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# **MPSoC Programming using the MAPS Compiler**

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ASP-DAC  
Taipei, Jan. 2010

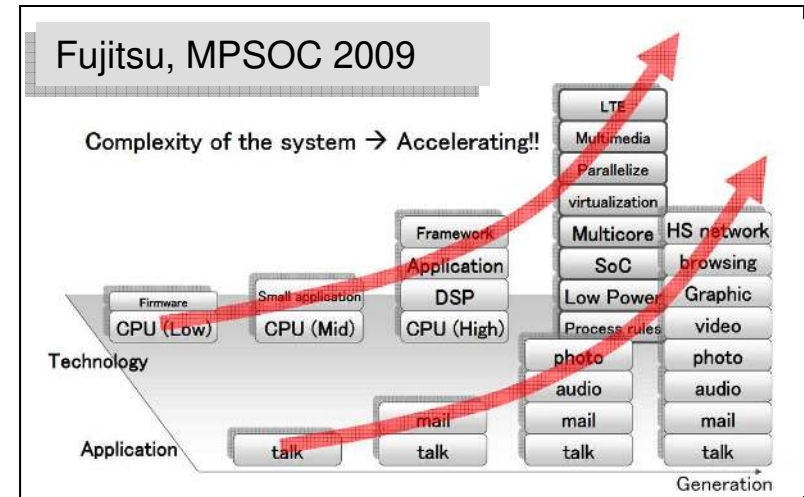
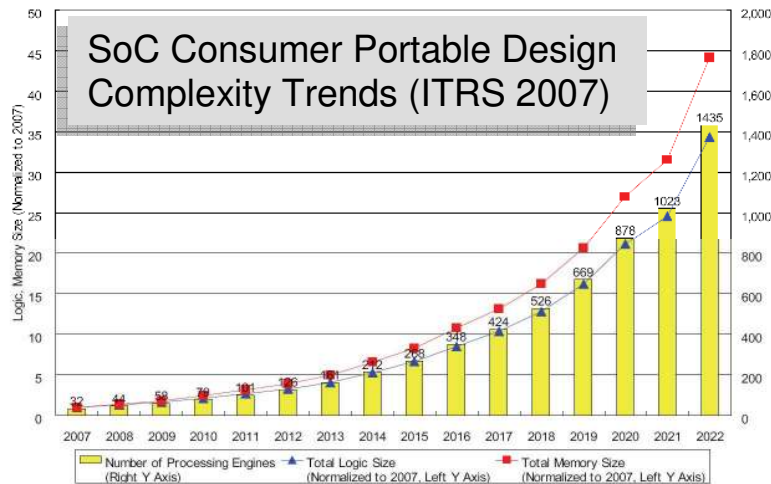


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Institute for Integrated Signal Processing Systems

# Motivation: MPSoCs and the Productivity Gap

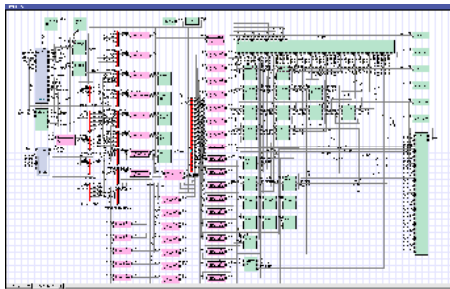
- **Multi-Processor Systems on Chip are a reality**
  - Increased HW and SW complexity



- **The productivity Gap: Requirements double every 10 months, HW/SW productivity every 2 years (Ecker, Mueller, Doemer, 2008)**

→ **Need better support for SW development in the MPSoC era**

## ■ MAPS: MPSoC Application Programming Studio:



Source: Virtual Platform of Shapes  
RDT, SSS RWTH Aachen



Source: Chen, NTU,  
MPSoC 2008

- Flexible input specification: 85% of embedded programmers use C/C++ ([www.eetimes.com](http://www.eetimes.com))
  - Legacy C-code and partitioning
  - Explicitly parallel C-like programming model (KPN)
- Abstraction & retargetability:
  - Abstract APIs for early SW design
  - Code generation hides HW dependent SW
- Functional validation:
  - Abstract simulator (HVP), no processor-specific tool chains involved
- Mapping & Scheduling frameworks:
  - Manage the huge design space
- Multiple application of different classes (real-time, best effort)

- **Motivation**

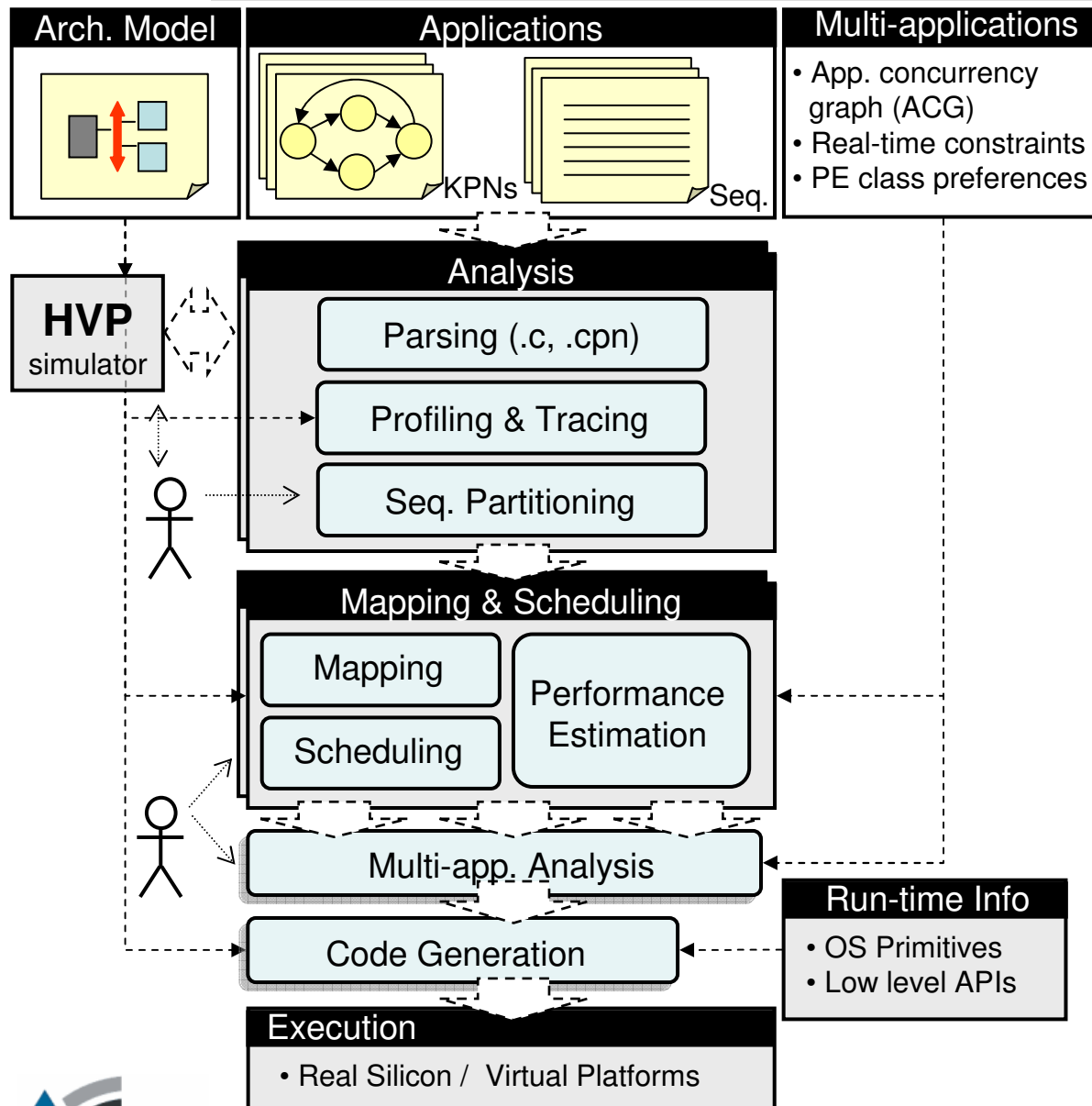
- ➔ **MAPS Overview**

- **Sequential and Parallel Flows**

- **Results**

- **Conclusions and Outlook**

# MAPS Flow Overview



- **Architecture model for retargetability**
- **Applications:**
  - C code for legacy
  - Parallel code to leverage a-priori knowledge
- **Analysis Phase:**
  - Profile-driven
  - Interactive
- **Mapping/Scheduling:**
  - Extensible
  - Cost-table driven performance estimation
- **Multiple Application**
  - Interaction through ACG
  - Composition approach
  - Different app. classes

# MAPS: Graphical User Interface

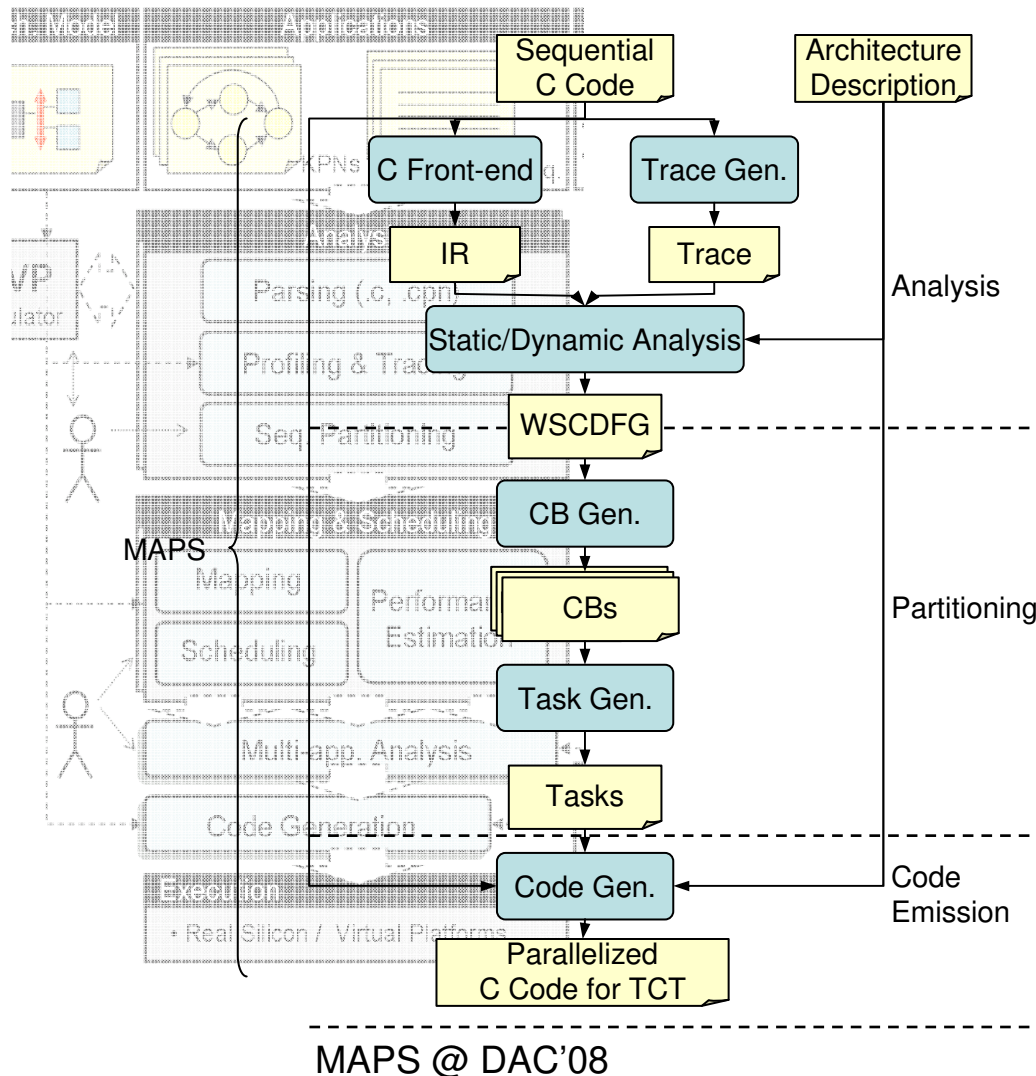
The screenshot displays the MAPS graphical user interface within the Eclipse SDK. The main window, titled "GTKWave - files\_jpeg\_prioritybased/JPEG\_ched\_3.vcd", shows a signal waveform with a time scale from 0 to 86531997 ns. A dependency graph, titled "\*main.mapsconcgraph\_diagram", is overlaid on the waveform. The graph consists of five nodes: "jpeg", "h264", "mimo", "mp3", and "aes". The "mimo" node is connected to "jpeg", "h264", and "mp3". The "mp3" node is connected to "h264" and "aes". The "aes" node is connected to "mp3". The graph is highlighted with an orange border.

The bottom panel shows the command prompt with the following output:

```
elapsedTime = 1.340000 sec  
mkdir -p ../profile  
mv btrace.txt ../profile
```

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# Sequential Flow: How it started...

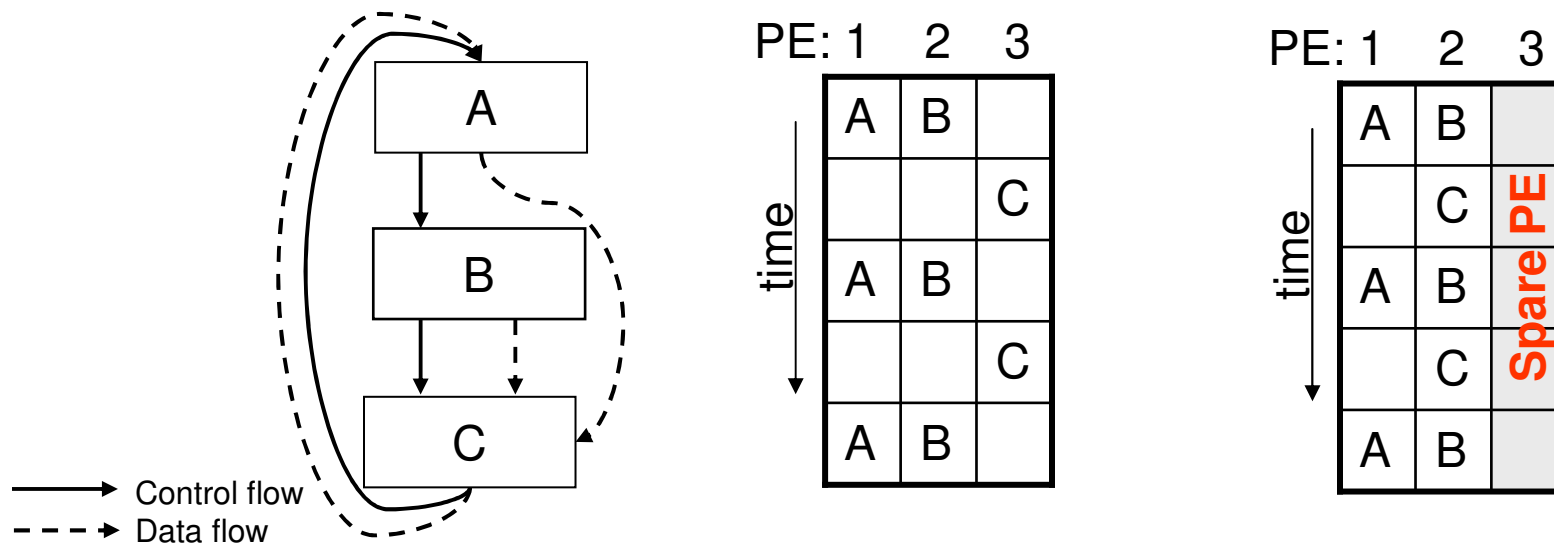


- Sequential flow as presented in DAC 2008
- Key points:
  1. Analysis phase: Traces for Dynamic Data Flow Analysis
  2. New analysis granularity: “Coupled” blocks as opposed to basic-blocks, functions,...
  3. Performance estimation: annotated 3-address-code IR via cost table
  4. Heuristic for hierarchical code partitioning
- Simple code generation for TCT platform (TiTech, Tokyo)
- Execution on TCT virtual/real platform



## Sequential Flow: Improvements

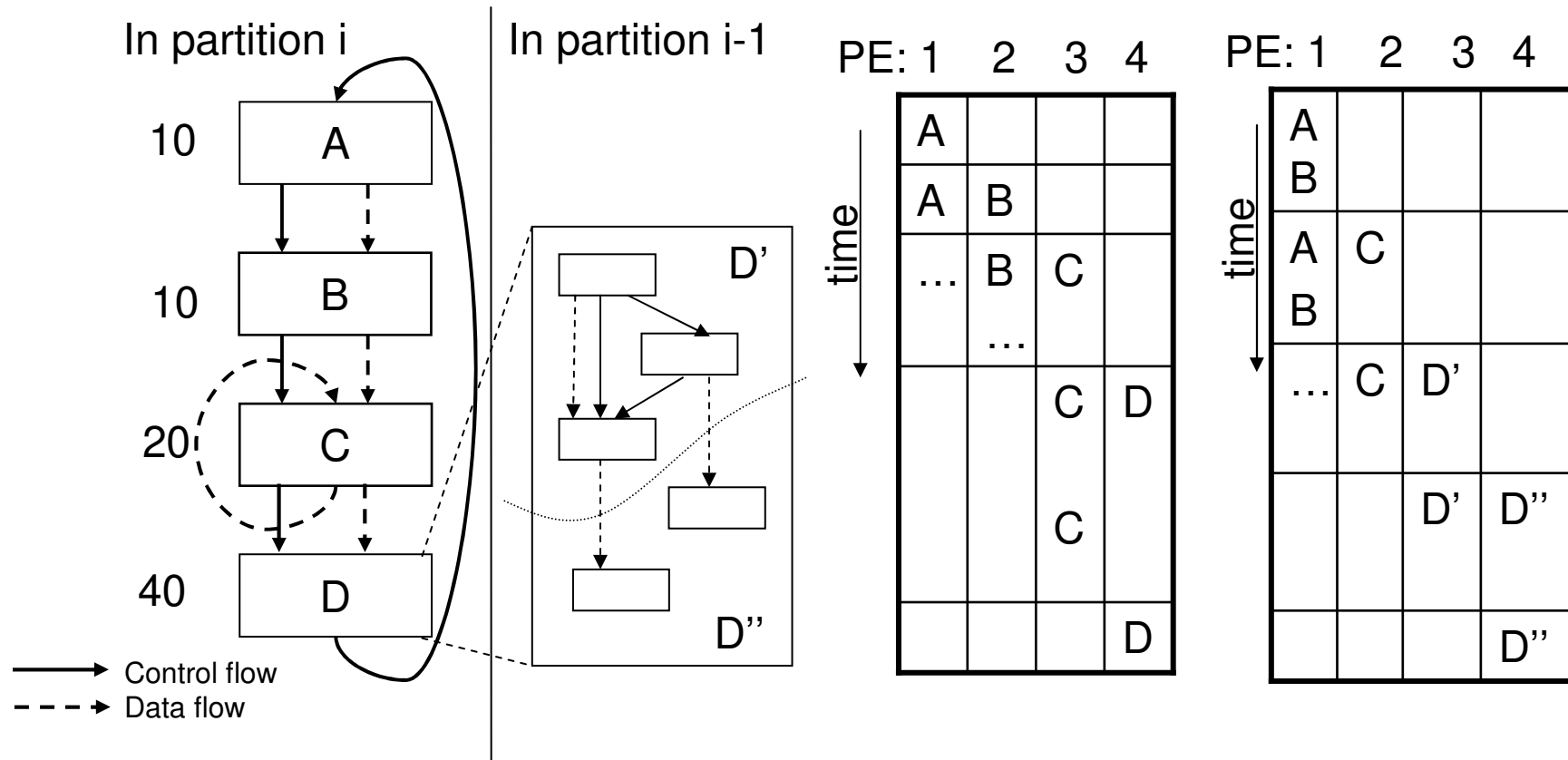
- **Analyze Strongly Connected Components (SCC): improves parallel efficiency, i.e. less PEs – similar execution time**



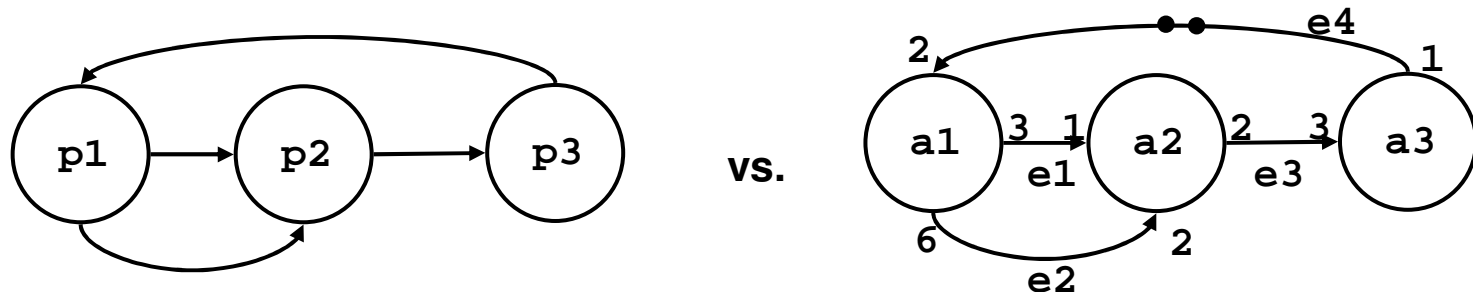
- SCCs are recognized and a heuristic is used to merge blocks in order to improve the parallel efficiency
- Especial care of nested SCCs

## Sequential Flow: Improvements (2)

- Balance partitions of functions in different locations of the Call Graph



- **Dataflow programming models gain everyday more acceptance... Which to use?**
  - HSDFs, SDFs, MRDFs, CFDF, KPN...

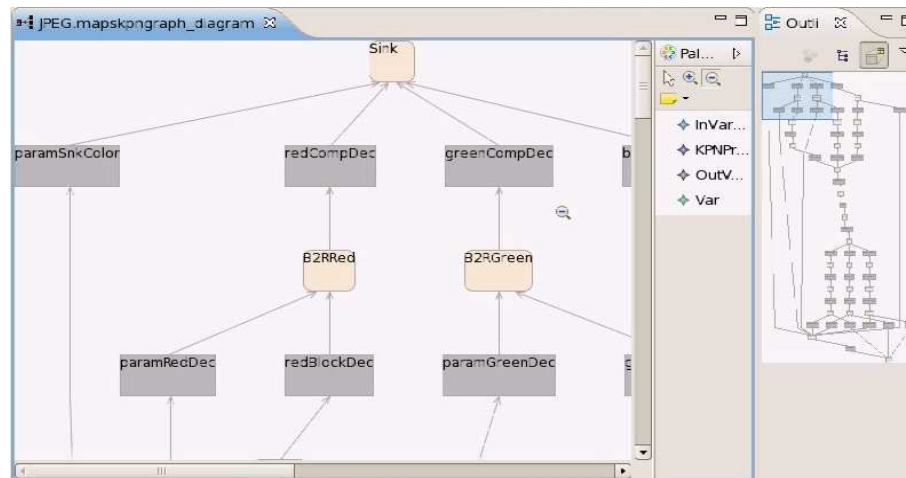


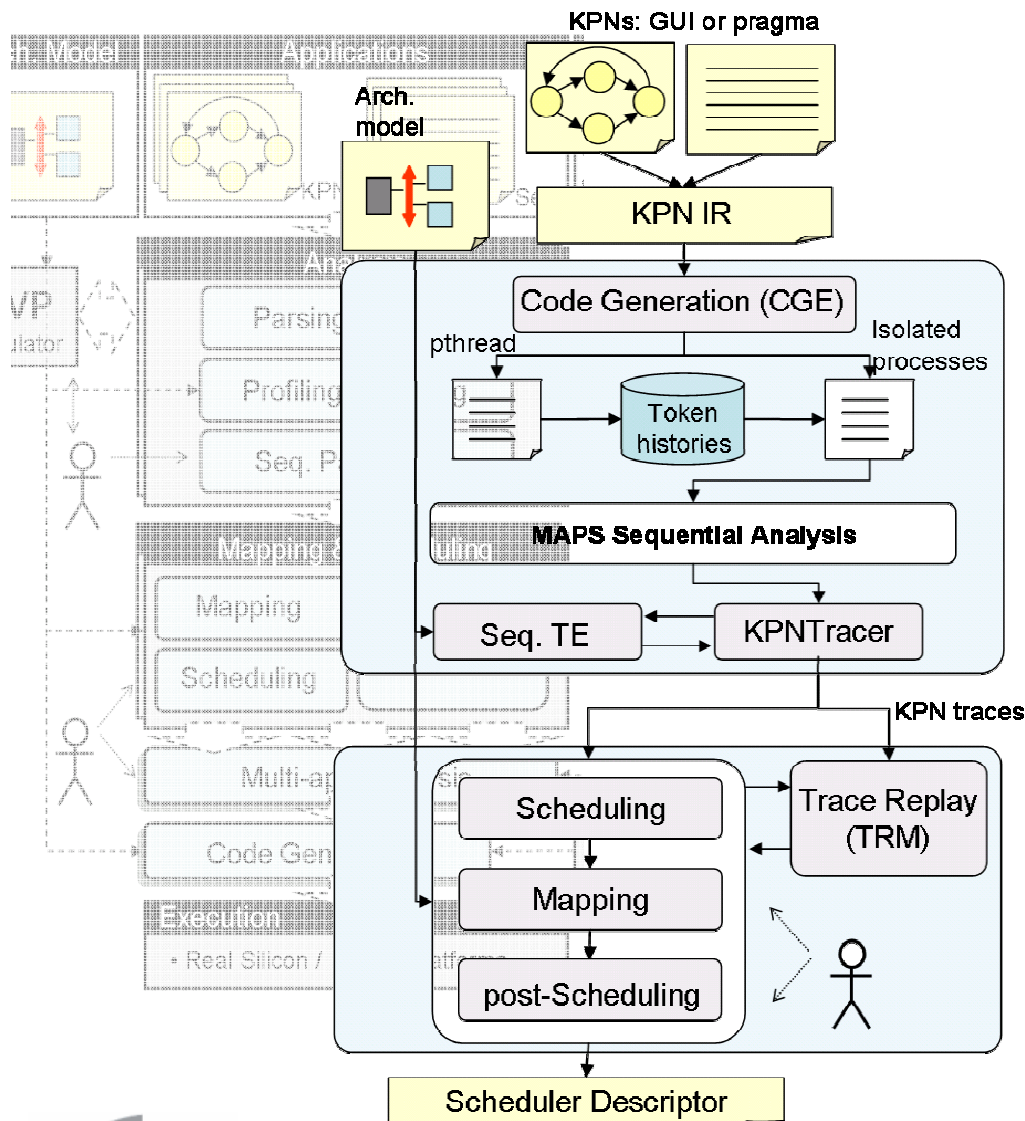
- **MAPS programming model: Based on the Kahn Process Networks (KPN) Model of Computation (MoC)**
  - Better expressiveness compared to other models
  - Simple semantics
  - More difficult to analyze and derive plausible schedules
    - Although comparable when handling multiple applications

- **Pragma extensions to represent KPN applications. Ex. RLE Decoding:**

```
1 __fifo int A, B;
2 #pragma maps process rle_dec, in(A), out(B), prefer(risc)
3 {int cnt, val, i;} // Local variables to the process
4 { // Process body: Repeated for ever
5   cnt = A; // Reads first token: count
6   val = A; // Reads second token: value
7   for (i = 0; i < cnt; ++i) {
8     B = val; // Outputs count times val
9   }}
```

- **GUI equivalent editor/viewer:**

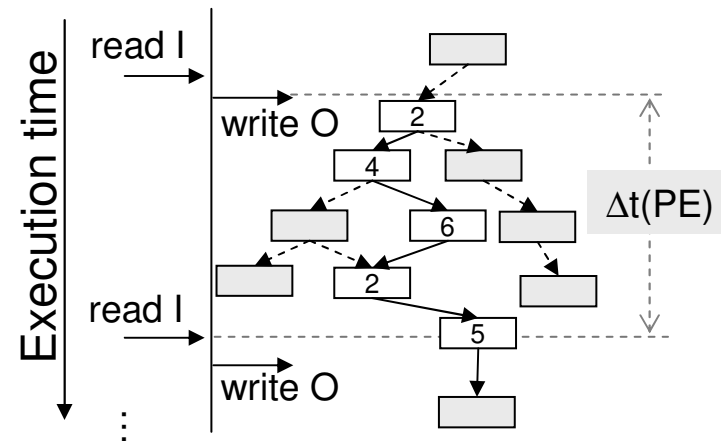
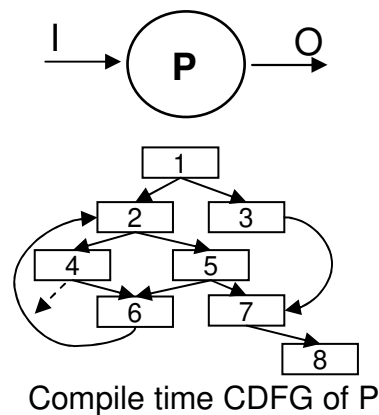




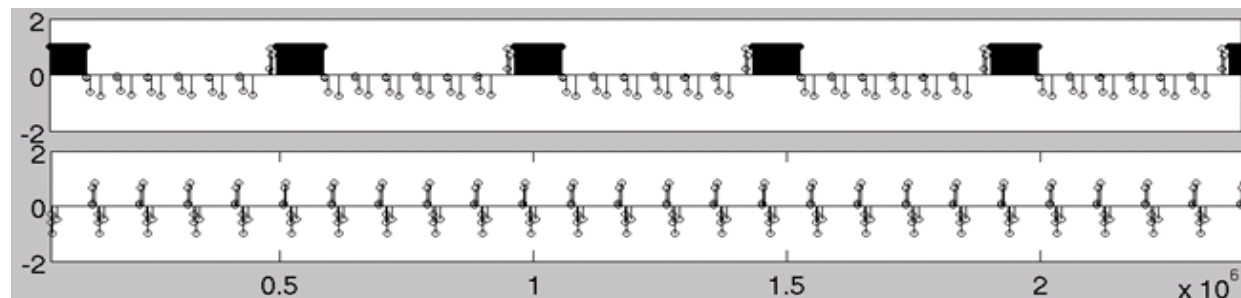
- **Parallel flow, details to appear in DATE Mar. 2010**
- **Key points:**
  1. Intermediate *pthread* code generation for tracing
  2. “*Sequentialized*” processes analyzed by traditional MAPS
  3. KPN tracer generates **KPN traces**
  4. Modular framework for scheduling and mapping: RR, RRWS, priority-based, FIFO,...
  5. TRM allows to compare different schedules
- **The scheduler descriptor can be used to generate code directly**

# Parallel Flow: What is a KPN Trace?

- A sequential trace is a series of basic blocks
- The KPN tracer identifies in which BBs channels were accessed



- A trace is a sequence of segments, where a segment is a sequence of BBs with a channel access in its last BB



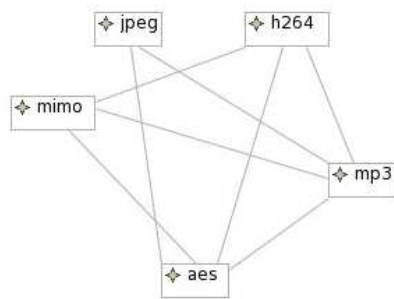
# Handling Multiple Applications

- Applications organized into classes:

- Hard/soft real time
- Best effort

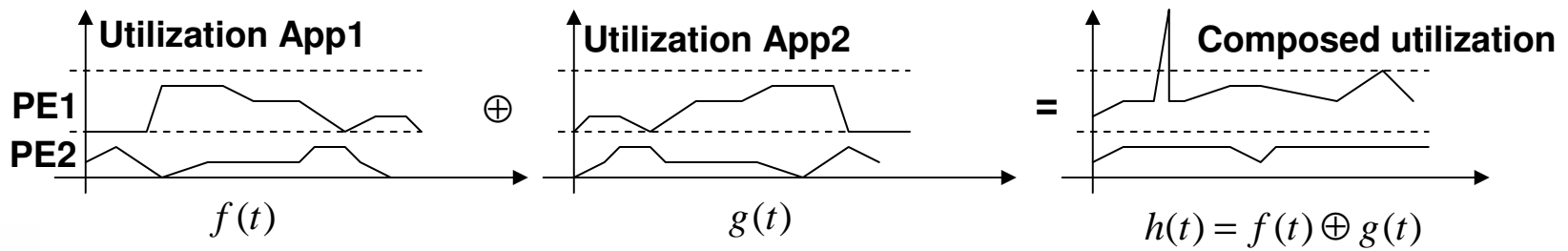


- The Application Concurrency Graph (ACG) serves to describe the interaction among applications



- A sub-graph of the ACG represent a *use-case or multi-application scenario*
- Schedules for different applications are computed separately

- Use-case analysis via *composition*:



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## ■ New partitioning passes: a toy example

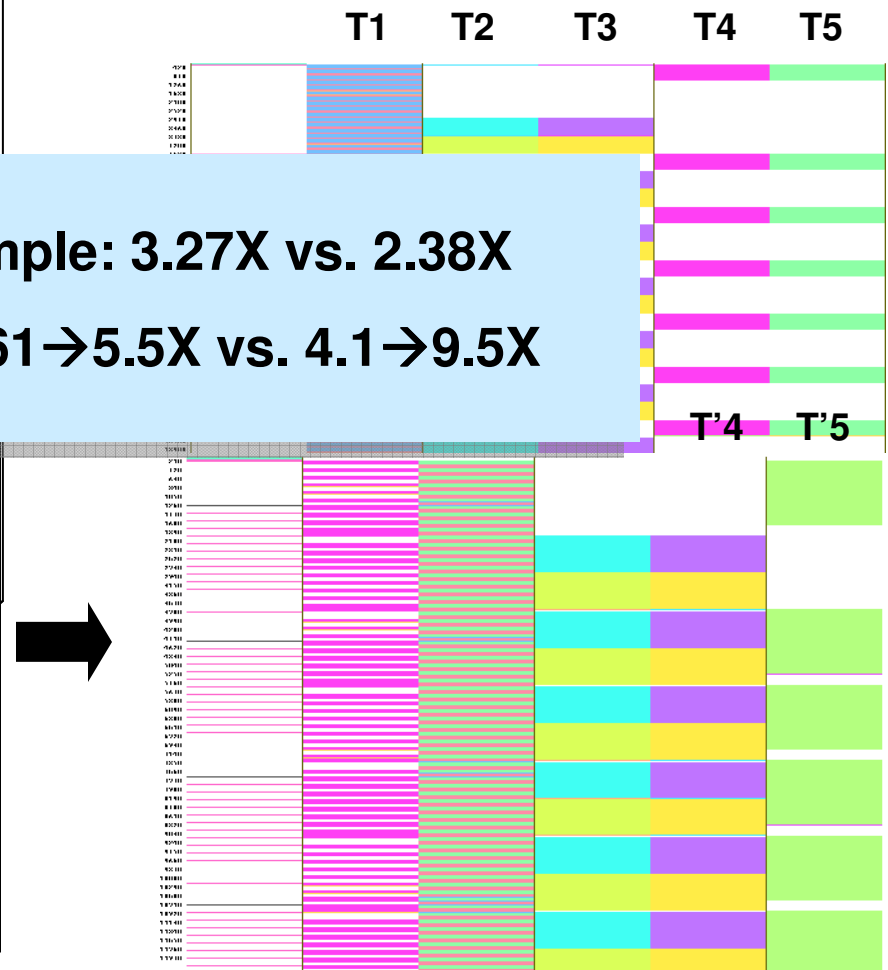
```

1: for (i = 0; i < N1; i++) {
2:   for (j = 0; j < N2; j++) {
3:     ret_param1 = use0(array1,j);
4:     ret_param1 = use0(array1,j);
5:     ret_param1 = use0(array1,j);
6:   }
7:   ret_param2 = def1(array2,i);
8:   ret_param2 = use1(array2,i);
9:   ret_param3 = def1(array3,i);
10:  ret_param3 = use1(array3,i);
11:  ret_param2 = fool(array4,0);
12:  ret_param3 = fool(array4,1);
13: }
    
```

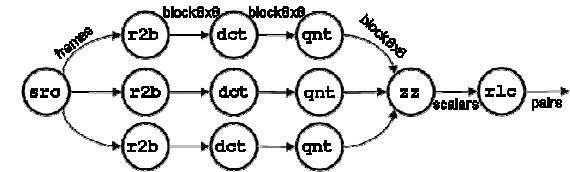
Annotations in the code block:
 

- T1**: A dashed box around lines 3-5, with arrows indicating a loop-carried dependency between the `use0` calls.
- T'2**: A dashed box around lines 4-5, with an arrow indicating a loop-carried dependency between the `use0` calls.
- T'3**: A dashed box around lines 7-8, with an arrow indicating a loop-carried dependency between the `def1` and `use1` calls.
- T'4**: A dashed box around lines 9-10, with an arrow indicating a loop-carried dependency between the `def1` and `use1` calls.
- T'5**: A dashed box around lines 11-12, with an arrow indicating a loop-carried dependency between the `fool` calls.

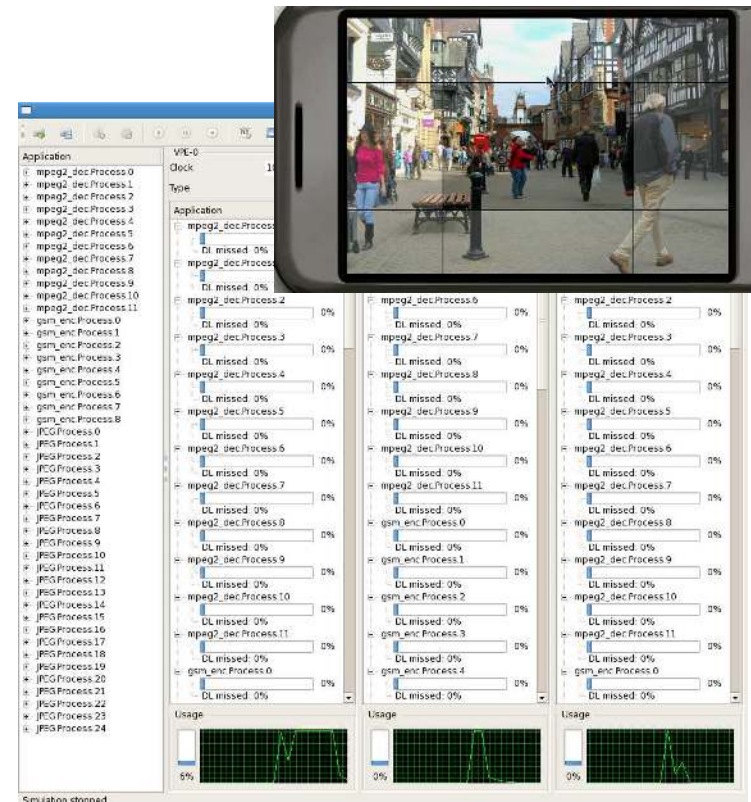
**In toy example: 3.27X vs. 2.38X**  
**In JPEG: 3.61 → 5.5X vs. 4.1 → 9.5X**



- The parallel flow has been tested on several real life applications:
  - MPEG2, JPEG, GSM, MIMO,...
  
- MAPS usability fully tested:
  - Parsing/tracing/profiling
  - Functional validation
  
- Later verification on different back-ends
  - TI-OMAP, TCT, OSIP



Source:  
[www.ti.com](http://www.ti.com)



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- **MAPS – A fairly complete tool set for MPSoC programming was presented:**
  - Sequential (C) & parallel (KPN) input specification
  - Abstraction: functional simulation, APIs
  - Mapping & scheduling of single and multiple applications to heterogeneous MPSoCs

**... in a user friendly Eclipsed-based GUI**
- **Current & future work in MAPS**
  - C extensions instead of *pragmas*, aka: **CPN**
  - Compiler development: CLANG, LLVM
  - Better performance estimation techniques: **TotalProf**
  - Improving mapping and scheduling heuristics
  - Research on *composability* for KPNs

# *Thank You!*

## *Questions??*

### *Acknowledgments:*

*This work has been supported by the UMIC (Ultra High-Speed Mobile Information and Communication) research centre. [www.umic.rwth-aachen.de](http://www.umic.rwth-aachen.de)*

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