

Video Article

Measuring the Mechanical Properties of Living Cells Using Atomic Force Microscopy

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Abstract

Mechanical properties of cells and extracellular matrix (ECM) play important roles in many biological processes including stem cell differentiation, tumor formation, and wound healing. Changes in stiffness of cells and ECM are often signs of changes in cell physiology or diseases in tissues. Hence, cell stiffness is an index to evaluate the status of cell cultures. Among the multitude of methods applied to measure the stiffness of cells and tissues, micro-indentation using an Atomic Force Microscope (AFM) provides a way to reliably measure the stiffness of living cells. This method has been widely applied to characterize the micro-scale stiffness for a variety of materials ranging from metal surfaces to soft biological tissues and cells. The basic principle of this method is to indent a cell with an AFM tip of selected geometry and measure the applied force from the bending of the AFM cantilever. Fitting the force-indentation curve to the Hertz model for the corresponding tip geometry can give quantitative measurements of material stiffness. This paper demonstrates the procedure to characterize the stiffness of living cells using AFM. Key steps including the process of AFM calibration, force-curve acquisition, and data analysis using a MATLAB routine are demonstrated. Limitations of this method are also discussed.

Video Link

The video component of this article can be found at <http://www.jove.com/video/50497/>

Introduction

Mechanical properties, especially stiffness, of individual cells and their surrounding extracellular matrices (ECM) are critical for many biological processes including cell growth, motility, division, differentiation, and tissue homeostasis.¹ It has been demonstrated that cell mechanical stiffness is mainly determined by the cytoskeleton, especially the networks of actin and intermediate filaments and other proteins associated with them.² Results from mechanical tests on *in vitro* networks of actin and intermediate filaments suggest that the cell mechanics is largely dependent on the cytoskeletal structure and the pre-stress in the cytoskeleton.³⁻⁵ Stiffness of live cells is then regarded as an index to evaluate the cytoskeletal structure⁶, myosin activity⁷ and many other cellular processes. More importantly, changes in cell mechanical properties are also often found to be closely associated with various disease conditions such as tumor formation and metastasis.⁸⁻¹⁰ Monitoring the mechanical stiffness of living cells can therefore provide a novel way to monitor cell physiology; to detect and diagnose diseases⁸; and to evaluate the effectiveness of drug treatments.^{11,12}

Multiple methods including particle-tracking microrheology,¹³⁻¹⁶ magnetic twisting cytometry,¹⁷ micropipette aspiration^{18,19} and microindentation²⁰⁻²² have been developed to measure the elasticity of cells. Particle tracking microrheology traces the thermal vibrations of either submicron fluorescent particles injected into cells or fiducial markers inside the cell cytoskeleton.²³ Elastic and viscous properties of cells are calculated from the measured particle displacements using the fluctuation-dissipation theorem.^{14,23} This method allows simultaneous measurements of local mechanical properties with high spatial resolution at different places in a cell. However, injecting fluorescent particles into cells may lead to changes in cellular function, cytoskeleton structure, and hence the cell mechanics. The micropipette aspiration method applies negative pressure in a micropipette of diameter ranging from 1 to 5 μm to suck a small piece of cell membrane into the pipette. Cell stiffness is calculated from the applied negative pressure and cell membrane deformation.¹⁸ This method, however, cannot detect the heterogeneous distribution of stiffness across the cell. Magnetic twisting cytometry (MTC) applies magnetic field to generate torque on super paramagnetic beads attached to the cell membrane.¹⁷ Cell stiffness is derived in this method from the relationship between the applied torque and the twisting deformation of the cell membrane. It is difficult to control the location of magnetic beads in the MTC method, and it is also challenging to characterize the twisting deformation with high resolution. Microindentation applies an indenter with well-defined geometry to punch into the cell. The indenting force and the resulting indentation in cells often follow the prediction of the Hertz model. Young's moduli of cells can be calculated from the force-indentation curves by fitting them to the Hertz model. This method has been widely applied to test the mechanical properties of

tissue and cells despite of its limitations such as uncertainty in contact point determination, applicability of the Hertz model, and the potential to physically damage the cells. Among the many devices for microindentaon²⁰, the Atomic Force Microscope (AFM) is commercially available and has been widely applied to characterize mechanical properties of living cells and tissues^{21,24-27}.

This paper demonstrates the procedure of using an Asylum MFP3D-Bio AFM to characterize cell mechanics. AFM not only provides high-resolution topography of cells but also has been widely applied to characterize the mechanical properties of tissue cells. The principle of AFM indentation is illustrated in **Figure 1**. The AFM cantilever approaches the cell from a few micrometers above; makes contact with the cell; indents the cell so that the cantilever deflection reaches a preselected set point; and pulls away from the cell. During this process the cantilever deflection is recorded as a function of its location as shown in **Figure 1**. Before making contact with the cell, the cantilever moves in the medium without any apparent deflection. When indenting on the cell, the cantilever bends and the deflection signal increases. The cantilevers are modeled as elastic beams so that their deflection is proportional to the force applied to the cell. By setting the maximum cantilever deflection, the maximum magnitude of force applied to the sample is limited to avoid damage to cells. The portion of the force curve from point b to point c in **Figure 1**, where the tip indents into the cell, is fit to the hertz model to extract the cell stiffness.

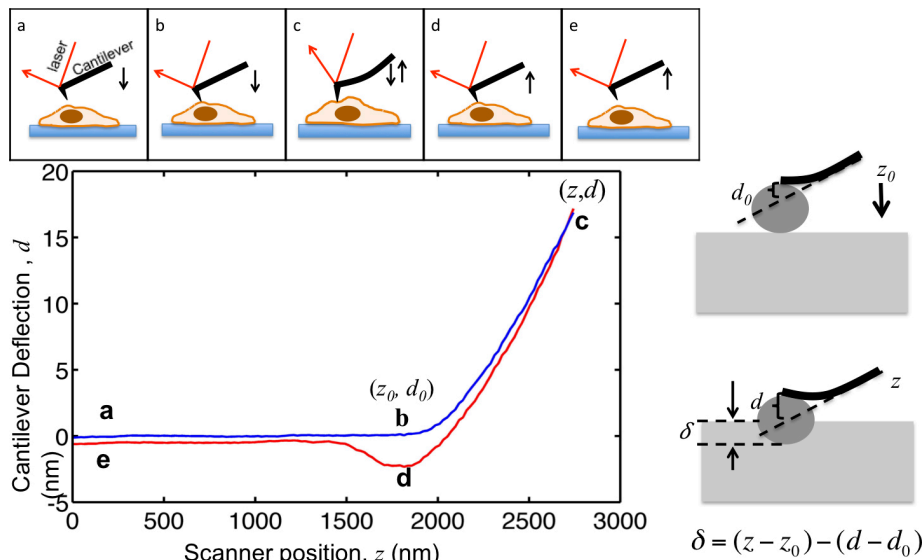


Figure 1. Illustration of AFM microindentation and interpretation of the force curve. The top panel shows the motion of AFM cantilever driven by the piezo scanner. The vertical location of cantilever z and the cantilever deflection signal d is recorded during the process. The cantilever starts from point a, a few micrometers above the cell. While approaching the cell, the sample indentation δ remains zero until it reaches point b, where the tip comes into contact with the cell. The coordinates of point b in the plot are critical values for data analysis, denoted by (z_0, d_0) . From b to c, the cantilever indents into the cell until the cantilever deflection reaches a set point, which is set to be the ratio between the targeted maximum indenting force and the cantilever spring constant. Once the deflection signal reaches the preset maximum value, the cantilever is then withdrawn from the cell to point d, where it often be pulled downwards due to tip-sample adhesion, detaches from the cell and returns to its initial location at e. The right panel illustrates the relationship between the indentation and the recorded z and d signal. In on the lower left panel is a plot of a representative force curve, the maximum indentation of a cantilever, of which the spring constant is measured to be 0.07N/m , is set to be 17 nm so that the maximum indenting force applied to sample is 1.2 nN . The key locations during the indentation are marked.

Protocol

1. Calibrate the Spring Constant of Cantilever

1. Load the cantilever into the AFM according to the manufacturer's instructions. It is necessary to clean the cantilever holder with ethanol before any experiments. This will help limit bacterial contamination to culture during the AFM measurements.
2. Calibrate InvOLS (Inverse Optical Lever Sensitivity). This parameter describes the amount of photodiode response (Volts) per nanometer of cantilever deflection.
3. Load a clean glass slide onto the sample stage, then install the AFM head and adjust the laser beam and alignment according to the manufacturer's instructions. Engage the AFM tip on the glass slide.
4. With the piezo withdrawn, realign the mirror to a photodiode reading of -2 V . Perform a force spectroscopy measurement with a trigger point (maximum photodiode response) of $+2\text{ V}$.
5. With the piezo withdrawn, realign the mirror to a photodiode reading of -2 V . Perform a force spectroscopy measurement with a trigger point (maximum photodiode response) of $+2\text{ V}$. *Note:* The voltage values here are specific to the Asylum AFM. This value should be set according to the specifications provided by manufacturer.

After data acquisition is complete, zoom in to the firm-contact region of the force curve. Perform a linear fit to this region to find the slope, which will be in V/nm . The reciprocal of this value describes the optical sensitivity of the cantilever-photodiode ensemble.

6. Reset the mirror alignment to a free deflection of 0 V .

7. Calibrate the cantilever spring constant. A thermal-tune method is used to determine the spring constant of the cantilever²⁸.
8. After calibrating the InvOLS, raise the scanner away from the sample stage such that there are no interactions between the tip and sample.
9. Begin capturing thermal data. During this process, the thermal vibration of the cantilever beam is recorded. The AFM software analyzes a power spectrum of such a thermal vibration and plots it in a data window.
10. After a few seconds of data acquisition, perform a fit to the data segment centered at the lowest-frequency (fundamental resonance) peak to determine the spring constant.

2. Loading the Sample

1. Install the Dish Heater accessory on the AFM stage, if not already equipped.
2. Set the temperature to 37 °C, and wait for 20 min for the system to reach a stable thermal equilibrium.
3. Place the culture dish on the AFM stage and secure it using the clamp provided with the dish heater. It is important to minimize the time between removal of the dish from the incubator and placing it on the stage, to avoid trauma to the cells. For measurements longer than 30 min, CO₂ independent medium should be used to replace the normal culture medium.
4. Apply a small drop of 37 °C culture medium to the tip of the AFM cantilever, and lower the AFM head until the tip is just submerged in liquid.
5. Using the top-view CCD camera, realign the laser beam on the cantilever (the alignment in liquid will be different than in air, because of the change in refractive index of the medium).
6. Engage the AFM tip on a clean area of the culture dish.
7. Perform calibration of the InvOLS as described above, for the cantilever sensitivity in the liquid environment.

Note: a) If cells are cultured on hydrogels, the calibration of InvOLS should be performed in advance against the bottom surface of a culture dish filled with cell culture media. When switching to cell samples, special attention has to be paid to not change the laser beam alignment with the cantilever. b) InvOLS has to be recalibrated whenever there is a change in the laser alignment. c) It is also recommended to take InvOLS as the average of value from several calibration curves, since each calibration generates a different InvOLS. The variation in InvOLS is, however, small comparing to the mean value. For example, calibrating an Bruker DNP-10 cantilever with spring constant 0.06 N/m in liquid by 100 times produce a mean InvOLS value of 66.3 nm/V, with standard deviation of only 0.5 nm/V.

3. Collecting Force Curves of Cell Indentation

1. Select a cell for indentation. With the aid of the optical microscope, move the stage to position the cantilever above the cell so that the tip is located in the peri-nuclei region. Precise adjustment of the cantilever position may be accomplished by applying offsets to the X and Y scanners.

Note: The AFM cantilever has to be withdrawn from the sample surface while moving the sample stage to select a target cell. This protects the cantilever from knocking into the sample, since the sample surface may not be flat.

2. Switch to Force Spectroscopy mode. Set the Indentation rate to within the range of 1-10 μm/sec, low enough to avoid hydrodynamic effects.
3. Set the deflection trigger point, which limits the maximum indenting force to avoid damage to cells. Select the Relative triggering option, which will correct for any drift in the deflection signal. A maximum force of 2 nN is a good starting point for most samples. This value, however, should be adjusted according to the sample stiffness. For soft samples a lower value should be used to avoid excessive indentation to the sample. For stiff samples a high value should be used to generate measurable indentation.
4. Set the force distance large enough to ensure that the tip will be fully detached from the cell between force measurements. Usually, the force distance is set at 5 μm.
5. Command the AFM to take a single force curve.
6. Collect at least three force curves at different locations in the peri-nuclei region of each cell. Although it is beneficial to take multiple curves on each cell for reliable statistical data, taking too many force curves can lead to changes in cell stiffness due to stress from the AFM probe.
7. When data collection is complete, withdraw the tip, and repeat steps 3.1-3.6 for as many cells as needed for good statistical data on cell stiffness under a certain sample condition. Usually, 30 cells are measured for each condition.

To characterize the distribution of stiffness within a single cell, force-map mode is applied. In the Force-map mode, set a scan size to include the region of interest; set an appropriate resolution; set the indentation parameters as those selected for single force curves; the AFM will then raster across the defined sample area and take single force curves at each pixel in the sample region.

4. Data Analysis

The recorded force curves are analyzed using a custom MATLAB procedure to calculate the cell stiffness. The following is a brief description of MATLAB procedure:

1. The MATLAB program identifies the contact point coordinates z_0 and d_0 (see **Figure 1**) using an algorithm adopted from a published method by Lin *et al.*²⁹.
2. For each data point in the force curve, perform a linear fit of the data to the left of the point of interest, and a Hertz model fit to the right (using the selected point as the initial point of contact), up to the set maximum indentation (200-300 nm recommended).
3. For each point, calculate the relative RMS error of both fits and sum these values.
4. The point which attains the minimum total fitting error is selected as the initial point of contact.

Note: Computation time can be reduced by implementing a golden-section search rather than linearly scanning the entire force curve.

5. Sample deformation δ and indenting force F are calculated as:

$$\delta = \begin{cases} 0 & z < z_0 \\ (z - z_0) - (d - d_0) & z \geq z_0 \end{cases}, \text{ and } F = \begin{cases} 0 & z < z_0 \\ k(d - d_0) & z \geq z_0 \end{cases}$$

6. A least squares fitting is applied to fit the F vs. δ data in the post-contact region, $z \geq z_0$, to the Hertz model to extract the Young's modulus, E of the cell:

$$F = \begin{cases} \frac{4ER^{0.5}}{3(1-\nu^2)} \delta^{1.5} & \text{Spherical tip of radius } R \\ \frac{2E \tan \phi}{\pi(1-\nu^2)} \delta^2 & \text{Sharp cone tip of opening angle } 2\phi \end{cases}$$

, where ν is the Poisson's ratio.

Note: When δ is more than 10% of the sample thickness (cell height), the measured cell stiffness is affected by the substrate stiffness. The thickness of peri-nuclear region is usually on the order of a few micrometers. Therefore, only the first 200-300 nm of F - δ curve is fit to the Hertz model.

Representative Results

Figure 2a shows three representative force curves taken from 3T3 fibroblasts cultured on plastic surface, polyacrylamide gel of Young's moduli 3,000 Pa and 17,000 Pa, respectively. After carefully identifying the contact points in the curves, the indenting force as function of cell deformation is plotted in **Figure 2b**. Under a force of magnitude smaller than 0.3 nN, a pyramid shape tip indents 3 micrometers into a cell cultured on a 3 kPa polyacrylamide gel. In contrast, a force more than 1.6 nN is required to indent 500 nanometers into the cell grown on plain culture dish using the same tip. It is clear from this graph that the cell cultured on soft polyacrylamide gel is softer than the cell cultured on the stiff culturing dish. Fitting the first segment ($\delta < 30$ nm) of the force- δ curves to the Hertz model gives Young's moduli of these three cells as 10 kPa, 1.2 kPa, and 1.10 kPa, respectively. Cells on the culture dish are 100 times stiffer than cells cultured on polyacrylamide gels. Solon *et al.* have reported similar results²⁵. They found that fibroblasts actively stiffen their cytoskeletons to match the stiffness of substrates they adhere to. Many other cell types have also been reported to become stiffer when cultured on stiffer substrates³⁰.

It is important to note that the indentation can cause plastic deformation in cells, which results kinks as illustrated in the purple curve. Normally, such curves should be excluded from the data analysis. However, the curve can still be used to calculate cell stiffness if the kink is beyond the range of fitting data. For example, the kink in the purple curve occurs at approximately 400 nm. This curve can still be analyzed by fitting the data only up to $\delta = 30$ nm to the Hertz model to yield a stiffness value of 1.2 kPa. It is also important to adjust the "triggering point" according to the sample stiffness. For example, the blue curve is taken from a soft cell cultured on a 3 kPa polyacrylamide gel. Setting the relative deflection trigger point at 5 nm, the AFM tip indents 3 micrometers into the cell. Such a large indentation should be prevented during the cell stiffness measurements, since it could rupture the cell membrane and kill the cell. Many other factors including the tip velocity and data acquisition rate during the force curve acquisition can affect the quality of acquired force curves and hence the resulting stiffness of cells³¹. To make reliable measurements it is necessary to adjust the all these parameters to acquire "clean" force curves as the red curve shown in **Figure 2a**, which has a flat pre-contact part followed by a nonlinear increasing post-contact part.

Figure 3a shows a fluorescence image from a 3T3 fibroblast on a cell culture dish. The cell is transfected with GFP vimentin, a type of intermediate filaments. AFM Force-mapping has been performed in this 80 μ m by 80 μ m area, with a resolution of 32 x 32 pixels. The resulting stiffness map is shown in **Figure 3b**. The stiffness varies across the cell. And, the lamellipodium region is stiffer and more heterogeneous than the peri-nuclear region that surrounds the stiff nucleus.

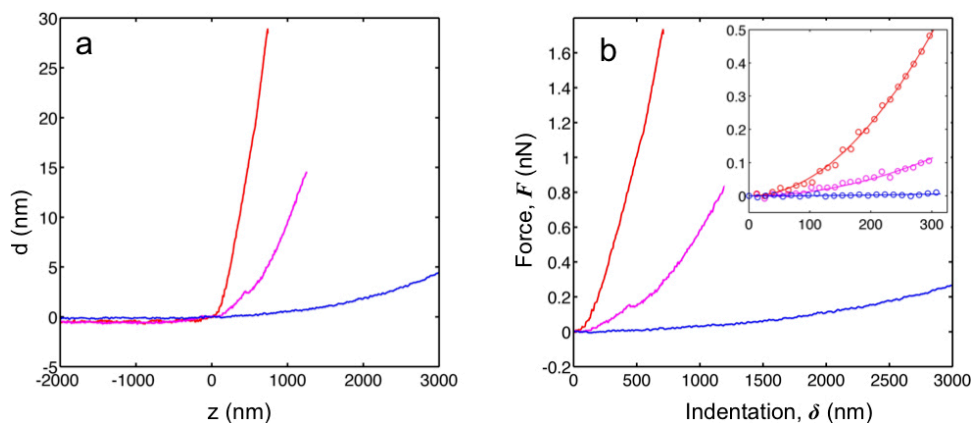


Figure 2. Force curve data and the analyzed force-indentation curve. **a)** A set of three representative force curve data acquired for 3T3 fibroblasts cultured on glass (red), 17 kPa polyacrylamide gel (purple), and 3 kPa polyacrylamide gel (blue). The curves are shifted so that the contact point (z_0, d_0) is located at the origin (0,0) of the coordinate system. **b)** The indentation-force curves calculated from **a)** and fitting of the indentation data to the Hertz model using only the first 300 nm of indentation. Inset in **b)** shows the goodness of fit to the Hertz model for the first 300 nm of indentation; circles are experimental data, lines represent the fit data. The spring constant of cantilever is 0.062 N/m in this case.

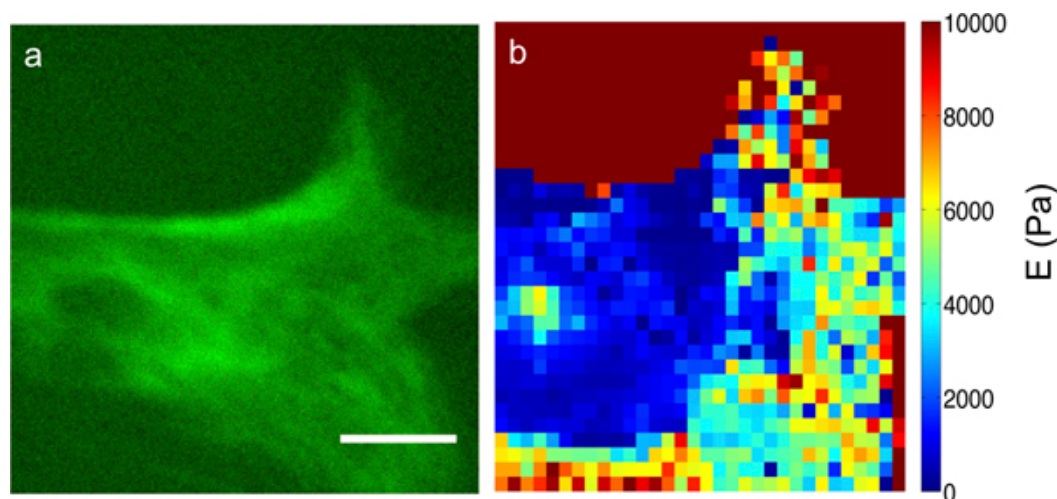


Figure 3. a) Fluorescence image of a 3T3 fibroblast transfected with GFP vimentin. Only a part of the cell is shown in the image. Scale bar represents 20 μm . **b)** A 32 x 32 pixel stiffness map of the same area. Each pixel represents 2.5 μm .

Discussion

The AFM indentation method has advantages to characterize mechanical properties of living cells. Albeit less sensitive than the magnetic twisting cytometry and optical tweezers, which can measure forces on the piconewton level³², the AFM can detect resistance force from samples ranging from tens of pico-Newton to hundreds of nano-Newton, comparable to range of force that can be applied to cells using a micropipette¹⁹. This range of force fits the needs to create measurable deformations in all types of cells¹⁹. The high spatial resolution makes it possible to characterize on the submicron level the heterogeneities in tissues and within single cells³³. It also allows real-time live cell measurements. Several AFM models designed for biological samples can operate in a fluid environment and are equipped with heated sample stages, which provide precise temperature control, making it possible to maintain a physiological environment for living cells during the measurements. AFM indentation has been successfully applied for measuring the mechanical properties of a range of cell types,^{25,34-36} and has been used extensively for assessing changes in mechanical properties of cells associated with cellular differentiation and in various diseased contexts.^{30,37}

An important step to calculate stiffness from force-curve is identifying the point where the tip first makes contact with the cell. The uncertainty in contact point can affect the elastic modulus³¹. For stiff materials, the deflection signal increases abruptly after the tip-sample contact, and the contact point is readily identified as turning point in the curves. Such a sharp turning point, however, often does not appear in the force-curves from cells, due to the low cell stiffness (see **Figure 2**). A MATLAB code is developed to accurately find the contact points in force curves from soft samples using the algorithm proposed by Lin *et al.*²⁹ The code can handle the force curves from soft samples, which enables us to automate the process of data analysis by automatically searching for the contact point and fitting the indentation data to Hertz model. The MATLAB code is applied to determine the contact points in 60 force curves taken at the same location of a polyacrylamide gel, of which the stiffness was measure to be 7.2 kPa by bulk rheology measurements. The code detected contact points in these curves. The range of variation in contact point

location is smaller than 15 nm. Based on these contact points, the calculated mean stiffness is 6.9 kPa, the standard deviation is 0.2 kPa, and the maximum range of variation 0.6 kPa. Results from this experiment provide a measure to evaluate the uncertainty of the measured stiffness. The 15 nm uncertainty in contact point results in an uncertainty in stiffness, which is less than 10% of the mean value. For softer gels with very low level of deflection signal, the uncertainty in contact point can be as high as 30 nm, which leads to an uncertainty in stiffness as high as 30%. The code is available as a supplement to this article.

AFM can reliably measure stiffness ranging from less than 100 Pa to 10^6 Pa, covering the range of stiffness for most tissues and cells. For reliable measurements, it is important to select the AFM cantilevers with spring constants well matched to the sample stiffness. When the cantilever is too stiff, its deflection is too small to detect and it could damage the cell; if the cantilever is too soft, it will not indent the cell sufficiently to obtain reliable material properties and its thermal vibrations can dominate the force curve. Cantilevers of 0.06 N/m with a pyramid tip are applicable for most cell types cultured on stiff culture dishes. These cantilevers, however, are not applicable to measure cells cultured on soft substrates. As shown in **Figure 2**, the cell cultured on a 3,000 Pa polyacrylamide gel is so soft that a 3 μ m indentation is required to generate a 5 nm deflection in the cantilever. The force curve is so flat that there is very little difference between the pre-contact and post-contact region. This leads to large uncertainty in the contact point and hence the resulting stiffness values. Using a softer cantilever only slightly improves contrast between the pre-contact and post-contact regions. To measurement such soft materials, cantilevers with large spherical tip are recommended. A 0.06 N/m cantilever with a spherical tip of 10 micrometers in diameter can be applied to measure samples with stiffness lower than 100 Pa. Cantilevers with spherical tip are commercially available from many vendors. They can also be custom-made by gluing microspheres to tipless cantilevers. The spherical tips provide larger deflection signal and prevent damage to the cell membrane. However, they are not applicable for high-resolution stiffness mapping due to their large contact area with the cells. **Table 1** provides a list of AFM probes recommended for cell stiffness measurements.

Model	Spring constant (N/m)	Tip Type	Tip radius (nm)
Bruker DNP10-D	0.06	Pyramid	20
Bruker MLCT-B/C/E	0.01/0.02/0.03	Pyramid	20
Novascan PT.GS	0.01/0.03/0.06	Glass sphere	2,000/5,000/10,000
Novascan PT.PS	0.01/0.03/0.06	Polystyrene Sphere	1,000/4,500/10,000

Table 1. A selection of AFM probes with applicable spring constant and tip geometry for cell indentation.

The limitations of the presented method should be also marked. The Hertz model that has been applied to fit the indentation data is a simplistic model. It predicts the force-indentation relationship for infinitesimal indentations of purely elastic materials by axisymmetric indenters. Some of the assumptions of the Hertz model do not apply to the cell indentation.

The Hertz model assumes homogeneous and linearly elastic material, while a cell is heterogeneous (see **Figure 3**) and nonlinearly elastic. In the lamellipodium region, it is rather inhomogeneous due to the heterogeneous structure of the actin cytoskeleton. The mechanical stiffness of a cell is reported as the average stiffness extracted from three or more force curves acquired from the relatively homogeneous perinuclear region.^{25,36} Reconstituted networks of actin and intermediate filament are strain-stiffening materials, *i.e.* they are stiffer at larger deformations.^{38,39} Such a nonlinear elasticity has been observed for living cells, but not accounted for in the Hertz model. To limit the effect of nonlinear elasticity on the reported cell stiffness, only the first 300 nm of the indentation data is fit to the Hertz model.

It is also assumed in the Hertz model that the materials are purely elastic. However, cells and their cytoskeleton are viscoelastic materials with stiffness dependent on the time scale of measurements. At shorter time scale, the cantilever deflection mainly comes from the elastic response of cells. At long time scale, however, the sample creeps and gives a softer response. The time scale of AFM indentation is controlled by tip velocity. Hence, the observed difference in cell stiffness is only meaningful when the force curves are acquired with the same indentation velocity. To quantitatively extract the frequency dependent viscoelasticity of cells, the AFM "force modulation" method has been developed by applying high frequency small amplitude oscillations upon a larger indentation^{21,27}.

The assumption of infinite sample thickness in the Hertz model does not apply for cells. Cells are typically a few micrometers thick in the perinuclear region, and a few hundred nanometers thick in the lamella region. Corrections have been made to account for the finite sample thickness.^{31,40} Data acquired from force-mapping contains both indentation data and cell height data. Local sample thickness can be calculated from the height data. Future work is required to implement the sample thickness corrections in the analysis for force-mapping data.

In summary, this paper presents a protocol to characterize the mechanical stiffness of living cells using an Asylum MFP3D-Bio atomic force microscope. The principles of AFM operation and the MATLAB data analysis procedure are applicable to all other AFM models. In recent years, optical microscopy techniques including bright field, confocal microscopy, and total internal reflection fluorescence microscopy (TIRF) have been combined with the AFM for real-time imaging of cells to mechanical stimuli.^{41,42} These setups also allow simultaneous measurements of cell mechanics and imaging of the cytoskeletal components. Correlating the local stiffness data to the distribution of local cytoskeletal components will provide insightful information on how the cytoskeletal components contribute to cell mechanics.

Disclosures

No conflicts of interest declared.

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