

MetaModelica

A Unified Equation-Based Semantical and Mathematical
Modeling Language

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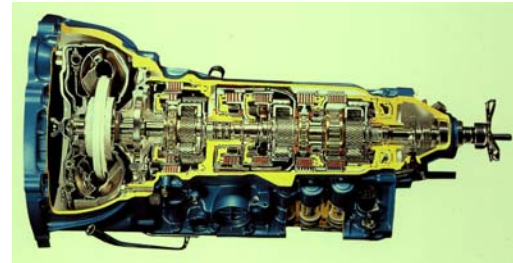
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 - Example
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Modelica - General Formalism to Model Complex Systems

- Robotics
- Automotive
- Aircrafts
- Satellites
- Biomechanics
- Power plants
- Hardware-in-the-loop, real-time simulation
- etc



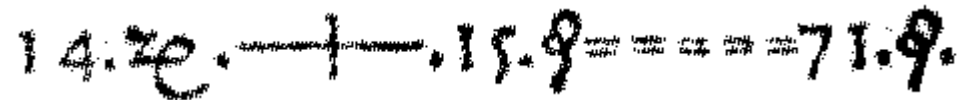
Modelica - The Next Generation *Modeling* Language

- *Declarative language*
 - Equations and mathematical functions allow acausal modeling, high level specification, increased correctness
- *Multi-domain modeling*
 - Combine electrical, mechanical, thermodynamic, hydraulic, biological, control, event, real-time, etc...
- *Everything is a class*
 - Strongly typed object-oriented language with a general class concept, Java & Matlab like syntax
- *Visual component programming*
 - Hierarchical system architecture capabilities
- *Efficient, nonproprietary*
 - Efficiency comparable to C; advanced equation compilation, e.g. 300 000 equations

- *Declarative and Object-Oriented*
- *Equation-based*; continuous and discrete equations
- *Parallel process* modeling of concurrent applications, according to synchronous data flow principle
- *Functions* with algorithms without global side-effects (but local data updates allowed)
- *Type system* inspired by Abadi/Cardelli (Theory of Objects)
- *Everything is a class* - Real, Integer, models, functions, packages, parameterized classes....

Equations were used in the third millenium B.C.

Equality sign was introduced by Robert Recorde in 1557



Newton (Principia, vol. 1, 1686) still wrote text:

“The change of motion is proportional to the motive force impressed; ...”

$$\frac{d}{dt}(m \cdot v) = \sum F_i$$

CSSL (1967) introduced special form of “equation”:

variable = expression

$$v = \text{INTEG}(F) / m$$

Programming languages usually do not allow equations

- What is *acausal* modeling/design?
- Why does it increase *reuse*?
The acausality makes Modelica classes *more reusable* than traditional classes containing assignment statements where the input-output causality is fixed.
- Example: a resistor *equation*:

$$\mathbf{R * i = v;}$$

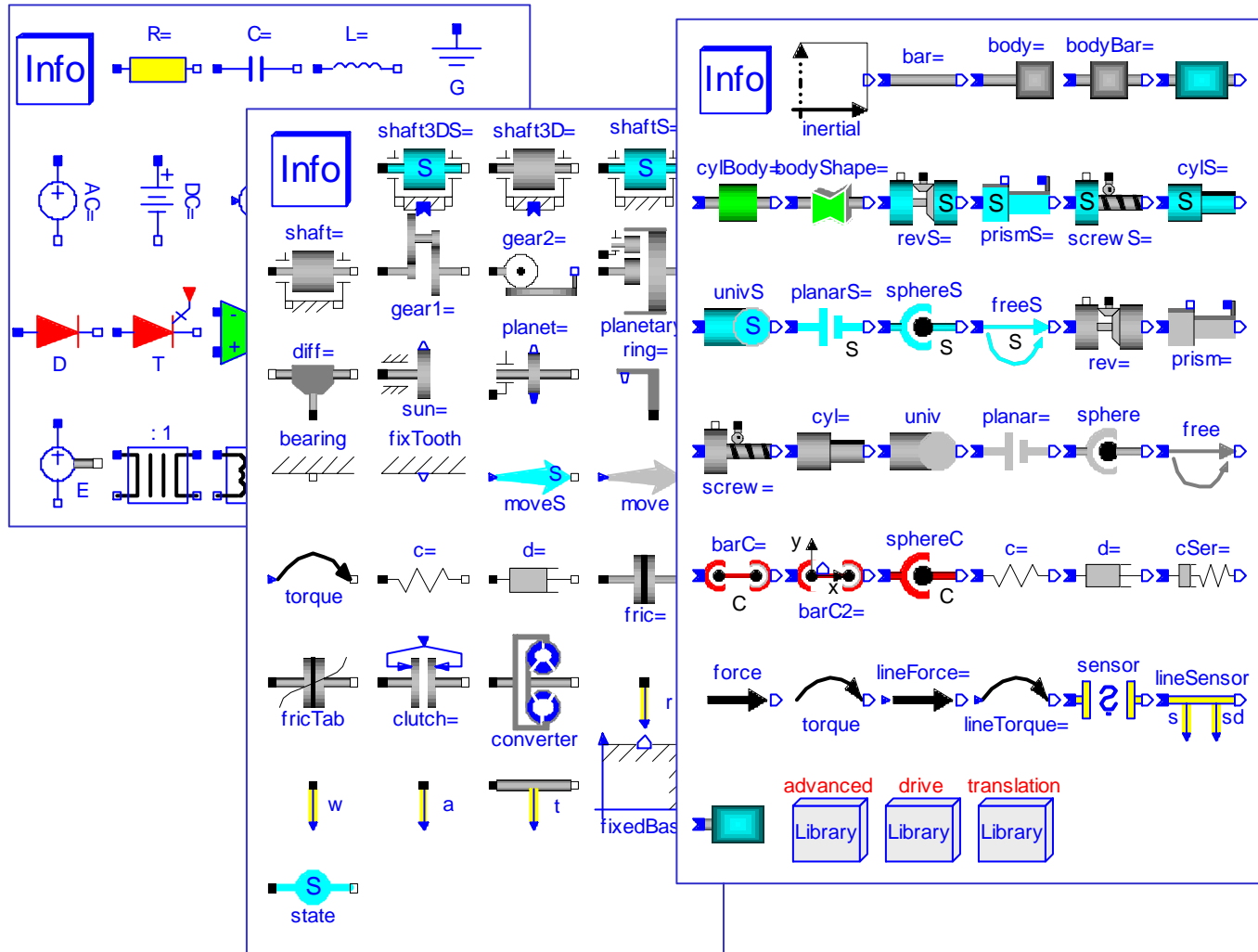
can be used in three ways:

$$\mathbf{i := v/R;}$$

$$\mathbf{v := R*i;}$$

$$\mathbf{R := v/i;}$$

Modelica - Reusable Class Libraries

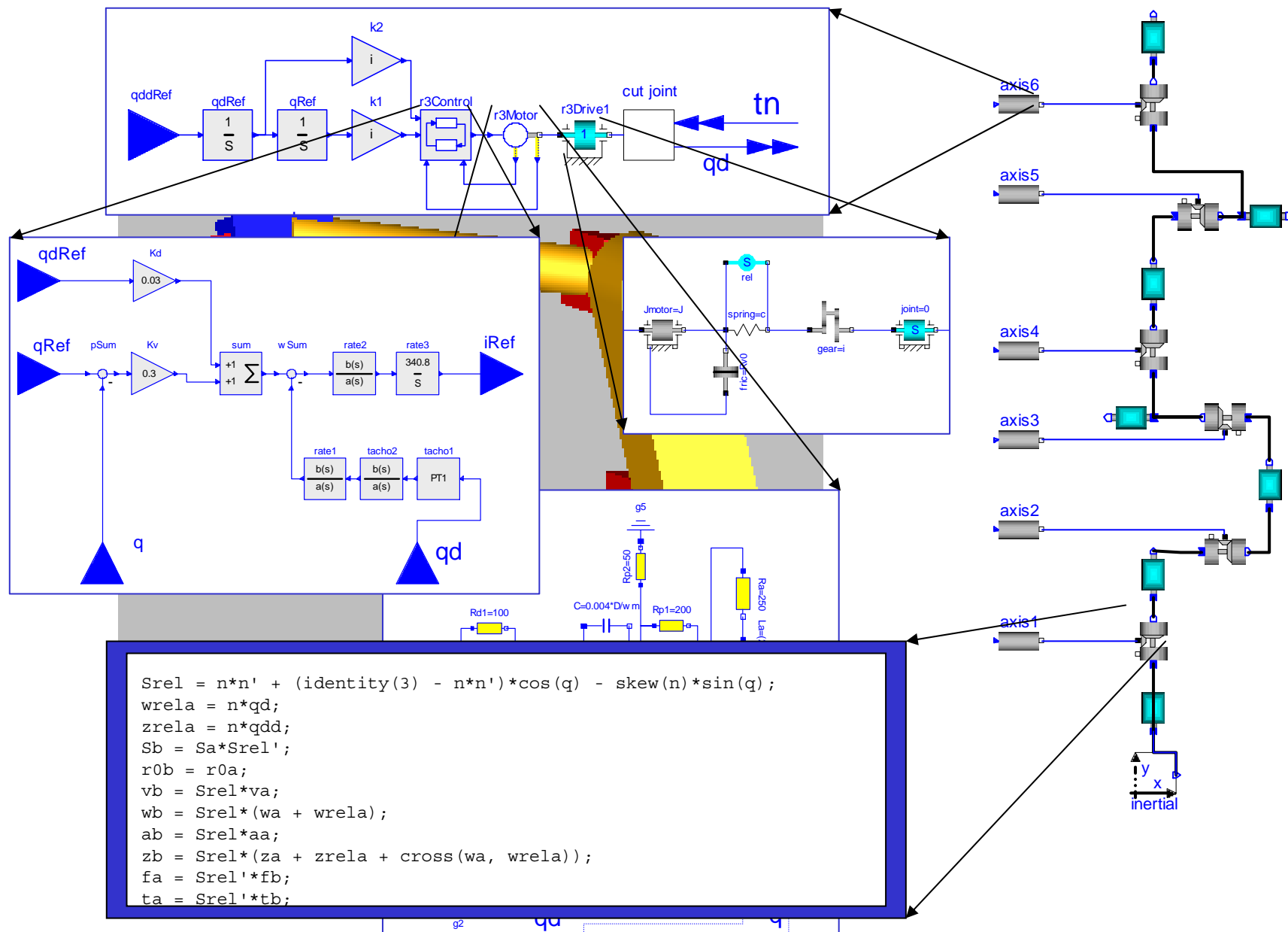


Graphical Modeling - Drag and Drop Composition

The screenshot displays the MathModelica System Designer interface. The central workspace shows a circuit diagram with the following components: a constant voltage source (constantVoltage1), a resistor (resistor1, R=20), an inductor (inductor1, L=1), an EMF source (EMF1, k=1), and a motor block (inertia1, J=1). The motor block is connected to a ground (ground1). The left sidebar shows the Library Browser with various mechanical and electrical components. The right sidebar shows the Components list. The bottom panel shows the Parameters table.

Name	Value	Description
J	1	kg.m ² Moment of inertia

Hierarchical Composition Diagram for a Model of a Robot



Multi-Domain Modelica Model - DCMotor

- A DC motor can be thought of as an electrical circuit which also contains an electromechanical component.

model DCMotor

```
Resistor R(R=100);
```

```
Inductor L(L=100);
```

```
VsourceDC DC(f=10);
```

```
Ground G;
```

```
ElectroMechanicalElement EM(k=10,J=10, b=2);
```

```
Inertia load;
```

equation

```
connect (DC.p, R.n);
```

```
connect (R.p, L.n);
```

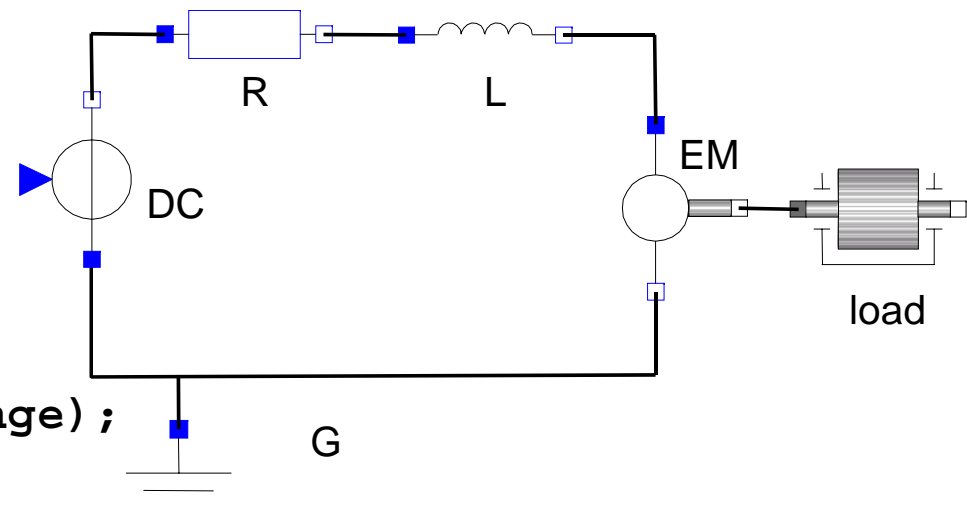
```
connect (L.p, EM.n);
```

```
connect (EM.p, DC.n);
```

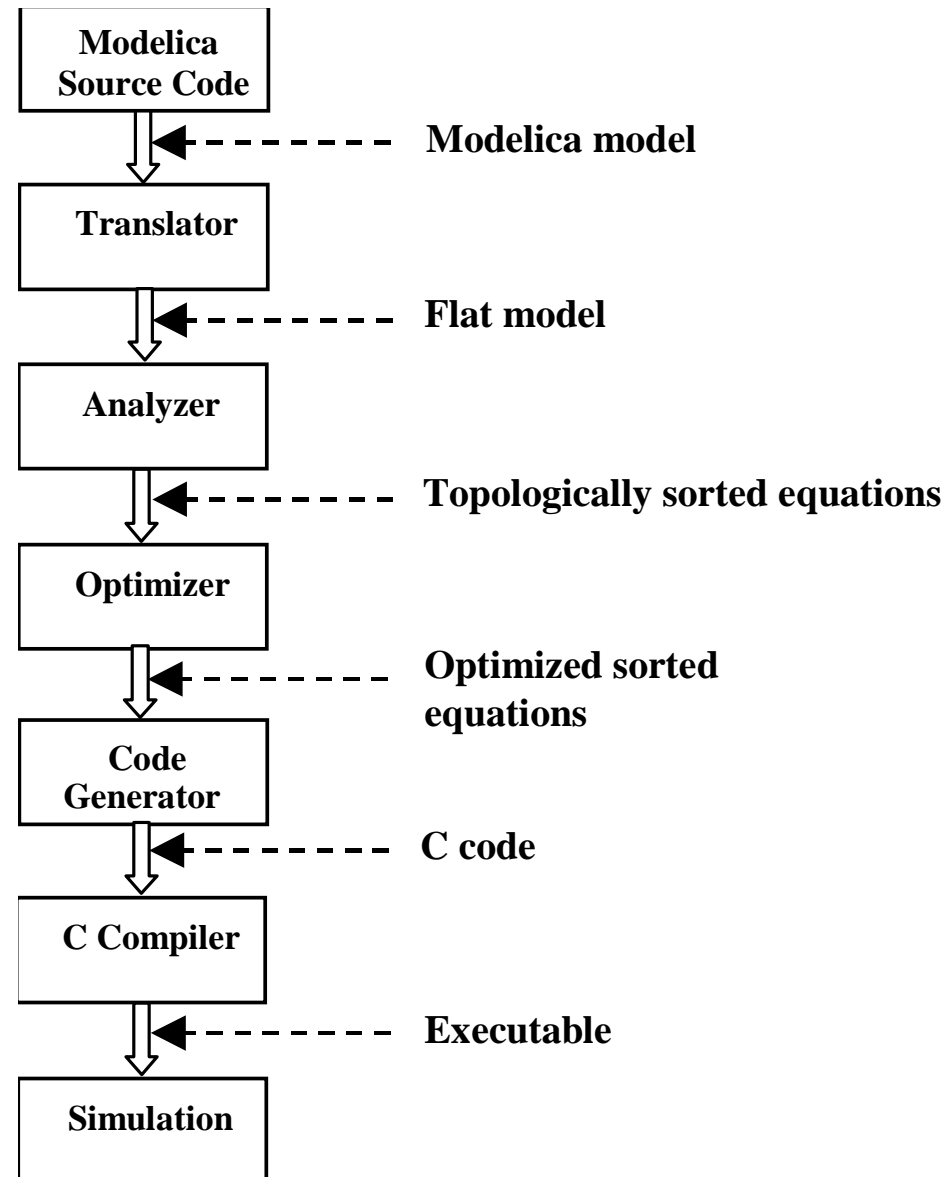
```
connect (DC.n, G.p);
```

```
connect (EM.flange, load.flange);
```

end DCMotor



Modelica compilation stages



Corresponding DCMotor Model Equations

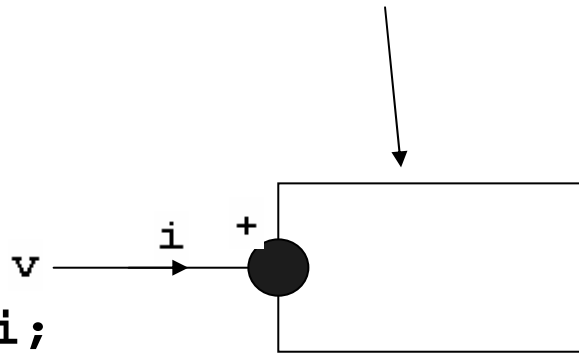
The following equations are automatically derived from the Modelica model:

$0 == DC.p.i + R.n.i$	$EM.u == EM.p.v - EM.n.v$	$R.u == R.p.v - R.n.v$
$DC.p.v == R.n.v$	$0 == EM.p.i + EM.n.i$	$0 == R.p.i + R.n.i$
	$EM.i == EM.p.i$	$R.i == R.p.i$
$0 == R.p.i + L.n.i$	$EM.u == EM.k * EM.\omega$	$R.u == R.R * R.i$
$R.p.v == L.n.v$	$EM.i == EM.M / EM.k$	
	$EM.J * EM.\omega == EM.M - EM.b * EM.\omega$	$L.u == L.p.v - L.n.v$
$0 == L.p.i + EM.n.i$		$0 == L.p.i + L.n.i$
$L.p.v == EM.n.v$	$DC.u == DC.p.v - DC.n.v$	$L.i == L.p.i$
	$0 == DC.p.i + DC.n.i$	$L.u == L.L * L.i'$
$0 == EM.p.i + DC.n.i$	$DC.i == DC.p.i$	
$EM.p.v == DC.n.v$	$DC.u == DC.Amp * Sin[2 \pi DC.f * t]$	
$0 == DC.n.i + G.p.i$		
$DC.n.v == G.p.v$		

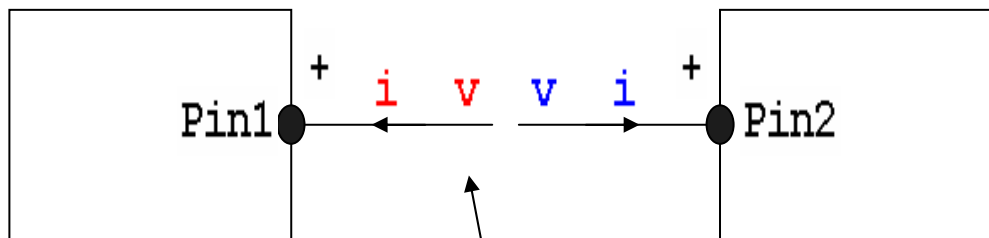
(load component not included)

Connector Classes, Components and Connections

```
connector Pin
  Voltage v;
  flow Current i;
end Pin;
```



Keyword **flow** indicates that currents of connected pins sums to zero.



A connect statement in Modelica

```
connect (Pin1, Pin2)
```

corresponds to

```
Pin1.v = Pin2.v
Pin1.i + Pin2.i = 0
```

Connection between Pin1 and Pin2

Common Component Structure as SuperClass

```
model TwoPin
```

```
  "Superclass of elements with two electrical pins"
```

```
  Pin p,n;
```

```
  Voltage v;
```

```
  Current i;
```

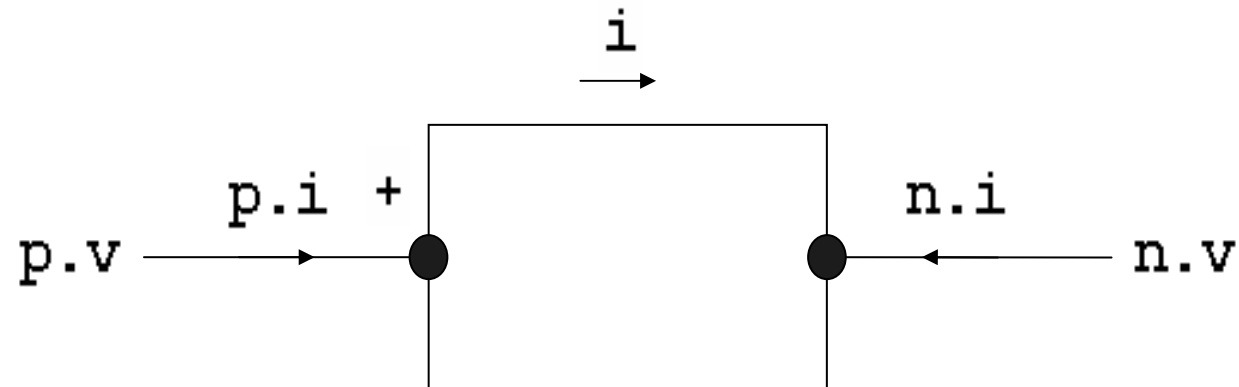
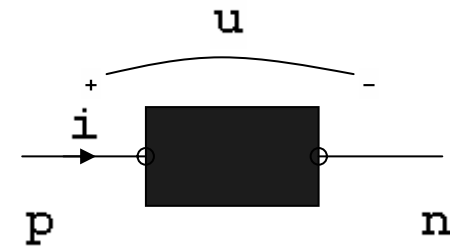
```
equation
```

```
  v = p.v - n.v;
```

```
  0 = p.i + n.i;
```

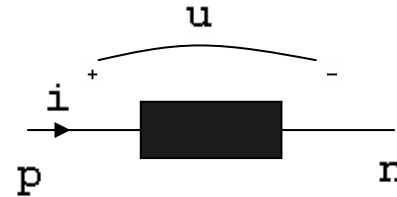
```
  i = p.i;
```

```
end TwoPin;
```

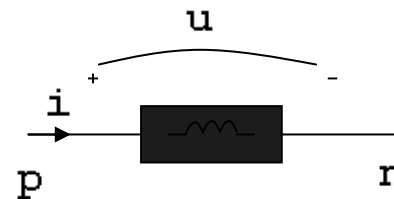


Electrical Components Reuse TwoPin SuperClass

```
model Resistor "Ideal electrical resistor"  
  extends TwoPin;  
  parameter Real R "Resistance";  
equation  
  R*i = u  
end Resistor;
```



```
model Inductor "Ideal electrical inductor"  
  extends TwoPin;  
  parameter Real L "Inductance";  
equation  
  L*der(i) = u  
end Inductor;
```



Corresponding DCMotor Model Equations

The following equations are automatically derived from the Modelica model:

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	$EM.i == EM.p.i$	$R.i == R.p.i$
$0 == R.p.i + L.n.i$	$EM.u == EM.k * EM.\omega$	$R.u == R.R * R.i$
$R.p.v == L.n.v$	$EM.i == EM.M / EM.k$	
	$EM.J * EM.\omega == EM.M - EM.b * EM.\omega$	$L.u == L.p.v - L.n.v$
$0 == L.p.i + EM.n.i$		$0 == L.p.i + L.n.i$
$L.p.v == EM.n.v$	$DC.u == DC.p.v - DC.n.v$	$L.i == L.p.i$
	$0 == DC.p.i + DC.n.i$	$L.u == L.L * L.i'$
$0 == EM.p.i + DC.n.i$	$DC.i == DC.p.i$	
$EM.p.v == DC.n.v$	$DC.u == DC.Amp * Sin[2 \pi DC.f * t]$	
$0 == DC.n.i + G.p.i$		
$DC.n.v == G.p.v$		

(load component not included)

- Syntax - there are many efficient parser generator tools
 - lex (flex), yacc (bison), ANTLR, Coco, etc.
- *Semantics:*
 - *there are no standard efficient and easy to use compiler-compiler tools*

- Can we adapt the Modelica equation-based style to define semantics of programming languages?
 - *Answer: Yes!*
- MetaModelica is just a part of the answer
 - executable language specification based on
 - a model (abstract syntax tree)
 - semantic functions over the model
 - elaboration and typechecking
 - translation
 - meta-programming
 - transformation
 - etc.
- Further improvement - more reuse of language specification parts when building specifications for a new language (Future Work)

- We started from
 - The Relational Meta-Language (RML)
 - A system for building executable natural semantics specifications
 - Used to specify Java, Pascal-subset, C-subset, Mini-ML, etc.
 - The OpenModelica compiler for Modelica specified in RML
- Idea: *integrate RML meta-modeling and meta-programming facilities within OpenModelica by extending the Modelica language.*
The notion of equation is used as the unifying feature
- Now we have
 - The MetaModelica language
 - The Modelica executable language specification (OpenModelica compiler) in MetaModelica (~114232 lines of code)
 - Meta-programming facilities for Modelica

MetaModelica extensions to Modelica (I)

- Modelica
 - classes, models, records, functions, packages
 - behaviour is defined by equations or/and functions
 - equations
 - differential equations
 - algebraic equations
 - partial differential equations
 - difference equations
 - conditional equations
- MetaModelica extensions
 - local equations
 - pattern equations
 - match expressions
 - lists, tuples, option and uniontypes

MetaModelica extensions to Modelica (II)

- pattern equations
 - unbound variables get their value by unification

```
Env.BOOLVAL(x,y) = eval_something(env, e);
```

- match expressions
 - pattern matching
 - case rules

```
pattern := match expression optional-local-declarations  
  case pattern-expression opt-local-declarations  
    optional-local-equations then value-expression;  
  case ...  
  ...  
  else optional-local-declarations  
    optional-local-equations then value-expression;  
end match;
```

```
package ExpressionEvaluator

// abstract syntax declarations
...
// semantic functions
...

end ExpressionEvaluator;
```

MetaModelica - Example (II)

```
package ExpressionEvaluator
```

```
// abstract syntax declarations
```

```
uniontype Exp
```

```
  record RCONST Real x1; end RCONST; 12
```

```
  record PLUS   Exp x1; Exp x2; end PLUS;
```

```
  record SUB    Exp x1; Exp x2; end SUB;
```

```
  record MUL    Exp x1; Exp x2; end MUL;
```

```
  record DIV    Exp x1; Exp x2; end DIV;
```

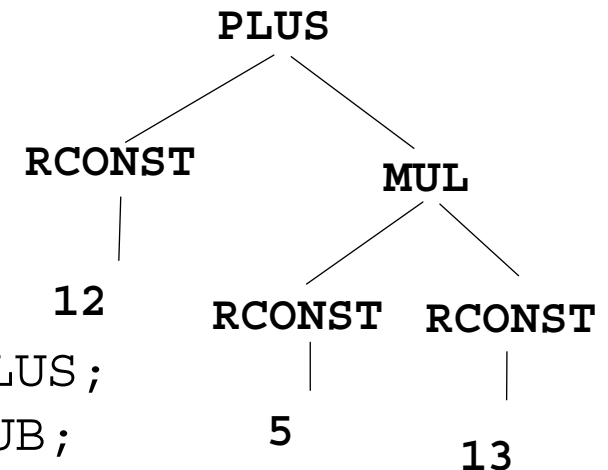
```
  record NEG    Exp x1;      end NEG;
```

```
end Exp;
```

```
// semantic functions
```

```
...
```

```
end ExpressionEvaluator;
```



Expression: 12+5*13

Representation:

```
PLUS (
  RCONST (12) ,
  MUL (
    RCONST (5) ,
    RCONST (13)
  )
)
```


MetaModelica – Example (III)

```
package ExpressionEvaluator
// abstract syntax declarations
...

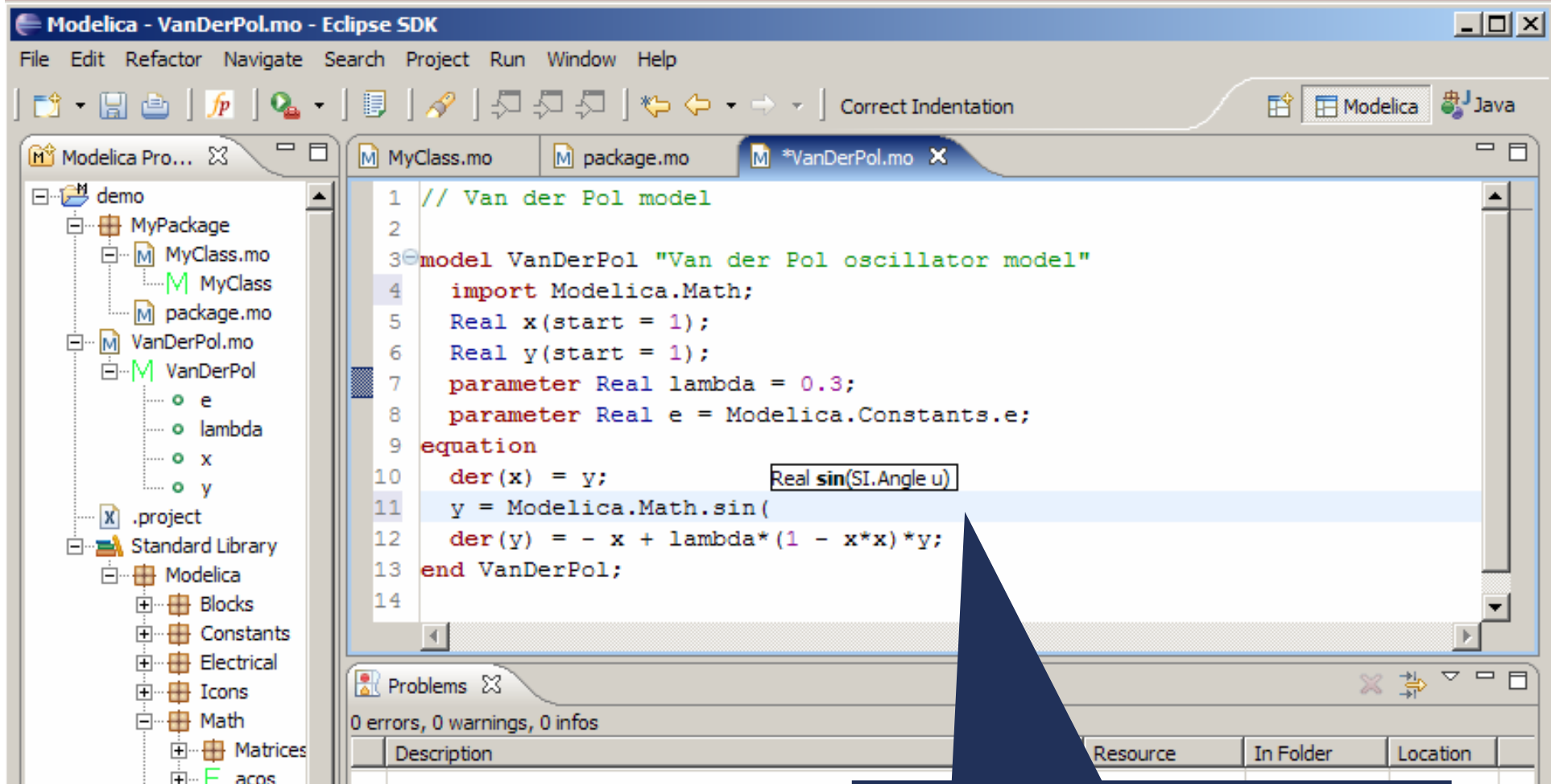
// semantic functions
function eval
  input  Exp  in_exp;
  output Real out_real;
algorithm
  out_real := match in_exp
    local Real v1,v2,v3;  Exp e1,e2;
    case RCONST(v1) then v1;
    case ADD(e1,e2) equation
      v1 = eval(e1);  v2 = eval(e2); v3 = v1 + v2;  then v3;
    case SUB(e1,e2) equation
      v1 = eval(e1);  v2 = eval(e2); v3 = v1 - v2;  then v3;
    case MUL(e1,e2) equation
      v1 = eval(e1);  v2 = eval(e2); v3 = v1 * v2;  then v3;
    case DIV(e1,e2) equation
      v1 = eval(e1);  v2 = eval(e2); v3 = v1 / v2;  then v3;
    case NEG(e1) equation
      v1 = eval(e1); v2 = -v1;  then v2;
  end match;
end eval;

end ExpressionEvaluator;
```

Modelica/MetaModelica Development Tooling (MDT)

- Supports textual editing of Modelica/MetaModelica code as an Eclipse plugin
- Was created to ease the development of the OpenModelica development (114232 lines of code) and to support advanced Modelica library development
- It has most of the functionality expected from a Development Environment
 - code browsing
 - code assistance
 - code indentation
 - code highlighting
 - error detection
 - automated build of Modelica/MetaModelica projects
 - debugging

Modelica/MetaModelica Development Tooling



Code Assistance on
function calling.

Conclusions and Future Work

- MetaModelica a language that integrates modeling of
 - physical systems
 - programming language semantics
- at the **equation** level

- MetaModelica is a step towards reusable libraries of specifications for programming language semantics

- Future Work
 - How do devise a suitable component model for the specification of a programming language semantics in terms of reusable components.
 - Tools to support such language modeling.

Thank you!
Questions?

<http://www.ida.liu.se/labs/pelab/rml>

<http://www.ida.liu.se/labs/pelab/modelica/OpenModelica.html>