MEDICAL IMAGE SEGMENTATION BY MARKER-CONTROLLED WATERSHED AND MATHEMATICAL MORPHOLOGY

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ABSTRACT

Segmentation by watershed transform is a fast, robust and widely used in image processing and analysis, but it suffers from over-segmentation. We present in this paper some improvements to this algorithm based on the mathematical morphology in order to get over this difficulty. The performance of this method is validated on medical images. The results obtained show the good performance of this approach.

KEYWORDS

Image processing, medical image segmentation, watershed, Marker controlled watershed, reconstruction, dilatation, Mathematical morphology.

1. Introduction

The segmentation is a very important stage in images and interpretation processing. There are two main approaches to segmentation: the frontier approach and the region approach [13, 14]. The segmentation by watershed combine the two approaches [1, 2]. This is a powerful technique for rapid detection of both edges and regions.

The major problem of the watershed transform is over-segmentation. Indeed, this algorithm is sensitive to any local minimum in the image, and tends to define the lines of the watershed transform where each local minimum gives rise to a region. To avoid this problem, powerful tools adapted to different problems have been proposed in the literature [3, 7]:

- Either reduce the number of minima and avoid calculation of too many regions.
- Proceed by either filtering techniques by merging the regions according to similarity criteria after spectral and spatial application of the watershed.

We have used markers to reduce the number of regional minima.

In Section 2 image segmentation with watershed algorithm is presented. The proposed method is presented in section 3. In section 4, a validation of our approach is given; experimental results are obtained by medical images. Finally we give a conclusion.

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2. WATERSHED ALGORITHM

The watershed transform is a tool morphological based for image segmentation. It is proposed by Digabel and Lantuejoul [1, 2, 4, 12], which consider a grey level image as a topographic relief. If one combines the grey level of each point at an altitude. It is then possible to define the watershed transform as the ridge forming the boundary between two watersheds. This is to compute the watershed of the said relief. Watersheds thus obtained correspond to regions of the image.

Watershed represents the boundaries between adjacent catchments. The minimum can be interpreted as markers of watershed regions and the watershed can be interpreted as contours, figure 1.

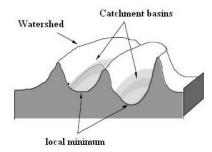


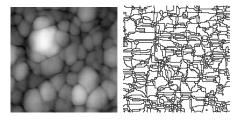
Figure 1: Modelling of contours by watershed transform

Many pre-processing techniques are proposed by the different researchers (filters, morphological operators) were then designed to reduce the number of regions not significant. Nevertheless, the work of Beucher [1, 2] demonstrated the limitations of these methods namely the oversegmentation.

2.1 The over-segmentation

The use of the single watershed algorithm does not really allow good segmentation because far too many regions are detected, figure 2. There are two main methods to limit this over-segmentation:

- hierarchical watershed segmentation [1, 2, 9].
- and watershed by markers [3, 10, 11].



Original image

Watershed 715 regions

Figure 2: Over-segmentation.

The hierarchical segmentation: The hierarchical approach is to generate a tree of regions from the result of the watershed. Regions and watershed are first indexed, and then the process of

hierarchical segmentation process merges the regions whose borders are the lowest. The result is a tree in which it is possible to explore the different levels of fusion regions [1, 2, 6, 8, 9].

Several studies have been made to get over the problem of over-segmentation by markers [1, 3, 5, 7, 10, 11].

2.2 Mathematical morphology

Mathematical morphology is a nonlinear branch of the signal processing field and concerns the application of set theory concepts to image analysis. Morphology refers to the study of shapes and structures from a general scientific perspective. Morphological filters or operators are nonlinear transformations, which modify geometric features of images.

These operators transform the original image into another image through the iteration with other image of a certain shape and size which is known as *structuring element* [10].

The structuring element is a basic structure that will be used to analyze locally, by comparison, the shapes of interest.

The choice of shape and size of the *structuring element* is very important: it influences the result [10], it may take the form of a disk of radius r, a rectangle or other shape.

There are several tools morphological in image segmentation namely erosion, dilation, reconstruction etc. We are interested in this work in the morphological reconstruction based on dilatation.

2.2.1 Morphological dilatation

Let X be a subset of E. If at any x we associate a position B(x) of the structuring element B, then the set X dilated by the structuring element B is defined as following:

$$\delta_B(X) = \left\{ x \in E, B(x) \cap X \neq \emptyset \right\} \tag{1}$$

The structuring element B, denoted by its center is moved to occupy successively all positions of the space E. For each position, we ask the question: does B intersect at X? Positive responses are all dilated, figure 3.

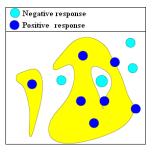


Figure 3: Morphological dilatation.

The dilatation is characterized by the following properties:

- Fills holes smaller than B.
- Fills narrow channels.

- Welds both forms close.
- The size of objects increases.
- Small details disappear.

In what follows, we propose a watershed by markers based on morphological reconstruction.

2.3 Morphological reconstruction

The morphological reconstruction is well known in the case of binary images, where it simply extracts the connected components of an image, which are "marked" with another image. The extended grey scale reconstruction, it can perform multiple tasks such as image filtering, domes, and extraction of the basin. In this paper, we used the image reconstruction algorithm based on morphological dilation.

Morphological reconstruction is based on morphological dilation [6], but notes the following unique properties:

- Processing is based on two images, a marker and a mask, rather than one image and a structuring element.
- Processing is based on the concept of connectivity, rather than a structuring element.
- Processing repeats until stability; i.e., the image no longer changes.

Morphological reconstruction can be thought of conceptually as repeated dilations of an image, called the *marker* image, until the contour of the marker image fits under a second image, called the *mask* image. In morphological reconstruction, the peaks in the marker image "spread out," or dilate. Figure 4 illustrates this processing in 1-D.

The marker and the mask can be two intensity images or binary having the same size. The resulting image is an intensity image or binary [4, 6].

The marker must have the same size as the mask, and its elements must be less than or equal to the elements of the mask. Connectivity used is 8-connected. [4, 6]

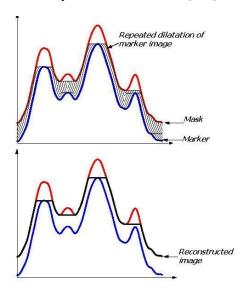


Figure 4: Repeated dilations of marker image, constrained by mask.[6]

To illustrate morphological reconstruction, consider this simple image *I*. It contains two primary regions, the blocks of pixels containing the values 14 and 18. The background is primarily all set to 10, with some pixels set to 11.

One way to create a marker image Mr is to subtract a constant h from the mask image I, but we must determine this constant.

$$Mr = I - h \tag{2}$$

The choice of the constant h is very important, it depends on the processed image, and we must choose the right value of this constant.

In this example we chose h=2 then Mr = I-2

Call the morphological reconstruction to reconstruct the image. In the output image I_{re} , note how all the intensity fluctuations except the intensity peak have been removed [6].

In the output image, all insignificant local maxima will be deleted.

3. PROPOSED SEGMENTATION

We have developed a segmentation method based on morphological operation, and watershed applied to grey level images. The key points of this method are:

Morphological reconstruction

- Extract the markers of regions
- Application of watershed transform

The watershed is the separation lines of greatest intensity in an image.

The markers will define the sources from which the algorithm of the watershed will simulate the rising waters.

Figure 5 show the steps of the proposed method.

- 1. Read the original image *I*.
- 2. Morphological reconstruction of the *I*.
- 3. To detect the minimum, compute the complement of image obtained by the morphological reconstruction, the result image noted Ic.
- 4. For markers of the original image, subtract from the original image I, the image Ic: dif = I Ic
- 5. Extended and imposed minimum, we obtained the *markers*
- 6. Compute the watershed transform of the markers
- 7. Show the watershed segmented image.

Figure 5: Proposed algorithm.

4. EXPERIMENTALE RESULTS

4.1 Introduction

In order to evaluate the performances of the proposed method we have considered 6 grey level medical images: *II* to *I6*. We have compared the results obtained by our method with those obtained by watershed without markers.

4.2 Results of segmentation

Figure 6 and table 1 show the results of segmentation.

- a. initial image a,
- **b.** watershed applied to the image a,
- c. image markers
- **d.** watershed applied to the image c
- e. superposition of the initial image with watershed.

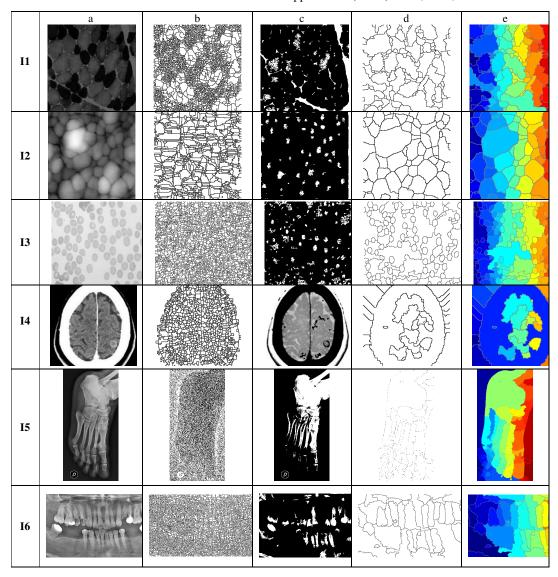


Figure 6: Results of segmentation.

The proposed method is applied to 6 medical images (X-ray, MRI) *I1* to *I6*: cell, muscle, brain, foot and dental image. The results of segmentation by the proposed algorithm shows the clarity and detection of objects (region and contour) marked by the image markers *c*.

The result obtained by watershed without markers (Figure 6.b) gives no information on the regions of the original image. Against the result obtained by watershed with markers shows the speed of segmentation and no more than 2 seconds in all tests. Thus the proposed method detects all objects of the original image (Figure 6.d and 6.e).

In table 1, the number of regions obtained was decreased; the proposed value of the constant h used in the reconstruction is well chosen and well the best. The problem of local minima is eliminated then the problem of over-segmentation is solved.

We proposed a simple algorithm, fast, easy to implement and get over the problem of over-segmentation.

The algorithm is useful to segment the objects that touch each other in an image.

Table1: Information results

Image	<i>I1</i>	<i>I2</i>	<i>I3</i>	<i>I4</i>	<i>I5</i>	<i>I6</i>
Value of constant h	14	5	3	30	47	45
Number of regions without markers	2772	715	3253	1047	164503	8376
Number of regions with our method	107	72	143	31	95	51

5. CONCLUSION

In this paper, we have proposed a method of segmentation watershed by markers and morphological operation. It is able to segment real medicals images. We have calculated automatically region markers. The markers are used to control the watershed to obtain good results.

The markers are generated automatically positioned and thereby avoiding the problem of oversegmentation, and manual marking.

The experimental results obtained show the good performance of this approach. This approach may be used for problems of decision support in medical diagnosis.

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