RESEARCH ARTICLE

Lord Kelvin's method of images in semigroup theory

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Abstract We show that Lord Kelvin's method of images is a way to prove generation theorems for semigroups of operators. To this end we exhibit three examples: a more direct semigroup-theoretic treatment of abstract delay differential equations, a new derivation of the form of the McKendrick semigroup, and a generation theorem for a semigroup describing kinase activity in the recent model of Kaźmierczak and Lipniacki (J. Theor. Biol. 259:291–296, 2009).

Keywords Abstract delay differential equations \cdot Kinase activity \cdot Signaling pathways \cdot Bessel process \cdot Boundary condition \cdot McKendrick equation \cdot Method of images

1 The general idea

Lord Kelvin's method of images is an ingenious way of solving problems involving boundary conditions, see e.g. [4, 7, 11, 14, 18, 19, 24] and references given there. The idea of employing the method to prove generation theorems for semigroups of operators goes apparently back to W. Feller who constructed the semigroup of the minimal (and the reflected) Brownian motion on \mathbb{R}^+ by noting that the space of odd (even) functions is left invariant by the semigroup of the unrestricted Brownian motion on \mathbb{R} , see [12], pp. 341–343, comp. [3]. These semigroups are generated by the one-dimensional Laplacian with Dirichlet and Neumann boundary conditions at the origin, respectively. A question whether a similar construction can be carried out also in the case of more general boundary conditions, seems to have been opened for

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decades. The method of images hinges on constructing an extension of a function $f \in C[0, \infty]$ to the whole of \mathbb{R} in such a way that the subspace of extensions of all $f \in C[0, \infty]$ is invariant for the unrestricted Brownian motion semigroup, but it has been unclear how this extension should be derived from the given boundary condition. Recently, in [6] the problem was implicitly solved in the case of Robin boundary condition, corresponding to the elastic Brownian motion [16, 20]. In [2], we show how to construct such extensions for general boundary conditions discussed in [20]. This note is devoted to further examples of an application of the method in the theory of semigroups of operators. These include a more direct semigroup-theoretic treatment of abstract delay differential equations [9], a simplified derivation of the form of the McKendrick semigroup [26], and the generation theorem for a semigroup describing kinase activity in the recent model of Kaźmierczak and Lipniacki [17]. For an alternative way of dealing with boundary conditions in semigroup theory see [13].

A proper context for the method of images in the theory of semigroups is provided by the notion of a similar semigroup [9] (or: isomorphic semigroup [3]). To recall, given two strongly continuous semigroups $\{e^{tA}, t \ge 0\}$ and $\{e^{tG}, t \ge 0\}$ in Banach spaces X and B, respectively, we say that they are similar or isomorphic if there exists an isomorphism $I : X \to B$ such that $e^{tA} = I^{-1}e^{tG}I$, $t \ge 0$. Then, the generators A and G are related by

$$D(A) = \{x \in \mathbb{X}; Ix \in D(G)\}, \qquad Ax = I^{-1}GIx.$$
(1.1)

A particular case of this situation is as follows. Suppose that \mathbb{Y} is a Banach space, Λ is a subset of \mathbb{R} , \mathbb{X} is a space of \mathbb{Y} -valued functions on Λ , and we are interested in proving that a certain operator A in \mathbb{X} is the generator of a strongly continuous semigroup. Assume also that there exists $\Lambda \subset \Lambda' \subset \mathbb{R}$ and a strongly continuous semigroup { $T(t), t \ge 0$ } of operators in a space \mathbb{B}_0 of \mathbb{Y} -valued functions on Λ' , generated by an operator G_0 resembling A. Usually, A is " G_0 with a boundary condition". One way to approach such a problem is extending functions in \mathbb{X} to functions in \mathbb{B}_0 so that the set of these extensions is an invariant subspace $\mathbb{B} \subset \mathbb{B}_0$ for { $T(t), t \ge 0$ }. Then, the part G of G_0 in \mathbb{B} is the generator of { $T(t)_{|\mathbb{B}}, t \ge 0$ }. Moreover, quite often, \mathbb{X} and \mathbb{B} are then isomorphic with natural isomorphism I mapping a function on Λ to its extension to Λ' , and $R := I^{-1}$ mapping a function on Λ' to its restriction on Λ . Then, there exists the semigroup in \mathbb{X} that is similar to { $e^{tG}, t \ge 0$ }. Hence, to show that A is the generator, it suffices to show (1.1). Then, as a bonus, we obtain the explicit form of e^{tA} , referred to as the *abstract Kelvin formula*:

$$e^{tA}f = Re^{tG}If, \quad f \in \mathbb{X}, \ t \ge 0.$$
(1.2)

The non-trivial part in the procedure described above is finding the way of extending functions on Λ to functions on Λ' so that all the remaining steps are valid. To explain the idea of deriving formulae for such extensions, let us recall that any strongly continuous semigroup leaves the domain of its generator invariant. Hence, if members f of D(A) are characterized by a functional equation (a boundary condition), say F(f) = 0, then we must have $F(Re^{tG}If) = 0, t \ge 0$. This, when coupled with $(If)_{|\Lambda} = f$, often determines $If, f \in D(A)$, and, by density of D(A), all If; see [2] and the examples that follow. As we will see, the method of images often leads to the most natural approach to the generation problem.

2 Delay differential equations

The monograph [9], pp. 420–422 presents the following construction of a fundamental semigroup related to an abstract delay differential equation. Let *B* be the generator of a semigroup $\{e^{tB}, t \ge 0\}$ in a Banach space \mathbb{Y} and, for a given r > 0, let $\mathbb{X} = C([-r, 0], \mathbb{Y})$. Also, let $\Phi \in \mathcal{L}(\mathbb{X}, \mathbb{Y})$ be an abstract delay operator. The key Theorem 6.1 in [9], states that the operator Af = f' with domain $\mathcal{D}(A) = \{f \in C^1([-r, 0], \mathbb{Y}); f(0) \in D(B), f'(0) = B[f(0)] + \Phi f\}$ is the generator of a strongly continuous semigroup in \mathbb{X} . The proof is carried in two steps. In the first step, it is shown that for $\Phi = 0$, the semigroup generated by *A* is given by the formula:

$$(e^{tA}f)(s) = \begin{cases} f(t+s), & t+s \le 0, \\ e^{(t+s)B}[f(0)], & t+s \ge 0. \end{cases}$$
(2.1)

Then, it is shown that the general case may be obtained by the Desch-Schappacher perturbation theorem.

We will prove that the method of images allows obtaining this result directly. To this end, for $\omega \ge 0$, let \mathbb{X}_{ω} be the space of continuous \mathbb{Y} -valued functions g on $[-r, \infty)$ such that $||g|| := \sup_{t \ge -r} e^{-\omega t} ||g(t)|| < \infty$. $(\mathbb{X}_{\omega}, ||| \cdot ||)$ is a Banach space. In the procedure described in Sect. 1, this space will play the role of \mathbb{B}_0 (for large ω). The formula

$$T(t)g(s) = g(s+t),$$

defines a strongly continuous semigroup T in \mathbb{X}_{ω} . Its infinitesimal generator is $G_0g = g'$ with domain composed of differentiable $g \in \mathbb{X}_{\omega}$ with $g' \in \mathbb{X}_{\omega}$.

As explained in Sect. 1, if the abstract Kelvin formula (1.2) is to hold, the extension g := If of $f \in D(A)$ must be chosen so that $RT(t)g \in D(A), t \ge 0$. In other words, g must be differentiable with

$$g'(t) = B[g(t)] + \Phi RT(t)g, \quad t \ge 0.$$
(2.2)

This suggests that g := If, $f \in \mathbb{X}$ be defined as a mild solution to (2.2): a continuous function g will be termed the Φ -*extension of* $f \in \mathbb{X}$ iff

$$Rg = f$$
 and $g(t) = e^{tB}[f(0)] + \int_0^t e^{(t-s)B} \Phi RT(s)g \, ds, \quad t \ge 0.$ (2.3)

Certainly, (2.2) is the very delay differential equation we want to deal with via semigroup generated by A. Interestingly, but not surprisingly, the method of images recovers (2.2) from the boundary condition characterizing D(A).

The appropriate existence and uniqueness result for Φ -extensions is contained in the following lemma.

Lemma 2.1

(a) For $f \in \mathbb{X}$, the Φ -extension exists and is unique.

- (b) If g is the Φ -extension of $f \in \mathbb{X}$, then T(t)g is the Φ -extension of $RT(t)g, t \ge 0$.
- (c) There is $\omega_0 \ge 0$ such that for all $\omega \ge \omega_0$, $g \in \mathbb{X}_{\omega}$ for all $f \in \mathbb{X}$.

Proof Without loss of generality, we assume $M := \sup_{t>0} \|e^{tB}\| < \infty$.

(a) Let $\Delta = \frac{3}{4M\|\Phi\|}$ and for fixed $f \in \mathbb{X}$, let \mathbb{Z} be the complete metric space of functions g in $C([-r, \Delta], \mathbb{Y})$ such that Rg = f; the metric here is $d(g_1, g_2) =$ $\sup_{t \in [0, \Delta]} \|g_1(t) - g_2(t)\|$. Let us consider $U : \mathbb{Z} \to \mathbb{Z}$ given by $Ug(t) = e^{tB}[f(0)] + \int_0^t e^{(t-s)B} \Phi RT(s)g \, ds$. (For $s \in [0, \Delta], T(s)g(u), u \in [-r, 0]$ is well-defined.) We have

$$d(Ug_1, Ug_2) = \sup_{t \in [0, \Delta]} \| \int_0^t e^{(t-s)B} \Phi RT(s)[g_1 - g_2] ds \le \Delta \|\Phi\| M \le \frac{3}{4} d(g_1, g_2).$$

Hence, by the Banach fixed point theorem [8], there exists a unique fixed point g of U, solving (2.3) for $t \in [0, \Delta]$. An analogous argument shows that if the extension g is defined on $[-r, n\Delta]$, then it may be continued to $[-r, (n+1)\Delta]$. Hence, g may be defined in a unique way for all $t \ge 0$.

(b) We check that

$$g(t+u) = e^{uB}[g(t)] + \int_0^u e^{(u-s)B} \Phi RT(s)[T(t)g] ds, \quad u, t \ge 0.$$
(2.4)

By uniqueness of Φ -extensions, this shows (b).

(c) By (b), the map $f \mapsto RT(t)g$ is a strongly continuous semigroup in \mathbb{X} . Hence, there exists $\omega \ge 0$ and $M_1 \ge 1$ such that $||g(t)||_{\mathbb{Y}} \le ||RT(t)g||_{\mathbb{X}} \le M_1 e^{\omega t} ||f||_{\mathbb{X}}, t \ge 0$, $f \in \mathbb{X}$. This implies $g \in \mathbb{X}_{\omega}$.

Theorem 2.2 A is the generator of a strongly continuous semigroup in X. Moreover, the abstract Kelvin formula

$$e^{tA}f(s) = g(s+t), \quad f \in \mathbb{X}, \ t \ge 0, \ s \in [-r, 0]$$
 (2.5)

holds with g being the Φ -extension of f.

Proof Let ω be as in Lemma 2.1. By the Closed Graph Theorem, *I* mapping $f \in \mathbb{X}$ to its Φ -extension is continuous. Since *I* has a continuous inverse *R*, the range \mathbb{B} of *I* is a closed linear subspace of \mathbb{X}_{ω} . By Lemma 2.1(b), \mathbb{B} is invariant for *T*.

We need to show that (1.1) holds with *G* being the part of G_0 in \mathbb{B} . It suffices to show that D(A) is the set of functions $f \in \mathbb{X}$ whose Φ -extensions *g* are differentiable with $g' \in \mathbb{B}$. If such an extension exists, by (2.3), $f(0) \in D(B)$, the right-hand derivative $g'_+(0)$ of *g* at 0 equals $B[f(0)] + \Phi f$, and *f* is continuously differentiable in $t \in [-r, 0]$ with $f'(0) = g'_+(0) = B[f(0)] + \Phi f$, proving that $f \in D(A)$. Conversely, let $f \in D(A)$ and, given $\lambda > \omega$, let $h := \lambda f - f' \in \mathbb{X}$. Since $\|e^{tG}\| \le e^{\omega t}$, there exists $g \in D(G)$ such that $R(\lambda g - Gg) = h$. Thus, $\lambda f(s) - f'(s) = \lambda g(s) - g'(s)$, $s \in [-r, 0]$, implying Rg = f. By the uniqueness of Φ -extensions, we are done. \Box

Remark 2.3 For $\Phi = 0$, the Φ -extensions satisfy $g(t) = e^{tB}[f(0)], t \ge 0$. Hence, (2.1) is a particular case of (2.5). Moreover, with (2.5) at hand, Lemmas 6.2 and 6.5 in [9] are immediate, and the whole analysis presented in Sects. VI 6, a–b of the monograph greatly simplifies.

3 The McKendrick semigroup

Let $L^1(\mathbb{R}^+)$ be the space of Lebesgue integrable functions on \mathbb{R}^+ with the norm $\|\phi\|_{L^1(\mathbb{R}^+)} = \int_{\mathbb{R}^+} |\phi(a)| \, da$ and let $e_{\omega}(a) = e^{-\omega a}$ (this function will be treated both as a function on \mathbb{R} and as its restriction to \mathbb{R}^+). Furthermore, let $L^1_{\omega}(\mathbb{R}^+)$ be the space of (classes of) measurable functions ϕ on \mathbb{R}^+ such that $e_{\omega}\phi \in L^1(\mathbb{R}^+)$ with the norm $\|\phi\|_{L^1_{\omega}(\mathbb{R}^+)} = \|e_{\omega}\phi\|_{L^1(\mathbb{R}^+)}$, and $L^1_{\omega}(\mathbb{R})$ be the space of (classes of) measurable functions φ on \mathbb{R} that $\|\varphi\|_{L^1_{\omega}(\mathbb{R})} := \int_{\mathbb{R}} (e^{\omega a} \wedge 1)|\varphi(a)| \, da < \infty$. We note that $L^1_{\omega}(\mathbb{R})$ is isometrically isomorphic to $L^1(\mathbb{R}^+) \times L^1_{\omega}(\mathbb{R}^+)$ for the norm $\|(\phi, \psi)\|_{L^1(\mathbb{R}^+) \times L^1_{\omega}(\mathbb{R}^+)} = \|\phi\|_{L^1(\mathbb{R}^+)} + \|\psi\|_{L^1_{\omega}(\mathbb{R}^+)}$. The isomorphism is given by $J\varphi = (\phi, \psi), \phi \in L^1_{\omega}(\mathbb{R})$ where $\phi(a) = \varphi(a)$ and $\psi(a) = \varphi(-a), a \ge 0$.

Let *b* and μ be non-negative, bounded, measurable functions on \mathbb{R}^+ ; equivalently, we treat *b* and μ as functions on \mathbb{R} that vanish on the negative half-axis. Let *A* be an operator in $L^1(\mathbb{R}^+)$ given by $A\phi = -\phi' - \mu\phi$ with domain Ker *F* where *F* : $W^{1,1}(\mathbb{R}^+) \to \mathbb{R}$ is given by

$$F(\phi) = \phi(0) - \int_{\mathbb{R}^+} b(a)\phi(a) \,\mathrm{d}a$$

and $W^{1,1}$ is the Sobolev space of integrable, absolutely continuous functions with derivatives in $L^1(\mathbb{R}^+)$. The abstract Cauchy problem related to *A* is called the McKendrick equation [22] or Sharpe-Lotka-McKendrick equation [25, 26], or Lotka-McKendrick equation [15]. In the population dynamics interpretation of this problem, ϕ is an age-profile of an age-structured population with births and deaths governed by *b* and μ , respectively. For this reason, it is customary to write the argument of ϕ as *a*, '*a*' standing for 'age'.

To show that A generates a strongly continuous semigroup in $L^1(\mathbb{R}^+)$ we consider the operator G_0 in $L^1_{\omega}(\mathbb{R})$ defined by

$$D(G_0) = W^{1,1}_{\omega}(\mathbb{R}), \qquad G_0 \phi = -\phi - \mu \phi,$$

where $W^{1,1}_{\omega}$ is the Sobolev-type space of absolutely continuous members of $L^1_{\omega}(\mathbb{R})$ with derivatives in $L^1_{\omega}(\mathbb{R})$; recall that $\mu(a) = 0$ for a < 0. G_0 generates the strongly continuous semigroup in $L^1_{\omega}(\mathbb{R})$ given by

$$T(t)\phi(a) = e^{-\int_{a-t}^{a} \mu(r) \, dr} \phi(a-t), \qquad (3.1)$$

and we have $||T(t)||_{\mathcal{L}(L^1_{\omega}(\mathbb{R}))} \leq e^{\omega t}, t \geq 0.$

We proceed as in Sect. 1, to find an extension $\varphi \in L^1_{\omega}(\mathbb{R})$ of $\phi \in L^1(\mathbb{R}^+)$. To this end, it suffices to find $\psi \in L^1_{\omega}(\mathbb{R}^+)$ related to φ via $\psi(t) = \varphi(-t), t \ge 0$. For $\phi \in D(A)$, we must have $F(T(t)\varphi) = 0$, or $\varphi(-t) = \int_0^\infty e^{-\int_{a-t}^a \mu(r) dr} \varphi(a-t) b(a) da, t \ge 0$. Hence, ψ must satisfy

$$\psi = \psi * b_{\mu} + C\phi, \qquad (3.2)$$

where $C\phi(t) := \int_t^\infty e^{-\int_{a-t}^a \mu(r) dr} \phi(a-t)b(a) da$, $b_\mu(a) = e^{-\int_0^a \mu(r) dr} b(a)$, $a \ge 0$ and * denotes convolution. Note that b_μ is bounded, b being bounded.

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Lemma 3.1

- (a) For φ ∈ L¹(ℝ⁺), ||Cφ||_{L¹_ω(ℝ⁺)} ≤ ||φ||_{L¹(ℝ⁺)} ||b||_∞/ω.
 (b) Let ω > ||b_μ||_∞ := sup_{a>0} |b_μ(a)|. For φ ∈ L¹(ℝ⁺), there exist unique ψ ∈ $L^1_{\omega}(\mathbb{R}^+)$ solving (3.2).
- (c) For $\phi \in \text{Ker } F$ there exists unique $\varphi \in L^1_{\omega}(\mathbb{R})$ such that for all $t \ge 0, T(t)\varphi \in$ Ker F and $\varphi_{\mathbb{R}^+} = \phi$. Here, we treat F as a functional on $W^{1,1}_{\omega}(\mathbb{R})$; in particular $T(t)\varphi \in W^{1,1}_{\omega}(\mathbb{R}).$

Proof (a) Follows by a straightforward calculation. In particular C is a bounded operator $C: L^1(\mathbb{R}^+) \to L^1_{\omega}(\mathbb{R}^+).$

(b) The norm of the map $L^1_{\omega}(\mathbb{R}^+) \ni \psi \mapsto \psi * b_{\mu} \in L^1_{\omega}(\mathbb{R}^+)$ does not exceed $\frac{\|b_{\mu}\|_{\infty}}{\omega} < 1. \text{ Hence, the only solution to (3.2) is } \psi = \sum_{n \ge 0} b_{\mu}^{n*} * C\phi.$ (c) If ϕ is absolutely continuous, so is $C\phi$ with $(C\phi)' = -\phi(0)b_{\mu} - \kappa$ where

 $\kappa(t) = \int_0^\infty [\mu(a)\phi(a) + \phi'(a)] e^{-\int_a^{a+t} \mu(r) dr} b(a+t) da$. Since b_μ and κ are bounded $(C\phi)'$ belongs to $L^1_{\omega}(\mathbb{R}^+)$. Therefore, ψ is absolutely continuous with ψ' equal to $\sum_{n\geq 0} b_{\mu}^{n*} * (C\phi)' + \phi(0) \sum_{n\geq 0} b_{\mu}^{n*} \in L^{1}_{\omega}(\mathbb{R}^{+})$, because $\sum_{n\geq 0} b_{\mu}^{n*}$ converges in $L^{1}_{\omega}(\mathbb{R}^{+})$. Since for $\phi \in \operatorname{Ker} F$, $\phi(0) = \int_{\mathbb{R}^{+}} \phi(a)b(a) \, da = \psi(0)$, we have $\varphi \in C^{-1}$ $W^{1,1}_{\omega}(\mathbb{R})$, and (3.2) forces $T(t)\varphi \in \text{Ker } F$. \square

For $\phi \in L^1(\mathbb{R}^+)$, the $\varphi \in L^1_{\omega}(\mathbb{R})$ defined by $\varphi(a) = \phi(a), \varphi(-a) = \psi(a), a \ge 0$ where ψ solves (3.2), will be referred to as the (b, μ) -extension of ϕ .

Theorem 3.2 A is the generator of a strongly continuous semigroup in $L^1(\mathbb{R}^+)$. Furthermore,

$$e^{tA}\phi(a) = T(t)\varphi(a) = e^{-\int_{a-t}^{a} \mu(r) dr}\varphi(a-t), \quad a, t \ge 0,$$
 (3.3)

where φ is the (b, μ) -extension of ϕ .

Proof Let \mathbb{B} be the space of (b, μ) -extensions of members of $L^1(\mathbb{R}^+)$. By Lemma 3.1 (b), $\mathbb{B} \subset L^1_{\omega}(\mathbb{R})$ for sufficiently large ω . As in Theorem 2.2, we show that \mathbb{B} is closed. Fix $s \ge 0$ and $\phi \in D(A) = \text{Ker } F$. By Lemma 3.1 (c), $T(t+s)\varphi \in \text{Ker } F$, $t \ge 0$. Thus, by uniqueness of (b, μ) -extensions $T(s)\varphi$ is the (b, μ) -extension of $[T(s)\varphi]_{\mathbb{R}^+} \in$ $L^1(\mathbb{R}^+)$. Hence, the image of D(A) = Ker F is invariant for T and so is \mathbb{B} , the image of D(A) being dense in \mathbb{B} .

Let G be the part of G_0 in \mathbb{B} and let $\varphi \in D(G)$. Then, $\phi := \varphi_{\mathbb{R}^+} \in L^1(\mathbb{R}^+)$ is absolutely continuous with $\phi' \in L^1(\mathbb{R}^+)$ and, by (3.2), $\phi(0) = \psi(0) = \int_{\mathbb{R}^+} \phi(a)b(a) da$, proving that $\phi \in D(A)$. Conversely, if $\phi \in D(A)$, then, by Lemma 3.1 (c), its (b, μ) extension belongs to $W^{1,1}_{\omega}(\mathbb{R})$. This shows (1.1).

Remark 3.3 A semigroup-theoretical treatment of the McKendrick equation usually involves some kind of perturbation argument, see [5], pp. 241–244 or [10], pp. 216–219. Our method and formula (3.3) are worth comparing with the remark on the bottom of the page 244 in [5], pp. 8–12 and formula (3.3) in [15], or pp. 138–151

in [21]. In fact, a natural, intuitive way of solving the McKendrick equation is by solving a renewal equation for the total birth rate, which is equivalent to (3.2). Interestingly, the method of images leads to (3.2) without appealing to population dynamics intuitions.

4 A Bessel process with mass inflow

Let $\mathbb{X} = C[0, 1]$ be the space of real continuous functions on [0, 1] and let $h(x) := x, x \in [0, 1]$. Let D(A) be composed of functions f such that (a) hf is twice continuously differentiable for $x \in (0, 1]$ and $\frac{1}{2h}(hf)''$ may be extended to a continuous function on [0, 1], and (b) $f'(1) = \mu f(1)$, where $\mu > 0$ is a given constant. We will show that A given by $Af = \frac{1}{2h}(hf)''$ is the generator of a semigroup in \mathbb{X} .

The operator A is clearly akin to G_0 in $C[0, \infty]$ given by $G_0 f = \frac{1}{2h}(hf)''$ with domain composed of those $f \in C[0, \infty]$ for which hf is twice continuously differentiable with $\frac{1}{2h}(hf)''$ extendable to a function in $C[0, \infty]$; here $h(x) = x, x \in [0, \infty)$. G_0 generates the strongly continuous semigroup in $C[0, \infty]$ given by

$$T(t)f(x) = \begin{cases} \int_0^\infty \frac{y}{x} [q_t(x-y) - q_t(x+y)] f(y) \, \mathrm{d}y, & x > 0, \\ \frac{2}{t} \int_0^\infty q_t(y) y^2 f(y) \, \mathrm{d}y, & x = 0, \end{cases} \quad t > 0, \quad (4.1)$$

where $q_t(x) = \frac{1}{\sqrt{2\pi t}} e^{-\frac{x^2}{2t}}$. To show this, we note that the Laplace transform of the right-hand side of (4.1) equals, for $x > 0, \lambda > 0$,

$$g(x) := (\lambda - G_0^*)^{-1} f(x) = \frac{1}{x\sqrt{2\lambda}} \int_0^\infty [e^{-\sqrt{2\lambda}|x-y|} - e^{-\sqrt{2\lambda}(x+y)}] y f(y) \, \mathrm{d}y,$$

where, for the sake of the present argument, G_0^* denotes the generator of (4.1). Hence, a direct computation shows that $g \in D(G_0)$ and $\lambda g - G_0 g = f$, implying $G_0 g = G_0^* g$. Since $\lambda - G_0^*$ is injective with range equal to X, G_0 cannot be a proper extension of G_0 , proving the claim.

T given by (4.1) is the semigroup of the three dimensional Bessel process, a process whose realization is the modulus of the three dimensional Brownian motion. In other words,

$$T(t)f(x) = Ef(|x + w(t)|)$$
(4.2)

where $w(t), t \ge 0$ is a standard three-dimensional Brownian motion, $x \in \mathbb{R}$ is identified with $(x, 0, 0) \in \mathbb{R}^3$ and *E* stands for expectation, see [23], p. 251.

The operator A_1 given by $A_1 f = Af - f$, $f \in C[0, 1]$ appears implicitly in the recent model of kinase activity in a living cell [17]. In this model, the cell is viewed as a unit ball where the active kinase particles diffuse freely and may be randomly inactivated (hence the term -f in the definition of $A_1 f$). Since it is assumed that the active kinase concentration depends merely on the distance from the ball center, we are actually dealing with a 3 dimensional Bessel process (with killing). The inactive kinase particles perform a similar motion but, upon touching the boundary some of them are being activated. The boundary condition $f'(1) = \mu f(1)$ describes

the "inflow" [17] of activated kinase particles reflected from the boundary x = 1. For simplicity, we do not take into account the fact that the number of kinase particles (active and inactive) is limited. Neither do we take into account fluctuations of activity of surface receptors; the detailed semigroup-theoretic treatment of the complete model exceeds the scope of this article, and will be the subject of further research.

Let $\mathbb{X}_{\omega}, \omega > 0$ be the space of continuous functions f such that $e_{\omega} f \in C[0, \infty]$ (where $e_{\omega}(x) = e^{-\omega x}, x \ge 0$). For the norm $||f||_{\omega} = ||e_{\omega}f||_{C[0,\infty]}$, \mathbb{X}_{ω} is a Banach space. Our main result is:

Theorem 4.1 There is $\omega > 0$ such that for each $f \in \mathbb{X}$ there exists $g_{\mu} : \mathbb{R}^+ \to \mathbb{R}$ such that $(g_{\mu})_{\mid [0,1]} = f$, $hg_{\mu} \in \mathbb{X}_{\omega}$ and

$$S(t)f(x) = \begin{cases} \int_0^\infty \frac{y}{x} [q_t(x-y) - q_t(x+y)] g_\mu(y) \, \mathrm{d}y, & x > 0, \\ \frac{2}{t} \int_0^\infty q_t(y) y^2 g_\mu(y) \, \mathrm{d}y, & x = 0, \end{cases} \quad t > 0, \quad (4.3)$$

is a strongly continuous semigroup in \mathbb{X} with generator A.

Formula (4.3) may be equivalently expressed as (compare (4.2))

$$S(t)f(x) = Eg_{\mu}(|x + w(t)|), \quad x \in [0, 1].$$
(4.4)

Because of the relative complexity of (4.3), it is difficult to derive g_{μ} directly. However, in (4.9) and (4.10) we will express *S* in terms of the much simpler, *canonical cosine family*

$$C(t)f(x) = \frac{1}{2}[f(x+t) + f(x-t)], \quad x, t \in \mathbb{R},$$
(4.5)

in \mathbb{Z}_{ω} , the space of continuous functions f on \mathbb{R} such that both $f_{|\mathbb{R}^+}$ and $\mathbb{R}^+ \ni x \mapsto f(-x)$ belong to \mathbb{X}_{ω} ; the norm in \mathbb{Z}_{ω} is $||f|| = \sup_{x \in \mathbb{R}} e^{-|x|\omega|} |f(x)|$. Therefore, in Lemma 4.2, we define extensions of $f \in \mathbb{X}$ to $f_{\nu} \in \mathbb{Z}_{\omega}$ in such a way that the subspace of such extensions is invariant for C. Then, we define g_{μ} in terms of f_{ν} .

Lemma 4.2 Let $v := \mu + 1$ and F_v be the functional in \mathbb{Z}_ω given by F(f) = vf(1) - f'(1), with domain D(F) composed of continuously differentiable $f \in \mathbb{Z}_\omega$. There is $\omega > 0$ such that for continuously differentiable $f \in C_0(0, 1]$ with f'(1) = vf(1) there exists a unique $f_v \in \mathbb{Z}_\omega$ such that:

(a) $C(t) f_{\nu}$ is odd for $t \in \mathbb{R}$, (b) $C(t) f_{\nu} \in \text{Ker } F$ for $t \in \mathbb{R}$.

Proof Let $P \in \mathcal{L}(\mathbb{Z}_{\omega})$ be given by $Pf(x) = f(1-x), x \in \mathbb{R}$, and let $F_P := F \circ P$, whence $Ff = f'(0) + \nu f(0), f \in D(F_P) := D(F)$. By a straightforward generalization of Lemma 1 in [2], (b) holds iff $f_{\nu,P} := Pf_{\nu}$ satisfies

$$f_{\nu,P}(x) = f_{\nu,P}(-x) + 2\nu \int_0^{-x} e^{\nu(-x-y)} f_{\nu,P}(y) \, \mathrm{d}y, \quad x \le 0,$$

and this is true iff f_{ν} satisfies

$$f_{\nu}(x) = f_{\nu}(2-x) + 2\nu \int_{2-x}^{1} e^{\nu(x+y-2)} f_{\nu}(y) \, \mathrm{d}y, \quad x \ge 1.$$
(4.6)

Similarly, (a) holds iff f_{ν} is odd. Therefore, we define f_{ν} by induction: having defined it on $[-n, n+1], n \ge 0$ we put

$$f_{\nu}(x) = \begin{cases} f_{\nu}(-x), & x \in [-n-1, -n], \\ f_{\nu}(2-x) + 2\nu \int_{2-x}^{1} e^{\nu(x+y-2)} f_{\nu}(y) \, \mathrm{d}y, & x \in [n+1, n+2]. \end{cases}$$
(4.7)

(Compare pp. 117–119 in [6].) We note that these formulae are *local* in the sense that the definition of $f_{\nu}(x), x \in [-n - 1, -n]$ depends merely on $f_{\nu}(x), x \in [n, n + 1]$ and the definition of $f_{\nu}(x), x \in [n + 1, n + 2]$ depends merely on $f_{\nu}(x), x \in [-n, 1]$. Hence, f_{ν} is odd and (4.6) holds.

Formula (4.7) defines f_{ν} for all, not necessarily differentiable, $f \in C_0(0, 1]$. This, not necessarily differentiable, f_{ν} will be referred to as the (C, ν) -extension of f.

Fix $s \in \mathbb{R}$ and consider $C(s) f_{\nu}$ for a continuously differentiable f such that $f'(1) = \nu f(1)$. Then, by cosine functional equation, $C(t)C(s) f_{\nu}$ is odd and belongs to Ker F. Hence, by uniqueness of (C, ν) -extensions,

$$C(s) f_{\nu} \text{ is the } (C, \nu) \text{-extension of } [C(s) f_{\nu}]_{\mid [0,1]}.$$

$$(4.8)$$

Since such functions f are dense in \mathbb{X} , the same is true for all $f \in \mathbb{X}$. It follows that $C_0(t), t \in \mathbb{R}$ defined by $C_0(t)f = [C(t)f_v]_{|[0,1]}, f \in \mathbb{X}$ is a strongly continuous cosine family. Hence, there exist $M \ge 1, \omega_0 > 0$ such that $\|C_0(t)\|_{\mathcal{L}(\mathbb{X})} \le M e^{\omega_0 t}$.

Fix $t \ge \frac{3}{2}$, t = n + t' where $t' \in [\frac{1}{2}, \frac{3}{2}]$, $n \ge 1$. Then $|f_{\nu}(t) - f_{\nu}(t-1)| = |f_{\nu}(1/2 + s) + f_{\nu}(1/2 - s)| \le 2 \sup_{x \in [0,1]} |C(s) f_{\nu}(x)| \le 2Me^{\omega_0(t-\frac{1}{2})} ||f||_{\mathbb{X}} = Ke^{\omega_0 t}$ where s = t - 1/2 and K depends on f. Therefore,

$$\begin{split} |f_{\nu}(t)| &\leq |f_{\nu}(t-1)| + K e^{\omega_0 t} \leq |f_{\nu}(t-2)| + K e^{\omega_0 (t-1)} + K e^{\omega_0 t} \leq \cdots \\ &\leq |f_{\nu}(t')| + K e^{\omega_0 t} [e^{-\omega_0 (n-1)} + \cdots + 1] \\ &\leq \sup_{t \in [1/2, 3/2]} |f_{\nu}(t)| + \frac{K}{1 - e^{-\omega_0}} e^{\omega_0 t}, \quad t \geq 3/2. \end{split}$$

This implies $f_{\nu} \in \mathbb{Z}_{\omega}$ for $\omega > \omega_0$, f_{ν} being odd.

Proof of Theorem 4.1 Step 1. Let $\mathbb{Z}_{\omega,e} \subset \mathbb{Z}_{\omega}$ be the subspace of (C, ν) -extensions of elements of X. Using the Closed Graph Theorem, we check that the map $\mathbb{X} \ni f \mapsto f_{\nu} \in \mathbb{Z}_{\omega}$ is bounded. Hence, as before, we see that $\mathbb{Z}_{\omega,e}$ is isomorphic to X, and (4.8) shows that $\mathbb{Z}_{\omega,e}$ is invariant for *C*. The generator *B* of the canonical cosine family (4.5) restricted to $\mathbb{Z}_{\omega,e}$ is given by Bf = f'' and its domain D(B) is composed of twice continuously differentiable functions in $\mathbb{Z}_{\omega,e}$ with second derivative in $\mathbb{Z}_{\omega,e}$.

Let B_{ν} in $C_0(0, 1]$ be given by $B_{\nu} f = f''$ with domain composed of twice continuously differentiable functions on [0, 1] such that $f'(1) = \nu f(1)$. Using Lemma 4.2

and arguing as in Theorem 2.2, we see that D(B) is the set of (C, ν) -extensions of elements of $D(B_{\nu})$. Therefore, B_{ν} generates the cosine operator function in \mathbb{X} given by

$$C_{\nu}(t)f = C(t)f_{\nu}.$$

Step 2. By the Weierstrass formula ([1], (3.102)), the semigroup generated by $\frac{1}{2}B_{\nu}$ is given by

$$e^{\frac{1}{2}B_{\nu}t}f(x) = \sqrt{\frac{2}{\pi t}} \int_{0}^{\infty} e^{-\frac{s^{2}}{2t}} C(s) f_{\nu}(x) ds$$
$$= \frac{1}{\sqrt{2\pi t}} \int_{0}^{\infty} [e^{-\frac{(s-x)^{2}}{2t}} - e^{-\frac{(s+x)^{2}}{2t}}] f_{\nu}(s) ds \quad x \ge 0,$$
(4.9)

where we used the fact that f_{ν} is odd. Since for $f \in \mathbb{X}$, $hf \in C_0(0, 1]$ we may define

$$S(t)f(x) = \frac{1}{x}e^{\frac{1}{2}B_{\nu}t}(hf)(x)$$

= $\int_0^\infty \frac{1}{x}[q_t(s-x) - q_t(s+x)](hf)_{\nu}(s) \,\mathrm{d}s, \quad x \in (0,1].$ (4.10)

By Dominated Convergence Theorem, S(t) f may be extended to a continuous function on [0, 1] by setting $S(t) f(0) = \frac{2}{t} \int_0^\infty y q_t(y) (hf)_{\nu}(y) dy$. Then, (4.10) shows that *S* is a semigroup of operators in X. Using (4.4) and elementary properties of Brownian motion, we check that *S* is strongly continuous. Setting $g_{\mu}(x) = \frac{1}{v} (hf)_{\nu}(x), x > 1$, gives (4.3).

Let *G* be the generator of *S*. We are left with showing G = A. If $f \in D(G)$ and $Gf = \lim_{t\to 0+} \frac{1}{t}(S(t)f - f)$, then $hGf = \lim_{t\to 0+} \frac{1}{t}[e^{\frac{1}{2}B_{\nu}t}(hf) - hf]$. Hence, hf belongs to $D(B_{\nu})$ and $hGf = \frac{1}{2}B_{\nu}(hf)$. Therefore, hf is twice continuously differentiable and $(hf)'(1) = \nu(hf)(1)$. This implies $f \in D(A)$ and $Gf = \frac{1}{2h}(hf)'' = Af$. Since *G* is a generator, *A* cannot be a proper extension of *G*, completing the proof. \Box

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