List Decoding of 2-Interleaved Binary Alternant Codes

Chih-Chiang Huang^{*}, Hedongliang Liu^{*}, Lukas Holzbaur^{*}, Sven Puchinger[†], and Antonia Wachter-Zeh^{*} ^{*}Insitute for Communications Engineering, Technical University of Munich, Germany [†]Hensoldt Sensors GmbH, Ulm, Germany

Abstract—This paper is concerned with list decoding of 2interleaved binary alternant codes. The principle of the proposed algorithm is based on a combination of a list decoding algorithm for (interleaved) Reed-Solomon codes and an algorithm for (noninterleaved) alternant codes. A new upper bound on the decoding radius is derived and the list size is shown to scale polynomially in the code parameters. While it remains an open problem whether this upper bound is achievable, the provided simulation results show that a decoding radius exceeding the binary Johnson radius can be achieved with a high probability of decoding success by the proposed algorithm.

I. INTRODUCTION

Given a received word, a unique decoder returns (at most) one codeword within a specified radius of the received word. In contrast, the goal of a list decoder is to return a list \mathcal{L} containing *all* codewords within Hamming distance at most the decoding radius τ from the received word. A code is said to be ℓ -list-decodable with radius τ if the returned list is of size at most ℓ for a decoding radius of at most τ . The most important benefit of a list decoding algorithm is that it commonly allows for increasing the decoding radius compared to unique decoding. In particular, it has been shown [2] that any code of length n and minimum distance d can be ℓ -list-decoded up to the field-size-independent *Johnson radius* $\frac{t}{n} < 1 - \sqrt{1 - \frac{d}{n}}$, while ℓ scales polynomially in n. This result was refined in [3] to show that any q-ary code can be decoded up to the (strictly larger) q-ary Johnson radius¹ $\frac{t}{n} < \theta_q \left(1 - \sqrt{1 - \frac{d}{\theta_q n}}\right)$, where $\theta_q = q - \frac{1}{q}$. Generalized Reed-Solomon (GRS) codes and their subfield

Generalized Reed-Solomon (GRS) codes and their subfield subcodes, referred to as *alternant codes*², are among the most popular classes of algebraic codes and their (list-) decoding has attracted considerable attention by researchers. In 1997, Sudan [4] presented an interpolation-based list decoding algorithm for low-rate GRS codes based on a generalization of the well-known Welch-Berlekamp algorithm. In 1999, Guruswami and Sudan improved the algorithm by introducing the idea of assigning higher multiplicities to points in the interpolation [5]. At the cost of an increased interpolation complexity, this algorithm allows for list-decoding GRS codes up to the field-size-independent Johnson bound. In 2003, Koetter and Vardy further improved the algorithm by introducing varying multiplicities [6] in order to use soft-information on the reliability of the received symbols. When applying this algorithm to alternant codes, the fact that the symbols in both the codewords and the received word are contained in a subfield can be regarded as soft information. In [7] it was shown that choosing the multiplicities accordingly further increases the decoding radius to the binary (q = 2) Johnson radius.

Interleaving is another powerful method to achieve a larger decoding radius. In interleaved decoding, each codeword is a matrix where every row is a codeword of a given code and the weight of the error is determined by the number of non-zero columns in the error matrix. This concept has been applied to GRS codes [8]–[12], alternant codes [13], and algebraic-geometry codes [14], [15].

Parvaresh [11] combined list and interleaved decoding by adapting the Guruswami-Sudan (GS) algorithm to the decoding of 2-interleaved GRS codes. To this end, trivariate polynomials are used to set up the interpolation constraints and the resultants of polynomials are used to recover the codeword. By combining the approaches of interleaved decoding and the GS algorithm, this decoder achieves a larger decoding radius than the GS algorithm, however, at the cost of a small probability of failure.

In this paper, we propose a list decoding algorithm for 2interleaved binary alternant codes that combines the ideas of applying the Koetter-Vardy algorithm [6] to alternant codes [7] and Parvaresh's algorithm to interleaved GRS codes [11]. Similar to Parvareh's algorithm, it is difficult to make a precise statement on the decoding radius of this code. Instead, we present an upper bound on this radius, along with simulation results showing that the decoding radius of the algorithm exceeds the decoding radii of all other algorithms known in literature for the chosen parameters. The drawback of the presented algorithm is that decoding is not guaranteed to succeed (similar to [11]). However, the simulation results indicate that this probability of failure is small, if the parameters of the algorithm are chosen suitably.

Due to space limitations, some proofs are omitted and can be found in the extended version [1] of this work.

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¹Note that the q-ary Johnson radius approaches the field-size-independent Johnson radius as $q \to \infty$.

²This class of codes contains some of the most popular codes over small fields, such as BCH and Goppa codes.

II. PRELIMINARIES

Let [n] be the set of integers $\{1, \ldots, n\}$. For a prime power qand an integer m, denote by \mathbb{F}_q the finite field with q elements and by \mathbb{F}_{q^m} its extension field. Let $\mathbb{F}_q^* := \mathbb{F}_q \setminus \{0\}$ and \mathbb{N}_0 be the natural numbers including zero. For two sets \mathcal{A}, \mathcal{B} , denote their Cartesian product by $\mathcal{A} \times \mathcal{B} := \{(a, b) \mid a \in \mathcal{A}, b \in \mathcal{B}\}$. Denote a linear code of length n and dimension k over the field \mathbb{F}_q by $[n, k]_q$. For a matrix $\mathbf{E} \in \mathbb{F}_q^{M \times n}$ define colsupp $(\mathbf{E}) \subseteq [n]$ as the set of indices of the non-zero columns in \mathbf{E} . Let $\mathbb{F}_q[X, Y, Z]$ be the ring of polynomials in X, Y, and Z with coefficients in \mathbb{F}_q . If clear from context, we omit the variables from the notation and simply write Gfor a polynomial $G(X, Y, Z) \in \mathbb{F}_q[X, Y, Z]$.

Definition 1 (Weighted Degree of Trivariate Monomials): Let $w = (w_1, w_2, w_3)$ be a tuple of positive integers. The (w-) weighted degree of a trivariate monomial $X^a Y^b Z^c$, is defined as

$$\deg_{\boldsymbol{w}}(X^a Y^b Z^c) \coloneqq w_1 a + w_2 b + w_3 c$$

We define the X-degree (resp. Y, Z) of a polynomial $G(X, Y, Z) \in \mathbb{F}_q[X, Y, Z]$ to be $\deg_X(G) \coloneqq \deg_{(1,0,0)}(G)$.

Definition 2 (Monomial Ordering): For two monomials $X^aY^bZ^c$ and $X^uY^vZ^s$, define a monomial ordering $\prec_{\boldsymbol{w}}$ with $X^aY^bZ^c \prec_{\boldsymbol{w}} X^uY^vZ^s$ if $\deg_{\boldsymbol{w}}(X^aY^bZ^c) < \deg_{\boldsymbol{w}}(X^uY^vZ^s)$. If the weighted degrees are equal, then $X^aY^bZ^c \prec_{\boldsymbol{w}} X^uY^vZ^s$ if and only if a < u or a = u and b < v. The leading monomial of a polynomial is the largest term under the ordering $\prec_{\boldsymbol{w}}$. The weighted degree of a polynomial $G(X,Y,Z) \in \mathbb{F}_q[X,Y,Z]$ is the weighted degree of its leading monomial.

Note that any polynomials $Q(X, Y, Z), P(X, Y, Z) \in \mathbb{F}_{2^m}[X, Y, Z]$ can be written in the form

$$Q(X, Y, Z) = \text{Coeff}_Q(X, Y) (Z - q_1(X, Y)) (Z - q_2(X, Y)) \dots,$$

$$P(X, Y, Z) = \text{Coeff}_P(X, Y) (Z - p_1(X, Y)) (Z - p_2(X, Y)) \dots,$$

where the coefficients $\operatorname{Coeff}_Q(X, Y)$ and $\operatorname{Coeff}_P(X, Y)$ are functions in X and Y and $q_i(X, Y)$, $p_j(X, Y)$ are the Z-roots of Q and P, respectively.

Definition 3 (Resultant [16], [17]): The resultant of two polynomials Q(X, Y, Z) and P(X, Y, Z) w.r.t. Z is

$$H_{Z}(X,Y) = \text{Resultant}\left(Q\left(X,Y,Z\right), P\left(X,Y,Z\right);Z\right)$$

:= Coeff $(X,Y) \prod_{i,j} \left(q_{i}\left(X,Y\right) - p_{j}\left(X,Y\right)\right),$

where $\operatorname{Coeff}(X, Y) = \operatorname{Coeff}_Q^{\deg_Z(P)} \operatorname{Coeff}_P^{\deg_Z(Q)}$.

Definition 4 (Generalized Řeed-Solomon Code): Denote by $S = \{\alpha_1, \alpha_2, \ldots, \alpha_n\} \subseteq \mathbb{F}_{q^m}$ a set of *n* distinct code locators and by $\mathcal{B} = \{\beta_1, \beta_2, \ldots, \beta_n\} \subseteq \mathbb{F}_{q^m}^*$ a set of column multipliers. An $[n, k_{\text{GRS}}]_{q^m}$ Generalized Reed-Solomon (GRS) is defined by

$$\operatorname{GRS}_{q^m}(\mathcal{S}, \mathcal{B}, k_{\operatorname{GRS}}) \coloneqq \left\{ \left(\beta_1 f(\alpha_1), \dots, \beta_n f(\alpha_n) \right) \\ \mid f(X) \in \mathbb{F}_{q^m}[X], \operatorname{deg}\left(f(X)\right) < k_{\operatorname{GRS}} \right\}.$$

It is well-known that GRS codes are maximum distance separable (MDS) codes, i.e., of minimum distance $d = n - k_{\text{GRS}} + 1$.

Definition 5 (Binary Alternant Code): Let $\operatorname{GRS}_{2^m}(\mathcal{S}, \mathcal{B}, k_{\operatorname{GRS}})$ be as in Definition 4. Its alternant

code is defined as

$$\mathcal{A}(\mathcal{S}, \mathcal{B}, k_{\text{GRS}}) \coloneqq \text{GRS}_{2^m}(\mathcal{S}, \mathcal{B}, k_{\text{GRS}}) \cap \mathbb{F}_2^n$$

Note that k_{GRS} is not the dimension of the alternant code, but only serves as a (loose) upper bound. However, as the parameters S, B, and k_{GRS} uniquely specify a GRS code, they also determine the corresponding alternant code.

Definition 6 (2-Interleaved Alternant Code): Let $A(S, B, k_{GRS})$ be as in Definition 5. Define the 2-interleaved alternant code as

$$\mathcal{I}A(\mathcal{S},\mathcal{B},k_{\text{GRS}};2) \coloneqq \left\{ \begin{pmatrix} \boldsymbol{c}^{(1)} \\ \boldsymbol{c}^{(2)} \end{pmatrix} \middle| \boldsymbol{c}^{(1)}, \boldsymbol{c}^{(2)} \in A(\mathcal{S},\mathcal{B},k_{\text{GRS}}) \right\}.$$

Throughout this paper, we associate the codewords $c^{(1)}, c^{(2)} \in \mathcal{A}(\mathcal{S}, \mathcal{B}, k_{GRS})$ with their respective evaluation polynomials $f(X), g(X) \in \mathbb{F}_{2^m}[X]$ by

$$\boldsymbol{c}^{(1)} = (\beta_1 f(\alpha_1), \dots, \beta_n f(\alpha_n)),$$
$$\boldsymbol{c}^{(2)} = (\beta_1 g(\alpha_1), \dots, \beta_n g(\alpha_n)).$$

Let $oldsymbol{R} \in \mathbb{F}_2^{2 imes n}$ be a received word with

$$\boldsymbol{R} = \begin{pmatrix} \boldsymbol{y} \\ \boldsymbol{z} \end{pmatrix} = \begin{pmatrix} \boldsymbol{c}^{(1)} \\ \boldsymbol{c}^{(2)} \end{pmatrix} + \begin{pmatrix} \boldsymbol{e}^{(1)} \\ \boldsymbol{e}^{(2)} \end{pmatrix} = \boldsymbol{C} + \boldsymbol{E}, \quad (1)$$

where $C \in \mathcal{IA}(\mathcal{S}, \mathcal{B}, k_{\text{GRS}}; 2)$. The *error positions* of E are given by $\mathcal{E} \coloneqq \text{colsupp}(E)$. Denote the *error-free positions* by $\overline{\mathcal{E}} \coloneqq [n] \setminus \mathcal{E}$.

Define the set \mathcal{P} of n received points as

$$\mathcal{P} \coloneqq \{(x_1, y_1, z_1), \dots, (x_n, y_n, z_n)\} \subset \mathcal{S} \times \mathbb{F}_2 \times \mathbb{F}_2,$$

where $(x_s, y_s, z_s) = (\alpha_s, \beta_s f(\alpha_s) + e_s^{(1)}, \beta_s g(\alpha_s) + e_s^{(2)}), \forall s \in [n]$ and a modified set \mathcal{P}' of received points as

$$\mathbf{P}' \coloneqq \{ \left(x_1, \beta_1^{-1} y_1, \beta_1^{-1} z_1 \right), \dots, \left(x_n, \beta_n^{-1} y_n, \beta_n^{-1} z_n \right) \}.$$

Denote by $\mathcal{P}'_{\mathcal{E}}$ and $\mathcal{P}'_{\bar{\mathcal{E}}}$ the subsets of \mathcal{P}' corresponding to the erroneous positions in \mathcal{E} and the error-free positions in $\bar{\mathcal{E}}$, respectively.

Definition 7 (Hasse Derivatives of Trivariate Polynomials [11]): For a polynomial $G(X,Y,Z) \in \mathbb{F}_q[X,Y,Z]$, the (a,b,c)-th Hasse derivative of G(X,Y,Z), denoted by $\mathscr{D}_{a,b,c}[G(X,Y,Z)]$, is defined as

$$\mathcal{D}_{a,b,c}\left[G\left(X,Y,Z\right)\right] \coloneqq \sum_{p=a}^{\infty} \sum_{q=b}^{\infty} \sum_{r=c}^{\infty} {p \choose a} {q \choose b} {r \choose c} g_{p,q,r} X^{p-a} Y^{q-b} Z^{r-c},$$

where $g_{p,q,r}$ denotes the coefficient of the term $X^pY^qZ^r$ in G(X, Y, Z).

Definition 8 (Multiplicity of Trivariate Polynomials [11, Def. 2.1]): Let $P = (x_s, y_s, z_s) \in \mathbb{F}_q \times \mathbb{F}_q \times \mathbb{F}_q$. The interpolation polynomial G(X, Y, Z) is said to pass through the point $P = (x_s, y_s, z_s)$ with multiplicity m_1 , or to have a zero of multiplicity m_1 at the point, if

$$\mathscr{D}_{a,b,c}\left[G\left(X,Y,Z\right)\right]\Big|_{P} = 0, \ \forall \ a,b,c \in \mathbb{N}_{0}, \ a+b+c < m_{1}.$$

By this definition, the interpolation constraint of passing through a point with multiplicity m_1 imposes $\binom{m_1+2}{3}$ linear constraints on the coefficients of G(X, Y, Z).

In this work, we fix the weight w of the w-weighted degree to be $w = (1, k_{\text{GRS}} - 1, k_{\text{GRS}} - 1)$, where k_{GRS} denotes the dimension of the GRS containing the alternant code (see Definition 5) under consideration.

III. LIST DECODING ALGORITHM FOR 2-INTERLEAVED BINARY ALTERNANT CODES

A. Sketch of the Algorithm

Let \mathbf{R} be a received word as defined in (1) and m_1, m_2 be integers such that $0 \leq m_2 < m_1$. We give a sketch of the proposed decoding algorithm consisting of the following steps: initialization, interpolation, and recovery.

1) Initialization: Let

$$\Delta \coloneqq (n (k_{\text{GRS}} - 1)^2 m_1 (m_1 + 1) (m_1 + 2) + 3n (k_{\text{GRS}} - 1)^2 m_2 (m_2 + 1) (m_2 + 2))^{\frac{1}{3}}$$
(2)

and $\mu \coloneqq \left\lceil \frac{\Delta}{k_{\rm GRS}-1} \right\rceil$. Initialize a set $\mathcal{G}^{(0)}$ of trivariate polynomials by

$$\mathcal{G}^{(0)} \coloneqq \left\{ G_1^{(0)}, G_2^{(0)}, \dots, G_l^{(0)} \right\}$$
$$= \left\{ Y^{\alpha} Z^{\beta} : \forall \alpha, \beta \in \mathbb{N}_0 \text{ s.t. } \alpha + \beta < \mu \right\}$$

Note that the size of $\mathcal{G}^{(0)}$ is $l \coloneqq \frac{\mu(\mu+1)}{2}$.

- Interpolation: Find a Groebner basis⁵ G of the ideal of all polynomials that, for all s ∈ [n], satisfy the interpolation constraints:
 - passes through (α_s, β_s⁻¹y_s, β_s⁻¹z_s) ∈ *P*' with multiplicity m₁,
 - passes through $(\alpha_s, \beta_s^{-1}\gamma_1, \beta_s^{-1}\gamma_2)$ with multiplicity $m_2, \forall (\gamma_1, \gamma_2) \in \mathbb{F}_2 \times \mathbb{F}_2 \setminus \{(y_s, z_s)\}.$
- 3) Recovery: Find the pair of interpolation polynomials $G_r, G_s \in \mathcal{G}$ of the lowest weighted-degree that do not have a common factor that is a polynomial in Y or Z. If no such pair of G_r, G_s can be found in \mathcal{G} , return a decoding failure. Otherwise, denote $\hat{\Delta} = \max\{\deg_{\boldsymbol{w}}(G_r), \deg_{\boldsymbol{w}}(G_s)\}$. Factorize the resultants (see Definition 3) of G_r and G_s with respect to Y and Z to get all the factors $Y \hat{f}(X)$ and $Z \hat{g}(X)$. Reconstruct the codewords $\hat{c}^{(1)}$ and $\hat{c}^{(2)}$ by evaluating $\hat{f}(X)$ and $\hat{g}(X)$ respectively. Append all the interleaved decoding radius $\hat{\tau} := \frac{n \hat{\Delta}/m_1}{1 m_2/m_1}$ and the list $\hat{\mathcal{L}}$ containing all codewords within radius $\hat{\tau}$ of the received word.

For details, please see the full algorithm in the extended version of this paper [1, Appendix].

B. Upper Bound on Decoding Radius of the Algorithm

Let \mathcal{G} be the Groebner basis for the ideal of all polynomials fulfilling the interpolation constraints in Section III-A. The following lemma gives a condition for the existence of a polynomial in \mathcal{G} of low weighted degree that fulfills the interpolation constraints.

Lemma 1: For Δ as in (2), there always exists a nonzero $G(X, Y, Z) \in \mathcal{G}$ with

$$\deg_{\boldsymbol{w}}(G(X,Y,Z)) \le \Delta.$$

 3 For the full algorithm to compute such a Groebner basis, see the extended version [1, Algorithm 2], which is adapted from the algorithm given in [11, Section 2.4].

Proof: By Definition 8, there are $\binom{m_1+2}{3}$ linear constraints imposed on a polynomial to pass through a point with multiplicity m_1 . Therefore, the total number of linear constraints imposed on the coefficients of any polynomial fulfilling the interpolation constraints is

$$C(m_1, m_2, n) \coloneqq n \cdot \binom{m_1 + 2}{3} + 3n \cdot \binom{m_2 + 2}{3}.$$

We call $C(m_1, m_2, n)$ the interpolation cost. Denote by $N(\Delta)$ be the number of trivariate monomials whose weighted degree is at most Δ . From the proof of [11, Lemma 2.1], $N(\Delta) > \frac{\Delta^3}{6(k_{\text{GRS}-1})^2}$. Finding a nonzero polynomial in $\mathbb{F}_{2^m}[X,Y,Z]$ that fulfills the interpolation constraints of Section III-A, 2) is equivalent to solving a linear system of equations with at most $C(m_1, m_2, n)$ constraints for at least $N(\Delta)$ unknowns. A nonzero solution is guaranteed to exist if $N(\Delta) > C(m_1, m_2, n)$. This inequality always holds with Δ as in (2). Since \mathcal{G} is a Groebner basis, it contains the polynomial of lowest weighted degree that fulfills the constraints and the lemma statement follows.

Denote by $\langle \mathcal{G} \rangle$ the set of polynomials spanned by \mathcal{G} . The following lemma gives a condition on the weighted degree of the interpolation polynomial $G(X, Y, Z) \in \langle \mathcal{G} \rangle$ such that f(X) and g(X) are a Y-root and Z-root of G(X, Y, Z), respectively.

Lemma 2: For a received word with t errors, let \mathcal{G} be the Groebner basis as in Section III-A. For any nonzero $G(X, Y, Z) \in \langle \mathcal{G} \rangle$ with

$$\deg_{\boldsymbol{w}} \left(G\left(X, Y, Z\right) \right) < m_1 \left(n - t\right) + m_2 t ,$$

it holds that $G(X, f(X), g(X)) \equiv 0$.

Proof: Let G(X,Y,Z) be a nonzero polynomial in $\langle \mathcal{G} \rangle$ and G(X,f(X),g(X)) = 0. Recall from Definition 7 and 8 that for any point (x_s,y_s,z_s) that G(X,Y,Z) passes through, we have

$$G (X + x_{s}, Y + y_{s}, Z + z_{s})$$

$$= \sum_{i} \sum_{j} \sum_{k} g_{i,j,k} (X + x_{s})^{i} (Y + y_{s})^{j} (Z + z_{s})^{k}$$

$$= \sum_{i} \sum_{j} \sum_{k} (\sum_{p} \sum_{q} \sum_{r} {p \choose i} {q \choose j} {r \choose k} g_{p,q,r} x_{s}^{p-i} y_{s}^{q-j} z_{s}^{r-k}) \cdot X^{i} Y^{j} Z^{k}$$

$$= \sum_{i} \sum_{j} \sum_{k} \mathscr{D}_{i,j,k} [G (X, Y, Z)] |_{(x_{s}, y_{s}, z_{s})} \cdot X^{i} Y^{j} Z^{k}.$$
(3)

Since $G(X, Y, Z) \in \langle \mathcal{G} \rangle$, G(X, Y, Z) passes through the (n-t) error-free received points in $\mathcal{P}'_{\bar{\mathcal{E}}}$ with multiplicity m_1 . Therefore, by Definition 8, we have

$$\mathcal{D}_{i,j,k}\left[G\left(X,Y,Z\right)\right]|_{(\alpha_{s},f(\alpha_{s}),g(\alpha_{s}))} = 0,$$

$$\forall i,j,k \in \mathbb{N}_{0} \text{ with } i+j+k < m_{1}, \forall s \in \bar{\mathcal{E}}.$$
 (4)

Hence, for the error-free points $(x_s, y_s, z_s) \in \mathcal{P}'_{\bar{\mathcal{E}}}$, (3) becomes

$$G(X + x_s, Y + y_s, Z + z_s) = \sum_{\substack{i \ i+j+k \ge m_1}} \sum_{\substack{k \ i+j+k \ge m_1}} g'_{i,j,k} \ X^i Y^j Z^k,$$

for some $g'_{i,j,k} \in \mathbb{F}_{2^m}$. Let

$$P(X) := G(X, f(X), g(X))$$

= $\sum_{\substack{i \neq j+k > = m_1}} \sum_{\substack{j \leq k \\ j \neq k > = m_1}} g'_{i,j,k} (X - \alpha_s)^i (f(X) - f(\alpha_s))^j (g(X) - g(\alpha_s))^k.$

Notice that

$$(f(X) - f(\alpha_s))|_{X = \alpha_s} = 0$$

$$(g(X) - g(\alpha_s))|_{X = \alpha_s} = 0 ,$$

so $(X - \alpha_s)$ divides $(f(X) - f(\alpha_s))$ and $(g(X) - g(\alpha_s))$. It follows that

$$\left(X - \alpha_s\right)^{m_1} |P\left(X\right), \ \forall s \in \bar{\mathcal{E}} \ .$$

Therefore, P(X) vanishes at the (n-t) error-free points $(\alpha_s, f(\alpha_s), g(\alpha_s)) \in \mathcal{P}'_{\bar{\mathcal{E}}}$ with multiplicity m_1 .

Similarly, as G(X, Y, Z) also passes through the erroneous points in $\mathcal{P}'_{\mathcal{E}}$ with multiplicity m_2 , P(X) vanishes at the *t* erroneous points $(\alpha_s, f(\alpha_s), g(\alpha_s)) \in \mathcal{P}'_{\mathcal{E}}$ with multiplicity m_2 .

Therefore, since $G \neq 0$ by definition,

$$\deg P(X) \ge m_1 (n-t) + m_2 t \; .$$

Recall that we fix the weights of \deg_{w} to be $w = (1, k_{\text{GRS}} - 1, k_{\text{GRS}} - 1)$. Since f(X) and g(X) have degree at most $k_{\text{GRS}} - 1$, this implies

$$\deg_{\boldsymbol{w}} \left(G\left(X, Y, Z\right) \right) \ge \deg_{X} \left(G\left(X, f\left(X\right), g\left(X\right) \right) \right) \ .$$

Hence, if deg_w
$$(G(X, Y, Z)) < m(n-t)+m_2t$$
, it holds that
 $G(X, f(X), g(X)) \equiv 0$.

Using this result, we now present an upper bound on the number of errors such that there exists at least one interpolation polynomial in \mathcal{G} fulfilling Lemma 2.

Theorem 1: Let Δ, m_1, m_2 , and \mathcal{G} be as in Section III-A. Then, for any received word with t errors, where

$$t \le \frac{n - \Delta/m_1}{1 - m_2/m_1},\tag{5}$$

there exists a $G(X, Y, Z) \in \mathcal{G}$ such that G(X, f(X), g(X)) = 0.

Proof: The upper bound follows from Lemma 1 and Lemma 2 by setting $\Delta \leq m_1 (n-t) + m_2 t$ and solving the inequality for t.

Note that the recovery step in Section III-A, 3) requires at least two polynomials in \mathcal{G} to have f(X) and g(X) as their Y- and Z-roots. A polynomial in \mathcal{G} is guaranteed to have this property, if its weighted degree fulfills the restriction of Lemma 2. The following theorem gives a bound on the number of errors such that the existence of at least two polynomials in \mathcal{G} of sufficiently small weighted degree is guaranteed.

Theorem 2: Consider a codeword of an $\mathcal{IA}(\mathcal{S}, \mathcal{B}, k_{\text{GRS}}; 2)$ code corrupted by t errors. Denote $n = |\mathcal{S}|$ and $d = n - k_{\text{GRS}} + 1$. Let m_1, m_2 and \mathcal{G} be as in Section III-A. Let

$$\sigma\left(\frac{m_2}{m_1}\right) \coloneqq \frac{1 - (1 - d/n)(1 + \nu)/2}{1 - m_2/m_1},\tag{6}$$

where $\nu = \sqrt{\frac{4}{3(1-d/n)} - \frac{1}{3} + \frac{4}{(1-d/n)}(\frac{m_2}{m_1})^3}$. If the number of errors is

$$t < n \cdot \sigma \left(\frac{m_2}{m_1}\right),\tag{7}$$

then there exist at least two polynomials $Q(X,Y,Z), P(X,Y,Z) \in \mathcal{G}$ such that

$$Q(X, f(X), g(X)) = 0$$
 and $P(X, f(X), g(X)) = 0$.

Proof: Let $G_1(X, Y, Z) \in \mathcal{G}$ be the polynomial of smallest weighted degree in \mathcal{G} and $\Delta_1 = \deg_{\boldsymbol{w}}(G_1(X, Y, Z))$. Note that G_1 is unique by definition of the monomial ordering $\prec_{\boldsymbol{w}}$ (see Definition 2).

We first show that $G_1 \neq 0$ only if

$$\Delta_1 > m_1 (k_{\text{GRS}} - 1). \tag{8}$$

Let the leading monomial of $G_1(X,Y,Z)$ be $g_{1,A,B,C}X^AY^BZ^C$, where $A \in [0, \Delta_1]$ and $B, C \in [0, \lfloor \frac{\Delta_1}{k_{\text{GRS}}-1} \rfloor]$. By Definition 1,

$$\Delta_1 = \deg_{\boldsymbol{w}} G_1\left(X, Y, Z\right) = A + \left(k_{\text{GRS}} - 1\right) \left(B + C\right).$$

By Definition 8 and the interpolation constraints, we have

$$\begin{aligned} \mathscr{D}_{a,b,c}\left[G_1\left(X,Y,Z\right)\right]|_{\left(\alpha_s,\beta_s^{-1}y_s,\beta_s^{-1}z_s\right)} &= 0,\\ \forall \ a,b,c \in \mathbb{N}_0 \text{ with } a+b+c < m_1, \forall s \in [n]. \end{aligned}$$

Denote $A' \coloneqq \min \{m_1 - B - C - 1, A\}$. For $B + C < m_1$ and $a \in [0, A']$, since $a + B + C < m_1$, we have

$$\mathcal{D}_{a,B,C}\left[G_{1}\left(X,Y,Z\right)\right]\Big|_{\left(\alpha_{s},\beta_{s}^{-1}y_{s},\beta_{s}^{-1}z_{s}\right)}$$
$$=\sum_{p=a}^{A} \binom{p}{a} g_{1,p,B,C} \alpha_{s}^{p-a} \left(\beta_{s}^{-1}y_{s}\right)^{B-B} \left(\beta_{s}^{-1}z_{s}\right)^{C-C}$$
$$\sum_{p=a}^{A} \binom{p}{a} g_{1,p,B,C} \alpha_{s}^{p-a} \left(\beta_{s}^{-1}z_{s}\right)^{C-C}$$

$$=\sum_{p=a}^{\infty} \binom{p}{a} g_{1,p,B,C} \ \alpha_s^{p-a} = 0$$

This is a linear system of equations

$$\binom{A'}{A'} g_{1,A',B,C} \alpha_s^0 + \binom{A'+1}{A'} g_{1,A'+1,B,C} \alpha_s^1 + \ldots + \binom{A}{A'} g_{1,A,B,C} \alpha_s^{A-A'} = 0, \quad \forall \ \alpha_s \in \mathcal{L}.$$
(9)

with n(A'+1) linear constraints and A+1 unknowns $g_{1,a,B,C}, a \in [0, A]$. If there are more linear constraints than unknowns in (9), then the only solution is $g_{1,i,B,C} = 0$, $\forall i \in [0, A]$. Therefore, we require $n(A'+1) \leq A+1$ to obtain a nonzero solution.

Recall that $A' = \min \{m_1 - B - C - 1, A\}$. For the case $A < m_1 - B - C - 1$, we always have

$$n(A'+1) = n(A+1) > A+1,$$

as this inequality holds for any non-trivial code with n > 1. For the other case, assume that (8) does not hold, i.e.,

$$\Delta_1 = A + (k_{\rm GRS} - 1) (B + C) < m_1 (k_{\rm GRS} - 1),$$

which leads to

$$A < (k_{\text{GRS}} - 1)(m_1 - B - C)$$

Then,

$$n(A'+1) = n(m_1 - B - C)$$

> $(k_{\text{GRS}} - 1)(m_1 - B - C) > A$

Therefore, (8) is a necessary condition such that there is a nonzero solution to (9), i.e., a nonzero G_1 of smallest weighted degree that fulfills the interpolation constraints.

Let $G_2(X, Y, Z) \in \mathcal{G}$ be the polynomial of second smallest weighted degree in \mathcal{G} and $\Delta_2 = \deg_{\boldsymbol{w}} G_2(X, Y, Z)$. Note that $G_1 \prec_{\boldsymbol{w}} G_2$ and therefore $\Delta_2 \ge \Delta_1$ according to Definition 2. By [11, Proof of Lemma 2.7], the number of monomials in G_2 of weighted degree smaller than Δ_2 is at most

$$\frac{\Delta_2^3}{6(k_{\rm GRS}-1)^2} - \frac{(\Delta_2 - \Delta_1)^3}{6(k_{\rm GRS}-1)^2}$$

By [18] and [11, Lemma 2.6], the number of monomials of degree at most Δ in $\langle {\cal G} \rangle$ is

$$n \cdot \binom{m_1+2}{3} + 3n \cdot \binom{m_2+2}{3}.$$

Therefore,

$$n \cdot {\binom{m_1+2}{3}} + 3n \cdot {\binom{m_2+2}{3}} \ge \frac{\Delta_2^3 - (\Delta_2 - \Delta_1)^3}{6(k_{\text{GRS}} - 1)^2}$$

Let $R \coloneqq \frac{k_{\text{GRS}} - 1}{n}$. By rearranging we obtain

$$\Delta_2^2 - \Delta_1 \Delta_2 + \frac{\Delta_1^2}{3} - \frac{2n^3 R^2 \left(\binom{m_1+2}{3} + 3\binom{m_2+2}{3} \right)}{\Delta_1} \le 0$$

Solving the inequality for Δ_2 we obtain

$$\Delta_2 \le \frac{\Delta_1}{2} \left(1 + \sqrt{-\frac{1}{3} + \frac{4}{3} \frac{n^3 R^2 m_1(m_1+1)(m_1+2) + 3n^3 R^2 m_2(m_2+1)(m_2+2)}{\Delta_1^3}} \right).$$
(10)

Note that the right-hand side of (10) is a function in Δ_1 and we denote it by $\mathcal{U}(\Delta_1)$. By taking the first derivative and the second derivative of $\mathcal{U}(\Delta_1)$, we observe that $\frac{\partial \mathcal{U}(\Delta_1)}{\partial \Delta_1} \leq 0$ for all $\Delta_1 \geq m_1(k_{\text{GRS}}-1)$. Therefore, $\mathcal{U}(\Delta_1)$ is a monotonically decreasing function for $\Delta_1 \geq m_1(k_{\text{GRS}}-1)$. Setting $\Delta_1 = m_1(k_{\text{GRS}}-1)$ in (10), gives an upper bound on Δ_2 .

$$\Delta_{2} \leq \frac{m_{1}nR}{2} \left(1 + \sqrt{-\frac{1}{3} + \frac{4}{3} \frac{n^{3}R^{2}m_{1}(m_{1}+1)(m_{1}+2) + 3n^{3}R^{2}m_{2}(m_{2}+1)(m_{2}+2)}{(nRm_{1})^{3}}} \right)$$

By Lemma 2, $G_{2}\left(X, f\left(X\right), g\left(X\right)\right) = 0$ holds when
 $m_{1}\left(n-t\right) + m_{2}t \geq$

$$\frac{m_1(n-t) + m_2t}{2} \left(1 + \sqrt{-\frac{1}{3} + \frac{4}{3} \frac{n^3 R^2 m_1(m_1+1)(m_1+2) + 3n^3 R^2 m_2(m_2+1)(m_2+2)}{(nRm_1)^3}} \right)$$
(11)

The bound in (7) is derived by solving inequality (11) for t. Note that to obtain a simpler (though slightly worse) bound we omit some terms that vanish as m_1 increases.

C. Guaranteed Decoding Radius

and

The bound on t given in (7) is derived by only considering the two polynomials of the lowest weighted degree in \mathcal{G} . However, it is not guaranteed that the resultants of these two polynomials can be factorized. The following proposition gives a condition such that there exists a pair of polynomials in \mathcal{G} whose resultants are nonzero.

Proposition 1: Consider a pair of polynomials $Q, P \in \mathbb{F}[X, Y, Z]$ with $Q, P \neq 0$. Let $H_Z(X, Y) :=$ Resultant (Q, P; Z) and $H_Y(X, Z) :=$ Resultant (Q, P; Y) (see Definition 3). Then, for any $f(X), g(X) \in \mathbb{F}[X]$,

$$H_Z(X,Y) \neq 0$$
 and $H_Z(X,f(X)) \equiv 0$ (12)

$$H_Y(X,Z) \neq 0 \text{ and } H_Y(X,g(X)) \equiv 0$$
 (13)

if and only if Q(X, Y, Z) and P(X, Y, Z) have no common factor which is a function in Y or Z and Q(X, f(X), g(X)) = P(X, f(X), g(X)) = 0.

Proof: From [11, Lemma 2.9] (see also [19]), the resultant $H_Z(X, Y)$ (similarly for $H_Y(X, Z)$ w.r.t. Z (to Y) is non-zero

if and only if Q and P do not have a common factor that is a polynomial in Y (in Z). From Definition 3, we can see that a Y-root of $H_Z(X,Y)$ is also a Y-root of Q(X,Y,Z) and P(X,Y,Z) and vice versa. Therefore, $H_Z(X, f(X)) \equiv 0$ if and only if Q(X, f(X), g(X)) = P(X, f(X), g(X)) = 0 and the statement of the proposition follows.

We cannot guarantee that the pair of polynomials of the lowest weighted degree in \mathcal{G} , from which the upper bound (7) is derived, do not have a common factor in Y and Z. Therefore, the achieved decoding radius $\hat{\tau}$ of the proposed algorithm is not guaranteed to achieve this bound. However, if the decoder does not fail, the returned list $\hat{\mathcal{L}}$ is guaranteed to contain all codewords within distance $\hat{\tau}$.

Theorem 3: Let $\hat{\mathcal{L}}$ be the returned list and $\hat{\tau}$ be the achieved decoding radius of the proposed algorithm, as described in the recovery step in Section III-A. Then the returned list $\hat{\mathcal{L}}$ contains all codewords within distance $\hat{\tau}$ from the received word.

Proof: Let C be a codeword at distance $t < \hat{\tau}$ of the received word. We follow the notations of Proposition 1. Recall from the recovery step in Section III-A that $G_r, G_s \in \mathcal{G}$ are the two polynomials which do not have a common factor in Y or Z and the achieved decoding radius of the proposed algorithm is $\hat{\tau} = \frac{n-\hat{\Delta}/m_1}{1-m_2/m_1}$. By Proposition 1, $H_Z(G_r, G_s)$ and $H_Y(G_r, G_s)$ are nonzero. Then $\max\{\deg_{\boldsymbol{w}}(G_r), \deg_{\boldsymbol{w}}(G_s)\} = \hat{\Delta} < m_1(n-t) + m_2t$. It follows from Lemma 2 that f(X) and g(X) (the polynomials associated to the codewords C) are Y-root and Z-root of both G_r and G_s . By Proposition 1, f(X) is a Y-root of $H_Z(G_r, G_s)$ and g(X) is a Z-root of $H_Y(G_r, G_s)$. Therefore, the codeword C is in the list $\hat{\mathcal{L}}$.

The following theorem shows that the decoding always succeeds when the number of errors is within the binary Johnson radius, which is the same radius achieved by the application [7] of Koetter-Vardy algorithm [6] to binary Goppa codes.

Theorem 4: Let $\hat{\tau}$ be the achieved decoding radius from the recovery step in Section III-A. Then, for sufficiently large m_1 and m_2 , we have

$$\hat{\tau} > \left\lceil \frac{1}{2} \left(n - n \sqrt{1 - \frac{2d}{n}} \right) - 1 \right\rceil,$$

and $\Pr\{\text{decoding failure}\} = 0$.

Proof: We prove this theorem by showing that the interpolation polynomials of the Koetter-Vardy algorithm are also contained in the constructed Groebner basis. The statement then follows from observing that the Koetter-Vardy algorithm has a deterministic decoding radius when m_1 and m_2 are large enough [7]. Specifically, when $t < \frac{1}{2}(n - n\sqrt{1 - 2\frac{d}{n}})$, there always exist two nonzero bivariate polynomials U(X,Y) and V(X,Z) of degree less than $m_1(n-t) + m_2t$ such that U(X, f(X)) = 0 and V(X, g(X)) = 0. The polynomials f(X) and g(X) can then be obtained by factorizing U(X,Y) and V(X,Z).

Now, we consider all l' polynomials of \mathcal{G} with $\deg_{\boldsymbol{w}} (G_i(X,Y,Z)) < m_1(n-t) + m_2t, \forall i \in \{1,2,\ldots,l'\}.$ From Lemma 2, we know $G_i(X, f(X), g(X)) = 0, \forall i \in \{1,2,\ldots,l'\}.$ $\{1, 2, \ldots, l'\}$. The proposed algorithm returns all codewords at distance t to the received word if and only if these l'polynomials do not have a common divisor that is a function in Y or Z (see the recovery step in III-A).

Since \mathcal{G} is a Groebner basis, U(X,Y) and V(X,Z) with weighted degree less than $m_1(n-t)+m_2t$ can be represented by linear combinations of these l' polynomials in \mathcal{G} . We write

$$U(X,Y) = \text{Coeff}_{u_1}G_{u_1}(X,Y,Z) + \text{Coeff}_{u_2}G_{u_2}(X,Y,Z) + \dots$$

$$V(X,Z) = \text{Coeff}_{v_1}G_{v_1}(X,Y,Z) + \text{Coeff}_{v_2}G_{v_2}(X,Y,Z) + \dots,$$

where $u_i, v_i \in \{1, 2, \dots, l'\}$ and the Coeff are some scalar coefficients.

Then, the greatest common divisor of $G_{u_1}(X,Y,Z), G_{u_2}(X,Y,Z), \ldots$ can only be a function in X or Y and the greatest common divisor of $G_{v_1}(X,Y,Z), G_{v_2}(X,Y,Z), \ldots$ can only be a function in X or Z. The theorem is proved because the greatest common divisor of these l' polynomials is not a function in Y or Z. Therefore, we always obtain a non-zero resultant and the proposed algorithm returns all codewords at distance at most t, i.e., $\hat{\tau} > t$.

D. Analysis of the Size of the Returned List

For a received word R with t errors, let \mathcal{G} be the Groebner basis returned by the interpolation step and $\hat{\mathcal{L}}$ be the list returned by the recovery step in Section III-A. We discuss the maximal list size $|\hat{\mathcal{L}}|$ of the proposed algorithm.

Lemma 3: For any pair of nonzero Q(X, Y, Z), $P(X,Y,Z) \in \mathcal{G}$ and t fulfilling (7), the number of Yroots of $H_Z(X,Y) = \text{Resultant}(Q,P;Z)$ is upper bounded by

$$\chi \coloneqq \left(\frac{m_1\left(n-t\right)+m_2t}{k_{\text{GRS}}-1}\right)^3 + 2\left(\frac{m_1\left(n-t\right)+m_2t}{k_{\text{GRS}}-1}\right).$$

Proof: From Definition 3, $H_Z(X,Y)$ has up to $\begin{array}{l} \left(\operatorname{Coeff}_{Q}\left(X,Y\right)\right) \ + \ \operatorname{deg}_{Y} \ \left(\operatorname{Coeff}_{P}\left(X,Y\right)\right) \ + \\ \left(\prod_{i,j}\left(q_{i}\left(X,Y\right) - p_{j}\left(X,Y\right)\right)\right) \ \text{solutions for } Y. \end{array}$ $\deg_{\mathbf{Y}}$ $\deg_{\mathbf{Y}}$ We have

and

$$\deg_{Y} (\operatorname{Coeff}_{P}(X,Y)) \leq \deg_{Y} (P(X,Y,Z))$$
$$\leq \frac{m_{1}(n-t) + m_{2}t}{k_{CPS} - 1}.$$
(15)

 $\prod_{i,j} \quad \begin{array}{l} \text{multiplies} \quad \text{up to} \\ \deg_{\mathbf{Z}} \quad \left(P\left(X,Y,Z\right) \right) \quad \text{terms.} \end{array}$ The product notation \deg_Z (Q(X,Y,Z)). For each term $q_i(X,Y) - p_j(X,Y)$, there are up to $\deg_{Y} (q_i(X,Y) - p_j(X,Y))$ solutions for Y. Therefore,

$$\deg_{Y} \left(\prod_{i,j} \left(q_{i}\left(X,Y\right) - p_{j}\left(X,Y\right) \right) \right)$$

$$\leq \deg_{Z} \left(Q\left(X,Y,Z\right) \right) \cdot \deg_{Z} \left(P\left(X,Y,Z\right) \right)$$

$$\cdot \deg_{Y} \left(q_{i}\left(X,Y\right) - p_{j}\left(X,Y\right) \right)$$

$$\leq \left(\frac{m_{1}\left(n-t\right) + m_{2}t}{k_{\text{GRS}} - 1} \right)^{3} .$$

$$(16)$$

We prove the Lemma by summing up the upper bounds in (14), (15), and (16). The Lemma is proved by studying the resultant with respect to Z. Note that the same result can be obtained by studying the resultant with respect to Y. It follows directly from the recovery step in Section III that the size $|\hat{\mathcal{L}}|$ of the returned list is at most χ , which grows polynomially in the code parameters.

In our simulation with n = 32, d = 13, t = 10, the size of the returned list is 1 with a probability > 99.9%.

E. Complexity Analysis

In the proposed algorithm, the interpolation step is the most computationally expensive step. In this step, we impose $n \cdot \binom{m_1+2}{3} + 3n \cdot \binom{m_2+2}{3}$ linear constraints. The overall complexity of the interpolation step is $O\left(n^2 R^{-\frac{2}{3}} m_1^8 + n^2 R^{-\frac{2}{3}} m_1^6 m_2^2\right)$, where $R = (k_{\text{GRS}} - 1)/n$. Note that when $m_1 \gg m_2$, the order of complexity of the proposed algorithm is the same as Parvaresh's algorithm for interleaved RS codes [11].

IV. CHOICES OF MULTIPLICITIES m_1 and m_2

The upper bound in Theorem 2 on the number of errors tis a function of the ratio m_2/m_1 . In this section, we discuss different strategies of choosing m_1 and m_2 .

As described in the interpolation step in Section III-A, m_1 denotes the multiplicity assigned to the received points in \mathcal{P}' and m_2 denotes the multiplicity assigned to the other points in $S \times \mathbb{F}_2 \times \mathbb{F}_2 \setminus \mathcal{P}'$. Therefore, the total number of multiplicities assigned to all points $(x, y, z) \in \mathcal{S} \times \mathbb{F}_2 \times \mathbb{F}_2$ is

$$m_{\text{total}} \coloneqq m_1 + (2^2 - 1) m_2$$

Given a total multiplicity m_{total} , the code length n, the designed minimum distance d, and the number of errors t, we discuss the following two strategies to choose the multiplicities m_1 and m_2 .

• Candidate 1: Choose the ratio m_2/m_1 such that it maximizes the upper bound (7) on the decoding radius, i.e.,

$$\frac{m_2}{m_1} = \arg \max_{\frac{m_2}{m_1} \in [0,1]} \left\{ \sigma \left(\frac{m_2}{m_1} \right) \right\}$$

with $\sigma(\frac{m_2}{m_1})$ defined as in (6).

• Candidate 2: Given a reliability matrix $\mathbf{\Pi} \in \mathbb{R}^{n \times 2^2}$ reflecting the reliabilities of the received points, find a multiplicity matrix $M \in \mathbb{N}_0^{n \times 2^2}$ as given in Algorithm 1, which is a generalization of [6, Algorithm A]. By $\pi_{i,j}$ and $m_{i,j}$ we denote the entries of Π and M, respectively.

For the 2²-ary symmetric channel⁴ with cross-over probability t/n, the reliability matrix Π is by

$$\pi_{i,j} = \begin{cases} 1 - t/n, & \text{if } y_i \cdot 2 + z_i = j, \\ \frac{t/n}{2^2 - 1}, & \text{else} \end{cases}, \ \forall i \in [n], j \in [4].$$

To find the best assignment of $m_{i,j}$ for a given number of interpolation constraints, the update of the entries $\pi_{i,i}^*$ in Line 4 should depend on the number of additional interpolation constraints imposed when updating the entry $m_{i,j}$. The number of interpolation constraints increases by

 ${}^{4}\textsc{Here,}$ we interpret the interleaved codeword $m{C}\in\mathbb{F}_{2}^{2 imes n}$ as a vector $m{c}\in$ $\mathbb{F}_{2^2}^n$.

Algorithm 1: Multiplicities Decision for Candidate 2

 Input: II, m_{total}, n

 1 Init: $\Pi^* \leftarrow \Pi, M \leftarrow 0, s \leftarrow m_{\text{total}} \cdot n$

 2 while $s \neq 0$ do

 3 Find position (i, j) of the largest entry $\pi^*_{i,j}$ in Π^*

 4 $\pi^*_{i,j} \leftarrow \frac{\pi_{i,j}}{\frac{1}{2}(m^2_{i,j} + 5m_{i,j} + 6)}$

 5 $m_{i,j} \leftarrow m_{i,j} + 1$

 6 $s \leftarrow s - 1$

 7 end

 Output: M

 $1/2(m_{i,j}^2 + 3m_{i,j} + 2)$ if the entry corresponding to $m_{i,j}$ is increased to $m_{i,j} + 1$. Note that the denominator of line 4 is $1/2((m_{i,j} + 1)^2 + 3(m_{i,j} + 1) + 2)$. When m_{total} is sufficiently large, the $m_{i,j}^2$ term in the denominator becomes the dominant term. Since the channel is symmetric, the algorithm then returns a multiplicity matrix converging to two distinct values m_1 and m_2 with

$$\frac{1-\frac{t}{n}}{m_1^2} \approx \frac{\frac{t/n}{2^2-1}}{m_2^2}.$$

Specifically, Algorithm 1 returns m_1 and m_2 with

$$\frac{m_2}{m_1} \approx \sqrt{\frac{t/n}{3\left(1 - t/n\right)}}$$

We illustrate the upper bound in Theorem 2 on the normalized decoding radius t/n of the proposed algorithm with both candidates of m_2/m_1 in Figure 1. For sufficiently large m_{total} , Candidate 1 and 2 result in a similar choice for m_1 and m_2 . Therefore, the upper bounds with either candidate coincide, as evident from Figure 1, where we set $m_{\text{total}} = 1000$. Note that this value is chosen to illustrate the *maximal* achievable radius and is generally not a practical choice for implementation.

For comparison, we also include the normalized decoding radii of other list decoding algorithms in Figure 1. It is evident that the upper bound of the proposed algorithm is larger than the decoding radius of other existing algorithms. Note that the Koetter-Vardy radius is also achievable by the proposed algorithm with success probability 1 (see Theorem 4).

V. SIMULATIONS

In this section, we provide simulation results for the proposed algorithm. Since the proposed algorithm does not guarantee successful decoding when $t > \frac{1}{2} \left(n - \sqrt{n(n-2d)}\right)$, we evaluate its performance by simulating the probability of a *decoding success*, which is the case that the transmitted codeword is in the returned list $\hat{\mathcal{L}}$.

The black point in Figure 1 corresponds to the parameters n = 32, d = 13, t = 10. As discussed in Section III-E, m_1 is the dominant term in the complexity of the algorithm. Due to limitations in computational power, we chose relatively small m_1 and m_2 for the simulation and are therefore not able to achieve the upper bound given in Theorem 2. Nevertheless, the number of errors t = 10 is beyond the decoding radius of the existing list decoding algorithms for a binary code with n = 32, and d = 13.

From the results on the probability of a decoding success, illustrated in Figure 2, it can be seen that, by choosing

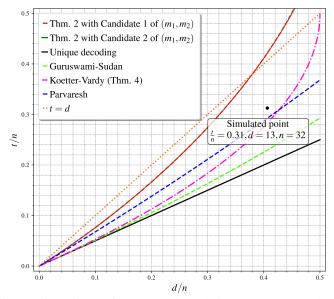


Fig. 1: Illustrations of the upper bounds in Theorem 2 on the normalized decoding radius t/n with difference candidates of (m_1, m_2) and the normalized decoding radius of Guruswami-Sudan algorithm [5] (field-size independent Johnson bound), Koetter-Vardy algorithm [6] (binary Johnson bound), and Parvaresh's algorithm [11] (for interleaved RS codes). The *x*-axis d/n is the normalized design minimum distance of the code being list-decoded. The "Simulated point" represents the parameters of the simulations described in Section V (see also Figure 2) and illustrates that, despite the bound of Theorem 2 being an upper bound on the radius, the achieved decoding radius exceeds the radius of all known algorithms.

proper (m_1, m_2) (e.g., (8, 3) or (8, 4)), the proposed algorithm can successfully decode beyond the radius of the other list decoding algorithms with high probability.

Moreover, we investigate the impact of m_1 and m_2 on success probability via simulations. Figure 2 shows the probability of decoding success for different combinations of m_1 and m_2 . We ran ≥ 100 simulations for every pair of (m_1, m_2) in Figure 2. It can be seen increasing m_{total} generally improves the probability of success, but only if the ratio of m_1 and m_2 is chosen suitably.

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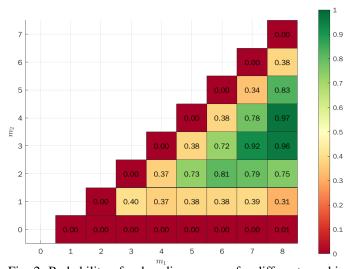


Fig. 2: Probability of a decoding success for different combinations of m_1 and m_2 for n = 32, d = 13, and t = 10. We consider a decoding success as the case that the transmitted codeword is in the list $\hat{\mathcal{L}}$.

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Appendix

Here we provide the detailed algorithms that are introduced in Section III-A.

Algorithm 2: List Decoder of 2-Interleaved Binary Alternant Codes (Initialization)

Input: Δ , k_{GRS} , $\mathcal{G}^{(0)} = \left\{ G_k^{(0)} = 0 \right\}_{k=1}^l$ 1 Init: $\mu \leftarrow \left\lceil \frac{\Delta}{k_{\text{GRS}} - 1} \right\rceil$, $l \leftarrow \frac{\mu(\mu+1)}{2}$ 2 for i := 0 to $\mu - 1$ do 3 | for j := 0 to $\mu - i - 1$ do 4 | $G_{(i-1)\mu - \frac{i(i+1)}{2} + j + 1}^{(0)} \leftarrow Y^i Z^j$ 5 | end 6 end Output: $\mathcal{G}^{(0)} = \left\{ G_k^{(0)} \right\}_{k=1}^l$

Algorithm 3: List Decoder of 2-Interleaved Binary Alternant Codes (Interpolation)

```
Input: \boldsymbol{\mathcal{G}}^{(0)} = \left\{ G_k^{(0)} \right\}_{k=1}^l, m_1, m_2, \boldsymbol{\mathcal{P}}
  1 Init: i = 1
  2 for (x_s, y_s, z_s) \in \mathcal{P} do
              for (\gamma_1,\gamma_2) \in (\mathbb{F}_2,\mathbb{F}_2) do
  3
                      if \gamma_1 = y_s \land \gamma_2 = z_s then
  4
                              for a := 0 to m_1 - 1 do
  5
                                      for b := 0 to m_1 - a - 1 do
   6
                                               for c := 0 to m_1 - a - b - 1 do
   7
                                                      for j := 1 to l do
   8
                                                              g_{j,p,q,r}^{(i-1)} \leftarrow \text{coefficient of the term } X^p Y^q Z^r \text{ in } G_j^{(i-1)}(X,Y,Z) \text{ as defined in Definition 7}
\delta_j \leftarrow \sum_{p=a} \sum_{q=b} \sum_{r=c} {p \choose a} {d \choose b} {r \choose c} g_{j,p,q,r}^{(i-1)} x_s^{p-a} (\gamma_1 \beta_j^{-1})^{q-b} (\gamma_2 \beta_j^{-1})^{r-c}
   9
  10
                                                       end
 11
                                                       j' \leftarrow j: The least weighted degree polynomial G_i^{(i-1)} s.t. \delta_i \neq 0
 12
                                                      Continue if \delta_j = 0, \forall j \in [1, l]

for j := 1 to l except j' do

\begin{vmatrix} G_j^{(i)}(X, Y, Z) \leftarrow G_j^{(i-1)}(X, Y, Z) - \frac{\delta_j}{\delta_{j'}} & G_{j'}^{(i-1)}(X, Y, Z) \end{vmatrix}
 13
 14
  15
                                                       end
 16
                                                      G_{j'}^{(i)}(X,Y,Z) \leftarrow (X-x_s) \ G_{j'}^{(i-1)}(X,Y,Z)
i \leftarrow i+1
 17
 18
                                               end
 19
                                       end
 20
                              end
 21
22
                       else
                               for a := 0 to m_2 - 1 do
 23
                                       for b := 0 to m_2 - a - 1 do
 24
                                               for c := 0 to m_2 - a - b - 1 do
 25
                                                      for j := 1 to l do
 26
                                                              g_{j,p,q,r}^{(i-1)} \leftarrow \text{coefficient of the term } X^p Y^q Z^r \text{ in } G_j^{(i-1)}\left(X,Y,Z\right) \text{ as defined in Definition 7}
\delta_j \leftarrow \sum_{p=a} \sum_{q=b} \sum_{r=c} {p \choose a} {q \choose b} {r \choose c} g_{j,p,q,r}^{(i-1)} x_s^{p-a} \left(\gamma_1 \beta_j^{-1}\right)^{q-b} \left(\gamma_2 \beta_j^{-1}\right)^{r-c}
 27
  28
                                                       end
 29
                                                      j' \leftarrow j : The least weighted degree polynomial G_i^{(i-1)} \operatorname{s.t.} \delta_j \neq 0
 30
                                                      Continue if \delta_j = 0, \forall j \in [1, l]

for j := 1 to l except j' do

\begin{vmatrix} G_j^{(i)}(X, Y, Z) \leftarrow G_j^{(i-1)}(X, Y, Z) - \frac{\delta_j}{\delta_{j'}} G_{j'}^{(i-1)}(X, Y, Z) \end{vmatrix}
 31
 32
 33
                                                      \begin{array}{l} \begin{array}{c} G_{j'}^{(i)}\left(X,Y,Z\right)\leftarrow\left(X-x_{s}\right) \ G_{j'}^{(i-1)}\left(X,Y,Z\right)\\ i\leftarrow i+1 \end{array}
 34
 35
 36
                                               end
 37
                                       end
 38
                              end
 39
                      end
 40
41
               end
42 end
43 \mathcal{G} = \left\{ G_k^{(i)} \right\}_{k=1}^l = \left\{ G_k \left( X, Y, Z \right) \right\}_{k=1}^l

44 Sort \mathcal{G} in the ascending order of weighted degree
       Output: G
```

Algorithm 4: List Decoder of 2-Interleaved Binary Alternant Codes (Recovery)

Input: $\mathcal{G} = \{G_k(X, Y, Z)\}_{k=1}^l$ 1 $Q(X, Y, Z) \leftarrow G_1(X, Y, Z)$ 2 for i := 2 to l do $P(X,Y,Z) \leftarrow G_i(X,Y,Z)$ 3 $\Phi\left(X,Y,Z\right) \leftarrow \gcd\left(Q\left(X,Y,Z\right),P\left(X,Y,Z\right)\right)$ 4 if $\deg_{Y}(\Phi(X,Y,Z)) = 0 \land \deg_{Z}(\Phi(X,Y,Z)) = 0$ then 5 $H_Z(X,Y) \leftarrow \text{Resultant} (Q(X,Y,Z), P(X,Y,Z) ; Z)$ 6 $\mathcal{F}_{1} \leftarrow \text{factorize } H_{Z}(X,Y)$ 7 for $F_1(X,Y)$ in \mathcal{F}_1 do 8 if $\deg_{\mathbf{Y}}(F_1(X,Y)) = 1 \land \deg_{\mathbf{X}}(F_1(X,Y)) < k_{GRS}$ then 9 $H_Y(X,Z) \leftarrow \text{Resultant} (Q(X,Y,Z), P(X,Y,Z); Y)$ 10 $\mathcal{F}_{2} \leftarrow \text{factorize } H_{Y}(X, Z)$ 11 for $F_2(X,Z)$ in \mathcal{F}_2 do 12 if $\deg_Z (F_2(X,Z)) = 1 \land \deg_X (F_2(X,Z)) < k_{GRS}$ then 13 $f(X) \leftarrow F_1(X, Y) - Y$ 14 $g(X) \leftarrow F_2(X,Z) - Z$ 15 Append (f(X), g(X)) to the returned list $\hat{\mathcal{L}}$ 16 end 17 end 18 19 end 20 end 21 break 22 else $U(X, Y, Z) \leftarrow \frac{Q(X, Y, Z)}{\Phi(X, Y, Z)}$ $V(X, Y, Z) \leftarrow \frac{P(X, Y, Z)}{\Phi(X, Y, Z)}$ 23 24 $H_Z(X,Y) \leftarrow \text{Resultant} (U(X,Y,Z),V(X,Y,Z);Z)$ 25 $\mathcal{F}_{1} \leftarrow \text{factorize } H_{Z}(X,Y)$ 26 for $F_1(X,Y)$ in \mathcal{F}_1 do 27 if $\deg_{Y}(F_{1}(X,Y)) = 1 \land \deg_{X}(F_{1}(X,Y)) < k_{GRS}$ then 28 $H_Y(X,Z) \leftarrow \text{Resultant} \left(U(X,Y,Z), V(X,Y,Z); Y\right)$ 29 $\mathcal{F}_{2} \leftarrow \text{factorize } H_{Y}(X, Z)$ 30 for $F_2(X,Z)$ in \mathcal{F}_2 do 31 if $\deg_{\mathbb{Z}}(F_2(X, Z)) = 1 \land \deg_{\mathbb{X}}(F_2(X, Z)) < k_{\text{GRS}}$ then 32 $f(X) \leftarrow F_1(X, Y) - Y$ 33 $g(X) \leftarrow F_2(X,Z) - Z$ 34 Append (f(X), g(X)) to the returned list $\hat{\mathcal{L}}$ 35 end 36 end 37 end 38 end 39 end 40 $Q(X,Y,Z) \leftarrow \Phi(X,Y,Z)$ 41 if i == l then 42 Return decoding failure 43 end 44 45 end 46 $\hat{\Delta} \leftarrow \deg_{\boldsymbol{w}} G_i(X, Y, Z)$ 47 $\hat{\tau} \leftarrow \frac{n - \hat{\Delta}/m_1}{1 - m_2/m_1}$ 48 Return $\hat{\tau}, \mathcal{L}$ Output: $\hat{\tau}, \hat{\mathcal{L}}$