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Lévy processes with finite variance conditioned to avoid an interval

Leif Döring^{*} Alexander R. Watson[†] Philip Weissmann[‡]

Abstract

Conditioning Markov processes to avoid a set is a classical problem that has been studied in many settings. In the present article we study the question if a Lévy process can be conditioned to avoid an interval and, if so, the path behavior of the conditioned process. For Lévy processes with finite second moments we show that conditioning is possible and identify the conditioned process as an *h*-transform of the original killed process. The *h*-transform is explicit in terms of successive overshoot distributions and is used to prove that the conditioned process diverges to $+\infty$ and $-\infty$ with positive probabilities.

Keywords: Markov processes; Lévy processes; killed Lévy processes; Doob h-transform; martingales.

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*University of Mannheim, Germany. E-mail: doering@uni-mannheim.de

 $^{\dagger}\mbox{University}$ of Manchester, UK. E-mail: alex.watson@manchester.ac.uk

 $^{\ddagger}\textsc{University}$ of Mannheim, Germany. E-mail: hweissma@mail.uni-mannheim.de

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1 Introduction

Conditioning Markov processes to avoid sets is a classical problem. Indeed, suppose $(\mathbb{P}^x)_{x\in E}$ is a family of Markov probabilities on the state space E, and that T is the first hitting time of a fixed set. When T is almost surely finite, it is non-trivial to construct and characterise the conditioned process through the natural limiting procedure

$$\lim_{s \to \infty} \mathbb{P}^x(\Lambda \,|\, s < T) \tag{1.1}$$

or the randomized version

$$\lim_{q \to 0} \mathbb{P}^x(\Lambda \,|\, e_q < T),\tag{1.2}$$

for $\Lambda \in \mathcal{F}_t$ and $x \in E$. Here, $(\mathcal{F}_t)_{t \geq 0}$ denotes the natural filtration of the underlying Markov process and e_q are independent exponentially distributed random variables with parameter q > 0.

A classical example is Brownian motion conditioned to avoid the negative half-line. In this case, the limits (1.1) and (1.2) lead to a so-called Doob *h*-transform of the Brownian motion killed on entering the negative half-line, by the positive harmonic function h(x) = x on $(0, \infty)$. This Doob *h*-transform turns out (see Chapter VI.3 of [20]) to be the Bessel process of dimension 3, which is transient. This example is typical, in that a conditioning procedure leads to a new process which is transient where the original process was recurrent.

Extensions of this result have been obtained in several directions, most notably to random walks and Lévy processes. A prominent example with several applications is that of a Lévy process conditioned to stay positive, which was found by Chaumont and Doney [5] using the randomised conditioning (1.2). In that case, the associated harmonic function h is given by the potential function of the descending ladder height process. Similarly, Bertoin and Doney [2] have shown how to condition a random walk to stay non-negative. Other examples include random walks conditioned to stay in a cone (Denisov and Wachtel [7]), isotropic stable processes conditioned to stay in a cone (Kyprianou et al. [15]), spectrally negative Lévy processes conditioned to stay in an interval (Lambert [17]), subordinators conditioned to stay in an interval (Kyprianou et al. [13]), Lévy processes conditioned to avoid the origin (Pantí [18] and Yano [24]) and self-similar Markov processes conditioned to avoid the origin (Kyprianou et al. [16]).

The purpose of this article is to take advantage of the path discontinuities of Lévy processes and to condition them to avoid an interval. In Döring et al. [8] this problem was tackled for strictly stable processes since their structure as self-similar Markov processes allowed to deduce the right harmonic functions. The proofs were based on the so called deep factorisation (see Kyprianou et al. [12, 14]), which analyses stable processes using the Lamperti-Kiu transform. In the present article, we consider Lévy processes with zero mean and finite variance. This assumes less structure on the Lévy process, but at the same time excludes the stable processes, which have infinite second moments. The discrete-time analogue of our problem was considered by Vysotsky [23], who used

a Doob *h*-transform to condition a centred random walk with finite second moment to avoid an interval. One of the harmonic functions we will discover is the analogue of the harmonic function found by Vysotsky for random walks, but the techniques needed are different.

Before presenting our results, we introduce the most important definitions and results concerning Lévy processes. More details can be found, for example, in Bertoin [1], Kyprianou [11] or Sato [22].

Lévy Processes: A Lévy process ξ is a stochastic process with stationary and independent increments whose trajectories are almost surely right-continuous with left-limits (RCLL). For each $x \in \mathbb{R}$, we define the probability measure \mathbb{P}^x under which the canonical process ξ starts at x almost surely. We write \mathbb{P} for the measure \mathbb{P}^0 . The dual measure $\hat{\mathbb{P}}^x$ denotes the law of the so-called dual process $-\xi$ started at x. A Lévy process can be identified using its characteristic exponent Ψ , defined by the equation $\mathbb{E}[e^{iq\xi_t}] = e^{-t\Psi(q)}$, $q \in \mathbb{R}$, which has the Lévy-Khintchine representation:

$$\Psi(q) = iaq + \frac{1}{2}\sigma^2 q^2 + \int_{\mathbb{R}} (1 - e^{iqx} + iqx \mathbb{1}_{\{|x| < 1\}}) \Pi(\mathrm{d}x), \quad q \in \mathbb{R},$$

where $a \in \mathbb{R}$ is the so-called centre of process, $\sigma^2 \ge 0$ is the variance of the Brownian component, and the Lévy measure Π is a real measure with no atom at 0 satisfying $\int (x^2 \wedge 1) \Pi(dx) < \infty$.

Our main assumption is:

(A) ξ has zero mean and finite variance, and is not a compound Poisson process.

We define $T_B = \inf\{t \ge 0 : \xi_t \in B\}$ for any open or closed set $B \subseteq \mathbb{R}$. This is known to be a stopping time with respect to the right-continuous natural enlargement of the filtration induced by ξ , which we denote by $(\mathcal{F}_t)_{t\ge 0}$. For certain auxiliary results, we will need to distinguish two cases:

(**B**) $\Pi(b-a,\infty) > 0$, i.e., upward jumps avoiding [a,b] are possible

and

 $(\hat{\mathbf{B}})$ $\Pi(-\infty, a-b) > 0$, i.e., downward jumps avoiding [a, b] are possible

Killed Lévy processes and h-transforms: For a < b the killed transition measures are defined as

$$p_t^{[a,b]}(x, \mathrm{d}y) = \mathbb{P}^x(\xi_t \in \mathrm{d}y, t < T_{[a,b]}), \quad t \ge 0.$$

The corresponding sub-Markov process is called the Lévy process killed in [a, b]. A harmonic function for the killed process is a measurable function $h : \mathbb{R} \setminus [a, b] \to [0, \infty)$ such that

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} h(\xi_{t}) \right] = h(x), \quad x \in \mathbb{R} \setminus [a,b], t \ge 0.$$
(1.3)

A harmonic function taking only strictly positive values is called a positive harmonic function. Thanks to the Markov property, harmonicity is equivalent to $(\mathbb{1}_{\{t < T_{[a,b]}\}}h(\xi_t))_{t \ge 0}$ being a \mathbb{P}^x -martingale with respect to $(\mathcal{F}_t)_{t \ge 0}$. When h is a positive harmonic function, the associated Doob h-transform is defined via the change of measure

$$\mathbb{P}_{h}^{x}(\Lambda) := \mathbb{E}^{x} \Big[\mathbb{1}_{\Lambda} \mathbb{1}_{\{t < T_{[a,b]}\}} \frac{h(\xi_{t})}{h(x)} \Big], \quad x \in \mathbb{R} \setminus [a,b],$$
(1.4)

for $\Lambda \in \mathcal{F}_t$. From Chapter 11 of Chung and Walsh [6], we know that under \mathbb{P}_h^x the canonical process is a conservative strong Markov process. In Chapter 11 of Chung

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and Walsh [6] it is shown that (1.4) extends from deterministic times to $(\mathcal{F}_t)_{t\geq 0}$ -stopping times T; that is,

$$\mathbb{P}_{h}^{x}(\Lambda, T < \infty) = \mathbb{E}^{x} \Big[\mathbb{1}_{\Lambda} \mathbb{1}_{\{T < T_{[a,b]}\}} \frac{h(\xi_{T})}{h(x)} \Big], \quad x \notin [a,b],$$
(1.5)

for $\Lambda \in \mathcal{F}_T$.

Ladder height processes and potential functions: A crucial ingredient in our analysis is the potential function U_- of the descending ladder height process, which is positive harmonic for a Lévy process killed on the negative half-line. To introduce U_- , some notation is needed. Denote the local time of the Markov process $(\sup_{s \le t} \xi_s - \xi_t)_{t \ge 0}$ at 0 by L, which is also called the local time of ξ at the maximum. Let $L_t^{-1} = \inf\{s > 0 : L_s > t\}$ denote the inverse local time at the maximum and $\kappa(q) = -\log \mathbb{E}[e^{-qL_1^{-1}}]$, for $q \ge 0$, the Laplace exponent of L^{-1} . We define $H_t = \sup_{s \le L_t^{-1}} \xi_s$, the so-called (ascending) ladder height process. It is well-known that H is a subordinator and we denote by a_+ the drift coefficient of H, and by μ_+ its Lévy measure. Under the dual measure $\hat{\mathbb{P}}$, the process L^{-1} is the inverse local time at the minimum, and we denote its Laplace exponent by $\hat{\kappa}$. Still under this dual measure, H is the descending ladder height process, and we define a_- and μ_- to be its drift coefficient and Lévy measure.

The *q*-resolvents of *H*, for $q \ge 0$, will be denoted by U_+^q ; that is,

$$U^q_+(\mathrm{d}x) \coloneqq \mathbb{E}\Big[\int_{[0,\infty)} e^{-qt} \mathbb{1}_{\{H^+_t \in \mathrm{d}x, L^{-1}_t < \infty\}} \,\mathrm{d}t\Big].$$

For q = 0 we abbreviate $U_+(dx) = U^0_+(dx)$, and denote the so-called potential function by $U_+(x) = U_+([0, x])$, for $x \ge 0$. We define U^q_- and U_- according to the same procedure for the descending ladder height process. If ξ is not a compound Poisson process, it is known that U_+ and U_- are continuous.

2 Main results

Before stating the main results, some more notation is needed to define our harmonic functions. We first define inductively the sequence of successive stopping times at which the process jumps crossing a or b:

$$\tau_0 \coloneqq 0, \tau_{k+1} \coloneqq \inf\{t > \tau_k : \xi_{t-} > b, \xi_t \le b\} \land \inf\{t > \tau_k : \xi_{t-} < a, \xi_t \ge a\}.$$

Second, let $K^{\dagger} := \inf\{k \ge 1 : \tau_k = T_{[a,b]}\}$ be the index indicating the time at which the process hits the given interval, let

$$\nu_k^x(\mathrm{d}y) = \mathbb{P}^x(\xi_{\tau_k} \in \mathrm{d}y, \tau_k < \infty, k \le K^{\dagger}), \quad x, y \in \mathbb{R} \setminus [a, b]$$

be the distribution of the position of ξ after its k-th jump across the interval, for $k \geq 0$.

It is important to note that each ν_k^x can be expressed explicitly in terms of the Lévy measures and potential measures of the ladder height processes. Indeed, ν_1^x is nothing but an overshoot distribution, for which a formula is given in Proposition III.2 of Bertoin [1], using that the overshoot of ξ has the same distribution as the overshoot of the corresponding ladder height subordinator H. Applying the strong Markov property successively yields explicit expressions for all other ν_k^x which can be found at the beginning of Section 4.

Theorem 2.1. If Assumptions (A) and (B) hold, then the function

$$h_{+}(x) := \begin{cases} \sum_{k=0}^{\infty} \int U_{-}(y-b) \nu_{2k}^{x}(\mathrm{d}y) & \text{if } x > b \\ \sum_{k=0}^{\infty} \int U_{-}(y-b) \nu_{2k+1}^{x}(\mathrm{d}y) & \text{if } x < a \end{cases}$$

is a positive harmonic function for ξ killed on entering [a, b], i.e.

 $\mathbb{E}^{x} \big[\mathbb{1}_{\{t < T_{[a,b]}\}} h_{+}(\xi_{t}) \big] = h_{+}(x), \quad t \ge 0, x \in \mathbb{R} \setminus [a,b].$

If Assumption (B) is not satisfied, then h_+ is still harmonic, but may not be positive. To be precise, when (B) fails, h_+ is positive on (b, ∞) but zero on $(-\infty, a)$.

Similarly, under (A) and (\hat{B}) , the function

$$h_{-}(x) := \begin{cases} \sum_{k=0}^{\infty} \int U_{+}(a-y) \nu_{2k+1}^{x}(\mathrm{d}y) & \text{if } x > b \\ \sum_{k=0}^{\infty} \int U_{+}(a-y) \nu_{2k}^{x}(\mathrm{d}y) & \text{if } x < a \end{cases}$$

is positive harmonic as well. As above, when (\hat{B}) fails, h_{-} remains harmonic, but is positive only on $(-\infty, a)$ and zero on (b, ∞) .

An important corollary of this discussion is the existence of positive harmonic functions under the Assumption (A) only:

Corollary 2.2. If Assumption (A) holds, then all linear combinations of h_+ and h_- with strictly positive coefficients are positive harmonic functions.

A significant part of the proof of Theorem 2.1 consists of showing that h_{\pm} are finite. As a consequence of this proof, we also obtain the inequality

$$\mathbb{P}^{x}(K^{\dagger} - 1 \ge k) \le \gamma^{k}, \quad k \ge 0, x \in \mathbb{R} \setminus [a, b],$$

where γ is defined by (4.7). In other words, the number of crossings of the interval [a, b] before it is hit is stochastically dominated by a geometric distribution.

The harmonic functions h_+ and h_- typically do not have a simple closed form (but Section 3 below for an example where they do). This would appear to reduce their applicability; however, we can use our definition to prove results on conditioning. We will show that the conditioning in the sense of (1.2) works and, as a consequence of general h-transform theory, that the conditioned process is strong Markov. Additionally, it turns out that the harmonic functions are explicit enough to explain the limiting behavior of trajectories under the conditioned law.

Remark 2.3. Vysotsky [23] considered the analogous problem for a centred random walk $S = (S_n)_{n \in \mathbb{N}}$ with finite variance. He derived a harmonic function V which is the discrete analogue of some linear combination of h_+ and h_- . However, it does not appear to be simple to translate the proofs of [23] to the case of a Lévy process. In discrete-time, it is enough to show that V(S) is a martingale by considering the first time-step. In continuous time, on the other hand, $t \leq T_{[a,b]}$ does not hold almost surely for any $t \geq 0$, and different arguments are required.

With the harmonic functions h_+ , h_- and their positive linear combinations it is now possible to *h*-transform the killed process as in (1.4). The *h*-transforms \mathbb{P}_+ (resp. \mathbb{P}_-) are defined through (1.4) with the positive harmonic functions h_+ (resp. h_-). We will show how to condition the Lévy process in order to obtain *h*-transforms with h_+ and h_- , and then derive the correct linear combination of h_+ and h_- corresponding to conditioning the Lévy process to avoid the interval in the sense of (1.2).

The next proposition gives a probabilistic representation of \mathbb{P}^x_+ by conditioning to avoid [a, b] and staying above b at late times. The analogous conditioning under (A) and (\hat{B}) below the interval results in the h-transform \mathbb{P}^x_- .

Proposition 2.4. Assume (A) and (B). Then

$$\mathbb{P}^{x}_{+}(\Lambda) = \lim_{q \searrow 0} \mathbb{P}^{x}(\Lambda \mid e_{q} < T_{[a,b]}, \xi_{e_{q}} > b), \quad x \notin [a,b],$$

for $\Lambda \in \mathcal{F}_t$, $t \geq 0$.

To understand the Lévy process conditioned to avoid the interval without additional condition on the late values a natural guess is an *h*-transform using a linear combination of h_+ and h_- . Possible asymmetry of the Lévy process implies that different weights must be chosen for h_+ and h_- . It emerges that the right harmonic function is

$$h := h_+ + Ch_-, \quad \text{where} \quad C = \lim_{q \searrow 0} \frac{\kappa(q)}{\hat{\kappa}(q)}. \tag{2.1}$$

/ \

Note that, if ξ oscillates and has finite variance, then $C \in (0, \infty)$ exists; see, for instance, Patie and Savov [19], Remark 2.21. From Corollary 2.2, it follows that h is a positive harmonic function if we assume only (A). The h-transform of ξ killed in [a, b] with h from (2.1) will be denoted by \mathbb{P}_{\uparrow} , i.e.

$$\mathbb{P}^x_{\uparrow}(\Lambda) = \mathbb{E}^x \Big[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \frac{h(\xi_t)}{h(x)} \Big], \quad x \notin [a,b],$$

for $\Lambda \in \mathcal{F}_t$. Our main result can now be formulated. Conditioning to avoid an interval is always possible for Lévy processes with second moments and the conditioned law corresponds to the *h*-transform with *h* from (2.1).

Theorem 2.5. Assume (A). Then,

$$\mathbb{P}^{x}_{\updownarrow}(\Lambda) = \lim_{q \searrow 0} \mathbb{P}^{x}(\Lambda \,|\, e_{q} < T_{[a,b]}), \quad x \notin [a,b],$$

for $\Lambda \in \mathcal{F}_t$, $t \geq 0$.

We remark that one can see from our proofs that

$$\lim_{q \searrow 0} \mathbb{P}^x(\Lambda \mid e_q < T_{[a,b]}) = \lim_{q \searrow 0} \mathbb{P}^x(\Lambda, t < e_q \mid e_q < T_{[a,b]}), \quad x \notin [a,b], \Lambda \in \mathcal{F}_t.$$

In particular the *h*-transform $\mathbb{P}^{x}_{\uparrow}(\Lambda)$ also equals the probability on the right-hand side. A characterisation of this form (i.e. including the event $t < e_q$) appears in different settings of conditioned Lévy processes, e.g. for the Lévy process conditioned to stay positive, Chaumont and Doney [5].

Typically the first property analyzed for a conditioned process is the long-time behavior. It is often the case that the conditioning turns a recurrent process into a transient process. Nonetheless, the limit behavior under \mathbb{P}_{\pm} , and in particular \mathbb{P}_{\downarrow} , is a priori unclear. Processes might be oscillating, diverge to $+\infty$ or $-\infty$, or might even diverge to both infinities with positive probability. The next proposition covers the case \mathbb{P}_+ :

Proposition 2.6. Assume (A) and (B). Then $\mathbb{P}^{x}_{+}(\lim_{t \to \infty} \xi_{t} = +\infty) = 1$ for all $x \notin [a, b]$.

Analogously, assuming (A) and (B) one can show that ξ drifts to $-\infty$ almost surely under \mathbb{P}_{-}^{x} . It remains to consider the behaviour of $(\xi, \mathbb{P}_{\downarrow}^{x})$. Our final theorem shows that Lévy processes with second moments conditioned to avoid an interval drift to either $+\infty$ or $-\infty$, each with (explicit) positive probabilities:

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Theorem 2.7. Assume (A). Then, \mathbb{P}^x_{\uparrow} is transient in the sense that

$$\mathbb{E}^x_{\uparrow} \Big[\int_{[0,\infty)} \mathbbm{1}_{\{\xi_t \in K\}} \, \mathrm{d}t \Big] < \infty, \quad x \notin [a,b],$$

for all bounded $K \subseteq \mathbb{R} \setminus [a, b]$. More precisely,

$$\mathbb{P}^{x}_{\uparrow}\left(\lim_{t\to\infty}\xi_{t}=+\infty\right)=\frac{h_{+}(x)}{h(x)} \quad \text{and} \quad \mathbb{P}^{x}_{\uparrow}\left(\lim_{t\to\infty}\xi_{t}=-\infty\right)=\frac{Ch_{-}(x)}{h(x)}, \quad x\notin[a,b],$$

so that, in particular, $\mathbb{P}^x_{\updownarrow}\text{-almost}$ all trajectories do not oscillate.

In the recent article [8] it was proved that stable processes conditioned to avoid an interval are transient. Since stable processes have infinite second moments, Theorem 2.7 does not apply, and it remains unclear if trajectories oscillate or diverge to $+\infty$ and $-\infty$ with positive probabilities. This is not merely a technical issue with our proof: for a stable process, the functions h_+ and h_- , as defined above, are actually infinite at every point of $\mathbb{R} \setminus [a, b]$; this can be shown directly using explicit formulas for the potential functions and overshoot distributions (see, e.g., Rogozin [21]).

3 An explicit example

When ξ is a Lévy process with no drift and two-sided exponential jumps, it is possible to compute the harmonic functions h_+ , h_- and h explicitly. Let

$$\xi_t = \sigma B_t + \sum_{i=1}^{N_t} Y_i, \quad t \ge 0,$$
(3.1)

where $\sigma \ge 0$, $(B_t)_{t\ge 0}$ is a standard Brownian motion, and $\sum_{i=1}^{N_t} Y_i$ is a compound Poisson process with rate $\lambda > 0$ and absolutely continuous jump distribution with density

$$f_Y(y) = \frac{1}{2} \eta e^{-\eta y} \mathbb{1}_{\{y>0\}} + \frac{1}{2} \eta e^{-\eta(-y)} \mathbb{1}_{\{y<0\}}.$$

For definiteness, let $\sigma = \sqrt{2}$ and $\lambda = 1$. The Laplace exponent ψ of ξ , given by $\mathbb{E}[e^{-\theta\xi_t}] = e^{-t\psi(\theta)}$, can be expressed, for $\theta \in (-\eta, \eta)$, by

$$\psi(\theta) = -\theta^2 - \frac{\theta^2}{(\eta+\theta)(\eta-\theta)} = \frac{\theta(\beta+\theta)}{\eta+\theta} \cdot \frac{(-\theta)(\beta-\theta)}{\eta-\theta},$$
(3.2)

where $\beta = \sqrt{\eta^2 + 1} > \eta$. Note that ξ oscillates and has finite variance, so (A) holds, (B) and (\hat{B}) both hold as well. Let

$$\upsilon(\theta) = \hat{\upsilon}(\theta) = \frac{\theta(\beta + \theta)}{\eta + \theta} = \theta + (\beta - \eta) \int_0^\infty (1 - e^{-\theta x}) \eta e^{-\eta x} \, \mathrm{d}x, \qquad \theta > -\eta$$

which is the Laplace exponent of a subordinator with unit drift, jump rate $\beta - \eta$ and exponential jumps of parameter η . Since

$$\psi(\theta) = \upsilon(\theta)\hat{\upsilon}(-\theta),$$

the uniqueness of the Wiener–Hopf factorisation [11, Theorem 6.15(iv)] implies that v and \hat{v} are indeed the Laplace exponents of the ascending and descending ladder height subordinators, respectively.

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Since

$$\int_{[0,\infty)} e^{-\theta x} U_{-}(\mathrm{d}x) = \int_{[0,\infty)} e^{-\theta x} U_{+}(\mathrm{d}x) = \frac{1}{\upsilon(\theta)} = \frac{\eta + \theta}{\theta(\beta + \theta)}$$
(3.3)

by [11, equation (5.23)], we can identify the potential measures

$$U_{-}(\mathrm{d}x) = U_{+}(\mathrm{d}x) = \left(\frac{\eta}{\beta} + \frac{\beta - \eta}{\beta}e^{-\beta x}\right)\mathrm{d}x,$$

and the potential functions

$$U_{-}(x) = U_{+}(x) = \frac{\eta}{\beta}x + \frac{\beta - \eta}{\beta^{2}}(1 - e^{-\beta x}), \quad x \ge 0.$$
(3.4)

To find h_+ in closed form we first need to find the measures ν_k^x explicitly. This can in principle be done using the expressions we have just found for U_{\pm} and the Lévy measures of the ladder height subordinators, but in fact the overshoot distributions have already been found in Kou and Wang [9], Corollary 3.1, where

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} \in dy) = \frac{\eta(\beta - \eta)}{\beta} (1 - e^{-\beta(a-x)}) e^{-\eta(y-a)} dy, \quad x < a < y,$$

and

$$\mathbb{P}^{x}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}y) = \frac{\eta(\beta - \eta)}{\beta} (1 - e^{-\beta(x-b)}) e^{-\eta(b-y)} \,\mathrm{d}y, \quad x > b > y,$$

are proven.

We now claim that

$$\nu_{2k+1}^{x}(\mathrm{d}y) = c^{2k}\nu_{1}^{x}(\mathrm{d}y), \quad x < a, y > b,$$
(3.5)

and

$$\nu_{2k+2}^{x}(\mathrm{d}y) = c^{2k}\nu_{2}^{x}(\mathrm{d}y), \quad x, y > b,$$
(3.6)

hold for all $k \ge 0$, where $c = e^{-\eta(b-a)}(\beta - \eta)/(\beta + \eta)$. For proving this, note that

$$\int_{(b,\infty)} (1 - e^{-\beta(z-b)}) e^{-\eta(z-a)} dz = \int_{(-\infty,a)} (1 - e^{-\beta(a-z)}) e^{-\eta(b-z)} dz$$
$$= e^{-\eta(b-a)} \frac{\beta}{\eta(\beta+\eta)}.$$

For k = 0 the claims are clearly correct. Next, note that for x > b:

$$\begin{split} \nu_2^x(\mathrm{d}y) &= \int\limits_{(-\infty,a)} \mathbb{P}^z(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) \, \mathbb{P}^x(\xi_{T_{(-\infty,b]}} \in \mathrm{d}z) \\ &= \left(\frac{\eta(\beta-\eta)}{\beta}\right)^2 (1-e^{-\beta(x-b)}) e^{-\eta(y-a)} \, \mathrm{d}y \int\limits_{(-\infty,a)} (1-e^{-\beta(a-z)}) e^{-\eta(b-z)} \mathrm{d}z \\ &= \left(\frac{\eta(\beta-\eta)}{\beta}\right)^2 (1-e^{-\beta(x-b)}) e^{-\eta(y-a)} e^{-\eta(b-a)} \frac{\beta}{\eta(\beta+\eta)} \, \mathrm{d}y \\ &= c \frac{\eta(\beta-\eta)}{\beta} (1-e^{-\beta(x-b)}) e^{-\eta(y-a)} \, \mathrm{d}y. \end{split}$$

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Now, let us assume the claims are correct for k - 1, $k \ge 1$. Then, for x < a, b < y,

$$\begin{split} \nu_{2k+1}^{x}(\mathrm{d}y) &= \int_{(b,\infty)} \nu_{2k}^{z}(\mathrm{d}y) \, \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} \in \mathrm{d}z) \\ &= c^{2k-2} \int_{(b,\infty)} \nu_{2}^{z}(\mathrm{d}y) \, \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} \in \mathrm{d}z) \\ &= c^{2k-2} c \Big(\frac{\eta(\beta-\eta)}{\beta}\Big)^{2} (1-e^{-\beta(a-x)}) e^{-\eta(y-a)} \, \mathrm{d}y \int_{(b,\infty)} (1-e^{-\beta(z-b)}) e^{-\eta(z-a)} \, \mathrm{d}z \\ &= c^{2k-1} \Big(\frac{\eta(\beta-\eta)}{\beta}\Big)^{2} e^{-\eta(b-a)} \frac{\beta}{\eta(\beta+\eta)} (1-e^{-\beta(a-x)}) e^{-\eta(y-a)} \, \mathrm{d}y \\ &= c^{2k-1} \Big(\frac{\beta-\eta}{\beta+\eta}\Big) e^{-\eta(b-a)} \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) \\ &= c^{2k} \nu_{1}^{x}(\mathrm{d}y), \end{split}$$

which is (3.5). Similarly we get, for x, y > b,

$$\begin{aligned} \nu_{2k+2}^{x}(\mathrm{d}y) &= \int_{(-\infty,a)} \nu_{2k+1}^{z}(\mathrm{d}y) \, \mathbb{P}^{x}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}z) \\ &= c^{2k} \int_{(-\infty,a)} \nu_{1}^{z}(\mathrm{d}y) \, \mathbb{P}^{x}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}z) \\ &= c^{2k} \int_{(-\infty,a)} \nu_{1}^{z}(\mathrm{d}y) \, \nu_{1}^{x}(\mathrm{d}z) \\ &= c^{2k} \nu_{2}^{x}(\mathrm{d}y) \end{aligned}$$

which is (3.6).

Having formulas for U_{-} and all ν_k we can proceed to compute h_{+} . Combining (3.4), (3.5) and (3.6) standard integration shows, for $k \ge 1$,

$$\int_{(b,\infty)} U_{-}(y-b) \nu_{2k+1}^{x}(\mathrm{d}y) = c^{2k} \int_{(b,\infty)} U_{-}(y-b) \nu_{1}^{x}(\mathrm{d}y)$$
$$= c^{2k} \frac{2c}{\beta} (1-e^{\beta(a-x)})$$
$$= \frac{2c^{2k+1}}{\beta} (1-e^{\beta(a-x)})$$

for x < a and

$$\int_{(b,\infty)} U_{-}(y-b) \nu_{2k+2}^{x}(\mathrm{d}y) = c^{2k} \int_{(b,\infty)} U_{-}(y-b) \nu_{2}^{x}(\mathrm{d}y)$$
$$= c^{2k} \frac{2c^{2}}{\beta} (1-e^{-\beta(x-b)})$$
$$= \frac{2c^{2k+2}}{\beta} (1-e^{-\beta(x-b)})$$

for x > b. Hence, substituting in the definition of h_+ gives

$$h_{+}(x) = \left(\sum_{k=0}^{\infty} c^{2k+1}\right) \frac{2}{\beta} (1 - e^{-\beta(a-x)}) = \frac{2c}{\beta(1-c^{2})} (1 - e^{-\beta(a-x)})$$

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for x < a and

$$\begin{aligned} h_{+}(x) &= \frac{\eta}{\beta}(x-b) + \frac{\beta-\eta}{\beta^{2}}(1-e^{-\beta(x-b)}) + \left(\sum_{k=0}^{\infty}c^{2k+2}\right)\frac{2}{\beta}(1-e^{-\beta(x-b)}) \\ &= \frac{\eta}{\beta}(x-b) + \frac{\beta-\eta}{\beta^{2}}(1-e^{-\beta(x-b)}) + \frac{2c^{2}}{\beta(1-c^{2})}(1-e^{-\beta(x-b)}) \\ &= \frac{\eta}{\beta}(x-b) + \left(\frac{\beta-\eta}{\beta^{2}} + \frac{2c^{2}}{\beta(1-c^{2})}\right)(1-e^{-\beta(x-b)}) \end{aligned}$$

for x > b. Analogously we obtain

$$h_{-}(x) = \begin{cases} \frac{2c}{\beta(1-c^{2})}(1-e^{-\beta(x-b)}) & \text{if } x > b\\ \frac{\eta}{\beta}(a-x) + \left(\frac{\beta-\eta}{\beta^{2}} + \frac{2c^{2}}{\beta(1-c^{2})}\right)(1-e^{-\beta(a-x)}) & \text{if } x < a \end{cases}$$

and, finally,

$$h(x) = \begin{cases} \frac{\eta}{\beta}(x-b) + \left(\frac{\beta-\eta}{\beta^2} + \frac{2(c+c^2)}{\beta(1-c^2)}\right)(1-e^{-\beta(x-b)}) & \text{if } x > b\\ \frac{\eta}{\beta}(a-x) + \left(\frac{\beta-\eta}{\beta^2} + \frac{2(c+c^2)}{\beta(1-c^2)}\right)(1-e^{-\beta(a-x)}) & \text{if } x < a, \end{cases}$$

using that by symmetry $\kappa = \hat{\kappa}$ and consequently $C = \lim_{q \searrow 0} \kappa(q) / \hat{\kappa}(q) = 1$.

Remark 3.1. It does not seem to be straightforward to find a general class of examples which are as explicit as this one. For instance, suppose ξ is a process in the 'meromorphic class' defined by [10], which includes those Lévy processes with rational Laplace exponent. Then, the overshoot distributions can be expressed in terms of affine combinations of exponential densities and their products (see [10, Theorem 3]) and the same is true of the renewal measures U_{\pm} (thanks to the expression for the Laplace exponent of the ladder height process found in [10, Corollary 2(ii)]). Therefore, the measures ν_k^x from this work, and the functions h_{\pm} and h, can be found as repeated convolutions of measures of this type. This is explicit enough to permit numerical evaluation of h_{\pm} , say, but not to give satisfactory analytic expressions.

4 Proofs

Before going into the proofs let us discuss the form of the measures ν_k defined before. We assume in the theorems that ξ oscillates, hence, all appearing first hitting times are almost surely finite. Keep in mind that on the event $\{K^{\dagger} > k\}$ the time τ_k is the time of the k^{th} jump across the interval. By the strong Markov property and $\nu_0^x(\mathrm{d} y) = \delta_x(\mathrm{d} y)$, we find the relations

$$\nu_{2k+1}^{x}(\mathrm{d}y) = \int_{(b,\infty)} \mathbb{P}^{z}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}y) \nu_{2k}^{x}(\mathrm{d}z) = \int_{(b,\infty)} \nu_{1}^{z}(\mathrm{d}y) \nu_{2k}^{x}(\mathrm{d}z),$$
$$\nu_{2k}^{x}(\mathrm{d}y) = \int_{(-\infty,a)} \mathbb{P}^{z}(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) \nu_{2k-1}^{x}(\mathrm{d}z) = \int_{(-\infty,a)} \nu_{1}^{z}(\mathrm{d}y) \nu_{2k-1}^{x}(\mathrm{d}z),$$

for x > b, and

$$\nu_{2k+1}^{x}(\mathrm{d}y) = \int_{(-\infty,a)} \mathbb{P}^{z}(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) \, \nu_{2k}^{x}(\mathrm{d}z) = \int_{(-\infty,a)} \nu_{1}^{z}(\mathrm{d}y) \, \nu_{2k}^{x}(\mathrm{d}z),$$
$$\nu_{2k}^{x}(\mathrm{d}y) = \int_{(b,\infty)} \mathbb{P}^{z}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}y) \, \nu_{2k-1}^{x}(\mathrm{d}z) = \int_{(b,\infty)} \nu_{1}^{z}(\mathrm{d}y) \, \nu_{2k-1}^{x}(\mathrm{d}z),$$

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for x < a. More generally, the strong Markov property also implies the relation

$$\int_{(b,\infty)} \nu_l^z(\mathrm{d}y) \, \nu_{2k}^x(\mathrm{d}z) = \nu_{2k+l}^x(\mathrm{d}y) \quad \text{and} \quad \int_{(-\infty,a)} \nu_l^z(\mathrm{d}y) \, \nu_{2k+1}^x(\mathrm{d}z) = \nu_{2k+l+1}^x(\mathrm{d}y) \quad (4.1)$$

for x > b and $k, l \in \mathbb{N}$ and the analogous identities hold for x < a. It is important to note that (see e.g. Bertoin [1], Proposition III.2) analytic formulas exist for the overshoot distributions:

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) = \int_{[x,a]} \mu_{+}(\mathrm{d}y - u) U_{+}(\mathrm{d}u - x), \quad x < a < y,$$
(4.2)

and, analogously,

$$\mathbb{P}^{x}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}y) = \int_{[b,x]} \mu_{-}(u - \mathrm{d}y) U_{-}(x - \mathrm{d}u), \quad x > b > y.$$
(4.3)

Hence, analytic expressions for the ν_k^x exist in the oscillating case even though these become more involved for big k due to the recursive definition. As an example, for x > b, we have

$$\nu_2^x(\mathrm{d}y) = \int_{(-\infty,a)} \mathbb{P}^z(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) \mathbb{P}^x(\xi_{T_{(-\infty,b]}} \in \mathrm{d}z)$$
$$= \int_{(-\infty,a)} \left[\int_{[b,x]} \left(\int_{[x,a]} \mu_+(\mathrm{d}y-u) U_+(\mathrm{d}u-x) \right) \mu_-(w-\mathrm{d}z) \right] U_-(x-\mathrm{d}w).$$

4.1 Finiteness of the harmonic function

Since h_+ and h_- are defined by infinite series finiteness has to be proved. Along the way we deduce upper bounds that are needed in the sections below.

Note that Assumption (A) implies that $\mathbb{E}[H_1]$ and $\mathbb{E}[H_1]$ are finite and this will be crucial for the technical steps which are necessary to prove the following.

Proposition 4.1. Assume (A), then there are constants $c_1, c_2, c_3 \ge 0$ such that

$$h_{+}(x) \le c_{1}U_{-}(x-b)\mathbb{1}_{\{x>b\}} + c_{2}U_{+}(a-x)\mathbb{1}_{\{x$$

in particular $h_+(x)$ is finite for all $x \in \mathbb{R} \setminus [a, b]$.

Before we start with the proof, we need a lemma which is intuitively clear, but needs a certain argumentation:

Lemma 4.2. Let ξ be a Lévy process which is not the negative of a subordinator. Then, for all y, z > 0,

$$\mathbb{P}(T_{(-\infty,-y]} > T_{[z,\infty)}) > 0.$$

Proof. Assume $\mathbb{P}(T_{(-\infty,-y]} \leq T_{[z,\infty)}) = 1$. For any x < 0, we have $T_{[z-x,\infty)} \geq T_{[z,\infty)}$ almost surely under \mathbb{P} , and it then follows that

$$\mathbb{P}^{x}(T_{(-\infty,x-y]} \le T_{[z,\infty)}) = \mathbb{P}(T_{(-\infty,-y]} \le T_{[z-x,\infty)})$$
$$\geq \mathbb{P}(T_{(-\infty,-y]} \le T_{[z,\infty)})$$
$$= 1$$

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for all x < 0. With the strong Markov property we get, for s > 0,

$$\mathbb{P}(T_{[z,\infty)} < s) \leq \mathbb{P}(T_{[z,\infty)} < T_{(-\infty,-y]} + s)$$

$$= \mathbb{E}\left[\mathbb{P}^{\xi_{T_{(-\infty,-y]}}}(T_{[z,\infty)} < s)\right]$$

$$\leq \mathbb{P}^{-y}(T_{[z,\infty)} < s)$$

$$\leq \mathbb{P}^{-y}(T_{[z,\infty)} < T_{(-\infty,-2y]} + s)$$

$$= \mathbb{E}^{-y}\left[\mathbb{P}^{\xi_{T_{(-\infty,-2y]}}}(T_{[z,\infty)} < s)\right]$$

$$\leq \mathbb{P}^{-2y}(T_{[z,\infty)} < s).$$

Inductively we get $\mathbb{P}(T_{[z,\infty)} < s) \leq \mathbb{P}^{-ny}(T_{[z,\infty)} < s)$ for all $n \in \mathbb{N}$ and hence

$$\mathbb{P}(T_{[z,\infty)} < s) \leq \lim_{n \to \infty} \mathbb{P}^{-ny}(T_{[z,\infty)} < s) = 0.$$

With this we see

$$\mathbb{P}(T_{[z,\infty)} < +\infty) = \lim_{s \to \infty} \mathbb{P}(T_{[z,\infty)} < s) \le \lim_{s \to \infty} \lim_{n \to \infty} \mathbb{P}^{-ny}(T_{[z,\infty)} < s) = 0,$$

but this cannot happen unless ξ is the negative of a subordinator. This concludes the proof. $\hfill \Box$

To prove Proposition 4.1 we will combine two statements. The discrete analogous statements were also used (with different arguments) by Vysotsky [23] to show finiteness of the harmonic function in the discrete case.

Lemma 4.3. Suppose that ξ is not a subordinator and $\mathbb{E}[H_1] < \infty$, then

$$\gamma_+ := \sup_{x < a} \mathbb{P}^x(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) < 1.$$

Proof. If ξ is the negative of a subordinator it holds $\gamma_+ = 0$. So assume that ξ is not the negative of a subordinator, in particular we can apply Lemma 4.2.

We separate three regions of the range of x. First we consider very small x, i.e. we consider the limit of x tending to $-\infty$, then we consider the values of x which are close to a and last we treat the remaining values.

We begin with x close to $-\infty$. If ξ drifts to $-\infty$, then $\mathbb{P}^x(T_{[a,\infty]} < \infty) \to 0$ as $x \searrow -\infty$, and in particular $\mathbb{P}^x(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) \to 0$ also. Therefore there exist a K < a and a $\gamma_1 < 1$ such that $\mathbb{P}^x(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) < \gamma_1$ when $x \le K$.

If ξ oscillates or drifts to ∞ , the bound for x close to $-\infty$ is more involved. Because $\mathbb{E}[H_1] < \infty$, ξ has stationary overshoots in the sense that the weak limit of $\mathbb{P}^x(\xi_{T_{[a,\infty)}} \in dy)$ for $x \searrow -\infty$ exists. It can be expressed as

$$\underset{x\searrow -\infty}{\text{w-lim}} \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) = \frac{1}{\mathbb{E}[H_{1}]}(a_{+}\delta_{a}(\mathrm{d}y) + \bar{\mu}_{+}(y-a)\mathrm{d}y),$$
(4.4)

where a_+ is the drift of (H, \mathbb{P}) and μ_+ its Lévy measure with the right-tail $\bar{\mu}_+$. For the first special version of a subordinator see for example Bertoin et al. [4], for the general version for example Bertoin and Savov [3]. Since weak convergence is equivalent to the pointwise convergence of the distribution function at continuity points, due to the

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explicit formula in (4.4) it holds that, for b > a,

$$\lim_{x \to -\infty} \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b) = \frac{1}{\mathbb{E}[H_{1}]} \int_{(b,\infty)} \bar{\mu}_{+}(y-a) dy$$
$$= \frac{1}{\mathbb{E}[H_{1}]} \int_{(b-a,\infty)} \bar{\mu}_{+}(y) dy$$
$$< \frac{1}{\mathbb{E}[H_{1}]} \int_{(0,\infty)} \bar{\mu}_{+}(y) dy$$
$$\leq 1.$$

Hence, also in this case there exist a K < a and a $\gamma_1 < 1$ such that

$$\mathbb{P}^x(\xi_{T_{[a,\infty)}} > b) \le \gamma_1$$

for all $x \leq K$. Now we have to treat the case $x \in (K, a)$. Therefore we separate two cases.

Case 1: The process ξ is regular upwards. First, we consider the limit for $x \nearrow a$. Since ξ is regular upwards it holds

$$\lim_{x \nearrow a} \mathbb{P}^x(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) < 1$$

and hence, there is some $\delta > 0$ such that

$$\gamma_2 := \sup_{x \in (a-\delta,a)} \mathbb{P}^x(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) < 1.$$

It remains to consider $x \in (K, a - \delta]$. First note that

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty)$$

= $\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} < T_{[a,\infty)} < \infty) + \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} > T_{[a,\infty)}).$

For the first term we use the Markov property to get

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} < T_{[a,\infty)} < \infty) = \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,K]} < T_{[a,\infty)} < \infty\}} \mathbb{P}^{\xi_{T_{(-\infty,K]}}}(\xi_{T_{[a,\infty)}} > b) \Big]$$

$$\leq \gamma_{1} \mathbb{P}^{x}(T_{(-\infty,K]} < T_{[a,\infty)} < \infty)$$

$$\leq \gamma_{1} \mathbb{P}^{x}(T_{(-\infty,K]} < T_{[a,\infty)}).$$

Together we have for all $x \in (K, a - \delta]$:

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) \leq \sup_{x \in (K,a-\delta]} \left(\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} < T_{[a,\infty)} < \infty) + \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} > T_{[a,\infty)}) \right)$$
$$\leq \sup_{x \in (K,a-\delta]} \left(\gamma_{1} \mathbb{P}^{x}(T_{(-\infty,K]} < T_{[a,\infty)}) + \mathbb{P}^{x}(T_{(-\infty,K]} > T_{[a,\infty)}) \right)$$
$$=: \gamma_{3}.$$

With Lemma 4.2 (applying on the dual process which is not the negative of a subordinator) we get

$$\sup_{x \in (K, a-\delta)} \mathbb{P}^x(T_{(-\infty, K]} > T_{[a, \infty)}) = \mathbb{P}^{a-\delta}(T_{(-\infty, K]} > T_{[a, \infty)}) < 1$$

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or, equivalently,

$$\inf_{x \in (K, a-\delta)} \mathbb{P}^x(T_{(-\infty, K]} < T_{[a,\infty)}) > 0$$

Because of this it follows that

$$\gamma_3 < \sup_{x \in (K, a - \delta)} \left(\mathbb{P}^x(T_{(-\infty, K]} < T_{[a, \infty)}) + \mathbb{P}^x(T_{(-\infty, K]} > T_{[a, \infty)}) \right) = 1.$$

Case 2: The process $\boldsymbol{\xi}$ is not regular upwards. In this case it holds

$$\sup_{x \in (K,a)} \mathbb{P}^x (T_{[a,\infty)} < T_{(-\infty,K]}) < 1,$$

or equivalently

$$\inf_{x \in (K,a)} \mathbb{P}^x(T_{(-\infty,K]} < T_{[a,\infty)}) > 0.$$
(4.5)

We split up again

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty)$$

= $\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} < T_{[a,\infty)} < \infty) + \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} > T_{[a,\infty)}).$

For the first term we use the Markov property to get

$$\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} < T_{[a,\infty)} < \infty) = \mathbb{E}^{x} \left[\mathbbm{1}_{\{T_{(-\infty,K]} < T_{[a,\infty)} < \infty\}} \mathbb{P}^{\xi_{T_{(-\infty,K]}}}(\xi_{T_{[a,\infty)}} > b) \right]$$
$$\leq \gamma_{1} \mathbb{P}^{x}(T_{(-\infty,K]} < T_{[a,\infty)} < \infty)$$
$$\leq \gamma_{1} \mathbb{P}^{x}(T_{(-\infty,K]} < T_{[a,\infty)}).$$

Together we have for all $x \in (K, a)$:

$$\begin{split} \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{[a,\infty)} < \infty) &\leq \sup_{x \in (K,a)} \left(\mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} < T_{[a,\infty)} < \infty) \right. \\ & \left. + \mathbb{P}^{x}(\xi_{T_{[a,\infty)}} > b, T_{(-\infty,K]} > T_{[a,\infty)}) \right) \\ &\leq \sup_{x \in (K,a)} \left(\gamma_{1} \mathbb{P}^{x}(T_{(-\infty,K]} < T_{[a,\infty)}) + \mathbb{P}^{x}(T_{(-\infty,K]} > T_{[a,\infty)}) \right) \\ &=: \gamma_{3}. \end{split}$$

From (4.5) follows that

$$\gamma_3 < \sup_{x \in (K,a)} \left(\mathbb{P}^x(T_{(-\infty,K]} < T_{[a,\infty)}) + \mathbb{P}^x(T_{(-\infty,K]} > T_{[a,\infty)}) \right) = 1.$$

For both of the two cases, set $\gamma_+ := \max(\gamma_1, \gamma_2, \gamma_3) < 1$.

Analogously to the lemma before it holds

$$\gamma_{-} := \sup_{x > b} \mathbb{P}^{x}(\xi_{T_{(-\infty,b]}} < a, T_{(-\infty,b]} < \infty) < 1,$$

provided that $\hat{\mathbb{E}}[H_1] < \infty$. The second Lemma which we need to prove Proposition 4.1 is the following:

Lemma 4.4. Assume ξ oscillates and $\hat{\mathbb{E}}[H_1] < \infty$. For all $\alpha \in (0,1)$ there exists a constant $C_+(\alpha) > 0$ such that

$$\mathbb{E}^{x} \Big[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} < a\}} \Big] \le \alpha U_{-}(x - b) + C_{+}(\alpha)$$

for all x > b.

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Proof. We start to show that

$$\int_{(K,\infty)} U_+(y)\,\mu_-(\mathrm{d} y) < +\infty$$

for all K > 0. For that we estimate $U_+(y)$ for y > K with Proposition III.1 of Bertoin [1] which says that there are constants $c_1, c_2 \ge 0$ such that

$$U_{+}(x) \le c_1 \left(\Phi\left(\frac{1}{x}\right) \right)^{-1}$$
 and $\Phi(x) \ge c_2 x \left(I\left(\frac{1}{x}\right) + a_{+} \right)$

for all x > 0, where $\Phi(\lambda) = \mathbb{E}\left[\int_{[0,\infty)} e^{-\lambda H_t} dt\right]$ and $I(x) = \int_{(0,x]} \bar{\mu}_+(y) dy$. We combine these two statements as follows:

$$U_{+}(x) \le c_1 \left(\Phi\left(\frac{1}{x}\right)\right)^{-1} \le c_1 \left(c_2 \frac{1}{x}(I(x) + a_{+})\right)^{-1} = \frac{c_1}{c_2} \frac{x}{I(x) + a_{+}} \le \frac{c_1}{c_2} \frac{x}{I(K)} = c_K x$$

for all x > K, where $c_K = \frac{c_1}{c_2 I(K)}$. Hence, by assumption,

$$\int_{(K,\infty)} U_+(y)\,\mu_-(\mathrm{d}y) \le c_K \int_{(K,\infty)} y\,\mu_-(\mathrm{d}y) \le c_K \hat{\mathbb{E}}\left[H_1\right] < +\infty$$

for all K > 0. The second inequality can be seen from $\hat{\mathbb{E}}[H_1] = \int_{(0,\infty)} y \mu_-(dy) + a_$ because H is a subordinator. Now, for fixed $\alpha \in (0,1)$, choose $K = K(\alpha) > 0$ such that

$$\int_{(K,\infty)} U_+(y)\,\mu_-(\mathrm{d}y) < \alpha. \tag{4.6}$$

To prove the claim let us first split as

$$\mathbb{E}^{x} \Big[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} < a\}} \Big]$$

= $\mathbb{E}^{x} \Big[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} \in [a-K,a)\}} \Big] + \mathbb{E}^{x} \Big[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} \in (-\infty,a-K)\}} \Big]$

and estimate the first summand, using monotonicity of U_+ , as

$$\mathbb{E}^{x} \left[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} \in [a-K,a)\}} \right] \leq U_{+}(K).$$

Applying the overshoot formula (4.3) the second summand can be treated in the following way:

$$\begin{split} & \mathbb{E}^{x} \Big[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} \in (-\infty,a-K)\}} \Big] \\ &= \int_{(-\infty,a-K)} U_{+}(a - y) \mathbb{P}^{x}(\xi_{T_{(-\infty,b]}} \in \mathrm{d}y) \\ &= \int_{[b,x]} \Big(\int_{(-\infty,a-K)} U_{+}(a - y) \mu_{-}(w - \mathrm{d}y) \Big) U_{-}(x - \mathrm{d}w) \\ &= \int_{[b,x]} \Big(\int_{(K+w-a,\infty)} U_{+}(y - w + a) \mu_{-}(\mathrm{d}y) \Big) U_{-}(x - \mathrm{d}w) \\ &\leq \int_{[b,x]} \Big(\int_{(K,\infty)} U_{+}(y) \mu_{-}(\mathrm{d}y) \Big) U_{-}(x - \mathrm{d}w) \\ &\leq \alpha U_{-}(x - b). \end{split}$$

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Defining $C_+(\alpha) \coloneqq U_+(K)$ we proved

$$\mathbb{E}^{x} \left[U_{+}(a - \xi_{T_{(-\infty,b]}}) \mathbb{1}_{\{\xi_{T_{(-\infty,b]}} < a\}} \right] \le \alpha U_{-}(x - b) + C_{+}(\alpha)$$

for all x > b.

Analogously to the lemma above one can show in the case that ξ oscillates and $\mathbb{E}[H_1] < \infty$ that for all $\alpha \in (0, 1)$ there exists a constant $C_-(\alpha) > 0$ such that

$$\mathbb{E}^{x} \left[U_{-}(\xi_{T_{[a,\infty)}} - b) \mathbb{1}_{\{\xi_{T_{[a,\infty)}} > b\}} \right] \le \alpha U_{+}(a - x) + C_{-}(\alpha), \quad x < a.$$

Now we are ready to combine Lemmas 4.3 and 4.4 to show finiteness of $h_+(x)$. The idea how to combine them was also used by Vysotsky [23].

Proof of Proposition 4.1. Set

$$\gamma = \max(\gamma_+, \gamma_-) < 1, \tag{4.7}$$

and let $\alpha \in (\gamma, 1)$ be arbitrary. In the first step we use the finiteness of $\mathbb{E}[H_1]$ and $\hat{\mathbb{E}}[H_1]$ combined with Lemmas 4.3 and 4.4 to find an upper bound for

$$\int_{(b,\infty)} U_-(y-b)\,\nu_{2k}^x(\mathrm{d} y), \quad x > b.$$

Note, from the definition of γ and by Lemma 4.3, that for x > b and $k \ge 1$:

$$\nu_{2k-1}^{x}(-\infty,a) = \int_{(b,\infty)} \mathbb{P}^{y}(\xi_{T_{(-\infty,b]}} < a) \nu_{2k-2}^{x}(\mathrm{d}y) \\
\leq \gamma \nu_{2k-2}^{x}(b,\infty) \\
= \gamma \Big(\mathbb{1}_{\{k=1\}} + \mathbb{1}_{\{k\geq 2\}} \int_{(-\infty,a)} \mathbb{P}^{y}(\xi_{T_{[a,\infty)}} > b) \nu_{2k-3}^{x}(\mathrm{d}y) \Big) \\
\leq \gamma \Big(\mathbb{1}_{\{k=1\}} + \gamma \mathbb{1}_{\{k\geq 2\}} \nu_{2k-3}^{x}(-\infty,a) \Big).$$

Inductively we get

$$\nu_{2k-1}^x(-\infty,a) \le \gamma^{2k-1}$$

for x > b and $k \ge 1$. Analogously for $k \ge 1$ we can show

$$\nu_{2k}^x(b,\infty) \le \gamma^{2k}$$

for x > b and

$$\nu^x_{2k-1}(b,\infty) \leq \gamma^{2k-1} \quad \text{and} \quad \nu^x_{2k}(-\infty,a) \leq \gamma^{2k}$$

for x < a. Now set $C(\alpha) = \max(C_{-}(\alpha), C_{+}(\alpha))$ and use Lemma 4.4 for $k \ge 1$ to find

$$\int_{(b,\infty)} U_{-}(y-b) \nu_{2k}^{x}(\mathrm{d}y) = \int_{(-\infty,a)} \left(\int_{(b,\infty)} U_{-}(y-b) \mathbb{P}^{v}(\xi_{T_{[a,\infty)}} \in \mathrm{d}y) \right) \nu_{2k-1}^{x}(\mathrm{d}v)$$

$$\leq \int_{(-\infty,a)} \alpha U_{+}(a-v) \nu_{2k-1}^{x}(\mathrm{d}v) + C(\alpha) \nu_{2k-1}^{x}(-\infty,a)$$

$$\leq \alpha \int_{(-\infty,a)} U_{+}(a-v) \nu_{2k-1}^{x}(\mathrm{d}v) + C(\alpha) \gamma^{2k-1}.$$

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We estimate the first term in the same way by

$$\alpha^2 \int_{(b,\infty)} U_{-}(y-b)\nu^x_{2k-2}(\mathrm{d}y) + C(\alpha)\alpha\gamma^{2k-2}$$

and hence,

$$\int_{(b,\infty)} U_{-}(y-b) \nu_{2k}^{x}(\mathrm{d}y) \le \alpha^{2} \int_{(b,\infty)} U_{-}(b-y) \nu_{2k-2}^{x}(\mathrm{d}y) + C(\alpha)(\gamma^{2k-1} + \alpha\gamma^{2k-2}).$$

Going on with this procedure until ν_0^x we see

$$\int_{(b,\infty)} U_{-}(y-b) \nu_{2k}^{x}(\mathrm{d}y) \leq U_{-}(x-b)\alpha^{2k} + C(\alpha) \sum_{i=0}^{2k-1} \gamma^{i} \alpha^{2k-1-i}$$
$$= U_{-}(x-b)\alpha^{2k} + C(\alpha)\alpha^{2k-1} \sum_{i=0}^{2k-1} \left(\frac{\gamma}{\alpha}\right)^{i}.$$

Now note

$$\alpha^{2k-1} \sum_{i=0}^{2k-1} \left(\frac{\gamma}{\alpha}\right)^i = \alpha^{2k-1} \frac{\left(\frac{\gamma}{\alpha}\right)^{2k} - 1}{\frac{\gamma}{\alpha} - 1} = \frac{\gamma^{2k} - \alpha^{2k}}{\gamma - \alpha}$$

and hence

$$\int_{(b,\infty)} U_-(y-b)\,\nu_{2k}^x(\mathrm{d}y) \le U_-(x-b)\alpha^{2k} + \frac{C(\alpha)}{\gamma - \alpha}(\gamma^{2k} - \alpha^{2k})$$

for $k \ge 1$ (for k = 0 we get obiously $U_{-}(x - b)$ as upper bound). In the same way we get for x < a:

$$\int_{(b,\infty)} U_{-}(y-b) \nu_{2k+1}^{x}(\mathrm{d}y) \le U_{+}(a-x)\alpha^{2k+1} + \frac{C(\alpha)}{\gamma - \alpha}(\gamma^{2k+1} - \alpha^{2k+1})$$

for $k \geq 0$ (here we get an upper bound dependent on U_+ because the number of steps is odd). All together we get

$$\begin{split} h_{+}(x) \\ &\leq \mathbbm{1}_{(b,\infty)}(x)U_{-}(x-b)\sum_{k=0}^{\infty}\alpha^{2k} + \mathbbm{1}_{(-\infty,a)}(x)U_{+}(a-x)\sum_{k=0}^{\infty}\alpha^{2k+1} + \frac{C(\alpha)}{\gamma-\alpha}\sum_{k=0}^{\infty}(\gamma^{k}-\alpha^{k}) \\ &= \frac{1}{1-\alpha^{2}}U_{-}(x-b)\mathbbm{1}_{(b,\infty)}(x) + \frac{\alpha}{1-\alpha^{2}}U_{+}(a-x)\mathbbm{1}_{(-\infty,a)}(x) + \frac{C(\alpha)}{\gamma-\alpha}\left(\frac{1}{1-\gamma} - \frac{1}{1-\alpha}\right) \\ &\text{ich finishes the proof of Proposition 4.1.} \\ \Box$$

which finishes the proof of Proposition 4.1.

4.2 Harmonicity of h_+ and h_-

In this section we give the proof of Theorem 2.1. Define, for $q \ge 0$ and $x \notin [a, b]$, the auxiliary functions

$$\begin{split} h^q_+(x) &:= \begin{cases} \sum_{k=0}^\infty \int U^q_-(y-b)\,\nu^x_{2k}(\mathrm{d} y) & \text{if } x > b \\ \sum_{k=0}^\infty \int U^q_-(y-b)\,\nu^x_{2k+1}(\mathrm{d} y) & \text{if } x < a \end{cases} \\ &= \begin{cases} \sum_{k=0}^\infty \mathbb{E}^x \Big[U^q_-(\xi_{\tau_{2k}}-b)\mathbbm{1}_{\{K^\dagger \ge 2k,\tau_{2k} < \infty\}} \Big] & \text{if } x > b \\ \sum_{k=0}^\infty \mathbb{E}^x \Big[U^q_-(\xi_{\tau_{2k+1}}-b)\mathbbm{1}_{\{K^\dagger \ge 2k+1,\tau_{2k+1} < \infty\}} \Big] & \text{if } x < a \end{cases}, \end{split}$$

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where $U_{-}^{q}(\mathrm{d}x) \coloneqq \mathbb{E}\left[\int_{[0,\infty)} e^{-qt} \mathbb{1}_{\{H_t \in \mathrm{d}x, L_t^{-1} < \infty\}} \mathrm{d}t\right]$ is the *q*-potential of the dual ladder height process. It follows immediately that $h_{+}^{q}(x) \leq h_{+}(x)$ for all $x \notin [a, b]$ and by monotone convergence that h_{+}^{q} converges pointwise to h_{+} for $q \searrow 0$.

Proposition 4.5. Assume (A) and let e_q be independent exponentially distributed random variables with parameter q > 0. Then, for $x \notin [a, b]$,

$$\frac{1}{\hat{\kappa}(q)} \mathbb{P}^x \left(e_q < T_{[a,b]}, \xi_{e_q} > b \right) \le h^q_+(x), \quad q > 0,$$
(4.8)

and

$$\lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^x \left(e_q < T_{[a,b]}, \xi_{e_q} > b \right) = h_+(x).$$
(4.9)

To prove this crucial proposition we need a small lemma which is basically just the strong Markov property:

Lemma 4.6. Let be $s \ge 0$ and $k \ge 0$. Then it holds

$$\int_{(b,\infty)} \mathbb{P}^{y}(s < T_{(-\infty,b]}) \nu_{2k}^{x}(\mathrm{d}y) = \mathbb{P}^{x}\left(s < \tau_{2k+1} - \tau_{2k}, K^{\dagger} \ge 2k+1\right)$$

and

$$\int_{(-\infty,a)} \mathbb{P}^{y}(s < T_{[a,\infty)}) \nu_{2k+1}^{x}(\mathrm{d}y) = \mathbb{P}^{x}\left(s < \tau_{2k+2} - \tau_{2k+1}, K^{\dagger} \ge 2k+2\right)$$

for x > b and

(-

$$\int_{\infty,a)} \mathbb{P}^y(s < T_{[a,\infty)}) \nu_{2k}^x(\mathrm{d}y) = \mathbb{P}^x\left(s < \tau_{2k+1} - \tau_{2k}, K^{\dagger} \ge 2k+1\right)$$

and

$$\int_{(b,\infty)} \mathbb{P}^{y}(s < T_{(-\infty,b]}) \nu_{2k+1}^{x}(\mathrm{d}y) = \mathbb{P}^{x}\left(s < \tau_{2k+2} - \tau_{2k+1}, K^{\dagger} \ge 2k+2\right)$$

for x < a.

Proof. We focus on the case x > b and prove the first equality. We use the strong Markov property in the shift operator formulation, see e.g. Chung and Walsh [6], p. 57. Therefore we introduce $D := \{\omega : [0, \infty) \to \mathbb{R} \mid \omega \text{ is RCLL}\}$. The shift operator is a map $\theta_t : D \to D$ such that $X_s \circ \theta_t = X_{t+s}$. The strong Markov property tells that for a $(\mathcal{F}_t)_{t\geq 0}$ -stopping time T it holds

$$\mathbb{1}_{\{T<\infty\}}\mathbb{E}^{\xi_T}[Y] = \mathbb{1}_{\{T<\infty\}}\mathbb{E}^x\left[Y\circ\theta_T\,|\,\mathcal{F}_T\right]$$
(4.10)

for all $\mathcal{F}_{\infty} := \bigcup_{t \ge 0} \mathcal{F}_t$ -measurable and integrable Y. Here, we set $T = \tau_{2k}$ and $Y = \mathbb{1}_{\{s < T_{(-\infty,b]}\}}$. It is clear that Y is bounded and that Y is \mathcal{F}_{∞} -measurable can be seen as follows:

$$\{s < T_{(-\infty,b]}\} = \{T_{(-\infty,b]} \le s\}^{\mathcal{C}} \in \mathcal{F}_s \subseteq \mathcal{F}_\infty.$$

With (4.10) we obtain for our choice of *Y*:

$$\mathbb{P}^{\xi_{\tau_{2k}}}\left(s < T_{(-\infty,b]}\right) = \mathbb{E}^{x}\left[\mathbb{1}_{\{s < T_{(-\infty,b]}\}} \circ \theta_{\tau_{2k}} \,|\, \mathcal{F}_{\tau_{2k}}\right].$$

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Using this we get

$$\int_{(b,\infty)} \mathbb{P}^{y} (s < T_{(-\infty,b]}) \nu_{2k}^{x} (dy)$$

$$= \mathbb{E}^{x} \left[\mathbb{1}_{\{\xi_{\tau_{2k}} > b, K^{\dagger} \ge 2k\}} \mathbb{P}^{\xi_{\tau_{2k}}} (s < T_{(-\infty,b]}) \right]$$

$$= \mathbb{E}^{x} \left[\mathbb{1}_{\{\xi_{\tau_{2k}} > b, K^{\dagger} \ge 2k\}} \mathbb{E}^{x} \left[\mathbb{1}_{\{s < T_{(-\infty,b]}\}} \circ \theta_{\tau_{2k}} | \mathcal{F}_{\tau_{2k}} \right] \right]$$

$$= \mathbb{E}^{x} \left[\mathbb{1}_{\{\tau_{2k} < T_{[a,b]}\}} \mathbb{P}^{x} (s + \tau_{2k} < \tau_{2k+1} | \mathcal{F}_{\tau_{2k}}) \right]$$

$$= \mathbb{E}^{x} \left[\mathbb{P}^{x} (\tau_{2k} < T_{[a,b]}, s < \tau_{2k+1} - \tau_{2k} | \mathcal{F}_{\tau_{2k}}) \right]$$

$$= \mathbb{P}^{x} (K^{\dagger} \ge 2k + 1, s < \tau_{2k+1} - \tau_{2k}).$$

We used that $\{\xi_{\tau_{2k}} > b\} \in \mathcal{F}_{\tau_{2k}}$ and $\{\tau_{2k} < T_{[a,b]}\} \in \mathcal{F}_{\tau_{2k}} \cap \mathcal{F}_{T_{[a,b]}} \subseteq \mathcal{F}_{\tau_{2k}}$ which can be seen by Theorem 1.3.6 of [6]. The remaining claims follow analogously.

Now we continue the proof of Proposition 4.5 for which we use the identity

$$\hat{\kappa}(q)U_{-}^{q}(x) = \mathbb{P}^{x}(e_{q} < T_{(-\infty,0]}), \quad x > 0, q > 0,$$
(4.11)

proved by Kyprianou [11], Section 13.2.1 for a general Lévy process.

Proof of Proposition 4.5. We only consider the case x > b and start to prove the bounds

$$1 \le \frac{\hat{\kappa}(q)h_{+}^{q}(x)}{\mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b)} \le \frac{1}{\mathbb{P}^{x}(e_{q} \ge T_{[a,b]})}.$$
(4.12)

To derive the lower bound we define $\tilde{\tau}_k = \min(\tau_k, T_{[a,b]})$. It follows, in particular, that $\tilde{\tau}_k = \tau_k$ on $K^{\dagger} \ge k$ and $\tilde{\tau}_{k+1} - \tilde{\tau}_k = 0$ on $K^{\dagger} \le k$. For the next chain of equalities we use (4.11), Lemma 4.6 and the lack of memory property of e_q :

$$\begin{split} \hat{\kappa}(q) & \int_{(b,\infty)} U_{-}^{q}(y-b) \, \nu_{2k}^{x}(\mathrm{d}y) = \int_{(b,\infty)} \mathbb{P}^{y}(e_{q} < T_{(-\infty,b]}) \, \nu_{2k}^{x}(\mathrm{d}y) \\ &= \mathbb{P}^{x}(\tau_{2k+1} - \tau_{2k} > e_{q}, K^{\dagger} \ge 2k+1) \\ &= \mathbb{P}^{x}(\tilde{\tau}_{2k+1} - \tilde{\tau}_{2k} > e_{q}) \\ &= \mathbb{P}^{x}(\tilde{\tau}_{2k+1} > e_{q}|e_{q} \ge \tilde{\tau}_{2k}) \\ &= \frac{\mathbb{P}^{x}(e_{q} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1}))}{\mathbb{P}^{x}(e_{q} \ge \tilde{\tau}_{2k})}. \end{split}$$

Furthermore, it holds that

$$\mathbb{P}^x(e_q \ge \tilde{\tau}_{2k}) \ge \mathbb{P}^x(e_q \ge T_{[a,b]})$$

because $\tilde{\tau}_{2k} \leq T_{[a,b]}$. So we obtain

$$\mathbb{P}^{x}(e_{q} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1})) \leq \hat{\kappa}(q) \int_{(b,\infty)} U_{-}^{q}(y-b) \nu_{2k}^{x}(\mathrm{d}y) \leq \frac{\mathbb{P}^{x}(e_{q} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1}))}{\mathbb{P}^{x}(e_{q} \geq T_{[a,b]})}.$$
 (4.13)

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Before proving the bounds of (4.12) we note that

$$\mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) = \mathbb{P}^{x}(e_{q} < \lim_{k \to \infty} \tilde{\tau}_{k}, \xi_{e_{q}} > b)
= \mathbb{P}^{x} \Big(\bigcup_{k=0}^{\infty} \{e_{q} \in [\tilde{\tau}_{k}, \tilde{\tau}_{k+1}), \xi_{e_{q}} > b\} \Big)
= \mathbb{P}^{x} \Big(\bigcup_{k=0}^{\infty} \{e_{q} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1})\} \Big)
= \sum_{k=0}^{\infty} \mathbb{P}^{x}(e_{q} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1})).$$
(4.14)

The first equality follows from the definition of $\tilde{\tau}_k$ and the facts that $T_{[a,b]} < \infty$ almost surely (because ξ is recurrent under Assumption (A)) and that τ_k diverges to $+\infty$ almost surely. The third one is due to the fact that for x < b the process remains above b only in the intervals $[\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1})$. With (4.14), summing (4.13) over k yields

$$\begin{split} \hat{\kappa}(q)h_{+}^{q}(x) &= \sum_{k=0}^{\infty} \hat{\kappa}(q) \int_{(b,\infty)} U_{-}^{q}(y-b) \nu_{2k}^{x}(\mathrm{d}y) \\ &\in \Big[\mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b), \frac{\mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b)}{\mathbb{P}^{x}(e_{q} \ge T_{[a,b]})} \Big] \end{split}$$

which is (4.12). Since ξ is recurrent $\mathbb{P}^{x}(e_q \geq T_{[a,b]})$ converges to 1 for $q \searrow 0$, hence, (4.12) implies the claim. \Box

The key for the proof of Theorem 2.1 are the relations in Proposition 4.5. We use them in a similar way Chaumont and Doney [5] proved harmonicity of a certain function for the Lévy process killed on the negative half-line.

Proof of Theorem 2.1. First note that (B) guarantees that $h_+(x)$ is strictly positive for all $x \in \mathbb{R} \setminus [a, b]$, which is not the case for x < a when (B) fails. From now on Assumption (B) won't be used anymore. For $x \in \mathbb{R} \setminus [a, b]$ and $t \ge 0$ we have to show

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} h_{+}(\xi_{t}) \right] = h_{+}(x).$$

First we show that the left-hand side is smaller or equal to the right-hand side. This can be done applying Proposition 4.5 in the first step and Fatou's Lemma in the second one:

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} h_{+}(\xi_{t}) \right] = \mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^{\xi_{t}}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \right]$$

$$\leq \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \right]$$

$$= \lim_{q \searrow 0} \frac{q}{\hat{\kappa}(q)} \int_{(0,\infty)} e^{-qs} \mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}}(s < T_{[a,b]}, \xi_{s} > b) \right] ds$$

$$= \lim_{q \searrow 0} \frac{q}{\hat{\kappa}(q)} \int_{(0,\infty)} e^{-qs} \mathbb{P}^{x}(s + t < T_{[a,b]}, \xi_{s+t} > b) ds$$

$$= \lim_{q \searrow 0} \frac{q}{\hat{\kappa}(q)} e^{qt} \int_{(t,\infty)} e^{-qs} \mathbb{P}^{x}(s < T_{[a,b]}, \xi_{s} > b) ds$$

$$= \lim_{q \searrow 0} \frac{q}{\hat{\kappa}(q)} e^{qt} \int_{(0,\infty)} e^{-qs} \mathbb{P}^{x}(s < T_{[a,b]}, \xi_{s} > b) ds$$

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$$\begin{split} &-\lim_{q\searrow 0} \frac{q}{\hat{\kappa}(q)} e^{qt} \int_{(0,t]} e^{-qs} \mathbb{P}^{x} (s < T_{[a,b]}, \xi_{s} > b) \, \mathrm{d}s \\ &= \lim_{q\searrow 0} \frac{1}{\hat{\kappa}(q)} e^{qt} \mathbb{P}^{x} (e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \\ &-\lim_{q\searrow 0} \frac{q}{\hat{\kappa}(q)} e^{qt} \int_{(0,t]} e^{-qs} \mathbb{P}^{x} (s < T_{[a,b]}, \xi_{s} > b) \, \mathrm{d}s \\ &= h_{+}(x) - \lim_{q\searrow 0} \frac{q}{\hat{\kappa}(q)} e^{qt} \int_{(0,t]} e^{-qs} \mathbb{P}^{x} (s < T_{[a,b]}, \xi_{s} > b) \, \mathrm{d}s \\ &= h_{+}(x). \end{split}$$

The last equality follows because, according to Kyprianou [11], Section 13.2.1, it holds that $\lim_{q\searrow 0} \frac{q}{\hat{\kappa}(q)} = 0$ if ξ oscillates. To show the equality it remains to show that we can replace the inequality in (4.15) by an equality. To apply the dominated convergence theorem, we use Proposition 4.5 which says also that

$$\frac{1}{\hat{\kappa}(q)} \mathbb{P}^{\xi_t} (e_q < T_{[a,b]}, \xi_{e_q} > b) \le h_+^q(\xi_t) \le h_+(\xi_t)$$

for all q > 0. Furthermore, we have just seen that

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} h_{+}(\xi_{t}) \right] \le h_{+}(x) < \infty.$$

So we can apply dominated convergence to switch the limit and the integral.

4.3 Conditioning and *h*-transforms

The aim of this section is to prove Proposition 2.4 and Theorem 2.5.

Proof of Proposition 2.4. Integrating out e_q and using Proposition 4.5, gives

$$\begin{split} &\lim_{q \searrow 0} \mathbb{P}^{x} (\Lambda \mid e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \\ &= \lim_{q \searrow 0} \frac{1}{\mathbb{P}^{x} (e_{q} < T_{[a,b]}, \xi_{e_{q}} > b)} \int_{(0,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s < T_{[a,b]}, \xi_{s} > b\right) \, \mathrm{d}s \\ &= \frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \int_{(0,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s < T_{[a,b]}, \xi_{s} > b\right) \, \mathrm{d}s \\ &= \frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \int_{(0,t]} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s < T_{[a,b]}, \xi_{s} > b\right) \, \mathrm{d}s \\ &+ \frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \int_{(t,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s < T_{[a,b]}, \xi_{s} > b\right) \, \mathrm{d}s. \end{split}$$

The first term is 0 because

$$\int_{(0,t]} q e^{-qs} \mathbb{P}^x \left(\Lambda, s < T_{[a,b]}, \xi_s > b \right) \, \mathrm{d}s \le \int_{(0,t]} q e^{-qs} \, \mathrm{d}s = 1 - e^{-qt}$$

and

$$\lim_{q\searrow 0} \frac{1-e^{-qt}}{\hat{\kappa}(q)} = \lim_{q\searrow 0} \frac{1-e^{-qt}}{q} \times \lim_{q\searrow 0} \frac{q}{\hat{\kappa}(q)} = t \times 0 = 0.$$

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That $1 - e^{-qt}/q$ converges to t can be seen via l'Hopital's rule and that $q/\hat{\kappa}(q)$ tends to 0 we have already seen in the proof of Theorem 2.1.

It follows by a substitution and the Markov property,

$$\begin{split} &\lim_{q \searrow 0} \mathbb{P}^{x} (\Lambda \mid e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \\ = &\frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \int_{(t,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s < T_{[a,b]}, \xi_{s} > b\right) \, \mathrm{d}s \\ = &\frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{e^{-qt}}{\hat{\kappa}(q)} \int_{(0,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s + t < T_{[a,b]}, \xi_{s+t} > b\right) \, \mathrm{d}s \\ = &\frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \int_{(0,\infty)} q e^{-qs} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}} (s < T_{[a,b]}, \xi_{s} > b) \right] \mathrm{d}s \\ = &\frac{1}{h_{+}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}} (e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \right]. \end{split}$$

From Proposition 4.5 we also know $\frac{1}{\hat{\kappa}(q)}\mathbb{P}^{\xi_t}(e_q < T_{[a,b]}, \xi_{e_q} > b) \leq h_+(\xi_t)$ for all q > 0 and $\mathbb{1}_{\Lambda}\mathbb{1}_{\{t < T_{[a,b]}\}}h_+(\xi_t)$ is integrable since h_+ is harmonic. So we can use dominated convergence to conclude

$$\begin{split} &\lim_{q \searrow 0} \mathbb{P}^{x}(\Lambda \mid e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \\ = & \frac{1}{h_{+}(x)} \mathbb{E}^{x} \Big[\mathbb{1}_{\Lambda} \mathbb{1}_{\{t < T_{[a,b]}\}} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^{\xi_{t}}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \Big] \\ = & \mathbb{E}^{x} \Bigg[\mathbb{1}_{\Lambda} \mathbb{1}_{\{t < T_{[a,b]}\}} \frac{h_{+}(\xi_{t})}{h_{+}(x)} \Bigg], \end{split}$$

where we used again Proposition 4.5 in the final equality. Hence, conditioning is possible and coincides with the *h*-transform with h_+ which confirms Proposition 2.4.

For the proof of Theorem 2.5 we will use a corollary of Proposition 4.5.

Corollary 4.7. Assume (A) and let e_q be an independent exponentially distributed random variable with parameter q > 0. Then, for $x \notin [a, b]$, we have

$$\mathbb{P}^{x}(e_{q} < T_{[a,b]}) \le \hat{\kappa}(q)h_{+}^{q}(x) + \kappa(q)h_{-}^{q}(x), \quad q > 0,$$
(4.16)

and

$$\lim_{q \to 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^x(e_q < T_{[a,b]}) = h_+(x) + Ch_-(x),$$
(4.17)

where $C = \lim_{q \searrow 0} \frac{\kappa(q)}{\hat{\kappa}(q)}$.

Proof. Let be $x \notin [a, b]$. With Proposition 4.5 and its counterpart for h_{-} we have

$$\mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) \leq \hat{\kappa}(q)h^{q}_{+}(x) \quad \text{and} \quad \mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} < a) \leq \kappa(q)h^{q}_{-}(x)$$

from which the first claim follows. Furthermore we have again with Proposition 4.5:

$$\lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^x(e_q < T_{[a,b]}, \xi_{e_q} > b) = h_+(x)$$

and

$$\lim_{q \searrow 0} \frac{1}{\kappa(q)} \mathbb{P}^x(e_q < T_{[a,b]}, \xi_{e_q} < a) = h_-(x).$$

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With this we get

$$\begin{split} &\lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^{x}(e_{q} < T_{[a,b]}) \\ &= \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} > b) + \lim_{q \searrow 0} \frac{\kappa(q)}{\hat{\kappa}(q)} \frac{1}{\kappa(q)} \mathbb{P}^{x}(e_{q} < T_{[a,b]}, \xi_{e_{q}} < a) \\ &= h_{+}(x) + Ch_{-}(x) \end{split}$$

and the proof is complete.

Proof of Theorem 2.5. We follow a similar strategy as in the proof of Proposition 2.4. First we use the second part of Corollary 4.7 and split up the integral again,

$$\begin{split} &\lim_{q\searrow 0} \mathbb{P}^x (\Lambda \mid e_q < T_{[a,b]}) \\ &= \lim_{q\searrow 0} \frac{1}{\mathbb{P}^x (e_q < T_{[a,b]})} \int\limits_{(0,\infty)} q e^{-qs} \mathbb{P}^x \left(\Lambda, s < T_{[a,b]}\right) \, \mathrm{d}s \\ &= \frac{1}{h_+(x) + Ch_-(x)} \lim_{q\searrow 0} \frac{1}{\hat{\kappa}(q)} \int\limits_{(0,\infty)} q e^{-qs} \mathbb{P}^x \left(\Lambda, s < T_{[a,b]}\right) \, \mathrm{d}s \\ &= \frac{1}{h_+(x) + Ch_-(x)} \lim_{q\searrow 0} \frac{1}{\hat{\kappa}(q)} \int\limits_{(0,t]} q e^{-qs} \mathbb{P}^x \left(\Lambda, s < T_{[a,b]}\right) \, \mathrm{d}s \\ &+ \frac{1}{h_+(x) + Ch_-(x)} \lim_{q\searrow 0} \frac{1}{\hat{\kappa}(q)} \int\limits_{(t,\infty)} q e^{-qs} \mathbb{P}^x \left(\Lambda, s < T_{[a,b]}\right) \, \mathrm{d}s. \end{split}$$

Analogously to the proof of Proposition 2.4 the first term is just 0. Note that since $\lim_{q\searrow 0} \kappa(q)/\hat{\kappa}(q)$ exists, the ratio is bounded for $q \in (0,1)$ by some $\beta > 0$. Hence, with Corollary 4.7 we get

$$\frac{1}{\hat{\kappa}(q)} \mathbb{P}^{y}(e_q < T_{[a,b]}) \le h_{+}^{q}(y) + \frac{\kappa(q)}{\hat{\kappa}(q)}h_{-}^{q}(y) \le h_{+}(y) + \beta h_{-}(y)$$

for all $y \notin [a, b]$. So we use dominated convergence to get

$$\begin{split} &\lim_{q \searrow 0} \mathbb{P}^{x} (\Lambda \mid e_{q} < T_{[a,b]}) \\ &= \frac{1}{h_{+}(x) + Ch_{-}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \int_{(t,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s < T_{[a,b]}\right) \, \mathrm{d}s \\ &= \frac{1}{h_{+}(x) + Ch_{-}(x)} \lim_{q \searrow 0} \frac{e^{-qt}}{\hat{\kappa}(q)} \int_{(0,\infty)} q e^{-qs} \mathbb{P}^{x} \left(\Lambda, s + t < T_{[a,b]}\right) \, \mathrm{d}s \\ &= \frac{1}{h_{+}(x) + Ch_{-}(x)} \lim_{q \searrow 0} \frac{e^{-qt}}{\hat{\kappa}(q)} \int_{(0,\infty)} q e^{-qs} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}} (s < T_{[a,b]}) \right] \, \mathrm{d}s \\ &= \frac{1}{h_{+}(x) + Ch_{-}(x)} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}} (e_{q} < T_{[a,b]}) \right] \\ &= \frac{1}{h_{+}(x) + Ch_{-}(x)} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \lim_{q \searrow 0} \frac{1}{\hat{\kappa}(q)} \mathbb{P}^{\xi_{t}} (e_{q} < T_{[a,b]}) \right] \\ &= \frac{1}{h_{+}(x) + Ch_{-}(x)} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \left(h_{+}(\xi_{t}) + Ch_{-}(\xi_{t}) \right) \right]. \end{split}$$

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4.4 Long-time behaviour

Finally, we analyze the transience behavior of the conditioned processes constructed in the previous section.

Proof of Proposition 2.6. **Step 1:** We show that ξ under \mathbb{P}^x_+ is almost surely bounded from below. First note that, for x < a,

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}}) \right] = \int_{(b,\infty)} h_{+}(y) \nu_{1}^{x}(\mathrm{d}y)$$
$$= \sum_{k=0}^{\infty} \int_{(b,\infty)} \int_{(b,\infty)} U_{-}(z-b) \nu_{2k}^{y}(\mathrm{d}z) \nu_{1}^{x}(\mathrm{d}y)$$
$$= \sum_{k=0}^{\infty} \int_{(b,\infty)} U_{-}(z-b) \nu_{2k+1}^{x}(\mathrm{d}z)$$
$$= h_{+}(x).$$

For the first equality we used $\nu_1^x(dy) = \mathbb{P}^x(\xi_{T_{[a,\infty)}} \in dy, T_{[a,\infty)} < T_{[a,b]})$ for x < a, in the second we plugged-in the definition of $h_+(y)$ for y > b and used Fubini's theorem, in the third we used (4.1) and for the final equality we used the definition of $h_+(x)$ for x < a. Since $\xi_{T_{(-\infty,c]}} < a$ for c < a it follows, for all $x \in \mathbb{R} \setminus [a,b]$, that

$$\begin{split} & \mathbb{P}_{+}^{x}(T_{(-\infty,c]} < \infty \text{ for all } c < a) \\ &= \lim_{c \to -\infty} \mathbb{P}_{+}^{x}(T_{(-\infty,c]} < \infty) \\ &= \frac{1}{h_{+}(x)} \lim_{c \to -\infty} \mathbb{E}^{x} \Big[\mathbbm{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} h_{+}(\xi_{T_{(-\infty,c]}}) \Big] \\ &= \frac{1}{h_{+}(x)} \lim_{c \to -\infty} \mathbb{E}^{x} \Big[\mathbbm{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} \mathbb{E}^{\xi_{T_{(-\infty,c]}}} \Big[\mathbbm{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}}) \Big] \Big] \\ &= \frac{1}{h_{+}(x)} \lim_{c \to -\infty} \mathbb{E}^{x} \Big[\mathbbm{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} \mathbb{E}^{x} \Big[(\mathbbm{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}})) \circ \theta_{T_{(-\infty,c]}} \, | \mathcal{F}_{T_{(-\infty,c]}} \Big] \Big], \end{split}$$

where we used again the strong Markov property (4.10) with $Y = \mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}}h_+(\xi_{T_{[a,\infty)}})$ in the final equality. According to Theorem 1.3.6 of Chung and Walsh [6] it holds that

$$\{T_{(-\infty,c]} < T_{[a,b]}\} \in \mathcal{F}_{T_{(-\infty,c]}} \cap \mathcal{F}_{T_{[a,b]}} \subseteq \mathcal{F}_{T_{(-\infty,c]}}.$$

So we continue for all $x \in \mathbb{R} \setminus [a, b]$ with

$$\begin{split} & \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} \mathbb{E}^{x} \Big[(\mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}})) \circ \theta_{T_{(-\infty,c]}} \, | \, \mathcal{F}_{T_{(-\infty,c]}} \Big] \Big] \\ &= \mathbb{E}^{x} \Big[\mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} (\mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}})) \circ \theta_{T_{(-\infty,c]}} \, | \, \mathcal{F}_{T_{(-\infty,c]}} \Big] \Big] \\ &= \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} ((\mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}})) \circ \theta_{T_{(-\infty,c]}}) \Big]. \end{split}$$

Now consider just x < a and observe

$$\mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} \big((\mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}})) \circ \theta_{T_{(-\infty,c]}} \big) \Big]$$

$$= \sum_{k=0}^{\infty} \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1})\}} \big((\mathbb{1}_{\{T_{[a,\infty)} < T_{[a,b]}\}} h_{+}(\xi_{T_{[a,\infty)}})) \circ \theta_{T_{(-\infty,c]}} \big) \Big]$$

$$= \sum_{k=0}^{\infty} \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} \in [\tilde{\tau}_{2k}, \tilde{\tau}_{2k+1})\}} \mathbb{1}_{\{\tilde{\tau}_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tilde{\tau}_{2k+1}}) \Big]$$

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$$= \sum_{k=0}^{\infty} \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} \in [\tau_{2k}, \tau_{2k+1})\}} \mathbb{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+1}}) \Big],$$

where $\tilde{\tau}_k = \min(\tau_k, T_{[a,b]})$ as in the proof of Proposition 4.5. Combining the above computations gives

$$\mathbb{P}^{x}_{+}(T_{(-\infty,c]} < \infty \text{ for all } c < a)$$

$$= \frac{1}{h_{+}(x)} \lim_{c \to -\infty} \sum_{k=0}^{\infty} \mathbb{E}^{x} \Big[\mathbb{1}_{\{T_{(-\infty,c]} \in [\tau_{2k}, \tau_{2k+1})\}} \mathbb{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+1}}) \Big]$$
(4.18)

for x < a. Our aim is to switch the limit and the sum. In order to justify the dominated convergence theorem it is enough to verify

$$\sum_{k=0}^{\infty} \mathbb{E}^{x} \left[\mathbb{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+1}}) \right] < \infty.$$

With Proposition 4.1 we have

 \sim

$$\begin{split} & \mathbb{E}^{x} \Big[\mathbbm{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+1}}) \Big] \\ & \leq c_{1} \mathbb{E}^{x} \Big[\mathbbm{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} U_{-}(\xi_{\tau_{2k+1}} - b) \Big] + c_{3} \mathbb{P}^{x}(\tau_{2k+1} < T_{[a,b]}) \\ & \leq c_{1} \mathbb{E}^{x} \Big[\mathbbm{1}_{\{K^{\dagger} \geq 2k+1\}} U_{-}(\xi_{\tau_{2k+1}} - b) \Big] + c_{3} \nu_{2k+1}^{x}((b,\infty)) \\ & \leq c_{1} \mathbb{E}^{x} \Big[\mathbbm{1}_{\{K^{\dagger} \geq 2k+1\}} U_{-}(\xi_{\tau_{2k+1}} - b) \Big] + c_{3} \gamma^{2k} \end{split}$$

where c_1, c_3 and γ are the constants from Proposition 4.1 and its proof. It follows that

$$\sum_{k=0}^{\infty} \mathbb{E}^{x} \left[\mathbb{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+1}}) \right]$$

$$\leq c_{1} \sum_{k=0}^{\infty} \mathbb{E}^{x} \left[\mathbb{1}_{\{K^{\dagger} \geq 2k+1\}} U_{-}(\xi_{\tau_{2k+1}} - b) \right] + c_{3} \sum_{k=0}^{\infty} \gamma^{2k}$$

$$= c_{1} h_{+}(x) + \frac{c_{3}}{1 - \gamma^{2}} < \infty.$$

So we can switch the limit and the integral in (4.18). With the same upper bound for every summand for itself we can even move the limit inside the expectation. Hence,

$$\mathbb{P}^{x}_{+}(T_{(-\infty,c]} < \infty \text{ for all } c < a)$$

= $\frac{1}{h_{+}(x)} \sum_{k=0}^{\infty} \mathbb{E}^{x} \left[\lim_{c \to -\infty} \mathbbm{1}_{\{T_{(-\infty,c]} \in [\tau_{2k}, \tau_{2k+1})\}} \mathbbm{1}_{\{\tau_{2k+1} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+1}}) \right].$

Since ξ oscillates (which implies $\tau_k < \infty \mathbb{P}^x$ -almost surely) we obtain that $\mathbb{1}_{\{T_{(-\infty,c]} \in [\tau_{2k}, \tau_{2k+1})\}}$ converges to 0 almost surely under \mathbb{P}^x for $c \to -\infty$. Hence,

$$\mathbb{P}^x_+(T_{(-\infty,c]} < \infty \text{ for all } c < a) = 0$$

for x < a. For x > b it is proved analogously that

$$\mathbb{P}^{x}_{+}(T_{(-\infty,c]} < \infty \text{ for all } c < a)$$

$$= \frac{1}{h_{+}(x)} \lim_{c \to -\infty} \sum_{k=0}^{\infty} \mathbb{E}^{x} \left[\mathbbm{1}_{\{T_{(-\infty,c]} \in [\tau_{2k+1}, \tau_{2k+2})\}} \mathbbm{1}_{\{\tau_{2k+2} < T_{[a,b]}\}} h_{+}(\xi_{\tau_{2k+2}})) \right]$$

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and, with the above argumentation, we also find that $\mathbb{P}^x_+(T_{(-\infty,c]} < \infty \text{ for all } c < a) = 0$ for x > b. This finishes the arguments for Step 1.

Step 2: In the second step we show that ξ is transient under \mathbb{P}^x_+ , i.e. only spends finite time in sets of the form $[d, a) \cup (b, c]$ for d < a and c > b. Actually, we even show that the expected occupation is finite:

$$\mathbb{E}_{+}^{x} \left[\int_{[0,\infty)} \mathbb{1}_{\{\xi_{t} \in [d,a) \cup (b,c]\}} dt \right] \\
= \int_{[0,\infty)} \mathbb{P}_{+}^{x} (\xi_{t} \in [d,a) \cup (b,c]) dt \\
= \int_{[0,\infty)} \mathbb{E}^{x} \left[\mathbb{1}_{\{\xi_{t} \in [d,a) \cup (b,c]\}} \mathbb{1}_{\{t < T_{[a,b]}\}} \frac{h_{+}(\xi_{t})}{h_{+}(x)} \right] dt \\
\leq \frac{1}{h_{+}(x)} \sup_{y \in [d,a) \cup (b,c]} h_{+}(y) \int_{[0,\infty)} \mathbb{E}^{x} \left[\mathbb{1}_{\{\xi_{t} \in [d,a) \cup (b,c]\}} \mathbb{1}_{\{t < T_{[a,b]}\}} \right] dt.$$
(4.19)

Recalling Proposition 4.1, $\sup_{y \in [d,a) \cup (b,c]} h_+(y)$ is finite and it remains to show finiteness of

$$\int_{[0,\infty)} \mathbb{E}^x \left[\mathbbm{1}_{\{\xi_t \in [d,a) \cup (b,c]\}} \mathbbm{1}_{\{t < T_{[a,b]}\}} \right] \mathrm{d}t$$

which is just the potential of $[d, a) \cup (b, c]$ of the process killed on entering [a, b]. To abbreviate we denote the potential of (ξ, \mathbb{P}^x) killed on entering a Borel set B by $U^B(x, dy)$. It follows

$$U^{[a,b]}(x,[d,a)\cup(b,c]) = \sum_{k=0}^{\infty} \left(U^{(-\infty,b]}(\nu_{2k}^x,(b,c]) + U^{[a,\infty)}(\nu_{2k+1}^x,[d,a)) \right).$$

To compute the righthand side we apply Proposition VI.20 of Bertoin [1] for y > b:

$$\begin{split} U^{(-\infty,b]}(y,(b,c]) &= U^{(-\infty,0]}(y-b,(0,c-b]) \\ &= \int_{(0,c-b]} \int_{[(y-b-u)^+,y-b]} U_+(\mathrm{d} u+v-(y-b)) \, U_-(\mathrm{d} v) \\ &= \int_{[0,y-b]} \left(\int_{(0,c-b]} \mathbbm{1}_{\{u \ge y-b-v\}} \, U_+(\mathrm{d} u-(y-b-v)) \right) U_-(\mathrm{d} v) \\ &= \int_{[0,y-b]} U_+(c+v-y) \, U_-(\mathrm{d} v) \\ &\leq U_+(c-b) U_-(y-b). \end{split}$$

It holds analogously that $U^{[a,\infty)}(y,[d,a)) \leq U_{-}(a-d)U_{+}(a-y)$ for y > a. So we have

$$\begin{split} U_{[a,b]}(x,[d,a)\cup(b,c]) &\leq U_{+}(c-b)\sum_{k=0}^{\infty}\int\limits_{(b,\infty)}U_{-}(y-b)\,\nu_{2k}^{x}(\mathrm{d}y) \\ &+ U_{-}(a-d)\sum_{k=0}^{\infty}\int\limits_{(-\infty,a)}U_{+}(a-y)\,\nu_{2k+1}^{x}(\mathrm{d}y) \\ &= U_{+}(c-b)h_{+}(x) + U_{-}(a-d))h_{-}(x) < \infty. \end{split}$$

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It follows in particular that the time the process (ξ, \mathbb{P}^x_+) spends in sets of the form $[d, a) \cup (b, c]$ is finite almost surely. Together with the first result that the process is bounded below almost surely and that the process is conservative it follows that $\lim_{t\to\infty} \xi_t = +\infty$ almost surely under \mathbb{P}^x_+ .

Proof of Theorem 2.7. The proof strategy is similar to the one above. Transience of the conditioned process is verified again by computing the occupation measure using the representation of the conditioned process as *h*-transform. The computation is in analogy to (4.19), using that $h = h_+ + Ch_-$ is bounded by Proposition 4.1.

Next, recall from the counterpart of Proposition 2.6 for \mathbb{P}^{x}_{-} that under (\hat{B}) ,

$$\mathbb{P}^x_-(T_{(-\infty,c]} < \infty) = 1, \quad c < a$$

for all $x \in \mathbb{R} \setminus [a, b]$. Since (1.5) implies

$$\mathbb{P}^{x}_{-}(T_{(-\infty,c]} < \infty) = \frac{1}{h_{-}(x)} \mathbb{E}^{x} \left[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} h_{-}(\xi_{T_{(-\infty,c]}}) \right]$$

we deduce

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} h_{-}(\xi_{T_{(-\infty,c]}}) \right] = h_{-}(x), \quad c < a$$
(4.20)

for all $x \in \mathbb{R} \setminus [a, b]$ under (\hat{B}). If (\hat{B}) fails we know

$$h_{-}(x) = \begin{cases} 0 & \text{if } x > b \\ U_{+}(a - x) & \text{if } x < a \end{cases}.$$

Let us check if (4.20) holds in this case, too. If x > b the left-hand side of (4.20) is 0 (because there are no jumps bigger than b - a), as well as the right-hand side. For x > a the measure \mathbb{P}^x_- corresponds to the process conditioned to stay below a which is known to drift to $-\infty$ (see Chaumont and Doney [5]). In particular it holds

$$\mathbb{P}^x_-(T_{(-\infty,c]} < \infty) = 1, \quad c < a$$

from which we can deduce (4.20) in the same way as before. So (4.20) holds for all $x \in \mathbb{R} \setminus [a, b]$ just under (A).

Again using (1.5) yields

$$\begin{split} & \mathbb{P}^{x}_{\uparrow}(T_{(-\infty,c]} < \infty) \\ &= \frac{1}{h(x)} \Big(\mathbb{E}^{x} \big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} h_{+}(\xi_{T_{(-\infty,c]}}) \big] + \mathbb{E}^{x} \big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} Ch_{-}(\xi_{T_{(-\infty,c]}}) \big] \Big) \\ &= \frac{1}{h(x)} \mathbb{E}^{x} \big[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} h_{+}(\xi_{T_{(-\infty,c]}}) \big] + \frac{Ch_{-}(x)}{h(x)}. \end{split}$$

In the proof of Proposition 2.6 we have already seen that $\mathbb{E}^x \left[\mathbb{1}_{\{T_{(-\infty,c]} < T_{[a,b]}\}} h_+(\xi_{T_{(-\infty,c]}}) \right]$ vanishes for $c \to -\infty$, hence,

$$\mathbb{P}^x_{\uparrow}(\xi \text{ is unbounded below}) = \mathbb{P}^x_{\uparrow}(T_{(-\infty,c]} < \infty \text{ for all } c < a) = \frac{Ch_{-}(x)}{h(x)}.$$

So we get

$$\mathbb{P}^{x}_{\uparrow}(\xi \text{ is bounded below}) = 1 - \frac{Ch_{-}(x)}{h(x)} = \frac{h_{+}(x)}{h(x)}$$

and, because of transience,

$$\frac{h_{\pm}(x)}{h(x)} = \mathbb{P}^x_{\uparrow}(\xi \text{ is bounded below}) = \mathbb{P}^x_{\uparrow}(\lim_{t \to \infty} \xi_t = \infty).$$

Analogously one derives $\mathbb{P}^x_{\uparrow}(\lim_{t\to\infty}\xi_t=\infty)=\frac{Ch_-(x)}{h(x)}$ and the proof is complete. \Box

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5 Extension to transient Lévy processes

When conditioning a process to avoid an interval, the most interesting case is when the process is recurrent; if it is transient, it may avoid the interval with positive probability, and things become simpler. On the other hand, the conditionings in Proposition 2.4, to avoid the interval while finishing above (or below) it, may still be non-trivial. In this section, we drop Assumption (A), and require only that ξ is not a compound Poisson process and does not oscillate. In particular, we do not assume that ξ has finite second moments; only for the study of h_- do we need further conditions.

Without loss of generality, we assume from now on that ξ drifts to $+\infty$, and indicate which of our results still hold and which need modification. Under this assumption, the function h defined by (2.1) simplifies to h_+ . This can be seen from the fact that $\kappa(0) = 0 < \hat{\kappa}(0)$, which implies $C = \lim_{q \searrow 0} \frac{\kappa(q)}{\hat{\kappa}(q)} = 0$.

5.1 Study of $h = h_+$

For the study of h (which is now equal to h_+) we need to distinguish two cases based on whether or not condition (B) is satisfied.

5.1.1 Condition (B) holds

Since the Lévy process is transient, the event $\{T_{[a,b]} = \infty\}$ has positive probability for every starting point. The conditioning simplifies dramatically and our results are still valid, as we now demonstrate. Let $\ell(x) := \mathbb{P}^x(T_{[a,b]} = \infty)$ for $x \notin [a,b]$. This is easily seen to be harmonic using the strong Markov property:

$$\mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} \ell(\xi_{t}) \right] = \mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}}(T_{[a,b]} = \infty) \right]$$

$$= \lim_{s \to \infty} \mathbb{E}^{x} \left[\mathbb{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}}(T_{[a,b]} > s) \right]$$

$$= \lim_{s \to \infty} \mathbb{P}^{x}(T_{[a,b]} > t + s)$$

$$= \mathbb{P}^{x}(T_{[a,b]} = \infty).$$

(5.1)

Transience ensures that ℓ is a positive harmonic function. We next show that ℓ is indeed a multiple of $h = h_+$. To do so we will use the identity $\hat{\kappa}(q)U_-^q(x) = \mathbb{P}^x(e_q < T_{(-\infty,0]})$, where e_q is an independent exponentially distributed random variable with parameter q > 0 (see Kyprianou [11], Section 13.2.1 for a general Lévy process). Since ξ drifts to $+\infty$, we have $\hat{\kappa}(0) > 0$, and hence

$$\hat{\kappa}(0)U_{-}(x) = \mathbb{P}^{x}(T_{(-\infty,0]} = \infty), \quad x > 0.$$

The idea is to separate the two-sided entrance problem in infinitely many one-sided entrance problems and use the strong Markov property to combine them. For x > b, using the strong Markov property, we find

$$\begin{split} & \mathbb{P}^{x}(T_{[a,b]} = \infty) \\ &= \mathbb{P}^{x}(T_{(-\infty,b]} = \infty) + \mathbb{P}^{x}(T_{[a,b]} = \infty, T_{(-\infty,b]} < \infty) \\ &= \mathbb{P}^{x}(T_{(-\infty,b]} = \infty) + \mathbb{E}^{x} \Big[\mathbbm{1}_{\{T_{(-\infty,b]} < \infty, \xi_{T_{(-\infty,b]} < a}\}} \mathbb{P}^{\xi_{T_{(-\infty,b]}}}(T_{[a,b]} = \infty) \Big] \\ &= \hat{\kappa}(0) U_{-}(x-b) + \mathbb{E}^{x} \Big[\mathbbm{1}_{\{T_{(-\infty,b]} < \infty, \xi_{T_{(-\infty,b]} < a}\}} \mathbb{E}^{\xi_{T_{(-\infty,b]}}} \Big[\mathbbm{1}_{\{\xi_{T_{[a,\infty)}} > b\}} \mathbb{P}^{\xi_{T_{[a,\infty)}}}(T_{[a,b]} = \infty) \Big] \Big] \\ &= \hat{\kappa}(0) U_{-}(x-b) + \int_{(b,\infty)} \mathbb{P}^{y}(T_{[a,b]} = \infty) \nu_{2}^{x}(\mathrm{d}y). \end{split}$$

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Now we split up $\mathbb{P}^y(T_{[a,b]}=\infty)$ in the same manner, i.e.,

$$\mathbb{P}^{y}(T_{[a,b]} = \infty) = \hat{\kappa}(0)U_{-}(y-b) + \int_{(b,\infty)} \mathbb{P}^{z}(T_{[a,b]} = \infty)\nu_{2}^{x}(\mathrm{d}z).$$

Using $\int\limits_{(b,\infty)} \nu_2^z(\mathrm{d} y) \, \nu_2^x(\mathrm{d} z) = \nu_4^x(\mathrm{d} y)$ from (4.1) yields

$$\mathbb{P}^{x}(T_{[a,b]} = \infty)$$

= $\hat{\kappa}(0) \Big(U_{-}(x-b) + \int_{(b,\infty)} U_{-}(y-b) \nu_{2}^{x}(\mathrm{d}y) \Big) + \int_{(b,\infty)} \mathbb{P}^{y}(T_{[a,b]} = \infty) \nu_{4}^{x}(\mathrm{d}y).$

By induction the following series representation is obtained:

$$\mathbb{P}^{x}(T_{[a,b]}=\infty) = \hat{\kappa}(0) \sum_{k=0}^{\infty} \int_{(b,\infty)} U_{-}(y-b) \nu_{2k}^{x}(\mathrm{d}y).$$

For x < a a similar computation can be carried out, and we obtain

$$\ell(x) = \mathbb{P}^{x}(T_{[a,b]} = \infty) = \begin{cases} \hat{\kappa}(0) \sum_{k=0}^{\infty} \int U_{-}(y-b) \nu_{2k}^{x}(\mathrm{d}y) & \text{if } x > b \\ \\ \hat{\kappa}(0) \sum_{k=0}^{\infty} \int U_{-}(y-b) \nu_{2k+1}^{x}(\mathrm{d}y) & \text{if } x < a \end{cases}$$
$$= \hat{\kappa}(0)h_{+}(x) = \hat{\kappa}(0)h(x).$$

Theorem 2.1: This is a consequence of the discussion above.

Theorem 2.5: Since we condition here on a positive probability event, the *h*-transform and the conditioning are related in a standard way, using the strong Markov property and integrating out e_q :

$$\begin{split} \mathbb{E}^{x} \Big[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \frac{\ell(\xi_{t})}{\ell(x)} \Big] &= \frac{1}{\mathbb{P}^{x}(T_{[a,b]} = \infty)} \mathbb{E}^{x} \Big[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}}(T_{[a,b]} = \infty) \Big] \\ &= \lim_{q \searrow 0} \frac{1}{\mathbb{P}^{x}(e_{q} < T_{[a,b]})} \mathbb{E}^{x} \Big[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \mathbb{P}^{\xi_{t}}(e_{q} < T_{[a,b]}) \Big] \\ &= \lim_{q \searrow 0} \frac{\mathbb{P}^{x}(\Lambda, t + e_{q} < T_{[a,b]})}{\mathbb{P}^{x}(e_{q} < T_{[a,b]})} \\ &= \lim_{q \searrow 0} \frac{e^{qt} \mathbb{P}^{x}(\Lambda, t < e_{q} < T_{[a,b]})}{\mathbb{P}^{x}(e_{q} < T_{[a,b]})} \\ &= \lim_{q \searrow 0} \mathbb{P}^{x}(\Lambda, t < e_{q} \mid e_{q} < T_{[a,b]}), \end{split}$$

for $\Lambda \in \mathcal{F}_t$, $t \geq 0$.

Proposition 2.4: The conditioning of Proposition 2.4 is equivalent to the conditioning of Theorem 2.5, since the additional condition to stay above the interval at late time vanishes in the limit due to the transience towards $+\infty$. Since $h = h_+$ the result of Proposition 2.4 follows.

Proposition 2.6 and Theorem 2.7: Since the conditioned measure is a restriction of the original one, the long-time behaviour of the conditioned process is identical to that of the original process. Hence, the statements of Proposition 2.6 and Theorem 2.7 hold.

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5.1.2 Condition (B) fails

The definition of h_+ in this case simplifies to

$$h_{+}(x) = \begin{cases} U_{-}(x-b) & \text{if } x > b\\ 0 & \text{if } x < a \end{cases}$$

This function is plainly not positive everywhere. It is nonetheless harmonic for the process killed on entering [a, b]. The conditionings in Theorem 2.5 and Proposition 2.4 can still be carried out but, as we now prove, the results are somewhat different.

Let $h_{\uparrow} : (b, \infty) \to [0, \infty)$ be given by $h_{\uparrow}(x) = U_{-}(x - b)$, the restriction of h_{+} to (b, ∞) . As shown by Chaumont and Doney [5], this function is harmonic for the process ξ killed on entering $(-\infty, b]$, and the *h*-transform of this process using h_{\uparrow} is the process ξ conditioned to avoid $(-\infty, b]$. We will write $(\mathbb{P}^{x}_{\uparrow})_{x \in (b,\infty)}$ for the probabilities associated with this Markov process.

Consider now the conditioning of **Proposition 2.4**. When x > b the process cannot cross below the set [a, b] and return above it without hitting the set. Therefore, we have that

$$\lim_{q \searrow 0} \mathbb{P}^x(\Lambda, t < e_q \mid e_q < T_{[a,b]}, \xi_{e_q} > b) = \lim_{q \searrow 0} \mathbb{P}^x(\Lambda, t < e_q \mid e_q < T_{(-\infty,b]}) = \mathbb{P}^x_{\uparrow}(\Lambda),$$

the last equality being due to Chaumont and Doney [5]. For x < a, $\mathbb{P}^x(e_q < T_{[a,b]}, \xi_{e_q} > b) = 0$ for every q > 0, so the conditioning does not have any sense. In total, the conditioning of Proposition 2.4 reduces to conditioning ξ to avoid $(-\infty, b)$.

We turn next to the conditioning in **Theorem 2.5**. Let us define $h_{\downarrow} : (-\infty, a) \to [0, \infty)$ by $h_{\downarrow}(x) = U_{+}(a - x)$, which is a positive harmonic function for the process killed on entering $[a, \infty)$ resulting in the process conditioned to avoid $[a, \infty)$ when *h*-transformed with h_{\downarrow} . As before, we write $(\mathbb{P}_{\downarrow}^{x})_{x \in (-\infty, a)}$ for the probabilities associated with the conditioned process, which is killed at its lifetime ζ . By the same reasoning in the case where (B) holds, $\lim_{q \searrow 0} \mathbb{P}^{x}(T_{[a,b]} > e_q) = \hat{\kappa}(0)h_{+}(x) = \hat{\kappa}(0)h_{\uparrow}(x)$ when x > b; and, when x < a, using the asymptotics of $T_{[a,\infty)}$ which we have already seen, we obtain $\mathbb{P}^{x}(T_{[a,b]} > e_q) = \mathbb{P}^{x}(T_{[a,\infty)} > e_q) \sim \kappa(q)U_{+}(a - x)$ as $q \searrow 0$, since ξ cannot jump over [a,b] from below. If x > b, and $\Lambda \in \mathcal{F}_t$, the same technique as in the proof of Theorem 2.5 gives rise to the calculation

$$\begin{split} &\lim_{q \searrow 0} \mathbb{P}^{x}(\Lambda, t < e_{q} \mid e_{q} < T_{[a,b]}) \\ &= \frac{1}{\hat{\kappa}(0)h_{\uparrow}(x)} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \lim_{q \searrow 0} \mathbb{P}^{\xi_{t}}(e_{q} < T_{[a,b]}) \right] \\ &= \frac{1}{\hat{\kappa}(0)h_{\uparrow}(x)} \mathbb{E}^{x} \left[\mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{[a,b]}\}} \lim_{q \searrow 0} \left(\mathbbm{1}_{\{t < T_{(-\infty,b]}\}} \hat{\kappa}(0)h_{\uparrow}(\xi_{t}) + \mathbbm{1}_{\{t > T_{(-\infty,b]}\}} \kappa(q)U_{+}(a - \xi_{t})) \right] \\ &= \frac{1}{h_{\uparrow}(x)} \mathbb{E}^{x} [h_{+}(\xi_{t}) \mathbbm{1}_{\Lambda} \mathbbm{1}_{\{t < T_{(-\infty,b]}\}}] = \mathbb{P}^{x}_{\uparrow}(\Lambda). \end{split}$$

Similarly, if x < a, we obtain $\lim_{q \searrow 0} \mathbb{P}^x(\Lambda, t < e_q \mid e_q < T_{[a,b]}) = \mathbb{P}^x_{\downarrow}(\Lambda, t < \zeta)$.

This shows that the conditioning from Theorem 2.5 leads not to a single Doob *h*-transform of a killed Lévy process, but rather to a Markov process which behaves entirely differently depending on whether it is started above or below the interval. The long-time behaviour can be deduced from Chaumont and Doney [5]: the conditioned process approaches $+\infty$ when started above *b*, and is killed when started below *a*.

5.2 Study of h_-

This section is kept informal; the claims can be proved by an adaptation of arguments developed in Section 4.

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In order to study h_{-} we need to assume that $\mathbb{E}[H_1] < \infty$ and $\mathbb{E}[H_1] < \infty$. Note that here the descending ladder height subordinator has finite lifetime ζ , so we understand $\mathbb{E}[H_1] = \mathbb{E}[H_1 \mathbb{1}_{1 < \zeta}]$. The function h_{-} is merely superharmonic, in the sense that

 $\mathbb{E}^x[h_-(\xi_t)\mathbb{1}_{\{t < T_{[a,b]}\}}] \le h_-(x), \quad x \in \mathbb{R} \setminus [a,b].$

We may still define the superharmonic transform

$$\mathbb{P}^{x}_{-}(\Lambda, t < \zeta) = \mathbb{E}^{x} \left[\mathbb{1}_{\Lambda} \mathbb{1}_{\{t < T_{[a,b]}\}} \frac{h_{-}(\xi_{t})}{h_{-}(x)} \right], \quad x \in \mathbb{R} \setminus [a,b],$$

but the transformed process is now a killed Markov process, with lifetime ζ . The dual version of the conditioning of **Proposition 2.4** is then given by

$$\mathbb{P}^{x}_{-}(\Lambda, t < \zeta) = \lim_{q \searrow 0} \mathbb{P}^{x}(\Lambda, t < e_{q} \mid e_{q} < T_{[a,b]}, \xi_{e_{q}} < a), \quad x \in \mathbb{R} \setminus [a,b],$$
(5.2)

and gives rise to a killed strong Markov process. This is a generalization of the subordinator conditioned to stay below a level as studied in Kyprianou et al. [13].

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