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MEASUREMENTS OF VELOCITY COMPONENTS IN THE WAKE OF A FULL-SCALE HELICOPTER ROTOR IN HOVER

Donald W. Boatwright

Mississippi State University

Prepared for:

Army Air Mobility Research and Development Laboratory

August 1972

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By Donald W. Boatwright

August 1972

EUSTIS DIRECTORATE U. S. ARMY AIR MOBILITY RESEARCH AND DEVELOPMENT LABORATORY FORT EUSTIS, VIRGINIA

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This report has been reviewed by the Eustis Directorate, U. S. Army Air Mobility Research and Development Laboratory, and is considered to be technically sound. The report is published for the exchange of information and the stimulation of ideas. The program was conducted under the technical management of Mr. Frederick A. Raitch of the Aeromechanics Division of this Directorate.

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AASE Report No. 72-59

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Donald W. Boatwright

Prepared by

Raspet Flight Research Laboratory The Department of Aerophysics and Aerospace Engineering Mississippi State University State College, Mississippi

for

EUSTIS DIRECTORATE U. S. ARMY AIR MOBILITY RESEARCH AND DEVELOPMENT LABORATORY FORT EUSTIS, VIRGINIA

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ABSTRACT

This report presents three-component wake velocity measurements made with a split-film total vector anemometer. The measurements were made in the wake of a full-scale OH-13E helicopter rotor which was mounted on a 60foot rotor test tower at Mississippi State University. Time-averaged velocity distributions along wake radii at various distances below the rotor disk were measured for two conditions of disk loading and three combinations of blade pitch and rotor speed. Instantaneous velocity measurements were made across the helical vortex trails to investigate the effects of blade pitch and rotor speed on vortex structure, core size, transport velocity, and distribution of axial and tangential velocity components within the vortices. The results indicated that maximum values of induced velocity in the mean wake exceeded twice the magnitude of momentum values, and that instantaneous values of the vertical velocity component in the vicinity of the vortex trails could be as large as ten times the momentum value of induced velocity at high thrust coefficients. Velocity distributions across the tip vortices revealed longitudinal components of velocity of the same order of magnitude as the rotational components. Also, tip vortex structure and dissipation characteristics were found to be sin.lar to the vortices shed from fixed-wing aircraft. The effects of varying the test parameters were reflected as significant changes of the flow within the rotor tip vortex trails, and as smaller variations of the velocity components of the inner wake region.

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FOREWORD

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This investigation was sponsored by the Eustis Directorate, U. S. Army Air Mobility Research and Development Laboratory under Contract DAAJ02-67-C-0105, DA Task 1F162204A13903. This report presents the results of Phase III as outlined in the contract. The Phase III period of effort extended from September 1970 through September 1971.

The author wishes to acknowledge the work of Mr. John Owens, who designed and perfected the electronics of the rotor tower data acquisition system. Also, grateful acknowledgment is made of Mr. Stan Miley's work in data reduction and computer programming.

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LIST OF SYMBOLS

	0
C _Q	rotor torque coefficient; $C_Q = \frac{Q}{\rho \pi R^2 (\Omega R)^2 R}$
C _T	rotor thrust coefficient; $C_T = \frac{T}{\rho \pi R^2 (\Omega R)^2}$
d	axial distance along a helical vortex path measured from the blade tip, ft
n	number of rotor revolutions or events
Q	rotor torque, ft-lb
R	rotor radius, ft
r	radial spanwise distance from the hub, ft
r _c	vortex corc radius, ft
r _v	vortex radius, ft
Т	rotor thrust, 1b
v _R	instantaneous total velocity magnitude, ft/sec
ν̄ _R	mean value of total velocity magnitude, ft/sec
v _a	vortex velocity measured parallel to y axis, ft/sec
v _t	vortex velocity in the xz plane, ft/sec
^v x, ^v y, ^v z	local instantaneous velocity components, ft/sec
\bar{v}_x , \bar{v}_y , \bar{v}_z	mean values of instantaneous velocity components, ft/sec
х, у, г	fixed axes of rotor tower coordinate system
x', y', z'	axes of probe sensor coordinate system
3	angle between mean and instantaneous resultant velocity vector, deg or rad
[©] 75	blade collective pitch at three-quarter span station, deg or rad
vo	absolute value of momentum induced velocity; $v_0 = \Omega R \frac{C_T}{2}$, ft/sec
ρ	air density, lb-sec ² /ft ⁴

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- $\label{eq:vr} {}^{\sigma} v_{\rm R} / {}^{\nu}{}_{\rm o} \qquad \begin{array}{l} {\rm standard\ deviation\ between\ instantaneous\ and\ mean\ resultant\ velocity\ magnitude} \\ {}^{\sigma}{}_{\rm c} \qquad {} {\rm standard\ deviation\ of\ the\ angle\ between\ instantaneous\ and\ mean\ resultant\ velocity\ vectors,\ deg\ or\ rad} \end{array}$
- ϕ_A, ϕ_B, ϕ_C angles between the resultant velocity vector and the perpendicular to anemometer probe sensors, deg or rad
- ψ blade azimuth angle measured counterclockwise from x axis, deg or rad

\$\$\$ rotor angular velocity, rad/sec

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INTRODUCTION

Theoretical methods of predicting rotor performance require detailed knowledge of the characteristics of the rotor wake so that mathematical models of the wake can be formulated. While partial wake characteristics can generally be obtained through flow visualization techniques, these techniques are insufficient to adequately describe the relationships between the inner shed vortex sheets and the trailing tip vortices. Also, flow visualization techniques are difficult to apply to full-scale rotors. While numerous model test programs have been conducted in the past few years which have depended primarily on flow visualization for description of the wake, the requirement for detailed information not available through flow visualization remains, particularly for full-scale rotors.

Some attempts have been made in the past to use hot-wire or hot-film anemometry as a method of providing supplementary information to that obtained through flow visualization. However, until the recent development of the three-dimensional probe, only partial information could be obtained with the single and x-array systems that were available. Furthermore, hot wires have proved to be difficult to use because of their delicacy and the constant threat of contamination of the sensor elements when exposed to an environment such as that in a rotor wake. As a result, past efforts to measure the rotor wake with hot-wire or hot-film anemometry have not been extensive, and have failed to provide true threedimensional wake data.

Because of the need for full-scale, experimental wake data, and due to recent development of the "total vector" or three-dimensional anementer, a test program was conducted at Mississippi State University to measure the flow field velocity distributions of a rotor in the hover configuration. It was originally planned that velocity components would be measured using a dozen or more of the total vector probes to obtain instantaneous velocity distribution along specific wake radii; however, because of funding limitations, only a single probe system could be obtained for these initial tests. As a result, it was necessary to sample the data at each station for a number of revolutions of the rotor, and to present the results in terms of the mean distributions of velocity at specific azimuth positions of the rotor blades. The single probe did permit an examination of the local instantaneous flow variations, however, and proved to be particularly useful for this purpose in the region of the tip vortices.

This project was initiated in September, 1970, with wake measurement tests being conducted from April through August, 1971. The measurements were made by utilizing an OH-13E engine and main rotor assembly which was installed on the full-scale rotor test tower at Mississippi State University. Objectives of the wake measurement tests were as follows:

1. To obtain the mean distributions of velocity components in the wake of the OH-13E rotor installation with the rotor operating

at selected values of the tip speed and collective pitch.

- 2. To examine the structure of the rotor tip vortices from measurements of velocity distribution across the helical vortex trails.
- 3. To determine the time-dependent positions, transport velocities, and dissipation characteristics of the rotor tip vortices with distance below the rotor disk.
- 4. To evaluate the total vector anemometer and rotor tower instrumentation systems.

Test data were acquired by traversing the total vector probe along an instrumentation boom which extended radially into the wake. This boom was positioned at preselected distances below the rotor disk. Analog probe output was stored on magnetic tape during tests, and was later converted to digital form by use of a Hewlett-Packard A to D converter and computer system.

DESCRIPTION OF TEST FACILITY AND EQUIPMENT

ROTOR TOWER

The tests presented in this report were conducted on the full-scale rotor test tower that was designed and built under the Phase I and Phase II portions of Contract DAAJ02-67-C-0105. An overall view of the tower is presented in Figure 1. The top of the tower is 58.3 feet above ground level, and is only 3.9 feet in diameter. These dimensions permit the testing of full-scale rotors with a minimum of tower and ground plane interference.

In its current state of development, no drive system has been installed in the tower. For this reason, an OH-13E rotor and engine assembly was installed on the tower for the Phase III test program. These tests represented the initial tests to be conducted on the tower.

Access to the top of the tower was achieved by utilizing a stairway system within the tower or by the use of an access gantry which was mounted on a railway extending outward from the tower base.

For the current wake measurement tests, it was necessary to design a support for the total vector probe which would permit positioning of the probe at selected radial stations. The supporting structure was required to have sufficient strength to support approximately 10 pounds of instrumentation while maintaining a high degree of rigidity in the unsteady wake. After consideration of several schemes, it was concluded that a cantilevered, triangular boom would be required to obtain the strength and rigidity characteristics that were desired. In addition, a cantilevered boom would provide the most feasible means of positioning the probe at various distances below the rotor disk through the use of vertical attachment beams welded to the outer structure of the tower. The final design incorporated a track along which the probe could be traversed, and was equipped with a support platform for the circuit control box cf the anemometer system. The boom was designed to position the probe sensors 20 inches above the structure to minimize the flow interference effects of the boom.

A sketch of the rotor tower showing the instrumentation boom and the wake survey measurement boundaries is presented in Figure 2.

OH-13E TEST INSTALLATION

An assembly consisting of the main rotor, engine, and drive system of an OH-13E helicopter was installed on the top of the rotor tower for wake measurement tests. The assembly rested on four load cells which were used to determine rotor thrust. The system also included a fifth load cell which was used to measure the torque of the engine and main rotor. Cyclic pitch controls of the rotor were locked in the zero-cyclic position. Engine instrumentation and controls, which included a collective pitch meter, were installed on the second level of the tower. The collective pitch meter responded to the output of a potentiometer which was activated by vertical movement of the swashplate. Collective pitch control was achieved with an electric motor drive system on the swashplate.

During tests, rctor angular velocity was determined from a binary counter which was triggered by a magnetic sensor on the rotor shaft. The rotor was a standard OH-13E rotor having the following characteristics:

disk area	969 sq ft
blade area (each)	17.67 sq ft
diameter	35.125 ft
root chord	1.167 ft
tip chord	0.845 ft
airfoil section	NACA 0015
blade twist	-4.25 deg (average)

The blades of the rotor were found to be slightly mismatched, with one blade having -4.0 degrees twist and the other -4.5 degrees twist. As a result, cyclic pitch was locked such that the incidence of the blade tips would be equal. In this report, all values of collective pitch, azimuth angle, and elapsed time are in reference to the blade having -4.0 degrees of twist.

TOTAL VECTOR ANEMOMETER SYSTEM

A Thermo-Systems, Inc. Model 1080 total vector anemometer system was used for measurements of the rotor wake velocity components. This system included a Model 1296F probe which had three sensor "rods". Each rod held a split-film sensor, such that a total of six hot-film anemometers were used to determine the direction and magnitude of a velocity vector. The three sensor rods were mounted on the support stem of the probe to form a mutually perpendicular array, with each sensor inclined at an angle of 54.73 degrees with respect to the support stem. With this arrangement, the sensor rods described a cone bisected by the support stem of the probe. During tests the probe was mounted upright in the rotor wake such that each sensor rod was depressed below the plane of the rotor disk by an angle of 35.27 degrees as a result of the coned arrangement of the sensor array. The temperature in the vicinity of the sensor array was measured by a small thermocouple located between the sensor rods.

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The three sensor rods were identified as sensors A, B, and C. For data reduction purposes, it was necessary to define the angular relationship between the orthogonal axes system described by the sensors and an axes system which was fixed to the rotor tower. The axes lying coincident with sensor rods A, B, and C were designated as axes x', y', and z', respectively, to distinguish this coordinate system from the fixed tower axes x, y, and z. An enlarged view of the sensor array is shown in Figure 3 in addition to an overall view of the total vector probe and control circuit box of the anenometer system.

The probe was factory calibrated, with calibration constants and data reduction equations being provided by the manufacturer. The anemometer system was capable of measuring velocity magnitude and direction over a full 360-degree solid angle in three-dimensional flow fields. The splitfilm sensors of the probe allowed unambiguous determination of magnitude and direction of the instantaneous velocity vector. Probe output consisted of six simultaneous velocity-dependent analog voltages and one 0to 5-volt analog temperature signal. Power required by the system was 110 volts ac.

A block diagram of the data acquisition and reduction systems is shown in Figure 4. The seven analog voltages from the probe were recorded on magnetic tape, using the signal from a magnetic pickup on the rotor mast as an rpm and blade position reference. A binary counter and relay system was used to automatically record the probe output voltages for 25 revolutions of the reference blade. Since it was necessary to condition the probe output signals in order to record them on magnetic tape, calibration of the recorder was required prior to each test. This procedure consisted of recording measured voltages which were applied simultaneously to each of the seven probe output channels.

Data supplied by the manufacturer for the anemometer system indicated a frequency response of 750 Hz, a velocity range of 0 to 300 ft/sec in air, and sensitivity of 0.1 ft/sec. Spatial resolution of the probe was specified as being less than 0.5 inch, spherical.

DATA REDUCTION EQUIPMENT

Conversion of analog signals to digital velocity information was made with a Hewlett-Packard Model 561CA A to D converter and Model 2114A computer as indicated in the block diagram of Figure 4. This system was capable of sampling each of the seven data channels at a rate of 500 bits per second without loss in accuracy of the computed results.

CALIBRATION PROCEDURES

LOAD CELLS

Prior to wake measurement tests, a static calibration was performed on the load cell system which was used to measure rotor thrust and torque. The calibration was accomplished by application of torque to the engine and rotor assembly while maintaining values of constant static thrust. A weighted platform and pulley arrangement was used for application of torque to the system. Thrust loads were varied by means of a hydraulic jack and aircraft scale.

The calibration revealed that indicated thrust was approximately 4.0 percent less than applied thrust, and was independent of rotor torque throughout the range of thrust values that could be obtained for normal operating conditions of the rotor. Because of the design of the system, however, the four thrust cells restrained rotation of the engine mounting assembly which caused the output of the single torque cell to be dependent on thrust loading.

During tests, corrected rotor torque was determined from curves of indicated versus applied torque which were plotted for each thrust increment of 100 pounds. Rotor thrust was determined by summing the indicated values of each thrust cell and by correction of this value for system error.

Empirical and flight test data were compared to the resulting performance curve of the test installation as shown in Figure 7. The empirical curve was derived from similar curves of Reference 1, and the hover test data were obtained from flight test results of References 2 and 3. The deviation of the performance curves at large thrust coefficient was attributed to possible errors of measuring rotor torque and to geometric differences of the helicopters and rotor tower installation. The possibility of errors in rotor torque measurements should not have affected the current tests, since only thrust coefficient was used as a significant test variable.

ANALOG DATA CIRCUIT

Output voltages of the total vector probe ranged from 0 to 20 volts de for the 0- to 300-ft/sec range of velocity. In order to record these voltages on magnetic tape, it was necessary to scale the probe signals to a range of \pm 1.0 volt. This was accomplished by potentiometers in each of the seven output channels of the probe. The scale factors of each data channel were determined by application of known voltages to the probe input side of the circuit, and by recording the output voltages on the tape recorder. This procedure was followed prior to each of the velocity measurement tests. In addition to providing reference voltages from which the voltage scale factors could be determined, the procedure also accounted for any changes in the electronic components of the system which may have occurred over the test period.

PROBE POSITION INDICATOR

The total vector probe could be remotely positioned at any desired radial location in the wake. Probe position was varied by the use of a traversing mechanism which was mounted on the track of the instrumentation boom. The traversing carriage was driven by a small, reversible electric motor which was activated from the control room of the rotor tower. A highturn potentiometer, located on the traversing carriage, was used to sense the radial location of the probe as indicated by a microammeter which was calibrated to indicate the radial distance of the probe from the center of the rotor hub.

Prior to each velocity measurement test, the potentiometer was adjusted to provide the correct indication of the starting location of the total vector probe. Tests showed a tendency of the carriage to coast slightly after the electric motor was de-energized, such that small adjustments were often required to accurately position the probe at a desired location. The traversing speed of the carriage could be adjusted between 0 and 0.5 ft/sec. The probe and traversing carriage are shown installed on the instrumentation boom in Figure 5.

TOTAL VECTOR PROBE

The total vector anemometer system, consisting of the probe and control circuit box, was calibrated by the manufacturer prior to delivery. Due to the need for special calibration equipment, it was not possible to calibrate the system at Mississippi State University. As a check against possible contamination or damage to the probe sensors and system circuitry, measurements of the zero-velocity output of each data channel were made prior to each test run for comparison to those supplied by the manufacturer.

On one occasion, it was necessary to return the system to the manufacturer for recalibration due to a shift of the zero-velocity voltages on two of the seven data channels. In this case, the problem was attributed to the effects of humidity on the electronic components of the circuit. The probe, itself, remained intact and showed no effects of sensor contamination upon completion of the wake measurement tests.

As a check of probe accuracy, several tests of the probe were made in the low-speed wind tunnel at Mississippi State. Other tests were conducted with an apparatus which utilized a centrifugal blower as a velocity source. In the latter case, honeycomb sections and screens were used to achieve a flat, exit velocity profile across a 2-inch-diameter pipe that was connected to the blower. In these tests, the probe sensor axes were fixed at selected angles relative to the flow. Probe output was measured throughout a velocity range of 0 to 118 ft/sec in the wind tunnel and a range of 0 to 63 ft/sec with the blower apparatus. The velocity components that were computed from analog probe data were compared with test values as determined with a calibrated airspeed indicator and from angular measurements of probe orientation. The assumption was made that the direction of the mean flow coincided with the longitudinal axes of the tes oriens of the wind tunnel and blower systems. This assumption was based on the results obtained from tests in which tufts and flow vanes were used to determine the direction of the mean flow.

HELICOPTER INSTRUMENTS AND BINARY COUNTER

Manifold pressure and tachometer gages were calibrated on a standard aircraft instrumentation test set. However, rotor speed was determined from the binary counter during tests, rather than from the aircraft tachometer. The counter was a standard three-digit instrument with a counting period of 1 minute. The input signal for the counter was derived from a magnetic pickup which produced one pulse for each revolution of the rotor. After the 1-minute counting period, the indicator would display for 30 seconds and then resume counting.

The collective pitch meter was calibrated from measurements made on the rotor blades with an aircraft propeller protractor.

WIND MEASUREMENT SET

Local winds were measured with a wind measuring set which was capable of producing a continuous record of both magnitude and direction of the ambient wind. Wind detectors were installed on the tower access gantry at a height of approximately 3 feet above rotor level. Prior to each test, the access gantry was moved to a position approximately 75 feet from the base of the tower.

The wind-measuring equipment was sensitive to velocities of less than 1.0 mph and was continuously monitored during wake measurements. The equipment was calibrated by placing the wind detectors in the entrance section of the low-speed wind tunnel prior to wake measurement tests.

DESCRIPTION OF TESTS

ENVIRONMENTAL CONDITIONS

Wake measurement tests were conducted at low, ambient wind conditions to minimize the effects of local winds on the wake data. However, each radial survey required approximately 30 minutes running time, such that some difficulty was encountered with variable wind conditions during the test runs. It was necessary to repeat some of the measurements because of this problem. Although an effort was made to initiate the test runs when no local winds could be detected, experience proved that this condition seldom existed. As a result, tests were initiated when ambient wind velocities were less than 3.0 mph, although in some cases gusts occurred during the data runs which exceeded this value. At the end of the test period, only those data that were least affected by ambient winds were selected for analyses.

It was also necessary to conduct measurements during conditions of low atmospheric humidity, since the electronic components of the anemometer were sensitive to moisture content of the air. The most favorable test conditions generally occurred in the early evening hours shortly after sunset.

ROTOR TEST PARAMETERS

Following performance tests, three operating conditions of the rotor were selected at which wake measurements would be made. These conditions, which were selected in order that the effects of rotor speed and blade pitch on the test data could be examined, were as follows:

Condition 1: $\Omega R = 625$ ft/sec, $\Theta_{75} = 6.25$ deg, $C_T = 0.0020$ Condition 2: $\Omega R = 450$ ft/sec, $\Theta_{75} = 10.75$ deg, $C_T = 0.0040$ Condition 3: $\Omega R = 450$ ft/sec, $\Theta_{75} = 6.25$ deg, $C_T = 0.0020$

The collective pitch values given above were used throughout the test program, but rotor rpm was allowed to vary slightly from the selected test values. This was done since small adjustments of rotor speed tended to result in smoother operation of the engine and rotor in some instances.

In order to account for the effects of small variations of thrust, all wake velocity data were nondimensionalized by the momentum value of induced velocity as determined from thrust measurements for each test run.

DATA ACQUISITION PROCEDURE

When favorable conditions were indicated by the wind-measuring equipment, tests were initiated by using the following procedure:

- 1. The total vector probe and traversing mechanism were installed on the instrumentation boom at a selected radial station. The probe potentiometer was adjusted until the proper radial station was indicated by the probe position indicator.
- With the probe sensors shielded, zero velocity output voltages of the probe were measured and checked against the values supplied by the manufacturer. Load cell output was also recorded prior to engine start.

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- 3. After recording local temperature and pressure, the engine was started and the rotor was set at the operating test conditions of tip speed and collective pitch.
- 4. With the rotor operating, two calibration voltages were fed through each channel of the anemometer circuit to the magnetic tape recorder. These voltages were used to determine the calibration constants of the recorder.
- 5. When rotor speed stabilized, output of the thrust and torque load cells was recorded.
- 6. Output of the total vector probe was recorded for 25 revolutions of the rotor at selected radial stations along the length of the boom. Measurements in the vicinity of the tip were made at radial stations which appeared to coincide with the path of the tip vortices. These positions were determined from observations of the probe signals displayed on an oscilloscope.

DATA REDUCTION PROCEDURE

The analog signals from the seven data channels of the total vector probe were processed by using an A to D converter and computer. Each data channel was sampled at blade azimuth angles of $\Psi = 0$, 45, 90, and 135 degrees for each revolution of the rotor. Twenty-five revolutions were analyzed at each radial station. The seven probe voltages at each azimuth angle and for each revolution of the rotor were then used to compute the local instantaneous velocity components of the wake. The mean values of the instantaneous components were then computed and used to determine the local, mean resultant velocity vector at each radial station in the wake.

The equations and probe constants, req.ired for calculation of the wake velocity components, were supplied by the manufacturer. The first step in computing the values of these components consisted of evaluating the heat transfer to each of the three sensor rods, A, B, and C. For sensor A, heat transfer as a function of environment temperature was expressed as

$$\frac{Q}{\Delta T}_{A} = \frac{(K_{1}E_{1}^{2} + K_{2}E_{2}^{2})}{T - T_{e}}$$
(1)

where K_1 , K_2 = calibration constants for channels 1 and 2 of sensor A

 E_1 , E_2 = brid γ voltages of channels 1 and 2

 T_e = environment temperature

T = sensor temperature

Heat transfer to sensors B and C was calculated in a similar manner by using the calibration constants and bridge voltages associated with each channel. The environment temperature, $T_{e_{2}}$ was determined from the output of a thermocouple located between the probe sensors.

After evaluation of heat transfer equations, the "effective" velocity for each sensor was calculated.

$$V = \left(\frac{Q}{B \triangle T}\right)^n \tag{2}$$

where V = "effective" velocity at "standard" conditions

B, n = constants determined from probe calibration

The "effective" velocity was defined as the velocity normal to the sensor which would produce the same output reading. "Standard" conditions were defined at a temperature of 70 degrees Fahrenheit and a barometric pressure of 14.7 psia.

The "effective" velocity for each of the three probe sensors was used to evaluate the resultant velocity magnitude.

$$v_{s} = \frac{v_{A}^{2} + v_{B}^{2} + v_{C}^{2}}{2 + \kappa^{2}}$$
(3)

where V_s = magnitude of the resultant velocity vector at "standard" conditions

 V_A , V_B , V_C = "effective" velocities for sensors A, B, and C

k = constant defined as a function of V_s

The value of V_8 was then corrected for variations in temperature and pressure.

$$v_{R} = v_{g} \left(\frac{P_{g}T}{PT_{g}}\right)$$
(4)

where P, T = test values of barometric pressure and temperature, respectively

 P_s , T_s = "standard" values of pressure and temperature, respectively

The next step, after finding the velocity magnitude, V_R , was to determine the angles between the velocity vector and the sensor axes. For example, the magnitude of the angle between V_R and the perpendicular to sensor A could be calculated from the relationship

$$|\phi_{A}| = \arcsin \left[\frac{1 - (V_{A}/V_{S})^{2}}{1 - k^{2}} \right]^{\frac{1}{2}}$$
 (5)

Similarly, the magnitude of angles ϕ_B and ϕ_C could be found by using the corresponding values of V_B and V_C that were previously determined. The sign of the angles was determined by comparing the magnitudes of the two output voltages obtained from each sensor by using a procedure furnished by the manufacturer. At this point, the velocity components along each of the three orthogonal probe sensors could be calculated.

The final step of the data reduction procedure consisted of a transformation of velocity components from the sensor axes to the fixed coordinate system of the rotor tower. Making use of the angular relationships between the tower and sensor coordinate systems as shown in Figure 6, expressions for the velocity components in the tower coordinate system were found to be

$$\mathbf{v}_{\mathbf{X}} = 0.7071 \ \mathbf{V}_{\mathbf{R}} \ (\sin \phi_{\mathbf{B}} - \sin \phi_{\mathbf{C}}) \tag{6}$$

 $\mathbf{v}_{\mathbf{v}} = \mathbf{V}_{\mathbf{R}} \left[0.8165 \sin \phi_{\mathbf{A}} - 0.4082 \left(\sin \phi_{\mathbf{B}} + \sin \phi_{\mathbf{C}} \right) \right]$ (7)

$$v_{\tau} = -0.5774 V_{\rm R} \left(\sin \phi_{\rm A} + \sin \phi_{\rm R} + \sin \phi_{\rm C}\right) \tag{8}$$

Equations 6, 7, and 8 were evaluated at each radial measurement station at blade azimuth angles of 0, 45, 90, and 135 degrees. The instantaneous velocity components were calculated at each azimuth angle for each of the 25 sets of wake data recorded at each measurement station. The arithmetic mean of each velocity component was then computed as

$$\bar{v}_{x} = \frac{1}{n} \sum_{i=1}^{n} (v_{x})_{i}, \quad \bar{v}_{y} = \frac{1}{n} \sum_{i=1}^{n} (v_{y})_{i}, \quad \bar{v}_{z} = \frac{1}{n} \sum_{i=1}^{n} (v_{z})_{i} \quad (n=25) \quad (9)$$

The mean value of the resultant velocity vector was then determined from the averaged values of the velocity components.

$$\bar{v}_{R} = \left(\bar{v}_{x}^{2} + \bar{v}_{y}^{2} + \bar{v}_{z}^{2}\right)^{\frac{1}{2}}$$
(10)

The standard deviation of both magnitude and direction of the local instantaneous resultant velocity vectors with respect to the mean value was computed to allow the unsteady properties of the wake to be examined. Deviation of the magnitude of the nondimensionalized resultant velocity vector was calculated from the expression

$$\nabla V_{R} / v_{o} = \left[\frac{1}{(n-1)} \sum_{i=1}^{n} \left[(V_{R_{i}} - \bar{V}_{R}) / v_{o} \right]^{2} \right]^{\frac{1}{2}}$$
(11)

The above equation differs slightly from the usual definition of "standard deviation" in that the summation of the squared differences is divided by "n-1" instead of "n" occurrences. This procedure was used since it is generally considered to produce better results when the number of occurrences is relatively small.

Deviation of the direction of the resultant velocity vector was denoted as c_{ϵ} , where ϵ was defined as the angle between the local instantaneous velocity vector and the mean value, \tilde{V}_R . This angle was calculated from the dot product of the instantaneous and mean velocity vectors. Standard deviation of the angle ϵ was expressed as

$$\sigma_{\varepsilon} = \left[\frac{1}{n-1} \sum_{i=1}^{n} \varepsilon_{i}^{2}\right]^{\frac{1}{2}} \quad (n=25)$$
(12)

Computed values of the mean velocity components and standard deviation parameters are presented in the Appendix of this report.

DATA CHARACTERISTICS

ACCURACY OF TEST DATA

Results of the wind tunnel and blower tests of the total vector probe indicated that accuracy of the probe varied with respect to the orientation of the probe sensors to the main flow direction. The probe was most accurate when its shank was aligned with the flow such that angular symmetry existed between the sensors and main flow direction. This condition would occur during actual tests when the resultant wake velocity vector was directed downward and was parallel to the vertical axis of the rotor tower.

Tests conducted with the probe sensors at various angles to the resultant flow indicated that velocity magnitude and angular errors were largest when the direction of the resultant flow was perpendicular to one of the probe sensors. Typical results of the probe tests are shown in Figures 8 and 9.

Angular deviations of the velocity vectors that were calculated from probe measurements exhibited considerable data scatter for all tests, and were generally larger than shown in Figure 9 when the probe was angled to the main flow. Because of data scatter, the accuracy of the probe was expressed in terms of the standard deviations of the data.

Calculated values of resultant velocity magnitude determined from the probe measurements fell within a range of ± 6 percent of the test values as shown in Figure 8. The more conservative estimates of probe error as determined from standard deviations of the test data are presented below for two conditions of probe orientation. In case (b), the direction of the resultant velocity vector was essentially perpendicular to one sensor of the probe.

Resultant Velocity Magnitude Error (0-118 ft/sec)

(a)	probe	shank	aligned with	flow	±	3.0%	V _R
(b)	probe	shank	angled to flo	νw	±	4.1%	VR

Angular Error (angle between actual resultant velocity vector and vector calculated from probe output)

(a) probe shank aligned with flow ± 2.5 deg	(a)	probe	shank	aligned	with	flow	± 2.5 deg
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(b) probe shank angled to flow ± 8.4 deg

The above results were obtained by feeding the probe analog signals through the data acquisition and reduction system of the current test program. For this reason, these values were considered to be valid for the entire data system. The results of the probe tests were consistent with the accuracy data supplied by the manufacturer, and should have been representative of the accuracy of velocity measurements in the inner wake flow where the resultant velocity vector has a large downward component parallel to the probe shank. However, velocity measurements made in the upflow region outside of the tip vortex trails and within the tip vortices were expected to be subject to errors in excess of the values stated above due to flow interference caused by the body of the probe.

Other tests of the probe traversing carriage, collective pitch meter, and binary rpm counter resulted in the following acculacy limitations of test parameters:

(a)	radial position of probe	$\pm 3 \text{ in.} (\Delta x/R = \pm 0.0142)$
(b)	collective pitch setting	± 0.25 deg
(c)	rotor angular velocity	± 3 rpm

WIND EFFECTS

In attempting to correlate the test data at various vertical stations beneath the rotor, it was obvious that the data at some stations were affected by wind. In spite of the precautions taken to reduce wind effects to a minimum, ideal conditions were not obtained in all instances during the measurements at each vertical station. The effects of wind were observed as radial shifts of the velocity distributions - either inboard or outboard - depending upon wind direction. Other inconsistencies of the data that were noted during comparison of velocity components in the plane of the rotor were also attributed to the possible addition of wind components to those of the wake proper. The above effects were most apparent in data obtained at stations z/R = -0.5, -1.0, and -2.0.

An analysis of the wind conditions which existed during tests revealed that wake deflection at the two lower stations was the result of wind velocities that were less than the 3.0-mph limitation established for tests. Only at station z/R = 0.5 did wind variations exceed this limitation. Unfortunately, test runs at these stations could not be repeated due to the absence of more favorable test conditions before termination of the project. Although data at the above stations were noticeably affected by wind gradients, these data are included in the opendix since they are subject to particular analyses and still exhilit the major characteristics of the wake flow.

PROBE PERFORMANCE

The total vector probe provided velocity data α f good quality and proved to be sufficiently responsive to the large cange of velocity fluctuations in the wake. Velocity fluctuations of ± 180 ft/sec were measured within the tip vortices at a response rate of approximately 230 Hz. The probe appeared equally as responsive to velocities of the outer wake in the ± 10 ft/sec range. The symmetry of the velocity distributions measured across the tip vortex trails indicated that errors of velocity measurement associated with the probe in reversed flow regions were not as large as anticipated.

LIMITATIONS TO ANALYSES

The limited number of vertical measurement stations and the displacements of the wake due to ambient wind resulted in difficulties of data interpretation, particularly since no prior wake information was available for the test installation. Consequently, flow visualization results from previous tests proved useful as aids to data analyses. These consisted of unpublished results obtained from tests of a UH-1B tail rotor at Mississippi State University and published results such as those of References 4 and 5.

Data analyses were primarily limited to observations of the mean characteristics of the wake, since only local instantaneous measurements could be obtained with the single probe. However, instantaneous measurements proved useful in determining the time-dependent variations of velocity in the region of the tip vortex trails. Changes of the mean wake characteristics as functions of vertical distance below the rotor disk could be observed by comparisons of the mean distributions of velocity components at successive vertical stations. However, compavisons of wake phenomena at specific radial coordinates in the far wake were largely prohibited as the result of radial shifts of the wake due to ambient winds.

DISCUSSION OF TEST RESULTS

GENERAL DESCRIPTION OF THE WAKE

In the near wake at z/R = -0.1, the radial distributions of total and induced velocity were characterized by sharp velocity peaks at the radial positions of the tip vortex paths. Inboard of these positions, the decrease of total velocity magnitude was essentially linear, resulting in a near triangular distribution as shown in Figures 10-17. In the far wake below z/R = -0.3, the velocity components became more evenly distributed across the vortex paths as the tip vortices expanded and dissipated. The changing characteristics of the velocity distributions with increasing distance below the rotor may be observed in Figures 10, 18, 19, and 20.

Radial velocities of the inner wake, v_x , generally feil within a range of ± 5 ft/sec for all tests, and tended to zero toward the hub. These components exhibited a characteristic negative-to-positive sign change with increasing distance below the rotor, which indicated the contraction and subsequent expansion of the wake.

Mean tangential velocity components measured parallel to the y axis, \tilde{v}_y , were of approximately the same magnitude as the radial components throughout the wake. An exception occurred directly beneath the rotor disk, where tangential components of 10 ft/sec were measured. A comparison of the wake velocity components at four vertical measurement stations is presented in Figures 21-24.

The measurements of the velocity components at blade azimuth positions of $\psi = 0$, 45, 90, and 135 degrees clearly indicated the oscillatory nature of the wake. The downward passage of the inboard vortex sheets across the probe resulted in variations of the magnitude of the mean wake components which were most significant in the near wake. Comparisons of the data revealed that the wake oscillations tended to demp out with increasing distance below the rotor, and were directly proportional to thrust coefficient. Azimuthal variations of the tangential velocity components in the plane of the rotor were observed to be slightly larger than those of the axial or vertical components. At a thrust coefficient of 0.004, the velocity components at z/R = -0.1 revealed time-dependent variations in magnitude as large as 3 ft/sec, or 15 percent of the momentum value of induced velocity.

The magnitude of the three velocity components measured outside the trailing tip vortices was generally less than 10 ft/sec, with tangential components tending to be slightly larger than the radial and vertical components. Entrained flow velocities near the blade tip ranged from 8.5 to 14 ft/sec, depending on the operating condition of the rotor. Below z/R = -0.5, radial velocity components of the outer wake were essentially zero, indicating essentially zero flow entrainment in the far wake.

The most significant characteristic of the velocity distribution was the change in the mean distributions of the three velocity components that occurred with passage of the tip vortex trail across the vertical measurement station. The changes in magnitude of the wake components with varying position of the tip vortices are shown in Figures 10-13. In Figure 10, the vortex of one blade has passed below the measurement station as indicated by the negative peak of radial velocity $\bar{v}_{\rm X}/v_0$. In Figure 11, slight disturbances of the velocity components indicate the approach of the next vortex. This vortex has arrived at a position very close to the measurement station in Figure 12, as shown by the sharp velocity peaks in this figure, and has continued downward to a position below the measurement level as shown in Figure 13.

In all cases, positive peaks of the wake tangential velocity component \bar{v}_y/v_0 were indicated within the vortex trail. The small changes of radial velocity in the vicinity of the vortex and the corresponding peaks of the vertical and tangential components of Figure 12 indicate that the mean position of the vortex was slightly outboard and at approximately the same vertical level as the probe sensors at a reference blade azimuth angle of 90 degrees.

Additional velocity distributions which show the effects of the tip vortices in Test Conditions 2 and 3 are shown in Figures 14-17 at z/R = -0.1. Below this position, the characteristic velocity peaks across the tip vortex trails rapidly diminished in magnitude and were seldom detected in measurements made below z/R = -0.7.

UNSTEADY CHARACTERISTICS OF THE WAKE

Standard deviations of the nondimensionalized total velocity vector were computed throughout the wake at each radial measurement station as previously defined in this report. The standard deviations of both magnitude and direction of the resultant wake vector are included in the compiled data of the Appendix. Values of these parameters at three distances below the rotor are plotted in Figures 25-29.

The deviation parameters clearly show the positions of the tip vortices and the growth of unsteady wake characteristics with increasing distance below the rotor disk. The large values of angular and magnitude deviation across the vortex trails were the result of a lack of uniform vortex structure or variations of the time-dependent positions of the rotor tip vortices with respect to the measurement stations. Since detailed measurements of vortices indicated that vortex structure near the rotor was essentially uniform, the large values of the deviation parameters in the vicinity of the vortex trails were concluded to be the result of unsteady variations of the path and transport velocities of the vortices.

Inspection of the data revealed that deviations of the total velocity vectors in the inner wake were small near the rotor, but large in the

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far wake. These deviations of the inner wake consisted primarily of fluctuations of the magnitude of the instantaneous total velocity vectors at given azimuth angles of the rotor. Deviations of the direction of the instantaneous velocity vectors were small throughout the inner wake.

In the inner wake region at z/R = -0.1, standard deviations of instantaneous total velocity magnitude were approximately 2 to 4 percent of the mean values of the resultant velocity vectors, and deviation of flow direction was approximately 3 degrees. At z/R = -0.7, these values had increased to approximately 9 percent and 5 degrees, respectively. Exceptions to these values were apparent at particular radial stations and azimuth angles of the rotor, where values of the deviation parameters exceeded the mean values across the wake. These exceptions were most apparent from measurements near the rotor as in Figures 25, 26 and 27.

Calculations made from rotor speed and velocity distributions revealed that the points of maximum angular and magnitude deviation in the inner wake corresponded to the stations at which the trailing vortex sheets of the rotor blades passed across the probe sensors. The measurements indicated that flow within the trailing vortex sheets was more unsteady than that of the surrounding wake. Deviations of the resultant velocity vectors measured across the trailing vortex sheets became larger as distance beneath the rotor disk increased, and indicated an expansion of these sheets which eventually resulted in an unstable condition of the inner wake. Deviations of total velocity magnitude at z/R = -1.5were as large as 30 percent of the mean flow value and were accompanied by angular deviations as large as 15 degrees. These conditions are illustrated in Figure 29. The observed characteristics of the inner wake appeared consistent with those shown in the flow visualization photographs of Reference 4.

The expansion of the tip vortices with distance below the rotor was apparent from a comparison of the velocity deviation parameters. At z/R = -0.1, the region within which instability of the vortices was measured was approximately 0.25 radii in width, or about 4.4 feet as shown in Figures 25, 26, and 27. At z/R = -0.7, the apparent diameter of the vortex exceeded 5 feet and continued to expand to over 10 feet at z/R = -1.5.

VORTEX DATA CHARACTERISTICS

Distributions of the instantaneous velocity components across a tip vortex trail at z/R = -0.1 are shown in Figures 30 and 31 for Test Condition 2 ($C_T = 0.004$). The axial (v_y) and vertical (v_z) velocity components of the vortex as shown in Figure 31 corresponded to the radial (v_x) components of Figure 30. These measurements show the velocity fluctuations which occurred as the vortex trail passed downward across the probe sensors. The high-velocity peaks in the distributions of radial and vertical velocity components and the rapid sign change of the radial components near $\Psi = 341$, 708, and 1068 degrees indicated that the vortices shed from one blade passed directly across the probe sensors. Calculations of the time required for the shed vortices to arrive at the measurement station revealed that the vortices which passed directly across the probe were shed from the Number 2 rotor blade rather than from the reference blade. The path of the reference blade vortices was slightly different from the path of the vortices shed from the Number 2 blade, as shown by the smaller variations of the velocity components at $\Psi = 509$, 869, and 1229 degrees.

The path variations of the rotor tip vortices were possibly the result of the 0.5-degree difference in twist of the blades. Subsequent measurements of the vortices shed from the reference blade showed that the mean radial spacing between the vortex paths of the two blades was approximately 0.025R, or 5.3 inches, at vertical stations in the near wake.

In examining the velocity distributions of Figures 30 and 31, it should be noted that the velocity components include the translational velocities of the vortex. However, the measurements clearly reveal the signatures of the vortices in the flow, since the translational velocity components are small with respect to the magnitude of the axial and tangential components of the vortices.

Measurements of the velocity components in the vicinity of the vortex trails were also made for Test Conditions 1 and 3. The flow for Test Condition 1 revealed essentially the same characteristic vortex structure as measured in Test Condition 2, showing only the shifted vertical positions of the vortices with respect to azimuthal position of the reference blade and a reduction of vortex strength. The flow for Test Condition 3, at low thrust, did not reveal the well-defined vortices of the other test conditions, although the presence of the vortices in the flow was clearly indicated by characteristic peaks in the plots of the velocity components.

VELOCITY DISTRIBUTIONS ACROSS THE VORTEX TRAILS

In an effort to further examine the flow within the vortices, the data were searched in an attempt to detect the instances in which the trailing vortices passed directly over the probe. Characteristics of the probe output signals clearly indicated the stations at which the probe was near the vortex trails, but it was not possible to determine if the vortex cores actually passed across the probe sensors from an examination of the data in analog form. This problem required that numerous analog data samples be converted to digital form by the computer in order to locate vortices which revealed the velocity distributions across the core. After extensive data analysis, a few cases were found at each of the vertical measurement stations above z/R = -0.7, in which the vortex cores passed directly over the probe. The difficulty of obtaining these data was enhanced by the instability of the vortex trajectories and the relatively small size of the vortex cores. Typical examples of the instantaneous velocity distributions across the core region of the vortex trails are shown in Figures 32-34. Since the vortices traveled across the probe with radial and vertical components of translational velocity and since the core centers were displaced with respect to the probe sensors, symmetrical velocity distributions were not obtained. As a result, it was necessary to assume that symmetry of the vortex structure existed in order to approximate the paths of the vortices with respect to the probe sensors as shown in Figures 32-34.

Estimates of the path velocities of the vortex cores were based on mean values of the velocity components when the vortices were above or below the measurement stations, and from considerations of symmetry of the velocity distributions across the vortices These estimates allowed the approximate radii of the vortex cores to be calculated after the paths of the vortices, with respect to the probe, had been determined. The time scale was fixed by rotor speed. By coincidence, the calculated core radii of the vortices shown in Figures 32 and 33 were exactly the same. Similar comparisons of other vortices revealed no significant differences of core size for these test conditions of equal rotor thrust.

The approximate azimuth angles which corresponded to points within the vortex cores are indicated by numerals on the blade azimuth scale and sketches of Figures 32-34. The distributions of the velocity components about these points show a characteristic increase of the radial and vertical velocity components of the vortex as the boundary of the core is approached, and peak values of axial velocity at the center of the core.

Limited capability of the computer in sampling the data at small increments of time prevented a more precise definition of the flow in the vicinity of the core boundaries. Also, the displacement of the path of the vortex cores with respect to the probe prevented direct measurement of the maximum velocities at the edge and center of the vortex cores.

In some instances, the vortex measurements revealed large velocity fluctuations in the region of the cores which were believed to have been associated with probe interference. The velocity fluctuations appeared to be largely confined to the axial velocity components of the vortex trails as shown in Figure 37. This result suggested that the stability of a vortex trail is perhaps more strongly related to the characteristics of the axial or longitudinal flow within the vortex cores than to the rotational components of the vortex.

The axial (v_y) components of each vortex increased in magnitude from the outer edge of the vortex until reaching a maximum value near the center of the core. Peak axial velocities as large as 190 ft/sec were measured in the center of the vortices. Tangential velocity values increased to a maximum at the boundary of the core and were minimum at the core center. Maximum values of tangential velocity within the vortex trails were of approximately the same magnitude as maximum values of the axial components. The tangential velocity components of the vortices were calculated as the resultants of the measured radial and vertical velocity components at equal values of blade azimuth angle.

Attempts to determine the mean distributions of axial and tangential velocity along the diameters of typical vortices were not successful due to uncertainties related to the path coordinates of the vortices with respect to the probe. However, the tangential velocity distributions of the vortices appeared to be generally consistent with classical vortex theory as found in many texts such as Reference 6.

Measurements of the vortex velocity distributions at z/R = -0.3 revealed no abrupt changes in vortex structure, although axial velocities in the core had decreased significantly. At lower levels in the wake, the vortices were very sensitive to the presence of the probe, and the measured axial and tangential velocities in the core continued to decrease. Below z/R = -0.7, the presence of vorticity in the mean flow could still be detected from the measurements, although well-defined vortices were seldom found below this station. The measurements revealed, however, that at least some of the vortices had not completely dissipated or broken up at a distance of 1.5 radii below the rotor disk when the rotor was operating at normal thrust.

At the lower thrust level of Test Condition 3, the vortices were very weak at a distance of 0.3 radii beneath the rotor disk, and no definitive measurements of the vortices for this condition were obtained below this level.

VORTEX CORE_VELOCITIES AND DIMENSIONS

The most significant feature observed from measurements of the rotor tip vortices was the rapid decline of axial velocity magnitude that occurred in the vortex cores with increasing distance below the rotor. This observation was based upon a comparison of the maximum values of axial velocity that were measured within the vortex cores. The measurements showed that the magnitude of the axial velocity components in the vortex cores decreased approximately 50 to 70 percent between stations z/R = -0.1 and -0.3. Extrapolation of the measurements toward the rotor disk indicated that axial core velocities would be extremely large in the immediate vicinity of the rotor. Below z/R = -0.3, the decline of axial velocity in the vortex cores consisted of a gradual approach to stagnation in the far wake.

Further comparisons of the maximum values of tangential velocity at the core boundaries revealed a more gradual reduction of these values below the rotor than was observed from comparisons of the maximum axial velocity components in the vortex cores. Rotational velocities varied from maximum values near 200 ft/sec in the near wake to 20 ft/sec in the far wake. Computed radii of the vortex cores indicated a trend toward increased core size in the far wake, but results were generally inconclusive. Average core radii were approximately 0.005R, a value commonly assumed in wake analyses methods such as those of References 4 and 7. The computations were complicated as a result of the failure to obtain measurements of the vortex velocity distributions when the vortex core passed directly across the probe sensors.

MEAN PROPERTIES OF THE TRAILING VORTICES

Values of maximum tangential velocity at the edge of the vortex cores, maximum axial velocity at the center of the cores, core radii, and vortex radii were plotted as functions of vertical distance below the rotor disk to obtain the mean values of these functions. Mean properties of the trailing vortices as determined from curves faired through the experimental data are shown in the table below.

Test Condition	Vertical Station,z/R	v _t (max) ft/sec	v _a (max) ft/sec	Core Radius r _c /R	Vortex Radius r _v /R
1	-0.1	136	147	0.004	0.125
1	-0.3	87	57	0.005	0.175
1	-0.5	57	42	0,006	0.225
1	-1.5	22	30	0.007	0.35
2	-0.1	200*	193	0.004	0.10
2	-0.3	150	83	0.005	0.15
2	-0.5	116	72	0.005	0.20
2	-1.5	38	28	-	0.30
3	-0.1	57	90	0.005	0.125
3	-0.3	39	40	0.005	0.20
3	-0.5	-	-	0.006	0.25
3	-1.5	-	-	-	0.35

Several factors concerning the values of the above table should be noted at this point. The values of vortex radii were determined from values of the standard deviation parameters which indicated the expanse of the mean wake within which the unsteady vortex-induced velocities were detected. Also, it should be emphasized that the tabulated values of maximum tangential and axial velocity were those obtained from a finite number of data samples and should not be considered optimum values. Of equal importance is the fact that the vortex velocity data include the effects of translation of the vortex trails with respect to the fixed probe. The possible effects of vortex dissipation during the time interval required for the vortex to travel across the probe are also contained in the measurements. These factors did not appear to significantly affect the data, however, since translational components of velocity were small in comparison to the axial and tangential vortex components. Also, vortex dissipation was relatively slow with respect to the small time intervals required to traverse the vortex.

VORTEX PATH COORDINATES AND TRANSPORT VELOCITIES

The approximate coordinates of the rotor tip vortices (as functions of blade azimuth angle) were determined from the velocity distributions at each vertical measurement station in the near wake. The analysis revealed that the paths of the trailing vortices of the two blades were not identical as previously noted, and that the azimuthal spacing of the vortices varied from the expected value of 180 degrees. This resulted in the data scatter shown in the plots of the tip vortex path coordinates of Figures 35 and 36. Vortex dissipation and ambient wind effects prohibited an extension of the results to vertical stations below z/R = -0.5.

The time-dependent variations of vortex spacing and path coordinates were believed to have been the result of several factors. The 0.5-degree difference in linear twist of the blades, the degree of accuracy of collective pitch setting, wind effects, and errors in determining the exact vortex positions from velocity measurements were all probable factors which resulted in poor definition of the vortex path coordinates.

The calculated transport velocities of the vortices varied as the result of the path variations noted above. The results indicated, however, that the vertical displacement of the vortices below z/R = -0.1 was approximately equal to one-half of the maximum resultant velocity of the inner vortex sheet at equivalent distances below the rotor. As a result, the rates of vertical displacement of the vortices at stations below z/R =-0.1 were essentially constant. This indicated that the vortices experienced maximum acceleration between the z/R = -0.1 level and the blade tip. It was also observed that the vertical transport velocity of the shed vortices increased linearly with tip speed and varied approximately as the square of collective pitch ratio.

EFFECTS OF TEST VARIABLES

Comparisons of the mean wake velocity distributions revealed that the effects of varying tip speed and collective pitch were reflected primarily as changes in magnitude of the velocity components of the inner wake and rotor tip vortices, and as changes of the time-dependent characteristics of the wake. When the velocity components of the wake were nondimensionalized by the momentum values of induced velocity, no large differences between the radial distributions of the velocity components of the wake were detected which could have been directly attributed to variations of the test parameters. Radial shifts of the wake were considered to be the result of wind effects, and were most pronounced for the condition of low rotor thrust (Test Condition 3). A comparison of data for the three test conditions also indicated that the induced inflow and tangential velocity components outside the trailing vortex boundaries tended to be slightly larger for Test Condition 3. The standard deviation parameters, however, revealed no significant differences of the unsteady flow characteristics of the wake as a result of changing test variables.

The most pronounced effects of the test variables were noted in measurements of the velocity distributions across the trailing vortices. Measured values of maximum tangential and axial velocity within the vortices increased substantially when the product of tip speed and collective pitch was increased to a maximum value in Test Condition 2. The vortices for the higher pitch condition also appeared to be slightly more restricted in size than did the vortices for the other test conditions.

Considerations of rotor thrust and circulation strength for each test condition indicated that maximum tangential velocity in the vortices should have varied directly as the product of tip speed and thrust coefficient, since differences of core radii for the various test conditions were small. The relative variations of the values of maximum tangential velocity magnitude in the vortices for Test Conditions 1 and 2 were roughly consistent with this approximation, but the corresponding values for Test Condition 3 appeared conservative. This is believed to have been the result of failure to accurately measure the velocities within the weaker and more unstable vortices with the rotor operating in the lowthrust condition.

Axial velocities in the tip vortex trails were also observed to vary as a function of the test variables. Comparisons of the data at z/R = -0.3 indicated that axial velocity magnitude in the vortex cores tended to vary linearly with increasing values of the product of tip speed and thrust coefficient, as did the tangential components of the vortex. Closer to the rotor, a linear relationship was obtained by comparisons of the maximum axial velocities of the vortices to the product of tip speed and collective pitch angle. At constant tip speed conditions of the rotor, the maximum axial components of the vortex trails were inversely proportional to thrust coefficient.

Only slight changes of the tip vortex path coordinates were observed for the three test conditions of the rotor. No significant differences in the extent of maximum wake contraction were detected from plots of the tip path coordinates. However, small variations of the radial coordinates indicated that maximum wake contraction occurred nearer the rotor disk when thrust coefficient was increased. No appreciable effects of tip speed on the vortex trajectories could be detected as shown by the identical vortex path coordinates for Test Conditions 1 and 3 in Figure 35.

COMPARISONS OF DATA WITH PREVIOUS RESULTS

VORTEX PATH COORDINATES

Path coordinates of the rotor tip vortices as determined from model data by Landgrebe (Reference 4) were compared to current results as shown in Figures 35 and 36. The model data were corrected to account for the differences of thrust coefficient and blade twist that existed between tests of the full-scale rotor and model. The considerable extent of azimuthal data scatter of the current results made direct comparisons of the path coordinates difficult, but certain trends could be detected. The path coordinates of the full-scale rotor agreed reasonably well with model data, except for the radial coordinates of Test Condition 2. In this case, Landgrebe's results indicated that contraction of the wake should have increased at the higher value of increased thrust coefficient, a condition not detected in the present tests. The wake of the fullscale rotor also appeared to contract to a maximum extent nearer the rotor disk than did the wake of the model rotors.

It is uncertain whether the earlier contraction of the full-scale wake could be due to the combined effects of the rotor tower and ground plane. The model data of Reference 4 indicated that the effects of a whirl test stand on path coordinates of the wake were small when the model was operating in ground effect. Also, the full-scale rotor in the current tests was operating at z/R = 3.87, a height at which ground plane effects should have been negligible. However, results obtained by locating cylinders of various sizes in the wake of a hovering model rotor did indicate that an expansion of the wake of 3.5 to 4.0 percent could possibly have occurred due to the effects of the rotor tower on the wake (Reference 8).

It should also be noted that the path coordinates of Figures 35 and 36 do not show the effects of differences in coning angle of the full-scale and model rotors. When these differences are considered, the apparent earlier contraction of the wake of the full-scale rotor is partially accounted for, since coning angles of the model were smaller than those of the full-scale rotor. However, this correction would also result in larger axial displacement velocities of the tip vortices of the full-scale rotor than those of the model.

In view of the above factors, it would appear that radial contraction of the full-scale wake is less a function of thrust coefficient than indicated from the model tests of Reference 4, and that axial displacement rates of the tip vortices near the rotor may be slightly higher than those of model rotors. These observations need to be further substantiated by additional tests of the full-scale rotor which would permit a more direct comparison of full-scale model data.

The full-scale data showed that tip path coordinates were independent of

tip speed and that axial transport velocities of the tip vortices varied directly with the momentum values of induced velocity. These results were in agreement with model test results.

TANGENTIAL VELOCITY COMPONENTS OF THE WAKE

Comparisons of the mean tangential velocity components (\bar{v}_y/v_0) of the inner wake region revealed azimuthal oscillations of the magnitude of these components at all vertical measurement stations in the wake. Inconsistent variations of tangential velocity magnitude were attributed primarily to the effects of ambient wind, rather than to unsteady oscillations of the wake itself.

Comparisons of the relative variations of tangential velocity components at each vertical measurement station showed that wake skew angles were larger for Test Condition 3 than for the other test conditions. The data indicated that wake skew angles were inversely proportional to thrust level as previously observed by Lehman in Reference 5. However, comparisons of the skew angles obtained from the data of Test Conditions 1 and 2 indicated that wake skew may also vary at constant thrust as a function of both tip speed and collective pitch angle. These comparisons led to the conclusion that wake skew varies inversely with the product of tip speed and collective pitch angle. For example, at z/R = -0.1, the mean deflection angle of the wake from the vertical direction was approximately 16 degrees for Test Condition 3, in which the lowest combination of tip speed and collective pitch angle was employed. The wake skew angle decreased to approximately 10 degrees when tip speed was increased in Test Condition 1 while maintaining constant collective pitch. The skew angle was reduced still further to a calculated value of 7.5 degrees in Test Condition 2, in which the product of tip speed and collective pitch angle was increased to its highest value while maintaining constant rotor thrust,

The results suggest that the neglect of tangential velocity components in wake analyses techniques would be of little consequence at nominal thrust values of helicopter rotors, but that the degree of error may increase with decreasing thrust level. The degree of error due to neglect of swirl components would appear to be more directly related to tip speed and collective pitch combinations than to disk loading alone.

RADIAL COMPONENTS OF WAKE VELOCITY

The directions of the radial velocity components (\bar{v}_x/v_0) were generally consistent with wake contraction and expansion. Near the rotor, the mean radial components of the inner wake were directed toward the hub, indicating wake contraction. In the far wake, the direction of these components was reversed. The mean values of radial velocity across the inner wake at each vertical station were smaller than the tangential components, and appeared to vary to a greater extent as a result of

ambient wind conditions than did the tangential velocity components.

Comparisons of the radial velocity components of Test Conditions 1 and 3 showed no significant effects of tip speed on the magnitude or direction of these components. This result agreed with the previous observation that the effects of tip speed on wake contraction could not be detected. Although data scatter largely masked the effects of the test variables, comparisons of radial velocity distributions at z/R = -0.1 revealed that the negative radial velocities for Test Condition 2 were slightly larger in magnitude than those measured at lower thrust coefficients. This would indicate that wake contraction does vary as a function of thrust coefficient as mentioned in Reference 4, although this condition could not be detected from comparisons of the measured radial positions of the tip vortices in current tests.

VORTEX VELOCITY CHARACTERISTICS

The rates at which the maximum values of tangential velocity within the vortex cores decreased with downstream distance behind the tips of the rotor blades were approximately the same as measured in the vortices of fix 1-wing aircraft by McCormick (Reference 9). The fixed-wing measurements showed that the maximum tangential velocities in the vortex decreased inversely with the square root of the distance behind the aircraft. A plot of the available data in Figure 38 shows the approximate parabolic decrease of maximum tangential velocity in the vortex cores as a function of distance measured along the vortex trails.

The positive axial velocities measured in the vortex cores with the fixed probe represented deficiencies of axial momentum within the vortex trails. The loss of axial momentum at the center of the vortices has been treated analytically by Newman (Reference 10), and has been experimentally observed by Dosanjh and others (Reference 11) in the vortices behind a half-wing in the wind tunnel. The axial velocity defect in a vortex trail is generally associated with profile drag losses of the vortex generator.

The decrease of maximum axial velocity in the vortex trails (Figure 39) indicated that the vortices had to expand with increasing distance behind the blades if the momentum losses represented by the axial velocity defects were to remain constant. This expansion of the vortices was apparent from comparisons of the velocity distributions and wake deviation parameters in the vicinity of the vortex trails. However, the expansion rates of the vortices appeared to be more closely related to the rates of maximum tangential velocity decline in the vortex trails than to the rates of maximum axial velocity decline. As shown in Figure 40, the growth of the vortex dimensions is apparently linear with respect to the square root of the distance behind the blade.

In many instances, the measurements within the vortex trails were characterized by velocity fluctuations in the core, while the outer portions of the vortices remained relatively stable as shown in Figure 37. The rotating velocity components of the vortices appeared less affected by the presence of the measurement probe than did the axial components. These results suggested that vortex stability may be strongly related to the axial flow properties of vortices as suggested by Bergman (Reference 12) and as observed by Olsen in experimental towing tests (Reference 13).

RESULTS AND CONCLUSIONS

- 1. The results of the initial wake survey conducted on the Mississippi State University rotor tower revealed that the total vector anemometer and tower instrumentation systems were adequate for the acquisition of wake velocity data which are quantitatively reliable. Comparisons of the measurements with limited analytical and experimental results indicated that accuracy of the anemometer and tower systems is also sufficient to allow qualitative examinations of the behavior of timedependent wake characteristics with variations of test parameters.
- 2. The wake of the hovering OH-13E rotor with linear twist was characterized by radial distributions of vertical wake velocity near the rotor which increased almost linearly from the hub to a position just inboard of the helical vortex trails. Maximum values of induced velocity in the inner wake were directly proportional to momentum values.
- 3. Maximum values of the vertical velocity component of the inboard vortex sheets exceeded twice the values of momentum-induced velocity in the vicinity of the rotor tip vortices and remained essentially constant with increasing distance below the rotor.
- 4. Mean values of the inner wake velocity components in the plane of the rotor disk were small near the hub and tended to increase toward the position of the tip vortex trails. The direction of the radial components was generally consistent with the contraction and expansion characteristics of the wake. Tangential components were largest at vertical stations nearest the rotor disk, indicating a higher swirl condition of the inner wake near the rotor than at lower stations in the wake.
- 5. The magnitude of the velocity components of the inner wake oscillated with respect to blade azimuth position. The amplitude of these oscillations was observed to be proportional to thrust coefficient and to vary inversely with distance below the rotor. The azimuthal variations of the radial and tangential velocity components of the inner wake tended to be larger than those of the axial components.
- 6. Wake skew angles near the rotor varied inversely with thrust level. Variations of wake skew which were measured at constant thrust conditions were inversely proportional to the product of tip speed and collective pitch angle.
- 7. The rate of vertical displacement of the rotor tip vortices was approximately one-half of the rate of maximum vertical displacement of the inboard vortex sheets. Below the point of maximum wake contraction, the vortices moved downward at a constant rate which was proportional to tip speed and the square root of thrust coefficient.

- 8. The flow in the region of the tip vortex trails was highly unsteady as indicated by standard deviations of the resultant wake velocity vectors. Local instabilities of the inner wake were also observed as the results of unsteady flow variations across the inboard vortex sheets. The wake became progressively unstable with the expansion of the rotor tip vortices and vortex sheets as distance below the rotor increased. The dimensions of the unsteady region across the vortex trails was observed to be proportional to the square root of the distance measured along the vortex trails to the tip of the blade.
- 9. Maximum tangential and axial velocities in the vortex trails were measured at the edge and center of the vortex cores, respectively. Axial velocity components of the rotor tip vortices were of the same order of magnitude as rotational components. The magnitude of the maximum tangential and axial velocities in the vortex trails varied approximately as the product of tip speed and rotor thrust coefficient.
- 10. Maximum tantential and axial velocities in the rotor tip vortices decreased in magnitude with increasing distance below the rotor. The rate at which the tangential components decreased was similar to that of vortices shed from fixed-wing aircraft. Maximum axial velocity in the vortices nearest the rotor decreased at a rate which exceeded that of the maximum tangential components.
- 11. Measurements of velocity distributions across the vortex trails indicated that the vortices tended to dissipate into the far wake rather than to "burst" or break up at specific distances below the rotor. The measurements revealed that at least some of the vortices retained their characteristic structure at distances as far as 1.5 radii below the rotor disk.
- 12. Comparisons of full-scale data to model data were largely inconclusive due to path variations and uneven spacing of the tip vortices of the full-scale rotor. Correlation of wake contraction coordinates with test variables could not be established from the full-scale data. Unsteady variations of the vortex path coordinates were attributed to differences of rotor blade twist, errors of collective pitch setting, and the effects of ambient wind.
- 13. The axial velocity components of the rotor tip vortices were more sensitive to the disturbances of the measurement probe than were the tangential components. Large fluctuations of axial flow within the vortex cores were measured when the rotational components were relatively stable. The results indicated that the stability of the vortex trails was strongly related to the characteristics of the internal axial flow in the region of the vortex cores.

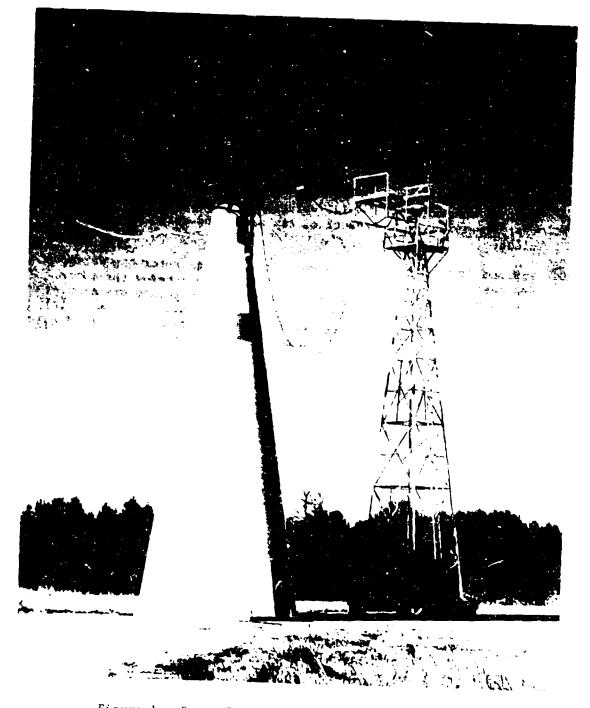
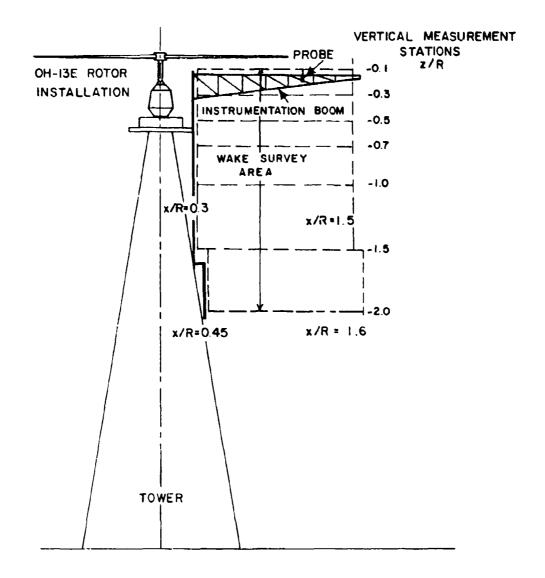
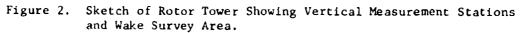
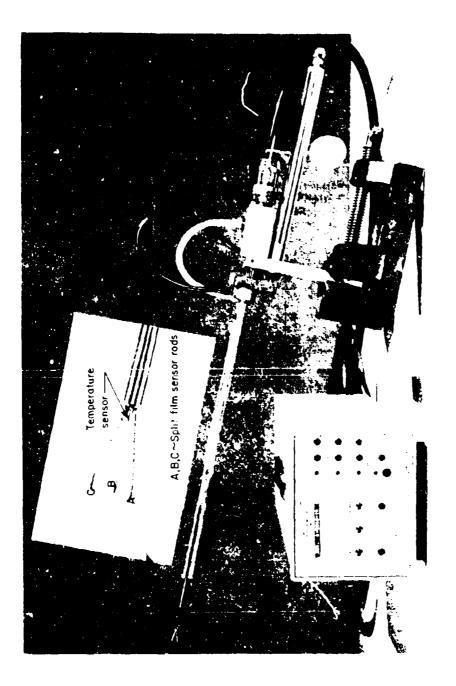


Figure 1. Rotor Tower With OH-13E Test Installation.

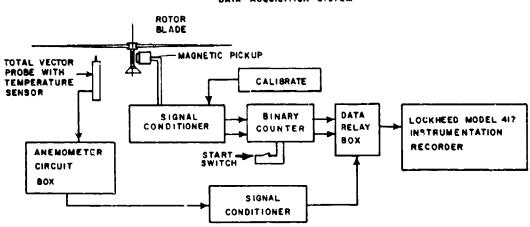






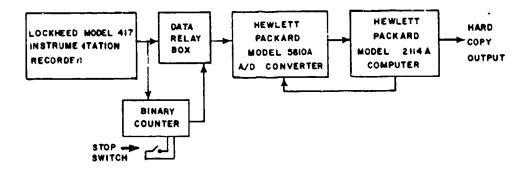
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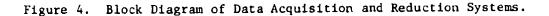
Figure 3. Jobal Vestor Probe and Control Circuit Box.



DATA ACQUISITION SYSTEM







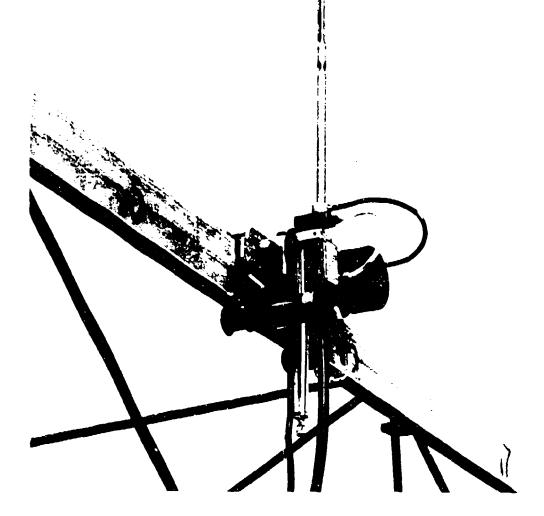
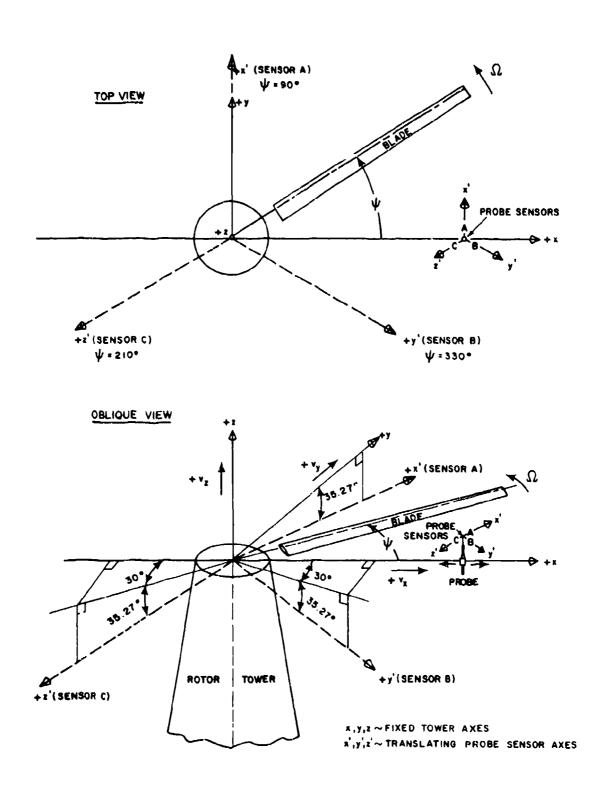
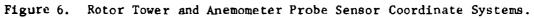


Figure 5. Test Configuration of Total Vector Probe and Traversing Mechanism.





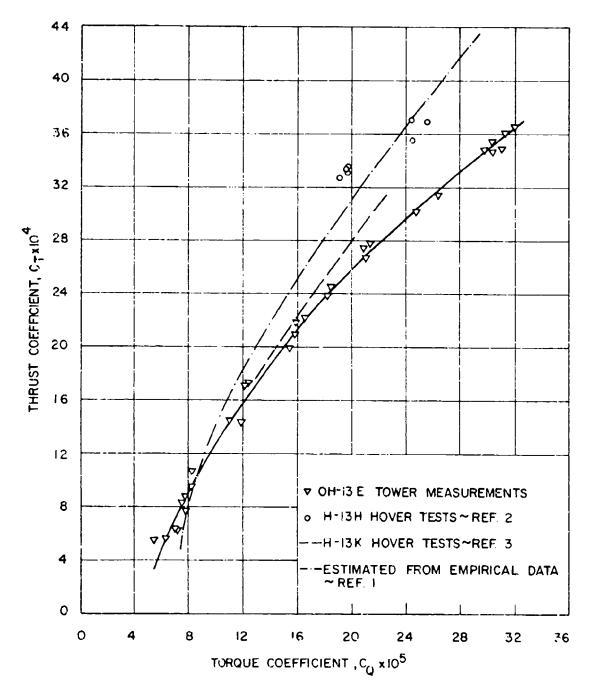


Figure 7. Comparison of Hovering Performance of the OH-13E Rotor Tower Installation With Flight Test and Empirical Data.

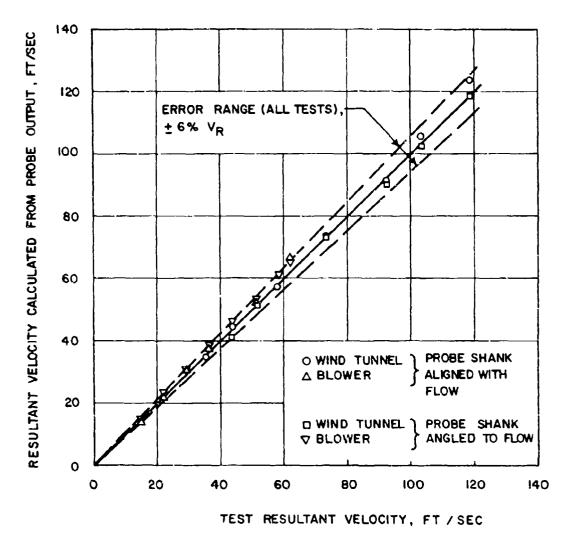


Figure 8. Velocity Measurement Error of Total Vector Probe.

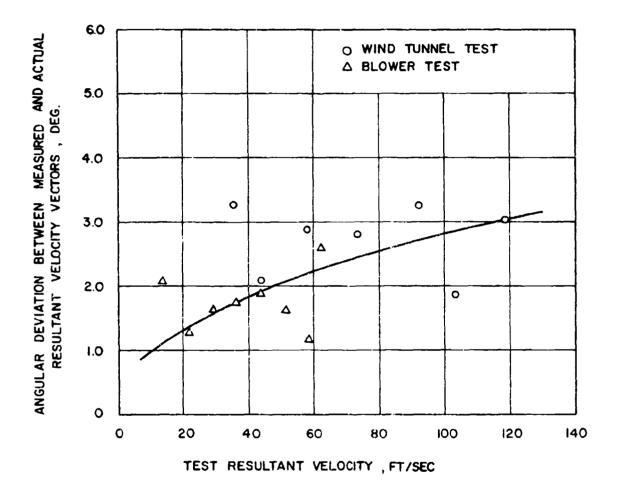


Figure 9. Angular Error of Total Vector Probe With Probe Shank Aligned With Flow Direction.

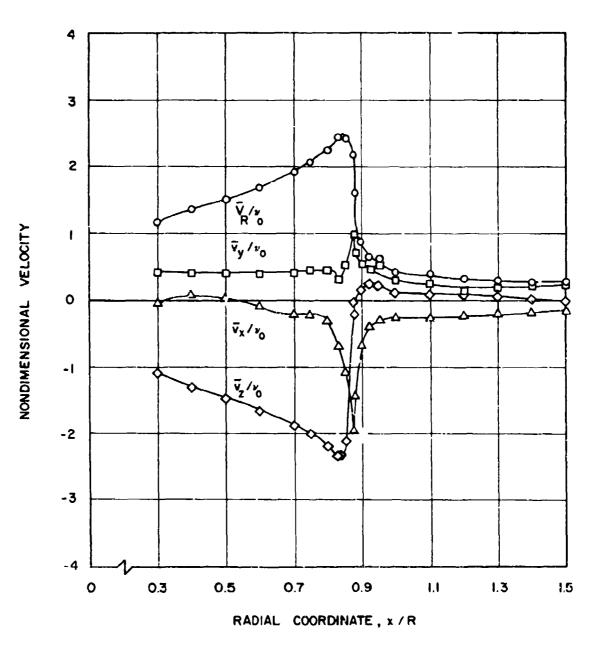


Figure 10. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -0.1, $\psi = 0$ deg.

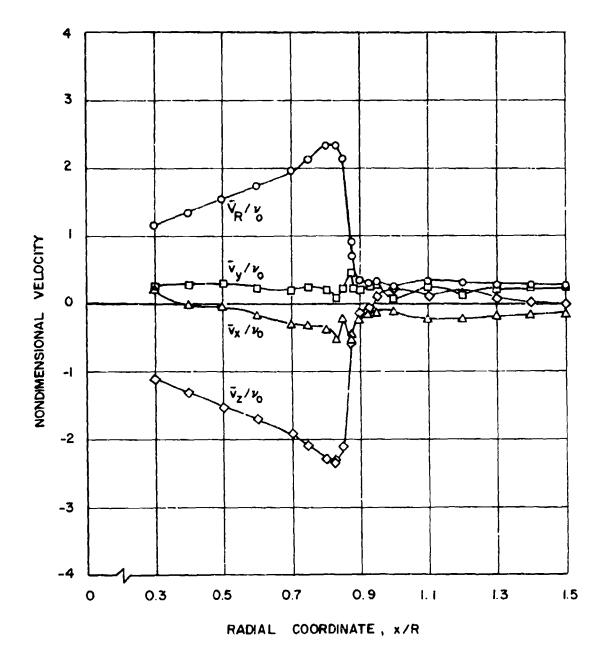


Figure 11. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -0.1, $\psi = 45$ deg.

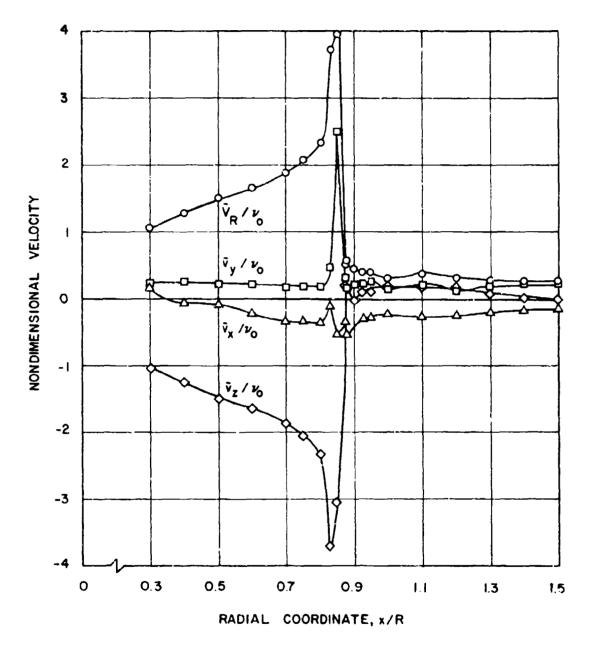


Figure 12. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -0.1, $\psi = 90$ deg.

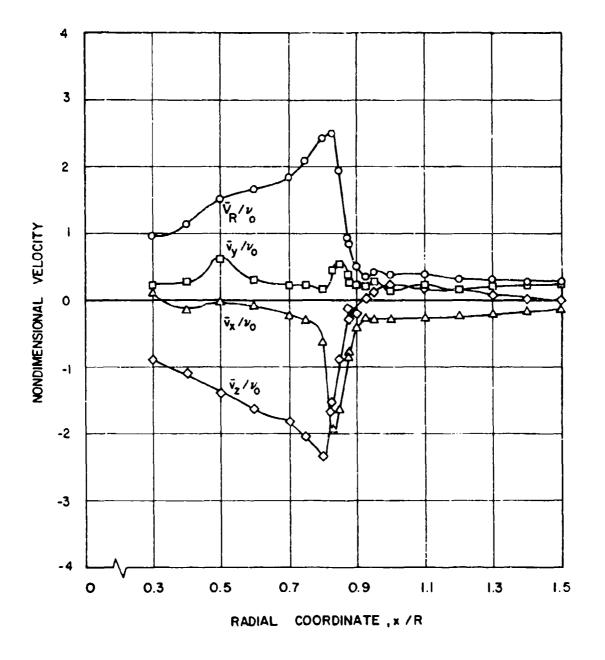


Figure 13. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -0.1, $\psi = 135$ deg.

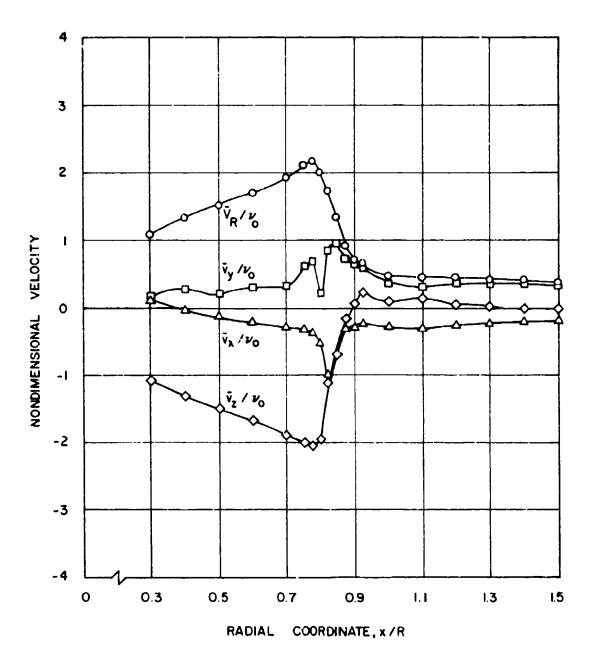


Figure 14. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 2, z/R = -0.1, $\psi = 0$ deg.

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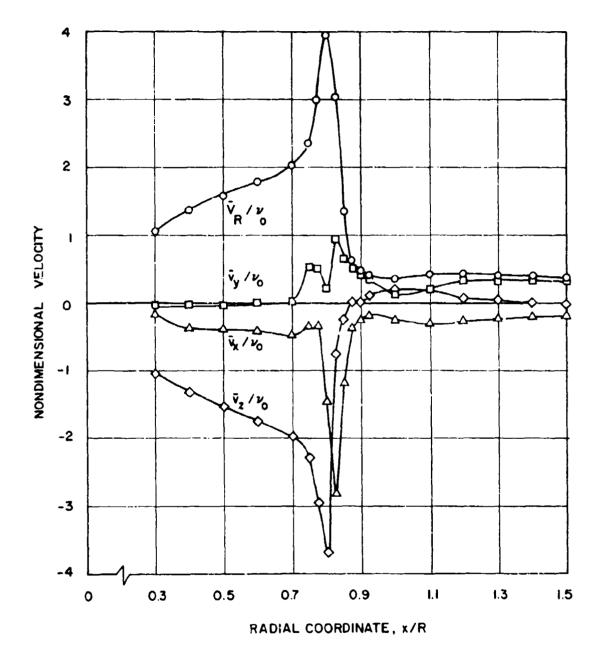


Figure 15. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 2, z/R = -0.1, $\psi = 90$ deg.

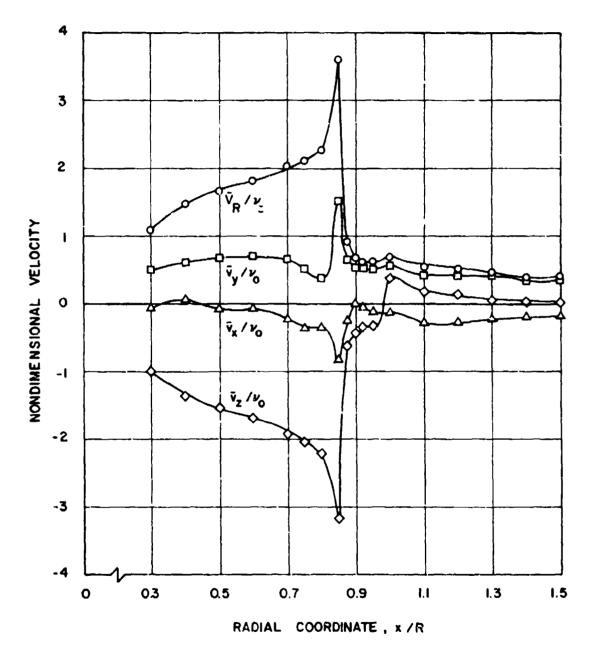


Figure 16. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 3, z/R = -0.1, $\psi = 0$ deg.

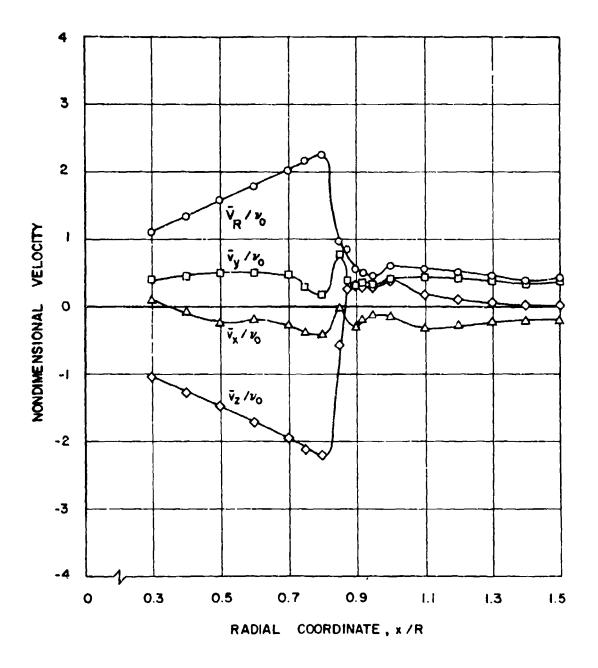


Figure 17. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 3, z/R = -0.1, $\psi = 90$ deg.

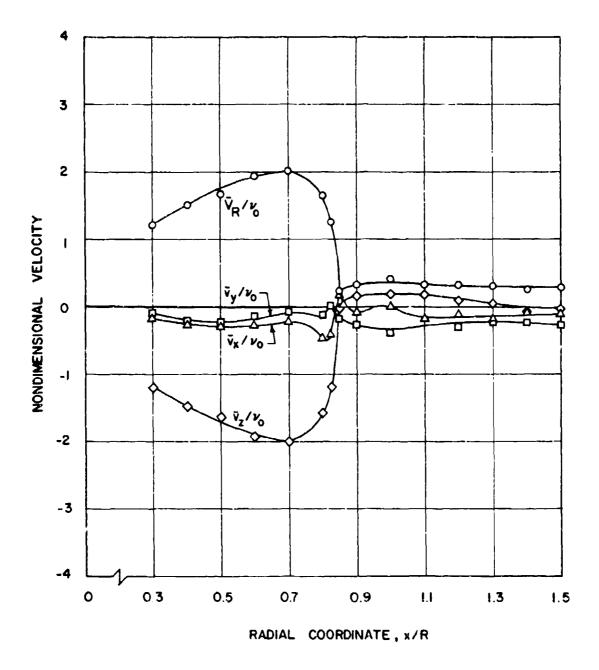


Figure 18. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -0.3, $\psi = 0$ deg.

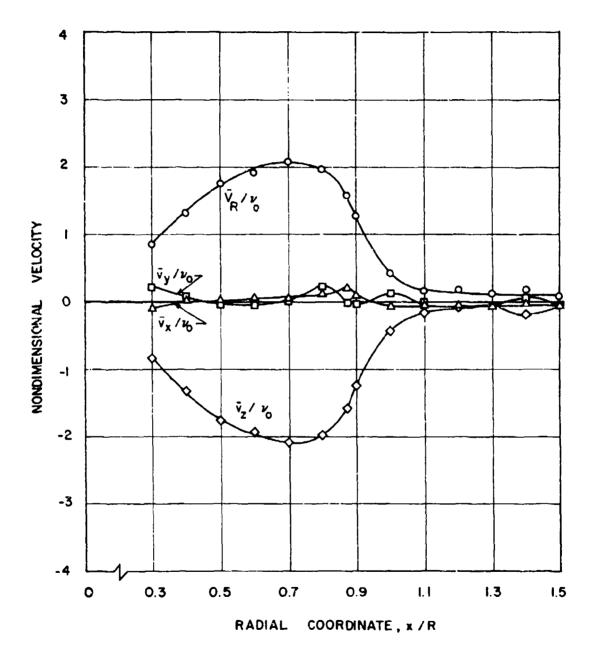


Figure 19. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -0.7, $\psi = 0$ deg.

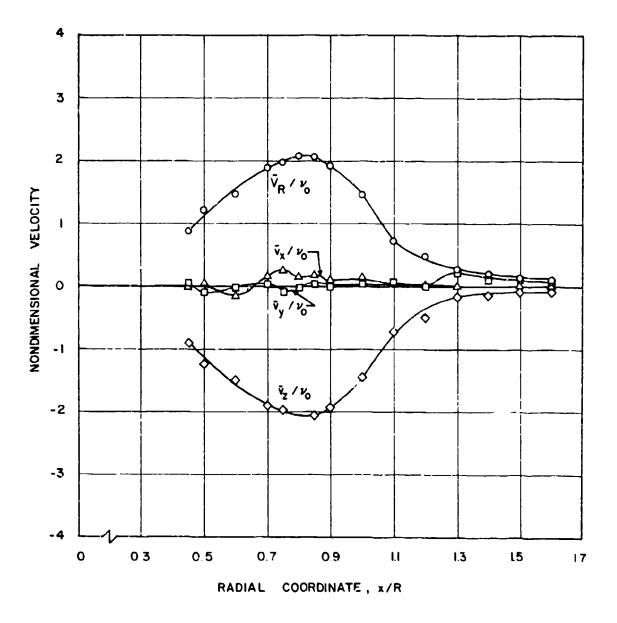


Figure 20. Radial Distribution of Mean Velocity Components and Resultant Velocity, Test Condition 1, z/R = -1.5, $\psi = 0$ deg.

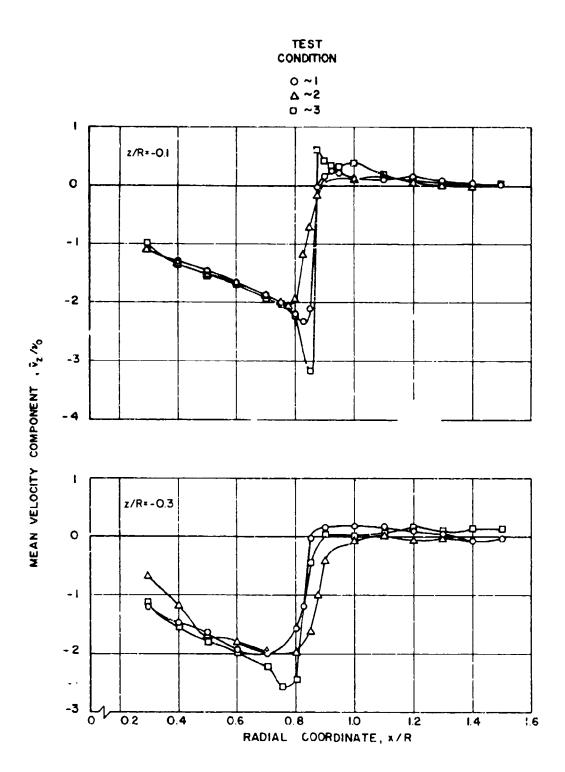
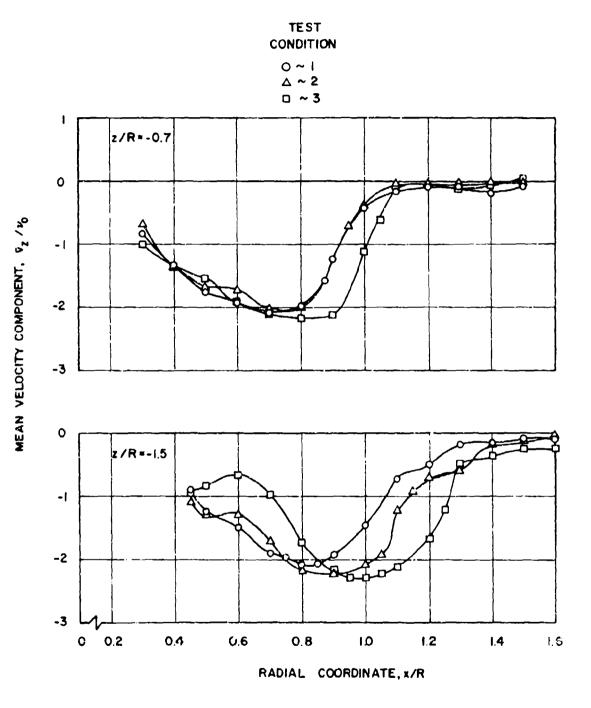


Figure 21. Comparison of Radial Distributions of Vertical Velocity Component, \bar{v}_z/v_0 , for Three Rotor Test Conditions, z/R = -0.1 and -0.3, $\psi = 0$ deg.



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Figure 22. Comparison of Radial Distributions of Vertical Velocity Component, \bar{v}_z/v_o , for Three Rotor Test Conditions, z/R = -0.7 and -1.5, $\psi = 0$ deg.

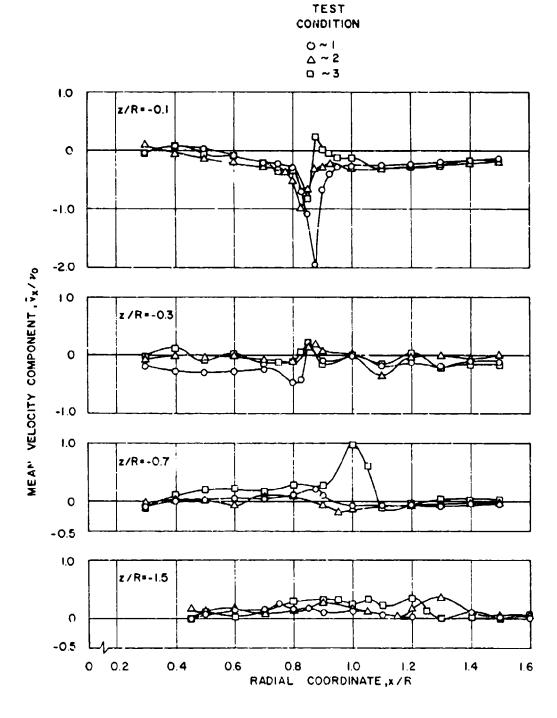


Figure 23. Comparison of Radial Distributions of Radial Velocity Component, v_x/v_0 , for Three Rotor Test Conditions, z/R = -0.1, -0.3, -0.7, and -1.5, $\psi = 0$ deg.

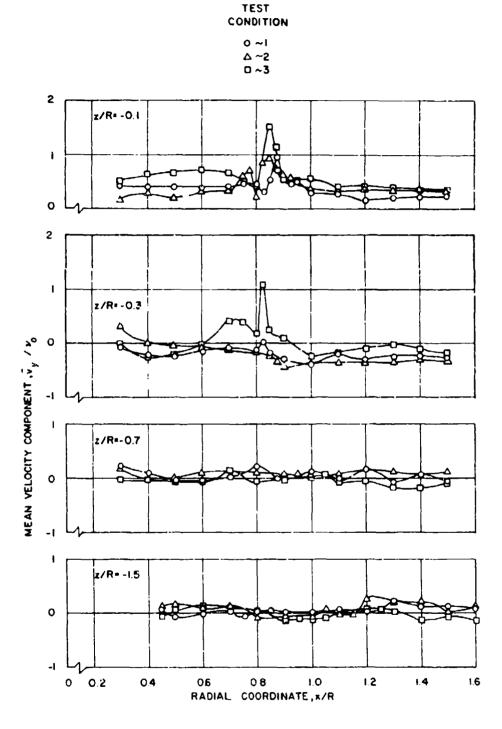


Figure 24. Comparison of Kadial Distributions of Tangential Velocity Component, \bar{v}_y/v_0 , for Three Rotor Test Conditions, z/R = -0.1, -0.3, -0.7, and -1.5, $\psi = 0$ deg.

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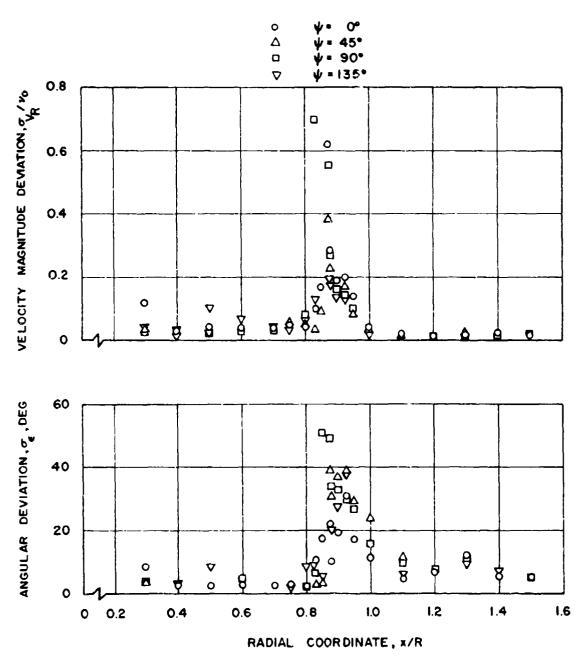


Figure 25. Standard Deviations of Instantaneous Total Velocity Vectors From Mean Values, Test Condition 1, z/R = -0.1.

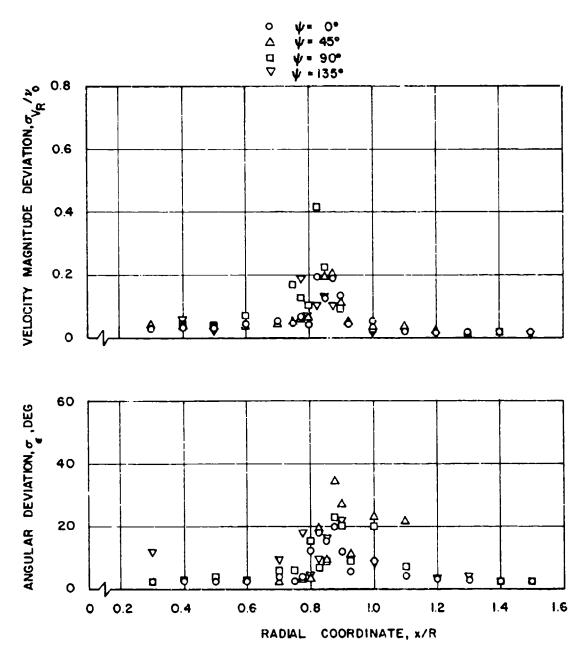
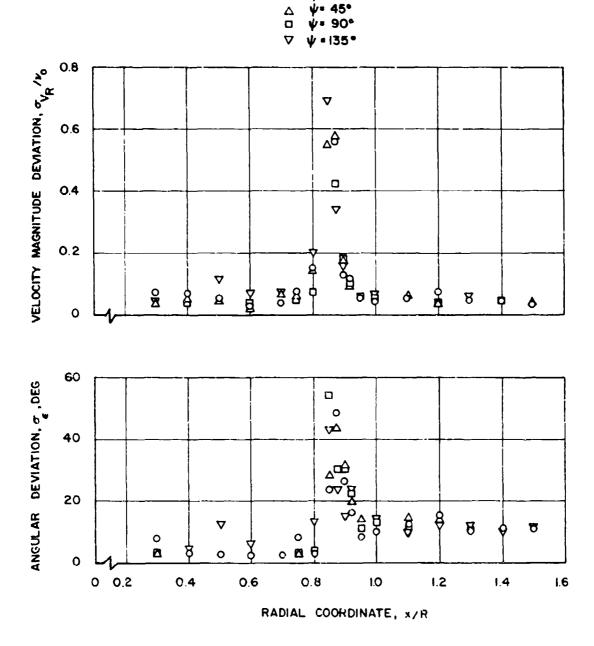


Figure 26. Standard Deviations of Instantaneous Total Velocity Vectors From Mean Values, Test Condition 2, z/R = -0.1.



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Figure 27. Standard Deviations of Instantaneous Total Velocity Vectors From Mean Values, Test Condition 3, z/R = -0.1.

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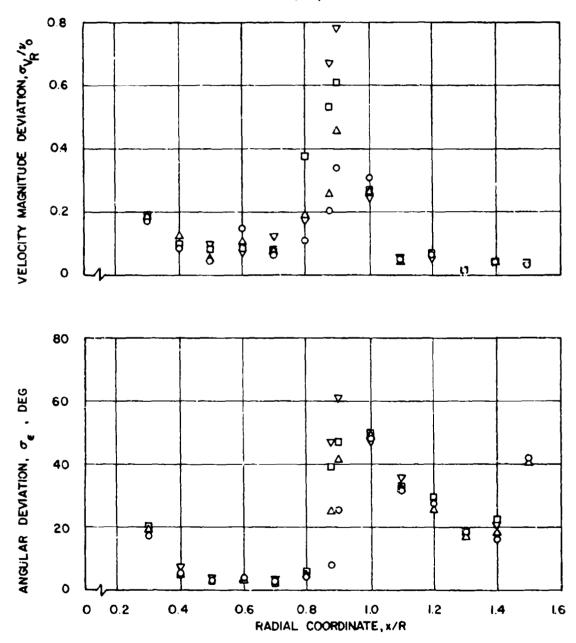


Figure 28. Standard Deviations of Instantaneous Total Velocity Vectors From Mean Values, Test Condition 1, z/R = -0.7.

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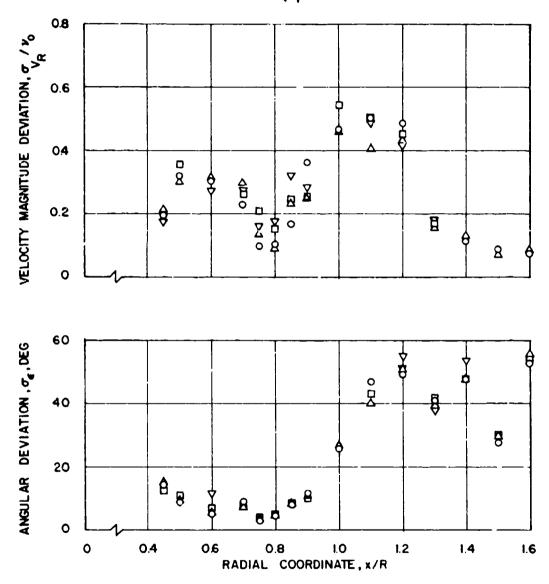


Figure 29. Standard Deviations of Instantaneous Total Velocity Vectors From Mean Values, Test Condition 1, z/R = -1.5.

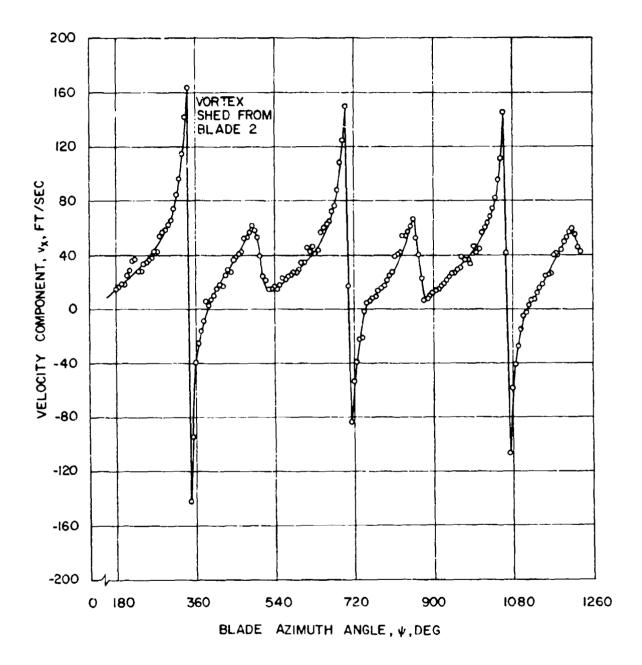


Figure 30. Instantaneous Velocity Components, v_x , Measured in the Vicinity of the Trailing Tip Vortices, Test Condition 2, x/R = 0.85, z/R = -0.1.

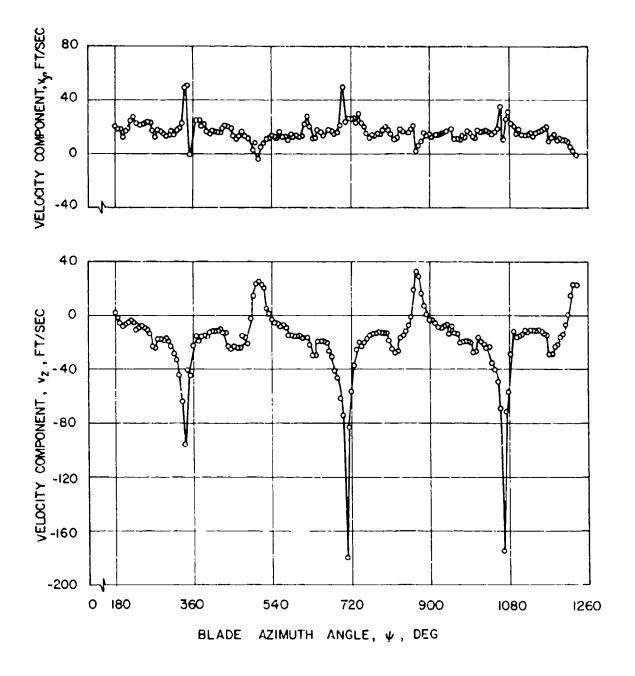
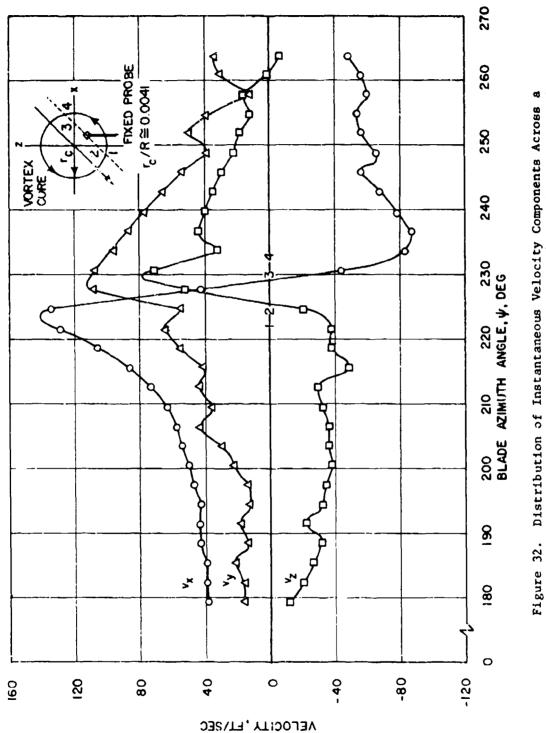


Figure 31. Instantaneous Velocity Components, v_y and v_z , Measured in the Vicinity of the Trailing Tip Vortices, Test Condition 2, x/R = 0.85, z/R = -0.1.





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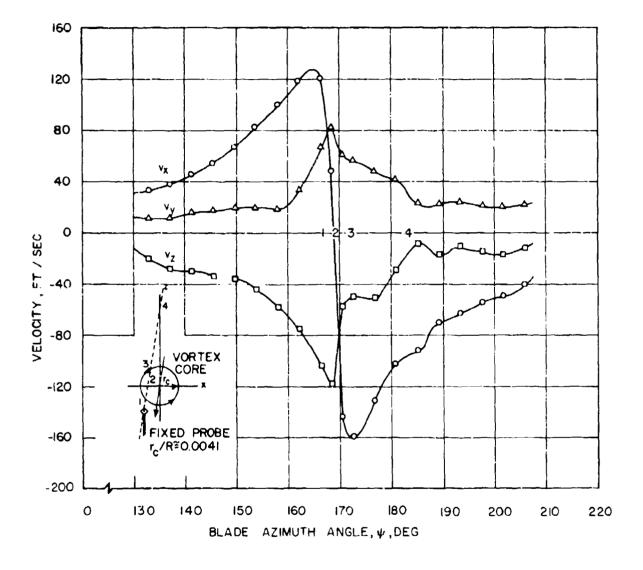
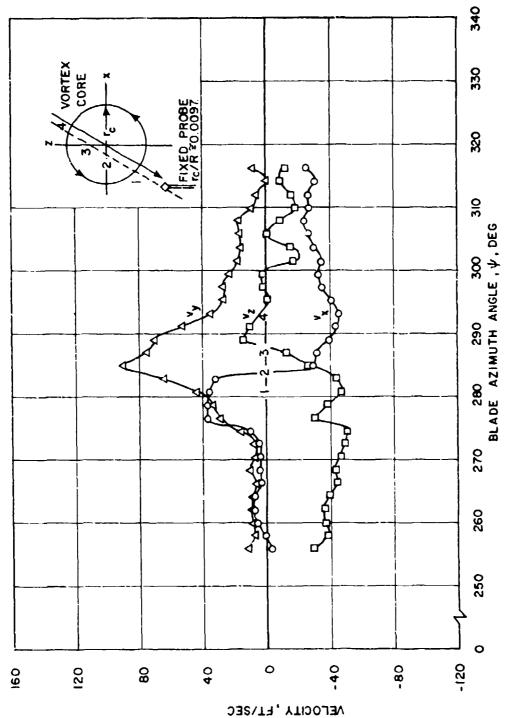


Figure 33. Distribution of Instantaneous Velocity Components Across a Trailing Vortex, Test Condition 2, x/R = 0.85, z/R = -0.1.



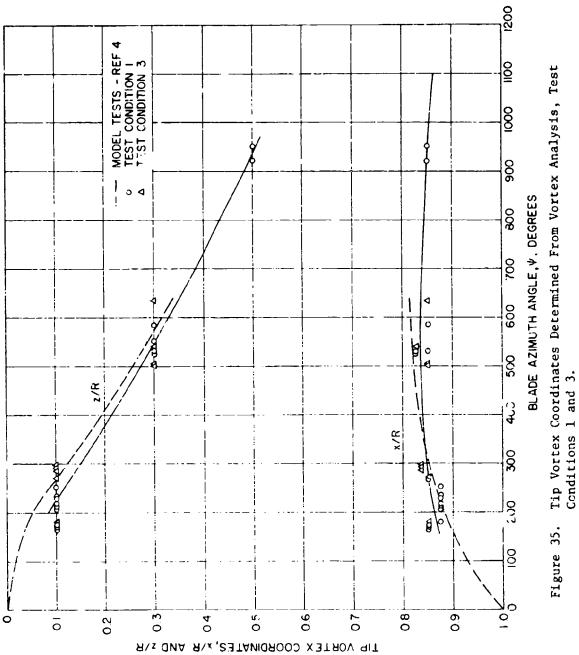
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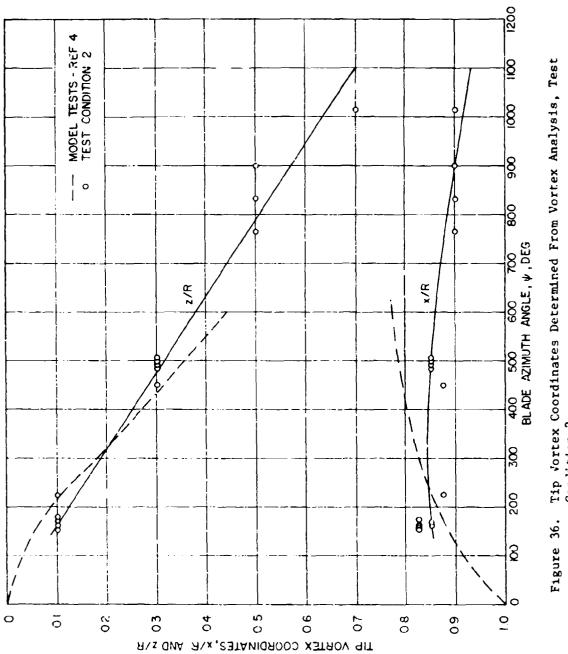
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Tip Vortex Coordinates Determined From Vortex Analysis, Test Condition 2.

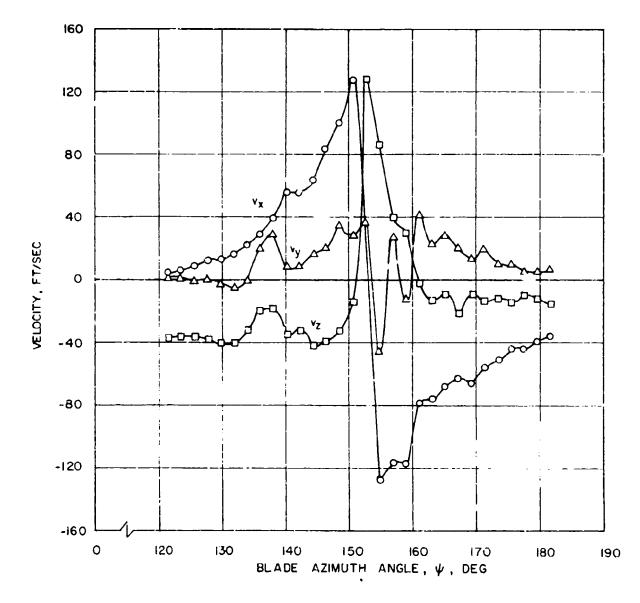
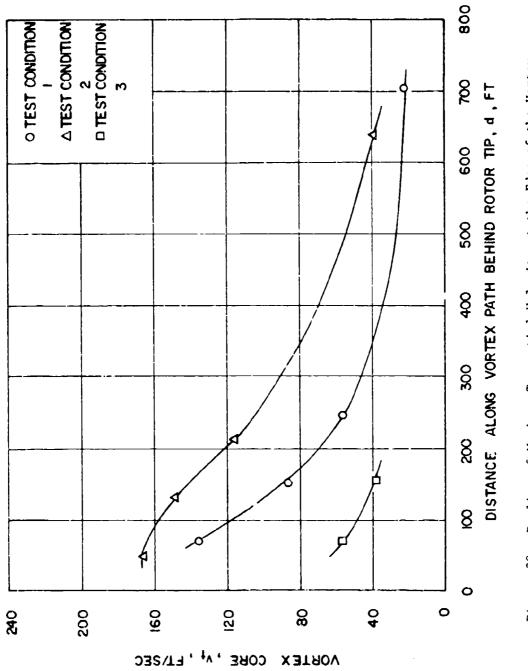


Figure 37. Distribution of Instantaneous Velocity Components Across a 'ortex With Unstable Axial Flow in the Core Region, Test Condition 2, x/R = 0.825, z/R = -0.1.





ARXIMUM TANGENTIAL VELOCITY AT THE EDGE OF THE

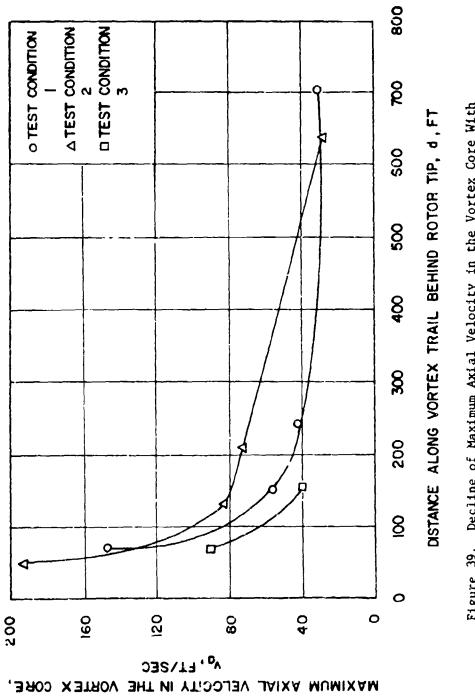


Figure 39. Decline of Maximum Axial Velocity in the Vortex Core With Distance Behind the Blade.

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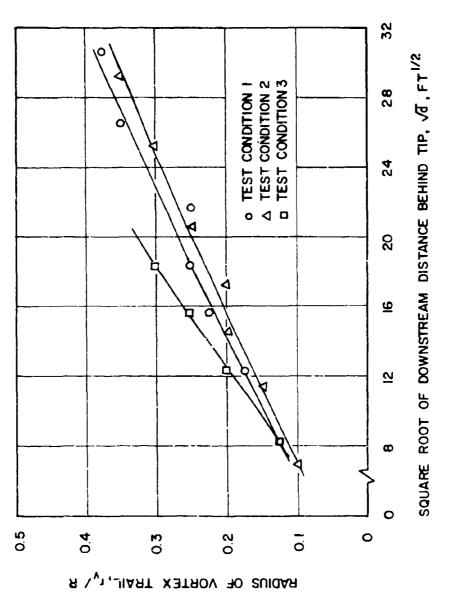
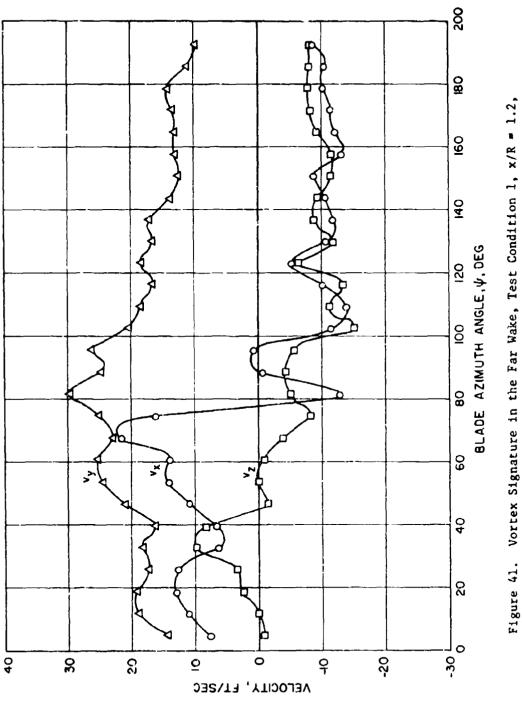


Figure 40. Growth of the Trailing Vortices Downstream of the Blade Tip.



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$\Omega R = 0$	CONDITION 1 631 ft/sec,	L, 2/R ≞ − , [©] 75 = 6 .	25 deg, C _T	= 0.0021			
x/R	¥,deg	⊽ _R /v₀	$\bar{\mathbf{v}}_{\mathbf{x}}/\mathbf{v}_{o}$	v¯ _y ∕∨₀	\bar{v}_{z}/v_{o}	σv _R /νο	σ _ε , de
0.3	0	1.161	028	.410	-1.086	.121	3.7
0.3	45	1.161	.211	.269	-1.109	.037	3.4
0.3	9 0	1.073	.174	.212	-1.038	.032	3.3
0.3	135	.972	.122	.231	937	.042	3.6
0.4	0	1.359	.077	.411	-1.293	.031	2.8
0.4	45	1.336	014	.293	-1.303	.019	2.6
0.4	90	1.281	056	.233	-1.248	.029	2.6
0.4	135	1.145	139	.292	-1.098	.035	2.9
0.5	0	1.515	.029	.401	-1.460	.044	2.7
0.5	45	1.535	040	.255	-1.513	.025	2.6
0.5	9 0	1.505	085	.232	-1.484	.024	2.6
0.5	135	1.518	024	.624	-1.383	.106	8.7
0.6	0	1.694	079	. 396	-1.646	.041	2.8
0.6	45	1.734	163	.238	-1.709	.040	2.6
0.6	9 0	1.672	206	.226	-1.644	.031	4.6
0.6	135	1,660	077	. 306	-1,630	.071	3.5
0.7	0	1.927	209	.412	-1.871	.041	2.6
0.7	45	1.945	299	.200	-1.912	.044	2.6
0.7	9 0	1.897	328	.186	-1.860	.036	2.6
0.7	135	1.843	226	. 229	-1.815	.044	2.6
0.75	0	2.071	222	.455	-2.008	.ن50	3.0
0.75	45	2.127	304	.226	-2.093	.058	2.6
0.75	9 0	2.093	326	.204	- 2.057	.050	3.0
0.75	135	2.082	286	.247	-2.047	.042	2.6
3.0	0	2.260	297	.445	-2.195	.046	2.6
0.8	45	2.331	378	.200	-2.291	051	2.6
0.8	9 0	2.346	349	.195	-2.312	.085	2.8
0.8	135	2.430	630	.174	-2.340	.075	8.9
0.83	0	2.444	685	. 318	-2.325	.101	10.7
0.83	45	2.333	518	.079	-2.273	.037	3.2
0.83	90	3.724	~.101	.486	-3.691	.700	6.8
0.83	135	2.500	1.928	.467	-1.522	.133	9.3

APPENDIX DISTRIBUTIONS OF MEAN WAKE VELOCITY COMPONENTS AND STANDARD DEVIATION PARAMETERS COMPUTED FROM EXPERIMENTAL WAKE SURVEY DATA, OH-13E ROTOR, HOVER CONDITION

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x/R	Ψ,deg	\bar{v}_R/v_o	ν _x /ν _o	⊽ _y /v₀	⊽ _z /v _o	^σ v _R ∕v₀	σ_{ϵ}, deg
0.85	0	2,422	-1.076	.533	-2.103	.171	17.6
0.85	45	2.129	220	.236	-2.105	.092	3.6
0.85	90	3.966	547	2.505	-3.026	2.714	50.9
0.85	135	1.946	-1.638	.550	~.895	.167	5.6
			21030		.055	.107	5.0
0.875	0	2.167	-1.942	.961	022	.621	22.0
0.875	45	.9 30	526	.473	603	. 382	39.1
0.875	90	.527	336	.336	.227	.556	49.3
0.875	135	.944	852	. 384	130	.193	21.6
0.88	0	1.604	-1.425	.710	196	.285	10.0
0.88	45	.701	448	.235	485	.229	30.9
0.88	90	.589	539	.180	.154	.270	34.1
0.88	135	.850	762	.264	268	.175	20.1
0.9	0	.873	671	.535	.161	.192	19.2
0.9	45	. 352	246	.218	127	.138	36.9
0.9	90	.465	396	.243	005	.164	33.0
0.9	135	.512	408	.234	203	.137	27.5
0,925	٥	250	30.0	160	450		
0.925	0	.658	-, 390	.462	.258	.201	31.1
0.925	45	. 310	179	.245	.065	.170	39.0
	90 1.25	. 401	296	.245	.115	.146	29.8
0 .9 25	135	.352	283	.208	.023	.136	38.7
0.95	0	.614	279	، 502	.215	.141	17.2
0.95	45	. 325	150	. 263	.117	.087	29.6
0.95	9 0	.402	266	.269	.136	.106	26.9
0 .95	135	.430	280	.299	.131	.105	27.5
1.0	0	.420	259	. 308	.123	.045	11 4
1.0	45	.255	112	.080	.215	.045	11.4 23.8
1.0	90	. 324	-,222	.150	.181	.034	
1.0	1 35	. 379	276	.147	.213	.034	15.7 11.2
110	1 33		.270	.14/	• 21 3	•029	11.2
1.1	0	. 389	250	.278	.109	.024	4.7
1.1	45	. 350	232	.234	.119	.020	11.9
1.1	90	.383	265	.219	.169	.021	9.7
1.1	135	. 399	275	.238	.163	.023	6.0
1.2	0	. 320	-,227	.163	.156	.014	6.7
1.2	45	. 315	223	.128	.182	.011	6.4
1.2	90	. 322	231	.129	.183	.014	7.6
1.2	135	. 325	237	.158	.157	.014	7.5
						. J L V	e • •

×/R	Ψ ,de g	\bar{v}_R/v_o	$\mathbf{\bar{v}_x}/v_o$	$\bar{\mathbf{v}}_{\mathbf{y}}/\mathbf{v}_{\mathbf{o}}$	$\mathbf{\tilde{v}_{z}}/v_{0}$	σv _R /νο	σ_{ϵ} ,deg
1.3	0	. 294	194	.202	.089	.019	12.3
1.3	45	. 297	194	.205	.092	.024	12.1
1.3	90	. 294	-,195	.200	.091	.017	11.3
1.3	1 35	. 303	200	.209	.088		10.5
1.7	1 32	. 30 5	.200	•207	.000	.025	10.1
1.4	0	. 279	162	.224	.039	.024	5.4
1.4	45	.277	163	.220	.043	.023	5.6
1.4	90	.276	-,161	.221	.038	.019	5.6
1.4	135	.274	164	.217	.035	.023	7.3
	•	2.01	1 20		000		
1.5	0	.281	139	.244	003	.016	5.2
1.5	45	.284	140	.247	003	.013	5.1
1.5	90	. 276	138	. 239	000	.018	5.2
1.5	135	.281	~.138	.244	003	.015	5.1
		2, $z/R = -$					
$\Omega \mathbf{R} = 4$	436 ft/sec	:, 0 ₇₅ = 10).75 deg, C ₁	r = 0.0039			
0.3	0	1.091	.114	.163	-1.073	.032	2.7
0.3	45	1.138	070	.023	-1.136	.042	2.7
0.3	90	1.050	-,156	031	-1.038	.033	2.9
0.3	135	.962	100	.062	955	.109	12.0
0.5		. 302	100	.002	- • • • • •	.109	12.0
0.4	0	1.342	049	.283		.034	2.8
0.4	45	1.428	233	.048		.038	3.0
0.4	9 0	1.364	373	020	-1.312	.043	2.9
0.4	135	1.346	.100	.100	-1.339	.061	3.3
0.5	0	1.520	137	.203	-1.500	.031	2.7
0.5	45	1.632	296	.007	-1.605	.037	2.6
0.5	90	1.569	394		-1.518	.040	2.0
0.5	135	1.497	079	.034	-1.495		
0.5	1.27	1.49/	079	+ U J +	-1.473	.028	2.7
0.6	0	1.705	198	. 304	-1.666	.047	2.6
0.6	45	1.830	370	.074	-1.790	.041	2.6
0.6	90	1.790	401	.015	-1.745	.074	4.2
0.6	135	1.678	199	.103	-1.662	.034	2.6
0.7	0	1.0/1	20/	220	1 000		~ /
		1.941	284	. 329	-1.892	.053	2.6
0.7	45	2.123	444	.057	-2.076	.047	2.6
0.7	90	2.023	471	.035	-1.96?	.044	2.3
0.7	135	2.010	385	.094	-1.970	.049	2.0
0.75	0	2.119	306	.638	-1.997	.04)	2.8
0.75	45	2.299	366	.341	-2.244	.049	2.7
0.75	9 0	2.353	334	.549	-2.263	.169	6.2
0.75	135	2.232	472	. 322	-2.158	.053	2.8

x/R	Ψ,deg	v _R /۰	ت _× /۷ _۵	⊽ _y /v₀	⊽ _z /∿₀	°v _R /vo	ರ ್,deg
0.775	0	2.182	372	.701	-2.032		
0.775	45	2.438	361	.442	-2.371	.070	4.1
0.775	90	3.003	340	.511		.063	3.9
0.775	135	2.268	-1.028	.611	-2.940	.129	3.4
• • • •		2.200	1.020	.011	-1.926	.189	18.0
0.8	0	2.010	515	.231	-1.929	.042	4.0
0.8	45	2.371	159	.147	-2.361	.068	2.6
0.8	90	3.955	-1.454	.235	-3.671	.106	6.0
0.8	135	1.757	-1.390	. 333	-1.021	.067	9.6
0.825	0	1.743	982	.862	-1.154	.195	10 1
0.825	45	2.044	.686	. 435	-1.876	.198	18.1
0.825	90	3.047	-2.802	.942	739	.417	19.5
0.825	135	1.448	-1.102	.578	740		7.1
			_,,,,,	• 570	/40	.105	9.9
0.85	0	1.350	652	.959	690	.126	15.4
0.85	45	1.090	.724	.644	500	.196	9.6
0.85	90	1.360	-1.169	.654	.233	.227	8.9
0.85	135	1,040	677	.664	428	.129	16.3
0.875	0	.823	304	. 749	156	170	
0.875	45	.442	.075	.420	115	.179	20.0
0.875	90	.631	368	.512	.027	.204	34.6
0.875	135	.600	302	.488		.183	23.0
			~. 302	• 400	177	.104	23.0
0 .9	0	.718	299	.648	.075	.136	12.2
0.9	45	.364	.004	.363	016	.114	27.2
0.9	90	.473	247	.403	.017	.095	20.5
0 .9	135	.448	182	. 398	097	.094	22.0
0.000	•					.074	22.0
0.925	0	.679	233	.588	.249	.046	5.9
0.925	45	.355	040	. 3 38	.102	.052	11.3
0.925	90	.413	188	. 347	.123	.048	9.5
0 .9 25	135	. 439	224	. 359	.117	.040	8.6
1.0	0	.480	289	. 370	.104	.055	9.0
1.0	45	.271	106	.106	. 226	.037	23.2
1.0	90	. 352	248	.132	.211	.028	
1.0	135	. 435	306	.165	.261	.028	20.1 8.3
1.1	0	100					
	0	.460	303	. 312	.150	.020	4.2
1.1	45	. 36 3	256	.121	.227	.036	21.7
1.1	90	.427	300	.211	.218	.023	7.4
1.1	135	.462	322	.251	.216	.022	4.2

x/R	¥,deg	ν _R /νε	ν x /ν _o	$\bar{\mathbf{v}}_{\mathbf{y}}/v_{0}$	⊽z/∿o	σ_{v_R/v_o}	σ _ε ,deg
1.2	0	.450	257	.364	.057	.017	3.1
1.2	45	.425	255	. 331	.078	.021	3.2
1.2	90	.438	265	. 339	.084	.016	3.1
1.2	1 35	.437	280	.312	.122	.014	3.5
1.3	0	.419	228	.351	.031	.018	3.1
1.3	45	.404	221	.336	.033	.014	2.7
1.3	90	.409	231	. 334	.047	.014	3.3
1.3	135	.403	236	. 320	.062	.015	3.9
1.4	0	.402	- .195	.351	009	.019	2.7
1.4	45	,401	198	.348	004	.021	2.6
1.4	90	. 399	200	.345	.001	.020	2.7
1.4	135	. 395	202	. 340	.007	.018	2.7
1.5	0	.387	186	. 339	012	.018	2.7
1.5	45	. 382	189	. 332	003	.013	2.6
1.5	90	.374	186	. 325	002	.017	2.7
1.5	135	. 383	187	.334	007	.012	2.7

TEST CONDITION 3, z/R = -0.10 $\Omega R = 454$ ft/sec, $\odot_{75} = 6.25$ deg, $C_T = 0.0020$

			-				
0.3	0	1.094	047	.513	966	.074	8.0
0.3	45	1.171	.132	.424	-1.084	.037	3.0
0.3	9 0	1.109	.107	.400	-1.029	.033	3.3
0.3	135	1.051	.043	.443	952	.043	3.4
• /	0	1 / 07	0.97	(1)	1 363	070	2 2
0.4	0	1.487	.084	.613	-1.352	.070	3.3
0.4	45	1.426	025	.468	-1.347	.053	2.8
0.4	90	1.346	087	.455	-1.264	.041	3.0
0.4	135	1.245	142	.479	-1.141	.061	4.8
0.5	O	1.670	065	.681	-1.524	.054	2.9
0.5	45	1.648	- .175	.519	-1.555	.049	2.9
0.5	90	1.588	240	.510	-1.485	.052	2.8
0.5	135	1.629	022	.937	-1.332	.120	12.7
0.6	0	1.821	066	.706	-1.677	.032	2.6
0.6	45	1.841	137	.522	-1.760	.022	2.6
	-		-				
0.6	90	1.791	- .191	.507	-1.707	.041	2.7
0.6	135	1.809	029	.682	-1.675	.072	6.3

×/R	¥,deg	\bar{v}_R / v_c	v _x / ₂₀	v _y /v _o	v _z /v _o	°v _R /o	σ_{ϵ} , deg
0.7	0	2.044	206	.671	-1.919		• •
0.7	45	2.045	270	.457	-1.975	.040	2.8
0.7	90	2.021	272	.470		.067	2.8
0.7	135	1.996	231	.533	-1.946	.043	2.7
			. 2 3 2		-1.910	.076	2.6
0.75	0	2.124	346	.521	-2.030	077	0 (
0.75	45	2.203	365	.281	-2.154	.077	8.6
0.75	9 0	2.161	377	.293	-2.107	.063	3.3
0.75	135	2.192	380	.293	-2.139	.053	3.6
			. 500	.295	-2.139	.048	3.5
0.8	0	2.274	330	. 396	-2.214	.153	
0.8	45	2.388	481	. 191	-2.332		3.1
0.8	90	2.250	406	.184	-2.205	.144	3.2
0.8	135	2.528	647	.609		.073	3.9
			.047	•009	-2.366	.204	13.7
0.85	0	3.602	815	1.526	-3.159	1.510	22 4
0.85	45	2.381	-1.669	.516	-1.617	.548	23.8
0.85	90	.971	022	. 789	566	1.119	28.1
0.85	135	1.110	937	.561	.198		54.0
					.190	.693	43.0
0.875	0	.922	.248	.649	.607	.559	48.6
0.875	45	.755	438	.402	.465	.577	43.5
0.875	90	.855	707	. 399	. 266	.426	
0.875	135	.851	750	. 342	.213	. 420	30.2
						• 541	23.8
0.9	0	.687	.008	. 541	.423	.131	26.5
0.9	45	.521	127	.397	. 313	.176	31.5
0.9	90	.560	297	. 342	. 328	.184	30.4
0.9	135	.656	413	.437	.264	.166	15.3
							10.5
0.92	0	.633	050	.531	. 341	.102	16.6
0.92	45	.444	060	.361	.251	.091	19.9
0.92	90	.506	185	.364	. 299	.102	22.4
0.92	135	• 5 35	269	.388	.252	.116	23.5
~ ~ ~							2000
0.95	0	.62 9	123	.520	. 332	.056	8.3
0.95	45	.407	048	. 311	.259	.053	13.9
0.95	90	.464	126	.304	.296	.060	11.0
0.95	135	. 507	258	. 385	.206	.062	13.7
							1J•/
1.0	0	.696	138	.563	. 384	.044	10.1
1.0	45	.579	··• U 36	.426	. 390	.046	9.9
1.0	90	.603	144	. 434	. 392	.057	13.1
1.0	135	.634	274	.470	. 325	.066	14.2
							1716

x/R	¥,deg	$\bar{v}_{R}^{\prime}/v_{o}^{\prime}$	$\mathbf{\vec{v}_x}/\mathbf{v_o}$	⊽ _y /∨ _o	$\mathbf{\bar{v}_z}/\mathbf{v_o}$	ov _R /vo	σ_{ϵ} , deg
1.1	0	.553	291	.436	.177	.054	12.6
1.1	45	.540	258	.419	.221	.059	14.4
1.1	9 0	.571	312	.442	.183	.051	11.8
1.1	135	.580	334	. 449	.153	.060	9.9
		••					
1.2	0	.517	265	.422	.137	.073	15.6
1.2	45	.515	282	.406	.142	.037	15.9
1.2	90	.519	281	.423	.108	.037	13.8
1.2	135	.523	277	, 435	.087	.036	13.1
1.3	0	.469	233	.403	.056	.048	10,1
1.3	45	.470	232	.404	.064	.050	10.4
1.3	90	.460	225	. 397	.051	.051	10.6
1.3	135	.454	-,218	. 396	.039	.062	11.9
1.4	0	. 395	188	.345	.03ô	.046	11.1
1.4	45	.402	194	. 349	.050	.048	11.2
1.4	90	. 395	195	. 342	.035	.045	11.3
1.4	135	. 389	188	. 339	.025	.048	10.7
T • 4	L L L	. 505	.100		.025	1040	2017
1.5	0	.408	177	. 36 7	.026	.034	12
1.5	45	.423	195	.374	.02 9	.040	11.0
1.5	9 0	.425	189	. 380	.020	.038	10.9
1.5	135	,411	180	.368	.023	.035	11.6
TEST	CONDITION	1, $z/R = -$	0.30				
Ω R [⊷]	634 ft/sec	°, ⁰ 75 [∞] 6.	25 deg, C _T	= 0.0020			
0.3	0	1.215	1.76	 079	-1.199	.080	6.4
0.3	45	1.237	186	214	-1.204	.041	3.3
0.3	90	1.181	227	254	-1.131	.046	3.2
0.3	135	1.122	240	251	-1.067	.050	3.4
0.4	0	1.502	269	211	-1.463	.034	2.6
0.4	45	1.467	326	102	-1.427	.089	6.6
0.4	90	1.565	157	199	-1.544	.050	2.8
0.4	135	1.513	176	~.209	-1.488	.045	2.6
0.5	0	1.675	294	239	-1.632	.036	2.8
0.5	45	1.735	204	165	-1.715	.081	3.2
0.5	90	1.707	242	267	-1.669	.044	2.7
0.5	135	1.665	285	267	-1.618	.032	2.8

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×/R	¥,d eg	\bar{v}_{R}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{x}}/\mathbf{v}_{\mathbf{o}}$	⊽ _y /v _o	\bar{v}_z / v_o	σv _R /vo	σ_{ϵ} , deg
0.6	0	1.943	267	147	-1.919	.059	2,8
0.6	45	1.978	323	235	-1.938	.066	2.6
0.6	90	1.942	366	249	-1.891	.071	2.6
0.6	135	1.924	391	245	-1.867	.072	3.1
							0.2
0.7	0	2.016	230	077	-2.002	.410	5.8
0.7	45	2.105	321	125	-2.077	.431	7.8
0.7	9 0	2.002	453	128	-1.946	.365	12.4
0.7	135	1.855	381	001	-1.815	.277	12.1
0.8	0	1.641	456	121	-1.572	.738	41.3
0.8	45	1.896	595	448	-1.743	.483	19.2
0.8	90	1.930	696	172	- 1.792	.531	22.6
0.8	135	1.765	323	103	-1.732	. 391	21.9
0.825	0	1.261	403	.014	-1.194	.930	48.2
0.825	45	1.388	681	015	-1.210	.666	34.1
0.825	90	1.530	698	164	-1.351	.733	35.1
0.825	135	1.408	649	035	1.249	.497	32.1
0.850	0	.245	.172	172	028	.587	59.5
0.850	45	.265	098	246	011	.570	65.7
0.850	90	. 360	232	275	020	. 400	54.7
0.850	135	.477	333	203	274	.362	49.0
01050	1.32	• • • / /	-•555	-1205	-+274	• 202	49.0
0.9	0	. 330	085	278	.156	. 307	46.9
0.9	45	. 380	115	~.344	.111	. 322	51.2
0.9	9 0	. 354	196	294	023	.259	50.6
0.9	135	.282	106	226	131	.281	54.3
1.0	0	.423	003	383	.181	.059	16.7
1.0	45	.450	.030	418	.162	.068	16.2
1.0	9 0	.455	014	422	.170	.077	17.8
1.0	135	.456	.001	422	.173	.054	18.5
1.1	0	. 326	167	215	.179	0.25	19 /
1.1	45	. 325	146	215 248	.179	.035 .051	18.4
-		. 343					21.4
1.1 1.1	90 135	. 343	171 193	245	.167	.042	15.6
*• *	101	0,00	175	236	.182	.033	15.6
1.2	0	. 333	111	293	.095	.038	19.5
1.2	45	. 332	085	308	.089	.046	20.3
1.2	90	. 340	104	312	.088	.043	20.0
1.2	135	. 336	112	302	-098	.044	20.3
							_0.5

x/R	¥,deg	\bar{v}_{R}/v_{o}	⊽ _x /v₀	$\mathbf{\bar{v}}_{y}/v_{o}$	⊽ _z /v₀	σ v_R/v_o	$\sigma_{\epsilon}^{}$, deg
1.3	0	. 308	185	241	.048	.018	1 2 7
1.3	45	. 302	168	244	.040	.018	13.7
1.3	90	. 315	188	249	.047	.022	16.7
1.3	135	. 308	189	239	.047	.020	13.3
			1109	• 2 3 3	.045	.025	14.6
1.4	0	.254	097	224	070	.144	36.9
1.4	45	.251	089	223	073	.163	37.9
1.4	90	.263	091	232	083	.178	37.6
1.4	135	.262	093	225	095	.197	37.9
1.5	0	.282	111	258	026	.116	26.7
1.5	45	.282	107	259	030	.133	26.7
1.5	9 0	.288	117	261	034	.157	20.7
1.5	135	.287	119	258	039	.188	27.0
						.100	27.9
	CONDITION						
$\Omega R =$	429 ft/sec	• ⁰ 75 = 10	.75 deg, C ₁	= 0.0040			
0.3	0	.724	055	. 31 3	651	.266	29.5
0.3	45	.704	058	.179	678	.264	33.9
0.3	90	.713	015	.134	700	.278	31.3
0.3	135	.678	.020	.222	640	.280	34.8
0.4	0	1.168	.003	.032	-1.168	.129	6.2
0.4	45	1.396	.089	002	-1.393	.071	6.3 6.3
0.4	9 0	1.262	.038	133	-1.255	.058	
0.4	135	1.144	026	136	-1.136	.044	4.2 4.4
					1.150	.044	4.4
0.5	0	1.681	028	018	-1.681	.022	2.6
0.5	45	1.673	128	086	-1.666	.036	2.7
0.5	90	1.623	167	118	-1.610	.065	3.7
0.5	135	1.657	.081	067	-1.653	.031	2.6
0.6	0	1.786	007	076	-1.785	.032	2.6
0.6	45	1.773	115	157	-1.763	.025	2.6
0.6	9 0	1.816	.086	.094	-1.811	.088	4.3
0.6	13 5	1.785	.123	119	-1.777	.030	2.6
0.7	0	1 0 70	04 5				
0.7	45	1.970	065	141	-1.964	.047	2.6
0.7		2.033	100	217	-2.019	.053	2.7
	90 125	2.065	.101	170	-2.056	.044	2.6
0.7	1.35	1.978	.036	160	-1.971	.044	2.7

x/R	Ψ,deg	\bar{v}_R / v_o	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	v _y /vo	$\bar{\mathbf{v}}_{\mathbf{z}}/v_{o}$	σ _{VK} /νο	σ_{ϵ} , deg
0.8	0	1.985	119	184	-1.973	.113	4.4
0.8	45	2.326	.197	145	-2.313	.102	2.7
0.8	90	2.292	.038	164	-2.286	.050	
0.8	135	2.123	022	181	-2.115		2.6
	200	2.225	.022		-2.115	.035	2.7
0.85	0	1.629	.149	211	-1.608	.228	11.3
0.85	45	2.026	.741	354	-1.852	.287	9.6
0.85	9 0	3.261	. 293	112	-3.246	.599	13.7
0.85	135	2.228	603	270	-2.127	. 342	14.8
					/	• 342	14.0
0.875	0	1.070	.195	338	996	.286	25.7
0.875	45	1.475	.982	262	-1.069	.215	17.2
0.875	90	2.041	1.862	.760	. 349	3.149	45.2
0.875	135	1.829	-1.460	342	-1.048	.565	21.5
~ ~	•						
0.9	0	.586	.067	423	400	.115	14.4
0.9	45	.613	.420	430	123	.212	27.0
0.9	90	.573	.090	483	.296	.207	36.3
0.9	135	.641	434	454	.124	.188	31.4
1.0	0	. 374	.024	366	075	1.45	<u> </u>
1.0	45	. 448	.141	424		.125	20.6
1.0	90	.440	.141		035	.144	19.5
1.0	135	.430	.005	438	.039	.159	23.6
1.0	135	.411	.005	407	.057	.228	31.8
1.1	0	. 359	035	- .357	.013	.049	16.5
1.1	45	. 396	.018	394	.024	.045	13.8
1.1	9 0	.402	.010	400	.034	.049	14.6
1.1	1 35	. 399	022	396	.040	.051	15.4
							1914
1.2	0	. 389	023	383	061	.052	6.8
1.2	45	.403	003	400	047	.048	7.4
1.2	90	.404	006	401	043	.049	7.5
1.2	135	.394	032	390	047	.055	10.6
1.3	0	. 358	006	25.7		<u> </u>	
1.3	45	.338	.006	357	019	.025	10.3
1.3	43 90		.021	372	010	.029	8.3
		.377	.009	376	016	.026	8.1
1.3	135	. 373	009	372	027	.034	6.6
1.4	0	. 31 3	058	300	067	.065	20.8
1.4	45	. 322	050	312	063	.060	20.8
1.4	90	. 336	051	325	068	.066	19.0
1.4	135	. 337	060	324	069	.008	
		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	.000	• 32 4	.009	.0/3	19.4

x/R	¥,deg	\tilde{v}_R / v_o	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	\bar{v}_y/v_o	\bar{v}_z/v_o	σ _{v_R/ν_o}	σ _ε ,deg
1.5	0	. 331	.008	327	054	.064	12.1
1.5	45	. 335	.010	332	042	.068	14.1
1.5	90	. 336	.007	332	054	.058	14.9
1.5	135	. 333	.002	329	056	.064	14.2
1	-05						
		3, z/R = -		- 0.0019			
11R = 1	abu it/sec	· ⁰ 75 - 0.	25 deg, C _T	₩ 0,0010			
0.3	0	1.118	025	024	-1.118	.112	9.7
0.3	45	1.252	.066	.122	-1.244	.177	11.0
0.3	9 0	1.223	.083	.111	-1.215	.134	13.9
0.3	135	1.145	.053	.024	-1.143	.131	13.1
0.4	0	1.585	.123	266	-1.557	.092	2.8
0.4	45	1.537	.038	311	-1.505	.051	3.0
0.4	90	1.469	.019	329	-1.432	.079	3.9
0.4	135	1.516	.191	135	-1.498	.112	5.7
•••							
0.5	0	1.806	065	222	-1.791	.057	4.1
0.5	45	1.781	- .026	019	-1.780	.091	5.1
0.5	90	1.864	.039	286	-1.842	.070	3.0
0.5	135	1.805	.005	287	-1.782	.064	3.1
0.6	0	1,983	.036	· - .027	-1.983	.103	6.7
0.6	45	2,112	.140	295	-2.087	.058	3.1
0.6	90	2.048	.069	327	-2.020	.076	3.7
0.6	135	1.986	.003	339	-1.956	.076	4.1
0.7	0	2.264	100	.402	-2.225	.200	4.8
0.7	45	2.307	176	. 376	-2.269	.224	6.3
0.7	90	2.251	218	. 381	-2.208	.217	5.9
0.7	135	2.236	261	.466	-2.171	.212	5.7
0.,	200	21250		.400	212/2		2.1
0.75	0	2.605	115	. 393	-2.572	.487	4.5
0.75	45	2.413	431	. 396	-2.341	.281	14.5
0.75	9 0	2.253	277	. 2.39	-2.223	.128	6.7
0.75	1 35	2.088	299	. 369	-2.033	.128	14.8
0.8	0	2.465	107	.186	-2.455	.267	11.0
0.8	45	2.381	314	033	-2.360	. 338	14.2
0.8	90	2.278	356	138	-2.246	.227	13.4
0.8	1 35	2.093	277	.024	-2.074	. 290	14.7
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x/R	^y ,deg	\bar{v}_{R}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{x}}/v_{o}$	⊽ _y /v₀	⊽ _z /∨₀	σv _R /ν _o	σ _ε ,deg
0,825	0	1.642	.053	1.095			•
0,825	45	1.759	.185		-1.222	. 367	27.0
0.825	90	1,814	. 244	,770	-1.571	.498	26.5
0.825	135	1.501	037	1.090	-1.429	.463	29.2
		1, 301	037	.553	-1.395	.564	36.9
0.85	0	.562	.218	.248	455	.951	57 .5
0.85	45	.649	.064	.251	594	.965	
0.85	9 0	.591	307	.259	434	.861	63.0
0.85	135	• 890	594	.207	629	.677	52.3 50.4
0.9	0	.174	140	000			
0.9	45	.461	241	.098	.029	.935	68.8
0.9	90	. 850		075	386	.770	58.4
0.9	135	1.053	380	.026	760	.826	48.7
	13 5	1.000	321	120	995	.578	34.2
1.0	0	.220	011	-,220	.013	. 367	57.0
1.0	45	.236	025	234	018	. 399	57.9
1.0	90	.247	073	226	071	.428	56.0
1.0	135	•276	099	216	140	.464	52.3 54.4
1.1	0	- 228	- 1/9				
1.1	45	.236	148 131	161	.066	.036	25.9
1.1	90	.249		193	.036	.034	24.2
1.1	135	.268	150	187	.067	.037	25.9
	1 3 3	•200	188	166	.096	.033	19.5
1.2	0	.178	.024	032	.157	.073	43.6
1.2	45	.184	.031	096	.154	.075	43.8
1.2	9 0	.199	.032	110	.162	.071	38.3
1.2	135	.200	.021	118	. 160	.073	38.2
1.3	0				1200	1075	30,2
1.3	0	•211	188	014	.093	.035	23.4
1.3	45	.200	175	024	.094	.036	25.4
	90	.208	180	016	.103	.039	25.8
1.3	135	.211	188	014	.095	.034	23.3
1.4	0	,225	156	.098	.128	000	
1.4	45	.221	153	.090	.132	.022	13.1
1.4	9 0	.227	162	.096	.132	.022	13.4
1.4	135	.227	161	.103		.022	9.9
				•103	.122	.020	10.7
1.5	0	.266	156	.173	.130	.033	19.7
1.5	45	.262	158	.159	.137	.039	22.3
1.5	90	.265	159	.173	.123	.035	17.6
1.5	135	.269	161	.182	.114	.036	17.6
						.050	10.4

TEST CONDITION 1, z/R = -0.50 $\Omega R = 634$ ft/sec, $\Theta_{75} = 6.25$ deg, $C_T = 0.0020$

x/R	Ÿ,deg	ν _R /ν _ο	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	⊽ _y /∿₀	⊽ _z /∨₀	σ _{VR} /vo	$\sigma_{\varepsilon}, \deg$
0.3	0	1.330	058	.486	-1.236	.044	3.5
0.3	45	1.477	.006	. 4 30	-1.413	.062	3.5
0.3	90	1.443	043	.401	-1.385	.044	2.6
0.3	135	1.401	062	.423	-1.334	.044	2.6
0.4	0	1.594	-,087	. 327	-1.558	.143	5.3
0.4	45	1.570	119	. 306	-1.535	.112	5.2
0.4	90	1.581	084	.541	-1.483	.126	7.1
0.4	135	1.626	040	.351	-1.587	.094	4.8
0.5	0	1.745	- 194	. 373	-1.694	.066	3.9
0.5	45	1.908	098	. 385	-1.866	.058	3.4
0.5	90	1.820	119	. 320	-1.788	.041	2.6
0.5	135	1.765	141	.321	-1.730	.038	2.6
0.6	0	2.044	166	.356	-2.006	.163	6.0
0.6	45	2.009	235	.219	-1.983	.107	6.5
0.6	90	1.962	187	.201	-1.943	.080	3.8
0.6	135	1.946	164	. 319	-1.912	.089	5.8
0.7	0	1.927	251	. 360	-1.876	. 305	18.6
Ŭ.7	45	1.872	332	.229	-1.828	.307	19.6
0.7	9 0	1.818	355	.222	-1.769	.292	22.1
0,7	135	1.821	141	.272	- 1.795	.226	16.2
0.75	0	1.673	409	. 340	-1.586	.297	27.7
0.75	45	1.627	361	. 239	-1.569	.262	26.5
0.75	9 0	1.610	131	.205	-1.592	.227	24.8
0.75	135	1.614	.151	.182	-1.596	.246	23.1
0.775	0	1.461	208	. 384	-1.395	.530	32.6
0.775	45	1.402	299	. 390	-1.313	.510	36.4
0.775	90	1.306	246	.242	-1.260	.404	38.7
0.775	135	1.356	181	.117	-1.338	, 383	30.2
0.8	0	.637	053	.590	234	. 383	41.5
0.8	45	.747	- .151	.605	411	. 398	41.3
0.8	9 0	.629	078	.478	401	. 406	51.6
0.8	135	.678	.150	.467	468	.456	44.7
0.9	0	.286	144	.205	.138	.101	32.7
0.9	45	.237	120	.171	.112	.104	33.7
0.9	90	.260	122	.183	.137	.110	38.4
0.9	135	.257	110	.176	.146	.128	39.0

x/R	¥,deg	\bar{v}_{R}/v_{o}	⊽ _x /∨ _o	⊽ _y /∨ _o	$\mathbf{\bar{v}_z}/v_o$	σv _R /ν _o	σ _ε , deg
1.0	0	.351	065	.297	.176	.047	11.3
1.0	45	. 334	059	.285	.164	.043	13.0
1.0	90	. 334	062	.276	.177	.035	13.7
1.0	135	. 352	068	.282	.200	.035	
			1000		.200	.020	12.8
1.1	0	.273	148	.208	.096	.029	14 7
1.1	45	.261	~.149	.195	.088	.023	14.7
1.1	90	.267	154	.199	.088	.028	17.2
1.1	135	.279	166	.202	.000	.028	14.3
					.070	•031	16.0
1.2	0	.268	129	.210	.106	.015	11.9
1.2	45	.258	117	.202	.109	.013	10.2
1.2	90	. 262	129	.203	.103	.015	12.1
1.2	135	.267	138	. 206	.099	.015	
			1190	1200	.075	•017	1.2.0
1.3	0	.275	149	. 2 30	.020	.020	6.1
1.3	45	.260	141	.217	.020	.017	6.4
1.3	90	.269	149	.223	.025	.019	6.8
1.3	135	.267	152	.217	.030	.019	8.2
				•== /	.030	.019	0.2
1.4	0	.234	121	.183	.081	.056	22.9
1.4	45	.231	109	.181	.092	.048	20.2
1.4	90	. 2 39	117	.187	.091	.052	20.2
1.4	135	.238	122	.182	.092	.045	18.3
					.052	.045	10.7
1.5	0	.291	173	.233	.025	.015	7.0
1.5	45	.292	173	.234	.023	.020	8.0
1.5	90	.287	173	. 227	.030	.016	7.2
1.5	135	. 295	181	.232	.029	.016	7.0
TEST ΩR ■	CONDITION : 429 ft/sec	2, z/R = - , ⁰ 75 = 10	-0.50).75 deg, C _T	- 0.0040			
0.3	0	1.319	.023	. 386	-1.261	.169	6.1
0.3	45	1.412	.022	. 400	-1.354	.155	5.3
0.3	9 0	1.358	.015	. 318	-1.320	.109	5.4
0.3	135	1.299	.016	. 321	-1.259	.052	5.7
					,	1052	5.7
0.4	0	1.655	043	. 333	-1.621	.039	3.2
0.4	45	1.637	098	. 292	-1.608	.032	3.0
0.4	90	1.615	084	. 292	-1.586	.068	3.5
0.4	135	1.716	044	. 326	-1.684	.040	2.7
							~ • /
0.5	0	1.826	097	.256	-1.806	.040	2.8
0.5	45	1.947	024	.492	-1.884	.094	3.4
0.5	9 0	1.945	058	.250	-1.928	.044	2.6
0.5	135	1.885	145	.214	-1.867	.061	2.7
							A: ♦ 7

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x/R	Ψ,deg	$\bar{v}_{R}^{\prime}/v_{o}$	$\nabla_{\mathbf{x}}/\nabla_{0}$	⊽ _y /∨₀	⊽ _z /∨₀	° _{VR} ∕v₀	₀ _€ ,deg
0.6	0	2.106	.008	. 342	-2.078	.096	4.2
0.6	45	2.299	009	.187	-2.291	.141	2,7
0.6	9 0	2.244	242	.043	-2.230	.090	5.1
0.6	135	2.159	320	.013	-2.135	.053	5.1
							512
0.7	0	1.850	.235	.171	-1.827	.149	4.5
0.7	45	2,107	.651	.136	-1.999	. 322	12.5
0.7	9 0	2.402	-,897	1.272	-1.830	. 806	34.2
0.7	13 5	2.145	938	. 404	-1.886	.373	23.0
0.8	0	1.276	. 896	.545	-,726	.668	39.4
0.8	45	1.025	.471	.719	-,558	.848	45.1
0.8	9 0	.686	005	.686	032	.653	52.8
0.8	135	.700	281	.620	165	.587	49.1
0.9	0	.141	.074	.094	.074	. 300	61.6
0.9	45	.083	.013	.002	.082	.401	61.1
0.9	9 0	.185	134	.101	.079	. 395	50.4
0 .9	135	.225	156	.132	.094	.276	51.1
1.0	0	.206	160	.062	.114	.035	19.4
1.0	45	.192	142	.052	.118	.036	22.5
1.0	9 0	.200	156	.054	.114	.035	21.6
1.0	135	.194	152	.042	.114	.090	24.5
1.1	0	. 225	175	.086	.113	.028	12.3
1.1	45	.203	159	.075	.101	.028	12.8
1.1	9 0	. 210	-,172	.074	.096	.025	12.6
1.1	1.35	.225	188	.067	.104	.029	11.9
1.2	0	.234	217	.049	.072	.026	9.7
1.2	45	.220	207	.043	.059	.029	10.5
1.2	9 0	.224	213	.037	.057	.028	10.8
1.2	135	. 2 39	231	.033	.050	.025	10.4
1.3	0	.260	200	.143	.084	.016	11.5
1.3	45	.257	185	.162	.073	.018	7.4
1.3	9 0	.262	198	.150	.084	.026	10.2
1.3	135	.255	202	.116	.105	.025	15.6
1.4	0	.255	234	.038	.094	.019	12.1
1.4	45	. 249	225	.030	.102	.017	11.4
1.4	9 0	.260	241	.052	.083	.015	10.6
1.4	135	. 263	248	.035	.082	.018	6.2

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x/R	¥,deg	$\bar{v}_{R}^{\prime}/v_{o}^{\prime}$	ν¯ _x /ν _o	$\mathbf{\bar{v}_y}/\mathbf{v_o}$	$\bar{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{\mathbf{o}}$	σv _R /νο	σ_{ϵ} , deg
1.5	0	.247	208	.122	.053	.026	15.0
1.5	45	.245	205	.125	.052	.018	12.9
1.5	9 0	.257	-,212	.136	.050	.021	11.4
1.5	135	.257	219	.127	.050	.024	11.0

and the second

TEST CONDITION 3, z/R = -0.50 $\Omega R = 450$ ft/sec, $\odot_{75} = 6.25$ deg, $C_{I} = 0.0020$

0.3	0	1.705	101	.462	-1.638	.051	3.0
0.3	45	1.685	137	.438	-1.621	.061	3.2
0.3	90	1.607	161	.412	-1.544	.073	3.6
0.3	135	1.643	043	.539	-1.551	.110	6.0
010	200	1.045	••••	••••	2,552		•••
0.4	0	1.802	204	.354	-1.755	.095	4.5
0.4	45	1.742	199	. 390	-1.686	.087	4.8
0.4	9 0	1.811	076	.478	-1.745	.132	4.4
0.4	135	1.826	124	. 323	-1.793	.059	3.8
0.5	0	2.073	123	.527	-2.001	.140	5.1
0.5	45	2.068	165	.294	-2.040	.087	3.5
0.5	90	2.058	187	.283	-2.030	.100	3,4
0.5	135	2.050	225	.286	-2.017	.071	3.5
0.6	0	1.689	052	.701	-1.536	.361	21.8
0.6	45	1.832	053	.570	-1.740	.229	21.7
0.6	90	1.815	.098	.477	-1.748	. 308	20.5
0.6	135	1.776	544	.545	-1.601	.426	27.1
0.7	0	.430	047	.378	199	. 302	38.6
0.7	45	. 357	.002	. 308	180	. 318	46.9
0.7	9 0	.379	026	. 339	168	. 339	44.8
0.7	135	. 370	031	. 328	168	. 314	48.1
0.8	0	. 331	147	.295	.033	.041	12.2
0.8	45	. 317	142	.284	.017	.047	12.1
0.8	9 0	. 313	129	.282	.041	.041	13.9
0.8	135	. 309	125	.278	,051	.035	13.4
0.9	0	. 320	183	.259	.041	.024	5.0
0.9	45	. 297	168	.242	.035	.021	5.0
0.9	90	. 296	~.172	.237	.045	.025	5.3
0.9	135	. 298	176	.234	.055	.019	6.4
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×/R	¥,deg	Ÿ _R /√₀	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	$\overline{\mathbf{v}}_{\mathbf{y}}/\mathbf{v}_{\mathbf{o}}$	ν _z /ν _o	σv _R /v _o	σ _ε ,deg
1.0	0	• 2 3 9	167	.163	.050	.171	20.4
1.0	45	.213	153	.142	.041	.224	22.6
1.0	9 0	,204	151	.131	.040	.249	23.7
1.0	135	.198	152	.120	.040	. 310	27.9
						. 520	27.9
1.1	0	. 322	233	. 152	.162	.026	8.7
1.1	45	.298	216	.135	.156	.022	9.8
1.1	90	. 302	214	.132	.167		8.5
1.1	135	, 309	220	.143	. 162	.028	7.6
1.2	0	. 360	267	.196	.142	.014	7.8
1.2	45	.351	258	.196	.133	.015	5.4
1.2	9 0	. 344	252	.190	.137	.019	6.8
1.2	135	.345	251	.185	.145	.015	7.7
1.3	0	.372	304	.160	.144	.029	12.8
1.3	45	.368	298	.168	.136	.029	11.7
1.3	90	. 254	280	.155	.152	.030	14.1
ι.3	135	.358	288	.154	.146	.027	13.1
1.4	0	.412	334	.192	.147	.042	13.6
1.4	45	.401	323	.182	.151	.037	14.5
1.4	90	. 397	314	.189	.153		
1.4	135	. 39 3	307	.198	.145	.038	14.0
1.5	0	. 397	303	.219	.134	.022	12.9
1.5	4.5	.385	305	.191	.137	.027	14.7
1.5	9 0	. 388	29%	.223	.120	.024	9.0
1.5	135	. 386	282	. 236	.119	.025	8.8
$\Omega R = 6$		l, z/R = - , ⊖ ₇₅ = 6.	0.70 25 deg, C _T	- 0.0020			
0.3	0	. 859	086	.218	827	.172	17.4
0.3	45	.858	043	.139	846	.186	19.4
0.3	9 0	.813	054	.194	788	.191	20.5
0.3	135	.865	094	.195	837	.175	18.2
0.4	0	1 22 3	010	000	1 200		. .
0.4	0	1.323	.020	.090	-1.320	.085	5.6
0.4	45	1.334	011	.101	-1.330	.122	5.6
	90	1.324	.022	.021	-1.323	.101	5.0
0.4	135	1.274	.020	015	-1.274	.117	7.3
0.5	0	1.758	.037	048	-1.756	.047	3.1
0.5	45	1.741	.014	066	-1.740	.054	3.1
0.5	90	1.704	.009	045	-1.704	.086	3.3
0.5	135	1.735	.025	.005	-1.735	.097	3,8
							5.0

x/R	Ψ,d_g	$\bar{v}_R^{/\nu}$ o	⊽ _x /∿₀	⊽y/∿o	ν¯ _z /ν _ο	^σ v _R ∕v _o	σ_{e} , deg
0.6	0	1.924	053				-
0.6	45	1.924	.053	047	-1.922	.149	4.0
0.6	90	1.945	.077	080	-1.981	.109	3.2
0.6	135		.095	197	-1.933	.088	3.7
0.0	1.))	1.899	.063	195	-1.888	.075	3.7
0.7	0	2.083	.058	.020	-2,082	.064	3.1
0.7	45	2.069	.044	.013	-2.068	.079	2.9
0.7	90	2.046	.017	.019	-2.045	.082	2.7
0.7	135	2.083	.048	.186	-2.074	.123	3.6
8.0	0	1.984	.123	. 2 39	-1.966	.109	4.2
0.8	45	2.131	.111	. 312	-2.105	.191	4.8
0.8	90	2.390	.098	. 299	-2.369	.378	5.9
0.8	135	2.328	.074	.288	-2.309	.177	6.2
0.875	0	1.582	.218	001	-1.567	.203	7.0
0.875	45	1.443	. 4 39	.104	-1.370	.203	7.9
0.875	9 0	1.295	.512	.231	-1.166	.535	25.0
0.875	1 35	1.366	084	.150	-1.355	.535	39.0 46.9
0.9	0	1 2/3		0.0.5			
0.9	45	1.243	.108	025	-1.238	. 342	25.3
0.9	40 90	1.107	. 337	.148	947	.460	41.4
0.9		.845	. 443	.259	672	.611	47.1
0.9	135	.873	.201	.265	807	.783	61.0
1.0	0	.441	073	.135	414	. 309	48.2
1.0	45	. 375	117	.103	341	.264	49.1
1.0	9 0	.337	138	006	307	.269	49.1
1.0	135	.370	157	025	334	.245	47.5
1.1	0	.170	060	.001	159	.050	31.5
1.1	45	.166	053	010	157	.045	31.9
i.1	90	.157	068	019	140	.045	32.5
1.1	135	.159	085	013	134	.055	35.6
						.055	22.0
1.2	0	.197	048	.168	091	.064	27.5
1.2	45	.196	057	.163	092	.062	25.6
1.2	90	.190	057	.160	086	.067	29.7
1.2	135	.190	056	.161	082	.057	28.2
1.3	0	.122	075	056	079	.016	18.5
1.3	45	.123	066	060	084	.013	16.8
1.3	90	.124	074	058	082	.015	18.2
1.3	135	.125	073	059	082	.014	17.8
					.002	1014	1/*0

x/R	¥,deg	\bar{v}_{R}/v_{c}	$\mathbf{\bar{v}_x}/\mathbf{v_c}$	\bar{v}_y/v_o	$\bar{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{0}$	σv _R /v _o	₀ _€ ,deg
1.4	0	.189	028	.065	176	.043	16.3
1.4	45	.188	033	.066	173	.043	18.5
1.4	90	.182	031	.060	169	.041	22.5
1.4	135	.184	031	.066	169	.041	21.4
±	1 35	.104		.000	109	1042	21.4
1.5	0	.092	046	045	066	.033	41.9
1.5	45	.092	046	046	065	.034	40.5
1.5	9 0	.089	048	049	060	.038	41.3
1.5	135	.089	048	044	061	.037	41.7
		2, z/R = -		0.0000			
17K = 4	+50 ft/sec	• ⁶ 75 = 10	0.75 deg, C ₁	= 0.0039			
0.3	0	.695	018	.192	-,668	.248	24.6
0.3	45	.711	058	.200	680	.229	23.7
0.3	9 0	.673	.051	.185	645	.244	26.7
0.3	1 35	.685	.021	.171	663	. 2 36	29.5
o /	•	1 2/7	0.07	045			
0.4	0	1.347	.027	.065	-1.345	.059	3.7
0.4	45	1.346	014	.099	-1.342	.073	3.5
0.4	90	1.383	.038	.069	-1.381	.085	5.3
0.4	135	1.365	.020	.082	-1.363	.107	4.7
0.5	0	1.668	.034	.035	-1.667	.041	2.6
0.5	45	1.611	.014	.030	-1.610	.048	2.6
0.5	90	1.591	.027	.037	-1.590	.058	2.8
0.5	135	1,718	.064	.027	-1.717	.044	2.6
0 (•						• •
0.6	0	1.722	050	.119	-1.717	.055	3.0
0.6	45	1.890	.123	.131	-1.882	.096	2.9
0.6	90	1.902	.100	.091	-1.897	.055	2.7
0.6	135	1.850	.041	.106	-1.846	.057	2.6
0.7	0	2.033	.084	.129	-2.027	.060	2.6
0.7	45	2.004	.081	.120	-1.998	.065	2.6
0.7	90	2.008	.073	.135	-2.002	.076	2.9
0.7	135	2.170	.123	. 28	-2.154	.098	3.0
~ ~							
0.8	0	1.987	.089	.096	-1.983	.044	2.8
0.8	45	1.968	.106	.068	-1.964	.069	4.0
0.8	90	2.012	.190	.059	-2.003	.070	2.6
0.8	135	2.272	. 347	.032	-2.245	.074	2.8
0.9	0	1.232	053	.079	-1.229	. 378	25.7
J.9	45	1.325	.175	.109	-1.309	.241	17.0
0.9	90	1.598	.698	022	-1.438	.556	29.7
0.9	135	2.196	.699	094	-2.080	.691	29.3

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x/R	Ψ,deg	v _R /v _o	\bar{v}_{x}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{y}}/\mathbf{v}_{\mathbf{o}}$	$\overline{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{0}$	σv _R /νο	σ_{ϵ} ,deg
0.95	0	.724	179	.072	698	. 318	40.2
0.95	45	.723	.121	033	712	. 387	36.9
0.95	90	.8 75	.672	052	-,557	.472	40.1
0.95	135	.993	.969	001	219	.698	43.6
							4310
1.0	0	.414	125	.067	389	.226	30.9
1.0	45	.426	.050	.122	405	.215	29.9
1.0	90	. 401	.195	.262	233	. 397	44.6
1.0	135	.278	.220	.112	128	. 499	50.4
1.1	0	.133	098	.087	024	.081	36.3
1.1	45	.132	073	.095	054	. 109	40.4
1.1	9 0	.115	055	.093	039	.111	43.9
1.1	135	.117	- .052	.102	024	.121	45.2
1.2	0	.172	055	.161	027	.042	19.1
1.2	45	.157	048	.146	030	.030	23.5
1.2	90	.158	050	.148	026	.033	24.5
1.2	135	.160	055	.148	021	.032	24.8
1.3	0	.134	043	.123	032	.036	24.6
1.3	45	.127	041	.116	028	.041	26.7
1.3	90	.120	039	.119	- .029	.045	24.8
1.3	135	.135	049	.123	023	.043	24.4
. ,							
1.4	0	.080	016	.078	008	.059	3 9. 7
1.4	45	.073	007	.073	001	.055	43.7
1.4	90	.071	009	.071	006	.061	46.3
1.4	135	.083	014	.082	.008	.055	39.7
1 5	0	10%				• • •	
1.5	0	.103	.001	.102	.013	.011	11.5
1.5	45	.104	.001	.103	.010	.012	10.5
1.5	90	.101	001	.100	.012	.013	11.6
1.5	135	.106	008	.105	.013	.014	11.1
ተፑፍጥ ብ		3, z/R = -	0 70				
			25 deg, C _T	- 0.0010			
4	50 10/800	, v ₇₅ - 0.	zo deg, c _T	~ 0.0019			
0.3	0	1 001	- 096	- 040	004	201	10 /

0.3	0	1.001	096	- 040	996	.201	12.4
0.3	45	1.000	085	077	994	.184	14.1
0.3	90	.954	115	011	947	.177	14.4
0.3	135	.951	119	027	943	.195	15.0

x/R	Ÿ,deg	\overline{v}_{R}/v_{o}	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	\bar{v}_y/v_o	\bar{v}_z / v_c	ovr/vo	$\sigma_{e}^{}, deg$
0.4	0	1.354	.108	043	-1.349	.131	10.1
0.4	45	1.357	.109	114	-1.348	.128	12.0
0.4	90	1.368	.149	050	-1.359	.173	10.1
0.4	1 35	1.390	.133	019	-1.384	.095	10.7
0.5	0	1.559	.210	068	-1.544	.078	5.1
0.5	45	1.603	.174	065	~1.592	.123	6.1
0.5	9 0	1.586	.201	025	-1.573	.112	5.9
0.5	135	1.570	. 219	082	-1.553	.074	5.6
0.6	0	1.912	.212	 062	-1.900	.049	2.8
0.6	45	1.872	.190	062 067	-1.862	.049	
0.6	9 0	1.933	.185	007			2.6
0.6	135	1.961	.207	068	-1.925	.092	3.2
0.0	1.22	1.901	.207	005	-1.949	.053	2.8
0.7	0	2.108	.174	.143	-2.096	.099	3.4
0.7	45	2.100	.210	043	-2.089	.071	2.7
0.7	90	2.070	.181	069	-2.061	.074	2.6
0.7	135	2.018	.144	059	-2.012	.059	2.6
0.8	0	2.187	.287	071	-2.167	.066	2.9
0.8	45	2.185	.276	099	-2.165	.108	2.9
0.8	90	2.149	.251	094	~2.132	.087	2.7
0.8	135	2.215	.253	.107	-2.198	.122	3.7
							517
0.9	0	2.130	.280	024	-2.112	.415	12.2
0.9	45	2.099	.206	.097	-2.087	.478	15.1
0.9	90	2.109	.117	.051	-2.105	.376	13.3
0.9	135	1.991	.120	.081	-1.986	.250	14.9
1.0	0	1.486	.979	.030	-1.118	.279	20.8
1.0	45	1.413	. 896	.046	-1.092	.640	38.4
1.0	90	1.526	.087	148	-1.516	.548	30.1
1.0	135	1.353	182	062	-1.339	.460	34.5
					,		2.13
1.05	0	.863	.605	.087	610	.377	36.2
1.05	45	.567	. 440	.049	353	.479	48.0
1.05	90	.380	.137	.088	343	.769	58.7
1.05	135	.840	381	034	748	. 383	37.8
1.1	0	.134	087	087	052	.158	50.9
1.1	45	.170	117	112	052	.191	46.1
1.1	90	.146	101	101	030	.180	50.9
1.1	135	.134	107	070	041	.149	50.6
-• -			- + • •			•	50.0

x/R	¥,deg	$\bar{v}_{R}^{\prime}/v_{o}^{\prime}$	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	\vec{v}_y / v_o	⊽ _z /v₀	σv _R /ν _o	σ_{ϵ} ,deg
1.2	0	.091	034	052	068	.100	55.8
1.2	45	.129	044	068	100	.107	49.4
1.2	90	.096	031	056	071	.120	48.5
1.2	135	.048	048	055	082	.117	45.4
1.3	0	.183	.032	180	010	.086	37.2
1.3	45	.196	.019	195	017	.088	33.5
1.3	90	.189	.017	187	017	.097	36.8
1.3	135	.186	013	182	036	.080	35.2
1.4	0	.181	.023	- .172	053	.027	24.0
1.4	45	.185	.021	178	048	.036	24.9
1.4	90	.186	.008	178	053	.034	22.5
1.4	135	.184	.009	177	050	.035	25.0
1.5	0	.096	.036	075	.048	.031	35.3
1.5	45	.092	.036	075	.040	.033	37.1
1.5	90	.089	.026	072	.046	.036	36.8
1.5	135	.090	. 031	067	.052	.038	38.3

TEST CONDITION 1, x/R = -1.0 $\Omega R = 634$ ft/sec, $\Theta_{75} = 6.25$ deg, $C_T = 0.0019$

0.3	0	1.822	050	- .326	-1.792	.101	3.8
0.3	45	1.860	043	321	-1.832	.100	3.4
0.3	90	1.842	033	364	-1.805	.096	2.9
0.3	135	1.822	035	328	-1.792	.087	2.9
0.4	0	1.777	070	197	-1.764	.452	4.6
0.4	45	1.823	031	143	-1.817	.455	4.4
0.4	90	1.833	045	233	-1.817	.430	3.8
0.4	135	1.804	058	250	-1.786	. 387	3.8
0.5	0	2.099	027	235	-2.085	.104	3.2
0.5	45	2.119	072	270	-2.101	.153	3.3
0.5	90	2.089	096	244	-2.072	.132	4.2
0.5	135	2.166	079	176	-2.157	.152	4.0
0.6	0	1.882	000	230	-1.868	. 333	12.7
0.6	45	1.950	.023	268	-1.931	.279	9.6
0.6	9 0	1.891	046	231	-1.877	.271	11.3
0.6	135	1.96G	121	325	-1.929	. 305	13.8

x/R	Ψ,deg	$\tilde{v}_{\underline{v}}/v_{o}$	\overline{v}_x / v_o	\bar{v}_y/v_o	$\bar{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{\mathbf{o}}$	σ _{VR} /νο	σ_{ε} ,deg
J. 7	0	1.524	.032	257	-1.502	.463	27.3
0.7	45	1.505	.066	216	-1.488	.559	26.2
0.7	90	1.399	044	098	-1.395	. 420	29.0
0.7	135	1.380	109	241	-1.355	. 489	31.7
•••	205				21000		5217
0.725	0	1.210	.020	318	-1.167	.436	28.8
0.725	45	1.100	~.010	303	-1.058	.471	33.8
0.725	9 0	1.129	.058	380	-1.062	.449	28.8
0.725	1 35	1.180	.041	446	-1.091	.403	31.3
0.775	0	.803	.022	541	~.592	.423	35.3
0.775	45	.820	.013	503	648	. 454	37.5
0.775	90	.881	010	571	671	.405	31.4
0.775	135	.845	.084	557	630	.421	34.3
0,8	0	. 596	.041	466	369	. 354	45.9
0.8	45	.517	033	381	348	.427	51.2
0.8	90	.604	.011	495	347	. 385	45.6
0.8	1 35	.634	000	523	359	. 346	36.4
0.9	0	. 362	040	355	.058	.083	26.4
0.9	45	. 348	035	343	.045	.076	27.0
0.9	90	. 366	020	360	.060	.071	25.7
0.9	135	. 350	008	344	.063	.066	25.0
1.0	0	. 379	067	364	085	.022	8.7
1.0	45	. 372	069	355	087	.023	8,6
1.0	90	. 383	060	368	086	.030	8.5
1.0	135	. 370	071	354	081	.026	8.4
						• • •	.
1.1	0	.415	-,051	410	040	.084	14.5
1.1	45	. 394	055	388	040	.077	16.2
1.1	90	.418	066	411	042	.096	15.5
1.1	135	. 390	061	384	032	.077	14.4
1.2	0	. 354	023	353	018	.043	11.2
1.2	45	. 339	037	337	008	.039	12.4
1.2	9 0	.350	036	349	007	.037	12.4
1.2	13 5	. 3 30	036	328	602	.038	13.4
1.3	0	. 340	040	338	.006	.035	14.7
1.3	45	. 311	035	308	.011	.027	17.5
1.3	90	. 332	030	330	.024	.033	18.3
1.3	135	. 307	049	303	.020	.040	19.6
							- / • 0

×/R	Ψ,deg	\bar{v}_R/v_o	$\bar{\mathbf{v}}_{\mathbf{x}}/\mathbf{v}_{o}$	$\bar{\mathbf{v}}_{\mathbf{y}}/\mathbf{v}_{0}$	$\bar{\mathbf{v}}_{\mathbf{z}}/v_{0}$	σv _R /vo	σ_{ϵ} , deg
1.4	0	. 335	126	309	027	.070	21.8
1.4	45	. 329	135	298	.029	.067	22.8
1.4	90	. 342	140	311	.020	.064	19.8
1.4	135	. 325	138	293	.023	.061	20.3
1.5	0	.355	125	332	019	.042	12.1
1.5	45	.351	125	327	018	.028	11.5
1.5	90	.359	122	337	013	.038	11.8
1.5	135	.341	125	316	018	.038	12.1

TEST CONDITION 2, z/R = -1.0 $\Omega R = 429$ ft/sec, $\odot_{75} = 10.75$ deg, $C_T = 0.0041$

0.3	0	1 707					
0.3	-	1.707	016	- .260	-1.687	.067	3.3
	45	1.796	015	- .245	-1.779	.067	2.6
0.3	90	1.781	 02 9	268	-1.761	.056	2.7
0.3	135	1.770	056	262	-1.749	.077	2.9
					,	10/7	2.9
0.4	0	1.995	095	238	-1.978	.064	2 7
0.4	45	1.958	058	168	-1.950		2.7
0.4	90	2.059	047	196	-2.049	.079	3.3
0.4	135	2.019	096	-,221		.074	3.0
		,	.070	221	-2.005	.053	2.9
0.5	0	2.133	-,069	140	2 1 2 7		
0.5	45	2.176	027		-2.127	.101	3.4
0.5	90	2.188		208	-2.166	.072	2.8
0.5	135	2.168	076	214	-2.176	.086	3.5
•••		2.100	154	282	-2.136	.083	3.6
0.6	0	2 051					
0.6		2.054	032	245	-2.039	.194	9.6
0.6	45	2.024	056	289	-2.002	.214	12.5
	90	2.083	.028	337	-2.055	.287	8.0
0.6	135	2.109	.05 9	308	-2.085	. 312	11.4
							11.4
0.675	0	1.611	009	293	-1.584	. 346	27.3
0.675	45	1.704	041	200	-1.692	. 346	16.5
0.675	90	1.673	.045	329	-1.639	. 321	
0.675	135	1.699	.162	258	-1.671	.277	21.6
					1.0/1	• 2 / 1	23.0
0.7	0	1.473	026	368	-1.426	155	• · -
0.7	45	1.426	.1.52	445		.455	24.5
0.7	90	1.436	• 075	298	-1.346	. 371	22.9
0.7	135	1.439	. 312		-1.354	. 392	24.2
	- 33	11433	• 312	304	-1.372	.461	28.8

x/R	Ψ,deg	\bar{v}_{R}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{x}}/\mathbf{v}_{0}$	$\bar{\mathbf{v}}_{\mathbf{y}}/\mathbf{v}_{0}$	ν¯ _z /ν _o	σ _{VR} /νο	σ_{ϵ} , deg
0.725	0	1,200	-,068	406	-1.127	. 438	30.C
0.725	45	1.156	031	343	-1.103	.473	28.3
0.725	90	1.143	.129	442	-1.047	.453	33.1
0.725	135	.885	.187	202	841	.528	43.4
0.8	0	.668	.085	- .347	564	. 442	44.1
0.8	45	.824	.104	331	748	. 477	42.7
0.8	90	.777	.085	297	713	.484	42.5
0.8	135	.818	.116	328	740	. 469	44.4
0.9	0	.423	.013	-,417	071	.201	31.9
0.9	45	.425	002	-,419	066	.182	28.7
0.9	90	. 374	005	372	041	.148	36.2
0.9	135	.407	032	400	062	.175	30.4
		• • • • •	1002	1400		• • • •	2014
1.0	0	.467	.082	457	053	.236	27.0
1.0	45	.486	.049	483	021	.172	19.3
1.0	90	.452	.079	445	.004	.179	25.0
1.0	135	.499	.066	494	.027	.220	18.6
1.1	0	. 389	.050	386	.007	.057	12.3
1.1	45	. 383	.042	381	.007	.057	13.8
1.1	90	. 378	.037	376	.007	.064	12.9
1.1	135	.377	.017	376	.010	.058	15.5
	233	• 377	••••	• 570	.010	.050	17.7
1.2	0	. 399	008	390	047	.049	12.6
1.2	45	.402	003	399	046	.054	14.3
1.2	9 0	.404	008	401	045	.050	12.2
1.2	135	.403	012	401	043	.048	11.0
1.3	0	. 384	.000	384	.014	.043	18.6
1.3	45	. 386	010	386	.010	.043	17.8
1.3	90	. 382	.004	382	.014	.042	18.3
1.3	135	. 382	007	381	.014	.040	20.0
1 , 3		1 202	007	301	.014	.04/	20.0
1.4	0	.378	026	364	098	.155	16.7
1.4	45	. 388	028	371	108	.179	17.0
1.4	90	. 389	026	371	114	.200	17.4
1.4	135	. 391	025	372	120	. 236	18.1
1.5	0	. 393	.002	389	056	.112	17.0
1.5	45	. 388	002	382	070	.139	17.3
1.5	90	. 386				.185	
1.5	135	. 300	011	379	072		17.8
1.2	T 22	. 374	009	- .387	071	.186	17.7

TEST	CONDITION 3, $z/R = -1.0$	
∩R =	450 ft/sec, Θ_{75} = 6.25 deg, C_{T} = 0.00)20

			•				
x/R	¥,deg	\overline{v}_{R}/v_{o}	⊽ _x /∨₀	\bar{v}_y/v_o	$\overline{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{\mathbf{o}}$	σv _R /νο	σ_{ϵ}, \deg
0.3	0	2.071	023	305	-2.048	.054	3.0
0.3	45	2.044	059	297	-2.021	.080	3,1
0.3	90	2.024	053	218	-2.012	.103	3.0
0.3	135	2.048	-,028	277	-2.029	.077	2 .9
0.4	0	2.079	059	195	-2.069	.291	4.1
0.4	45	2.116	041	299	-2.095	.272	3.2
0.4	90	2.096	-,078	-,318	-2.070	.247	3.5
0.4	1 35	2.048	071	247	-2.032	.258	3.8
0.5	0	2.303	.017	182	-2.295	.154	4.8
0.5	45	2.272	039	162	-2.266	. 204	5.9
0.5	90	2.259	068	115	-2.255	.175	6.0
0.5	1 35	2.249	.000	159	-2.243	.161	4.9
0.575	0	2.090	062	050	-2.088	.347	10.4
0.575	45	2.050	068	033	-2.049	.240	10.1
0.575	9 0	2.064	.022	012	-2.064	.257	11.4
0.575	1 35	2.106	021	080	-2.104	.242	10.2
0.6	0	2.015	079	-, 372	-1.979	. 302	16.5
0.6	45	2.013	037	374	-1.977	. 320	14.9
0.6	90	1.980	072	415	-1.935	. 396	14.3
0.6	135	1.979	.052	443	-1.928	. 359	12.8
0.65	0	1.676	007	208	-1.663	. 310	20.7
0.65	45	1.613	029	-,202	-1.600	.367	23.7
0.65	9 0	1.571	021	316	-1.539	.454	22.6
0.65	135	1.685	028	253	-1.666	.483	23.7
0.675	0	1.478	016	244	-1.458	• 364	29.0
0.675	45	1.583	.041	220	-1.567	.479	20.7
0.675	9 0	1.595	057	161	-1.586	.486	28.1
0.675	135	1.638	047	-,283	-1.612	.601	27.3
0.7	0	1.207	.094	355	-1.150	.460	31.1
0.7	45	1.200	.092	383	-1.134	. 328	28.6
0.7	9 0	1.196	.146	-,337	-1,138	.347	32.0
0.7	135	1.322	.205	374	-1.252	.410	28.5
0.725	0	. 860	.162	428	728	.459	40.1
0.725	45	.815	.133	386	705	. 490	45.5
0.725	90	.872	.144	323	797	.463	43.1
0.725	135	.909	.096	380	820	.449	41.3

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k /R	¥,deg	$\bar{v}_{\rm R}/v_{\rm o}$	$\mathbf{\bar{v}_x}/v_0$	\bar{v}_{y}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{0}$	σv _R /vo	σ _ε ,deg
Э.8	0	.573	.157	420	357	.264	37.7
0.8	45	.565	.111	456	315	.276	38.4
0.8	90	.618	.098	. 699	350	. 335	38.4
0.8	135	.645	.134	520	257	. 328	35.0
							0.000
0.9	0	.542	.082	495	06	.226	32.8
0.9	45	. 5 30	.003	505	161	.190	32.2
0.9	9 0	.553	.063	509	206	.270	33.0
0.9	135	.560	.090	489	259	.243	31.0
1.0	0	. 449	005	447	047	.047	11.9
1.0	45	.447	002	443	056	.052	12.8
1.0	90	.445	014	442	053	.052	12.1
1.0	135	. 4 36	018	432	056	.056	12.0
1.1	0	.428	012	426	036	.033	8.0
1.1	4.5	.429	018	427	045	.029	7.5
1.1	90	.425	022	422	039	.035	7.1
1.1	135	.421	023	418	038	.031	6.9
1.2	0	,432	.007	432	.008	.053	21.5
1.2	45	.425	.003	425	.001	.051	23.5
1.2	90	.430	.015	430	002	.057	22.0
1.2	135	.430	.003	430	.012	.048	18.8
	_						
1.3	0	.435	.050	432	001	.083	17.9
1.3	45	.441	.064	436	006	.073	17.1
1.3	90	.444	.061	440	.001	.076	15.1
1.3	135	.438	.052	-,435	001	.067	14.8
• •			• • •				
1.4	0	.469	.006	469	.007	.034	11.2
1.4	45	.477	008	477	.008	۰045	11.2
1.4	90	.467	009	467	.007	.041	11.8
1.4	135	.472	028	471	002	.046	11.6
1.5	0	.413	180	367	059	.031	10.6
1.5	45	.410	168	369	061	.032	10.6
1.5	90	.414	186	365	059	.039	9.9
1.5	135	.413	194	360	059	.041	10.1
		• • • • •	• = 2 =	. 200	••••	• • • • •	TO • T

2.2.2.2.2.2.2.2

		1, z/R = - -, ⁰ 75 = 6.	1.5 25 deg, C _T	0.0021			
x/R	^y ,deg	\overline{v}_{R}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{x}}/\mathbf{v}_{o}$	$\bar{\mathbf{v}}_{y}/v_{o}$	\bar{v}_z/v_o	σ _{VR} ∕v₀	σ _ε ,deg
0.45	0	.897	.001	.064	895	.199	14.1
0.45	45	.923	.062	.056	~.920	.212	14.7
0.45	9 0	.875	.043	.092	869	.204	12.7
0.45	135	.858	,054	.109	849	.177	14.5
0.5	0	1.233	.073	084	-1.228	. 320	8,8
0.5	45	1.192	.078	064	-1.188	. 300	9.5
0.5	90	1.209	.097	052	-1,204	.357	10.9
0.5	135	1.178	.108	079	-1.170	. 307	10.4
0.6	0	1.490	.147	014	-1.483	. 304	5.1
0.6	45	1.524	.139	.002	-1.518	.314	5.6
0.6	90	1.500	.139	.019	-1.493	.303	6.9
0.6	135	1.540	.139	007	-1.534	.272	11.6
0.7	0	1.900	.152	.036	-1.894	,232	9.0
0.7	45	1.887	.128	.082	-1.881	.299	7.5
0.7	90	1.874	.127	.060	-1.869	.262	7.4
0.7	135	1.890	.174	.057	-1.881	.273	8.5
0.75	0	1.991	.266	062	-1.972	.099	3.0
0.75	45	1.974	.258	063	-1.956	.140	3.5
0.75	90	2.014	.240	081	-1.998	.210	3.9
0.75	135	2.000	.198	069	-1,989	.161	4.4
0.8	0	2.091	.164	.012	-2.085	.103	4.5
0.8	45	2.066	.165	.039	-2.059	.091	5.0
0.8	90	2.059	.162	.035	-2.052	.154	4.9
0.8	135	2.120	.150	.054	-2.114	.177	5.0
0.85	0	2.071	.182	.040	-2.063	.170	8,0
0.85	45	2.043	.190	- .017	-2.034	.236	8.4
0.85	90	2.049	.203	.013	-2.039	.247	8.2
0.85	135	2.010	.191	.013	-2.001	. 322	8.1
0.9	0	1.927	.111	.016	-1.924	. 36 3	11.5
0.9	45	1,987	.118	.005	-1.984	.251	11.0
0.9	90	2.012	.230	062	-1.997	.252	10.7
0.9	135	1.977	.210	096	-1.963	.283	10.1
1.0	0	1.462	.135	.024	-1.456	.468	25.7
1.0	45	1.473	.188	•088	-1.459	.462	26.7
1.0	90	1.506	.197	.093	-1.490	.544	25.9
1.0	135	1.431	.291	.166	-1.391	.463	26.5

Numero,

x /R	Ÿ,deg	ν¯ _R /ν _o	⊽ _x /v₀	⊽y/vo	ν¯ _z /ν _o	^o v _R /v _o	σ _ε ,deg
1.1	0	.729	.071	.068	722	. 506	46.9
1.1	45	.843	104	013	837	.406	40.9
1.1	90	.875	.038	. 192	853	.504	43.2
1.1	135	.790	.109	.004	782	.489	43.2
• •	_						
1.2	0	.497	.029	.017	498	.487	49.1
1.2	45	.459	.022	.085	451	.435	50.6
1.2	90	.453	.058	.175	413	.452	50.4
1.2	135	.387	.033	.141	359	.418	55.1
1.3	0	.286	.007	.232	167	,170	(1.0
1.3	45	.276	000	. 226	158		41.0
1.3	90	. 295	.018	.225	151	.161	39.2
1.3	135	. 305	.022	.246	180	.170 .180	41.4
			1022	• 4 4 0	-,180	.180	38.4
1.4	0	.214	.117	.113	140	. 116	47.7
1.4	45	.231	.138	.128	134	.133	48.0
1.4	90	.217	.124	.113	137	.112	48.0
1.4	135	.194	. 109	.110	117	.130	53.6
1.5	0	1 / 0	• • •				
1.5	0	.149	.018	.130	071	.089	27.7
1.5	45	.143	.019	.134	047	.071	29.6
1.5	9 0	.149	.028	.133	061	.086	30.1
1.5	135	.149	.027	.136	053	.084	30.7
1.6	0	.122	.001	.091	081	.077	52.8
1.6	45	.115	.013	.080	082	.087	55.9
1.6	90	.121	001	.083	087	.088	53.9
1.6	135	.115	.001	.080	082	.085	52.4
TEST C ΩR = 4	ONDITION : 31 ft/sec	2, z/R = - 0 ₇₅ = 10	1.5 .75 deg, C _T	- 0.0041			
0.45	0	1.100	.185	.111	-1.079	.169	12.0
0.45	45	1.121	.219	.128	-1.092	.137	11.0
0.45	90	1.166	.191	.197	-1.133	.146	7.2
0.45	135	1.136	.203	.167	-1.105	.162	11.2
0.5	0	1.309	.146	36/	1 101	051	
0.5	45	1.375	.146	.154 .146	-1.291	.251	7.5
0.5	90	1.405	.096		-1.363	.215	5.4
0.5	135	1.370	.096	.165	-1.391	.189	6.6
		1.3/0	• • • • •	.195	-1.353	.182	6.1

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у' қ	Ψ,deg	$\bar{v}_{R}^{\prime}/v_{o}$	⊽ _x /∨₀	⊽ y/v₀	$\overline{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{\mathbf{o}}$	σ _{VR} /ν _o	σ _ε ,deg
Ũ F	0	1.280	.178	.053	-1.266	.162	4.1
0	45	1.285	.174	.068	-1.271	.132	4.4
0.6	90	1.274	.163	.075	-1.261	.124	3.7
0.6	135	1.277	.118	.117	-1.266	.101	3.5
0.7	0	1.716	.067	.136	-1.709	.227	4.4
0.7	45	1.678	.099	.083	-1.673	.225	5.5
0.7	90	1.668	.071	.113	-1.662	.273	3.3
0.7	135	1.705	.076	.144	-1.697	.225	3.1
0.8	0	2. 17 1	.143	081	-2.165	.145	6.1
0.8	45	2.322	.267	040	-2.306	.199	5.1
0.8	90	2.295	.161	027	-2.289	.246	6.5
0.8	135	2.349	.123	.008	-2.346	.226	8.5
0.9	0	2.245	.278	059	-2.227	.243	5.8
0.9	45	2.314	.372	188	-2.276	.154	5.1
0.9	90	2.319	. 356	160	-2.286	.207	6.9
0.9	135	2.307	.269	.167	-2.285	. 302	12.3
1.0	0	2.082	.177	048	-2.074	.207	7.2
1.0	45	2.175	.251	024	-2.161	,196	6.3
1.0	90	2.122	. 364	090	-2.088	.195	6.7
1.0	135	2.193	.475	194	-2.132	.197	6.3
1.05	0	1.942	.138	.065	-1.936	.407	14.3
1.05	45	1.831	.215	160	-1.811	.451	17.9
1.05	90	1.802	.271	082	-1.780	.352	16.9
1.05	135	1.700	. 347	047	-1.064	.421	21.8
1.1	0	1.222	087	031	-1.219	.481	37.7
1.1	45	1.203	100	.008	-1.199	. 365	28.5
1.1	90	1.079	.032	.037	-1.078	.463	35.6
1.1	135	1.033	.148	. 289	981	.478	33.3
1.15	0	.924	.052	026	923	.477	38.5
1.15	45	.928	.057	088	922	.412	
1.15	90	.923	.025	036	922	. 349	32.0 22.1
1.15	135	.882	.206	.001	858	.470	36.2
1.2	0	.770	. 166	. 264	704	.432	(1)
1.2	45	.836	. 269	. 192	768		41.3
1.2	90	.852	.130	.115	834	.429	39.1
1.2	135	.910	.036	.080	902	.521	42.7
					-,702	.428	37.4

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x/R	Ψ, deg	\bar{v}_R / v_o	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	vّ پ/۷ ₀	ν¯ _z /ν _o	σv _R /v _o	σ_{ϵ} , deg
1.3	0	.723	.357	.212	591		
1.3	45	.694	.269	.142		. 316	36.5
1.3	90	. 784	.355	.142	624	. 326	39.0
1.3	135	. 709	.302	.166	676	. 375	33.4
			. 302	.100	619	. 313	32.3
1.4	0	.285	.107	. 208	162	.238	40.1
1.4	45	. 3 05	.128	.216	174	.251	39.5
1.4	90	.338	.105	.242	212	.248	31.6
1.4	135	. 346	.098	.252	215	. 229	32.6
1.5	0	.102	.051	.032	082	.074	47.7
1.5	45	.091	.048	.036	069	.081	50.1
1.5	9 0	.094	.054	.039	067	.070	50.1
1.5	135	.090	.050	.046	060	.067	50.4
						.007	30.0
1.6	0	.127	.065	.101	042	.051	35.9
1.6	45	.121	.067	.090	~.045	.058	39.6
1.6	90	.118	.066	.088	042	.051	37.7
1.6	135	.121	.063	.098	032	.041	35.1
TEST ΩR =	CONDITION : 452 ft/sec.	3, z/R = -1 0.075 = 6.1	1.5 25 deg, C _T	= 0.0020			
0.45	0	.936	.007	059	934	2//	15 0
0.45	45	.896	.005	165	880	.244 .246	15.0
0.45	90	.972	.028	031	971	. 258	18.0
0.45	135	.975	.056	111	967	. 290	15.3
~ ~	_					• 2 9 0	15.9
0.5	0	• 846	.113	.047	837	.256	18.5
0.5	45	.812	.078	.053	806	.198	24.1
0.5	90	. 798	.072	.064	792	.149	17.8
0.5	135	.815	.071	.111	804	.202	20.6
0.6	0	.668	.043	.144	651	.169	20.1
0.6	45	.662	.059	.123	648	.182	20.1
0.6	9 0	.630	.080	.088	619	.182	16.7
0.6	135	.650	.060	.109	638	.160	21.9
<u> </u>	_					• 100	18.6
0.7	0	.984	.150	.054	971	.115	5.7
0.7	45	.9 74	.137	.074	961	.104	6.3
0.7	90	.949	.123	.074	938	.120	8.0
0.7	135	.960	.126	•049	950	.107	6.1

(a) (b) (b)

x/R	Ÿ,deg	⊽ _R /vo	$\overline{\mathbf{v}}_{\mathbf{x}}/\mathbf{v}_{\mathbf{o}}$	⊽ _y ∕∨ _o	$\bar{\mathbf{v}}_{z}/v_{o}$	σ _{v_R/ν_o}	σ _ε ,deg
0.8	0	1.755	. 300	.032	-1.729	.1.38	4.2
0.8	45	1.778	.291	.035	-1.753	.157	4.3
0.8	90	1.773	. 264	.024	-1.753	.153	3.5
0.8	135	1.772	.245	.087	-1.753	.111	4.1
		1		.007	-1.755	• = 1 1	4.1
0.9	0	2.213	. 329	102	-2.186	.088	3.0
0.9	45	2.198	. 322	117	-2.171	.090	2.9
0.9	9 C	2.207	. 329	137	-2.178	.084	2.9
0.9	1 35	2.191	. 312	134	-2.164	.146	3.4
0.95	0	2.315	. 317	106	2 201	000	
0.95	45	2.276	.291	088	···2.291	.099	3.9
0.95	90	2.270	.273		-2.256	.121	3.3
0.95	135	2.330		.010	-2.261	.135	3.3
0.95	133	2.330	.290	054	-2.311	.103	3.3
1.0	0	2.310	. 260	113	-2.293	.166	5.3
1.0	45	2.286	.248	053	-2.272	. 16 7	7.5
1.0	9 0	2.304	. 314	087	-2.281	.112	4.9
1.0	135	2.355	.294	073	-2.335	.143	4.5
1.05	0	2.262	. 325	092	2 2 2 2	1 7 3	3.0
1.05	45	2.187	. 280	092 093	-2.237	.171	7.2
1.05	9 0	2.196	. 360	128	-2.167	.269	8.8
1.05	135	2.193			-2.162	.258	7.9
1.05	100	2.193	. 395	206	-2.147	• 339	9.1
1.1	0	2.151	. 239	.075	-2.137	.327	15.3
1.1	45	2.127	.261	.013	-2.111	.246	14.9
1.1	9 0	2.148	.264	028	-2.131	.229	11.3
1.1	135	2.141	. 306	.010	-2.119	.288	14.9
1.2	0	1.714	. 348	.074	-1.677	507	
1.2	45	1.703	.169	015	-1.677	.507	25.8
1.2	90	1.569	.097	.134		.497	20.6
1.2	135	1.601	.133		-1.561	.485	31.9
1.2	101	1.001	•172	.102	-1.592	.400	27.8
1.25	0	1.218	.137	.088	-1.207	.456	35.3
1.25	45	1.269	.088	.112	-1.261	.417	30.2
1.25	90	1.235	.177	.138	-1.214	.517	32.8
1.25	135	1.139	.172	.164	-1.114	.502	37.3
				• • •	21 227		51.5
1.3	0	.469	.020	.031	468	. 340	50.2
1.3	45	.498	051	.082	488	. 397	49.8
1.3	9 0	.538	144	.048	516	. 343	40.9
1.3	135	.595	099	.098	579	.365	39.2

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x/R	¥,deg	\bar{v}_R / v_o	$\mathbf{\bar{v}_x}/v_o$	⊽y/v₀	\bar{v}_z/v_o	σv _R /vo	σ_{ϵ} ,deg
1.4	0	.377	.027	128	354	.202	26.2
1.4	45	.365	.050	131	337	.202	26.3
1.4	9 0	. 372	.010	140	344		28.9
1.4	135	364	.002	~.163	326	.184 .158	24.1
				.105	520	,138	26.0
1.5	0	.251	009	071	241	.106	43.2
1.5	45	.247	015	062	239	.117	43.Z 44.y
1.5	90	.255	024	067	245	.090	41.3
1.5	135	. 251	005	086	236	.100	41.5
• /							42.4
1.6	0	.283	.073	139	235	.055	11.2
1.6	45	.292	.067	154	239	.060	9.7
1.6	90	. 290	.068		239	.054	9.9
1.6	135	. 293	.065	155	240	.056	10.7
TEST	CONDITION	1, $z/R = -$	-2.0				
$\Omega R =$	634 ft/sec	, 0 ₇₅ = 6	25 deg, $C_{\rm T}$	- 0.0020			
0.45	0	1.602	.107	- .077	-1.596	25.2	
0.45	45	1.628	.025	077	-1.626	.353	9.5
0.45	90	1.641	.066	020	-1.640	.234 .270	8.3
0.45	135	1.653	029	043	-1.652	.270	6.3
_					1.052	• - 1 -	7.0
0.5	0	1.585	.009	021	-1.585	.216	4.7
0.5	45	1.567	.010	024	-1.567	.242	6.2
0.5	90	1.576	.038	047	-1.574	.206	6.3
0.5	135	1.591	.025	024	-1.591	.223	6.6
0 (0.0
0.6	0	1.778	.076	.088	-1.774	.179	8.8
0.6	45	1.760	.039	.046	-1.759	.157	9.1
0.6	90	1.803	.083	.090	-1.799	.209	6.6
0.6	135	1.767	.066	.076	-1.764	.116	10.3
0.7	0	1 95 2					
0.7	45	1.852	.067	.012	-1.850	.290	14.2
0.7	90	1.908	.074	.009	-1.907	.248	9.5
0.7	135	1.922	.082	.011	-1.921	. 340	10.5
0.7	1 33	1.914	.016	058	-1.913	. 272	10.8
0.8	0	1.427	037	055	1 101		
0.8	45	1.328	016	.055	-1.426	. 414	22.4
0.8	90	1.303	024	.132	-1.322	.433	25.6
0.8	135	1.291	.002	.048	-1.301	. 395	28.1
		1.671	.002	.078	-1.289	.417	25.8

x/R	¥,d eg	v _R /vo	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	⊽y/v₀	ν¯ _z /ν _o	σv _R /vo	o _e ,deg
0.9	0	.653	.168	. 166	609	.406	45.2
0.9	45	.663	.082	.153	640	. 373	43.5
0.9	90	.652	022	.099	645	. 369	43.8
0.9	135	. 756	.103	.156	733	. 368	36.4
0.925	0	.480	.059	. 392	270	.263	36.3
0.925	45	.530	.084	.465	240	.233	31.4
0.925	90	.496	.031	.449	209	.203	28.7
0.925	135	.524	.115	.464	216	.252	31.8
1.0	0	.168	131	.095	044	.066	36.3
1.0	45	.159	126	.089	037	.067	38.5
1.0	90	.161	122	.097	040	.071	39.7
1.0	135	.156	115	.098	040	.075	40.2
1.1	0	.191	125	.125	072	.062	31.0
1.1	45	.191	128	.119	078	.061	26.2
1.1	9 0	.196	130	.122	081	.056	27.0
1.1	135	.197	131	.119	087	.058	25.3
1.2	0	.226	·.131	.145	113	.029	13.2
1.2	45	.224	130	.143	113	.032	15.3
1.2	90	.228	136	.146	109	.030	13.6
1.2	135	.222	131	.144	106	.032	15.7
1.3	0	.158	103	.077	092	.038	32.2
1.3	45	.166	101	.079	105	.035	27.0
1.3	9 0	.166	111	.082	092	.033	27.7
1.3	135	.166	107	.086	094	.037	27.8
1.4	0	.273	147	.186	137	.028	12.6
1.4	45	.271	146	.183	136	.036	14.7
1.4	90	.274	153	.182	137	.030	14.0
1.4	1.35	.276	151	.187	135	.039	14.4
1.5	0	.301	186	. 210	109	.036	12.5
1.5	45	. 300	185	.209	109	.040	14.3
1.5	90	. 302	185	.211	111	.045	12.7
1.5	135	. 303	183	.212	114	.042	13.2
1.6	0	. 330	226	.226	083	.043	11.7
1.6	45	. 328	225	.223	086	.044	10.7
1.6	90	. 331	233	.216	092	.037	10.4
1.6	135	. 333	227	.224	097	.042	9.9

TEST CONDITION 2, z/R = -2.0 $\Im R = 450$ ft/sec, $\Im_{75} = 10.75$ deg, $C_T = 0.0040$

x/R	Ψ,deg	$\bar{v}_R^{}/v_o$	$\mathbf{\bar{v}_x}/v_o$	⊽y/v₀	$\bar{\mathbf{v}}_{\mathbf{z}}/\mathbf{v}_{\mathbf{o}}$	σ _{vr} /ν _o	σ_{ϵ} , deg
0.45	0	1.906	.254	.453	-1.833	.289	15.4
0.45	45	1.954	.247	. 375	-1.901	.224	13.3
0.45	9 0	1.955	.165	. 362	-1.914	.176	10.7
0.45	135	1.987	.190	. 388	-1.939	.243	13.6
0.5	ð	1.832	.168	. 380	-1.785	.280	9.6
0.5	45	1.843	.166	• 360	-1.800	.244	12.2
0.5	90	1.817	.123	.419	-1.764	.250	12.2
0.5	135	1.780	.101	. 390	-1.734	. 328	13.8
0.6	Ú	1.684	.153	.345	-1.641	. 337	17.4
0.6	45	1.695	.170	.301	-1.659	. 325	16.4
0.6	90	1.7 1 0	.108	.336	-1.673	. 35 3	15.7
0.6	135	1.625	.110	.297	-1.594	. 334	23.2
0.7	0	1.833	.258	.210	-1.802	.248	15.4
0.7	45	1.812	.247	.216	-1.782	. 301	16.9
0.7	90	1.786	. 344	.273	-1.731	. 308	19.8
0.7	135	1.798	.157	.238	-1.775	. 361	14.7
0.8	0	1.843	. 479	.336	-1.748	. 346	24.6
0.8	45	1.827	. 336	.351	-1.761	. 359	23.7
0.8	9 0	1.778	.376	. 429	-1.684	.377	23.1
0.8	135	1.690	.270	.412	-1.616	. 308	23.6
0.825	0	1.565	.276	.425	-1.481	.422	25.4
0.825	45	1.468	.271	.425	-1.410	.423	27.4
0.825	9 0	1.552	.227	. 379	-1.488	.439	25.2
0.825	135	1.492	.189	. 319	-1.445	- 473	26.0
0.85	0	1.114	.284	.371	-1.011	.474	34.8
0.85	45	1.017	.404	. 350	865	.470	38.2
0.85	90	1.027	.268	. 374	918	.502	39.0
0.85	135	1.077	. 367	.383	937	.571	39.5
0.9	0	.462	.122	.381	231	.203	37.2
0.9	45	.434	.086	.321	279	.234	40.1
0.9	90	.435	.071	. 350	248	.171	37.0
0.9	1 35	.412	.102	. 318	241	.162	38.6
1.0	0	. 335	.053	. 317	094	.115	26.9
1.0	45	. 346	.043	. 336	071	.135	26.6
1.0	90	. 357	.066	. 341	079	.127	26.1
1.0	135	. 334	.070	. 316	084	.116	24.7

x/R	¥,deg	v _R /vo	$\mathbf{\bar{v}_x}/\mathbf{v_o}$	⊽y/vo	$\mathbf{\bar{v}_z}/v_o$	σv _R /ν _o	σ _ε ,deg
1.1	0	. 349	.117	.299	137	.123	24.9
1.1	45	. 337	.092	.296	132	.123	29.3
1.1	90	. 346	.094	. 302	-,141	.129	28.8
1.1	135	. 376	.108	. 325	156	.173	26.6
1 0							
1.2	0	.292	.048	.268	107	.051	14.1
1.2	45	.286	.051	.259	109	.057	14.1
1.2	90	.288	.051	.265	100	.064	10.5
1.2	135	.286	.054	.262	102	.064	14.1
1.3	0	. 322	023	. 317	052	.057	11.2
1.3	45	. 316	027	. 310	053	.051	10.7
1.3	90	. 311	025	. 305	053	.054	12.8
1.3	135	. 316	026	.311	046	.055	12.6
			1020	• 511	-,040	.0.0	12.4
1.4	0	.206	027	.193	067	.074	39.4
1.4	45	.217	027	.205	···.067	.074	38.3
1.4	9 0	.219	032	.206	067	.080	36.6
1.4	135	.219	029	.205	071	.079	37.3
						,	57.5
1.5	0	.259	-•.026	.257	015	.081	23.1
1.5	45	.259	027	.257	018	.078	22.9
1.5	90	.257	032	.255	016	.073	23.7
1.5	135	.252	027	.250	011	.076	24.0
1.6	0	. 294	066	.287	010	100	<u></u>
1.6	45	.292	074	.287	013	.103	21.7
1.6	90	. 302	075	.282	019	.098	23.2
1.6	135	.295	075		013	.093	20.0
1.0	135	• 2 9 5	075	.284	025	.093	21.1
TEST C	ONDITION	3, $z/R = -$	2.0				
$\Omega \mathbf{R} = 4$	54 ft/sec	$\theta_{75} = 6.$	25 deg, C _T	= 0.0021			
0.45	0	1.674	.373	.517	-1.548	.413	26.0
0.45	45	1.619	.373	. 421	-1.519	.503	26.8
0.45	90	1.697	. 309	.418	-1.615	.303	24.5
0.45	135	1.697	. 426	.552	-1.547	.422	21.7
	~ ~ / /	****	• 720		-1.741	.434	24.8
0.5	0	1.487	.321	.476	-1.372	.472	29.1
0.5	45	1.646	.210	.474	-1.563	.455	26.8
0.5	9 0	1.588	.341	.442	-1.486	.408	28.8
0.5	135	1.575	.340	. 469	-1.465	.377	25.4
					-		

x/R	¥,deg	⊽ _R /v₀	$\mathbf{\bar{v}_x}/v_o$	⊽y/v₀	ν _z /ν _o	σv _R /vo	$\sigma_{\epsilon}^{}$, deg
0.6	0	1.293	.468	.538	-1.079	.400	30.7
0.6	45	1.271	.283	.488	-1.138	. 399	32.6
0.6	90	1.216	. 364	. 439	-1.074	. 409	31.4
0.6	135	1.281	. 377	. 420	-1.150	. 385	29.1
0.625	0	1.277	. 383	. 491	-1.114	. 398	31.5
0.625	45	1.256	.370	.422	-1.123	. 369	32.3
0.625	90	1.246	.411	.413	-1,102	. 36 3	32.5
0.625	135	1.242	. 395	. 393	-1.110	.403	33.9
A 7	•		/ a a				
0.7	0	1.128	.497	.664	764	.481	33.3
0.7	45	1.109	. 350	.526	912	.461	33.1
0.7	90	1.122	• 509	.510	861	.426	32.9
0.7	135	1.132	.500	.542	858	.446	32.4
0.8	0	.811	.521	.507	358	.481	40.4
0.8	45	.768	.470	.486	365	. 482	43.0
0.8	90	.699	.432	.477	273	.451	48.9
0.8	135	.804	.491	.574	276	.460	37.8
0.9	0	.626	.427	.434	145	.422	39.4
0.9	45	.590	.409	.377	145	.422	
0.9	90	.614	.438	. 393	174	.402	43.7
0.9	135	.635	.438	.452	122	.474	41.6 38.3
	133	••••	. 423	.452	122	.400	2013
1.0	0	.456	. 269	.345	129	.231	38.4
1.0	45	.470	.252	. 384	096	.173	37.3
1.0	90	.454	.252	. 360	114	.174	38.5
1.0	135	.458	.254	. 354	140	.221	37.1
1.1	0	.441	. 260	. 352	049	100	20 E
1.1	45	.429	. 286	. 318	033	.158 .151	38.5
1.1	90	.469	.279	.375	033		40.3
1.1	135	.484	. 307	.373	040	.161	33.0
	133	. 404	. 507	• • • • •	025	.155	33.2
1.2	0	.489	.231	.429	.040	.103	17.0
1.2	45	.494	.234	.433	.044	.090	16.7
1.2	9 0	.483	.237	.417	.058	.079	16.8
1.2	1 35	.466	.240	. 396	.051	.070	20.6
1.3	0	.446	.161	.411	.063	0.05	20.0
1.3	45	.449	.164	.411		.085	20.0
1.3	90	.449	.167	.413	.062	.088	19.5
1.3	135	.440	.171	.410	.053	.086	18.1
1.7		•••••••••••••••••••••••••••••••••••••••	.1/1	. 410	.053	.101	18.2

x/R	¥,deg	\bar{v}_{R}/v_{o}	$\bar{\mathbf{v}}_{\mathbf{x}}/v_{0}$	⊽y/v₀	ν¯ _z /ν _o	σv _R /νο	σ _ε ,deg
1.4	0	.406	.147	.372	.075	.045	15.4
1.4	45	.400	.154	. 36 3	.068	.048	14.5
1.4	9 0	. 400	.147	. 366	.064	.046	15.2
1.4	135	.405	.145	. 371	.073	.048	14.5
1.5	0	.421	.118	. 404	.008	.072	18.5
1.5	45	.414	.138	. 390	.004	.071	18.4
1.5	90	. 395	.116	.377	003	.069	19.2
1.5	135	. 374	.115	. 356	.004	.071	18.9
1.6	0	.455	.138	. 425	084	.027	5.3
1.6	45	.457	.138	.427	086	.026	5.0
1.6	90	.460	.129	.434	077	.029	5.4
1.6	135	.463	.136	.435	082	.028	5.7