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LINEAR TRANSFORMATIONS THAT PRESERVE THE NILPOTENT MATRICES

PETER BOTTA, STEPHEN J. PIERCE AND WILLIAM E. WATKINS

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LINEAR TRANSFORMATIONS THAT PRESERVE THE NILPOTENT MATRICES

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Let sl_n be the algebra of $n\times n$ matrices with zero trace and entries in a field with at least n elements. Let $\mathfrak N$ be the set of nilpotent matrices. The main result in this paper is that the group of nonsingular linear transformations L on sl_n such that $L(\mathfrak N)=\mathfrak N$ is generated by the inner automorphisms: $X\to S^{-1}XS$; the maps: $X\to aX$, for $a\ne 0$; and the map: $X\to X'$ that sends a matrix X to its transpose.

Introduction. Let M_n be the algebra of $n \times n$ matrices over a field K and let S be an algebraic set in M_n . There are a number of theorems characterizing the linear maps L on M_n that preserve S, i.e. $L(S) \subseteq S$. For example there are results for $\{X: \det X = 0\}$ by Dieudonné [4], $\{X: \operatorname{rank} X \leq 1\}$ by Jacob [8] and Marcus and Moyls [10], the orthogonal group by Pierce and Botta [2] and other linear groups by Dixon [5]. In every instance the transformations L that preserve these various algebraic sets have one of these two forms:

(1)
$$L(X) = PXO$$
, for all X

or

(2)
$$L(X) = PX^{t}Q$$
, for all X

where P and Q are in M_n . There are conditions on P and Q which depend on the algebraic set S. For example if $S = \{X: \det X = 0\}$ and L is nonsingular then P and Q are nonsingular; if S is the orthogonal group then PQ = I and P must be a scalar multiple of a matrix in the orthogonal group over the algebraic closure of K. For a good survey of further results of this type see Marcus [9].

In this paper we characterize the nonsingular linear transformations L that preserve the set $\mathfrak R$ of nilpotent matrices. Since the linear span of $\mathfrak R$ is the space sl_n of matrices with trace zero, we may as well assume that L is a transformation on sl_n . (In order to see that $\mathfrak R$ spans sl_n , let E_{ij} be the matrix whose only nonzero entry is a 1 in position (i,j). The nilpotent matrices E_{ij} and $E_{ii}+E_{ij}-E_{ji}-E_{ji}$ for $i\neq j$ span sl_n .)

Actually we characterize all nonsingular semilinear mappings that

Actually we characterize all nonsingular semilinear mappings that preserve nilpotence. The main theorem can be extended to matrices with entries from an integral domain. The extension follows from a modification of a result of Chevalley [3, p. 104, Théorème 3].

THEOREM. Let $n \geq 3$, K be a field with at least n elements and suppose that L is a nonsingular linear transformation on sl_n such that $L(\mathfrak{N}) \subseteq \mathfrak{N}$. Then L either has form (1) or (2), where PQ is a non-zero scalar matrix.

Without the assumption that L is nonsingular the theorem is false. Any map whose image is contained in the algebra $\mathfrak A$ of the strictly upper triangular matrices preserves nilpotence. The proof of the theorem depends on a result of Gerstenhaber about maximal spaces of nilpotent matrices. We also use some elementary algebraic geometry and the fundamental theorem of projective geometry [1, p. 88, Theorem 2.26].

LEMMA 1 (Gerstenhaber [6]). Suppose K has at least n elements and \mathfrak{M} is a space of nilpotent matrices. Then $\dim \mathfrak{M} \leq n(n-1)/2$. If $\dim \mathfrak{M} = n(n-1)/2$, then there exists a non-singular matrix S such that $\mathfrak{M} = S^{-1}\mathfrak{A}S$, where \mathfrak{A} is the algebra of strictly upper triangular matrices. Moreover, any matrix of nilindex n is contained in exactly one maximal nilpotent algebra.

Tangent Spaces. Let $K[X] = K[X_{11}, ..., X_{nn}]$ be the ring of polynomials in n^2 variables with coefficients in K. For r = 1, 2, ..., n, let $E_r(X) \in K[X]$ be the rth elementary symmetric function of the matrix $X = (X_{ij})$, i.e. $E_r(X)$ is the sum of all principal $r \times r$ subdeterminants of X. We let J be the ideal in K[X] generated by $E_1(X), ..., E_n(X)$ and rad $J = \{F \in K[X]: F^k \in J \text{ for some positive integer } k\}$. Clearly we have $\mathfrak{N} = \{A \in M_n: F(A) = 0 \text{ for all } F \in J\}$. If $A \in \mathfrak{N}$ then

$$\tan(J, A) = \left\{ B \in M_n : \frac{dF}{dt}(A + tB) \Big|_{t=0} = 0 \quad \text{for all } F \in J \right\}$$

and

$$\tan(\operatorname{rad} J, A) = \left\{ B \in M_n : \left. \frac{dF}{dt} (A + tB) \right|_{t=0} = 0 \text{ for all } F \in \operatorname{rad} J \right\}.$$

Both of these are vector spaces and the second is the usual tangent space at the point A of the algebraic set \mathfrak{N} . Further, the second is a subspace of the first.

If A and B belong to \mathfrak{N} and are similar then their tangent spaces defined above are related by the appropriate similarity. Further note that $C \in \tan(J, A)$ if and only if $(d/dt)E_r(A + tC)|_{t=0} = 0$ for all $r = 1, 2, \ldots, n$. If $A \in \mathfrak{N}$ is of nilindex n, then, by taking A into upper Jordan canonical form, one sees that the equations for $X \in \tan(J, A)$ are, up to a similarity,

$$0 = \sum_{i=0}^{n-j} X_{j+i,i+1}, \quad j = 1, 2, \dots, n.$$

Therefore dim $tan(J, A) = n^2 - n$. Since J is generated by n polynomials, if N is of nilindex n we have [7, p. 28, 37]

$$n^2 - n \le \dim \mathfrak{N} \le \dim \tan(\operatorname{rad} J, N) \le \dim \tan(J, N) = n^2 - n.$$

So if N is of nilindex n then tan(rad J, N) = tan(J, N).

LEMMA 2. If $A, B \in \mathcal{N}$ are both of nilindex n then AB = BA if and only if tan(rad J, A) = tan(rad J, B).

Proof. A is of nilindex n so its minimal and characteristic polynomials are equal. Therefore, if AB = BA, then B is a polynomial in A. By the above remarks, we may assume that

$$A = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ 0 & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & 1 \\ 0 & 0 & 0 & \cdots & 0 \end{bmatrix},$$

so

$$B = \begin{bmatrix} 0 & a_1 & a_2 & \cdots & a_{n-1} \\ 0 & 0 & a_1 & \cdots & a_{n-2} \\ 0 & 0 & 0 & \cdots & a_{n-3} \\ \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & 0 & \cdots & a_1 \\ 0 & 0 & 0 & \cdots & 0 \end{bmatrix},$$

where $a_i \in K$. Since B is of nilindex n, $a_1 \neq 0$. A direct computation shows that

$$\frac{d}{dt}E_n(B+tX)\Big|_{t=0} = a_1^{n-1}X_{n1}.$$

Hence the equation for B arising from E_n is $X_{n1} = 0$, which is the same as for A. One has that

$$\left. \frac{d}{dt} E_r(B + tX) \right|_{t=0} = a_1^{r-1} \sum_{i=0}^{n-r} X_{r+i\,i+1} + \sum_{j=1}^{r-1} A_j \sum_{i=0}^{n-j} X_{j+i\,i+1}$$

for suitable constants A_j depending on a_1, \ldots, a_{n-1} . By induction, the equation for B arising from E_r is

$$a_1^{r-1}\sum_{i=0}^{n-r}X_{r+i\,i+1}=0,$$

and since $a_1 \neq 0$ this is the same as for A. Since tan(J, A) = tan(rad J, A) the results follows.

On the other hand, suppose tan(rad J, A) = tan(rad J, B). We may assume A is as above. Let E_{ij} be the matrix with 1 in the (i, j) position and zeros elsewhere. Then

$$E_{ii} \in \tan(\operatorname{rad} J, A), \quad i > j,$$

and

$$E_{ii} - E_{i+1\,i+1} \in \operatorname{tan}(\operatorname{rad} J, A), \quad i \leq j.$$

Writing $B = (b_{ij})$, we have

$$\frac{d}{dt}E_{2}(B + tE_{ji})\Big|_{t=0} = b_{ij}, \quad \text{if } i > j,$$

$$\frac{d}{dt}E_{2}(B + t(E_{j}i - E_{j+1\,i+1}))\Big|_{t=0} = \pm (b_{ij} - b_{i+1\,j+1}) \quad \text{if } i \le j$$

Therefore $b_{ij} = 0$ if i > j and $b_{ij} = b_{i+1,j+1}$ if $i \le j$, and B is a polynomial in A.

LEMMA 3. If $L: \operatorname{sl}_n \to \operatorname{sl}_n$ is a nonsingular linear transformation with the property that $L(\mathfrak{N}) = \mathfrak{N}$, and $A \in \mathfrak{N}$, then $L(\tan(\operatorname{rad} J, A)) = \tan(\operatorname{rad} J, L(A))$.

Proof. The map $\tilde{L}: K[X] \to K[X]$ defined by $\tilde{L}(f)(A) = f(L(A))$ is a K-algebra homomorphism. Since L is nonsingular and $L(\mathfrak{N}) = \mathfrak{N}$ and rad $J = \{ f \in K[X]: f(N) = 0, \text{ for all } N \in \mathfrak{N} \}$, we have $\tilde{L}(\text{rad } J) = \text{rad } J$. Thus

$$\tan(\operatorname{rad} J, L(A)) = \left\{ B \in M_n : \frac{df}{dt} (L(A) + tB) \Big|_{t=0} \quad \text{for all } f \in \operatorname{rad} J \right\}$$

$$= \left\{ L(C) \in M_n : \frac{df}{dt} (L(A) + tL(C)) \Big|_{t=0} \quad \text{for all } f \in \operatorname{rad} J \right\}$$

$$= \left\{ L(C) \in M_n : \frac{d\tilde{L}(f)}{dt} (A + tC) \Big|_{t=0} = 0 \quad \text{for all } f \in \operatorname{rad} J \right\}$$

$$= L(\tan(\operatorname{rad} J, A)).$$

Proof of theorem. First we observe that $L(\mathfrak{N}) = \mathfrak{N}$. This follows from Lemma 1 of Dixon [5] and the fact that L is nonsingular.

We now show that L preserves nilindex n. If $A \in \mathcal{N}$ and rank $A \leq n - 2$, then A kills two linearly independent vectors v, w. Let $\mathcal{M}_1, \mathcal{M}_2$ be maximal nilpotent algebras containing A and killing v, w respectively. Every maximal nilpotent algebra kills exactly one line, so $\mathcal{M}_1 \neq \mathcal{M}_2$. By Lemma 1, L maps maximal nilpotent algebras to maximal nilpotent algebras and again by lemma 1, L preserves the matrices of nilindex n.

Now we show that if $A \in \mathfrak{N}$ has rank one, then so does L(A). Let U be the unit auxiliary matrix $E_{12} + \cdots + E_{n-1,n}$.

First note that the only members of \mathfrak{A} which commute with U and E_{12} are multiples of E_{1n} . Thus the centre of any maximal nilpotent algebra is one-dimensional and is generated by a rank one matrix.

Let $A \in \mathfrak{N}$ have rank one. Then for some nonsingular S, $S^{-1}AS = E_{1n}$. Let $\mathfrak{N} = S\mathfrak{N}S^{-1}$. Then A generates the centre of \mathfrak{N} . Let $V \in \mathfrak{N}$ have nilindex n. Then V and A + V have nilindex n and commute. It follows from Lemmas 2 and 3 that L(A + V) commutes with L(V). Hence L(A) commutes with L(V). Since the nilindex n matrices in \mathfrak{N} generate \mathfrak{N} , L(A) is in the centre of the maximal nilpotent algebra $L(\mathfrak{N})$. Hence L(A) has rank one.

We next define two bijections on the lines (through the origin) of K^n and use the fundamental theorem of projective geometry. For each line $\langle v \rangle \in K^n$, define two n-1 dimensional subspaces of \mathfrak{N} by

$$M(v) = \{X \in \mathfrak{N} \mid \operatorname{Im} X = \langle v \rangle \},$$

 $M'(v) = \{X' \mid X \in M(v)\}.$

We will show that L(M(v)) = M(w) or M'(w) and L(M'(v)) = M(w') or M'(w') for some $w, w' \in K^n$. The bijections will be $\varphi(v) = w$ and $\theta(v) = w'$.

We note a few facts about M(v). Any nonzero member of M(v) has rank one. If $v, w \in K^n$, and are nonzero, then M(v) and M(w) are conjugate, and if w = Av, A nonsingular, then $M(w) = AM(v)A^{-1}$. In tensor notation, $M(v) = v \otimes v^{\perp}$ and $M^t(v) = v^{\perp} \otimes v$. (Here, \perp means orthogonal complement with respect to the dot product.) It is easily verified that $M(u) \cap M(v) = M(u) = M(v)$ if u and v are linearly dependent and 0 otherwise, and that $M(u) \cap M^t(v) = \langle u \otimes v \rangle$ if $u \cdot v = 0$ and is 0 otherwise. Finally, observe that any n - 1 dimensional subspace of \mathfrak{N} with all of its nonzero matrices having rank one must be an M(v) or an $M^t(v)$. It follows that for $v \in K^n$, there is a $w \in K^n$ such that L(M(v)) = M(w) or $M^t(w)$.

Suppose we have $v, w \in K^n$ with L(M(v)) = M(v') and $L(M(w)) = M^t(w')$. Since $n \ge 3$, pick u orthogonal to v and w. Then $M(v) \cap M^t(u)$

and $M(w) \cap M'(u)$ are one dimensional. If L(M'(u)) = M(u') then $M(u') \cap M(v') = L(M'(u) \cap M(v))$ has dimension 1; which is impossible, as $M(u') \cap M(v')$ has dimension 0 or $n-1 \ge 2$. If L(M'(u)) = M'(u'), we reach a similar contradiction. A similar argument holds when we examine the images of M'(v) and M'(w). Thus, by replacing L with the map $X \to L(X)^t$ if necessary, we may assume that for any nonzero $v \in K^n$, L(M(v)) = M(w) and L(M'(v)) = M'(u) for appropriate $u, w \in K^n$.

Thus we define two maps φ , θ induced by L on the lines of K^n . We have $L(M(v)) = M(\varphi(v))$ and $L(M'(v)) = M'(\theta(v))$ for $v \in K^n$.

Since $L(\mathfrak{N}) = \mathfrak{N}$, L^{-1} also preserves nilpotence and hence φ and θ are bijections on the lines of K^n .

Now we show that φ and θ preserve coplanarity of lines in K^n and thus satisfy the hypothesis of the fundamental theorem of projective geometry. Let $\langle u_1 \rangle$, $\langle u_2 \rangle$, $\langle u_3 \rangle$ be three distinct coplanar lines in K^n . Then

$$2n - 1 = \dim(M(u_1) + M(u_2) + M(u_3))$$

$$= \dim L(M(u_1) + M(u_2) + M(u_3))$$

$$= \dim(M(\varphi(u_1)) + M(\varphi(u_2)) + M(\varphi(u_3))).$$

If $\varphi(u_1)$, $\varphi(u_2)$, $\varphi(u_3)$ are linearly independent then

$$\dim(M(\varphi(u_1)) + M(\varphi(u_2)) + M(\varphi(u_3))) = 3n - 3$$

and this is impossible since $n \ge 3$. Thus $\varphi(u_1)$, $\varphi(u_2)$, $\varphi(u_3)$ are coplanar and φ satisfies the hypothesis of the fundamental theorem of projective geometry. So does θ . Thus there exist semilinear maps S and T on K^n such that $\varphi(u) = \langle Su \rangle$ and $\theta(u) = \langle Tu \rangle$, for all nonzero u in K^n .

There are linear maps P and Q on K^n and automorphisms σ and τ on K such that $Sv = P(\sigma v)$ and $Tv = Q(\tau v)$. (The automorphisms act componentwise.) Then

$$L(M(v)) = M(P\sigma v) = PM(\sigma v)P^{-1}$$

and

$$L(M^{t}(v)) = M^{t}(Q\tau v) = Q^{t^{-1}}M^{t}(\tau v)Q^{t}.$$

Suppose $u \cdot v = 0$. Then $\dim(M(u) \cap M^t(v)) = 1$ and so

$$\dim(M(P\sigma u)\cap M^t(Q\tau v))=1$$

and thus $(P\sigma u) \cdot (Q\tau v) = 0$, i.e.,

$$u\cdot\sigma^{-1}(P^tQ\tau v)=0.$$

Let R be the semilinear map defined by

$$Rv = \sigma^{-1}(P^tQ\tau v).$$

Then $u \cdot v = 0$ implies $u \cdot Rv = 0$. Thus R = dI is a scalar map, $\sigma = \tau$ and P'Q = dI.

Replace the map L with the map $X \to P^{-1}L(X)P$. Then $L(M(v)) = M(\sigma v)$ and $L(M^t(v)) = M^t(\sigma v)$, for all nonzero v in K^n . Thus if $u \cdot v = 0$ then $L(u \otimes v) = c(u \otimes v)\sigma(u \otimes v)$, where c is a scalar valued function. If $v \in \langle u_1, u_2 \rangle^{\perp}$, then by comparing $L((u_1 + u_2) \otimes v)$ with $L(u_1 \otimes v) + L(u_2 \otimes v)$ we get $c(u_1 \otimes v) = c(u_2 \otimes v)$. Similarly if $u \in \langle v_1, v_2 \rangle$, then $c(u \otimes v_1) = c(u \otimes v_2)$.

Now we show that c is a constant function. Suppose that $u_1 \cdot v_1 = 0$ and $u_2 \cdot v_2 = 0$. Pick $v_3 \in \langle u_1, u_2 \rangle^{\perp}$. Then $c(u_1 \otimes v_1) = c(u_1 \otimes v_3) = c(u_2 \otimes v_3) = c(u_2 \otimes v_2)$. Thus c is a constant function say $c(u \otimes v) = k$. Then $L(u \otimes v) = k\sigma(u \otimes v)$, for all u, v with $u \cdot v = 0$.

Since L is linear, σ is the identity automorphism. The rank one nilpotent matrices span sl, and so the theorem is proved.

REMARK. When n = 2, the same result is obtained by a simple computation.

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AND

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