Limit theorems for discretely observed stochastic volatility models

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A general set-up is proposed to study stochastic volatility models. We consider here a two-dimensional diffusion process (Y_t, V_t) and assume that only (Y_t) is observed at *n* discrete times with regular sampling interval Δ . The unobserved coordinate (V_t) is an ergodic diffusion which rules the diffusion coefficient (or volatility) of (Y_t) . The following asymptotic framework is used: the sampling interval tends to 0, while the number of observations and the length of the observation time tend to infinity. We study the empirical distribution associated with the observed increments of (Y_t) . We prove that it converges in probability to a variance mixture of Gaussian laws and obtain a central limit theorem. Examples of models widely used in finance, and included in this framework, are given.

Keywords: diffusion processes; discrete time observations; empirical distributions; limit theorems; mathematical finance; stochastic volatility

1. Introduction

Diffusion processes are now widely used for modelling purposes in various fields and especially in finance. Many papers are devoted to the estimation of drift and diffusion coefficients of such models. The diffusion sample path may be continuously or discretely observed and numerous asymptotic results have been obtained. Among many references, let us quote Kutoyants (1984), Dacunha-Castelle and Florens-Zmirou (1986), Donahl (1987), Genon-Catalot (1990), Larédo (1990), Genon-Catalot and Jacod (1993), Bibby and Sorensen (1995) and Kessler (1995). In these studies, when multidimensional diffusions are considered, all coordinates are assumed to be observed.

However, the case of an unobserved or hidden coordinate may occur in practice. Examples can be found in the field of finance with the introduction of the stochastic volatility models. Indeed, in this area, the term volatility stands for the diffusion coefficient of stock returns. The seminal model of Black and Scholes (1973) assumes that stock price processes follow a geometric Brownian motion with constant volatility, but recent empirical evidence has extensively shown that this constant volatility assumption is unrealistic (see, for example,

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Bollerslev *et al.* (1992) for a survey paper, and Taylor and Xu (1994, 1995) among many others). As an answer, some researchers have proposed models which include stochastic volatility in such a way that the couple (stock price, volatility) still behaves as a two-dimensional diffusion process (Hull and White (1987); Wiggins (1987); Scott (1987); Chesney and Scott (1989); Stein and Stein (1991); Heston (1993); Leblanc (1996)). This raises a difficulty since only the stock price is observable, while the volatility is unobservable.

Indeed, assume that (S_t) is the price process of some stock or asset and that the stock returns are ruled as usual by

$$\frac{\mathrm{d}S_t}{S_t} = \mu_t \,\mathrm{d}t + \sigma_t \,\mathrm{d}B_t.$$

Here, (σ_t) is the volatility of (S_t) , and (B_t) is a Brownian motion. In the first models, μ_t and σ_t are constants or deterministic functions of t. It follows from the discussion above that $V_t = \sigma_t^2$ can be modelled by a diffusion process, driven by another Brownian motion $(W_t, t \ge 0)$.

In this set-up, Nelson (1992) and Foster and Nelson (1994) give a solution to the problem of filtering (V_t) through (S_t) , i.e., they define estimators \hat{V}_t of V_t given the data up to time t of (S_u) . Our concern here is different. It is not to estimate the stochastic value V_t , but to get information on the distribution of the (V_t) process. So we are in the presence of a hidden Markov process. Most references in this field are concerned with discrete-time models, e.g., hidden Markov chains (see, for example, Elliott *et al.* (1995)). However, among the references quoted above, a few continuous-time models have been studied; in these papers, some estimators of parameters present in the (V_t) model are computed in specific cases, using stock prices data, with heuristic and empirical approach, but no theoretical study.

Our aim here is to propose a general set-up to study stochastic volatility models. Let us consider a two-dimensional diffusion (Y_t, V_t) such that

$$dY_t = \varphi(V_t) dt + V_t^{1/2} dB_t, \quad Y_0 = 0,$$

$$dV_t = b(V_t) dt + a(V_t) dW_t, \quad V_0 = \eta,$$

where $(B_t, W_t)_{t\geq 0}$ is a two-dimensional standard Brownian motion, (V_t) is a positive diffusion process and η is a positive random variable independent of $(B_t, W_t)_{t\geq 0}$.

In the model equations above, Y_t stands for $\log S_t$. The sample path (Y_t) is discretely observed at regularly spaced times $t_i = i\Delta$, i = 0, ..., n. The aim is to get information on the (V_t) model from the observations $(Y_{t_1}, ..., Y_{t_n})$ only. We introduce here the appropriate assumptions and asymptotic framework. The key assumption is that the diffusion (V_t) has to be ergodic. Apart from this assumption, the diffusion model for (V_t) can be quite general; so our results will apply to most of the specific models proposed in the financial literature.

Our asymptotic framework is as follows. The number of observations *n* tends to infinity, the sampling interval $\Delta = \Delta_n$ tends to zero, and the length of the observation time interval $n\Delta_n$ tends to infinity. We investigate the asymptotic behaviour of the empirical distribution \hat{P}_n associated with the random variables

$$X_{i} = X_{i}^{n} = \frac{1}{\Delta_{n}^{1/2}} (Y_{t_{i}} - Y_{t_{i-1}}),$$
(1)

where $t_i = t_i^n = i\Delta_n$, $i = 0, \ldots, n$, i.e.,

$$\hat{P}_n = \frac{1}{n} \sum_{i=1}^n \delta_{X_i^n},$$

where δ_a is the Dirac measure at point *a*.

The paper is organized as follows. In Sections 2 and 3, we set $\varphi = 0$. We assume that (V_t) is a strictly stationary positive process with stationary distribution $\pi(v) dv$ on $(0, +\infty)$. The main result of this paper is a convergence theorem for

$$\hat{P}_n(f) = \int_{\mathbb{R}} f(x) \, \mathrm{d}\hat{P}_n(x) = \frac{1}{n} \sum_{i=1}^n f(X_i^n),\tag{2}$$

where f belongs to a class of functions \mathscr{F} satisfying appropriate conditions. This class contains the functions $f(x) = x^{2p}$, $p \ge 1$ such that $E\eta^{2p}$ is finite. We prove in Theorem 1 that $\hat{P}_n(f)$ converges in probability to $P_{\pi}(f)$, where P_{π} is the distribution of $X = \epsilon \eta^{1/2}$ and (ϵ, η) has distribution $\mathscr{N}(0, 1) \otimes \pi(v) \, dv$. Therefore, the distribution P_{π} is a variance mixture of Gaussian laws, the mixing distribution being the stationary distribution of the unobservable diffusion (V_t) .

In Theorem 2, we prove that, under the additional assumption $n\Delta_n^2 \to 0$,

$$(n\Delta_n)^{1/2}[\hat{P}_n(f) - P_{\pi}(f)]$$

converges in distribution to a Gaussian distribution $\mathcal{N}(0, V(f))$. A difficulty arises when checking $V(f) < +\infty$. For this, we give a sufficient condition (Proposition 1) involving only the distribution π , which implies that V(f) is finite for any f in \mathcal{F} . The convergence in distribution also holds for finite-dimensional distributions (Theorem 3).

In Section 4, we study the case $\varphi \neq 0$. Under appropriate assumptions on φ , the results of Theorems 1 and 2 are unchanged (Theorem 4). This implies that φ may be known or unknown. Section 5 is devoted to the study of related models. We investigate the case where $V_t = \sigma_t^2$ with (σ_t) a stationary diffusion on \mathbb{R} . This includes the case of (σ_t) a Gaussian diffusion. Some examples are given in Section 6.

The results obtained here clearly have several statistical implications. The empirical distribution \hat{P}_n can be used to estimate the stationary distribution π of the unobserved diffusion (V_t) . This subject will be investigated in a forthcoming paper.

2. Model and assumptions

2.1. The model

Let $(Y_t, V_t)_{t \ge 0}$ be the two-dimensional diffusion process defined as the solution of

$$dY_t = V_t^{1/2} dB_t, Y_0 = 0,$$
 (3)

$$\mathrm{d}V_t = b(V_t)\,\mathrm{d}t + a(V_t)\,\mathrm{d}W_t, \ V_0 = \eta,\tag{4}$$

where

(1) $(B_t, W_t)_{t\geq 0}$ is a standard Brownian motion of \mathbb{R}^2 defined on a probability space $(\Omega, \mathcal{A}, \mathbf{P})$ and

(2) η is a random variable defined on Ω , independent of $(B_t, W_t)_{t\geq 0}$.

Equation (4) defines a one-dimensional diffusion process. We make now the classical assumptions on functions b and a which ensure that the solution of (4) is a positive recurrent diffusion on $(0, +\infty)$ and a strictly stationary and ergodic process.

(A1) b, a are continuous real functions on \mathbb{R} , and C^1 functions on $(0, +\infty)$ such that

$$\exists k > 0, \quad \forall v > 0, \quad b^2(v) + a^2(v) \le k(1 + v^2) \quad \text{and} \quad \forall v > 0, \quad a(v) > 0.$$

For $v_0 > 0$, define

$$s(v) = \exp\left(-2\int_{v_0}^{v} \frac{b(u)}{a^2(u)} \,\mathrm{d}u\right). \tag{5}$$

(A2)

$$\int_{0+} s(v) \, \mathrm{d}v = +\infty, \quad \int^{+\infty} s(v) \, \mathrm{d}v + \infty, \quad \int^{+\infty}_{0} \frac{\mathrm{d}v}{a^2(v)s(v)} = M < +\infty.$$

Let

$$\pi(v) = \frac{1}{M} \frac{1}{a^2(v)s(v)} \mathbf{1}_{(v>0)}.$$
(6)

(A3) The initial random variable η has distribution $\pi(v) dv$. (A4) $\exists \gamma \ge 2, \int_0^{+\infty} v^{\gamma} \pi(v) dv < +\infty$.

Assumptions (A1) and (A2) ensure existence and uniqueness of the solution of (4) together with the positive recurrence on $(0, +\infty)$. In particular, the following holds:

 $\mathbf{P}(V_t \ge 0, \forall t \ge 0) = 1.$

Assumption (A3) provides the strict stationarity property. Note that, for each $t \ge 0$, V_t has distribution $\pi(v) dv$ which satisfies, under (A4), $EV_t^{\gamma} < \infty$. So we introduce the notation

$$m(p) = \int_0^{+\infty} v^p \pi(v) \, \mathrm{d}v = \mathrm{E} V_t^p \qquad \text{for } 0 \le p \le \gamma.$$
(7)

Comment 1. We are aware that, in the financial papers, more general models are considered. The two Brownian motions (B_t) and (W_t) are supposed to be correlated; the drift function of (Y_t) may depend on t, Y_t and V_t . Here, we have chosen to simplify the model in order to clarify the statistical problems involved in this class of models.

2.2. Observations and asymptotic framework

The diffusion (V_t) is supposed to be unobservable but it rules the conditional variance of (Y_t) (see (3) and (4)). We assume that (Y_t) is observable but only at *n* discrete times with regular sampling interval Δ . We denote by $t_i = i\Delta$, i = 0, ..., n, these observation times. Our results are obtained in the asymptotic framework defined as follows. As $n \to +\infty$,

$$\Delta = \Delta_n \to 0$$
 and $T_n = n\Delta_n \to +\infty.$ (8)

The length T_n of the time interval where observations are available tends to infinity, while the sampling interval tends to 0.

Comment 2. In order to justify the double asymptotic framework, let us point out that a discrete Δ -sampling observation of (Y_t) on a fixed time interval provides information on the conditional variance V_T as $\Delta \to 0$. This is the filtering approach of Nelson (1992). To go further and obtain estimators for parameters in b(.) and a(.), we have to use the ergodicity properties of (V_t) , and so let $T = n\Delta_n$ tends to infinity. We refer for this to a forthcoming paper.

Our concern is the study of the asymptotic behaviour of $\hat{P}_n(f)$ (see (2)). In the next section, we introduce the appropriate class of functions f for this study.

2.3. The class of functions

For $f: \mathbb{R} \to \mathbb{R}$, let us consider, when defined, the function $h_f: \mathbb{R}^+ \to \mathbb{R}$:

$$h_f(v) = \int_{\mathbb{R}} f(xv^{1/2}) n(x) \,\mathrm{d}x,$$
(9)

where $n(x) = 1/(2\pi)^{1/2} \exp(-x^2/2)$ is the $\mathcal{N}(0, 1)$ density. We consider the following conditions.

(C1) Function f is C^1 and such that, for the exponent γ given in (A4),

$$\exists K_1 > 0, \, \forall x \in \mathbb{R}, \qquad |f(x)| \le K_1(1+|x|^{\gamma}). \tag{10}$$

(C2) Function f is such that $h_f \in C^1[0, +\infty)$ and, for γ given in (A4),

$$\exists K_2 > 0, \forall v \ge 0, \qquad |h'_f(v)| \le K_2(1 + v^{\gamma/2}).$$
 (11)

Denote by \mathscr{F}_{γ} the class of functions satisfying (C1) and (C2). Under (C1), the function h_f is well defined and continuous and satisfies $h_f(v) = Ef(\epsilon v^{1/2})$, where ϵ is a $\mathscr{N}(0, 1)$ random variable. Let us point out that, for $f \in \mathscr{F}_{\gamma}$, using (C1), (C2) and (A4),

$$\mathrm{E}h_{f}^{2}(V_{t}) = \mathrm{E}h_{f}^{2}(\eta) < +\infty, \qquad \mathrm{E}h_{f}^{\prime}{}^{2}(V_{t}) = \mathrm{E}h_{f}^{\prime}{}^{2}(\eta) < +\infty.$$

Note that $Eh_f(\eta) = Ef(\epsilon \eta^{1/2})$ where (ϵ, η) has distribution $\mathcal{N}(0, 1) \otimes \pi(v) dv$. Therefore, the distribution of $\epsilon \eta^{1/2}$ is a variance mixture of Gaussian laws, the mixing distribution being the stationary distribution of V_t . We shall denote this distribution by P_{π} . For $f \in \mathcal{F}_{\gamma}$, we have

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$$P_{\pi}(f) = \int_{\mathbb{R}} f(x) \, \mathrm{d}P_{\pi}(x) = \iint f(\epsilon v^{1/2}) n(x) \pi(v) \, \mathrm{d}x \, \mathrm{d}v = \int_{\mathbb{R}^+} h_f(v) \pi(v) \, \mathrm{d}v.$$
(12)

Let us give examples of functions f belonging to \mathscr{F}_{γ} .

(1) For $t \in \mathbb{R}$ and $f(x) = \exp(itx)$, $h_f(v) = \exp(-t^2v/2)$, and $P_{\pi}(f) = \mathbb{E}[\exp(-t^2\eta/2)]$. Although in this example, the function f is complex valued, the results below will be true because h_f is a real-valued function so that $P_{\pi}(f)$ is real.

(2) For $1 \le p \le \gamma/2$, $f(x) = x^{2p}$, $h_f(v) = C_{2p}v^p$, where

$$C_k = \int_{\mathbb{R}} |x|^k n(x) \,\mathrm{d}x \tag{13}$$

is the kth absolute moment of the distribution $\mathcal{N}(0, 1)$ and, using (7) and (12),

$$P_{\pi}(f) = C_{2p} \mathbb{E}\eta^p = C_{2p} m(p).$$

(3) This is a generalization of Example 2. Set $f(x) = g(x^2)$, $g \in C^1[0, +\infty)$, and

$$\exists K > 0, \quad \forall u \ge 0, \quad |g(u)| + |g'(u)| \le K(1 + u^{\gamma/2}).$$

Finally, we introduce the function

$$A_f(v) = \int_0^v [h_f(u) - P_\pi(f)] \pi(u) \,\mathrm{d}u.$$
(14)

Note that $A_f(+\infty) = 0$.

3. Limit theorems for the empirical distribution

3.1. Main results

We successively state the convergence in probability of $\hat{P}_n(f)$ and then the central limit theorem.

Theorem 1. Assume (A1)–(A4) and let f belong to \mathscr{F}_{γ} . Then, if $\Delta_n \to 0$ and $n\Delta_n \to +\infty$,

$$\hat{P}_n(f) \xrightarrow[n \to +\infty]{} P_{\pi}(f)$$
 in probability.

Going a step further into the analysis, we define

$$V(f) = 4M \int_0^{+\infty} s(v) A_f^2(v) \, \mathrm{d}v, \tag{15}$$

where s(.) and M are defined in (A2) and $A_f(v)$ is given in (14). Let us notice that the formula for V(f) does not depend on the choice of the value v_0 used to compute s(v) (see assumption (A2)). This is because the product Ms(v) does not depend on v_0 .

Theorem 2. Assume (A1)–(A4) and let f belong to \mathscr{F}_{γ} . Assume that $\Delta_n \to 0$ and $n\Delta_n \to +\infty$. If, moreover, $n\Delta_n^2 \to 0$ and $V(f) < +\infty$, then

$$(n\Delta_n)^{1/2}[\hat{P}_n(f) - P_n(f)] \xrightarrow[n \to +\infty]{\mathscr{D}} \mathscr{N}(0, V(f)).$$

If $f(x) = x^2$, the additional condition $n\Delta_n^2 \to 0$ is not needed.

Proofs of both theorems rely upon lemmas that we state now.

3.2. Preliminary lemmas

Let us define

$$\bar{V}_i = \frac{1}{\Delta_n} \int_{t_{i-1}}^{t_i} V_s \,\mathrm{d}s. \tag{16}$$

Lemma 1. Assume (A1)–(A4). Then, for $1 \le p \le \gamma$,

$$\mathrm{E}\bar{V}_i^p \leq m(p),$$

where m(p) is given in (7).

Proof. Since $p \ge 1$, the Hölder inequality gives

$$\bar{V}_i^p \leq \frac{1}{\Delta_n} \int_{t_{i-1}}^{t_i} V_s^p \,\mathrm{d}s,$$

which, by stationarity, gives the result.

Lemma 2. Assume (A1)–(A4). There exists a constant C such that, for $0 \le v \le 1$,

$$\mathcal{E}(V_v - V_0)^2 \le Cv,$$

where C only depends on m(2) and k (see (A1) and (7)).

Proof. This lemma is a straightforward consequence of our assumptions. We have

$$V_v - V_0 = \int_0^v b(V_u) \, \mathrm{d}u + \int_0^v a(V_u) \, \mathrm{d}W_u.$$

Thus, it follows that

$$(V_v - V_0)^2 \leq 2\left(\int_0^v b(V_u) \,\mathrm{d}u\right)^2 + 2\left(\int_0^v a(V_u) \,\mathrm{d}W_u\right)^2 \leq 2v \int_0^v b^2(V_u) \,\mathrm{d}u + 2\left(\int_0^v a(V_u) \,\mathrm{d}W_u\right)^2.$$

By (A1), we obtain

$$E(V_v - V_0)^2 \leq 2k \left(v \int_0^v [1 + E(V_u^2)] \, du + \int_0^v [1 + E(V_u^2)] \, du \right).$$

Now, by (A4), $EV_u^2 = \int v^2 \pi(v) \, dv = m(2) < +\infty$. Hence, $E(V_v - V_0)^2 \le 2k[1 + m(2)](v^2 + v)$. This gives the lemma.

Lemma 3. Assume (A1)–(A4). Let $\psi \in C^1[0, +\infty)$ be such that

$$\exists K > 0, \quad \forall v \ge 0, \quad |\psi'(v)| \le K(1 + v^{\gamma/2}).$$

Then,

$$B_n(\psi) = \frac{1}{n} \sum_{i=1}^n \psi(\bar{V}_i) - \frac{1}{n\Delta_n} \int_0^{n\Delta_n} \psi(V_s) \,\mathrm{d}s = \Delta_n^{1/2} O_P(1).$$

Proof. First note that, if ψ is linear, $B_n(\psi) \equiv 0$. Otherwise,

$$B_n(\psi) = \frac{1}{n\Delta_n} \sum_{i=1}^n \int_{t_{i-1}}^{t_i} [\psi(\bar{V}_i) - \psi(V_s)] \, \mathrm{d}s.$$

Applying the Taylor formula yields

$$\psi(\bar{V}_i) - \psi(V_s) = (\bar{V}_i - V_s)R_i(s),$$

with

$$R_i(s) = \int_0^1 \psi' [V_s + u(\bar{V}_i - V_s)] \,\mathrm{d}u.$$

Now consider

$$\bar{V}_i - V_s = \frac{1}{\Delta_n} \int_{t_{i-1}}^{t_i} (V_t - V_s) \,\mathrm{d}t.$$

Thus

$$|B_n(\psi)| \leq \frac{1}{n\Delta_n^2} \sum_{i=1}^n \int_{t_{i-1}}^{t_i} \mathrm{d}s \quad |R_i(s)| \int_{t_{i-1}}^{t_i} |V_t - V_s| \,\mathrm{d}t$$

Therefore, taking the expectation and then applying the Schwarz inequality lead to

$$\mathbf{E}|B_n(\psi)| \leq \frac{1}{n\Delta_n^2} \sum_{i=1}^n \int_{t_{i-1}}^{t_i} \int_{t_{i-1}}^{t_i} \mathrm{d}s \, \mathrm{d}t \, [\mathbf{E}(V_t - V_s)^2 \, \mathbf{E}R_i(s)^2]^{1/2}.$$
(17)

Lemma 2 and the strict stationarity give, for s, $t \in [t_{i-1}, t_i]$ and n large enough,

$$E(V_t - V_s)^2 = E(V_{|t-s|} - V_0)^2 \le C|t-s|.$$
(18)

Coming back to $R_i(s)$, we have, using the assumption on ψ' ,

$$|R_i(s)| \le K \int_0^1 [1 + |V_s + u(\bar{V}_i - V_s)|^{\gamma/2}] \, \mathrm{d}u,$$

$$V_s + u(\bar{V}_i - V_s) = \frac{1}{\Delta_n} \int_{t_{i-1}}^{t_i} [uV_t + (1 - u)V_s] \, \mathrm{d}t$$

Thus, by Hölder's inequality, since $\gamma/2 \ge 1$,

$$|V_s + u(\bar{V}_i - V_s)|^{\gamma/2} \leq \frac{1}{\Delta_n} \int_{t_{i-1}}^{t_i} |uV_t + (1-u)V_s|^{\gamma/2} dt \leq \frac{K(\gamma)}{\Delta_n} \int_{t_{i-1}}^{t_i} (V_t^{\gamma/2} + V_s^{\gamma/2}) dt,$$

for some constant $K(\gamma)$ and for all $u \in [0, 1]$. So,

$$|R_i(s)| \leq KK(\gamma) \left(1 + \frac{1}{\Delta_n} \int_{t_{i-1}}^{t_i} (V_t^{\gamma/2} + V_s^{\gamma/2}) \,\mathrm{d}t \right)$$

and

$$R_i(s)^2 \leq L\left(1 + \frac{1}{\Delta_n}\int_{t_{i-1}}^{t_i} (V_t^{\gamma} + V_s^{\gamma})\,\mathrm{d}t\right),\,$$

for some constant L > 0. Using now assumption (A4), we obtain

$$\mathbb{E}R_i(s)^2 \le L[1+2m(\gamma)]. \tag{19}$$

Applying inequalities (18) and (19) to (17) leads to

$$\mathbb{E}|B_n(\psi)| \leq \{CL[1+2m(\gamma)]\}^{1/2} \frac{1}{n\Delta_n^2} \sum_{i=1}^n \int_{t_{i-1}}^{t_i} \int_{t_{i-1}}^{t_i} \mathrm{d}s \,\mathrm{d}t \,|t-s|^{1/2}.$$

By a straightforward computation

$$\int_{t_{i-1}}^{t_i} \int_{t_{i-1}}^{t_i} \mathrm{d}s \,\mathrm{d}t \,|t-s|^{1/2} = \frac{8}{15} \Delta_n^2 \Delta_n^{1/2}.$$

This implies that $E|B_n(\psi)| \leq L' \Delta_n^{1/2}$ for some constant L' > 0. Thus, we get the result of Lemma 3.

3.3. Proofs of the theorems

Let us now prove the theorems.

Proof of Theorem 1. Let us study $\hat{P}_n(f) - P_{\pi}(f)$ when f belongs to \mathscr{F}_{γ} . Let $\mathscr{G} = \sigma(V_0, W_t, t \ge 0)$, and denote by $\mathbb{E}^{\mathscr{G}}$ the conditional expectation with respect to \mathscr{G} . Conditionally on \mathscr{G} , the random variables $(X_i, i = 1, ..., n)$ defined in (1) are independent and X_i has distribution $\mathscr{N}(0, \overline{V_i})$ where $\overline{V_i}$ is defined in (16). Moreover, let us check that

$$\mathbf{E}|f(X_i)| < \infty, \qquad \mathbf{E}^{\mathscr{G}}f(X_i) = h_f(\bar{V}_i).$$

By (C1), $|f(X_i)| \leq K_1(1+|X_i|^{\gamma})$. So, using Lemma 1, and (13) for the definition of C_{γ} ,

$$\mathbf{E}|X_i|^{\gamma} = \mathbf{E}\,\mathbf{E}^{\mathscr{G}}|X_i|^{\gamma} = C_{\gamma}\,\mathbf{E}\bar{V}_i^{\gamma/2} \leqslant C_{\gamma}\,m\left(\frac{\gamma}{2}\right).$$

Thus, $|f(X_i)|$ has finite expectation and

$$\mathbb{E}^{\mathscr{G}}f(X_{i}) = \int_{\mathbb{R}} f(x) \exp\left(-\frac{x^{2}}{2\bar{V}_{i}}\right) \frac{\mathrm{d}x}{(2\pi\bar{V}_{i})^{1/2}} = \int_{\mathbb{R}} f(x\bar{V}_{i}^{1/2})n(x)\,\mathrm{d}x = h_{f}(\bar{V}_{i}).$$

Now, we can split the difference $\hat{P}_n(f) - P_{\pi}(f)$ into the sum of three terms:

$$\hat{P}_n(f) - P_\pi(f) = A_n + B_n + D_n,$$
(20)

with, using the notation introduced in Lemma 3,

$$A_n = \frac{1}{n} \sum_{i=1}^n [f(X_i) - \mathbb{E}^{\mathscr{G}} f(X_i)],$$
(21)

$$B_n = \frac{1}{n} \sum_{i=1}^n \mathbb{E}^{\mathscr{T}} f(X_i) - \frac{1}{n\Delta_n} \int_0^{n\Delta_n} h_f(V_s) \, \mathrm{d}s = B_n(h_f),$$
(22)

$$D_n = \frac{1}{n\Delta_n} \int_0^{n\Delta_n} h_f(V_s) \,\mathrm{d}s - \int_0^\infty h_f(v) \pi(v) \,\mathrm{d}v.$$
(23)

Recall that

$$P_{\pi}(f) = \int_0^\infty h_f(v) \pi(v) \,\mathrm{d}v.$$

Since f satisfies (C2), we can apply Lemma 3 with $\psi = h_f$. Thus,

$$B_n(h_f) = \Delta_n^{1/2} O_P(1).$$
(24)

We may apply to (V_t) an ergodic theorem for one-dimensional positive recurrent diffusion (see, for example, Rogers and Williams (1987, p. 300)). Since $n\Delta_n \to +\infty$, we have, almost surely,

$$\frac{1}{n\Delta_n}\int_0^{n\Delta_n}h_f(V_s)\,\mathrm{d} s \underset{n\to+\infty}{\to}\int_0^{\infty}h_f(v)\pi(v)\,\mathrm{d} v.$$

Thus,

$$D_n \xrightarrow[n \to +\infty]{} 0$$
 almost surely. (25)

Let us now study A_n . For this, set

$$\chi_i^n = \frac{1}{n} [f(X_i) - \mathbb{E}^{\mathscr{G}} f(X_i)].$$

Conditionally on \mathscr{G} , the random variables χ_i^n are centred and independent. Thus,

$$\mathrm{E}^{\mathscr{G}}(A_n^2) = \sum_{i=1}^n \mathrm{E}^{\mathscr{G}}(\chi_i^n)^2.$$

Now

$$\mathbf{E}^{\mathscr{G}}(\chi_{i}^{n})^{2} = \frac{1}{n^{2}} \{ \mathbf{E}^{\mathscr{G}} f^{2}(X_{i}) - [\mathbf{E}^{\mathscr{G}} f(X_{i})]^{2} \} \leq \frac{1}{n^{2}} \mathbf{E}^{\mathscr{G}} f^{2}(X_{i}) = \frac{1}{n^{2}} \int f^{2}(x \bar{V}_{i}^{1/2}) n(x) \, \mathrm{d}x.$$

Using condition (C1) leads to $f^2(x) \leq K'_1(1 + x^{2\gamma})$. Thus,

$$\mathbf{E}^{\mathscr{G}} f^2(X_i) \leq K_1' (1 + C_{2\gamma} \bar{V}_i^{\gamma}).$$

Therefore, by Lemma 1,

$$\mathbb{E}(\chi_i^n)^2 \leq \frac{1}{n^2} K_1' [1 + C_{2\gamma} m(\gamma)]$$

This implies that

$$\mathbf{E}A_n^2 \leq \frac{1}{n}K_1'[1 + C_{2\gamma}m(\gamma)].$$

Thus,

$$A_n = n^{-1/2} O_{\mathbf{P}}(1). \tag{26}$$

Joining (24)-(26) achieves the proof of Theorem 1.

Proof of Theorem 2. We study now $(n\Delta_n)^{1/2} [\hat{P}_n(f) - P_n(f)]$. Using the notation in (21)–(23),

$$(n\Delta_n)^{1/2}[\hat{P}_n(f) - P_\pi(f)] = (n\Delta_n)^{1/2}A_n + (n\Delta_n)^{1/2}B_n(h_f) + (n\Delta_n)^{1/2}D_n.$$
 (27)

Two cases may occur; if $f(x) = x^2$, the function $h_f(v) \equiv v$, and, in this case, $B_n(h_f) \equiv 0$. Otherwise, it follows from (24) that

$$(n\Delta_n)^{1/2}B_n(h_f) = (n\Delta_n^2)^{1/2}O_{\mathbf{P}}(1).$$

Hence, if $n\Delta_n^2 \to 0$ as $n \to +\infty$, this term will asymptotically vanish. From (26), we see that

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$$(n\Delta_n)^{1/2}A_n = \Delta_n^{1/2}O_{\mathbf{P}}(1),$$

which also goes to 0.

We only have to study the convergence in distribution of the third term of (27). It is equal to

$$(n\Delta_n)^{1/2}D_n = \frac{1}{(n\Delta_n)^{1/2}} \int_0^{n\Delta_n} \left(h_f(V_s) - \int_0^\infty h_f(v) \pi(v) \, \mathrm{d}v \right) \, \mathrm{d}s.$$

In order to apply a central limit theorem for one-dimensional positive recurrent diffusions (see, for example, Florens-Zmirou (1984)), let us set

$$H_f(u) = h_f(u) - \int_0^\infty h_f(v) \pi(v) \,\mathrm{d}v$$

Clearly, the following holds:

$$\int_0^\infty H_f(v)\pi(v)\,\mathrm{d}v=0.$$

Therefore,

$$\frac{1}{(n\Delta_n)^{1/2}} \int_0^{n\Delta_n} H_f(V_s) \,\mathrm{d}s \underset{n \to +\infty}{\xrightarrow{\mathscr{D}}} \mathcal{N}(0, V(f)),$$

where V(f) is given by the formula

$$V(f) = 4 \int_0^\infty \pi(v) \left(s(v)a(v) \int_0^v du \frac{H_f(u)}{a^2(u)s(u)} \right)^2 dv.$$

Definitions (5), (6), (9) and (14) lead to the expression of V(f) given in (15).

Consequence. Let us consider sampling intervals $\Delta_n = n^{-\alpha}$. The conditions $\Delta_n \to 0$ and $n\Delta_n \to +\infty$ lead to $0 < \alpha < 1$. The additional condition $n\Delta_n^2 \to 0$ leads to $\frac{1}{2} < \alpha < 1$. Therefore, the rate of convergence of Theorem 2 is $(n\Delta_n)^{1/2} = n^{(1-\alpha)/2}$ with $0 < (1-\alpha)/2 < \frac{1}{4}$.

3.4. Some bounds for the asymptotic variance

The result of Theorem 2 holds under the assumption that the quantity V(f) defined in (15) is finite. For this, we have to study the behaviour around 0 and $+\infty$ of the function $s(v)A_f^2(v)$. The proposition below provides explicit bounds which can be easily computed.

Proposition 1. Assume (A1)–(A4) and

(i)
$$\int_{0^+} \mathrm{d} v \, s(v) \left(\int_0^v \pi(u) \, \mathrm{d} u \right)^2 < +\infty,$$

and

(ii)
$$\int_{v}^{\infty} \mathrm{d}v \, s(v) \left(\int_{v}^{+\infty} u^{\gamma/2} \pi(u) \, \mathrm{d}u \right)^{2} < +\infty,$$

then, for all $f \in \mathscr{F}_{\gamma}, V(f) < +\infty.$

Proof. This result is a straightforward consequence of the following lemma.

Lemma 4. Assume (A1)–(A4) and let f belong to \mathscr{F}_{γ} . Then,

(i) there exist C > 0 and $v_0 > 0$ such that

$$\forall v \in [0, v_0], \quad |A_f(v)| \leq C \int_0^v \pi(u) \,\mathrm{d}u$$

and

(ii) there exist C' > 0 and $v_1 > 0$ such that

$$\forall v \ge v_1, \quad |A_f(v)| \le C' \int_v^{+\infty} u^{\gamma/2} \pi(u) \,\mathrm{d} u.$$

Proof. Condition (C1) states that

$$\exists K_1 > 0, \quad \forall x \in \mathbb{R}, \quad |f(x)| \leq K_1(1+|x|^{\gamma}).$$

Therefore, see (9) and (13),

$$\forall v \geq 0, \quad |h_f(v)| \leq K_1(1+C_{\gamma}v^{\gamma/2}).$$

Now,

$$|A_f(v)| \leq \int_0^v [|h_f(u)| + |P_{\pi}(f)|]\pi(u) \,\mathrm{d}u.$$

This leads to (i).

To deal with the neighbourhood of $+\infty$, we first recall that $A_f(+\infty) = 0$. Hence

$$A_{f}(v) = -\int_{v}^{+\infty} \pi(u) \, \mathrm{d}u \, [h_{f}(u) - P_{\pi}(f)].$$

Therefore,

$$|A_f(v)| \leq \int_v^{+\infty} \pi(u) \,\mathrm{d}u \, [|h_f(u)| + |P_{\pi}(f)|],$$

which leads to (ii).

Remark. In some cases, V(f) can be explicitly computed. However, Proposition 1 gives sufficient conditions for checking that V(f) is finite. Both conditions are easy to check and interesting because they only involve the diffusion model for (V_t) and the moment condition on the stationary distribution π .

3.5. Finite-dimensional distributions

Theorem 2 can be extended to finite-dimensional distributions. Let f, g be two functions in \mathscr{F}_{γ} . Set V(f) = V(f, f) and

$$V(f, g) = 4M \int_0^\infty s(v) A_f(v) A_g(v) \, \mathrm{d}v.$$
(28)

Theorem 3. Assume (A1)–(A4) and let (f_1, \ldots, f_k) be a finite set of functions in \mathscr{F}_{γ} . Assume that $\Delta_n \to 0$ and $n\Delta_n \to +\infty$. If, moreover, $n\Delta_n^2 \to 0$ and $V(f_i, f_i) < +\infty$ for $i = 1, \ldots, k$, then the vector

$$(n\Delta_n)^{1/2}[\hat{P}_n(f_i) - P_\pi(f_i)]_{1 \le i \le k}$$

converges in distribution to $\mathcal{N}_k(0, (V(f_i, f_j))_{1 \le i,j \le k})$.

Proof. Clearly, the assumption $V(f_i, f_i) < \infty$ for i = 1, ..., k implies that all the quantities $V(f_i, f_j)$ are well defined. Now, let $\alpha_1, ..., \alpha_k$ be given real numbers, and set $f = \alpha_1 f_1 + ... + \alpha_k f_k$. Then,

$$\hat{P}_n(f) - P_{\pi}(f) = \sum_{i=1}^k \alpha_i [\hat{P}_n(f_i) - P_{\pi}(f_i)].$$

Since $h_f(v) = \sum_{i=1}^k \alpha_i h_{f_i}(v)$, the function $A_f(v)$ associated with f satisfies

$$A_f(v) = \sum_{i=1}^k \alpha_i A_{f_i}(v)$$

and V(f, f) has the expansion

$$V(f, f) = \sum_{i=1}^{k} \alpha_i^2 V(f_i, f_i) + 2 \sum_{1 \le i < j \le k} \alpha_i \alpha_j V(f_i, f_j).$$

This gives the result.

4. Extension to the presence of a drift in the (Y_t) model

Stochastic models for stock prices and instantaneous standard deviations of the stock returns are generally given by

$$dS_t = \mu S_t dt + V_t^{1/2} S_t dB_t,$$

$$dV_t = b(V_t) dt + a(V_t) dW_t.$$

Only (S_t) is observed and, in the simplest case, μ is a deterministic constant. In order to recover the previous setting, let $Y_t = \log S_t$. Then, a standard application of the Ito formula yields

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$$dY_t = (\mu - \frac{1}{2}V_t) dt + V_t^{1/2} dB_t$$

This example shows the interest of studying models where there is a drift term in (Y_t) depending only on the instantaneous conditional variance V_t .

Let us now consider the model

$$dY_t = \varphi(V_t) dt + V_t^{1/2} dB_t, \qquad Y_0 = 0,$$

$$dV_t = b(V_t) dt + a(V_t) dW_t \qquad V_0 = \eta,$$

with η independent of $(B_t, W_t)_{t\geq 0}$. From now on, we assume (A1)–(A4). As previously, define

$$X_i = \frac{1}{\Delta_n^{1/2}} (Y_{t_i} - Y_{t_{i-1}}), \quad i = 1, \ldots, n,$$

and introduce the random variables

$$\xi_i = \frac{1}{\Delta_n^{1/2}} \int_{t_{i-1}}^{t_i} V_s^{1/2} \, \mathrm{d}B_s, \quad i = 1, \ldots, n.$$

Clearly, the results of Section 3 apply to the ξ_i variables. We obtain below that these results are still true when X_i is substituted for ξ_i .

Let us define

$$\hat{P}_n = \frac{1}{n} \sum_{i=1}^n \delta_{X_i}, \qquad \hat{Q}_n = \frac{1}{n} \sum_{i=1}^n \delta_{\xi_i}.$$

Theorem 4. Assume (A1)–(A4). Let f belong to \mathscr{F}_{γ} and assume moreover that f' is such that

 $\exists p, 1 \leq p \leq \gamma, \exists C, \forall x \in \mathbb{R}, |f'(x)| \leq C(1+|x|^p).$

Then, if the drift function φ satisfies $E|\varphi(\eta)|^{p+1} < +\infty$, one has

- (i) if Δ_n tends to 0 and $n\Delta_n$ tends to infinity, Theorem 1 holds for $\hat{P}_n(f)$, and
- (ii) if moreover $n\Delta_n^2$ tends to 0, Theorem 2 holds for $\hat{P}_n(f)$.

Proof. Theorem 1 and Theorem 2 hold for \hat{Q}_n . So, only the difference $\hat{P}_n(f) - \hat{Q}_n(f)$ has to be studied. By the Taylor formula,

$$\hat{P}_n(f) - \hat{Q}_n(f) = \frac{1}{n} \sum_{i=1}^n (X_i - \xi_i) \int_0^1 f' [\xi_i + u(X_i - \xi_i)] \, \mathrm{d}u.$$

Note that $X_i - \xi_i = \Delta_n^{-1/2} \int_{t_{i-1}}^{t_i} \varphi(V_s) ds$ are \mathscr{G} -measurable random variables where $\mathscr{G} = \sigma(V_0, (W_t, t \ge 0))$. Using the assumption on f',

$$|f'[\xi_i + u(X_i - \xi_i)]| \le C(1 + |\xi_i + u(X_i - \xi_i)|^p) \le C'(1 + |\xi_i|^p + |X_i - \xi_i|^p),$$

for all $u \in [0, 1]$. Taking the conditional expectation with respect to \mathscr{G} and using that ξ_i is $\mathscr{N}(0, \overline{V}_i)$ lead to

$$\mathbf{E}^{\mathscr{G}}[f'[\xi_i + u(X_i - \xi_i)]] \leq C'(1 + C_p \bar{V}_i^{p/2} + |X_i - \xi_i|^p).$$

Recall that $\bar{V}_i = (1/\Delta_n) \int_{t_{i-1}}^{t_i} V_s \, ds$ and that C_p is the *p*th absolute moment of the $\mathcal{N}(0, 1)$ distribution. Therefore,

$$\mathbb{E}|\hat{P}_n(f) - \hat{Q}_n(f)| \leq \frac{C'}{n} \sum_{i=1}^n L_i,$$

with

$$L_{i} = \mathbb{E}[|X_{i} - \xi_{i}|(1 + C_{p}\bar{V}_{i}^{p/2} + |X_{i} - \xi_{i}|^{p})]$$

For $k \ge 1$, one has

$$\mathbf{E}|X_i - \xi_i|^k = \Delta_n^{k/2} \mathbf{E}\left(\left|\frac{1}{\Delta n}\int_{t_{i-1}}^{t_i} \varphi(V_s)\,\mathrm{d}s\right|^k\right) \leq \Delta_n^{k/2} \mathbf{E}|\varphi(\eta)|^k.$$

Using now the Cauchy-Schwarz inequality, and applying Lemma 1 to \bar{V}_i , we get

$$\mathbb{E}(|X_i - \xi_i| \bar{V}_i^{p/2}) \leq [\mathbb{E}(X_i - \xi_i)^2 \mathbb{E} \bar{V}_i^p]^{1/2} \leq \Delta_n^{1/2} [\mathbb{E} \varphi^2(\eta)]^{1/2} m(p)^{1/2}.$$

Joining these results, we obtain

$$L_i \leq \Delta_n^{1/2} \{ \mathbf{E} | \varphi(\eta) | + C_p [\mathbf{E} \varphi^2(\eta)]^{1/2} m(p)^{1/2} \} + \Delta_n^{(p+1)/2} \mathbf{E} | \varphi(\eta) |^{p+1}$$

Therefore,

$$\mathbf{E}|\hat{P}_n(f) - \hat{Q}_n(f)| \le C'' \Delta_n^{1/2}.$$

Thus $|\hat{P}_n(f) - \hat{Q}_n(f)| = \Delta_n^{1/2} O_{\mathbf{P}}(1)$. So, the presence of a drift function φ in the (Y_t) model induces a bias of order $\Delta_n^{1/2}$. We see that

$$\hat{P}_n(f) - \hat{Q}_n(f) \xrightarrow[n \to \infty]{} 0$$
 in probability,

and, if $n\Delta_n^2 \to 0$,

$$(n\Delta_n)^{1/2}[\hat{P}_n(f) - \hat{Q}_n(f)] \xrightarrow[n \to \infty]{} 0$$
 in probability.

This achieves the proof of Theorem 4.

5. Extension to some related models

Usually, in the financial models, the conditional instantaneous variance of the observed diffusion (Y_t) is given by σ_t^2 and, depending on the researchers, either σ_t or $V_t = \sigma_t^2$ is ruled by a stochastic differential equation. The second case has been studied above. However, this framework puts aside some models (see, for example, Example 4 in Section 6). This is the reason why we study the extension to the case where the stochastic differential equation involves σ_t .

Let $(Y_t, \sigma_t)_{t \ge 0}$ be the two-dimensional diffusion process defined by

$$\mathrm{d}Y_t = \sigma_t \,\mathrm{d}B_t, \quad Y_0 = 0,\tag{29}$$

$$d\sigma_t = b(\sigma_t) dt + a(\sigma_t) dW_t, \quad \sigma_0 = \xi,$$
(30)

with $(B_t, W_t)_{t\geq 0}$ a standard Brownian motion of \mathbb{R}^2 , and ξ independent of $(B_t, W_t)_{t\geq 0}$. Note that $dY_t = \sigma_t dB_t$ and $dY_t = (\sigma_t^2)^{1/2} dB_t$ gives the same distribution for the process Y_t . Now we assume the following.

(A'1) Functions b and a are C^1 on \mathbb{R} and such that

 $\exists k > 0, \quad \forall u \in \mathbb{R}, \quad b^2(u) + a^2(u) \le k(1+u^2).$

(A'2) The function s(u) of diffusion σ_t is defined as in (5) but now for u in \mathbb{R} , and

$$\int_{-\infty}^{+\infty} s(u) \, \mathrm{d}u = \int_{-\infty}^{+\infty} s(u) \, \mathrm{d}u = +\infty, \qquad \tilde{M} = \int_{-\infty}^{+\infty} \frac{\mathrm{d}u}{a^2(u)s(u)} < +\infty.$$

(A'3) Let $\tilde{\pi}(u) = 1/\tilde{M}a^2(u)s(u)$ denote the stationary distribution of σ_t on \mathbb{R} . Assumption (A3) therefore becomes as follows: the initial random variable ξ has distribution $\tilde{\pi}(u) du$.

(A'4) We assume that $\tilde{\pi}$ verifies

$$\exists a \ge 4, \quad \int_{\mathbb{R}} |u|^{a} \tilde{\pi}(u) \, \mathrm{d}u < +\infty.$$

We consider now the class of functions $\mathscr{F}_{\alpha/2}$ (see (10) and (11) for the definition of \mathscr{F}_{γ} , and (9) for the definition of $h_f(v)$). Denote the *p*th moment of $\tilde{\pi}$ by

$$\tilde{m}(p) = \int_{\mathbb{R}} u^p \tilde{\pi}(u) \, \mathrm{d}u \quad \text{for } 0 \le p \le \alpha.$$
(31)

From the observations Y_{t_i} defined by (29), we consider the same variables X_i as defined in (1). Now, let us denote

$$P_{\tilde{\pi}}(f) = \int_{\mathbb{R}} h_f(u^2) \tilde{\pi}(u) \,\mathrm{d}u.$$
(32)

The main difference here is that $P_{\hat{\pi}}$ is the distribution of $\epsilon |\xi|$, where (ϵ, ξ) has distribution $\mathcal{N}(0, 1) \otimes \tilde{\pi}(u) \, du$. Note that

$$\mathbf{E}h_f(\xi^2) = \mathbf{E}f(\epsilon|\xi|) = P_{\tilde{\pi}}(f)$$

Let us define

$$\tilde{A}_f(v) = \int_{-\infty}^v [h_f(u^2) - P_{\tilde{\pi}}(f)]\tilde{\pi}(u) \,\mathrm{d}u, \quad v \in \mathbb{R},$$
(33)

$$\tilde{V}(f) = 4\tilde{M} \int_{\mathbb{R}} s(u) \tilde{A}_{f}^{2}(u) \,\mathrm{d}u.$$
(34)

Then, the following holds.

Theorem 5. Assume (A'1)–(A'4) and that f belongs to $\mathscr{F}_{\alpha/2}$. Now, if $\Delta_n \to 0$ and $n\Delta_n \to +\infty$, then

(i) $\hat{P}_n(f) \to P_{\tilde{\pi}}(f)$ in probability, as n tends to infinity and (ii) if moreover $n\Delta_n^2 \to 0$ and $\tilde{V}(f) < +\infty$,

$$(n\Delta_n)^{1/2}[\hat{P}_n(f) - P_{\tilde{\pi}}(f)] \xrightarrow[n \to +\infty]{\mathscr{Y}} \mathscr{N}(0, \ \tilde{V}(f)).$$

If $f(x) = x^2$, the additional assumption $n\Delta_n^2 \to 0$ is not needed.

The proof is a minor generalization of our earlier results and is omitted. As previously for Theorem 2, Theorem 5 holds whenever $\tilde{V}(f) < +\infty$. The useful sufficient conditions which allow one to check this property are now the following:

(i)
$$\int_{-\infty} \mathrm{d} v \, s(v) \left(\int_{-\infty}^{v} |u|^{\gamma/2} \tilde{\pi}(u) \, \mathrm{d} u \right)^2 < +\infty,$$

(ii)
$$\int_{v}^{\infty} \mathrm{d}v \, s(v) \left(\int_{v}^{+\infty} |u|^{\gamma/2} \tilde{\pi}(u) \, \mathrm{d}u \right)^{2} < +\infty.$$

Then, if (i) and (ii) hold, for all $f \in \mathscr{F}_{a/2}$, $V(f) < +\infty$. As in Lemma 4, these conditions are deduced from upper bounds for $\tilde{A}_f(v)$ near $-\infty$ and $+\infty$.

6. Examples

Several parametric models for the stochastic volatility V_t have been proposed by various workers. We give below some examples which are all included in the above framework. Assumptions (A1)–(A4) are readily checked and the stationary distribution π , is, in each case, a simple and classical distribution whose moments can be easily computed.

Now, the results of the previous sections show that the moments of the distribution P_{π} can be consistently estimated by means of empirical moments built from the observations. An important point is that the 2*p*th moments of P_{π} are linked to the *p*th moments of π by the relation

$$\int x^{2p} \, \mathrm{d}P_{\pi}(x) = C_{2p} \int v^p \pi(v) \, \mathrm{d}v = C_{2p} m(p)$$

(see (7) and (13)).

Therefore all the moments of the distribution π can be consistently estimated. Details and simulation results will be investigated in a separate paper. Let us now consider the examples.

Example 1 (Heston 1993).

$$\mathrm{d}V_t = \frac{c^2}{2}(a - \lambda V_t)\,\mathrm{d}t + c V_t^{1/2}\,\mathrm{d}W_t.$$

Assumption (A2) holds if $\lambda > 0$ and $a \ge 1$. The stationary distribution $\pi(v) dv$ of (V_t) is the standard gamma distribution with parameters a and λ :

$$\pi(v) = \frac{\lambda^a}{\Gamma(a)} \exp\left(-\lambda v\right) v^{a-1} \mathbf{1}_{(v>0)}.$$

This distribution has moments of order p for all positive p. Hence (A4) holds. These moments are given by

$$m(p) = \frac{\Gamma(a+p)}{\Gamma(a)\lambda^p}.$$

Example 2. This example is the diffusion approximation of a discrete GARCH(1, 1) model:

$$\mathrm{d}V_t = \frac{c^2}{2}(\lambda - aV_t)\,\mathrm{d}t + cV_t\,\mathrm{d}W_t.$$

Assumption (A2) holds if $\lambda > 0$ and a > -1. The stationary distribution π of (V_t) is the distribution with density

$$\pi(v) = \frac{\lambda^{a+1}}{\Gamma(a+1)} v^{-a} \exp\left(-\frac{\lambda}{v}\right) \frac{1}{v^2} \mathbf{1}_{v>0}.$$

Hence, it is the distribution of 1/X where X is a random variable distributed according to a gamma distribution with parameters a + 1 and λ . The moments of π are defined by

$$m(p) = \lambda^p \frac{\Gamma(a+1-p)}{\Gamma(a+1)} \quad \text{if} \quad p < a+1,$$
$$m(p) = +\infty \quad \text{if} \quad p \ge a+1.$$

Example 3. (Chesney and Scott 1989).

$$V_t = \exp(X_t), \quad dX_t = \alpha(\beta - X_t) dt + \rho dW_t$$

Clearly, since (X_t) is an Ornstein–Uhlenbeck diffusion process with stationary distribution $\mathcal{N}(\beta, \rho^2/2\alpha)$, if $\alpha > 0$, (V_t) is ergodic with a log-normal stationary distribution which has moments of any order, given by

$$m(p) = \exp\left(p\beta + \frac{p^2}{2}\frac{\rho^2}{2\alpha}\right).$$

Example 4 (Scott 1987; Stein and Stein 1991).

$$V_t = \sigma_t^2$$
, $d\sigma_t = \alpha(\beta - \sigma_t) dt + \rho dW_t$.

Here, when $\alpha > 0$, (σ_t) is an ergodic diffusion on \mathbb{R} (see Section 5), $\tilde{\pi}(u)$ is the distribution $\mathcal{N}(\beta, \rho^2/2\alpha)$ and

$$\tilde{m}(2p) = \mathbf{E}\left[\beta + \left(\frac{\rho^2}{2\alpha}\right)^{1/2}\epsilon\right]^{2p},$$

where ϵ has distribution $\mathcal{N}(0, 1)$. When $\beta = 0$, this is a special case of Example 1.

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