

Less is More: Active Learning with Support Vector Machines

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March 9, 2006

- Introduction
- Support Vector Machines
- A greedy optimal strategy
- A simple heuristic
- Experiments
- Conclusions

- labeled examples
 - obtained costly
 - presence of domain experts
- Solution: *active learning*
 - selects the training examples the most *informative*
 - increases performance by reducing the number of the training examples

Support Vector Machines

- defines a unique hyperplane that separates positive and negative examples and for which the margin is maximized
- *soft SVM*
 - used when data are not separable
 - separate data with a minimal number of errors
- *bound examples*
 - examples incorrectly classified
 - examples within the margin

A greedy optimal strategy

- based on *probabilities* assigned to points classified by SVM

$$P(y = 1|x) = \frac{1}{1 + \exp(-f(x))}$$

where $f(x)$ is the output of SVM

- based on the *expected error* :
sum of the expected error of each training example weighted by the distributions of test examples

A greedy optimal strategy

- algorithm:
 - for each candidate unlabeled example x , calculate $P(y = 1|x)$ and $P(y = -1|x)$
 - Add $(x, 1)$ to the training set, retrain, and calculate the new expected error $E_{(x,1)}$
 - Remove $(x, 1)$, add $(x, -1)$ to the training set, retrain, and calculate $E_{(x,-1)}$
 - Estimate expecting error as
$$E_x = P(y = 1|x) * E_{(x,1)} + P(y = -1|x) * E_{(x,-1)}$$
 - Choose the unlabeled example x , which has the minimum E_x
- impractical: evaluating each candidate requires solving two QP problems

A simple heuristic

- example nearest to the dividing hyperplane
- for all the unlabeled examples find the distance between them and the hyperplane (dot product computation) and select the one that has the minimum distance
- reduction of the uncertainty area which is situated near the dividing hyperplane

- two domains:
 - binary classification of 4 newsgroup pairs from the 20 Newsgroups data set
 - topic classification on a subset of five topics from Reuters
- number of examples in every iteration = 8
 - trade-off against the cost of re-solving a new QP problem (more examples per iteration, less QP problems) and the cost of labelling an example
- active learning performs better than random selecting

- *stopping criterion*
 - when the margin has been exhausted \Rightarrow when there are no other training examples within the margin
- the performance increases up to a peak and after it starts to decrease
 - until the margin has been exhausted (until peak) \Rightarrow performance increases, the model remains consistent
 - when margin contains no available training data \Rightarrow examples that make the model inconsistent may be added (soft SVM), performance decreases

Conclusions

- reduce of the number of the training examples
- reduce in time
- give bounds for b
- accuracy decrease very soon \Rightarrow stop ?