

Kolmogorov-Sinai Entropy Rate versus Physical Entropy

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(Received 28 May 1998)

We elucidate the connection between the Kolmogorov-Sinai entropy rate κ and the time evolution of the physical or statistical entropy S . For a large family of chaotic conservative dynamical systems including the simplest ones, the evolution of $S(t)$ for far-from-equilibrium processes includes a stage during which S is a simple linear function of time whose slope is κ . We present numerical confirmation of this connection for a number of chaotic symplectic maps, ranging from the simplest two-dimensional ones to a four-dimensional and strongly nonlinear map. [S0031-9007(98)08099-5]

PACS numbers: 05.45.Ac, 05.70.Ln

This paper tries to clarify the connection between the Kolmogorov-Sinai (KS) entropy and the physical entropy for a chaotic conservative dynamical system. This connection is obviously very important if one is to understand the impact on thermodynamics and statistical mechanics of the large amount of work done by mathematicians on the behavior of chaotic systems [1]. To start with the KS entropy, it is not really an entropy but an entropy per unit time, or an “entropy rate.” It is a single number κ , which is a property solely of the chaotic dynamical system considered. As for the physical entropy $S(t)$, the entropy of the second law of thermodynamics, it is a function of time, and this function depends not only on the particular dynamical system, but also on the choice of an initial probability distribution for the state of that system. Though it is clear that the original definition of κ [2] was meant to provide a connection with $S(t)$, the precise connection does not seem to be well known nowadays, and the few statements found in the textbooks are often vague [3].

The simplest connection one might guess would be the following: the KS entropy rate would be the maximum possible absolute value of the rate of variation of the physical entropy, i.e., $|dS/dt| \leq \kappa$. But this is wrong, because a counterexample can easily be found [4,5]. The actual connection is less direct and, in many cases, it requires that $S(t)$ be averaged over many histories (or trajectories), so as to give equal weights to initial distributions from all regions of phase space. Then, assuming these initial distributions to be very far from equilibrium, the variation with time of the physical entropy goes through three successive, roughly separated stages. In the first stage, $S(t)$ is heavily dependent on the details of the dynamical system and of the initial distribution; no generic statement can be made; dS/dt can be positive or negative, large or small; and, in particular, it can be larger than κ . In the second stage, $S(t)$ is a linear increasing function whose slope is κ . In the third stage, $S(t)$ tends asymptotically toward the constant value which characterizes equilibrium, for which the distribution is uniform in the available part of phase space. It may

happen, however, that the simple and generic stage 2 is absent, with stages 1 and 3 merging into each other. This is true when the initial distribution is not sufficiently different from the equilibrium distribution.

We make no claim of having a rigorous mathematical proof of these statements. We do have an incomplete, but quite suggestive, analytical discussion [4], which cannot fit in the space available here. The latter part of this Letter will present a few very convincing numerical simulations for symplectic maps of two and four dimensions. Reference [4] contains more map results, as well as a three-dimensional flow. There is already some work by Dellago and Posch [6] which contains a two-dimensional nonlinear map treated in a very similar way. Some of our ideas are also present in Ref. [7], including the three-stage idea, but the crucial connection with the KS entropy rate, valid for any number of dimensions and for nonlinear systems, is not there. Note that the definition of a single global κ is not always a useful one, for instance, for several weakly coupled subsystems; in such cases the connection clearly needs generalization.

The definition of the KS entropy rate can be found in many textbooks [8]. To calculate it here, we use the fact that it is equal to the sum of the positive Lyapunov exponents [9]. Our definition for the out-of-equilibrium physical entropy is $S = \text{const} - I$, where I is the Shannon information [10]. These S and I are coarse grained [11]. Coarse graining consists in performing a slight smearing, or smoothing, of the probability distribution in phase space before calculating S or I . The fine-grained quantities do not vary with time at all, because Liouville’s theorem says that the volume of phase space is conserved. The shape of that volume, however, becomes increasingly complicated and fractalized, due to the chaotic dynamics. Hence, under smoothing, the volume occupied keeps increasing. There are many ways to perform a coarse graining. For this paper, we assume that phase space is divided into a large number of cells c_α with volumes v_α , such that $\sum_\alpha v_\alpha = V$, the total volume of available phase space. Then we define I by

$$I(t) = \sum_{\alpha} p_{\alpha}(t) \log \left[\frac{V}{v_{\alpha}} p_{\alpha}(t) \right], \quad (1)$$

where $p_{\alpha}(t)$ is the probability that the state of the system in phase space at time t falls inside cell c_{α} . In the following it will be more convenient to work with $I(t)$ rather than $S(t)$. This is because, when I is used, there is a convenient reference point, the uniform distribution, whose I always vanishes, irrespective of the coarse graining. On the other hand, the constant quantity $I + S$, and therefore S , do depend on the coarse graining.

This type of coarse graining allows an alternative version of the significance of κ for the evolution of a physical system. Let us assume the initial distribution to be very strongly localized in phase space; i.e., most cells contain zero probability initially. Then, during the generic “second stage” mentioned earlier, the total number of occupied cells, i.e., cells with nonvanishing p_{α} , varies proportionally to $e^{\kappa t}$. Our simulations verify this fact well (see Fig. 3).

We return to the need for averaging, in our simulations, many histories starting from different parts of phase space. This has to be done whenever the local κ (the sum of the positive local Lyapunov exponents) varies appreciably from place to place, which is the normal case for nonlinear systems. For linear maps (like the generalized cat map below) it is not necessary. For other systems, it would never be necessary if we could use a fine-enough coarse graining, to give the probability time to spread throughout phase space before any appreciable increase in entropy. Unfortunately, such fine grain would require computers far more powerful than exist now. In the real thermodynamical world with many dimensions, what kind of coarse graining should preferably be used is, we believe, a wide open question.

For what may be the simplest of all conservative chaotic systems, the baker’s map, the correctness of our three-stage description for the behavior of $I(t)$ can be shown analytically [4]. Our first simulations are done with the “generalized cat map” inside a unit square:

$$\begin{aligned} P &= p + kq \pmod{1}, \\ Q &= p + (1 + k)q \pmod{1}, \end{aligned} \quad (2)$$

where k is a positive control parameter. Figure 1 shows $I(t)$ for four values of k (see caption). The coarse-graining grid is obtained by dividing each axis into 400 equal segments. The initial distribution consists of 10^6 points placed at random inside a square whose size is that of a coarse-graining cell, and the center of that square is picked at random anywhere on the map. Each of the four curves is an average over 100 runs, i.e., 100 histories with different initial distributions chosen at random, as mentioned. Each curve shows clearly the stage-2 linear behavior, the negative of the slope being accurately given by the (analytically calculable) Lyapunov exponent:

$$\lambda = \log \frac{1}{2} (2 + k + \sqrt{k^2 + 4k}) = \kappa. \quad (3)$$

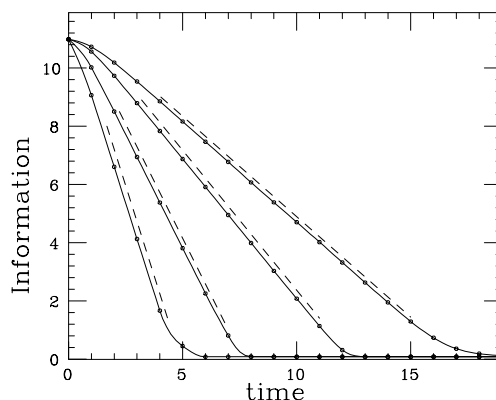


FIG. 1. Generalized cat map: $k = 10, 3, 1$, and 0.5 (from left to right); $\kappa = 2.48, 1.57, 0.96$, and 0.69 , respectively; $N = 10^6$; grid = 400×400 ; $V_i = V_{\text{cell}}$; average of 100 histories. Here, and in Figs. 2, 3, 4, 6, and 7, we show in dashes, and slightly displaced from the simulation results, straight lines with the predicted $-\kappa$.

Figure 2 shows how $I(t)$ depends on the initial distribution and on the coarse graining. Now $k = 1$ only. Other conditions are the same as in Fig. 1, except that we calculate a single history instead of averaging 100. This makes no big difference in this case, because the local Lyapunov exponent is the same everywhere. In the six top curves six different sizes are compared for the initial square; the grid is as in Fig. 1. The first size is that of 1 coarse-graining cell, then 4 cells, 16, 64, 256, and 1024 cells (from top to bottom). All six curves have the same stage-2 slope given by $-\kappa$. Their vertical displacement is $\log 2$ for each factor of 2 in the linear dimension of the initial distribution. The three bottom curves show how $I(t)$ depends on the coarse graining. The size of the initial square is always that of 1024 original coarse-graining cells. For the upper curve (sixth from the top) the cells are as in Fig. 1, for the middle curve they are squares 4 times larger in area, and for the bottom curve they are 4 times larger again.

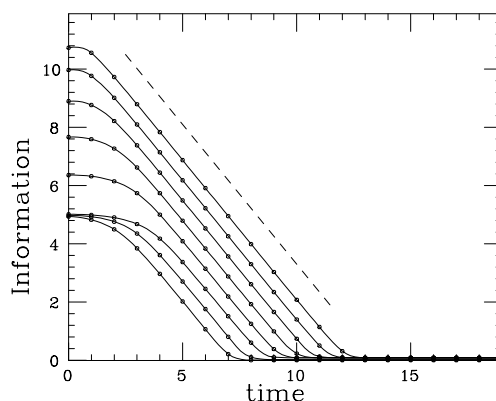


FIG. 2. Generalized cat map: $k = 1$; $\kappa = 0.96$; $N = 10^6$. From top to bottom: grid = 400×400 , $V_i/V_{\text{cell}} = 1, 4, 16, 64, 256$, and 1024 (six curves); and grid = $200 \times 200, 100 \times 100$, $V_i/V_{\text{cell}} = 1024$ (two curves), one history.

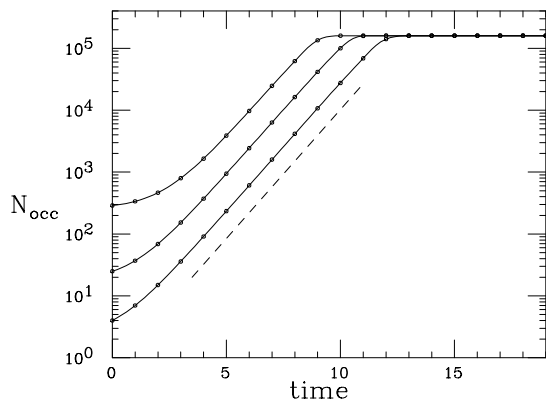


FIG. 3. Generalized cat map: $k = 1$; $\kappa = 0.96$; $N = 10^6$; grid = 400×400 ; $V_i/V_{\text{cell}} = 1, 16, \text{ and } 256$ (bottom to top), one history.

Once again, all three curves have the same stage-2 slope of $-\kappa$. They are displaced vertically from each other by the log of the factor in coarse-graining linear dimension, i.e., $\log 2$.

In Fig. 3 we plot on a log scale the number of occupied cells vs time for the finest coarse graining and three progressively larger initial distributions, whose centers are picked at random as always. All three stage-2 straight lines are indeed fitted by $e^{\kappa t}$. Their vertical displacement is a factor of 4, which is also the factor in the linear size of the initial distributions.

The second system studied is the standard map [12], again a two-dimensional conservative map in the unit square, but this time nonlinear,

$$P = p + \frac{k}{2\pi} \sin(2\pi q) \pmod{1},$$

$$Q = q + P \pmod{1}. \tag{4}$$

The map is only partially chaotic, but the percentage of chaos increases with the control parameter k , and we use large values of k , namely, 20, 10, and 5. For $k = 5$ there

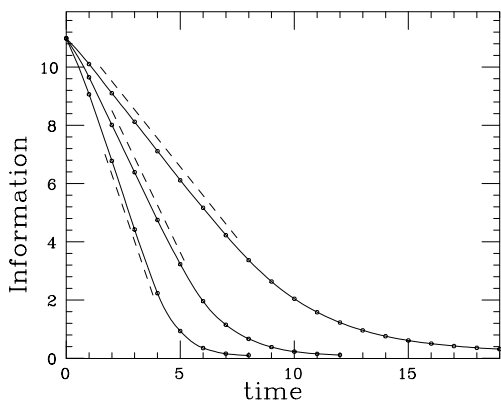


FIG. 4. Standard map: $k = 20, 10, 5$ (from left to right), $\kappa = 2.30, 1.62, \text{ and } 0.98$ respectively; $N = 10^6$; grid = 400×400 ; $V_i = V_{\text{cell}}$; average of 100 histories ($k = 20, 10$); 1000 histories ($k = 5$).

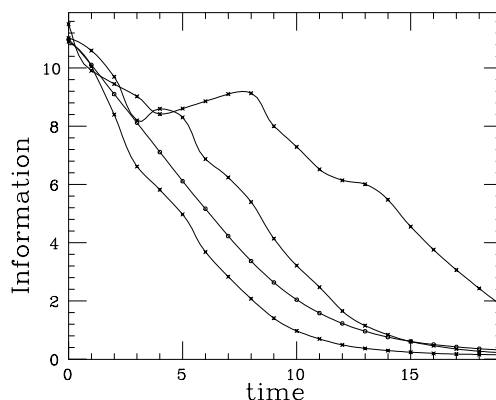


FIG. 5. Standard map: $k = 5$; $\kappa = 0.98$; three single histories compared with the average from Fig. 4.

are two sizable regular islands, associated with a period 2 stable trajectory. We calculated the Lyapunov exponent numerically, leaving out the regular islands for $k = 5$. This yielded $\lambda = \kappa = 2.30, 1.62, \text{ and } 0.98$, respectively, for the three k 's. Figure 4 shows the three curves $I(t)$, with the top curve corresponding to the smallest k . The coarse-graining grid, the choice of initial distribution, and the averaging are the same as for Fig. 1, but it was necessary to include 1000 histories in the averaging for $k = 5$. Each curve has a stage-2 linear portion whose slope is correctly given by $-\kappa$. Figure 5 presents three single histories (\times) for $k = 5$, as well as the average curve from Fig. 4 (\circ). For such a very nonlinear system, with too coarse a grain, the single curves vary wildly and the averaging is essential.

Our next example is a four-dimensional system, a generalized cat map. It is a linear symplectic map [13], reduced to a unit-size hypercube by introducing “mod 1” in each of the four transformation equations. The two positive Lyapunov exponents λ_1 and λ_2 can be calculated analytically, and the KS entropy rate is $\kappa = \lambda_1 + \lambda_2$. For this system we made up the coarse-graining grid by

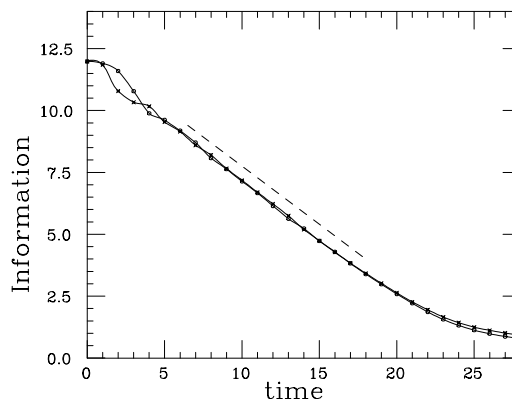


FIG. 6. Four-dimensional generalized cat map; $\lambda_1 = 0.223$; $\lambda_2 = 0.247$; $\kappa = 0.470$; $N = 10^6$; grid = 20^4 ; $V_i = (20)^{-4}V_{\text{cell}}$; two single histories.

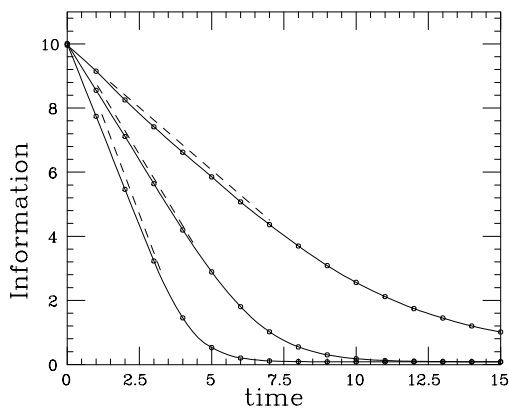


FIG. 7. Four-dimensional nonlinear map: (Bottom) $k_1 = 10$; $k_2 = 5$; $m = 0.5$; $\lambda_1 = 1.65$; $\lambda_2 = 0.75$; $\kappa = 2.40$. (Middle) $k_1 = 5$; $k_2 = 3$; $m = 0.5$; $\lambda_1 = 1.03$; $\lambda_2 = 0.45$; $\kappa = 1.48$. (Top) $k_1 = 3$; $k_2 = 1$; $m = 0.5$; $\lambda_1 = 0.62$; $\lambda_2 = 0.16$; $\kappa = 0.78$. $N = 10^6$; grid = 20^4 ; $V_i = V_{\text{cell}}$; average of 100 histories.

dividing each of the four axes into 20 equal segments. The initial distribution consists of 10^6 points placed at random inside one hypercube of size $400^{-1} \times 400^{-1} \times 400^{-1} \times 400^{-1}$, and the center of the hypercube is picked at random anywhere on the map. Figure 6 shows $I(t)$ for 2 single histories. They differ greatly in their stage-1, but both have nearly linear stage-2's with the correct slope given by $-\kappa$.

Finally we have a four-dimensional nonlinear map, made up of two coupled standard maps,

$$P_1 = p_1 + \frac{k_1}{2\pi} \sin(2\pi q_1) \pmod{1}, \quad (5)$$

$$Q_1 = q_1 + P_1 + mP_2 \pmod{1}.$$

$$P_2 = p_2 + \frac{k_2}{2\pi} \sin(2\pi q_2) \pmod{1}, \quad (6)$$

$$Q_2 = q_2 + P_2 + mP_1 \pmod{1}.$$

We worked with 3 sets of control parameters (k_1, k_2) , namely, (10,5), (5,3), and (3,1). The coupling parameter m was 0.5 in all cases. We calculated the two Lyapunov exponents numerically [14], then added them up to get κ . The numerical values are in the figure caption. The initial volume was the size of one cell, and we averaged over 100 histories. Figure 7 shows $I(t)$. It has a fairly well defined second stage with a slope close to $-\kappa$ in all cases.

The work we have reported makes very explicit the connection between the KS entropy rate, when it is meaningful, and the time dependence of the physical entropy or information. Yet it is far from a complete answer. It assumes that, at the beginning of the system's evolution, the probability distribution spreads very fast to all corners of phase space before undergoing much

fractalization, so that its subsequent variation is well described by a global κ . But there are other possible scenarios. For instance, there may be gradual overall evolution in space as well as in time, a possibility which is not included by our assumption that all parts of phase space must start on an equal footing. In conclusion, although this work constitutes only a quick foray into the subject, we hope that our assertions can function as guiding principles for research attempting to bring together the mathematics of chaos and the physics of far-from-equilibrium thermodynamics.

We thank A. D'Andrea, A. Rapisarda, and M. Saraceno for fruitful discussions. We also thank S. Ganguli and B. Müller who furnished some pointers to the literature. Financial support was provided by INFN (for V.L.), and at MIT by the U.S. Department of Energy (D.O.E.) under Contract No. DE-FC02-94ER40818.

Note added.—Since this Letter was submitted, another example of the connection between KS entropy rate and physical entropy was published by Dzugutov *et al.* [15].

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