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Multi-Objective Optimization of WEDM of Aluminum Hybrid Composites Using AHP and Genetic Algorithm

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Abstract

Aluminum hybrid composites have the potential to satisfy emerging demands of lightweight materials with enhanced mechanical properties and lower manufacturing costs. There is an inclusion of reinforcing materials with variable concentrations for the preparation of hybrid metal matrix composites to attain customized properties. Hence, it is obligatory to investigate the impact of different machining conditions for the selection of optimum parameter settings for aluminum-based hybrid metal matrix composite material. The present study aims to identify the optimum machining parameters during wire electrical discharge machining of samples prepared with graphite, ferrous oxide, and silicon carbide. In the present research work, five different process parameters and three response parameters such as material removal rate, surface roughness, and spark Gap are considered for process optimization. Energy-dispersive spectroscopy and scanning electron microscopy analysis reported the manifestation of the recast layer. Analytical hierarchy process and genetic algorithm have been successfully implemented to identify the best machining conditions for hybrid composites.

Keywords Wire electrical discharge machining \cdot Optimization \cdot Analytical hierarchy process \cdot Genetic algorithm \cdot Metal matrix composites

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Abbreviations

			1
Al	Aluminum	Fe2O ₃	Ferrous oxide
MMC	Metal matrix composites	SiC	Silicon carbide
Al-MMC	Aluminum metal matrix composites	AHP	Analytical hierarchy proc
WEDM	Wire electrical discharge machining	GA	Genetic algorithm

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SEM	Scanning electron microscope
EDS	Energy-dispersive X-ray spectroscopy
DOE	Design of experiments
MRR	Material removal rate (mm ³ /min)
SR	Surface roughness (µm)
SG	Spark gap (mm)
Ip	Pulse peak current (A)
Ton	Pulse-on-time (µs)
Toff	Pulse-off-time (µs)
WF	Wire feed rate (m/min.)
WT	Wire tension (G)
SV	Spark gap-set voltage (V)
Ra	Average Surface Roughness (µm)
SN ratio	Signal-to-noise ratio
Wg	Gap width (µm)
B	Width of cut (µm)
D	Diameter of wire electrode (µm)
C _m	Machining speed (mm/min)
Н	Height of workpiece (mm)
dB	Decibels
r _{ii}	Normalized matrix
a_{ii}	Decision matrix
n	Number of entries
V_i	Statistical variance
W_i	Objective weight
MRR _{MAX}	Maximization of material removal rate
SR _{MIN}	Minimization of surface roughness
SG _{MIN}	Minimization of spark gap
Z _{MIN}	Multi-objective function minimization

1 Introduction

MMC materials are an exciting alternative to counter the growing demand for lighter materials as they exhibit high strength specifically for dynamic structures [1]. Due to customized properties, these materials have been consistently used for armored vehicles, driveshafts, turbine rotors, lightweight bicycle frames, and engine components [2]. Some of the major automobile manufacturers such as Honda, General Motors, Toyota, and Nissan are using MMCs for production of engine blocks, piston rings, connecting rods, calipers, liners, etc. [3]. The performance advantages of MMCs are their tailored thermo-physical properties that include low density, high fatigue strength, good thermal conductivity, and wear resistance [4]. Al, in alloy form, is the best-sought matrix for the fabrication of MMCs due to the reason that these are economical and possess good compatibility with a wide range of ceramic reinforcements. The mechanical properties of Al-MMC can be tailored by selectively introducing ceramic particulates in the matrix phase, i.e., Al alloy. Al-MMCs are specifically used for multichip electronic modules and Printer Circuit Board heat sinks by Alcoa Innometalx



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and Lanxide, respectively [3]. The materials such as Al_2O_3 , SiC, Gr, SiO₂, B, B₄C, BN, and AlN are among the choices to reinforce the metal/alloy matrix [5]. These materials are finding myriad applications in the aerospace, defense, electronic packaging, and automotive industry [6]. MMCs can be fabricated through a wide range of manufacturing methods. These include liquid metallurgy and powder metallurgy, deposition of matrix vapor phase [7, 8]. Processing through the liquid metallurgy route has proven to be economical [9]. Further, stir casting is a comparatively simpler and economical choice to produce MMC materials in bulk. In such methods, the solidification rate of the molten alloy, which is added with reinforcement material, influences the microstructures of the cast MMC. The hybrid MMCs are gaining popularity owing to better property combinations offered by multiple reinforcements being incorporated in the matrix phase [10]. Reportedly, many researchers have taken a keen interest in the processing of composites made of combinations of alloys/metals and reinforcing materials. Interestingly, the simultaneous addition of soft reinforcements such as graphite improves the wear behavior of the composite materials which were made harder by the addition of SiC as a ceramic reinforcement [11].

Having witnessed the vulnerability of the conventional tools in the machining of MMCs, the researchers are relying on non-conventional machining methods. One of such prospectuses, i.e., electrical discharge machining technology, has caught decent attention from manufacturing engineers owing to its proven potential in cutting intricate shapes in dies, punches, and molds made of materials known for superior mechanical properties [12, 13]. Over the years, the Electrical Discharge Machining process has become a key machining intervention to cut electrically conductive materials without worrying about their range. WEDM has taken greater attention of researchers in the last decade due to the supply of soft computing techniques such as genetic algorithm, fuzzy logics and artificial neural network [14]. Besides advanced algorithms, conventional optimization techniques such as Taguchi and principal component analysis have been widely adopted as modeling methods [15]. The objective function in the Electrical Discharge Machining and WEDM processes can be defined in many ways to offer solutions to multi-response optimization problems.

Rajyalakshmi and Ramaiah [16] applied the Taguchi and grey relational analysis during an experimental study on Inconel 825 using WEDM process. The study was focused to improve the MRR, SR, and SG. The experiment was conducted using L_{36} ($2^1 \times 3^7$) orthogonal array design based upon Taguchi's method and finally, the response graph plots for grey relational analysis were produced. Theory of grey relational analysis convincingly overcomes the shortcomings of conventional statistical methods and only requires limited information to predict the behavior of uncertain and complex systems. Fard et al. [17] investigated dry WEDM using integrated Adaptive Neuro-Fuzzy Inference System models with the Artificial Bee Colony algorithm. So, researchers assigned weights to different responses to meet different machining requirements. Krishna and Rao [18] applied a harmony search algorithm to simultaneous optimization of performance measures such as wire wear and kerf width and successfully proposed an optimal set of machining control parameters.

In an attempt to investigate the mechanical strength, hardness, and wear resistance of aluminum reinforced with silicon carbide and tungsten, Fenghong et al. [19] used the stir casting technique for sample preparation. Improvement in mechanical strength, hardness, and wear resistance was experienced due to uniform distribution of reinforcements. Palanisamy et al. [20] studied the impact of three process parameters of EDM on surface finish, tool wear, and material removal rate while machining of stir-casted Al-MMCs. Grey relation analysis technique was implemented to identify optimum conditions, and maximum impact of discharge current was observed. In a recent study [21], composites were prepared using AA6061 as matrix material and SIC as reinforcement along with jute ash to highlight agriculture waste management. It was observed that tensile strength, wear resistance, and hardness of stir-casted samples were increased due to proper dispersion of reinforcements. Moreover, the presence of SiC enhanced the wear resistance and hardness.

Yadav et al. [22] reported an improvement in bonding strength of matrix material (Al) reinforced with SiC and titanium diboride. Stir casting has been used to prepare test samples of Al reinforced by tungsten carbide; findings reveal that there was an increase of 62% and 6% in tensile strength and hardness respectively [23]. On the other hand, the flexural strain was reduced with an increase in molybdenum disulfide powder in AA6061-T6 [24]. In another study, the doping of graphite manifested better wear resistance as compared to than molybdenum disulfide particles-based composite for the selected parameters at a normal environment. Moreover, under all conditions, the wear rate increases with an applied load and sliding distance [25]. Kumar et al. [26] predicted the optimum conditions for maximized wear resistance and tensile strength of Al reinforced with SiC particles. It was found that 15 s dispersion time with 45° blade angle and stirring speed of 250 rpm yielded the best results.

Computational fluid dynamics was used to predict the best blade design based on hardness and compressive strength of stir-casted aluminum composites [27]. Researchers [28] have also investigated the vortex pressure through computational fluid dynamics during composite preparation as it significantly affects particle distribution. The flow pattern of reinforcements was visualized and optimized using the Taguchi DOE method. It was deduced that holding time of ten minutes and 45° stirrer blade angle resulted in maximum homogeneity. Finite element modeling studies have been performed to compare the tensile strength during experimentation and simulation [29]. The best results were found with 15% reinforcement of SiC, and simulation results were supported by experimental data.

Literature survey and recent studies [30] reveal that some experimental work has been conducted and optimization tools are implemented to optimize surface finish, material removal rate, mechanical and morphological properties of stir-casted Al-MMCs during EDM. The practical limitations of these studies are the lack of advanced optimization tools such as AHP and GA which solve complex problems with multiple and conflicting responses. There is a lack of acceptable and of adequate analytical models to predict the machine response characteristics due to the stochastic nature of WEDM and the presence of the reinforcements in the host matrix material adds more complexity. It necessitates experimental investigations of WEDM using samples of aluminum-based MMC, and further developing predictive regression models. Because many machining parameters influence the process and uncertain nature of these processes, realizing the best performance is a challenge, which needs to apply research on this area. At the production stage, manufacturing industries use such optimization tools for multi-objective optimization which yields maximized output. For meeting these challenges, the present work is focused on multi-objective optimization wherein weights have been assigned to various performance measures to cater to the need of various sectors. The outcome of the study presented in this research work will be able to give new guidelines to researchers and practitioners to understand the influence of various parameters on responses for machining Al/ $(SiC_p + Gr_P + Fe_2O_{3p})$ hybrid MMC.

2 Materials and Methods

The aluminum hybrid composite sample used for the present study has been casted by preheating SIC), Gr and Fe_2O_3 followed by mold cavity preparation. Afterward, the aluminum was stir-casted using an electric motor for uniform and vortex flow.

Electronica Sprincut-734 made WEDM was used for experiments. The MRR and average SR were measured during WEDM operations. The WEDM machine tool was programmed to cut the workpiece into a size of $5 \text{ mm} \times 5 \text{ mm} \times 12 \text{ mm}$ in each machining operation. The machined surface roughness height was measured at three different positions, and the mean values were taken for analyzing the machined surface quality using surface roughness heights measuring instrument (supplied by Surfcom 130A, Zeiss, Japan). The SR is based upon roughness average (Ra),



which is desired to be minimum, hence considered as output for the present study. An evaluation length of 4 mm was used to determine SR after each experiment. The average cutting speed data (mm/min) are measured upon with reference to the original length of cutting operation for each trial. The width of cuts (B, mm) was evaluated using Digimatic Caliper Mitutoyo, Japan. The relation as per Eq. (1) has got in use to determine the spark gap width (Wg, μ m) for each experiment [30].

$$2W_g + D = B \tag{1}$$

MRR for each experiment performed is based upon Eq. (2) [30].

$$MRR = (C_m. B. H) mm^3 / min$$
(2)

Taguchi DOE technique is used for current experimentation as it has got an edge with the potential of considering multiple factors at once and determining the optimal parameters with lesser experimental trials than the conventional DOE approach. As per this approach, the L_{27} orthogonal array was selected for performing the experimental investigation. According to a chosen orthogonal array, only 27 experiments are required to be performed to study the entire control parameter space using the L_{27} orthogonal array. Each control parameter is assigned to a column, and 27 control parameter combinations are needed.

Table 1 describes the WEDM parameters considered for experiments along with their chosen levels. Further, 27 combinations involving each factor as well as their levels in equal ratio to retain the orthogonality of the design of experiments were formulated [19]. The flowchart of the present methodology is shown in Fig. 1.

The SN ratio is defined in mathematical form for higherthe-better (i.e., maximization of output, example: MRR) and shown as Eq. (3) [30]:

SN Ratio
$$\eta = -10 \log_{10} \left[\frac{1}{n} \sum_{i=1}^{n} \frac{1}{y_i^2} \right]$$
 (3)

and for lower-the-better (i.e., minimization of output, example: SR) and shown as Eq. (4) [30]:

SN Ratio
$$\eta = -10 \log_{10} \left[\frac{1}{n} \sum_{i=1}^{n} y_i^2 \right]$$
 (4)

Figure 2a plots the EDS spectra of a machined sample which indicates the presence of carbon, zinc, silicon, magnesium, and oxygen, while aluminum has a major concentration at 1.5 keV. The presence of oxygen indicates the deionization of dielectric fluid at elevated temperatures which occurs due to high pulse-on time. This phenomenon is confirmed by the porosity manifested in the machined surface as visualized in the SEM micrograph in Fig. 2b. Some cracks can be noticed on the machined surface owing to the high temperature generated from the recast layer during WEDM machining. However, most areas of the machined surface are free from cracks owing to moderate tensile residual stress in the recast layer. Figure 2c shows the elemental concentration retrieved from SEDS testing.

3 Results and Discussion

In the present work, the effect of six independent variables viz. Ip, T_{on} , Toff, WF, WT, SV on three different dependent variables viz. MRR, SR and SG is investigated using regression tools, AHP, and GA.

The SN ratios of MRR, SR, and SG in all the 27 experimental runs have been calculated using Minitab 19 analytical tool and are shown in Table 2. The specimen prepared during experimentation is displayed in Fig. 3.

As per 3D response surface plots, the interaction effects of Ip, Ton, Toff, WF, WT, SV on MRR are recovered. As per the WEDM process, the process of melt removal occurs on the machined surface in the form of craters. The MRR value starts increasing with an increase in the peak current but instead decreases with the pulse peak current rising further, as shown in Fig. 4a. The simultaneous effect of Ton and WF on MRR is shown in Fig. 4b. In the machining zone, the rise in pulse peak current provides greater electrical discharge energy, fostering deeper craters on the machined surface, leading to higher MRR. But deeper craters minimize the energy density of the discharge on the electrical discharge

S. No	Input parameters	Notation	Level			Unit	
			1	2	3		
1	Pulse peak current (Ip)	A	80	100	120	A	
2	Pulse-on-time (Ton)	В	0.5	0.8	1.1	μs	
3	Pulse-off-time (Toff)	С	20	16	12	μs	
4	Wire feed rate (WF)	D	5	7	9	m/min	
5	Wire tension (WT)	Е	850	1000	1200	G	
6	Spark gap-set voltage (SV)	F	25	30	35	V	

Table 1Levels of variablesused during experimentation





Fig. 1 Process flowchart for experimentation

spot and thus decrease the MRR. With the decrease in pulseoff time, it is shown that the values of MRR continue to increase disingenuously. The frequency of discharges over a machining period has been correlated with this case. The high number of discharges within a specific interval of time has a tendency to produce more melt and hence more MRR. The presence of ceramic reinforcements can diffuse a significant amount of thermal energy which can decrease the MRR at a low-level setting of pulse-on-time. However, extended pulse duration renders a sharp spike in thermal energy and hence causes more erosion of the workpiece. The increase in wire feed had a positive impact on MRR. Figure 5a plots the effect of Ton and WF on MRR. The increase in WF induced a slight increase in surface roughness, and maximum surface roughness of 1.6 μ m was achieved at 9 m/min. Whereas the increase in Ton increases the roughness to 1.5 μ m up to 0.85 μ s, it remains constant with further increase in Ton. The abrupt initial increase in roughness of materials occurs due to higher Ton, the spark time is elongated which erodes higher material. The phenomenon of pit formation is observed at higher Ton conditions which decrease the surface clarity. However, this phenomenon led to a higher material removal rate as discussed. Figure 5b shows initially the SR increase with an increase





Fig. 2 a EDS spectra of the processed specimen b SEM image of surface c weight percentage of elements

in spark voltage, while after 30 V, the SR is decreased. The increase in SR at the medium range may be attributed to unstable spark at this level which created non-uniform material removal from the surface leading to asperities. However, the lower and upper range yields good surface finish values due to uniform erosion. On other hand, SR is directly proportional to wire tension. The increased frequency of oscillation of wire results in the deterioration of material surface.

In Fig. 6a, the effects of Toff and Ip on SG are shown. The linear existence of SG variance with a time off pulse was observed. The breakage in pulse slightly increases the gap between tool and workpiece. For all current set values, the SG increases with the decrease in Toff. Higher spark voltage and lower WT combination can be shown to result in lower



SG (see Fig. 6b). The spark voltage and wire tension are the most significant parameters which influence the spark gap.

4 Multi-Objective Optimization

As discussed in the previous section, the impact of each parameter on output is different and non-uniform. Moreover, the parameters are interacting with each other, and hence it is difficult to identify optimum conditions for three response parameters. Conventional optimization techniques cannot suggest a single set of parameters for attaining the best values of MRR, SR, and SG for the present context. Hence, there is a need to implement an

Table 2SN ratios for MRR,SR, and SG for each experiment

Exp No	Contro	ol paramet	ters				S/N ratios (dB)				
	A (I _p)	B (T _{on})	C (T _{off})	D (W _F)	E (W _T)	F (SV)	MRR	SR	SG		
1	80	0.5	20	5	850	25	14.3201	0.19322	35.8097		
2	80	0.5	20	5	1000	30	14.1514	-1.82630	35.6503		
3	80	0.5	20	5	1200	35	14.9015	-3.26323	35.3401		
4	80	0.8	16	7	850	25	16.3381	-0.83575	34.5632		
5	80	0.8	16	7	1000	30	18.7604	-1.83334	33.4733		
6	80	0.8	16	7	1200	35	18.1911	-1.91036	33.2309		
7	80	1.1	12	9	850	25	19.4162	- 1.01069	32.7278		
8	80	1.1	12	9	1000	30	19.6905	-4.38645	32.6157		
9	80	1.1	12	9	1200	35	19.2663	-4.88059	32.4685		
10	100	0.5	16	9	850	30	17.5704	-3.22736	33.6387		
11	100	0.5	16	9	1000	35	17.7050	-3.76732	33.7649		
12	100	0.5	16	9	1200	25	17.5716	- 5.67959	33.1122		
13	100	0.8	12	5	850	30	21.1761	-2.54210	32.6902		
14	100	0.8	12	5	1000	35	21.7343	-3.33452	32.2879		
15	100	0.8	12	5	1200	25	20.9299	-5.50162	32.7278		
16	100	1.1	20	7	850	30	19.6155	-3.26323	32.0065		
17	100	1.1	20	7	1000	35	19.1808	-2.05553	32.2879		
18	100	1.1	20	7	1200	25	19.0578	-3.18533	32.7278		
19	120	0.5	12	7	850	35	18.6900	-2.57445	33.1122		
20	120	0.5	12	7	1000	25	17.7298	-3.78419	32.5786		
21	120	0.5	12	7	1200	30	17.5012	-3.96214	32.4320		
22	120	0.8	20	9	850	35	18.6566	-0.98436	32.3597		
23	120	0.8	20	9	1000	25	18.4856	-2.58090	32.1110		
24	120	0.8	20	9	1200	30	18.8461	-4.43350	32.4685		
25	120	1.1	16	5	850	35	19.7157	-3.11886	32.0065		
26	120	1.1	16	5	1000	25	20.1439	-4.36546	32.1110		
27	120	1.1	16	5	1200	30	19.6155	-3.14914	31.9376		



Fig. 3 Specimen prepared after machining

advanced optimization technique that may suggest the optimum parametric settings. In the present study, regression analysis is implemented followed by GA and AHP.

4.1 Regression Analysis

The regression method is applied to investigate the effect of input on output. SPSS software is used to apply the regression method. The present work is focused on three response parameters; therefore, four single objective equations are formulated with the help of the regression method. In the manufacturing environment, numerous variables influence the output parameters. The mathematical model defines a relationship between independent and response parameters as shown in Eq. 5 [31].

$$Y = \beta_0 + \sum_{i=1}^n \beta_i \times C_i + \sum_{i=1}^n \beta_{ii} \times C_i^2 + \sum_{i=1}^n \beta_{ij} \times C_i C_j$$
(5)

For six variables, Eq. 5 can be written as shown in Eq. 6, where C_1 , C_2 , C_3 , C_4 , C_5 , C_6 are the process parameters and Y denotes the response parameters [31].





Fig. 4 a Effect of Ip and Toff on MRR b Effect of Ip and WF on MRR



Fig. 5 a Effect of Ton and WF on SR b Effect of WT and SV on SR



Fig. 6 a Effect of Toff and Ip on SG b Effect of SV and WT on SG





$$Y = \beta_0 + \beta_1 C_1 + \beta_2 C_2 + \beta_3 C_3 + \beta_4 C_4 + \beta_5 C_5 + \beta_6 C_6 + \beta_7 C_1 \times C_2$$
(6)

In the present context, there are six input variables of the WEDM process, whereas MRR, SR, and SG are output parameters. Three Eqs. (7, 8, and 9) are developed, one for each output, using regression methods, where maximization of MRR and minimization of SR and SG are objectives respectively.

 $MRR_{MAX} = -94 + 0.53 A - 35.1 B + 1.74 C + 4.9 D + 0.148 E + 3.98 F - 0.00233 A \times A + 26.6 B \times B$

$$- 0.056 C \times C + 0.0999 D \times D - 0.000036 E \times E - 0.0431 F \times F - 0.000486 A \times E - 0.0261 A \times F - 0.0324 B \times E$$

$$+ 2.28 B \times F + 0.00240 C \times F - 0.116 C \times F - 0.0111 D \times F - 0.536 D \times F + 0.00581 A \times D \times F - 0.130 B \times D \times F$$
(7)

 $+ \ 2.28 \ B \times F \ + \ 0.00240 \ C \times E \ - \ 0.116 \ C \times F \ - \ 0.0111 \ D \times E \ - \ 0.536 \ D \times F \ + \ 0.00581 \ A \times D \times F \ - \ 0.130 \ B \times D \times F$

+ $0.000217 D \times E \times F$

8038



 $SR_{MIN} = -91.4 + 0.615 A - 5.5 B + 2.69 C + 4.14 D + 0.0937 E + 0.430 F - 0.00307 A \times A + 3.95 B \times B$ - 0.0828 C × C + 0.0282 D × D - 0.000024 E × E - 0.0252 F × F - 0.000302 A × E + 0.00892 A × F - 0.01836 B × E + 0.215 B × F + 0.001266 C × E - 0.0464 C × F - 0.00721 D × E - 0.159 D × F + 0.00043 A × D × F + 0.0572 B × D × F + 0.000161 D × E × F

$$SG_{MIN} = 0.088 - 0.000749 A - 0.0247 B - 0.00456 C - 0.00143 D - 0.000067 E + 0.00405 F + 0.000006 A \times A + 0.0219 B \times B + 0.000156 C \times C - 0.000083 D \times D + 0.000000 E \times E + 0.000006 F \times F + 0.000000 A \times E - 0.000048 A \times F + 0.000026 B \times E + 0.00112 B \times F - 0.000003 C \times E + 0.000059 C \times F + 0.000009 D \times E - 0.000263 D \times F + 0.000004 A \times D \times F - 0.000267 B \times D \times F - 0.000000 D \times E \times F$$
(9)

Surface plots showed that there is a non-uniform impact of each process parameter on MRR, SR, and SG of parts processed through WEDM process. The optimum parametric settings of MRR would adversely impact the SR and SG and vice versa. Hence, there is a need to identify a single set of parameters that would yield satisfactory results in terms of MRR, SR, and SG. This multi-objective problem of WEDM can be solved by implementing AHP and GA. Conventionally, the weighted sum approach, distance function method, min-max, and Taguchi techniques are used for solving multi-objective problems. However, the accuracy of these methods depends upon the knowledge of the expert who decides the ranking and relative importance of objective functions. Discontinuity of objective function is another limitation of these techniques. Hence, the combination of AHP and GA is used in the present study of multi-objective problems [32]. GA is a robust technique that eliminates the requirement of gradient information and inherent parallelism for locating design space. The primary aim is to determine a single combination of WEDM process parameters within the constraints which would simultaneously maximize the MRR and minimize the SR and SG. Initially, three equations for each objective function (MRR, SR, and SG) are converted into a single equation as a multi-objective function as shown in Eq. 13.

4.2 Implementation of AHP

The simple method to convert single objective equations into a multi-objective equation is a weighted sum method and the same technique is adopted in the present work. The weightage is assigned to single objective equations to formulate a multi-objective equation. In this research work, a hybrid methodology is adopted to assign the weightage to objective functions. The AHP and statistical variance are used to assign subjective weights and objective weights respectively [33]. Afterward, AHP is implemented to assign different types of objective weights to each response and displayed in Table 3.

AHP is the most commonly used multi-criteria decisionmaking tool to find the subjective priority of attributes. The nine-point Satty's scale was used to develop a pairwise comparison between response parameters. The expert's opinions were taken to formulate the pairwise comparison matrix [32].

Objectives weights of attributes can be determined using the statistical variance concept. The steps involved in finding the values of objective weights are mentioned below:

Step 1 Decision matrix: The values of attributes in a tabular form.

Step 2 Normalized matrix: The normalized matrix can be developed using Eq. 10 [33].

$$r_{\rm ij} = a_{\rm ij} / \sum_{i}^{n} a_{\rm ij} \tag{10}$$

Step 3 Compute the values of statistical Variance: The values of statistical variance are found using Eq. 11 [33]:

Table 3 Subjective weights for AHP

	MRR	SR	SG	Subjec- tive weights
MRR	1	1/2	2	0.297
SR	2	1	3	0.54
SG	1/2	1/3	1	0.163

Table 4 Different objective weights assigned to response parameters

	MRR	SR	GG
AHP Weights	0.297	0.540	0.163
Equal weights	0.333	0.333	0.333
Objective weights	0.506	0.332	0.162
Hybrid weights	0.381	0.405	0.214



Step 4 Determine objective weights: The objective

weights are computed using Eq. 12 [33].

$$V_i = \frac{1}{n} \sum_{i=1}^{n} \{r_{ij} - (r_{ij}) \text{mean}\}^2$$

(11)





Optimization type	Goal	Ip	Ton	Toff	WF	WT	SV
Single objective	MRR _{MAX}	80.000	0.500	12.000	5.000	850.000	35.000
Single objective	SR _{MIN}	80.000	0.500	12.000	9.000	850.000	35.000
Single objective	SG _{MIN}	120.000	1.100	12.000	9.000	1200.000	25.000
Multi-objective using equal weights	Z _{MIN}	80.000	0.500	12.000	5.000	850.000	35.000
Multi-objective using AHP weights	Z _{MIN}	80.000	0.500	12.000	5.000	850.000	35.000
Multi-objective using Objective weights	Z _{MIN}	80.000	0.500	12.000	5.000	850.000	35.000
Multi-objective using Hybrid weights	Z _{MIN}	80.000	0.500	12.000	5.000	850.000	35.000

Table 5Single and multi-objective optimization results





Fig. 8 Current best individual using genetic algorithm

$$W_i = \frac{V_i}{\sum\limits_{i=1}^{n} V_i}$$
(12)

The hybrid weights are computed using the geometric mean of AHP and Equal weights. Each value of the geometric mean is divided by the sum of all geometric values. The objective weights assigned to different response parameters are shown in Table 4. MATLAB is used to run the genetic algorithm program codes, and the results are summarized in Table 5. The result of multi-objective optimization showed that the value of SG set voltage is constant in all conditions of optimization. The value of Ip, Ton and Toff is also same in all conditions of multi-objective optimization.

It can be concluded that values remain constant for equal weight, AHP weight, objective weight, and hybrid weight functions. Moreover, values for pulse-off time remain constant for all weights while values differ for the two parameters in the case of MRR, SR, and SG weight settings.

Figure 8 shows the best individual value of each parameter for multi-objective optimization using hybrid weights. It can be deduced that a total number of 72 generations were involved when genetic algorithm codes were executed by MATLAB for finding the best results. Moreover, the mean and best fitness values are very close to each other which confirms the accuracy of the results. It is advised that the value of pulse peak current must be set at 80A, pulse-on-time at 0.5 μ s, pulse-off-time at 12 μ s, wire feed rate at 12 m/min., wire tension at 850G, spark gap-set voltage at 35 V. The confirmatory experiments (Table 6) were performed at suggested set of parameters, and it was observed that there is an improvement in all the response parameters.

$$\begin{split} Z_{\text{MIN}} &= -W_1(-94 \ + \ 0.53 \ A \ - \ 35.1 \ B \ + \ 1.74 \ C \ + \ 4.9 \ D \ + \ 0.148 \ E \ + \ 3.98 \ F \ - \ 0.00233 \ A \times A \ + \ 26.6 \ B \times B \\ &= 0.056 \ C \times C \ + \ 0.0999 \ D \times D \ - \ 0.000036 \ E \times E \ - \ 0.0431 \ F \times F \ - \ 0.000486 \ A \times E \ - \ 0.0261 \ A \times F \\ &= 0.0324 \ B \times E \ + \ 2.28 \ B \times F \ + \ 0.00240 \ C \times E \ - \ 0.116 \ C \times F \ - \ 0.0111 \ D \times E \ - \ 0.536 \ D \times F \\ &+ \ 0.00581 \ A \times D \times F \ - \ 0.130 \ B \times D \times F \ + \ 0.000217 \ D \times E \times F) \ + \ W_2(-91.4 \ + \ 0.615 \ A \ - \ 5.5 \ B \ + \ 2.69 \ C \\ &+ \ 4.14 \ D \ + \ 0.0937 \ E \ + \ 0.430 \ F \ - \ 0.00307 \ A \times A \ + \ 3.95 \ B \times B \ - \ 0.0828 \ C \times C \ + \ 0.0282 \ D \times D \\ &- \ 0.000024 \ E \times E \ - \ 0.0252 \ F \times F \ - \ 0.000307 \ A \times A \ + \ 3.95 \ B \times B \ - \ 0.0828 \ C \times C \ + \ 0.0282 \ D \times D \\ &- \ 0.000024 \ E \times E \ - \ 0.0252 \ F \times F \ - \ 0.000302 \ A \times E \ + \ 0.00892 \ A \times F \ - \ 0.01836 \ B \times E \ + \ 0.215 \ B \times F \\ &+ \ 0.0001266 \ C \times E \ - \ 0.0464 \ C \times F \ - \ 0.00721 \ D \times E \ - \ 0.159 \ D \times F \ + \ 0.00043 \ A \times D \times F \ + \ 0.0572 \ B \times D \times F \\ &+ \ 0.000161 \ D \times E \times F \ + \ W_3(0.088 \ - \ 0.000749 \ A \ - \ 0.0247 \ B \ - \ 0.000456 \ C \ - \ 0.000143 \ D \ - \ 0.000006 \ E \times E \\ &+ \ 0.000006 \ F \times F \ + \ 0.000006 \ A \times A \ + \ 0.0219 \ B \times B \ + \ 0.000156 \ C \times C \ - \ 0.000083 \ D \times D \ + \ 0.0000006 \ E \times E \\ &+ \ 0.000006 \ F \times F \ + \ 0.0000006 \ A \times A \ + \ 0.0219 \ B \times B \ + \ 0.000026 \ B \times E \ + \ 0.000112 \ B \times F \\ &+ \ 0.000006 \ F \times F \ + \ 0.0000006 \ A \times E \ - \ 0.000006 \ B \times E \ + \ 0.000006 \ B \times E \ + \ 0.0000006 \ B \times$$

$$- 0.000267 B \times D \times F - 0.000000 D \times E \times F)$$

4.3 Implementation of Genetic Algorithm (GA)

5 Conclusions

GA is a nature-based algorithm and used to solve nonlinear objective functions. Holland [34] developed the GA and further modified by Goldberg [35] in 1989. GA is used to achieve the best fitness values, and its results are more reliable, especially in a constrained optimization problem. The process flowchart of the genetic algorithm is shown in Fig. 7. The hybrid aluminum metal matrix composites have been machined using the WEDM process under five different machining conditions, and output is computed in terms of MRR, SG, and SR. It was found that different parameters, i.e., Ip, Ton, Toff, WF, WT, and SV have a conflicting influence on the response which led to the need for the



Table 6 Comparison of
response during confirmatory
experiments

S. No	Response	Observed value (Indi- vidual best)	Observed value (At Opti- mum conditions)	Percentage improve- ment
1	MRR (mm ³ /min)	12.212	13.897	13.79
2	SR (µm)	1.101	0.890	-19.16
3	SG (mm)	0.016	0.014	-12.50

implementation of advanced optimization tools for the selection of optimum parameters. The combined implementation of regression, weighted sum method, AHP, and GA has been performed to identify optimum parametric settings for different objective weights. The manufacturers have the flexibility to adopt suggested combinations of parameters for achieving desired results. The following conclusions are derived from present experimentation:

- The results of multi-objective optimization advised to set the value of Ip at 80 A, Ton at 0.5 μ s, Toff at 12 μ s, WF at 5 m/min, WT at 850 G, and SV at 35 V to get optimum values of response parameters.
- The percentage improvement of 13.79%, 19.16%, and 12.50% has been observed as compared to individual best values during the confirmatory experiments.

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