Limited Automata and Context-Free Languages

Giovanni Pighizzini Andrea Pisoni

Dipartimento di Informatica Università degli Studi di Milano, Italy

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The Chomsky Hierarchy

1-tape Turing Machines		type 0
Linear Bounded Automata	ty	pe 1
Pushdown Automata	type 2	
Finite Automata	type 3	

Limited Automata [Hibbard'67]

One-tape Turing machines with restricted rewritings

Definition

Fixed an integer $d \ge 1$, a d-limited automaton is

- ▶ a one-tape Turing machine
- which is allowed to rewrite the content of each tape cell only in the first d visits

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Computational power

- For each $d \ge 2$, d-limited automata characterize context-free languages [Hibb
 - [Hibbard'67]
- ► 1-limited automata characterize regular languages [Wagner&Wechsung'86]

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Finite Automata	type 3		

Determinism vs Nondeterminism

➤ 2-Limited Automata ≡ Pushdown Automata: descriptional complexity point of view

$$2$$
-LAs \rightarrow PDAs
Exponential gap

▶ Determinism vs Nondeterminism

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$$2-LAs \rightarrow PDAs$$

Exponential gap

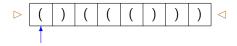
$$PDAs \rightarrow 2-LAs$$

Polynomial upper bound

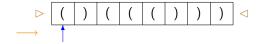
Determinism vs Nondeterminism

Deterministic Context-Free Languages ≡ Deterministic 2-LAs

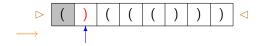




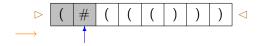
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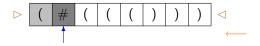
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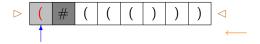
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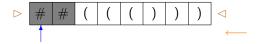
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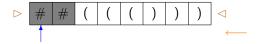
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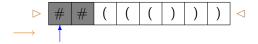
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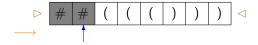
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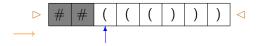
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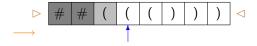
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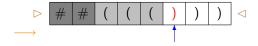
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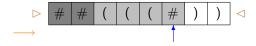
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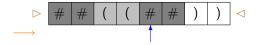
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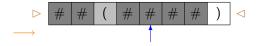
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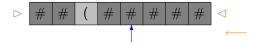
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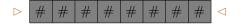
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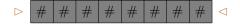
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Special cases:

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Each cell is rewritten only in the first 2 visits!



Simulation of 2-Limited Automata by Pushdown Automata

Problem

How much it costs, in the description size, the simulation of 2-LAs by PDAs?

This work

Exponential cost!

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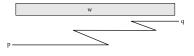
Exponential cost!

- Fixed a 2-limited automaton
- ▶ Transition table τ_w

w is a "frozen" string

$$\tau_w \subseteq Q \times \{-1, +1\} \times Q \times \{-1, +1\}$$



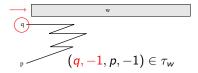


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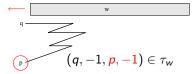
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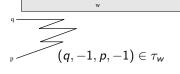
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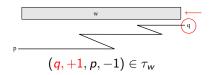


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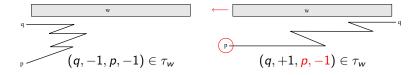
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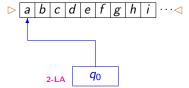
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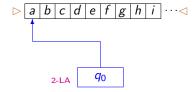


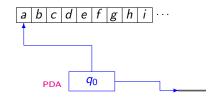
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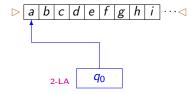


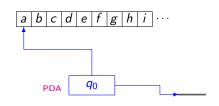
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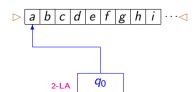


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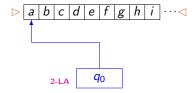


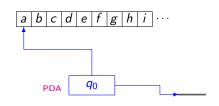


Some computation steps...

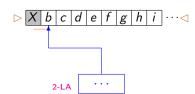


Initial configuration

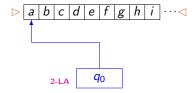


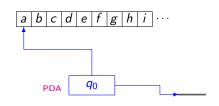


Some computation steps...

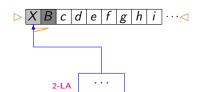


Initial configuration

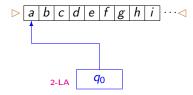


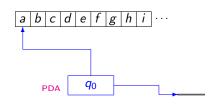


Some computation steps...



Initial configuration

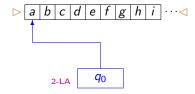


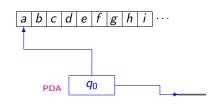


Some computation steps...

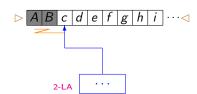


Initial configuration

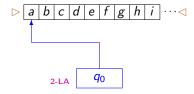


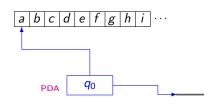


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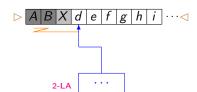


Initial configuration

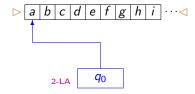


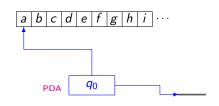


Some computation steps...

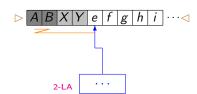


Initial configuration

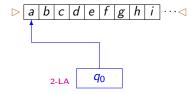


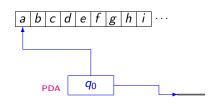


Some computation steps...

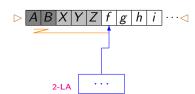


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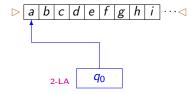


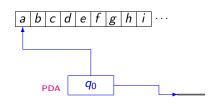


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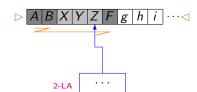


Initial configuration

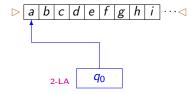


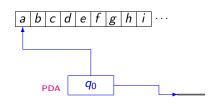


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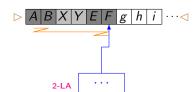


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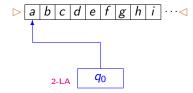


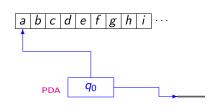


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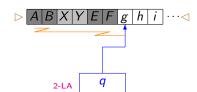


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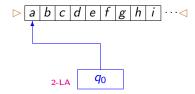


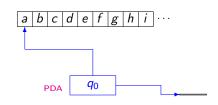


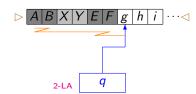
Some computation steps...

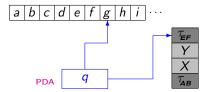


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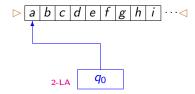


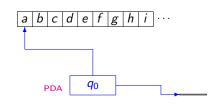


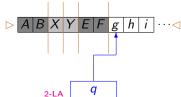


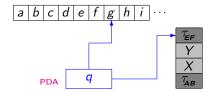


Initial configuration

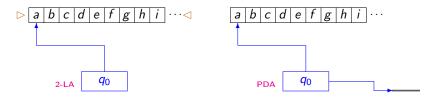






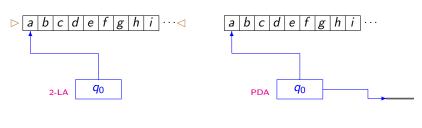


Initial configuration



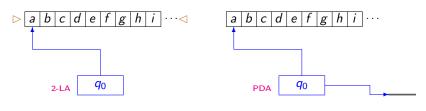


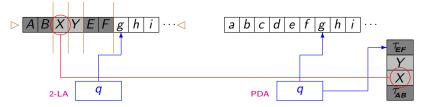
Initial configuration



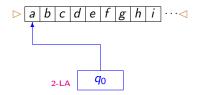


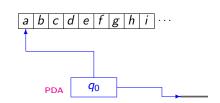
Initial configuration

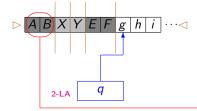


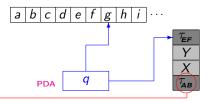


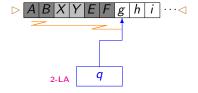
Initial configuration

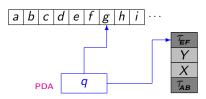


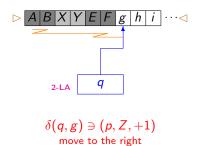


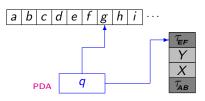


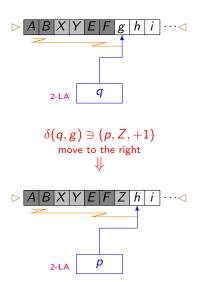


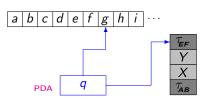


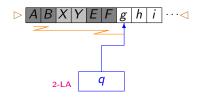




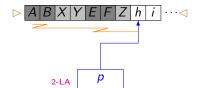


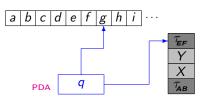




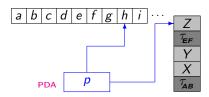


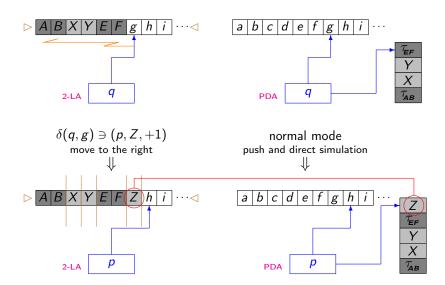
$$\delta(q,g) \ni (p,Z,+1)$$
move to the right
 $\downarrow \downarrow$

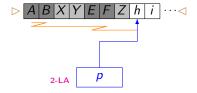


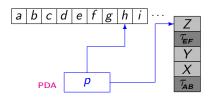


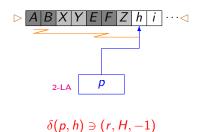




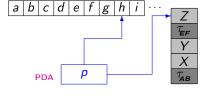


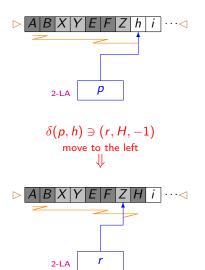


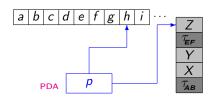


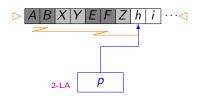


move to the left

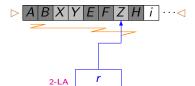


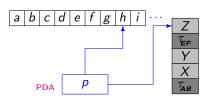




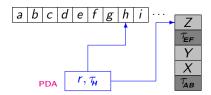


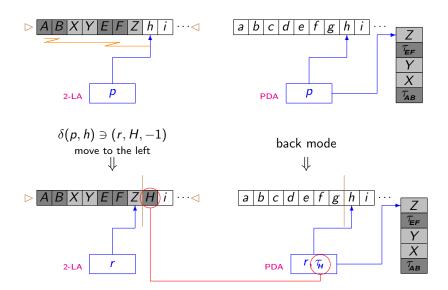
$$\delta(p,h)\ni (r,H,-1)$$
 move to the left

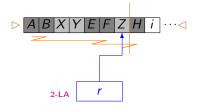


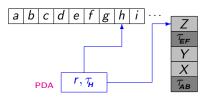


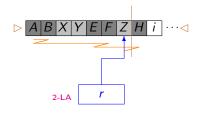




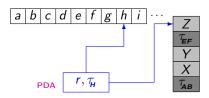


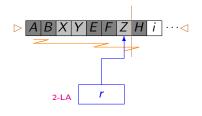




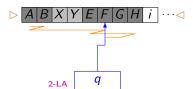


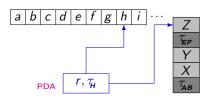
$$\delta(r,Z) \ni (q,G,-1)$$
 move to the left ψ

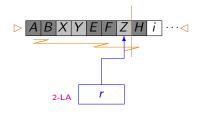




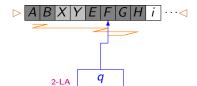
$$\delta(r,Z) \ni (q,G,-1)$$
move to the left

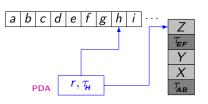




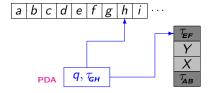


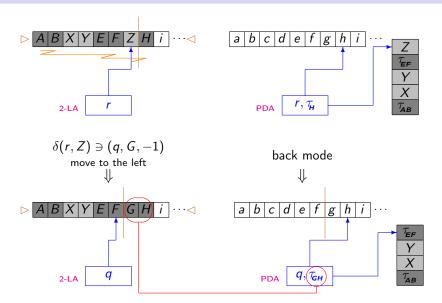
$$\delta(r,Z) \ni (q,G,-1)$$
move to the left

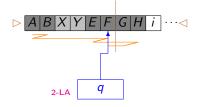


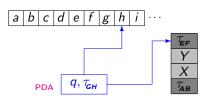


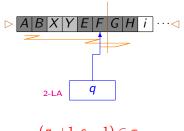


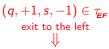


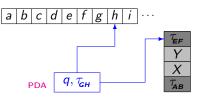


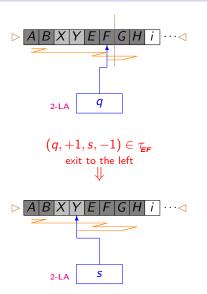


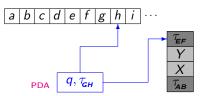


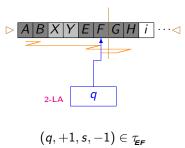




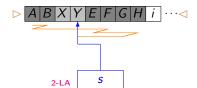


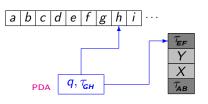




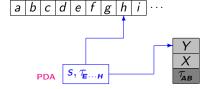


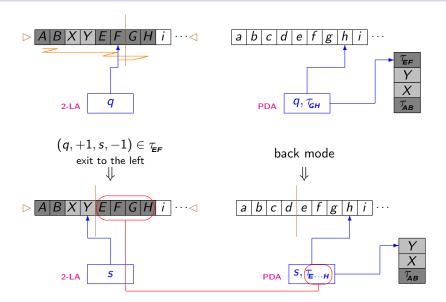
$$(q,+1,s,-1)\in au_{ extsf{\textit{EF}}}$$
 exit to the left

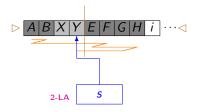


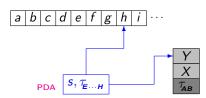


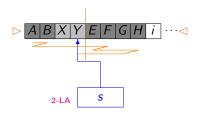




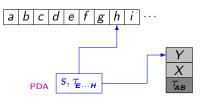


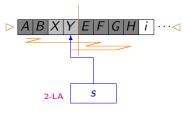


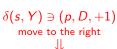


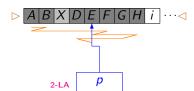


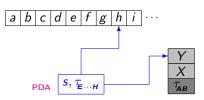
$$\delta(s, Y) \ni (p, D, +1)$$
move to the right
 $\downarrow \downarrow$

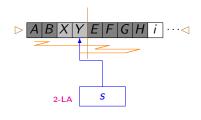




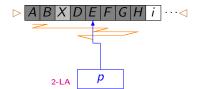


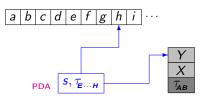


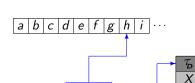




$$\delta(s, Y) \ni (p, D, +1)$$
move to the right
 $\downarrow \downarrow$

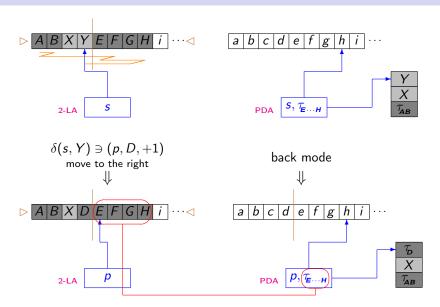


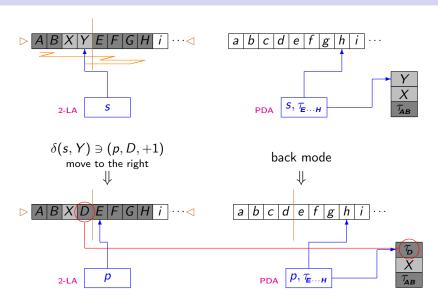


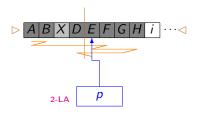


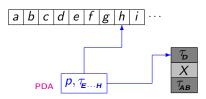
 $p, \tau_{\!\!\!\!E\cdots H}$

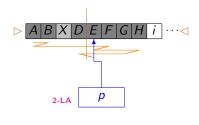
back mode

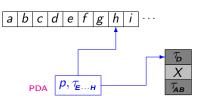


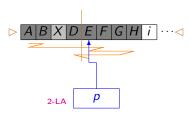


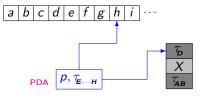




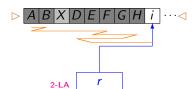


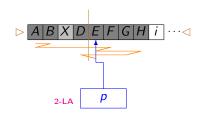




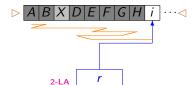


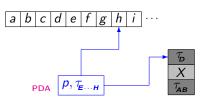
$$(p,-1,r,+1) \in \tau_{\mathbf{E}\cdots\mathbf{H}}$$
 exit to the right



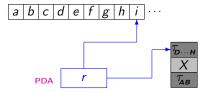


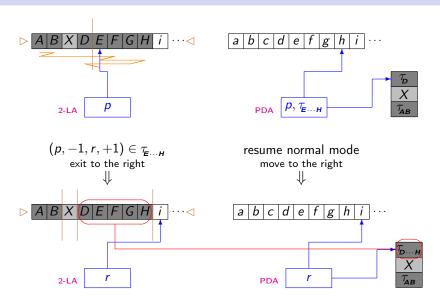
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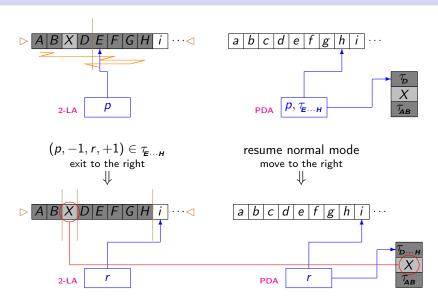


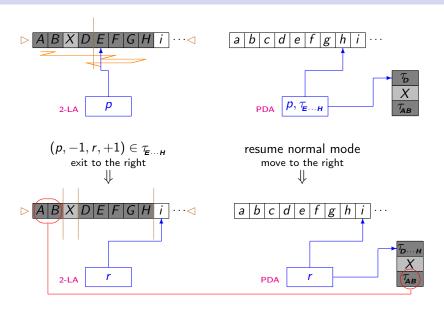


resume normal mode move to the right









Summing up...

Cost of the simulation

- ▶ In the resulting PDA transition tables are used for
 - states
 - pushdown alphabet
- ► Exponential upper bound for the size of the resulting PDA
- Optimal

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Simulation of 2-LAs by PDAs Summing up...

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- Determinism is preserved by the simulation provided that the input of the PDA is right end-marked
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Simulation of Pushdown Automata by 2-Limited Automata

 $PDAs \rightarrow 2-LAs$

Polynomial cost!

(in the description size)

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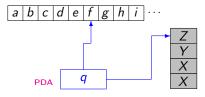
PDAs → 2-LAs

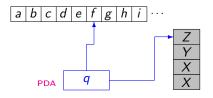
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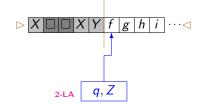
 $\mathsf{DPDAs} \to \mathsf{D2}\text{-}\mathsf{LAs}$

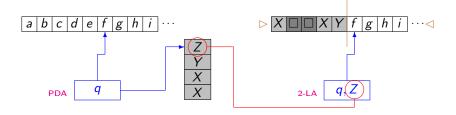
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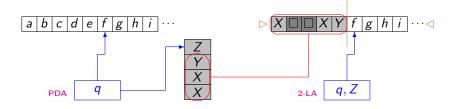
(in the description size)

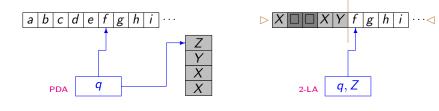












Normal form for (D)PDAs:

- ▶ at each step, the stack height increases at most by 1
- ightharpoonup ϵ -moves cannot push on the stack

Each (D)PDA can be simulated by an equivalent (D)2-LA of polynomial size

Determinism vs Nondeterminism in Limited Automata

Corollary of the simulations

Deterministic 2-LAs \equiv Deterministic Context-Free Languages

On the other hand, the language

$$L = \{a^n b^n c \mid n \ge 0\} \cup \{a^n b^{2n} d \mid n \ge 0\}$$

is accepted by a deterministic 3-LA, but it is not a DCFL

Infinite hierarchy [Hibbard'67]

For each $d \ge 2$ there is a language which is accepted by a deterministic d-limited automaton and that cannot be accepted by any deterministic (d-1)-limited automaton

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- Descriptional complexity aspects for d > 2
 We conjecture that for d > 2 the size gap from d-limited automata to PDAs remains exponential
- Descriptional complexity aspects in the unary case
 - Unary context-free language are regular [Ginbsurg&Rice'62]

• Ex:
$$L_n = (a^{2^n})^*$$

	size
2-LA	O(n)
DPDA	O(n)
minimal DFA	2 ⁿ
minimal 2NFA	2 ⁿ

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Thank you for your attention!