximate welfare measure will accurately rank alternative policy rules insofar as they result in only a small degree of variability of the relevant state variables, and they result in average values of the state variables that are close to the assumed steady-state values. Thus our analysis should be most reliable in the case of rules which imply an average rate of inflation not too different from zero and an average level of output near the optimal steady-state level \bar{Y} , and in which the fluctuations in both inflation and output are small. In fact, the policies that we characterize as optimal within various families of possible policy rules all imply low inflation rates, and also low variability of inflation and output, in the case that the variability of the real disturbances (represented by ξ_t) is small enough.

Linearization around this particular (optimal) steady state is extremely convenient, since our approximate measure of W takes an especially simple form in that case. In particular, in this case our second-order approximation for W depends only upon a first-order approximation to the equilibrium responses of inflation and output to the exogenous shocks. This means that we can solve a log-linear approximation to the model's equilibrium conditions using standard linear methods, as sketched in the previous subsection, and obtain an approximation to W that neglects only terms of third order and higher in the deviations from the steady state. This result depends upon the absence of any first-order contribution to our welfare measure from changes in the average level of output under alternative rules (as a result of the optimality of the level \bar{Y} relative to which we consider deviations); for if W contained a term of first order in the average level of output, then *second-order* terms in the equations determining output would matter for a second-order approximation to W .

In fact, in the calculations reported here, we furthermore assume that the tax rate τ actually varies depending on the monetary policy rule, so as to ensure that $E[\log Y_t] = \log \bar{Y}$ in any event. This allows us to obtain a measure of the deadweight loss associated with price-

level instability that abstracts from any effects of alternative monetary policies upon the long-run average level of output. While many analyses of the welfare effects of monetary policy have emphasized exactly such effects,¹⁸ we think there is good reason to abstract from them. Our primary reason is that there exist other policy instruments, such as the general level of and structure of taxation, which allow the government to influence the average level of output while, at the same time, being much less well-suited for the achievement of stabilization objectives, since they cannot be adjusted quickly and precisely in response to shocks. It thus makes sense to assume that, in an optimal policy regime, the other instruments are chosen to achieve the desired average level of output for a given monetary policy, while the monetary policy rule is chosen to minimize those contributions to deadweight loss that are independent of the economy's average level of output. We do this by choosing the monetary policy rule that maximizes W under the assumption that the other instruments are adjusted in the manner stated in response to any change in the monetary policy rule.

Abstracting from these effects also has the advantage of making our results independent of a feature of our model about which we are especially uncomfortable, namely its predictions about the effects of sustained inflation upon the long-run level of output.¹⁹ One might think that sustained inflation should result in adaptations that eliminate any effects of the average inflation rate upon average output. One such adaptation would be price commitments that specify a constant rate of price increase of π^* between the occasions upon which the commitments are modified, as assumed in Yun (1996). With this modification, our model would come to satisfy the “natural rate hypothesis”. In the modified model, the correct second-order approximation to W would be exactly the one that we report here, but then it would apply to small fluctuations in the rate of inflation around *any* average value π^* .²⁰

We show in the Appendix that, under these assumptions, a second-order approximation for W is given by

$$\begin{aligned}
 W = & -\frac{1}{2}u_C\bar{Y}(\sigma + \omega)\text{var}\{(E_{t-2}(\hat{Y}_t - \hat{Y}_t^S))\} - \frac{1}{2}u_C\bar{Y}(\theta^{-1} + \omega)E[\text{var}_z\{\log y_t(z)\}] \\
 & +\text{terms independent of policy} + \mathcal{O}(\|\xi\|^3),
 \end{aligned} \tag{1.30}$$

where the suppressed final terms are either independent of the evolution of the endogenous variables, or of third order or smaller in the size of the exogenous disturbances. Note that this welfare measure depends solely upon the allocation of real resources, summarized by the pattern of levels of production $\{y_t(z)\}$ at each point in time. However, equation (1.30) indicates that welfare depends not only upon the degree to which aggregate output deviates from the natural level of output Y^S , but also upon the degree of (inefficient) dispersion of output levels across the different varieties of goods being produced at each point in time.

The dispersion of output levels directly corresponds, in equilibrium, to the degree of dispersion of output prices. Prices differ across goods, in turn, only because of variation in the overall price level (together with the fact that different suppliers adjust their prices at different times). The $E[\text{var}_z\{\log y_t(z)\}]$ term in (1.30) can accordingly be expressed as a function of the aggregate inflation process, as shown in the Appendix. With this substitution, we obtain

$$W = -\frac{1}{2}u_C\bar{Y}\left\{(\omega + \sigma)\text{var}\{E_{t-2}(\hat{Y}_t - \hat{Y}_t^S)\} + \frac{\theta(1 + \theta\omega)}{(1 - \alpha)^2}\left[\alpha\text{var}\{E_{t-2}\pi_t\} + \alpha\pi^{*2} + \left(\alpha + \frac{1 - \gamma}{\gamma}\right)\text{var}(\pi_t - E_{t-2}\pi_t)\right]\right\} + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3). \quad (1.31)$$

Here π^* again denotes the steady-state rate of inflation associated with a given policy rule (the rate of inflation when the shocks $\xi_t = 0$ for all time); it corresponds, neglecting terms of second order or higher, to the average rate of inflation (or to the unconditional mean of $\hat{\pi}$) in the stationary equilibrium. The notation “t.i.p.” refers to the terms that are independent of policy.

Expression (1.31) can be written more compactly as

$$W = -\Omega[L + \pi^{*2}] + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3) \quad (1.32)$$

where

$$L = \text{var}\{\pi_t\} + \psi^{-1}\text{var}\{\pi_t - E_{t-2}\pi_t\} + \Lambda\text{var}\{E_{t-2}(\hat{Y}_t - \hat{Y}_t^S)\}, \quad (1.33)$$

and $\Omega, \Lambda > 0$. The quantity $L + \pi^{*2}$ represents the measure of deadweight loss due to price-level instability that we shall use to evaluate alternative monetary policies. Here the loss

measure L collects the terms that depend solely upon the degree of variability of inflation and the output gap, while π^{*2} is proportional to the deadweight loss due to nonzero inflation, even when it is perfectly steady.²¹

Note that our loss measure L is similar in form to a type of *ad hoc* loss function,

$$\text{var}\{\pi_t\} + \lambda \text{var}\{\hat{Y}_t - \hat{Y}_t^S\},$$

for some $\lambda > 0$, assumed in many analyses of optimal monetary policy (e.g., Taylor (1979), Bean (1983)). Our utility-based derivation, however, allows us to assign a specific numerical weight to the relative importance of stabilization of output around Y^S , as opposed to inflation stabilization. It also clarifies the kinds of stabilization that are important. Because of the lags involved in pricing, it turns out to be desirable to reduce the variability of both expected inflation and unexpected inflation. Moreover, the variability of unexpected inflation deserves somewhat greater weight, unlike what the *ad hoc* loss function above would imply. The analysis also makes it clear that it is the variability of quarter-to-quarter inflation, rather than some longer-horizon average rate of inflation, or the deviation of the price level from some deterministic or stochastic trend path, that is most closely related to the welfare losses due to price-level instability. Finally, it makes it clear that it is the variability of $\hat{Y} - \hat{Y}^S$, rather than the variability of deviations of output from trend or the variability of output growth, that matters for welfare. Specifically, it is the variability of the part of $\hat{Y} - \hat{Y}^S$ that is forecastable two quarters earlier that policy should seek to minimize.

It is worth noting that all three of the terms in (1.33) are directly related, in different ways, to inflation variability. For the analysis of optimal policy below, it is helpful to rewrite L so that it depends only on the stochastic process for the relative price variable \hat{X} . We show in the Appendix that the model's structural equations imply that (1.33) may be rewritten in the form

$$L = \text{var}(E_{t-2}\hat{X}_t) + \psi \text{var}[\hat{X}_t - E_{t-2}\hat{X}_t] + \frac{\Lambda}{\kappa^2} \text{var}[E_{t-2}(\hat{X}_t - \beta\hat{X}_{t+1})]. \quad (1.34)$$

This shows that the deadweight losses measured by L are zero if variations in \hat{X} are eliminated (as we show below to be possible in principle). Thus a constant rate of inflation is

both necessary and sufficient for achievement of the minimum value of $L = 0$. This means that, even though our proposed welfare criterion (1.30) assigns ultimate importance *only* to the efficiency of the level of real activity in each sector of the economy, it in fact justifies giving complete priority to inflation stabilization as opposed to output stabilization.

Given the model, one can compute the value of L as well as that of its components for any rule that sets the interest rate as a function of the history of inflation and output in such a way that there is a unique stationary equilibrium. But this still leaves open the question of whether there is a trade-off between stabilizing the economy by reducing L and keeping a low steady state level of inflation. As suggested by Summers (1991), the requirement that nominal interest rates must always be positive implies that a low average rate of inflation is inconsistent with a great deal of stabilization. The reason is that a low average rate of inflation implies that the average interest rate is low, and this means that the interest rate cannot be too variable. At the same time, keeping the variability of interest rates low weakens the government's ability to reduce L by having the interest rate respond to shocks. To see this, it is worth displaying the relation between interest rates and \hat{X} implied by our model.

This relationship can easily be derived from the equilibrium conditions (1.17), (1.20), and (1.21), together with the requirement that

$$E_t(\hat{Y}_{t+2} - \hat{G}_{t+2}) = \hat{Y}_{t+2} - \hat{G}_{t+2}, \quad (1.35)$$

which is implied by the fact that interest-sensitive purchases in period $t + 2$ are determined at t . We first take the difference between (1.21) and the expectation of this equation at $t - 2$, and use (1.17) and (1.35) to obtain

$$(\hat{X}_t - \beta E_{t-1} \hat{X}_{t+1}) - E_{t-2}(\hat{X}_t - \beta \hat{X}_{t+1}) = \kappa[(\hat{G}_t - \hat{Y}_t^S) - E_{t-2}(\hat{G}_t - \hat{Y}_t^S)] - \frac{\kappa}{\omega + \sigma} \phi_{t-1}.$$

Using this expression to substitute for ϕ_{t-1} in (1.21), we obtain

$$\hat{Y}_t = \hat{Y}_t^S + \kappa^{-1} E_{t-2}(\hat{X}_t - \beta \hat{X}_{t+1}) + [(\hat{G}_t - \hat{Y}_t^S) - E_{t-2}(\hat{G}_t - \hat{Y}_t^S)]. \quad (1.36)$$

We now rewrite (1.17) using (1.36) to substitute for \hat{Y}_t and the expression just above to substitute for ϕ_{t-1} . This yields

$$E_t \hat{R}_{t+1} = E_t \hat{X}_{t+2} + \hat{\rho}_t + \frac{\sigma}{\kappa} E_t [(\hat{X}_{t+2} - \beta \hat{X}_{t+3}) - (\hat{X}_{t+1} - \beta \hat{X}_{t+2})] - \frac{\omega}{\kappa} [E_t(\hat{X}_{t+1} - \beta \hat{X}_{t+2}) - E_{t-1}(\hat{X}_{t+1} - \beta \hat{X}_{t+2})] \quad (1.37)$$

where we have used the fact that (1.20) implies that $E_{t-2}\pi_t = E_{t-2}\hat{X}_t$, and where

$$\hat{\rho}_t \equiv \omega[(\hat{G}_{t+1} - \hat{Y}_{t+1}^S) - E_{t-1}(\hat{G}_{t+1} - \hat{Y}_{t+1}^S)] - \sigma[E_t(\hat{G}_{t+2} - \hat{Y}_{t+2}^S) - (\hat{G}_{t+1} - \hat{Y}_{t+1}^S)]. \quad (1.38)$$

Note that $\hat{\rho}_t$ is an exogenous stochastic process, that can be expressed as a function of the history of the shocks \bar{e}_{it} .

Equation (1.37) represents the only restriction implied by our model on the behavior of \hat{R}_t given the evolution of \hat{X}_t . For any given process for \hat{X}_t , the variance of \hat{R}_t is obviously minimized by setting \hat{R}_{t+1} equal to the right-hand side of (1.37). In the case where one wishes to stabilize prices completely, this means that \hat{R}_{t+1} is given by $\hat{\rho}_t$, as discussed in Rotemberg and Woodford (1997). This means that the interest rate at $t + 1$ must rise whenever $(\hat{G}_{t+1} - \hat{Y}_{t+1}^S)$ increases unexpectedly at t . If, instead, upwards revisions in $(\hat{G}_{t+1} - \hat{Y}_{t+1}^S)$ are matched by upwards revisions in \hat{X}_{t+1} , \hat{R}_{t+1} need not rise as much. In other words, if inflation is allowed to respond to these shocks, the interest rate does not have to respond as much to them.

We propose a simple representation of the quantitative connection between average inflation and the variability of interest rates as in Rotemberg and Woodford (1997). In particular, we suppose that, along any equilibrium path, the lowest possible value of r^* (and π^*) consistent with a given degree of interest-rate variability is given by

$$r^* = \rho + \pi^* = k\sigma(\hat{R}), \quad (1.39)$$

where $\sigma(\hat{R})$ refers to the standard deviation of the unconditional distribution for \hat{R}_t in the stationary equilibrium associated with a given policy rule. We let the factor k equal 2.26, which is the ratio of the mean funds rate to its standard deviation under the historical regime

so that, in effect, we are assuming that this is the minimum possible value for this ratio.²² For any monetary policy rule we consider, we thus compute the variance of the nominal funds rate, and then use (1.39) to determine the associated value of π^* . We then compare policy rules according to how low a value they imply for the overall deadweight loss measure $L + \pi^{*2}$.²³

While minimizing the welfare losses of the agents in the economy is a rather obvious objective for policy, it is worth looking more generally at the effect of different monetary policy rules on the variances of output, inflation, and interest rates. This analysis has several benefits. First, it provides intuition for our results concerning the effects of different rules on $L + \pi^{*2}$. Second, because this analysis is not as dependent on the subset of parameters that we calibrate, it remains valid even if some of our calibrations are inappropriate.

Finally, the model may be incorrect in ways that maintain the validity of our estimates of the structural parameters but vitiate our welfare analysis. We do not know the precise range of variations on the model for which this would be true. One simple example would be if there are changes over time in the elasticity of substitution of different goods for each other. This would imply that the Dixit-Stiglitz aggregator varies over time. The resulting changes in the elasticity of demand faced by each firm would lead firms to desire changes in the ratio of price to marginal cost. As far as the algebra of the model is concerned, such changes in the desired markup have the same effect as changes in Y_t^S . The difference is that, under this alternative interpretation, it is no longer socially desirable for output to track the time variation in Y_t^S . In particular, variation in desired markups would justify an objective of reducing the variance of output relative to trend more than is implied by our minimization of $L + \pi^{*2}$ below. For this reason, as well as for comparability of our results with those of other studies, we look at a relatively wide range of consequences of the monetary rules we study.

2 Consequences of Simple Policy Rules

As noted earlier, we wish to compare a variety of types of monetary policy rules that make the interest rate r_t depend on the history of output, inflation and the interest rate itself. In this section, we explore the effects of varying the parameter in some very simple rules of this kind. These simple rules, which are variants of the rule proposed by Taylor (1993), have some practical advantages. Their simplicity makes them easy to understand so that a central bank that adopted them ought to find it easy to explain what it is doing. As a result, the public ought to find it easy to monitor the central bank's compliance with its rule. Finally, the use of similar rules in the other papers in this volume makes our results concerning the desirability of these rules directly comparable to theirs.

When we study rules that can be described by only a small number of parameters, we study the consequences of parameter variation for two sorts of issues. First we analyze the range of parameter which ensure that a determinate rational expectations equilibrium exists; as an extensive prior literature has stressed, determinacy of equilibrium cannot be taken for granted in rational expectations models, especially in the case of a monetary policy defined by an interest-rate rule. (See, e.g., Bernanke and Woodford, 1997, for general discussion of this issue, and illustrations in the context of a model similar to the one that we use here.) Next we study the effect of parameter variation within the range of parameter values for which equilibrium is determinate.

2.1 Performance Measures for Alternative Rules

For each of the rules we consider, we compute a number of statistics relating to the variability of inflation, output and interest rates in the unique stationary rational expectations equilibrium associated with that rule. These statistics are reported in Table 1 for a number of rules of particular interest. The significance of the parameters a , b and c that define these rules is explained below.²⁴

Among the specific rules included in the table are several that are also considered in

other papers in this volume. These are labeled $A_i - D_i$, with i equal to 0 in the case of rules where the interest rate responds to contemporaneous output and inflation, while i equals 1 in the case where it responds with a lag. The table also reports the effects of setting the parameters at the values that represent the best rule (in the sense of minimization of our utility-based loss measure $L + \pi^{*2}$) within each of several families of simple rules discussed below (these are labeled $E_0 - G_0$, and $E_1 - G_1$). Finally, we also report the statistics associated with our estimate of actual U.S. policy during the period 1979-1995 (rule H), and for the unconstrained optimal policy according to our model, discussed in section 3 (rule I).

The statistics reported in Table 1 include the variance of output around trend, the variance of inflation and the variance of the Federal funds rate. In addition to these conventional statistics, we also report the variance of quarterly innovations in the rational forecast of the long-run price level. This is the variance of changes in the variable

$$p_t^\infty \equiv E_t \lim_{T \rightarrow \infty} [\log P_T - T\pi^*],$$

which is just the stochastic trend in the price level in the sense of Beveridge and Nelson (1982). (Note that it follows from this definition that the first difference of p^∞ is also the innovation in this variable.) We include this statistic as an alternative index of the degree of price stability associated with different equilibria. The advantage of this statistic is that it reflects the extent to which agents make capital gains and losses on long term nominal contracts and some analysts have expressed concern over these (e.g., Hall and Mankiw (1994)). Finally, we also report the coefficient β_∞ of a regression of the innovation at t in the forecast of the long-run price level p^∞ on the quarter t innovation in the (log) price level at $t + 1$. (Recall that according to our model, the price level P_{t+1} is determined at date t .) This coefficient tells us whether inflation innovations in quarter t eventually lead to a higher price level or whether instantaneous increases in the price level are later offset by subsequent expected reductions in prices. In the case of a random walk in the log price level, we should find $\beta_\infty = 1$, while if temporary price-level increases are eventually completely offset, we should find $\beta_\infty = 0$.

The first column of Table 1 serves as a key for Figures 1, 2 and 3, where the consequences of these rules for the variability of output, inflation, interest rates and long-run price-level forecasts are plotted. The first of these figures has a certain similarity to the policy frontier shown in Taylor (1979), in that rules that have smaller standard deviations of inflation tend to involve larger standard deviations of output and vice versa. The only rules that appear to be “dominated” in this plot are the rules with labels in the series C_i and D_i . These are simple “Taylor Rules” that make the funds rate a function only of current inflation and output, and they respond much more strongly to output fluctuations than does our optimal rule in that family (labeled F_0). The rules in families C_i and D_i are worse than the B_i rules because they induce a higher standard deviation of inflation without reducing the standard deviation of output. Interestingly, the rule F_0 , which is the best rule of this type in terms of minimizing our utility-based loss measure, is something of an outlier as well in that it involves more variability of both inflation and output relative to other rules in the set. From the point of view solely of the criteria plotted in this figure, historical policy seems to be slightly worse than the rules described by B_i , but not significantly so.

Figure 2 paints a different picture, one that involves pure dominance relations and no trade-offs. Once again, the rules C_i and D_i are particularly bad, in that they now also involve a high standard deviation of the funds rate. Among the remaining rules, those with a lower standard deviation of inflation tend to have lower standard deviations of the funds rate so they allow average inflation to be lower as well. Thus, the best rules in this plot are the rules E_i which, as we shall see below, also minimize $L + \pi^{*2}$ among rules that are as simple as these. These involve both low standard deviations of inflation and interest rates, while the other rules perform worse on both dimensions. When coupled with the results of Figure 1, we see that – leaving aside C_i and D_i – the rules we consider here have the property that those that reduce the standard deviation of output tend to raise the standard deviation of inflation and interest rates simultaneously.

Figure 3 shows the implications of these rules for the variance of inflation and the variance in the innovation of the forecast of the long-run price-level. We see in this Figure that the

specific rules we consider rank equally along these two dimensions. The price-level rules G_i and the E_i rules have both the lowest variance of inflation and the smallest innovations in the long run price level. That the price-level rules have low variances in the long-run price level is not surprising, since they ensure the price level is stationary. What is perhaps more surprising is that the best of the rules that respond to deviations of the inflation rate from target have this property as well.

The regression coefficients β_∞ of the innovation in the long-run price level on the current price level innovation reported in Table 1 help to explain this finding. This coefficient is obviously zero for the price-level rules, since these equilibria involve no change in the forecast of the long-run price level at any time. For the E_i rules as well as for the rule marked I , which is the rule that minimizes $L + \pi^{*2}$ among all possible rules, this coefficient is actually smaller than -1. This means that increases in the contemporaneous price level eventually lead to a lower price level, and indeed, to a lower price level by an amount that is even greater than the size of the initial price-level innovation (but with an opposite sign). Thus, while the long-run price level is not being stabilized, expected reductions in future inflation more than offset the initial increase in the price level. This stands in sharp contrast to the other rules reported in the table. For these rules, this coefficient exceeds one so that increases in the current price level lead to even larger increases in the long-run price level. This means that, on average, increases in inflation are followed by further inflation. This clearly destabilizes the long-run price level. In addition, because expected future inflation leads price setters who can change their prices at t to raise their prices by more, it also means that inflation at t is increased by policies that follow inflation at t with further inflation. For this reason, policies with high values of β_∞ have both variable inflation and large variances in the innovation of the long run price level.

The remaining columns of Table 1 report statistics that measure various components of the utility-based measure of deadweight loss derived in the previous section. The columns labeled $\text{var}(\pi)$, $\text{var}(\pi - E\pi)$ and $\text{var}\{E(Y - Y^S)\}$ report the values of the three unconditional variances that receive positive weights in expression (1.33) for the loss measure L . The third

column from the right then reports the implied value for L . This is our summary measure of the deadweight losses due to variability of inflation and output, in units of the variance of inflation. We scale inflation so that $\pi = 1$ corresponds to a 1% inflation per year. Hence, $L = 1$ indicates the same degree of deadweight loss as results from this inflation rate. The next-to-last column reports the minimum value of π^* consistent with the degree of funds rate variability required by the policy rule, using (1.39) to derive this. Finally, the last column reports the implied value of $L + \pi^{*2}$, our total measure of deadweight loss.

One interesting fact about the table is that the ranking of alternative rules according to their implications for the variability of $\hat{Y} - \hat{Y}^S$ is quite different from their ranking according to their implications for the variability of output relative to its deterministic trend path. The Henderson-McKibbin (1993) rule D_0 , that minimizes $\text{var}(\hat{Y})$ among those considered in the table, implies the *highest* degree of variability of output relative to the natural level \hat{Y}^S . This indicates that responding to deviations of output from a deterministic trend, while perhaps successful as a way of stabilizing output around that trend, may well be counter-productive if one is interested in keeping output close to its natural level. (Compare Figures 6 and 8 below, for further illustration of this point.)

Another fact that is apparent from the table is that the ranking of different rules according to the value achieved for L is essentially the same as their ranking in terms of the variability of inflation. Thus our utility-based welfare criterion $L + \pi^{*2}$ leads to conclusions that are similar to those that would be reached by giving some weight to the reduction of both the variability of inflation and the variability of the funds rate. In both these respects, the rules labeled E_i , G_i , and I are better than the others. We turn now to a more systematic exploration of the consequences of parameter variations, in order to clarify why this is so.

2.2 Simple “Taylor Rules”

We first consider the consequences of varying a and b in simple “Taylor rules” of the form

$$\hat{r}_t = a\hat{\pi}_t + b\hat{Y}_t, \quad (2.1)$$

where once again $\hat{r}_t \equiv r_t - r^*$ and $\hat{\pi}_t \equiv \pi_t - \pi^*$. Note that both the rule C_0 proposed by

Taylor (1993) and the related rule D_0 considered by Henderson and McKibbin (1993) belong to this family. Our aim here is to highlight the trade-offs involved in choice between having interest rates respond to output and having interest rates respond to inflation.

In the case of simple Taylor rules of the form (2.1) with a constrained to be positive, our loss criterion $L + \pi^{*2}$ reaches a minimum when a equals 2.88 and b equals 0.02. The consequences of this rule for our loss measures is displayed in Table 1, where the rule is designated F_0 . As one might guess, this rule (which places essentially all of the weight on inflation variations rather than output variations) allows much greater variations in output relative to trend than do rules C_0 and D_0 . However, according to our model, it leads to *less* variability of output relative to its natural level, which is what matters for our loss measure. It also results in significantly less variability of inflation, and noticeably less variability of the funds rate. (It is actually the latter difference that is most significant for our loss measure, because of the reduction in the average inflation rate π^* that it allows.) The ultimate result is a reduction in deadweight loss by a factor of three, relative to the other proposals. However, our model and our loss measure imply that this rule would not represent an improvement upon historical U.S. policy in the Volcker-Greenspan period. To do better we must not simply vary the weights on inflation and output, but consider at least slightly more sophisticated rules.

Before turning to other families of rules, it is worth noting that the welfare criterion $L + \pi^{*2}$ reaches an even lower value, according to our model, if we allow a and b to be negative in (2.1). The optimum then involves a equal to -1 and b equal to -1.3 . The idea that negative values of a and b are acceptable may be surprising. For this reason, Figure 4 displays both the region where equilibrium is determinate as well as a contour plot of $L + \pi^{*2}$ as we vary a and b . The equilibrium is not unstable for any of these parameter values (*i.e.*, a stationary equilibrium always exists), but equilibrium is indeterminate in the shaded region. Indeterminacy arises, for example, when b is zero and a is small and positive. This indeterminacy implies, among other things, that inflation can vary simply as a result of changes in expectations. A “sunspot” can lead inflation at t to rise, for example. The

real interest rate would then fall (because the nominal interest rate responds little) and the resulting increase in output means that expected future inflation is lower than current inflation. Thus the change in the expected future path of inflation that is required to justify the initial change in inflation is consistent with expected future inflation converging back to the target inflation rate π^* . In this case, a stationary rational expectations equilibrium is possible in which such fluctuations occur simply because they are expected to.

If, instead, a is large and positive, no such equilibrium is possible. Any increase in inflation above its unique saddle-path value is matched by increases in real interest rates which imply that output must fall. This, in turn, implies that expected future inflation rates must be higher than current inflation, given the nature of our AS curve. Thus, inflation must be expected to explode and, since this is not consistent with stationarity, inflation must equal its saddle-path value in the unique stationary equilibrium. Similarly, as mentioned above, the equilibrium is determinate when a and b are both negative.

Figure 4 presents contour lines for the value of our loss measure $L + \pi^{*2}$ in the regions where equilibrium is determinate. Policy F_0 appears as a star on this figure, at the point of a local minimum of the loss measure. However, the region of determinate equilibria with negative a and b also contains a local minimum. This point, which is shown with a star inside a circle, is actually the global minimum value. Nonetheless, we have chosen to present the local minimum F_0 in Table 1, on the ground that restricting attention to values $a > 0$ corresponds to rules that are more similar to the Taylor and Henderson-McKibbin proposals. In addition, once we consider more general families of rules, we do find that the best rules involve tightening monetary policy (*i.e.*, raising the funds rate) in response to inflation increases, as conventional wisdom (at least since the work of Wicksell (1907)) would indicate.

Similar contour plots for other statistics reported in Table 1 provide further insight into why our loss measure varies with a and b as it does. Figure 5 shows the contour plots of the variance of inflation, while Figure 6 shows the contour plots for the variance of $(\hat{Y} - \hat{Y}^S)$. These figures are essentially identical to each other, and they are both similar to the contour

plot for L itself. There is thus no trade-off between stabilizing inflation and stabilizing $(\hat{Y} - \hat{Y}^S)$; the same parameters stabilize both. This follows immediately from our AS curve which relates inflation to departures of \hat{Y} from \hat{Y}^S . For the ranges considered in our figures, a wheel marks the global optimum for the performance criterion being considered. Thus, the figure shows that these variances become as small as possible when a is at its maximum possible value of 20 while b is set to a small negative number. Making a big contributes to stabilization because it ensures that interest rates rise a lot when either \hat{G} rises or \hat{Y}^S falls. This ensures that inflation does not rise much in either case and that, at least after the demand for output adjusts to changes in real rates, output does not rise in the former case while it declines substantially in the latter.

As Figure 7 indicates, the rule that minimizes L by setting a equal to 20 leads to very variable interest rates. This is in part due to the delays in the response of output to interest rates. These delays imply that changes in \hat{G}_t that become known at $t - 1$ inevitably change output at t since C_t is predetermined. This leads firms to raise their prices at t unless long term real interest rates rise unexpectedly. With c equal to zero, this means that prices can only be stabilized if the nominal interest rate at t rises a great deal. The resulting variability of interest rates then requires a high average inflation rate for interest rates never to be negative. This high inflation is so costly, at least relative to the benefits of the additional stabilization that is possible with a high value of a , that the contour plots for the variance of the interest rate are essentially identical to the contour plots for $L + \pi^{*2}$. The point that minimizes the variance of interest rates has a sufficiently stable inflation to be quite desirable as far as total welfare is concerned.

It is interesting to note that the stabilization of output requires a quite different set of parameters. This is demonstrated in Figure 8 which gives the contour plots for the variance of output. This variance is reduced by keeping a small and positive while making b very large. Not surprisingly, output is stabilized if the real interest rate is raised significantly by the central bank whenever output rises while it is lowered when output declines. What is interesting here is that the effect of the policy parameters on the variance of $(\hat{Y} - \hat{Y}^S)$,

which are essentially the same as the effects on L , are very different from the effects on the variance of Y . The reason is that the VAR of Rotemberg and Woodford (1997) identifies large short run fluctuations in \hat{Y}^S . As long as these are treated as variations in the welfare maximizing level of output, setting b large is not desirable and, indeed, stabilization of $(\hat{Y} - \hat{Y}^S)$ requires that b be negative at least when a is 20. Even higher values of a reduce the variance of $(\hat{Y} - \hat{Y}^S)$ still further. Obviously, the result that the stabilization of \hat{Y} relative to \hat{Y}^S requires very different policies from those that stabilize output relative to trend is very sensitive to the assumption that our estimate of \hat{Y}^S is indeed the welfare maximizing level of output. This conclusion would presumably change dramatically if movements in \hat{Y}^S were viewed as resulting from changes in distortions such as changes in desired markups. From an empirical point of view these two interpretations may be difficult to disentangle because we identify \hat{Y}^S by measuring shifts in the empirically estimated aggregate supply equation given by (1.22). Unfortunately, changes in desired markups will shift this equation just as much as changes in technology or other changes in the welfare maximizing level of output.

2.3 Rules that Involve a Lagged Interest-Rate

We achieve improvements in household welfare if we generalize the family of simple Taylor rules to allow the funds rate to respond also to lagged values of itself. We thus consider generalized Taylor rules of the form

$$\hat{r}_t = a\hat{\pi}_t + b\hat{Y}_t + c\hat{r}_{t-1}, \quad (2.2)$$

where we now allow c to be greater than zero. This allows for interest rate smoothing, so that sustained changes in output and inflation lead to only gradual changes in interest rates. Actual policy in the United States and elsewhere seems to involve some degree of interest rate smoothing, though academic commentators have often questioned why this should be so.²⁵ Nor is there any reason to restrict attention to the case $0 \leq c < 1$, though it is only in that case that the policy rule can be described as involving partial adjustment toward a “target” funds rate that depends upon current output and inflation, as assumed for example

in Clarida *et al.* (1997). An alternative is to follow Fuhrer and Moore (1995) and model U.S. interest rates by supposing that c is equal to one, so that it is *changes* in the funds rate, rather than the level of the funds rate, that respond to deviations in inflation and output from their typical levels. Policy proposals of this kind are considered elsewhere in this volume with rules A_0 and B_0 in Table 1 being examples of such rules. We find that policies that involve values of c even greater than one often result in determinate rational expectations equilibria in our model, and so we consider arbitrary positive values of c . In fact, rules with $c > 1$ turn out to possess an important advantage, and this is one of our most important findings.

To gain some insight into the consequences of varying c , we set b equal to zero and discuss contour plots in the $\{a, c\}$ plane for various measures of economic performance. Our motivation for starting with plots that set b equal to zero is that, as we show below, the welfare optimum obtains near this point. Moreover, the resulting family of rules has a very simple interpretation as the family in which interest rates depend only on inflation and lagged interest rates. Figure 9 displays the resulting contour plots for $\text{var}(\hat{\pi})$ which, once again, are essentially identical to those for both the variance of $\hat{Y} - \hat{Y}^S$ and for L itself. One interesting aspect of this figure is that it shows that determinacy obtains with c greater than one even if a is negative so that the Fed reacts perversely to inflation by cutting rates when inflation rises. The reason is that, as in the earlier case with negative values of a , these rules also induce explosions in response to deviations of inflation and output from saddle point paths.

One surprising aspect of the figure is that it shows that “explosive” monetary rules in which c exceeds one do not produce explosive equilibria. In a way, this potential explosiveness of interest rates is effective at keeping the economy on track in this model. It means that, unless the price level reacts properly, the real interest rate falls or increases exponentially. An exponential increase in real rates represents a rather substantial reduction in expected future aggregate demand and thus leads firms to cut prices. The result is that the economy stays on a non-explosive path in which increases in inflation are matched by subsequent reductions in inflation which ensure that the interest rate does not explode. In fact, higher

values of c actually increase the range of values of a for which a determinate equilibrium exists, by helping to solve the problem of indeterminacy discussed above.

The figure also shows that, within the range being considered, the goal of inflation stabilization is furthered by setting a to as large as possible. The variance of inflation reaches its minimum value (over the range of rules shown in the figure) when a equals 20 and c takes a positive value less than one. If the range of the figure were extended, the optimum would involve even higher values of a . Thus, the key to inflation stabilization remains making sure that the interest rate reacts vigorously to inflation.

Interestingly, a higher value of c turns out to be better if one seeks to stabilize the long run price level. This can be seen in Figure 10 which shows that, for any given value of a , the variance of Δp^∞ reaches a minimum of zero for c equal to one. Further insight into this behavior of the variance of Δp^∞ can be obtained from Figure 11 which shows β^∞ as a function of a and c . This figure shows that, when c is zero, β^∞ is greater than one so that initial increases in inflation are followed by further inflation. The reason for this is that an increase in \hat{G}_t raises the price level at t somewhat in spite of the increase in interest rates that takes place at t . But, unless the price level continues rising, interest rates would immediately return back to their steady state level. The result is that, in equilibrium, prices do keep rising because the initial increase in prices means that marginal cost has gone up for the firms which did not raise their price at t . Consequently, increases in the price level at t are followed by further increases in prices which, admittedly, are kept somewhat in check by the fact that the interest rate remains somewhat above the steady state for some time.

If, instead, c is made higher, the interest rate tends to stay high after an increase in \hat{G} even if the price level ceases to rise. This means that firms can be induced not to change their prices in the aftermath of an increase in \hat{G} . The result is that initial increases in prices are followed by smaller increases so that β^∞ is smaller and the variance of Δp^∞ falls. Setting c equal to one as suggested by Fuhrer and Moore (1995) makes β^∞ equal to zero so that the shocks have no effect on the long run price level. Even higher values of c imply that initial increases in inflation are followed by such high real rates that the expected long run price

level is lower than the initial price level so that β^∞ is negative.

For a given initial increase in inflation and interest rates, higher values of c imply that the long run real rate rises more both because future short rates are expected to be higher and because future inflation is expected to be lower. Since unexpected increases in the long term real rate prevent prices from rising this means that, for given a , increases in \hat{G} (and reductions in \hat{Y}^S) lead to smaller immediate price and interest rate increases the higher is c . This is reflected in Figure 12 which shows that, for each a , the interest rate is less variable the higher is c . It also shows that, not surprisingly, the variance of interest rates increases with a .

While we have focused on stabilizing the variability of interest rates because of their implication for average inflation, the Fed also seems to be concerned with stabilizing the *change* in the funds rate from one week or month to the next. This would explain Rudebusch's (1995) finding that changes in the target rate are followed by further changes in the same direction. Figure 13 thus displays the variance of the change in interest rates in the $\{a, c\}$ plane. Interestingly, this figure is nearly identical to the figure for the variance of the interest rate itself. Thus, in our model, stabilization of the short term nominal rate is achieved in the same way as stabilization of the quarterly change in this rate.

As we saw in Figure 9, setting c to a very high value destabilizes the inflation rate. In part this is because sufficiently high values of c imply that increases in inflation at t must be matched by reductions in inflation in the future. These predictable movements in inflation both raise the variance of $\hat{\pi}$ and increase the loss L . For that reason, Figure 14 shows that $L + \pi^{*2}$ reaches its lowest value for a low value of a and a moderate value of c . This minimum is very close to the point which minimizes $L + \pi^{*2}$ within the family (2.2) since this minimum obtains when a , b and c equal 1.22, .06 and 1.28 respectively. This is the rule labeled E_0 in Table 1.

2.4 Rules Using Only Lagged Data

One criticism sometimes leveled (see, e.g., McCallum (1997)) against all rules of the kind considered thus far is that they require the Fed to make use of data about current output and inflation that it does not actually have when it sets the current interest rate. There are two reasons why such variables may simply be unobservable by the central bank. These are that some important economic data is collected retrospectively and that even the data that are collected concurrently need to be processed before their message about the economy as a whole can be distilled. A further difficulty with responding to contemporaneous variables may be that, even if these are observable immediately, the political process of responding to them takes time.

None of this denies that the central bank continually updates its estimate of the current state of the economy. And it should be recalled that our model of the delays in the response of output and inflation implies that the relevant data exist in principle in the quarter *prior* to the one in which the data must be used under rules (2.1) and (2.2). However, it is reasonable to suppose that the central bank's estimate of the state of the economy generally differs from the economy's actual state. In this case, responding to the current estimate of the current state differs from the rules (2.1) and (2.2). If rules of the form (2.1) and (2.2) are applied to the error-ridden current estimates, the interest rate is affected by the measurement error, and a thorough evaluation of these rules would require an analysis of these effects.

Thus we now suppose instead that the Federal Reserve does not respond to output and inflation variations except with a one quarter lag. In this class of rules,

$$\hat{r}_t = a\hat{\pi}_{t-1} + b\hat{Y}_{t-1} + c\hat{r}_{t-1}. \quad (2.3)$$

Considering the effect of such a lag also allows us to compare our results with other papers in this volume since some of these also include the rules we label A_1 through D_1 in Table 1.

Even if the Fed had a reasonably accurate estimate of the current state of the economy, there would be good reasons to be interested in lagged-data rules of this form. In particular, the use of such rules would make Fed operations more transparent to the public at large if

the public only had this lagged information. By avoiding the use of information that the public does not have, it becomes both easier to describe Fed operations and easier for people to detect when the Fed has departed from the rule. An alternative, of course, might be to respond to internal estimates and publish these estimates of the state of the economy as they become available. The study of this alternative, and its effects on transparency given that this estimate will at least sometimes be wrong, is clearly beyond the scope of this paper.

We start in Figure 15 by displaying how the variance of inflation varies with a and b when c is set equal to zero. This Figure is quite different from Figure 5 which involves the same parameters and performance criterion in the case of contemporaneous Taylor rules. Unlike what occurs with rules where the interest rate responds contemporaneously, large values of a and b lead to unstable equilibria in the case where the interest rate responds only to lagged output and inflation. Ignoring b , this can be understood as follows. Inflationary shocks now lead to delayed increases in interest rates which imply delayed reductions in inflation. The rule then requires that subsequent interest rates fall so that inflation rises once again. For a sufficiently strong reaction of interest rates to lagged inflation, *i.e.*, a high value of a , the resulting oscillations are explosive. Thus, the parameters that minimize the variance of $\hat{\pi}$ in the case of a contemporaneous rule no longer do so when the government can only react with a delay. In particular, this minimization now requires that a be equal to about 15.

Figure 16 which gives the contour plot for the variance of $\hat{\pi}$ when b is set to zero while a and c are allowed to vary tells a similar story. Again, high values of a lead to explosive equilibria. By contrast, high values of c with low values of a , do not. Note that high values of c coupled with moderate values of a mean that the eventual reaction of interest rates to increased inflation is extremely large. Nonetheless, these rules are less destabilizing than having the interest rate respond strongly to inflation after a delay of one quarter.

Even in the case of rules that react with a lag, the stabilization of interest rates continues to require high values of c together with small values of a . The result is that Figure 17 shows that $L + \pi^{*2}$ achieves a minimum for a combination of a and c that is quite similar to the combination that was optimal in the case where the interest rate reacted contempo-

aneously. Moreover, the minimum value of $L + \pi^{*2}$ within the family (2.3) is obtained for very similar parameters. In particular, it requires that a , b and c be equal to 1.27, .08 and 1.13 respectively.

This is the rule called E_1 in Table 1. Clearly, these parameters are very similar to those (the rule E_0) that minimize $L + \pi^{*2}$ when contemporaneous data are used. What is more surprising, however, is that Table 1 indicates that the minimized value of $L + \pi^{*2}$ is very similar in the two cases. In other words, this welfare criterion equals 1.10 when the best contemporaneous rule is used while it equals 1.13 when the best of the rules that respond to lagged values is used. Recall that the units of this welfare criterion are squares of percentage *yearly* inflation rates. Thus, the difference in loss is equivalent to the difference between having a completely stable annual inflation rate of 1.06 percent per year and having a completely stable annual inflation rate of 1.05 percent per year. This difference is trivial.

This similarity is not surprising once one recognizes that the optimal contemporaneous rules involves a high value of c . This means that, even in the case of contemporaneous rules, most of the reaction of interest rates to an inflationary shock such as an increase in \hat{G} or a reduction in \hat{Y}^S takes place with a delay. Given this, it is not surprising that the further delay that comes about from responding to inflation and output with a lag has trivial welfare consequences. From an economic perspective, what is important is that delayed responses still allow for substantial revisions in long term real interest rates, and it is these which help stabilize inflation.

2.5 Price-Level Targeting Rules

In this subsection we consider the possibility of making the funds rate respond to deviations of the price *level* from some target path (assumed to be a deterministic trend with growth rate π^*), rather than responding to inflation. In particular, we consider rules of the form

$$\hat{r}_t = a\hat{P}_t + b\hat{Y}_t + c\hat{r}_{t-1}. \quad (2.4)$$

The rule given by (2.4) has the advantage that (if $a \neq 0$) it makes the price level stationary

around the target (deterministic trend) path. Such rules thus reduce $\text{var}(\Delta p^\infty)$ to the maximum possible extent by ensuring this variance is zero. This may be considered a desirable goal of policy; for example, Hall and Mankiw (1994) discuss the advantages of a price-level targeting rule in this regard.²⁶ Such rules also address the desire expressed by the 90 % of the respondents to Shiller's (1996) survey, that any change in the price level be subsequently reversed. We wish to consider whether rules of this kind are also desirable in terms of the other measures of performance that we treat here, or to what degree one might have to sacrifice other goals for the sake of stability of the long-run price level forecast.

Figure 18 displays the contour plots of $L + \pi^{*2}$, once again setting b equal to zero. As the Figure shows, price-level rules tend to be unstable when a is negative and c is large; lower values of c with negative values of a lead to indeterminate equilibria instead. Within the positive orthant, these rules do lead to determinate equilibria, however. In particular, points with positive a and c equal to zero lead to unique determinate equilibria. Since the same is true for rules in the family (2.2) with b equal to zero, c equal to one and a positive, the corresponding equilibria must be the same. To see this, note that, when b is zero, c is one and a is positive, rules in family (2.2) take the form

$$\Delta \hat{r}_t = a \Delta \hat{P}_t. \tag{2.5}$$

Price-level rules in the family (2.4) must also satisfy this equation when b and c are zero since, in this case, (2.5) is just the first difference of (2.4). Thus, if the equilibrium with the first-differenced rule (2.5) is unique, it must be the same as that of the corresponding price level rule. This explains why we found that rules in the family (2.2) with b equal to zero and c equal to one had the dual property that the long run price level was stable and that β^∞ was equal to zero. These rules were in fact equivalent to price-level rules.

However, the optimal price-level rule is not a member of the family (2.2) because the optimal b and c within the class (2.4) are not equal to zero. In particular, the lowest value for $L + \pi^{*2}$ within the family of price level rules (2.4), obtains when a , b and c equal .26, .07 and 1.03 respectively. Because the optimal b is zero, this point is close to the optimum

depicted in Figure 18. Once again, the desire to stabilize interest rates leads to a high value of c , though this parameter has a somewhat different meaning in the context of price level rules than it does in the context of the family (2.2).

Perhaps the most interesting aspect of these price level rules is that even the best such rule is somewhat worse from the perspective of $L + \pi^{*2}$ than the best rule that responds to contemporaneous inflation. Indeed, household welfare is slightly lower than it would be if the central bank followed the best rule that responds only to the lagged levels of inflation and output. The best among the rules that respond to lagged output and the lagged price level is even worse. Admittedly, the resulting differences in our welfare criterion are small but it is worth knowing that price level rules are not particularly attractive in this context.

One could argue that these results do not really say whether it is worth stabilizing the price level, because we are only looking at a very narrow class of rules. To see whether one can obtain some incremental improvement in our criterion function by responding to *both* the price level and the rate of inflation, we analyze hybrid rules of the form

$$\hat{r}_t = a_0 \hat{P}_t + a_1 \hat{P}_{t-1} + b \hat{Y}_t + c \hat{r}_{t-1} \quad (2.6)$$

When we choose parameters a_0 , a_1 , b , and c to minimize $L + \pi^{*2}$, we obtain the values $a_0 = 1.22$, $a_1 = -1.22$, $b = .06$, and $c = 1.28$. Since $a_1 = -a_0$, the optimal member of this family is a member of the more restricted family (2.2) and, in fact, it is once again the rule labeled E_0 in Table 1. There is thus nothing to be gained, from the point of view of our utility-based welfare criterion, by generalizing this family to add a term that ensures that the interest rate reacts to the price level, even though adding even a small term of that kind would serve to stabilize the long-run price level.

The reason is that the best rule within the class (2.2) involves some base drift and this base drift is optimal. Interestingly, this base drift is very different from, and in some ways exactly opposite to, the base drift that people usually worry about. In particular, it is *not* optimal to respond to shocks that temporarily raise inflation by allowing the price level to be higher forever – *i.e.*, to choose a rule that implies $\beta_\infty > 0$. On the contrary, as

discussed earlier, what is optimal is to have such shocks be followed by price declines that are sufficiently large that, eventually, the price level ends up *below* its initial value (when corrected for the average rate of inflation π^*). This is advantageous because the expectation of future price declines, by itself, dampens the initial inflationary effect of increases in \hat{G} and reductions in \hat{Y}^S . It is then possible to obtain the same degree of current price stabilization without having to raise interest rates so much. For this reason, the variability of interest rates is lower in the E_i rules than in the best price-level targeting rules. This additional stability of interest rates is what makes the E_i rules more attractive from the point of view of the loss criterion $L + \pi^{*2}$ as well.

3 Optimal Policy

In this section we consider the best policy rule, from the point of view of minimization of our deadweight loss measure $L + \pi^{*2}$. We start by analyzing not monetary rules *per se* but allocations. In particular, we ask what (conditional) paths of output, inflation and interest rates achieve the lowest value of $L + \pi^{*2}$ while being consistent with our IS and AS curves as well as with the stochastic process for \hat{G}_t and \hat{Y}_t^S given in (1.28) and (1.27). In other words, we compute the optimal response of the whole economy to these structural disturbances.

We then show that this optimal response of the economy is the unique equilibrium that emerges when the interest rate is set according to a rule belonging to the general class (1.23). This means that one cannot do better from the point of view of minimizing $L + \pi^{*2}$ than by using a rule within this class. Moreover, it should be obvious that the member of this class that induces the optimal allocation is also the optimal rule within the class given by (1.23).

3.1 Optimal Responses of the Economy to Real Disturbances

In this subsection we compute the optimal allocation and characterize it as a response of the economy to the innovations in \hat{G}_t and \hat{Y}_t^S . For this purpose we start by constructing a moving average representation of the stochastic process for the real disturbances \hat{G} and \hat{Y}^S . From (1.28) and (1.27) it follows that these variables can be written as functions of the

history of the two i.i.d. shocks in e_t^\dagger . Since these two shocks consist of $e_{2,t}$ and $e_{3,t}$, we can rewrite the stochastic process of the structural disturbances as

$$\hat{G}_{t+1} = \sum_{i=2}^3 \sum_{j=0}^{\infty} \Phi_{Gj}^i e_{i,t-j}, \quad \hat{Y}_{t+1}^S = \sum_{i=1}^2 \sum_{j=0}^{\infty} \Phi_{Sj}^i e_{i,t-j}. \quad (3.1)$$

The exact decomposition of the two shocks in (3.1) is irrelevant for present purposes; each is allowed to affect the evolution of both structural disturbances.

We now consider how the endogenous variables ought to evolve. Because we can write our loss measure in the form (1.34), it suffices to consider the evolution of \hat{X} . It should be obvious from (1.34) that there is no advantage to any random movements in \hat{X} apart from those needed for \hat{X}_t to respond to the shocks that contain information about the evolution of the real disturbances. Thus we may restrict attention to processes \hat{X} which may be written in the form

$$\hat{X}_{t+1} = \sum_{i=1}^2 \sum_{j=0}^{\infty} \Phi_{Xj}^i e_{i,t-j}. \quad (3.2)$$

Substituting this into (1.34), we find that L equals

$$L = \sum_{i=2}^3 \sigma_i^2 \left[\sum_{j=1}^{\infty} (\Phi_{Xj}^i)^2 + \psi (\Phi_{X0}^i)^2 + \frac{\Lambda}{\kappa^2} \sum_{j=1}^{\infty} (\Phi_{Xj}^i - \beta \Phi_{Xj+1}^i)^2 \right], \quad (3.3)$$

where σ_i^2 is the variance of $e_{i,j}$. We seek to obtain parameters Φ_{Xj} that make L as low as possible for a given variance of the funds rate, subject also to any constraints upon the joint evolution of \hat{X} and \hat{R} implied by our structural model.

Using (1.38) and (3.1) we can write $\hat{\rho}_t$ as a function of the lagged e 's. This means that, using (3.2) in (1.37) we obtain an expression for the funds rate as a function of the history of the shocks,

$$\hat{R}_{t+1} = \sum_{i=1}^2 \sum_{j=0}^{\infty} \Phi_{Rj}^i e_{i,t-j}, \quad (3.4)$$

where the coefficients Φ_{Rj}^i can be written as functions of the coefficients Φ_{Gj}^i , Φ_{Sj}^i and Φ_{Xj}^i . This in turn allows us to write

$$\text{var}(\hat{R}) = \sum_{i=1}^2 \sum_{j=0}^{\infty} (\Phi_{Rj}^i)^2 \sigma_i^2. \quad (3.5)$$

The characterization of the optimal process \hat{X} then reduces to the choice of coefficients $\Phi_{X_j}^i$ to minimize the Lagrangian $L + \lambda \text{var}(\hat{R})$, where we substitute (3.3) for L and (3.5) for $\text{var}(\hat{R})$. Here $\lambda \geq 0$ is a multiplier indicating the weight placed on the variance of the funds rate. By minimizing the Lagrangian for different choices of $\lambda \geq 0$, we obtain the family of constrained-optimal equilibria. This family corresponds to the frontier of minimum possible values of L for any given level of $\text{var}(\hat{R})$ (and hence of π^*) that we report in Rotemberg and Woodford (1997).

There exists a particular value of λ^{27} such that the marginal reduction in π^{*2} from raising λ further (using (1.39) to determine the lowest value of π^* consistent with any given value of $\text{var}(\hat{R})$) is of the same size as the resulting increase in L . The constrained-optimal equilibrium associated with this particular value of λ achieves the minimum value of $L + \pi^{*2}$ among all allocations consistent with the structural equations of our model. The variability of inflation, output, the funds rate, and long-run price level growth in this allocation are indicated by point I in Figures 1-3 above, and the row labeled I in Table 1.

Observe that the optimal allocation does not involve complete stabilization of inflation or of the long-run price level. This is not because complete stabilization is impossible in principle, but because complete stabilization would require too great a degree of volatility of the funds rate, and consequently too high an average inflation rate.²⁸ Thus the concern expressed by Summers (1991) – that the desire to maintain a very low average rate of inflation conflicts with the desire to use interest rates as an instrument of stabilization, given the existence of a zero nominal interest rate floor – matters quantitatively in the context of our model. On the other hand, our results imply that it is possible, at least in principle, to stabilize both inflation and the funds rate – and thus, both the average rate of inflation and the variance of inflation – to a greater extent than has been achieved by historical policy. This can be seen from the relative locations of points H and I in Figure 2. Similarly, Table 1 shows that both L and π^* are lower with the optimal policy than with historical policy.

3.2 Implementing the Optimal Allocation

While the optimal allocation is consistent with (3.4), it is important to stress that equation (3.4) does not represent a viable policy proposal, even if the Fed could directly observe the structural disturbances and infer the history of the shocks e_{it} . Such a way of setting interest rates would, instead, result in price-level indeterminacy, because the path of the funds rate would be exogenously specified, with no feedback from the evolution of prices or real activity.²⁹ Thus the construction of a feedback rule for the funds rate that implements the optimal allocation – that is not only consistent with it, but also renders it the unique stationary equilibrium consistent with the proposed policy rule – remains a non-trivial problem. Furthermore, it is of considerable interest to ask how policy should make use of the information revealed by the evolution of inflation and output, as in the various variants of the Taylor rule discussed in section 2. Thus we are especially interested in finding a rule of the form

$$C(L)\hat{r}_t = A(L)\hat{\pi}_t + B(L)\hat{Y}_t, \quad (3.6)$$

where $A(L), B(L), C(L)$ are finite-order lag polynomials, that implements the optimal allocation.

To do this, we first consider whether any rule of this form is consistent with the stochastic processes for interest rates, inflation and output that characterize this allocation. Substituting (3.2) into (1.20) and (1.36), we can write $\hat{\pi}_t$ and \hat{Y}_t as moving averages of $e_{2,t}$ and $e_{3,t}$. These moving average representations for the optimal evolution of inflation and output can be written compactly as

$$\hat{Z}_t \equiv \begin{bmatrix} \hat{\pi}_t \\ \hat{Y}_t \end{bmatrix} = \Phi_Z(L)e_{t-1} \quad (3.7)$$

where

$$e_t \equiv \begin{bmatrix} e_{2,t} \\ e_{3,t} \end{bmatrix}.$$

Similarly writing (3.4) as $\hat{R}_t = \Phi_R(L)e_{t-1}$, it would then seem natural to attempt to obtain a representation of the form

$$\hat{R}_t = \theta(L)\hat{Z}_t \quad (3.8)$$

by writing $\theta(L) \equiv \Phi_R(L)\Phi_Z^{-1}(L)$. Unfortunately, $\Phi_Z(L)$ does not prove to be invertible, since the polynomial $|\Phi_Z(z)|$ has a root inside the unit circle.³⁰ This root is $1/c$, where c is approximately 1.3267. We can, however, write $\Phi_Z(L) = (1 - cL)D(L)$, where $D(L)$ is invertible so that $(1 - cL)e_{t-1}$ is equal to $D(L)^{-1}\hat{Z}_t$. This means that

$$(1 - cL)\hat{R}_t = (1 - cL)\Phi_R(L)e_{t-1} = \tilde{\theta}(L)\hat{Z}_t. \quad (3.9)$$

where $\tilde{\theta}(L) \equiv \Phi_R(L)D(L)^{-1}$.

This gives us a relation of the form (3.6) between the funds rate, its own past values, and current and past values of inflation and output. The two elements ($i = 1, 2$) of the matrix lag polynomial $\tilde{\theta}(L)$ can be written as

$$\tilde{\theta}_i(L) \equiv \sum_{j=0}^{\infty} \tilde{\theta}_{ij}L^j,$$

where the coefficients $\tilde{\theta}_{ij}$ are square-summable, so that long lags j contribute only a small amount to the overall variation in the right-hand side of (3.9). However, the coefficients $\tilde{\theta}_{ij}$ die out for large j only relatively slowly; they evolve asymptotically according to the difference equation

$$\tilde{\theta}_{ij} = -\tilde{a}\tilde{\theta}_{i,j-1} - \tilde{b}\tilde{\theta}_{i,j-2},$$

where the coefficients \tilde{a} and \tilde{b} are approximately equal to 1.0404 and .9643 respectively.³¹ These values imply that the characteristic equation $z^2 + \tilde{a}z + \tilde{b} = 0$ has a pair of complex roots with modulus approximately equal to .9820. Thus the coefficients $\tilde{\theta}_{ij}$ decline in magnitude only at an average rate of less than 2 percent per quarter; a very long distributed lag is required for an accurate approximation to the exactly optimal rule of the form (3.9). The length of the distributed lag that is needed can be reduced significantly by further quasi-differencing of \hat{R}_t , yielding a rule of the form (3.6), where $A(L) \equiv a_0 + a_1L + a_2L^2 \dots \equiv (1 + \tilde{a}L + \tilde{b}L^2)\tilde{\theta}_1(L)$, $B(L) \equiv b_0 + b_1L + b_2L^2 \dots \equiv (1 + \tilde{a}L + \tilde{b}L^2)\tilde{\theta}_2(L)$ and $C(L) \equiv 1 - c_1L - c_2L^2 \dots \equiv (1 + \tilde{a}L + \tilde{b}L^2)(1 - cL)$. The coefficients in the matrix lag polynomials $A(L)$ and $B(L)$ then become negligible much sooner.

Ignoring the constant, the policy rule that we derive in this fashion can then be written as

$$\begin{aligned}
\hat{r}_t = & .29\hat{r}_{t-1} + .42\hat{r}_{t-2} + 1.28\hat{r}_{t-3} \\
& +.22\hat{Y}_{t-1} - .25\hat{Y}_{t-2} + \dots \\
& +.16\hat{\pi}_t + 1.00\hat{\pi}_{t-1} + 2.45\hat{\pi}_{t-2} - 1.45\hat{\pi}_{t-3} + .74\hat{\pi}_{t-4} \\
& - .08\hat{\pi}_{t-5} + .25\hat{\pi}_{t-6} + .33\hat{\pi}_{t-7} + .23\hat{\pi}_{t-8} + .25\hat{\pi}_{t-9} \\
& +.19\hat{\pi}_{t-10} + .17\hat{\pi}_{t-11} + .13\hat{\pi}_{t-12} + .09\hat{\pi}_{t-13} + .06\hat{\pi}_{t-14} + \dots, \quad (3.10)
\end{aligned}$$

where the omitted terms in \hat{Y}_{t-j} are all of size .01 or smaller (to two decimal places), and the omitted terms in $\hat{\pi}_{t-j}$ are all of size .03 or smaller (to two decimal places).³² Supposing that the monetary policy rule is given by (3.10), we find that our model has a unique stationary rational expectations equilibrium. Furthermore, this unique equilibrium involves responses of output, inflation and interest rates to the real shocks that closely approximate the optimal responses derived in the previous subsection. Thus we conclude that (3.10) does belong to the admissible class of interest-rate feedback rules resulting in a determinate equilibrium; that it represents a good approximation to the optimal rule within the general class of rules of the form (3.6); and that the optimal rule within this class implements the optimal allocation as defined above. Rule (3.10) is accordingly the optimal policy rule, labeled *I* in Table 1 and in Figures 1 – 3.

Several features of this optimal interest-rate feedback rule are worth noting. First, the coefficient on $\hat{\pi}_t$ is a small positive number, which means that the optimal rule calls for some immediate tightening in response to an observation of inflation above the target level. However, most of the tightening prescribed by the rule in response to an inflation rate above target occurs later. This subsequent tightening is reflected both in the series of positive coefficients on lagged inflation deviations $\hat{\pi}_{t-j}$ in (3.10), and in the series of positive coefficients on lagged deviations of the funds rate itself. Even putting aside the consequences of the lagged funds rate terms, the $\hat{\pi}_{t-j}$ terms in (3.10) prescribe a much larger response to lagged inflation than to current inflation; for example, these terms place an average weight

of .7 on the rate of inflation over quarters 1 through 4 prior to the quarter in which the funds rate is being set, or four times the weight that is placed on inflation in the current quarter.

Second, the coefficient on \hat{Y}_t is exactly zero. This means that the optimal response to an innovation in \hat{G}_t that increases output relative to what it would have been forecasted to be a quarter earlier is to keep the interest rate at t unchanged. This does not mean that there is no optimal response to observed variations in output relative to trend; but that the optimal response is a delayed one. Moreover, the interest rate ought to respond more to the *growth* rate of output a quarter earlier, than to the *level* of output.³³

Finally, the lag polynomial $C(L)$ has a root inside the unit circle, equal to the reciprocal of $c = 1.33$. Thus, just as in our optimal generalized Taylor rules, the optimal rule calls not simply for interest-rate smoothing, but for an explosively growing response of the funds rate to deviations of inflation from target. These explosions are avoided only if subsequent deviations with the opposite sign eventually counteract the effects of an initial deviation. If the inflation rate were permanently above its target, interest rates would grow asymptotically as $(1.33)^t$, just as if we chose $c = 1.33$ in the case of the family of simple rules (2.2). This explosive behavior is of course exactly what we concluded was desirable in our previous discussion of simple rules, and indeed the value $c = 1.33$ is not too different from the most desirable value of c in the case of simple rules.

One way of comparing the implications of (3.10) with other candidate interest-rate rules is to plot its implications for the cumulative response of the funds rate to a sustained deviation of either inflation from target, or output from its trend level. This particular way of describing the various feedback rules has the advantage of being independent of the degree of quasi-differentiation that may have been used in the way that the rule is stated; for example, it treats (3.9) and (3.10) as equivalent. The prescribed cumulative responses of the funds rate to sustained one percent deviations in the two variables are displayed in the two panels of Figure 19. Each panel compares the prescribed response of the funds rate under four different rules: our estimate of historical U.S. policy over the period 1979-1995, the rule proposed by Taylor (1993) as a rough description of recent U.S. policy, the optimal rule E_0

within the family (2.2), and our unrestricted optimal rule (3.10). We see that, after two quarters of inflation being above target, the first two rules (which are quite similar to each other in this respect) involve much smaller responses of the interest rate to the inflation deviation than the latter two. Our unrestricted optimal rule is actually less aggressive than the optimal rule of the form (2.2) over the horizon displayed in this panel. Indeed, the initial reaction to inflation is actually smaller in this unrestricted optimum than it is in the case of the simple Taylor rule. This serves to highlight once again the fact that our model recommends postponing the reaction of interest rates while simultaneously increasing the absolute magnitude of these delayed reactions.

The second panel shows the responses to a sustained output deviation. Here the Taylor rule as well as our estimate of actual policy involve much stronger reactions of the interest rate over the first three quarters than are implied by either of the optimal rules. For the unrestricted optimal rule, the reaction remains more muted for the entire six-quarter horizon displayed here. This indicates an important difference between actual policy, at least as either Taylor or we have characterized it, and optimal policy according to our model: our model suggests that interest-rate responses to output above trend should be much weaker, at least in the first few quarters, than they actually are. On the other hand, this does not mean that optimal policy would not involve interest rates eventually being raised. For the optimal policy in the class (2.2), interest rates are actually higher after five quarters of high output than they would be under actual policy or the simple Taylor rule. If one extends the plot a few more quarters, this is also true of the unrestricted optimal policy, and both optimal rules (unlike the two characterizations of actual policy) imply that the funds rate eventually explodes.

A final feature of the optimal rule that is worth pointing out is its implication for long-run price-level stability. We observe that the optimal rule has the form of an inflation-targeting rule, rather than a price-level targeting rule, and indeed it does not imply trend-stationarity of the price level. On the other hand, it *does* imply a tendency for unexpected increases in the price level to be subsequently offset by (forecastable) price level declines. This is indicated

by a coefficient β^∞ which is negative, indicating that unexpected price-level increases are eventually more than completely offset by subsequent price-level declines, as in the case of the optimal simple rules E_0 and E_1 . As a result, optimal policy involves a significant degree of stabilization of the rate of change of long-run price-level forecasts – the standard deviation of Δp^∞ is reduced by a factor of four, relative to our estimate of historical policy.

Finally, it is worth asking to what extent our analysis implies that a simple rule such as E_0 or E_1 can be improved upon by using additional information. We have already observed that, according to our structural model, the history of inflation and output variations alone, if observed with sufficient accuracy and timeliness, provide all of the information needed to implement the optimal equilibrium. Thus a sufficiently flexible rule of the form (3.6) suffices. But, as a practical matter, it is probably even more interesting to observe that our results imply that the unrestricted optimal rule is not too different from, and not too much better than, the optimal rule within a simple family such as (2.2). Ninety nine percent of the nearly fifteen-fold reduction in the size of the deadweight loss $L + \pi^{*2}$ that is achievable by going from actual policy to optimal policy can be obtained by adopting the simple rule E_0 . Furthermore, if E_0 is not considered operational due to its reliance upon measures of the current quarter's inflation and output, the simple rule E_1 , that requires only the previous quarter's data, results in performance that is nearly as good. Thus our analysis supports the view that simple policy rules, variations upon the sort of rule proposed by Taylor (1993), have highly desirable properties both from the point of view of stabilizing inflation, interest rates, and the long-run price level, as well as from the point of view of economic welfare.

4 Conclusions

Our results offer a number of conclusions of importance for the design of a monetary policy rule. All of our conclusions are subject, of course, to the caveat that the seriousness with which they should be taken depends upon one's confidence in the extent to which the specification of our structural model is not grossly incorrect.

Probably our most important conclusion is that a simple interest-rate feedback rule of

the kind proposed by Taylor (1993) can achieve outcomes nearly as good as are achievable in principle by any policy, assuming that the commitment of the monetary authority to the rule can be made sufficiently credible. At least in the context of the simple structural model that we consider, an interest-rate feedback rule that uses only information about the recent behavior of inflation and output does quite well (and only the response to the recent level of inflation matters much for this). Furthermore, performance under the best rule of this kind is not significantly reduced if *lagged* inflation data are used. Thus lags in the availability of accurate measurements of inflation are not necessarily a serious problem for the implementation of such a rule.

It is worth noting in particular that a “backward-looking” rule, in which interest rates respond to measures of inflation that has already occurred, rather than to forecasts (of one sort or another) of future inflation (as in the rules considered by Rudebusch and Svensson (1998) and Batini and Haldane (1998)), do quite well. We show that, at least in our simple model, the theoretically optimal policy has a backward-looking representation, given by (3.10). Perhaps more to the point, even very simple backward-looking rules, such as rules E_0 and E_1 in Table 1, are quite good approximations to optimal policy.

It is interesting to note that we obtain this result despite using a structural model that implies that monetary policy has no effects upon inflation until the following quarter (and the largest effect only after two quarters), and no effects upon real activity until after two quarters. Lags in the effects of a monetary policy change do *not* imply that an effective policy must be “forward-looking”. The crucial insight is that there is no need for *policy* to be “forward-looking” as long as the *private sector* is. A commitment to raise interest rates *later*, after inflation increases, is sufficient to cause an immediate contraction of aggregate demand in response to a shock that is expected to give rise to inflationary pressures. This channel should be effective as long as aggregate demand depends upon expected *future* interest rates (or equivalently, upon *long* rates), and not simply upon current short rates; as long as the monetary authority is understood to be committed to adhere to the contemplated policy rule in the future, and not only at the present time; and private agents have model-

consistent (or “rational”) expectations. Indeed, if, as our model implies, aggregate demand is affected *only* by expectations of future interest rates, and not by unexpected interest-rate variations (either immediately or with a lag), then a credible commitment to systematically respond in the future is the *only* way in which monetary policy can be effective. But when one conceives policy in these terms, there is no need for that commitment about future action to involve a commitment to be “forward-looking” at that future date.

Despite our general support for the type of policy rule proposed by Taylor, our analysis suggests that the best rules differ from the specific rule that he proposes in important respects. Probably the most important difference is our conclusion that short-term interest rates should depend not only upon deviations of inflation from target, but also upon their own past values – ideally, with a coefficient even greater than one. A less radical-sounding version of our proposal would be to make the *change* in the funds rate, rather than the *level* of the funds rate, a function of deviations of inflation from its target value, as is also found to be desirable in the forward-looking models studied by Levin *et al.* (1998). It is interesting to note that in forward-looking models of these kinds, such dependence, even with a coefficient greater than one on the lagged value, does not lead to instrument instability. This result contrasts sharply with the conclusion that one would obtain using a traditional, purely backward-looking macroeconomic model, such as the one considered by Rudebusch and Svensson (1998).

In our analysis, the desirability of such dependence upon the lagged funds rate does not depend upon any assumption that variability in the change in the funds rate from one period to the next is a bad thing in itself. Rather, it represents a way of allowing the central bank to commit itself to raise interest rates later, in response to an increase in inflation that is not offset by a subsequent (and sufficiently prompt) inflation decline, without having to have much of the *eventual* interest rate response occur immediately. Assuming that the private sector understands this commitment and is forward-looking in its behavior, this allows the central bank to have a large effect upon aggregate demand without having (in equilibrium) to move interest rates very much. This in turn is desirable if one wishes to maintain a low

volatility of interest rates. We argue that a low volatility of the funds rate is in fact desirable as it allows a given degree of inflation stabilization to be consistent with a lower *average* rate of inflation, due to the zero floor for the nominal funds rate.

Our results here plainly depend upon the assumption not only that the private sector is forward-looking, but that private agents fully understand and believe in the central bank's policy rule. One might wonder whether such an analysis gives a correct account of the consequences of adopting such a rule, especially in the short run, given that it would represent a significant departure from present policy (according to our estimates). Nonetheless, our analysis shows that the possibility of achieving a significant degree of stabilization without a great deal of interest rate volatility through this channel is an important advantage of a high degree of credibility for the central bank's commitment to a monetary policy rule. This helps to clarify why the design of arrangements under which such a rule could be credible could have significant benefits.

Another respect in which our conclusions differ from Taylor's proposal is that we find there to be little gain from making interest rates depend upon the current level of economic activity. We find that optimal rules within our simple families involve a small positive response to the level of detrended output, but it is much more modest than the sort of response suggested by Taylor, or indicated by our estimate of actual U.S. policy. The reason it is undesirable to respond to output deviations, in our model, is that deviations of output from trend have so little to do with deviations of output from *potential* (which, according to our estimates, is quite volatile). It is possible that an alternative interpretation of the residuals in our aggregate supply equation, under which they would not all represent variations in the *efficient* level of output, would increase the role for responses to output variations in an optimal rule. Alternatively, it is possible that if we considered other real variables (such as employment) along with variations in detrended output, we would be able to construct a better proxy for deviations of output from potential (as proposed, for example, by McCallum and Nelson (1998)), to which it would be desirable for interest rates to respond.

Finally, our results shed light upon the debate about the relative advantages of price-level

targeting and inflation targeting. We find that under a desirable policy, the central bank should consistently act to subsequently reverse any movements of inflation above its target level, rather than simply preventing further price increases without undoing the ones that have already occurred. Nonetheless, according to our analysis, there is no special significance to the goal of returning the price level to a *deterministic* target path. Our optimal policy rules actually imply that an unexpected increase in inflation should *decrease* the expected long-run price level. Such an outcome is obtained by a policy that involves no reference to a target price-level path. It follows simply from the dependence of the funds rate upon the lagged funds rate, mentioned above, which has the consequence that, in equilibrium, inflation increases must be followed by subsequent, and even greater, inflation declines, in order to avoid causing the funds rate to grow explosively.

5 Appendix: Derivation of the Utility-Based Loss Function

Here we present further details of the derivation of equations (1.30), (1.31), (1.33), and (1.34), which describe our utility-based loss function $L + \pi^{*2}$. We begin with the derivation of (1.30) as a second-order Taylor series approximation to (1.29). Note that our objective function is of the form $W \equiv E[w_t]$, where w_t is the average utility flow (integrating over the continuum of households) each period. This utility flow may be written as a function solely of the pattern of real activity $\{y_t(z)\}$ within a period, and the exogenous shocks:

$$w_t = u(Y_t - G_t; \xi_t) - \int_0^1 v(y_t(z); \xi_t) dz. \quad (5.1)$$

We begin by considering a Taylor series expansion for each of the two terms in this expression, expanding around the levels of output $y_t(z) = \bar{Y}$ for each z , and the values $G_t = \bar{G}$, $\xi_t = 0$ for the exogenous shocks. Here \bar{Y} represents the level of output in an *optimal* steady state; it represents the constant equilibrium level of output in an equilibrium with no variation in the values of G_t and ξ_t around their steady-state values, a constant price level, and a tax rate $\tau = \tau^* \equiv -(\theta - 1)^{-1}$ that perfectly offsets the distortion resulting from firms' monopoly power. (As we shall see, our loss function takes an especially simple form in this case, and we wish to direct attention to the terms in it that survive even under these ideal circumstances. We leave for further work the analysis of how the welfare effects of monetary policy change when one considers possible interactions between monetary policy and distortions other than the one resulting from sluggish nominal price adjustment.) The steady-state value \bar{G} is chosen to equal $E[G_t]$, and the shocks ξ_t are normalized so that $E[\xi_t] = 0$; thus the steady-state values of the exogenous variables equal their unconditional means.

A second-order Taylor series expansion for the first term on the right-hand side of (5.1) is given by

$$u = u(\bar{C}; 0) + u_C \cdot (C_t - \bar{C}) + u_\xi \cdot \xi_t$$

$$+\frac{1}{2}u_{CC}(C_t - \bar{C})^2 + u_{C\xi} \cdot (C_t - \bar{C})\xi_t + \frac{1}{2}u_{\xi\xi}\xi_t^2 + \mathcal{O}(\|\xi\|^3) \quad (5.2)$$

$$= u(\bar{C}; 0) + u_C \bar{Y} \cdot (\hat{Y}_t + \frac{1}{2}\hat{Y}_t^2 - \tilde{G}_t) + u_\xi \cdot \xi_t \\ + \frac{1}{2}u_{CC}\bar{Y}^2 \cdot (\hat{Y}_t - \tilde{G}_t)^2 + u_{C\xi}\bar{Y} \cdot (\hat{Y}_t - \tilde{G}_t)\xi_t + \frac{1}{2}u_{\xi\xi}\xi_t^2 + \mathcal{O}(\|\xi\|^3) \quad (5.3)$$

$$= u_C \bar{Y} \cdot \hat{Y}_t + \frac{1}{2}[u_C \bar{Y} + u_{CC}\bar{Y}^2] \cdot \hat{Y}_t^2 \\ - u_{CC}\hat{Y}_t^2 \cdot [\tilde{G}_t + s_C \bar{C}_t]\hat{Y}_t + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3) \quad (5.4)$$

$$= u_C \bar{Y} \cdot \hat{Y}_t + \frac{1}{2}[u_C \bar{Y} + u_{CC}\bar{Y}^2] \cdot \hat{Y}_t^2 \\ - u_{CC}\hat{Y}_t^2 \cdot \hat{G}_t \hat{Y}_t + \text{t.i.p.} + \text{unf.} + \mathcal{O}(\|\xi\|^3). \quad (5.5)$$

In (5.2), we simply expand in terms of the index of aggregate consumption C_t , where $\bar{C} \equiv \bar{Y} - \bar{G}$, and each of the partial derivatives is evaluated at the steady-state values $(\bar{C}; 0)$. Here the term $\mathcal{O}(\|\xi\|^3)$ indicates that we neglect terms that are of third or higher order in the deviations of the various variables from their steady-state values. In the case of a monetary policy rule that implies $\pi^* = 0$ and a tax rate $\tau = \tau^*$, the variables will deviate from these values in an equilibrium only because of fluctuations in the shocks G_t and ξ_t around their steady-state values. In this case, the omitted terms are all of third or higher order in the size of the exogenous shocks (and we use $\|\xi\|$ to indicate the a measure of the size of these shocks, where the size of fluctuations in G_t is intended to be included). More generally, the omitted terms also include terms that are of third or higher order in deviations of π^* from the value zero and of τ from the value τ^* ; but we shall (for now) retain terms that are of first or second order in perturbations of those assumptions about long-run aspects of policy. In (5.3), we rewrite the expressions in terms of $\hat{Y}_t \equiv \log(Y_t/\bar{Y})$ and $\tilde{G}_t \equiv (G_t - \bar{G})/\bar{Y}$, using the Taylor expansion

$$Y_t = \bar{Y} \cdot [1 + \hat{Y}_t + \frac{1}{2}\hat{Y}_t^2] + \mathcal{O}(\|\xi\|^3).$$

In (5.4), we suppress the terms that are independent of policy (because they involve only constants and exogenous disturbances), denoted “t.i.p.” as in the text, and make use of the definition $u_{C\xi} \cdot \xi_t = -u_{CC}\bar{C}\bar{C}_t$ to obtain a scalar representation of the disturbance to the

marginal utility of consumption. Finally, in (5.5), we recall the notation

$$\hat{G}_t \equiv \tilde{G}_t + s_C E_{t-2} \bar{C}_t = \tilde{G}_t + s_C \bar{C}_t + \text{unf.},$$

where “unf.” stands for an unforecastable term (i.e., a term x_t with the property that $E_{t-2} x_t = 0$). Unforecastable terms may be neglected because we are ultimately interested only in the unconditional expectation of each of the terms in (5.5).

Similarly, a second-order Taylor series expansion of household z 's disutility of working is given by

$$\begin{aligned} v &= v(\bar{Y}; 0) + v_y \cdot (y_t(z) - \bar{Y}) + v_\xi \cdot \xi_t \\ &\quad + \frac{1}{2} v_{yy} \cdot (y_t(z) - \bar{Y})^2 + v_{y\xi} \cdot (y_t(z) - \bar{Y}) \xi_t + \frac{1}{2} v_{\xi\xi} \xi_t^2 + \mathcal{O}(\|\xi\|^3) \\ &= v_y \bar{Y} \cdot \hat{y}_t(z) + \frac{1}{2} [v_y \bar{Y} + v_{yy} \bar{Y}^2] \cdot \hat{y}_t(z)^2 - v_{yy} \bar{Y}^2 \cdot \hat{y}_t(z) \bar{Y}_t + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3), \end{aligned} \quad (5.6)$$

where now $\hat{y}_t(z) \equiv \log(y_t(z)/\bar{Y})$, and \bar{Y}_t , defined by the relation $v_{y\xi} \xi_t = -v_{yy} \bar{Y} \bar{Y}_t$, provides a scalar measure of disturbances to the marginal disutility of supply. Integrating (5.6) over z we obtain

$$\begin{aligned} \int_0^1 v(y_t(z); \xi_t) dz &= v_y \bar{Y} \cdot E_z \hat{y}_t(z) + \frac{1}{2} [v_y \bar{Y} + v_{yy} \bar{Y}^2] \cdot [E_z \hat{y}_t(z)]^2 + \frac{1}{2} [v_y \bar{Y} + v_{yy} \bar{Y}^2] \cdot \text{var}_z \hat{y}_t(z) \\ &\quad - v_{yy} \bar{Y}^2 \cdot E_z \hat{y}_t(z) \bar{Y}_t + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3). \end{aligned} \quad (5.7)$$

Next we wish to express the terms in (5.7) involving the population average $E_z \hat{y}_t(z)$ in terms of the Dixit-Stiglitz output aggregate \hat{Y}_t instead. To do so, we first compute a Taylor series expansion for the right-hand side of the aggregator equation (1.2), obtaining

$$\hat{Y}_t = E_z \hat{y}_t(z) + \frac{1}{2} \left(\frac{\theta - 1}{\theta} \text{var}_z \hat{y}_t(z) + \mathcal{O}(\|\xi\|^3) \right).$$

Solving this equation for $E_z \hat{y}_t(z)$ and substituting into (5.7) yields

$$\begin{aligned} \int_0^1 v(y_t(z); \xi_t) dz &= v_y \bar{Y} \cdot \hat{Y}_t + \frac{1}{2} [v_y \bar{Y} + v_{yy} \bar{Y}^2] \cdot \hat{Y}_t^2 + \frac{1}{2} [\theta^{-1} v_y \bar{Y} + v_{yy} \bar{Y}^2] \cdot \text{var}_z \hat{y}_t(z) \\ &\quad - v_{yy} \bar{Y}^2 \cdot \hat{Y}_t \bar{Y}_t + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3). \end{aligned} \quad (5.8)$$

Substituting (5.5) and (5.8) into (5.1), we obtain

$$\begin{aligned}
w_t &= u_C \bar{Y} \cdot [\hat{Y}_t + \frac{1}{2}(1 - \sigma)\hat{Y}_t^2 + \sigma \hat{G}_t \hat{Y}_t] \\
&\quad - v_y \bar{Y} \cdot [\hat{Y}_t + \frac{1}{2}(1 + \omega)\hat{Y}_t^2 + \frac{1}{2}(\theta^{-1} + \omega)\text{var}_x \hat{y}_t(z)] + \text{t.i.p.} + \text{unf.} + \mathcal{O}(\|\xi\|^3) \\
&= -\frac{1}{2}u_C \hat{Y} \cdot [(\sigma + \omega)\hat{Y}_t^2 - 2(\sigma + \omega)\hat{Y}_t^S \hat{Y}_t + (\theta^{-1} + \omega)\text{var}_z \hat{y}_t(z)] \\
&\quad + \text{t.i.p.} + \text{unf.} + \mathcal{O}(\|\xi\|^3). \tag{5.9}
\end{aligned}$$

Note that in deriving (5.9) from the line above we have (at last) used the assumption that \bar{Y} is the efficient level of output, so that $u_C = v_y$, and the definition

$$\hat{Y}_t^S \equiv (\sigma + \omega)^{-1}[\sigma \hat{G}_t + \omega E_{t-1} \bar{Y}_t] = (\sigma + \omega)^{-1}[\sigma \hat{G}_t + \omega \bar{Y}_t] + \text{unf.}$$

Then taking the unconditional expectation of (5.9), we obtain

$$\begin{aligned}
W &= -\frac{1}{2}u_C \hat{Y} \cdot [(\sigma + \omega)\text{var}\{\hat{Y}_t - \hat{Y}_t^S\} + (\sigma + \omega)[E\{\hat{Y}_t\}]^2 + (\theta^{-1} + \omega)E\{\text{var}_z \hat{y}_t(z)\}] \\
&\quad + \text{t.i.p.} + \mathcal{O}(\|\xi\|^3). \tag{5.10}
\end{aligned}$$

As promised, we have obtained a welfare measure that allows us to compute all second-order or lower terms in W using only a first-order (log-linear) approximation to the equilibrium solution for the pattern of activity $\{y_t(z)\}$, since no terms of order $\mathcal{O}(\|\xi\|^2)$ in the solution for $y_t(z)$ have any effect upon terms of order lower than $\mathcal{O}(\|\xi\|^3)$ in (5.10).³⁴ If we furthermore assume that the tax rate τ (or some other aspect of “long-run” policy) is adjusted so as to guarantee that $E\{\hat{Y}_t\} = 0$ (i.e., $\log Y_t$ equals $\log \bar{Y}$ on average) regardless of the monetary policy rule, then the $[E\{\hat{Y}_t\}]^2$ term in (5.10) can also be suppressed, as this term is also independent of the monetary policy rule. Our decision to assume this results from a belief, as discussed in the text, that monetary policy is not an appropriate instrument with which to seek to affect the long-run average level of economic activity, given the existence of other instruments with which policymakers may more directly seek to offset the distortion resulting from suppliers’ market power. Finally, noting that \hat{Y}_t equals $E_{t-2} \hat{Y}_t$ plus a forecast error term that is both unforecastable and independent of monetary policy, one

can show that

$$\text{var}\{\hat{Y}_t - \hat{Y}_t^S\} = \text{var}\{E_{t-2}(\hat{Y}_t - \hat{Y}_t^S)\} + \text{t.i.p.}$$

Substitution of this into (5.10), along with the stipulation that $E\{\hat{Y}_t\} = 0$ regardless of monetary policy, then yields (1.30).

Some might prefer instead an analysis that would assume a tax rate τ that remained invariant under alternative monetary policy rules. In this case, we would not be able to drop the $[E\{\hat{Y}_t\}]^2$ term in (5.10). However, our model implies that

$$E\{\hat{Y}_t\} = \frac{1-\beta}{\kappa} E\{\hat{X}_t\} + \mathcal{O}(\|\xi\|^2) = \frac{1-\beta}{\kappa} E\{\pi_t\} + \mathcal{O}(\|\xi\|^2),$$

where the first equality follows from taking the unconditional expectation of all terms in (1.21), and the second from taking the unconditional expectation of all terms in (1.20). (Note that in the log-linear approximations to the model equations reported in the paper, we routinely suppress terms of order $\mathcal{O}(\|\xi\|^2)$.) Thus the only difference in the alternative case would be the presence of an additional negative term in π^{*2} in (1.31). This would have no effect upon the definition of the loss from incomplete stabilization L in (1.33), but it would mean that in (1.32) we would have $L + \mu\pi^{*2}$ instead of $L + \pi^{*2}$, for a certain $\mu > 1$, as our overall deadweight loss measure. This would imply that the optimal point on the $L - \pi^*$ frontier (discussed and graphed in Rotemberg and Woodford, 1997) would be slightly different from the one that we assume here, involving a slightly smaller, though still slightly positive, value of π^* . Such a change makes no qualitative difference, however, in the conclusions announced here about the nature of optimal policy.

Next we turn to the derivation of (1.31) from (1.30). As noted in the text, we need to show that the dispersion of levels of production across differentiated goods is a function of the degree of variability of the aggregate price level. We begin by noting that output dispersion follows from price dispersion, since (1.3) implies that

$$E\text{var}_z\{\log y_t(z)\} = \theta^2 E\text{var}_z\{\log p_t(z)\}. \quad (5.11)$$

To relate the cross-sectional variance of prices to the variability over time of the price index P_t , we begin by recalling that in any period t , a fraction α of suppliers charge the

same price as at $t - 1$ (and the distribution of their prices is the same as the distribution of period $t - 1$ prices); a fraction $(1 - \alpha)\gamma$ charge a common new price p_t^1 chosen at $t - 1$, and a fraction $(1 - \alpha)(1 - \gamma)$ charge a common new price p_t^2 chosen at $t - 2$. Then, introducing the notation, $\bar{p}_t \equiv E_z \log p_t(z)$, we obtain

$$\begin{aligned}
\text{var}_z\{\log p_t(z)\} &= \text{var}_z\{\log p_t(z) - \bar{p}_{t-1}\} = E_z\{[\log p_t(z) - \bar{p}_{t-1}]^2\} + (\Delta\bar{p}_t)^2 \\
&= \alpha E_z\{[\log p_{t-1}(z) - \bar{p}_{t-1}]^2\} + (1 - \alpha)\gamma[\log p_t^1 - \bar{p}_{t-1}]^2 \\
&\quad + (1 - \alpha)(1 - \gamma)[\log p_t^2 - \bar{p}_{t-1}]^2 + (\Delta\bar{p}_t)^2 \\
&= \alpha \text{var}_z\{\log p_{t-1}(z)\} + (1 - \alpha)\gamma[\log p_t^1 - \bar{p}_{t-1}]^2 \\
&\quad + (1 - \alpha)(1 - \gamma)[\log p_t^2 - \bar{p}_{t-1}]^2 + (\Delta\bar{p}_t)^2.
\end{aligned} \tag{5.12}$$

Taking the unconditional expectation of both sides of (5.12) then yields

$$\begin{aligned}
E[\text{var}_z\{\log p_t(z)\}] &= \gamma E[(\log p_t^1 - \bar{p}_{t-1})^2] + (1 - \gamma)E[(\log p_t^2 - \bar{p}_{t-1})^2] \\
&\quad + (1 - \alpha)^{-1}E[(\Delta\bar{p}_t)^2].
\end{aligned} \tag{5.13}$$

Similar reasoning as is used in deriving (5.12) also yields

$$\begin{aligned}
\bar{p}_t - \bar{p}_{t-1} &= E_z\{\log p_t(z) - \bar{p}_{t-1}\} \\
&= \alpha E_z\{\log p_{t-1}(z) - \bar{p}_{t-1}\} + (1 - \alpha)\gamma[\log p_t^1 - \bar{p}_{t-1}] \\
&\quad + (1 - \alpha)(1 - \gamma)[\log p_t^2 - \bar{p}_{t-1}] \\
&= (1 - \alpha)\gamma[\log p_t^1 - \bar{p}_{t-1}] + (1 - \alpha)(1 - \gamma)[\log p_t^2 - \bar{p}_{t-1}].
\end{aligned} \tag{5.14}$$

Taking the expectation of (5.14) conditional upon date $t - 2$ information, one obtains

$$E_{t-2}(\bar{p}_t - \bar{p}_{t-1}) = (1 - \alpha)[\log p_t^2 - \bar{p}_{t-1}] + \mathcal{O}(\|\xi\|^2), \tag{5.15}$$

using the fact that $\bar{p}_t^2 = E_{t-2}\bar{p}_t^1 + \mathcal{O}(\|\xi\|^2)$ and that all date $t - 1$ prices are known at $t - 2$. This combined with (5.14) implies that

$$(\bar{p}_t - \bar{p}_{t-1}) - (1 - \gamma)E_{t-2}(\bar{p}_t - \bar{p}_{t-1}) = (1 - \alpha)\gamma[\log p_t^1 - \bar{p}_{t-1}] + \mathcal{O}(\|\xi\|^2). \tag{5.16}$$

Furthermore, given that we are expanding around a steady state with zero inflation, the right hand sides of both (5.15) and (5.16) consist solely of terms of order $\mathcal{O}(\|\xi\|)$. Thus by squaring (5.15) and taking the conditional expectation, we obtain

$$\begin{aligned} E[(\log p_t^2 - \bar{p}_{t-1})^2] &= (1 - \alpha)^{-2} E[(E_{t-2} \Delta \bar{p}_t)^2] + \mathcal{O}(\|\xi\|^3) \\ &= (1 - \alpha)^{-2} \text{var}\{E_{t-2} \Delta \bar{p}_t\} + (1 - \alpha)^{-2} [E \Delta \bar{p}_t]^2 + \mathcal{O}(\|\xi\|^3). \end{aligned}$$

A similar expression for $E[(\log p_t^1 - \bar{p}_{t-1})^2]$ is implied by (5.16). Substituting these expressions into (5.13) then yields

$$\begin{aligned} E[\text{var}_z\{\log p_t(z)\}] &= \frac{\alpha}{(1 - \alpha)^2} \{\text{var}\{E_{t-2} \Delta \bar{p}_t\} + [E \Delta \bar{p}_t]^2\} \\ &\quad + \frac{1 - \gamma(1 - \alpha)}{\gamma(1 - \alpha)^2} \text{var}\{\Delta \bar{p}_t - E_{t-2} \Delta \bar{p}_t\} + \mathcal{O}(\|\xi\|^3). \end{aligned} \quad (5.17)$$

Finally, the definition of the price index (1.4) implies that

$$\bar{p}_t = \log P_t + \mathcal{O}(\|\xi\|^2).$$

Making this substitution in (5.17), we obtain

$$\begin{aligned} E[\text{var}_z\{\log p_t(z)\}] &= \frac{\alpha}{(1 - \alpha)^2} \{\text{var}\{E_{t-2} \pi_t\} + [E \pi_t]^2\} \\ &\quad + \frac{1 - \gamma(1 - \alpha)}{\gamma(1 - \alpha)^2} \text{var}\{\pi_t - E_{t-2} \pi_t\} + \mathcal{O}(\|\xi\|^3). \end{aligned} \quad (5.18)$$

Substitution of (5.11) and (5.18) into (1.30), and using the fact that (as a consequence of our definition of π^*) $E \pi_t = \pi^* + \mathcal{O}(\|\xi\|^2)$, then yields (1.31). This last expression can in turn obviously be written in the form (1.32), where L is defined by (1.33), and

$$\Omega \equiv -\frac{1}{2} u_C \bar{Y} \theta (1 + \theta \omega) \frac{\alpha}{(1 - \alpha)^2}, \quad \Lambda \equiv \frac{(1 - \alpha) \kappa}{(1 - \alpha \beta) \theta}.$$

Finally, we can rewrite L so that it depends only on the stochastic process for the relative price variable \hat{X} . To do this, note first that (1.21) implies that

$$E_{t-2}(\hat{Y}_t - \hat{Y}_t^S) = (1/\kappa) E_{t-2}(\hat{X}_t - \beta \hat{X}_{t+1}). \quad (5.19)$$

At the same time, (1.20) implies that

$$\pi_t - E_{t-2}\pi_t = \psi(\hat{X}_t - E_{t-2}\hat{X}_t), \quad (5.20)$$

so that

$$\text{var}(\pi_t) = \text{var}(E_{t-2}\hat{X}_t) + \psi^2\text{var}(\hat{X}_t - E_{t-2}\hat{X}_t). \quad (5.21)$$

Substituting the expressions in (5.19), (5.20) and (5.21) in the term in square brackets in (1.33), we obtain (1.34).

Footnotes

1. Throughout these derivations, we assume an economy with zero growth for simplicity. More properly, we assume a deterministic trend for real activity, and variables such as Y_t refer to detrended values, that take constant values in the steady state. In our estimation of the model, we use a series for \hat{Y}_t obtained by removing a linear trend from the log of real GDP.
2. Details of this and other aspects of our Taylor series expansions are presented more fully in the Appendix.
3. Except for our introduction of the two-period delay in the determination of interest-sensitive purchases, our derivation of this “expectational IS equation” follows the earlier work of authors such as Koenig (1987), Kerr and King (1996), McCallum and Nelson (1997), and Woodford (1996).
4. This general approach to modeling the dynamics of price adjustment is adopted in a large number of recent quantitative equilibrium business cycle studies, beginning with Yun (1996) and King and Watson (1996).
5. The allowance for non-zero τ is primarily so that we can linearize around a steady state in which the constant level of output is efficient. The convenience of this for our purposes is discussed in the Appendix.
6. Under the assumption that $\tau = -(\theta - 1)^{-1}$, this requires that \bar{Y} satisfy the equation $u_C(\bar{Y} - \bar{G}; 0) = v_y(\bar{Y}; 0)$, which also defines the efficient level of output.
7. The factor $(1 - \alpha)/\alpha$ turns out to be convenient in giving a simpler form to equations such as (1.20) below.
8. Up to the log-linear approximation used in all of our computations of the equilibria associated with alternative policy rules, the steady-state real interest rate is given by $\rho = -\log \beta$, as a consequence of (1.6).
9. We need not assume that the monetary authority actually knows the true value of ρ . The rule (1.23) involves a single constant term $K = [1 - \sum_j c_j]r^* - \sum_j a_j \pi^*$, and it is this that the authority must know in order to implement the rule. However, according to our

model, a given value of K implies (generically) a unique value of π^* (which may or may not be correctly estimated by the authority). We choose to parameterize alternative policy rules in terms of π^* rather than in terms of K because of the simpler interpretation of the latter parameter.

10. In fact, we estimate a VAR model of r_t and π_t that includes constant terms in the equations, and use these constant terms to obtain our econometric estimates of r^* and π^* . The latter estimates then imply our estimated value for the model parameter ρ (and hence β). In the exposition here, we drop the constant terms for simplicity.

11. Note that with these definitions, $\hat{r}_t = \hat{R}_t - \pi^*$. The difference in the definitions follows from the difference in the rate of inflation in the steady state with respect to which deviations are calculated under the two definitions. It is also worth noting that \hat{r}_t bears the same relation to \hat{R}_t as $\hat{\pi}_t$ bears to π_t .

12. Our estimation strategy is discussed in more detail in Appendix 1 of Rotemberg and Woodford (1998).

13. Rotemberg and Woodford (1998) provides more details about both this method of construction and the properties of the constructed series.

14. This compares, for example, with a standard deviation of only 2.1 percent for our detrended output process \hat{Y}_t . The high volatility of the constructed \hat{G}_t process is mainly due to its high serial correlation (serial correlation coefficient of .92), rather than to extraordinary volatility of the \hat{G}_t innovations, which correspond in fact to the \hat{Y}_t innovations in our VAR model. It is possible that the data would be better described by a model in which C_t , \bar{C}_t and G_t are not required to have a common deterministic trend. The volatility of the constructed \hat{Y}_t^S process, instead, is largely due to the presence of a very volatile transitory component. For example, the standard deviation of $E_{t-2}\hat{Y}_t^S$ is only 4.3 percent.

15. It should go without saying that this does not imply that the model is necessarily correct. If our model is incorrectly specified, changes in the monetary policy rule will have effects other than those implied by our analysis. What makes the model preferable to purely backward-looking models is that, as stressed by Lucas (1976), it is highly implausible that

purely backward-looking specifications of IS and AS curves will remain invariant with respect to changes in the monetary rule.

16. For an alternative approach, compare King and Wolman (1998).

17. The rate of inflation matters for the evaluation of (1.29) in such a steady state because it determines the dispersion of relative prices and hence the dispersion of the relative quantities produced of the various goods z .

18. See, e.g., Benabou and Konieczny (1994), King and Wolman (1996) and Feldstein (1997).

19. For example, McCallum and Nelson (1998) criticize the Calvo model of price-setting on the ground that its failure to conform to the “natural rate hypothesis” is unrealistic. Our closely related model has exactly the feature that they criticize.

20. King and Wolman (1998) also argue, on alternative grounds, that optimal policy should involve a steady-state inflation rate of $\pi^* = 0$, despite the fact that a small positive inflation rate can raise steady-state output by lowering average markups, and that (if one assumes $\tau = 0$, as they do) this would raise the steady-state value of the period utility flow $u(C) - v(y)$. Their argument involves calculation of the optimal time-dependent policy (under commitment) to maximize the average level of discounted utility over the infinite horizon. They show that this optimal time-dependent (and time-inconsistent) policy involves a commitment to an inflation rate that converges to zero asymptotically, even though the optimal *stationary* rate of inflation would be positive.

21. Note that the latter measure considers only the welfare costs of steady inflation that result from the relative price distortions that follow from the lack of continuous price adjustment. As noted earlier, we abstract from any effects of steady inflation upon the steady-state level of aggregate output. We also abstract from other welfare costs of inflation, such as the costs of economizing on real money balances, that are emphasized in many discussions of this issue. It seems likely that the effects that we neglect should, if anything, make it even more desirable that average inflation be low. Since many of our results consider the trade-off between stabilization objectives and the objective of a low average rate of inflation, and since our results, when we consider the overall minimization of $L + \pi^{*2}$, recommend a low average

rate of inflation in any event, we do not feel that an attempt to quantify such additional considerations is likely to change our conclusions dramatically.

22. Note that our definitions imply that $\hat{R}_t = r_t - \rho$, so that $\sigma(\hat{R}) = \sigma(r)$. We refer to $\sigma(\hat{R})$ in (1.39) because the structural equations of our model are written in terms of the variable \hat{R}_t , and so we solve for the equilibrium fluctuations in that variable.

23. The advantage of this substitute for the more rigorous approach of imposing the requirement that $R_t \geq 0$ at all times, given estimated shock distributions with bounded supports, is a considerable saving in computational effort. First, imposing a constraint of the form (1.39), our optimization problem continues to be a linear-quadratic one (if we use approximation (1.32) to the objective, and a log-linear approximation to the model structural equations), and as a result the optimal policy is described by a linear rule, which we can obtain using linear methods. Second, under this form of constraint, the optimal policy does not depend upon any more detailed description of the distribution of the exogenous shocks e_t^\dagger than their means and variances. This means that we do not need to estimate more detailed properties of these distributions, and that our conclusions are not dependent upon properties of such distributions that are likely to be very poorly estimated in a sample of our size.

24. Briefly, in each case, a measures the extent to which the funds rate responds to deviations of inflation and/or the price level from its target value, b measures the extent to which the funds rate responds to deviations of output from trend, and c measures the extent to which the funds rate responds to deviations in its own lagged value.

25. See, e.g., Goodfriend (1991), Rudebusch (1995), Goodhart (1996) and Sack (1997).

26. But for a contrary view of the relative desirability of inflation stabilization and price-level stabilization, see, e.g., Gertler (1996).

27. As reported in Rotemberg and Woodford (1997), the value is approximately .2249.

28. As explained in section 1.2 above, complete stabilization of the path of the price level would require that $\hat{R}_t = \hat{r}_{t-1}$ each period. Given our estimated shock processes, this would imply a standard deviation of funds rate variations of 27 percentage points – ten times the funds rate volatility associated with historical policy. (See Table 2 in Rotemberg and

Woodford, 1997.) Using (1.39) to determine the minimum required value for π^* , we conclude that the average inflation rate would have to equal 58 percent per year.

29. The result that equilibrium is indeterminate in this case can be observed from the fact that the point $a = 0, b = 0$ is in the zone of indeterminacy in Figures 4 – 8, or similarly that the point $a = 0, c = 0$ is in the zone of indeterminacy in Figures 9 – 12.

30. We demonstrate this numerically by truncating the infinite lag polynomial $\Phi_Z(L)$ at a finite number of lags, and solving for the roots of $|\Phi_Z(z)|$. In our numerical work, we use the terms for $j = 0$ through 130 in (3.2). We stop at lag 130 because both $\Phi_Z(1)$ as well as our estimate of the root of $|\Phi_Z(z)|$ which lies inside the unit circle are little affected by the addition of further terms.

31. We determined this by inspection of the coefficients $\tilde{\theta}_{ij}$, which can be computed recursively. The coefficients that we compute obey the stated recursion, up to four decimal places of accuracy, for both $i = 1, 2$, for all values of j between 61 and 92. After this, the recursion breaks down, presumably because a small numerical error in our estimate of c introduces a non-trivial error into our computation of $\tilde{\theta}_{ij}$ for larger values of j .

32. For $j = 50$ and above, the terms in $\hat{\pi}_{t-j}$ are all .0001 or smaller, while the same is true of the \hat{Y}_{t-j} terms for $j = 19$ and above. Whether the small non-zero values that we still obtain for large j indicate that further quasi-differencing is needed in order to obtain a rule of the form (3.6) with finite lag polynomials, or are simply due to numerical error, we have not been able to determine.

33. Interestingly, our estimated historical policy rule for the U.S., reported in Rotemberg and Woodford (1997), also implies more response to the growth rate than to the detrended level of real GDP; but the historical rule can be more accurately described as making the funds rate respond to $\hat{Y}_t - \hat{Y}_{t-2}$ rather than to $\hat{Y}_{t-1} - \hat{Y}_{t-2}$.

34. This result depends upon our having linearized around the efficient \bar{Y} , since otherwise our expression for W would contain a term that is linear in $E\{\hat{Y}_t\}$. However, even without this choice, we could have obtained the same result by assuming that tax policy adjusts in response to any change in the monetary policy rule in order to preserve a particular value

for $E\{\hat{Y}_t\}$, where this quantity then becomes one of the terms independent of the monetary policy rule. In fact, we assume that taxes respond to keep output fixed in the work reported here in any event.

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Table 1
Statistics for Several Policy Rules

	a	b	c	Var(R)	Var(Y)	Var(π)	Var(Δp_{∞})	β_{∞}	Var($\pi - E\pi$)	Var(E(Y-Y'))	L	π^*	L + π^{*2}
Contemporaneous-data Taylor rules:													
A ₀	3.00	0.80	1.00	6.24	7.24	0.66	4.00	3.82	0.27	8.77	1.32	2.66	8.38
B ₀	1.20	1.00	1.00	6.41	2.73	1.82	16.05	5.44	0.48	11.69	2.80	2.74	10.29
C ₀	1.50	0.50	0.00	17.14	3.87	7.34	121.14	11.14	0.81	13.86	8.72	6.37	49.29
D ₀	1.50	1.00	0.00	16.26	1.79	6.76	100.77	9.80	0.83	14.63	8.18	6.13	45.73
E ₀	1.22	0.06	1.28	1.88	13.47	0.38	1.47	-1.86	0.19	11.37	1.09	0.11	1.10
F ₀	2.88	0.02	0.00	8.65	15.42	1.04	16.77	6.38	0.37	10.35	1.86	3.66	15.26
Lagged-data Taylor rules:													
A ₁	3.00	0.80	1.00	5.89	10.32	0.66	4.20	3.84	0.28	6.56	1.23	2.50	7.47
B ₁	1.20	1.00	1.00	5.99	3.30	1.83	16.30	5.43	0.49	9.58	2.71	2.54	9.18
C ₁	1.50	0.50	0.00	13.83	4.63	5.97	94.12	10.04	0.78	11.17	7.19	5.42	36.55
D ₁	1.50	1.00	0.00	14.86	3.32	5.85	83.99	9.08	0.81	11.69	7.12	5.73	39.91
E ₁	1.27	0.08	1.28	1.87	13.92	0.37	1.12	-1.35	0.19	12.18	1.12	0.10	1.13
Price-level targeting rules:													
G ₀	0.26	0.07	1.03	2.00	11.14	0.34	0.00	0.00	0.23	11.93	1.11	0.21	1.16
G ₁	0.38	0.10	0.85	2.04	11.35	0.34	0.00	0.00	0.25	12.57	1.15	0.24	1.21
Estimated historical U.S. policy:													
H	--	--	--	7.64	4.79	2.28	26.19	5.60	0.66	12.14	3.43	3.26	14.06
Optimal policy:													
I	--	--	--	1.93	11.30	0.39	1.77	-2.19	0.20	7.57	0.93	0.15	0.95

Figure 1: Selected Rules: The Standard Deviations of Output and Inflation

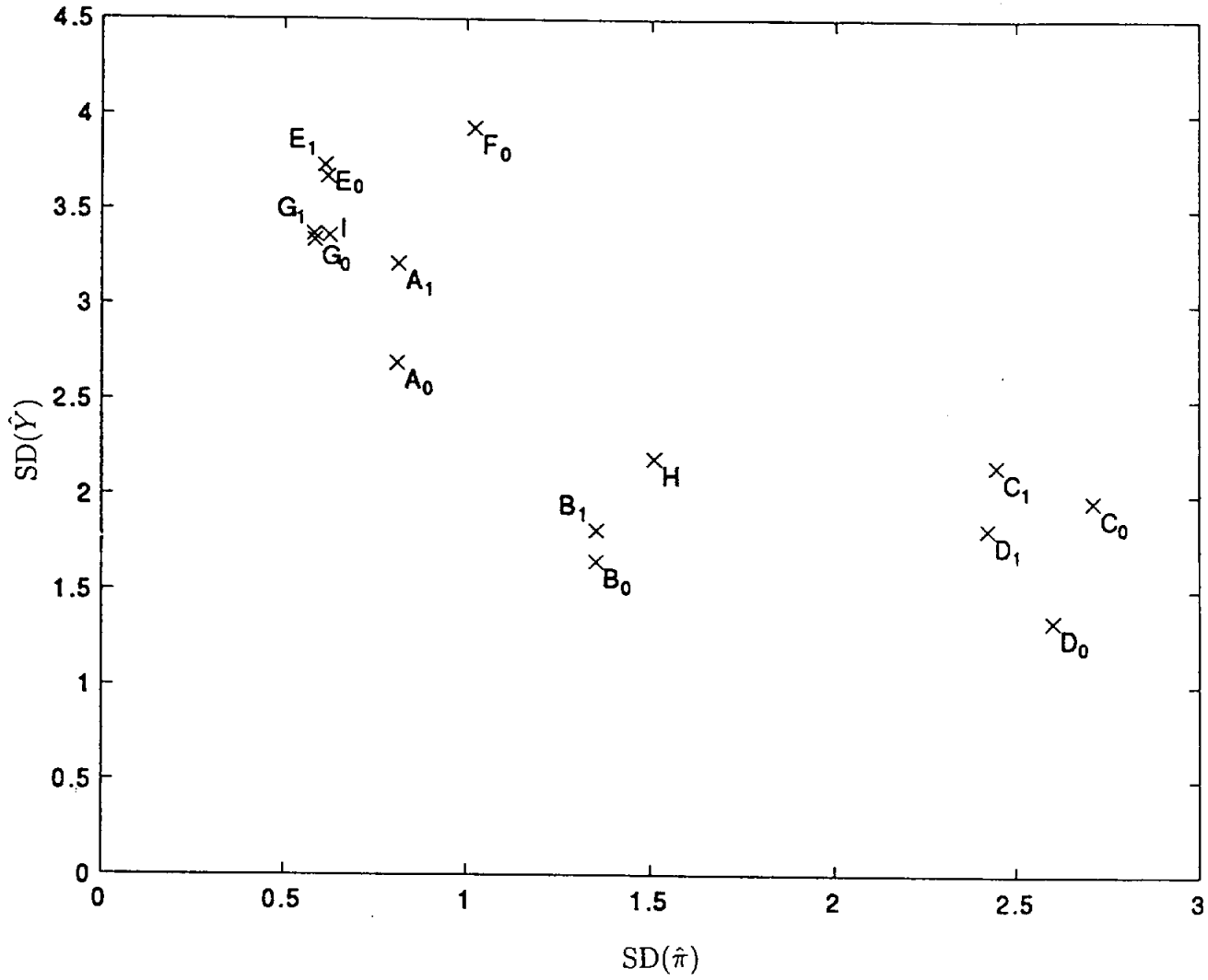


Figure 2: Selected Rules: The Standard Deviations of the Interest Rate and Inflation

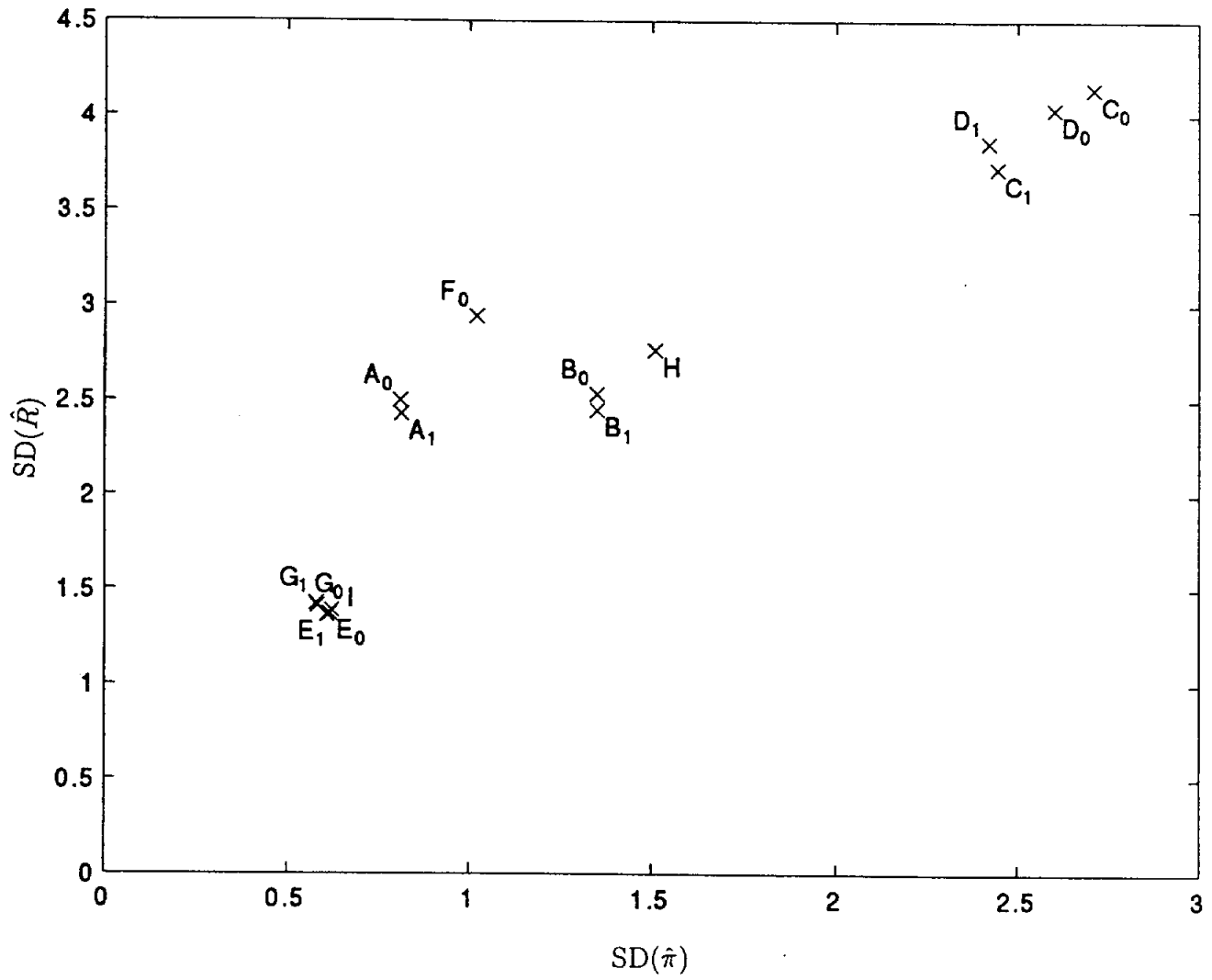


Figure 3: Selected Rules: The Standard Deviations of Inflation and of the Innovation in the Long Run Price Level

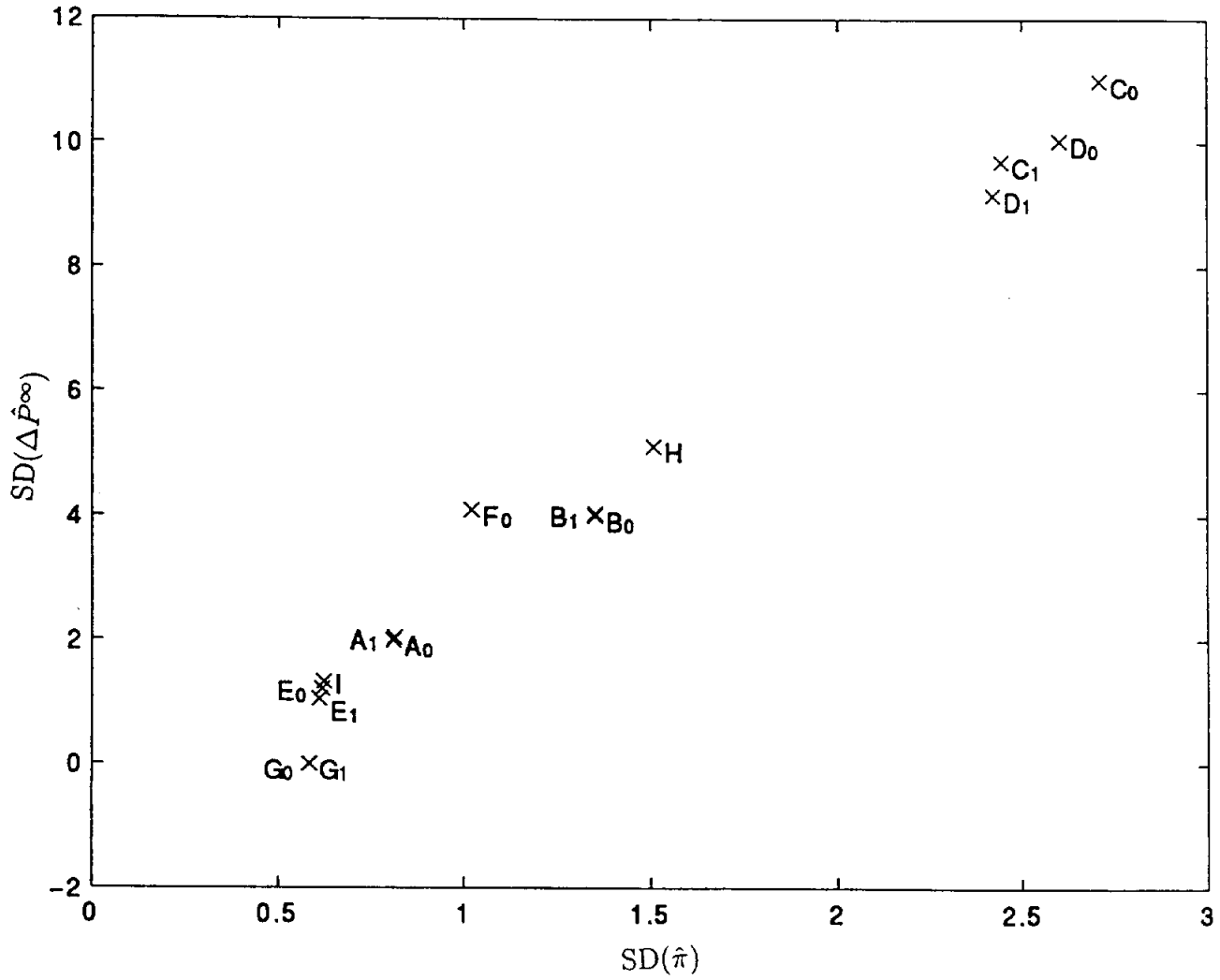
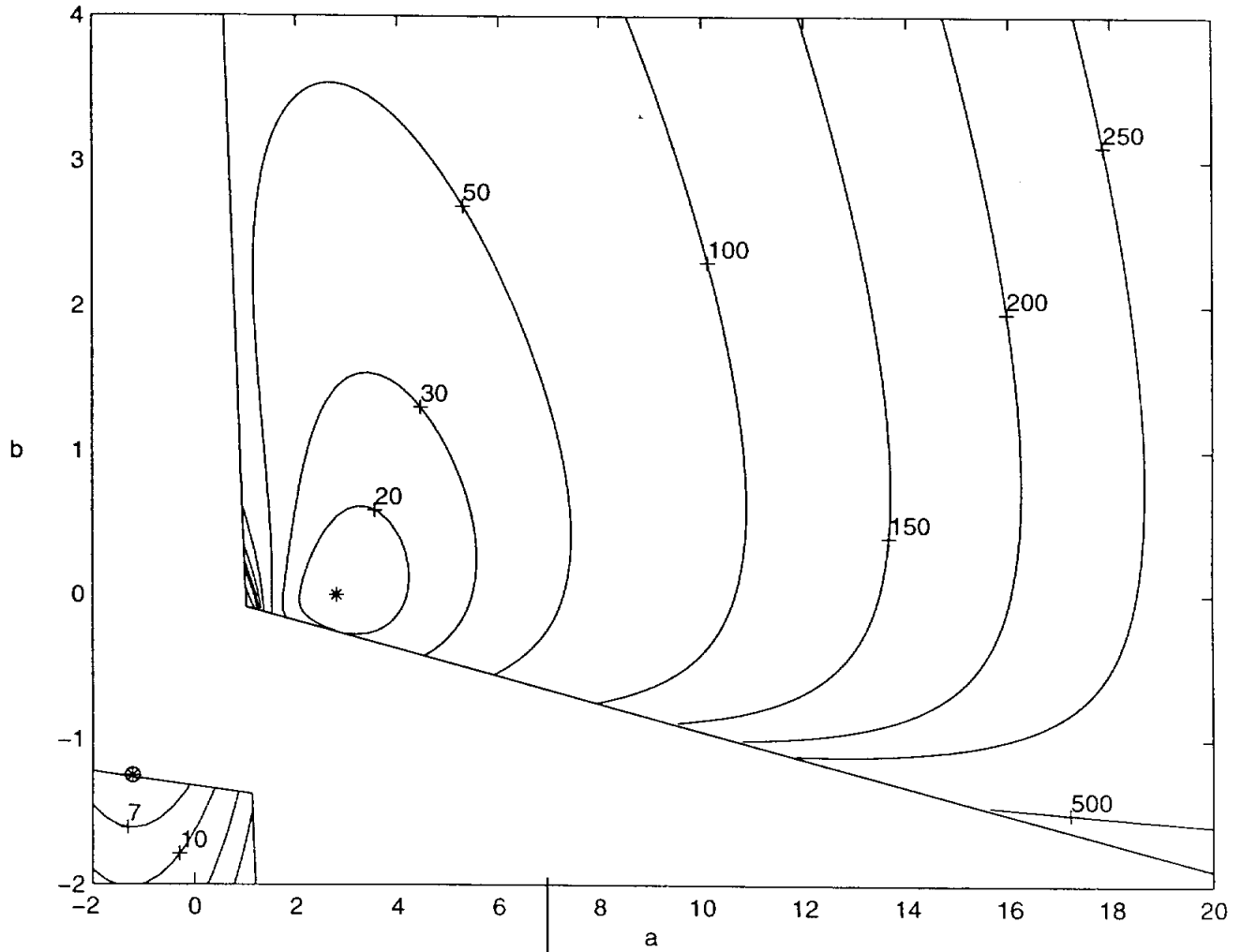


Figure 4: Simple Taylor Rules:
 $L + \pi^{*2}$ as a function of a and b



Region of Indeterminacy

Figure 5: Simple Taylor Rules:
 $\text{var}(\hat{\pi})$ as a function of a and b

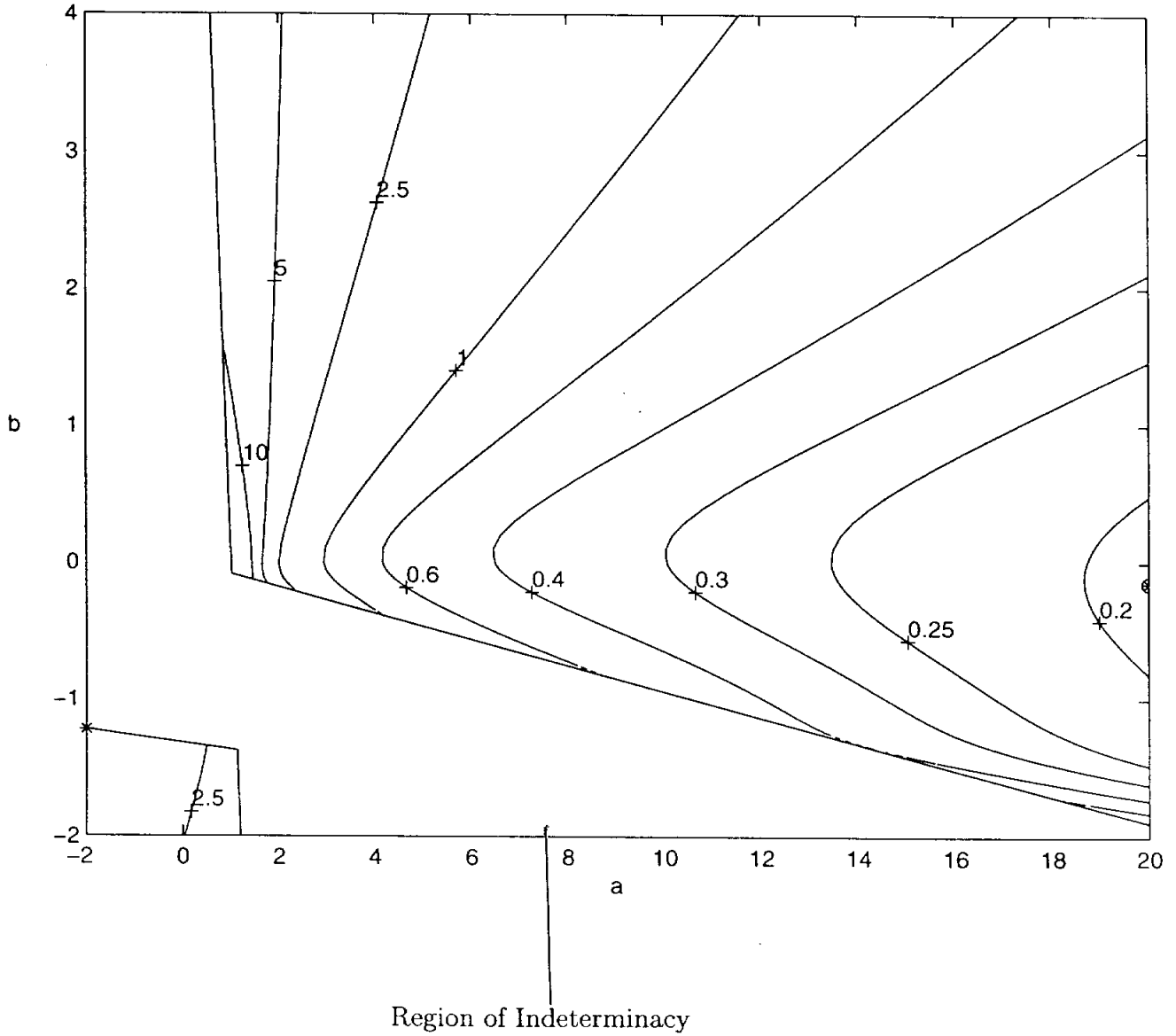
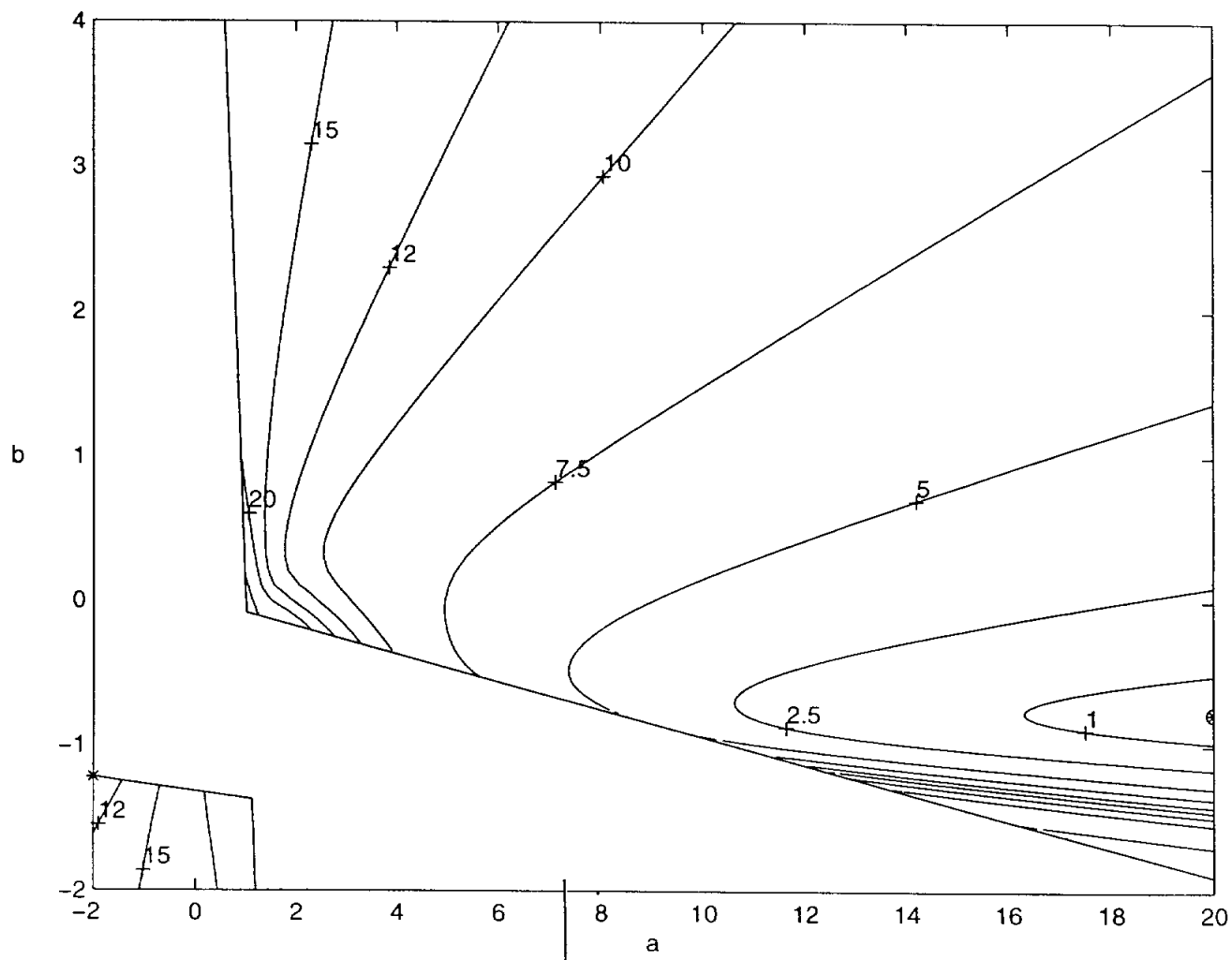
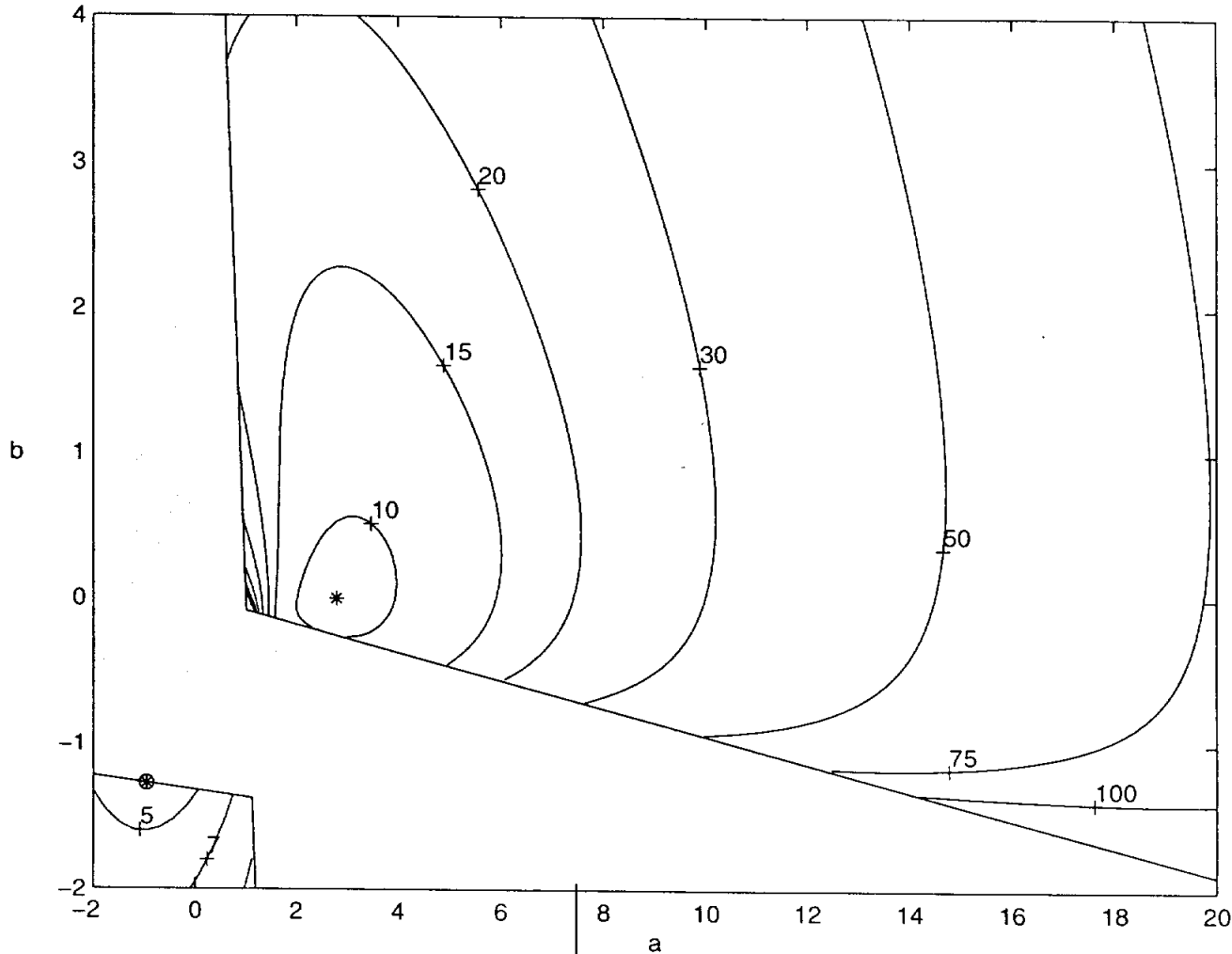


Figure 6: Simple Taylor Rules:
 $\text{var}(\hat{Y} - \hat{Y}^S)$ as a function of a and b



Region of Indeterminacy

Figure 7: Simple Taylor Rules:
 $\text{var}(\hat{R})$ as a function of a and b



Region of Indeterminacy

Figure 8: Simple Taylor Rules:
 $\text{var}(\hat{Y})$ as a function of a and b

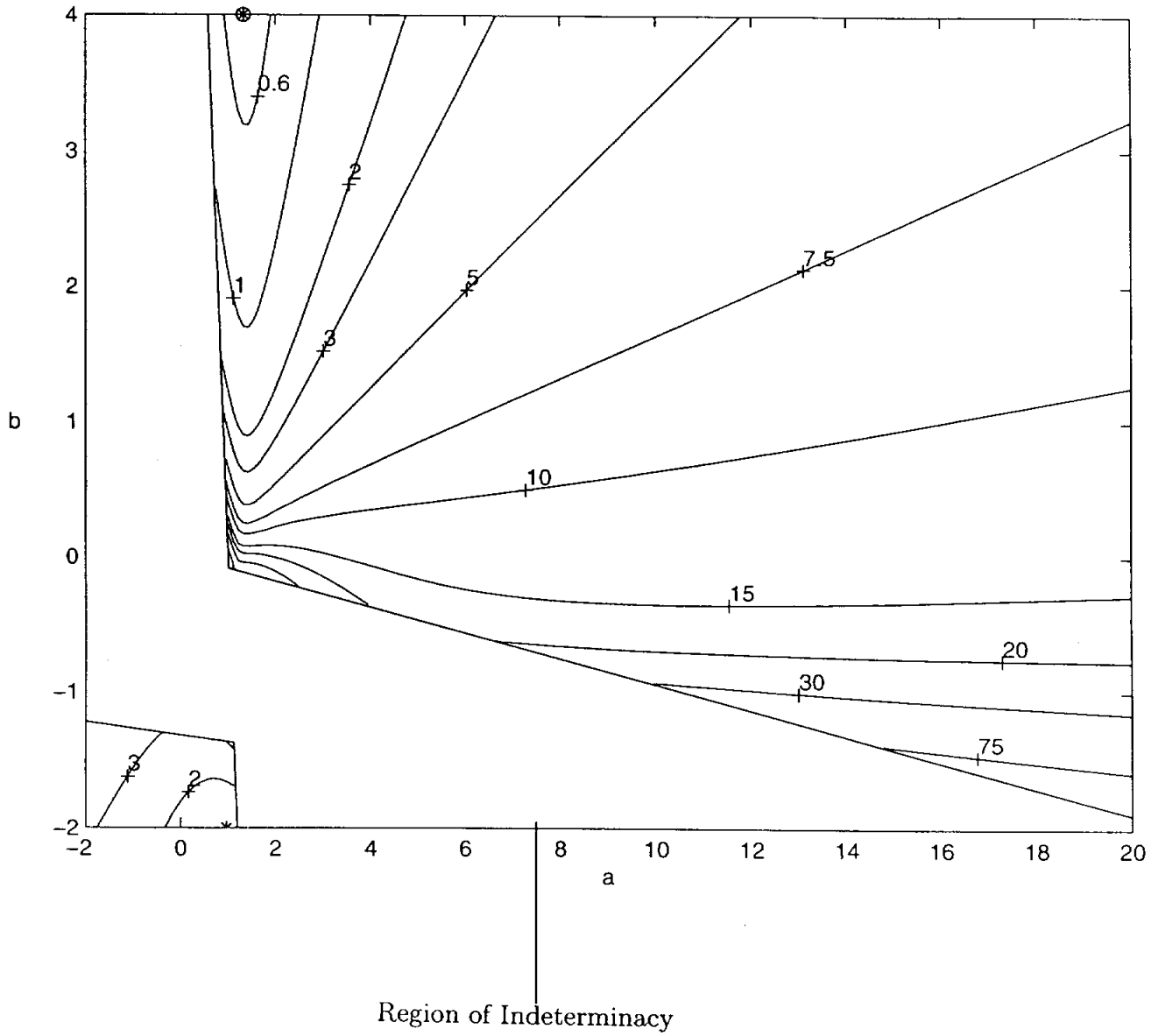


Figure 9: Generalized Taylor Rules:
 $\text{var}(\hat{\pi})$ as a function of a and c

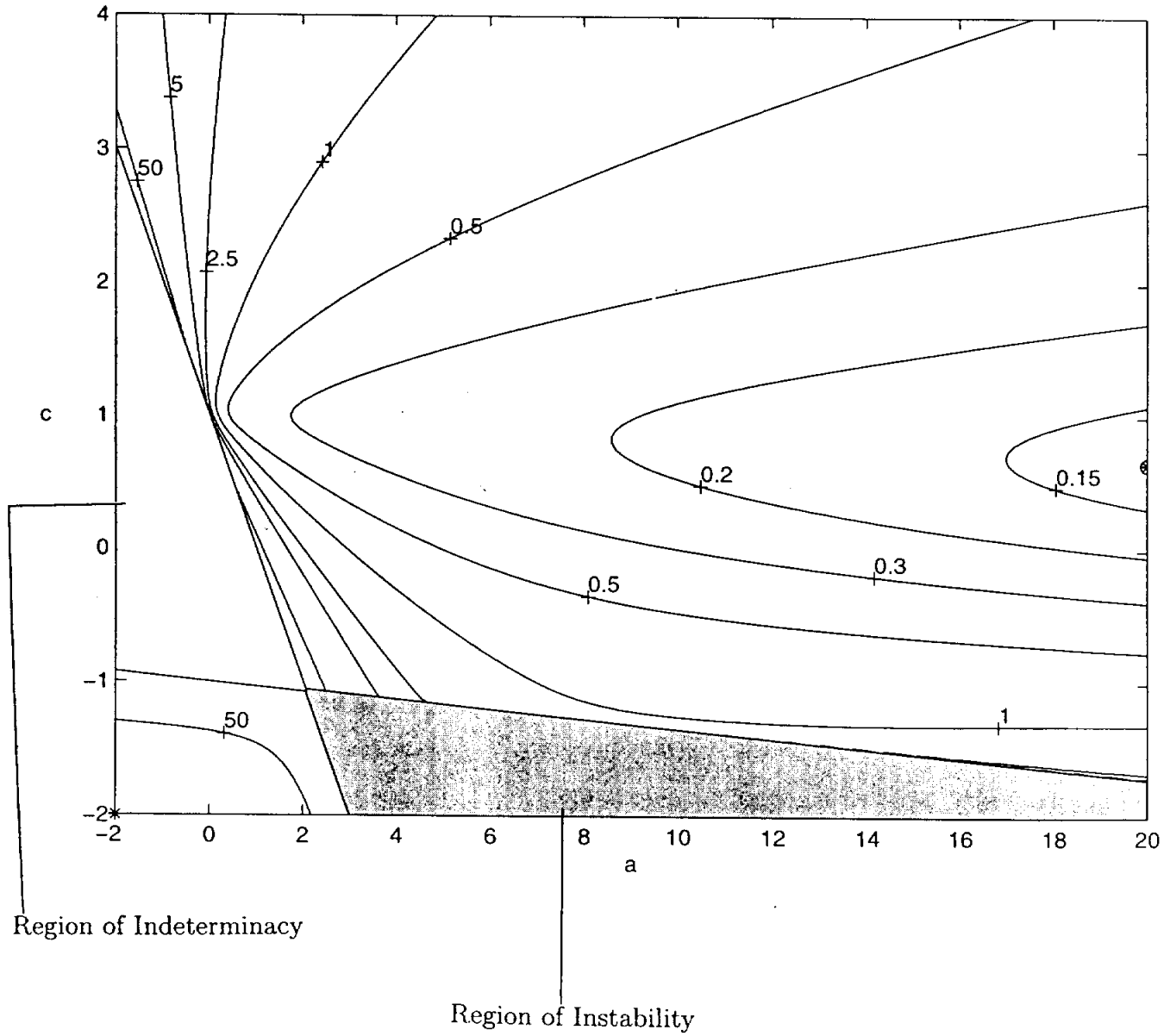


Figure 10: Generalized Taylor Rules:
 $\text{var}(\Delta p^\infty)$ as a function of a and c

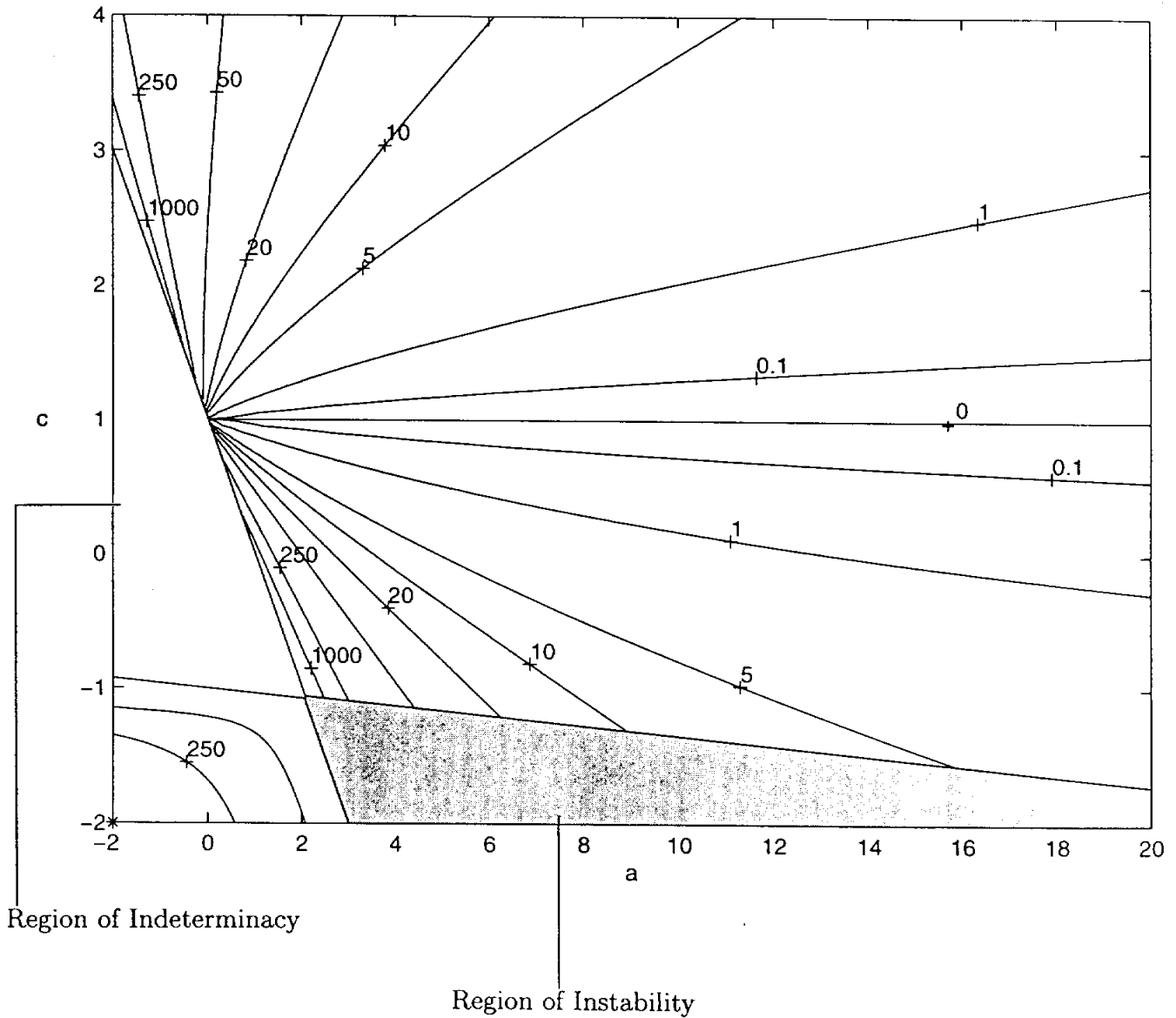


Figure 11: Generalized Taylor Rules:
 β^∞ as a function of a and c

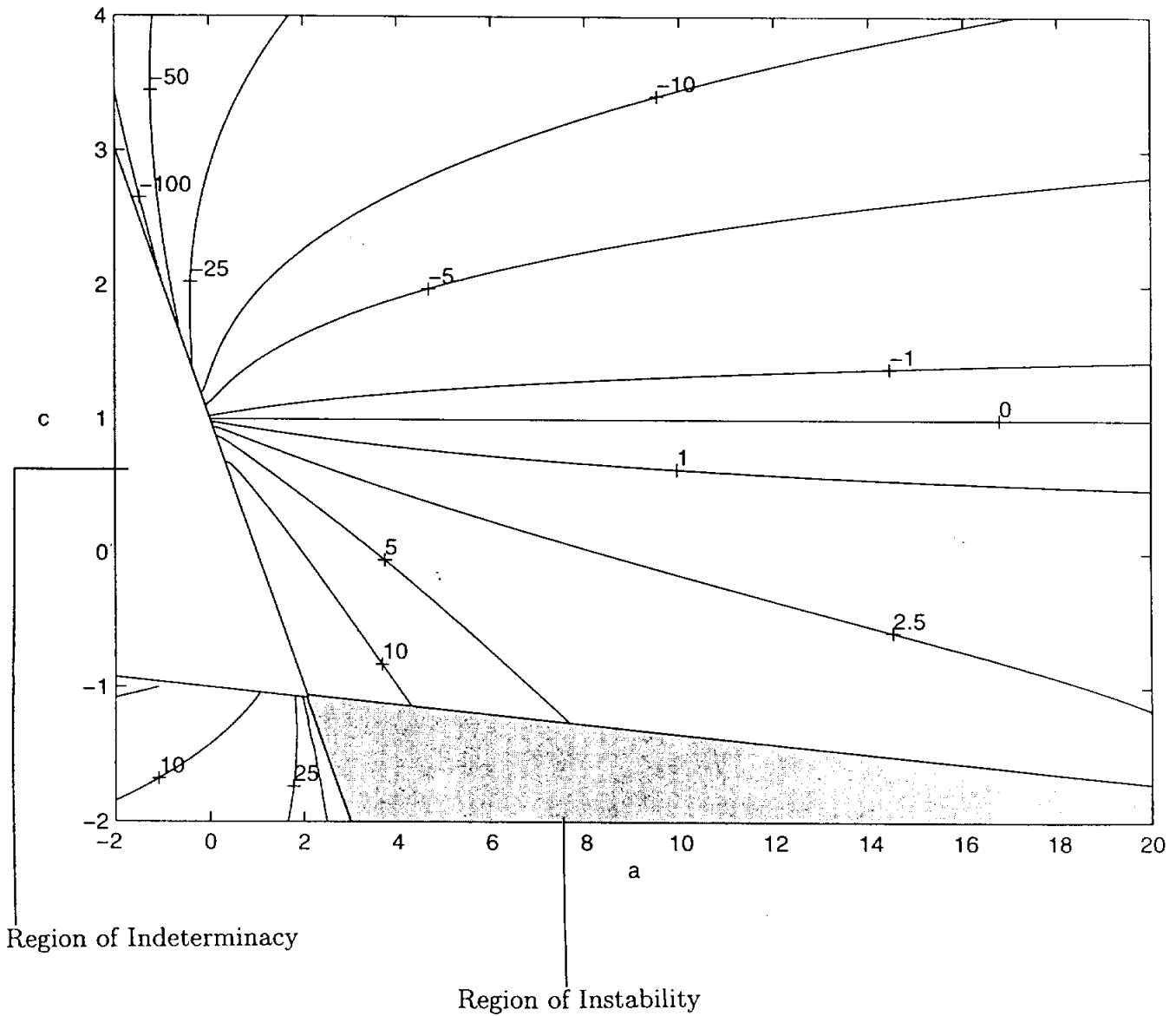


Figure 12: Generalized Taylor Rules:
 $\text{var}(\hat{R})$ as a function of a and c

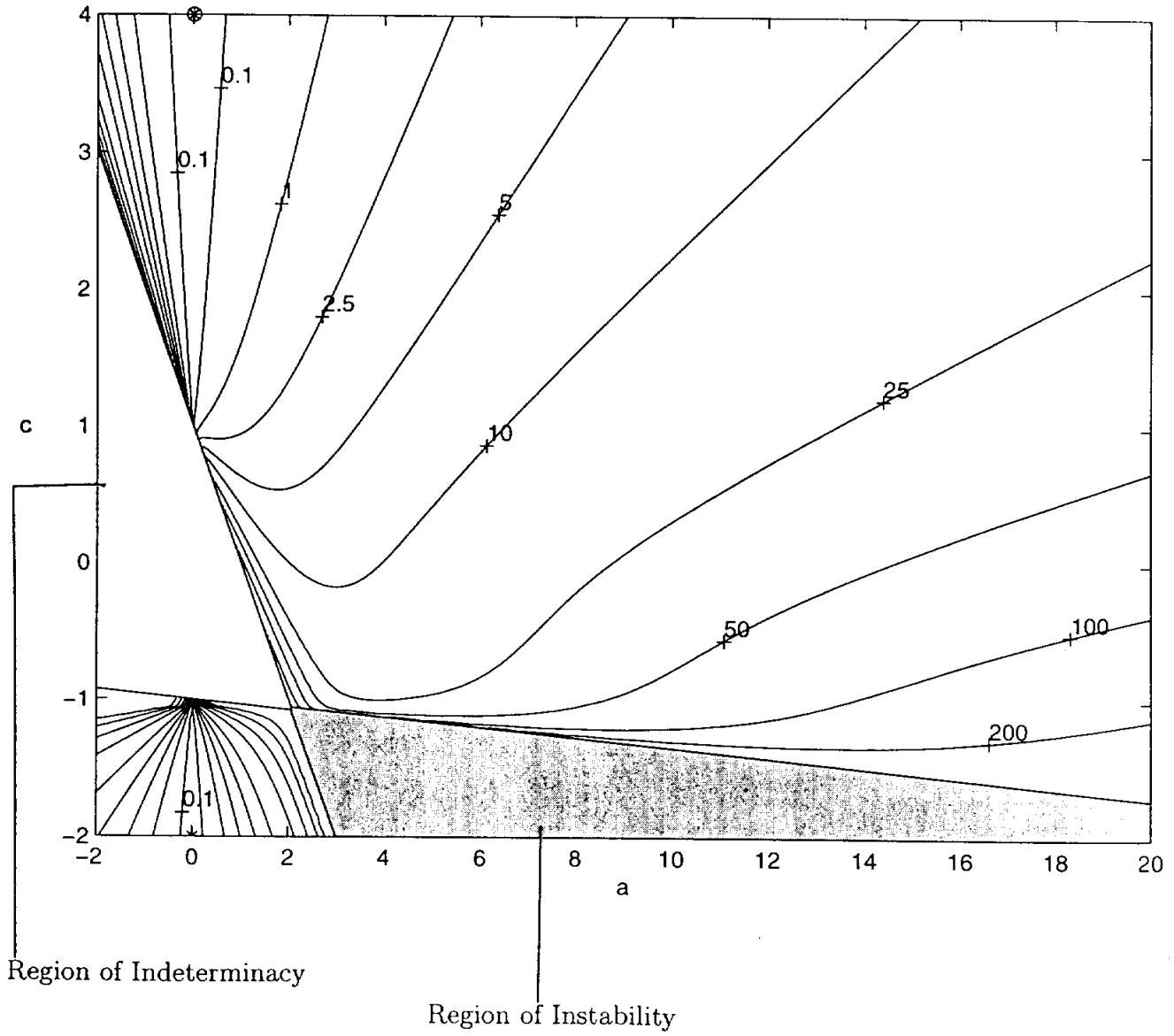


Figure 13: Generalized Taylor Rules:
 $\text{var}(\hat{R}_t - \hat{R}_{t-1})$ as a function of a and c

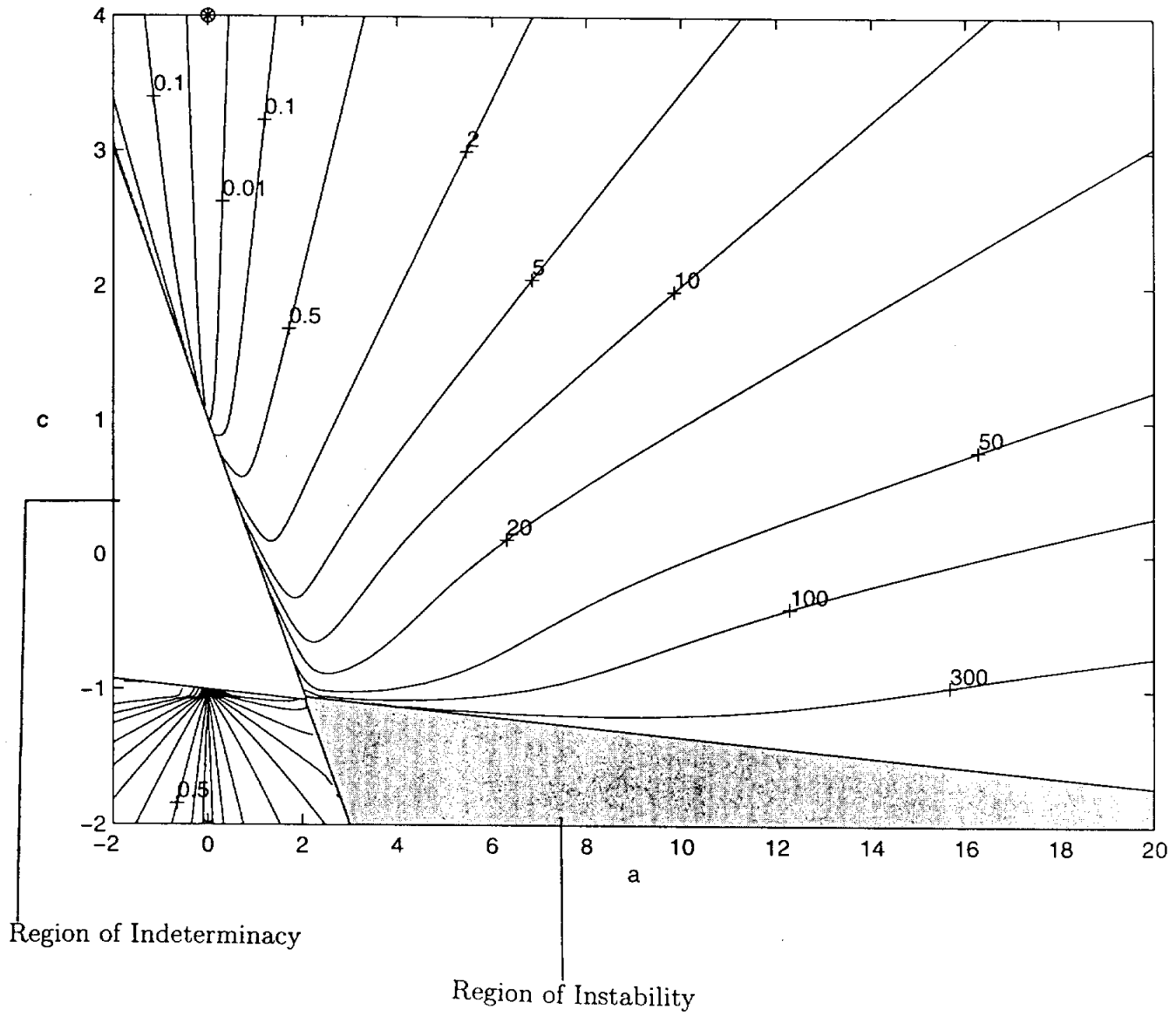


Figure 14: Generalized Taylor Rules:
 $L + \pi^{*2}$ as a function of a and c

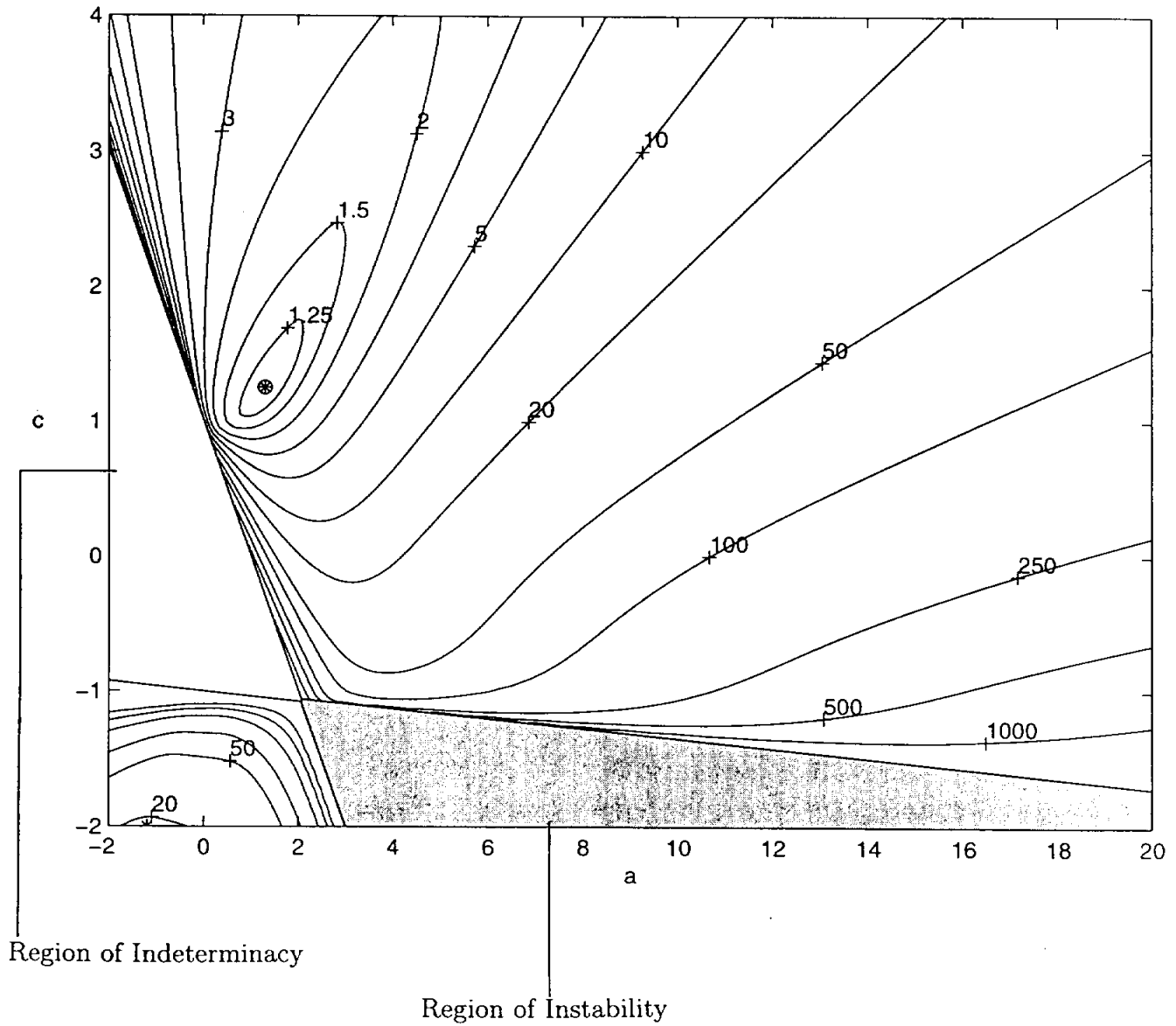


Figure 15: Lagged Response Rules:
 $\text{var}(\hat{\pi})$ as a function of a and b

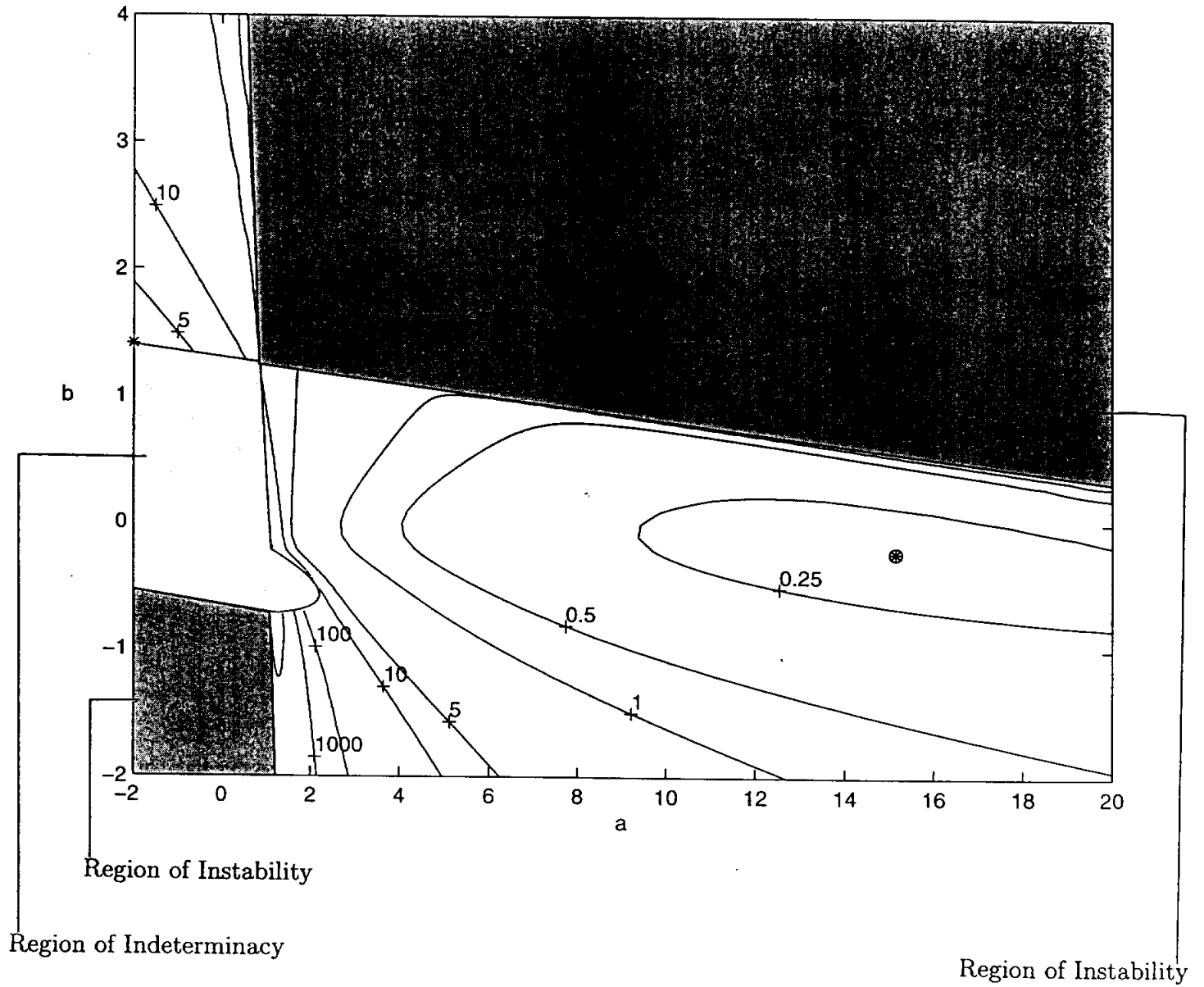


Figure 16: Lagged Response Rules:
 $\text{var}(\hat{\pi})$ as a function of a and c

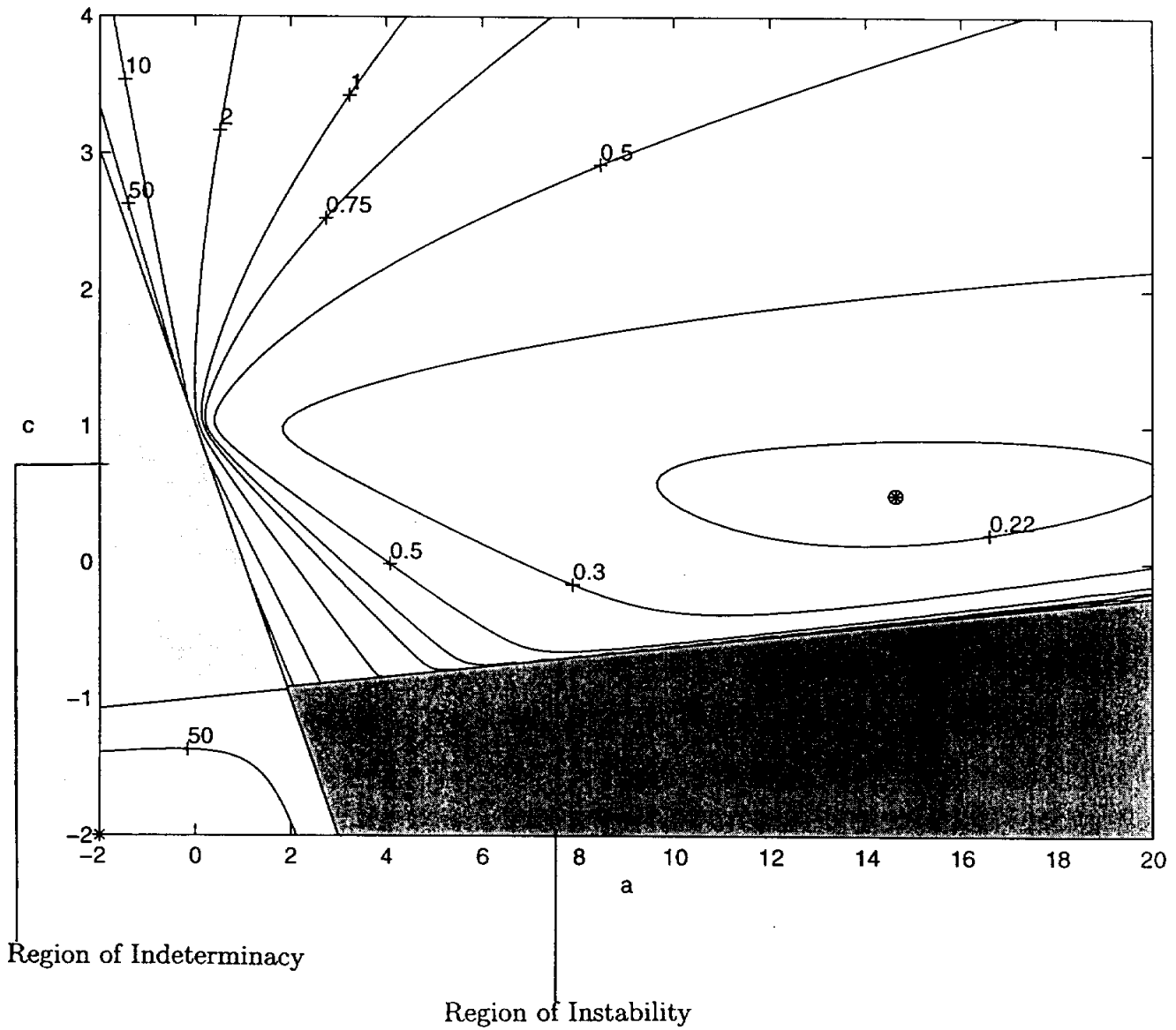


Figure 17: Lagged Response Rules:
 $L + \pi^2$ as a function of a and c

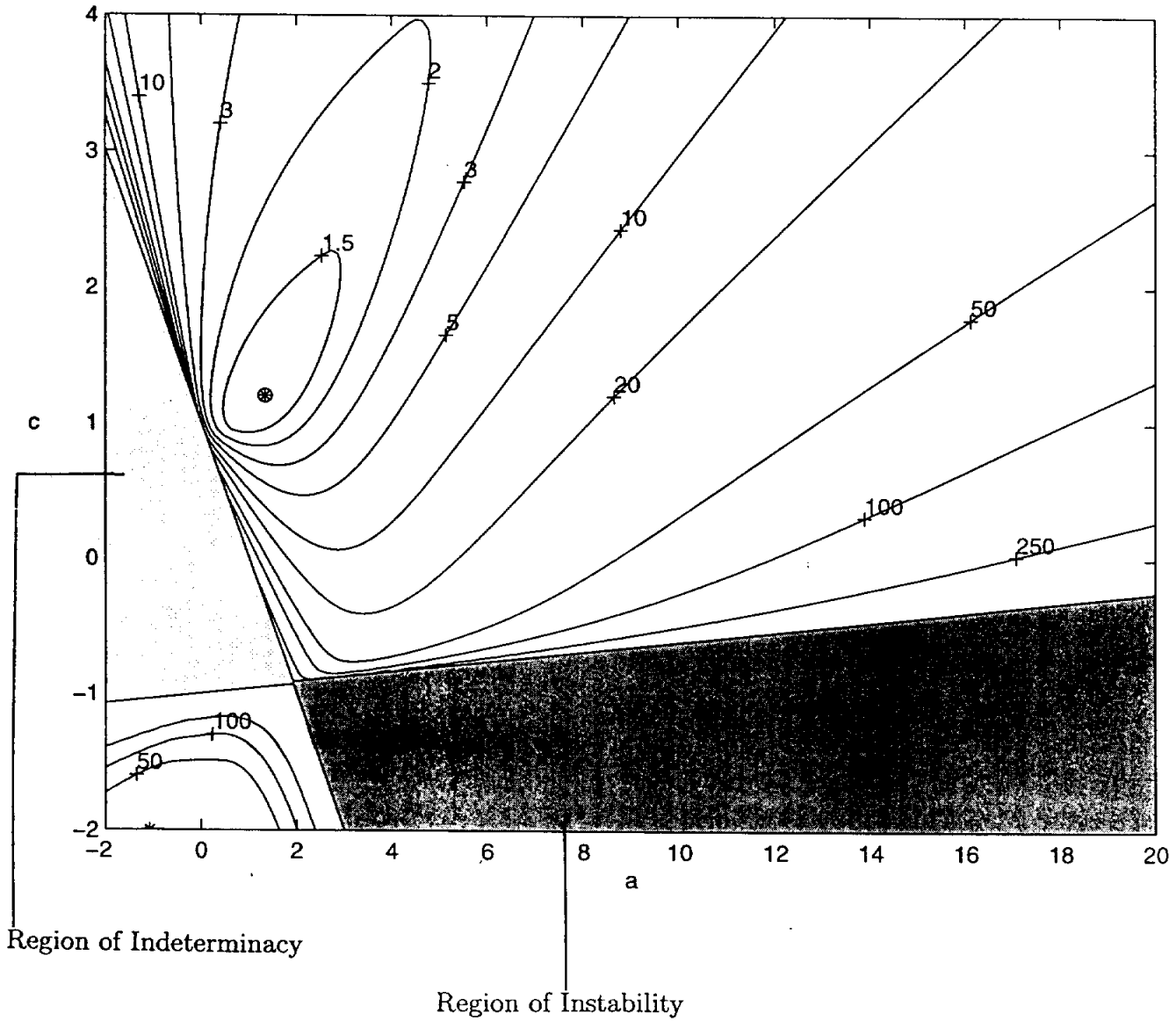


Figure 18: Price Level Rules:
 $L + \pi^{*2}$ as a function of a and c

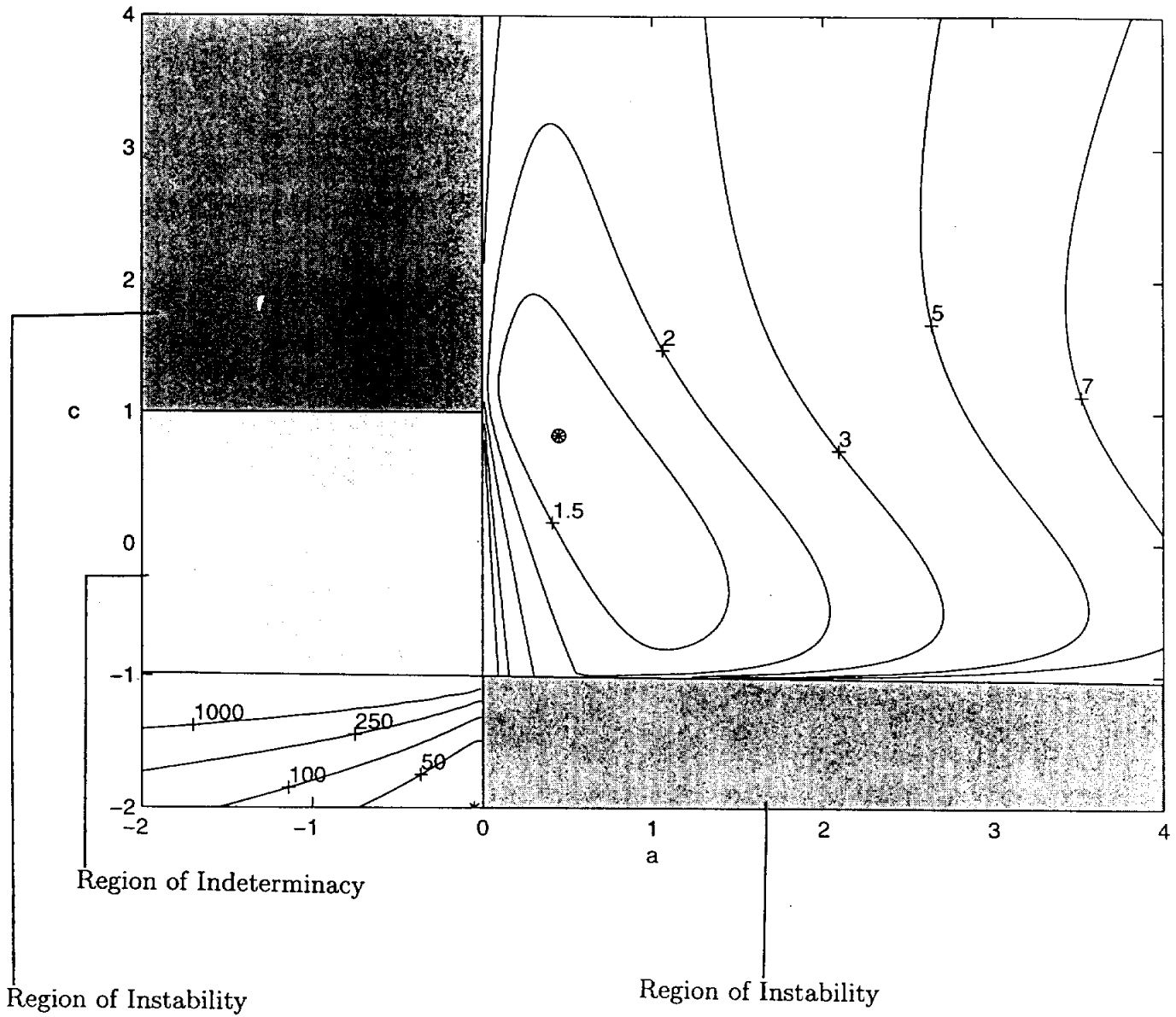


Figure 19: Response of Interest Rate to Permanent Shocks

