



Lattice-Based Threshold-Changeability for Standard Shamir Secret-Sharing Schemes

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Overview

- (t,n) -Threshold Secret Sharing Schemes
 - Classical Shamir Scheme
- Changeable-Threshold Secret-Sharing Schemes
 - Drawbacks of previous solutions
- Our Approach: Lattice-Based Threshold-Changeability for Classical Shamir Scheme
 - Brief Review of Point Lattices
 - Method for increasing the threshold from t to $t' > t$
 - Lattice-based Decoding Algorithm & Correctness Analysis
 - Lattice-based Information-Theoretic Security Analysis



(t,n)-Threshold Secret Sharing

- Fundamental cryptographic scheme (Shamir, 1979)
 - Informal Definition:
 - A Dealer owning a secret s wishes to “distribute” knowledge of s among a group of n shareholders such that two conditions hold:
 - Correctness: Any subset of t shareholders can together recover s
 - Security: Any subset of less than t shareholders cannot recover s
 - Many applications in information security – especially for achieving robustness of distributed security systems:
 - Consider an access control system with n servers
 - System is called t-robust if security is maintained even against attackers who succeed in breaking into up to $t-1$ servers
 - Can be achieved by distributing the access control secret among the n servers using a (t,n)-threshold secret sharing scheme.



(t,n)-Threshold Secret-Sharing

Definition 1 (Threshold Scheme) A (t, n) -threshold secret-sharing scheme $TSS = (GC, D, C)$ consists of three efficient algorithms:

1 *GC (Public Parameter Generation):* Takes as input a security parameter $k \in \mathcal{N}$ and returns a string $x \in \mathcal{X}$ of public parameters.

2 *D (Dealer Setup):* Takes as input $(k, x) \in \mathcal{N} \times \mathcal{X}$ and a secret $s \in \mathcal{S}(k, x) \subseteq \{0, 1\}^{k+1}$ and returns n shares $\mathbf{s} = (s_1, \dots, s_n)$, where $s_i \in \mathcal{S}_i(k, x)$ for $i = 1, \dots, n$. We denote by

$$D_{k,x}(\cdot, \cdot) : \mathcal{S}(k, x) \times \mathcal{R}(k, x) \rightarrow \mathcal{S}_1(k, x) \times \dots \times \mathcal{S}_n(k, x)$$

the mapping induced by algorithm D (here $\mathcal{R}(k, x)$ denotes the space of random inputs to D).

3 *C (Share Combiner):* Takes as input $(k, x) \in \mathcal{N} \times \mathcal{X}$ and any subset $\mathbf{s}_I = (s_i : i \in I)$ of t shares, and returns a recovered secret $s \in \mathcal{S}(k, x)$. (here $I \subseteq [n]$ is a subset of size $\#I = t$).



(t,n)-Threshold Secret-Sharing

■ Classical Shamir Scheme (Shamir '79)

1. $GC(k)$ (Public Parameter Generation):

- (a) Pick a (not necessarily random) prime $p \in [2^k, 2^{k+1}]$ with $p > n$.
- (b) Pick uniformly at random n distinct non-zero elements $\alpha = (\alpha_1, \dots, \alpha_n) \in D((\mathbf{Z}_p^*)^n)$. Return $x = (p, \alpha)$.

2. $D_{k,x}(s, \mathbf{a})$ (Dealer Setup): To share secret $s \in \mathbf{Z}_p$ using $t-1$ uniformly random elements $\mathbf{a} = (a_1, \dots, a_{t-1}) \in \mathbf{Z}_p^{t-1}$, build the polynomial

$$a_{s,\mathbf{a}}(x) = s + a_1x + a_2x^2 + \dots + a_{t-1}x^{t-1} \in \mathbf{Z}_p[x; t-1].$$

The i th share is $s_i = a(\alpha_i) \bmod p$ for $i = 1, \dots, n$.

3. $C_{k,x}(s_I)$ (Share Combiner): To combine shares $s_I = (s_i : i \in I)$ for some $I \subseteq [n]$ with $\#I = t$, compute by Lagrange interpolation the unique polynomial $b \in \mathbf{Z}_p[x; t-1]$ such that $b(\alpha_i) \equiv s_i \pmod{p}$ for all $i \in I$. The recovered secret is $s = b(0) \bmod p$.



Changeable-Threshold Secret-Sharing

- Motivation:
 - In applications, choice of the threshold parameter t is a compromise between two conflicting factors:
 - Value of Protected System & Attacker Resources
 - → Pushing the threshold as high as possible
 - User Convenience and Cost
 - → Pushing the threshold as low as possible
 - Hence actual value of t will be an “equilibrium” value, which will change in time as the relative strength of the above conflicting factors change in time
- This motivates study of Changeable-Threshold Secret-Sharing schemes



Changeable-Threshold Secret-Sharing

- Drawbacks of previous solutions are at least one of:
 - Dealer Involvement after setup phase [eg. Blundo'93]
 - Dealer broadcasts a message to all shareholders to allow them to update their shares from a (t,n) to a (t',n) scheme
 - Implication: Dealer must communicate after setup!
 - Initial (t,n) -threshold scheme is non-standard [eg. Martin'99]
 - Simple example: Dealer gives each shareholder two shares of the secret, one for a (t,n) scheme, another for a (t',n) scheme
 - Implication: Dealer must plan ahead!
 - Shareholders privately communicate with each other [eg. Desmedt'97]
 - E.g. Shareholders re-distribute secret among themselves for a (t',n) scheme via secure computation protocol
 - Implication: Shareholders must communicate!
- Our scheme does not have any of these drawbacks!
 - Although we only achieve relaxed correctness/security

Changeable-Threshold Secret-Sharing

- Basic idea of our approach

- To increase threshold from t to $t' > t$,

- Each Shareholder adds a random 'noise' integer (of appropriate size) to his share, to obtain a subshare

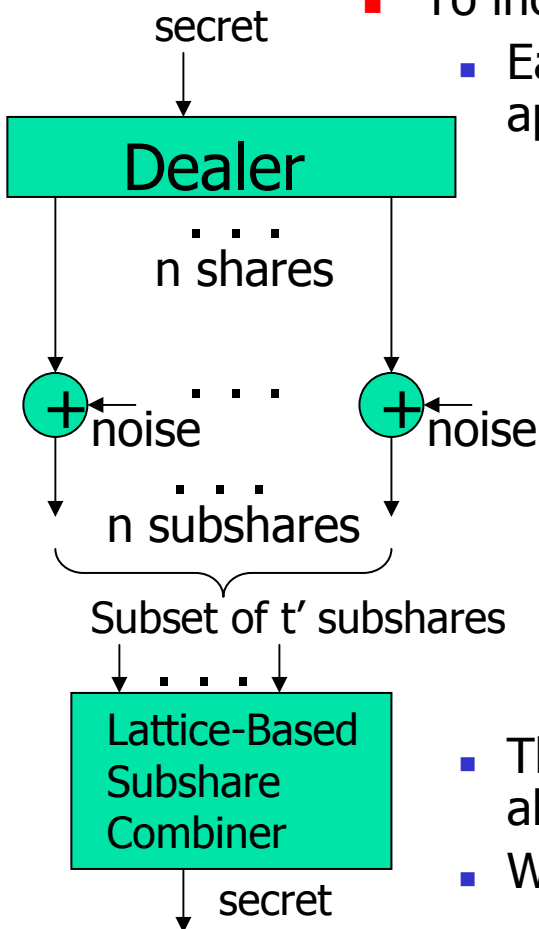
- Subshares contain only partial information on original shares

- We expect that:

- Any t subshares are not sufficient to recover secret
 - But t' subshares (for some $t' > t$ depending on size of noise added) are sufficient to recover secret if we have an appropriate 'error-correction algorithm'
 - (e.g if noise bit-length = $\frac{1}{2}$ of share length, we expect that $t' \sim 2t$ subshares uniquely determine the secret)

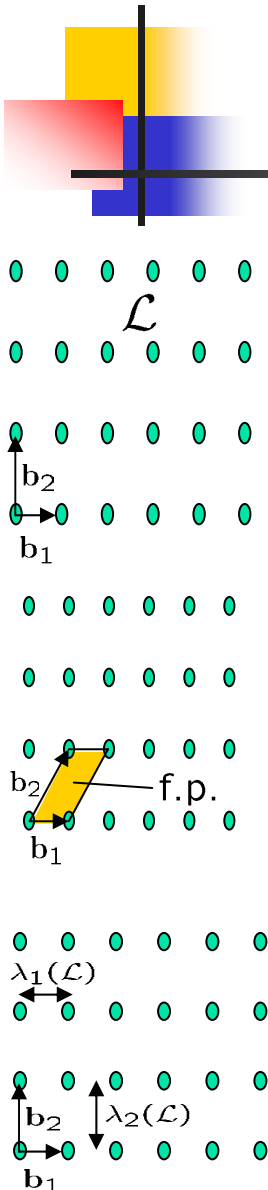
- The new 'subshare combiner' algorithm is the error correction algorithm

- We construct this algorithm using lattice basis reduction! 8



Point Lattices (Brief Intro)

- Definition (Lattice): Given a basis of n linearly-independent vectors $\mathbf{b}_1, \dots, \mathbf{b}_n$ in vector space \mathbb{R}^n , we call the set \mathcal{L} of all integer linear combinations of these vectors a lattice of dimension n
- A basis matrix B of lattice \mathcal{L} is an $n \times n$ matrix listing basis vectors in rows
- The determinant $\det(\mathcal{L})$ of lattice \mathcal{L} is $|\det(B)|$ where B is any basis matrix for \mathcal{L} .
 - Geometrically, $\det(\mathcal{L})$ is equal to the volume of any fundamental parallelepiped (f.p.) of \mathcal{L} .
- We use infinity-norm $\|\cdot\|_\infty$ (max. abs. value of coordinates) to measure "length" of lattice vectors
- Define "Minkowski Minima" $\lambda_1(\mathcal{L}), \dots, \lambda_n(\mathcal{L})$ of lattice \mathcal{L} :
 - $\lambda_1(\mathcal{L})$ = shortest infinity-norm over all non-zero vectors of \mathcal{L}
 - $\lambda_i(\mathcal{L})$ = shortest infinity-norm bound over all i linearly-independent vectors of \mathcal{L}



Point Lattices (Brief Intro)

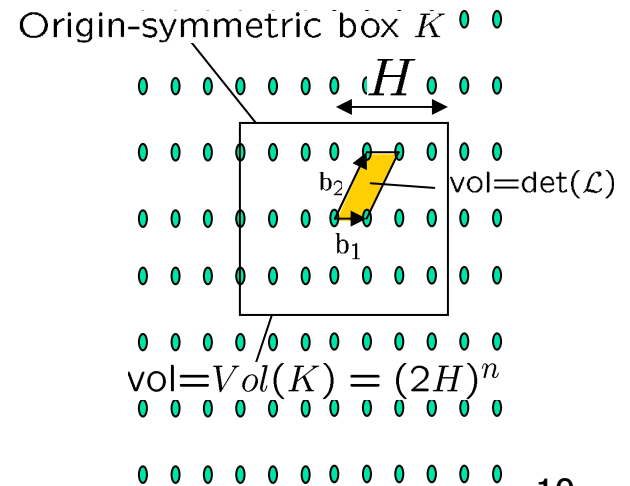
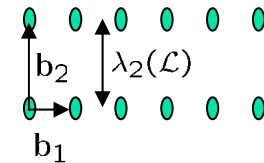
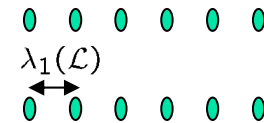
Theorem 1 (Minkowski's First Theorem) Let \mathcal{L} be a lattice in \mathbb{R}^n . Then

$$\lambda_1(\mathcal{L}) \leq \det(\mathcal{L})^{\frac{1}{n}}.$$

Theorem 2 (Minkowski's Second Theorem) Let \mathcal{L} be a lattice in \mathbb{R}^n . Then

$$(\lambda_1(\mathcal{L}) \cdots \lambda_n(\mathcal{L}))^{1/n} \leq 2 \det(\mathcal{L})^{1/n}.$$

Theorem. [Blichfeldt-Corput] Let \mathcal{L} be a lattice in \mathbb{R}^n and let K denote the origin-centered box $\{\mathbf{v} \in \mathbb{R}^n : \|\mathbf{v}\|_\infty < H\}$ of volume $\text{Vol}(K) = (2H)^n$. Then the number of points of the lattice \mathcal{L} contained in the box K is at least $2 \cdot \text{Int}\left(\frac{\text{Vol}(K)}{2^n \det(\mathcal{L})}\right) + 1$, where for any $z \in \mathbb{R}$, $\text{Int}(z)$ denotes the largest integer which is strictly less than z .

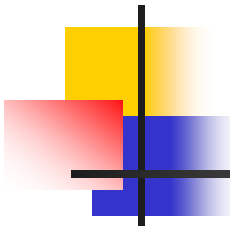




Point Lattices (Brief Intro)

- **The Closest Vector Problem (CVP)**
Given a basis for a lattice \mathcal{L} in \mathbb{Q}^n , and a “target” vector $\mathbf{t} \in \mathbb{Q}^n$, find a closest lattice vector $\mathbf{v} \in \mathcal{L}$ (i.e. $\|\mathbf{v} - \mathbf{t}\|_\infty = \min_{\mathbf{u} \in \mathcal{L}} \|\mathbf{u} - \mathbf{t}\|_\infty$).
- Exact (and near-exact) version of CVP is hard to solve efficiently in theory (NP-hard)
- But efficient Approximate-CVP algorithms exist
An algorithm is called a *CVP approximation algorithm* with $\|\cdot\|_\infty$ -approximation factor γ_{CVP} if it is guaranteed to find a lattice vector \mathbf{v} such that $\|\mathbf{v} - \mathbf{t}\|_\infty \leq \gamma_{CVP} \cdot \min_{\mathbf{u} \in \mathcal{L}} \|\mathbf{u} - \mathbf{t}\|_\infty$.
- First polynomial-time algorithm [Babai '86] suffices for us:

$$\gamma_{Bab} = n^{1/2} 2^{n/2}$$



Threshold-Changeability for Classical Shamir Scheme - Algorithms

- Increasing the threshold from t to $t' > t$

We use an efficient CVP approx. algorithm A_{CVP} with approx. factor γ_{CVP} . Let $\Gamma_{CVP} = \log(\lceil \gamma_{CVP} + 1 \rceil)$ ($= O(t' + t)$ for Babai).

$H_i(s_i)$ (i th Subshare Generation): To transform share $s_i \in \mathbf{Z}_p$ of original (t, n) -threshold scheme into subshare $t_i \in \mathbf{Z}_p$ of desired (t', n) -threshold scheme ($t' > t$) the i th shareholder does the following (for all $i = 1, \dots, n$):

- 1 Determine noise bound H for δ_c -correctness

- (a) Set $H = \max(\lfloor p^\alpha / 2 \rfloor, 1)$ with

- (b) $\alpha = 1 - \frac{1 + \delta_F}{(t'/t)} > 0$ (noise bitlength fraction)

- (c) $\delta_F = \frac{(t'/t)}{k} \left(\log(\delta_c^{-1/t'} nt) + \Gamma_{CVP} + 1 \right)$.

- 2 Compute $t_i = \alpha_i \cdot s_i + r_i \bmod p$ for a uniformly random integer r_i with $|r_i| < H$.

Threshold-Changeability for Classical Shamir Scheme - Algorithms

- Noisy subshares decoding algorithm (subshare combiner)

$C'_{k,x}(t_I)$ (Subshare Combiner): To combine subshares $t_I = (t_i : i \in I)$ for some $I = \{i[1], \dots, i[t']\}$ with $\#I = t'$ (for δ_c -correctness):

- Build the following $(t'+t) \times (t'+t)$ matrix $M_{Sha}(\alpha_I, H, p)$, whose rows form a basis for a full-rank lattice $\mathcal{L}_{Sha}(\alpha_I, H, p)$ in $\mathbb{Q}^{t'+t}$:

$$M_{Sha}(\alpha_I, H, p) = \begin{pmatrix} p & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & p & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & p & 0 & 0 & \dots & 0 \\ \alpha_{i[1]} & \alpha_{i[2]} & \dots & \alpha_{i[t']} & H/p & 0 & \dots & 0 \\ \alpha_{i[1]}^2 & \alpha_{i[2]}^2 & \dots & \alpha_{i[t']}^2 & 0 & H/p & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \alpha_{i[1]}^t & \alpha_{i[2]}^t & \dots & \alpha_{i[t']}^t & 0 & 0 & \dots & H/p \end{pmatrix}.$$

Here $H = \lfloor p^\alpha/2 \rfloor$, $\alpha = 1 - \frac{1+\delta_c}{(t'/t)}$, $\delta_F = \frac{(t'/t)}{k} \left(\log(\delta_c^{-1/t'} nt) + \Gamma_{CVP} + 1 \right)$.

- Define $\mathbf{t}' = (t_{i[1]}, \dots, t_{i[t']}, 0, 0, \dots, 0) \in \mathbf{Z}^{t'+t}$.
- Run CVP Approx. alg. A_{CVP} on lattice $\mathcal{L}_{Sha}(\alpha_I, H, p)$ with target vector \mathbf{t}' . Let $\mathbf{c} = (c_1, \dots, c_{t'}, c_{t'+1}, \dots, c_{t'+t}) \in \mathbb{Q}^{t'+t}$ denote the output vector returned by A_{CVP} .
- Compute recovered secret $\hat{s} = (p/H) \cdot c_{t'+1} \bmod p$.

Threshold-Changeability for Classical Shamir Scheme - Correctness

- Decoding algorithm correctness analysis (Main ideas):

- By construction, the dealer's secret polynomial

$$a(x) = s + a_1x + \dots + a_{t-1}x^{t-1}$$

- gives rise to a lattice vector

$$a' = (\alpha_{i[1]}a(\alpha_{i[1]}) - k_1p, \dots, \alpha_{i[t']}a(\alpha_{i[t']}) - k_{t'}p, \frac{s}{p}H, \frac{a_1}{p}H, \dots, \frac{a_{t-1}}{p}H)$$

- which is "close" to the target vector

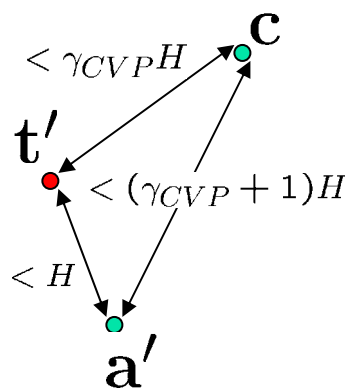
$$t' = (\alpha_{i[1]}a(\alpha_{i[1]}) - k_1p + r_{i[1]}, \dots, \alpha_{i[t']}a(\alpha_{i[t']}) - k_{t'}p + r_{i[t']}, 0, 0, \dots, 0)$$

- That is, $\|a' - t'\|_\infty < H$, so the approx. "close" lattice vector \mathbf{C} returned by A_{CVP} satisfies $\|\mathbf{c} - t'\|_\infty < \gamma_{\text{CVP}}H$.

- By triangle inequality, the "error" lattice vector $\mathbf{z} = \mathbf{c} - a'$ is "short": $\|\mathbf{z}\|_\infty < (\gamma + 1)H$

- and our algorithm fails only if this "error" lattice vector is "bad" in the sense: $\frac{p}{H}\mathbf{c}[t'+1] - \frac{p}{H}\mathbf{a}'[t'+1] = \frac{p}{H}\mathbf{z}[t'+1] \not\equiv 0 \pmod{p}$

- We use counting argument to upper bound number of public vectors α_I for which $\mathcal{L}_{\text{Sha}}(\alpha_I)$ contains "short" and "bad" vectors





Threshold-Changeability for Classical Shamir Scheme - Correctness

- Algorithm correctness analysis (continued)
 - Counting argument to upper bound number of public vectors α_I for which $\mathcal{L}_{Sha}(\alpha_I)$ contains “short” and “bad” vectors reduces to following algebraic counting lemma:

Lemma. Fix a prime p , positive integers (n, t, H) , and a non-empty set A of polynomials over \mathbf{Z}_p of degree at least 1 and at most t . The number of vectors $\alpha = (\alpha_1, \dots, \alpha_n) \in \mathbf{Z}_p^n$ for which there exists a polynomial $a \in A$ such that $\|a(\alpha_i)\|_{L,p} < H$ for all $i = 1, \dots, n$ is upper bounded by $\#A \cdot (2Ht)^n$.
 - We use this to obtain an upper bound on fraction of “bad” public vectors $(\alpha_1, \dots, \alpha_n) \in (\mathbf{Z}_p)^n$ for which combiner may not always work
 - This “bad” fraction δ_c can be made as small as we wish, for sufficiently large security parameter $k = O(\log \delta_c^{-1})$

Threshold-Changeability for Classical Shamir Scheme - Security

- Security Analysis (Main Ideas):
 - We assume a uniform distribution on secret space \mathbf{Z}_p :
 - Secret entropy $H(s \in \mathbf{Z}_p) = \log p \in [k, k + 1]$
 - We show that, for all choices of the public vector $\alpha_I \in D((\mathbf{Z}_p^*)^{t_s})$ except for a small "bad" fraction $\delta_s = O(1/k^{t'})$, the following holds:
 - For all subshare subsets $I \subseteq [n]$ of size $\#I = t_s \leq \text{Int}(f(k)(t' - t'/t))$ with $\lim_{k \rightarrow \infty} f(k) = 1$
 - and all values $s_I = (s_{i[1]}, \dots, s_{i[t_s]})$ for the corresponding subshare vector,
 - the conditional probability distribution $P_{k,x}(\cdot | s_I)$ for the secret given the observed subshare vector value s_I is "close" to uniform: $P_{k,x}(s | s_I) \leq 2^{\epsilon_s} / p$ for all $s \in \mathbf{Z}_p$ with $\epsilon_s(k) = O(\log k)$
 - \rightarrow Secret entropy loss is bounded as (for all I and s_I)
 - $$L_{k,x}(s_I) = |H(s \in \mathbf{Z}_p) - H(s \in \mathbf{Z}_p | s_I)| \leq \epsilon_s(k)$$

Threshold-Changeability for Classical Shamir Scheme - Security

- Security analysis (cont.)

- To derive bound $P_{k,x}(s|s_I) \leq 2^{\epsilon s}/p$ for all $s \in \mathbf{Z}_p$ we observe

$$P_{k,x}(s|s_I) = \frac{\#S_{s,p}(\alpha_I, t, p, H, s_I)}{\#S_{0,1}(\alpha_I, t, p, H, s_I)},$$

- where for integers $\hat{s} \in \{0, s\}$ and $\hat{p} \in \{1, p\}$ we define

$$S_{\hat{s},\hat{p}}(\alpha_I, t, p, H, s_I) \stackrel{\text{def}}{=} \{a \in \mathbf{Z}_p[x; t-1] : \|\alpha_{i[j]}a(\alpha_{i[j]}) - s_{i[j]}\|_{L,p} < H \forall j \in [t_s] \text{ and } a(0) \equiv \hat{s} \pmod{\hat{p}}\}.$$

- We lower bound $\#S_{0,1}$ (no. of dealer poly consistent with shares)
- We upper bound $\#S_{s,p}$ (no. of dealer poly consistent with shares and any fixed value s for the secret)

Threshold-Changeability for Classical Shamir Scheme - Security

- Security analysis (cont.)

- We first reduce the problem to lattice point counting:

Lemma. Let $\mathcal{L}_{Sha}(\alpha_I, t, p, H, \hat{p})$ denote the lattice with basis matrix

$$M_{Sha}(\alpha_I, t, p, H, \hat{p}) = \begin{pmatrix} p & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ 0 & p & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & p & 0 & 0 & \dots & 0 \\ \hat{p}\alpha_{i[1]} & \hat{p}\alpha_{i[2]} & \dots & \hat{p}\alpha_{i[t_s]} & 2H/(p/\hat{p}) & 0 & \dots & 0 \\ \alpha_{i[1]}^2 & \alpha_{i[2]}^2 & \dots & \alpha_{i[t_s]}^2 & 0 & 2H/p & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \alpha_{i[1]}^t & \alpha_{i[2]}^t & \dots & \alpha_{i[t_s]}^t & 0 & 0 & \dots & 2H/p \end{pmatrix},$$

← \mathbf{b}_1
■
■
■
← \mathbf{b}_{t_s+t}

and define the vector $\hat{\mathbf{s}}_I \in \mathbb{Q}_{t_s+t}$ by

$$\hat{\mathbf{s}}_I \stackrel{\text{def}}{=} \left(s_{i[1]} - \hat{s}\alpha_{i[1]}, \dots, s_{i[t_s]} - \hat{s}\alpha_{i[t_s]}, H\left(1 - \frac{1 + 2\hat{s}}{p}\right), H\left(1 - \frac{1}{p}\right), \dots, H\left(1 - \frac{1}{p}\right) \right).$$

Then the sizes of the following two sets are equal:

$$\mathcal{S}_{\hat{s}, \hat{p}}(\alpha_I, t, p, H, \mathbf{s}_I) \stackrel{\text{def}}{=} \{a \in \mathbf{Z}_p[x; t-1] : \|\alpha_{i[j]}a(\alpha_{i[j]}) - s_{i[j]}\|_{L,p} < H \forall j \in [t_s] \text{ and } a(0) \equiv \hat{s} \pmod{\hat{p}}\},$$

and

$$\mathcal{V}_{\hat{s}, \hat{p}}(\alpha_I, t, p, H, \hat{\mathbf{s}}_I) \stackrel{\text{def}}{=} \{\mathbf{v} \in \mathcal{L}_{Sha}(\alpha_I, t, p, H, \hat{p}) : \|\mathbf{v} - \hat{\mathbf{s}}_I\|_\infty < H\}.$$

Proof idea: We define a 1-1 and onto map from $\mathcal{V}_{\hat{s}, \hat{p}}$ to $\mathcal{S}_{\hat{s}, \hat{p}}$ by mapping vector

$$\mathbf{v} = k_1^y \mathbf{b}_1 + \dots + k_{t_s}^y \mathbf{b}_{t_s} + k^y \mathbf{b}_{t_s+1} + a_1^y \mathbf{b}_{t_s+2} + \dots + a_{t-1}^y \mathbf{b}_{t_s+t}$$

to polynomial

$$a_{\mathbf{v}}(x) = [\hat{s} + k^y \hat{p}]_p + [a_1^y]_p x + \dots + [a_{t-1}^y]_p x^{t-1}$$

Threshold-Changeability for Classical Shamir Scheme - Security

- Security analysis (cont.)
 - Now we use lattice tools to lower bound $\#V_{0,1}$
 - Note $\#V_{0,1}$ is a “non-homogenous” counting problem: we need the number of lattice points in a box
 $T_{s_I}(H) = \{\mathbf{v} \in \mathbb{Q}^{t_s+t} : \|\mathbf{v} - \hat{s}_I\|_\infty < H\}$ centred on a (non-lattice) vector \hat{s}_I
 - We reduce this non-homogenous problem to two simpler problems:
 - The homogenous problem of lower bounding the number of lattice points in an origin-centred box

$$T_0(H - \epsilon) = \{\mathbf{v} \in \mathbb{Q}^{t_s+t} : \|\mathbf{v}\|_\infty < H - \epsilon\} \quad \text{where } \epsilon \leq \left(\frac{t_s+t}{2}\right) \lambda_{t_s+t}(\mathcal{L}_{Sha})$$

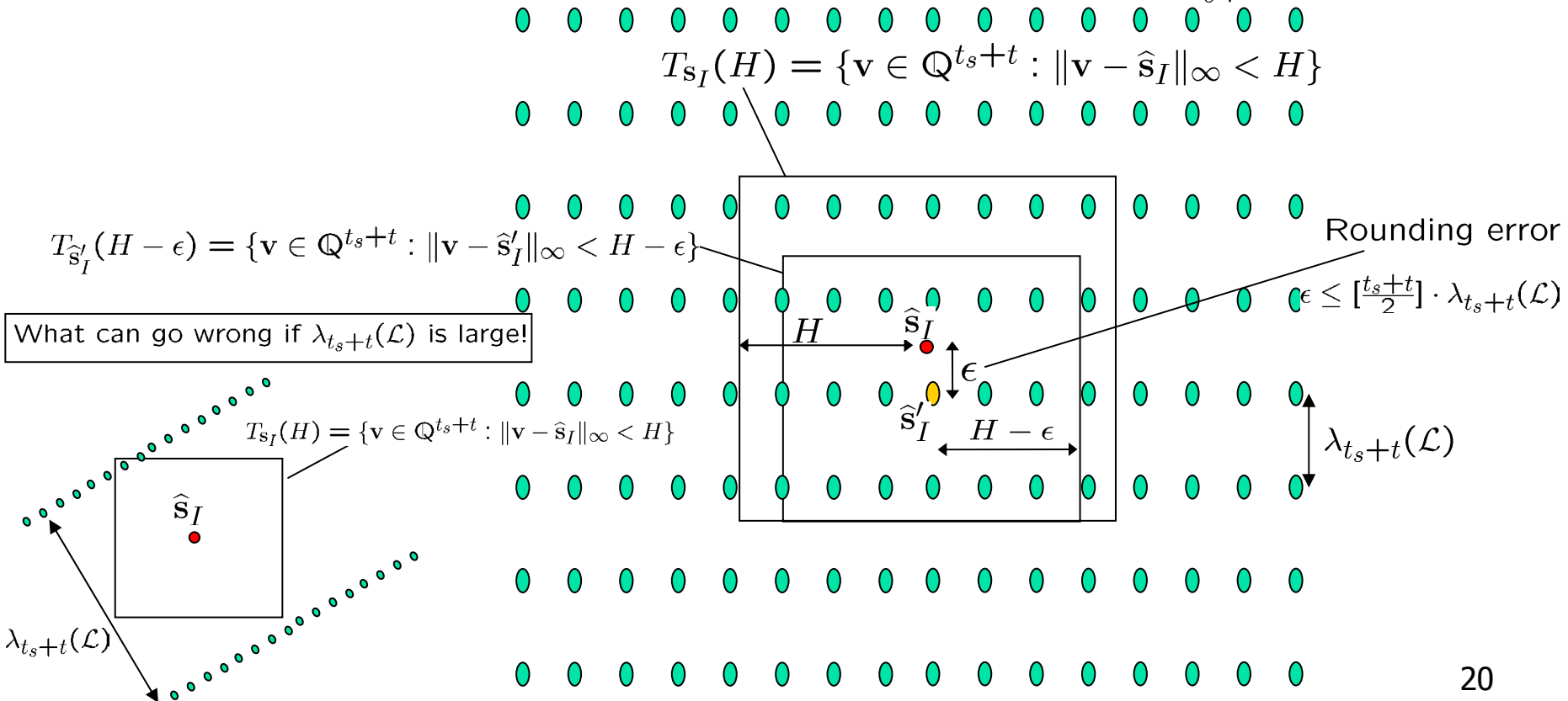
- Upper bounding the largest Minkowski minimum $\lambda_{t_s+t}(\mathcal{L}_{Sha})$

We show $\#V_{\hat{s}, \hat{p}_0} \geq \#\{\mathbf{v} \in T_0(H - \epsilon) \cap \mathcal{L}_{CRT}\}$

Threshold-Changeability for Classical Shamir Scheme - Security

- Security analysis (cont.)

- Proof idea of reduction of "non-homogenous lower bound" to "homogenous lower bound" + upper bound on $\lambda_{t_s+t}(\mathcal{L}_{Sha})$





Threshold-Changeability for Classical Shamir Scheme - Security

- Security analysis (cont.)

- Problem 1 (point counting in origin-symmetric box) is solved directly by applying Blichfeldt-Corput Theorem:

$$\#\{v \in \mathcal{L}_{Sha} \cap T_0(H - \epsilon)\} \geq 2Int \left(\frac{Vol(T_0(H - \epsilon))}{2^{ts+t} \det(\mathcal{L}_{Sha})} \right)$$

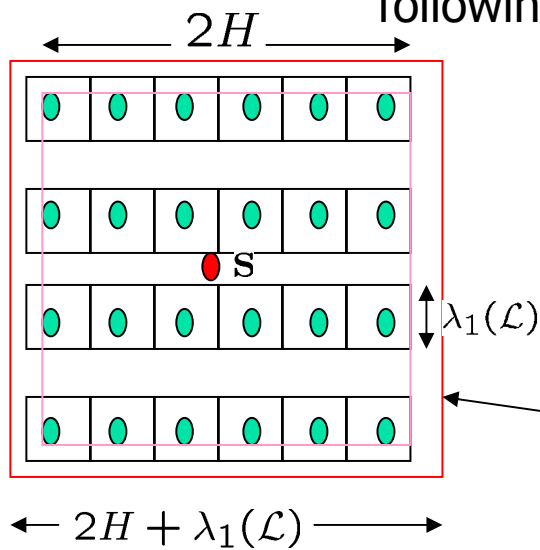
- Problem 2 (upper bounding $\lambda_{ts+t}(\mathcal{L}_{Sha})$) is solved by applying Minkowski's Second Theorem to reduce it first to the problem of lower bounding the first Minkowski minimum(shortest vector norm)

$$\lambda_{ts+t}(\mathcal{L}_{Sha}) \leq \frac{2^{ts+t} \det(\mathcal{L}_{Sha})}{\lambda_1(\mathcal{L}_{Sha})^{ts+t-1}}$$

- We lower bound the first Minkowski minimum $\lambda_1(\mathcal{L}_{Sha})$ (except for a "small" fraction of "bad" public vectors $(\alpha_1, \dots, \alpha_n)$) by applying our algebraic counting lemma (using similar argument used in correctness analysis)

Threshold-Changeability for Classical Shamir Scheme - Security

- Security analysis (cont.)
 - This completes the results needed to lower bound $\#V_{0,1}$
 - Recall that we also need to upper bound $\#V_{s,p}$
 - We reduce this problem also to lower bounding $\lambda_1(\mathcal{L}_{Sha})$ with the following result:



Lemma. For any lattice \mathcal{L} in \mathbb{R}^n , vector $s \in \mathbb{R}^n$, and $H > 0$, we have

$$\#\{v \in \mathcal{L} : \|v - s\|_\infty < H\} \leq \left[\frac{2H}{\lambda_1(\mathcal{L})} + 1 \right]^n.$$

Upper bound total vol of small boxes $\#V \times \lambda_1^n$
by volume of large box $(2H + \lambda_1(\mathcal{L}))^n$

- And now we use our lower bound on $\lambda_1(\mathcal{L}_{Sha})$ again!



Conclusions

- Presented lattice-based threshold changeability algorithms for Shamir secret-sharing
- Proved concrete bounds on correctness and security using classical results from theory of lattices