

LINEAR ISOMETRIES BETWEEN SUBSPACES OF CONTINUOUS FUNCTIONS

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ABSTRACT. We say that a linear subspace A of $C_0(X)$ is strongly separating if given any pair of distinct points x_1, x_2 of the locally compact space X , then there exists $f \in A$ such that $|f(x_1)| \neq |f(x_2)|$. In this paper we prove that a linear isometry T of A onto such a subspace B of $C_0(Y)$ induces a homeomorphism h between two certain singular subspaces of the Shilov boundaries of B and A , sending the Choquet boundary of B onto the Choquet boundary of A . We also provide an example which shows that the above result is no longer true if we do not assume A to be strongly separating. Furthermore we obtain the following multiplicative representation of T : $(Tf)(y) = a(y)f(h(y))$ for all $y \in \partial B$ and all $f \in A$, where a is a unimodular scalar-valued continuous function on ∂B . These results contain and extend some others by Amir and Arbel, Holsztyński, Myers and Novinger. Some applications to isometries involving commutative Banach algebras without unit are announced.

1. INTRODUCTION

Let \mathbb{K} denote the field of real or complex numbers. For a locally compact Hausdorff space X , we denote by $C_0(X)$ the Banach space of all continuous \mathbb{K} -valued functions defined on X which vanish at infinity, equipped with its usual supremum norm. If X is compact, we write $C(X)$ instead of $C_0(X)$. $X \cup \{\infty\}$ denotes the Alexandroff compactification of X .

Let A be a linear subspace of $C_0(X)$. We will denote by σA the set of all $x_0 \in X$ such that for each neighborhood U of x_0 , there is a function f in A such that $|f(x)| < \|f\|$ for all $x \in X - U$. Let us define the set

$$\sigma_0 A := \sigma A \cap \{x \in X : \text{there exists } f \in A \text{ such that } f(x) \neq 0\}.$$

If it exists, we will denote by ∂A the Shilov boundary of A , that is, the minimal closed subset of X with the property that each function in A assumes its maximum on ∂A . On the other hand, it is said that $x_0 \in X$ is a strong boundary point of A if for each neighborhood U of x_0 , there is a function f in A such that $|f(x_0)| = \|f\|$ and $|f(x)| < \|f\|$ for all $x \in X - U$. We will denote by τA the set of all strong boundary points of A .

We will denote by $\text{Ch } A$ the Choquet boundary of A . Let us recall that each extreme point of the unit ball V of the dual space of A has the form μe_x , where μ is a complex number of modulus 1 and e_x is the evaluation map at the point $x \in X$,

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$e_x(f) = f(x)$ ($f \in C_0(X)$). The *Choquet boundary* for A is defined as $\{x \in X : e_x \text{ is an extreme point of } V\}$. Recall that although the Choquet boundary is usually defined in the case when X is compact and A separates points and contains the constants, both definitions agree in this case.

We say that a linear subspace A of $C_0(X)$ is separating (resp. strongly separating) if given any pair of distinct points x_1, x_2 of X , then there exists $f \in A$ such that $f(x_1) \neq f(x_2)$ (resp. $|f(x_1)| \neq |f(x_2)|$). It is well-known that the Shilov boundary of a separating subalgebra of $C_0(X)$ always exists.

A separating (resp. strongly separating) linear subspace A of $C_0(X)$ is said to be a separating (resp. strongly separating) function subspace if for all $x \in X$, there exists $f \in A$ such that $f(x) \neq 0$.

The source of this article is the classical Banach-Stone theorem. In its present form it states as follows: if there exists a linear isometry T of $C_0(X)$ onto $C_0(Y)$, then there are a homeomorphism h of Y onto X and a continuous map $a : Y \rightarrow \mathbb{K}$, $|a| \equiv 1$, such that T can be written as a weighted composition map, that is,

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in Y \text{ and all } f \in C_0(X).$$

This well-known theorem has been generalized in several directions, for instance, by considering injective (not necessarily surjective) linear isometries. Perhaps the most important result of this type is due to Holsztyński [15]: if there exists a linear isometry T of $C(X)$ into $C(Y)$, then we can find a closed subset Y_0 of Y and a continuous map h of Y_0 onto X and a continuous map $a : Y_0 \rightarrow \mathbb{K}$, $|a| \equiv 1$, such that

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in Y_0 \text{ and all } f \in C(X).$$

Some years before, Geba and Semadeni [14] had obtained an analogue of Holsztyński's theorem though for isotonic injective linear isometries. Also a number of applications of Holsztyński's theorem can be found in the literature. Recently, for instance, it has played a crucial role in the classification of isometric shift operators on $C(X)$ (see, e.g., [12] and [13]).

Generalizations of a similar type are provided by replacing $C_0(X)$ by its subspaces or subalgebras. Indeed, in 1948, Myers [20] proved that, if $\mathbb{K} = \mathbb{R}$, then a sufficient condition for X and Y to be homeomorphic is that a completely regular linear subspace of $C(X)$ and such a subspace of $C(Y)$ be isometrically isomorphic. Let us recall that a closed linear subspace A of $C_0(X)$ is said to be completely regular if every $x \in X$ is a strong boundary point of A , i.e., $\tau A = X$.

In 1959, Nagasawa [21] (see also [11]) extended the Banach-Stone theorem for function algebras, that is, closed separating subalgebras with unit of $C(X)$ -spaces. He proved that two function algebras are isomorphic as algebras if and only if they are isometric as Banach spaces.

In 1975, Novinger [22] went a step further and extended some of the above generalizations: if there exists a linear isometry T from a linear subspace A of $C(X)$ which is separating and contains the constants into $C_0(Y)$, then there are a continuous map h of the Choquet boundary of $T(A)$, $\text{Ch } T(A)$, onto $\text{Ch } A$ and a continuous map $a : \text{Ch } T(A) \rightarrow \mathbb{K}$, $|a| \equiv 1$, such that

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in \text{Ch } T(A) \text{ and all } f \in A.$$

Similar extensions of the Banach-Stone theorem have been given for subspaces of $C_0(X)$ equipped with different norms. Among these subspaces we point out

the following: spaces of differentiable functions (see, e.g., [7]); spaces of absolutely continuous functions (see, e.g., [23]); spaces of Lipschitz functions (see, e.g., [10]).

If we weaken the geometric bond between $C_0(X)$ and $C_0(Y)$, the homeomorphism between X and Y may wither: Milutin [19] proved that if X is *any* uncountable compact metric space (for instance, $X = [0, 1] \cup \{2\}$), then $C(X)$ is linearly homeomorphic to $C([0, 1])$. However, if the isometry is not weakened too much, good results can still be accomplished: Amir [1] and Cambern [6] proved that if $C_0(X)$ and $C_0(Y)$ are isomorphic under an isomorphism T satisfying $\|T\| \cdot \|T^{-1}\| < 2$, which is the best constant, then X and Y must also be homeomorphic. This theorem has been extended to cover various subspaces of $C_0(X)$ -spaces, for instance, extremely regular subspaces (see, e.g., [5], [8], [9] or [16]) and function algebras (see, e.g., [17]).

The corresponding Banach-Stone theorem for E -valued continuous functions is not true even when the Banach space E is the two dimensional space \mathbb{R}^2 and X , Y are compact metric spaces (see [24]). Thus, the main concern in this line is to determine the geometric properties of E which allow analogues of the Banach-Stone theorem. A systematic account of many of the generalizations in this and the above directions can be found in [4] or [18].

In this paper we deal with some of these generalizations. Indeed we focus on Holsztyński and Novinger's directions. Namely we study linear isometries of a strongly separating linear subspace A of $C_0(X)$ into $C_0(Y)$ or onto such a subspace B of $C_0(Y)$. We show that such isometries can be written as weighted composition maps on some subspaces of Y ($\sigma_0 B$ for the onto case). Furthermore, under the onto assumption, we prove that $\sigma_0 A$ and $\sigma_0 B$ are homeomorphic. As straightforward consequences of this result we first show that the set of strong boundary points of A and B are homeomorphic. Also ∂A and ∂B are homeomorphic if A and B are assumed to be strongly separating function subspaces. We also provide an example which shows that this latter result may fail if the hypothesis " A is strongly separating" is replaced by the weaker one " A is separating".

Next we extend some results (op. cit.) by Amir and Arbel [3], Holsztyński [15], Myers [20] and Novinger [22]. We also apply our main results to study the isometries between separating function subalgebras of $C_0(X)$ and $C_0(Y)$ or, more generally, between semisimple commutative Banach algebras without unit and their Shilov boundaries.

Finally, we would like to remark that our techniques are not based on the usual concepts, such as extreme points of the unit ball of the dual of $C_0(X)$, T -sets or M -ideals, used to prove the Banach-Stone theorem and their generalizations. We only use straightforward concepts instead.

2. SOME PREVIOUS LEMMAS

In the sequel we will assume that every linear subspace A of $C_0(X)$ has nonvoid Shilov boundary. Anyway, let us note that the Shilov boundary of a strongly separating linear subspace of $C_0(X)$ is nonvoid and coincides with the closure of its Choquet boundary ([2, Theorem 1]).

Lemma 2.1. *Let A be a linear subspace of $C_0(X)$. Then $\partial A = \sigma A$.*

Proof. Let $x_0 \in \partial A$. Given an open neighborhood U of x_0 , the closed set $X - U$ cannot be a boundary for A since it does not contain ∂A . Consequently, there

exists a function $f \in A$ which does not attain its maximum value on $X - U$, that is, $|f(x)| < \|f\|$ for all x outside U .

Conversely, let $x_0 \in \sigma A$. If $x_0 \notin \partial A$, then there exists an open neighborhood U of x_0 such that $\partial A \cap U = \emptyset$. Hence, there exists a function $f \in A$ not attaining its maximum value on ∂A , which contradicts the definition of boundary. \square

Lemma 2.2. *Let A be a linear subspace of $C_0(X)$. Let T be a linear isometry from A into $C_0(Y)$. Let $x \in X$ such that there exists $f \in A$ with $\|f\| = |f(x)|$. Let*

$$C_x := \{f \in A : 1 = \|f\| = |f(x)|\}.$$

For any $f \in A$, let

$$L(f) := \{y \in Y : \|Tf\| = |(Tf)(y)|\}$$

and let $I_x := \bigcap_{f \in C_x} L(f)$. Then I_x is a nonempty subset of Y .

Proof. For any $f \in C_x$, we have

$$I_x \subset M_f := \{y \in Y : |(Tf)(y)| \geq \|Tf\|/2\}$$

and M_f is compact because $Tf \in C_0(Y)$. Hence, we only need to prove that if f_1, \dots, f_n belong to C_x , then $\bigcap_{i=1}^n L(f_i) \neq \emptyset$. We have that $1 = \|f_i\| = |f_i(x)|$ for all $i = 1, \dots, n$. Let $f \in A$ be defined as

$$\sum_{i=1}^n (|f_i(x)| / f_i(x)) f_i.$$

Clearly $|f(x)| = n = \|f\|$. Since T is an isometry, $\|Tf\| = n$ and there is $y \in Y$ such that

$$n = |(Tf)(y)| = \sum_{i=1}^n (|f_i(x)| / f_i(x)) |(Tf_i)(y)|.$$

As $\|Tf_i\| \leq 1$ for all $i = 1, \dots, n$, we deduce that $|(Tf_i)(y)| = 1$ for all $i = 1, \dots, n$, that is, $y \in \bigcap_{i=1}^n L(f_i)$. \square

Remark. Let A be a linear subspace of $C_0(X)$ and let $x_0 \in \partial A$. We then define the following subset of Y :

$$V_{x_0} := \{y \in Y : |(Tf)(y)| = |f(x_0)| \text{ for all } f \in A\}.$$

Lemma 2.3. *Let A be a linear subspace of $C_0(X)$ and let $x_0 \in \sigma_0 A$. Then $V_{x_0} \neq \emptyset$.*

Proof. Let $f_0 \in A$ such that $|f_0(x_0)| = 1$. Given $\epsilon > 0$, let

$$U_{f_0, \epsilon} := \{x \in X : 1 - \epsilon < |f_0(x)| < 1 + \epsilon\}.$$

Let U be an open neighborhood of x_0 . We will assume that $U \subseteq U_{f_0, \epsilon}$. Since $x_0 \in \sigma_0 A$ and U is an open neighborhood of x_0 , there exists a function $g_0 \in A$ such that $\|g_0\| = 1$ and $|g_0(x)| < 1$ for all x outside U . Since $(X \cup \{\infty\}) - U$ is compact, we can consider

$$s := \sup_{x \in X - U} \{|g_0(x)|\} < 1.$$

Then there exists $M > 0$ such that $\|f_0\| + Ms < 1 + \epsilon + M$. Take $x \in U$. Then

$$|(f_0 + Mg_0)(x)| \leq 1 + \epsilon + M.$$

If $x \notin U$, then

$$|(f_0 + Mg_0)(x)| < \|f_0\| + Ms < 1 + \epsilon + M.$$

As a consequence, $\|f_0 + Mg_0\| < 1 + \epsilon + M$. Hence, $\|T(f_0 + Mg_0)\| < 1 + \epsilon + M$. Furthermore, since

$$\lim_{M \rightarrow +\infty} \frac{\|f_0 + Mg_0\|}{1 + M} = 1,$$

we can choose M in such a way that $|f_0 + Mg_0|$ attains its maximum value inside U . Otherwise,

$$\lim_{M \rightarrow +\infty} \frac{\|f_0 + Mg_0\|}{1 + M} \leq \lim_{M \rightarrow +\infty} \frac{\|f_0\| + Ms}{1 + M} = s < 1,$$

which is a contradiction. Thus, let $x_1 \in U$ such that $\|f_0 + Mg_0\| = |(f_0 + Mg_0)(x_1)|$.

Let $x_2 \in U$ such that $\|g_0\| = |g_0(x_2)| = 1$. It is clear that we can choose g_0 such that $|(f_0 + Mg_0)(x_2)| = |f_0(x_2)| + M|g_0(x_2)|$. Thus,

$$\|f_0 + Mg_0\| \geq |(f_0 + Mg_0)(x_2)| \geq M + 1 - \epsilon.$$

Consequently,

$$\|Tf_0 + MTg_0\| \geq M + 1 - \epsilon.$$

From the definition of I_{x_1} (see Lemma 2.2), we infer that

$$\|Tf_0 + MTg_0\| = |(Tf_0 + MTg_0)(y_1)| \geq M + 1 - \epsilon$$

for all $y_1 \in I_{x_1}$. Since $|(Tg_0)(y)| \leq 1$ for all $y \in Y$, we deduce that $|(Tf_0)(y_1)| \geq 1 - \epsilon$ for all $y_1 \in I_{x_1}$.

Next we shall show that $|(Tf_0)(y_1)| \leq 1 + \epsilon$ for all $y_1 \in I_{x_1}$. Let us define the function

$$g_1 := \frac{f_0 + Mg_0}{\|f_0 + Mg_0\|}.$$

Hence $|g_1(x_1)| = 1 = \|g_1\|$ and $|g_1| < 1$ outside U . Since $(X \cup \{\infty\}) - U$ is compact, we can consider

$$r := \sup_{x \in X - U} \{|g_1(x)|\} < 1.$$

Arguing as above, we find a number $N \in \mathbb{K}$ such that $|f_0 + Ng_1|$ attains its maximum value inside U and $\|f_0 + Ng_1\| < 1 + \epsilon + |N|$. Furthermore, we can choose N in such a way that

$$|(Tf_0 + NTg_1)(y_1)| = |(Tf_0)(y_1)| + |N|||(Tg_1)(y_1)|.$$

As a consequence, since $|(Tg_1)(y_1)| = 1$, we have

$$|N| + 1 + \epsilon \geq \|Tf_0 + NTg_1\| \geq |(Tf_0 + NTg_1)(y_1)| = |(Tf_0)(y_1)| + |N|,$$

that is, $|(Tf_0)(y_1)| \leq 1 + \epsilon$ for all $y_1 \in I_{x_1}$. Gathering up the information we have obtained so far, it is clear that we can find a net (x_α) in X converging to x_0 and a net (y_α) in Y such that $y_\alpha \in I_{x_\alpha}$ for all α and such that there exists a subnet (y_β) of (y_α) converging to some $y_0 \in Y \cup \{\infty\}$ with $|(Tf_0)(y_0)| = 1$. This latter fact shows that $y_0 \neq \infty$. Furthermore, it is apparent, from the above arguments, that, for any open neighborhood V of x_0 , there exist a term x_{β_0} of the net (x_β) and a function $g_{\beta_0} \in A$ such that $|g_{\beta_0}(x_{\beta_0})| = 1 = \|g_{\beta_0}\|$ and $|g_{\beta_0}| < 1$ outside V .

On the other hand, let $g \in A$ such that $g(x_0) = 0$. We shall show that $(Tg)(y_0) = 0$. Given $\epsilon > 0$, let

$$U_{g,\epsilon} := \{x \in X : |g(x)| < \epsilon\}.$$

Let V be an open neighborhood of x_0 such that $V \subseteq U_{g,\epsilon}$. Hence, as mentioned above, there exist a term x_{β_0} of the net (x_β) and a function $g_{\beta_0} \in A$ such that $|g_{\beta_0}(x_{\beta_0})| = 1 = \|g_{\beta_0}\|$ and $|g_{\beta_0}| < 1$ outside V . Arguing as above, we find a

number $P \in \mathbb{K}$ such that the function $|g + Pg_{\beta_0}|$ attains its maximum value inside V and $\|g + Pg_{\beta_0}\| < \epsilon + |P|$. Furthermore, we can choose P in such a way that

$$|(Tg + PTg_{\beta_0})(y_{\beta_0})| = |(Tg)(y_{\beta_0})| + |P|(Tg_{\beta_0})(y_{\beta_0})|.$$

As a consequence, since $(Tg_{\beta_0})(y_{\beta_0}) = 1$, we have

$$|P| + \epsilon \geq \|Tg + PTg_{\beta_0}\| \geq |(Tg + PTg_{\beta_0})(y_{\beta_0})| = |(Tg)(y_{\beta_0})| + |P|,$$

that is, $|(Tg)(y_{\beta_0})| \leq \epsilon$. Therefore, since the net (y_β) converges to y_0 , we infer that $(Tg)(y_0) = 0$.

Let us now consider $l \in A$ such that $|l(x_0)| = 1$. Let us define the function

$$l' := \frac{f_0(x_0)}{l(x_0)} \cdot l$$

and let $g \in A$ such that $l' = f_0 + g$. It is clear that $g(x_0) = 0$. Consequently, by the above paragraph, $(Tg)(y_0) = 0$ and, since $l'(x_0) = 1$,

$$|(Tl')(y_0)| = |(Tf_0)(y_0) + (Tg)(y_0)| = 1$$

and, thus, $|(Tl)(y_0)| = 1$.

Finally, if $f \in A$, then we define $f' = f/|f(x_0)|$. Hence $|f'(x_0)| = 1$. As a consequence, by the previous paragraph, we infer that $|(Tf')(y_0)| = 1$, i.e., $|f(x_0)| = |(Tf)(y_0)|$. The proof is complete. \square

Lemma 2.4. *Let A be a strongly separating linear subspace of $C_0(X)$ and let T be a linear isometry from A into $C_0(Y)$. If x_0 is a strong boundary point of A , then $V_{x_0} = I_{x_0}$.*

Proof. It suffices to check that $I_{x_0} \subseteq V_{x_0}$ since the other inclusion is apparent.

We will first show that, if $f \in A$ satisfies $f(x_0) = 0$, then $(Tf)(y) = 0$ for all $y \in I_{x_0}$. Let us suppose that there exists $y_0 \in I_{x_0}$ such that $(Tf)(y_0) \neq 0$ and $f(x_0) = 0$ for some $f \in A$. We will assume, without loss of generality, that $\|f\| = 1$ and $(Tf)(y_0) = \alpha > 0$. Let

$$U = \{x \in X : |f(x)| \geq \alpha/2\}.$$

Since x_0 is a strong boundary point of A and $y_0 \in I_{x_0}$, there exists $g \in A$ such that, multiplying by a constant if necessary, $|g(x_0)| = 1 = \|g\|$, $|g(x)| < 1$ for all $x \in U$ and $(Tg)(y_0) = 1$. Since, from the definition of $C_0(X)$, U is a compact set, we can consider

$$s := \sup_{x \in U} \{|g(x)|\} < 1.$$

Thus there is a real number $M > 0$ such that $1 + Ms < \alpha + M$. We will distinguish two cases: If $x \in U$, then

$$|(f + Mg)(x)| \leq 1 + Ms.$$

If $x \notin U$, then

$$|(f + Mg)(x)| \leq \alpha/2 + M.$$

That is, we have that $\|f + Mg\| < \alpha + M$, but

$$\alpha + M = (Tf)(y_0) + (MTg)(y_0) \leq \|T(f + Mg)\|,$$

which is absurd since T is an isometry.

Finally, let us suppose that there exists $y' \in I_{x_0}$ such that $|(Tf)(y')| \neq |f(x_0)|$ for some $f \in A$. Since x_0 is a strong boundary point of A , there will exist a function

$k \in A$ such that $k(x_0) = 1 = \|k\|$. Hence it is straightforward to check that the function

$$l(x) := f(x) - f(x_0) \cdot k(x)$$

belongs to A and, furthermore,

$$l(x_0) = 0$$

and

$$(Tl)(y') = (Tf)(y') - f(x_0) \cdot (Tk)(y') \neq 0$$

since $|(Tk)(y')| = 1$. This fact contradicts the paragraph above. \square

3. INTO ISOMETRIES BETWEEN SUBSPACES

Theorem 3.1. *Let T be a linear isometry of a strongly separating linear subspace A of $C_0(X)$ into $C_0(Y)$. Then there are a subset Y_0 of Y , which is a boundary for $T(A)$, a continuous map h from Y_0 onto $\sigma_0 A$ and a continuous map $a : Y_0 \rightarrow \mathbb{K}$, such that $|a(y)| = 1$ for all $y \in Y_0$, and*

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in Y_0 \text{ and all } f \in A.$$

Furthermore, if $\sigma_0 A$ is compact, then Y_0 is closed.

Proof. Let Y_0 be the set $\bigcup_{x \in \sigma_0 A} V_x$. It is clear, by Lemma 3.3, that Y_0 is nonvoid. In order to prove that Y_0 is a boundary for $T(A)$, let us suppose that there exists $f \in A$ such that

$$|(Tf)(y)| < \|Tf\| = \|f\|$$

for all $y \in Y_0$. Then we can find $x_0 \in \sigma_0 A$ such that

$$|f(x_0)| = \|f\| = \|Tf\|.$$

Let $y_0 \in V_{x_0}$. Then $y_0 \in Y_0$ and

$$\|f\| = \|Tf\| = |f(x_0)| = |(Tf)(y_0)|,$$

which contradicts the above assumptions.

Next, we define the map h of Y_0 onto $\sigma_0 A$ as $h(y) := x$ if $y \in V_x$. Since A is strongly separating, given $x, x' \in \sigma_0 A$ with $x \neq x'$, it is easy to check that $V_x \cap V_{x'} = \emptyset$. Thus the map h is well-defined. Moreover, since $V_x \neq \emptyset$ for every $x \in \sigma_0 A$, h is onto.

In order to prove the continuity of h , suppose that $h(y_0) = x_0$ for some $y_0 \in Y_0$. Let $f \in A$ such that $f(x_0) = 1$. Hence, $|(Tf)(y_0)| = 1$. Let (y_α) be a net in Y_0 converging to y_0 and let $h(y_\alpha) = x_\alpha$ for all α . Since $|(Tf)(y_0)| = 1$, we can assume, without loss of generality, that $|(Tf)(y_\alpha) - 1| < 1/2$ for all α . Then, from the definition of V_{x_α} , $|f(x_\alpha)| > 1/2$ for all α . Let (x_β) be a subnet of (x_α) converging to $x_1 \in X \cup \{\infty\}$. Consequently, $|f(x_1)| \geq 1/2$. Hence, $x_1 \neq \infty$. If $x_1 \neq x_0$, then we take $g \in A$ such that

$$|g(x_0)| = 1 \neq s = |g(x_1)|.$$

Take a subnet (y_γ) of (y_β) such that

$$|(Tg)(y_\gamma) - (Tg)(y_0)| < |1 - s|/2.$$

Hence

$$||g(h(y_\gamma))| - 1| < |1 - s|/2$$

and $(|g(x_\gamma)|)$ does not converge to $|g(x_1)|$, which is a contradiction. Hence every subnet of (x_α) has a subnet that converges to x_0 and then we have that (x_α) converges to x_0 .

Now, let us define a map a of Y_0 into \mathbb{K} as follows: given $y \in Y_0$, let f be any function in A such that $f(h(y)) = 1$. Hence, we define $a(y) := (Tf)(y)$ for all $y \in Y_0$. This is a well-defined map because if we take another function g in A such that $g(h(y)) = 1$, then $(f - g)(h(y)) = 0$ and by the definition of h , $(Tf)(y) = (Tg)(y)$.

On the other hand, it is clear that $|a(y)| = 1$ for all $y \in Y_0$.

Next we prove both that T can be written as a weighted composition map and, as a consequence, the continuity of a . We have already proved that if $f(h(y)) = 0$, then $(Tf)(y) = 0$ for all $y \in Y_0$ and all $f \in A$. If $f(h(y)) \neq 0$ for some $f \in A$ and some $y \in Y_0$, then let

$$g = f - f(h(y))k.$$

k being any function in A such that $k(h(y)) = 1$. Clearly $g(h(y)) = 0$. Thus, $(Tg)(y) = 0$, that is,

$$(Tf)(y) = a(y)f(h(y)).$$

In order to prove the continuity of a , we will show that for each $y \in Y_0$, there exists an open neighborhood of y where a is continuous. Let us consider any $f \in A$ such that $f(h(y)) \neq 0$ and let

$$W := \{x \in \sigma_0 A : f(x) \neq 0\}.$$

It is clear that $h^{-1}(W)$ is an open neighborhood of y . Moreover the map $Tf/(f \circ h)$ is continuous on $h^{-1}(W)$, and a and $Tf/(f \circ h)$ coincide on $h^{-1}(W)$.

Finally, assume that $\sigma_0 A$ is compact and let $y_0 \in Y$ such that there exists a net (y_α) in Y_0 converging to y_0 . For all α , y_α belongs to some V_{x_α} (see remark preceding Lemma 2.3) with $h(y_\alpha) = x_\alpha \in \sigma_0 A$. Hence the net above has a subnet (x_β) which converges to some $x_0 \in \sigma_0 A$. Since

$$|f(x_\beta)| = |(Tf)(y_\beta)|$$

for all β and all $f \in A$, we deduce, by the continuity of f and Tf , that

$$|f(x_0)| = |(Tf)(y_0)|$$

for all $f \in A$, that is, $y_0 \in V_{x_0} \subset Y_0$. \square

Remark. Theorem 3.1 generalizes Holsztyński's theorem by taking X compact and $A = C(X)$.

Corollary 3.2. *In the same conditions as in Theorem 3.1, h sends $\text{Ch}T(A)$ onto $\text{Ch}A$.*

Proof. By [2, Theorem 1], we know that the Choquet boundary of A is contained in ∂A . On the other hand, for every point x of $\text{Ch}A$, there exists $f \in A$ such that $f(x) \neq 0$, so $\text{Ch}A \subset \sigma_0 A$. Since $T^{-1} : T(A) \rightarrow A$ is a linear surjective isometry, we have that its adjoint $(T^{-1})' : A' \rightarrow (T(A))'$ sends the extreme points of the unit ball of A' onto such points of $(T(A))'$. So, if $x \in \text{Ch}A$, $(T^{-1})'e_x = \mu e_y$, where $\mu \in \mathbb{K}$, $|\mu| = 1$ and $y \in Y$. If $f \in A$,

$$\begin{aligned} |(Tf)(y)| &= |\mu(Tf)(y)| \\ &= |\mu e_y(Tf)| \\ &= |((T^{-1})'e_x)(Tf)| \\ &= |f(x)|. \end{aligned}$$

We conclude that $y \in V_x$ and, consequently, that $\text{Ch}A \subseteq h(\text{Ch}T(A))$.

The other inclusion follows from the same arguments since $(T^{-1})'$ is bijective. \square

Remark. It is evident, from Corollary 3.2, that Theorem 3.1 extends the main result (Theorem 1) of [22].

Theorem 3.3. *Let T be a linear isometry of a strongly separating linear subspace A of $C_0(X)$ into $C_0(Y)$. Then $Tf = E(a \cdot f \circ h)$, where h is a continuous map defined from a subset Y_0 of Y onto $\sigma_0 A$, $a : Y_0 \rightarrow \mathbb{K}$ is a continuous map such that $|a| \equiv 1$ and $E : Z \rightarrow C_0(Y)$ is a norm-preserving linear extension with $Z = \{a \cdot f \circ h : f \in A\}$.*

Proof. Let a , h , and Y_0 be as in Theorem 3.1 and let us define $Eg := Tf$ being $g := a \cdot f \circ h$ for some $f \in A$. Clearly this definition completes the proof. \square

4. THE ONTO CASE

Theorem 4.1. *Let T be a linear isometry of a strongly separating linear subspace A of $C_0(X)$ onto such a subspace B of $C_0(Y)$. Then there exist a homeomorphism h of $\sigma_0 B$ onto $\sigma_0 A$ and a continuous map $a : \sigma_0 B \rightarrow \mathbb{K}$, such that $|a(y)| = 1$ for all $y \in \sigma_0 B$, and*

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in \sigma_0 B \text{ and all } f \in A.$$

Proof. Let h and Y_0 be as in Theorem 3.1. To prove the injectivity of h , we shall check that the sets V_x are singletons. Suppose that $y_0, y_1 \in V_x$ for some $x \in \sigma_0 A$ and $y_0 \neq y_1$. Consequently

$$|(Tf)(y_0)| = |(Tf)(y_1)| = |f(x)|$$

for all $f \in A$, which contradicts the strongly separating property of B .

We now show that $Y_0 = \sigma_0 B$. Let $y_0 \in Y_0$. There exists $x_0 \in \sigma_0 A$ such that

$$x_0 = h(y_0).$$

Let U be any open neighborhood of y_0 . It falls out of the way we obtain y_0 in Lemma 2.3 that there exists a set I_x , for some $x \in X$, contained in U . This means, according to the definition of I_x (see Lemma 2.1), that

$$\bigcap_{f \in C_x} L(f) \subset U,$$

that is,

$$\left(\bigcap_{f \in C_x} L(f) \right) \cap ((X \cup \{\infty\}) \setminus U) = \emptyset.$$

Thus we have an intersection of closed subsets whose intersection with the compact set $(X \cup \{\infty\}) \setminus U$ is empty. Hence, there exist finitely many functions $\{f_1, \dots, f_n\} \subset C_x$ such that

$$\bigcap_{i=1}^n L(f_i) \subset U.$$

We can assume, with no loss of generality, that

$$f_i(x) = 1, \quad i = 1, \dots, n.$$

Then the function $f := \sum_{i=1}^n f_i$ satisfies $f(x) = n$. As a consequence,

$$|(Tf)(y)| < \|Tf\| = n$$

for all $y \notin U$, which implies that $y_0 \in \sigma_0 B$.

Conversely, to prove that $\sigma_0 B \subset Y_0$, take $y_0 \in \sigma_0 B$. We now consider the inverse of T , which is an isometry of B onto A . By Theorem 3.1, there exists a continuous

map k from a subset X_0 of X , defined as $\bigcup_{y \in \sigma_0 B} V_y$, onto $\sigma_0 B$. As above, we can prove that $X_0 \subset \sigma_0 A$. Let us consider $x_0 \in X_0$ such that $k(x_0) = y_0$. It just remains to prove that $y_0 \in V_{x_0}$. We know that, for all $g \in B$,

$$|(T^{-1}g)(x_0)| = |g(y_0)|,$$

that is, for all $f \in A$,

$$|(Tf)(y_0)| = |f(x_0)|.$$

Consequently, $h(y_0) = x_0$. Hence, h is a homeomorphism of $\sigma_0 A$ onto $\sigma_0 B$. Finally, by Theorem 3.1, T is a weighted composition map. \square

Now the following corollary holds because of Theorem 4.1 and Corollary 3.2.

Corollary 4.2. *In the same conditions as in Theorem 4.1, h is a homeomorphism of $\text{Ch } B$ onto $\text{Ch } A$.*

Remarks. 1. Let T be the isometric embedding of $C_0(\mathbb{N})$ into $C(\mathbb{N} \cup \{\infty\})$. This example shows both that, in Theorem 3.1, Y_0 may not be closed and that, in Theorem 3.3, the Shilov boundaries of A and B are not homeomorphic in general. However, if A and B are assumed to be strongly separating function subspaces, then it is straightforward, from the definition of $\sigma_0 A$ (resp. $\sigma_0 B$) and by Lemma 2.1, that their Shilov boundaries are homeomorphic.

2. The following example shows that this latter assertion may fail if we replace the hypothesis “ A is strongly separating” by “ A is separating”: Let us define the compact set

$$X := \left\{1 - \frac{1}{n} : n \in \mathbb{N}\right\} \cup \left\{-1 + \frac{1}{n} : n \in \mathbb{N}\right\} \cup \{-1, 1\}$$

and let A' be the set of all functions $f_n \in C(X)$, $n = 2, 3, 4, \dots$, defined as follows: if n is even,

$$f_n(x) := \begin{cases} 1 & \text{if } x = 1 - \frac{1}{n}, \\ -1 + \frac{1}{n} & \text{if } x = -1 + \frac{1}{n}, \\ 0 & \text{otherwise.} \end{cases}$$

If n is odd,

$$f_n(x) := \begin{cases} -1 & \text{if } x = -1 + \frac{1}{n}, \\ 1 - \frac{1}{n} & \text{if } x = 1 - \frac{1}{n}, \\ 0 & \text{otherwise.} \end{cases}$$

Given $x \in X$ (resp. $x \in Y$), we will denote by χ_x the characteristic function of the singleton $\{x\}$. Let us define the function $f \in C(X)$ in the following way:

$$f(x) := \left(\sum_{n=2}^{\infty} f_n(x)\right) + \chi_1 - \chi_{-1}$$

Let A be the linear span of A' and f .

On the other hand, let us define the compact set

$$Y := \left\{\frac{1}{n} : n \in \mathbb{N}\right\} \cup \{0\}$$

and let us define $g \in C(Y)$ as follows:

$$g(x) := \left(\sum_{n=1}^{\infty} \chi_{\frac{1}{n}}\right) + \chi_0.$$

Let B be the linear span of the set $\{\chi_{\frac{1}{n}} : n \in \mathbb{N}\}$ and g . It is now a routine matter to verify that A is a (not strongly) separating linear subspace of $C(X)$. Also, A is linearly isometric to B . However,

$$\partial A = \left\{1 - \frac{1}{n} : n \text{ even}\right\} \cup \left\{-1 + \frac{1}{n} : n \text{ odd}\right\} \cup \{-1, 1\}$$

is not homeomorphic to $\partial B = Y$.

3. The assertion of Theorem 4.1 cannot be strengthened to the effect “ X homeomorphic to Y ”. A counterexample is obtained by taking the isometry T of $C_0(X) = C_0(0, 1)$ into $C_0(Y) = C_0((0, 1) \cup (1, 2))$ defined to be $(Tf)(x) = f(x)$ if $x \in (0, 1)$, and $(Tf)(x) = f(x - 1)/2$ if $x \in (1, 2)$. Clearly X is not homeomorphic to Y because Y is not connected.

Corollary 4.3. *Let T , X , Y , A and B be as in Theorem 4.1. If, in addition, we assume that either τA or τB is a nonempty set, then τA and τB are homeomorphic.*

Proof. Let us define the set

$$Y_{00} = \bigcup_{x \in \tau A} V_x.$$

By the definition of h (see the proof of Theorem 3.1) and since it is injective (Theorem 4.1), we infer that $h(Y_{00}) = \tau A$. Hence, by virtue of Theorem 4.1, it suffices to check that $Y_{00} = \tau B$. Let $y_0 \in Y_{00}$. There exists $x_0 \in \tau A$ such that $x_0 = h(y_0)$. Let U be any open neighborhood of y_0 . If $y \notin U$, then $y \in V_{x_0}$ since, by Lemma 2.4, $V_{x_0} = I_{x_0}$ whenever x_0 is a strong boundary point. Thus, by Lemma 2.2, there is $f_y \in A$ such that

$$1 = f_y(x_0) = \|f_y\|$$

and

$$|(Tf_y)(y)| < 1.$$

For each $y \in (Y \cup \{\infty\}) - U$, we take an open neighborhood U_y of y such that $|(Tf_y)(y')| < 1$ for all $y' \in U_y$. Since $(Y \cup \{\infty\}) - U$ is compact, we can find $\{y_1, \dots, y_n\} \subset (Y \cup \{\infty\}) - U$ such that $(Y \cup \{\infty\}) - U \subset \bigcup_{i=1}^n U_{y_i}$. Now, let us define the map

$$g = \left(\sum_{i=1}^n f_{y_i}\right)/n.$$

It is clear that

$$1 = g(x_0) = \|g\|$$

and

$$1 = |(Tg)(y_0)| = \|Tg\|.$$

Moreover, $|(Tg)(y)| < 1$ for all y outside U . Consequently, the elements of Y_{00} are strong boundary points for B .

Conversely, let $y_0 \in \tau B$. Arguing as in the preceding paragraph, we prove $X_{00} \subset \tau A$, where

$$X_{00} := \bigcup_{y \in \tau B} V_y.$$

Thus, there exists $x_0 \in \tau A$ such that $k(x_0) = y_0$, where k is the inverse of h (see the proof of Theorem 4.1). That is, $y_0 \in V_{x_0} \subset Y_{00}$ and we are done. \square

The following corollary shows that Myers' theorem ([20]) is valid also for non-compact spaces and complex valued functions. Moreover we can write the isometry as a weighted composition map.

Corollary 4.4. *Let T be a linear isometry of a completely regular linear subspace A of $C_0(X)$ onto such a subspace B of $C_0(Y)$. Then there exist a homeomorphism h of Y onto X and a continuous map $a : Y \rightarrow \mathbb{K}$, such that $|a(y)| = 1$ for all $y \in Y$, and*

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in Y \text{ and all } f \in A.$$

Proof. It is evident from the definition of completely regular linear subspace that $\sigma_0 A = X$ and $\sigma_0 B = Y$. The result follows now from Theorem 4.1. \square

Remark. It is clear that the linear isometry T extends uniquely to an isometry from $C_0(X)$ onto $C_0(Y)$.

5. SUBSPACES AS QUOTIENT SPACES

Corollary 5.1. *Let T be a linear isometry of a strongly separating subspace A of $C_0(X)$ into $C_0(Y)$. Then $\sigma_0 A$ is homeomorphic to a quotient of a subspace Y_0 of Y .*

Proof. With the same notation as in Theorem 3.1, let us define the following equivalence in Y_0 : $y_0 \sim y_1$ if y_0, y_1 belong to the same V_x , for some $x \in \sigma_0 A$. If π denotes the natural quotient map of Y_0 onto (Y_0/\sim) , then the map $h^\sim = h \circ \pi^{-1}$ is a continuous bijection of (Y_0/\sim) onto $\sigma_0 A$. To prove the continuity of $(h^\sim)^{-1}$, take a net (x_α) in $\sigma_0 A$ converging to $x_0 \in \sigma_0 A$. For each α , take $y_\alpha \in V_{x_\alpha}$. Clearly there exists a subnet (y_β) of (y_α) converging to a point $y_0 \in Y \cup \{\infty\}$. Take any $f \in A$. Then $(|f(x_\beta)|)$ converges to $|f(x_0)|$ and $|(Tf)(y_\beta)|$ converges to $|(Tf)(y_0)|$. As

$$|(Tf)(y_\beta)| = |f(x_\beta)|$$

for all β , we have that

$$|f(x_0)| = |(Tf)(y_0)|$$

for all $f \in A$, that is, $y_0 \in V_{x_0}$. This implies that $((h^\sim)^{-1}(x_\beta))$ converges to $(h^\sim)^{-1}(x_0)$. In this way, every subnet of $((h^\sim)^{-1}(x_\alpha))$ has a subnet converging to $(h^\sim)^{-1}(x_0)$. So $((h^\sim)^{-1}(x_\alpha))$ converges to $(h^\sim)^{-1}(x_0)$. Then $(h^\sim)^{-1}$ is continuous. \square

Remark. Let us suppose that, in Corollary 5.1, X is compact and $1 \in A$. We now consider the quotient space Y/D , where D is a decomposition of Y which consists of the subsets V_x , $x \in \sigma_0 A$, and the singletons $\{y\}$ such that $y \in Y - Y_0$. Since now $a = T1$ then $\|a\| = 1$ and we can define an isometry T^\sim of A into $C_0(Y/D)$ by the requirement that $(T^\sim f)(y^\sim) = (\bar{a}Tf)(\pi^{-1}(y^\sim))$ for all $f \in A$ and all $y^\sim \in Y/D$, where \bar{a} denotes the complex conjugate of the map a and π the natural quotient map of Y onto Y/D . T^\sim is well defined because, by Theorem 3.1, $\bar{a}Tf$ is constant on each V_x , $x \in \sigma_0 A$. As in Corollary 5.1, we prove that $\sigma_0 A$ is homeomorphic to a subspace $(Y/D)_0$ of Y/D , defined like Y_0 in Theorem 3.1. Moreover, with the hypothesis of Corollary 5.1, there exists a norm-preserving linear extension U from the subspace $\{A \circ h\}$ of $C(Y_0)$ into $C_0(Y)$ defined to be $U(g) := \bar{a}(Tf)$, where $g := f \circ h$ for some $f \in A$.

All these remarks show that Corollary 5.1 extends a result by D. Amir and B. Arbel [3, Theorem 1], if we assume that X is compact and $A = C(X)$. Furthermore, this assumption lets us claim that if $T(C(X))$ is a strongly separating linear subspace, then it is complemented in $C_0(Y)$. To prove this, we define a projection π from $C_0(Y)$ onto $T(C(X))$ as follows: given $f \in C_0(Y)$, let $\pi(f)$ be

$$T(\bar{a}(h^{-1}(-))) \cdot f(h^{-1}(-))$$

where h^{-1} is the inverse of h defined as in Theorem 4.1. It is easy to check that $\pi \circ T = T$ and, consequently, $\pi^2 = \pi$.

6. ISOMETRIES BETWEEN SUBALGEBRAS

Theorem 6.1. *Let T be a linear isometry of a separating function subalgebra A of $C_0(X)$ onto such a subspace B of $C_0(Y)$. Then*

- 1.– ∂A is homeomorphic to ∂B .
- 2.– There exists a continuous map $b : Y \rightarrow \mathbb{K}$ such that

$$T(fg)(y) = b(y)(Tf)(y)(Tg)(y) \text{ for all } y \in Y \text{ and all } f, g \in A.$$

Proof. 1.– It suffices to show that A is strongly separating. Let $x_1, x_2 \in X$ with $x_1 \neq x_2$. There exists $f \in A$ such that $f(x_1) = z_1$ and $f(x_2) = z_2$ with $z_1 \neq z_2$. If $|z_1| = |z_2|$, then we consider the function $g := f + f^2 \in A$. Hence, $g(x_1) = z_1(1 + z_1)$ and $g(x_2) = z_2(1 + z_2)$. With no loss of generality, we can assume that $\operatorname{Re} z_1$ and $\operatorname{Re} z_2$ are different. Otherwise we multiply the function f by the complex number i and, since $z_1 \neq z_2$, we infer that $\operatorname{Re} iz_1 \neq \operatorname{Re} iz_2$. Then

$$\begin{aligned} |g(x_1)|^2 &= |z_1|^2 |1 + z_1|^2 \\ &= |z_1|^2 (1 + z_1) \overline{(1 + z_1)} \\ &= |z_1|^2 (1 + z_1 + \bar{z}_1 + |z_1|^2) \\ &= |z_1|^2 |1 + 2\operatorname{Re} z_1 + |z_1|^2| \end{aligned}$$

and

$$\begin{aligned} |g(x_2)|^2 &= |z_2|^2 |1 + z_2|^2 \\ &= |z_2|^2 (1 + z_2) \overline{(1 + z_2)} \\ &= |z_2|^2 (1 + z_2 + \bar{z}_2 + |z_2|^2) \\ &= |z_2|^2 |1 + 2\operatorname{Re} z_2 + |z_2|^2|. \end{aligned}$$

Clearly, $|g(x_1)| \neq |g(x_2)|$. Summing up, A is a strongly separating linear subspace of $C_0(X)$ and the result follows from Theorem 4.1.

2.– We know, by Theorem 4.1, that $a(y)T(fg)(y) = (Tf)(y)(Tg)(y)$ for all $f, g \in A$ and all $y \in \partial B$. Consequently, if b denotes the complex conjugate of a ,

$$T(fg)(y) = b(y)(Tf)(y)(Tg)(y)$$

for all $y \in \partial B$ and all $f, g \in A$.

Let $y_0 \in Y - \partial B$ and let $f \in A$ such that $(Tf)(y_0) = 0$. We now show that $T(fg)(y_0) = 0$ for all $g \in A$. It is clear that the maps

$$T(fg)(Tk)(Tk)$$

and

$$(Tk^2)(Tf)(Tg)$$

coincide on ∂B , for $k \in A$ such that $(Tk)(y_0) \neq 0$. Thus they coincide on Y and consequently $T(fg)(y_0) = 0$.

To extend b from ∂B to Y , take, for each $y \in Y - \partial B$, f, g in A such that $(Tf)(y) \neq 0$ and $(Tg)(y) \neq 0$. Then we define

$$b(y) = T(fg)(y)/(Tf)(y)(Tg)(y).$$

This extension of the map b to the whole Y is well defined because if we consider $k, l \in A$ with $(Tk)(y) \neq 0$ and $(Tl)(y) \neq 0$, then

$$T(fg)(Tk)(Tl)$$

and

$$(Tf)(Tg)T(kl)$$

coincide on ∂B and, as a consequence, on Y . The continuity of b follows from the continuity of $T(fg)$, Tf and Tg in an open neighborhood of each y . \square

Theorem 6.2. *Let A, B be semisimple commutative Banach algebras (not necessarily with unit), such that $\|f\|^2 = \|f^2\|$ for all $f \in A$ (resp. $f \in B$). If T is a linear isometry of A into (resp. onto) B , then there exists a continuous map (resp. a homeomorphism) h of a subset Y_0 of the maximal ideal space Y of B (resp. the Shilov boundary ∂B) onto the Shilov boundary, ∂A , of A and a continuous map $a : Y_0 \rightarrow \mathbb{K}$ (resp. $a : \partial B \rightarrow \mathbb{K}$) with $|a(y)| = 1$ for all $y \in Y_0$ (resp. $y \in \partial B$) and*

$$(Tf)(y) = a(y)f(h(y)) \text{ for all } y \in Y_0 \text{ (resp. } \partial B) \text{ and all } f \in A.$$

Proof. Since $\|f\|^2 = \|f^2\|$ for all $f \in A$ (for all $f \in B$ respectively), the Gelfand transform is an isometry of A (resp. B) into $C_0(X)$ (resp. $C_0(Y)$), where X (resp. Y) is the maximal ideal space of A (resp. B). We can, therefore, regard A and B as separating function subalgebras of $C_0(X)$ and $C_0(Y)$ respectively, and the result follows from Theorem 3.1 and Theorem 4.1. \square

Corollary 6.3. (Nagasawa) *Two semisimple commutative Banach algebras with unit A and B such that $\|f\|^2 = \|f^2\|$ for all $f \in A$ (resp. $f \in B$) are isometric as Banach spaces if and only if they are isomorphic as algebras.*

Proof. Let us first regard A and B as in the proof of Theorem 6.2 and let T be a linear isometry of A onto B . It is clear, since both subalgebras have unit 1, that, in this context, the continuous function a which appears in Theorem 6.1 is $T1$. That is, $a \in B$. Furthermore, since T is onto, there exists $f \in A$ such that $Tf = 1$. Finally, from Theorem 6.1, we infer both that $b = a^{-1} \in B$ and that $b \cdot T$ is the desired algebra isomorphism.

The converse is clear. \square

Remark. As a consequence of Theorem 6.2 we deduce, for example, that the Shilov boundary of H^∞ , i.e. the space of bounded analytic functions on the open unit disk, is homeomorphic to the Shilov boundary of the algebra H_0^∞ consisting of all $f \in H^\infty$ that vanish at the origin. This falls immediately out of the linear isometry

$f \mapsto z \cdot f$ of H^∞ onto H_0^∞ . This example also shows that H^∞ and H_0^∞ , despite being isometric as Banach spaces, are not algebraically isomorphic since H_0^∞ does not have a unit. Consequently we cannot strengthen Corollary 6.3 to the effect “ A and B are algebraically isomorphic”, that is, Nagasawa’s result for uniform algebras with unit (see [21]).

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