# MÖBIUS ISOTROPIC SUBMANIFOLDS IN $S^{n}$ 

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#### Abstract

Let $x: \boldsymbol{M}^{m} \rightarrow \boldsymbol{S}^{n}$ be a submanifold in the $n$-dimensional sphere $\boldsymbol{S}^{n}$ without umbilics. Two basic invariants of $x$ under the Möbius transformation group in $S^{n}$ are a 1-form $\Phi$ called the Möbius form and a symmetric $(0,2)$ tensor $\mathbf{A}$ called the Blaschke tensor. $x$ is said to be Möbius isotropic in $\boldsymbol{S}^{n}$ if $\Phi \equiv 0$ and $\mathbf{A}=\lambda d x \cdot d x$ for some smooth function $\lambda$. An interesting property for a Möbius isotropic submanifold is that its conformal Gauss map is harmonic. The main result in this paper is the classification of Möbius isotropic submanifolds in $S^{n}$. We show that (i) if $\lambda>0$, then $x$ is Möbius equivalent to a minimal submanifold with constant scalar curvature in $S^{n}$; (ii) if $\lambda=0$, then $x$ is Möbius equivalent to the preimage of a stereographic projection of a minimal submanifold with constant scalar curvature in the $n$-dimensional Euclidean space $\boldsymbol{R}^{n}$; (iii) if $\lambda<0$, then $x$ is Möbius equivalent to the image of the standard conformal map $\tau: \boldsymbol{H}^{n} \rightarrow \boldsymbol{S}_{+}^{n}$ of a minimal submanifold with constant scalar curvature in the $n$-dimensional hyperbolic space $\boldsymbol{H}^{n}$. This result shows that one can use Möbius differential geometry to unify the three different classes of minimal submanifolds with constant scalar curvature in $\boldsymbol{S}^{n}, \boldsymbol{R}^{n}$ and $\boldsymbol{H}^{n}$.


1. Introduction. Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be an $m$-dimensional submanifold in the $n$ dimensional sphere $S^{n}$ without umbilics. Let $\left\{e_{i}\right\}$ be a local orthonormal basis for the first fundamental form $I=d x \cdot d x$ with dual basis $\left\{\theta_{i}\right\}$. Let $I I=\sum_{i j \alpha} h_{i j}^{\alpha} \theta_{i} \theta_{j} e_{\alpha}$ be the second fundamental form of $x$ and $H=\sum_{\alpha} H^{\alpha} e_{\alpha}$ the mean curvature vector of $x$, where $\left\{e_{\alpha}\right\}$ is a local orthonormal basis for the normal bundle of $x$. We define $\rho^{2}=m /(m-1) \cdot\left(\|I I\|^{2}-m\|H\|^{2}\right)$, where $\|\|$ is the norm with respect to the induced metric $d x \cdot d x$ on $\boldsymbol{M}$. Then two basic Möbius invariants of $x$, the Möbius form $\Phi=\sum_{i} C_{i}^{\alpha} \theta_{i} e_{\alpha}$ and the Blaschke tensor $\mathbf{A}=\rho^{2} \sum_{i j} A_{i j} \theta_{i} \theta_{j}$, are defined by (cf. [W])

$$
\begin{align*}
C_{i}^{\alpha}= & -\rho^{-2}\left(H_{, i}^{\alpha}+\sum_{j}\left(h_{i j}^{\alpha}-H^{\alpha} \delta_{i j}\right) e_{j}(\log \rho)\right)  \tag{1.1}\\
A_{i j}= & -\rho^{-2}\left(\operatorname{Hess}_{i j}(\log \rho)-e_{i}(\log \rho) e_{j}(\log \rho)-\sum_{\alpha} H^{\alpha} h_{i j}^{\alpha}\right)  \tag{1.2}\\
& -\frac{1}{2} \rho^{-2}\left(\|\nabla \log \rho\|^{2}-1+\|H\|^{2}\right) \delta_{i j}
\end{align*}
$$

[^0]where $\operatorname{Hess}_{i j}$ and $\nabla$ are the Hessian-matrix and the gradient with respect to $d x \cdot d x$. A submanifold $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ is called Möbius isotropic if $\Phi \equiv 0$ and $\mathbf{A}=\lambda d x \cdot d x$ for some function $\lambda$.

Let $\boldsymbol{H}^{n}$ be the $n$-dimensional hyperbolic space defined by

$$
\boldsymbol{H}^{n}=\left\{\left(y_{0}, y_{1}, \ldots, y_{n}\right) \mid-y_{0}^{2}+y_{1}^{2}+\cdots y_{n}^{2}=-1, y_{0}>0\right\}
$$

Let $\boldsymbol{S}_{+}^{n}$ be the hemisphere in $\boldsymbol{S}^{n}$ whose first coordinate is positive. Let $\sigma: \boldsymbol{R}^{n} \rightarrow \boldsymbol{S}^{n} \backslash\{(-1,0)\}$ and $\tau: \boldsymbol{H}^{n} \rightarrow \boldsymbol{S}_{+}^{n}$ be the following conformal diffeomorphisms:

$$
\begin{align*}
\sigma(u) & =\left(\frac{1-|u|^{2}}{1+|u|^{2}}, \frac{2 u}{1+|u|^{2}}\right), \quad u \in \boldsymbol{R}^{n},  \tag{1.3}\\
\tau(y) & =\left(\frac{1}{y_{0}}, \frac{y_{1}}{y_{0}}\right), \quad y_{0}>0, \quad-y_{0}^{2}+y_{1} \cdot y_{1}=-1, \quad y_{1} \in \boldsymbol{R}^{n} . \tag{1.4}
\end{align*}
$$

Then we can state our main result as follows:
CLASSIFICATION THEOREM. Any Möbius isotropic submanifold in $S^{n}$ is Möbius equivalent to one of the following Möbius isotropic submanifolds:
(i) minimal submanifolds with constant scalar curvature in $\boldsymbol{S}^{n}$;
(ii) the images of $\sigma$ of minimal submanifolds with constant scalar curvature in $\boldsymbol{R}^{n}$;
(iii) the images of $\tau$ of minimal submanifolds with constant scalar curvature in $\boldsymbol{H}^{n}$.

This paper is organized as follows. In Section 2 we give Möbius invariants and structure equations for submanifolds in $S^{n}$. In Section 3 we show that the conformal Gauss map of an isotropic submanifold in $S^{n}$ is harmonic. In Section 4 we give conformal invariants for submanifolds in $\boldsymbol{R}^{n}$ and $\boldsymbol{H}^{n}$ and relate them to the Möbius invariants of submanifolds in $\boldsymbol{S}^{n}$. Using these relations we show that all submanifolds in (i), (ii) and (iii) of the classification theorem are Möbius isotropic submanifolds. Then in Section 5 we prove the classification theorem for Möbius isotropic submanifolds.

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2. Möbius invariants for submanifolds in $\boldsymbol{S}^{n}$. In this section we define Möbius invariants and recall structure equations for submanifolds in $\boldsymbol{S}^{n}$. For more detail we refer to [W].

Let $\boldsymbol{R}_{1}^{n+2}$ be the Lorentzian space with inner product

$$
\begin{equation*}
\langle x, w\rangle=-x_{0} w_{0}+x_{1} w_{1}+\cdots+x_{n+1} w_{n+1} \tag{2.1}
\end{equation*}
$$

where $x=\left(x_{0}, x_{1}, \ldots, x_{n+1}\right)$ and $w=\left(w_{0}, w_{1}, \ldots, w_{n+1}\right)$. Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be a $m$ dimensional submanifold of $\boldsymbol{S}^{n}$ without umbilics. We define the Möbius position vector $Y$ : $\boldsymbol{M} \rightarrow \boldsymbol{R}_{1}^{n+2}$ of $x$ by

$$
\begin{equation*}
Y=\rho(1, x)=(\rho, \rho x), \quad \rho^{2}=m /(m-1) \cdot\left(\|I I\|^{2}-m\|H\|^{2}\right)>0 \tag{2.2}
\end{equation*}
$$

Then we have the following

THEOREM 2.1 ([W]). Two submanifolds $x, \tilde{x}: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ are Möbius equivalent if and only if there exists $T$ in the Lorentz group $O(n+1,1)$ in $\boldsymbol{R}_{1}^{n+2}$ such that $Y=\tilde{Y} T$.

As a matter of fact, the Möbius group in $S^{n}$ is isomorphic to the subgroup $O^{+}(n+1,1)$ of $O(n+1,1)$ which preserves the positive part of the light cone in $\boldsymbol{R}_{1}^{n+2}$. It follows immediately from Theorem 2.1 that

$$
\begin{equation*}
g=\langle d Y, d Y\rangle=\rho^{2} d x \cdot d x \tag{2.3}
\end{equation*}
$$

is a Möbius invariant (cf. [CH]). We call it the induced Möbius metric for $x$. Now let $\Delta$ be the Laplace operator of $g$. Then there is an identity given by

$$
\langle\Delta Y, \Delta Y\rangle=1+m^{2} \kappa
$$

where $\kappa$ is the normalized scalar curvature of $g$ (cf. [W]). We define

$$
\begin{equation*}
N=-\frac{1}{m} \Delta Y-\frac{1}{2 m^{2}}\left(1+m^{2} \kappa\right) Y \tag{2.4}
\end{equation*}
$$

Then we have

$$
\begin{equation*}
\langle Y, Y\rangle=\langle N, N\rangle=0, \quad\langle Y, N\rangle=1 \tag{2.5}
\end{equation*}
$$

Moreover, if we take a local orthonormal basis $\left\{E_{i}\right\}$ for the Möbius metric $g$ with dual basis $\left\{\omega_{i}\right\}$, then we have

$$
\begin{equation*}
\left\langle E_{i}(Y), E_{j}(Y)\right\rangle=\delta_{i j}, \quad\left\langle E_{i}(Y), Y\right\rangle=\left\langle E_{i}(Y), N\right\rangle=0, \quad 1 \leq i, j \leq m \tag{2.6}
\end{equation*}
$$

Let $\mathbf{V}$ be the orthogonal complement to the subspace in $\boldsymbol{R}_{1}^{n+2}$ spanned by $\left\{Y, N, E_{i}(Y)\right\}$. Then we have the following orthogonal decomposition:

$$
\begin{equation*}
\boldsymbol{R}_{1}^{n+2}=\operatorname{span}\{Y, N\} \oplus \operatorname{span}\left\{E_{1}(Y), \ldots, E_{m}(Y)\right\} \oplus \mathbf{V} \tag{2.7}
\end{equation*}
$$

$\mathbf{V}$ is called the Möbius normal bundle of $x$. A local orthonormal basis $\left\{E_{\alpha}\right\}$ for $\mathbf{V}$ can be written as

$$
\begin{equation*}
E_{\alpha}=\left(H^{\alpha}, H^{\alpha} x+e_{\alpha}\right), \quad m+1 \leq \alpha \leq n \tag{2.8}
\end{equation*}
$$

Now, let $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ be the Grassmannian manifold consisting of all positive definite oriented $(n-m)$-planes in the Lorentz space $\boldsymbol{R}_{1}^{n+2}$. The conformal Gauss map $f: \boldsymbol{M} \rightarrow$ $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right) \subset \bigwedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right)$ is then defined by

$$
\begin{equation*}
f=E_{m+1} \wedge E_{m+2} \wedge \cdots \wedge E_{n} \tag{2.9}
\end{equation*}
$$

Since $\left\{Y, N, E_{1}(Y), \ldots, E_{m}(Y), E_{m+1}, \ldots, E_{n}\right\}$ are Möbius invariant moving frame in $\boldsymbol{R}_{1}^{n+2}$ along $\boldsymbol{M}$, we can write the structure equations as

$$
\begin{align*}
E_{i}(N) & =\sum_{j} A_{i j} E_{j}(Y)+\sum_{\alpha} C_{i}^{\alpha} E_{\alpha}  \tag{2.10}\\
E_{j}\left(E_{i}(Y)\right) & =-A_{i j} Y-\delta_{i j} N+\sum_{k} \Gamma_{i j}^{k} E_{k}(Y)+\sum_{\alpha} B_{i j}^{\alpha} E_{\alpha}  \tag{2.11}\\
E_{i}\left(E_{\alpha}\right) & =-C_{i}^{\alpha} Y-\sum_{j} B_{i j}^{\alpha} E_{j}(Y)+\sum_{\beta} \Gamma_{\alpha i}^{\beta} E_{\beta}, \tag{2.12}
\end{align*}
$$

where $\left\{\Gamma_{i j}^{k}\right\}$ is the Levi-Civita connection of the Möbius metric $g ;\left\{\Gamma_{\alpha i}^{\beta}\right\}$ is the normal connection for $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$, which is a Möbius invariant; $\mathbf{A}=\sum_{i j} A_{i j} \omega_{i} \otimes \omega_{j}$ and $\Phi=$ $\sum_{i \alpha} C_{i}^{\alpha} \omega_{i}\left(\rho^{-1} e_{\alpha}\right)$ are called the Blaschke tensor and the Möbius form, respectively; and $\mathbf{B}=\sum_{i j \alpha} B_{i j}^{\alpha} \omega_{i} \omega_{j}\left(\rho^{-1} e_{\alpha}\right)$ is called the Möbius second fundamental form of $x$. The relations between $\mathbf{A}, \Phi, \mathbf{B}$ and the Euclidean invariants of $x$ are given by (1.1), (1.2) and

$$
\begin{equation*}
B_{i j}^{\alpha}=\rho^{-1}\left(h_{i j}^{\alpha}-H^{\alpha} \delta_{i j}\right) \tag{2.13}
\end{equation*}
$$

The integrability conditions for the structure equations (2.10) through (2.12) are given by (cf. [W])

$$
\begin{align*}
& A_{i j, k}-A_{i k, j}=\sum_{\alpha}\left(B_{i k}^{\alpha} C_{j}^{\alpha}-B_{i j}^{\alpha} C_{k}^{\alpha}\right),  \tag{2.14}\\
& C_{i, j}^{\alpha}-C_{j, i}^{\alpha}=\sum_{k}\left(B_{i k}^{\alpha} A_{k j}-B_{k j}^{\alpha} A_{k i}\right),  \tag{2.15}\\
& B_{i j, k}^{\alpha}-B_{i k, j}^{\alpha}=\delta_{i j} C_{k}^{\alpha}-\delta_{i k} C_{j}^{\alpha}  \tag{2.16}\\
& R_{i j k l}=\sum_{\alpha}\left(B_{i k}^{\alpha} B_{j l}^{\alpha}-B_{i l}^{\alpha} B_{j k}^{\alpha}\right)+\left(\delta_{i k} A_{j l}+\delta_{j l} A_{i k}-\delta_{i l} A_{j k}-\delta_{j k} A_{i l}\right),  \tag{2.17}\\
& R_{\alpha \beta i j}=\sum_{k}\left(B_{i k}^{\alpha} B_{k j}^{\beta}-B_{i k}^{\beta} B_{k j}^{\alpha}\right),  \tag{2.18}\\
& \sum_{i} B_{i i}^{\alpha}=0, \quad \sum_{i j \alpha}\left(B_{i j}^{\alpha}\right)^{2}=\frac{m-1}{m}, \quad \operatorname{tr} \mathbf{A}=\sum_{i} A_{i i}=\frac{1}{2 m}\left(1+m^{2} \kappa\right), \tag{2.19}
\end{align*}
$$

where $\kappa$ is the normalized scalar curvature of $g$. From (2.16) and (2.19) we get

$$
\begin{equation*}
\sum_{i} B_{i j, i}^{\alpha}=(1-m) C_{j}^{\alpha} \tag{2.20}
\end{equation*}
$$

DEFINITION 2.2. Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be a submanifold in $\boldsymbol{S}^{n}$ without umbilics. We call $x$ a Möbius isotropic submanifold in $\boldsymbol{S}^{n}$ if $\Phi \equiv 0$ and there exists a function $\lambda: \boldsymbol{M} \rightarrow \boldsymbol{R}$ such that $\mathbf{A}=\lambda g$.

Proposition 2.3. Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be a Möbius isotropic submanifold in $\boldsymbol{S}^{n}$. Then the function $\lambda$ in Definition 2.2 has to be constant.

Proof. Since $\Phi \equiv 0$ and $\mathbf{A}=\lambda g$, we can write (2.10) as $d N=\lambda d Y$, which implies that $d \lambda \wedge d Y=0$. Since $\left\{E_{1}(Y), \ldots, E_{m}(Y)\right\}$ are linearly independent, we get $\lambda=$ constant.
3. Conformal Gauss map of submanifolds in $\boldsymbol{S}^{n}$. Let $x: M \rightarrow S^{n}$ be a submanifold in $\boldsymbol{S}^{n}$. We assume that $\boldsymbol{M}$ is oriented. Then we can give the normal bundle $\boldsymbol{N}(\boldsymbol{M})$ of $x$ an orientation. Let $\left\{e_{\alpha}\right\}$ be a local orthonormal basis for $\boldsymbol{N}(\boldsymbol{M})$ which gives the orientation. Using the bundle isometry $\tau: N(\boldsymbol{M}) \rightarrow \mathbf{V}$ defined by $e_{\alpha} \rightarrow\left(H^{\alpha}, H^{\alpha} x+e_{\alpha}\right)$, we can give $\mathbf{V}$ an orientation. We define the conformal Gauss map $f: \boldsymbol{M} \rightarrow \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right) \subset \bigwedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right)$ by

$$
\begin{equation*}
f=E_{m+1} \wedge E_{m+2} \wedge \cdots \wedge E_{n} \tag{3.1}
\end{equation*}
$$

where $\left\{E_{\alpha}\right\}$ is an oriented orthonormal basis for $\mathbf{V}$. We denote by $I_{G}$ the induced metric of the standard embedding of $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ in $\bigwedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right)$. Our goal in this section is to prove the following

Theorem 3.1. Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be a Möbius isotropic submanifold in $\boldsymbol{S}^{n}$. Then its conformal Gauss map $f:(\boldsymbol{M}, g) \rightarrow\left(\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right), I_{G}\right)$ is harmonic.

Let $(\boldsymbol{M}, g)$ and $(\boldsymbol{N}, h)$ be two semi-Riemannian manifolds. We assume that $g$ is positive definite and $h$ is a metric of type $(r, s)$. Then locally we can write

$$
\begin{equation*}
g=\sum_{i=1}^{m} \theta_{i}^{2}, \quad h=-\sum_{\alpha=1}^{r} \theta_{\alpha}^{2}+\sum_{\lambda=r+1}^{r+s} \theta_{\lambda}^{2} \tag{3.2}
\end{equation*}
$$

We denote by $\left\{\theta_{i j}\right\}$ the connection forms of $g$ with respect to $\left\{\theta_{i}\right\}$ and denote by $\left\{\theta_{\alpha \beta}, \theta_{\alpha \lambda}, \theta_{\lambda \mu}\right\}$ the connection forms of $h$ with respect to $\left\{\theta_{\alpha}, \theta_{\lambda}\right\}$. Here we use the following ranges of the indices:

$$
\begin{equation*}
1 \leq i, j \leq m, \quad 1 \leq \alpha, \beta \leq r, \quad r+1 \leq \lambda, \mu \leq r+s \tag{3.3}
\end{equation*}
$$

Then we have

$$
\begin{align*}
d \theta_{i} & =\sum_{j} \theta_{i j} \wedge \theta_{j}  \tag{3.4}\\
d \theta_{\alpha} & =-\sum_{\beta} \theta_{\alpha \beta} \wedge \theta_{\beta}+\sum_{\lambda} \theta_{\alpha \lambda} \wedge \theta_{\lambda}, \quad d \theta_{\lambda}=-\sum_{\beta} \theta_{\lambda \beta} \wedge \theta_{\beta}+\sum_{\mu} \theta_{\lambda \mu} \wedge \theta_{\mu} \tag{3.5}
\end{align*}
$$

Now, let $f: \boldsymbol{M} \rightarrow \boldsymbol{N}$ be a smooth map. We define $\left\{f_{\alpha i}, f_{\lambda i}\right\}$ by

$$
\begin{equation*}
f^{*} \theta_{\alpha}=\sum_{i} f_{\alpha i} \theta_{i}, \quad f^{*} \theta_{\lambda}=\sum_{i} f_{\lambda i} \theta_{i} \tag{3.6}
\end{equation*}
$$

The second fundamental form $\left\{f_{\alpha i, j}, f_{\lambda i, j}\right\}$ of $f: \boldsymbol{M} \rightarrow \boldsymbol{N}$ is defined by

$$
\begin{align*}
d f_{\alpha i}+\sum_{j} f_{\alpha j} \theta_{j i}-\sum_{\beta} f_{\beta i} f^{*} \theta_{\beta \alpha}+\sum_{\lambda} f_{\lambda i} f^{*} \theta_{\lambda \alpha} & =\sum_{j} f_{\alpha i, j} \theta_{j}  \tag{3.7}\\
d f_{\lambda i}+\sum_{j} f_{\lambda j} \theta_{j i}-\sum_{\alpha} f_{\alpha i} f^{*} \theta_{\alpha \lambda}+\sum_{\mu} f_{\mu i} f^{*} \theta_{\mu \lambda} & =\sum_{j} f_{\lambda i, j} \theta_{j} \tag{3.8}
\end{align*}
$$

Then $f: \boldsymbol{M} \rightarrow \boldsymbol{N}$ is harmonic if and only if

$$
\begin{equation*}
\sum_{i} f_{\alpha i, i}=0, \quad \sum_{i} f_{\lambda i, i}=0, \quad 1 \leq \alpha \leq r, \quad r+1 \leq \lambda \leq r+s \tag{3.9}
\end{equation*}
$$

To prove Theorem 3.1 we study first the geometry of the Grassmannian manifold $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ as a submanifold in the pseudo-Euclidean space $\bigwedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right)$ with the inner product induced by $\left(\boldsymbol{R}_{1}^{n+2},\langle\rangle,\right)$. Let $\tilde{O}(n+1,1)$ be the manifold defined by

$$
\begin{equation*}
\tilde{O}(n+1,1)=\left\{\left.T \in G L(n+2, \boldsymbol{R})\right|^{t} T I_{1} T=J\right\} \tag{3.10}
\end{equation*}
$$

where $I_{1}=\operatorname{diag}\{-1,1, \ldots, 1\}$ and $J=\left(\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right) \oplus \operatorname{diag}\{1, \ldots, 1\}$. Then

$$
T=\left(\xi_{-1}, \xi_{0}, \xi_{1}, \ldots, \xi_{n}\right) \in \tilde{O}(n+1,1)
$$

if and only if

$$
\begin{align*}
\left\langle\xi_{-1}, \xi_{-1}\right\rangle & =\left\langle\xi_{0}, \xi_{0}\right\rangle=0, \quad\left\langle\xi_{-1}, \xi_{0}\right\rangle=1  \tag{3.11}\\
\left\langle\xi_{a}, \xi_{-1}\right\rangle & =\left\langle\xi_{a}, \xi_{0}\right\rangle=0, \quad\left\langle\xi_{a}, \xi_{b}\right\rangle=\delta_{a b}, \quad 1 \leq a, b \leq n \tag{3.12}
\end{align*}
$$

Let $\pi: \tilde{O}(n+1,1) \rightarrow \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ be the fibre bundle defined by

$$
\begin{equation*}
\pi(T)=\xi_{m+1} \wedge \cdots \wedge \xi_{n} \tag{3.13}
\end{equation*}
$$

Then around each point in $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ there exists an open set $U \subset \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ such that we have a local section

$$
\begin{equation*}
T=\left(\xi_{-1}, \xi_{0}, \xi_{1}, \ldots, \xi_{n}\right): U \rightarrow \tilde{O}(n+1,1) \tag{3.14}
\end{equation*}
$$

Thus the embedding of $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ in $\bigwedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right)$ can be written locally by the position vector

$$
\begin{equation*}
\xi=\xi_{m+1} \wedge \cdots \wedge \xi_{n}: U \rightarrow \wedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right) \tag{3.15}
\end{equation*}
$$

Since $\left\{\xi_{-1}, \xi_{0}, \xi_{1}, \ldots, \xi_{n}\right\}$ is a moving frame in $\boldsymbol{R}_{1}^{n+2}$ along $U \subset \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$, we can write the structure equations as

$$
\begin{equation*}
d \xi_{A}=\sum_{B} \theta_{A B} \xi_{B}, \quad-1 \leq A, B \leq n, \tag{3.16}
\end{equation*}
$$

where $d$ stands for the differential operator on $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ and $\left\{\theta_{A B}\right\}$ are local 1-forms on $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$. The integrability conditions for (3.16) are given by

$$
\begin{equation*}
d \theta_{A B}=\sum_{C} \theta_{A C} \wedge \theta_{C B}, \quad-1 \leq A, B, C \leq n \tag{3.17}
\end{equation*}
$$

Since (3.11) and (3.12) hold on $U$, we get from (3.16) that

$$
\begin{align*}
\theta_{0(-1)} & =\theta_{(-1) 0}=0, \quad \theta_{00} \tag{3.18}
\end{align*}=-\theta_{(-1)(-1)}, ~=\quad \theta_{(-1) a}=-\theta_{a 0}, \quad \theta_{a b}=-\theta_{b a}, \quad 1 \leq a, b \leq n .
$$

We make the following convention on the range of indices:

$$
1 \leq i, j, k \leq m, \quad m+1 \leq \alpha, \beta, \gamma \leq n, \quad-1 \leq A, B, C \leq n .
$$

Then from (3.15) we get

$$
\begin{align*}
d \xi= & \sum_{\alpha} \xi_{m+1} \wedge \cdots \wedge d \xi_{\alpha} \wedge \cdots \wedge \xi_{n}  \tag{3.20}\\
= & \sum_{\alpha}(-1)^{\alpha-m-1} \theta_{\alpha(-1)} \xi_{-1} \wedge \xi_{m+1} \wedge \cdots \wedge \widehat{\xi_{\alpha}} \wedge \cdots \wedge \xi_{n} \\
& +\sum_{\alpha}(-1)^{\alpha-m-1} \theta_{\alpha 0} \xi_{0} \wedge \xi_{m+1} \wedge \cdots \wedge \widehat{\xi_{\alpha}} \wedge \cdots \wedge \xi_{n} \\
& +\sum_{\alpha, i}(-1)^{\alpha-m-1} \theta_{\alpha i} \xi_{i} \wedge \xi_{m+1} \wedge \cdots \wedge \widehat{\xi_{\alpha}} \wedge \cdots \wedge \xi_{n}
\end{align*}
$$

Thus the induced metric $I_{G}$ of $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ in $\bigwedge^{n-m}\left(\boldsymbol{R}_{1}^{n+2}\right)$ is given by

$$
\begin{equation*}
I_{G}=\langle d \xi, d \xi\rangle=\sum_{\alpha}\left(\theta_{\alpha(-1)} \otimes \theta_{\alpha 0}+\theta_{\alpha 0} \otimes \theta_{\alpha(-1)}\right)+\sum_{\alpha i} \theta_{\alpha i}^{2} \tag{3.21}
\end{equation*}
$$

If we define

$$
\begin{equation*}
\phi_{\alpha(-1)}=\frac{1}{\sqrt{2}}\left(\theta_{\alpha(-1)}-\theta_{\alpha 0}\right), \quad \phi_{\alpha 0}=\frac{1}{\sqrt{2}}\left(\theta_{\alpha(-1)}+\theta_{\alpha 0}\right), \tag{3.22}
\end{equation*}
$$

then we can write

$$
\begin{equation*}
I_{G}=-\sum_{\alpha} \phi_{\alpha(-1)}^{2}+\sum_{\alpha} \phi_{\alpha 0}^{2}+\sum_{\alpha i} \theta_{\alpha i}^{2} \tag{3.23}
\end{equation*}
$$

Thus $\left\{\phi_{\alpha(-1)}, \phi_{\alpha 0}, \theta_{\alpha i}\right\}$ is a local orthonormal basis of $T^{*} \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$, which implies that $I_{G}$ is a semi-Riemannian metric on $\boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ of type $((n-m),(n-m)(m+1))$. From (3.22), (3.17), (3.18) and (3.19) we get

$$
\begin{align*}
d \phi_{\alpha(-1)}= & \sum_{\beta} \theta_{\alpha \beta} \wedge \phi_{\beta(-1)}+\theta_{00} \wedge \phi_{\alpha 0}+\sum_{k} \frac{1}{\sqrt{2}}\left(\theta_{k 0}-\theta_{k(-1)}\right) \wedge \theta_{\alpha k}  \tag{3.24}\\
d \phi_{\alpha 0}= & \theta_{00} \wedge \phi_{\alpha(-1)}+\sum_{\beta} \theta_{\alpha \beta} \wedge \phi_{\beta 0}-\sum_{k} \frac{1}{\sqrt{2}}\left(\theta_{k(-1)}+\theta_{k 0}\right) \wedge \theta_{\alpha k}  \tag{3.25}\\
d \theta_{\alpha k}= & \frac{1}{\sqrt{2}}\left(\theta_{k 0}-\theta_{k(-1)}\right) \wedge \phi_{\alpha(-1)}+\frac{1}{\sqrt{2}}\left(\theta_{k(-1)}+\theta_{k 0}\right) \wedge \phi_{\alpha 0}  \tag{3.26}\\
& +\sum_{j \beta}\left(-\theta_{j k} \delta_{\alpha \beta}+\theta_{\alpha \beta} \delta_{j k}\right) \theta_{\beta j}
\end{align*}
$$

By (3.5) we obtain the following connection forms of $I_{G}$ with respect to the orthonormal basis $\left\{\phi_{\alpha(-1)}, \phi_{\alpha 0}, \theta_{\alpha i}\right\}:$

$$
\begin{align*}
\Omega_{\alpha(-1) \beta(-1)} & =-\theta_{\alpha \beta}, \quad \Omega_{\alpha(-1) \beta 0}=\theta_{00} \delta_{\alpha \beta}, \quad \Omega_{\alpha(-1) \beta k}=\frac{1}{\sqrt{2}}\left(\theta_{k 0}-\theta_{k(-1)}\right) \delta_{\alpha \beta},  \tag{3.27}\\
\Omega_{\alpha 0 \beta(-1)} & =-\theta_{00} \delta_{\alpha \beta}, \quad \Omega_{\alpha 0 \beta 0}=\theta_{\alpha \beta}, \quad \Omega_{\alpha 0 \beta k}=-\frac{1}{\sqrt{2}}\left(\theta_{k(-1)}+\theta_{k 0}\right) \delta_{\alpha \beta},  \tag{3.28}\\
\Omega_{\alpha k \beta(-1)} & =\frac{1}{\sqrt{2}}\left(\theta_{k(-1)}-\theta_{k 0}\right) \delta_{\alpha \beta}, \quad \Omega_{\alpha k \beta 0}=\frac{1}{\sqrt{2}}\left(\theta_{k(-1)}+\theta_{k 0}\right) \delta_{\alpha \beta},  \tag{3.29}\\
\Omega_{\alpha k \beta j} & =-\theta_{j k} \delta_{\alpha \beta}+\theta_{\alpha \beta} \delta_{j k} .
\end{align*}
$$

Now, let $f: \boldsymbol{M} \rightarrow \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ be the conformal Gauss map of a submanifold $x: \boldsymbol{M} \rightarrow$ $\boldsymbol{S}^{n}$. Let $\left\{Y, N, E_{1}(Y), \ldots, E_{m}(Y), E_{m+1}, \ldots, E_{n}\right\}$ be the Möbius moving frame in $\boldsymbol{R}_{1}^{n+2}$ along $\boldsymbol{M}$. Then we can find a local section $T$ of $\pi: \tilde{O}(n+1,1) \rightarrow \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ given by (3.14) such that

$$
\begin{equation*}
\left(Y, N, E_{1}(Y), \ldots, E_{m}(Y), E_{m+1}, \ldots, E_{n}\right)=T \circ f=\left(f^{*} \xi_{-1}, \ldots, f^{*} \xi_{n}\right) \tag{3.30}
\end{equation*}
$$

It follows from (2.10), (2.11), (2.12) and (3.16) that

$$
\begin{gather*}
f^{*} \theta_{00}=0, \quad f^{*} \theta_{k(-1)}=-\sum_{j} A_{k j} \omega_{j}, \quad f^{*} \theta_{k 0}=-\omega_{k},  \tag{3.31}\\
f^{*} \theta_{i j}=\omega_{i j}:=\sum_{k} \Gamma_{i k}^{j} \omega_{k}, \quad f^{*} \theta_{\alpha \beta}=\omega_{\alpha \beta}:=\sum_{i} \Gamma_{\alpha i}^{\beta} \omega_{i},  \tag{3.32}\\
f^{*} \theta_{\alpha(-1)}=-\sum_{i} C_{i}^{\alpha} \omega_{i}, \quad f^{*} \theta_{\alpha 0}=0, \quad f^{*} \theta_{\alpha k}=-\sum_{j} B_{k j}^{\alpha} \omega_{j} . \tag{3.33}
\end{gather*}
$$

If we define $\left\{f_{\alpha(-1) i}, f_{\alpha 0 i}, f_{\alpha k i}\right\}$ by
(3.34) $\quad f^{*} \phi_{\alpha(-1)}=\sum_{i} f_{\alpha(-1) i} \omega_{i}, \quad f^{*} \phi_{\alpha 0}=\sum_{i} f_{\alpha 0 i} \omega_{i}, \quad f^{*} \theta_{\alpha k}=\sum_{i} f_{\alpha k i} \omega_{i}$.

Then by (3.22) and (3.33) we have

$$
\begin{equation*}
f_{\alpha(-1) i}=-\frac{1}{\sqrt{2}} C_{i}^{\alpha}, \quad f_{\alpha 0 i}=-\frac{1}{\sqrt{2}} C_{i}^{\alpha}, \quad f_{\alpha k i}=-B_{k i}^{\alpha} \tag{3.35}
\end{equation*}
$$

By definition (cf. (3.7) and (3.8)) the second fundamental form $\left\{f_{\alpha(-1) i, j}, f_{\alpha 0 i, j}, f_{\alpha k i, j}\right\}$ are defined by the following formulas

$$
\begin{align*}
d f_{\alpha(-1) i} & +\sum_{j} f_{\alpha(-1) j} \omega_{j i}-\sum_{\beta} f_{\beta(-1) i} f^{*} \Omega_{\beta(-1) \alpha(-1)}+\sum_{\beta} f_{\beta 0 i} f^{*} \Omega_{\beta 0 \alpha(-1)}  \tag{3.36}\\
& +\sum_{\beta k} f_{\beta k i} f^{*} \Omega_{\beta k \alpha(-1)}=\sum_{j} f_{\alpha(-1) i, j} \omega_{j}, \\
d f_{\alpha 0 i} & +\sum_{j} f_{\alpha 0 j} \omega_{j i}-\sum_{\beta} f_{\beta(-1) i} f^{*} \Omega_{\beta(-1) \alpha 0}+\sum_{\beta} f_{\beta 0 i} f^{*} \Omega_{\beta 0 \alpha 0}  \tag{3.37}\\
& +\sum_{\beta k} f_{\beta k i} f^{*} \Omega_{\beta k \alpha 0}=\sum_{j} f_{\alpha 0 i, j} \omega_{j}, \\
d f_{\alpha k i} & +\sum_{j} f_{\alpha k j} \omega_{j i}-\sum_{\beta} f_{\beta(-1) i} f^{*} \Omega_{\beta(-1) \alpha k}+\sum_{\beta} f_{\beta 0 i} f^{*} \Omega_{\beta 0 \alpha k}  \tag{3.38}\\
& +\sum_{\beta j} f_{\beta j i} f^{*} \Omega_{\beta j \alpha k}=\sum_{j} f_{\alpha k i, j} \omega_{j} .
\end{align*}
$$

It follows from (3.27) through (3.29) and (3.31) through (3.35) that

$$
\begin{align*}
f_{\alpha(-1) i, j} & =-\frac{1}{\sqrt{2}}\left(C_{i, j}^{\alpha}-\sum_{k} B_{i k}^{\alpha} A_{k j}+B_{i j}^{\alpha}\right),  \tag{3.39}\\
f_{\alpha 0 i, j} & =-\frac{1}{\sqrt{2}}\left(C_{i, j}^{\alpha}-\sum_{k} B_{i k}^{\alpha} A_{k j}-B_{i j}^{\alpha}\right),  \tag{3.40}\\
f_{\alpha k i, j} & =-\left(B_{k i, j}^{\alpha}+C_{i}^{\alpha} \delta_{k j}\right) . \tag{3.41}
\end{align*}
$$

Thus we know from (2.19) and (2.20) that the conformal Gauss map $f: \boldsymbol{M} \rightarrow \boldsymbol{G}_{n-m}^{+}\left(\boldsymbol{R}_{1}^{n+2}\right)$ is harmonic if and only if

$$
\begin{equation*}
\sum_{i} C_{i, i}^{\alpha}-\sum_{i, j} B_{i j}^{\alpha} A_{i j}=0, \quad(m-2) C_{k}^{\alpha}=0, \quad 1 \leq k \leq m, \quad 1 \leq \alpha \leq n \tag{3.42}
\end{equation*}
$$

In the case $m=2$, the first equation of (3.42) is exactly the Euler-Lagrange equation for the Willmore functional (which is the Möbius volume functional, cf. [W]). The surfaces in $\boldsymbol{S}^{n}$ satisfying this equation are known as Willmore surfaces in $S^{n}$. The conformal Gauss map of a surface in $\boldsymbol{S}^{n}$ has been studied by Bryant ([BR]) for $n=3$ and Rigoli ([R]) for $n>3$ by using complex coordinate on the surface. It follows immediately from (3.42) that

THEOREM 3.2 ([BR], [R]). A surface $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ is Willmore if and only if its conformal Gauss map is harmonic.

In the case $m>2$, we know that the conformal Gauss map of $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ is harmonic if and only if it satisfies

$$
\begin{equation*}
C_{k}^{\alpha} \equiv 0, \quad \sum_{i, j} B_{i j}^{\alpha} A_{i j} \equiv 0, \quad 1 \leq k \leq m, \quad m+1 \leq \alpha \leq n . \tag{3.43}
\end{equation*}
$$

Since for any Möbius isotropic submanifold we have $C_{k}^{\alpha} \equiv 0$ and $A_{k i} \equiv \lambda \delta_{k i}$ for some $\lambda$, which implies (3.42). Thus we complete the proof of Theorem 3.1.
4. Conformal invariants for submanifolds in $\boldsymbol{R}^{n}$ and $\boldsymbol{H}^{n}$. Let $\sigma: \boldsymbol{R}^{n} \rightarrow \boldsymbol{S}^{n}$ and $\tau: \boldsymbol{H}^{n} \rightarrow \boldsymbol{S}_{+}^{n}$ be the conformal maps definded by (1.3) and (1.4). Using $\sigma$ and $\tau$, we can regard submanifolds in $\boldsymbol{R}^{n}$ and $\boldsymbol{H}^{n}$ as submanifolds in $\boldsymbol{S}^{n}$. In this section we give the conformal invariants for submanifolds in $\boldsymbol{R}^{n}$ and $\boldsymbol{H}^{n}$, and relate them to the Möbius invariants for submanifolds in $\boldsymbol{S}^{n}$. By using these relations, we show that any minimal submanifolds with constant scalar curvature in $\boldsymbol{R}^{n}, \boldsymbol{H}^{n}$ and $\boldsymbol{S}^{n}$ are Möbius isotropic.

Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be a minimal submanifold with constant scalar curvature in $\boldsymbol{S}^{n}$. Then by the Gauss equation we know that $\rho^{2}=m /(m-1) \cdot\left(\|I I\|^{2}-m\|H\|^{2}\right)$ is a constant. Thus from (1.1) and (1.2) we get

$$
C_{i}^{\alpha}=0, \quad A_{i j}=\frac{1}{2} \rho^{-2} \delta_{i j}
$$

By definition $x$ is a Möbius isotropic submanifold in $S^{n}$.
Let $u: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$ be a submanifold without umbilics in $\boldsymbol{R}^{n}$. Let $\left\{\tilde{e}_{i}\right\}$ be a local orthonormal basis for the first fundamental form $\tilde{I}=d u \cdot d u$ with the dual basis $\left\{\tilde{\theta}_{i}\right\}$. Let $\tilde{I I}=\sum_{i j \alpha} \tilde{h}_{i j}^{\alpha} \tilde{\theta}_{i} \tilde{\theta}_{j} \tilde{e}_{\alpha}$ be the second fundamental form of $u$ and $\tilde{H}=\sum_{\alpha} \tilde{H}^{\alpha} \tilde{e}_{\alpha}$ be the mean curvature vector of $u$, where $\left\{\tilde{e}_{\alpha}\right\}$ is a local orthonormal basis for the normal bundle of $u$. We
define

$$
\begin{align*}
\tilde{g}= & \tilde{\rho}^{2} d u \cdot d u, \quad \tilde{\rho}^{2}=m /(m-1) \cdot\left(\|\tilde{I I}\|^{2}-m\|\tilde{H}\|^{2}\right)  \tag{4.1}\\
\tilde{B}_{i j}^{\alpha}= & \tilde{\rho}^{-1}\left(\tilde{h}_{i j}^{\alpha}-\tilde{H}^{\alpha} \delta_{i j}\right)  \tag{4.2}\\
\tilde{C}_{i}^{\alpha}= & -\tilde{\rho}^{-2}\left(\tilde{H}^{\alpha}, i+\sum_{j}\left(\tilde{h}_{i j}^{\alpha}-\tilde{H}^{\alpha} \delta_{i j}\right) \tilde{e}_{j}(\log \tilde{\rho})\right)  \tag{4.3}\\
\tilde{A}_{i j}= & -\tilde{\rho}^{-2}\left(\operatorname{Hess}_{i j}(\log \tilde{\rho})-\tilde{e}_{i}(\log \tilde{\rho}) \tilde{e}_{j}(\log \tilde{\rho})-\sum_{\alpha} \tilde{H}^{\alpha} \tilde{h}_{i j}^{\alpha}\right)  \tag{4.4}\\
& -\frac{1}{2} \tilde{\rho}^{-2}\left(\|\nabla \log \tilde{\rho}\|^{2}+\sum_{\alpha}\left(\tilde{H}^{\alpha}\right)^{2}\right) \delta_{i j}
\end{align*}
$$

We call the globally defined tensors $\tilde{g}, \tilde{\Phi}=\sum_{i \alpha} \tilde{C}_{i}^{\alpha} \tilde{\theta}_{i} \tilde{e}_{\alpha}, \tilde{\mathbf{A}}:=\tilde{\rho}^{2} \sum_{i j} \tilde{A}_{i j} \tilde{\theta}_{i} \tilde{\theta}_{j}$ and $\tilde{\mathbf{B}}=\tilde{\rho} \sum_{i j \alpha} \tilde{B}_{i j}^{\alpha} \tilde{\theta}_{i} \tilde{\theta}_{j} \tilde{e}_{\alpha}$ the Möbius metric, the Möbius form, the Blaschke tensor and the Möbius second fundamental form of $u: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$, respectively.

Now, let $\sigma: \boldsymbol{R}^{n} \rightarrow \boldsymbol{S}^{n}$ be the conformal map given by (1.3). We define $x:=\sigma \circ u: \boldsymbol{M} \rightarrow$ $\boldsymbol{S}^{n}$. Then $x$ is a submanifold in $\boldsymbol{S}^{n}$ without umbilics. We denote by $\Phi$ and $\mathbf{A}$ the Möbius form and the Blaschke tensor of $x$ defined by (1.1) and (1.2), and denote by $g$ and $\mathbf{B}$ the Möbius metric and the Möbius second fundamental form defined by (2.3) and (2.13) for $x=\sigma \circ u$, respectively. Our goal in this section is to prove the following

Theorem 4.1. $g=\tilde{g}, \quad \mathbf{B}=d \sigma(\tilde{\mathbf{B}}), \Phi=d \sigma(\tilde{\Phi})$ and $\mathbf{A}=\tilde{\mathbf{A}}$. In particular, $\{\tilde{g}, \tilde{\mathbf{B}}, \tilde{\Phi}, \tilde{\mathbf{A}}\}$ are conformal invariants for submanifolds in $\boldsymbol{R}^{n}$.

Let $\sigma: \boldsymbol{R}^{n} \rightarrow \boldsymbol{S}^{n}$ be the conformal map given by

$$
\begin{equation*}
x=\sigma(u)=\left(\frac{1-|u|^{2}}{1+|u|^{2}}, \frac{2 u}{1+|u|^{2}}\right), \quad u \in \boldsymbol{R}^{n} \tag{4.5}
\end{equation*}
$$

Then for any vector $V \in T_{u} \boldsymbol{R}^{n}$ we have

$$
\begin{equation*}
d \sigma(V)=\frac{2}{1+|u|^{2}}\{-(u \cdot V) x+(-u \cdot V, V)\} \tag{4.6}
\end{equation*}
$$

Thus we get

$$
\begin{equation*}
d x \cdot d x=\frac{4}{\left(1+|u|^{2}\right)^{2}} d u \cdot d u \tag{4.7}
\end{equation*}
$$

Now, let $u: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$ be a submanifold in $\boldsymbol{R}^{n}$ and $x=\sigma \circ u: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$. We denote by $\left\{\tilde{e}_{i}\right\}$ and $\left\{\tilde{e}_{\alpha}\right\}$ local orthonormal basis for $d u \cdot d u$ and the normal bundle of $u$ respectively, and define

$$
\begin{equation*}
e_{i}=\frac{1+|u|^{2}}{2} \tilde{e}_{i}, \quad e_{\alpha}=\frac{1+|u|^{2}}{2} d \sigma\left(\tilde{e}_{\alpha}\right) \tag{4.8}
\end{equation*}
$$

Then $\left\{e_{i}\right\}$ is a local orthonormal basis for $d x \cdot d x$ with dual basis $\left\{\theta_{i}\right\}$ and $\left\{e_{\alpha}\right\}$ is a local orthonormal basis for the normal bundle of $x$ in $\boldsymbol{S}^{n}$. It follows from (4.6) that

$$
\begin{align*}
e_{i}(x) & =\frac{1+|u|^{2}}{2} d \sigma\left(\tilde{e}_{i}(u)\right)=-\left(u \cdot \tilde{e}_{i}(u)\right) x+\left(-u \cdot \tilde{e}_{i}(u), \tilde{e}_{i}(u)\right)  \tag{4.9}\\
e_{\alpha} & =\frac{1+|u|^{2}}{2} d \sigma\left(\tilde{e}_{\alpha}\right)=-\frac{2 u \cdot \tilde{e}_{\alpha}}{1+|u|^{2}}(1, u)+\left(0, \tilde{e}_{\alpha}\right)  \tag{4.10}\\
& =-\left(u \cdot \tilde{e}_{\alpha}\right) x+\left(-u \cdot \tilde{e}_{\alpha}, \tilde{e}_{\alpha}\right)
\end{align*}
$$

By (4.9) we get

$$
\begin{equation*}
e_{i} e_{j}(x)=\frac{1+|u|^{2}}{2}\left(\left(-\delta_{i j}, 0\right)+\left(-u \cdot \tilde{e}_{j} \tilde{e}_{i}(u), \tilde{e}_{j} \tilde{e}_{i}(u)\right)\right) \bmod \left(x, e_{i}(x)\right) \tag{4.11}
\end{equation*}
$$

Thus (4.10) and (4.11) yield

$$
\begin{equation*}
h_{i j}^{\alpha}=\frac{1+|u|^{2}}{2} \tilde{h}_{i j}^{\alpha}+\tilde{e}_{\alpha} \cdot u \delta_{i j}, \quad H^{\alpha}=\frac{1+|u|^{2}}{2} \tilde{H}^{\alpha}+\tilde{e}_{\alpha} \cdot u \tag{4.12}
\end{equation*}
$$

It follows from (4.12) and (4.7) that

$$
\begin{align*}
\rho^{2} & =\frac{\left(1+|u|^{2}\right)^{2}}{4} \tilde{\rho}^{2}  \tag{4.13}\\
g & =\rho^{2} d x \cdot d x=\tilde{\rho}^{2} d u \cdot d u=\tilde{g} \tag{4.14}
\end{align*}
$$

It is clear that $\tilde{g}$ is a conformal invariant. By (4.12) and (4.13) we get

$$
\begin{equation*}
B_{i j}^{\alpha}=\rho^{-1}\left(h_{i j}^{\alpha}-H^{\alpha} \delta_{i j}\right)=\tilde{\rho}^{-1}\left(\tilde{h}_{i j}^{\alpha}-\tilde{H}^{\alpha} \delta_{i j}\right)=\tilde{B}_{i j}^{\alpha} \tag{4.15}
\end{equation*}
$$

By (4.10) we get

$$
d e_{\alpha}=\left(-u \cdot d \tilde{e}_{\alpha}, d \tilde{e}_{\alpha}\right) \quad \bmod (x, d x)
$$

which implies that

$$
\begin{equation*}
\theta_{\alpha \beta}=d e_{\alpha} \cdot e_{\beta}=d \tilde{e}_{\alpha} \cdot \tilde{e}_{\beta}=\tilde{\theta}_{\alpha \beta} \tag{4.16}
\end{equation*}
$$

Let $\left\{H^{\alpha}{ }_{i}\right\}$ and $\left\{\tilde{H}^{\alpha}{ }_{, i}\right\}$ be the covariant derivatives of the mean curvature vector in the normal bundle of $x=\sigma \circ u: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ and $u: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$, respectively. By definition we have

$$
d H^{\alpha}+\sum_{\beta} H^{\beta} \theta_{\beta \alpha}=\sum_{i} H^{\alpha}{ }_{, i} \theta_{i}, \quad d \tilde{H}^{\alpha}+\sum_{\beta} \tilde{H}^{\beta} \tilde{\theta}_{\beta \alpha}=\sum_{i} \tilde{H}^{\alpha}{ }_{, i} \tilde{\theta}_{i} .
$$

Since $\tilde{\theta}_{i}=\left(\left(1+|u|^{2}\right) / 2\right) \theta_{i}$, from (4.12) and (4.16) we get

$$
\begin{equation*}
H^{\alpha}{ }_{, i}=\left(\frac{1+|u|^{2}}{2}\right)^{2} \tilde{H}^{\alpha}{ }_{, i}-\frac{1+|u|^{2}}{2} \sum_{j}\left(\tilde{h}_{i j}^{\alpha}-\tilde{H}^{\alpha} \delta_{i j}\right)\left(\tilde{e}_{j}(u) \cdot u\right) . \tag{4.17}
\end{equation*}
$$

By (4.13) we get

$$
\begin{equation*}
e_{j}(\log \rho)=\frac{1+|u|^{2}}{2} \tilde{e}_{j}(\log \tilde{\rho})+\tilde{e}_{j}(u) \cdot u \tag{4.18}
\end{equation*}
$$

We define $\left\{C_{i}^{\alpha}\right\}$ and $\left\{\tilde{C}_{i}^{\alpha}\right\}$ by (1.1) and (4.3), respectively. It follows from (4.17) and (4.18) that

$$
\begin{equation*}
C_{i}^{\alpha}=\tilde{C}_{i}^{\alpha} \tag{4.19}
\end{equation*}
$$

Let $\left\{\theta_{i j}\right\}$ and $\left\{\tilde{\theta}_{i j}\right\}$ be the Levi-Civita connections of $d x \cdot d x$ and $d u \cdot d u$ with respect to the basis $\left\{e_{i}\right\}$ and $\left\{\tilde{e}_{i}\right\}$, respectively. Then by (4.7) we have

$$
\begin{equation*}
\theta_{i j}=\tilde{\theta}_{i j}+\frac{2 u \cdot \tilde{e}_{j}(u)}{1+|u|^{2}} \tilde{\theta}_{i}-\frac{2 u \cdot \tilde{e}_{i}(u)}{1+|u|^{2}} \tilde{\theta}_{j} \tag{4.20}
\end{equation*}
$$

We define the $\operatorname{Hess}_{i j}(\log \rho)$ and $\operatorname{Hess}_{i j}(\log \tilde{\rho})$ by

$$
\begin{aligned}
d\left(e_{i}(\log \rho)\right)+\sum_{j} e_{j}(\log \rho) \theta_{j i} & =\sum_{j} \operatorname{Hess}_{i j}(\log \rho) \theta_{j} \\
d\left(\tilde{e}_{i}(\log \tilde{\rho})\right)+\sum_{j} \tilde{e}_{j}(\log \tilde{\rho}) \tilde{\theta}_{j i} & =\sum_{j} \operatorname{Hess}_{i j}(\log \tilde{\rho}) \tilde{\theta}_{j}
\end{aligned}
$$

Using (4.18) and (4.20), we get

$$
\begin{align*}
& \operatorname{Hess}_{i j}(\log \rho)=\left(\frac{1+|u|^{2}}{2}\right)^{2} \operatorname{Hess}_{i j}(\log \tilde{\rho})+\left(u \cdot \tilde{e}_{i}(u)\right)\left(u \cdot \tilde{e}_{j}(u)\right) \\
& \quad+\frac{1+|u|^{2}}{2}\left(\sum_{\alpha} \tilde{h}_{i j}^{\alpha}\left(\tilde{e}_{\alpha} \cdot u\right)+\left(u \cdot \tilde{e}_{j}(u)\right) \tilde{e}_{i}(\log \tilde{\rho})+\left(u \cdot \tilde{e}_{i}(u)\right) \tilde{e}_{j}(\log \tilde{\rho})\right)  \tag{4.21}\\
& \quad+\left(\frac{1+|u|^{2}}{2}-\frac{1+|u|^{2}}{2} \sum_{k}\left(u \cdot \tilde{e}_{k}(u)\right) \tilde{e}_{k}(\log \tilde{\rho})-\sum_{k}\left(u \cdot \tilde{e}_{k}(u)\right)^{2}\right) \delta_{i j}
\end{align*}
$$

Using (4.12) and (4.18), we also get

$$
\begin{aligned}
& e_{i}(\log \rho) e_{j}(\log \rho)+\sum_{\alpha} H^{\alpha} h_{i j}^{\alpha} \\
&=\left(\frac{1+|u|^{2}}{2}\right)^{2}\left(\tilde{e}_{i}(\log \tilde{\rho}) \tilde{e}_{j}(\log \tilde{\rho})+\sum_{\alpha} \tilde{H}^{\alpha} \tilde{h}_{i j}^{\alpha}\right) \\
&+\frac{1+|u|^{2}}{2}\left(\tilde{e}_{i}(\log \tilde{\rho})\left(\tilde{e}_{j}(u) \cdot u\right)+\tilde{e}_{j}(\log \tilde{\rho})\left(\tilde{e}_{i}(u) \cdot u\right)\right) \\
&+\left(\tilde{e}_{i}(u) \cdot u\right)\left(\tilde{e}_{j}(u) \cdot u\right)+\frac{1+|u|^{2}}{2} \tilde{h}_{i j}^{\alpha}\left(\tilde{e}_{\alpha} \cdot u\right) \\
&+\left(\sum_{\alpha}\left(\tilde{e}_{\alpha} \cdot u\right)^{2}+\frac{1+|u|^{2}}{2} \sum_{\alpha}\left(\tilde{e}_{\alpha} \cdot u\right) \tilde{H}^{\alpha}\right) \delta_{i j}
\end{aligned}
$$

$$
\begin{align*}
& \frac{1}{2}\left(\|\nabla \log \rho\|^{2}-1+\sum_{\alpha}\left(H^{\alpha}\right)^{2}\right)=\frac{1}{2}\left(\frac{1+|u|^{2}}{2}\right)^{2}\left(\|\nabla \log \tilde{\rho}\|^{2}+\sum_{\alpha}\left(\tilde{H}^{\alpha}\right)^{2}\right) \\
& \quad+\frac{1+|u|^{2}}{2}\left(\sum_{k} \tilde{e}_{k}(\log \tilde{\rho})\left(\tilde{e}_{k}(u) \cdot u\right)+\sum_{\alpha} \tilde{H}^{\alpha}\left(\tilde{e}_{\alpha} \cdot u\right)\right)  \tag{4.23}\\
& \quad+\frac{1}{2} \sum_{k}\left(u \cdot \tilde{e}_{k}(u)\right)^{2}+\frac{1}{2} \sum_{\alpha}\left(u \cdot \tilde{e}_{\alpha}(u)\right)^{2}-\frac{1}{2}
\end{align*}
$$

Let $\left\{A_{i j}\right\}$ and $\left\{\tilde{A}_{i j}\right\}$ be the tensor defined by (1.2) and (4.4), respectively. Then we get from (4.13), (4.21), (4.22) and (4.23) that

$$
\begin{equation*}
A_{i j}=\tilde{A}_{i j} \tag{4.24}
\end{equation*}
$$

Now, we come to the proof of Theorem 4.1. It follows from (4.14) that $g=\tilde{g}$. We take $\omega_{i}=\rho \theta_{i}=\tilde{\rho} \tilde{\theta}_{i}$. Then by (4.24) we get $\mathbf{A}=\tilde{\mathbf{A}}$. From (4.8) and (4.13) we get $d \sigma\left(\tilde{\rho}^{-1} \tilde{\boldsymbol{e}}_{\alpha}\right)=$ $\rho^{-1} e_{\alpha}$. Thus we get from (4.15) and (4.19) that $d \sigma(\tilde{\mathbf{B}})=\mathbf{B}$ and $d \sigma(\tilde{\Phi})=\Phi$. This completes the proof of Theorem 4.1.

It follows from (4.3) and (4.4) that
THEOREM 4.2. The images of $\sigma$ of minimal submanifolds with constant scalar curvature in $\boldsymbol{R}^{n}$ are Möbius isotropic submanifolds in $\boldsymbol{S}^{n}$.

Let $\boldsymbol{R}_{1}^{n+1}$ be the Lorentzian space with inner product

$$
\langle y, w\rangle=-y_{0} w_{0}+y_{1} w_{1}+\cdots+y_{n} w_{n}, \quad y=\left(y_{0}, \ldots, y_{n}\right), w=\left(w_{0}, \ldots, w_{n}\right)
$$

Let $\boldsymbol{H}^{n}=\left\{y \in R_{1}^{n+1} \mid\langle y, y\rangle=-1, y_{0}>0\right\}$ be the $n$-dimensional hyperbolic space. We define now the conformal invariants for the submanifolds in $\boldsymbol{H}^{n}$. Let $y: \boldsymbol{M} \rightarrow \boldsymbol{H}^{n}$ be a submanifold in $\boldsymbol{H}^{n}$ without umbilics. Let $\left\{\hat{e}_{i}\right\}$ be a local orthonormal basis for $\langle d y, d y\rangle$ with dual basis $\left\{\hat{\theta}_{i}\right\}$. Let $\widehat{I I}=\sum_{\alpha i j} \hat{h}_{i j}^{\alpha} \hat{\theta}_{i} \hat{\theta}_{j} \hat{e}_{\alpha}$ be the second fundamental form of $y$ and $\hat{H}=$ $\sum_{\alpha} \hat{H}^{\alpha} \hat{e}_{\alpha}$ the mean curvature vector of $y$, where $\left\{\hat{e}_{\alpha}\right\}$ is a local orthonormal basis for the normal bundle of $y$. We define

$$
\begin{align*}
\hat{g}= & \hat{\rho}^{2}\langle d y, d y\rangle, \quad \hat{\rho}^{2}=m /(m-1) \cdot\left(\|\widehat{I} I\|^{2}-m\|\hat{H}\|^{2}\right)  \tag{4.25}\\
\hat{B}_{i j}^{\alpha}= & \hat{\rho}^{-1}\left(\hat{h}_{i j}^{\alpha}-\hat{H}^{\alpha} \delta_{i j}\right)  \tag{4.26}\\
\hat{C}_{i}^{\alpha}= & -\hat{\rho}^{-2}\left(\hat{H}^{\alpha},_{i}+\sum_{j}\left(\hat{h}_{i j}^{\alpha}-\hat{H}^{\alpha} \delta_{i j}\right) \hat{e}_{j}(\log \hat{\rho})\right)  \tag{4.27}\\
\hat{A}_{i j}= & -\hat{\rho}^{-2}\left(\operatorname{Hess}_{i j}(\log \hat{\rho})-\hat{e}_{i}(\log \hat{\rho}) \hat{e}_{j}(\log \hat{\rho})-\sum_{\alpha} \hat{H}^{\alpha} \hat{h}_{i j}^{\alpha}\right)  \tag{4.28}\\
& -\frac{1}{2} \hat{\rho}^{-2}\left(\|\nabla \log \hat{\rho}\|^{2}+1+\sum_{\alpha}\left(\hat{H}^{\alpha}\right)^{2}\right) \delta_{i j}
\end{align*}
$$

We call $\hat{g}$ the Möbius metric of $y, \hat{\mathbf{B}}=\hat{\rho} \sum_{i j \alpha} \hat{B}_{i j}^{\alpha} \hat{\theta}_{i} \hat{\theta}_{j} \hat{e}_{\alpha}$ the Möbius second fundamental form of $y, \hat{\Phi}=\sum_{i \alpha} \hat{C}_{i}^{\alpha} \hat{\theta}_{i} \hat{e}_{\alpha}$ the Möbius form of $y$ and $\hat{\mathbf{A}}=\sum_{i j} \hat{\rho}^{2} \hat{A}_{i j} \hat{\theta}_{i} \hat{\theta}_{j}$ the Blaschke tensor of $y$, respectively.

Set $D^{n}=\left\{\left.u \in \boldsymbol{R}^{n}| | u\right|^{2}<1\right\}$. Let $\mu: D^{n} \rightarrow \boldsymbol{H}^{n}$ be the conformal diffeomorphism given by

$$
\begin{equation*}
\mu(u)=\left(\frac{1+|u|^{2}}{1-|u|^{2}}, \frac{2 u}{1-|u|^{2}}\right) . \tag{4.29}
\end{equation*}
$$

Then $u=\mu^{-1} \circ y: \boldsymbol{M} \rightarrow D^{n}$ is a submanifold in $D^{n}$ without umbilics. We denote by $\{\tilde{g}, \tilde{\mathbf{B}}, \tilde{\Phi}, \tilde{\mathbf{A}}\}$ the basic Möbius invariants for $u=\mu^{-1} \circ y: \boldsymbol{M} \rightarrow D^{n} \subset \boldsymbol{R}^{n}$. Using the same method as in the proof of Theorem 4.1, we can prove that

THEOREM 4.3. $\hat{g}=\tilde{g}, \hat{\mathbf{B}}=d \mu(\tilde{\mathbf{B}}), \hat{\Phi}=d \mu(\tilde{\Phi})$ and $\hat{\mathbf{A}}=\tilde{\mathbf{A}}$. In particular, $\{\hat{g}, \hat{\mathbf{B}}, \hat{\Phi}, \hat{\mathbf{A}}\}$ are conformal invariants for submanifolds in $\boldsymbol{H}^{n}$.

Let $\tau: \boldsymbol{H}^{n} \rightarrow \boldsymbol{S}_{+}^{n}$ be the conformal diffeomorphism defined by (1.4). Then we have $\tau=\sigma \circ \mu^{-1}$. Thus from Theorem 4.1 and Theorem 4.3 we get

THEOREM 4.4. Let $y: \boldsymbol{M} \rightarrow \boldsymbol{H}^{n}$ be a submanifold in $\boldsymbol{H}^{n}$ without umbilics. Let $x=\tau \circ y: \boldsymbol{M} \rightarrow \boldsymbol{S}_{+}^{n}$. Then we have

$$
g=\hat{g}, \quad \mathbf{B}=d \tau(\hat{\mathbf{B}}), \quad \Phi=d \tau(\hat{\Phi}), \quad \mathbf{A}=\hat{\mathbf{A}} .
$$

In particular, $\{\hat{g}, \hat{\mathbf{B}}, \hat{\Phi}, \hat{\mathbf{A}}\}$ are conformal invariants for submanifolds in $\boldsymbol{H}^{n}$.
It follows immediately from (4.27) and (4.28) that
THEOREM 4.5. The images of $\tau$ of minimal submanifolds with constant scalar curvature in $\boldsymbol{H}^{n}$ are Möbius isotropic submanifolds in $\boldsymbol{S}^{n}$.
5. The classification of Möbius isotropic submanifolds in $S^{n}$. In this section we prove the classification theorem mentioned in Section 1.

Let $x: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be a Möbius isotropic submanifold in $\boldsymbol{S}^{n}$. By definition we have

$$
\begin{equation*}
A_{i j}=\lambda \delta_{i j}, \quad C_{i}^{\alpha} \equiv 0 \tag{5.1}
\end{equation*}
$$

It follows from (2.10) and Proposition 2.3 that

$$
\begin{equation*}
d N=\lambda d Y \tag{5.2}
\end{equation*}
$$

for some constant $\lambda$. Using (5.1) and the last equation in (2.19), we get

$$
\begin{equation*}
A_{i j}=\frac{1}{2 m^{2}}\left(1+m^{2} \kappa\right) \delta_{i j}, \quad \kappa=\text { constant } \tag{5.3}
\end{equation*}
$$

where $\kappa$ is the normalized scalar curvature of the Möbius metric. By (5.2) we can find a constant vector $\boldsymbol{c} \in \boldsymbol{R}_{1}^{n+2}$ such that

$$
\begin{equation*}
N=\frac{1}{2 m^{2}}\left(1+m^{2} \kappa\right) Y+\boldsymbol{c} \tag{5.4}
\end{equation*}
$$

It follows from (5.4) and (2.5) that

$$
\begin{equation*}
\langle\boldsymbol{c}, \boldsymbol{c}\rangle=-\frac{1}{m^{2}}\left(1+m^{2} \kappa\right), \quad\langle Y, \boldsymbol{c}\rangle=1 \tag{5.5}
\end{equation*}
$$

Then we consider the following three cases: (i) $\boldsymbol{c}$ is timelike; (ii) $\boldsymbol{c}$ is lightlike; (iii) $\boldsymbol{c}$ is spacelike.

First, we consider the case (i) that $\langle\boldsymbol{c}, \boldsymbol{c}\rangle=-r^{2}$ with $r=\sqrt{1+m^{2} \kappa} / m>0$. By (2.2) and $\langle Y, N\rangle=1$ we know that the first coordinate of $Y$ is positive and of $N$ is negative. Thus by (5.4) we know that the first coordinate of $\boldsymbol{c}$ is negative. So there exists a $T \in O^{+}(n+1,1)$ such that

$$
\begin{equation*}
(-r, 0)=c T=N T-\frac{r^{2}}{2} Y T . \tag{5.6}
\end{equation*}
$$

Let $\tilde{x}: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ be the submanifold which is Möbius equivalent to $x$ such that $\tilde{Y}=Y T$ (cf. Theorem 2.1). Then we have $\tilde{N}=N T$. Since

$$
\begin{equation*}
\boldsymbol{c} T=(-r, 0), \quad\langle\tilde{Y}, \boldsymbol{c} T\rangle=1, \quad \tilde{Y}=\tilde{\rho}(1, \tilde{x}) \tag{5.7}
\end{equation*}
$$

we get

$$
\begin{equation*}
\tilde{\rho}=r^{-1}=\text { constant } \tag{5.8}
\end{equation*}
$$

It follows from (5.6) and (2.4) that

$$
\begin{equation*}
(-r, 0)=\tilde{N}-\frac{r^{2}}{2} \tilde{Y}, \quad \tilde{N}=-\frac{1}{m} \tilde{\Delta} \tilde{Y}-\frac{1}{2} r^{2} \tilde{Y} \tag{5.9}
\end{equation*}
$$

Since $\tilde{\rho}=r^{-1}$, we know from $\tilde{g}=\tilde{\rho}^{2} d \tilde{x} \cdot d \tilde{x}$ that the Laplace operator $\Delta_{M}$ of $d \tilde{x} \cdot d \tilde{x}$ is given by $\Delta_{\boldsymbol{M}}=\tilde{\rho}^{2} \tilde{\Delta}$. Thus by (5.9) we get

$$
\begin{equation*}
\Delta_{\boldsymbol{M}} \tilde{x}+m \tilde{x}=0 . \tag{5.10}
\end{equation*}
$$

By Takahashi's theorem ([T]) we know that $\tilde{x}: \boldsymbol{M} \rightarrow \boldsymbol{S}^{n}$ is a minimal submanifold. The normalized scalar curvature $\tilde{\kappa}$ of $d \tilde{x} \cdot d \tilde{x}$ is a constant given by

$$
\begin{equation*}
\tilde{\kappa}=\tilde{\rho}^{2} \kappa=\frac{m^{2} \kappa}{1+m^{2} \kappa} . \tag{5.11}
\end{equation*}
$$

Next, we consider the case (ii) that $\langle\boldsymbol{c}, \boldsymbol{c}\rangle=0$. By making use of a Möbius transformation if necessary, we may assume that $\boldsymbol{c}=(-1,1,0)$. Thus by (5.4) and (2.4) we have

$$
\begin{equation*}
\boldsymbol{c}=(-1,1,0)=N=-\frac{1}{m} \Delta Y \tag{5.12}
\end{equation*}
$$

We write $x=\left(x_{0}, x_{1}\right)$. Then $Y=\left(\rho, \rho x_{0}, \rho x_{1}\right)$. By (5.5) and (5.12) we get $\langle Y, \boldsymbol{c}\rangle=$ $\rho\left(1+x_{0}\right)=1$, which implies that $x_{0} \neq-1$ and $x(\boldsymbol{M}) \subset \boldsymbol{S}^{n} \backslash\{(-1,0)\}$.

Now, let $\sigma^{-1}: \boldsymbol{S}^{n} \backslash\{(-1,0)\} \rightarrow \boldsymbol{R}^{n}$ be the stereographic projection from the point $(-1,0) \in \boldsymbol{S}^{n}$. We define $u=\sigma^{-1} \circ x: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$. Then by (1.3) we have

$$
\begin{equation*}
Y=\rho(1, x)=\left(\rho, \frac{\rho\left(1-|u|^{2}\right)}{1+|u|^{2}}, \frac{2 \rho u}{1+|u|^{2}}\right) . \tag{5.13}
\end{equation*}
$$

From $\langle Y, \boldsymbol{c}\rangle=1$ we get $\rho=\left(1+|u|^{2}\right) / 2$. Thus we get from (5.13) that

$$
Y=\left(\frac{1+|u|^{2}}{2}, \frac{1-|u|^{2}}{2}, u\right) .
$$

The Möbius metric of $x$ is given by

$$
\begin{equation*}
g=\langle d Y, d Y\rangle=d u \cdot d u \tag{5.14}
\end{equation*}
$$

which is exactly the first fundamental form of $u=\sigma^{-1} \circ x: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$. In particular, the Laplace operator $\Delta$ of $g$ coincides with the Laplace operator of $d u \cdot d u$. Comparing the last coordinate in (5.12), we get $\Delta u=0$. Thus $u=\sigma^{-1} \circ x: \boldsymbol{M} \rightarrow \boldsymbol{R}^{n}$ is a minimal submanidold. By (5.14) and (5.4) we know that the normalized scalar curvature of $u$ is exactly the scalar curvature $\kappa$ of $g$. Since $\langle\boldsymbol{c}, \boldsymbol{c}\rangle=-\left(1+m^{2} \kappa\right) / m^{2}=0$, we get $\kappa=-1 / m^{2}$.

Finally, we consider the case that $\langle\boldsymbol{c}, \boldsymbol{c}\rangle=r^{2}$ with $r=\sqrt{-\left(1+m^{2} \kappa\right)} / m>0$. By making use of a Möbius transformation if necessary, we may assume that $\boldsymbol{c}=(0, r, 0)$. We write $x=\left(x_{0}, x_{1}\right)$. Then $Y=\left(\rho, \rho x_{0}, \rho x_{1}\right)$. It follows from (5.5) that $\langle Y, \boldsymbol{c}\rangle=\rho r x_{0}=1$, which implies that $x_{0}>0$ and $x(\boldsymbol{M}) \subset S_{+}^{n}$.

Now, let $\tau: \boldsymbol{H}^{n} \rightarrow \boldsymbol{S}_{+}^{n}$ be the conformal diffeomorphsim defined by (1.4) and $y=$ $\tau^{-1} \circ x: \boldsymbol{M} \rightarrow \boldsymbol{H}^{n} \subset \boldsymbol{R}_{1}^{n+1}$. Since $\langle Y, \boldsymbol{c}\rangle=\rho r x_{0}=1$, we get $x_{0}=1 / r \rho$. By (1.4) we get $y_{0}=1 / x_{0}=r \rho$ and

$$
\begin{equation*}
Y=\left(\rho, \rho x_{0}, \rho x_{1}\right)=\left(\frac{y_{0}}{r}, \frac{1}{r}, \frac{y_{1}}{r}\right) . \tag{5.15}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
g=\langle d Y, d Y\rangle=r^{-2}\langle d y, d y\rangle \tag{5.16}
\end{equation*}
$$

The Laplace operator $\Delta_{\boldsymbol{M}}$ of $\langle d y, d y\rangle$ is given by $\Delta_{\boldsymbol{M}}=r^{-2} \Delta$. By (5.4) and (2.4) we have

$$
\begin{equation*}
-\frac{1}{m} \Delta Y+\frac{r^{2}}{2} Y=-\frac{r^{2}}{2} Y+(0, r, 0) \tag{5.17}
\end{equation*}
$$

which is equivalent to the equation

$$
\begin{equation*}
\Delta_{M} y-m y=0 . \tag{5.18}
\end{equation*}
$$

Thus $y=\tau^{-1} \circ x: \boldsymbol{M} \rightarrow \boldsymbol{H}^{n}$ is a minimal submanifold. Since the Möbius metric $g$ has constant scalar curvature, we know from (5.16) that $y: \boldsymbol{M} \rightarrow \boldsymbol{H}^{n}$ has constant scalar curvature.

Thus we complete the proof of the classification theorem.

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