

ITERATIVE PROJECTION AND REFLECTION METHODS: THEORY AND PRACTICE

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The focus of this thesis is the family of so-called *projection and reflection methods*. These methods form the basis for a class of iterative algorithms which can be used to solve the *feasibility problem*, that is, the problem of finding a point in the intersection of a collection of constraint sets. Many optimisation and reconstruction problems can be profitably modelled within this framework, although the formulation is not always immediately obvious. In a typical feasibility problem the target intersection set is difficult to deal with directly, and projection and reflection algorithms overcome this by exploiting relatively simpler structure in each of the individual constraint sets from the collection. From the perspective of the practitioner, the methods are appealing due to their relative simplicity, ease-of-implementation and empirical good performance.

In recent times, a particular member of the family, the *Douglas–Rachford method*, has received special attention. This is, in part, due to its striking ability to successfully solve a variety of difficult nonconvex problems including those of a combinatorial nature. From a theoretical perspective, the lack of a sound theoretical foundation to justify and to explain such empirical successes begs for further investigation.

The organisation of the thesis is as follows: Chapter 1 introduces basic definitions, notation and background, before formally introducing the feasibility problem framework and fundamental projection-type algorithms. Chapter 2 focuses on theory in the presence of convex constraint sets, and introduces the recently developed *cyclic Douglas–Rachford method*. Chapter 3 focuses on theory in the absence of convexity. In this case, theoretical underpinnings are still in development and rather more cumbersome. Specific classes or instances of nonconvex feasibility problems must be considered separately. Chapter 4 investigates applications, particularly of the

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Douglas–Rachford algorithm to settings without convexity. Chapter 5 indicates open problems for future research.

The main contributions of the thesis can be summarised as follows.

- The discovery and analysis of the *cyclic Douglas–Rachford method* [2, 3], in the convex setting; the first many-set extension of the classical Douglas–Rachford method not requiring a product-space reformulation.
- A thorough study of the local regularity properties of sparse nonnegative vector and low-rank positive-semi-definite matrix constraints. A knowledge of these properties is of fundamental importance, for instance, in justifying the application of the Douglas–Rachford method to problems involving low-dimensional distance matrix reconstruction.
- The first global convergence results for the classical Douglas–Rachford method which apply to problems of a combinatorial nature. These results complement the emerging *local theory* [4] as well as being of interest in their own right.
- An extensive empirical investigation of nonconvex problems which the Douglas–Rachford method can successfully solve [1]. This growing library of problems is important both for the refinement of applications and to guide theoretical developments.

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