

COMPUTER TECHNOLOGY

Millisecond interval timer and auditory reaction time programs for the IBM PC

ROGER GRAVES and RON BRADLEY

University of Victoria, Victoria, British Columbia, Canada

Many types of behavioral research require the determination of elapsed time, for example to establish interstimulus intervals and to measure reaction time. The use of an IBM PC for on-line control of such applications is limited by the poor timing resolution ordinarily available. The IBM BIOS time information that is used for the BASIC TIMER function can result in interval timing errors as great as 110 msec. A machine language subroutine is described that can provide 1-msec accuracy. A BASIC program is also described that employs this subroutine to measure auditory reaction time.

Many applications for a personal computer as an on-line controller in psychology studies require an interval timing capability with millisecond resolution. Recording of reaction times is a prime example. Unfortunately, the TIMER function available from IBM BASIC provides time readout in 55-msec increments. Using TIMER twice for interval timing would thus result in potential errors as great as 110 msec. (The fact that the values returned by TIMER contain two decimal places suggests a precision of 10 msec; however, actual precision is 55 msec, as evidenced in successive returned values that remain unchanged, and then suddenly change by .05 or .06 sec.) The cause of this poor resolution rests with the IBM BIOS, which updates time information only every 55 msec.

Smith and Puckett (1984) discussed the problem of the IBM PC time resolution and reported that the 8253 timing chip used in the IBM PC actually contains timing information with microsecond resolution. They described machine language programs that can be used to access this information. Their programs, however, are not written in a form that can be used directly for research timing applications using BASIC. Appendices A and B show two machine language programs that incorporate Smith and Puckett's approach in a form that can be called from BASIC.

The first program, TIMERSET, is used to set the timer chip into Mode 2. The second program, TMRREAD, is used to return 6 bytes of data (3 basic integer variables), representing the number of clock counts since the preced-

ing midnight. The Appendix A and B listings include brief documentation of program operation; more complete information can be found in Smith and Puckett's (1984) article. For use with interpreted BASIC, these two programs were assembled and linked with the IBM Macro Assembler into one machine language program, TIMER.BIN. For use with compiled BASIC programs, TIMERSET and TMRREAD are written in a form that allows them to be linked with compiled programs.

The accuracy of the timing provided by the TMRREAD program was checked with an interpreted BASIC program, TESTCRT.BAS, which measures the time for 10 frames of the color monitor display. The correct time is 166.67 msec. The results for 100 trials using an IBM PC/XT were: mean of 167.07 msec, standard deviation of 0.06 msec, and maximum error of 0.61 msec. These data indicate that good timing accuracy can be obtained even with interpreted BASIC. Similar results were obtained with another IBM PC/XT and with several "true-compatible" PC/XT clones. The program did not return correct times on a semicompatible Zenith Z-158 running GW-BASIC. A compiled BASIC version of this program was linked with TIMERSET and TMRREAD to produce an executable program (TESTCRT.EXE). The results on the IBM PC/XT—mean of 166.88 msec, standard deviation of 0.02 msec, and maximum error of 0.34 msec—demonstrate that the decreased overhead of compiled programs will improve accuracy of timing.

Appendix C provides a BASIC program, RT.BAS, which illustrates how TIMER.BIN can be used to establish predetermined time intervals (interstimulus intervals) and to measure event latencies (subject reaction time). The listing of RT.BAS includes descriptive information on the program operation. Basically, the program produces a beep stimulus and then uses TMRREAD to measure the subject's reaction time to press the space bar. Following

Preparation of this article was supported in part by Grant A-1021 from the National Science and Engineering Research Council. This work would not have been possible without the contributions of Tom Allen and Eric Hargreaves to earlier versions of the programs.

Requests for reprints should be sent to: Roger Graves, Department of Psychology, University of Victoria, Victoria, British Columbia V8W 2Y2, Canada.

an intertrial interval, which is also established using TMRREAD, the stimulus is presented again for another trial, and so forth. To prevent the subject from anticipating the stimulus, the intertrial interval is made random in the range of 2,000–8,000 msec. Since the SOUND command in BASIC appears to produce sound in synchrony with timer interrupts, it was necessary to control sound generation directly using a method described by Norton (1985). During the development of RT.BAS, it was also found that the TIMER and ON TIMER functions of BASIC could not be used in the same program as TMRREAD (or TIMER.BIN) since they impair the accuracy of timing using TMRREAD.

Timing performance using the IBM PC was checked against reaction times recorded independently using a Gerbrands digital millisecond timer. A Schmitt trigger circuit connected to the IBM PC speaker leads started the timer when audio voltage appeared at the speaker. A Gerbrands voice-operated relay stopped the timer when a microphone placed at the keyboard detected the sound of the keypress response. Results for 20 trials using the standard IBM PC keyboard showed times that were slow on average by 18.4 msec ($SD = 4.3$ msec). Results for 20 trials using the keyboard from a clone with the same IBM PC showed times that were slow on average by 36.7 msec ($SD = 2.9$ msec). These discrepancies, which presumably arise from delays in the keyboard, indicate that the keyboard is not an ideal response device for critical applications. However, for applications in which random errors of the order of these standard deviations (4 msec) can be tolerated, the times can be corrected by subtracting the mean

error. This was done in the RT.BAS program listed in Appendix C. Greatly improved accuracy was obtained by using the buttons on a joystick as the response device (Gravis Mk IV joystick, connected to an AST SixPacPlus game port). With the same independent timing setup and 20 trials, the PC times were slow on average by 0.55 msec ($SD = 0.51$ msec) with no discrepancy greater than 1 msec. These latter results confirm that good reaction time accuracy can be obtained with the IBM PC even with interpreted BASIC. The listing of RT.BAS in Appendix C includes the commands that were employed to detect game button responses.

AVAILABILITY

A diskette containing RT.BAS, TESTCRT.BAS; the ASCII (.ASM) and assembled (.OBJ) versions of TIMERSET and TMRREAD; and the ASCII compiler (.ASC), compiled (.OBJ), and linked (.EXE) versions of TESTCRT (which also serve to illustrate how the timing programs are called in compiled BASIC) is available for \$6 (Canadian) from the Neuropsychology Clinic, Department of Psychology, University of Victoria, Victoria, British Columbia V8W 2Y2, Canada.

REFERENCES

- NORTON, P. (1985). *The programmer's guide to the IBM PC*. Bellview, Washington: Microsoft Press.
SMITH, B., & PUCKETT, T. (1984, April). Life in the fast lane. *PC Tech Journal*, 63-74.

APPENDIX A

Listing of TIMERSET Program

```

PAGE
    title   TIMERSET
    name    TIMERSET    ;module

comment |

Environment:  IBM PC, tested under DOS 3.1

Segmentation: Program segment CODE, byte aligned

Specifications: This module is designed to be called with the
                 BASIC "CALL" statement. The result of calling
                 this routine will be the placing of Counter 0
                 of the 8253 timer chip into Mode 2 and setting
                 the Counter 0 count value to zero (equivalent
                 to 65536). In this mode the timer updates the
                 BIOS registers after each 65536 system clock
                 cycles and can retain the number of system clock
                 cycles ("residual count") since the last update.

Implementation: Called from BASIC

example:
10 DEF SEG =
20 BLOAD"TIMERSET.BIN"
30 DEFINT A-Z
40 A = 0
50 CALL A()
```

APPENDIX A (Continued)

Original Code by: Bob Smith, Tom Puckett
PC TECH JOURNAL, April 1984

Modified by: R. Bradley, Aug. 1986

```

|
CODE SEGMENT BYTE PUBLIC 'CODE'

    ASSUME CS:CODE
    PUBLIC TIMERSET

;equates.....

TIMER_0 EQU 040H           ;8253 Counter 0 Port
TIMER_CTL EQU 043H        ;8253 Control Port
TIMER_SET EQU 00110100B   ;8253 Counter 0,
                           ;set to Mode 2

;timerset module.....

TIMERSET PROC FAR

    PUSH    AX
    PUSH    CX
    MOV     AL,TIMER_SET
    OUT    TIMER_CTL,AL    ;set Counter 0 to mode 2
    XOR    AL,AL           ;zero AL register
    NOP
    OUT    TIMER_0,AL      ;8253 recovery time
                           ;set low order count
                           ;byte to zero
    NOP
    NOP
    OUT    TIMER_0,AL      ;8253 recovery time
                           ;set high order count
                           ;byte to zero
    MOV    CX,20000        ;loop to ensure
LOOP:  LOOP LOOP           ;previous count ends
    POP    CX
    POP    AX
    RET

TIMERSET ENDP
CODE ENDS
END

```

APPENDIX B

Listing of TMRREAD

```

PAGE
    title TMRREAD
    name TMRREAD ;module

```

comment |

Environment: IBM PC, tested under DOS 3.1

Segmentation: Program segment CODE, byte aligned

Specifications: This module is designed to be called with the BASIC "CALL" statement. The result of calling this routine will be the return of microsecond timing data from the 8253 timer and the BIOS second and hour fields. The microsecond count is obtained from Counter 0 of the 8253 timer. In order for the timer count to be valid, Counter 0 must have been initialized for Mode 2 operation by calling the TIMERSET module.

```

*****
"MODE 2 OPERATION OF 8253 MUST BE INVOKED BEFORE THIS
MODULE IS RUN"
*****

```

APPENDIX B (Continued)

Implementation: Called from BASIC

example:

```
10 DEF SEG =
20 BLOAD"TMRRREAD.BIN"
30 DEFINT A-Z
40 A = 0
50 CALL A(HIGH, LOW, RESIDUAL)
```

where HIGH = BIOS timer high
 LOW = BIOS timer low
 RESIDUAL = Counter 0 residual count

Returns: will return BIOS timer fields, and the Counter 0 residual count. Data is returned to the BASIC program using the BASIC stack.

BASIC can only accept integer values in the range of -32768 to 32767 so routine subtracts 32768 from the data and passes back valid BASIC integers.

```
STACK POINTER + 10 = TIMER HIGH COUNT
STACK POINTER + 8  = TIMER LOW COUNT
STACK POINTER + 6  = RESIDUAL COUNT
```

Original Code by: Bob Smith & Tom Puckett,
 PC TECH JOURNAL, April 1984

Modified by: R. Bradley, Aug. 1986

suggested invocation:

Called from BASIC program. Module is first linked with TIMRSET.EXE and can then be run from BASIC with the CALL NUMBER(HIGH,LOW,RESIDUAL) command after being loaded into the BASIC program.

```

|
BIOS_SEG EQU 040H
BIOS_DATA SEGMENT AT 040H

    ORG 06CH

TIMER_LOW DW ?           ;bios timer storage
TIMER_HIGH DW ?          ;words

BIOS_DATA ENDS

CODE SEGMENT BYTE PUBLIC 'CODE' ;code segment

    ASSUME CS:CODE
    PUBLIC TMRRREAD

;equates.....

TIMER_0 EQU 040H         ;8253 counter 0 port
TIMER_CTL EQU 043H       ;8253 control port
TIMER_LATCH EQU 00H      ;8253 command - save current
                        ; residual count

;tmrread module.....

TMRRREAD PROC FAR

    PUSH BP
    MOV BP,SP
    PUSH DS
    POP ES                ;use ES for storing data
    MOV AX,BIOS_SEG
    MOV DS,AX            ;new DS points to BIOS

    ASSUME DS:BIOS_DATA,ES:NOTHING

    MOV AL,TIMER_LATCH   ;save current residual count
```

APPENDIX B (Continued)

```

      CLI                      ;disable interrupts
      OUT TIMER_CTL,AL        ;command for 8253 timer
      MOV BX,TIMER_LOW       ;get BIOS timer values
      MOV CX,TIMER_HIGH
      IN AL,TIMER_0          ;get 8253 count
      MOV AH,AL
      NOP
      IN AL,TIMER_0
      STI
      XCHG AH,AL             ;put timer count in
      NEG AX                 ;correct order and invert
      XCHG AX,CX
      SUB AX,32768           ;set up data for BASIC
      SUB BX,32768           ;integers
      SUB CX,32768
      MOV DX,BX              ;move timer low to DX
      MOV BX,[BP+10]         ;get TIMER HIGH from
      MOV ES:[BX],AX         ;stack and load with AX
      MOV BX,[BP+8]         ;get TIMER LOW from
      MOV ES:[BX],DX         ;stack and load with DX
      MOV BX,[BP+6]         ;get 8253 count from
      MOV ES:[BX],CX         ;stack and load with CX
      PUSH ES
      POP AX
      MOV DS,AX              ;restore old DS
      POP BP                 ;restore old BP
      RET 6

  THRREAD  ENDP
  CODE     ENDS
  END

```

APPENDIX C
Listing of RT.BAS

```

100 GOTO 140 '
110 '
120 '
130 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
140 KEY OFF: CLS 'CLEAR SCREEN
150 DEFINT A-Z 'DEFINE VARIABLES, CONSTANTS & FUNCTIONS
160 P=&H60 'PORT FOR KEYBOARD RESPONSE
165 'P=&H201 'PORT FOR GAME BUTTON RESPONSE
170 Q=&H61 'PORT FOR CONTROLLING SPEAKER
180 N=255 'MASK TO DETECT KEYBOARD RESPONSE
185 'N=240 'MASK TO DETECT GAME BUTTON RESPONSE
190 I=0 'INDEX FOR LOOP
200 K=80 'CONSTANT FOR 80 MSEC LENGTH OF SOUND
210 H=0: H1=0: H2=0 'HIGH BYTES OF TIME COUNT
220 L=0: L1=0: L2=0 'LOW BYTES OF TIME COUNT
230 R=0: R1=0: R2=0 'RESIDUAL BYTES OF TIME COUNT
240 ITI#=0# 'CONSTANT FOR INTERTRIAL INTERVAL
250 CORRECTION#=18.4# 'MEASURED MEAN ERROR WITH IBM-PC
      KEYBOARD (KEYBOARD DELAY?)

255 'CORRECTION#=0# 'NO CORRECTION NEEDED FOR GAME BUTTON
260 K#=41# 'MSECS TAKEN BY TIME COMPARISON
270 COUNT=CINT(1193280!/1000!) 'TIMER COUNT FOR A FREQ OF 1000 HZ
280 LO.COUNT=COUNT MOD 256 'CALCULATE LOW ORDER BYTE
290 HI.COUNT=COUNT/256 'CALCULATE HIGH ORDER BYTE
300 SNOFF=INP(&H61) 'OLD VALUE OF PORT H61 (FOR SPEAKER)
310 SNDON=(SNOFF OR &H3) 'NEW VALUE TO TURN SPEAKER ON
320 T1#=0: T2#=0: T3#=0 'TIME VARIABLES
330 RT#=0 'REACTION TIME
340 D#=32768# 'FOR ADDING TO COUNT VARIABLES
350 E#=65536# 'FOR MULTIPLYING COUNT VARIABLES
360 F#=.000838095# 'NUMBER OF MILLISECONDS PER COUNT
370 A%=0: B%=0 'LOCATIONS OF MACHINE LANG SUBROUTINES
380 DEF FNT#(H,L,R)={((CDBL(H)+D#)*E#*E#)+((CDBL(L)+D#)*E#)+(CDBL(R)+D#)}*F#
390 'FUNCTION TO CONVERT RETURNED COUNT VARIABLES TO NUMBER MSEC SINCE MIDNIGHT
400 DIM A(120) 'ARRAY USED TO LOAD TIMING SUBROUTINES
410 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
420 A%=VARPTR(A(0)) 'A% = START OF MEMORY FOR TIMING SUBROUTINES
430 BLOAD"TIMER.BIN",A% 'LOAD TIMING SUBROUTINES
440 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
450 PRINT " PRESS THE SPACE BAR AS QUICKLY AS YOU CAN WHEN YOU HEAR THE
BEEP":PRINT

```

APPENDIX C (Continued)

```

455 'PRINT " PRESS A BUTTON ON THE JOYSTICK AS QUICKLY AS YOU CAN WHEN YOU HEAR
THE BEEP"
460 '
470 OUT &H43,&HB6 'GET 8253 TIMER CHANNEL 2 READY FOR COMMAND
480 OUT &H42,LO.COUNT 'LOAD LOW BYTE OF SOUND FREQ.
490 OUT &H42,HI.COUNT 'LOAD HIGH BYTE OF SOUND FREQ.
500 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
510 ' ESTABLISH INTERTRIAL INTERVAL
520 A%=VARPTR(A(0)) 'A% = START OF MEMORY FOR TIMERSUBROUTINE
530 CALL A% 'SET 8253 TIMER CHANNEL 0 TO MODE 2
540 B%=VARPTR(A(0))+&H17 'B% = LOCATION OF TMRREAD SUBROUTINE
550 CALL B%(H,L,R): T2#=FNT%(H,L,R) 'T2# = CURRENT TIME
560 ITI#=(INT(RND*(7000))+2000) 'RANDOM NUMBER BETWEEN 2000 AND 8000
570 ITI#=ITI#+T2#-K# 'TIME AT WHICH TO EXIT DELAY LOOP
580 CALL B%(H,L,R): IF FNT%(H,L,R)<ITI# THEN GOTO 580
590 'DELAY FOR ITI MILLISECONDS
600 'USING INTERPRETED BASIC, THIS METHOD OF ESTABLISHING INTERVALS CAN NOT
610 'BE USED FOR INTERVALS LESS THAN 41 MSEC. - ALSO, THE INTERVALS MAY BE IN
620 'ERROR BY AS MUCH AS 41 MSEC. - THIS IS THE TIME TAKEN FOR THE
630 'TIME COMPARISON IN LINE 580.
640 'THIS IS BETTER THAN THE 110 MSEC POSSIBLE ERROR USING THE "TIMER" COMMAND.
650 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
660 ' MEASURE REACTION TIME
670 A%=VARPTR(A(0)) 'A% = START OF MEMORY FOR TIMERSUBROUTINE
680 CALL A% 'SET 8253 TIMER CHANNEL 0 TO MODE 2
690 B%=VARPTR(A(0))+&H17 'B% = LOCATION OF TMRREAD SUBROUTINE
700 OUT Q,SNDON:CALL B%(H1,L1,R1) 'START SOUND AND GET CURRENT TIME
710 FOR I=1 TO K: NEXT 'CONTINUE SOUND DURING LOOP DELAY
720 OUT Q,SNDOFF 'STOP SOUND
730 DEF SEG=0: POKE 1050,PEEK(1052):DEF SEG 'CLEAR KEYBOARD BUFFER
735 ' 'NO COMMAND FOR GAME BUTTONS
740 WAIT P,N:CALL B%(H2,L2,R2)
745 'WAIT P,N,N:CALL B%(H2,L2,R2)
750 '
760 'LINE 740 WAITS FOR KEYBOARD RESPONSE AND THEN GETS TIME AT RESPONSE
770 'LINE 745 WAITS FOR GAME BUTTON RESPONSE AND THEN GETS TIME AT RESPONSE
780 '
790 T1#=FNT%(H1,L1,R1) 'T1# = TIME AT STIMULUS
800 T2#=FNT%(H2,L2,R2) 'T2# = TIME AT RESPONSE
810 RT#=T2#-T1#-CORRECTION# 'RT# = REACTION TIME
820 PRINT USING "#####";RT#, 'PRINT REACTION TIME IN MILLISECONDS
830 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
840 GOTO 560 'REPEAT STIMULUS
850 '!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!
860 'NOTE: THE CONVERSION IN LINE 790 TAKES 35 MILLISECONDS WHEN
870 'USING INTERPRETED BASIC.
880 'THEREFORE, THIS SHOULD NOT BE DONE UNTIL AFTER THE TIMED INTERVAL
890 'IN ORDER TO PREVENT ERRORS IN TIMING SHORT INTERVALS.
900 '
910 'TO USE THE AST SixPacPlus GAME PORT AND JOYSTICK BUTTONS FOR THE RESPONSE
915 'REPLACE LINES 160, 180, 250, 450, 730, AND 740 WITH LINES
165, 185, 255, 455, 735, AND 745 RESPECTIVELY.

```

(Manuscript received September 26, 1986;
revision accepted for publication December 12, 1986.)