

L^2 -ERROR ANALYSIS OF FULLY DISCRETE DISCONTINUOUS GALERKIN APPROXIMATIONS FOR NONLINEAR SOBOLEV EQUATIONS

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ABSTRACT. In this paper, we develop a symmetric Galerkin method with interior penalty terms to construct fully discrete approximations of the solution for nonlinear Sobolev equations. To analyze the convergence of discontinuous Galerkin approximations, we introduce an appropriate projection and derive the optimal L^2 error estimates.

1. Introduction

In this paper, we consider the following nonlinear Sobolev equation

$$(1.1) \quad \begin{aligned} u_t - \nabla \cdot (a(u)\nabla u + b(u)\nabla u_t) &= f(u) && \text{in } \Omega \times (0, T], \\ (a(u)\nabla u + b(u)\nabla u_t) \cdot n &= 0 && \text{on } \partial\Omega \times (0, T], \\ u(x, 0) &= u_0(x) && \text{on } \Omega, \end{aligned}$$

where Ω is an open bounded domain in \mathbb{R}^d , $d = 2$ with smooth boundary $\partial\Omega$, n denotes the unit outward normal vector to $\partial\Omega$ and a , b and f are known functions.

The problem (1.1) represents many physical phenomena such as the flow of fluids through fissured materials [5], thermodynamics [7] and others. For the existence, uniqueness and stability of the solution of the problem (1.1), we refer to [6, 8, 20] and the reference cited in [10]. By many authors the finite difference approximations to the solution of (1.1) have been investigated in the several literatures [9, 11, 12].

Arnold, Douglas and Thomee [1, 2] and Nakao [15] constructed the Galerkin approximations to the solution of (1.1) with periodic boundary conditions in

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one dimensional space, and obtained the optimal L^2 error estimates and super-convergence results.

In [13], Lin studied the Galerkin approximation of (1.1) with $d = 2$ and derived the optimal L^2 error estimates using Crank-Nicolson method. Lin and Zhang [14] constructed the semidiscrete finite element approximations and derived the optimal L^2 error estimates with nonlinear boundary condition.

Recently in [18, 19], the authors adapted discontinuous Galerkin methods to (1.1) and obtained the optimal H^1 error estimates.

In this paper, we construct the fully discrete approximation of the problem (1.1) using the discontinuous Galerkin method for the spatial discretization and Crank-Nicolson method for the time step discretization. Compared to the classical Galerkin method, the discontinuous Galerkin method has advantages such as the potential error control, the mesh adaption and the local mass conservation.

This paper is organized as follows: In Section 2, we introduce some notations and necessary assumptions on the data and the regularity of the solution of the problem (1.1). In Section 3, we construct finite element spaces, introduce the convergence of the approximations and construct discrete some bilinear forms and auxiliary projection. In Section 4, we formulate discrete fully discrete discontinuous Galerkin approximations and prove the optimal convergence in $\ell^\infty(L^2)$ error estimates.

2. Notations and basic assumptions

For an $s \geq 0$ and a domain $E \subset \mathbb{R}^d$, we let $H^s(E)$ the Sobolev space of order s equipped with the usual Sobolev norm $\|u\|_{s,E}$.

We simply write $\|\cdot\|_s$ instead of $\|\cdot\|_{s,\Omega}$ if $E = \Omega$. And also the usual seminorm of a function defined on E is denoted by $|\cdot|_{s,E}$ and we simply denote $|\cdot|_s$ instead of $|\cdot|_{s,\Omega}$, if $E = \Omega$.

Let $\mathcal{E}_h = \{E_1, E_2, \dots, E_{N_h}\}$ be a regular quasi-uniform subdivision of Ω where E_i is a triangle or a quadrilateral if $d = 2$ and E_i is a 3-simplex or 3-rectangle if $d = 3$. Let $h_i = \text{diam}(E_i)$ be the diameter of E_i and $h = \max_{1 \leq i \leq N_h} h_i$. We assume that there exists a constant $\rho > 0$ such that each E_i contains a ball of radius ρh_i . The quasiuniformity requirement is that there is a constant $\gamma > 0$ such that

$$\frac{h}{h_i} \leq \gamma, \quad i = 1, 2, \dots, N_h.$$

Now we assume that for $t \in [0, T]$ and $(x, p) \in \Omega \times \mathbb{R}$, the following regularity conditions on a , b , f and u are satisfied:

(A1) There exist constants a_0 and a^* such that

$$0 < a_0 \leq a(x, p), \quad b(x, p) \leq a^*.$$

- (A2) $a(x, p)$, $b(x, p)$ and $f(x, p)$ are continuously differentiable with respect to each variable and are uniformly bounded such as $\left| \frac{\partial a}{\partial p} \right|$, $\left| \frac{\partial b}{\partial p} \right|$, $\left| \frac{\partial^2 a}{\partial p^2} \right|$, $\left| \frac{\partial^2 b}{\partial p^2} \right|$, $\left| \frac{\partial f}{\partial p} \right| \leq K$ for some constant $K > 0$.
- (A3) $u \in C^2(\Omega \times [0, T])$ is a unique solution to the problem (1.1) and u , $u_t \in L^\infty([0, T], H^s(\Omega))$ for $s \geq \frac{d}{2} + 1 + \delta$ for $\delta > 0$, $u_{tt} \in L^\infty(H^{\frac{d}{2}+1})$.
- (A4) ∇u and ∇u_t are bounded in $L^\infty(\Omega \times [0, T])$.

3. Finite element spaces and an auxiliary projection

For an $s \geq 0$ and a given subdivision \mathcal{E}_h , we define the following space

$$H^s(\mathcal{E}_h) = \{v \in L^2(\Omega) \mid v|_{E_i} \in H^s(E_i), \quad i = 1, 2, \dots, N_h\}.$$

Let the edges (or faces if $d = 3$) of \mathcal{E}_h be denoted by $\{e_1, e_2, \dots, e_{P_h}, e_{P_h+1}, \dots, e_{M_h}\}$ where $e_k \subset \Omega$, $1 \leq k \leq P_h$ and $e_k \subset \partial\Omega$, $P_h + 1 \leq k \leq M_h$. With each edge (or face) e_k , $1 \leq k \leq P_h$, we associate a unit outward normal vector n_k to E_i if $e_k = \partial E_i \cap \partial E_j$ and $i < j$. For $P_h + 1 \leq k \leq M_h$, we define $n_k = n$ the unit outward normal vector to $\partial\Omega$.

To present the discontinuous Galerkin scheme, we need some notations on edges, if $d = 2$, or faces if $d = 3$, between two elements. For $\phi \in H^s(\mathcal{E}_h)$, $s > \frac{1}{2}$ we define the following average function $\{\phi\}$ and the jump function $[\phi]$ such that

$$\begin{aligned} \{\phi\} &= \frac{1}{2}(\phi|_{E_i})|_{e_k} + \frac{1}{2}(\phi|_{E_j})|_{e_k}, \quad \forall x \in e_k, \quad 1 \leq k \leq P_h, \\ [\phi] &= (\phi|_{E_i})|_{e_k} - (\phi|_{E_j})|_{e_k}, \quad \forall x \in e_k, \quad 1 \leq k \leq P_h, \end{aligned}$$

where $e_k = \partial E_i \cap \partial E_j$, $i < j$.

We associate the following broken norms with the space $H^s(\mathcal{E}_h)$, $s \geq 1$

$$\begin{aligned} \|\phi\|_0^2 &= \sum_{i=1}^{N_h} \|\phi\|_{0,E_i}^2, \\ \|\phi\|_1^2 &= \sum_{i=1}^{N_h} (\|\phi\|_{1,E_i}^2 + h_i^2 \|\nabla^2 \phi\|_{0,E_i}^2) + J_\beta^\sigma(\phi, \phi), \end{aligned}$$

where

$$J_\beta^\sigma(\phi, \psi) = \sum_{k=1}^{P_h} \frac{\sigma_k}{|e_k|^\beta} \int_{e_k} [\phi][\psi] ds, \quad \beta > 0$$

is an interior penalty term and σ is a discrete positive function that takes the constant value σ_k on the edge e_k and is bounded below by $\sigma_0 > 0$ and above by $\sigma^* > 0$.

Let r be a positive integer. The finite element space used in this paper is taken to be

$$D_r(\mathcal{E}_h) = \{v \in L^2(\Omega) : v|_{E_j} \in P_r(E_j), \quad j = 1, 2, \dots, N_h\},$$

where $P_r(E_j)$ denotes the set of polynomials of degree less than or equal to r on E_j .

Now we state the following hp -approximation properties whose proofs can be found in [3, 4].

Lemma 3.1. *Let $E_j \in \mathcal{E}_h$ and $\phi \in H^s(E_j)$. Then there exist a positive constant C depending on s, γ , and ρ but independent of ϕ, r and h and a sequence $z_r^h \in P_r(E_j), r = 1, 2, \dots$ such that for any $0 \leq q \leq s$,*

$$\begin{aligned} \|\phi - z_r^h\|_{q,E_j} &\leq C \frac{h_j^{\mu-q}}{r^{s-q}} \|\phi\|_{s,E_j} \quad s \geq 0, \\ \|\phi - z_r^h\|_{0,e_j} &\leq C \frac{h_j^{\mu-\frac{1}{2}}}{r^{s-\frac{1}{2}}} \|\phi\|_{s,E_j} \quad s > \frac{1}{2}, \\ \|\phi - z_r^h\|_{1,e_j} &\leq C \frac{h_j^{\mu-\frac{3}{2}}}{r^{s-\frac{3}{2}}} \|\phi\|_{s,E_j} \quad s > \frac{3}{2}, \end{aligned}$$

where $\mu = \min(r + 1, s)$ and e_j is an edge or a face of E_j .

Lemma 3.2. *For each $E_j \in \mathcal{E}_h$, there exists a positive constant C depending only on γ and ρ such that the two following trace inequalities hold:*

$$\begin{aligned} \|\phi\|_{0,e_j}^2 &\leq C \left(\frac{1}{h_j} |\phi|_{0,E_j}^2 + h_j |\phi|_{1,E_j}^2 \right), \quad \forall \phi \in H^1(E_j), \\ \left\| \frac{\partial \phi}{\partial n_j} \right\|_{0,e_j}^2 &\leq C \left(\frac{1}{h_j} |\phi|_{1,E_j}^2 + h_j |\phi|_{2,E_j}^2 \right), \quad \forall \phi \in H^2(E_j), \end{aligned}$$

where e_j is an edge or a face of E_j and n_j is the unit outward normal vector to E_j .

Now we introduce the following bilinear mappings $A(\rho; \cdot, \cdot)$ and $B(\rho; \cdot, \cdot)$ defined on $H^s(\mathcal{E}_h) \times H^s(\mathcal{E}_h)$

$$\begin{aligned} A(\rho; \phi, \psi) &= (a(\rho) \nabla \phi, \nabla \psi) - \sum_{k=1}^{P_h} \int_{e_k} \{a(\rho) \nabla \phi \cdot n_k\} [\psi] - \sum_{k=1}^{P_h} \int_{e_k} \{a(\rho) \nabla \psi \cdot n_k\} [\phi] \\ &\quad + J_\beta^\sigma(\phi, \psi), \\ B(\rho; \phi, \psi) &= (b(\rho) \nabla \phi, \nabla \psi) - \sum_{k=1}^{P_h} \int_{e_k} \{b(\rho) \nabla \phi \cdot n_k\} [\psi] - \sum_{k=1}^{P_h} \int_{e_k} \{b(\rho) \nabla \psi \cdot n_k\} [\phi] \\ &\quad + J_\beta^\sigma(\phi, \psi). \end{aligned}$$

Using the bilinear mappings A and B , we construct the weak formulation of the problem (1.1) as follows

$$(3.1) \quad \begin{aligned} (u_t(t_{j\theta}), v) + A(u(t_{j\theta}); u(t_{j\theta}), v) + B(u(t_{j\theta}); u_t(t_{j\theta}), v) &= (f(u(t_{j\theta})), v), \\ \forall v \in H^s(\mathcal{E}_h). \end{aligned}$$

Now for $\lambda > 0$ we define the following bilinear forms $A_\lambda(\rho; \cdot, \cdot)$ and $B_\lambda(\rho; \cdot, \cdot)$ on $H^s(\mathcal{E}_h) \times H^s(\mathcal{E}_h)$ such that

$$\begin{aligned} A_\lambda(\rho; \phi, \psi) &= A(\rho; \phi, \psi) + \lambda(\phi, \psi), \\ B_\lambda(\rho; \phi, \psi) &= B(\rho; \phi, \psi) + \lambda(\phi, \psi). \end{aligned}$$

A_λ and B_λ satisfy the following boundedness and coercivity properties, respectively. The proofs can be found in [16, 17].

Lemma 3.3. *For $\lambda > 0$, there exists a constant $C > 0$ satisfying*

$$\begin{aligned} |A_\lambda(\rho; \phi, \psi)| &\leq C \|\phi\|_1 \|\psi\|_1, \\ |B_\lambda(\rho; \phi, \psi)| &\leq C \|\phi\|_1 \|\psi\|_1, \quad \forall \phi, \psi \in H^s(\mathcal{E}_h). \end{aligned}$$

Lemma 3.4. *For $\lambda > 0$, there exists a constant $\underline{c} > 0$ satisfying*

$$\begin{aligned} A_\lambda(\rho; \phi, \phi) &\geq \underline{c} \|\phi\|_1^2, \\ B_\lambda(\rho; \phi, \phi) &\geq \underline{c} \|\phi\|_1^2, \quad \forall \phi \in D_r(\mathcal{E}_h). \end{aligned}$$

Wheeler [21] introduced an elliptic projection to prove the optimal L^2 error estimates for Galerkin approximation to parabolic differential equations. Modifying this idea we define a differentiable map $\tilde{u}(t) : [0, T] \rightarrow D_r(\mathcal{E}_h)$ such that

$$(3.2) \quad A_\lambda(u; u - \tilde{u}, v) + B_\lambda(u; u_t - \tilde{u}_t, v) = 0, \quad \forall v \in D_r(\mathcal{E}_h).$$

By Lemma 3.3 and Lemma 3.4, $\tilde{u}(t)$ is well-defined.

4. The optimal $\ell^\infty(L^2)$ error estimates

For a positive integer $N > 0$, we let $\Delta t = \frac{T}{N}$ and $t_j = j(\Delta t)$, $0 \leq j \leq N$. For $0 \leq j \leq N$, we define $g_j = g(x, t_j)$ and for $0 \leq j \leq N - 1$, we define

$$\begin{aligned} \partial_t g_j &= \frac{g_{j+1} - g_j}{\Delta t}, \quad g_{j\theta} = \frac{1}{2}(1 + \theta)g_{j+1} + \frac{1}{2}(1 - \theta)g_j \quad \text{and} \\ t_{j\theta} &= \frac{1}{2}(1 + \theta)t_{j+1} + \frac{1}{2}(1 - \theta)t_j. \end{aligned}$$

Now we formulate a fully discrete discontinuous Galerkin approximation to (3.1) as follows: Find $\{U_n\}_{n=1}^N \subset D_r(\mathcal{E}_h)$ satisfying

$$(4.1) \quad \begin{aligned} (\partial_t U_j, v) + A(U_{j\theta}; U_{j\theta}, v) + B(U_{j\theta}; \partial_t U_j, v) &= (f(U_{j\theta}), v), \quad v \in D_r(\mathcal{E}_h) \\ (U_0, v) &= (u_0, v). \end{aligned}$$

In this section we prove the optimal convergence of $u(t_j) - U_j$ in L^2 space. To analyze the error in L^2 space, we denote $\eta(x, t) = u(x, t) - \tilde{u}(x, t)$ and $\xi(x, t_j) = \tilde{u}(x, t_j) - U_j(x)$, $j = 0, 1, \dots, N$.

Now we state the following approximations for η and η_t whose proofs can be found in [16, 17].

Theorem 4.1. *If $u_t \in L^2(H^s)$ and $u_0 \in H^s$, then there exists a constant C independent of h and Δt such that*

- (i) $\|\eta_t\|_0 + h\|\eta_t\|_1 \leq Ch^s(\|u_t\|_{L^2(H^s)} + \|u_0\|_s),$
- (ii) $\|\eta\|_0 + h\|\eta\|_1 \leq Ch^s(\|u_t\|_{L^2(H^s)} + \|u_0\|_s).$

Theorem 4.2. *If $u_t \in L^2(H^s)$, $u_{tt} \in H^s$, $u_{ttt} \in H^s$ and $u_0 \in H^s$, then there exists a constant C independent of h and Δt such that*

- (i) $\|\eta_{tt}\|_1 \leq Ch^{s-1}\{\|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{H^s} + \|u_0\|_s\},$
- (ii) $\|\eta_{ttt}\|_1 \leq Ch^{s-1}\{\|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{H^s} + \|u_{ttt}\|_{H^s} + \|u_0\|_s\}$

provided that $\beta \leq \frac{1}{d-1}$.

Proof. Differentiating the both sides of (3.2) with respect to t , we get

$$\begin{aligned}
 & \left(\left(\frac{d}{dt} a(u) \right) \nabla \eta, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} a(u) \right) \nabla \eta \cdot n_k \right\} [v] \\
 (4.2) \quad & - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} a(u) \right) \nabla v \cdot n_k \right\} [\eta] + A_\lambda(u; \eta_t, v) + \left(\left(\frac{d}{dt} b(u) \right) \nabla \eta_t, \nabla v \right) \\
 & - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla \eta_t \cdot n_k \right\} [v] - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla v \cdot n_k \right\} [\eta_t] \\
 & + B_\lambda(u; \eta_{tt}, v) = 0.
 \end{aligned}$$

Now we define the bilinear forms A_t and B_t as follows

$$\begin{aligned}
 A_t(u; \eta, v) &= \left(\left(\frac{d}{dt} a(u) \right) \nabla \eta, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} a(u) \right) \nabla \eta \cdot n_k \right\} [v] \\
 &\quad - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} a(u) \right) \nabla v \cdot n_k \right\} [\eta], \\
 B_t(u; \eta_t, v) &= \left(\left(\frac{d}{dt} b(u) \right) \nabla \eta_t, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla \eta_t \cdot n_k \right\} [v] \\
 &\quad - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla v \cdot n_k \right\} [\eta_t].
 \end{aligned}$$

From (4.2) and the definitions of A_t and B_t , we get

$$B_\lambda(u; \eta_{tt}, v) = -A_\lambda(u; \eta_t, v) - A_t(u; \eta, v) - B_t(u; \eta_t, v), \quad \forall v \in D_r(\mathcal{E}_h).$$

We let

$$\theta = P_h u - \tilde{u},$$

where $P_h u$ is the polynomial approximation of u satisfying the properties in Lemma 3.1. Then we have the following equalities

$$B_\lambda(u; \theta_{tt}, \theta_{tt}) = B_\lambda(u; u_{tt} + P_h u_{tt} - u_{tt} - \tilde{u}_{tt}, \theta_{tt})$$

$$\begin{aligned}
 &= B_\lambda(u; \eta_{tt}\theta_{tt}) - B_\lambda(u; u_{tt} - P_h u_{tt}, \theta_{tt}) \\
 &= -A_\lambda(u; \eta_t, \theta_{tt}) - A_t(u; \eta, \theta_{tt}) - B_t(u; \eta_t, \theta_{tt}) \\
 &\quad - B_\lambda(u; u_{tt} - P_h u_{tt}, \theta_{tt}).
 \end{aligned}$$

By Lemma 3.3 and Lemma 3.4 we obtain

$$\|\theta_{tt}\|_1 \leq C(\|\eta_t\|_1 + \|\eta\|_1 + \|u_{tt} - P_h u_{tt}\|_1),$$

which implies

$$\begin{aligned}
 (4.3) \quad \|\eta_{tt}\|_1 &\leq \|u_{tt} - P_h u_{tt}\|_1 + \|P_h u_{tt} - \tilde{u}_{tt}\|_1 \\
 &\leq \|u_{tt} - P_h u_{tt}\|_1 + C(\|\eta_t\|_1 + \|\eta\|_1 + \|u_{tt} - P_h u_{tt}\|_1).
 \end{aligned}$$

From Lemma 3.1 we have the following estimation

$$\begin{aligned}
 &\|u_{tt} - P_h u_{tt}\|_1^2 \\
 &= \sum_{i=1}^{N_h} \|u_{tt} - P_h u_{tt}\|_{1, E_i}^2 + \sum_{i=1}^{N_h} h_i^2 \|\nabla^2(u_{tt} - P_h u_{tt})\|_{0, E_i}^2 \\
 &\quad + J_\beta^\sigma(u_{tt} - P_h u_{tt}, u_{tt} - P_h u_{tt}) \\
 &\leq C\left(h^{2(s-1)}\|u_{tt}\|_s^2 + h^{-(d-1)\beta} \sum_{k=1}^{P_h} \|[u_{tt} - P_h u_{tt}]\|_{0, \epsilon_k}^2\right) \\
 &\leq C[h^{2(s-1)}\|u_{tt}\|_s^2 + h^{-(d-1)\beta-1}(h^{2s}\|u_{tt}\|_s^2)] \\
 &\leq Ch^{2(s-1)}\|u_{tt}\|_s^2.
 \end{aligned}$$

By applying the inequality above to (4.3) we obtain the following

$$\begin{aligned}
 \|\eta_{tt}\|_1^2 &\leq C(\|u_{tt} - P_h u_{tt}\|_1^2 + \|\eta\|_1^2 + \|\eta_t\|_1^2) \\
 &\leq Ch^{2(s-1)}(\|u_{tt}\|_{H^s}^2 + \|u_t\|_{L^2(H^s)}^2 + \|u_0\|_s^2),
 \end{aligned}$$

which implies

$$(4.4) \quad \|\eta_{tt}\|_1 \leq Ch^{s-1}(\|u_{tt}\|_{H^s} + \|u_t\|_{L^2(H^s)} + \|u_0\|_s).$$

Differentiating the both sides of (4.2) with respect to t , we get

$$\begin{aligned}
 (4.5) \quad &\left(\left(\frac{d^2}{dt^2}a(u)\right)\nabla\eta, \nabla v\right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{\left(\frac{d^2}{dt^2}a(u)\right)\nabla\eta \cdot n_k\right\}[v] \\
 &- \sum_{k=1}^{P_h} \int_{e_k} \left\{\left(\frac{d^2}{dt^2}a(u)\right)\nabla v \cdot n_k\right\}[\eta] + \left(\left(\frac{d}{dt}a(u)\right)\nabla\eta_t, \nabla v\right) \\
 &- \sum_{k=1}^{P_h} \int_{e_k} \left\{\left(\frac{d}{dt}a(u)\right)\nabla\eta_t \cdot n_k\right\}[v] - \sum_{k=1}^{P_h} \int_{e_k} \left\{\left(\frac{d}{dt}a(u)\right)\nabla v \cdot n_k\right\}[\eta_t]
 \end{aligned}$$

$$\begin{aligned}
 & + \left(\left(\frac{d}{dt} a(u) \right) \nabla \eta_t, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} a(u) \right) \nabla \eta_t \cdot n_k \right\} [v] \\
 & - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} a(u) \right) \nabla v \cdot n_k \right\} [\eta_t] + A_\lambda(u; \eta_{tt}, v) + \left(\left(\frac{d^2}{dt^2} b(u) \right) \nabla \eta_t, \nabla v \right) \\
 & - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d^2}{dt^2} b(u) \right) \nabla \eta_t \cdot n_k \right\} [v] - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d^2}{dt^2} b(u) \right) \nabla v \cdot n_k \right\} [\eta_t] \\
 & + \left(\left(\frac{d}{dt} b(u) \right) \nabla \eta_{tt}, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla \eta_{tt} \cdot n_k \right\} [v] \\
 & - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla v \cdot n_k \right\} [\eta_{tt}] + \left(\left(\frac{d}{dt} b(u) \right) \nabla \eta_{tt}, \nabla v \right) \\
 & - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla \eta_{tt} \cdot n_k \right\} [v] - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d}{dt} b(u) \right) \nabla v \cdot n_k \right\} [\eta_{tt}] \\
 & + B_\lambda(u; \eta_{ttt}, v) = 0.
 \end{aligned}$$

Now we define the bilinear mappings A_{tt} and B_{tt} as follows

$$\begin{aligned}
 A_{tt}(u; \eta, v) & = \left(\left(\frac{d^2}{dt^2} a(u) \right) \nabla \eta, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d^2}{dt^2} a(u) \right) \nabla \eta \cdot n_k \right\} [v] \\
 & \quad - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d^2}{dt^2} a(u) \right) \nabla v \cdot n_k \right\} [\eta], \\
 B_{tt}(u; \eta_t, v) & = \left(\left(\frac{d^2}{dt^2} b(u) \right) \nabla \eta_t, \nabla v \right) - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d^2}{dt^2} b(u) \right) \nabla \eta_t \cdot n_k \right\} [v] \\
 & \quad - \sum_{k=1}^{P_h} \int_{e_k} \left\{ \left(\frac{d^2}{dt^2} b(u) \right) \nabla v \cdot n_k \right\} [\eta_t].
 \end{aligned}$$

From (4.5) and the definitions of A_{tt} and B_{tt} , we get

$$\begin{aligned}
 (4.6) \quad B_\lambda(u; \eta_{ttt}, v) & = -A_\lambda(u; \eta_{ttt}, v) - A_{tt}(u; \eta, v) - 2A_t(u; \eta_t, v) \\
 & \quad - B_{tt}(u; \eta_t, v) - 2B_t(u; \eta_{tt}, v), \quad \forall v \in D_r(\mathcal{E}_h).
 \end{aligned}$$

By (4.6) we obtain

$$\begin{aligned}
 B_\lambda(u; \theta_{ttt}, \theta_{ttt}) & = B_\lambda(u; u_{ttt} + P_h u_{ttt} - u_{ttt} - \tilde{u}_{ttt}, \theta_{ttt}) \\
 & = B_\lambda(u; \eta_{ttt}, \theta_{ttt}) - B_\lambda(u; u_{ttt} - P_h u_{ttt}, \theta_{ttt}) \\
 & = -A_\lambda(u; \eta_{tt}, \theta_{ttt}) - A_{tt}(u; \eta, \theta_{ttt}) \\
 & \quad - 2A_t(u; \eta_t, \theta_{ttt}) - B_{tt}(u; \eta_t, \theta_{ttt}) \\
 & \quad - 2B_t(u; \eta_{tt}, \theta_{ttt}) - B_\lambda(u; u_{ttt} - P_h u_{ttt}, \theta_{ttt}).
 \end{aligned}$$

By Lemma 3.3, Lemma 3.4, (4.4) and Theorem 3.1, we obtain

$$\begin{aligned}\|\theta_{ttt}\|_1 &\leq C(\|u_{tt}\|_1 + \|\eta\|_1 + \|\eta_t\|_1 + \|u_{ttt} - P_h u_{ttt}\|_1) \\ &\leq Ch^{s-1}(\|u_{tt}\|_{H^s} + \|u_t\|_{L^2(H^s)} + \|u_0\|_s + \|u_{ttt}\|_{H^s}),\end{aligned}$$

which implies

$$\begin{aligned}\|\eta_{ttt}\|_1 &\leq \|u_{ttt} - P_h u_{ttt}\|_1 + \|P_h u_{ttt} - \tilde{u}_{ttt}\|_1 \\ &\leq Ch^{s-1}(\|u_{tt}\|_{H^s} + \|u_t\|_{L^2(H^s)} + \|u_0\|_s + \|u_{ttt}\|_{H^s}). \quad \square\end{aligned}$$

By simple computation, we obviously obtain the two following lemmas.

Lemma 4.1. *If $\rho_{j\theta}$ satisfies*

$$\partial_t \tilde{u}_j - \tilde{u}_t(t_{j\theta}) = (\Delta t)\rho_{j\theta},$$

then there exists a constant C independent of h and Δt such that

(i) *if $0 < \theta \leq 1$*

$$\begin{aligned}\|\rho_{j\theta}\|_0 &\leq C(\|u_0\|_s + \|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{L^\infty(H^s)}), \\ \|\rho_{j\theta}\|_1 &\leq C(\|u_0\|_s + \|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{L^\infty(H^s)}),\end{aligned}$$

(ii) *if $\theta = 0$*

$$\begin{aligned}\|\rho_{j\theta}\|_0 &\leq C\Delta t(\|u_0\|_s + \|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{L^\infty(H^s)} + \|u_{ttt}\|_{L^\infty(H^s)}), \\ \|\rho_{j\theta}\|_1 &\leq C\Delta t(\|u_0\|_s + \|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{L^\infty(H^s)} + \|u_{ttt}\|_{L^\infty(H^s)}).\end{aligned}$$

Lemma 4.2. *If we let $r_{j\theta} = \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}$, then there exists a constant C independent of h and Δt such that*

$$\begin{aligned}\|r_{j\theta}\|_0 &\leq C(\Delta t)^2(\|u_0\|_s + \|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{L^\infty(H^s)}), \\ \|r_{j\theta}\|_1 &\leq C(\Delta t)^2(\|u_0\|_s + \|u_t\|_{L^2(H^s)} + \|u_{tt}\|_{L^\infty(H^s)}).\end{aligned}$$

Theorem 4.3. *For sufficiently small $\lambda > 0$ and $\delta > 0$, if $u_t \in L^\infty(H^s)$ and $u_{tt} \in L^\infty(H^s)$, then there exists a constant $C > 0$ independent on h and Δt such that*

(i) *if $\theta \in (0, 1]$ and there exists a constant C_0 satisfying $h^{-\frac{d}{2}}\Delta t \leq C_0$, then*

$$\|u(t_j) - U_j\|_0 \leq C(h^\mu + \Delta t)(\|u_0\|_s + \|u_t\|_{L^\infty(H^s)} + \|\nabla u_t\|_{L^\infty} + \|u_{tt}\|_{L^\infty(H^1)}),$$

(ii) *if $\theta = 0$, then*

$$\begin{aligned}\|u(t_j) - U_j\|_0 &\leq C(h^\mu + \Delta t^2)(\|u_0\|_s + \|u_t\|_{L^\infty(H^s)} + \|\nabla u_t\|_{L^\infty} + \|u_{tt}\|_{L^\infty(H^1)} \\ &\quad + \|u_{ttt}\|_{L^\infty(H^1)})\end{aligned}$$

hold for $j = 1, 2, \dots, N$, where $s = \frac{d}{2} + 1 + \delta$ and $\mu = \min(r + 1, s)$.

Proof. From (3.1) and (4.1) we have

$$\begin{aligned}(4.7) \quad &(u_t(t_{j\theta}) - \partial_t U_j, v) + A_\lambda(u(t_{j\theta}); u(t_{j\theta}), v) - A_\lambda(U_{j\theta}; U_{j\theta}, v) \\ &+ B_\lambda(u(t_{j\theta}); u_t(t_{j\theta}), v) - B_\lambda(U_{j\theta}; \partial_t U_j, v) \\ &= (f(u(t_{j\theta})) - f(U_{j\theta}), v) + \lambda(u(t_{j\theta}) - U_{j\theta}, v) + \lambda(u_t(t_{j\theta}) - \partial_t U_j, v).\end{aligned}$$

From the definition of η and ξ , we have

$$(4.8) \quad \begin{aligned} u_t(t_{j\theta}) - \partial_t U_j &= \eta_t(t_{j\theta}) + \tilde{u}_t(t_{j\theta}) - \partial_t \tilde{u}_j + \partial_t \xi_j \\ &= \eta_t(t_{j\theta}) + \Delta t \rho_{j\theta} + \partial_t \xi_j. \end{aligned}$$

By the definition of η , we get

$$(4.9) \quad \begin{aligned} &A_\lambda(u(t_{j\theta}); u(t_{j\theta}), v) - A_\lambda(U_{j\theta}; U_{j\theta}, v) \\ &= A_\lambda(U_{j\theta}; \xi_{j\theta}, v) + A_\lambda(u(t_{j\theta}); u(t_{j\theta}), v) - A_\lambda(U_{j\theta}; \tilde{u}_{j\theta}, v) \\ &= A_\lambda(U_{j\theta}; \xi_{j\theta}, v) + A_\lambda(u(t_{j\theta}); \eta(t_{j\theta}), v) + A_\lambda(u(t_{j\theta}); \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}, v) \\ &\quad + A_\lambda(u(t_{j\theta}); \tilde{u}_{j\theta}, v) - A_\lambda(U_{j\theta}; \tilde{u}_{j\theta}, v). \end{aligned}$$

Form the definition of η , we have

$$(4.10) \quad \begin{aligned} &B_\lambda(u(t_{j\theta}); u_t(t_{j\theta}), v) - B_\lambda(U_{j\theta}; \partial_t U_j, v) \\ &= B_\lambda(U_{j\theta}; \partial_t \xi_j, v) + B_\lambda(u(t_{j\theta}); u_t(t_{j\theta}), v) - B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, v) \\ &= B_\lambda(U_{j\theta}; \partial_t \xi_j, v) + B_\lambda(u(t_{j\theta}); \eta_t(t_{j\theta}), v) \\ &\quad + B_\lambda(u(t_{j\theta}); \tilde{u}_t(t_{j\theta}) - \partial_t \tilde{u}_j, v) + B_\lambda(u(t_{j\theta}); \partial_t \tilde{u}_j, v) \\ &\quad - B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, v). \end{aligned}$$

Substituting (4.8)-(4.10) in (4.7) implies

$$\begin{aligned} &(\partial_t \xi_j, v) + A_\lambda(U_{j\theta}; \xi_{j\theta}, v) + B_\lambda(U_{j\theta}; \partial_t \xi_j, v) \\ &= -(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta}, v) - A_\lambda(u(t_{j\theta}); \eta(t_{j\theta}), v) - A_\lambda(u(t_{j\theta}); \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}, v) \\ &\quad - A_\lambda(u(t_{j\theta}); \tilde{u}_{j\theta}, v) + A_\lambda(U_{j\theta}; \tilde{u}_{j\theta}, v) - B_\lambda(u(t_{j\theta}); \eta_t(t_{j\theta}), v) \\ &\quad - B_\lambda(u(t_{j\theta}); \tilde{u}_t(t_{j\theta}) - \partial_t \tilde{u}_j, v) - B_\lambda(u(t_{j\theta}); \partial_t \tilde{u}_j, v) + B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, v) \\ &\quad + f(u(t_{j\theta}) - f(U_{j\theta}), v) + \lambda(u(t_{j\theta}) - U_{j\theta}, v) + \lambda(u_t(t_{j\theta}) - \partial_t U_j, v). \end{aligned}$$

By (3.2) and (4.8), we have

$$(4.11) \quad \begin{aligned} &(\partial_t \xi_j, v) + A_\lambda(U_{j\theta}; \xi_{j\theta}, v) + B_\lambda(U_{j\theta}; \partial_t \xi_j, v) \\ &= -(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta}, v) - A_\lambda(u(t_{j\theta}); \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}, v) \\ &\quad - A_\lambda(u(t_{j\theta}); \tilde{u}_{j\theta}, v) + A_\lambda(U_{j\theta}; \tilde{u}_{j\theta}, v) \\ &\quad - B_\lambda(u(t_{j\theta}); \tilde{u}_t(t_{j\theta}) - \partial_t \tilde{u}_j, v) - B_\lambda(u(t_{j\theta}); \partial_t \tilde{u}_j, v) \\ &\quad + B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, v) + (f(u(t_{j\theta})) - f(U_{j\theta}), v) \\ &\quad + \lambda(\eta(t_{j\theta}) + \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta} + \xi_{j\theta}, v) \\ &\quad + \lambda(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta} + \partial_t \xi_j, v). \end{aligned}$$

If we choose $v = \xi_{j\theta} + \partial_t \xi_j$ in (4.11), we get

$$(4.12) \quad \begin{aligned} &(\partial_t \xi_j, \xi_{j\theta} + \partial_t \xi_j) + A_\lambda(U_{j\theta}; \xi_{j\theta}, \xi_{j\theta}) + B_\lambda(U_{j\theta}; \partial_t \xi_j, \xi_{j\theta}) \\ &\quad + A_\lambda(U_{j\theta}; \xi_{j\theta}, \partial_t \xi_j) + B_\lambda(U_{j\theta}; \partial_t \xi_j, \partial_t \xi_j) \\ &= -(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) - A_\lambda(u(t_{j\theta}); \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\ &\quad - A_\lambda(u(t_{j\theta}); \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) + A_\lambda(U_{j\theta}; \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \end{aligned}$$

$$\begin{aligned}
& + B_\lambda(u(t_{j\theta}); \Delta t \rho_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) - B_\lambda(u(t_{j\theta}); \partial_t \tilde{u}_j, \xi_{j\theta} + \partial_t \xi_j) \\
& + B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, \xi_{j\theta} + \partial_t \xi_j) + (f(u(t_{j\theta})) - f(U_{j\theta}), \xi_{j\theta} + \partial_t \xi_j) \\
& + \lambda(\eta(t_{j\theta}) + \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta} + \xi_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& + \lambda(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta} + \partial_t \xi_j, \xi_{j\theta} + \partial_t \xi_j).
\end{aligned}$$

By Cauchy Schwarz's inequality, we obviously have

$$\begin{aligned}
(4.13) \quad (\xi_{j\theta}, \partial_t \xi_j) & = \left(\frac{1+\theta}{2} \xi_{j+1} + \frac{1-\theta}{2} \xi_j, \frac{\xi_{j+1} - \xi_j}{\Delta t} \right) \\
& \geq \frac{1}{2\Delta t} (\|\xi_{j+1}\|_0^2 - \|\xi_j\|_0^2).
\end{aligned}$$

By the definition of A_λ we obtain

$$\begin{aligned}
(4.14) \quad & A_\lambda(U_{j\theta}; \xi_{j\theta}, \partial_t \xi_j) \\
& = (a(U_{j\theta}) \nabla \xi_{j\theta}, \nabla(\partial_t \xi_j)) - \sum_{k=1}^{P_h} \int_{e_k} \{a(U_{j\theta}) \nabla \xi_{j\theta} \cdot n_k\} [\partial_t \xi_j] \\
& \quad - \sum_{k=1}^{P_h} \int_{e_k} \{a(U_{j\theta}) \nabla(\partial_t \xi_j) \cdot n_k\} [\xi_{j\theta}] + J_\beta^\sigma(\xi_{j\theta}, \partial_t \xi_j) + \lambda(\xi_{j\theta}, \partial_t \xi_j) \\
& \geq \frac{a_0}{2\Delta t} (\|\nabla \xi_{j+1}\|_0^2 - \|\nabla \xi_j\|_0^2) - \sum_{k=1}^{P_h} \int_{e_k} \{a(U_{j\theta}) \nabla \xi_{j\theta} \cdot n_k\} [\partial_t \xi_j] \\
& \quad - \sum_{k=1}^{P_h} \int_{e_k} \{a(U_{j\theta}) \nabla(\partial_t \xi_j) \cdot n_k\} [\xi_{j\theta}] + \frac{1}{2\Delta t} [J_\beta^\sigma(\xi_{j+1}, \xi_{j+1}) \\
& \quad - J_\beta^\sigma(\xi_j, \xi_j)] + \frac{\lambda}{2\Delta t} (\|\xi_{j+1}\|_0^2 - \|\xi_j\|_0^2).
\end{aligned}$$

From the definition of B_λ we get the following

$$\begin{aligned}
(4.15) \quad & B_\lambda(U_{j\theta}; \partial_t \xi_j, \xi_{j\theta}) \\
& = (b(U_{j\theta}) \nabla(\partial_t \xi_j), \nabla \xi_{j\theta}) - \sum_{k=1}^{P_h} \int_{e_k} \{b(U_{j\theta}) \nabla(\partial_t \xi_j) \cdot n_k\} [\xi_{j\theta}] \\
& \quad - \sum_{k=1}^{P_h} \int_{e_k} \{b(U_{j\theta}) \nabla \xi_{j\theta} \cdot n_k\} [\partial_t \xi_j] + J_\beta^\sigma(\partial_t \xi_j, \xi_{j\theta}) + \lambda(\partial_t \xi_j, \xi_{j\theta}) \\
& \geq \frac{a_0}{2\Delta t} (\|\nabla \xi_{j+1}\|_0^2 - \|\nabla \xi_j\|_0^2) - \sum_{k=1}^{P_h} \int_{e_k} \{b(U_{j\theta}) \nabla(\partial_t \xi_j) \cdot n_k\} [\xi_{j\theta}] \\
& \quad - \sum_{k=1}^{P_h} \int_{e_k} \{b(U_{j\theta}) \nabla \xi_{j\theta} \cdot n_k\} [\partial_t \xi_j] + \frac{1}{2\Delta t} (J_\beta^\sigma(\xi_{j+1}, \xi_{j+1}) \\
& \quad - J_\beta^\sigma(\xi_j, \xi_j)) + \frac{\lambda}{2\Delta t} (\|\xi_{j+1}\|_0^2 - \|\xi_j\|_0^2).
\end{aligned}$$

Applying (4.13)-(4.15) in (4.12) we have the following inequality

$$\begin{aligned}
& \frac{1}{2\Delta t} \left[(1+2\lambda)(\|\xi_{j+1}\|_0^2 - \|\xi_j\|_0^2) + 2(J_\beta^\sigma(\xi_{j+1}, \xi_{j+1}) - J_\beta^\sigma(\xi_j, \xi_j)) \right. \\
& \quad \left. + 2a_0(\|\nabla \xi_{j+1}\|_0^2 - \|\nabla \xi_j\|_0^2) \right] + \|\partial_t \xi_j\|_0^2 + c(\|\xi_{j\theta}\|_1^2 + \|\partial_t \xi_j\|_1^2) \\
(4.16) \quad & \leq -(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad - A_\lambda(u(t_{j\theta}); \tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad - A_\lambda(u(t_{j\theta}); \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) + A_\lambda(U_{j\theta}; \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad + B_\lambda(u(t_{j\theta}); \Delta t \rho_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad - B_\lambda(u(t_{j\theta}); \partial_t \tilde{u}_j, \xi_{j\theta} + \partial_t \xi_j) + B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad + (f(u(t_{j\theta})) - f(U_{j\theta}), \xi_{j\theta} + \partial_t \xi_j) \\
& \quad + \lambda(\eta(t_{j\theta}) + \xi_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad + \lambda(\tilde{u}(t_{j\theta}) - \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad + \lambda(\eta_t(t_{j\theta}) + \Delta t \rho_{j\theta} + \partial_t \xi_j, \xi_{j\theta} + \partial_t \xi_j) \\
& \quad + \sum_{k=1}^{P_h} \int_{e_k} \{(a(U_{j\theta}) + b(U_{j\theta})) \nabla \xi_{j\theta} \cdot n_k\} [\partial_t \xi_j] \\
& \quad + \sum_{k=1}^{P_h} \int_{e_k} \{(a(U_{j\theta}) + b(U_{j\theta})) \nabla (\partial_t \xi_j) \cdot n_k\} [\xi_{j\theta}] \\
& = \sum_{i=1}^{11} I_i.
\end{aligned}$$

For sufficiently small $\varepsilon > 0$ there exists a constant $C > 0$ such that

$$\begin{aligned}
|I_1| & \leq (\|\eta_t(t_{j\theta})\|_0 + \|\Delta t \rho_{j\theta}\|_0)(\|\xi_{j\theta}\|_0 + \|\partial_t \xi_j\|_0) \\
& \leq C \left(\|\eta_t(t_{j\theta})\|_0^2 + (\Delta t)^2 \|\rho_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 \right) + \varepsilon \|\partial_t \xi_j\|_0^2.
\end{aligned}$$

From Lemma 4.2 I_2 can be estimated as follows

$$|I_2| \leq C \|r_{j\theta}\|_1 \|\xi_{j\theta} + \partial_t \xi_j\|_1 \leq C(\Delta t)^4 + \varepsilon \|\xi_{j\theta}\|_1^2 + \varepsilon \|\partial_t \xi_j\|_1^2.$$

Now we can separate I_3 as follows

$$\begin{aligned}
I_3 & = A_\lambda(a(U_{j\theta}); \tilde{u}_{j\theta}; \xi_{j\theta} + \partial_t \xi_j) - A_\lambda(u(t_{j\theta}); \tilde{u}_{j\theta}, \xi_{j\theta} + \partial_t \xi_j) \\
& = \left((a(U_{j\theta}) - a(u(t_{j\theta}))) \nabla \tilde{u}_{j\theta}, \nabla (\xi_{j\theta} + \partial_t \xi_j) \right) \\
& \quad - \sum_{k=1}^{P_h} \int_{e_k} \{(a(U_{j\theta}) - a(u(t_{j\theta}))) \nabla \tilde{u}_{j\theta} \cdot n_k\} [\xi_{j\theta} + \partial_t \xi_j] \\
& \quad - \sum_{k=1}^{P_h} \int_{e_k} \{(a(U_{j\theta}) - a(u(t_{j\theta}))) \nabla (\xi_{j\theta} + \partial_t \xi_j) \cdot n_k\} [\tilde{u}_{j\theta}]
\end{aligned}$$

$$= \sum_{l=1}^3 I_{3l}.$$

Now we estimate I_{31} :

$$\begin{aligned} I_{31} &\leq C \|\nabla \tilde{u}_{j\theta}\|_{L^\infty} (\|\eta(t_{j\theta})\|_0 + \|r_{j\theta}\|_0 + \|\xi_{j\theta}\|_0) (\|\nabla \xi_{j\theta}\|_0 + \|\nabla(\partial_t \xi_j)\|_0) \\ &\leq C \left(\|\eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + \|\nabla \xi_{j\theta}\|_0^2 \right) + \varepsilon \|\partial_t \xi_j\|_1^2. \end{aligned}$$

We apply Lemma 3.2 to estimate I_{32} as follows

$$\begin{aligned} I_{32} &\leq \sum_{k=1}^{P_h} \|\nabla \tilde{u}_{j\theta}\|_{\infty, e_k} (\|\eta(t_{j\theta})\|_{0, e_k} + \|r_{j\theta}\|_{0, e_k} + \|\xi_{j\theta}\|_{0, e_k}) (\|\xi_{j\theta}\|_{0, e_k} \\ &\quad + \|\partial_t \xi_j\|_{0, e_k}) \\ &\leq C \sum_{i=1}^{N_h} \|\nabla \tilde{u}_{j\theta}\|_{\infty, E_i} \left(h_i^{-1/2} \|\eta(t_{j\theta})\|_{0, E_i} + h_i^{1/2} \|\nabla \eta(t_{j\theta})\|_{0, E_i} \right. \\ &\quad \left. + h^{-1/2} \|r_{j\theta}\|_{0, E_i} + h^{1/2} \|\nabla r_{j\theta}\|_{0, E_i} + h^{-1/2} \|\xi_{j\theta}\|_{0, E_i} \right) \\ &\quad \cdot h^{\frac{\beta(d-1)}{2}} \left(J(\xi_{j\theta}, \xi_{j\theta})^{1/2} + J(\partial_t \xi_j, \partial_t \xi_j)^{1/2} \right) \\ &\leq C \left(\|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + h^2 \|\nabla r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 \right) \\ &\quad + \varepsilon \|\xi_{j\theta}\|_1^2 + \varepsilon \|\partial_t \xi_j\|_1^2. \end{aligned}$$

From the approximation of η in Theorem 4.1

$$\begin{aligned} I_{33} &\leq C \sum_{k=1}^{P_h} \left(\|\nabla(\xi_{j\theta})\|_{\infty, e_k} + \|\nabla(\partial_t \xi_j)\|_{\infty, e_k} \right) \left(\|\eta(t_{j\theta})\|_{0, e_k} + \|r_{j\theta}\|_{0, e_k} \right. \\ &\quad \left. + \|\xi_{j\theta}\|_{0, e_k} \right) \|\eta_{j\theta}\|_{0, e_k} \\ &\leq C \sum_{i=1}^{N_h} \left(\|\nabla \xi_{j\theta}\|_{\infty, E_i} + \|\nabla(\partial_t \xi_j)\|_{\infty, E_i} \right) h^{-1/2} \left(\|\eta(t_{j\theta})\|_{0, E_i} + h \|\nabla \eta(t_{j\theta})\|_{0, E_i} \right. \\ &\quad \left. + \|r_{j\theta}\|_{0, E_i} + h \|\nabla r_{j\theta}\|_{0, E_i} + \|\xi_{j\theta}\|_{0, E_i} \right) h^{-1/2} \left(\|\eta(t_{j\theta})\|_{0, E_i} \right. \\ &\quad \left. + h \|\nabla \eta(t_{j\theta})\|_{0, E_i} \right) \\ &\leq C h^{-\frac{d}{2}-1} \sum_{i=1}^{N_h} \left(\|\nabla \xi_{j\theta}\|_{0, E_i} + \|\nabla(\partial_t \xi_j)\|_{0, E_i} \right) \left(\|\eta(t_{j\theta})\|_{0, E_i} + h \|\nabla \eta(t_{j\theta})\|_{0, E_i} \right. \\ &\quad \left. + \|r_{j\theta}\|_{0, E_i} + \|\xi_{j\theta}\|_{0, E_i} \right) \cdot h^{\frac{d}{2}+1} (\|u_t\|_{L^\infty(H^{\frac{d}{2}+1})} + \|u_0\|_{\frac{d}{2}+1}) \\ &\leq C \left(\|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + \|\nabla \xi_{j\theta}\|_0^2 \right) + \varepsilon \|\partial_t \xi_j\|_1^2. \end{aligned}$$

Therefore, we get

$$|I_3| \leq C \left(\|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + \|\nabla \xi_{j\theta}\|_0^2 \right) \\ + \varepsilon \|\xi_{j\theta}\|_1^2 + 3\varepsilon \|\partial_t \xi_j\|_1^2.$$

From the definition of I_4 , we obtain

$$|I_4| \leq C \|\Delta t \rho_{j\theta}\|_1 (\|\xi_{j\theta}\|_1 + \|\partial_t \xi_j\|_1) \\ \leq C (\Delta t)^2 \|\rho_{j\theta}\|_1^2 + \varepsilon \|\xi_{j\theta}\|_1^2 + \varepsilon \|\partial_t \xi_j\|_1^2.$$

From the definition of I_5 , we can separated I_5 as follows

$$I_5 = B_\lambda(U_{j\theta}; \partial_t \tilde{u}_j, \xi_{j\theta} + \partial_t \xi_j) - B_\lambda(u(t_{j\theta}); \partial_t \tilde{u}_j, \xi_{j\theta} + \partial_t \xi_j) \\ = \left((b(U_{j\theta}) - b(u(t_{j\theta}))) \nabla(\partial_t \tilde{u}_j), \nabla(\xi_{j\theta} + \partial_t \xi_j) \right) \\ - \sum_{k=1}^{P_h} \int_{e_k} \{ (b(U_{j\theta}) - b(u(t_{j\theta}))) \nabla(\partial_t \tilde{u}_j) \cdot n_k \} [\xi_{j\theta} + \partial_t \xi_j] \\ - \sum_{k=1}^{P_h} \int_{e_k} \{ (b(U_{j\theta}) - b(u(t_{j\theta}))) \nabla(\xi_{j\theta} + \partial_t \xi_j) \cdot n_k \} [\partial_t \tilde{u}_j] \\ = \sum_{j=1}^3 I_{5j}.$$

I_{51} is estimated in the following way

$$I_{51} \leq C \|\nabla(\partial_t \tilde{u}_j)\|_\infty \left(\|\eta(t_{j\theta})\|_0 + \|r_{j\theta}\|_0 + \|\xi_{j\theta}\|_0 \right) \left(\|\nabla \xi_{j\theta}\|_0 + \|\nabla(\partial_t \xi_j)\|_0 \right) \\ \leq C \left(\|\eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + \|\nabla \xi_{j\theta}\|_0^2 \right) + \varepsilon \|\partial_t \xi_j\|_1^2,$$

because

$$\|\nabla(\partial_t \tilde{u}_j)\|_{L^\infty} = \left\| \frac{\nabla \tilde{u}_{j+1} - \nabla \tilde{u}_j}{\Delta t} \right\|_{L^\infty} = \left\| \frac{1}{\Delta t} \int_{t_j}^{t_{j+1}} \nabla \tilde{u}_t(\tau) d\tau \right\|_{L^\infty} \\ \leq \|\nabla \tilde{u}_t\|_{L^\infty} \leq C \|\eta_t\|_{\frac{d}{2}+1+\delta} + \|\nabla u_t\|_{L^\infty} \leq C,$$

provided that $u_t \in L^\infty(H^{\frac{d}{2}+1+\delta})$ and $\nabla u_t \in L^\infty$.

Similarly, there exists $C > 0$ such that

$$I_{52} \leq C \sum_{k=1}^{P_h} \|\nabla(\partial_t \tilde{u}_j)\|_{\infty, e_k} \left(\|\eta(t_{j\theta})\|_{0, e_k} + \|r_{j\theta}\|_{0, e_k} + \|\xi_{j\theta}\|_{0, e_k} \right) \left(\|\xi_{j\theta}\|_{0, e_k} \right) \\ + \|\partial_t \xi_j\|_{0, e_k} \\ \leq C \sum_{i=1}^{N_h} \|\nabla(\partial_t \tilde{u}_j)\|_{\infty, E_i} h_i^{-1/2} \left(\|\eta(t_{j\theta})\|_{0, E_i} + h_i \|\nabla \eta(t_{j\theta})\|_{0, E_i} + \|r_{j\theta}\|_{0, E_i} \right)$$

$$\begin{aligned}
& + \|\xi_{j\theta}\|_{0,E_i} h_i^{\frac{\beta(d-1)}{2}} \left(J(\xi_{j\theta}, \xi_{j\theta})^{1/2} + J(\partial_t \xi_j, \partial_t \xi_j)^{1/2} \right) \\
& \leq C \left(\|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 \right) + \varepsilon \|\xi_{j\theta}\|_1^2 + \varepsilon \|\partial_t \xi_j\|_1^2.
\end{aligned}$$

By applying the trace inequality and Lemma 4.1, we have

$$\begin{aligned}
I_{53} & \leq C \sum_{k=1}^{P_h} \left(\|\nabla \xi_{j\theta}\|_{\infty, e_k} + \|\nabla(\partial_t \xi_j)\|_{\infty, e_k} \right) \left(\|\eta(t_{j\theta})\|_{0, e_k} + \|r_{j\theta}\|_{0, e_k} + \|\xi_{j\theta}\|_{0, e_k} \right) \\
& \quad \|\partial_t \tilde{u}_j - u_t(t_{j\theta})\|_{0, e_k} \\
& \leq C \sum_{i=1}^{N_h} h_i^{-\frac{d}{2}} \left(\|\nabla \xi_{j\theta}\|_{0, E_i} + \|\nabla(\partial_t \xi_j)\|_{0, E_i} \right) h_i^{-\frac{1}{2}} \left(\|\eta(t_{j\theta})\|_{0, E_i} + h \|\nabla \eta(t_{j\theta})\|_{0, E_i} \right. \\
& \quad \left. + \|r_{j\theta}\|_{0, E_i} + \|\xi_{j\theta}\|_{0, E_i} \right) \left[h_i^{-\frac{1}{2}} (\|\eta_t(t_{j\theta})\|_{0, E_i} + h \|\nabla \eta_t(t_{j\theta})\|_{0, E_i}) \right. \\
& \quad \left. + h_i^{\frac{\beta(d-1)}{2}} \Delta t \|\rho_{j\theta}\|_{1, E_i} \right].
\end{aligned}$$

Since

$$\|\eta_t(t_{j\theta})\|_{0, E_i} + h \|\nabla \eta_t(t_{j\theta})\|_{0, E_i} \leq Ch^{\frac{d}{2}+1} \|u_t\|_{L^\infty(H^{\frac{d}{2}+1})} \quad \text{and} \quad h^{-\frac{d}{2}} \Delta t \|\rho_{j\theta}\|_1 \leq C,$$

$$I_{53} \leq C \left(\|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 \right) + \varepsilon \|\xi_{j\theta}\|_1^2 + \varepsilon \|\partial_t \xi_{j\theta}\|_1^2.$$

From the estimations of I_{5i} , $1 \leq i \leq 3$, we have

$$\begin{aligned}
|I_5| & \leq C \left(\|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + \|\nabla \xi_{j\theta}\|_0^2 \right) \\
& \quad + 2\varepsilon \|\xi_{j\theta}\|_1^2 + 3\varepsilon \|\partial_t \xi_j\|_1^2.
\end{aligned}$$

We obtain the following estimates of I_i for each $6 \leq i \leq 11$.

$$\begin{aligned}
|I_6| & \leq C (\|\eta(t_{j\theta})\|_0 + \|\xi_{j\theta}\|_0 + \|r_{j\theta}\|_0) (\|\xi_{j\theta}\|_0 + \|\partial_t \xi_j\|_0) \\
& \leq C \left(\|\eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 \right) + \varepsilon \|\partial_t \xi_j\|_0^2, \\
|I_7| & \leq C \left(\|\eta(t_{j\theta})\|_0^2 + \|\xi_{j\theta}\|_0^2 \right) + \varepsilon \|\partial_t \xi_j\|_0^2, \\
|I_8| & \leq C \|r_{j\theta}\|_0 (\|\xi_{j\theta}\|_0 + \|\partial_t \xi_j\|_0) \leq C \|r_{j\theta}\|_0^2 + \varepsilon \|\xi_{j\theta}\|_0^2 + \varepsilon \|\partial_t \xi_j\|_0^2, \\
|I_9| & \leq \lambda (\|\eta_t(t_{j\theta})\|_0 + \|\Delta t \rho_{j\theta}\|_0 + \|\partial_t \xi_j\|_0) (\|\xi_{j\theta}\|_0 + \|\partial_t \xi_j\|_0) \\
& \leq \lambda \left(\|\eta_t(t_{j\theta})\|_0^2 + (\Delta t)^2 \|\rho_{j\theta}\|_0^2 + \frac{3}{2} \|\xi_{j\theta}\|_0^2 \right) + \frac{5}{2} \lambda \|\partial_t \xi_j\|_0^2, \\
|I_{10}| & = \sum_{k=1}^{P_h} \int_{e_k} \{ (a(U_{j\theta}) + b(U_{j\theta})) \nabla \xi_{j\theta} \cdot n_k \} [\partial_t \xi_j] \leq C \|\nabla \xi_{j\theta}\|_0^2 + \varepsilon \|\partial_t \xi_j\|_1^2, \\
|I_{11}| & \leq C J(\xi_{j\theta}, \xi_{j\theta}) + \varepsilon \|\partial_t \xi_j\|_1^2 \leq C (J(\xi_{j+1}, \xi_{j+1}) + J(\xi_j, \xi_j)) + \varepsilon \|\partial_t \xi_j\|_1^2.
\end{aligned}$$

Substituting the estimates of I_i ($1 \leq i \leq 11$) into (4.16), we get

$$(4.17) \quad \frac{1}{2\Delta t} \left[(1 + 2\lambda) (\|\xi_{j+1}\|_0^2 - \|\xi_j\|_0^2) + 2(J_\beta^\sigma(\xi_{j+1}, \xi_{j+1}) - J_\beta^\sigma(\xi_j, \xi_j)) \right]$$

$$\begin{aligned}
& + 2a_0(\|\nabla\xi_{j+1}\|_0^2 - \|\nabla\xi_j\|_0^2) + \frac{1}{2}\|\partial_t\xi_j\|_0^2 + \frac{c}{2}\|\xi_{j\theta}\|_1^2 + \frac{c}{2}\|\partial_t\xi_j\|_1^2 \\
\leq & C\left[\|\eta_t(t_{j\theta})\|_0^2 + (\Delta t)^2\|\rho_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + (\Delta t)^4 + \|\eta(t_{j\theta})\|_0^2\right. \\
& + h^2\|\nabla\eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\nabla\xi_{j\theta}\|_0^2 + (\Delta t)^2\|\rho_{j\theta}\|_1^2 \\
& \left. + J_\beta^\sigma(\xi_{j+1}, \xi_{j+1}) + J_\beta^\sigma(\xi_j, \xi_j)\right].
\end{aligned}$$

If we sum both sides of (4.17) from $j = 0$ to $N - 1$, then we obtain

$$\begin{aligned}
& \|\xi_N\|_0^2 - \|\xi_0\|_0^2 + \frac{2}{3}J(\xi_N, \xi_N) - 2J(\xi_0, \xi_0) + a_0\Delta t\left(\frac{4}{3}\|\nabla\xi_N\|_0^2 - 4\|\nabla\xi_0\|_0^2\right) \\
& + \frac{2}{3}\Delta t\sum_{j=0}^{N-1}\left(\|\partial_t\xi_j\|_0^2 + c\|\xi_{j\theta}\|_1^2 + c\|\partial_t\xi_j\|_1^2\right) \\
\leq & C(\Delta t)\sum_{j=0}^{N-1}\left(\|\eta_t(t_{j\theta})\|_0^2 + (\Delta t)^2\|\rho_{j\theta}\|_0^2 + \|\xi_{j\theta}\|_0^2 + (\Delta t)^4 + \|\eta(t_{j\theta})\|_0^2\right. \\
& \left. + h^2\|\nabla\eta(t_{j\theta})\|_0^2 + \|r_{j\theta}\|_0^2 + \|\nabla\xi_{j\theta}\|_0^2 + J_\beta^\sigma(\xi_j, \xi_j) + J_\beta^\sigma(\xi_{j+1}, \xi_{j+1})\right),
\end{aligned}$$

which implies

$$\begin{aligned}
& \|\xi_N\|_0^2 + \frac{2}{3}J(\xi_N, \xi_N) + \frac{4}{3}a_0\Delta t\|\nabla\xi_N\|_0^2 + \frac{2c}{3}\Delta t\sum_{j=0}^{N-1}\left(\|\partial_t\xi_j\|_0^2 + \|\xi_{j\theta}\|_1^2 + \|\partial_t\xi_j\|_1^2\right) \\
\leq & \left(\|\xi_0\|_0^2 + 2a_0J(\xi_0, \xi_0) + 4a_0\Delta t\|\nabla\xi_0\|_0^2\right) \\
& + C(\Delta t)\sum_{j=0}^{N-1}\left(\|\eta_t(t_{j\theta})\|_0^2 + (\Delta t)^2\|\rho_{j\theta}\|_0^2 + \|\eta(t_{j\theta})\|_0^2 + h^2\|\nabla\eta(t_{j\theta})\|_0^2\right) \\
& + C\Delta t\sum_{j=0}^N\left(\|\nabla\xi_j\|_0^2 + (\Delta t)^4 + \|r_j\|_0^2\right) \\
& + C(\Delta t)\sum_{j=0}^{N-1}\left(\|\nabla\xi_{j\theta}\|_0^2 + J_\beta^\sigma(\xi_j, \xi_j) + J_\beta^\sigma(\xi_{j+1}, \xi_{j+1})\right),
\end{aligned}$$

where Δt is sufficiently small.

By the discrete version of Gronwall's lemma, we get

$$\begin{aligned}
& \|\xi_N\|_0^2 + J(\xi_N, \xi_N) + \Delta t\|\nabla\xi_N\|_0^2 + \Delta t\sum_{j=0}^{N-1}\left(\|\partial_t\xi_j\|_0^2 + \|\xi_{j\theta}\|_1^2 + \|\partial_t\xi_j\|_1^2\right) \\
\leq & C\left\{\|\xi_0\|_0^2 + J(\xi_0, \xi_0) + \Delta t\|\nabla\xi_0\|_0^2 + \Delta t\sum_{j=0}^{N-1}\left(\|\eta_t(t_{j\theta})\|_0^2 + (\Delta t)^2\|\rho_{j\theta}\|_0^2\right)\right.
\end{aligned}$$

$$+ \|\eta(t_{j\theta})\|_0^2 + h^2 \|\nabla \eta(t_{j\theta})\|_0^2 \Big) + \Delta t \sum_{j=0}^N \left((\Delta t)^4 + \|r_j\|_0^2 \right) \Big\}.$$

Now we choose an appropriate initial approximation $U_0(x)$ for example $U_0(x) = \tilde{u}(x, 0)$, to get

$$\begin{aligned} & \|\xi_N\|_0^2 + J(\xi_N, \xi_N) + \|\nabla \xi_N\|_0^2 + \Delta t \sum_{j=0}^{N-1} (\|\partial_t \xi_j\|_0^2 + \|\xi_{j\theta}\|_1^2 + \|\partial_t \xi_j\|_1^2) \\ & \leq C(\Delta t) h^{2\mu} \sum_{j=0}^{N-1} (\|u_0\|_s^2 + \|u_t\|_{L^2(H^s)}^2 + (\Delta t)^2 \|\rho_{j\theta}\|_0^2) + C(\Delta t) \sum_{j=0}^N [(\Delta t)^4 + \|r_j\|_0^2], \end{aligned}$$

where $\mu = \min(r + 1, s)$.

If $\theta \in (0, 1]$,

$$\begin{aligned} & \|\xi_N\|_0^2 + J(\xi_N, \xi_N) + \|\nabla \xi_N\|_0^2 + \Delta t \sum_{j=0}^{N-1} (\|\partial_t \xi_j\|_0^2 + \|\xi_{j\theta}\|_1^2 + \|\partial_t \xi_j\|_1^2) \\ & \leq C(\Delta t) h^{2\mu} \left(\sum_{j=0}^N (\|u_0\|_s^2 + \|u_t\|_{L^2(H^s)}^2 + \|u_{tt}\|_{L^\infty((t_j, t_{j+1}); L_2)}) \right) \\ & \quad + C(\Delta t)^2 \|u_{tt}\|_{L^\infty(H^2)}. \end{aligned}$$

If $\theta = 0$,

$$\begin{aligned} & \|\xi_N\|_0^2 + J(\xi_N, \xi_N) + \|\nabla \xi_N\|_0^2 + \Delta t \sum_{j=0}^{N-1} (\|\partial_t \xi_j\|_0^2 + \|\xi_{j\theta}\|_1^2 + \|\partial_t \xi_j\|_1^2) \\ & \leq C(\Delta t) \left[h^{2\mu} \sum_{j=0}^N (\|u_0\|_s^2 + \|u_t\|_{L^2(H^s)}^2 + (\Delta t)^4 \|u_{ttt}\|_{L^\infty((t_j, t_{j+1}); L_2)}) \right. \\ & \quad \left. + (\Delta t)^4 \|u_{tt}\|_{L^\infty(t_j, t_{j+1}; H^2)}^2 \right]. \end{aligned}$$

Therefore if $\theta \in (0, 1]$ we have

$$\|e\|_{\ell^\infty(L^2)} \leq C(h^\mu + \Delta t) (\|u_0\|_s + \|u_t\|_{L^\infty(H^s)} + \|\nabla u_t\|_{L^\infty} + \|u_{tt}\|_{L^\infty(H^1)})$$

and if $\theta = 0$,

$$\begin{aligned} \|e\|_{\ell^\infty(L^2)} & \leq C(h^\mu + (\Delta t)^2) (\|u_0\|_s + \|u_t\|_{L^\infty(H^s)} + \|\nabla u_t\|_{L^\infty} + \|u_{tt}\|_{L^\infty(H^1)} \\ & \quad + \|u_{ttt}\|_{L^\infty(H^1)}). \end{aligned}$$

□

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