# LIE DERIVATIVES ON HOMOGENEOUS <br> REAL HYPERSURFACES <br> OF TYPE $A$ IN COMPLEX SPACE FORMS 

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#### Abstract

The purpose of this paper is to give some characterizations of homogeneous real hypersurfaces of type $A$ in complex space forms $M_{n}(c), c \neq 0$, in terms of Lie derivatives.


## 1. Introduction

A complex $n$-dimensional Kaehler manifold of constant holomorphic sectional curvature $c$ is called a complex space form, which is denoted by $M_{n}(c)$. The complete and simply connected complex space form is isometric to a complex projective space $P_{n}(C)$, a complex Euclidean space $C^{n}$, or a complex hyperbolic space $H_{n}(C)$ according as $c>0, c=$ 0 or $c<0$ respectively. The induced almost contact metric structure of a real hypersurface $M$ of $M_{n}(c)$ is denoted by ( $\phi, \xi, \eta, g$ ).

Now, there exist many studies about real hypersurfaces of $M_{n}(c)$, $c \neq 0$. One of the first researches is the classification of homogeneous real hypersurfaces of a complex projective space $P_{n}(C)$ by Takagi [13], who showed that these hypersurfaces of $P_{n}(C)$ could be divided into six types which are said to be of type $A_{1}, A_{2}, B, C, D$ and $E$, and in [3] Cecil-Ryan and in [8] Kimura proved that they are realized as the tubes of constant radius over Hermitian symmetric spaces of compact type of rank 1 or rank 2. Also Berndt [1], [2] showed recently that all real hypersurfaces with constant principal curvatures of a complex

[^0]hyperbolic space $H_{n}(C)$ are realized as the tubes of constant radius over certain submanifolds when the structure vector field $\xi$ is principal.

On the other hand, Okumura [12] and Montiel and Romero [11] proved the followings respectively.

Theorem A. Let $M$ be a real hypersurface of $P_{n}(C), n \geq 2$. If it satisfies

$$
\begin{equation*}
A \phi-\phi A=0, \tag{1.1}
\end{equation*}
$$

then $M$ is locally congruent to a tube of radius $r$ over one of the following Kaehler submanifolds:
$\left(A_{1}\right)$ a hyperplane $P_{n-1}(C)$, where $0<r<\frac{\pi}{2}$,
( $A_{2}$ ) a totally geodesic $P_{k}(C)(1 \leq k \leq n-2)$, where $0<r<\frac{\pi}{2}$.
Theorem B. Let $M$ be a real hypersurface of $H_{n}(C), n \geq 2$. If it satisfies (1.1), then $M$ is locally congruent to one of the following hypersurfaces:
$\left(A_{0}\right)$ a horosphere in $H_{n}(C)$, i.e., a Montiel tube,
$\left(A_{1}\right)$ a tube of a totally geodesic hyperplane $H_{k}(C) \quad(k=0$ or $n-1)$,
$\left(A_{2}\right)$ a tube of a totally geodesic $H_{k}(C)(1 \leq k \leq n-2)$.
Now hereafter, unless otherwise stated, the above kind of real hypersurfaces in Theorem A or in Theorem B are said to be of real hypersurfaces of type $A$.

From two decades ago there have been so many investigations for real hypersurfaces of type $A$ in $M_{n}(c), c \neq 0$ and several characterizations of this type have been obtained by many differential geometers (See [1], [3], [7], [11] and [12]). But until now in terms of Lie derivatives only a few characterizations are known to us. From this point of view we have paid our attention to the works of Okumura [12] and Montiel and Romero [11] as in Theorem A and in Theorem B respectively. They showed that a real hypersurface $M$ in $P_{n}(C)$ or in $H_{n}(C)$ is locally congruent to a real hypersurface of type $A$ if and only if the structure vector $\xi$ is an infinetesimal isometry, that is $\mathcal{L}_{\xi} g=0$, which is equivalent to (1.1), where $\mathcal{L}_{\xi}$ denotes the Lie derivative along the structure vector $\xi$.

Being motivated by these results Ki , Kim and Lee [4] proved that the Lie derivatives $\mathcal{L}_{\xi} g=0, \mathcal{L}_{\xi} \phi=0$ or $\mathcal{L}_{\xi} A=0$ are equivalent to each other, where $A$ denotes the second fundamental tensor of $M$ in $M_{n}(c)$.

In this paper we want to generalize these results and to investigate further properties of real hypersurfaces of type $A$ in terms of the tensorial formulas concerned with the Lie derivatives along the structure vector field $\xi$ as follows:

Theorem. Let $M$ be a real hypersurface of $M_{n}(c), c \neq 0, n \geqq 3$. Assume that the structure vector $\xi$ of $M$ satisfies one of the followings :
(1) $\mathcal{L}_{\xi} g=f g \quad$ for the induced Rimannian metric $g$,
(2) $\mathcal{L}_{\xi} \phi=f \phi \quad$ for the structure tensor $\phi$,
(3) $\mathcal{L}_{\xi} \phi=f A$ for the second fundamental tensor $A$,
(4) $\mathcal{L}_{\xi} \phi=f A \phi \quad$ for the certain tensor $A \phi$ of type $(1,1)$ or,
(5) $\mathcal{L}_{\xi} \phi=f \phi A \quad$ for the certain tensor $\phi A$ of type (1,1),
where $f$ denotes any differentiable function defined on $M$. Then $M$ is locally congruent to a real hypersurface of type $A$.

In section 2 the theory of real hypersurfaces in complex space forms is recalled and in section 3 we will prove the first part of the Theorem when $\xi$ becomes an infinitesimal conformal transformation. In section 4 we will give the complete proof of the latter parts of the Theorem in above. Namely, some characterizations of real hypersurfaces in $M_{n}(c)$ will be given in terms of the tensorial formulas concerned with the Lie derivatives $\mathcal{L}_{\xi} \phi$.

## 2. Preliminaries

Let $M$ be a real hypersurface of a complex $n$-dimensional complex space form $M_{n}(c), c \neq 0, n \geqq 3$ and let $C$ be a unit normal vector field on a neighborhood of a point $x$ in $M$. We denote by $J$ an almost complex structure of $M_{n}(c)$. For a local vector field $X$ on a neighborhood $x$ in $M$, the transformation of $X$ and $C$ under $J$ can be represented as

$$
J X=\phi X+\eta(X) C, \quad J C=-\xi,
$$

where $\phi$ defines a skew-symmertic transformation on the tangent bundle $T M$ of $M$, while $\eta$ and $\xi$ denote a 1 -form and a vector field on a neighborhood of $x$ in $M$, respectively. Moreover it is seen that $g(\xi, X)=\eta(X)$, where $g$ denotes the induced Riemannian metric on $M$. By properties of the almost complex structure $J$, the set $(\phi, \xi, \eta, g)$ of tensors satisfies

$$
\begin{equation*}
\phi^{2}=-I+\eta \otimes \xi, \quad \phi \xi=0, \quad \eta(\phi X)=0, \quad \eta(\xi)=1 \tag{2.1}
\end{equation*}
$$

where $I$ denotes the identity transformation and $X$ denotes any vector field tangent to $M$. Accordingly, this set $(\phi, \xi, \eta, g)$ defines the almost contact metric structure on $M$. Furthermore the covariant derivative of the structure tensors are given by

$$
\begin{equation*}
\left(\nabla_{X} \phi\right) Y=\eta(Y) A X-g(A X, Y) \xi, \quad \nabla_{X} \xi=\phi \bar{A} X \tag{2.2}
\end{equation*}
$$

where $\nabla$ is the Riemannian connection of $g$ and $A$ denotes the shape operator with respect to the unit normal $C$ on $M$. Since the ambient space is of constant holomorphic sectional curvature $c$, the equations of Gauss and Codazzi are respectively given as follows :

$$
\begin{align*}
& R(X, Y) Z=\frac{c}{4}\{g(Y, Z) X-g(X, Z) Y+g(\phi Y, Z) \phi X-g(\phi X, Z) \phi Y  \tag{2.3}\\
&-2 g(\phi X, Y) \phi Z\}+g(A Y, Z) A X-g(A X, Z) A Y
\end{align*}
$$

$$
\begin{equation*}
\left(\nabla_{X} A\right) Y-\left(\nabla_{Y} A\right) X=\frac{c}{4}\{\eta(X) \phi Y-\eta(Y) \phi X-2 g(\phi X, Y) \xi\} \tag{2.4}
\end{equation*}
$$

where $R$ denotes the Riemannian curvature tensor of $M$ and $\nabla_{X} A$ denotes the covariant derivative of the shape operator $A$ with respect to $X$.

Now, in order to get our result, we introduce a lemma which was proved by Ki and Suh [6] as follows:

Lemma 2.1. Let $M$ be a real hypersurface of a complex space form $M_{n}(c)$. If $A \phi+\phi A=0$, then $c=0$.

## Real hypersurfaces of type $A$

## 3. The infinitesimal conformal transformations

Before going to prove our assertion in Case (1), let us introduce a slight weaker condition than an infinitesimal isometry.

A vector field $X$ on a Riemannian manifold is said to be an infinitesimal conformal transformation if the metric tensor $g$ satisfies $\mathcal{L}_{X} g=f g$, where $\mathcal{L}_{X}$ denotes the Lie derivative with respect to the vector field $X$ and $f$ denotes a differentiable function defined on $M$.

Let $M$ be a real hypersurface of $M_{n}(c), c \neq 0, n \geqq 3$, whose structure vector $\xi$ is an infinitesimal conformal transformation. Then the metric tensor $g$ on $M$ satisfies

$$
\begin{aligned}
\left(\mathcal{L}_{\xi} g\right)(X, Y) & =g((\phi A-A \phi) X, Y) \\
& =f g(X, Y),
\end{aligned}
$$

where $X$ and $Y$ are any vector fields tangent to $M$. It yields that

$$
(\phi A-A \phi) X=f X
$$

for any differentiable function $f$ on $M$. From this, putting $X=\xi$, we have

$$
\begin{equation*}
\phi A \xi=f \xi . \tag{3.1}
\end{equation*}
$$

So, from applying the operator $\phi$ we have

$$
\begin{equation*}
A \xi=\alpha \xi \tag{3.2}
\end{equation*}
$$

where $\alpha$ denotes $g(A \xi, \xi)$. By virtue of the latter two formulas (3.1) and (3.2) we know that $f$ identically vanishes. This means the structure vector $\xi$ becomes an infinitesimal isometric transformation. Thus by Theorems A and B in the introduction, we have completed the proof of our Theorem in Case (1).
4. Some characterizations of real hypersurfaces in terms of $\mathcal{L}_{\xi} \phi$

In this section let us prove the latter part of our main Theorem. Namely, we will give some characterizations of real hypersurfaces of
type $A$ in terms of the Lie derivatives of the structure tensor $\phi$ along the structure vector $\xi$.

Let $M$ be a real hypersurface of $M_{n}(c), c \neq 0, n \geqq 3$ whose structure vector $\xi$ on $M$ satisfies

$$
\mathcal{L}_{\xi} \phi=f T
$$

where $f$ is a differentiable function and $T$ is a tensor field of type ( 1,1 ) defined on $M$. By the definition of the Lie derivative and (2.2) we have

$$
\begin{equation*}
\mathcal{L}_{\xi} \phi=\phi^{2} A-\phi A \phi+A \xi \otimes \eta-\xi \otimes \eta(A)=f T \tag{4.1}
\end{equation*}
$$

from which together with (2.1), it follows that

$$
\begin{equation*}
A-A \xi \otimes \eta+\phi A \phi=-f T \tag{4.2}
\end{equation*}
$$

Operating the linear transformation (4.2) to the structure vector $\xi$ and taking account of (2.1), we have

$$
\begin{equation*}
f T \xi=0 . \tag{4.3}
\end{equation*}
$$

Next, operating $\phi$ to (4.2) to the left and using (2.1), we have

$$
\begin{equation*}
A \phi-\phi A+\phi A \xi \otimes \eta-\xi \otimes \eta(A \phi)=f \phi T . \tag{4.4}
\end{equation*}
$$

Operating $\phi$ to (4.2) to the right and making use of (2.1), we have

$$
\begin{equation*}
\phi A-A \phi-\phi A \xi \otimes \eta=f T \phi \tag{4.5}
\end{equation*}
$$

Taking the inner product of (4.2) with the structure vector $\xi$, we have for any $X$ in $T M$

$$
\begin{equation*}
g(A X, \xi)-\alpha \eta(X)+f g(T X, \xi)=0 \tag{4.6}
\end{equation*}
$$

Then from (4.4) and (4.5) we have

LEmma 4.1. Let $M$ be a real hypersurface of $M_{n}(c), c \neq 0, n \geqq 3$. Assume that the structure vector $\xi$ satisfies $\mathcal{L}_{\xi} \phi=f T$, where $f$ is a differentiable function and $T$ is a tensor field of type ( 1,1 ). If the structure vector $\xi$ is principal, then it satisfies

$$
\begin{equation*}
f \phi T+f T \phi=0, \quad 2(A \phi-\phi A)=f(\phi T-T \phi) \tag{4.7}
\end{equation*}
$$

Case (2): $T=\phi$
Assume that $T=\phi$. In this Case (2) the formula (4.6) yields the structure vector $\xi$ is principal. Then, by Lemma 4.1 we have $A \phi-\phi A=$ 0 . So by virtue of Theorems A and B, we have our assertion under this case.

Case (3): $T=A$.
We assume that $T=A$. By (4.4) and (4.5), we have

$$
\begin{gather*}
A \phi-(1+f) \phi A+\phi A \xi \otimes \eta-\xi \otimes \eta(A \phi)=0  \tag{4.8}\\
\phi A-(1+f) A \phi-\phi A \xi \otimes \eta=0 \tag{4.9}
\end{gather*}
$$

Acting the structure vector $\xi$ to the linear transformation (4.8), we get

$$
\begin{equation*}
f \phi A \xi=0 \tag{4.10}
\end{equation*}
$$

Taking an inner product (4.9) with the structure vector $\xi$, we have

$$
\begin{equation*}
(1+f) \phi A \xi=0 \tag{4.11}
\end{equation*}
$$

From (4.10) and (4.11) we have

$$
\phi A \xi=0
$$

that is, $\xi$ is the principal curvature vector with principal curvature $\alpha$. Then by Lemma 4.1 we have

$$
\begin{gather*}
f(A \phi+\phi A)=0  \tag{4.12}\\
(2+f)(A \phi-\phi A)=0 \tag{4.13}
\end{gather*}
$$

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Let us denote by $M_{1}$ a subset of $M$ consisting of points at which $f(x) \neq 0$. Now let us assume $M_{1}$ is not empty. Then, by (4.12), we see that $A \phi+\phi A=0$ on $M_{1}$, and hence $c=0$ on $M_{1}$ by Lemma 2.1. This makes a contradiction. So $M_{1}$ is empty. Therefore the function $f$ vanishes identically on $M$. Then (4.13) together with Theorems A and B we have our assertion in Case (3).

Case (4): $T=A \phi$
Next, we assume that $T=A \phi$. Then, by (4.6), we have

$$
\begin{equation*}
A \xi-\alpha \xi=-f \phi A \xi \tag{4.14}
\end{equation*}
$$

Applying $\phi$ to (4.14) and using (2.1) and (4.14), we have $\left(1+f^{2}\right) \phi A \xi=$ 0 , that is, $\xi$ is the principal curvature vector with principal curvature $\alpha$. From this and (4.5) we have

$$
\begin{equation*}
\phi A-A \phi+f(A-\alpha \eta \otimes \xi)=0 \tag{4.15}
\end{equation*}
$$

Operating $\phi$ to (4.15) to the right and using (2.1) and the fact $\xi$ is principal, we get

$$
\begin{equation*}
\phi A \phi+f A \phi+(A-\alpha \eta \otimes \xi)=0 \tag{4.16}
\end{equation*}
$$

from which together with (4.15), it follows

$$
\begin{equation*}
\phi A-\left(1+f^{2}\right) A \phi-f \phi A \phi=0 . \tag{4.17}
\end{equation*}
$$

Next, operating $\phi$ to (4.16) to the left and using (2.1), we get

$$
\begin{equation*}
\phi A-A \phi+f \phi A \phi=0 . \tag{4.18}
\end{equation*}
$$

From (4.15) and (4.18), we find

$$
\begin{equation*}
f \phi A \phi-f(A-\alpha \eta \otimes \xi)=0 \tag{4.19}
\end{equation*}
$$

From this, operating $\phi$ to the left and using (2.1) and the fact $\xi$ is principal, we have

$$
\begin{equation*}
f(A \phi+\phi A)=0 . \tag{4.20}
\end{equation*}
$$

Let $M_{1}$ be an open set consisting of points $x$ in $M$ such that $f(x) \neq 0$. If $M_{1}$ is not empty, then, by (4.20), we see that $A \phi+\phi A=0$ on $M_{1}$, and hence $c=0$ on $M_{1}$ by Lemma 2.1. This makes a contradiction. Hence $M_{1}$ is empty. Therefore the function $f$ vanishes identically on $M$. From this, together with (4.15), we have $\phi A=A \phi$. So by Theorems A and B, we have our assertion in this case.

Case (5): $T=\phi A$
Finally, we assume that $T=\phi A$. Then, by (4.6), the structure vector $\xi$ is principal curvature vector with principal curvature $\alpha$. From this together with (4.5) we have

$$
\begin{equation*}
\phi A-A \phi=f \phi A \phi \tag{4.21}
\end{equation*}
$$

From this, applying $\phi$ to the left and using (2.1) and $\xi$ is principal, we get

$$
\begin{equation*}
\phi A \phi+(A-\alpha \eta \otimes \xi)=f A \phi \tag{4.22}
\end{equation*}
$$

Next, operating $\phi$ to (4.22) to the right and using (2.1), we find

$$
\begin{equation*}
A \phi-\phi A+f(A-\alpha \eta \otimes \xi)=0 \tag{4.23}
\end{equation*}
$$

from which together with (4.21) and (4.22) it follows

$$
\begin{equation*}
2(A \phi-\phi A)+f^{2} A \phi=0 \tag{4.24}
\end{equation*}
$$

Operating $\phi$ to (4.23) to the left and using (2.1) and also the fact $\xi$ is principal, we have

$$
\phi A \phi+f \phi A+(A-\alpha \eta \otimes \xi)=0
$$

from which together with (4.23) it follows

$$
\begin{equation*}
A \phi-\phi A=f \phi A \phi+f^{2} \phi A \tag{4.25}
\end{equation*}
$$

From (4.21) and (4.25) we have

$$
2(A \phi-\phi A)=f^{2} \phi A
$$

from which together with (4.24) it follows

$$
f^{2}(A \phi+\phi A)=0
$$

Let us also denote by $M_{1}$ an open set consisting of points $x$ in $M$ such that $f(x) \neq 0$. Then by the same argument as in above, we know that such an open subset $M_{1}$ do not exist. So $f$ vanishes identically on $M$. Thus we also have our assertion in Case (5).

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